

Evolutionary Multi-Objective Optimization: A Parallel Computing Approach

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Computer Science

Background

→ Multi-Objective Problem

Models

- \rightarrow DTLZ2
- \rightarrow XOMO
- → POM3

Algorithms

- ightarrow Evolutionary Algorithm
- ightarrow Differential Evolution
- → GALE: Geometric Active Learner

Parallelization Strategies

- → The Island Model
- $\rightarrow \, \mathsf{Master}\text{-}\mathsf{Slave} \,\, \mathsf{Model} \,\,$

Evaluation Metrics → Evaluation

- → Lvaluatio
- $\to\,\mathsf{Measures}$

Experimental Setup

Results

- \rightarrow Island Model
 - \rightarrow Master-Slave Model

Future Work

- → Feature Models
- → Results: Feature Models
- \rightarrow Other Extensions:

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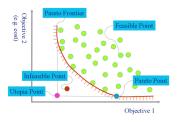


Figure: Sample Pareto Frontier



► Pareto Frontier State of solutions which are equally good.

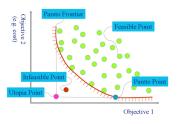


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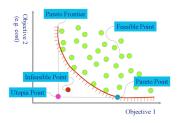


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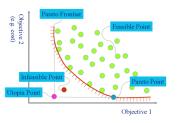


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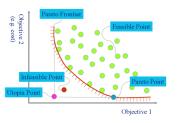


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- Utopia Point The ideal theoretical solution we would love to reach but practically its not possible

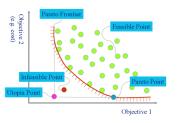


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Models

→ DTI 72

DTLZ-2



▶ **Decisions** DTLZ-2 has 30 decisions where each decision ranges between 0 and 1.

$$0 \leq x_i \leq 1 \quad \text{ where } \ i=1,2,3....30$$

► **Objectives** A point that lies on the Pareto frontier.

$$f_1(x) = (1 + g(x_M)) \cos(x_1 \pi/2) \dots \cos(x_{M-1} \pi/2)$$

$$f_2(x) = (1 + g(x_M)) \cos(x_1 \pi/2) \dots \cos(x_{M-1} \pi/2)$$

$$f_3(x) = (1 + g(x_M)) \sin(x_1 \pi/2)$$

$$where \qquad g(x_M) = \sum_{x \in x_M} (x_i - 0.5)^2$$

▶ Optimal Solution: Ideal Decisions are $x_i = 0.5$ where i = 1, 2, 3...30 Ideal objectives should satisfy the equation $\sum_{m=1}^{3} f_m^2 = 1$

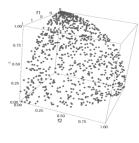


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XOMO



► Monte Carlo Simulator modelling NASA's space program software.

XOMO



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- ▶ 23 decisions lines of code, storage, cyclometric complexity etc.

XOMO



- ► Monte Carlo Simulator modelling NASA's space program software.
- ▶ 23 decisions lines of code, storage, cyclometric complexity etc.
- ▶ 4 objectives all minimized
 - ► Total Developer **Effort**.
 - Months to complete project.
 - ► Total **Defects** in project.
 - ► Risk involved in project.



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POM3



▶ Implements Boehm & Turner model of agile programming

POM₃



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- ▶ 9 decisions like size of project, project plan, team size etc.

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- ► Implements Boehm & Turner model of agile programming
- ► Teams select tasks as they appear in the scrum backlog.
- ▶ 9 decisions like size of project, project plan, team size etc.
- ► The model contains 4 objectives
 - Minimize Cost.
 - Maximize Utility.
 - ► Maximize Completion Percentage.
 - ► Minimize Idle Time for Developers.



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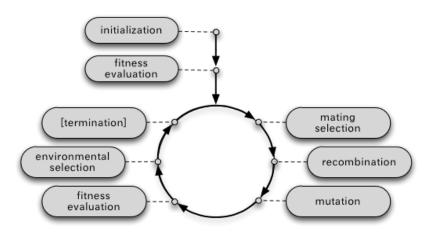
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Evolutionary Algorithm







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Differential Evolution(DE)



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- ► Stochastic evolutionary optimization technique.
- ► Iteratively approximates the shape of the Pareto Frontier

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- ► Stochastic evolutionary optimization technique.
- ▶ Iteratively approximates the shape of the Pareto Frontier
- ► Advantages:
 - ► Simple & Computationally Inexpensive.
 - ► High dimensional problems can be handled easily.
 - Solutions are very stable.

DE - Algorithm



Pseudo-code 3.2 Differential Evolution

Begin

Generate randomly an initial population of solutions.

Calculate the fitness of the initial population.

Repeat

For each parent, select three solutions at random.

Create one offspring using the DE operators.

Do this a number of times equal to the population size.

For each member of the next generation

If offspring(x) is more fit than parent(x)

Parent(x) is replaced.

Until a stop condition is satisfied.

End.



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- ► Builds piecewise approximation to the best solutions of the pareto frontier.



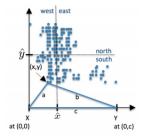
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- ► Based on WHERE which is a recursive clustering technique based on Dimensionality Reduction.



- ▶ Near linear time Multi-Objective Evolutionary Algorithm.
- Builds piecewise approximation to the best solutions of the pareto frontier.
- Based on WHERE which is a recursive clustering technique based on Dimensionality Reduction.
- ► Advantages:
 - Less Number of Computations.
 - Adept at handling problems that are non-differentiable, non-liner, multi-dimensional or multi-constraint.
 - ► Concise representation of problem space.

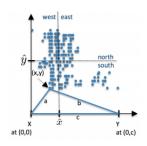


► Cluster data based on WHERE





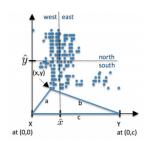
► Cluster data based on WHERE



Pick point X from the cluster. Then pick point East furthest from X and point West furthest from East. Let c be the distance between East and West.



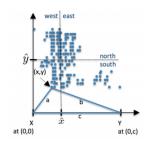
► Cluster data based on WHERE



- Pick point X from the cluster. Then pick point East furthest from X and point West furthest from East. Let c be the distance between East and West.
- For every other point in the cluster, compute a and b which represents distance of the point from East and West respectively.



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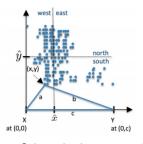


- Pick point X from the cluster. Then pick point East furthest from X and point West furthest from East. Let c be the distance between East and West.
- For every other point in the cluster, compute a and b which represents distance of the point from East and West respectively.
- Compute the projection \mathbf{x} as $\mathbf{x} = (\mathbf{a}^2 + \mathbf{c}^2 \mathbf{b}^2)/2\mathbf{c}$

GALE - Algorithm



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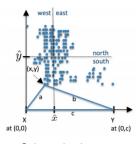


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- Select the best point from the non-dominated cluster and mutate towards it and store the best points.

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- Select the best point from the non-dominated cluster and mutate towards it and store the best points.
- ► Repeat for **n** generations.



Parallelization Strategies

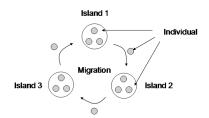
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Island Model



 Divide the initial population(N) into sub-populations of equal size(n) among k processors.

$$n = \frac{N}{k}$$



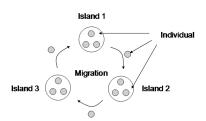
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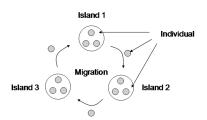
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- ► Evolve each sub-population independently.
- Aggregate the final population of each processor after the total number of generations.





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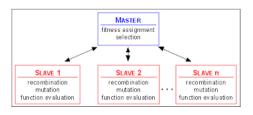
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Master-Slave Model



► Master selects a population for each free slave in each generation.



Master-Slave Model



- Master selects a population for each free slave in each generation.
- ► Slave evaluates the fitness and computes the best solution(s) for each population set.



Master-Slave Model



- Master selects a population for each free slave in each generation.
- Slave evaluates the fitness and computes the best solution(s) for each population set.
- Slave performs mutation on each population subset and sends it to master for next generation.





Evaluation Metrics

- → Evaluation



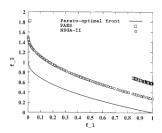
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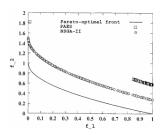




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Convergence:

- ► Accuracy of the obtained solutions.
- Represents the HyperVolume between the obtained solutions and Pareto Frontier





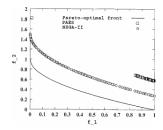
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► Diversity:

- ► Spread of the proposed solutions.
- ► Ideally the solutions should be well distributed across the Pareto Frontier





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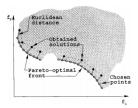
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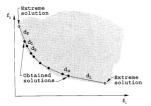


Convergence:



- Find a set of H optimal solutions.
- For each solution, compute the minimum eucledian distance from each of the solutions to a point on the Pareto Frontier.
- ► The average of these distances represent convergence.

Diversity:



- d_i is the distance between consecutive solutions.
- $ightharpoonup \overline{d}$ is the mean of d_i
- ▶ d_f & d_I are distance between extreme and boundary solutions.

$$\Delta = \frac{d_f + d_l + \sum_{i=1}^{N-1} |d_i - \bar{d}|}{d_f + d_l + (N-1)\bar{d}}$$



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► HPC

- The henry2 shared memory linux cluster at NCSU.
- Up to 16 shared memory processor cores and up to 128GB of memory accessible through a dedicated queue.



Results

- → Island Model

DTLZ-2(Island Model)



Rank	Optimizer	Median	IQR	Quartile Chart
1	DE(Parallel)	2.30 x 10 ⁻⁵	2.74 x 10 ⁻⁶	- -
1	DE(Serial)	2.36 x 10 ⁻⁵	3.04 x 10 ⁻⁶	- -
2	GALE(Serial)	5.49 x 10 ⁻⁴	8.32 x 10 ⁻⁶	- -
2	GALE(Parallel)	5.54 x 10 ⁻⁴	2.21 x 10 ⁻⁵	

Figure: Convergence of serial & parallel DE & GALE

DTLZ-2(Island Model)



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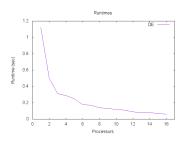
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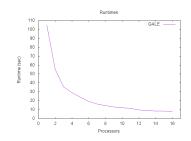
Rank	Optimizer	Median	IQR	Quartile Chart
1	GALE(Parallel)	0.416	0.070	-
1	DE(Parallel)	0.417	0.049	- -
1	DE(Serial)	0.431	0.056	-
1	GALE(Serial)	0.432	0.047	- -

Figure: Diversity of serial & parallel DE & GALE

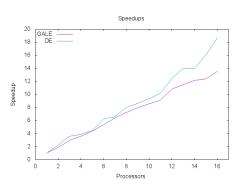
DTLZ-2(Island Model)

Runtimes:





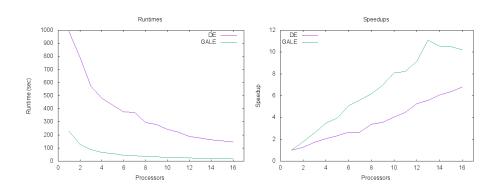




POM3(Island Model)



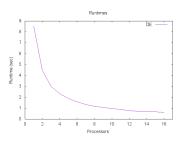
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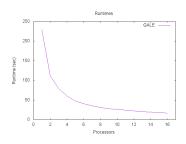


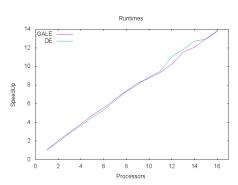
XOMO(Island Model)

Computer Science

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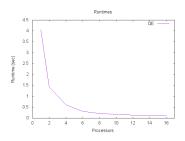
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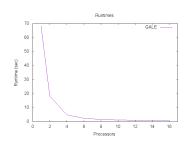
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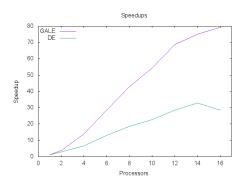
DTLZ-2(Master-Slave Model)

Computer Science

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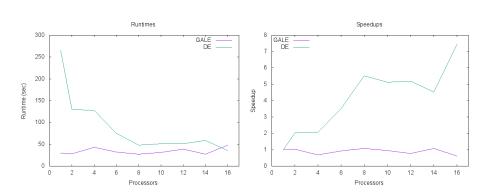




POM3(Master-Slave Model)



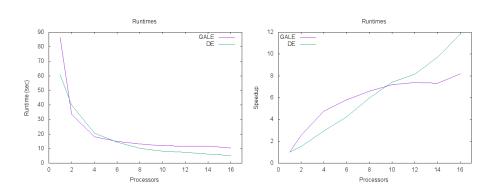
Runtimes:



XOMO(Master-Slave Model)



Runtimes:





Future Work

- \rightarrow Feature Models

Feature Model



► A **feature model** is a compact representation of all the products of the Software Product Line in terms of "features". Feature models are visually represented by means of feature diagrams.

Feature Model



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- ► For our experiment we use the Emergency Response(ERS) feature model, which has **35 decisions** and **3 objectives**.



Background

→ Multi-Objective Problem

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- ightarrow DTLZ
- \rightarrow XUIVI
- → POM3

Algorithms

- ightarrow Evolutionary Algorithm
 - → Differential Evolution
 - → GALE: Geometric Active Learner

Parallelization Strategies

- → The Island Model
- → Master-Slave Model

=valuation Metrics

- -> Lvaiuatio
 - → Measures

Experimental Setup

Results

- → Island Mode
 - ightarrow Master-Slave Model

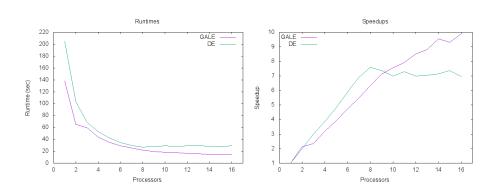
Future Work

- → Feature Models
- $\rightarrow \mbox{ Results: Feature Models}$
- → Other Extensions:

Emergency Response(Island Model)



Runtimes:





Future Work

- → Other Extensions:

Other Extensions:



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- Mutation strategies for real world problems which are heavily constrained.
- ► Extending these parallelization strategies for other Evolutionary algorithms like NSGA2, SPEA, IBEA etc
- ► Strategies for efficiently dividing the feature space for parallelization.

In Conclusion..



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- ▶ Differential Evolution is preferred for Mathematical Problems.

In Conclusion...



- ► Parallelization is effective for Multi Objective Evolutionary Algorithms.
- ▶ Differential Evolution is preferred for Mathematical Problems.
- ► GALE is preferred for Real-World Problems where model evaluation is expensive.