CPE 381: Fundamentals of Signals and Systems for Computer Engineers

03 Continuous-Time Signals

Fall 2025

Rahul Bhadani

Announcement

- ₱ Homework 01 Due September 01 11:59 PM
- Quiz 01, based on Chapter 01 Continuous-Time Signals from the Textbook. Available from September 05, 12:01 AM to September 07, 11:59 PM. 30 Questions, 45 Minutes.
- for Office hour: 08/28 Aug Wednesday, 1 PM 3:30 PM.
- No class on September 02, 2024: Labor Day, University Closed.

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Outline

- 1. Motivation
- 2. Operation on Signals
- 3. Basic Signals as Building Blocks
- 4. Modulation and Windowing

<u>◆</u> Motivation

Signals and Systems is 'Grandfather' of Data Science for Electrical and Computer Engineers

Classification of Signals

We care about the following properties when dealing with signals:

- Predictability: Random or Deterministic
- Variations of time and amplitude: continuous, discrete (time or x-axis) / quantized (amplitude or y-axis)
- Periodic/Aperiodic
- Finite energy/finite power; Infinite energy/Infinite power

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Operation on Signals

Basic Mathematical Operations

- **7** Addition: x(t) + y(t)
- **7** Subtraction: x(t) y(t)
- **f** Constant multiplication: kx(t) where k is a constant

Time-shift

- $f(x(t-\tau)) \rightarrow \text{Signal is delayed}$
- $f(x(t+\tau)) \rightarrow \text{Signal is advanced}$

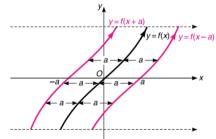
f(x) transforms to f(x-a)

i.e., $f(x) \longrightarrow f(x-a)$; a is positive. Shift the graph of f(x) through 'a' unit towards right

f(x) transforms to f(x + a).

i.e., $f(x) \longrightarrow f(x+a)$; a is positive. Shift the graph of f(x) through 'a' units towards left.

Graphically it could be stated as



Time Reflection

7 $x(t) \rightarrow x(-t)$: take mirror image **along the y-axis**

Note: The book doesn't specify whether to take the mirror image along the y-axis or not and it is confusing because the signal used in example 1.3.1 is symmetric with respect to both the x and y axes.

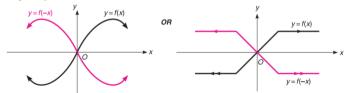
$$f(x)$$
 transforms to $f(-x)$
i.e., $f(x) \longrightarrow f(-x)$

To draw y = f(-x), take the image of the curve y = f(x) in *y*-axis as plane mirror.

OR

"Turn the graph of f(x) by 180° about y-axis."

Graphically it is stated as;



Signal Stretching along *y*-axis

 $f(x) \to af(x); \quad a>1$: Stretch the graph of f(x) 'a' times along y-axis.

 $f(x)
ightarrow rac{1}{a} f(x); \quad a>1$: Shrink the graph of f(x) 'a' times along y-axis.

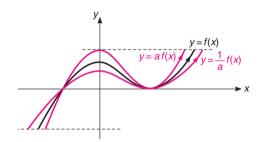
f(x) transforms to a f(x)

i.e.,
$$f(x) \longrightarrow af(x)$$
; $a > 1$

Stretch the graph of f(x) 'a' times along y-axis.

$$f(x) \longrightarrow \frac{1}{a}f(x); a > 1.$$

Shrink the graph of f(x) 'a' times along y-axis.



Signal Stretching along *x*-axis

- $f(x) \to af(ax); \quad a>1$: Stretch the graph of f(x) 'a' times along x-axis.
- $f(x) o f\Big(rac{1}{a}x\Big); \quad a>1$: Shrink the graph of f(x) 'a' times along x-axis.

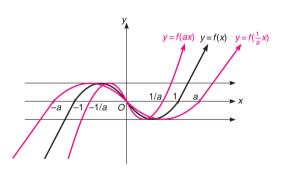
f(x) transforms to f(ax)

i.e.,
$$f(x) \longrightarrow f(ax)$$
; $a > 1$

Shrink (or contract) the graph of f(x) 'a' times along x-axis.

again
$$f(x) \longrightarrow f\left(\frac{1}{a}x\right); a > 1$$

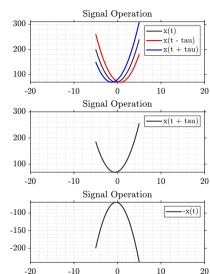
Stretch (or expand) the graph of f(x) 'a' times along *x*-axis.

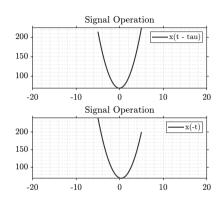


Example and MATLAB Code

$$x(t) = 6t^2 + 4t + 70$$

Code: https://github. com/rahulbhadani/ CPE381_FA25/blob/ main/Code/ signal_operation.m







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Even and Odd Signals

- Even Signal: x(t) = x(-t)
- **7** Odd Signal: x(t) = -x(-t)
- Any signal can be represented by the sum of even and odd signals $y(t) = y_e(t) + y_o(t)$

$$y_e(t) = 0.5[y(t) + y(-t)]$$

$$\gamma_o(t) = 0.5[\gamma(t) - \gamma(-t)]$$

Periodic Signals

- **7** Defined for all possible values of $t, -\infty < t < \infty$.
- f There is the real value $T_0 \in \mathbb{R}^+$, called the fundamental frequency such that $x(t+kT_0)=x(t), k \in \mathbb{I}$.
- A constant signal is periodic of a non-definable fundamental period.
- \P A $\cos(\omega t + heta)$, $\omega = 2\pi/T_0$, $\omega = 2, heta = -\pi/2, A = 2$.

What's the fundamental frequency, $1/T_0$?



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Energy and Power of Signals

What's the instantaneous power of a resistor?

Energy:

$$E_{x} = \int_{-\infty}^{\infty} |x(t)|^{2} dt$$

Power:

$$P_{x} = \lim_{T \to \infty} \frac{1}{2T} \int_{-T}^{T} |x(t)|^{2} dt$$

A signal is called finite power if the signal power is finite.



Basic Signals as Building Blocks

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Complex Exponentials

Consider
$$A=|A|e^{j\theta}$$
, $a=r+k\Omega_0$

- $x(t) = Ae^{at} = ...$
- **7** Real part $f(t) = \text{Re}\{x(t)\}, = \dots$

$$-|A|e^{rt} \le f(t)) \ge |A|e^{rt}$$
. $r < 0$, $f(t)$ is damped, $r > 0$, $f(t)$ grows.

f Imaginary part $g(t) = \text{Im}\{x(t)\}, = ...$

Sinusoids

A sinusoid of the general form:

$$A\cos(\Omega_0 t + \theta) = A\sin(\Omega_0 t + \theta + \pi/2), \quad -\infty < t < \infty$$

- A is the amplitude
- θ is phase shift
- f Fundamental period T_0 is

$$T_0=rac{2\pi}{\Omega_0}=rac{1}{f_0}$$



Rectangular pulse and Unit impulse

 \red{f} A rectangular pulse of duration Δ and unit area:

$$p_{\Delta}(t) = egin{cases} rac{1}{\Delta}, & -\Delta/2 \leq t \leq \Delta/2 \ 0, & ext{otherwise} \end{cases}$$

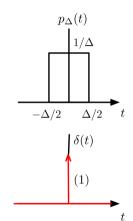
Unit Impulse:

$$\delta(t) = \lim_{\Delta o 0} p_{\Delta}(t)$$

Calculate

$$\int_{-\infty}^t p_{\Delta}(t)$$

Hint: there are three possible cases.



Unit Step

Integration of rectangular pulse:

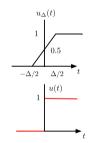
$$u_{\Delta}(t) = \int_{-\infty}^t p_{\Delta}(t) = egin{cases} 1, & t \geq rac{\Delta}{2} \ rac{1}{\Delta}(t + rac{\Delta}{2}), & rac{\Delta}{2} \leq t \leq rac{\Delta}{2} \ 0, & t < -rac{\Delta}{2} \end{cases}$$

Limit case:

$$\lim_{\Delta o 0} u_{\Delta}(t) = egin{cases} 1, & t \geq 0 \ 0, & t < 0 \end{cases}$$

A common case is to ignore t = 0 case, which gives us unit step function as

$$u(t) = \begin{cases} 1, & t \ge 0 \\ 0, & t < 0 \end{cases}$$



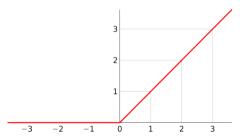


Ramp Signal

The ramp signal is r(t) = tu(t)

The relation between the ramp, the unit step, and the unit impulse:

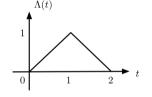
$$\frac{dr(t)}{dt} = u(t)$$
$$\frac{d^2r(t)}{dt^2} = \delta(t)$$

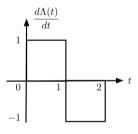


Triangular Pulse

The triangular pulse is

$$\Lambda(t) = egin{cases} t, & 0 \leq t \leq 1 \ -t+2, & 1 < t \leq 2 \ 0, & ext{otherwise} \end{cases}$$





 $\uparrow \Lambda(t)$ can also be written as:

$$\Lambda(t) = r(t) - 2r(t-1) + r(t-2)$$

Triangular Pulse as Ramp Functions I

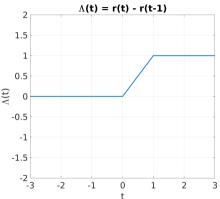
Let's verify this by evaluating $\Lambda(t)$ at different intervals:

First, find out the first part:

$$\Lambda_1(t) = egin{cases} t, & 0 \leq t \leq 1 \ 0, & ext{otherwise} \end{cases}$$

which can be written as: can be written using the ramp function r(t) as:

$$\Lambda_1(t) = r(t) - r(t-1)$$



Triangular Pulse as Ramp Functions II

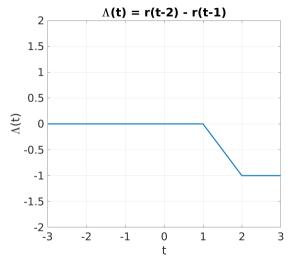
Second part:

$$\Lambda_1(t) = egin{cases} -t+2, & 1 < t \leq 2 \ 0, & ext{otherwise} \end{cases}$$

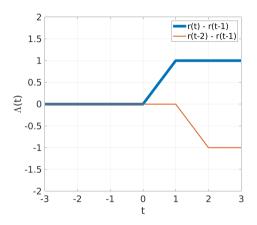
which can be written as: can be written using the ramp function $\boldsymbol{r}(t)$ as:

$$\Lambda_1(t) = r(t-2) - r(t-1)$$

Putting together



Triangular Pulse as Ramp Functions III



Sifting Property

The product of f(t) and $\delta(t)$ gives zero everywhere except at the origin where we get an impulse of area f(0), that is, $f(t)\delta(t)=f(0)\delta(t)$. Hence,

$$\int_{-\infty}^{\infty} f(t)\delta(t)dt = \int_{-\infty}^{\infty} f(0)\delta(dt) = f(0)\int_{-\infty}^{\infty} \delta(t)dt = f(0)$$

This is called Sifting Property.

If we delay or advance the $\delta(t)$ function in the integrated, the result is that all values of f(t) are sifted out except for the value corresponding to the location of the delta function, that is,

$$\int_{-\infty}^{\infty}\! f(t)\delta(t-\tau)dt = \int_{-\infty}^{\infty}\! f(\tau)\delta(t-\tau)dt = f(\tau)\int_{-\infty}^{\infty}\delta(t-\tau)dt = f(\tau) \quad \text{for any } \tau$$

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Generic Representation of Signals

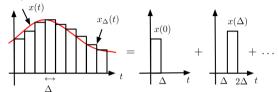
Hence, if we do integration in terms of variable τ , we get a generic representation of signals in terms of impulse and shifted impulse.

$$x(t) = \int_{-\infty}^{\infty} x(\tau) \delta(t - \tau) d\tau$$

$$x(t) = \int_{-\infty}^{\infty} x(\tau) \delta(t - t_0) d\tau$$

$$x(t) = \int_{-\infty}^{\infty} x(\tau) \delta(t - t_0) d\tau$$

$$x(t) = \int_{-\infty}^{\infty} x(\tau) \delta(t - \tau) d\tau$$



7 Approximation of x(t):

$$x_{\Delta}(t) = \sum_{-\infty}^{\infty} x_{\Delta}(t - k\Delta) = \sum_{-\infty}^{\infty} x(k\Delta)p_{\Delta}(t - k\Delta)\Delta$$

In the limit as $\Delta \to 0$ these pulses become impulses, separated by an infinitesimal value:

$$\lim_{\Delta \to 0} x_{\Delta}(t) \to x(t) = \int_{-\infty}^{\infty} x(\tau) \delta(t - \tau) d\tau$$



Modulation and Windowing

Modulation

Multiplication by a complex exponential shifts the frequency of the original signal.

Definition

Superimposing a low-frequency signal on a high-frequency carrier signal is called **Modulation**.

Example:

Consider an exponential signal $x(t)=e^{j\Omega_0t}$ of frequency Ω_0 . If we multiply an exponential $e^{j\phi t}$ with x(t), then:

$$x(t)e^{j\phi t} = e^{j(\Omega_0 + \phi)t} = \cos((\Omega_0 + \phi)t) + j\sin((\Omega_0 + \phi)t)$$

 $\phi > 0$: the frequency of new exponential is greater than Ω_0 , otherwise lower.

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Various Types of Modulation

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A(t)cos(\Omega(t)t + \theta(t))
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- f A(t) changes: Amplitude Modulation
- $\uparrow \Omega(t)$ changes: Frequency Modulation
- f $\theta(t)$ changes: Phase Modulation

Windowing

For a window signal w(t), the time-windowed signal x(t)w(t) displays x(t) within the support of w(t).

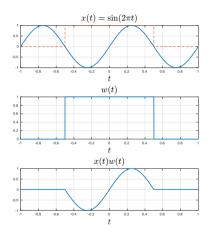
Example:

$$x(t) = \sin(2\pi t)$$

$$w(t) = egin{cases} 1 & ext{if } -0.5 \leq t \leq 0.5 \ 0 & ext{otherwise} \end{cases}$$

Code for the graph:

https://github.com/rahulbhadani/CPE381_FA25/blob/main/Code/windowing.m



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Up Next

Fourier Transform