

Ans. 1 (a) Let $X(t) = ax_1(t) + bx_2(t)$

$$\begin{aligned} \Rightarrow Y(t) &= t^2 X(t-1) \\ &= t^2 [ax_1(t-1) + bx_2(t-1)] \\ &= t^2 ax_1(t-1) + bt^2 x_2(t-1) \\ &= ay_1(t) + by_2(t) \quad [\text{Linear}] \end{aligned}$$

If $y(t)$ is response to $x(t)$ then $y(t-T)$ must be response to $x(t-T)$ for time invariant systems

$$\Rightarrow y(t-T) = (t-T)^2 x(t-T)$$

Let response to $x(t-T)$ be $Y(t)$

$$\begin{aligned} \therefore Y(t) &= t^2 x(t-T-1) \\ \Rightarrow Y(t) &\neq y(t-T) \rightarrow \text{Time variant} \end{aligned}$$

[Linear & time variant system]

Ans. 2 (b) $y[n] = (x[n-2])^2$

Let $X[n] = ax_1[n] + bx_2[n]$

$$\begin{aligned} Y[n] &= (ax_1[n-2] + bx_2[n-2])^2 \\ &= a^2 y_1[n-2] + b^2 y_2[n-2] + 2ab x_1[n-2] x_2[n-2] \\ &\neq a^2 y_1[n] + b^2 y_2[n] \quad (\text{non-linear}) \end{aligned}$$

$$1) \text{ } X[n-k] = x$$

$$1) \text{ } X[n] = x[n-k] \rightarrow \text{input}$$

$$\begin{aligned} Y[n] &= (X[n-2])^2 \\ &= (x[n-k-2])^2 \\ &= y[n-k] \end{aligned} \quad (\text{Time Invariant})$$

System is non-linear & time invariant

Ans. 1(c) $y[n] = x[n+1] - x[n-1]$

$$\text{Let } X[n] = ax_1[n] + bx_2[n]$$

$$\rightarrow y[n] = a[x_1[n+1] - x_1[n-1]] + b[x_2[n+1] - x_2[n-1]]$$

$$\begin{aligned} \rightarrow \cancel{y[n]} Y[n] &= ax_1[n+1] + bx_2[n+1] - ax_1[n-1] - bx_2[n-1] \\ &= ay_1[n] + by_2[n] \end{aligned} \quad (\text{Linear})$$

$$\text{Let } X[n] = x[n-k]$$

$$\begin{aligned} Y[n] &= X[n+1] - X[n-1] \\ &= x[n-k+1] - x[n-k-1] \\ &= y[n-k] \end{aligned} \quad (\text{Time Invariant})$$

System is linear & time invariant

Ans 1(d) $y(t) = EV(x(t))$

$$y(t) = \frac{x(t) + x(-t)}{2}$$

let $X(t) = ax_1(t) + bx_2(t)$

$$Y(t) = \frac{X(t) + X(-t)}{2}$$

$$= \frac{ax_1(t) + bx_2(t) + ax_1(-t) + bx_2(-t)}{2}$$

$$= ay_1(t) + by_2(t) \quad (\text{Linear})$$

let: $X(t) = x(t-k)$

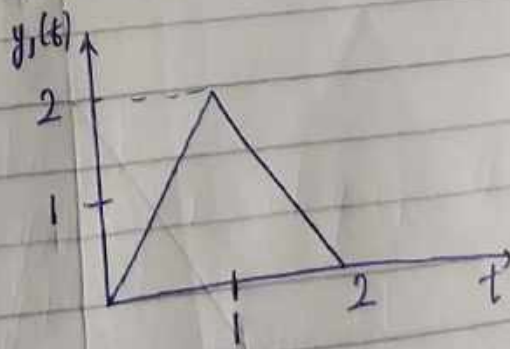
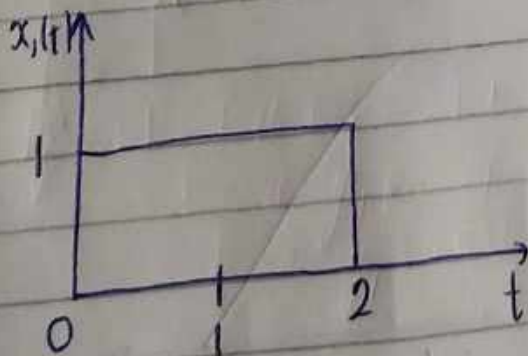
$$Y(t) = \frac{X(t) + X(-t)}{2} = \frac{x(t-k) + x(-t-k)}{2}$$

$$\neq y(t-k) \quad \left[\because y(t-k) = \frac{x(t-k) + x(-t+k)}{2} \right]$$

(Time variant)

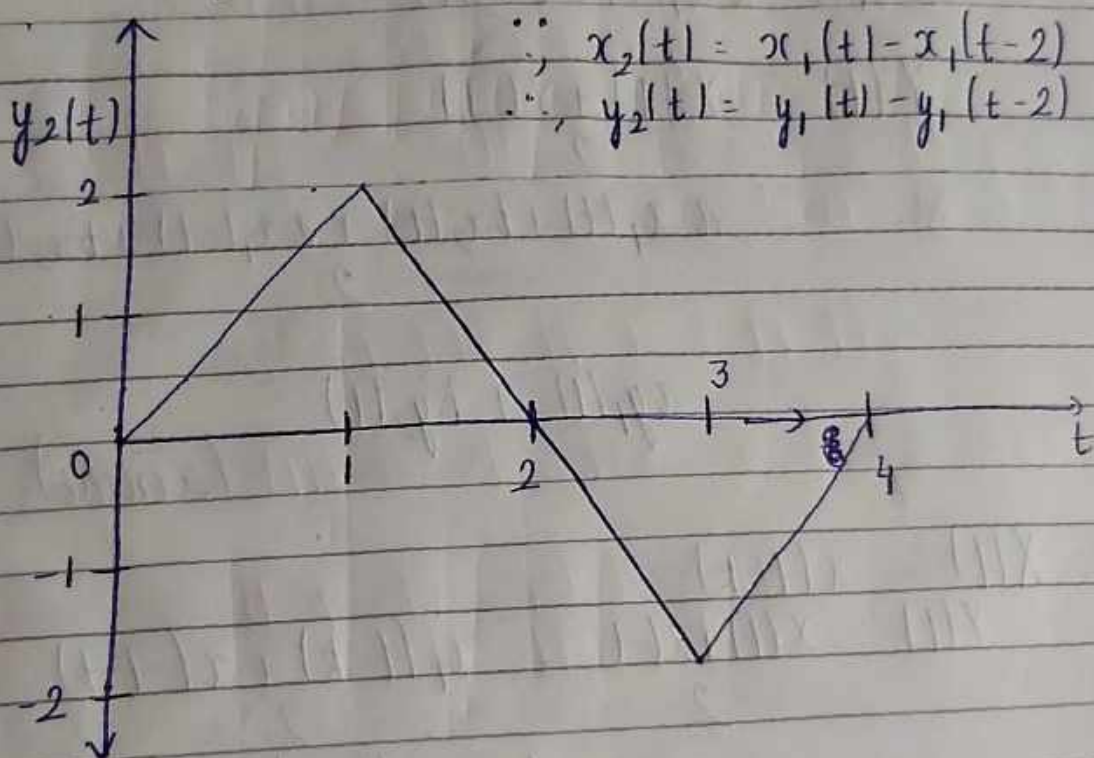
System is linear & time variant

Ans 2

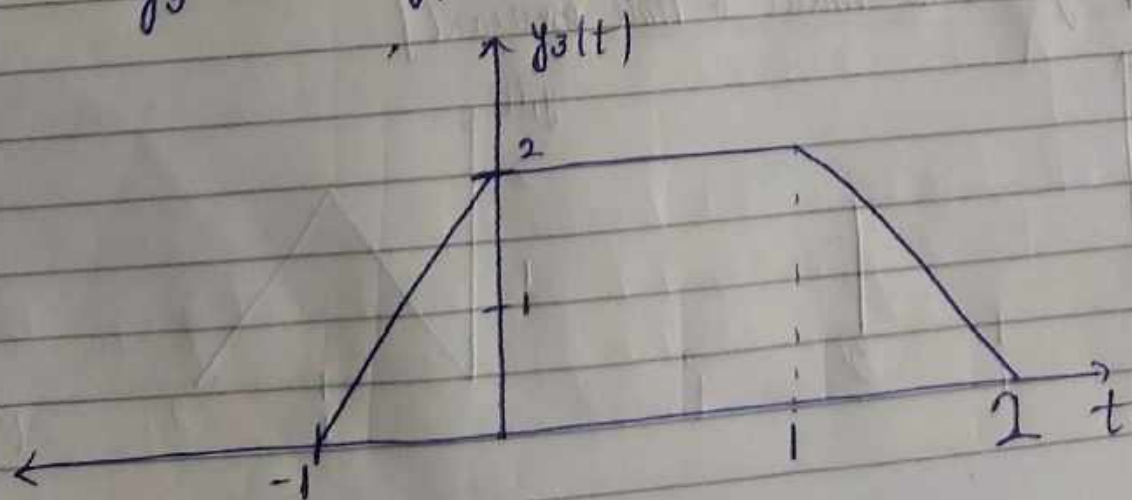


→ (a) First half is trivial. Second half is ^a shifted version and reversed version of the input.

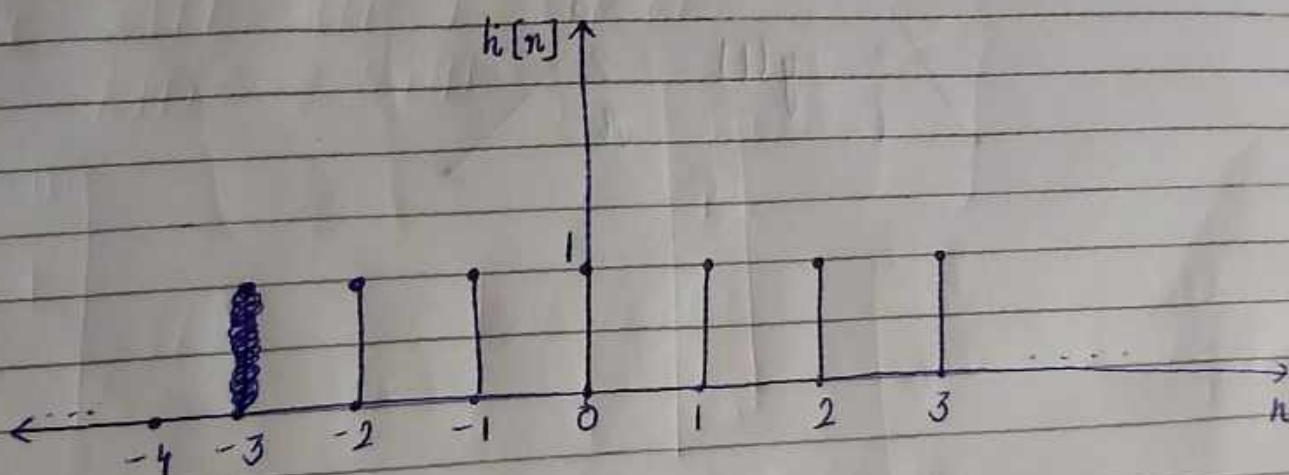
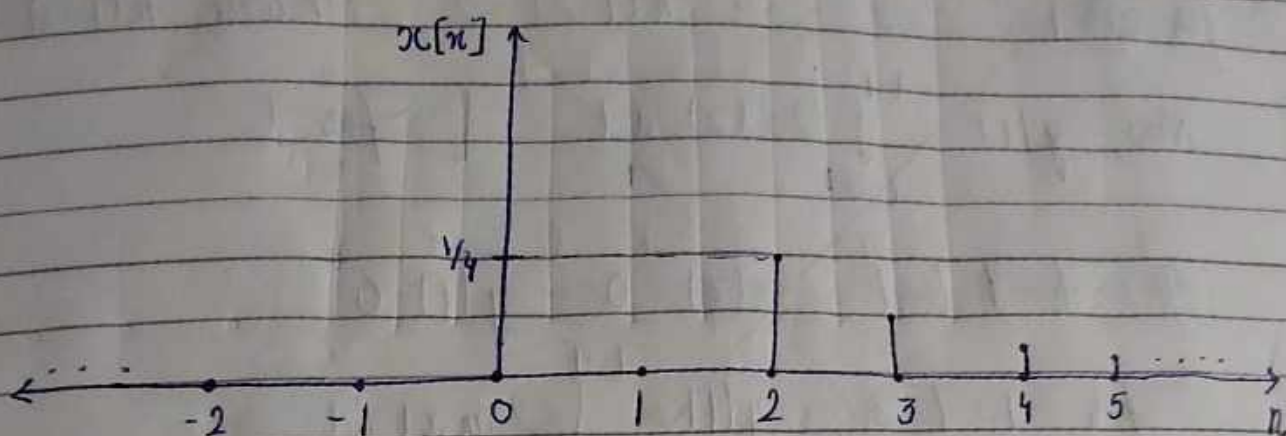
So assuming, it is an LTI system, output after ~~the~~ $t=2$ will also be shifted & reversed.



(b)
 $x_3(t) = x_1(t) + x_1(t+1)$
 $y_3(t) = y_1(t) + y_1(t+1)$

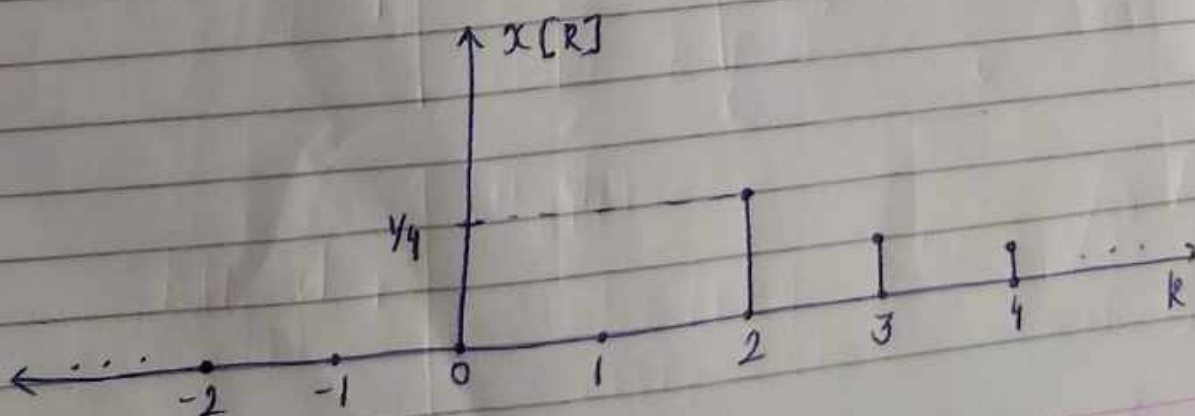


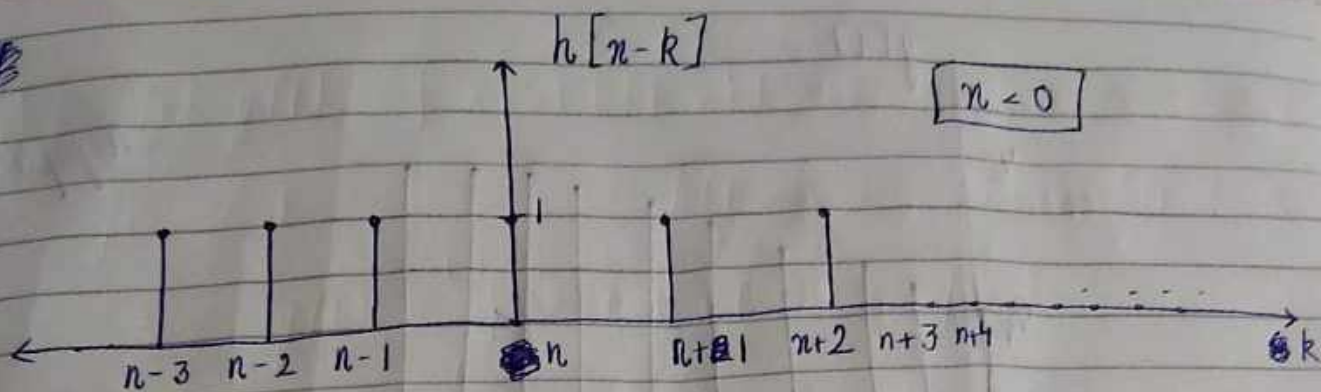
Ans 3 $x[n] = \left(\frac{1}{2}\right)^n u[n-2]$



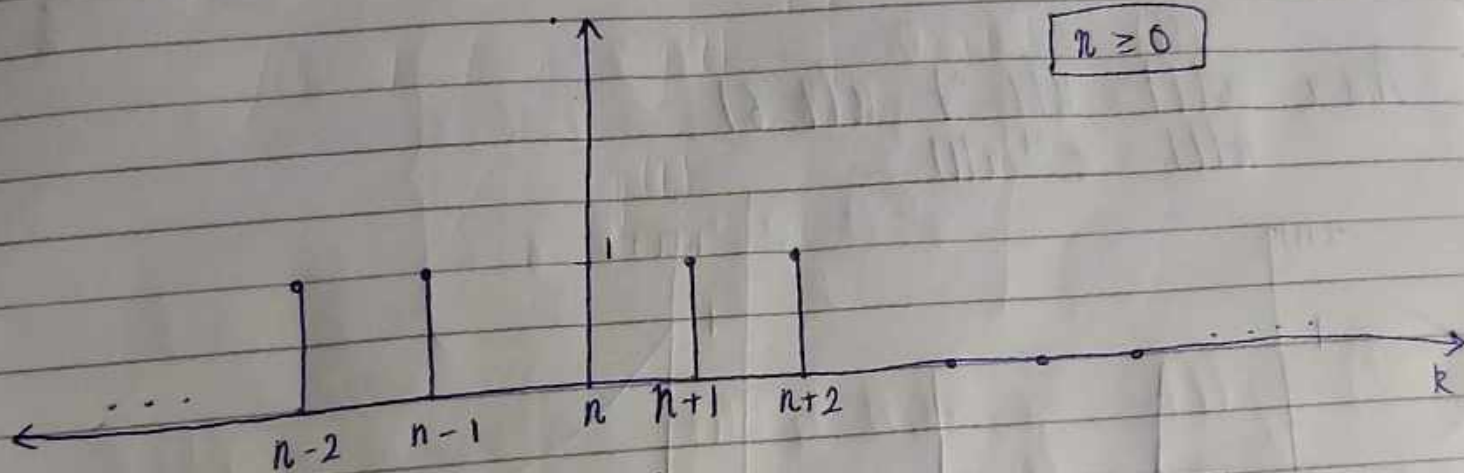
$$y[n] = \sum_{k=-\infty}^{\infty} x[k] h[n-k]$$

$$= x[n] * h[n]$$





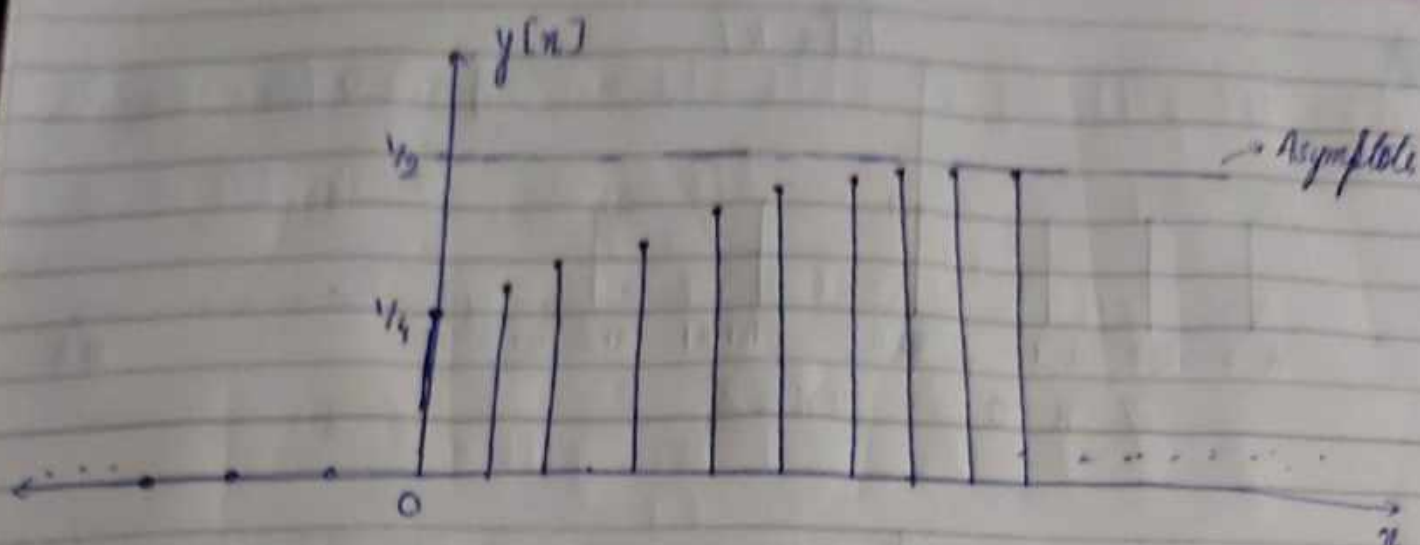
$$\text{If } n < 0 \rightarrow 2+n \leq 2$$



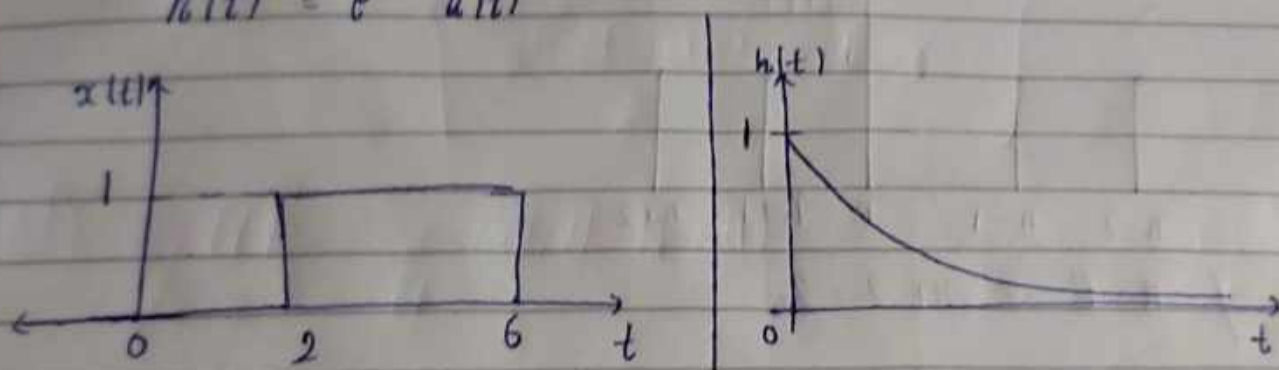
$$\text{If } n \geq 0 \Rightarrow n+2 \geq 2$$

$$\therefore y[n] = \begin{cases} 0, & n < 0 \\ \sum_{k=2}^{n+2} \left(\frac{1}{2}\right)^k, & n \geq 0 \end{cases}$$

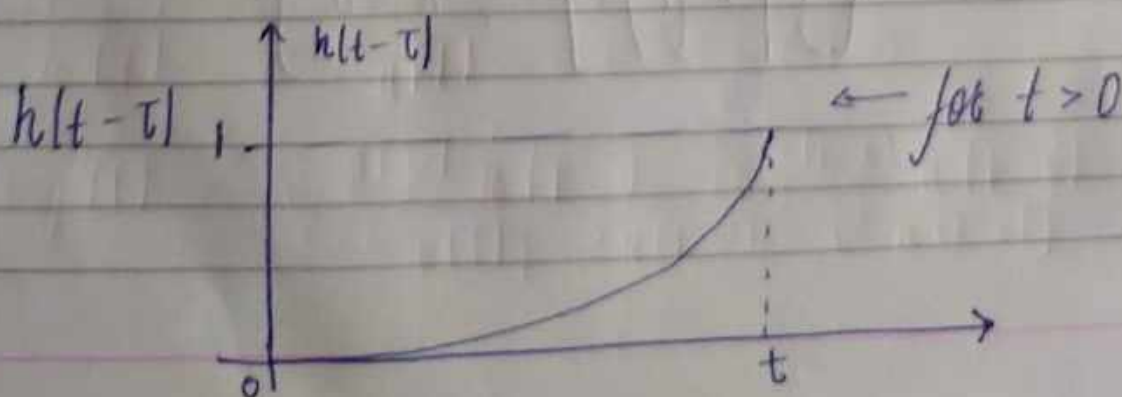
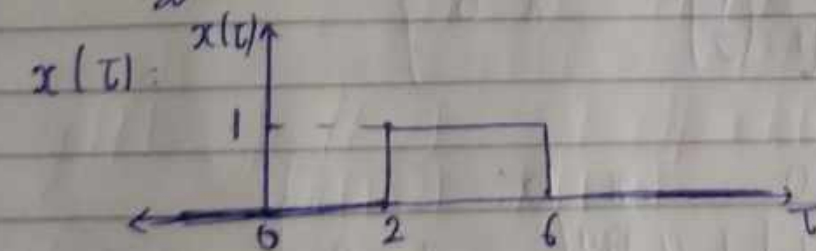
$$\Rightarrow y[n] = \begin{cases} 0, & n < 0 \\ \frac{1}{2} \left[1 - \left(\frac{1}{2}\right)^{n+1} \right], & n \geq 0 \end{cases}$$



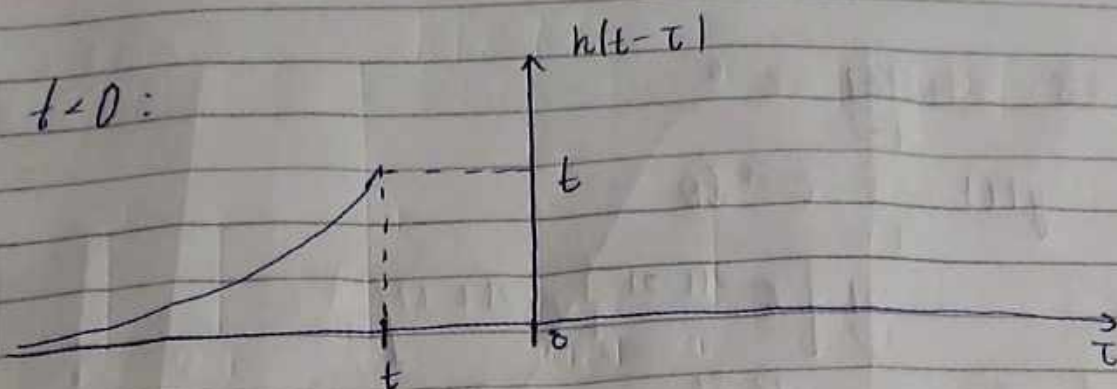
Ans 4 $x(t) = u(t-2) - u(t-6)$
 $h(t) = e^{-2t} u(t)$



(a) $y(t) = \int_{-\infty}^{\infty} x(\tau) h(t-\tau) d\tau$



→ for $t < 0$:



$$\text{Now, } y(t) = x(t) * h(t) = \int_{-\infty}^{\infty} x(\tau) h(t-\tau) d\tau$$

$$\therefore x(t) = 0 \quad \forall -\infty < t < 2 \quad \& \quad 6 < t < \infty$$

$$y(t) = \int_{2-t}^{t-6} x(\tau) h(t-\tau) d\tau$$

$$y(t) = \int_{t-6}^{t-2} h(\theta) d\theta$$

$$[\theta = t - \tau]$$

$$\text{Now, } h(\theta) = \begin{cases} 0, & \theta < 0 \\ e^{-2\theta}, & \theta \geq 0 \end{cases}$$

$$\textcircled{1} \text{ For } t < 2 \Rightarrow h(\theta) = 0 \quad \forall \theta$$

$$\Rightarrow y(t) = 0$$

$$\textcircled{2} \text{ For } 2 < t < 6, \quad h(\theta) = \begin{cases} 0, & \theta < 0 \\ e^{-2\theta}, & \theta \geq 0 \end{cases}$$

$$\Rightarrow y(t) = \int_{t-6}^0 0 d\theta + \int_0^{t-2} e^{-2\theta} d\theta$$

$$\Rightarrow y(t) = 1 - \frac{e^{4-2t}}{2}$$

③ For $t > 6$, $h(t) = e^{-2t}$,

$$y(t) = \int_{t-6}^{t-2} e^{-2\theta} d\theta$$

$$= \frac{-1}{2} \left[e^{-2(t-2)} - e^{-2(t-6)} \right]$$

$$\boxed{y(t) = \frac{e^{12-2t} - e^{-2(t-2)}}{2}}$$

$$\therefore y(t) = \begin{cases} 0 & t < 2 \\ \frac{1 - e^{4-2t}}{2}, & 2 \leq t \leq 6 \\ \frac{e^{12-2t} - e^{4-2t}}{2} & t > 6 \end{cases}$$

(b) $g(t) = \frac{d}{dt} (x(t)) * h(t)$

$$\frac{d}{dt} (x(t)) = \frac{d}{dt} [u(t-2) - u(t-6)]$$

$$= \delta(t-2) - \delta(t-6)$$

$$g(t) = [\delta(t-2) - \delta(t-6)] * h(t)$$

$$= h(t-2) - h(t-6)$$

$$h(t) = e^{-2t} u(t)$$

$$g(t) = e^{-2(t-2)} u(t-2) - e^{-2(t-6)} u(t-6)$$

$$= e^{-2t} \cancel{u(t)} [e^4 u(t-2) - e^{12} u(t-6)]$$

$$\textcircled{1} \quad t-2 < 0 \Rightarrow t < 2 \Rightarrow u(t-2) = 0, \quad u(t-6) = 0 \\ g(t) = 0$$

$$\textcircled{2} \quad 2 < t < 6 \Rightarrow u(t-2) = 1, \quad u(t-6) = 0 \\ \Rightarrow g(t) = e^{-2t}(e^4) = e^{4-2t} \\ \Rightarrow \boxed{g(t) = e^{4-2t}}$$

$$\textcircled{3} \quad t > 6 \Rightarrow u(t-2) = u(t-6) = 1 \\ g(t) = e^{-2t}(e^4 - e^{12}) \\ \boxed{g(t) = e^{4-2t}(1 - e^8)}$$

$$\therefore, \boxed{g(t) = \begin{cases} 0, & t < 2 \\ e^{4-2t}, & 2 \leq t \leq 6 \\ e^{4-2t}(1 - e^8), & t > 6 \end{cases}}$$

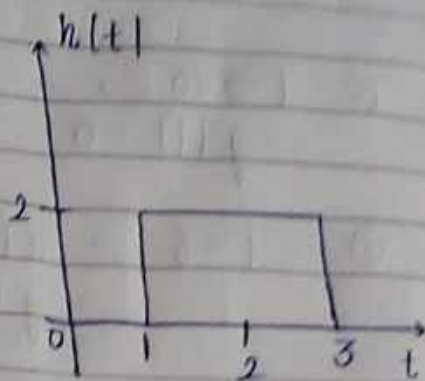
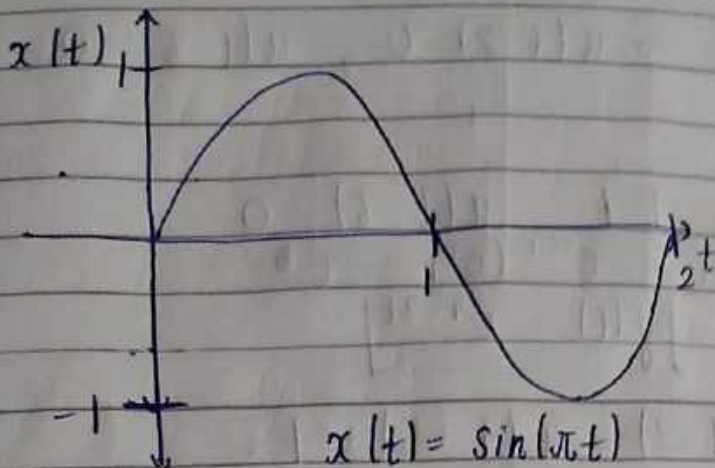
~~$y(t)$~~

$$\textcircled{c) \quad y(t) = \begin{cases} 0, & t < 2 \\ \frac{1}{2}[1 - e^{4-2t}], & 2 \leq t \leq 6 \\ \frac{1}{2}[e^{12-2t} - e^{4-2t}], & t > 6 \end{cases}}$$

$$\Rightarrow \boxed{y(t) = \begin{cases} g(t), & t < 2 \\ (\frac{1}{2})(1 - g(t)), & 2 \leq t \leq 6 \\ (-\frac{1}{2})g(t), & t > 6 \end{cases}}$$

$$\Rightarrow \boxed{g(t) = \frac{d}{dt}(y(t)) = \frac{d}{dt}(x(t) * h(t))}$$

Ans 5(a)



Now, $y(t) = \int_{-\infty}^{\infty} x(\tau) h(t-\tau) d\tau$

where, $x(\tau) = \begin{cases} \sin(\pi\tau) & , 1 \leq \tau \leq 2 \\ 0 & , \text{otherwise} \end{cases}$

$h(t-\tau) = \begin{cases} 2 & , t-3 \leq \tau \leq t-1 \\ 0 & , \text{otherwise} \end{cases}$

$\therefore y(t) = \int_0^2 \sin(\pi\tau) h(t-\tau) d\tau$

$\Rightarrow y(t) = \int_{t-2}^t \sin[\pi(t-\theta)] h(\theta) d\theta \quad [\theta = t-\tau]$

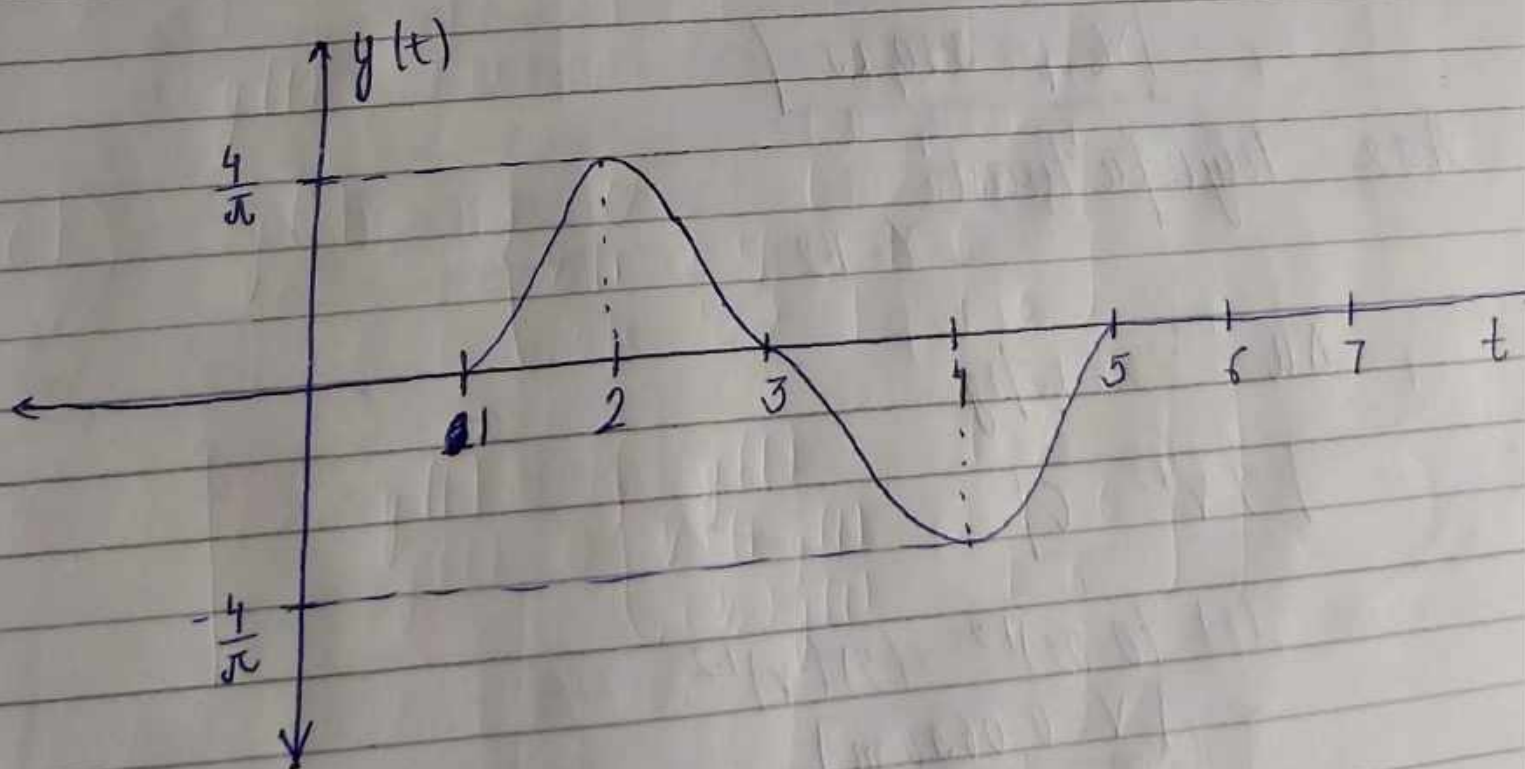
① ~~$t < 1$~~ $t < 1$ and $t-2 > 3 \Rightarrow t > 5$
 $\Rightarrow h(\theta) = 0 \Rightarrow y(t) = 0$

② $1 \leq t \leq 3 \Rightarrow y(t) = \int_{t-2}^t 0 d\tau + \int_1^t 2 \sin(\pi t - \pi\theta) d\theta$
 $\Rightarrow y(t) = \frac{2}{\pi} [1 + \cos(\pi t)]$

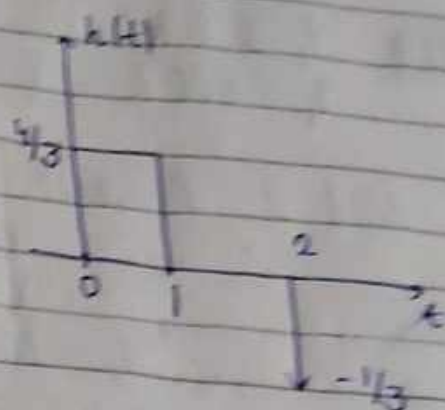
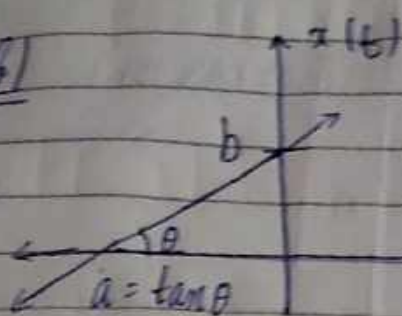
$$\textcircled{3} \quad \begin{matrix} 1 < t-2 < 3 \\ 3 < t < 5 \end{matrix} \Rightarrow y(t) = \int_{t-2}^3 [2 \sin(\pi t - \pi \theta)] d\theta + \int_3^t 0 d\theta$$

$$\boxed{y(t) = \frac{2}{\pi} [-1 - \cos(\pi t)]}$$

$$\therefore y(t) = \begin{cases} \frac{2}{\pi} (1 + \cos(\pi t)) & , 1 < t < 3 \\ -\frac{2}{\pi} (1 + \cos(\pi t)) & , 3 < t < 5 \\ 0 & , \text{otherwise} \end{cases}$$



Ans 5 (B)



$$\Rightarrow \cancel{x(t) = at + b}$$

$$\Rightarrow x(t) = at + b$$

$$\text{let } h(t) = h_1(t) + \left(\frac{-1}{3} \delta(t-2) \right)$$

$$\therefore, y(t) = x(t) * h(t)$$

$$= x(t) * (h_1(t) - \frac{1}{3} \delta(t-2))$$

$$= x(t) * h_1(t) - \frac{1}{3} x(t) * \delta(t-2)$$

$$= x(t) * h_1(t) - \frac{1}{3} x(t-2)$$

$$\text{Now, } h_1(t) = \begin{cases} \frac{4}{3}, & 0 \leq t \leq 1 \\ 0, & \text{otherwise} \end{cases}$$

$$\therefore, x(t) * h_1(t) = \int_{-\infty}^{\infty} x(t-\theta) h_1(\theta) d\theta \quad [t-\tau=0]$$

$$= \int_0^1 x(t-\theta) \left(\frac{4}{3} \right) d\theta + 0$$

$$= \frac{4}{3} \int_0^1 [at - a\theta + b] d\theta$$

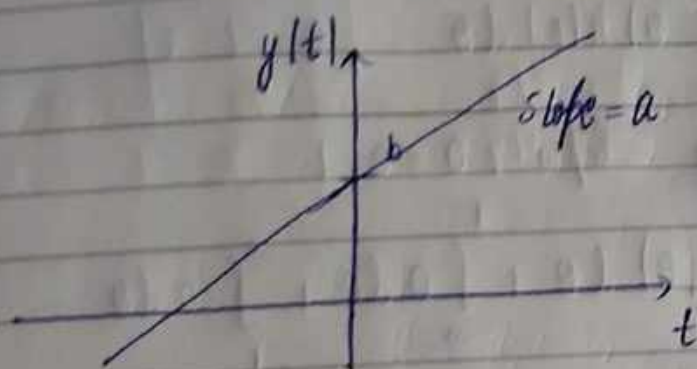
$$\Rightarrow x(t) * h_1(t) = \frac{4}{3} (at + b) - \frac{2a}{3}$$

Now, $\frac{x(t-2)}{3} = \frac{1}{3} [a(t-2) + b]$

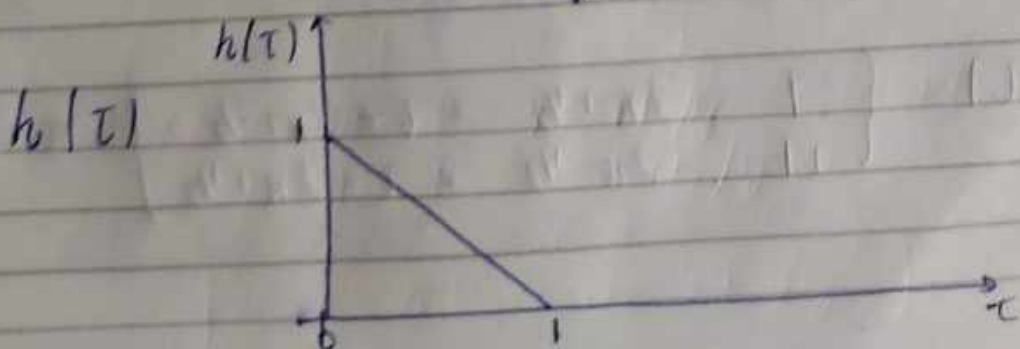
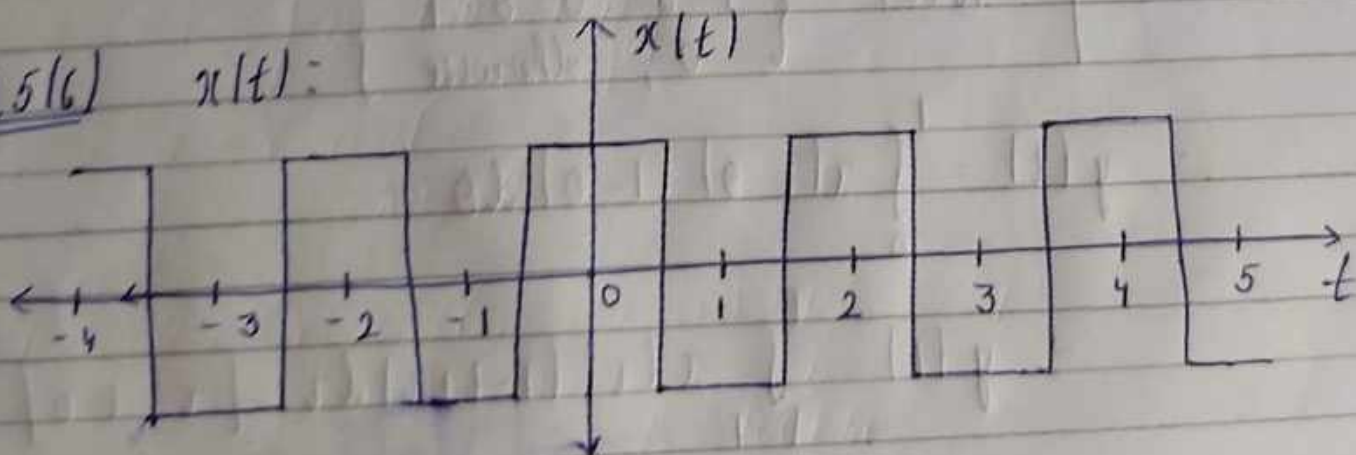
$\therefore y(t) = x(t) * h_1(t) = \frac{1}{3} x(t-2)$

$= \frac{1}{3} (at+b) = \frac{2a}{3} + \frac{1}{3} [a(t-2) + b]$

$\Rightarrow y(t) = at+b$
 $\Rightarrow \boxed{y(t) = x(t)}$

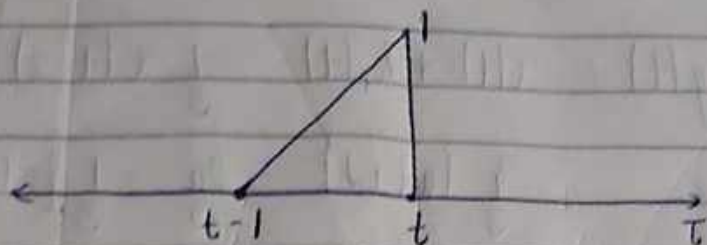


Ans. 5(c) $x(t) =$



$$y(t) = \int_{-\infty}^{\infty} x(\tau) h(t-\tau) d\tau$$

$$h(t-\tau) =$$



$$\text{in } y(t) = \int_{-\infty}^{\infty} x(\tau) h(t-\tau) d\tau$$

$$y(t) = \int_{-\infty}^{\infty} x(t-\theta) h(\theta) d\theta \quad [\theta = t-\tau]$$

Since, $h(\theta) \rightarrow$ non-zero only b/w $0 \leq \theta \leq 1$:

$$y(t) = \int_0^1 x(t-\theta) h(\theta) d\theta + \int_{-\infty}^0 0 d\theta + \int_1^{\infty} 0 d\theta$$

$$\Rightarrow \left| h(\theta) = \begin{cases} 1-\theta & 0 \leq \theta \leq 1 \\ 0, & \text{otherwise} \end{cases} \right.$$

$$\therefore, y(t) = \int_0^1 x(t-\theta) (1-\theta) d\theta$$

$$\Rightarrow y(t) = \int_{t-1}^t x(\tau) (1-t+\tau) d\tau \quad [\tau = t-\theta]$$

$$\left| x(\tau) = \begin{cases} -1, & 2n + 1/2 \leq \tau \leq 2n + 3/2 \\ +1, & 2n - 1/2 \leq \tau \leq 2n + 1/2 \end{cases} \right. \quad n \in \mathbb{I}$$

$$(1) \quad 2n + \frac{1}{2} \leq t \leq 2n + \frac{3}{2}$$

$$(2) \quad 2n - \frac{1}{2} \leq t \leq 2n + \frac{1}{2}, \quad n \in \mathbb{I}$$

We can take $n=0$ as $x(t) \rightarrow$ periodic.

$$(1) \quad n=0 \Rightarrow \frac{1}{2} \leq t \leq \frac{3}{2}$$

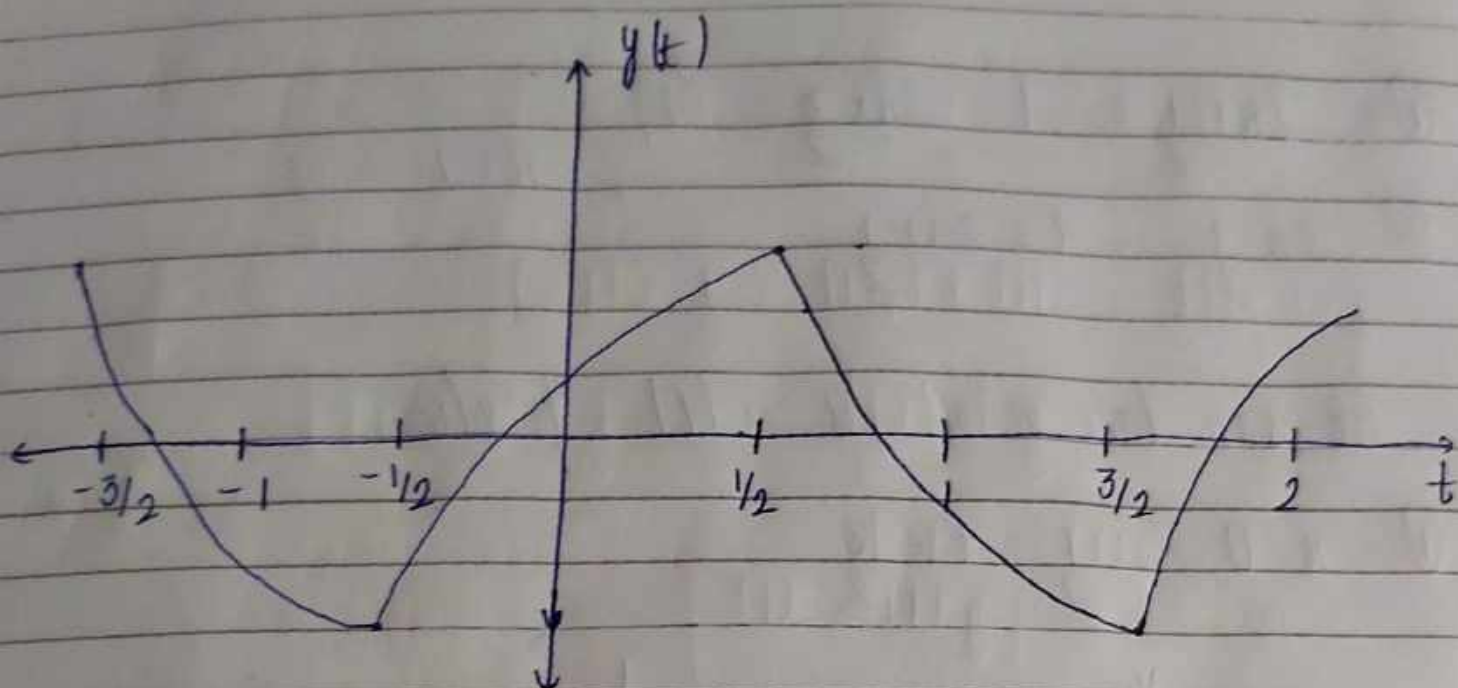
$$\begin{aligned} y(t) &= \int_{t-1}^{\frac{1}{2}} 1(1-t+\tau) d\tau + \int_{\frac{1}{2}}^t (-1)(1-t+\tau) d\tau \\ &= (1-t) \left(\frac{1}{2} - t + 1 \right) - \frac{1}{8} - \frac{(t-1)^2}{2} + (-1) \left[(1-t) \left(t - \frac{1}{2} \right) + \frac{t^2}{2} - \frac{1}{8} \right] \\ &= t^2 - 3t + \frac{7}{4} \quad \text{for } 2n + \frac{1}{2} \leq t \leq 2n + \frac{3}{2}, n \in \mathbb{I} \end{aligned}$$

$$(2) \quad n=0 \Rightarrow -\frac{1}{2} \leq t \leq \frac{1}{2}$$

$$y(t) = \int_{t-1}^{-\frac{1}{2}} (-1)(1-t+\tau) d\tau + \int_{-\frac{1}{2}}^t (1)(1-t+\tau) d\tau$$

$$\Rightarrow -t^2 + t + \frac{1}{4} \Rightarrow \text{for } 2n - \frac{1}{2} \leq t \leq 2n - \frac{3}{2}, n \in \mathbb{I}$$

Now, since the funcⁿ is periodic, the graph b/w $\left[-\frac{1}{2}, \frac{3}{2}\right]$ will repeat with a period of 2.



$$y(t) = \begin{cases} (t-2n)^2 - 3(t-2n) + 7/4 & ; 2n+1/2 \leq t \leq 2n+3/2 \\ -|t-2n|^2 + (t-2n) + 1/4 & ; 2n-1/2 \leq t \leq 2n+1/2 \end{cases}$$