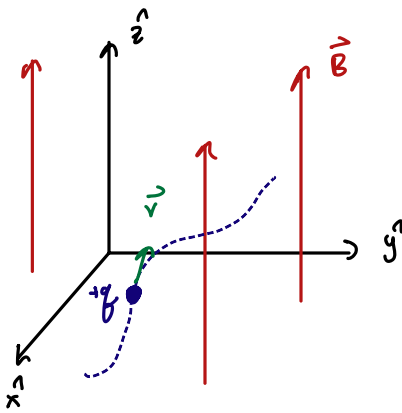


Lecture 7



$$\vec{F} = q \vec{v} \times \vec{B} \quad \vec{B} = B \hat{z}$$

$$\Rightarrow \vec{F} = q v_y B \hat{x} - q v_x B \hat{y}$$

$$m \dot{v}_x \hat{x} + m \dot{v}_y \hat{y} = q v_y B \hat{x} - q v_x B \hat{y}$$

$$\Rightarrow m \dot{v}_x = q v_y B \quad m \dot{v}_y = -q v_x B$$

$$\dot{v}_x = \omega v_y, \quad \dot{v}_y = -\omega v_x$$

$$\omega = \frac{qB}{m} \quad \text{"cyclotron frequency"}$$

$$\text{let } \eta = v_x + i v_y$$

$$\dot{\eta} = \dot{v}_x + i \dot{v}_y$$

$$= (\omega v_y) + i(-\omega v_x) = -i\omega (i v_y + v_x) = -i\omega \eta$$

$$\dot{\eta} = -i\omega \eta \quad \rightarrow \text{we can solve this!}$$

$$\frac{d\eta}{dt} = -i\omega \eta$$

$$\Rightarrow \eta = A e^{-i\omega t}$$

let's take a closer look

Complex exponentials

$$e^z = 1 + z + \frac{1}{2!} z^2 + \frac{1}{3!} z^3 + \dots \quad \text{let } z = i\theta$$

$$e^{i\theta} = 1 + i\theta + \frac{i^2 \theta^2}{2!} + \frac{i^3 \theta^3}{3!} + \frac{i^4 \theta^4}{4!} + \frac{i^5 \theta^5}{5!} + \frac{i^6 \theta^6}{6!} + \frac{i^7 \theta^7}{7!} + \frac{i^8 \theta^8}{8!} + \dots$$

$$i \equiv \sqrt{-1} \quad \Rightarrow \quad i^0 = 1$$

$$i^1 = i$$

$$i^2 = -1$$

$$i^3 = i^2 i = -i$$

$$i^4 = i^2 i^2 = (-1)(-1) = +1$$

$$i^5 = i^4 i = i$$

$$i^6 = i^4 i^2 = -1$$

$$i^7 = i^4 i^3 = -i$$

$$i^8 = i^4 i^4 = +1$$

} The pattern repeats

$$e^{i\theta} = \underbrace{\left(1 - \frac{\theta^2}{2!} + \frac{\theta^4}{4!} - \frac{\theta^6}{6!} + \frac{\theta^8}{8!} + \dots \right)}_{\cos \theta} + i \underbrace{\left(\theta - \frac{\theta^3}{3!} + \frac{\theta^5}{5!} - \frac{\theta^7}{7!} + \dots \right)}_{\sin \theta}$$

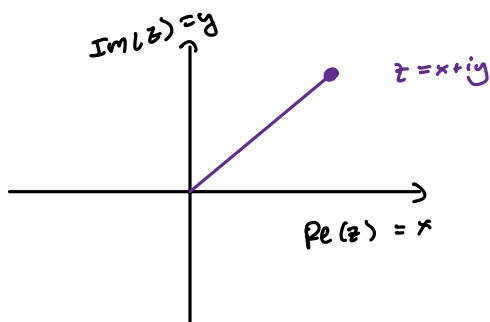
$$\Rightarrow e^{i\theta} = \cos\theta + i\sin\theta$$

Euler's Formula

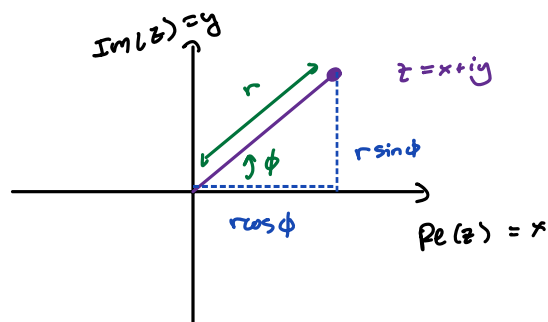
What does it mean? In general: $z = \operatorname{Re}(z) + i \operatorname{Im}(z)$ let $x = \operatorname{Re}(z)$
 $y = \operatorname{Im}(z)$

$$\Rightarrow z = x + iy \quad \text{where } x, y \text{ are any real \# } \in (-\infty, \infty)$$

We can represent this visually:



We can also use polar coordinates



Back to Euler's formula.

$$\text{If } z = e^{i\theta} = \cos\theta + i\sin\theta \Rightarrow x = \cos\theta \quad y = \sin\theta$$

$$r = \sqrt{x^2 + y^2} = \sqrt{\cos^2\theta + \sin^2\theta} = 1$$

$$r = 1$$

$$\text{Also } x = r \cos\phi \quad \& \quad y = r \sin\phi$$

$$x = \cos\theta = r \cos\phi = \cos\phi$$

$$y = \sin\theta = r \sin\phi = \sin\phi$$

}

the θ in Euler's formula
is the ϕ in polar
 coordinates!

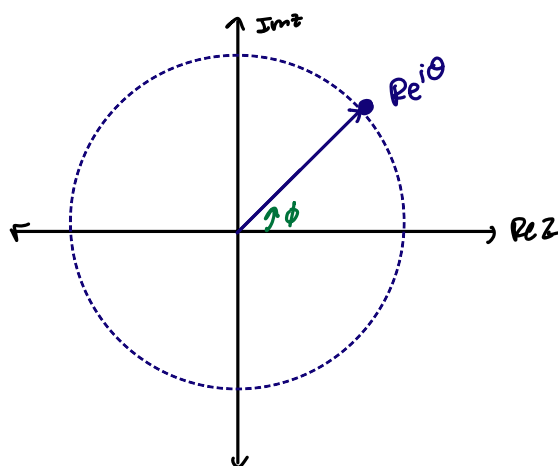
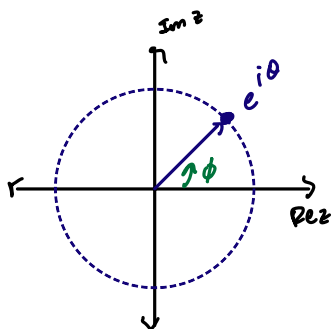
In general, any complex # can be written in two ways:

$$z = x + iy$$

"Cartesian"

$$z = Re^{i\theta}$$

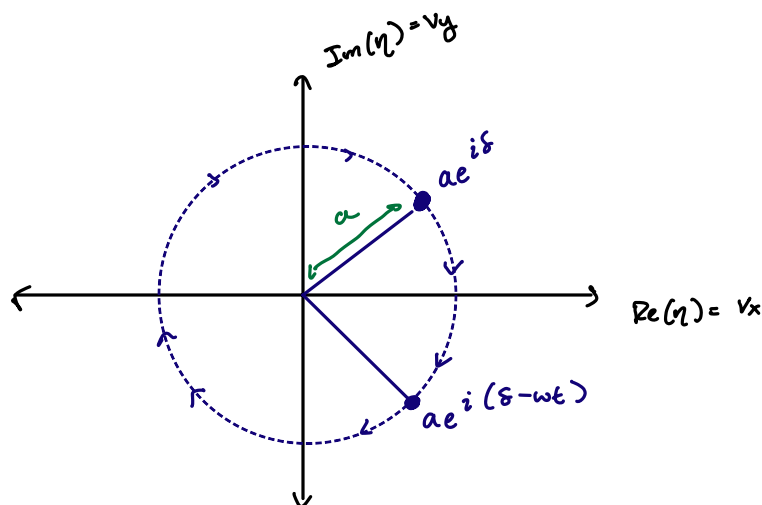
"polar"



Back to our solution of a charge moving in a \vec{B} field:

$$\eta = A e^{-i\omega t} = (a e^{i\delta}) e^{-i\omega t} = a e^{i(\delta - \omega t)} \quad \& \quad \eta = v_x + i v_y$$

A can be complex!



$$\eta = a e^{i(\delta - \omega t)}$$

$$\eta = v_x + i v_y$$

$$\eta = a [\cos(\delta - \omega t) + i \sin(\delta - \omega t)]$$

$$\Rightarrow v_x = a \cos(\delta - \omega t) \quad v_y = a \sin(\delta - \omega t)$$

To find $x(t)$ & $y(t)$, easier to go back to polar coordinates:

$$\dot{\vec{z}} = \dot{x} + i \dot{y} \quad \dot{\vec{z}} = \dot{x} + i \dot{y} = v_x + i v_y = \eta$$

$$\frac{d\vec{z}}{dt} = \eta$$

$$\int_{\vec{z}_0}^{\vec{z}} d\vec{z} = \int_0^t \eta dt' = \int_0^t a e^{i(\delta - \omega t')} dt'$$

$$\vec{z}' \Big|_{\vec{z}_0}^{\vec{z}} = \frac{a}{-i\omega} e^{i(\delta - \omega t')} \Big|_0^t$$

$$\vec{z} - \vec{z}_0 = \frac{ai}{\omega} [e^{i(\delta - \omega t)} - e^{i\delta}]$$

$$\vec{z} = \vec{z}_0 + \frac{ia}{\omega} e^{i\delta} + \frac{ia}{\omega} e^{i(\delta - \omega t)}$$

$$z = x_0 + iy_0 - \frac{ia}{\omega} \cos \delta + \frac{a}{\omega} \sin \delta + \frac{ia}{\omega} e^{i(\delta - \omega t)}$$

let $x_0 = -\frac{a}{\omega} \sin \delta$ and $y_0 = \frac{a}{\omega} \cos \delta$ (change origin)

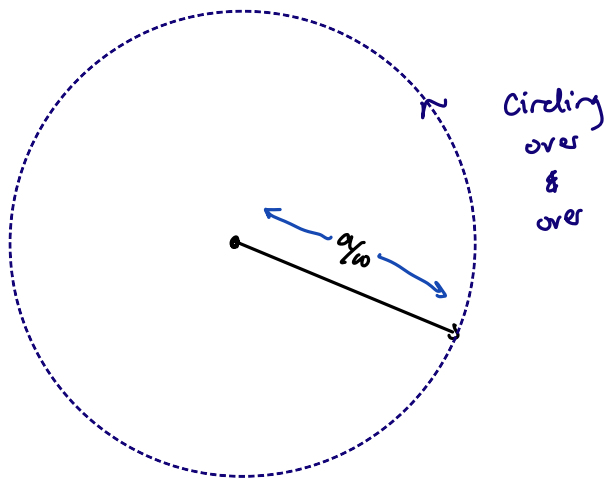
$$z = \frac{ia}{\omega} e^{i(\delta - \omega t)} = \frac{ia}{\omega} \cos(\delta - \omega t) - \frac{a}{\omega} \sin(\delta - \omega t) = x(t) + iy(t)$$

$$x(t) = -\frac{a}{\omega} \sin(\delta - \omega t)$$

$$y(t) = \frac{a}{\omega} \cos(\delta - \omega t)$$

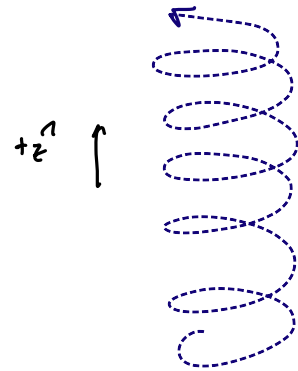
$$z(t) = \frac{ia}{\omega} e^{i(\delta - \omega t)}$$

In the x-y plane, this motion is



Remember $\dot{z} = v$

$$\Rightarrow z(t) = z_0 + v_0 t$$



$$|\vec{v}_{\text{transverse}}| = |\dot{\eta}| = \left| a e^{i(\delta - \omega t)} \right| = a = v$$

$$|R| = \left| \frac{z}{t} \right| = \left| \frac{ia}{\omega} e^{i(\delta - \omega t)} \right| = \frac{a}{\omega} = \frac{v}{\omega} = \frac{mv}{qB}$$

End of Chapter 2!