

# HW6 Rahul Deshmukh

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```
In [1]: import numpy as np
        from sympy import *
        import matplotlib.pyplot as plt
```

Problem 1:

$$y' = -5y \text{ and } y(0) = 1$$

a) The ODE is stable as  $\lambda < 0$

b) For euler's method to be stable we have the condition on the step size

$$h < \frac{-2}{\lambda}$$

and for this problem ( $\lambda = -5$ )  $h < \frac{-2}{-5}$  i.e.  $h < 0.4$

Therefore Euler's Method is not stable for this ODE when using a step size of  $h = 0.5$

c) Solving using Euler's Method

```
In [2]: def Euler_ODE(y0,h,A,a,b):
        N= int((b-a)/h)
        x= np.linspace(a,b,N+1)
        if np.size(y0)>1:
            p= np.zeros((np.size(y0),(N+1)))
            p[:,0]=np.copy(y0)
            for i in range(0,N):
                t=a+i*h;
                k1=A(p[:,i],t)
                p[:,i+1]=p[:,i]+(h)*(k1)
        else:
            p= np.zeros((N+1))
            p[0]=np.copy(y0)
            for i in range(0,N):
                t=a+i*h;
                k1=A(p[i],t)
                p[i+1]=p[i]+(h)*(k1)
        return(x,p)
```

```

In [3]: a=0;b=5;y0=1
        h1=0.5;h2=0.1;
        def A(y,t):
            return(np.array([-5*y+0*t]))
        p1=Euler_ODE(y0,h1,A,a,b)
        p2=Euler_ODE(y0,h2,A,a,b)

In [4]: x = symbols('x')
        y = Function('y')
        Y=dsolve(Derivative(y(x),x)+5*y(x),y(x))
        print('The analytical solution is: '+str(Y))

The analytical solution is: Eq(y(x), C1*exp(-5*x))

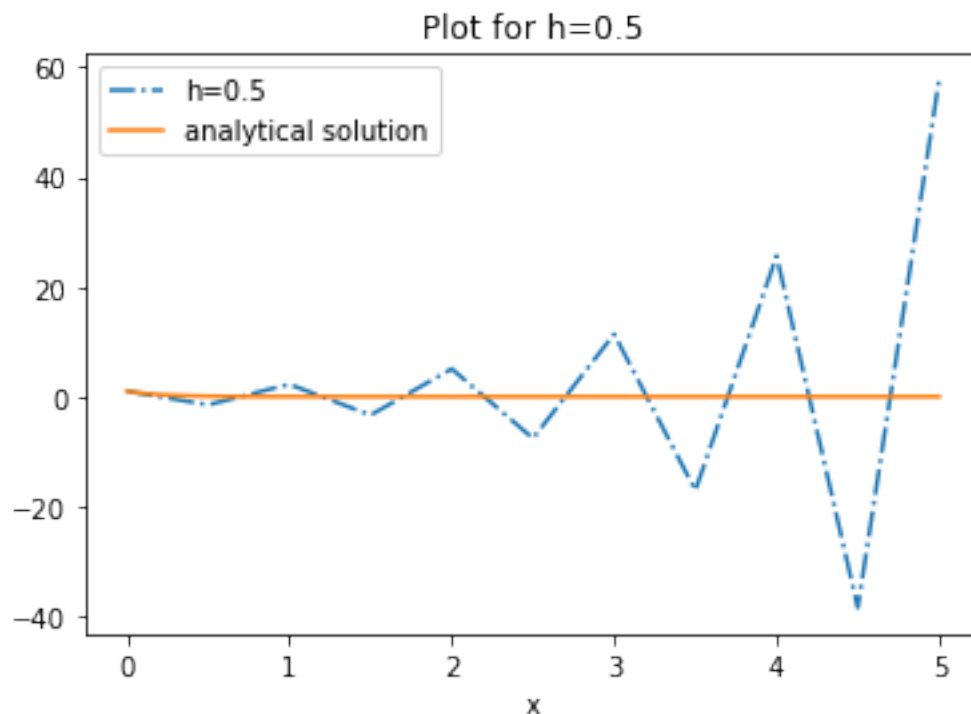
```

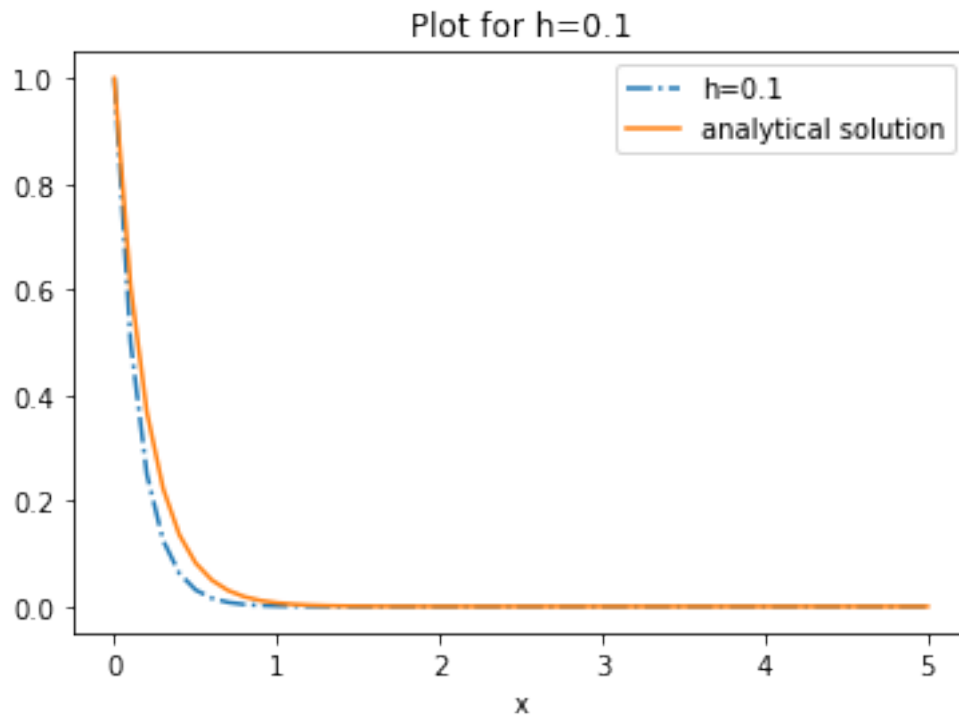
The analytical solution satisfying the initial value is  $y(x) = e^{-5x}$

```

In [5]: a=plt.plot(p1[0],p1[-1], '-.', label='h=0.5')
        c,= plt.plot(p2[0],np.e**(-5*p2[0]),label='analytical solution')
        plt.title('Plot for h=0.5')
        plt.legend(handles=[a,c])
        plt.xlabel('x')
        plt.show()
        b=plt.plot(p2[0],p2[-1], '-.', label='h=0.1')
        c,= plt.plot(p2[0],np.e**(-5*p2[0]),label='analytical solution')
        plt.legend(handles=[b,c])
        plt.title('Plot for h=0.1')
        plt.xlabel('x')
        plt.show()

```





d) For Backward Eulers to be stable we have the condition on  $h > 0$ . Therefore for  $h = 0.5$  the backward eulers method will be stable

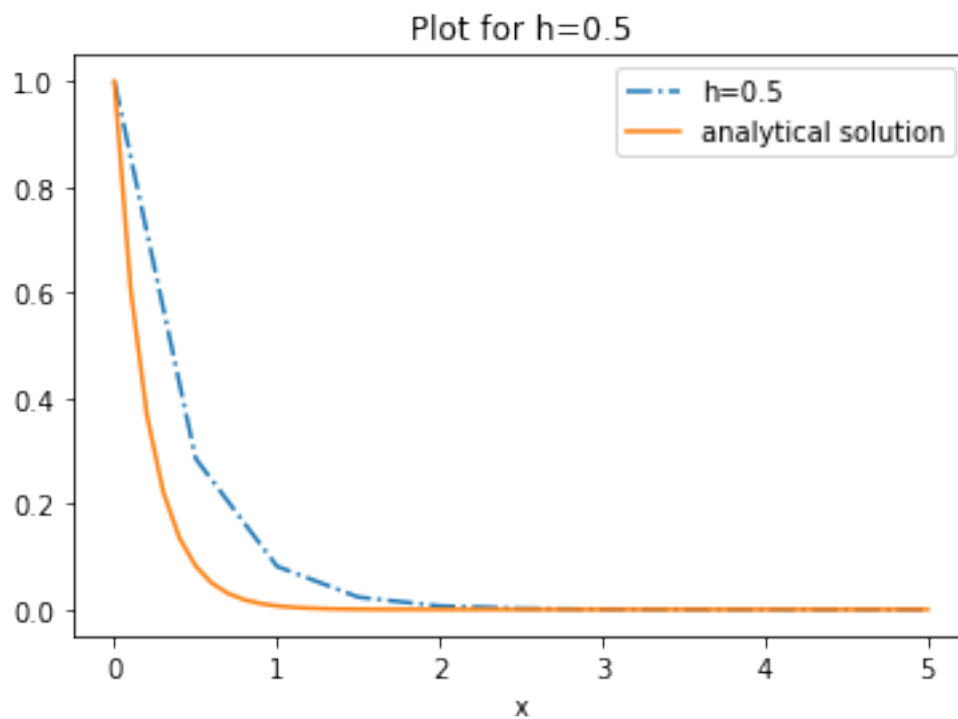
e) Solving using Backward Eulers Method

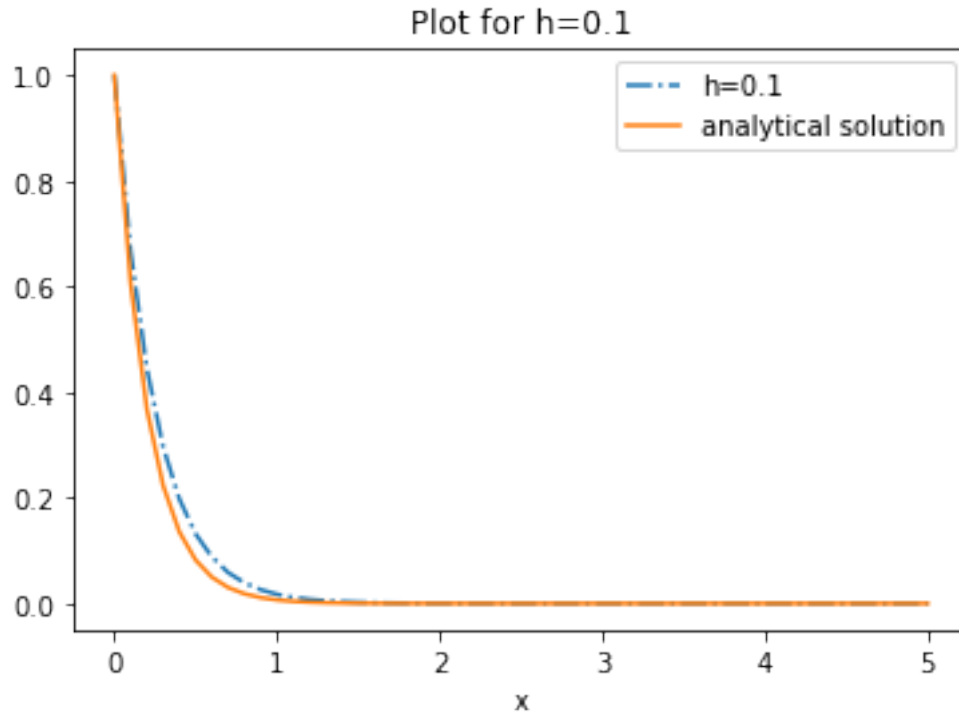
```
In [6]: def back_euler(y0,h,f,a,b): #function good for single ODE of the form y'=f(y,t) with y t
        N= int((b-a)/h) #better to use Euler_ODE when we have higher power on y term
        x= np.linspace(a,b,N+1)
        p= np.zeros(N+1)
        p[0]=y0
        t = symbols('t')
        for i in range(0,N):
            s=solve(y-h*f.subs(t,a+i*h)-p[i],y) #back_euler can be messy as y can have multi
            p[i+1]=s[0] #and we dont have a selection criteria
        return(x,p)
y = symbols('y')
t = symbols('t')
f=-5*y+0*t;
y0=1;h1=0.5;h2=0.1
a=0;b=5
p1=back_euler(y0,h1,f,a,b)
p2=back_euler(y0,h2,f,a,b)
```

```

In [7]: a=plt.plot(p1[0],p1[-1], '-.',label='h=0.5')
c,= plt.plot(p2[0],np.e**(-5*p2[0]),label='analytical solution')
plt.title('Plot for h=0.5')
plt.legend(handles=[a,c])
plt.xlabel('x')
plt.show()
b=plt.plot(p2[0],p2[-1], '-.',label='h=0.1')
c,= plt.plot(p2[0],np.e**(-5*p2[0]),label='analytical solution')
plt.legend(handles=[b,c])
plt.title('Plot for h=0.1')
plt.xlabel('x')
plt.show()

```





Problem 2:

a) Analytical solution

Let us convert the Second order Differential equation to a systems of differential equations

$$y_1 = y$$

$$y_2 = y'$$

$$y_1' = y_2$$

$$y_2' = -8.96 * y_1 - 6 * y_2$$

and initial condition

$$y_1(0) = 1$$

$$y_2(0) = 5$$

$$\Rightarrow \begin{bmatrix} y_1' \\ y_2' \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -8.96 & -6 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \end{bmatrix}$$

```
In [8]: M= Matrix([[0,1],[-8.96,-6]])
p,d = M.diagonalize()
print(d)
print(p)
c1 = symbols('c1')
c2 = symbols('c2')
c=solve([c1*p[0,0]+c2*p[0,1]-1,c1*p[1,0]+c2*p[1,1]-5],[c1,c2])
print(c)
```

```
Matrix([[-3.200000000000000, 0], [0, -2.800000000000000]])
Matrix([[-5.000000000000000, -5.000000000000000], [16.00000000000000, 14.00000000000000]])
{c1: 3.900000000000000, c2: -4.100000000000000}
```

The analytical solution is:

$$\begin{bmatrix} y \\ y' \end{bmatrix} = \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = 3.9 * \begin{bmatrix} -5 \\ 16 \end{bmatrix} * e^{-3.2x} - 4.1 * \begin{bmatrix} -5 \\ 14 \end{bmatrix} e^{-2.8x}$$

$$y = -19.5 * e^{-3.2x} + 20.5 * e^{-2.8x}$$

b) Solve using 4th order Runge-Kutta method

```
In [9]: def RK4_ODE(y0,h,A,a,b):
        N= int((b-a)/h)
        x= np.linspace(a,b,N+1)
        p= np.zeros((np.size(y0),(N+1)))
        p[:,0]=np.copy(y0)
        for i in range(0,N):
            t=a+i*h;
            k1=A(p[:,i],t)
            t=a+i*h+h/2;
            k2=A((p[:,i]+((h/2)*k1)),t)
            t = a+i*h+h/2;
            k3=A((p[:,i]+((h/2)*k2)),t)
            t=a+i*h+h;
            k4=A((p[:,i]+((h)*k3)),t)
            p[:,i+1]=p[:,i]+(h/6)*(k1+2*k2+2*k3+k4)
        return(x,p)

In [10]: y0=np.array([1,5])
        h=0.08;a=0;b=8;
        def A(y,t):
            return(np.array([0*y[0]+1*y[1]+0*t,-8.96*y[0]-6*y[1]+0*t]))
        sol = RK4_ODE(y0,h,A,a,b)
        a = sol[1]
        rk=a[0,:]
```

c) Solve using Euler's method

```
In [11]: y0=np.array([1,5])
        h=0.08;a=0;b=8;
        def A(y,t):
            return(np.array([0*y[0]+1*y[1]+0*t,-8.96*y[0]-6*y[1]+0*t]))
        sol = Euler_ODE(y0,h,A,a,b)
        a = sol[1]
        eu=a[0,:]
```

d) solve using Taylor series method of order two

```
In [12]: def Taylor_ODE(y0,h,F,dF,a,b):
    N= int((b-a)/h)
    x= np.linspace(a,b,N+1)
    if np.size(y0)>1:
        p= np.zeros((np.size(y0),(N+1)))
        p[:,0]=np.copy(y0)
        for i in range(0,N):
            t=a+i*h;
            k1=F(p[:,i],t)
            k2=dF(p[:,i],t)
            p[:,i+1]=p[:,i]+(h)*(k1)+(h**2/2)*k2
    else:
        p= np.zeros((N+1))
        p[0]=np.copy(y0)
        for i in range(0,N):
            t=a+i*h;
            k1=A(p[i],t)
            k2=dF(p[i],t)
            p[i+1]=p[i]+(h)*(k1)+(h**2/2)*k2
    return(x,p)
```

Our system of equations is:

$$\underline{Y}' = \underline{F} = \begin{bmatrix} y_1' \\ y_2' \end{bmatrix} = \begin{bmatrix} 0 * y_1 + 1 * y_2 \\ -8.96 * y_1 - 6 * y_2 \end{bmatrix}$$

For Taylor series of order two we need to find  $\underline{F}'$

$$\begin{aligned} \underline{F}' &= \begin{bmatrix} y_1'' \\ y_2'' \end{bmatrix} = \begin{bmatrix} 1 * y_2' \\ -8.96 * y_1' - 6 * y_2' \end{bmatrix} = \begin{bmatrix} -8.96 * y_1 - 6 * y_2 \\ -8.96 * y_2 - 6 * (-8.96 * y_1 - 6 * y_2) \end{bmatrix} \\ &\Rightarrow \underline{F}' = \begin{bmatrix} -8.96 * y_1 - 6 * y_2 \\ 53.76 * y_1 + 44.96 * y_2 \end{bmatrix} \end{aligned}$$

```
In [13]: y0=np.array([1,5])
    h=0.08;a=0;b=8;
    def F(y,t):
        return(np.array([0*y[0]+1*y[1]+0*t,-8.96*y[0]-6*y[1]+0*t]))
    def dF(y,t):
        return(np.array([-8.96*y[0]-6*y[1]+0*t,53.76*y[0]+44.96*y[1]+0*t]))
    sol = Taylor_ODE(y0,h,F,dF,a,b)
    a = sol[1]
    ty=a[0,:]
```

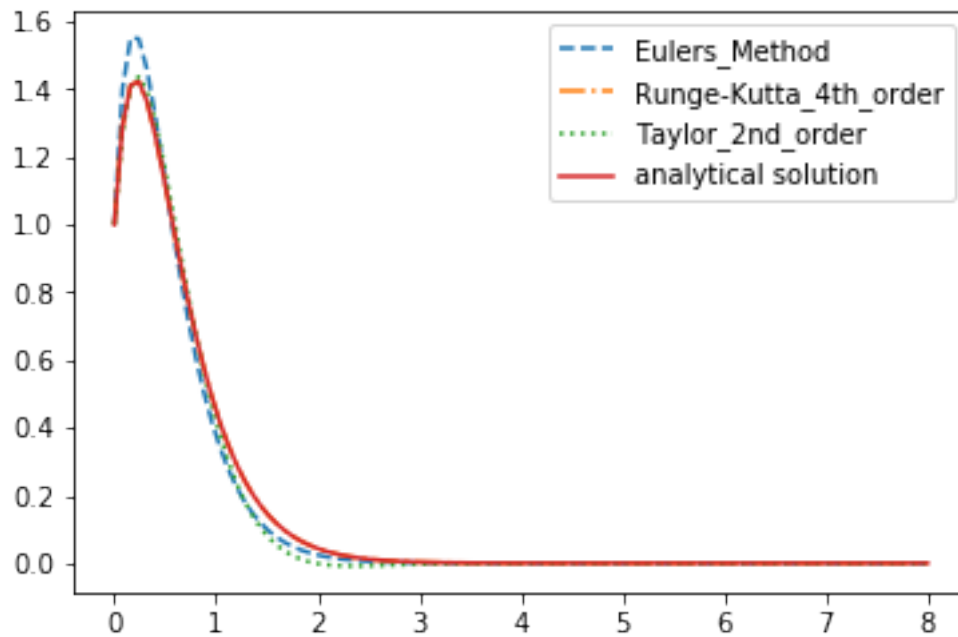
d) Plot

```
In [14]: def ana(t):
    return(-19.5*np.e**(-3.2*t)+20.5*np.e**(-2.8*t))
```

```

peu,=plt.plot(sol[0],eu,'--',label='Eulers_Method')
prk,=plt.plot(sol[0],rk,'-.',label='Runge-Kutta_4th_order')
pty,=plt.plot(sol[0],ty,':',label='Taylor_2nd_order')
pana,=plt.plot(sol[0],ana(sol[0]),label='analytical solution')
plt.legend(handles=[peu,prk,pty,pana])
plt.show()

```



Problem 3:

```

In [15]: def F(y,t):
            return(np.array([-0.013*y[0]-1000*y[0]*y[2]+0*t,-2500*y[1]*y[2]+0*t,
                              -0.013*y[0]-1000*y[0]*y[2]-2500*y[1]*y[2]+0*t]))
        y0=np.array([1,1,0])
        h=0.0001;a=0;b=5;
        sol1 = RK4_ODE(y0,h,F,a,b)
        m = sol1[1]
        sol2=Euler_ODE(y0,h,F,a,b)
        n = sol2[1]

In [16]: rk=m[0,:]
        eu=n[0,:]
        prk,=plt.plot(sol1[0],rk,'--',label='Runge-Kutta_4th_order')
        peu,=plt.plot(sol2[0],eu,'-.',label='Eulers_Method')
        plt.legend(handles=[prk,peu])
        plt.title('y1')
        plt.show()

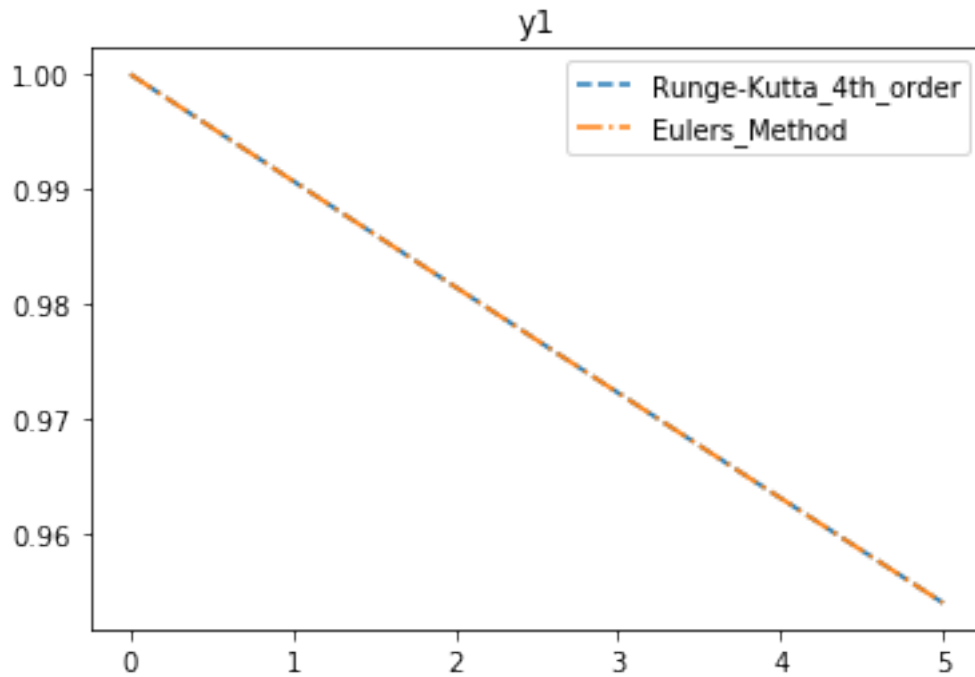
```

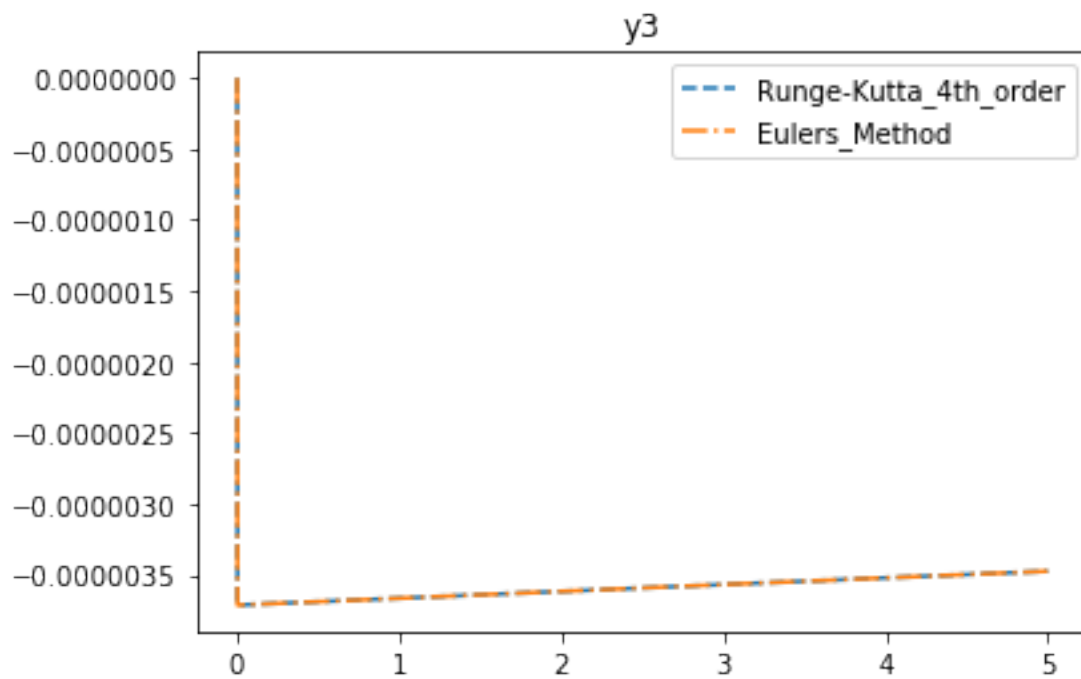
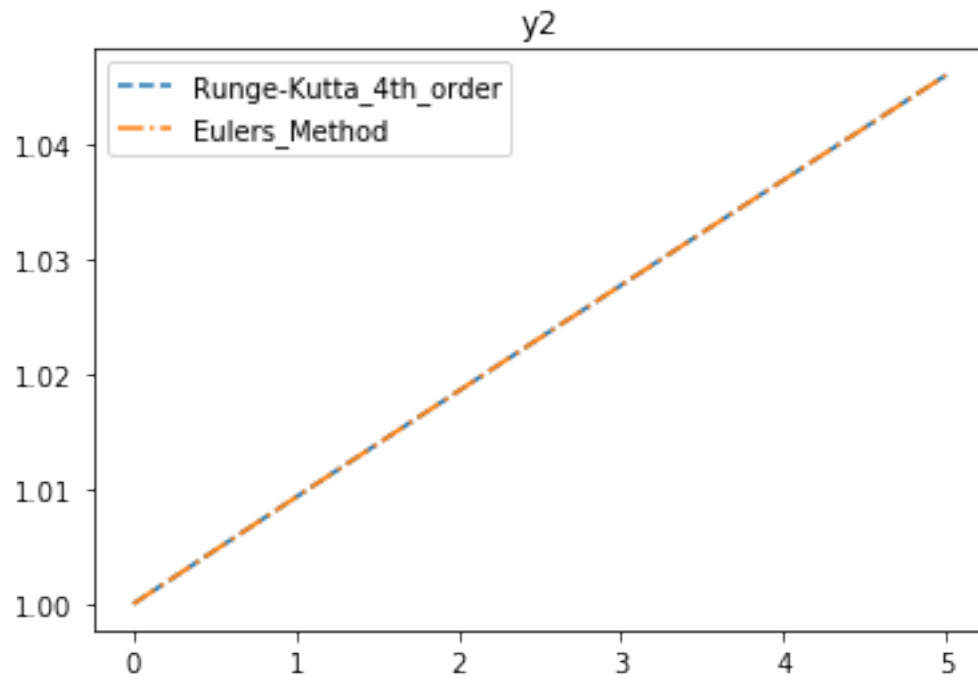


```

rk=m[1,:]
eu=n[1,:]
prk=plt.plot(sol1[0],rk,'--',label='Runge-Kutta_4th_order')
peu=plt.plot(sol2[0],eu,'-.',label='Eulers_Method')
plt.legend(handles=[prk,peu])
plt.title('y2')
plt.show()
rk=m[2,:]
eu=n[2,:]
prk=plt.plot(sol1[0],rk,'--',label='Runge-Kutta_4th_order')
peu=plt.plot(sol2[0],eu,'-.',label='Eulers_Method')
plt.legend(handles=[prk,peu])
plt.title('y3')
plt.show()

```





Problem 4:

For a Second order Runge-Kutta Method we have:

$$Q(z) = 1 + z + \frac{1}{2}z^2$$

so absolute stability requires:

$$\left| 1 + (h\lambda) + \frac{1}{2}(h\lambda)^2 \right| < 1$$

lets solve this inequality

```
In [17]: x = symbols('x')
         q=1+x+(1/2)*x**2
         print(solve_univariate_inequality(q<1, x))

And(-2.0 < x, x < 0.0)
```

Therefore for Second order Runge-Kutta Method we have the condition the following condition:

$$-2 < (h\lambda) < 0$$

We have  $0 < h < \frac{2}{|\lambda|}$  for  $\lambda < 0$

a)

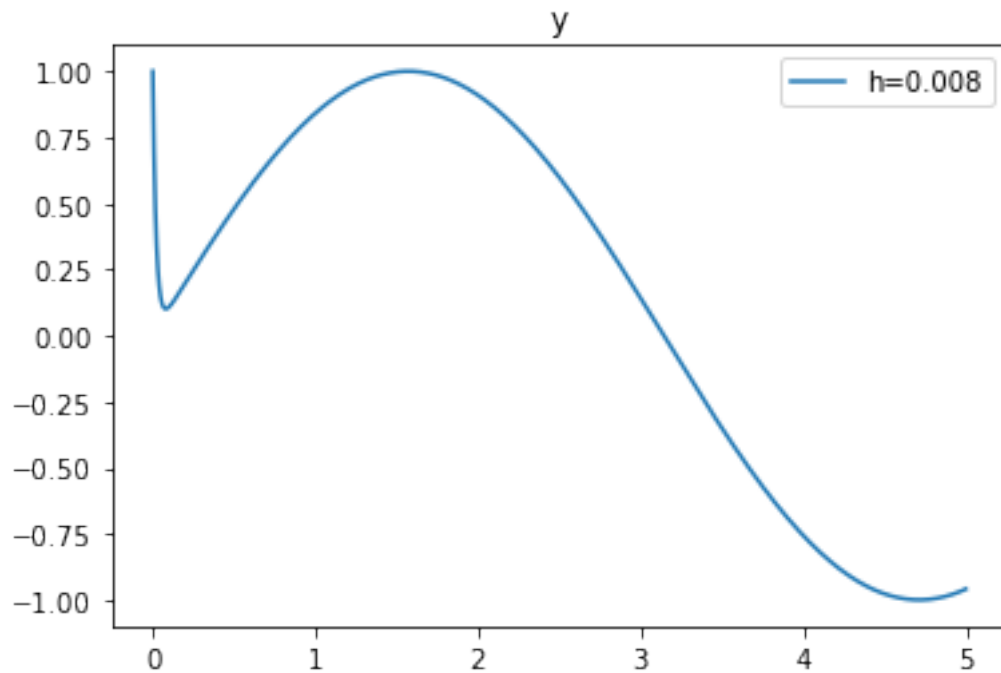
```
In [18]: def RK2_ODE(y0,h,A,a,b):
         N= int((b-a)/h)
         x= np.linspace(a,b,N+1)
         if np.size(y0)>1:
             p= np.zeros((np.size(y0),(N+1)))
             p[:,0]=np.copy(y0)
             for i in range(0,N):
                 t=a+i*h;
                 k1=A(p[:,i],t)
                 t=a+i*h+h;
                 k2=A((p[:,i]+((h)*k1)),t)
                 p[:,i+1]=p[:,i]+(h/2)*(k1+k2)
         else:
             p= np.zeros((N+1))
             p[0]=np.copy(y0)
             for i in range(0,N):
                 t=a+i*h;
                 k1=A(p[i],t)
                 t=a+i*h+h;
                 k2=A((p[i]+((h)*k1)),t)
                 p[i+1]=p[i]+(h/2)*(k1+k2)
         return(x,p)
```

i)

Finding eigenvalues of homogenous system and for this Problem  $\lambda = -200$  and  $0 < h < 2/|\lambda|$   
for  $\lambda < 0$   
 $\Rightarrow h < 2/200 = 0.01$

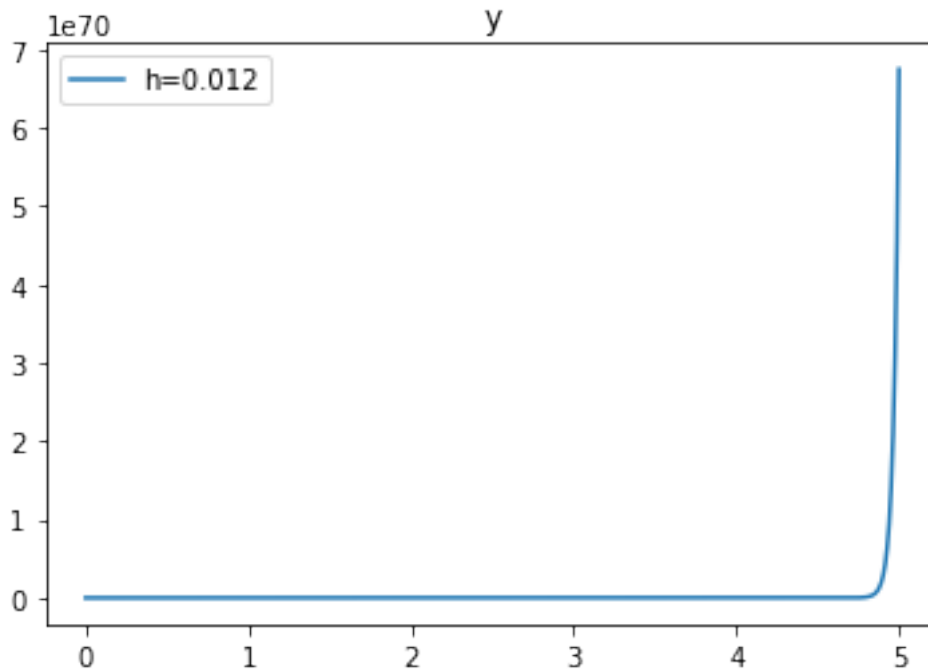
ii)

```
In [19]: def F(y,t):
          return(-200*y+200*np.sin(t)+np.cos(t))
          y0=1;a=0;b=5;h=0.008
          sol=RK2_ODE(y0,h,F,a,b)
          rk = sol[1]
          prk,=plt.plot(sol[0],rk,label='h=0.008')
          plt.legend(handles=[prk])
          plt.title('y')
          plt.show()
```



iii)

```
In [20]: y0=1;a=0;b=5;h=0.012
          sol=RK2_ODE(y0,h,F,a,b)
          rk= sol[1]
          prk,=plt.plot(sol[0],rk,label='h=0.012')
          plt.legend(handles=[prk])
          plt.title('y')
          plt.show()
```



b)

i) Finding eigenvalues of homogenous system and  $0 < h < 2/|\lambda|$  for  $\lambda < 0$

```
In [21]: M=Matrix([[9,24],[-24,-51]])
         p,v=M.diagonalize()
         print(v)
```

```
Matrix([[-39, 0], [0, -3]])
```

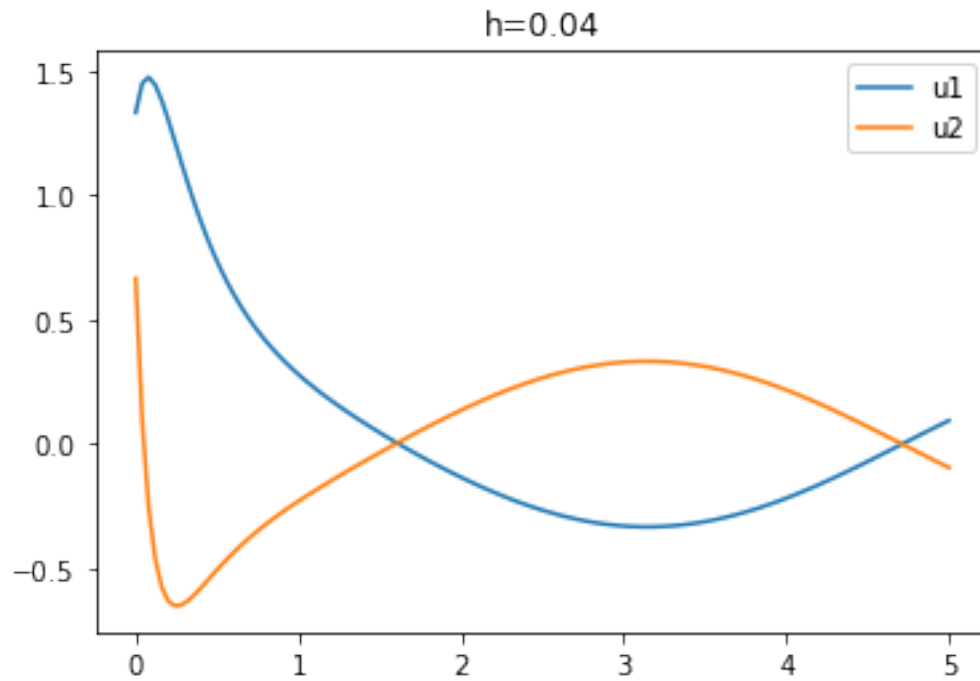
Therefore  $h < 2/39 \simeq 0.05128$

ii)

```
In [22]: def F(y,t):
         return(np.array([9*y[0]+24*y[1]+5*np.cos(t)-(1/3)*np.sin(t),
                          -24*y[0]-51*y[1]-9*np.cos(t)+(1/3)*sin(t)]))

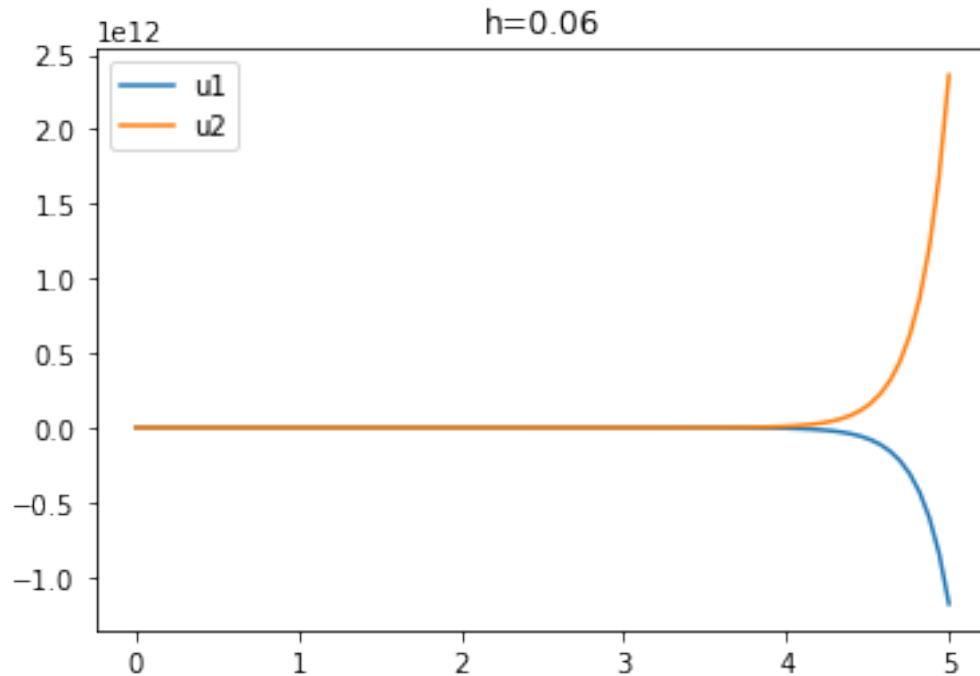
         y0= np.array([(4/3),(2/3)])
         a=0;b=5;h=0.04
         sol=RK2_ODE(y0,h,F,a,b)
         rk = sol[1]

In [23]: u1=plt.plot(sol[0],rk[0,:],label='u1')
         u2=plt.plot(sol[0],rk[1,:],label='u2')
         plt.legend(handles=[u1,u2])
         plt.title('h=0.04')
         plt.show()
```



iii)

```
In [24]: a=0;b=5;h=0.06
         sol=RK2_ODE(y0,h,F,a,b)
         rk = sol[1]
         u1=plt.plot(sol[0],rk[0,:],label='u1')
         u2=plt.plot(sol[0],rk[1,:],label='u2')
         plt.legend(handles=[u1,u2])
         plt.title('h=0.06')
         plt.show()
```



c)

i) Finding eigenvalues of homogenous system and  $0 < h < 2/|\lambda|$  for  $\lambda < 0$

```
In [25]: M=Matrix([[-20,-19],[-19,-20]])
          p,v=M.diagonalize()
          print(v)
Matrix([[-39, 0], [0, -1]])
```

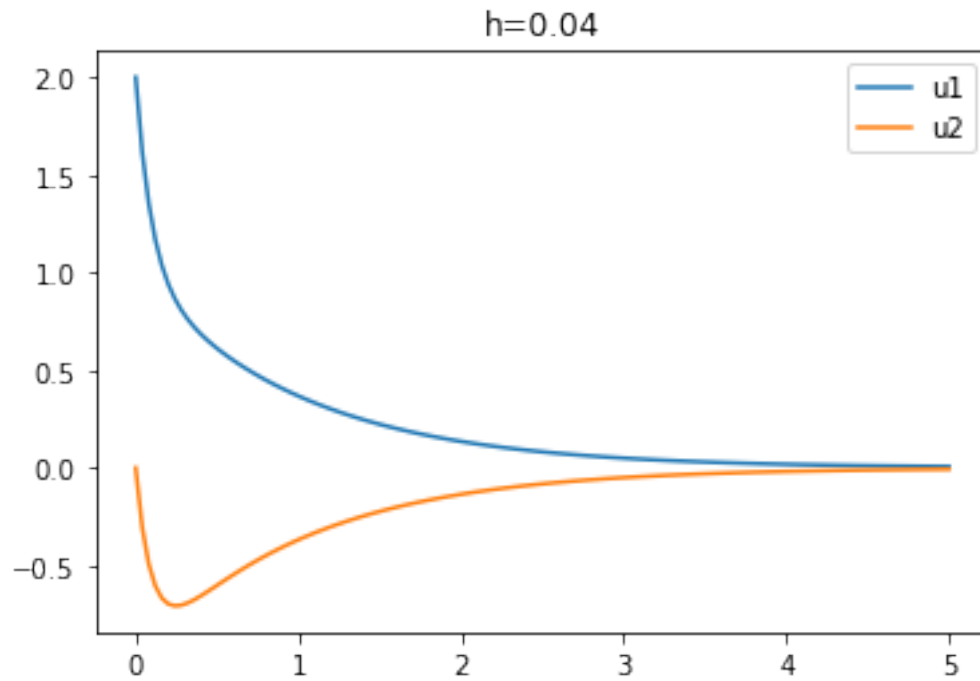
Therefore  $h < 2/39 \simeq 0.05128$

ii)

```
In [26]: def F(y,t):
          return(np.array([-20*y[0]-19*y[1],
                           -19*y[0]-20*y[1]]))

          y0= np.array([2,0])
          a=0;b=5;h=0.04
          sol=RK2_ODE(y0,h,F,a,b)
          rk = sol[1]

In [27]: u1=plt.plot(sol[0],rk[0,:],label='u1')
          u2=plt.plot(sol[0],rk[1,:],label='u2')
          plt.legend(handles=[u1,u2])
          plt.title('h=0.04')
          plt.show()
```



iii)

```
In [28]: a=0;b=5;h=0.06
sol=RK2_ODE(y0,h,F,a,b)
rk = sol[1]
u1=plt.plot(sol[0],rk[0,:],label='u1')
u2=plt.plot(sol[0],rk[1,:],label='u2')
plt.legend(handles=[u1,u2])
plt.title('h=0.06')
plt.show()
```



