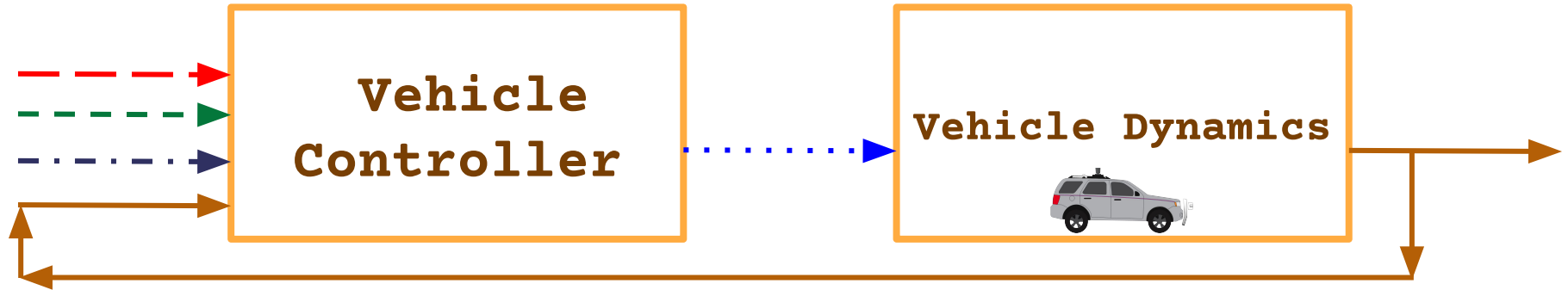


- > Leader Speed
- > Relative Speed
- .-.-> Relative Distance
- > Output Speed
- .....> Commanded Speed



Feedback Control