

# DL\_Lab\_Exercises

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## 1 ECE 637 Deep Learning Lab Exercises

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### 2 Section 1

#### 2.1 Exercise 1.1

1. Create two lists, A and B: A contains 3 arbitrary numbers and B contains 3 arbitrary strings.
2. Concatenate two lists into a bigger list and name that list C.
3. Print the first element in C.
4. Print the second last element in C via negative indexing.
5. Remove the second element of A from C.
6. Print C again.

```
[ ]: # ----- YOUR CODE -----  
A = [1,2,3]  
B = ['a', 'b', 'c']  
C = A + B  
print(C[0])  
print(C[-2])  
C.remove(A[1])  
print(C)
```

1

b

[1, 3, 'a', 'b', 'c']

#### 2.2 Exercise 1.2

In this exercise, you will use a low-pass IIR filter to remove noise from a sine-wave signal.

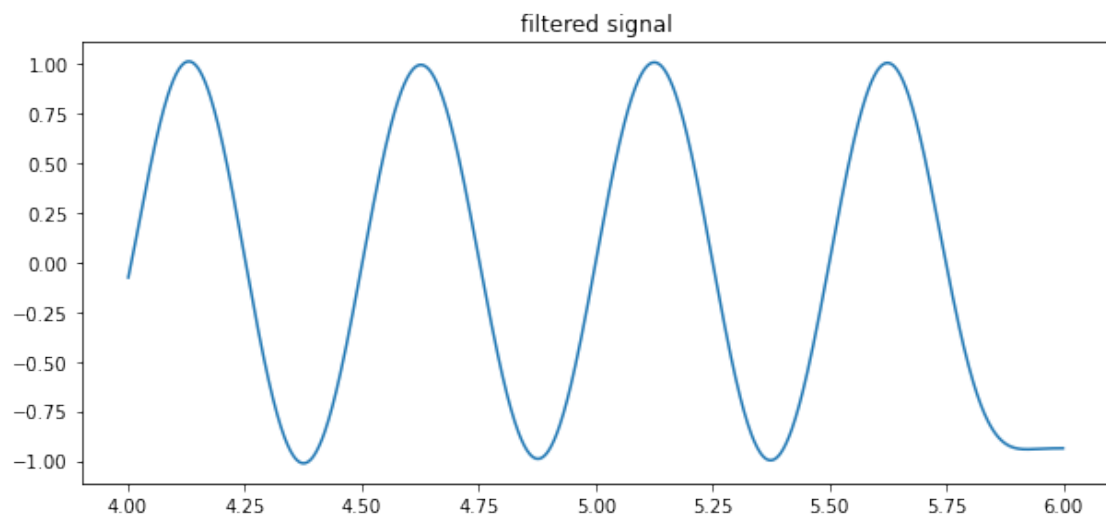
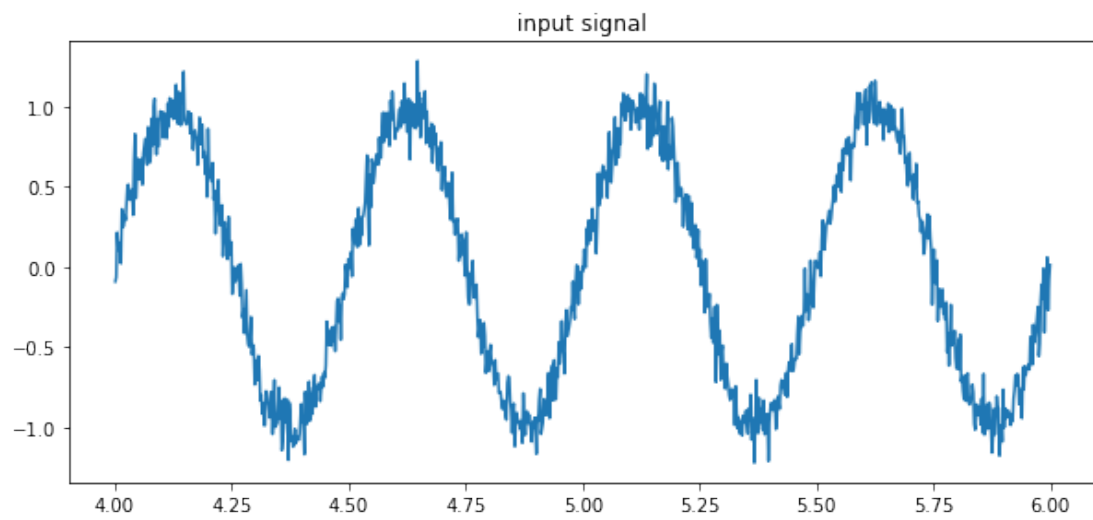
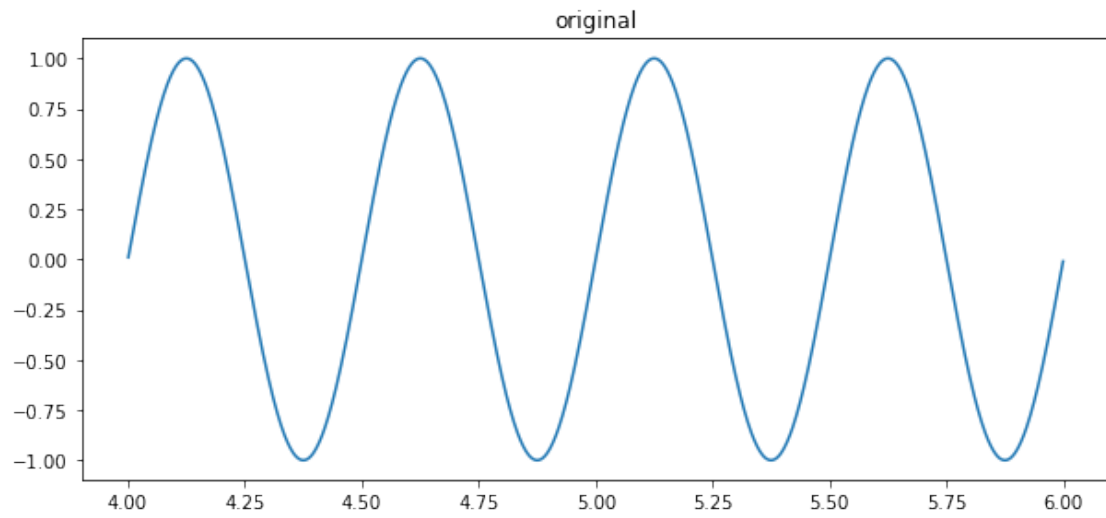
You should organize your plots in a 3x1 subplot format.

1. Generate a discrete-time signal,  $x$ , by sampling a 2Hz continuous time sine wave signal with peak amplitude 1 from time 0s to 10s and at a sampling frequency of 500 Hz. Display the signal,  $x$ , from time 4s to 6s in the first row of a 3x1 subplot with the title "original signal".

2. Add Gaussian white random noise with 0 mean and standard deviation 0.1 to  $x$  and call it  $x_n$ . Display  $x_n$  from 4s to 6s on the second row of the subplot with the title "input signal".
3. Design a low-pass butterworth IIR filter of order 5 with a cut-off frequency of 4Hz, designed to filter out the noise. Hint: Use the `signal.butter` function and note that the frequencies are relative to the Nyquist frequency. Apply the IIR filter to  $x_n$ , and name the output  $y$ . Hint: Use `signal.filtfilt` function. Plot  $y$  from 4s to 6s on the third row of the subplot with the title "filtered signal".

```
[ ]: import numpy as np                # import the numpy packages and use a
      ↪ shorter aliasing name
import matplotlib.pyplot as plt      # again import the matplotlib's pyplot
      ↪ packages
from scipy import signal             # import a minor package signal from
      ↪ scipy
plt.figure(figsize=(10, 15))         # fix the plot size

# ----- YOUR CODE -----
f=2
fs=500
t = np.linspace(0,10,fs*10)
t = t[4*fs:6*fs]
x = np.sin(2*np.pi*f*t)
gn = np.random.normal(0,0.1,np.size(t))
x_n = x + gn
fc = 4
w = fc/(fs/2)
b,a = signal.butter(5,w)
y = signal.filtfilt(b,a,x_n)
plt.subplot(3,1,1)
plt.plot(t,x)
plt.title('original')
plt.subplot(3,1,2)
plt.plot(t,x_n)
plt.title('input signal')
plt.subplot(3,1,3)
plt.plot(t,y)
plt.title('filtered signal')
plt.show()
```



## 3 Section 2

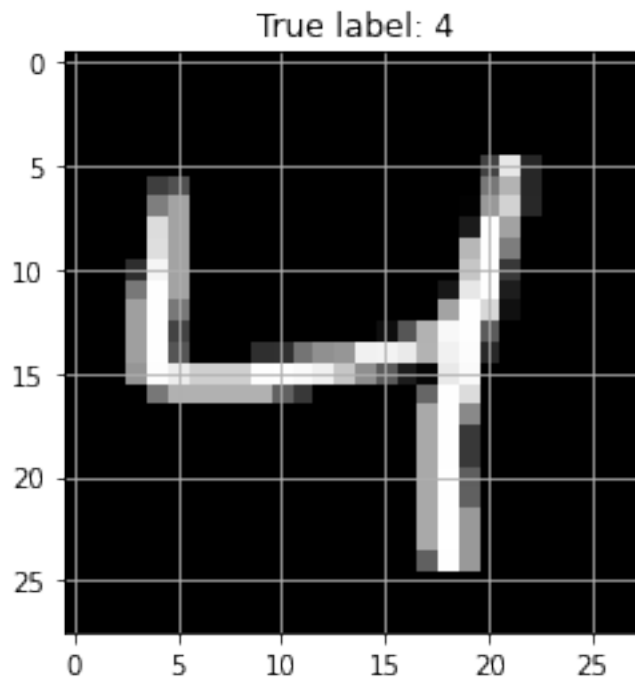
### 3.1 Exercise 2.1

- Plot the third image in the test data set
- Find the corresponding label for the this image and make it the title of the figure

```
[ ]: import keras
from keras.datasets import mnist
(train_images, train_labels), (test_images, test_labels) = mnist.load_data()

train_images = train_images.reshape((60000, 28, 28, 1))
test_images = test_images.reshape((10000, 28, 28, 1))

# ----- YOUR CODE -----
k = 2
image = train_images[k,:,:,:]
label = train_labels[k]
plt.imshow(image, cmap='gray')
ax = plt.gca()
ax.grid(b=None)
plt.title('True label: '+str(label))
plt.show()
```



## 3.2 Exercise 2.2

It is usually helpful to have an accuracy plot as well as a loss value plot to get an intuitive sense of how effectively the model is being trained.

- Add code to this example for plotting two graphs with the following requirements:
- Use a 1x2 subplot with the left subplot showing the loss function and right subplot showing the accuracy.
- For each graph, plot the value with respect to epochs. Clearly label the x-axis, y-axis and the title.

(Hint: The value of of loss and accuracy are stored in the hist variable. Try to print out hist.history and hist.history.keys().)

```
[ ]: import keras
from keras.datasets import mnist
from keras import models
from keras import layers
from keras.utils import to_categorical

(train_images, train_labels), (test_images, test_labels) = mnist.load_data()

train_images = train_images.reshape((60000, 28, 28, 1))
test_images = test_images.reshape((10000, 28, 28, 1))

network = models.Sequential()
network.add(layers.Flatten(input_shape=(28, 28, 1)))
network.add(layers.Dense(512, activation='relu'))
network.add(layers.Dense(10, activation='softmax'))

network.summary()

network.compile(optimizer='rmsprop', loss='categorical_crossentropy',
               metrics=['accuracy'])

train_images_nor = train_images.astype('float32') / 255
test_images_nor = test_images.astype('float32') / 255

train_labels_cat = to_categorical(train_labels)
test_labels_cat = to_categorical(test_labels)

hist = network.fit(train_images_nor, train_labels_cat, epochs=5, batch_size=128)

test_loss, test_acc = network.evaluate(test_images_nor, test_labels_cat)
print('test_accuracy:', test_acc)
```

Model: "sequential"

-----

Layer (type)	Output Shape	Param #
--------------	--------------	---------

```

=====
flatten (Flatten)                (None, 784)                0
-----
dense (Dense)                    (None, 512)               401920
-----
dense_1 (Dense)                  (None, 10)                5130
=====

Total params: 407,050
Trainable params: 407,050
Non-trainable params: 0

-----
Epoch 1/5
469/469 [=====] - 2s 2ms/step - loss: 0.4352 -
accuracy: 0.8749
Epoch 2/5
469/469 [=====] - 1s 2ms/step - loss: 0.1149 -
accuracy: 0.9668
Epoch 3/5
469/469 [=====] - 1s 2ms/step - loss: 0.0688 -
accuracy: 0.9793
Epoch 4/5
469/469 [=====] - 1s 2ms/step - loss: 0.0478 -
accuracy: 0.9861
Epoch 5/5
469/469 [=====] - 1s 2ms/step - loss: 0.0341 -
accuracy: 0.9896
313/313 [=====] - 1s 2ms/step - loss: 0.0802 -
accuracy: 0.9740
test_accuracy: 0.9739999771118164

```

```

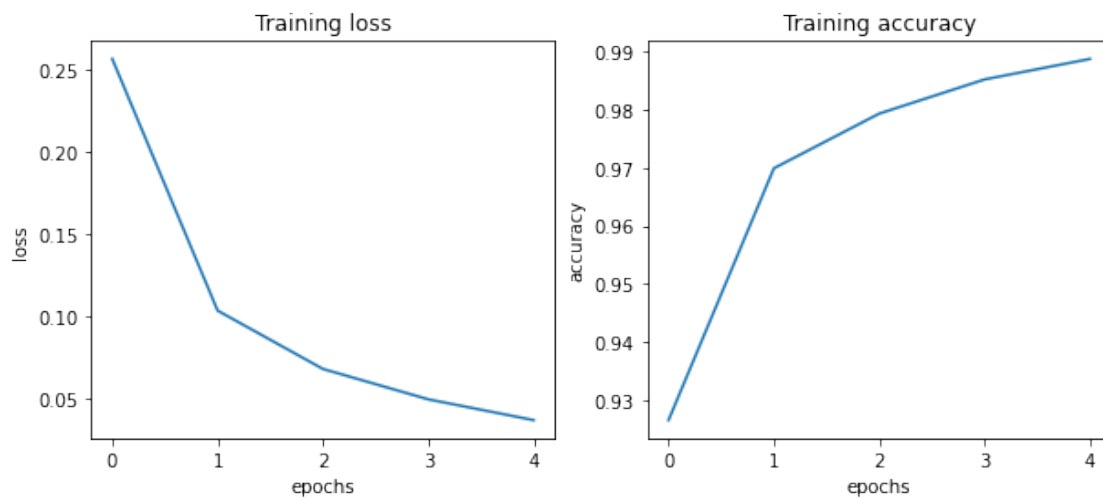
[: import matplotlib.pyplot as plt

plt.figure(figsize=(10, 4))

# ----- YOUR CODE -----
eps = np.arange(5)
plt.subplot(1,2,1)
#plot of loss
plt.plot(eps, hist.history['loss'])
plt.xlabel('epochs')
plt.ylabel('loss')
plt.title('Training loss')
#plot of accuracy
plt.subplot(1,2,2)
plt.plot(eps, hist.history['accuracy'])
plt.xlabel('epochs')
plt.ylabel('accuracy')

```

```
plt.title('Training accuracy')
plt.show()
```



### 3.3 Exercise 2.3

Use the dense network from Section 2 as the basis to construct of a deeper network with

- 5 dense hidden layers with dimensions [512, 256, 128, 64, 32] each of which uses a ReLU non-linearity

**Question:** Will the accuracy on the testing data always get better if we keep making the neural network larger?

*No, the accuracy on testing data will not always get better if we keep making the neural network larger. This is because as we increase the model complexity, the model will tend to overfit to the training data and hence result in poor testing accuracy*

```
[ ]: import keras
from keras import models
from keras import layers

# ----- YOUR CODE -----
network = models.Sequential()
network.add(layers.Flatten(input_shape=(28, 28, 1)))
network.add(layers.Dense(512, activation='relu'))
network.add(layers.Dense(256, activation='relu'))
network.add(layers.Dense(128, activation='relu'))
network.add(layers.Dense(64, activation='relu'))
network.add(layers.Dense(32, activation='relu'))
network.add(layers.Dense(10, activation='softmax'))

network.summary()
```

Model: "sequential\_1"

Layer (type)	Output Shape	Param #
flatten_1 (Flatten)	(None, 784)	0
dense_2 (Dense)	(None, 512)	401920
dense_3 (Dense)	(None, 256)	131328
dense_4 (Dense)	(None, 128)	32896
dense_5 (Dense)	(None, 64)	8256
dense_6 (Dense)	(None, 32)	2080
dense_7 (Dense)	(None, 10)	330
Total params: 576,810		
Trainable params: 576,810		
Non-trainable params: 0		

```
[ ]: import keras
from keras.datasets import mnist
from keras.utils import to_categorical

(train_images, train_labels), (test_images, test_labels) = mnist.load_data()

train_images = train_images.reshape((60000, 28, 28, 1))
test_images = test_images.reshape((10000, 28, 28, 1))

network.compile(optimizer='rmsprop', loss='categorical_crossentropy',
    metrics=['accuracy'])

train_images_nor = train_images.astype('float32') / 255
test_images_nor = test_images.astype('float32') / 255

train_labels_cat = to_categorical(train_labels)
test_labels_cat = to_categorical(test_labels)

hist = network.fit(train_images_nor, train_labels_cat, epochs=5, batch_size=128)

test_loss, test_acc = network.evaluate(test_images_nor, test_labels_cat)
print('test_accuracy:', test_acc)
```

Epoch 1/5



```

469/469 [=====] - 2s 3ms/step - loss: 0.5690 -
accuracy: 0.8149
Epoch 2/5
469/469 [=====] - 1s 3ms/step - loss: 0.1081 -
accuracy: 0.9689
Epoch 3/5
469/469 [=====] - 1s 3ms/step - loss: 0.0714 -
accuracy: 0.9792
Epoch 4/5
469/469 [=====] - 1s 3ms/step - loss: 0.0522 -
accuracy: 0.9846
Epoch 5/5
469/469 [=====] - 1s 3ms/step - loss: 0.0377 -
accuracy: 0.9894
313/313 [=====] - 1s 2ms/step - loss: 0.0908 -
accuracy: 0.9761
test_accuracy: 0.9761000275611877

```

## 4 Section 3

### 4.1 Exercise 3.1

In this exercise, you will access the relationship between the feature extraction layer and classification layer. The example above uses two sets of convolutional layers and pooling layers in the feature extraction layer and two dense layers in the classification layers. The overall performance is around 98% for both training and test dataset. In this exercise, try to create a similar CNN network with the following requirements:

- Achieve the overall accuracy higher than 99% for training and testing dataset.
- Keep the total number of parameters used in the network lower than 100,000.

```

[ ]: import keras
from keras import models
from keras import layers

network = models.Sequential()

# ---- Feature extraction section
# First Layer
network.add(layers.Conv2D(16, (3, 3), activation='relu', input_shape=(28, 28, 1)))
network.add(layers.Conv2D(16, (3, 3), activation='relu', input_shape=(28, 28, 1)))
network.add(layers.MaxPooling2D((2, 2)))
# Second Layer
network.add(layers.Conv2D(32, (3, 3), activation='relu'))
network.add(layers.Conv2D(32, (3, 3), activation='relu'))
network.add(layers.MaxPooling2D((2, 2)))

```

```

# ---- Classification section
# Rearrange the data
network.add(layers.Flatten())
# Third Layer
network.add(layers.Dense(128, activation='relu'))
# Third Layer
network.add(layers.Dense(64, activation='relu'))
# Fourth Layer
network.add(layers.Dense(10, activation='softmax'))

network.summary()

```

Model: "sequential\_2"

Layer (type)	Output Shape	Param #
conv2d (Conv2D)	(None, 26, 26, 16)	160
conv2d_1 (Conv2D)	(None, 24, 24, 16)	2320
max_pooling2d (MaxPooling2D)	(None, 12, 12, 16)	0
conv2d_2 (Conv2D)	(None, 10, 10, 32)	4640
conv2d_3 (Conv2D)	(None, 8, 8, 32)	9248
max_pooling2d_1 (MaxPooling2D)	(None, 4, 4, 32)	0
flatten_2 (Flatten)	(None, 512)	0
dense_8 (Dense)	(None, 128)	65664
dense_9 (Dense)	(None, 64)	8256
dense_10 (Dense)	(None, 10)	650

Total params: 90,938  
 Trainable params: 90,938  
 Non-trainable params: 0

```

[ ]: from keras.datasets import mnist
      from keras.utils import to_categorical

      (train_images, train_labels), (test_images, test_labels) = mnist.load_data()

```

```

train_images = train_images.reshape((60000, 28, 28, 1))
train_images_nor = train_images.astype('float32') / 255
test_images = test_images.reshape((10000, 28, 28, 1))
test_images_nor = test_images.astype('float32') / 255

train_labels_cat = to_categorical(train_labels)
test_labels_cat = to_categorical(test_labels)

network.compile(optimizer='rmsprop', loss='categorical_crossentropy',
    metrics=['accuracy'])
network.fit(train_images_nor, train_labels_cat, epochs=5, batch_size=128)

test_loss, test_acc = network.evaluate(test_images_nor, test_labels_cat)
print('test_accuracy:', test_acc)

```

```

Epoch 1/5
469/469 [=====] - 4s 5ms/step - loss: 0.5349 -
accuracy: 0.8270
Epoch 2/5
469/469 [=====] - 2s 5ms/step - loss: 0.0647 -
accuracy: 0.9801
Epoch 3/5
469/469 [=====] - 2s 5ms/step - loss: 0.0371 -
accuracy: 0.9885
Epoch 4/5
469/469 [=====] - 2s 5ms/step - loss: 0.0278 -
accuracy: 0.9906
Epoch 5/5
469/469 [=====] - 2s 5ms/step - loss: 0.0191 -
accuracy: 0.9938
313/313 [=====] - 1s 2ms/step - loss: 0.0253 -
accuracy: 0.9923
test_accuracy: 0.9922999739646912

```

## 5 Section 4

### 5.1 Exercise 4.1

In this exercise you will need to create the entire neural network that does image denoising tasks. Try to mimic the code provided above and follow the structure as provided in the instructions below.

**Task 1:** Create the datasets 1. Import necessary packages 2. Load the MNIST data from Keras, and save the training dataset images as `train_images`, save the test dataset images as `test_images` 3. Add additive white gaussian noise to the train images as well as the test images and save the noisy images to `train_images_noisy` and `test_images_noisy` respectively. The noise should have mean value 0, and standard deviation 0.4. (Hint: Use [np.random.normal](#)) 4. Show

the first image in the training dataset as well as the test dataset (plot the images in 1 x 2 subplot form)

```
[ ]: from keras.datasets import mnist
from keras.utils import to_categorical

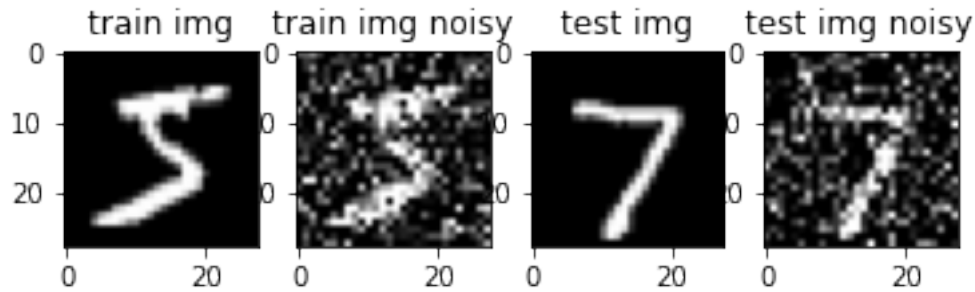
(train_images, train_labels), (test_images, test_labels) = mnist.load_data()

#add noise
train_images_noisy = np.clip(train_images + 255*np.random.normal(0,0.4,
    ↳train_images.shape),0.,255.)
test_images_noisy = np.clip(test_images + 255*np.random.normal(0,0.4,
    ↳test_images.shape),0.,255.)

train_images_noisy = train_images_noisy.reshape((60000, 28, 28, 1))
train_images_noisy_nor = train_images_noisy.astype('float32') / 255
test_images_noisy = test_images_noisy.reshape((10000, 28, 28, 1))
test_images_noisy_nor = test_images_noisy.astype('float32') / 255

train_images = train_images.reshape((60000, 28, 28, 1))
train_images_nor = train_images.astype('float32') / 255
test_images = test_images.reshape((10000, 28, 28, 1))
test_images_nor = test_images.astype('float32') / 255

#plot images
#training image
plt.subplot(1,4,1)
plt.imshow(train_images[0,:,:,:],cmap='gray')
plt.title('train img')
plt.subplot(1,4,2)
plt.imshow(train_images_noisy[0,:,:,:],cmap='gray')
plt.title('train img noisy')
#testing image
plt.subplot(1,4,3)
plt.imshow(test_images[0,:,:,:],cmap='gray')
plt.title('test img')
plt.subplot(1,4,4)
plt.imshow(test_images_noisy[0,:,:,:],cmap='gray')
plt.title('test img noisy')
plt.show()
```



**Task 2:** Create the neural network model 1. Create a sequential model called encoder with the following layers sequentially: \* convolutional layer with 32 output channels, 3x3 kernel size, and the padding convention 'same' with 'relu' activation function. \* max pooling layer with 2x2 kernel size \* convolutional layer with 16 output channels, 3x3 kernel size, and the padding convention 'same' with 'relu' activation function. \* max pooling layer with 2x2 kernel size \* convolutional layer with 8 output channels, 3x3 kernel size, and the padding convention 'same' with 'relu' activation function and name the layer as 'convOutput'. \* flatten layer \* dense layer with output dimension as encoding\_dim with 'relu' activation function. 2. Create a sequential model called decoder with the following layers sequentially: \* dense layer with the input dimension as encoding\_dim and the output dimension as the product of the output dimensions of the 'convOutput' layer. \* reshape layer that convert the tensor into the same shape as 'convOutput' \* convolutional layer with 8 output channels, 3x3 kernel size, and the padding convention 'same' with 'relu' activation function. \* upsampling layer with 2x2 kernel size \* convolutional layer with 16 output channels, 3x3 kernel size, and the padding convention 'same' with 'relu' activation function. \* upsampling layer with 2x2 kernel size \* convolutional layer with 32 output channels, 3x3 kernel size, and the padding convention 'same' with 'relu' activation function \* convolutional layer with 1 output channels, 3x3 kernel size, and the padding convention 'same' with 'sigmoid' activation function 3. Create a sequential model called autoencoder with the following layers sequentially: \* encoder model \* decoder model

```
[ ]: # ----- YOUR CODE -----
encoding_dim = 32

# Build Encoder
encoder = models.Sequential()
encoder.add(layers.Conv2D(32, (3, 3),padding='same', activation='relu',
    ↳input_shape= train_images_noisy_nor.shape[1:]))
encoder.add(layers.MaxPooling2D((2, 2)))
encoder.add(layers.Conv2D(16, (3, 3),padding='same', activation='relu'))
encoder.add(layers.MaxPooling2D((2, 2)))
encoder.add(layers.Conv2D(8, (3, 3),padding='same',
    ↳activation='relu',name='convOutput'))
encoder.add(layers.Flatten())
encoder.add(layers.Dense(encoding_dim, activation='relu'))

# shape considerations
```

```

convShape = encoder.get_layer('convOutput').output_shape[1:]
denseShape = convShape[0]*convShape[1]*convShape[2]

# Build Decoder
decoder = models.Sequential()
decoder.add(layers.Dense(denseShape, input_shape=(encoding_dim,)))
decoder.add(layers.Reshape(convShape))
decoder.add(layers.Conv2D(8, (3, 3), activation='relu', padding='same'))
decoder.add(layers.UpSampling2D((2, 2)))
decoder.add(layers.Conv2D(16, (3, 3), activation='relu', padding='same'))
decoder.add(layers.UpSampling2D((2, 2)))
decoder.add(layers.Conv2D(32, (3, 3), activation='relu', padding='same'))
decoder.add(layers.Conv2D(1, (3, 3), activation='sigmoid', padding='same'))

# Build Autoencoder
autoencoder = models.Sequential()
autoencoder.add(encoder)
autoencoder.add(decoder)

```

```

[: encoder.summary()
decoder.summary()
autoencoder.summary()

```

Model: "sequential\_3"

Layer (type)	Output Shape	Param #
conv2d_4 (Conv2D)	(None, 28, 28, 32)	320
max_pooling2d_2 (MaxPooling2)	(None, 14, 14, 32)	0
conv2d_5 (Conv2D)	(None, 14, 14, 16)	4624
max_pooling2d_3 (MaxPooling2)	(None, 7, 7, 16)	0
convOutput (Conv2D)	(None, 7, 7, 8)	1160
flatten_3 (Flatten)	(None, 392)	0
dense_11 (Dense)	(None, 32)	12576

=====  
 Total params: 18,680  
 Trainable params: 18,680  
 Non-trainable params: 0

Model: "sequential\_4"

Layer (type)	Output Shape	Param #
--------------	--------------	---------

```

=====
dense_12 (Dense)                (None, 392)                12936
-----
reshape (Reshape)                (None, 7, 7, 8)            0
-----
conv2d_6 (Conv2D)                (None, 7, 7, 8)            584
-----
up_sampling2d (UpSampling2D)     (None, 14, 14, 8)          0
-----
conv2d_7 (Conv2D)                (None, 14, 14, 16)         1168
-----
up_sampling2d_1 (UpSampling2D)   (None, 28, 28, 16)         0
-----
conv2d_8 (Conv2D)                (None, 28, 28, 32)         4640
-----
conv2d_9 (Conv2D)                (None, 28, 28, 1)          289
=====
Total params: 19,617
Trainable params: 19,617
Non-trainable params: 0

-----
Model: "sequential_5"

-----
Layer (type)                Output Shape                Param #
=====
sequential_3 (Sequential)    (None, 32)                  18680
-----
sequential_4 (Sequential)    (None, 28, 28, 1)           19617
=====
Total params: 38,297
Trainable params: 38,297
Non-trainable params: 0
-----

```

### Task 3: Create the neural network model

Fit the model to the training data using the following hyper-parameters: \* adam optimizer \* binary\_crossentropy loss function \* 20 training epochs \* batch size as 256 \* set shuffle as True  
Compile the model and fit ...

```

[ ]: autoencoder.compile(optimizer='adam', loss='binary_crossentropy')
      history = autoencoder.fit(train_images_noisy_nor, train_images_nor,
                                epochs=20,
                                batch_size=256,
                                shuffle=True)

```

```

Epoch 1/20
235/235 [=====] - 3s 9ms/step - loss: 0.3471
Epoch 2/20

```

```

235/235 [=====] - 2s 9ms/step - loss: 0.1811
Epoch 3/20
235/235 [=====] - 2s 9ms/step - loss: 0.1367
Epoch 4/20
235/235 [=====] - 2s 9ms/step - loss: 0.1264
Epoch 5/20
235/235 [=====] - 2s 9ms/step - loss: 0.1214
Epoch 6/20
235/235 [=====] - 2s 9ms/step - loss: 0.1164
Epoch 7/20
235/235 [=====] - 2s 9ms/step - loss: 0.1135
Epoch 8/20
235/235 [=====] - 2s 9ms/step - loss: 0.1112
Epoch 9/20
235/235 [=====] - 2s 9ms/step - loss: 0.1093
Epoch 10/20
235/235 [=====] - 2s 9ms/step - loss: 0.1076
Epoch 11/20
235/235 [=====] - 2s 9ms/step - loss: 0.1063
Epoch 12/20
235/235 [=====] - 2s 9ms/step - loss: 0.1055
Epoch 13/20
235/235 [=====] - 2s 9ms/step - loss: 0.1044
Epoch 14/20
235/235 [=====] - 2s 9ms/step - loss: 0.1038
Epoch 15/20
235/235 [=====] - 2s 8ms/step - loss: 0.1028
Epoch 16/20
235/235 [=====] - 2s 8ms/step - loss: 0.1024
Epoch 17/20
235/235 [=====] - 2s 8ms/step - loss: 0.1016
Epoch 18/20
235/235 [=====] - 2s 9ms/step - loss: 0.1014
Epoch 19/20
235/235 [=====] - 2s 9ms/step - loss: 0.1010
Epoch 20/20
235/235 [=====] - 2s 9ms/step - loss: 0.1006

```

**Task 4:** Create the neural network model (No need to write code, just run the following commands)

```

[ ]: def showImages(input_imgs, encoded_imgs, output_imgs, size=1.5,
    ↳groundTruth=None):

    numCols = 3 if groundTruth is None else 4

    num_images = input_imgs.shape[0]

```



```

encoded_imgs = encoded_imgs.reshape((num_images, 1, -1))

plt.figure(figsize=((numCols+encoded_imgs.shape[2])/input_imgs.shape[2])*size,
↳num_images*size))

pltIdx = 0
col = 0
for i in range(0, num_images):

    col += 1
    # plot input image
    pltIdx += 1
    ax = plt.subplot(num_images, numCols, pltIdx)
    plt.imshow(input_imgs[i].reshape(28, 28))
    plt.gray()
    ax.get_xaxis().set_visible(False)
    ax.get_yaxis().set_visible(False)
    if col == 1:
        plt.title('Input Image')

    # plot encoding
    pltIdx += 1
    ax = plt.subplot(num_images, numCols, pltIdx)
    plt.imshow(encoded_imgs[i])
    plt.gray()
    ax.get_xaxis().set_visible(False)
    ax.get_yaxis().set_visible(False)
    if col == 1:
        plt.title('Encoded Image')

    # plot reconstructed image
    pltIdx += 1
    ax = plt.subplot(num_images, numCols, pltIdx)
    plt.imshow(output_imgs[i].reshape(28, 28))
    plt.gray()
    ax.get_xaxis().set_visible(False)
    ax.get_yaxis().set_visible(False)
    if col == 1:
        plt.title('Reconstructed Image')

    if numCols == 4:
        # plot ground truth image
        pltIdx += 1
        ax = plt.subplot(num_images, numCols, pltIdx)
        plt.imshow(groundTruth[i].reshape(28, 28))
        plt.gray()

```

```

ax.get_xaxis().set_visible(False)
ax.get_yaxis().set_visible(False)

if col == 1:
    plt.title('Ground Truth')

plt.show()

```

```

[:]: num_images = 10

input_labels = test_labels[0:num_images]
I = np.argsort(input_labels)

input_imgs = test_images_noisy[I]

encoded_imgs = encoder.predict(test_images_noisy[I]/255.)
output_imgs = decoder.predict(encoded_imgs)

showImages(input_imgs, encoded_imgs, output_imgs, size=2,
    ↳groundTruth=test_images_nor[I])

```

Input Image	Encoded Image	Reconstructed Image	Ground Truth
