SUPPORT VECTOR MACHINES

A SUPPORT VECTOR MACHINE IS USED TO BUILD BINARY CLASSIFIERS POINTS: ALL

CATEC LIES: SPAMORHAM

THIS MEANS THAT GIVEN ASSET OF PAIRS, A SUPPORT VECTOR MACHINE WILL LASS THOSE POINTS INTO 2 CATEGORIES

IN ADDITION, SUPPORT VECTOR MACHINES MAKE THEIR CLASSIFICATION DECISION ON THE BASIS OF A "LINEAR FUNCTION" OF THE POINT'S COORDINATES

LASTLY, SVICTINVOLVE AN EXPLICIT TRAINING STAGE WHEN THE MODEL "LEARNS" FROM A SET OF TRAINING DATA

IF A POINT IT X = (X1, X2, X3, ...Xn)A LINEAR FUNCTION IS SOMETHING LIKE

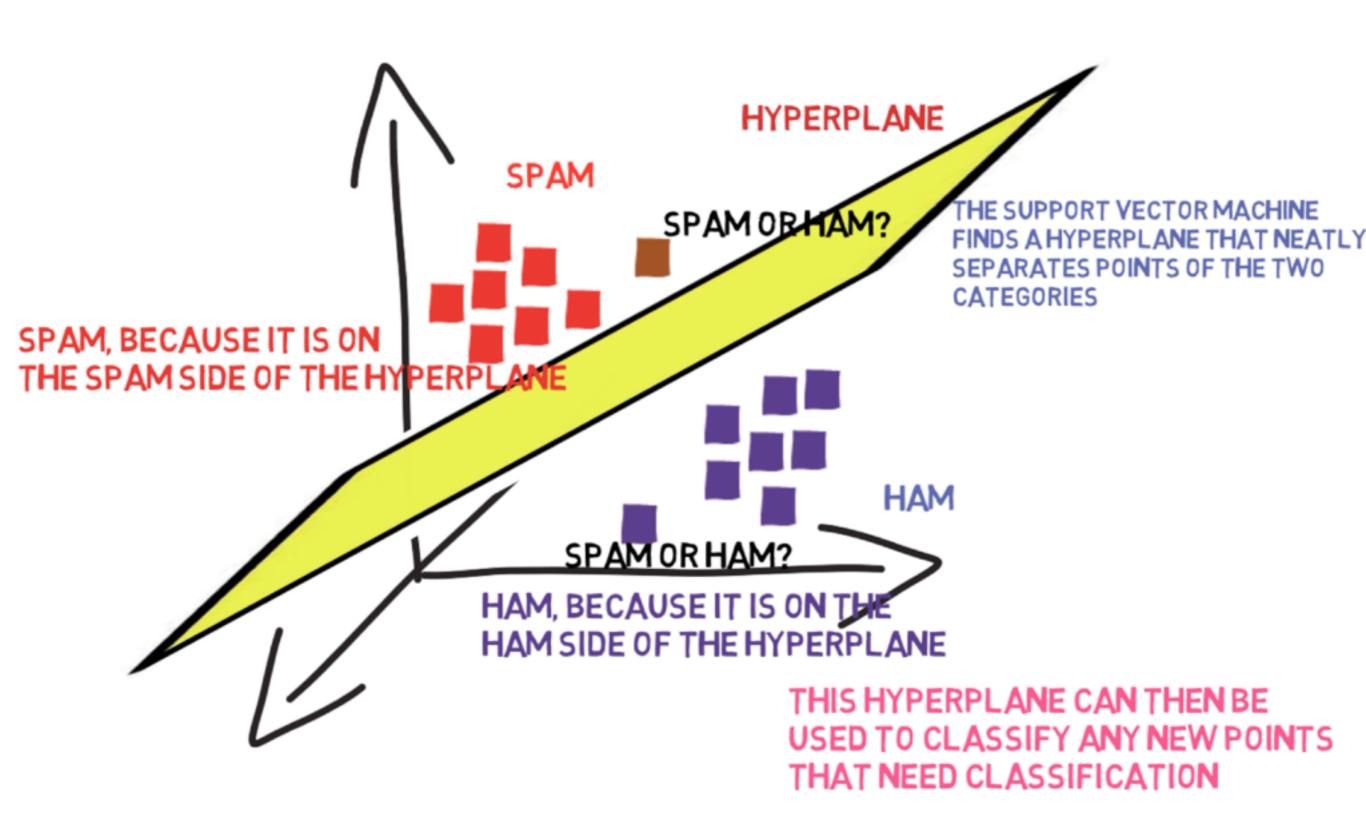
f(X) = aX1 + aX2 + cX3 + zXn THE SUPPORT VEC

THE SUPPORT VECTOR MAINHINE WILL RUN A TEST LIKE IF F(X) > 0, EMAIL IS SPAM, ELSE EVAIL IS HAM

ALSO, SUPPORT VECTOR MACHINES DO SP.
NOT INVOLVE EXPLICIT ASSUMPTIONS ABOUT
THE PROBABILITY DISTRIBUTIONS OF THE POINTS

(NAIVE RAYES CLASSIFIERS, FOR INSTANCE, ASSUME THAT THE DISTRIBUTIONS OF DIFFERENT FEATURES ARE INDEPENDENT)

"A SUPPORT VECTOR MACHINE
IS A SUPERVISED MACHINE-LEARNING
APPROACHUSED TO BUILD LINEAR,
NON-PROBABILISTIC BINARY) CLASSIFIERS"



FIRST OFF - WHAT IS A HYPERPLANE?

IN A VECTOR SPACE OF N DIMENSIONS, A HYPERPLANE IS A GEOMETRIC SHAPE I.E. A SET OF POINTS - WITH (N-1) DIMENSIONS AND 0 THICKNESS IN ONE DIMENSION

THE EQUATION OF THE SET OF POINTS DEFINING THE HYPERPLANE IS ALWAYS "LINEAR"

ALL POINTS ON THE PLANE WILL SATISFY THIS EQUATION

Ax + By + Cz = D

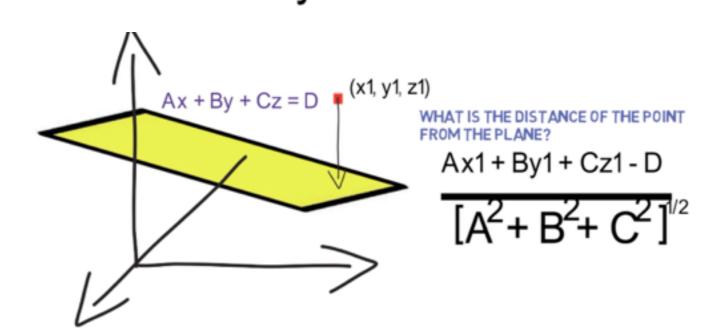
IS THE EQUATION OF A HYPERPLANE
IN 3D SPACE (I.E. A USUAL PLANE
OF THE SORT WE JUST DREW)

ALL POINTS ON ONE SIDE OF THE PLANE WILL SATISFY THE CONDITION

$$Ax + By + Cz > D$$

AND ALL POINTS ON THE OTHER SIDE WILL SATISFY Ax + By + Cz < D

THIS IS THE LINEAR EQUATION THAT THE SYMUSES TO CLASSIFY POINTS - WHICH IS WHY THE SYM IS A LINEAR CLASSIFIER



NOW COMING BACK TO OUR BASIC PROBLEM - HOW DOES THE SUPPORT VECTOR MACHINE FIND THE "BEST" HYPERPLANE TO SEPARATE THE 2 SETS OF POINTS?

THE SOLUTION IS CALLED

THE MAXIMUM
MARGIN HYPERPLANE

INTUITIVEL , THE "BEST" HYPERPLANE IS ONE T' AT:

MAXIMIZES SUM OF THE OBJECTIVE FUNCTION
DISTANCES OF THE NEAREST
POINTS ON EITHER SIDE

CONSTRAINTS

(WHILE STILL MAKING SURE THAT ALL POINTS OF ONE TYPE RE ON ONE SIDE OF THE PLANE AND ALL POINTS OF THE OTHER ARE ON THE OTHER)

THIS IS SET UP BEAUTIFULLY AS AN OPTIMIZATION PROBLEM

WE WON'T GO INTO THE DETAILS
OF HOW EXACTLY THAT OPTIMIZATION
PROBLEM IS FRAMED MATHEMATICALLY
OR SOLVED -

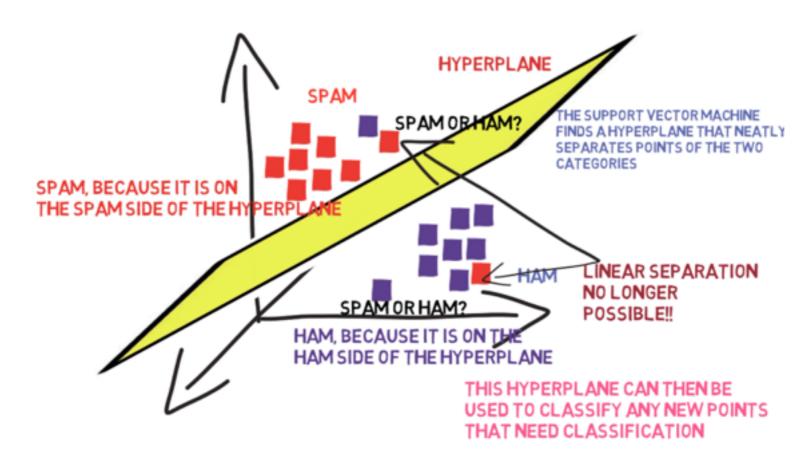
(IT TURNS OUT THE MAXIMUM MARGIN HYPERPLANE IS A FUNCTION OF THE SUPPORT VECTORS ALONE)

BUT SUFFICE IT TO SAY THAT IT CAN BE CONVERTED INTO A FAIRLY STANDARD QUADRATIC PROGRAMMING PROBLEM FOR WHICH STANDARD SOLUTION TECHNIQUES EXIST

THE MAXIMUM MARGIN HYPERPLANE IS FOUND - AND BTY

IS FOUND - AND BTW THE
"SUPPORT VECTORS" ARE
SIMPLY THE "NEAREST POINTS"
ON EACH SIDE - WHICH
"SUPPORT" THE HYPERPLANE

LINEARLY SEPARABLE?



THIS REQUIRES MORE MATHEMATICAL HEAVY LIFTING, BUT SOME GREAT SOUL HAS FOUND A WAY AROUND THIS:

THE SOFT MARGIN METHOD

WHICH FINDS A HYPERPLANE THAT DOES "AS CLEAN A SEPARATION AS POSSIBLE"

THIS METHOD ALSO ALLOWS MEASUREMENT
OF THE DEGREE OF MISCLASSIFICATION IN THE
TRAINING DATA

BUT THERE IS ACTUALLY WAY TO USE SUPPORT VECTOR MACHINES TO PERFORM NON-LINEAR CLASSIFICATION USING SOMETHING CALLED

THE KERNEL TRICK

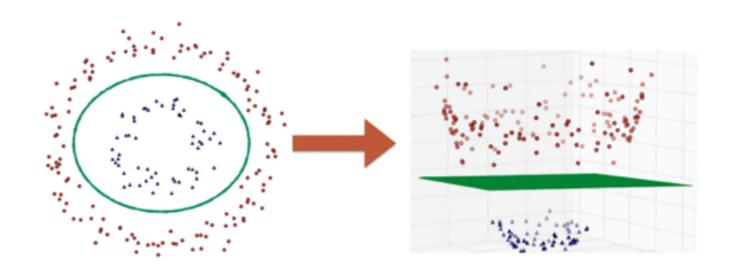
WHY DOES THIS MATTER TO US?

BECAUSE THE KERNEL TRICK IS A WAY
IN WHICH SUPPORT VECTOR MACHINES
CAN DO THEIR THING IN VERY VERY HIGH
DIMENSIONALITY SPACES

(THE KERNEL TRICK HELPS GET AROUND THE CURSE OF DIMENSIONALITY)

THE PROBLEM WITH THE LINEAR CLASSIFICATION SETUP IS THE NEED TO CALCULATE DOT PRODUCTS OF VECTORS WITH HUGE NUMBERS OF ELEMENTS

AKERNEL IS A FUNCTION THAT ALLOWS THE CLASSIFICATION TO BE DONE IMPLICITLY, I.E. WITHOUT ACTUALLY DEALING WITH THE FEATURE VECTOR IN ELEMENT-WISE OPERATIONS



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THE CLASSIFICATION TO BE DONE
IMPLICITLY, I.E. WITHOUT ACTUALLY
DEALING WITH THE FEATURE VECTOR
IN ELEMENT-WISE OPERATIONS

THE KERNEL IS SIMPLY A

(NON-LINEAR) FUNCTION THAT OPERATES
ON TWO POINTS - THIS
KERNEL FUNCTION IS USED
INSTEAD OF A DOT PRODUCT

NOTE THAT KERNEL FUNCTIONS
OPERATE IN A TRANSFORMED
FEATURE SPACE, WHICH CAN
BE OF FAR HIGHER DIMENSIONALITY
THAN THE ORIGINAL FEATURE SPACE

EVEN THOUGH THE DIMENSIONALITY
IN WHICH THEY OPERATE IS HIGHER,
THEY WILL FIND THE MAXIMUM MARGIN
HYPERPLANE MORE EASILY BECAUSE
OF THE KERNEL TRICK

THIS MAXIMUM MARGIN
HYPERPLANE IS IN THE
TRANSFORMED FEATURE
SPACE, AND IS LINEAR IN
THAT SPACE..

..ALTHOUGH IT MIGHT BE NON-LINEAR IN THE ORIGINAL FEATURE SPACE

THUS THE KERNEL TRICK ALSO ALLOWS A
WAY TO SOLVE PROBLEMS WHERE THE
DATA IS NOT LINEARLY SEPARABLE BY PROJECTING SUCH DATA INTO
HIGHER DIMENSION SPACE