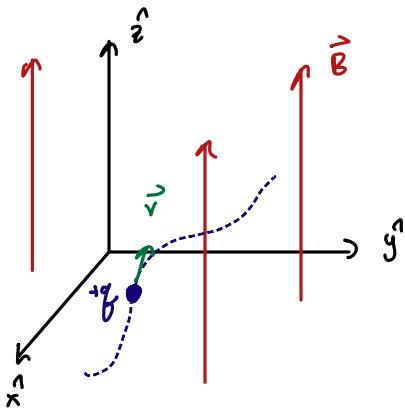


## Lecture 7



$$\vec{F} = q \vec{v} \times \vec{B} \quad \vec{B} = B \hat{z}$$

$$\Rightarrow \vec{F} = q v_y B \hat{x} - q v_x B \hat{y}$$

$$m \ddot{v}_x \hat{x} + m \ddot{v}_y \hat{y} = q v_y B \hat{x} - q v_x B \hat{y}$$

$$\Rightarrow m \ddot{v}_x = q v_y B \quad m \ddot{v}_y = -q v_x B$$

$$\ddot{v}_x = \omega v_y \quad , \quad \ddot{v}_y = -\omega v_x \quad \omega = \frac{qB}{m} \quad \text{"cyclotron frequency"}$$

Let  $\eta = v_x + i v_y$

$$\begin{aligned} \dot{\eta} &= \dot{v}_x + i \dot{v}_y \\ &= (\omega v_y) + i (-\omega v_x) = -i\omega (i v_y + v_x) = -i\omega \eta \end{aligned}$$

$$\dot{\eta} = -i\omega \eta \quad \Rightarrow \text{we can solve this!}$$

$$\frac{d\eta}{dt} = -i\omega \eta$$

$$\Rightarrow \eta = Ae^{-i\omega t}$$

Let's take a closer look

### Complex exponentials

$$e^z = 1 + z + \frac{1}{2!} z^2 + \frac{1}{3!} z^3 + \dots \quad \text{let } z = i\theta$$

$$e^{i\theta} = 1 + i\theta + \frac{i^2 \theta^2}{2!} + \frac{i^3 \theta^3}{3!} + \frac{i^4 \theta^4}{4!} + \frac{i^5 \theta^5}{5!} + \frac{i^6 \theta^6}{6!} + \frac{i^7 \theta^7}{7!} + \frac{i^8 \theta^8}{8!} + \dots$$

$$i \equiv \sqrt{-1} \Rightarrow i^0 = 1$$

$$i^1 = i$$

$$i^2 = -1$$

$$i^3 = i^2 i = -i$$

$$i^4 = i^2 i^2 = (-1)(-1) = +1$$

$$i^5 = i^4 i = i$$

$$i^6 = i^4 i^2 = -1$$

$$i^7 = i^4 i^3 = -i$$

$$i^8 = i^4 i^4 = 1$$

The pattern repeats

$$e^{i\theta} = \left( 1 - \frac{\theta^2}{2!} + \frac{\theta^4}{4!} - \frac{\theta^6}{6!} + \frac{\theta^8}{8!} + \dots \right) + i \left( \theta - \frac{\theta^3}{3!} + \frac{\theta^5}{5!} - \frac{\theta^7}{7!} + \dots \right) \sin \theta$$

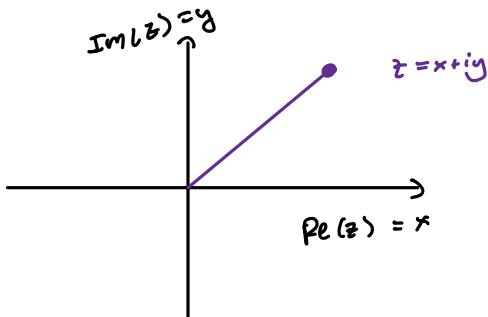
$$\Rightarrow e^{i\theta} = \cos\theta + i\sin\theta$$

Euler's Formula

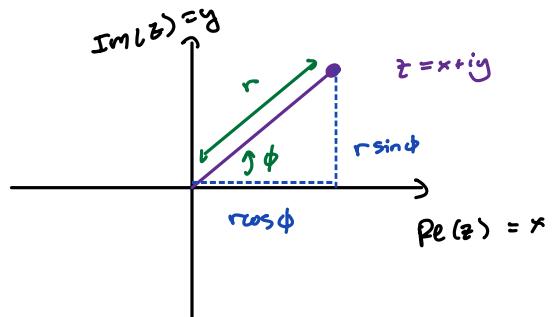
What does it mean? In general:  $z = \operatorname{Re}(z) + i \operatorname{Im}(z)$  let  $x = \operatorname{Re}(z)$   
 $y = \operatorname{Im}(z)$

$$\Leftrightarrow z = x + iy \quad \text{where } x, y \text{ are any real } \# \in (-\infty, \infty)$$

We can represent this visually:



We can also use polar coordinates



Back to Euler's formula.

$$\text{If } z = e^{i\theta} = \cos\theta + i\sin\theta \Rightarrow x = \cos\theta \quad y = \sin\theta$$

$$r = \sqrt{x^2 + y^2} = \sqrt{\cos^2\theta + \sin^2\theta} = 1$$

$$r=1$$

$$\text{Also } x = r\cos\phi \quad \& \quad y = r\sin\phi$$

$$\left. \begin{array}{l} x = \cos\theta = r\cos\phi = \cos\phi \\ y = \sin\theta = r\sin\phi = \sin\phi \end{array} \right\} \quad \begin{array}{l} \text{the } \theta \text{ in Euler's formula} \\ \text{is the } \phi \text{ in polar} \\ \text{coordinates!} \end{array}$$

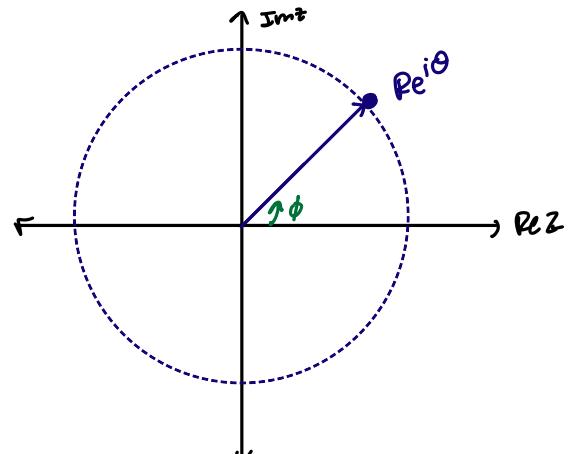
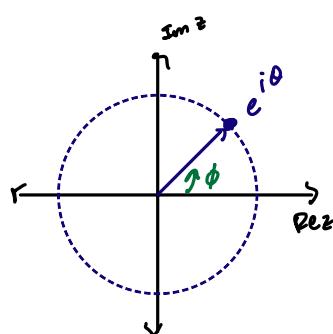
In general, any complex # can be written in two ways:

$$z = x + iy$$

"Cartesian"

$$z = Re^{i\theta}$$

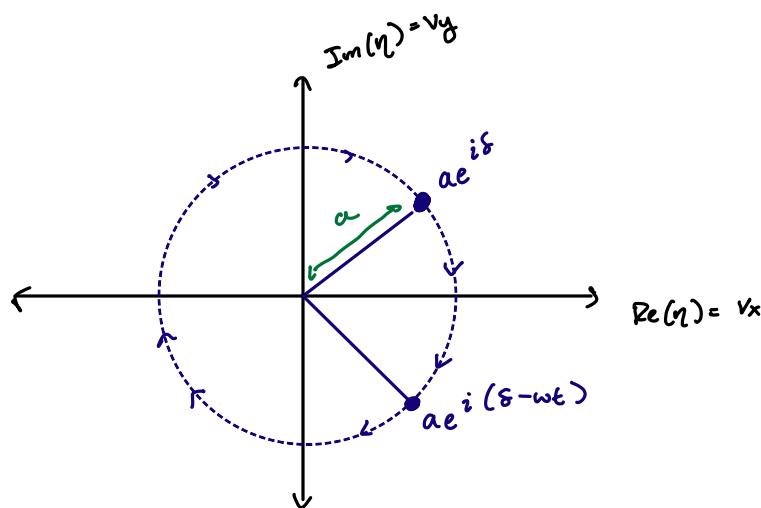
"polar"



Back to our solution of a charge moving in a  $\vec{B}$  field:

$$\eta = Ae^{-i\omega t} = (ae^{i\delta}) e^{-i\omega t} = ae^{i(\delta-\omega t)} \quad \text{and } \eta = v_x + i v_y$$

$A$  can  
be complex!



$$\eta = ae^{i(\delta-\omega t)} \quad \eta = v_x + i v_y$$

$$\eta = a [\cos(\delta - \omega t) + i \sin(\delta - \omega t)]$$

$$\Rightarrow v_x = a \cos(\delta - \omega t) \quad v_y = a \sin(\delta - \omega t)$$

To find  $x(t)$  &  $y(t)$ , easier to go back to polar coordinates:

$$\vec{z} = x + iy \quad \vec{z} = \vec{x} + i\vec{y} = v_x + i v_y = \eta$$

$$\frac{d\vec{z}}{dt} = \eta$$

$$\int_{\vec{z}_0}^{\vec{z}} d\vec{z}' = \int_0^t \eta dt' = \int_0^t ae^{i(\delta-\omega t')} dt'$$

$$\vec{z}' \Big|_{\vec{z}_0}^{\vec{z}} = \frac{a}{-i\omega} e^{i(\delta-\omega t')} \Big|_0^t$$

$$\vec{z} - \vec{z}_0 = \frac{ai}{\omega} \left[ e^{i(\delta-\omega t)} - e^{i\delta} \right]$$

$$\vec{z} = \vec{z}_0 + \frac{ia}{\omega} e^{i\delta} + \frac{ia}{\omega} e^{i(\delta-\omega t)}$$

$$\vec{z} = x_0 + iy_0 - \frac{ia}{\omega} \cos \delta + \frac{a}{\omega} \sin \delta + \frac{ia}{\omega} e^{i(\delta - \omega t)}$$

Let  $x_0 = -\frac{a}{\omega} \sin \delta$  and  $y_0 = \frac{a}{\omega} \cos \delta$  (change origin)

$$\vec{z} = \frac{ia}{\omega} e^{i(\delta - \omega t)} = \frac{ia}{\omega} [\cos(\delta - \omega t) - \frac{a}{\omega} \sin(\delta - \omega t)] = x(t) + iy(t)$$

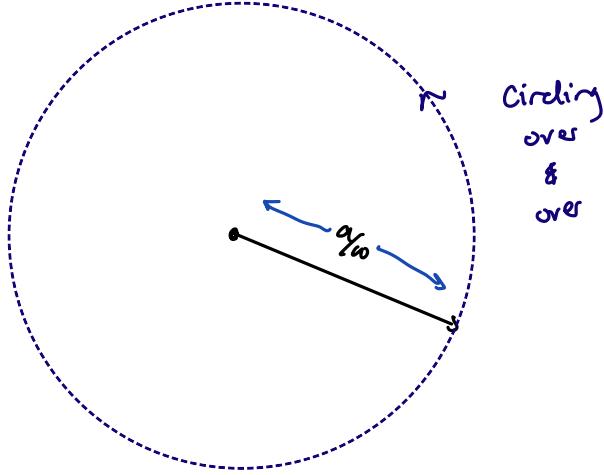
$$x(t) = -\frac{a}{\omega} \sin(\delta - \omega t)$$

$$y(t) = \frac{a}{\omega} \cos(\delta - \omega t)$$

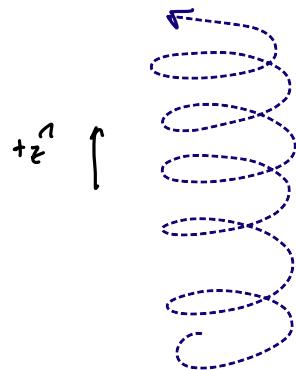
$$\vec{z}(t) = \frac{ia}{\omega} e^{i(\delta - \omega t)}$$

In the x-y plane, this motion is

Remember  $\ddot{z} = 0$



$$\Rightarrow z(t) = z_0 + v_0 z t$$



$$|\vec{v}_{transverse}| = |\eta| = |ae^{i(\delta - \omega t)}| = a = v$$

$$|R| = |\vec{z}| = \left| \frac{ia}{\omega} e^{i(\delta - \omega t)} \right| = \frac{a}{\omega} = \frac{v}{\omega} = \frac{mv}{qB}$$

End of Chapter 2!