Sarang S. Sane

We have seen the following methods to find the solutions to a system of linear equations Ax = b:

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  - 1. Find the dependent variables (corr. to columns with leading entries) and independent variables (corr. to other columns).

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- ▶ If A is in (reduced) row echelon form, we can find all the solutions as follows :
  - 1. Find the dependent variables (corr. to columns with leading entries) and independent variables (corr. to other columns).
  - 2. Assign a value to each independent variable. Calculate the values of each dependent variable using the unique equation in which it occurs.

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- ► The Gaussian elimination method to determine all solutions of a system of linear equations.
- Computing the inverse using Gaussian elimination.

# The augmented matrix

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We denote the augmented matrix by 
$$[A|b]$$
 and put a vertical line between the first  $n$  columns and the last column  $b$  while writing it.

$$\begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \vdots & \vdots \\ a_{m1} & a_{m2} & \cdots & \vdots \\ a_{mn} & \vdots & \vdots$$

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We denote the augmented matrix by [A|b] and put a vertical line between the first n columns and the last column b while writing it.

$$3x_1 + 2x_2 + x_3 + x_4 = 6$$
$$x_1 + x_2 = 2$$
$$7x_2 + x_3 + x_4 = 8$$

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The augmented matrix is  $[A|b] = \begin{bmatrix} 3 & 2 & 1 & 1 & 6 \\ 1 & 1 & 0 & 0 & 2 \\ 0 & 7 & 1 & 1 & 8 \end{bmatrix}$ .

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The solutions of Ax = b are precisely the solutions of Rx = c.



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Since R is in reduced row echelon form, we can find ALL its solutions (as described earlier).

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\begin{bmatrix} 3 & 2 & 1 & 1 & | & 6 \\ 1 & 1 & 0 & 0 & | & 2 \\ 0 & 7 & 1 & 1 & | & 8 \end{bmatrix}
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$$\begin{bmatrix} 3 & 2 & 1 & 1 & | & 6 \\ 1 & 1 & 0 & 0 & | & 2 \\ 0 & 7 & 1 & 1 & | & 8 \end{bmatrix} \xrightarrow{R_1/3} \qquad \begin{bmatrix} 1 & 2/3 & 1/3 & 1/3 & | & 2 \\ 1 & 1 & 0 & 0 & | & 2 \\ 0 & 7 & 1 & 1 & | & 8 \end{bmatrix}$$

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$$R_2-R_1$$

$$\begin{bmatrix} 1 & 2/3 & 1/3 & 1/3 & 2 \\ 0 & 1/3 & -1/3 & -1/3 & 0 \\ 0 & 7 & 1 & 1 & 8 \end{bmatrix}$$

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$$\begin{bmatrix} 1 & 2/3 & 1/3 & 1/3 & 2 \\ 0 & 1 & -1 & -1 & 0 \\ 0 & 7 & 1 & 1 & 8 \end{bmatrix} \xrightarrow{3R_2} \begin{bmatrix} 1 & 2/3 & 1/3 & 1/3 & 2 \\ 0 & 1/3 & -1/3 & -1/3 & 0 \\ 0 & 7 & 1 & 1 & 8 \end{bmatrix}$$

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$$\begin{bmatrix} 1 & 2/3 & 1/3 & 1/3 & | & 2 \\ 0 & 1 & -1 & -1 & | & 0 \\ 0 & 0 & 8 & 8 & | & 8 \end{bmatrix}$$

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$$\begin{bmatrix} 1 & 2/3 & 1/3 & 1/3 & | & 2 \\ 0 & 1 & -1 & -1 & | & 0 \\ 0 & 0 & 8 & 8 & | & 8 \end{bmatrix} \xrightarrow{R_3/8} \qquad \begin{bmatrix} 1 & 2/3 & 1/3 & 1/3 & | & 2 \\ 0 & 1 & -1 & -1 & | & 0 \\ 0 & 0 & 1 & 1 & | & 1 \end{bmatrix}$$

# Another example

$$x_1 + x_2 + x_3 = 2$$
$$x_2 - 3x_3 = 1$$
$$2x_1 + x_2 + 5x_3 = 0$$

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The matrix representation of this system of linear equations is:

$$A = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & -3 \\ 2 & 1 & 5 \end{bmatrix} \qquad x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \qquad b = \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix}$$

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The augmented matrix is  $\begin{bmatrix} 1 & 1 & 1 & 2 \\ 0 & 1 & -3 & 1 \\ 2 & 1 & 5 & 0 \end{bmatrix}$ 

# Another example (contd.)

$$\begin{bmatrix} 1 & 1 & 1 & 2 \\ 0 & 1 & -3 & 1 \\ 2 & 1 & 5 & 0 \end{bmatrix}$$

# Another example (contd.)

$$\begin{bmatrix} 1 & 1 & 1 & 2 \\ 0 & 1 & -3 & 1 \\ 2 & 1 & 5 & 0 \end{bmatrix} \xrightarrow{R_3 - 2R_1} \begin{bmatrix} 1 & 1 & 1 & 2 \\ 0 & 1 & -3 & 1 \\ 0 & -1 & 3 & -4 \end{bmatrix}$$

Another example (contd.)

$$\begin{bmatrix}
1 & 0 & 1 & | & 2 \\
0 & 1 & | & 3 & | & 1 \\
2 & 1 & 5 & | & 3 & | & 2
\end{bmatrix}
\xrightarrow{R_3-2R_1}
\begin{bmatrix}
1 & 1 & 1 & | & 2 \\
0 & 1 & -3 & | & 1 \\
0 & -1 & 3 & | & -4
\end{bmatrix}
\xrightarrow{R_3+R_2}
\xrightarrow{R_3+R_2}
\begin{bmatrix}
1 & 1 & | & 1 & | & 1 \\
0 & 1 & -3 & | & 1 \\
0 & 0 & 0 & | & -3
\end{bmatrix}
\xrightarrow{R_1-R_2}$$
This system does not solution.

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For a homogeneous system, there are only two different possibilities: possibilities:

- ▶ 0 is the unique solution
- there are infinitely many solutions other than 0.

In a homogeneous system of equations, if there are more variables than equations, then it is guaranteed to have nontrivial solutions.

### Computing the inverse

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Computing the inverse of an invertible matrix 
$$A$$
 is equivalent to:

Finding solutions of  $Ax = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ ,  $Ay = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$  and  $Az = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$ .

A  $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$ 

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# Thank you