

## Activity 4

1. Time to review! Draw free body diagrams on top of the following figures, and write down Newton's second law (or conservation of momentum) in terms of components of your chosen coordinate system. Write them as differential equations that describe the equation of motion. In each case, outline your method of solving the differential equation and obtaining the kinematic equations.

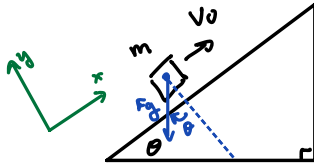


Figure 1: A block of mass  $m$  slides up a hill that makes angle  $\theta$  with the horizontal. Gravitational acceleration is  $g$  and gravity points downwards.

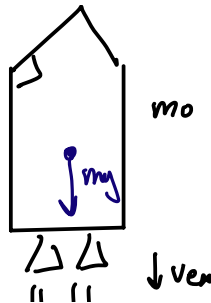


Figure 2: A rocket shoots upwards. It starts with initial mass  $m_0$  and expels fuel at a speed  $v_{ex}$ . Gravitational acceleration is  $g$  and gravity points downwards.

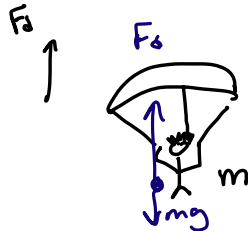


Figure 3: A parachuter of mass  $m$  falls with drag force  $\vec{F} = -cv^2 \hat{v}$ . Gravitational acceleration is  $g$  and gravity points downwards.

$$\vec{F} = mg \sin \theta \hat{x} + (F_N - mg \cos \theta) \hat{y}$$

$$m\ddot{x} = -mg \sin \theta$$

Multiply both sides by  $dt$  & integrate for  $v(t) = \dot{x}(t)$

Multiply both sides by  $dt$  & integrate for  $x(t)$

$$\vec{F}_{ext} = \dot{\vec{P}}$$

$$-mg \hat{y} = \frac{d\vec{P}}{dt}$$

$$-mg dt = d\vec{P} - \vec{P}$$

$$P = mv$$

$$P + dP = (m + dm)(v + dv) + (-dm)(v - v_{ex})$$

$$= mv + m dv + v dm + 0(z^2) - v dm + v_{ex} dm$$

$$-mg dt = m dv + v dm - m dv$$

$$-mg dt = m dv + v dm$$

If you want to go further,  
divide by  $m$

$$-g dt = dv + v \frac{dm}{m}$$

Integrate

$$\int_{t_0}^t -g dt' = \int_{v_0}^v dv' + v_{ex} \int_{m_0}^m \frac{dm'}{m'}$$

$$m\ddot{x} = -mg \hat{y} + cv^2 \hat{y}$$

$$m\dot{y} = -mg + cv^2$$

$$m\dot{v} = -mg + cv^2$$

Separate variables into  $dv$ ,  $dt$  and integrate.

Rearrange to get  $v(t) = \dot{y}(t)$

Multiply both sides by  $dt$  & integrate  
to get  $y(t)$

If you got this  
far, that's fine

$$y(t) = v - v_0 + v_{ex} \ln\left(\frac{m}{m_0}\right)$$

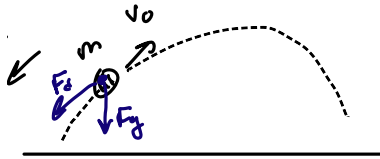


Figure 4: A projectile of mass  $m$  is shot with speed  $v_0$  and experiences a drag force  $\vec{F}_d = -b\vec{v}$  and gravity pointing downwards.

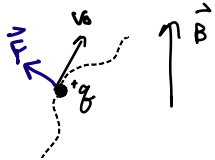


Figure 5: A charge  $+q$  moves in a magnetic field  $\vec{B} = B\hat{z}$  with an initial velocity  $\vec{v}_0$ . There is no gravity.

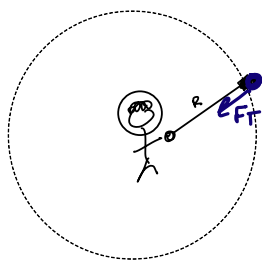


Figure 6: An astronaut swings a mass in a circle. There is no gravity.

$$m\vec{a} = -b v_x \hat{x} + (-b v_y - mg) \hat{y}$$

$$m\dot{x} = -b v_x \quad m\dot{y} = -b v_y - mg$$

$$\dot{v}_x = -\frac{b}{m} v_x \quad \dot{v}_y = -\frac{b}{m} v_y - g$$

separate variables ( $dv_x$  and  $dt$ ;  $dv_y$  and  $dt$ ) and integrate to find  $v_x(t)$ ,  $v_y(t)$

Multiply both sides by  $dt$  & integrate to find  $x(t)$ ,  $y(t)$

$$m\vec{a} = q(\vec{v} \times \vec{B}) = q v_y B \hat{x} - q v_x B \hat{y}$$

$$m\ddot{x} = q v_y B \quad m\ddot{y} = -q v_x B$$

$$\dot{v}_x = \frac{qB}{m} v_y \quad \dot{v}_y = -\frac{qB}{m} v_x$$

- Define  $\eta = v_x + i v_y$  & derive  $\dot{\eta} = i \eta$
- separate variables ( $d\eta$ ,  $dt$ ) and integrate
- Find  $\eta(t)$
- use Euler's eqn to extract  $v_y$ ,  $v_x$
- Multiply both sides by  $dt$  & integrate to find  $y(t)$ ,  $x(t)$

$$\vec{F} = -F_r \hat{r}$$

$$m\vec{a} = -F_r \hat{r}$$

$$m(\ddot{r} - r\dot{\phi}^2) = -F_r$$

$$m(r\ddot{\phi} + 2\dot{r}\dot{\phi}) = 0$$

We know  
 $r = R = \text{const.}$

$$\Rightarrow \begin{cases} -mr\dot{\phi}^2 = -F_r \\ mr\ddot{\phi} = 0 \end{cases} \Rightarrow \dot{\phi} = \omega_0$$

$$\phi = \omega_0 t + \phi_0$$

$$-mR\omega_0^2 = F_r$$

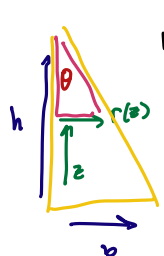
$$-mR\omega_0^2 = F_r$$

$$\vec{R}_{CM} = \frac{1}{M} \int \vec{r} dm \quad I = \int r^2 dm \Rightarrow I = \int r^2 \mu dV \Rightarrow I = \mu \int r^3 d\rho d\phi dz$$

2. The position of the center of mass,  $\vec{R}_{CM}$  and the moment of inertia  $I$  of a system of  $N$  particles are defined as:

$$\vec{R}_{CM} = \frac{1}{M} \sum_{\alpha=1}^N m_{\alpha} \vec{r}_{\alpha} \quad I = \sum_{\alpha} m_{\alpha} \rho_{\alpha}^2, \quad (1)$$

where  $\rho$  is the distance of particle  $\alpha$  from the axis of rotation. Find the moment of inertia of the uniform cone shown in Fig. 7.



we know  $\tan \theta = \frac{b}{h}$  (yellow  $\Delta$ )  
 and  $\tan \theta = \frac{r(z)}{h-z}$  (pink  $\Delta$ )  
 $\Rightarrow \frac{b}{h} = \frac{r(z)}{h-z}$   
 $b - \frac{bz}{h} = r(z)$

$$I = \mu \int r^3 d\rho dz d\phi = \mu \int_0^h \int_0^{r(z)} \rho^3 d\rho dz \int_0^{2\pi} d\phi$$

$$I = \mu \int_0^h \int_0^{bz/h} \rho^3 d\rho dz (2\pi)$$

$$I = 2\pi \mu \int_0^h \left[ \frac{1}{4} \rho^4 \right]_0^{bz/h} dz$$

$$I = 2\pi \mu \int_0^h \frac{b^4 z^4}{4h^4} dz = \frac{2\pi \mu b^4}{4h^4} \left( \frac{z^5}{5} \right)_0^h$$

$$I = \frac{\pi \mu b^4}{2h^4} \left( \frac{h^5}{5} \right) = \frac{\pi \mu b^4 h}{10}, \quad \mu = \frac{M}{V_{\text{cone}}} = \frac{M}{\left( \frac{\pi b^2 h}{3} \right)}$$

$$\mu = \frac{3M}{\pi b^2 h}$$

$$I = \frac{\pi b^4 h}{10} \left( \frac{3M}{\pi b^2 h} \right) = \boxed{\frac{3M b^2}{10}}$$

Figure 7: The cone rotating about the  $z$ -axis. It has height  $h$  and radius  $b$  at the base

3. Find the work done from point A to point B along the three paths shown in Fig. 8. Use:

$$W(A \rightarrow B) = \int_A^B \vec{F} \cdot d\vec{r} \quad (2)$$

$$\vec{F} = xy^2\hat{x} + y^3\hat{y} \quad (3)$$

Useful integral:

$$\int xe^x dx = (x-1)e^x + C \quad \vec{F} \cdot d\vec{r} = xy^2 dx + y^3 dy \quad (4)$$

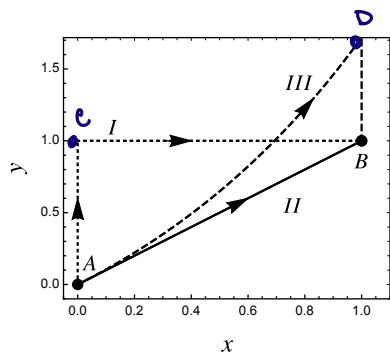


Figure 8: The paths the force acts along. Path II is defined by  $y = x$  and path III is defined by  $y = e^x - 1$

$$W_I = \int_A^C y^3 dy + \int_C^B xy^2 dx = \int_0^1 y^3 dy + \int_0^1 x(1)^2 dx = \left. \frac{y^4}{4} \right|_0^1 + \int_0^1 x dx$$

$$= \frac{1}{4} + \left. \frac{x^2}{2} \right|_0^1 = \frac{1}{4} + \frac{1}{2} = \boxed{\frac{3}{4}}$$

Along II,  $x=y \Rightarrow dx=dy$

$$\vec{F} \cdot d\vec{r} = x^3 dx + x^3 dx = 2x^3 dx$$

$$W_{II} = \int_A^B 2x^3 dx = \int_0^1 2x^3 dx = \left. \frac{2x^4}{4} \right|_0^1 = \boxed{\frac{1}{2}}$$

Along III up to point D:

$$y = e^x - 1$$

$$dy = e^x dx$$

$$\vec{F} \cdot d\vec{r} = x(e^x - 1)^2 dx + (e^x - 1)^3 e^x dx$$

$$= (xe^{2x} - 2xe^x + x + e^{4x} - 3e^{3x} + 3e^{2x} - e^x) dx + (e^{3x} - 3e^{2x} + 3e^x - 1)e^x dx$$

From point D  $\rightarrow$  B:

$x=1$   $dy$  only  
 $dx=0$  at point D,  $x=1$   
 $y = e - 1$

$$W_{III} = \int_A^D [xe^{2x} - 2xe^x + x + e^{4x} - 3e^{3x} + 3e^{2x} - e^x] dx + \int_D^B y^3 dy$$

$$= \left. \frac{1}{4} \int_0^1 2xe^{2x} (2dx) + \left[ -2(x-1)e^x + \frac{1}{2}x^2 + \frac{1}{4}e^{4x} - \frac{3}{2}e^{3x} + \frac{3}{2}e^{2x} - e^x \right]_0^1 \right. + \int_{e-1}^1 y^3 dy$$

$$= \frac{1}{4} \left[ (2x-1)e^{2x} \right]_0^1 + \left[ 0 + \frac{1}{2} + \frac{1}{4}e^4 - e^3 + \frac{3}{2}e^2 - e + 2(-1)(1) - 0 - \frac{1}{4} + \cancel{x} - \frac{3}{2} + \cancel{x} \right] + \left. \frac{1}{4}y^4 \right|_{e-1}^1$$

$$= \frac{1}{4} \left[ (1)e^2 - (-1)(1) \right] + \frac{1}{4}e^4 - e^3 + \frac{3}{2}e^2 - e - \frac{1}{4} - 1 + \frac{1}{4} - \frac{1}{4}(e-1)^4$$

$$\quad \quad \quad \frac{1}{4}e^2 + \frac{1}{4}$$

$$= \cancel{\frac{1}{4}e^4} - \cancel{e^3} + \frac{7}{4}e^2 - \cancel{e} - 1 + \cancel{\frac{1}{4}} - \frac{1}{4}(\cancel{e^4} - \cancel{4e^3} + 6e^2 - 4e + 1)$$

$$= (7/2 - 6/4)e^2 - 1 = \boxed{2e^2 - 1 = W_{III}}$$