

$$\int x^n dx = \frac{x^{n+1}}{n+1}$$

$$\int \frac{1}{x} dx = \log(x)$$

$$\frac{d}{dx} x^n = n \cdot x^{n-1}$$

NAME Integrals

CLASS

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Invigilator

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Marks

Remarks of the Examiner, if any

Signature of the Parent

1st kind $\rightarrow \int_0^{\infty} \cos x dx \Rightarrow$ Value of Integral, $a, b = \infty$

2nd kind $\rightarrow \int_0^{\infty} \frac{1}{x} dx \Rightarrow f(x)$ is not bounded ; 3rd kind = 1 + 2

$$\int_{-b}^b f(x) dx = \lim_{R_1 \rightarrow \infty} \int_{R_1}^{R_2} f(x) dx \quad \left| \quad \int_a^b f(x) dx = \lim_{\substack{E_1 \rightarrow 0^+ \\ E_2 \rightarrow 0^+}} \int_{a+E_1}^{b-E_2} f(x) dx \right.$$

Test - Integral (I) :-

$$\int_a^{\infty} \frac{1}{x^p} dx = \ln \left(\frac{R}{a} \right) \quad P=1$$

$$\frac{1}{1-P} \left[\frac{1}{R^{P-1}} - \frac{1}{a^{P-1}} \right] \quad P \neq 1$$

$P \leq 1 \rightarrow$ divergent

$P > 1 \rightarrow$ converging $\rightarrow \left[\frac{1}{P-1} \cdot \frac{1}{a^{P-1}} \right]$

Test Integral II :-

$$\int_a^b \frac{1}{(x-a)^p} dx$$

$P < 1 \rightarrow$ convergent

$$\frac{1}{1-P} \cdot \frac{1}{(b-a)^{P-1}}$$

$P > 1 \rightarrow$ divergent

Gamma and Beta :-

$$\Gamma(m, n) = \int_0^1 x^{m-1} (1-x)^{n-1} dx ; m > 0, n > 0 \Rightarrow \Gamma(m, n) = \Gamma(n, m)$$

$$\Gamma(n) = \int_0^{\infty} e^{-x} \cdot x^{n-1} dx \quad (n > 0)$$

$$\Rightarrow \boxed{\Gamma(n+1) = n \cdot \Gamma(n)}$$

$$\boxed{\Gamma(n) = \frac{\Gamma(n+1)}{n}}$$

$$\Gamma(1) = 1$$

$$\boxed{\Gamma(n+1) = n!}$$

$$\boxed{\Gamma(1/2) = \sqrt{\pi}}$$

$$\boxed{\Gamma(z) \cdot \Gamma(1-z) = \frac{\pi}{\sin(\pi z)}}$$

$$\boxed{\Gamma(m, n) = \frac{\Gamma(m) \cdot \Gamma(n)}{\Gamma(m+n)}}$$

$y = f(x) \Rightarrow f'(x) > 0 \Rightarrow$ increasing

$f'(x) < 0 \Rightarrow$ decreasing

$f''(x) > 0 \Rightarrow$ concave up

$f''(x) < 0 \Rightarrow$ concave down

$f''(x) = 0 \Rightarrow$ point of inflection

$$f(x) = \frac{x^n}{x^m} \Rightarrow$$

oblique asy :-

if $n = m + 1$

$$f(x) = \frac{x^2 + 1}{x^2 - 1} = x + 1 + \frac{2}{x-1}$$

$y = x + 1$ is an

oblique asym.

$$\lim_{x \rightarrow \infty} \frac{2}{x-1} \rightarrow 0$$

$$f(x) = e^{kx}$$

$y = 0$ hori

no vert.

curvature :-

$$K = \left| \frac{d\psi}{ds} \right|$$

$$y = f(x)$$

$$\frac{d\psi}{ds} = \frac{d\psi}{dx} \left| \frac{ds}{dx} \right|$$

$$K = \frac{f''(x)}{\left[1 + (f'(x))^2 \right]^{3/2}}$$

$$\Rightarrow f''(x) = \frac{d}{dx} (f'(x)) \Rightarrow f'(x) = \frac{dy}{dx}$$

$$\frac{df}{dx}, \frac{d^2f}{dx^2}$$

Radius of curvature = $\frac{1}{K}$

$$r = \frac{\left[1 + \left(\frac{dy}{dx} \right)^2 \right]^{3/2}}{\frac{d^2y}{dx^2}}$$

$$r = \frac{ds}{d\psi} = \frac{(1+y'^2)^{3/2}}{y''}$$

$$\frac{\partial z}{\partial u} = \frac{\partial z}{\partial x} \cdot \frac{\partial x}{\partial u} + \frac{\partial z}{\partial y} \cdot \frac{\partial y}{\partial u} \quad \text{assignment}$$

unit exist or not
x=0, y=0

along x-axis

$$x=y$$

$$x=y^2$$

total derivative (chain Rule) :-

$$\frac{du}{dt} = \frac{\partial u}{\partial x} \cdot \frac{\partial x}{\partial t} + \frac{\partial u}{\partial y} \cdot \frac{\partial y}{\partial t}$$

$$u = f(x, y)$$

$$x = \phi(t); y = \psi(t)$$

$$u = f(\phi(t), \psi(t))$$

$$\frac{du}{dt}$$

special case

$$z = f(x, y); y = g(x) \rightarrow z = f(x, g(x))$$

$$\frac{dz}{dx} = \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} \cdot \frac{dy}{dx}$$

did book

Implicit differentiation :-

$$f(x, y) = 0$$

$$0 = f_x + f_y \frac{dy}{dx}$$

$$\frac{dy}{dx} = -\frac{f_x}{f_y} \rightarrow \frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}$$

$$(y = f(x)) \rightarrow \text{explicit} \quad \frac{dy}{dx}$$

$$(f(x, y) = 0) \rightarrow \text{implicit} \quad \frac{dy}{dx}$$

$$J\left(\frac{u, v}{x, y}\right) = \frac{\partial(u, v)}{\partial(x, y)} =$$

$$\begin{vmatrix} \frac{\partial u}{\partial x} & \frac{\partial u}{\partial y} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{vmatrix}$$

maxima, minima, saddle :-

$$\text{critical points} \Rightarrow \frac{\partial f}{\partial x} = 0, \frac{\partial f}{\partial y} = 0$$

H = Hessian matrix

$$D = f_{xx} \cdot f_{yy} - f_{xy}^2 \text{ (discriminant)}$$

$$H = \begin{bmatrix} f_{xx} & f_{xy} \\ f_{yx} & f_{yy} \end{bmatrix}$$

let (a, b) \rightarrow critical point

If $D > 0$ and $f_{xx}(a, b) > 0$ then (a, b) minima

$D > 0$ and $f_{xx}(a, b) < 0$ then maxima

$D < 0$ then (a, b) saddle point

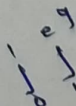
$$f'(x) = 0$$

$$f''(x) < 0$$

maxima

$$f''(x) > 0$$

minima



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$$g(x, y) = c$$

$$f(x, y) = x + y$$

$$g(x, y) = x^2 + y^2 = 1$$

Lagrange's Method :-

$$\frac{\partial h}{\partial x} - \lambda \frac{\partial g}{\partial x} = 0 \quad \left. \begin{array}{l} \text{find } (x, y) \end{array} \right\}$$

$$\frac{\partial h}{\partial y} - \lambda \frac{\partial g}{\partial y} = 0$$

$$x^2 + y^2 = 1$$

$$x = \pm \sqrt{1 - y^2}$$

$$f_x = 1, f_y = 1$$

$$g_x = 2x, g_y = 2y$$

$$1 = \lambda(2x)$$

$$1 = \lambda(2y) \Rightarrow x = y$$

vector-calculus

Directional Derivative = D_uf

$$\vec{u} = (u_1, u_2)$$

$$D_{\vec{u}}f = \frac{\partial f}{\partial x} u_1 + \frac{\partial f}{\partial y} u_2$$

Gradient

$$\text{grad } f = \nabla f = \frac{\partial f}{\partial x} \hat{i} + \frac{\partial f}{\partial y} \hat{j}$$

$$D_{\vec{u}}f = (\text{grad } f) \cdot \vec{u}$$

$$|\text{grad } f| = \sqrt{f_x^2 + f_y^2}$$

Divergence

$$F(x, y, z) = P \hat{i} + Q \hat{j} + R \hat{k} \Rightarrow \nabla = \frac{\partial}{\partial x} \hat{i} + \frac{\partial}{\partial y} \hat{j} + \frac{\partial}{\partial z} \hat{k}$$

$$\text{Divergence } F = \nabla \cdot F$$

$$= \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z}$$

(→) Rotating clock wise

(→) No Rotating

$$\text{curl } F = \vec{\nabla} \times \vec{F}$$

$$= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ P & Q & R \end{vmatrix}$$

Laplacian operator

$$\Delta f = \nabla^2 f = \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2}$$

consider \vec{F}

$$\text{If } \vec{\nabla} \times \vec{F} = \vec{0} \Rightarrow \vec{F} \text{ irrotational (or) curl free}$$

$$\text{If } \vec{\nabla} \cdot \vec{F} = 0 \text{ then } \vec{F} \text{ solenoidal divergence free}$$

$$\text{If } \vec{F} = \vec{\nabla} \phi \quad \vec{F} \text{ conservative and } \phi \text{ is scalar pot. of } \vec{F}$$

$$\frac{ds}{dx} = \sqrt{1 + \left(\frac{dy}{dx}\right)^2}$$

s → length of the curve

$$\frac{ds}{dt} = \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2 + \left(\frac{dz}{dt}\right)^2}$$

Line Integral :-

$$\text{work done} = \vec{F} \cdot d\vec{r}$$

$$\vec{F} = F_x \hat{i} + F_y \hat{j} + F_z \hat{k}$$

$$d\vec{r} = dx \hat{i} + dy \hat{j} + dz \hat{k}$$

$$\int \vec{F} \cdot d\vec{r} = \int F_x dx + F_y dy + F_z dz$$

$$\vec{F} = y^2 z^3 \hat{i} + 2xy z^3 \hat{j} + 3xy^2 z^2 \hat{k}$$

$$C: x = t^2, y = t, z = t^2$$

$$(0,0,0) \rightarrow (1,1,1)$$

$$\int_C y^2 z^3 dx + 2xy z^3 dy + 3xy^2 z^2 dz$$

$$dx = 2t dt \quad dy = dt \quad dz = 2t dt$$

Green's Theorem:

$$\oint_C f(x,y) dx + g(x,y) dy = \iint_D \left(\frac{\partial g}{\partial x} - \frac{\partial f}{\partial y} \right) dx dy$$