On Strategies for Improving Software Defect Prediction

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Abstract—Programming inherently introduces defects into programs, as a result software systems can crash or fail to deliver an important functionality. It is very important to test a software throughly before it can be used. But an extensive testing can be prohibitively expensive or may take too much time to conduct This necessitates the use of automated software defect prediction tools. Although numerous machine learning algorithms are available to detect defects in software, but several factors undermine the accuracy of such algorithm. This paper uses Classification and Regression Trees (CART) and Random Forests to examines two approaches to counter the aforementioned problem. The first approach involves the use Synthetic Minority Oversampling Technique (also known as SMOTE). The second approach attempts to use a metaheursitic algorithm such as differential evolution to find the right set of parameters that can change the performance of the predictor.

Index Terms-	—Defect Prediction,	Machine Learning,	Differential Evolution,	CART, Random	Forest

1 Introduction

The rest of this paper is organized as follows—Section 2 offers a small illustration of the impact of SMOTE and tuning on the accuracy of the predictor. Section 3 highlights the underlying principles used

in this paper. Section ?? presents the experimental setup followed by section ?? which presents the experimental results and discuss each one. Section ?? contains concluding remarks and finally section ?? talks about the future work.

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amc	average method complexity	e.g. number of JAVA byte codes			
avg_cc	average McCabe average McCabe's cyclomatic complexity seen in class				
ca	afferent couplings	how many other classes use the specific class.			
cam					
		of number of different method parameter types in whole class and number of methods.			
cbm	coupling between methods	total number of new/redefined methods to which all the inherited methods are coupled			
cbo	coupling between objects	increased when the methods of one class access services of another.			
ce	efferent couplings	how many other classes is used by the specific class.			
dam	data access	ratio of the number of private (protected) attributes to the total number of attributes			
dit	depth of inheritance tree				
ic	inheritance coupling	number of parent classes to which a given class is coupled (includes counts of methods and variables			
		inherited)			
lcom	lack of cohesion in methods	number of pairs of methods that do not share a reference to an instance variable.			
locm3	another lack of cohesion measure	if m, a are the number of $methods, attributes$ in a class number and $\mu(a)$ is the number of methods			
		accessing an attribute, then $lcom3 = ((\frac{1}{a}\sum_{j}^{a}\mu(a_{j})) - m)/(1-m)$.			
loc	lines of code				
max_cc	maximum McCabe	maximum McCabe's cyclomatic complexity seen in class			
mfa	functional abstraction	number of methods inherited by a class plus number of methods accessible by member methods of the			
		class			
moa	aggregation	count of the number of data declarations (class fields) whose types are user defined classes			
noc	number of children				
npm	number of public methods				
rfc	response for a class	number of methods invoked in response to a message to the object.			
wmc	weighted methods per class				
defect	defect	Boolean: where defects found in post-release bug-tracking systems.			

Figure 1: OO measures used in our defect data sets. Last line is the dependent attribute (whether a defect is reported to a post-release bug-tracking system).

Rank	Treatment	Med	IQR		Rank	Treatment	Med	IQR	
1	RF	41.0	3.0	•	1	RF	39.0	1.0	•-
2	CART	44.0	3.0	•	2	CART	43.0	2.0	-•
3	CART (SMOTE)	70.0	2.0	•	3	CART (SMOTE)	56.0	2.0	-
4	RF (SMOTE)	78.0	1.0	•	4	RF (SMOTE)	60.0	2.0	-
			(a)	ant				(b) C	Camel
Rank	Treatment	Med	IQR		Rank	Treatment	Med	IQR	
1	RF (SMOTE)	0.0	0.0	•	1	RF	0.0	0.0	•
1	CART (SMOTE)	15.0	15.0		1	CART (SMOTE)	84.0	1.0	•
2	RF	50.0	1.0	•	1	RF (SMOTE)	88.0	1.0	•
3	CART	56.0	1.0	•	1	CART	93.0	0.0	•
			(c)	Ivy				(d)	Jedit
Rank	Treatment	Med	IQR		Rank	Treatment	Med	IQR	
1	CART	36.0	3.0	•	1	RF (SMOTE)	2.0	2.0	•
1	RF	40.0	4.0		2	CART (SMOTE)	14.0	5.0	•
2	RF (SMOTE)	53.0	6.0	-•	3	RF	22.0	2.0	•
2	CART (SMOTE)	54.0	4.0	-	4	CART	41.0	2.0	•
			(e)	POI				(f) I	Log4j
Rank	Treatment	Med	IQR		Rank	Treatment	Med	IQR	
1	CART	47.0	1.0	•	1	RF	51.0	0.0	•
2	RF	51.0	1.0	•—	1	CART	53.0	0.0	•
2	CART (SMOTE)	50.0	4.0	•——	1	CART (SMOTE)	56.0	10.0	
3	RF (SMOTE)	56.0	3.0	-	1	RF (SMOTE)	56.0	1.0	─
			(g) L	ucene				(h) P	Beans
Rank	Treatment	Med	IQR		Rank	Treatment	Med	IQR	
1	CART (SMOTE)	63.0	1.0	-	1	RF	24.0	1.0	•
2	RF (SMOTE)	68.0	2.0	-	2	CART	52.0	18.0	
3	CART	70.0	2.0		2	CART (SMOTE)	59.0	2.0	-•
3	RF	70.0	2.0	•——	2	RF (SMOTE)	60.0	1.0	•

Table 1: Performance scores (g values) for the data sets.

(j) Xalan

(i) Velocity

Algorithm 1 Pesudocode for DE with Early Termination

```
Require: np = 10, f = 0.75, cr = 0.3, life = 5, Goal \in \{pd, f, ...\}
Ensure: S_{best}
  2: \  \, \textbf{function} \  \, \mathsf{DE}(np, \, f, \, cr, \, \mathit{life}, \, \mathit{Goal}) \\
        Population \leftarrow InitializePopulation(np)
        S_{best} \leftarrow GetBestSolution(Population)
 5:
        while life > 0 do
 6:
            NewGeneration \leftarrow \emptyset
 7:
            for i=0 \rightarrow np-1 do
 8:
                S_i \leftarrow \text{Extrapolate}(Population[i], Population, cr, f)
 9:
                if Score(S_i) \ge Score(Population[i]) then
10:
                     NewGeneration.append(S_i)
11:
12:
                     NewGeneration.append(Population[i])
13:
                 end if
14:
             end for
15:
             Population \leftarrow NewGeneration
16:
             if \neg Improve(Population) then
17:
                life-=1
18:
             end if
19:
             S_{best} \leftarrow GetBestSolution(Population)
20:
         end while
21:
         return S_{best}
22: end function
23: \ \textbf{function} \ \ \textbf{Score}(Candidate)
24:
         set tuned parameters according to Candidate
         model \leftarrow \overline{TrainLearner()}
25:
26:
         result \leftarrow TestLearner(model)
27:
        return Goal(result)
28: end function
29: function Extrapolate(old, pop, cr, f)
30:
        a, b, c \leftarrow threeOthers(pop, old)
31:
         newf \leftarrow \emptyset
         for \tilde{i}=0 \rightarrow np-1 do
32:
33:
             if cr < random() then
34:
                 newf.append(old[i])
35:
             else
36:
                 if typeof(old[i]) == bool then
37:
                    newf.append (\mathsf{not}\ old[i])
38:
39:
                    newf.append(trim(i,(a[i] + f * (b[i] - c[i]))))
40:
                 end if
41:
             end if
42:
         end for
43:
         return new f
44: end function
```

2 MOTIVATING EXAMPLE

- 3 BACKGROUND NOTES
- 3.1 Defect Prediction
- 3.2 SMOTE
- 3.3 The Classifiers
- 3.4 Differential Evolution
- 4 EXPERIMENTAL SETUP
- 4.1 Data Sets
- 5 EXPERIMENTAL RESULTS