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Index Construction

- Simple and Distributed Approaches

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> Topics to be covered

➤ Recap:

- Phrase Queries
- Proximity Search
- Permuterm Index
- Bi-gram Indexes
- Spell Correction
- Noisy Channel Modelling

➤ Index Construction

- BSBI
- SPIMI
- Distributed Indexing
 - An Illustration

➤ More topics to come up ... Stay tuned ...!!

Recap: Information Retrieval

- **Information Retrieval (IR)** is finding material (usually documents) of an unstructured nature (usually text) that satisfies an information need from within large collections (usually stored on computers).
- During these days, we frequently think first of web search, but there are many other cases:
 - E-mail search
 - Searching your laptop
 - Corporate knowledge bases
 - Legal information retrieval
 - Images / Patent / Transportation Related Searches
 - and so on . . .

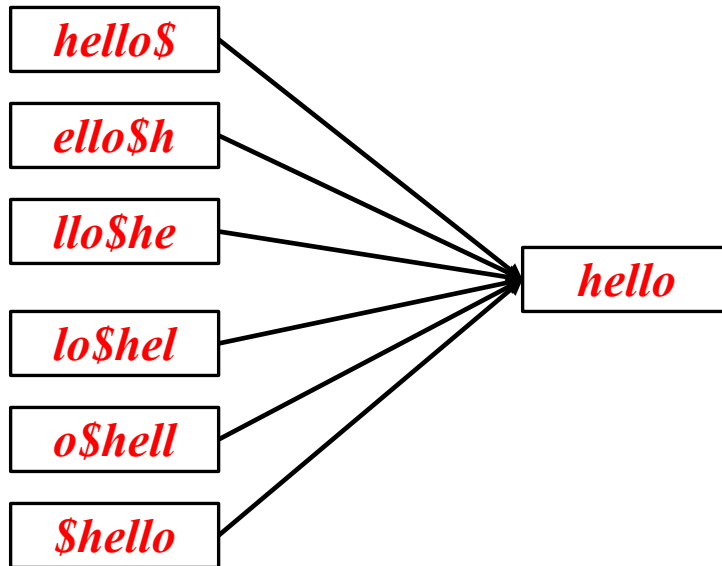
Recap: Wild-card queries: *

- **mon***: find all docs containing any word beginning with “mon”.
 - Easy with binary tree (or B-tree) dictionary: retrieve all words in range: **mon** \leq **w** $<$ **moo**
 - ***mon**: find words ending in “mon”: harder
 - Maintain an additional B-tree for terms backwards.
- Can retrieve all words in range: **nom** \leq **w** $<$ **non**

From this, how can we enumerate all terms meeting the wild-card query **pro*cent** ?

Recap: Permuterm index

- Add a \$ to the end of each term
- Rotate the resulting term and index them in a B-tree
- For term hello, index under:
 - **hello\$, ello\$h, llo\$he, lo\$hel, o\$hell, \$hello**where \$ is a special symbol.



**Empirically, dictionary
quadruples in size**

Recap: Spelling Tasks

- Spelling Error Detection
- Spelling Error Correction:
 - Autocorrect
 - hte→the
 - Suggest a correction
 - Suggestion lists

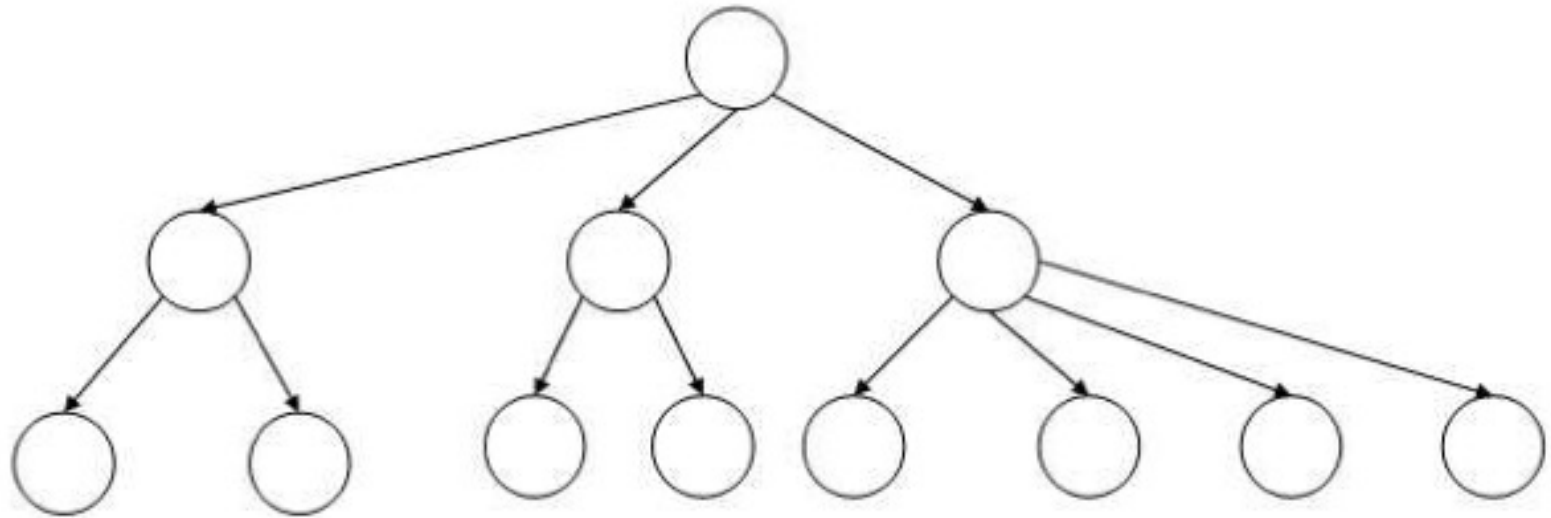
Dictionary array of fixed-width entries

term	document frequency	pointer to postings list
a	656,265	→
aachen	65	→
...
zulu	221	→

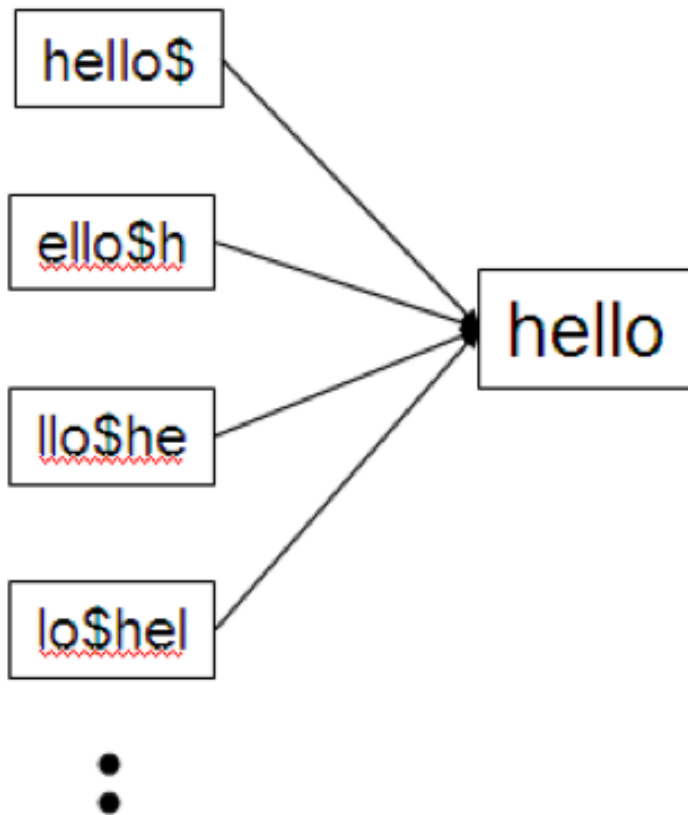
space needed: 20 bytes 4 bytes 4 bytes

Thanks to Manning et al for their slides used in this section. We gratefully acknowledge this support to the IR community

B-tree for looking up entries in array



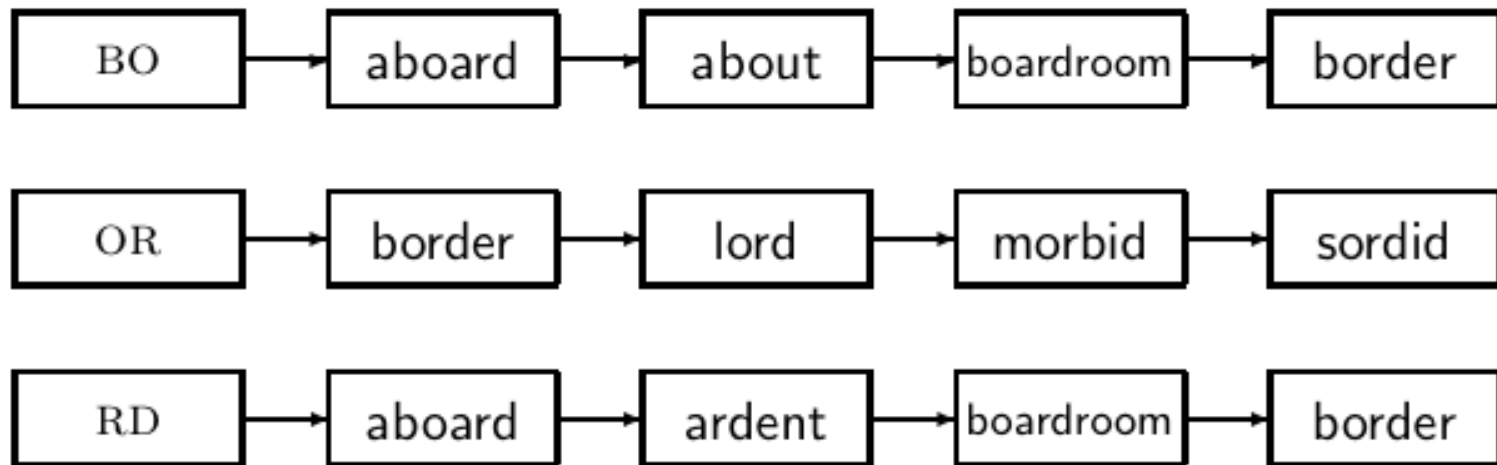
Wildcard queries using a permuterm index



Queries:

- For X, look up X\$
- For X*, look up X*\$
- For *X, look up X\$*
- For *X*, look up X*
- For X*Y, look up Y\$X*

k-gram indexes for spelling correction: bordroom



Levenshtein distance for spelling correction

LEVENSHTEINDISTANCE(s_1, s_2)

```
1  for  $i \leftarrow 0$  to  $|s_1|$ 
2  do  $m[i, 0] = i$ 
3  for  $j \leftarrow 0$  to  $|s_2|$ 
4  do  $m[0, j] = j$ 
5  for  $i \leftarrow 1$  to  $|s_1|$ 
6  do for  $j \leftarrow 1$  to  $|s_2|$ 
7      do if  $s_1[i] = s_2[j]$ 
8          then  $m[i, j] = \min\{m[i-1, j] + 1, m[i, j-1] + 1, m[i-1, j-1]\}$ 
9          else  $m[i, j] = \min\{m[i-1, j] + 1, m[i, j-1] + 1, m[i-1, j-1] + 1\}$ 
10 return  $m[|s_1|, |s_2|]$ 
```

Operations: insert, delete, replace, copy

Exercise: Understand Peter Norvig's spelling corrector

```
import re, collections
def words(text): return re.findall('[a-z]+', text.lower())
def train(features):
    model = collections.defaultdict(lambda: 1)
    for f in features:
        model[f] += 1
    return model
NWORDS = train(words(file('big.txt').read()))
alphabet = 'abcdefghijklmnopqrstuvwxyz'
def edits1(word):
    splits      = [(word[:i], word[i:]) for i in range(len(word) + 1)]
    deletes     = [a + b[1:] for a, b in splits if b]
    transposes  = [a + b[1] + b[0] + b[2:] for a, b in splits if len(b) > 1]
    replaces    = [a + c + b[1:] for a, b in splits for c in alphabet if b]
    inserts     = [a + c + b      for a, b in splits for c in alphabet]
    return set(deletes + transposes + replaces + inserts)
def known_edits2(word):
    return set(e2 for e1 in edits1(word) for e2 in
        edits1(e1) if e2 in NWORDS)
def known(words): return set(w for w in words if w in NWORDS)
def correct(word):
    candidates = known([word]) or known(edits1(word)) or
        known_edits2(word) or [word]
    return max(candidates, key=NWORDS.get)
```

Hardware basics

- Many design decisions in information retrieval are based on hardware constraints.
- We begin by reviewing hardware basics that we'll need in this course.

Hardware basics

- Access to data is much faster in memory than on disk. (roughly a factor of 10)
- Disk seeks are “idle” time: No data is transferred from disk while the disk head is being positioned.
- To optimize transfer time from disk to memory: one large chunk is faster than many small chunks.
- Disk I/O is block-based: Reading and writing of entire blocks (as opposed to smaller chunks). Block sizes: 8KB to 256 KB
- Servers used in IR systems typically have several GB of main memory, sometimes tens of GB, and TBs or 100s of GB of disk space.
- Fault tolerance is expensive: It's cheaper to use many regular machines than one fault tolerant machine.

Some Stats (ca. 2008)

symbol	statistic	value
s	average seek time	5 ms = 5×10^{-3} s
b	transfer time per byte	$0.02 \mu\text{s} = 2 \times 10^{-8}$ s
	processor's clock rate	10^9 s^{-1}
P	lowlevel operation (e.g., compare & swap a word)	$0.01 \mu\text{s} = 10^{-8}$ s
	size of main memory	several GB
	size of disk space	1 TB or more

RCV1 Collection

- Shakespeare's collected works are not large enough for demonstrating many of the points
- As an example for applying scalable index construction algorithms, we will use the Reuters RCV1 collection.
- English newswire articles sent over the wire in 1995 and 1996 (one year).

A Reuters RCV1 Document



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Extreme conditions create rare Antarctic clouds

Tue Aug 1, 2006 3:20am ET

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SYDNEY (Reuters) - Rare, mother-of-pearl colored clouds caused by extreme weather conditions above Antarctica are a possible indication of global warming, Australian scientists said on Tuesday.

Known as nacreous clouds, the spectacular formations showing delicate wisps of colors were photographed in the sky over an Australian

Reuters RCV1 Statistics

N	documents	800,000
L	tokens per document	200
M	terms (= word types)	400,000
	bytes per token (incl. spaces/punct.)	6
	bytes per token (without spaces/punct.)	4.5
T	bytes per token (= word type)	7.5
	non-positional postings	100,000,000

Exercise: Average frequency of a term (how many tokens)?
4.5

bytes per word token vs. 7.5 bytes per word type: why the difference? How many positional postings?



Index construction: Sort postings in memory

term	docID		term	docID
i	1		ambitious	2
did	1		be	2
enact	1		brutus	1
julius	1		brutus	2
caesar	1		capitol	1
i	1		caesar	1
was	1		caesar	2
killed	1		caesar	2
i'	1		did	1
the	1		enact	1
capitol	1		hath	1
brutus	1		i	1
killed	1		i	1
me	1	⇒	i'	1
so	2		it	2
let	2		julius	1
it	2		killed	1
be	2		killed	1
with	2		let	2
caesar	2		me	1
the	2		noble	2
noble	2		so	2
brutus	2		the	1
hath	2		the	2
told	2		told	2
you	2		you	2
caesar	2		was	1
was	2		was	2
ambitious	2		with	2

Sort-based index construction

- As we build index, we parse docs one at a time.
- The final postings for any term are incomplete until the end.
- Can we keep all postings in memory and then do the sort in-memory at the end?
- No, not for large collections
- At 10–12 bytes per postings entry, we need a lot of space for large collections.
- $T = 100,000,000$ in the case of RCV1: we can do this in memory on a typical machine in 2010.
- But in-memory index construction does not scale for large collections.
- Thus: We need to store intermediate results on disk.

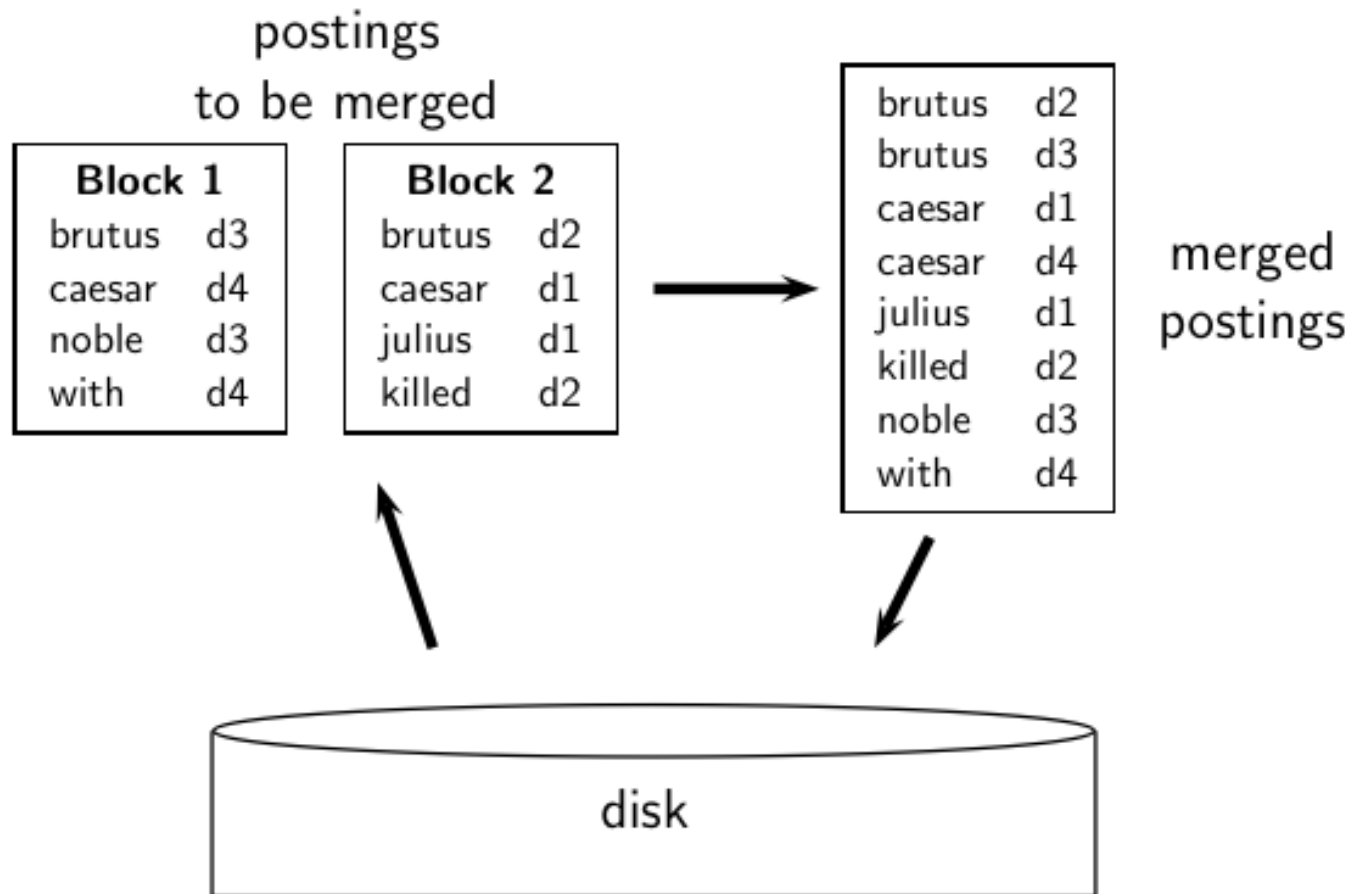
Same algorithm for disk?

- Can we use the same index construction algorithm for larger collections, but by using disk instead of memory?
- No: Sorting $T = 100,000,000$ records on disk is too slow – too many disk seeks.
- We need an external sorting algorithm.

“External” sorting algorithm (using few disk seeks)

- We must sort $T = 100,000,000$ non-positional postings.
- Each posting has size 12 bytes (4+4+4: termID, docID, document frequency).
- Define a block to consist of 10,000,000 such postings
- We can easily fit that many postings into memory.
- We will have 10 such blocks for RCV1.
- Basic idea of algorithm:
- For each block: (i) accumulate postings, (ii) sort in memory, (iii) write to disk
- Then merge the blocks into one long sorted order.

Merging two blocks



Blocked Sort-Based Indexing

BSBINDEXCONSTRUCTION()

```
1   $n \leftarrow 0$ 
2  while (all documents have not been processed)
3  do  $n \leftarrow n + 1$ 
4       $block \leftarrow \text{PARSENEXTBLOCK}()$ 
5       $\text{BSBI-INVERT}(block)$ 
6       $\text{WRITEBLOCKTODISK}(block, f_n)$ 
7   $\text{MERGEBLOCKS}(f_1, \dots, f_n; f_{\text{merged}})$ 
```

➤ **Key decision:** What is the size of one block?

Problem with sort-based algorithm

- Our assumption was: we can keep the dictionary in memory.
- We need the dictionary (which grows dynamically) in order to implement a term to termID mapping.
- Actually, we could work with term,docID postings instead of termID,docID postings . . .
- . . . but then intermediate files become very large. (We would end up with a scalable, but very slow index construction method.)

Single-pass in-memory indexing

- Abbreviation: SPIMI
- Key idea 1: Generate separate dictionaries for each block – no need to maintain term-termID mapping across blocks
- Key idea 2: Don't sort. Accumulate postings in postings lists as they occur
- With these two ideas we can generate a complete inverted index for each block.
- These separate indexes can then be merged into one big index.

SPIMI-Invert

SPIMI-INVERT(*token_stream*)

```
1  output_file ← NEWFILE()
2  dictionary ← NEWHASH()
3  while (free memory available)
4  do token ← next(token_stream)
5      if term(token) ∉ dictionary
6          then postings_list ← ADDTODICTIONARY(dictionary,term(token))
7          else postings_list ← GETPOSTINGSLIST(dictionary,term(token))
8          if full(postings_list)
9              then postings_list ← DOUBLEPOSTINGSLIST(dictionary,term(token))
10         ADDTOPOSTINGSLIST(postings_list,docID(token))
11  sorted_terms ← SORTTERMS(dictionary)
12  WRITEBLOCKTODISK(sorted_terms,dictionary,output_file)
13  return output_file
```

Merging of blocks is analogous to BSBI.

SPIMI: Compression

- Compression makes SPIMI even more efficient.
- Compression of terms
- Compression of postings

Exercise: Time 1 machine needs for Google size collection

BSBINDEXCONSTRUCTION()

```

1   $n \leftarrow 0$ 
2  while (all documents have not been processed)
3  do  $n \leftarrow n + 1$ 
4     $block \leftarrow \text{PARSENEXTBLOCK}()$ 
5     $\text{BSBI-INVERT}(block)$ 
6     $\text{WRITEBLOCKTODISK}(block, f_n)$ 
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```

symbol	statistic	value
s	average seek time	5 ms = 5×10^{-3} s
b	transfer time per byte	$0.02 \mu\text{s} = 2 \times 10^{-8}$ s
	processor's clock rate	10^9 s^{-1}
p	lowlevel operation	$0.01 \mu\text{s} = 10^{-8}$ s
	number of machines	1
	size of main memory	8 GB
	size of disk space	unlimited
N	documents	10^{11} (on disk)
L	avg. # word tokens per document	10^3
M	terms (= word types)	10^8
	avg. # bytes per word token (incl. spaces/punct.)	6
	avg. # bytes per word token (without spaces/punct.)	4.5
	avg. # bytes per term (= word type)	7.5

Hint: You have to make several simplifying assumptions – that's

ok, just state them clearly.

Distributed indexing

- For web-scale indexing (don't try this at home!): must use a distributed computer cluster
- Individual machines are fault-prone.
 - Can unpredictably slow down or fail.
- How do we exploit such a pool of machines?

Google data centers (2007 estimates; Gartner)

- Google data centers mainly contain commodity machines.
- Data centers are distributed all over the world.
- 1 million servers, 3 million processors/cores
- Google installs 100,000 servers each quarter.
- Based on expenditures of 200–250 million dollars per year
- This would be 10% of the computing capacity of the world!
- If in a non-fault-tolerant system with 1000 nodes, each node has 99.9% uptime, what is the uptime of the system (assuming it does not tolerate failures)?
- Answer: 63%
- Suppose a server will fail after 3 years. For an installation of 1 million servers, what is the interval between machine failures?
- Answer: less than two minutes

Distributed Indexing

- Maintain a master machine directing the indexing job – considered “safe”
- Break up indexing into sets of parallel tasks
- Master machine assigns each task to an idle machine from a pool.

Parallel tasks

- We will define two sets of parallel tasks and deploy two types of machines to solve them:
- Parsers
- Inverters
- Break the input document collection into splits (corresponding to blocks in BSBI/SPIMI)
- Each split is a subset of documents.

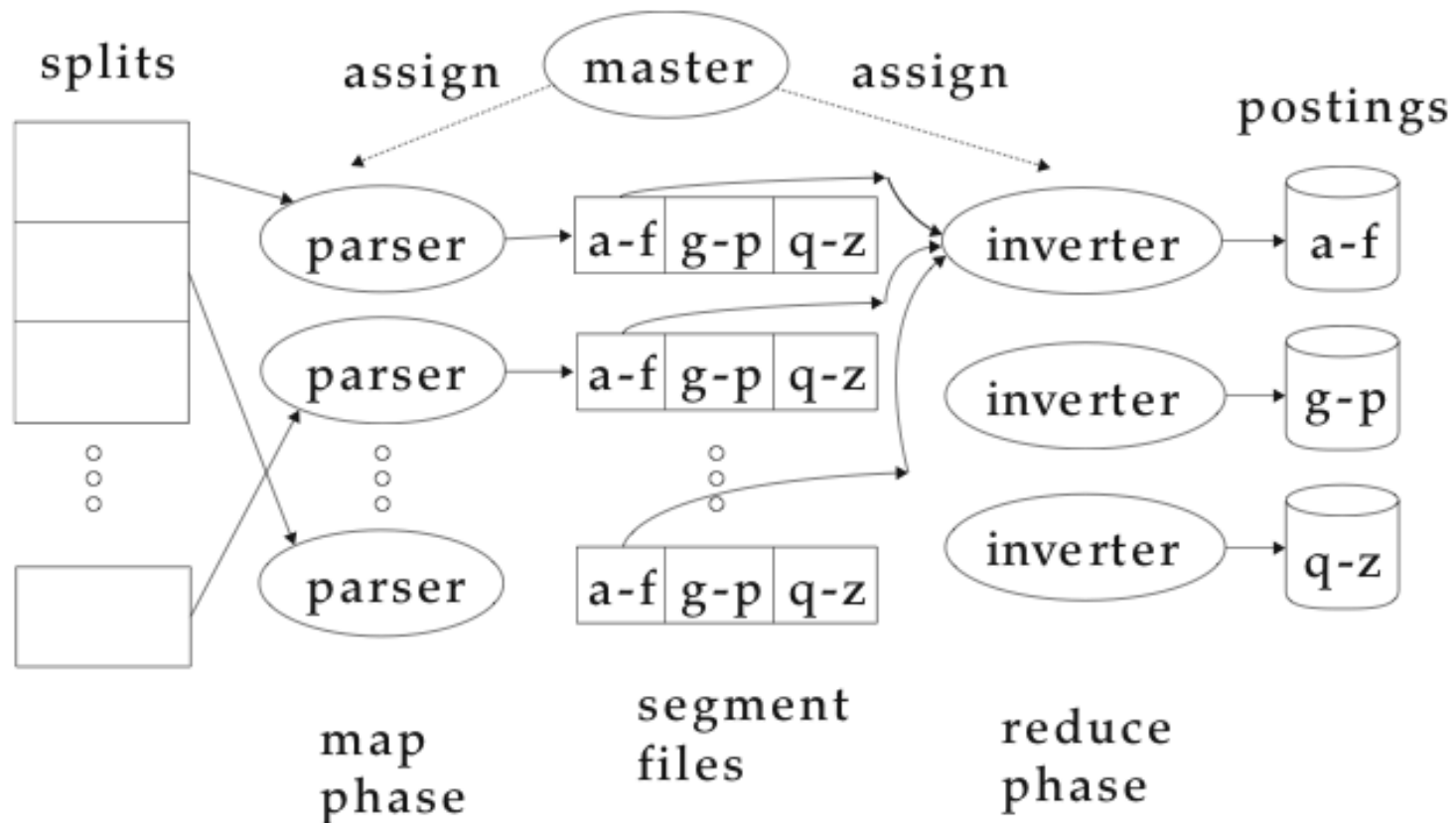
Parsers

- Master assigns a split to an idle parser machine.
- Parser reads a document at a time and emits (term,docID)-pairs.
- Parser writes pairs into j term-partitions.
- Each for a range of terms' first letters
- E.g., a-f, g-p, q-z (here: $j = 3$)

Inverters

- An inverter collects all (term,docID) pairs (= postings) for one term-partition (e.g., for a-f).
- Sorts and writes to postings lists

Data flow



MapReduce

- The index construction algorithm we just described is an instance of MapReduce
- MapReduce is a robust and conceptually simple framework for distributed computing . . .
- . . .without having to write code for the distribution part.
- The Google indexing system (ca. 2002) consisted of a number of phases, each implemented in MapReduce.
- Index construction was just one phase.
- Another phase: transform term-partitioned into document-partitioned index.

Index construction in MapReduce

Schema of map and reduce functions

map: input $\rightarrow \text{list}(k, v)$
reduce: $(k, \text{list}(v)) \rightarrow \text{output}$

Instantiation of the schema for index construction

map: web collection $\rightarrow \text{list}(\text{termID}, \text{docID})$
reduce: $(\langle \text{termID}_1, \text{list}(\text{docID}) \rangle, \langle \text{termID}_2, \text{list}(\text{docID}) \rangle, \dots) \rightarrow (\text{postings_list}_1, \text{postings_list}_2, \dots)$

Example for index construction

map: $d_2 : C \text{ DIED}, d_1 : C \text{ CAME}, C \text{ C'ED} \rightarrow (\langle C, d_2 \rangle, \langle \text{DIED}, d_2 \rangle, \langle C, d_1 \rangle, \langle \text{CAME}, d_1 \rangle, \langle C, d_1 \rangle, \langle \text{C'ED}, d_1 \rangle)$
reduce: $(\langle C, (d_2, d_1, d_1) \rangle, \langle \text{DIED}, (d_2) \rangle, \langle \text{CAME}, (d_1) \rangle, \langle \text{C'ED}, (d_1) \rangle) \rightarrow (\langle C, (d_1:2, d_2:1) \rangle, \langle \text{DIED}, (d_2:1) \rangle, \langle \text{CAME}, (d_1:1) \rangle, \langle \text{C'ED}, (d_1:1) \rangle)$

Summary

In this class, we focused on:

(a) **Recap: Positional Indexes**

- Wild card Queries
- Spelling Correction
- Noisy Channel modelling for Spell Correction

(b) **Various Indexing Approaches**

- Block Sort based Indexing Approach
- Single Pass In Memory Indexing Approach
- Distributed Indexing using Map Reduce
- Examples and illustration

Summary

In this class, we focused on:

(a) Recap: Positional Indexes

- i. Positional Index Size
- ii. Wild card Queries
- iii. Permuterm index

(b) Spelling Correction

- i. Types of Spelling Correction
- ii. Noisy Channel modelling for Spell Correction
- iii. Spelling Suggestions

Acknowledgements

Thanks to ALL RESEARCHERS:

- Modern Information Retrieval Baeza-Yates and Ribeiro-Neto, Addison Wesley, 1999.
- **Introduction to Information Retrieval Manning, Raghavan and Schutze, Cambridge University Press, 2008.**
- Search Engines Information Retrieval in Practice W. Bruce Croft, D. Metzler, T. Strohman, Pearson, 2009.
- Information Retrieval Implementing and Evaluating Search Engines Stefan Büttcher, Charles L. A. Clarke and Gordon V. Cormack, MIT Press, 2010.
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- **Prof. Mandar Mitra, Indian Statistical Institute, Kolkatata (<https://www.isical.ac.in/~mandar/>)**

Assistance

- You may post your questions to me at any time
- You may meet me in person on available time or with an appointment
- You may ask for one-to-one meeting

Best Approach

- You may leave me an email any time
(email is the best way to reach me faster)



Questions It's Your Time



Contact Information

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