

CAT VEHICLE REU Summer 2020

Software Downloads

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Prerequisite

- ❖ We will be working on Ubuntu 18.04 most of the time.
- Programming tools required: C++, MATLAB/Simulink, Python
- All work must be committed to version control: we will use github.com/jmscslgroup
 - Send your github.com userID
- We will use latex to write reports and any papers.
- ♦ Make sure your system has sufficient disk space (> 100 GFB is recommended)



Installing Ubuntu 18.04



Ways to use Ubuntu

- Virtual Machine
 - VMWare Workstation
 - VMWare Player
 - VMWare Fusion for Mac
 - Oracle Virtual Box
- Linux subsystem in Windows

- Stand-alone
 - Strictly Ubuntu 18.04
 - https://releases.ubunt
 u.com/18.04/

Install VMWARE Workstation



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College of Engineering IT Support

IT Support Home Page

This is the main IT support site for the College of Engineering at the University of Arizona, Tucson. From this page, you can create or manage tickets that you have submitted. Access resources that are available to Engineering students, staff, and faculty.

There are also external links to Azure Development Tools for Teaching, formerly known as MSDN-AA licensing, and to E On The Hub website with VMWare and other applications. The are links to see what software we have available in the labs. Plus the ever popular FAQ's

Support Tickets

My Support Tickets New Ticket FAOs

Software

VMware and Others Web Store Azure Development Tools For Teaching(formerly know as MSDN-Licensing) Lab Software UofA Software Licensing Not required if you are already using a native Ubuntu 18.04 system

Go to
 https://support.engr.arizona.edu/

- Click VMware and Others Web Store
- You will be asked to login using your NetId
- Select VMware Workstation Player 15 for Windows or any linux machine



Install VMWARE Workstation

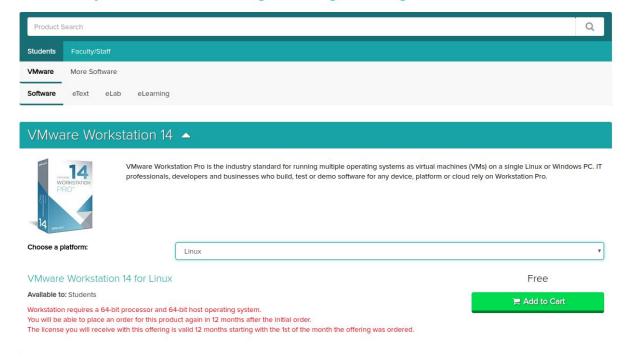


- Select VMware Workstation 15 for Windows or any linux machine
- Or VMware Fusion 11 for Mac
- Add to cart > checkout
 - Copy and save the serial number somewhere
- Download the software
- Enter serial key upon installation, if asked!





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VMWARE - Alternative ARIZONA Options

If your U of A license is still not active, you can use free version of VMWare player: https://my.vmware.com/en/web/vmware/free#desktop end user computing/vmware workstation player/15 0



Obtaining Ubuntu 18.04



Ubuntu 18.04

- Ubuntu 18.04 can be downloaded from https://releases.ubuntu.com/bionic/. Choose 64-bit PC (AMD64) desktop image. Clicking the link on Ubuntu page will download an iso file.
- Once you install the VMWare Player or Fusion, you will need to restart the system. Additionally, you will need to enable VT-X virtualization through BIOS Boot menu. Every system (Lenovo, HP, DELL, etc.) has different ways to do, hence it is not possible to include those instructions here. Please look up online on how to do that for your system.
- Once VT-X virtualization is enabled, start your VMWare Player or Fusion, and follow the steps in the video https://youtu.be/lIhRkea8LpA to create a Ubuntu Virtual Machine.



Installing ROS in a new system



Install ROS Melodic

- Follow the steps mentioned in http://wiki.ros.org/melodic/Installation/Ubuntu%C2%A0 to install ros in your new system.
- For CAT Vehicle development, we will require more packages.
- Install these packages:

 sudo apt-get install ros-melodic-controller-manager -y

 sudo apt-get install ros-melodic-ros-control ros-melodic-ros-controllers -y

 sudo apt-get install ros-melodic-gazebo-ros-control -y

 sudo apt-get install ros-melodic-image-transport-* -y

 sudo apt-get install ros-melodic-joystick-drivers -y



Configuring ROS for your system

- When you are using ROS in a shared network, it is required that your ubuntu hostname is unique to avoid name-resolution conflict.
- Change the hostname from catvehicle to your favorite hostname in /etc/hostname folder. E.g. You can choose your UofA netId.

sudo gedit /etc/hostname

* We will also change the name of localhost to refer your computer.

sudo gedit /etc/hosts

and replace catvehicle with your netId.



Configuring ROS for your system

- In .bashrc file set the hostname for ROS_HOSTNAME to the same name you used for system hostname.
 - ➤ gedit ~/.bashrc
 - E.g. If you have set machine's hostname to firstnamelastname, then in .bashrc file, set the ROS_HOSTNAME to firstnamelastname.
 - Search ROS_HOSTNAME in the file .bashrc and change export ROS_HOSTNAME=reu.local to

export ROS_HOSTNAME=firstnamelastname.local



Installing MATLAB



Download MATLAB

In order to download MATLAB, you need to sign up to a MATLAB account with your official University of Arizona email id (aka CATMAIL). After signing in with your U of A email id, download MATLAB installer for MATLAB R2020b.

- Once you install matlab, you need to add an alias in .bashrc for easy access to MATLAB
 - alias matlab="/usr/local/MATLAB/R2020b/bin/matla b"



Configuring ROS for your system

❖ To run roscore on the local machine, change

export ROS_MASTER_URI=http://catvehicle.local:11311/

to

export ROS_MASTER_URI=http://firstnamelastname.local:11311/



Development IDE

- Preferred: Visual Studio Code
- Anaconda/VirtualEnv for Python
- Github Desktop
- Meld Diff Tool