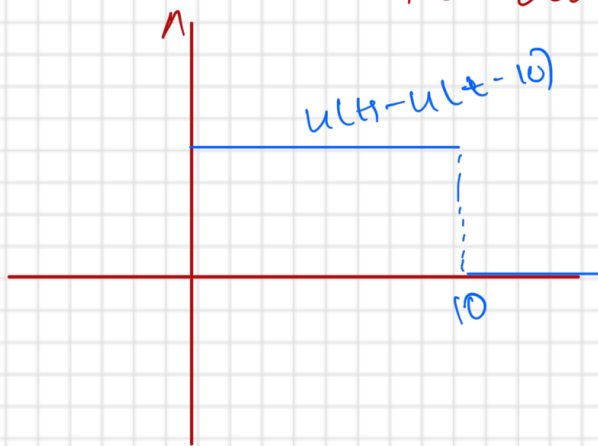


① Input: $x(t)$ Output: $x(t)f(t)$

Let $f(t) = u(t) - u(t-10)$, determine whether the system with input $x(t)$ and $y(t)$ is BIBO stable.

Solution

For bounded $x(t)$, i.e. $|x(t)| < M < \infty$,
 the output is bound, as



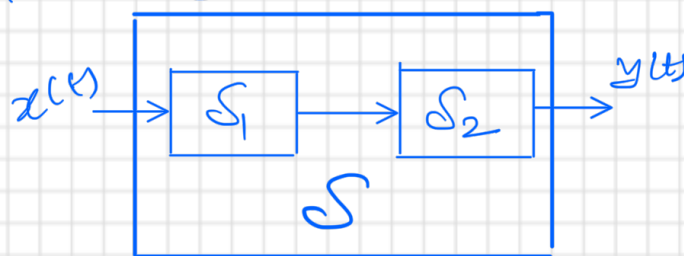
$f(t) = u(t) - u(t-10)$
 is a constant signal

$y(t) = x(t)f(t)$ is bounded
 as well.

Hence, the system is BIBO stable.

Q2. Consider a system composed of two subsystems:

S_1 and S_2



Impulse response of S_1 is $h_1(t) = \delta(t) - 2e^{-t}u(t)$
 " " " S_2 is $h_2(t) = e^t u(t)$

Is the system S BIBO stable.

Solution

Composite system's impulse response is given
 by $h(t) = h_1(t) * h_2(t)$
 $= e^t u(t) * [\delta(t) - 2e^{-t} u(t)]$

Note: Convolution with $\delta(t)$ returns the original signal, i.e. $f(t) * \delta(t) = f(t)$

So

$$\begin{aligned} & e^t u(t) * [\delta(t) - 2e^{-t} u(t)] \\ &= e^t u(t) * \delta(t) - e^t u(t) * (2e^{-t} u(t)) \\ &= e^t u(t) - \underbrace{e^t u(t) * (2e^{-t} u(t))} \end{aligned}$$

$$(f * g)(t) = \int_{-\infty}^t f(\tau) g(t-\tau) d\tau$$

$$= 2 \int_{-\infty}^t e^{\tau} u(\tau) e^{-(t-\tau)} u(t-\tau) d\tau$$

$$= 2 \int_t^{\infty} e^{\tau} u(\tau) e^{-t} e^{\tau} u(t-\tau) d\tau$$

$$= 2e^{-t} \int_0^t e^{2\tau} d\tau = 2e^{-t} \cdot \frac{e^{2\tau}}{2} \Big|_0^t$$

$$= 2e^{-t} \frac{e^{2t}}{2} - e^{-t}$$

$$= e^t - e^{-t}$$

$$= e^t u(t) - e^{-t} u(t), t \geq 0$$

$$\begin{aligned} \text{So } h(t) &= e^t u(t) - (e^t u(t) - e^{-t} u(t)) \\ &= e^{-t} u(t) \end{aligned}$$

As $e^{-t} u(t)$ is absolutely integrable

$\left(\int_0^{\infty} |e^{-t} u(t)| dt < \infty \right)$ the system is BIBO stable.