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December 14, 2017

Problem 1:

The given equation

$$\frac{\partial T}{\partial t} + v \frac{\partial T}{\partial y} = \frac{4h}{\rho c_{p} d} (T_{g}(y) - T)$$

is a first order partial differential equation(advection equation) with Boundary condition:

$$T(0,t) = 3$$

and Initial condition:

$$T(y,0) = T_g(y) = (3 + 10e^{\frac{-1}{2y}})$$

the domain of the body is given as

$$0 \le y \le 10$$

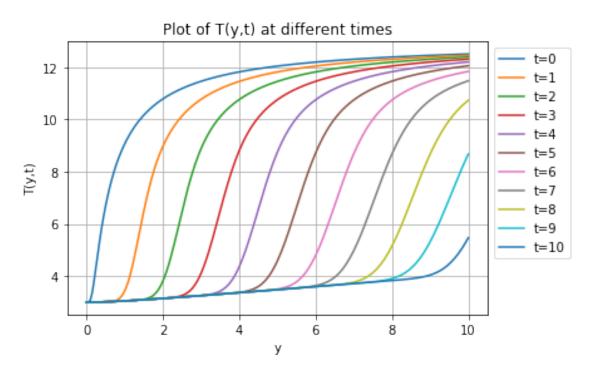
Now we need to discretize the spatial and time domain using first oder fininte differences. As we know the boundary term at y=0, using a Backward difference for spatial coordinate is suitable and a forward difference for time.

The discretized equation can be written as:

$$\frac{T_i^{k+1} - T_i^k}{\Delta t} + v \frac{T_i^k - T_{i-1}^k}{\Delta x} = \frac{4h}{\rho c_v d} (T_g(y_i) - T_i^k)$$

and we need to solve for T_i^{k+1} by advancing in time with this three point stencil

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In [3]: a=0; b=10;
        v=1; h=990; p=1000; cp=4180; d=70/1000;
        c=(4*h)/(p*cp*d);
        dy=0.05; dt=0.005
        def Tg(y):
            if y==0:
                return(3)
            else:
                return((3+10*np.e**(-1/(2*y))))
        def Ta(t):
            return(3)
        tf=10
        T=solve_advection_PDE(a,b,tf,dy,dt,v,c,Ta,Tg,Tg)
In [4]: y = np.linspace(a,b,int((b-a)/dy)+1)
        t = np.linspace(0,tf,int(tf/dt)+1)
        for i in range(0,tf+1):
            z=int(i/dt)
            plt.plot(y,T[:,z],label='t='+str(i))
        plt.legend(bbox_to_anchor=(1,1),loc=0)
        plt.xlabel('y')
        plt.ylabel('T(y,t)')
        plt.title('Plot of T(y,t) at different times')
        plt.grid('on')
        plt.show()
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Problem 2:
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PDE:

$$C\frac{\partial u}{\partial x} = D\frac{\partial^2 u}{\partial x^2}$$

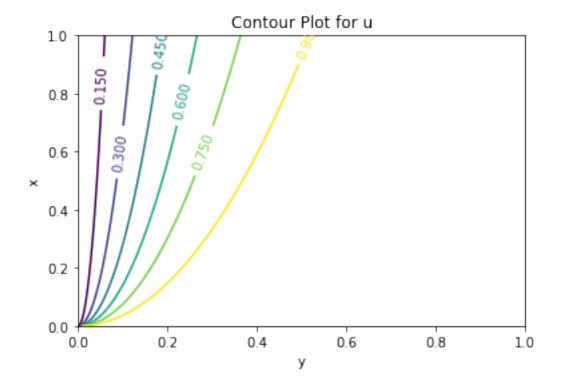
the above PDE is similar to Heat equation with x analogous to t BC:

$$u(x, y = 0) = 0$$

 $u(x, y = 1) = 1$
 $u(x = 0, y) = 1$

a)

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In [5]: def solve_heat_PDE(a,b,tf,dx,dt,c,ua,ub,ut0): #c is constant appearing in the PDE Ut=c*Ua
            if dt>dx**2/(2*c):
                print('The choice of element size and time step is not stable')
            N=int((b-a)/dx); M=int((tf)/dt);
            u=np.zeros(((N+1),(M+1)))#u(x,t)
            for i in range(0,N+1):
                u[i,0]=ut0(i*dx) #assinging the initial condition
            for k in range(0,M+1):
                u[0,k]=ua(k*dt)#assining the BC at x=a
                u[-1,k]=ub(k*dt)#assining the BC at x=b
            for k in range(1,M+1):
                for i in range(1,N):
                    u[i,k]=u[i,k-1]+c*(dt/(dx**2))*(u[i+1,k-1]-2*u[i,k-1]+u[i-1,k-1])
            return(u)
In [6]: a=0;b=1;xf=1;
        dx=0.001; dy=0.01;
        C=1; D=0.05;
        c=D/C;
        def ua(x):
            return(0)
        def ub(x):
            return(1)
        def utO(y):
            return(1)
        u=solve_heat_PDE(a,b,xf,dy,dx,c,ua,ub,ut0)
In [7]: x = np.linspace(a,b,int((b-a)/dy)+1)
        y = np.linspace(0,xf,int(xf/dx)+1)
        X, Y = np.meshgrid(x,y)
        cp=plt.contour(X,Y,np.transpose(u))
        plt.clabel(cp, inline=True,fontsize=10)
        plt.title('Contour Plot for u')
        plt.xlabel('y')
        plt.ylabel('x')
        plt.show()
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b) Finding the analytical solution:

Let us convert the above PDE into a form of heat equation (for convenience) by replacing x with t and y with x we get:

$$\frac{\partial u}{\partial t} = c^2 \frac{\partial^2 u}{\partial x^2}$$

where $c^2 = C/D = 0.05$

we have the following **boundary conditions** for the problem:

$$u(0,t) = 0$$

$$u(1,t) = 1$$

and the initial condition:

$$u(x,0) = 1$$

Now lets contruct the steady state solution for this problem: for steady state we have:

$$\frac{\partial u}{\partial t} = 0 = c^2 \frac{\partial^2 u}{\partial x^2}$$
$$\Rightarrow \frac{\partial^2 u}{\partial x^2} = 0$$

therefore $u_{\infty} = ax + b$

Now u_{∞} needs to satisf the Boundary conditions Therefore $u_{\infty}(0) = u(0,t) = 0 = a * 0 + b$ $\Rightarrow b = 0$

Also $u_{\infty}(1) = u(1,t) = 1 = a * 1 \Rightarrow a = 1 \Rightarrow u_{\infty} = x$

Now, lets say that $\bar{u}(x,t) = u(x,t) - u_{\infty}$

we can observe that $\frac{\partial \bar{u}}{\partial t} = \frac{\partial u}{\partial t}$ and $\frac{\partial^2 \bar{u}}{\partial x^2} = \frac{\partial^2 u}{\partial x^2}$ i.e. $\bar{u}(x,t)$ satisfies the PDE The **boundary conditions** for $\bar{u}(x,t)$ will be:

$$\bar{u}(0,t) = u(0,t) - u_{\infty}(0) = 0 - 0 = 0$$

$$\bar{u}(1,t) = u(1,t) - u_{\infty}(1) = 1 - 1 = 0$$

And **initial condition** $\bar{u}(x,t)$ is:

$$\bar{u}(x,0) = u(0,t) - u_{\infty}(0) = 1 - x$$

Using Separation of variables we have $\bar{u}(x,t) = F(x)G(t)$ Using the PDE we get

$$\frac{\dot{G}}{c^2 G} = \frac{F''}{F} = k$$

If k > 0 we will obtain a trivial solution for F(x)

For $k = -p^2$:

 $F(x) = A\cos(px) + B\sin(px)$

using BCs we get $F_n(x) = sin(n\pi x)$ and $p = n\pi$ similarly we get $G_n(t) = B_n e^{-(n\pi c)^2 t}$

 $\bar{u}(x,t) = \sum_{n=1}^{\infty} B_n(\sin(n\pi x))e^{-(n\pi c)^2 t}$

Now using initial condition we have $\bar{u}(x,0) = 1 - x$

Therefore, B_n are the coefficients of the Fourier sine series of odd periodic extension of 1-x

$$B_n = \frac{2}{1} \left(\int_0^1 (1-x) \sin(n\pi x) dx \right) = \frac{2}{1} \left((1-x) \frac{(-\cos(n\pi x))}{n\pi} \Big|_0^1 - (-1) \frac{(-\sin(n\pi x))}{(n\pi)^2} \Big|_0^1 \right) = \frac{2}{n\pi}$$

$$\bar{u}(x,t) = \sum_{n=1}^{\infty} \frac{2}{n\pi} (\sin(n\pi x)) e^{-(n\pi c)^2 t}$$

 $u(x,t) = \bar{u}(x,t) + u_{\infty}$

$$\Rightarrow u(x,t) = x + \sum_{n=1}^{\infty} \frac{2}{n\pi} (\sin(n\pi x)) e^{-(n\pi c)^2 t}$$

 $\Rightarrow u(x,t) = x + \sum_{n=1}^{\infty} \frac{2}{n\pi} (\sin(n\pi x)) e^{-(n\pi c)^2 t}$ Now let us change back to our initial variables for the given equaition

$$\Rightarrow u(y,t) = y + \sum_{n=1}^{\infty} \frac{2}{n\pi} (\sin(n\pi y)) e^{-(n\pi c)^2 x}$$

In [8]: def exact(x,t,c,N):

for i in range(1,N+1):

s=s+(2/(i*np.pi))*np.sin(i*np.pi*x)*(np.e**(-((i*np.pi*c)**2)*t))

s=s+x

return(s)

In [9]: x1=np.array([0.1,0.5,0.8])

ey=np.zeros((int((b-a)/dy)+1,len(x1)))

N=10 # number of terms in Fourier sine series

Y = np.linspace(a, b, int((b-a)/dy)+1)

for i in range(0,len(x1)):

for j in range(0,int((b-a)/dy)+1):

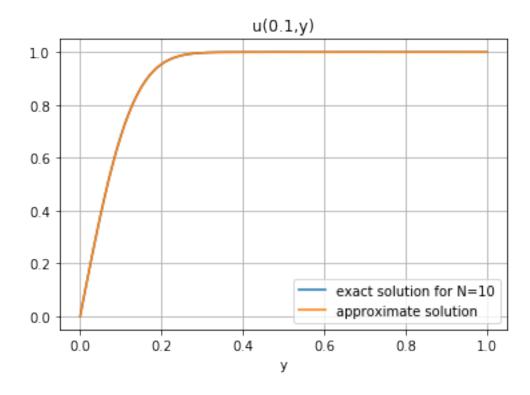
ey[j,i]=exact(Y[j],x1[i],np.sqrt(c),N)

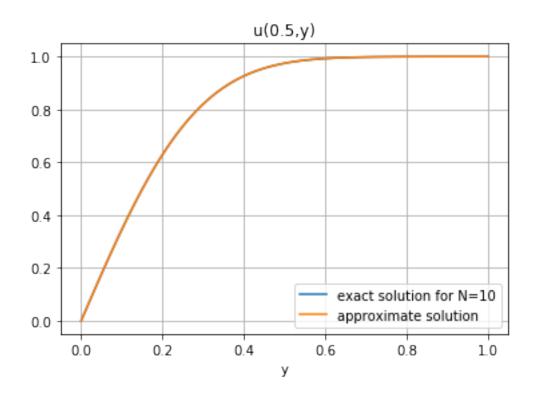
p1,=plt.plot(Y,ey[:,i],label='exact solution for N='+str(N))

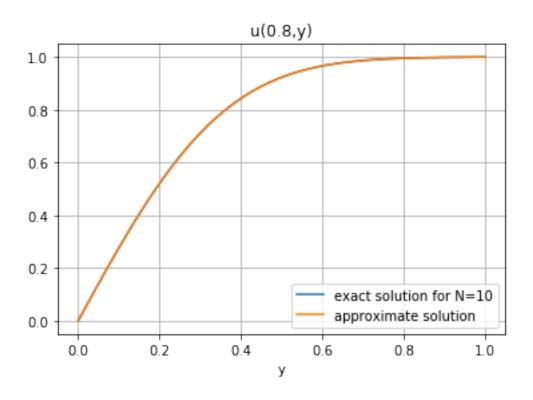
p2,=plt.plot(Y,u[:,int(x1[i]/dx)],label='approximate solution')

plt.legend(handles=[p1,p2])

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plt.title('u('+str(x1[i])+',y)')
plt.xlabel('y')
plt.grid('on')
plt.show()
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As we can observe from the above plots, the analytical solution and the numerical solution are coincident . Therefore we have a good approximation