

The null space of a matrix finding nullity and a basis for the null space

Sarang S. Sane

Contents



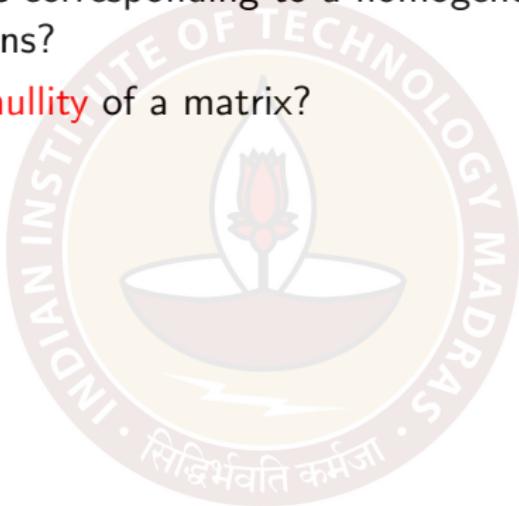
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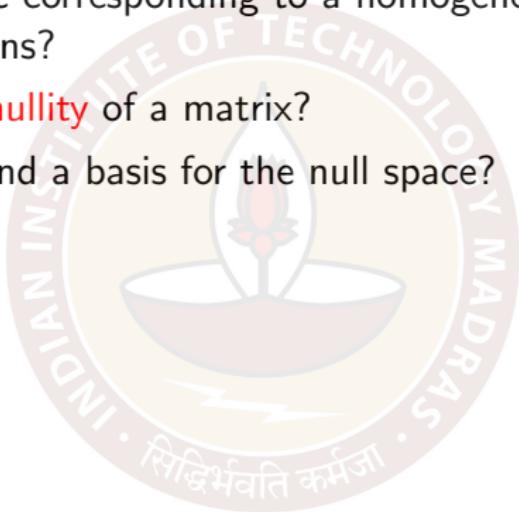


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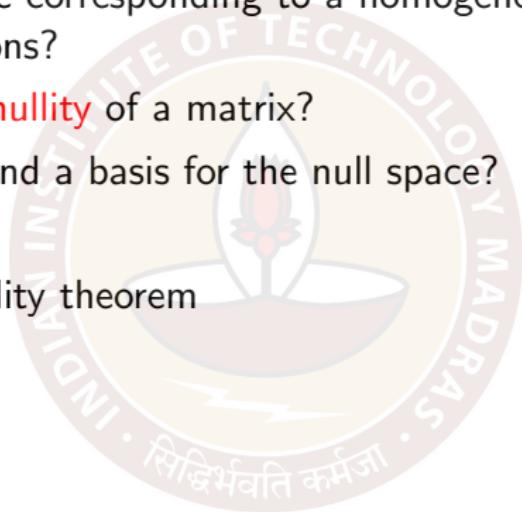
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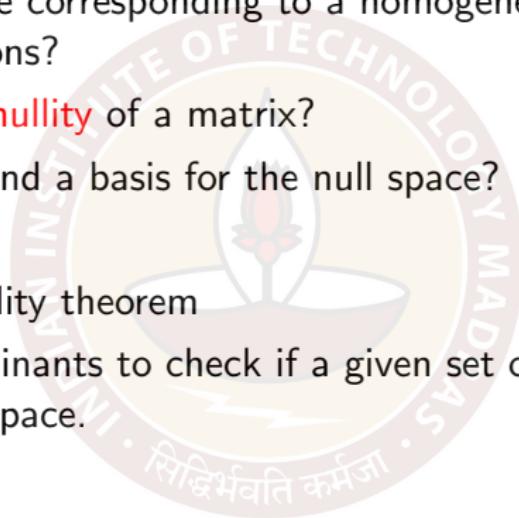
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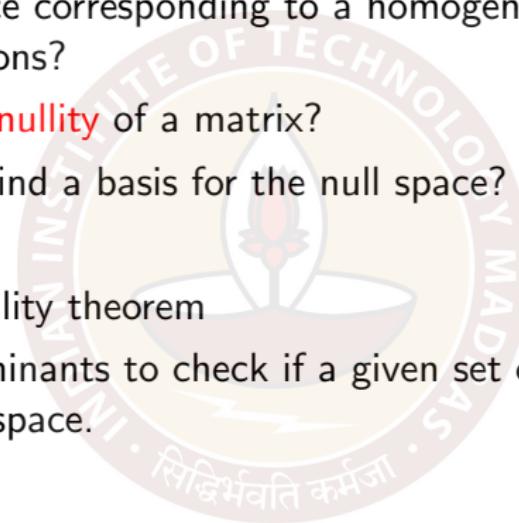
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Recall : We can find the dimension and a basis for a vector space spanned by a set of vectors using Gaussian elimination.

Solution space of a homogeneous system of linear equations

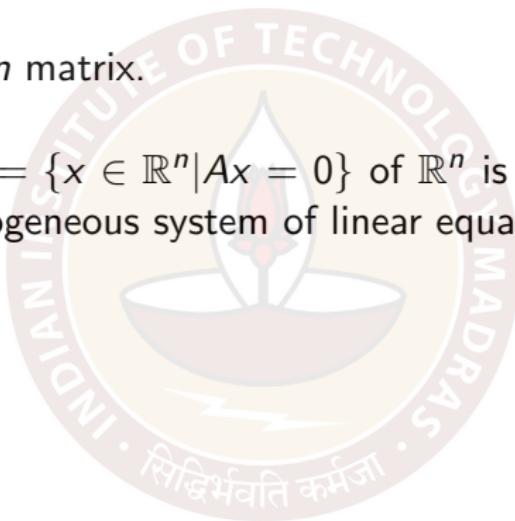
Let A be an $m \times n$ matrix.



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The subspace $W = \{x \in \mathbb{R}^n | Ax = 0\}$ of \mathbb{R}^n is called the **solution space** of the homogeneous system of linear equation $Ax = 0$ or the **null space** of A .



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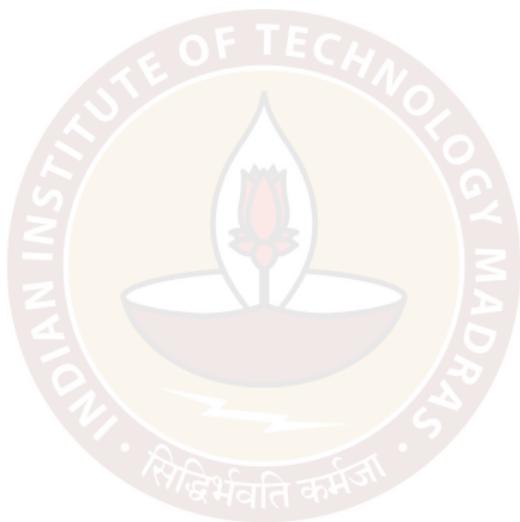
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$$\begin{aligned} x, y \in W &\Rightarrow Ax = Ay = 0 \rightarrow A(x+y) \\ &= Ax + Ay = 0 + 0 = 0. \\ &\Rightarrow x+y \in W. \\ \lambda \in \mathbb{R}, \quad & \Rightarrow A(\lambda x) = \lambda(Ax) = \lambda 0 = 0. \end{aligned}$$

Finding the nullity and a basis for the null space

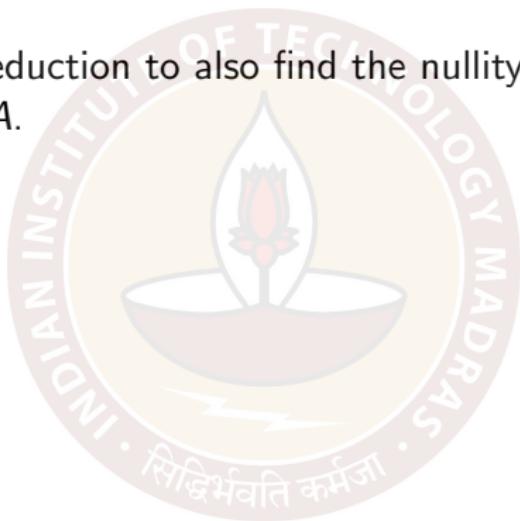
We have seen how to find the dimension and a basis for the row space of A using row reduction.



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We have seen how to find the dimension and a basis for the row space of A using row reduction.

We will use row reduction to also find the nullity and a basis for the null space of A .



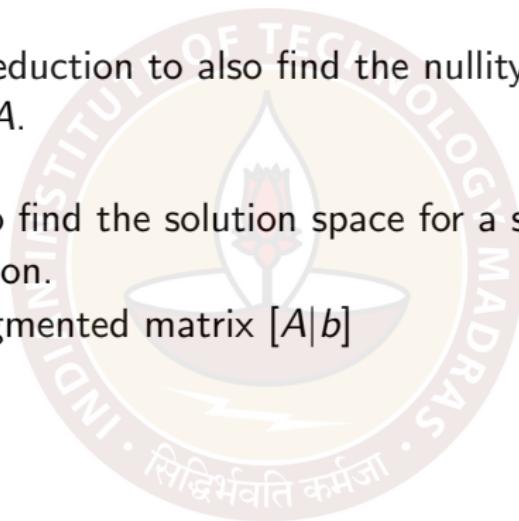
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- ▶ Form the augmented matrix $[A|b]$
- ▶ Apply the same row reduction operations on the augmented matrix that are used to row reduce A to obtain the augmented matrix $[R|c]$ where R is the matrix in reduced row echelon form obtained from A .

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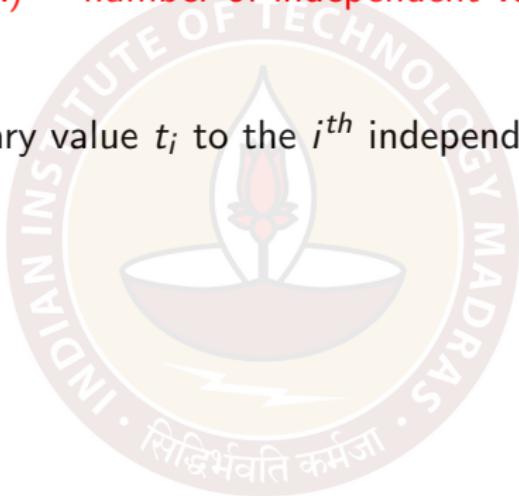
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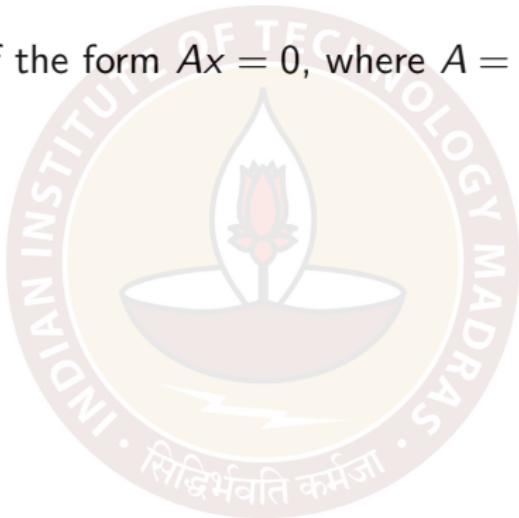
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The vectors obtained by substituting $t_i = 1$ and $t_j = 0 \forall j \neq i$ as i varies constitutes a basis of the null space of A (i.e. the solution space of $Ax = 0$).

Example : 3×3 matrix

Consider the (matrix representation of the) homogeneous system of linear equations of the form $Ax = 0$, where $A = \begin{bmatrix} 1 & 1 & 1 \\ 2 & 2 & 2 \\ 3 & 3 & 3 \end{bmatrix}$



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Independent variables : x_2, x_3 , dependent variable : x_1 .



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Hence, $\text{nullity}(A) = 2$.

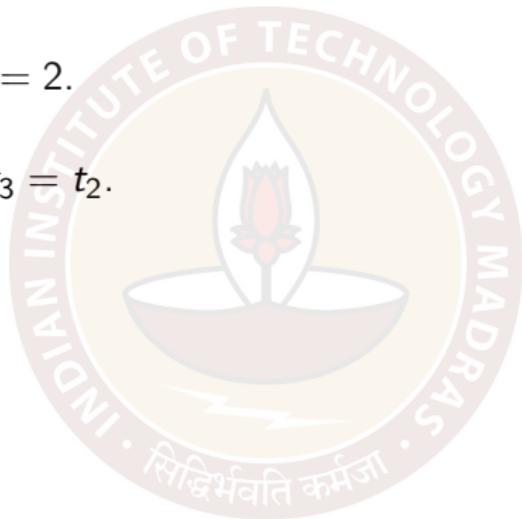


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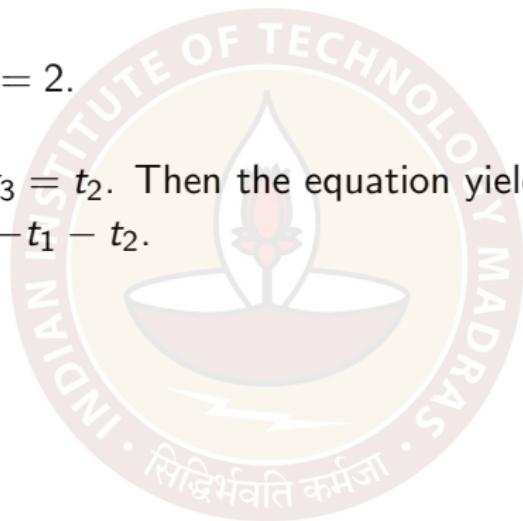


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Hence, the null space of A (i.e. the solution space of $Ax = 0$) is
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$t_1 = 1, t_2 = 0$ yields the basis vector $(-1, 1, 0)$.

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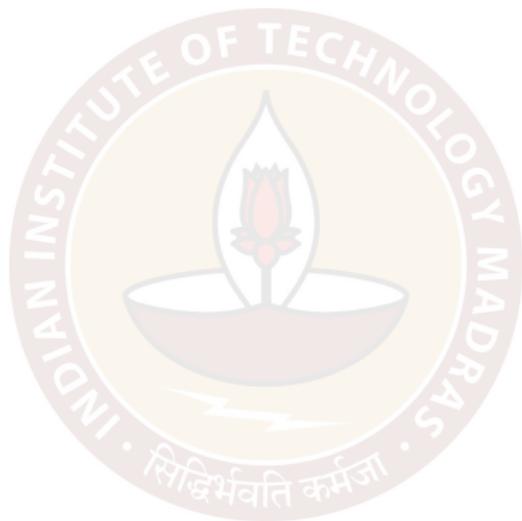
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Hence, a basis for the null space is $(-1, 1, 0), (-1, 0, 1)$.

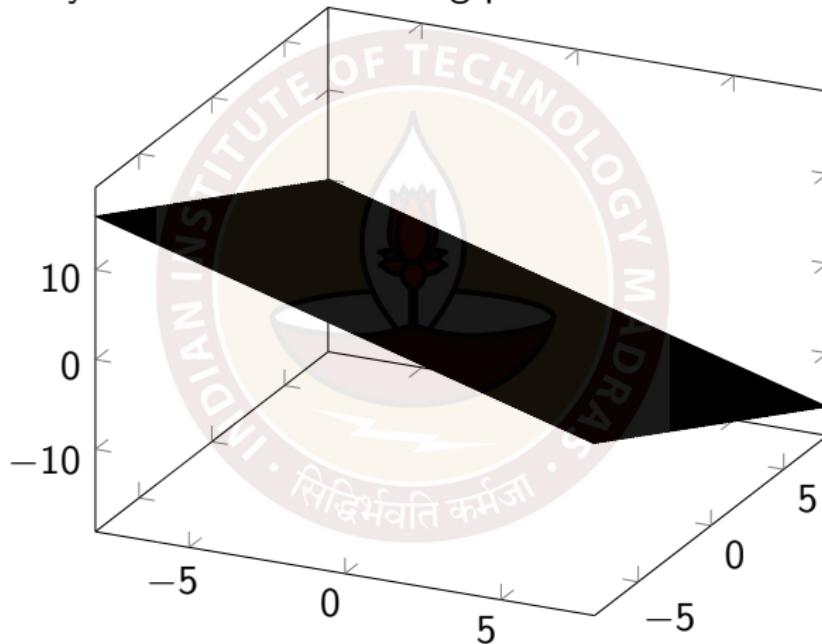
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Geometrically we have the following plane as the solution space :



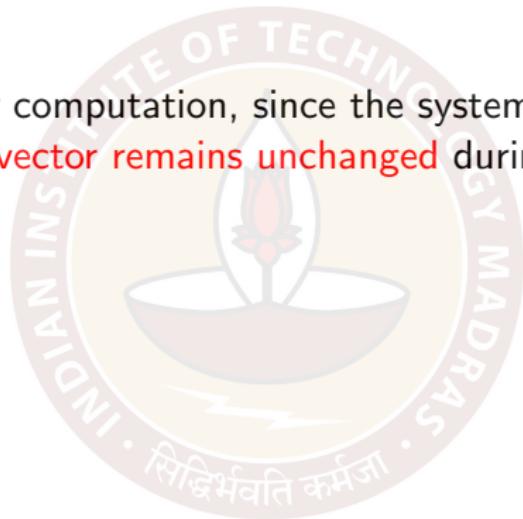
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Geometrically we have the following plane as the solution space :



Augmentation not required

Notice that in our computation, since the system is homogeneous,
the augmented 0 vector remains unchanged during the row
reduction process.



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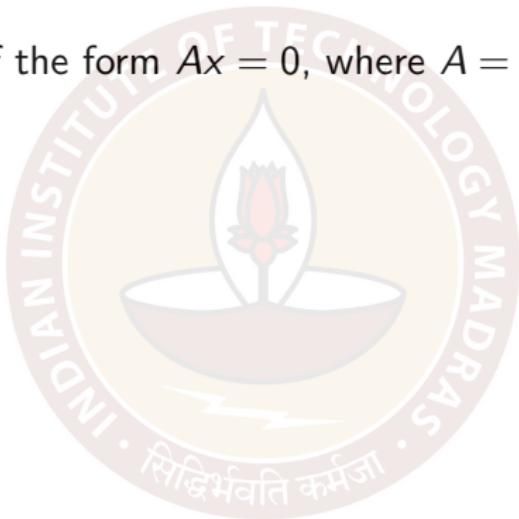
Notice that in our computation, since the system is homogeneous, the augmented 0 vector remains unchanged during the row reduction process.

So we will drop the 0 column augmented to the matrix while performing the row reduction computations and use it only for solving for the dependent variables.

Example : 3×4 matrix

Consider the (matrix representation of the) homogeneous system of

linear equations of the form $Ax = 0$, where $A = \begin{bmatrix} 1 & 2 & 0 & 3 \\ 2 & 3 & 0 & 3 \\ 1 & 1 & 1 & 2 \end{bmatrix}$.



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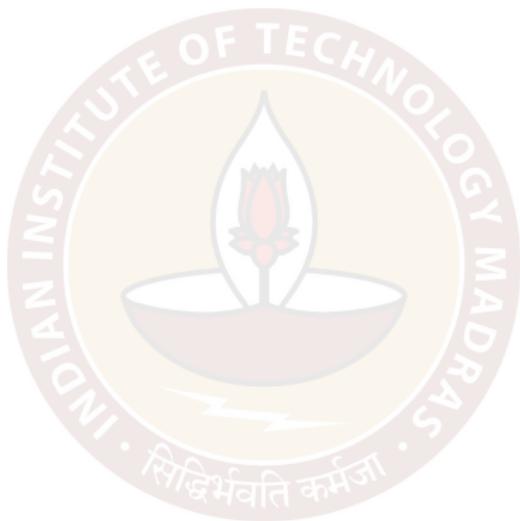
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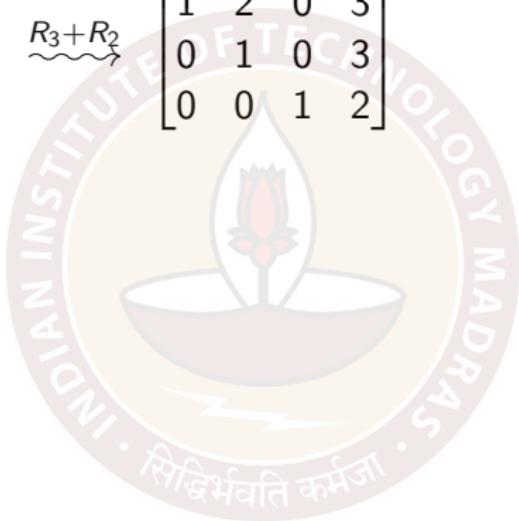
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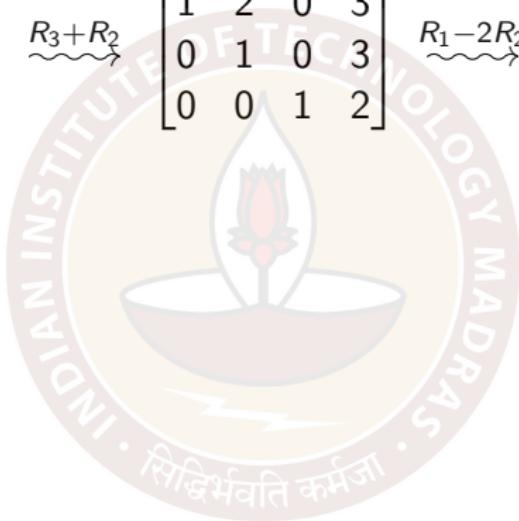
$$\left[\begin{array}{cccc} 1 & 2 & 0 & 3 \\ 0 & 1 & 0 & 3 \\ 0 & -1 & 1 & -1 \end{array} \right] \xrightarrow{R_3 + R_2} \left[\begin{array}{cccc} 1 & 2 & 0 & 3 \\ 0 & 1 & 0 & 3 \\ 0 & 0 & 1 & 2 \end{array} \right]$$



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Hence, *nullity(A) = 1*.

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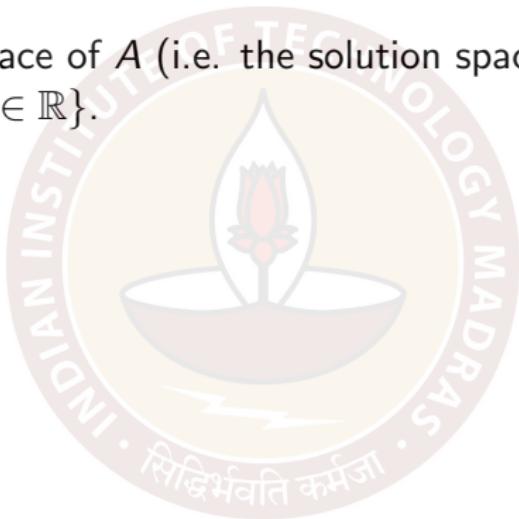
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$$x_1 - 3x_4 = 0 \quad x_2 + 3x_4 = 0 \quad x_3 + 2x_4 = 0,$$

and hence we obtain that $x_1 = 3t, x_2 = -3t, x_3 = -2t$.

Example contd.

Hence, the null space of A (i.e. the solution space of $Ax = 0$) is $\{(3t, -3t, -2t, t) | t \in \mathbb{R}\}$.



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Hence, the null space of A (i.e. the solution space of $Ax = 0$) is $\{(3t, -3t, 2t, t) | t \in \mathbb{R}\}$.

$t = 1$ yields the basis vector $(3, -3, 2, 1)$.

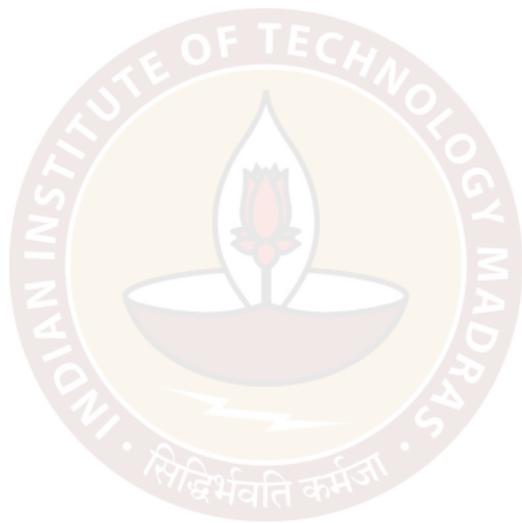
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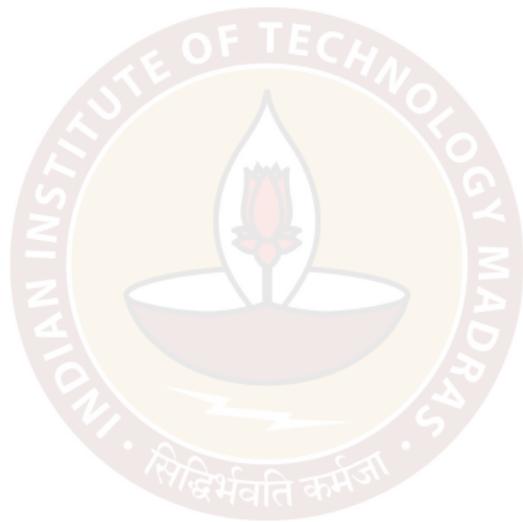
Hence, a basis for the null space of $A = \begin{bmatrix} 1 & 2 & 0 & 3 \\ 2 & 3 & 0 & 3 \\ 1 & 1 & 1 & 2 \end{bmatrix}$ is $(3, -3, 2, 1)$.

The rank-nullity theorem



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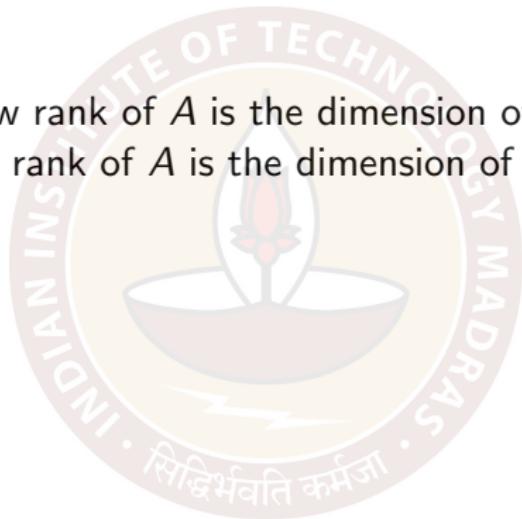
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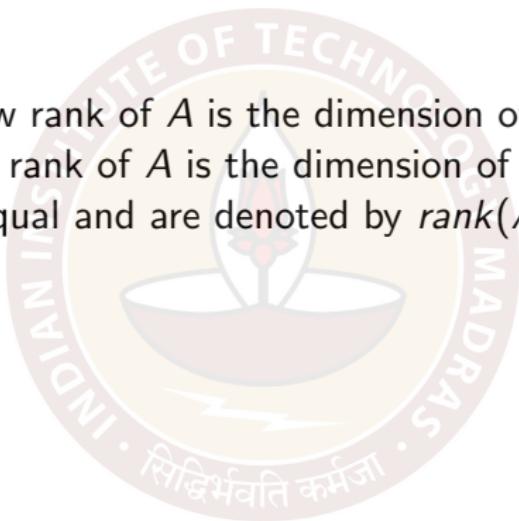
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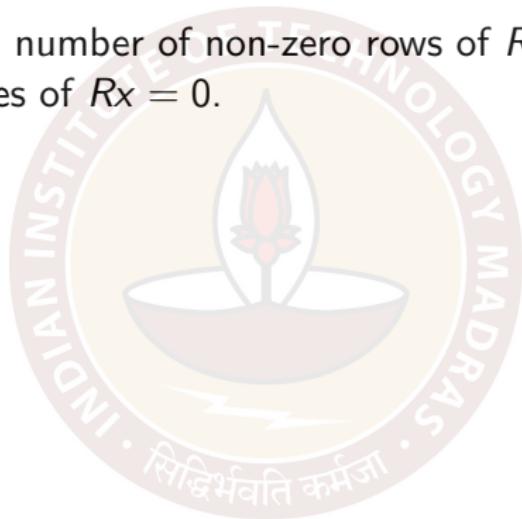
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Note that for a matrix R in the row echelon form, the **number of non-zero rows = number of dependent variables** for the corresponding homogeneous system $Rx = 0$.

The rank-nullity theorem (contd.)

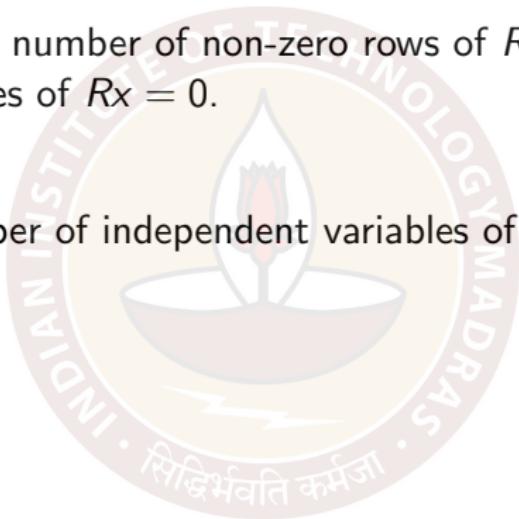
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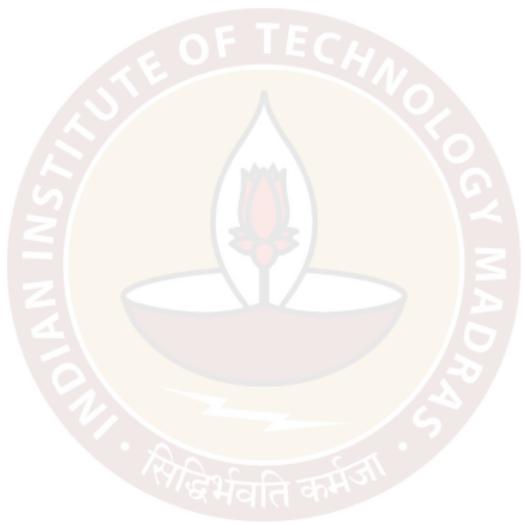
$\text{nullity}(A) = \text{number of independent variables of } Rx = 0.$

Therefore, we have the rank-nullity theorem :

Theorem

For an $m \times n$ matrix A , $\text{rank}(A) + \text{nullity}(A) = n.$

How to check if a set of n vectors is a basis for \mathbb{R}^n



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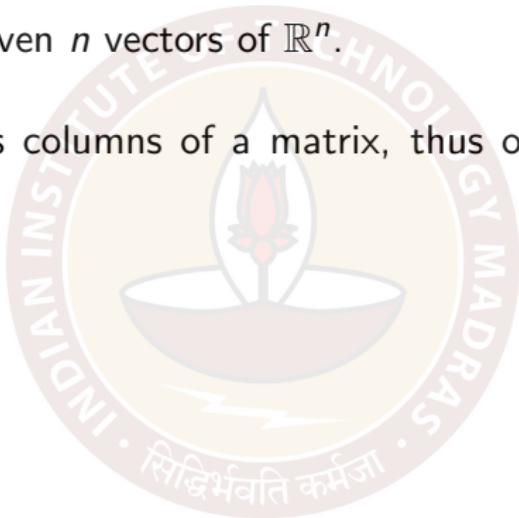


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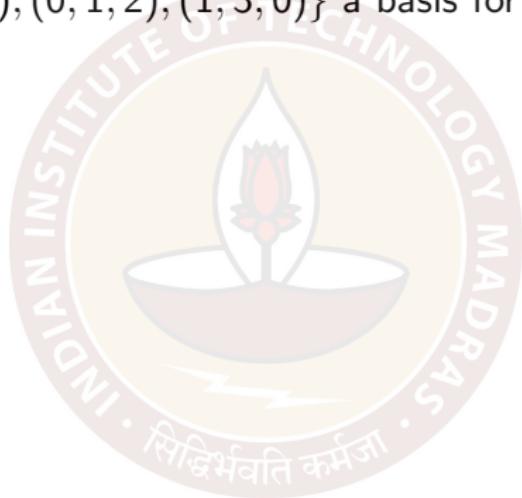
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The vectors $(1, -2), (5, -10)$ yields the matrix $\begin{bmatrix} 1 & 5 \\ -2 & -10 \end{bmatrix}$ with determinant 0. This is not a basis for \mathbb{R}^2 .

Example in \mathbb{R}^3

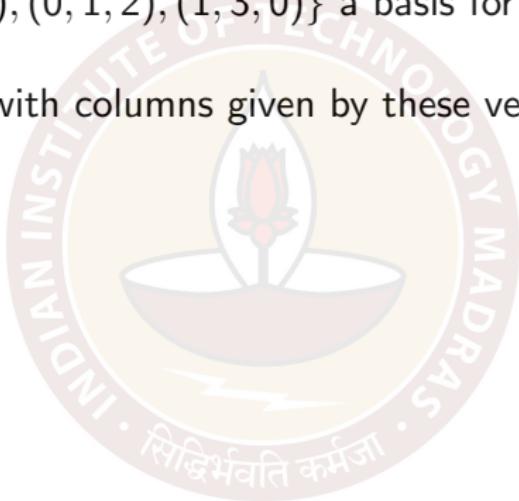
Is the set $\{(1, 2, 3), (0, 1, 2), (1, 3, 0)\}$ a basis for \mathbb{R}^3 ?



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$$\det(A) = 1 \times (-6) - 0 \times (-9) + 1 \times (4 - 3) = -6 + 0 + 1 = -5 \neq 0.$$

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x_1 x_2 x_3

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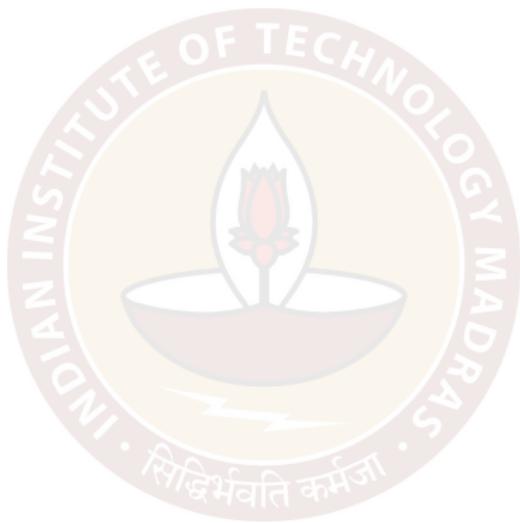
Hence the given set of vectors forms a basis of \mathbb{R}^3 .

Let $b \in \mathbb{R}^3$. Need: $a_1, a_2, a_3 \in \mathbb{R}$ s.t. $\sum a_i x_i = b$.

$$A \begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix} = b. \text{ Unique soln. is } \begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix} = A^{-1} b.$$

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$$A = \begin{bmatrix} 1 & 0 & 1 & 2 \\ 2 & 1 & 3 & 6 \\ 3 & 2 & 0 & 5 \\ 0 & 1 & 2 & 3 \end{bmatrix}$$

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Example in \mathbb{R}^4

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Form a matrix with columns given by these vectors.

$$A = \begin{bmatrix} 1 & 0 & 1 & 2 \\ 2 & 1 & 3 & 6 \\ 3 & 2 & 0 & 5 \\ 0 & 1 & 2 & 3 \end{bmatrix}$$

$A \left[\begin{array}{cccc} 1 & 0 & 1 & 2 \\ 2 & 1 & 3 & 6 \\ 3 & 2 & 0 & 5 \\ 0 & 1 & 2 & 3 \end{array} \right] = 0$
& solve.

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Hence the given set of vectors does not form a basis of \mathbb{R}^4 .

Thank you

