

ECE 637: Lab 8

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Section 3.1 Report

1. Original and thresholded image:



(a) Original image



(b) Thresholded image

2. Computed RMSE and fidelity values:

Listing 1: RMSE and fidelity for section 3.1

1	house_threshold
2	RMSE: 87.393 Fidelity : 75.420

3. For python code for fidelity function refer to Listing 8 at page 4

For python code refer to Listing 7 at page 4 and Listing 12 at page 9.

Section 4.2 Report

- The three Bayer index matrices of sizes 2x2, 4x4, and 8x8:

Listing 2: Bayer index matrices

```
1 Bayer index matrix: size 2x2
2 [[1 2]
3  [3 0]]
4 Bayer index matrix: size 4x4
5 [[ 5  9  6 10]
6  [13  1 14  2]
7  [ 7 11  4  8]
8  [15  3 12  0]]
9 Bayer index matrix: size 8x8
10 [[21 37 25 41 22 38 26 42]
11  [53  5 57  9 54  6 58 10]
12  [29 45 17 33 30 46 18 34]
13  [61 13 49  1 62 14 50  2]
14  [23 39 27 43 20 36 24 40]
15  [55  7 59 11 52  4 56  8]
16  [31 47 19 35 28 44 16 32]
17  [63 15 51  3 60 12 48  0]]
```

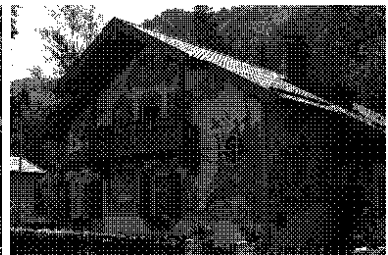
- The three halftoned images:



(a) Halftoned image for 2x2



(b) Halftoned image for 4x4



(c) Halftoned image for 8x8

- RMSE and Fidelity for each of the three halftoned images:

Listing 3: RMSE and fidelity for 2x2

```
1 house_dither2
2 RMSE:97.669    Fidelity:48.217
```

Listing 4: RMSE and fidelity for 4x4

```
1 house_dither4
2 RMSE:101.007   Fidelity:15.524
```

Listing 5: RMSE and fidelity for 8x8

```
1 house_dither8
2 RMSE:100.915   Fidelity:15.087
```

For python refer to Listing 9 at page 6, Listing 10 at page 7 and Listing 12 at page 9.

Section 5 Report

- For python code refer to Listing 11 at page 7
- The error diffusion result:



Figure 3: Error diffusion result

- RMSE and fidelity results:

Listing 6: RMSE and fidelity

```
1 house_error_diff
2 RMSE:98.847    Fidelity :13.640
```

- Table of RMSE and fidelity

Method	RMSE	Fidelity
Simple thresholding	87.393	75.420
Order dithering 2x2	97.669	48.217
Order dithering 4x4	101.007	15.524
Order dithering 8x8	100.915	15.087
Error diffusion	98.847	13.640

As we can observe visually from the halftoned images produced using different methods, the image contours improved when we used order dithering. However, the RMSE metric increases in this case which indicates that RMSE is not an appropriate metric. For the case of Fidelity the metric score decreases as we increase the size of dithering and visually the image contours improve and we can see smoother grayscale colors. Therefore, fidelity is a good metric in this case. Fidelity score is the lowest for Error diffusion method and visually the image also looks the closest to the input image out of all the halftoned images.

Appendix

Got to [git repo](#) for complete code.

Listing 7: Python code for section 3

```
1  #!/usr/bin/env python3
2  # -*- coding: utf-8 -*-
3  """
4  @author: rahul
5  ECE637 DIP-1: lab 8 Halftoning
6  section 3
7  """
8
9  import numpy as np
10 from PIL import Image
11 import os, sys
12 import matplotlib.pyplot as plt
13 from matplotlib import cm
14
15 from utils import RMSE, Fidelity
16
17 def get_base(filename):
18     base = os.path.basename(filename).split('.')[0]
19     return base
20
21 def main(input_img, Threshold):
22     #compute binary image using threshold
23     out_img = (255*(input_img>Threshold).astype(np.int)).astype(np.uint8)
24     #compute rmse
25     rmse = RMSE(input_img, out_img)
26     fidelity = Fidelity(input_img, out_img)
27     return out_img, rmse, fidelity
28
29 if __name__=="__main__":
30     input_img_name = sys.argv[1]
31     output_img_name = get_base(input_img_name)+ '_threshold '
32     Threshold = 127.0
33
34     im = Image.open(input_img_name)
35     input_img = np.array(im)
36
37     out_img, rmse, fidelity = main(input_img, Threshold)
38
39     #print info
40     print(output_img_name)
41     print("RMSE:%0.3f \t Fidelity:%0.3f"%(rmse, fidelity))
42
43     #save plots and images
44     gray = cm.get_cmap('gray',256)
45     plt.figure(frameon=False)
46     plt.imshow(out_img, cmap=gray, interpolation='none')
47     plt.axis('off')
48     plt.savefig(output_img_name+'.pdf', bbox_inches='tight', pad_inches=0)
49
50     out_im = Image.fromarray(out_img)
51     out_im.save(output_img_name+'.tif')
```

Listing 8: Python code for RMSE and Fidelity

```

1 #!/usr/bin/env python3
2  #-*- coding: utf-8 -*-
3  """
4  @author: rahul
5  ECE637 DIP-1: lab 8 Halftoning
6  utility file for image metrics
7  """
8
9  import numpy as np
10 from scipy.signal import convolve2d
11
12 def conv2d(X_img, conv_filter):
13     "apply conv with zero padding"
14     filter_size, _ = conv_filter.shape
15     filter_half_wd = filter_size//2
16     theta = conv_filter.flatten()
17     ht, wd = X_img.shape
18     padded_img = np.zeros((ht+2*filter_half_wd, wd+2*filter_half_wd))
19     padded_img[filter_half_wd:-filter_half_wd, filter_half_wd:-filter_half_wd] =
        X_img
20     out_img = np.zeros((ht, wd))
21     for row in range(ht):
22         for col in range(wd):
23             x = padded_img[row : row + 2*filter_half_wd + 1,
24                             col : col + 2*filter_half_wd + 1]
25             out_img[row, col] = np.dot(x.flatten(), theta)
26     return out_img
27
28 def Un_gamma_correct(img, gamma):
29     lin = 255.*((img/255.）**gamma)
30     return lin.astype(np.uint8)
31
32 def Scale_to_equal_brightness(img):
33     return Un_gamma_correct(img, 1./3.)
34
35 def LPF(img, sigma=np.sqrt(2), size=7):
36     "pass image through low-pass filter"
37     #make the filter
38     h = np.zeros((size, size))
39     for r in range(size):
40         for c in range(size):
41             i = r - (size//2)
42             j = c - (size//2)
43             h[r, c] = np.exp(-1.0*(i**2+j**2)/(2.0*(sigma**2)))
44     h /= np.sum(h) #normalize
45     #convolve filter
46     out_img = convolve2d(img, h, mode='same')
47     #out_img = conv2d(img, h)
48     #rescale to 0-255
49     out_img -= out_img.min()
50     out_img *= (255./out_img.max())
51     return out_img.astype(np.uint8)
52
53 def RMSE(original_img, binary_image):
54     "compute rmse error between two images"
55     h, w = original_img.shape
56     assert (h, w) == binary_image.shape
57     rmse = (1./(h*w))*np.sum((original_img.astype(np.float32) -

```

```

58         binary_image.astype(np.float32))**2)
59     return np.sqrt(rmse)
60
61 def Fidelity(original_img, binary_img):
62     "Compute image fidelity metric"
63     gamma = 2.2
64     # un-gamma correct the images
65     original_lin = Un_gamma_correct(original_img, gamma)
66     binary_lin = Un_gamma_correct(binary_img, gamma)
67     #print(np.linalg.norm(binary_lin-binary_img))
68     # LPF
69     original_lin_lpf = LPF(original_lin)
70     binary_lin_lpf = LPF(binary_lin)
71     assert original_lin_lpf.shape==original_img.shape
72     # scale to equal brightness (cube-root)
73     f_tilde = Scale_to_equal_brightness(original_lin_lpf)
74     b_tilde = Scale_to_equal_brightness(binary_lin_lpf)
75     #rmse
76     fidelity = RMSE(f_tilde, b_tilde)
77     return fidelity

```

Listing 9: Python code for section 4

```

1  #!/usr/bin/env python3
2  #- coding: utf-8 -*-
3  """
4  @author: rahul
5  ECE637 DIP-1: lab 8 Halftoning
6  section 4
7  """
8
9  import numpy as np
10 from PIL import Image
11 import os, sys
12 import matplotlib.pyplot as plt
13 from matplotlib import cm
14
15 from utils import RMSE, Fidelity
16
17 def get_base(filename):
18     base = os.path.basename(filename).split('.')[0]
19     return base
20
21 def Dither_mat(N):
22     if N==2:
23         return np.array([[1,2],[3,0]])
24     else:
25         return np.block([[4*Dither_mat(N//2) + 1, 4*Dither_mat(N//2) + 2 ],
26                           [4*Dither_mat(N//2) + 3, 4*Dither_mat(N//2)      ]])
27
28 def Threshold_mat(dither_mat):
29     N,_=dither_mat.shape
30     T = np.zeros((N,N))
31     for i in range(N):
32         for j in range(N):
33             T[i,j] = 255.0*((dither_mat[i,j] + 0.5)/N**2)
34     return T
35
36 def main(input_img, dither_size, gamma):

```

```

37 h,w = input_img.shape
38 linear_img = 255.*(input_img/255.）**gamma
39 dither_mat = Dither_mat(dither_size)
40 threshold_mat = Threshold_mat(dither_mat)
41
42 out_img = np.zeros((h,w))
43 for i in range(h):
44     for j in range(w):
45         r = i%dither_size; c = j%dither_size
46         if linear_img[i,j] > threshold_mat[r,c]:
47             out_img[i,j] = 255
48         else:
49             out_img[i,j] = 0
50     return out_img.astype(np.uint8)
51
52 if __name__=="__main__":
53     input_img_name = sys.argv[1]
54     dither_size = np.int(sys.argv[2])
55     output_img_name = get_base(input_img_name)+ '_dither'+str(dither_size)
56     gamma=2.2
57     print(output_img_name)
58
59     im = Image.open(input_img_name)
60     input_img = np.array(im)
61
62     out_img= main(input_img, dither_size, gamma)
63     #compute rmse
64     rmse = RMSE(input_img, out_img)
65     fidelity = Fidelity(input_img, out_img)
66     #print info
67     print("RMSE:%0.3f \t Fidelity:%0.3f"%(rmse, fidelity))
68
69     #save plots and images
70     gray = cm.get_cmap('gray',256)
71     plt.figure(frameon=False)
72     plt.imshow(out_img, cmap=gray, interpolation='none')
73     plt.axis('off')
74     plt.savefig(output_img_name+'.pdf', bbox_inches='tight', pad_inches=0)
75
76     out_im = Image.fromarray(out_img)
77     out_im.save(output_img_name+'.tif')

```

Listing 10: Python code for printing bayer matrices

```

1  #!/usr/bin/env python3
2  # -*- coding: utf-8 -*-
3  """
4  Created on Thu Apr  8 17:15:10 2021
5
6  @author: rahul
7  """
8  from order_dithering import Dither_mat
9
10 for i in [2,4,8]:
11     d = Dither_mat(i);
12     print('Bayer index matrix: size %d%d'%(i,i))
13     print(d)

```

Listing 11: Python code for section 5

```

1 #!/usr/bin/env python3
2  #-*- coding: utf-8 -*-
3  """
4  @author: rahul
5  ECE637 DIP-1: lab 8 Halftoning
6  section 5
7  """
8
9  import numpy as np
10 from PIL import Image
11 import os, sys
12 import matplotlib.pyplot as plt
13 from matplotlib import cm
14
15 from utils import RMSE, Fidelity
16
17 def get_base(filename):
18     base = os.path.basename(filename).split('.')[0]
19     return base
20
21 def main(input_img, gamma, Threshold):
22     h,w = input_img.shape
23     linear_img = 255.*(input_img/255.）**gamma
24     out_img = np.zeros((h,w))
25     H = np.array([7., 3., 5., 1.])/16.
26     K = [0, 1, 1, 1]
27     L = [1, -1, 0, 1]
28     for i in range(h):
29         for j in range(w):
30             old_pxl = linear_img[i,j]
31             q = 255. if old_pxl>Threshold else 0.
32             out_img[i, j] = q
33             e = old_pxl - q
34             for h_kl,k,l in zip(H,K,L):
35                 r = i+k; c = j+l
36                 if r<h and r>=0 and c<w and c>=0:
37                     linear_img[r,c] += e*h_kl
38     return out_img.astype(np.uint8)
39
40 if __name__=="__main__":
41     input_img_name = sys.argv[1]
42     output_img_name = get_base(input_img_name)+ '_error_diff'
43     gamma=2.2
44     Threshold = 127.
45     print(output_img_name)
46
47     im = Image.open(input_img_name)
48     input_img = np.array(im)
49
50     out_img= main(input_img, gamma, Threshold)
51     #compute rmse
52     rmse = RMSE(input_img, out_img)
53     fidelity = Fidelity(input_img, out_img)
54     #print info
55     print("RMSE:%0.3f \t Fidelity:%0.3f"%(rmse, fidelity))
56
57     #save plots and images
58     gray = cm.get_cmap('gray',256)

```



```

59 plt.figure(frameon=False)
60 plt.imshow(out_img, cmap=gray, interpolation='none')
61 plt.axis('off')
62 plt.savefig(output_img_name+'.pdf', bbox_inches='tight', pad_inches=0)
63
64 out_im = Image.fromarray(out_img)
65 out_im.save(output_img_name+'.tif')

```

Listing 12: Bash code for running python code

```

1  #!/bin/bash
2
3  img_dir=../..
4
5  #section 3
6  python simple_thresholding.py "$img_dir"/house.tif | tee sec3.log
7  mv ./*.tif ./output/sec3/
8  mv ./*.pdf ./output/sec3/
9  mv ./*.log ./output/sec3/
10 echo 'section 3 done'
11
12 #section 4
13 python print_dither.py | tee dither_mats.log
14 for (( size=2; size<=8; size*=2 ))
15 do
16 python order_dithering.py "$img_dir"/house.tif $size | tee dither_"$size".log
17 done
18 mv ./*.tif output/sec4/
19 mv ./*.pdf output/sec4/
20 mv ./*.log output/sec4/
21 echo 'section 4 done'
22
23 #section 5
24 python error_diffusion.py "$img_dir"/house.tif | tee sec5.log
25 mv ./*.pdf output/sec5/
26 mv ./*.tif output/sec5/
27 mv ./*.log output/sec5
28 echo 'section 5 done'

```