ARTIFICIAL NEURAL NETWORKS

ARTIFICIAL NEURAL NETWORKS ARE A CLASS
OF MACHINE LEARNING TECHNIQUES THAT
WERE LOOSELY INSPIRED BY THE HUMAN
NERVOUS CYSTEM - "LOO

"WERE" BECAUSE THIS WAS THE CASE
WHEN THESE TECHNIQUES WERE FIRST
PROPOSED IN THE 1950S - MODERN
IMPLEMENTATIONS LOOK VERY MUCH
LIKE OTHER STATISTICAL TECHNIQUES WE
HAVE COVERED

"LOOSELY" BECAUSE THE COMPARISON
WITH THE HUMAN NERVOUS SYSTEM
HAS TENDED TO EVOKE IMPRESSIONS
OF SELF-AWARE, ALMOST HUMAN COMPUTERS,
THAT HAVE LITTLE TO DO WITH MOST OF
THESE TECHNIQUES

ARTIFICIAL NEURAL NETWORKS ARE ANALOGOUS
TO SUPPORT VECTOR MACHINES AND OTHER
LEARNING TECHNIQUES -

INDEED, THE FIRST AND PROTOTYPICAL EXAMPLE OF AN ARTIFICIAL NEURAL NETWORK IS

A PERCEPTRON

WHICH IS BASICALLY A BINARY CLASSIFIER - SIMILAR TO A SUPPORT VECTOR MACHINE, BUT LESS SOPHISTICATED

ARTIFICIAL NEURAL NETWORKS
HAVE HAD A HARD TIME LIVING
UP TO SEVERAL DECADES OF HYPE -

BUT ANNS ARE NOW FINDING USE
IN APPLICATIONS LIKE HANDWRITING
ANALYSIS AND COMPUTER VISION

PERCEPTRON

VERY CLOSELY RELATED TO A SUPPORT VECTOR MACHINE, WHICH WE ALREADY HAVE SPENT SOME TIME ON -

SUPPORT **VECTOR MACHINES**

A SUPPORT VECTOR MACHINE IS USED

ES: SPAM OR HAM

THIS MEANS THAT GIVEN ASSET OF P A SUPPORT VECTOR MACHINE WILL THOSE POINTS INTO 2 CATEGORIES

IN ADDITION, SUPPORT VECTOR MACHINES MAKE THEIR CLASSIFICATION DECISION ON THE BASIS OF A "LINEAR FUNCTION" OF THE POINT'S COORDINATES

INVOLVE AN EXPLICIT SET OF TRAINING

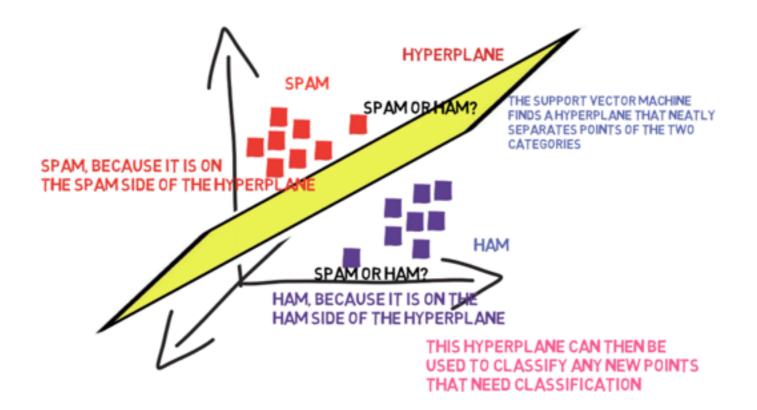
f(X) = aX1 + aX2 + cX3 + zXn THE SUPPORT VEG

IF F(X) > 0, EMAIL IS **RUN A TEST LIF** SPAM, ELSE E AIL IS HAM

ALSO, SUPPORT VECTOR MACHINES DO OT INVOLVE EXPLICIT ASSUMPTIONS AB PROBABILITY DISTRIBUTIONS OF THE P

> HAT THE DISTRIBUTIONS OF DIFFERENT RE INDEPENDENT

NON-PROBABILIS



FIRST OFF - WHAT IS A HYPERPLANE?

IN A VECTOR SPACE OF N DIMENSIONS, A HYPERPLANE IS A GEOMETRIC SHAPE I.E. A SET OF POINTS - WITH (N-1) DIMENSIONS AND 0 THICKNESS IN ONE DIMENSION

THE EQUATION OF THE SET OF POINTS DEFINING THE HYPERPLANE IS ALWAYS "LINEAR"

ALL POINTS ON THE PLANE WILL SATISFY THIS EQUATION

Ax + By + Cz = D

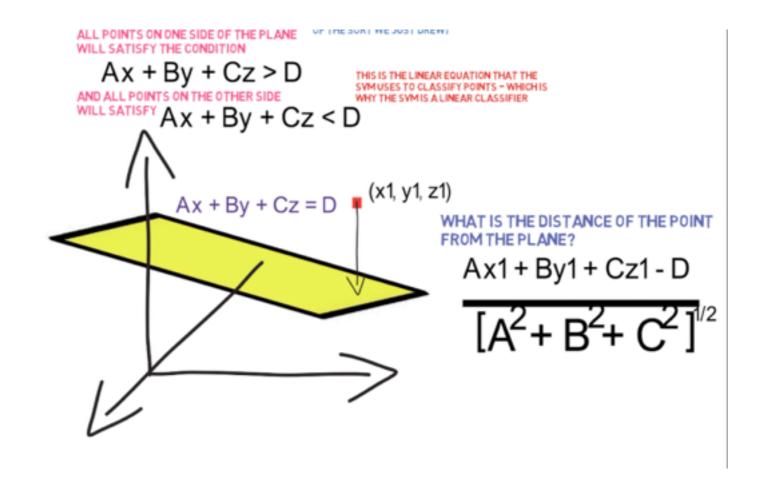
IS THE EQUATION OF A HYPERPLANE
IN 3D SPACE (I.E. A USUAL PLANE
OF THE SORT WE JUST DREW)

ALL POINTS ON ONE SIDE OF THE PLANE WILL SATISFY THE CONDITION

Ax + By + Cz > D

AND ALL POINTS ON THE OTHER SIDE WILL SATISFY Ax + By + Cz < D

THIS IS THE LINEAR EQUATION THAT THE SVM USES TO CLASSIFY POINTS - WHICH IS WHY THE SVM IS A LINEAR CLASSIFIER



NOW COMING BACK TO OUR BASIC PROBLEM - HOW DOES THE SUPPORT VECTOR MACHINE FIND THE "BEST" HYPERPLANE TO SEPARATE THE 2 SETS OF POINTS?

INTUITIVELY, THE "BEST" HYPERPLANE IS ONE THAT:

MAXIMIZES SUM OF THE OBJECTIVE FUNCTION
DISTANCES OF THE NEAREST
POINTS ON EITHER SIDE CONS

CONSTRAINTS

THIS IS SET UP BEAUTIFULLY AS AN OPTIMIZATION PROBLEM..

(WHILE STILL MAKING SURE THAT ALL POINTS OF ONE TYPE ARE ON ONE SIDE OF THE PLANE, AND ALL POINTS OF THE OTHER ARE ON THE OTHER)

NOW COMING BACK TO OUR BASIC PROBLEM - HOW DOES THE SUPPORT VECTOR MACHINE FIND THE "BEST" HYPERPLANE TO SEPARATE THE 2 SETS OF POINTS?

THE SOLUTION IS CALLED
THE MAXIMUM
MARGIN HYPERPLANE

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WE WON'T GO INTO THE DETAILS
OF HOW EXACTLY THAT OPTIMIZATION
PROBLEM IS FRAMED MATHEMATICALLY
OR SOLVED -

BUT SUFFICE IT TO SAY THAT IT CAN BE CONVERTED INTO A FAIRLY STANDARD QUADRATIC PROGRAMMING PROBLEM FOR WHICH STANDARD SOLUTION TECHNIQUES EXIST

THE MAXIMUM MARGIN HYPERPLANE IS FOUND - AND BTV

IS FOUND - AND BTW THE
"SUPPORT VECTORS" ARE
SIMPLY THE "NEAREST POINTS"
ON EACH SIDE - WHICH
"SUPPORT" THE HYPERPLANE

NOW ALL OF THIS WAS ABOUT SUPPORT VECTOR MACHINES, BUT ALSO APPLIED TO

PERCEPTRONS