

Motor.cpp File Reference

Source code for a class that implements a motor. [More...](#)

```
#include "Motor.h"
#include "avr/io.h"
#include <stdint.h>
#include "TC_Config.h"
#include "Pin.h"
```

Detailed Description

Source code for a class that implements a motor.

This class allows the user to implement a motor. The motor will respond to a duty cycle between -100 and 100, with a duty cycle of 0 causing the motor to coast regardless of direction. Each motor object of this class can controlled independently.

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