

Introduction to FVM in two dimensions



In this section, to illustrate the underlying concepts of the FVM in higher dimensions, we consider the two-dimensional Poisson equation:

$$\underline{\underline{D}} = \begin{pmatrix} D_{xx} & 0 \\ 0 & D_{yy} \end{pmatrix} \quad \nabla \cdot (\underline{\underline{D}}(\underline{x}, \underline{y}) \nabla \varphi) = f(\underline{x}, \underline{y}), \quad (\underline{x}, \underline{y}) \in \Omega \subset \mathbb{R}^2 \quad (22)$$

$$\underline{\underline{J}} = \underline{\underline{D}} \nabla \varphi$$

subject to the general boundary conditions:

$$\frac{\partial \varphi}{\partial \underline{n}} = \nabla \varphi \cdot \hat{\underline{n}} \quad A_b \varphi + B_b \frac{\partial \varphi}{\partial n} = C_b, \quad \text{on } \partial \Omega \quad (23)$$



where $\frac{\partial \varphi}{\partial n}$ denotes the directional derivative normal (pointing outwards) to the boundary $\partial \Omega$ and A_b, B_b, C_b are constants.

Both the diffusivity $D(x, y)$ and the function $f(x, y)$ are assumed to vary spatially.



$$J = \begin{pmatrix} D_{xx} & 0 \\ 0 & D_{yy} \end{pmatrix} \begin{pmatrix} \frac{\partial \phi}{\partial x} \\ \frac{\partial \phi}{\partial y} \end{pmatrix} = \begin{pmatrix} D_{xx} \frac{\partial \phi}{\partial x} \\ D_{yy} \frac{\partial \phi}{\partial y} \end{pmatrix}$$

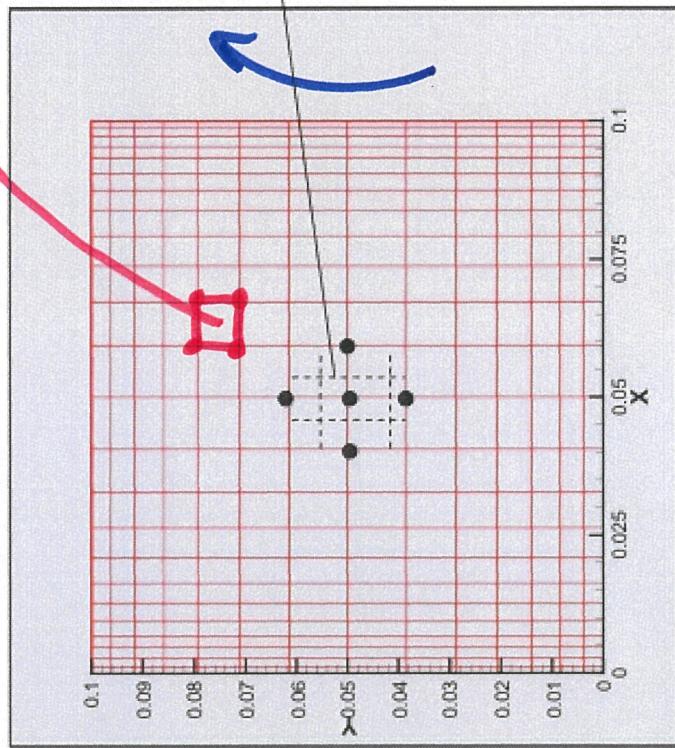
How would we deal with Heterogeneity?

$$D = \begin{pmatrix} D_{xx} & D_{xy} \\ D_{yx} & D_{yy} \end{pmatrix} \underset{\text{Diagonalize}}{\approx} \begin{matrix} \underline{D} \\ \underline{\Lambda} \end{matrix} = P \underline{\Lambda} P^T$$

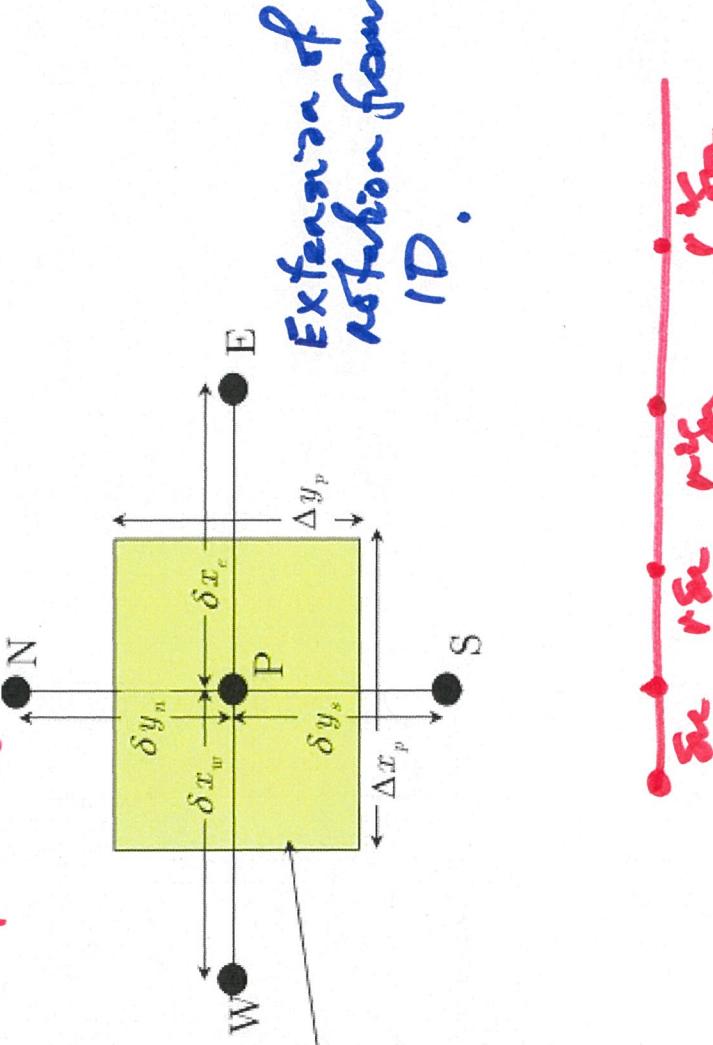
Rearrange the general B.C.:

$$\underline{B_x} = \frac{C_b - A_b \underline{\Lambda}}{B_b}$$

Assign the element properties i.e., Sandstone



(a)



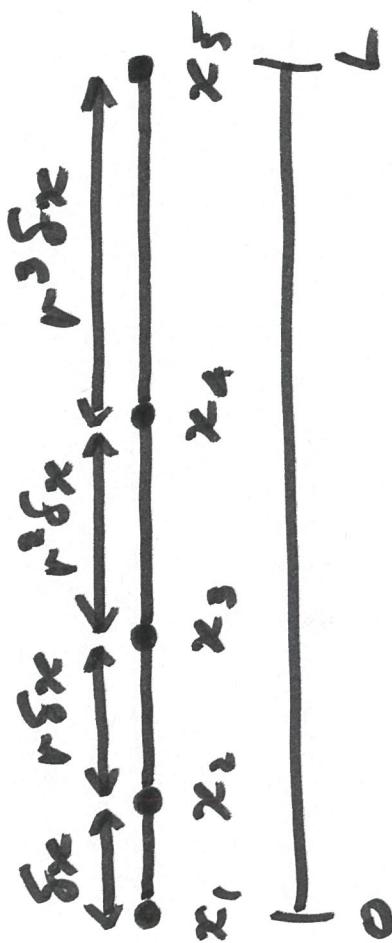
(b)

Figure: Structured mesh in two-dimensions: (a) mesh with irregular node spacing; (b) The control volume V_p is shown in yellow depicting the usual control volume notation.

Mesh Refinement:

Geometric factor

" $\frac{r}{k}$ " given



How do we find δx ?

$$\delta x + r \delta x + r^2 \delta x + r^3 \delta x = L$$

$$\delta x (1 + r + r^2 + r^3) = L$$

$$\therefore \delta x = \frac{(1 - r^4)}{(1 - r)}$$

$$\begin{aligned}x_2 &= x_1 + r \delta x \\x_3 &= x_2 + r \delta x \\x_4 &= x_3 + r \delta x\end{aligned}$$

check:

$$(1 - r)(1 + r + r^2 + r^3) = \frac{1 + r + r^2 + r^3}{1 - r}$$

$$\sum_{k=0}^3 r^k =$$

$$1 + r + r^2 + r^3 - r^4$$

Model Equation :

$$\underline{\nabla} \cdot \underline{J} = \frac{\partial}{\partial x} \varphi = \left(\frac{\partial x}{\partial x} \frac{\partial \varphi}{\partial x} \right) + \left(\frac{\partial y}{\partial x} \frac{\partial \varphi}{\partial y} \right) \cdot \dots \quad (1)$$

$$\underline{\nabla} \cdot \underline{J} = f(x, y) \quad \text{for } (x, y) \in \Omega$$

Boundary conditions:

$$\frac{\partial \varphi}{\partial n} = \frac{C_b}{B_b} - \frac{A_b}{B_b} \varphi \quad \text{on } \partial \Omega$$

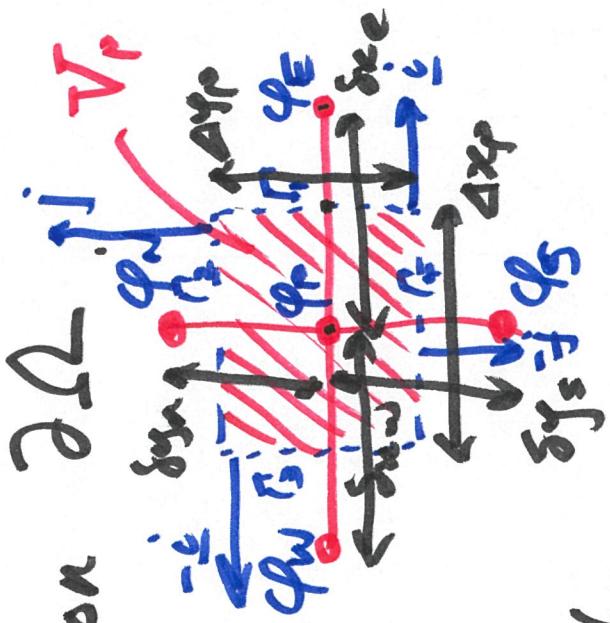
USE FVM for discretization:

Integrate (1) over V_F :

$$\iint_{V_F} \underline{\nabla} \cdot \underline{J} dx dy = \iint_{V_F} f(x, y) dx dy$$

Use Gauss Divergence Thm:

$$\int_{\Gamma} \underline{J} \cdot \hat{n} d\sigma = \Delta x \Delta y_F \bar{f} \quad ,$$



$$\iint_A \sigma \cdot f dV = \iint_{V_F} \sigma \cdot f dV = \frac{1}{\Delta x_F \Delta y_F} \iint_{V_F} f(x, y) dx dy$$

$$\text{i.e., } \sum_{j=1}^4 \int_{\Omega_j} \underline{J} \cdot \hat{\underline{n}} \, d\sigma =$$

$$\Delta x_p \Delta y_p \bar{f} \quad (\text{Exact at this point in the definition})$$

Q: What is the

We now introduce approximations which would be second order if evaluated at cell center.

$$(\underline{J} \cdot \hat{\underline{n}})_{m_i} \quad (1)$$

$$\int_{\Omega_i} \underline{J} \cdot \hat{\underline{n}} \, d\sigma \approx$$

One-point (mid-point) quadrature rule.

Evaluate flux of the mid-point of face $S_i(\underline{J} + \frac{1}{2}\hat{\underline{n}})$

$$\frac{\partial x_N}{\partial x_e} (\varphi_e - \varphi_p) \Delta y_p +$$

$$\frac{\partial x_N}{\partial y_e} (\varphi_N - \varphi_p) \Delta x_p$$

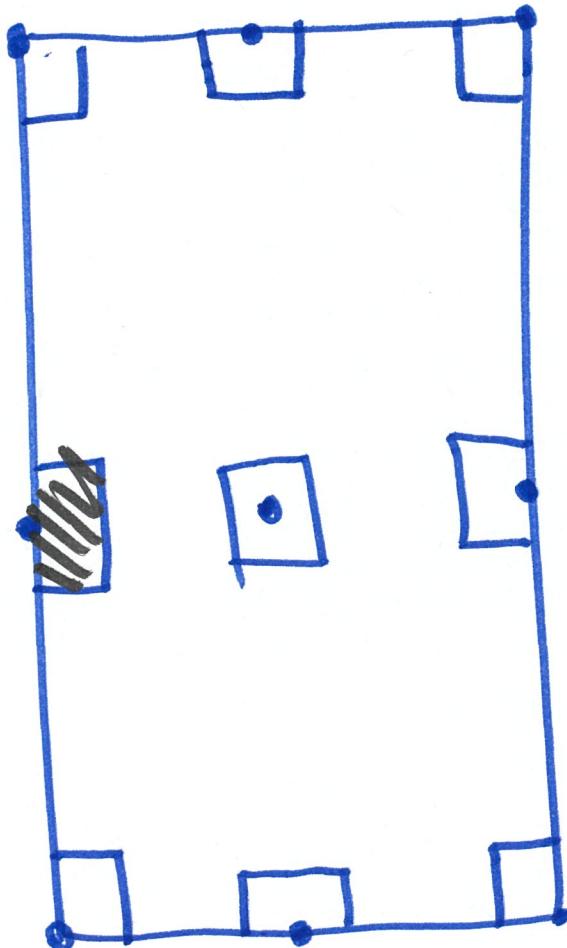
$$+ \frac{\partial x_N}{\partial x_w} (\varphi_w - \varphi_p) \Delta y_p + \frac{\partial x_S}{\partial y_s} (\varphi_s - \varphi_p) \Delta x_p$$

$$+ \frac{\partial x_N}{\partial y_s} (\varphi_N - \varphi_p) \Delta x_p = \Delta x_p \Delta y_p f_p$$

$$\int_{\Omega_i} (\underline{J} \cdot \hat{\underline{n}}) \, d\sigma \quad \dots \quad (2)$$

In terms of "FSOLVE"

$$\begin{aligned}\tilde{f}_p(y) := & \frac{\partial x_{\epsilon}}{\partial x_0} (\varphi_{\epsilon} - \varphi_p) \Delta y_p + \frac{\partial x_n}{\partial y_n} (\varphi_n - \varphi_p) \Delta x_p \\ & + \frac{\partial x_n}{\partial x_0} (\varphi_n - \varphi_p) \Delta y_p + \frac{\partial y_s}{\partial y_s} (\varphi_s - \varphi_p) \Delta x_p \\ & - \Delta x_p \Delta y_p f_p.\end{aligned}$$



We need
to consider
nine different
cases.

To obtain

$$\left. \begin{aligned} D_{xxc} &\approx \frac{1}{2}(D_{xxr} + D_{xxe}) \\ D_{xxw} &\approx \frac{1}{2}(D_{xxp} + D_{xxw}) \\ D_{yya} &\approx \frac{1}{2}(D_{yyr} + D_{yyw}) \\ D_{yyS} &\approx \frac{1}{2}(D_{yyr} + D_{yyS}) \end{aligned} \right\}$$

We use arithmetic averaging.

Next, dealing with surface boundary conditions:

As an example,

$$\boxed{D_{yy} \frac{\partial \varphi}{\partial y} = \frac{D_{yy} G_b}{B_b} - \frac{D_{yy} A_b \varphi}{B_b} - \text{North face B.C. at } y = L_y}$$

This expression is to be used for the North flux:

$$\varphi = L_y$$

Replace this expression in (2) for the general

$$\begin{aligned} \frac{D_{xxc}}{B_{ee}} (\varphi_e - \varphi_p) \Delta y_p + \left(\frac{D_{yyS}}{B_b} - \frac{D_{yy} A_b \varphi_p}{B_b} \right) \Delta x_p \\ + \frac{D_{xxw}}{B_{ew}} (\varphi_e - \varphi_p) \Delta y_p + \frac{D_{yyS}}{B_{ew}} (\varphi_s - \varphi_p) \Delta x_p = \Delta x_p \Delta y_p f_p \end{aligned}$$

If $y = l_y$ is $A_b \varphi(x, y_L) + B_b \frac{\partial \varphi}{\partial y}(x, y_L) = C_b$

$$y = l_y$$

$\uparrow j$



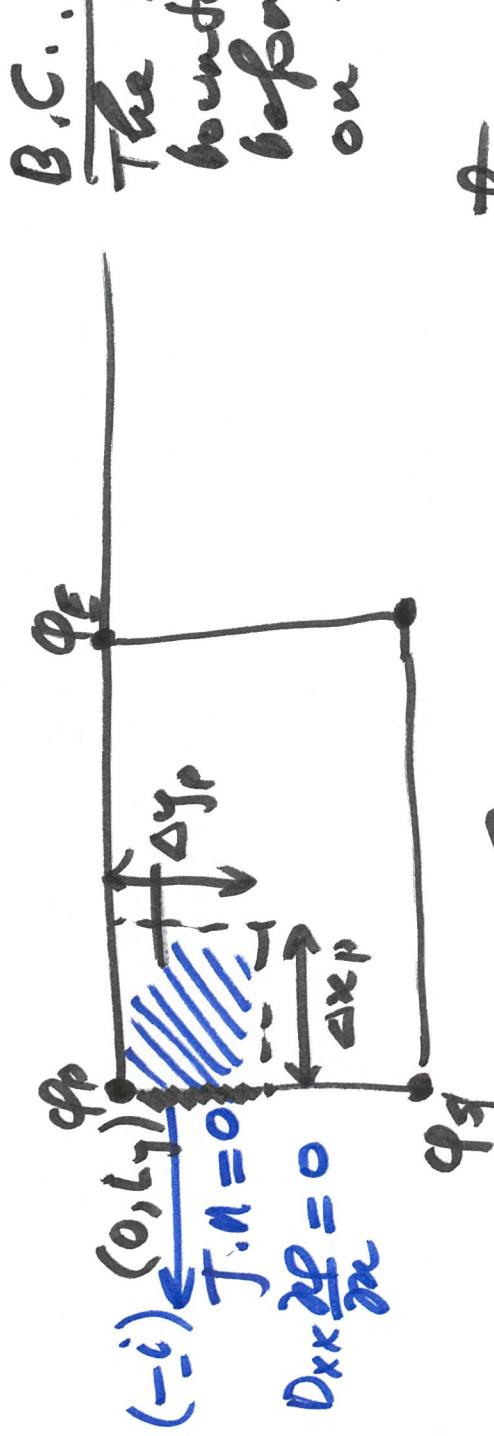
$$A_b \varphi(x, y_L) + B_b \frac{\partial \varphi}{\partial y}(x, y_L) = C_b$$

$$\text{Recall } J = \begin{pmatrix} D_{xx} & 0 \\ 0 & D_{yy} \end{pmatrix} \left(\frac{\partial \varphi}{\partial x} \frac{\partial \varphi}{\partial y} \right) = \begin{pmatrix} D_{xx} \frac{\partial \varphi}{\partial x} & D_{yy} \frac{\partial \varphi}{\partial y} \\ 0 & D_{yy} \frac{\partial \varphi}{\partial y} \end{pmatrix}$$

$$\therefore J \cdot \dot{t} = D_{yy} \frac{\partial \varphi}{\partial y}(x, y_L)$$

$$\text{Rearrange: } B_b \frac{\partial \varphi}{\partial y}(x, y_L) = C_b - \frac{A_b \varphi(x, y_L)}{B_b}$$

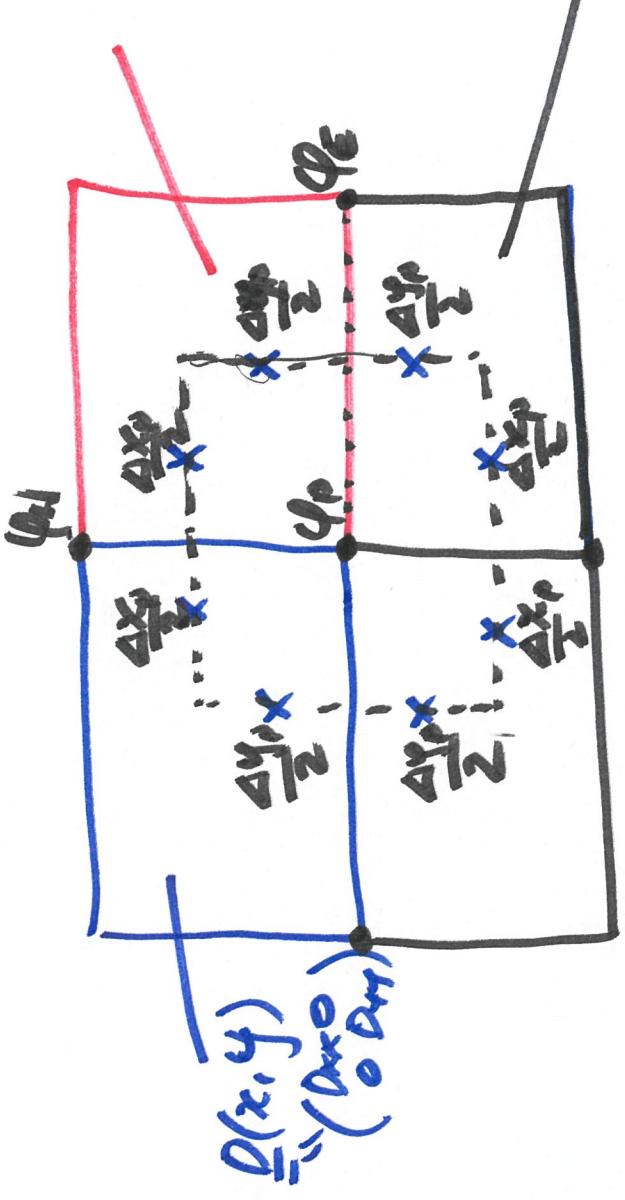
$$\therefore D_{yy} \frac{\partial \varphi}{\partial y}(x, y_L) = D_{yy} \left(\frac{C_b}{B_b} - \frac{A_b \varphi(x, y_L)}{B_b} \right)$$



B.C. :
 The same math
 boundary condition as
 before, but no flux
 on the $x = 0$ boundary.
 (west face)

The FVE equation becomes

$$\begin{aligned}
 & \frac{\partial x_P}{\partial x} (\phi_E - \phi_P) \Delta y_P + \left(\frac{\partial y_P C_b}{B_b} - \frac{\partial y_P A_b}{\partial x} \phi_P \right) \Delta x_P \\
 & \text{See } + \frac{\partial y_P}{\partial y_P} (\phi_S - \phi_P) \Delta x_P = \Delta x_P \Delta y_P f_P.
 \end{aligned}$$



Material type
must be recorded
 $\underline{D}(x, y) = (D_{xx} \ 0)$ "red type"
 $\underline{D}(x, y) = (0 \ D_{yy})$ "blue type"

$$\sum_{j=1}^8 \int_{r_j} T \cdot \hat{n} ds = \Delta x_p \Delta y_p f_p$$

$$\underline{D}(x, y) = \begin{pmatrix} D_{xx} & 0 \\ 0 & D_{yy} \end{pmatrix}$$

$$\stackrel{(R)}{=} \frac{D_{xx}}{\delta y_n} (\varphi_n - \varphi_p) \frac{\Delta x_p}{2} + \frac{D_{yy}}{\delta y_n} (\varphi_n - \varphi_p) \frac{\Delta y_p}{2}$$

$$+ \frac{D_{xx}}{\delta x_n} (\varphi_n - \varphi_p) \frac{\Delta y_p}{2} + \frac{D_{yy}}{\delta x_n} (\varphi_n - \varphi_p) \frac{\Delta x_p}{2} + \dots = \Delta x_p \Delta y_p f_p.$$

$$\stackrel{(R)}{=} \frac{D_{xx} \varphi_e}{\delta x_n} (\varphi_e - \varphi_p) \frac{\Delta y_p}{2} + \frac{D_{yy} \varphi_e}{\delta x_n} (\varphi_e - \varphi_p) \frac{\Delta x_p}{2} + \frac{D_{xx} \varphi_w}{\delta x_n} (\varphi_w - \varphi_p) \frac{\Delta y_p}{2} + \frac{D_{yy} \varphi_w}{\delta x_n} (\varphi_w - \varphi_p) \frac{\Delta x_p}{2}$$