



CAT VEHICLE REU 2019

Getting started: Setting up development environment

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Before we proceed ...

- ❖ We will be working on Ubuntu 18.04 most of the time.
- ❖ Programming tools required: C++, MATLAB/Simulink, Python, C++
- ❖ All work must be committed to version control: we will use git.engr.arizona.edu
 - I highly recommend committing your work every hour or whenever you think you have achieved something
- ❖ We will use latex to write reports and any papers.
- ❖ Make sure your system has sufficient disk space [> 100 GFB is recommended]

Course page

- ❖ Piazza: <https://piazza.com/class/jwck37wbfos2ai>
- ❖ When in doubt ask questions on Piazza. It is possible that someone already knows the answer.

Installing Virtual Machine

Install VMWARE Workstation

THE UNIVERSITY OF ARIZONA



College of Engineering
IT Support

IT Support Home Page

This is the main IT support site for the College of Engineering at the University of Arizona, Tucson. From this page, you can create or manage tickets that you have submitted. Access resources that are available to Engineering students, staff, and faculty.

There are also external links to Azure Development Tools for Teaching, formerly known as MSDN-AA licensing, and to E On The Hub website with VMWare and other applications. There are links to see what software we have available in the labs. Plus the ever popular FAQ's

Support Tickets

[My Support Tickets](#)
[New Ticket](#)
[FAQs](#)

Software

[VMware and Others Web Store](#)
[Azure Development Tools For Teaching\(formerly know as MSDN-Licensing\)](#)
[Lab Software](#)
[UofA Software Licensing](#)

- ❖ Not required if you are already using a native Ubuntu 18.04 system
- ❖ Got to <https://support.engr.arizona.edu/>
- ❖ Click VMware and Others Web Store
- ❖ You will be asked to login using your NetId
- ❖ Select VMware Workstation Player 15 for Windows or any linux machine

Install VMWARE Workstation



- ❖ Select VMware Workstation 15 for Windows or any linux machine
- ❖ Or VMware Fusion 11 for Mac
- ❖ Add to cart -> checkout
- ❖ Copy and save the serial number somewhere
- ❖ Download the software
- ❖ Enter serial key upon installation, if asked!

Install VMWARE Workstation

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Students

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VMware

More Software

Software

eText

eLab

eLearning

VMware Workstation 14 ▲



VMware Workstation Pro is the industry standard for running multiple operating systems as virtual machines (VMs) on a single Linux or Windows PC. IT professionals, developers and businesses who build, test or demo software for any device, platform or cloud rely on Workstation Pro.

Choose a platform:

Linux ▼

VMware Workstation 14 for Linux


Available to: Students

Workstation requires a 64-bit processor and 64-bit host operating system.

You will be able to place an order for this product again in 12 months after the initial order.

The license you will receive with this offering is valid 12 months starting with the 1st of the month the offering was ordered.

Free

 Add to Cart


Install VMWARE Workstation

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Details (Order Number: 100611207398)

Downloads



VMware Workstation 14 for Linux - Download

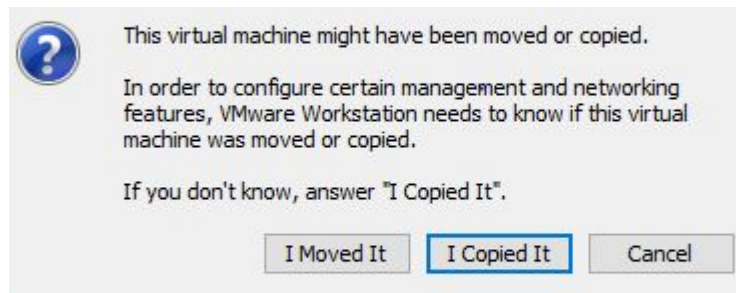
Serial Number: XXXXX-XXXXX-XXXXX-XXXXX-XXXXX

Download

Obtaining pre-configured Ubuntu 18.04

Download virtual disk

- ❖ Go to <http://bit.ly/2j0cGtf> and download the zip file.
- ❖ Unzip the zip file at any desired location.
- ❖ Start the VMware workstation you installed in the previous step.
- ❖ From file-> open, select .vmx file from the folder you just unzipped.
- ❖ Click the green triangle button in the Workstation to boot the vm.
- ❖ You may see a dialogue like on shown below. Select 'I Copied it'.



- ❖ Ask for password in the class.

Installing ROS in a new system

Install ROS Melodic

- ❖ These steps are not required if you are using Ubuntu 18.04 in a VM
- ❖ Follow the steps mentioned in <http://wiki.ros.org/melodic/Installation/Ubuntu%20Ao> to install ros in your new system.
- ❖ For CAT Vehicle development, we will require more packages.
- ❖ Install these packages:

```
sudo apt-get install ros-melodic-controller-manager -y  
sudo apt-get install ros-melodic-ros-control ros-melodic-ros-controllers -y  
sudo apt-get install ros-melodic-gazebo-ros-control -y  
sudo apt-get install ros-melodic-image-transport-* -y  
sudo apt-get install ros-melodic-joystick-drivers -y
```



Configuring ROS for your system

- ❖ When you are using ROS in a shared network, it is required that your ubuntu hostname is unique to avoid nameo-resolution conflict.
- ❖ Change the hostname from `catvehicle` to your favorite hostname in `/etc/hostname` folder. E.g. You can choose your UofA netId.

```
sudo gedit /etc/hostname
```

- ❖ We will also change the name of localhost to refer your computer.

```
sudo gedit /etc/hosts
```

and replace `catvehicle` with your netId.

Configuring ROS for your system

- ❖ In `.bashrc` file set the hostname for `ROS_HOSTNAME` to the same name you used for system hostname.
 - `gedit ~/.bashrc`
 - E.g. If you have set machine's hostname to `firstnamelastname`, then in `.bashrc` file, set the `ROS_HOSTNAME` to `firstnamelastname`.
 - Search `ROS_HOSTNAME` in the file `.bashrc` and change `export`
`ROS_HOSTNAME=reu.local` to
`export ROS_HOSTNAME=firstnamelastname.local`

Download MATLAB

- ❖ In order to download MATLAB, you need to sign up to MATLAB account with your official University of Arizona email id [aka CAT MAIL]. After signing in with your U of A email id, download MATLAB installer for MATLAB R2019a.
- ❖ Once you install matlab, you need to add an alias in .bashrc for easy access to MATLAB
 - `alias matlab="/usr/local/MATLAB/R2019a/bin/matlab"`

Configuring ROS for your system

❖ To run roscore on the local machine, change

```
export ROS_MASTER_URI=http://catvehicle.local:11311/
```

to

```
export ROS_MASTER_URI=http://firstnamelastname.local:11311/
```


Installing MATLAB

Obtain and install WebGME

- ❖ `npm install -g webgme-cli`
- ❖ At this point, I ask you to close the terminal and reopen it.
- ❖ `webgme init WebGMEFirstProject`
- ❖ `cd WebGMEFirstProject`
- ❖ `webgme start`
- ❖ Once dependencies are resolved, open a web browser and type <http://localhost:8080>
- ❖ Detailed documentation at
 - https://webgme.readthedocs.io/en/latest/getting_started/creating_a_repository.html
 - <https://github.com/webgme/webgme-cli>
- ❖ More on WebGME later ...

Installing WebGME

Obtain and install WebGME

- ❖ WebGME stands for Web Generic Modeling Environment [more on this later ...]
- ❖ Install nodejs: your system may already have nodejs. But we want only a specific version of nodejs. Hence if you have nodejs already installed, uninstall it.

```
➤ sudo apt-get remove nodejs
```

- ❖ Install nvm:

```
➤ curl -o- https://raw.githubusercontent.com/nvm-sh/nvm/v0.34.0/install.sh | bash
```

```
➤ source ~/.bashrc
```

```
➤ nvm install v12.3.1
```

```
➤
```

[See next slide]

Obtain and install WebGME

- ❖ Installing MongoDB: follow steps at <https://docs.mongodb.com/manual/tutorial/install-mongodb-on-ubuntu/> to install mongodb on your Ubuntu machine. It is also possible that you already have MongoDB installed.
- ❖

```
echo "deb [ arch=amd64 ] https://repo.mongodb.org/apt/ubuntu  
bionic/mongodb-org/4.0 multiverse" | sudo tee  
/etc/apt/sources.list.d/mongodb-org-4.0.list
```
- ❖

```
sudo apt-get update
```
- ❖

```
sudo apt-get install -y mongodb-org
```
- ❖

```
sudo service mongod start
```