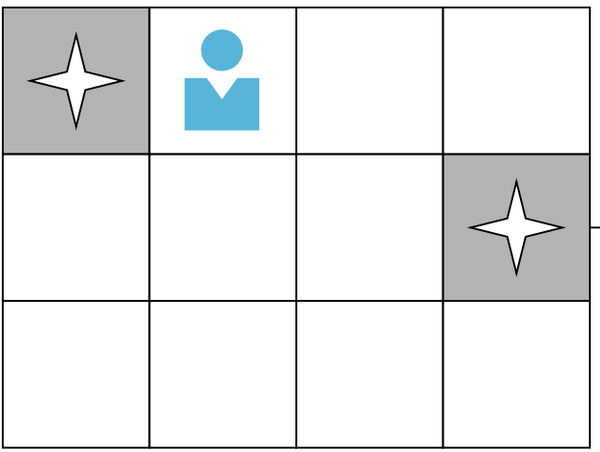
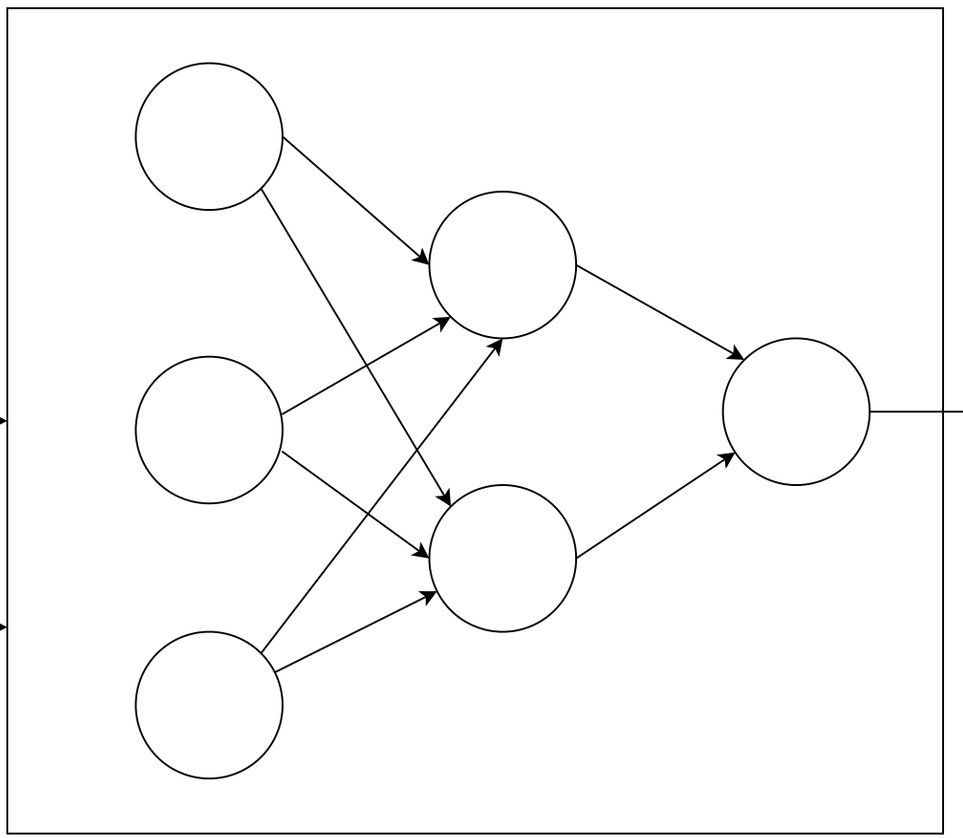
Action + State = Expected Return



State, s

Move Right

Action, a



$Q(s, a)$

Input

Agent

Output