

Pre-projection theorem

Gram-Schmidt Process

ROB 501

Necmiye Ozay

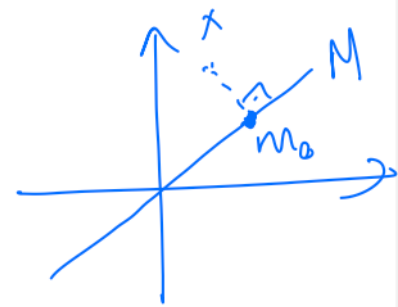
- Last time: Least squares (high level)

$$\hat{\alpha} = \operatorname{argmin}_{\alpha \in \mathbb{R}^2} ||Y - A\alpha||^2$$

$$\hat{\alpha} = (A^T A)^{-1} A^T Y$$

- We will build the proof but we need a few new concepts

Pre-projection Theorem



$(X, \mathbb{R}, \langle \cdot, \cdot \rangle)$ be an inner product space.

Let $M \subset X$ be a subspace, and $x \in X$.

Then,

(a) If $m_0 \in M$ s.t. $\|x - m_0\| \leq \|x - m\| \quad \forall m \in M$,

then m_0 is unique.

(b) A necessary and sufficient condition

$m_0 = \arg \min_{m \in M} d(x, m)$ for $m_0 \in M$ to be a minimizer of $\min_{m \in M} d(x, m)$ is that the error vector

$(x - m_0)$ is orthogonal to M , i.e. $(x - m_0) \perp M$

Proof: (\Rightarrow)

Claim b) Let $m_0 \in M$. If $\underbrace{\|x - m_0\| = d(x, M)}_p$,
then $\underbrace{(x - m_0) \perp M}_q$. $p \Rightarrow q$

Contrapositive: $\neg q \Rightarrow \neg p$

$x - m_0 \not\perp M \Rightarrow \|x - m_0\| > \underline{d(x, M)}$

$x - m_0 \not\perp M \Rightarrow \exists \bar{m} \in M$ s.t. $x - m_0 \not\perp \bar{m}$
 \parallel

$$\langle x - m_0, \bar{m} \rangle \neq 0$$

$\Rightarrow (\bar{m} \text{ is non-zero; i.e. } \|\bar{m}\| \neq 0)$

We can write:

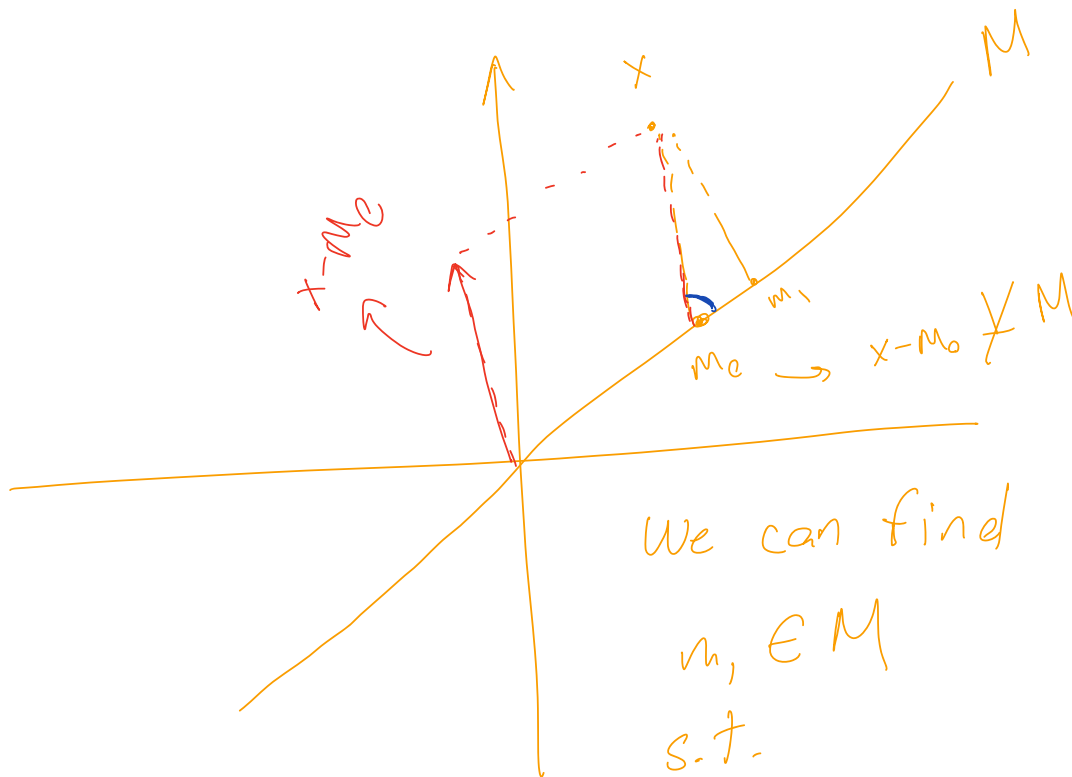
$$\left\langle x - m_0, \frac{\bar{m}}{\|\bar{m}\|} \right\rangle = \frac{1}{\|\bar{m}\|} \underbrace{\langle x - m_0, \bar{m} \rangle}_{\neq 0} \neq 0$$

Thus, without loss of generality,
we can assume $\|\bar{m}\| = 1$.

Define: $\beta = \langle x - m_0, \bar{m} \rangle \neq 0$

$$m_i = m_0 + \beta \bar{m} \in M$$

"To show $\|x - m_1\| < \|x - m_0\|$ "



$$\begin{aligned} \|x - m_1\|^2 &= \|x - m_0 - \beta \bar{m}\|^2 \\ &= \langle \underline{x - m_0}, \underline{x - m_0 - \beta \bar{m}} \rangle \\ &= \underbrace{\langle x - m_0, x - m_0 \rangle} + \langle -\beta \bar{m}, x - m_0 \rangle \\ &\quad + \langle x - m_0, -\beta \bar{m} \rangle + \langle -\beta \bar{m}, -\beta \bar{m} \rangle \\ &= \|x - m_0\|^2 - 2\beta \underbrace{\langle x - m_0, \bar{m} \rangle}_{\beta} + \beta^2 \\ &= \|x - m_0\|^2 - \beta^2 \quad (\text{since } \beta \neq 0, \beta^2 > 0) \end{aligned}$$

$$\Rightarrow \|x - m_1\|^2 < \|x - m_0\|^2$$

$\Rightarrow m_0$ cannot be a minimizer.

Other direction for Claim b (+ Claim a)

(\Leftarrow) If $x - m_0 \perp M$, then $\|x - m_0\| = d(x, M)$

(and m_0 is unique).

Proof: Assume $x - m_0 \perp M$ and $\overset{\text{let}}{m} \in M$

be arbitrary.

$$\|x - m\|^2 = \|\boxed{x - m_0} + \boxed{m_0 - m}\|^2$$

Since $(m_0 \in M, m \in M) \Rightarrow m_0 - m \in M$

Also $x - m_0 \perp M \Rightarrow (x - m_0) \perp (m_0 - m)$

by Pythagorean theorem:

$$\|x - m_0 + m_0 - m\|^2 = \|x - m_0\|^2 + \|m_0 - m\|^2$$

$$\therefore d(x, M)^2 = \inf_{m \in M} \|x - m\|^2$$

by our construction

$$= \inf_{m \in M} \|x - m_0\|^2 + \|m_0 - m\|^2$$

$m \in M$

$$= \|x - m_0\|^2 + \inf_{m \in M} \|m_0 - m\|^2$$

$$\geq 0$$

the smallest value
of this term is 0,
and it is only
achieved when $m = m_0$

$\Rightarrow m_0$ is the unique minimizer.

and for $m = m_0$, we get $d(x, M) = \|x - m_0\|$.

$$\boxed{(b')} = \langle \alpha_1 x_1 + \alpha_2 x_2, y \rangle_1$$

EECS 560 Handout:¹ Inner Product Spaces

$$= \alpha_1 \langle x_1, y \rangle + \alpha_2 \langle x_2, y \rangle$$

Definition: Let (X, \mathbb{C}) be a vector space. A function

$$\langle \cdot, \cdot \rangle: X \times X \rightarrow \mathbb{C}$$

is an **inner product** if

$$(a) \langle x, y \rangle = \overline{\langle y, x \rangle}$$

$$(b) \langle x, \alpha y_1 + \beta y_2 \rangle = \alpha \langle x, y_1 \rangle + \beta \langle x, y_2 \rangle$$

$$(c) \langle x, x \rangle \geq 0 \text{ for any } x \in X, \text{ and } \langle x, x \rangle = 0 \Leftrightarrow x = 0.$$

In the case of a real vector space (X, \mathbb{R}) , replace (a) with

$$(a'): \langle x, y \rangle = \langle y, x \rangle.$$

Examples:

$$(a) (\mathbb{C}^n, \mathbb{C}) \quad \langle x, y \rangle = \bar{x}^T y = \underbrace{x^*}_{\text{complex conjugate transpose}} y$$

complex conjugate transpose

$$(b) (\mathbb{R}^n, \mathbb{R}) \quad \langle x, y \rangle = x^T y$$

$$(c) X = C[a, b] = \text{space of continuous functions on } [a, b]$$

$$\langle f, g \rangle = \int_a^b f(t)g(t)dt$$

Theorem: [Cauchy-Schwarz Inequality] Suppose that $\mathcal{F} = \mathbb{R}$ or \mathbb{C} . Let $(X, \mathcal{F}, \langle \cdot, \cdot \rangle)$ be an **inner product space** (i.e. (X, \mathcal{F}) is a vector space and $\langle \cdot, \cdot \rangle$ is an inner product on X). Then, for all $x, y \in X$,

$$|\langle x, y \rangle| \leq \langle x, x \rangle^{1/2} \cdot \langle y, y \rangle^{1/2}.$$

Proof: See Chen, Second Edition, page 59. □

¹Courtesy of Jessie Grizzle.

Corollary: Let $(X, \mathcal{F}, \langle \cdot, \cdot \rangle)$ be an inner product space. Then

$$\|x\| := \langle x, x \rangle^{1/2}$$

is a norm on X .

Proof: The main thing to establish is the triangle inequality:

$$\|x + y\| \leq \|x\| + \|y\|.$$

This is equivalent to showing:

$$\|x + y\|^2 \leq \|x\|^2 + 2\|x\| \|y\| + \|y\|^2.$$

Brute force computation:

$$\begin{aligned} \|x + y\|^2 &= \langle x + y, x + y \rangle \\ &= \langle x + y, x \rangle + \langle x + y, y \rangle \\ &= \overline{\langle x, x + y \rangle} + \overline{\langle y, x + y \rangle} \\ &= \overline{\langle x, x \rangle} + \overline{\langle x, y \rangle} + \overline{\langle y, x \rangle} + \overline{\langle y, y \rangle} \\ &= \langle x, x \rangle + \langle y, x \rangle + \langle x, y \rangle + \langle y, y \rangle \\ &= \|x\|^2 + \|y\|^2 + \langle y, x \rangle + \langle x, y \rangle \\ &\leq \|x\|^2 + \|y\|^2 + |\langle y, x \rangle| + |\langle x, y \rangle| \\ &\leq \|x\|^2 + \|y\|^2 + 2 \underbrace{\langle x, x \rangle^{1/2}}_{\|x\|} \cdot \underbrace{\langle y, y \rangle^{1/2}}_{\|y\|}, \end{aligned}$$

where the last inequality is from Cauchy-Schwarz Inequality. □

Definition:

- (a) Two vectors x and y are **orthogonal** if $\langle x, y \rangle = 0$. Notation: $x \perp y$.
- (b) A **set of vectors** S is **orthogonal** if

$$\forall x, y \in S, \quad x \neq y, \quad \langle x, y \rangle = 0.$$

- (c) If in addition $\|x\| = 1 \quad \forall x \in S$, S is an *orthonormal set*.

Construct a new set $v = \{v_i \mid i=1, \dots, n\}$
 s.t. v is an ³orthogonal set.

HOW TO CONSTRUCT ORTHONORMAL SETS ?

Given

Gram-Schmidt Process: Two steps: orthogonalize, then normalize.

Let $\{y_i \mid i = 1, \dots, n\}$ be a *linearly independent* set of vectors. Define a set of vectors $\{v_i \mid i = 1, \dots, n\}$ by:

$$\begin{aligned} v_1 &= y_1 \\ v_2 &= y_2 - a_{21}v_1 \end{aligned}$$

and **choose** a_{21} so that $\langle v_1, v_2 \rangle = 0$.

$$\begin{aligned} \therefore 0 &= \langle v_1, v_2 \rangle = \langle v_1, y_2 - a_{21}v_1 \rangle \\ &= \langle v_1, y_2 \rangle - a_{21} \langle v_1, v_1 \rangle = 0 \\ \therefore a_{21} &= \frac{\langle v_1, y_2 \rangle}{\|v_1\|^2} \end{aligned} \quad a_{21} = \frac{\langle v_1, y_2 \rangle}{\|v_1\|^2}$$

Write $v_3 = y_3 - a_{31}v_1 - a_{32}v_2$

$$\begin{aligned} \rightarrow 0 &= \langle v_1, v_3 \rangle = \langle v_1, y_3 - a_{31}v_1 - a_{32}v_2 \rangle \\ &= \langle v_1, y_3 \rangle - a_{31} \langle v_1, v_1 \rangle - a_{32} \underbrace{\langle v_1, v_2 \rangle}_{=0} \end{aligned}$$

$$\therefore a_{31} = \frac{\langle v_1, y_3 \rangle}{\|v_1\|^2}$$

$$\begin{aligned} \rightarrow 0 &= \langle v_2, v_3 \rangle = \langle v_2, y_3 - a_{31}v_1 - a_{32}v_2 \rangle \\ &= \langle v_2, y_3 \rangle - a_{31} \underbrace{\langle v_2, v_1 \rangle}_{=0} - a_{32} \langle v_2, v_2 \rangle \end{aligned}$$

$$\therefore a_{32} = \frac{\langle v_2, y_3 \rangle}{\|v_2\|^2}$$

In general, one obtains:

$$v_k = y_k - \sum_{j=1}^{k-1} \underbrace{\frac{\langle v_j, y_k \rangle}{\|v_j\|^2}}_{a_{kj}} \cdot v_j.$$

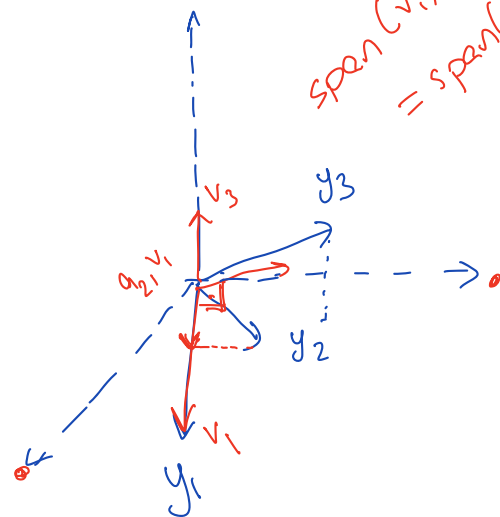
Now, $\{v_k \mid k = 1, \dots, n\}$ is an **orthogonal** set.

Define: $\tilde{v}_i = \frac{v_i}{\|v_i\|} \Rightarrow \{\tilde{v}_i \mid i = 1, \dots, n\}$ is **orthonormal**.

$$\tilde{v}_i = \frac{v_i}{\|v_i\|}$$

$$y_2 = v_2 + a_{21}v_1$$

$$\text{span}(v_1, v_2) = \text{span}(y_1, y_2)$$



Example: Construct a set of orthonormal vectors from

$$y_1^T = \begin{bmatrix} 1 & 0 & 1 \end{bmatrix}, \quad y_2^T = \begin{bmatrix} -1 & 2 & 1 \end{bmatrix}, \quad y_3^T = \begin{bmatrix} 0 & 1 & 2 \end{bmatrix}$$

The vectors are easily checked to be linearly independent.

Step 1: Let

$$\begin{aligned} v_1 &= y_1 = \begin{bmatrix} 1 & 0 & 1 \end{bmatrix}^T \\ v_2 &= y_2 - \frac{\langle v_1, y_2 \rangle}{\langle v_1, v_1 \rangle} v_1 = y_2, \quad (\text{because } \langle v_1, y_2 \rangle = 0) \end{aligned}$$

In this case y_1 and y_2 were already orthogonal, so there was nothing to do. Continuing,

$$v_3 = y_3 - \frac{\langle v_1, y_3 \rangle}{\langle v_1, v_1 \rangle} v_1 - \frac{\langle v_2, y_3 \rangle}{\langle v_2, v_2 \rangle} v_2 \tag{1}$$

$$= y_3 - \frac{2}{2} v_1 - \frac{4}{6} v_2 \tag{2}$$

$$= \begin{bmatrix} -\frac{1}{3} & -\frac{1}{3} & \frac{1}{3} \end{bmatrix}^T \tag{3}$$

Step 2: Normalize v_i to get \tilde{v}_i :

$$\tilde{v}_1 = \frac{v_1}{\|v_1\|} = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \quad \tilde{v}_2 = \frac{v_2}{\|v_2\|} = \frac{1}{\sqrt{6}} \begin{bmatrix} -1 \\ 2 \\ 1 \end{bmatrix}, \quad \tilde{v}_3 = \frac{v_3}{\|v_3\|} = \frac{1}{\sqrt{3}} \begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix}.$$

□

Problem:[0] Let $\{y_1, \dots, y_n\}$ be a linearly independent set and let $\{v_1, \dots, v_n\}$ be the orthogonal set produced by the Gram-Schmidt process. Then, $\forall 1 \leq l \leq n$,

$$\underbrace{\text{span}\{y_1, \dots, y_l\}} = \text{span}\{v_1, \dots, v_l\}.$$

Solution: Recall

$$v_k = y_k - \sum_{j=1}^{k-1} \frac{\langle v_j, y_k \rangle}{\|v_j\|^2} \cdot v_j \quad (4)$$

$l = 1$: $v_1 = y_1$ so it is trivially true.

Suppose now it is true for $l = k - 1$; will show holds for $l = k$. From (4),

$$y_k = v_k + \sum_{j=1}^{k-1} \frac{\langle v_j, y_k \rangle}{\|v_j\|^2} \cdot v_j \Rightarrow \text{span}\{y_1, \dots, y_k\} \subset \text{span}\{v_1, \dots, v_k\}.$$

Left to show: $v_k \in \text{span}\{y_1, \dots, y_k\}$.

By hypothesis,

$$v_j \in \text{span}\{y_1, \dots, y_{k-1}\} \text{ for all } 1 \leq j \leq k-1,$$

so

$$\sum_{j=1}^{k-1} \left(\frac{\langle v_j, y_k \rangle}{\|v_j\|^2} \right) v_j \in \text{span}\{y_1, \dots, y_{k-1}\} \subset \text{span}\{y_1, \dots, y_k\}.$$

Clearly, $y_k \in \text{span}\{y_1, \dots, y_k\}$.

$$\therefore v_k = y_k - \sum_{j=1}^{k-1} \left(\frac{\langle v_j, y_k \rangle}{\|v_j\|^2} \right) v_j \in \text{span}\{y_1, \dots, y_k\}$$

because $\text{span}\{y_1, \dots, y_k\}$ is a subspace. □

Definition: $x \perp y \Leftrightarrow \langle x, y \rangle = 0$; $x \perp S \Leftrightarrow \forall y \in S, \langle x, y \rangle = 0$.

Problem:[1] Suppose that $x \perp \{y_1, \dots, y_k\}$ (i.e. $\langle x, y_i \rangle = 0, 1 \leq i \leq k$). Then x is \perp to $\text{span}\{y_1, \dots, y_k\}$, i.e. $\langle x, w \rangle = 0 \forall w \in \text{span}\{y_1, \dots, y_k\}$.

Solution: $\langle x, \sum_{i=1}^k \alpha_i y_i \rangle = \sum_{i=1}^k \alpha_i \langle x, y_i \rangle = 0$

□

$$\langle x, w \rangle$$

Problem:[2] Let $\{v_1, \dots, v_n\}$ be an **orthonormal basis** for a vector space (X, \mathbb{R}) . Calculate the representation of $x \in X$ with respect to $\{v_1, \dots, v_n\}$.

Solution: $\{v_1, \dots, v_n\}$ a basis $\Rightarrow \exists !$ coeff. $\alpha_1, \dots, \alpha_n \in \mathbb{R}$ such that

$$x = \alpha_1 v_1 + \alpha_2 v_2 + \dots + \alpha_n v_n.$$

Now,

$$\begin{aligned} \langle v_i, x \rangle &= \langle v_i, \sum_{k=1}^n \alpha_k v_k \rangle \\ &= \sum_{k=1}^n \alpha_k \underbrace{\langle v_i, v_k \rangle}_{\delta_{ik}} \\ &= \alpha_i \end{aligned}$$

$$\therefore \boxed{\alpha_i = \langle v_i, x \rangle}$$

$$\text{or, } x = \sum_{i=1}^n \langle v_i, x \rangle v_i$$

□

RECIPROCAL BASIS VECTORS

Problem:[3] Let $(X, \mathbb{R}, \langle \cdot, \cdot \rangle)$ be an n -dim. inner product space, and let $\{v_1, \dots, v_n\}$ be a basis for X (*not* necessarily orthonormal). Show that for each $i = 1, 2, \dots, n$, $\exists r_i \in X$ such that

$$\langle r_i, v_j \rangle = \begin{cases} 1 & j = i \\ 0 & j \neq i \end{cases} \quad (5)$$

Solution: Suffices to prove this for $i = 1$. Apply the Gram-Schmidt process to the linearly independent set $\{v_2, v_3, \dots, v_n, v_1\}$. Note that v_1 has been permuted to the end. (To compute r_3 for example, you would permute v_3 to the end and apply the same procedure.) The Gram-Schmidt process will produce n -vectors $\{\tilde{v}_2, \tilde{v}_3, \dots, \tilde{v}_n, \tilde{v}_1\}$. By construction, $\langle \tilde{v}_1, \tilde{v}_j \rangle = 0$, $j = 2, \dots, n$, which implies, by Problem 1, that

$$\tilde{v}_1 \perp \text{span}\{\tilde{v}_2, \dots, \tilde{v}_n\}, \quad (6)$$

and by Problem 0 that

$$\tilde{v}_1 \perp \text{span}\{v_2, \dots, v_n\}. \quad (7)$$

From the Gram-Schmidt Process,

$$\tilde{v}_1 = v_1 - \sum_{j=2}^n \frac{\langle \tilde{v}_j, v_1 \rangle}{\|\tilde{v}_j\|^2} \tilde{v}_j.$$

Therefore, $v_1 = \tilde{v}_1 + \sum_{j=2}^n \frac{\langle \tilde{v}_j, v_1 \rangle}{\|\tilde{v}_j\|^2} \tilde{v}_j$, and hence,

$$\langle \tilde{v}_1, v_1 \rangle = \langle \tilde{v}_1, \tilde{v}_1 \rangle \quad \text{by (6) and (7).}$$

\therefore If we choose $r_1 = \frac{\tilde{v}_1}{\|\tilde{v}_1\|^2}$, we have

$$\langle r_1, v_j \rangle = \begin{cases} 1 & j = 1 \\ 0 & j \neq 1 \end{cases} \quad \text{as desired.}$$

□

Remarks: (a) $\{r_1, \dots, r_n\}$ satisfying (5) is called a **reciprocal basis**. (b) In order to find r_k , simply rotate v_k to back as in $\{v_1, \dots, v_{k-1}, v_{k+1}, \dots, v_n, v_k\}$ and apply the Gram-Schmidt procedure as above.

WAN'T COVER

Problem:[4] Let $(X, \mathbb{R}, \langle \cdot, \cdot \rangle)$ be an n -dim. inner product space, let $\{v_1, \dots, v_n\}$ be a basis for X , and let $\{r_1, \dots, r_n\}$ be the corresponding reciprocal basis. Show that for all $x \in X$,

$$x = \sum_{i=1}^n \langle r_i, x \rangle v_i \quad (8)$$

In other words, determining the representation of x with respect to $\{v_1, \dots, v_n\}$ can be accomplished by computing inner products!

Solution: Because $\{v_1, \dots, v_n\}$ is a basis, there exist unique $\alpha_i \in \mathbb{R}$ such that

$$x = \sum_{i=1}^n \alpha_i v_i \quad (9)$$

Hence,

$$\langle r_i, x \rangle = \langle r_i, \sum_{k=1}^n \alpha_k v_k \rangle \quad (10)$$

$$= \sum_{k=1}^n \alpha_k \langle r_i, v_k \rangle \quad (11)$$

$$= \alpha_i \quad (12)$$

because $\langle r_i, v_k \rangle$ equals one if $i = k$ and zero otherwise. This proves (8).

Inner Products: Example Computation for $(\mathbb{R}^3, \mathbb{R})$

Given data:

$$\langle p, q \rangle = p^T q = \sum_{i=1}^3 p_i q_i$$

$$\{y_1, y_2, y_3\} = \left\{ \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \right\}$$

Apply Gram-Schmidt to Produce an Orthogonal Basis:

$$v_1 = y_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$

$$\|v_1\|^2 = (v_1)^T v_1 = 2;$$

$$v_2 = y_2 - \frac{\langle v_1, y_2 \rangle}{\|v_1\|^2} v_1$$

$$= \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} - \underbrace{\begin{bmatrix} 1 & 1 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}}_3 \frac{1}{2} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} -\frac{1}{2} \\ \frac{1}{2} \\ 3 \end{bmatrix}$$

$$\|v_2\|^2 = 9\frac{1}{2} = \frac{19}{2};$$

$$v_3 = y_3 - \frac{\langle v_1, y_3 \rangle}{\|v_1\|^2} v_1 - \frac{\langle v_2, y_3 \rangle}{\|v_2\|^2} v_2$$

$$= \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} - \underbrace{\begin{bmatrix} 1 & 1 & 0 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}}_1 \frac{1}{2} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} - \underbrace{\begin{bmatrix} -\frac{1}{2} & \frac{1}{2} & 3 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}}_{3\frac{1}{2}} \frac{1}{\frac{19}{2}} \begin{bmatrix} -\frac{1}{2} \\ \frac{1}{2} \\ 3 \end{bmatrix}$$

$$= \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} - \begin{bmatrix} \frac{1}{2} \\ \frac{1}{2} \\ 0 \end{bmatrix} - \begin{bmatrix} -\frac{7}{38} \\ \frac{7}{38} \\ \frac{21}{19} \end{bmatrix} = \begin{bmatrix} -\frac{6}{19} \\ \frac{6}{19} \\ -\frac{2}{19} \end{bmatrix}.$$

Normalize to obtain Orthonormal Basis:

$$\begin{aligned}\tilde{v}_1 &= \frac{v_1}{\|v_1\|} = \begin{bmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \\ 0 \end{bmatrix} \\ \tilde{v}_2 &= \frac{v_2}{\|v_2\|} = \begin{bmatrix} \frac{-1}{\sqrt{38}} \\ \frac{1}{\sqrt{38}} \\ 3\sqrt{\frac{2}{19}} \end{bmatrix} \\ \tilde{v}_3 &= \frac{v_3}{\|v_3\|} = \frac{19}{\sqrt{76}} \begin{bmatrix} -\frac{6}{19} \\ \frac{6}{19} \\ -\frac{2}{19} \end{bmatrix}\end{aligned}$$

Obtain Reciprocal Basis:

We seek a basis $\{r_1, r_2, r_3\}$ such that $\langle r_i, y_j \rangle = \delta_{ij}$.

Step 1: r_1 is found by applying the Gram-Schmidt process to $\{y_2, y_3, y_1\}$.

$$\begin{aligned}v_1^1 &:= y_2 = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \\ v_1^2 &:= y_3 - \frac{\langle v_1^1, y_3 \rangle}{\|v_1^1\|^2} v_1^1 = \begin{bmatrix} -\frac{5}{14} \\ \frac{2}{7} \\ -\frac{1}{14} \end{bmatrix} \\ v_1^3 &:= y_1 - \frac{\langle v_1^1, y_1 \rangle}{\|v_1^1\|^2} v_1^1 - \frac{\langle v_1^2, y_1 \rangle}{\|v_1^2\|^2} v_1^2 = \begin{bmatrix} \frac{2}{3} \\ \frac{2}{3} \\ -\frac{2}{3} \end{bmatrix} \\ r_1 &:= \frac{v_1^3}{\|v_1^3\|^2} = \begin{bmatrix} \frac{1}{2} \\ \frac{1}{2} \\ -\frac{1}{2} \end{bmatrix}\end{aligned}$$

Step 2: r_2 is found by applying the Gram-Schmidt process to $\{y_3, y_1, y_2\}$.

$$\begin{aligned}
 v_2^1 &:= y_3 = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \\
 v_2^2 &:= y_1 - \frac{\langle v_1^1, y_1 \rangle}{\|v_1^1\|^2} v_1^1 = \begin{bmatrix} 1 \\ \frac{1}{2} \\ -\frac{1}{2} \end{bmatrix} \\
 v_2^3 &:= y_2 - \frac{\langle v_1^1, y_2 \rangle}{\|v_1^1\|^2} v_1^1 - \frac{\langle v_1^2, y_2 \rangle}{\|v_1^2\|^2} v_1^2 = \begin{bmatrix} \frac{2}{3} \\ -\frac{2}{3} \\ \frac{2}{3} \end{bmatrix} \\
 r_2 &:= \frac{v_2^3}{\|v_2^3\|^2} = \begin{bmatrix} \frac{1}{2} \\ -\frac{1}{2} \\ \frac{1}{2} \end{bmatrix}
 \end{aligned}$$

Step 3: r_3 is found by applying the Gram-Schmidt process to $\{y_1, y_2, y_3\}$.

$$\begin{aligned}
 v_3^1 &:= y_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \\
 v_3^2 &:= y_2 - \frac{\langle v_1^1, y_2 \rangle}{\|v_1^1\|^2} v_1^1 = \begin{bmatrix} -\frac{1}{2} \\ \frac{1}{2} \\ 3 \end{bmatrix} \\
 v_3^3 &:= y_3 - \frac{\langle v_1^1, y_3 \rangle}{\|v_1^1\|^2} v_1^1 - \frac{\langle v_1^2, y_3 \rangle}{\|v_1^2\|^2} v_1^2 = \begin{bmatrix} -\frac{6}{19} \\ \frac{6}{19} \\ -\frac{2}{19} \end{bmatrix} \\
 r_3 &:= \frac{v_3^3}{\|v_3^3\|^2} = \begin{bmatrix} -\frac{3}{2} \\ \frac{3}{2} \\ -\frac{1}{2} \end{bmatrix}
 \end{aligned}$$

Inner Products: Example Computation for $(C[0, 1], \mathbb{R})$

Given data:

$$C[0, 1] = \{f : [0, 1] \rightarrow \mathbb{R} \mid f \text{ continuous}\}, \quad \langle f, g \rangle = \int_0^1 f(\tau)g(\tau)d\tau$$

$$\{y_1, y_2, y_3\} = \{1, t, t^2\}$$

Apply Gram-Schmidt to Produce an Orthogonal Basis:

$$v_1 = y_1 = 1$$

$$\|v_1\|^2 = \int_0^1 (1)^2 d\tau = 1;$$

$$v_2 = y_2 - \frac{\langle v_1, y_2 \rangle}{\|v_1\|^2} v_1$$

$$= t - \underbrace{\int_0^1 1 \cdot \tau d\tau}_{\frac{1}{2}} \cdot \frac{1}{1} \cdot 1 = t - \frac{1}{2}$$

$$\|v_2\|^2 = \int_0^1 \left(\tau - \frac{1}{2}\right)^2 d\tau = \frac{1}{12};$$

$$v_3 = y_3 - \frac{\langle v_1, y_3 \rangle}{\|v_1\|^2} v_1 - \frac{\langle v_2, y_3 \rangle}{\|v_2\|^2} v_2$$

$$= t^2 - \underbrace{\int_0^1 1 \cdot \tau^2 d\tau}_{\frac{1}{3}} \cdot \frac{1}{1} \cdot 1 - \underbrace{\int_0^1 \left(\tau - \frac{1}{2}\right) \tau^2 d\tau}_{\frac{1}{12}} \left(\frac{1}{\frac{1}{12}}\right) \left(t - \frac{1}{2}\right)$$

$$= t^2 - \frac{1}{3} - \left(t - \frac{1}{2}\right)$$

$$= t^2 - t + \frac{1}{6}.$$

Doing Inner products on $C[a,b]$ in MATLAB

```
>> clear *
>> syms t % declare to be a symbolic variable

>> % INT(S,a,b) is the definite integral of S with respect to
    % its symbolic variable from a to b.  a and b are each
    % double or symbolic scalars.

>> y1=1+0*t % Otherwise MATLAB is too dumb to realize
            % that y1 is a trivial function of the symbolic
            % variable t
y1 = 1

>> y2=t;
>> y3=t^2;

% Start the G-S Procedure. Here we assume  $C[0,1]$ , that is
%  $C[a,b]$ , with  $[a,b]=[0,1]$ 

>> v1=y1

v1=1

>> v2=y2-int(v1*y2,0,1)*v1/int(v1^2,0,1)

v2=t-1/2

>> v3=y3-int(v1*y3,0,1)*v1/int(v1^2,0,1)-
    int(v2*y3,0,1)*v2/int(v2^2,0,1)

v3=t^2+1/6-t

% Next, normalize to length one

v1_tilde=v1/int(v1^2,0,1)^.5
```

```
v1_tilde=1
```

```
>> v2_tilde=v2/int(v2^2,0,1)^.5
```

```
v2_tilde=(t-1/2)*12^(1/2)
```

```
>> simplify(v2_tilde);
```

```
ans=(2*t-1)*3^(1/2)
```

```
>> v3_tilde=simplifyfy(v3/int(v3^2,0,1)^.5)
```

```
v3_tilde=(6*t^2+1-6*t)*5^(1/2)
```

A useful lemma

Lemma: Let $(\mathcal{X}, \mathcal{F})$ be an n -dimensional vector space and, for $1 \leq k < n$, let $\{v^1, \dots, v^k\}$ be a linearly independent set in \mathcal{X} . Then, $\exists v^{k+1} \in \mathcal{X}$ such that $\{v^1, \dots, v^{k+1}\}$ is linearly independent.

Proof: $p \Rightarrow q$ (contrapositive: $\neg q \Rightarrow \neg p$)

p : $1 \leq k < n$, $\{v^1, \dots, v^k\}$ is linearly independent

q : $\exists v^{k+1} \in \mathcal{X}$ s.t. $\{v^1, \dots, v^k, v^{k+1}\}$ is lin. indep.

Assume $\neg q$: $\forall x \in \mathcal{X} \quad x \in \text{span}\{v^1, \dots, v^k\}$

$$\Rightarrow \mathcal{X} \subset \text{span}\{v^1, \dots, v^k\}$$

$$n = \dim(\mathcal{X}) \leq \dim(\{v^1, \dots, v^k\}) \leq k$$

$$\therefore k \geq n \Rightarrow \neg p$$

Completion to a basis:

Proposition: Let $(\mathcal{X}, \mathcal{F})$

be n -dim vect. space.

If $\{v^1, \dots, v^k\}$ is a lin.

ind. set $1 \leq k < n$ in \mathcal{X} ,

$\exists \{v^{k+1}, \dots, v^n\}$ s.t.

$\{v^1, \dots, v^n\}$ is a basis for \mathcal{X} .

Orthogonal complement

Consider an inner product space $(X, \mathcal{F}, \langle \cdot, \cdot \rangle)$
" \mathbb{R} or \mathbb{C}

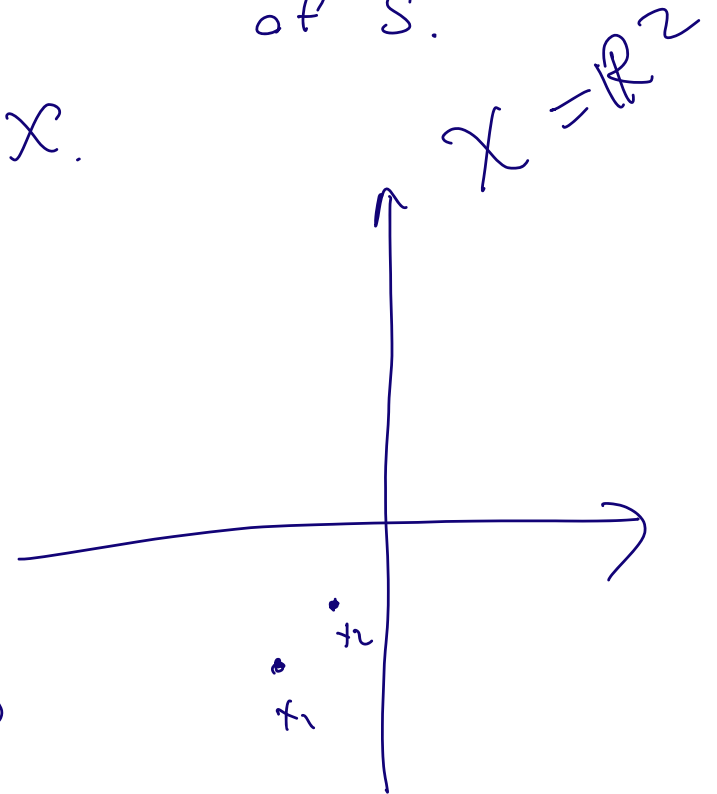
Def: Suppose $S \subset X$ is a subset. Then,

$S^\perp := \{x \in X \mid x \perp S\}$ is the orthogonal complement of S .

Exercise: ① S^\perp is a subspace of X .

② $S^\perp = (\text{span}(S))^\perp$

$$S = \{x_1, x_2\}$$



$$\langle x, y \rangle = \bar{x}^T y$$

$$\langle y, x \rangle = \bar{y}^T x$$

$$\overline{\langle y, x \rangle} = \overline{\bar{y}^T x} = y^T \bar{x}$$

$$x = a \tilde{x}$$

$$\tilde{x} = \frac{x}{\|x\|_V}$$

$$\|x\|_V = a$$

$$\sup_{\tilde{x} \in \mathbb{R}^n, \tilde{x} \neq 0} \frac{\|A \tilde{x}\|_V}{\|\tilde{x}\|_V} = \frac{\|A \tilde{x}\|_V}{\|\tilde{x}\|_V} = 1$$

$$\sup_{\tilde{x} \in \mathbb{R}^n, \tilde{x} \neq 0, \|\tilde{x}\|_V = 1} \|A \tilde{x}\|_V$$

$$\sup_{\tilde{x} \in \mathbb{R}^n, \|\tilde{x}\|_V = 1} \|A \tilde{x}\|_V$$

$(\mathbb{R}^n, \mathbb{R})$ OFFICE HOUR

$$\|\cdot\|_2$$

$$\|\cdot\|_1$$

$$\|\cdot\|_p$$

$$f_1(A) = \sup_{x \in \mathbb{R}^n, x \neq 0} \frac{\|Ax\|_1}{\|x\|_1}$$

$$f_2(A) = \sup_{x \in \mathbb{R}^n, x \neq 0} \frac{\|Ax\|_2}{\|x\|_2}$$

$$\begin{bmatrix} 1 & -1 \\ -0.2 & 0.2 \end{bmatrix} \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

\rightarrow if $\langle x, y \rangle = x^T A y$ is an inner product



$\langle x, x \rangle^{1/2}$ is a norm

$$\overline{z_1 \cdot z_2} = \overline{z_1} \cdot \overline{z_2}$$

$$\sup_{\tilde{x} \in \mathbb{R}^n, \|\tilde{x}\|_0 = 1} \|A \tilde{x}\|_\infty$$

$$A \tilde{x} = \begin{bmatrix} A_1 \\ A_2 \\ \vdots \\ A_n \end{bmatrix} \tilde{x}$$

$$\tilde{x} = \begin{bmatrix} 1 \\ 0.5 \\ 1 \end{bmatrix}$$