

# Unit – 3 TYPE CHECKING

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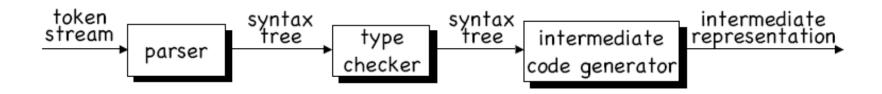
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# Type Checking

#### **Type Checking**





- TYPE CHECKING is the main activity in semantic analysis.
- Goal: calculate and ensure consistency of the type of every expression in a program
- If there are type errors, we need to notify the user.
- Otherwise, we need the type information to generate code that is correct.



# Type Systems and Type Expressions

#### Type systems



- Every language has a set of types and rules for assigning types to language constructs.
- Example from the C specification:
  - "The result of the unary & operator is a pointer to the object referred to by the operand. If the type of the operand is '...' then the type of the result is 'pointer to ...'
- Usually, every expression has a type.
- Type have structure: the type 'pointer to int' is
   CONSTRUCTED from the type 'int'

#### Basic vs. constructed types



- Most programming languages have basic and constructed types.
- BASIC TYPES are the atomic types provided by the language.
  - Pascal: boolean, character, integer, real
  - C: char, int, float, double
- CONSTRUCTED TYPES are built up from basic types.
  - Pascal: arrays, records, sets, pointers
  - C: arrays, structs, pointers

### Type expressions



- We denote the type of language constructs with TYPE EXPRESSIONS.
- Type expressions are built up with TYPE CONSTRUCTORS.

- 1. A basic type is a type expression. The basic types are boolean, char, integer, and real. The special basic type type\_error signifies an error. The special type void signifies "no type"
- 2. A type name is a type expression (type names are like typedefs in C)

# Type expressions



- A type constructor applied to type expressions is a type expression.
  - a. Arrays: if T is a type expression, then pointer(T) is a type expression denoting the type "pointer to an object of type T"
    - Array(I,T)  $\leftarrow$  I: index set, T: element type
  - **b.** Products: if T1 and T2 are type expressions, then their Cartesian product  $T1 \times T2$  is also a type expression.
  - **c.** Records: a record is a special kind of product in which the fields have names (examples below)
  - **d. Pointers**: if T is a type expression, then pointer(T) is a type expression denoting the type "pointer to an object of type T"
  - **e.** Functions: functions map elements of a domain D to a range R, so we write D -> R to denote "function mapping objects of type D to objects of type R" (examples below)
- 4. Type expressions may contain variables, whose values are themselves type expressions. 

  polymorphism

#### Record type expressions



#### The Pascal code

```
type row = record
                                  address: integer;
                                  lexeme: array[1..15] of char
                         end;
        var table: array[1..10] of row;
associates type expression
record((address \times integer) \times (lexeme \times array(1..15,char)))
with the variable row, and the type expression
array(1..101, record((address \times integer) \times (lexeme \times array(1..15, char)))
with the variable table
```

# Function type expressions



#### The C declaration

```
int *foo( char a, char b );
```

would associate type expression

```
char × char -> pointer(integer)
```

with foo. Some languages (like ML) allow all sorts of crazy

function types, e.g.

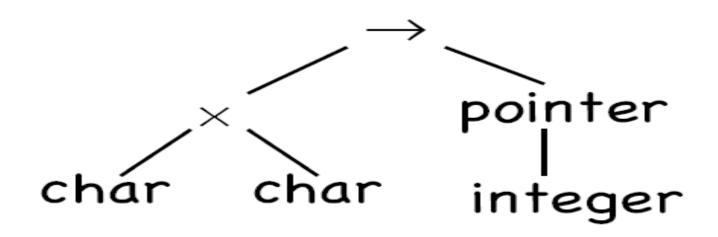
```
(integer -> integer) -> (integer -> integer)
```

denotes functions taking a function as input and returning another function

# Graph representation of type expressions



• The recursive structure of a type can be represented with a tree, e.g. for char × char -> pointer(integer):



 Some compilers explicitly use graphs like these to represent the types of expressions.

#### Type systems and checkers



- A TYPE SYSTEM is a set of rules for assigning type expressions to the parts of a program.
- Every type checker implements some type system.
- Syntax-directed type checking is a simple method to implement a type checker.

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# Static vs. dynamic type checking



- **STATIC** type checking is done at compile time.
- **DYNAMIC** type checking is done at run time.
- Any kind of type checking CAN be done at run time.
- But this reduces run-time efficiency, so we want to do static checking when possible.
- A SOUND type system is one in which ALL type errors can be found statically.
- If the compiler guarantees that every program it accepts will run without type errors, then the language is STRONGLY TYPED.



# An Example Type Checker

#### Example type checker



- Let's build a translation scheme to synthesize the type of every expression from its subexpressions.
- Here is a Pascal-like grammar for a sequence of declarations (D) followed by an expression (E)

```
P \rightarrow D; E
D \rightarrow D; D \mid id : T
T \rightarrow char \mid integer \mid array [ num ] of T \mid \uparrow T
E \rightarrow literal \mid num \mid id \mid E \mod E \mid E \mid E \mid \mid E \uparrow
```

Example program: key: integer; key mod 1999

#### The type system



- The basic types are char and integer. type\_error signals an error.
- All arrays start at 1, so array[256] of char leads to type expression: array(1..256,char)
- The symbol ↑ in an declaration specifies a pointer type, so \(\gamma\) integer leads to type expression: pointer(integer)

# Translation scheme for declarations



```
P \rightarrow D; E
D \rightarrow D ; D
\mathbf{D} \rightarrow \mathbf{id} : \mathbf{T}
                                      { addtype(id.entry, T.type) }
T \rightarrow char
                                      { T.type := char }
T \rightarrow integer
                                      { T.type := integer }
                                      \{ T.type := pointer(T_1.type) \}
T \rightarrow \uparrow T_1
T \rightarrow array [num] of T_1 { T.type := array(1.. num.val, T_1.type)}
```

Try to derive the annotated parse tree for the declaration

X: array[100] of ↑ char

# Type checking for expressions



Once the identifiers and their types have been inserted into the symbol table, we can check the type of the elements of an expression:

```
E \rightarrow literal
                                 { E.type := char }
                                 { E.type := integer }
E \rightarrow num
                                   { E.type := lookup(id.entry) }
\mathbf{E} \rightarrow \mathbf{id}
E \rightarrow E_1 \mod E_2
                                   { if E_1.type =integer and E_2.type = integer
                                 then E.type := integer
                                 else E.type := type_error }
\mathbf{E} \rightarrow \mathbf{E_1} [\mathbf{E_2}]
                                  { if E_2.type = integer and E_1.type =
array(s,t)
                                 then E.type := t else E.type := type_error }
E \rightarrow E_1 \uparrow
                                 { if E_1.type = pointer(t)
                                 then E.type := t else E.type := type-error }
```

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#### How about boolean types?



Try adding

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T -> boolean

Relational operators < <= = >= > <>

Logical connectives and or not

to the grammar, then add appropriate type checking semantic actions.

#### Type checking for statements



- Usually we assign the type VOID to statements.
  - ❖ If a type error is found during type checking, though, we should set the type to type\_error
  - Let's change our grammar allow statements:

$$P \rightarrow D; S$$

❖ i.e., a program is a sequence of declarations followed by a sequence of statements.

#### Type checking for statements



Now we need to add productions and semantic actions:

```
S \rightarrow id := E
                         { if id.type = E.type then S.type := void
                                   else S.type := type error }
S \rightarrow if E then S_1
                                    { if E.type = boolean
                                    then S.type := S_1.type
                                    else S.type := type error }
S \rightarrow while E do S_1 { if E.type = boolean
                                    then S.type := S_1.type
                                    else S.type := type error }
S \rightarrow S_1 ; S_2
                         { if S_1.type = void and S_2.type = void
                                    then S.type := void
                                    else S.type := type error.
```

#### Type checking for function calls



- Suppose we add a production  $E \rightarrow E (E)$
- Then we need productions for function declarations:

$$T \rightarrow T_1 \rightarrow T_2$$
 { T.type :=  $T_1$ .type  $\rightarrow$  T2.type }

and function calls:

$$E \to E_1 \ (E_2) \qquad \{ \ if \ E_2.type = s \ and \ E_1.type = s \to t \\$$
 
$$then \ E.type := t$$
 
$$else \ E.type := type\_error \ \}$$

### Type checking for function calls



Multiple-argument functions, however, can be modeled as functions that take a single PRODUCT argument.

root: (real 
$$\rightarrow$$
 real) x real  $\rightarrow$  real

this would model a function that takes a real function

over the reals, and a real, and returns a real. In C:

float root( float (\*f)(float), float x );

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### Type expression equivalence



- Type checkers need to ask questions like:
  - "if E1.type == E2.type, then ..."
- What does it mean for two type expressions to be equal?
  - STRUCTURAL EQUIVALENCE says two types are the same if they are made up of the same basic types and constructors.
  - NAME EQUIVALENCE says two types are the same if their constituents have the **SAME NAMES**.

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### Structural Equivalence



```
boolean sequiv(s, t)
         if s and t are the same basic type
                  return TRUE;
         else if s == array(s_1, s_2) and t == array(t_1, t_2)
                  return sequiv(s_1, t_1) and sequiv(s_2, t_2)
         else s == s_1 \times s_2 and t = t_1 \times t_2 then
                  return sequiv(s_1, t_1) and sequiv(s_2, t_2)
         else if s == pointer(s_1) and t == pointer(t_1)
                  return sequiv(s_1, t_1)
         else if s == s_1 \rightarrow s_2 and t == t_1 \rightarrow t_2 then
                  return sequiv(s_1, t_1) and sequiv(s_2, t_2)
                                                  Try: int foo( int, float )
         return false}
```

#### Relaxing structural equivalence



- We don't always want strict structural equivalence.
  - E.g. for arrays, we want to write functions that accept arrays of any length.
- To accomplish this, we would modify sequiv() to accept any bounds:

```
• • •
```

```
else if s == array(s_1, s_2) and t == array(t_1, t_2)
return sequiv(s<sub>2</sub>, t<sub>2</sub>)
```

• • •

#### **Encoding types**



- Recursive routines are very slow.
- Recursive type checking routines increase the compiler's run time.
- In the compilers of the 1970's and 1980's, compilers took too long time to run.
- So designers came up with ENCODINGS for types that allowed for faster type checking.

#### Name equivalence



 Most languages allow association of names with type expressions. This makes type equivalence trickier.

```
Example from Pascal:
 type link = \uparrowcell;
 var next: link;
         last: link;
         p: ↑ cell;
         q,r: ↑ cell;
Do next, last, p, q, and r have the same type?
In Pascal, it depends on the implementation!
In structural equivalence, the types would be the same.
But NAME EQUIVALENCE requires identical NAMES.
```

#### Handling cyclic types



Suppose we had the Pascal declaration

```
type link = \uparrowcell;
                            cell = record
cell = record
       info: integer;
       next: link;
end;
                       info
                               integer
                                         info
                                                 integer
```

The declaration of cell contains itself (via the next pointer).

The graph for this type therefore contains a cycle.

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### Cyclic types



The situation in C is slightly different, since it is impossible to refer to an undeclared name.

C uses name equivalence for structs to avoid recursion (after expanding typedef's). But it uses structural equivalence elsewhere.

### Type conversion



- Suppose we encounter an expression x+i where x has type float and i has type int.
- CPU instructions for addition could take EITHER float OR int as operands, but not a mix.
- This means the compiler must sometimes convert the operands of arithmetic expressions to ensure that operands are consistent with operators.
- With postfix as an intermediate language for expressions,
   we could express the conversion as follows:

x i inttoreal float+

where **real**+ is the floating point addition operation.

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# Type coercion

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If type conversion is done by the compiler without the programmer requesting it, it is called IMPLICIT conversion or type **COERCION**.

**EXPLICIT** conversions are those that the programmer specifices, e.g. x = (int)y \* 2;

Implicit conversion of **CONSTANT** expressions should be done at compile time.

#### Type checking example

#### with coercion

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**Production** Semantic Rule

E -> num E.type := integer

**E** -> num . num **E**.type := real

E -> id E.type := lookup(id.entry)

 $E \rightarrow E_1$  op  $E_2$   $E.type := if E_1.type == integer and E_2.type == integer$ 

then integer

else if  $E_1$ .type == integer and  $E_2$ .type == real

then real

else if  $E_1$ .type == real and  $E_2$ .type == integer

then real

else if  $E_1$ .type == real and  $E_2$ .type == real

then real

else type\_error



#### END OF TYPE CHECKING

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