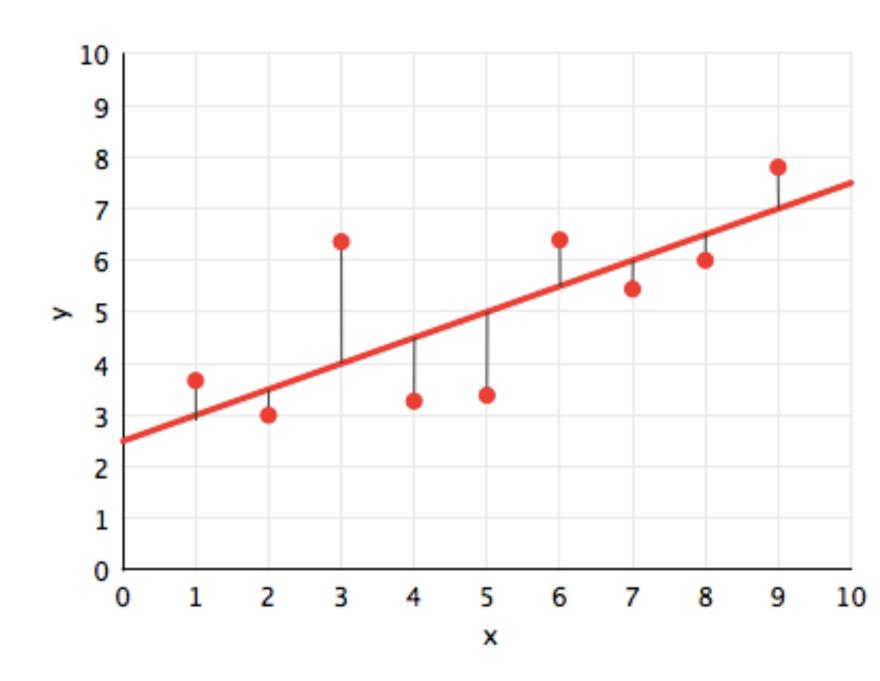
Day 1 Session 1

Linear Regression with Gradient Descent

REGRESSION

- how many dollars will you spend?
- what is your creditworthiness
- how many people will vote for Bernie t days before election
- use to predict probabilities for classification
- causal modeling in econometrics



HYPOTHESIS SPACES

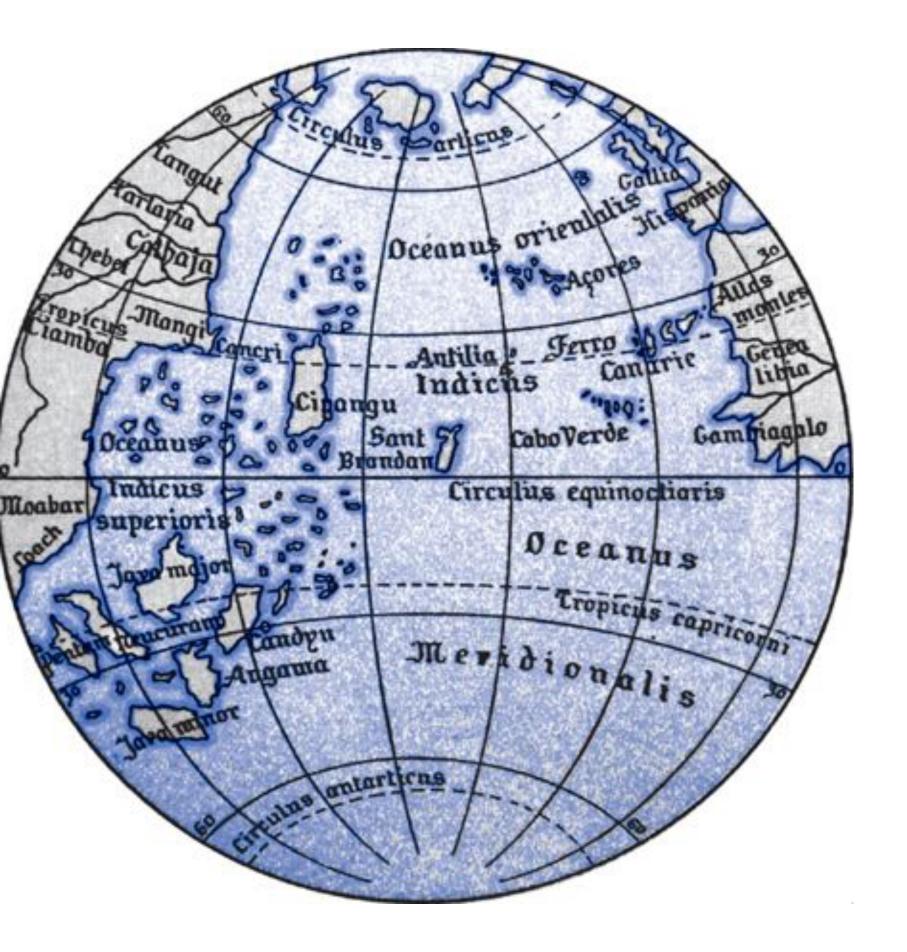
A polynomial looks so:

$$h(x)= heta_0+ heta_1x^1+ heta_2x^2+\ldots+ heta_nx^n=\sum_{i=0}^n heta_ix^i$$

All polynomials of a degree or complexity d constitute a hypothesis space.

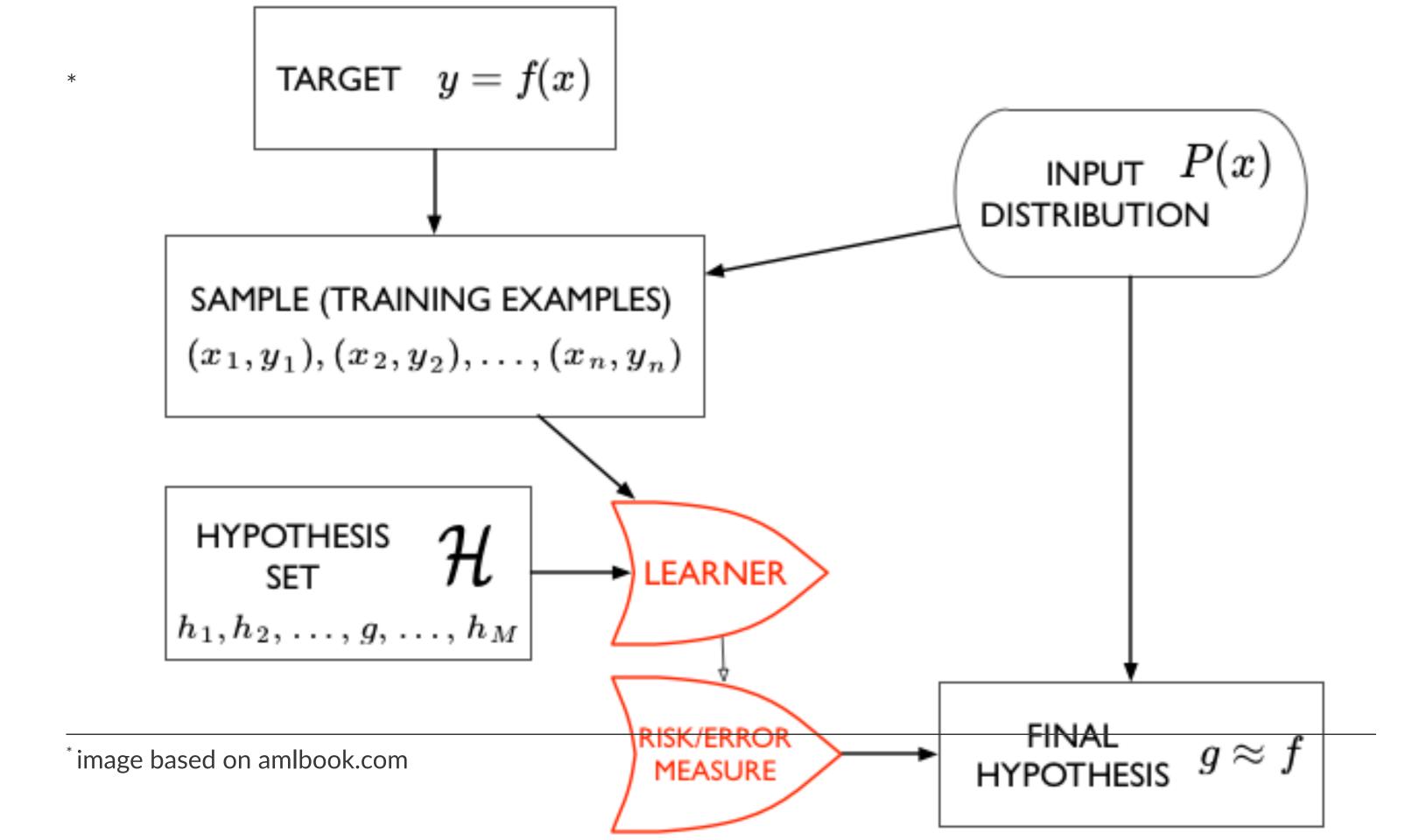
$$\mathcal{H}_{ exttt{1}}: h_{ exttt{1}}(x) = heta_{ exttt{0}} + heta_{ exttt{1}} x$$

$$\mathcal{H}_{20}: h_{20}(x) = \sum_{i=0}^{20} heta_i x^i$$



SMALL World vs BIG World

- Small World answers the question: given a model class (i.e. a Hypothesis space, whats the best model in it). It involves parameters. Its model checking.
- *BIG World* compares model spaces. Its model comparison with or without "hyperparameters".



Linear Regression

$$\hat{y} = f_{ heta}(x) = heta^T x$$

Cost Function:

$$R(heta) = rac{1}{2} \sum_{i=1}^m (f_ heta(x^{(i)} - y^{(i)})^2$$

MINIMIZE SQUARED ERROR

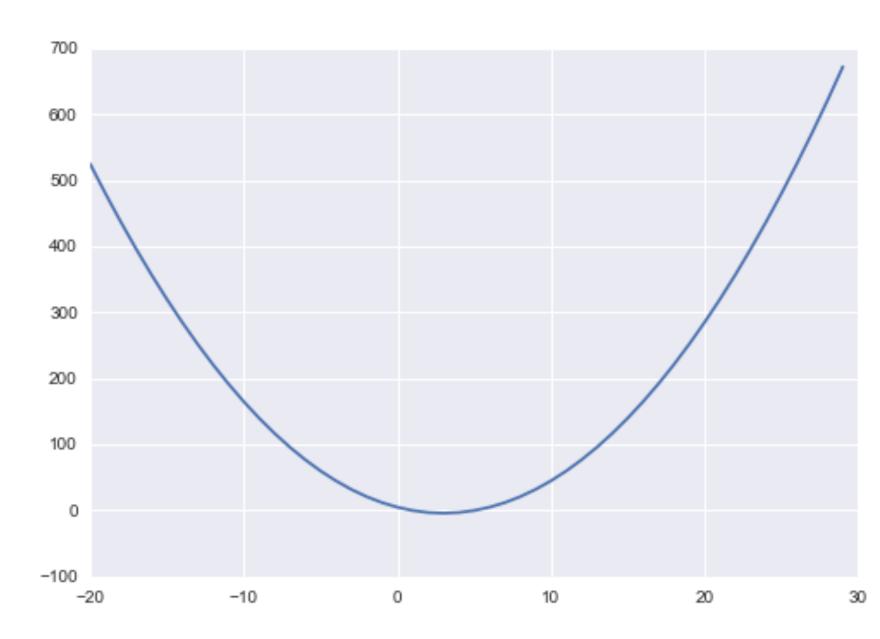
Gradient ascent (descent)

basically go opposite the direction of the derivative.

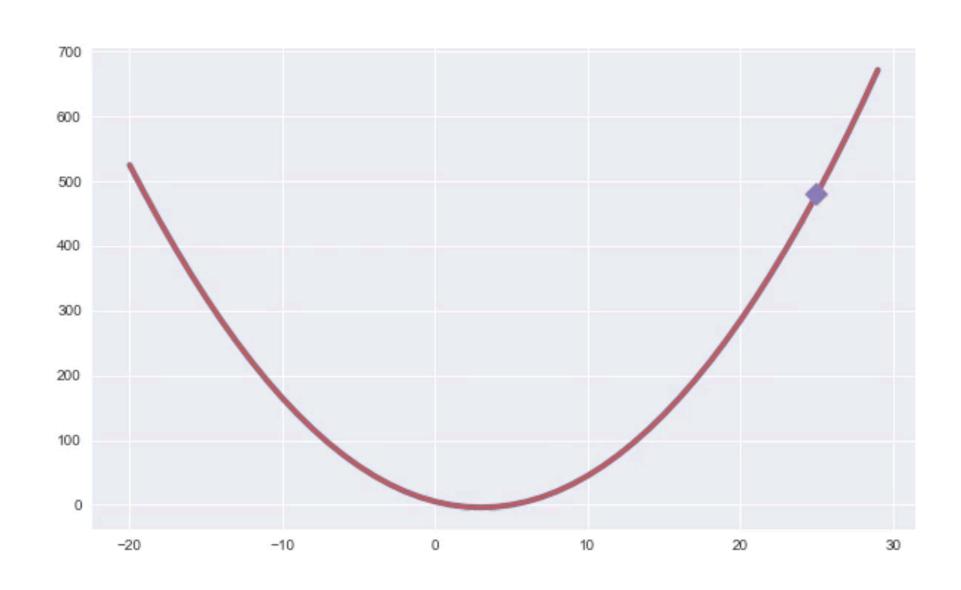
Consider the objective function:

$$J(x) = x^2 - 6x + 5$$

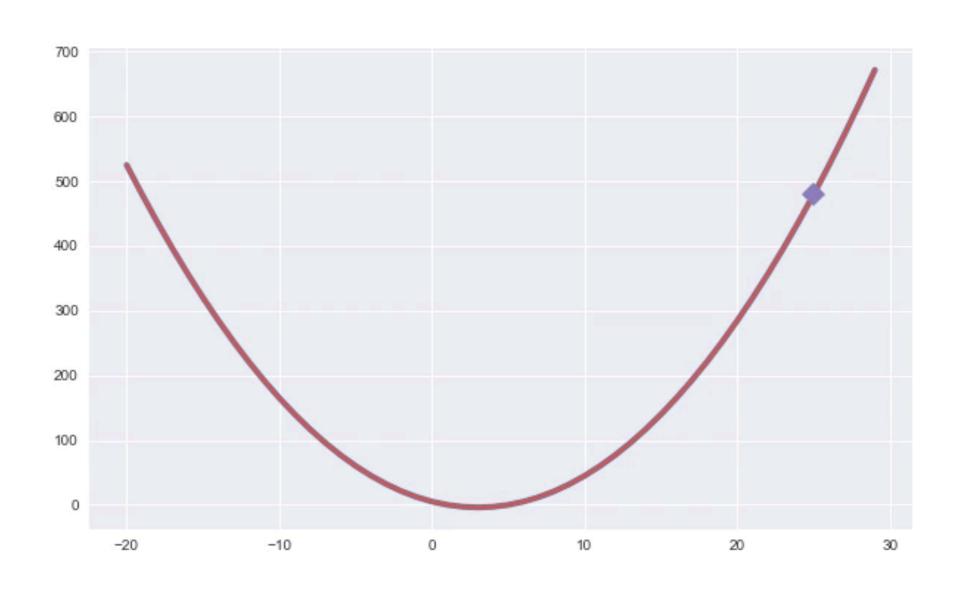
```
gradient = fprime(old_x)
move = gradient * step
current_x = old_x - move
```



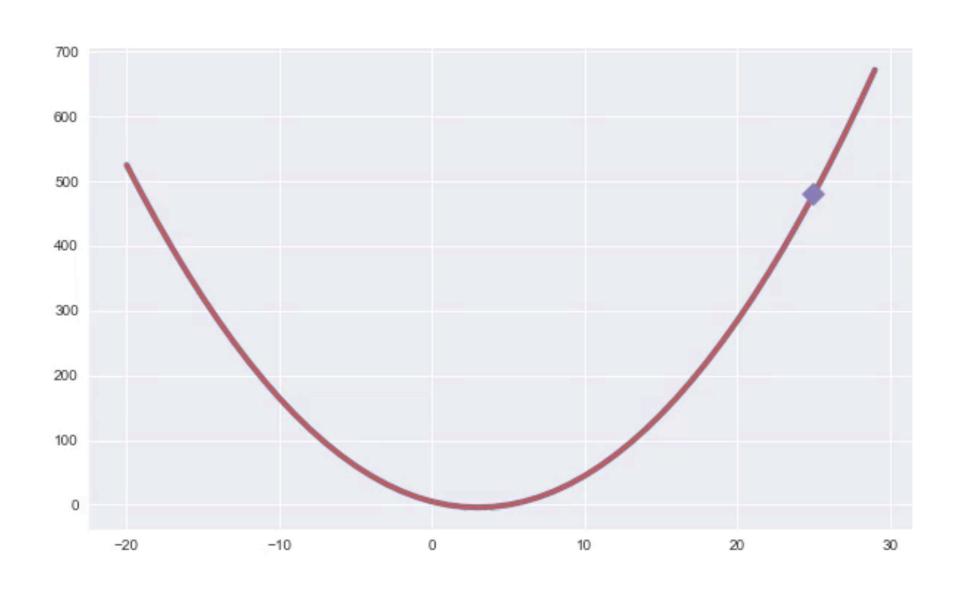
good step size



too big step size



too small step size



Gradient Descent.

We want:

$$abla_h R_{out}(h) =
abla_h \int dx p(x,y) R_{out}(h(x),y)$$

For a particular sample, use the Law of Large numbers:

$$oxed{
abla_h R_{out}(h) \sim oxed{
abla_h rac{1}{N} \sum_{i \in \mathcal{D}} R_{in}(h(\hat{x}_i), y_i)}}$$

Gradient Descent

$$heta := heta - \eta
abla_{ heta} R(heta) = heta - \eta \sum_{i=1}^m
abla R_i(heta)$$

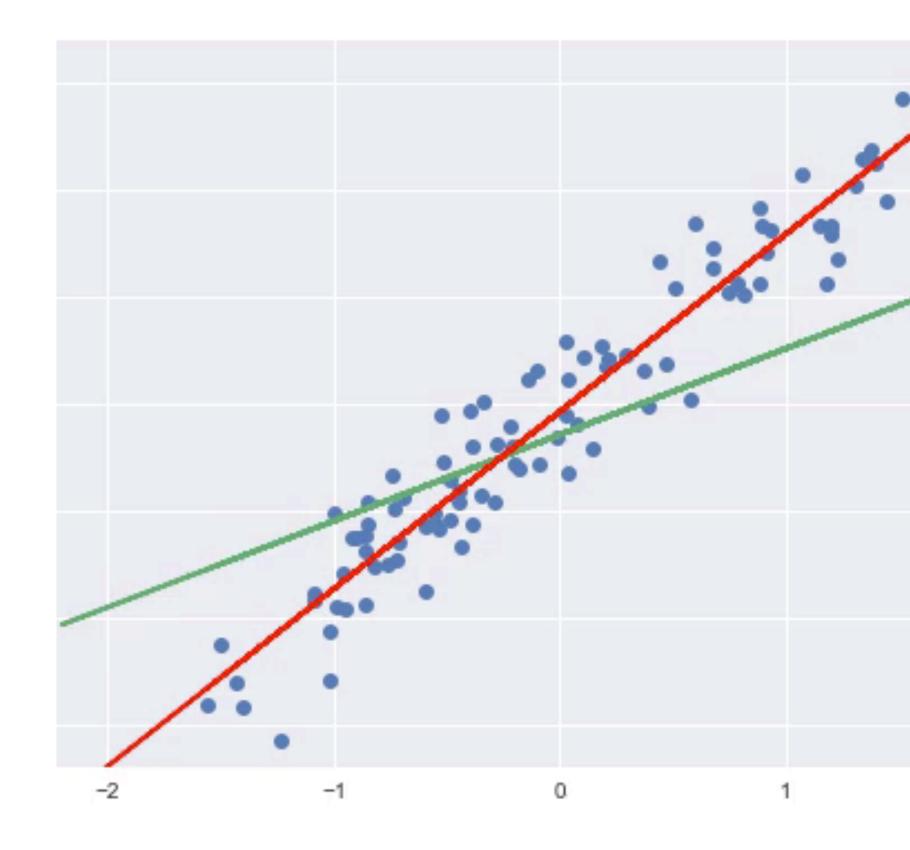
where η is the learning rate.

ENTIRE DATASET NEEDED

```
for i in range(n_epochs):
   params_grad = evaluate_gradient(loss_function, data, params)
   params = params - learning rate * params grad`
```

Linear Regression: Gradient Descent

$$heta_j := heta_j + lpha \sum_{i=1}^m (y^{(i)} - f_ heta(x^{(i)})) x_j^{(i)}$$



Stochastic Gradient Descent

$$\theta := \theta - \alpha \nabla_{\theta} R_i(\theta)$$

ONE POINT AT A TIME

For Linear Regression:

$$heta_j := heta_j + lpha(y^{(i)} - f_ heta(x^{(i)})) x_j^{(i)}$$

```
for i in range(nb_epochs):
    np.random.shuffle(data)
    for example in data:
        params_grad = evaluate_gradient(loss_function, example, params)
        params = params - learning_rate * params_grad
```

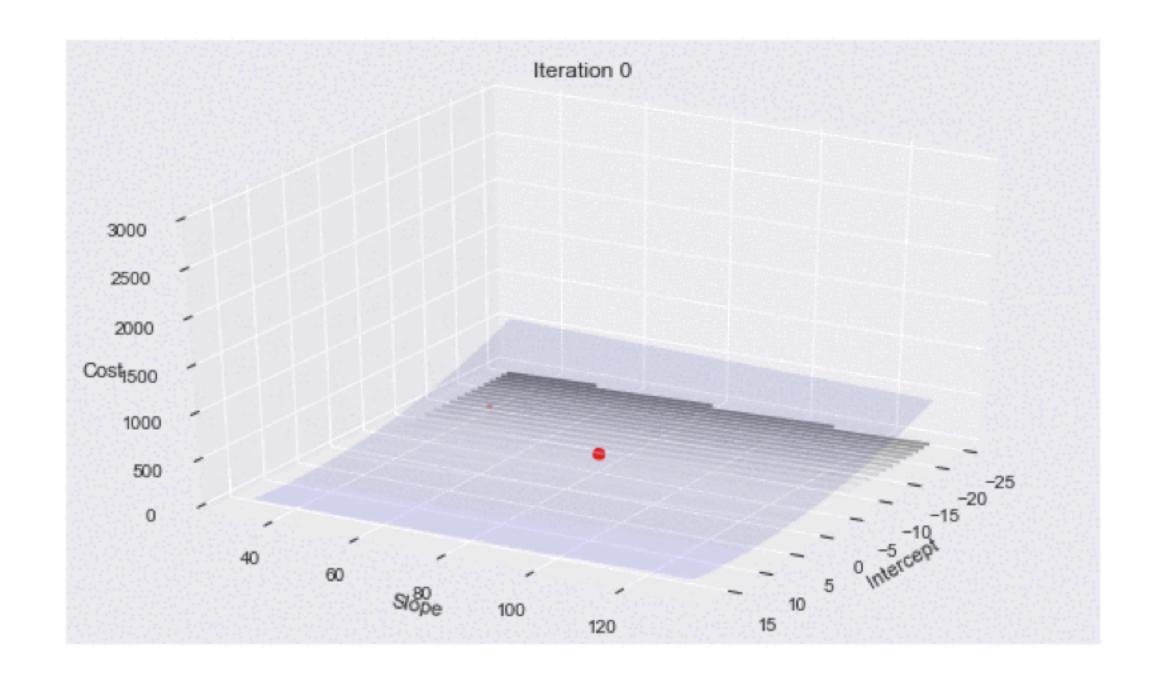
Mini-Batch SGD (the most used)

$$heta := heta - \eta
abla_{ heta} J(heta; x^{(i:i+n)}; y^{(i:i+n)})$$

```
for i in range(mb_epochs):
    np.random.shuffle(data)
    for batch in get_batches(data, batch_size=50):
        params_grad = evaluate_gradient(loss_function, batch, params)
        params = params - learning rate * params grad
```

Mini-Batch: do some at a time

- the risk surface changes at each gradient calculation
- thus things are noisy
- cumulated risk is smoother, can be used to compare to SGD
- epochs are now the number of times you revisit the full dataset
- shuffle in-between to provide even more stochasticity



Frequentist Statistics

Answers the question:

What is Data?

with

"data is a sample from an existing population"

- data is stochastic, variable
- model the sample. The model may have parameters
- find parameters for our sample. The parameters are considered **FIXED**.

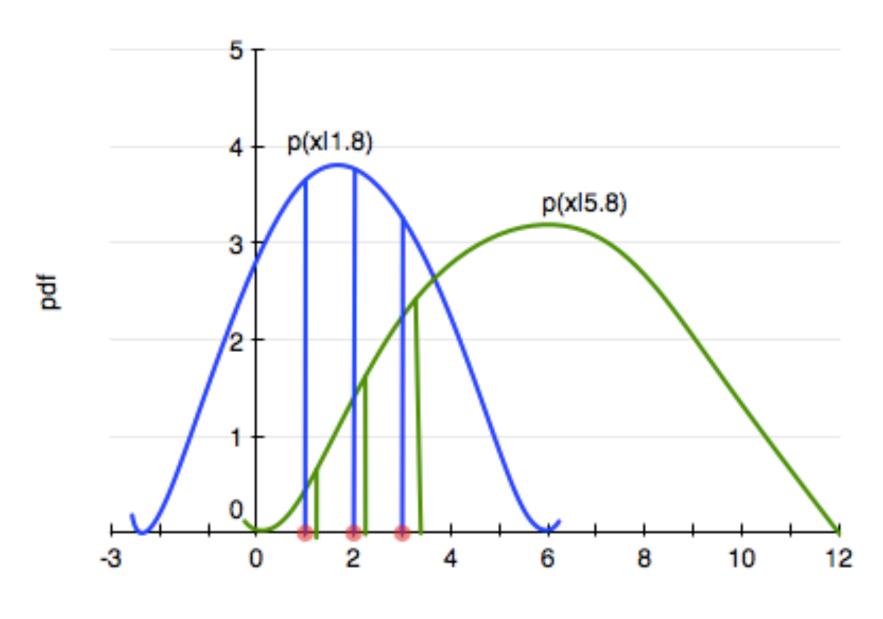
Likelihood

How likely it is to observe values x_1, \ldots, x_n given the parameters λ ?

$$L(\lambda) = \prod_{i=1}^{m} P(x_i|\lambda)$$

How likely are the observations if the model is true?

Maximum Likelihood estimation



We have data on the wing length in millimeters of a nine members of a particular species of moth. We wish to make inferences from those measurements on the population quantities μ and σ .

Y = [16.4, 17.0, 17.2, 17.4, 18.2, 18.2, 18.2, 19.9, 20.8]

Let us assume a gaussian pdf:

$$p(y|\mu,\sigma^2) = rac{1}{\sqrt{2\pi\sigma^2}}e^{-(rac{y-\mu}{2\sigma})^2}$$

Gaussian Distribution

MLE Estimators

LIKELIHOOD:
$$p(y_1,\ldots,y_n|\mu,\sigma^2) = \prod_{i=1}^n p(y_i|\mu,\sigma^2)$$

$$=\prod_{i=1}^n rac{1}{\sqrt{2\pi\sigma^2}} e^{-(rac{(y_i-\mu)^2}{2\sigma^2})} = rac{1}{\sqrt{2\pi\sigma^2}} \mathrm{exp} iggl\{ -rac{1}{2} \sum_i rac{(y_i-\mu)^2}{\sigma^2} iggr\}$$

Take partials for $\hat{\mu}_{MLE}$ and $\hat{\sigma}_{MLE}^2$

MLE for Moth Wing

$$\hat{\mu}_{MLE} = rac{1}{N} \sum_{i} y_i = ar{Y}; \; \hat{\sigma}_{MLE}^2 = rac{1}{N} \sum_{i} (Y_i - ar{Y}^2)$$

 $\hat{\sigma}_{MLE}^2$ is a biased estimator of the population variance, while $\hat{\mu}_{MLE}$ is an unbiased estimator.

That is, $E_D[\hat{\mu}_{MLE}] = \mu$, where the D subscripts means the expectation with respect to the predictive, or data-sampling, or data generating distribution.

VALUES: sigma 1.33 mu 18.14

Example Exponential Distribution Model

$$f(x;\lambda) = egin{cases} \lambda e^{-\lambda x} & x \geq 0, \ 0 & x < 0. \end{cases}$$

Describes the time between events in a homogeneous Poisson process (events occur at a constant average rate). Eg time between buses arriving.

log-likelihood

Maximize the likelihood, or more often (easier and more numerically stable), the log-likelihood

$$\ell(\lambda) = \sum_{i=1}^n ln(P(x_i \mid \lambda))$$

In the case of the exponential distribution we have:

$$\ell(lambda) = \sum_{i=1}^n ln(\lambda e^{-\lambda x_i}) = \sum_{i=1}^n \left(ln(\lambda) - \lambda x_i
ight).$$

Maximizing this:

$$rac{d\ell}{d\lambda} = rac{n}{\lambda} - \sum_{i=1}^n x_i = 0$$

and thus:

$$rac{1}{\lambda_{MLE}} = rac{1}{n} \sum_{i=1}^n x_i,$$

which is the sample mean of our sample.

True vs estimated

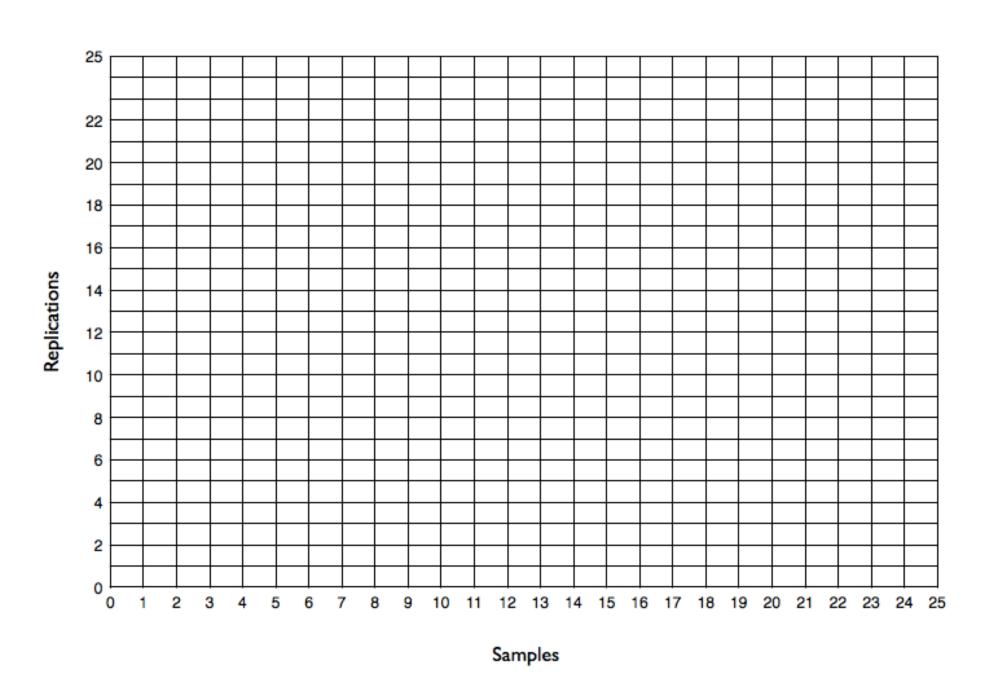
If your model describes the true generating process for the data, then there is some true μ^* .

We dont know this. The best we can do is to estimate $\hat{\mu}$.

Now, imagine that God gives you some M data sets **drawn** from the population, and you can now find μ on each such dataset.

So, we'd have M estimates.

M samples of N data points



Sampling distribution

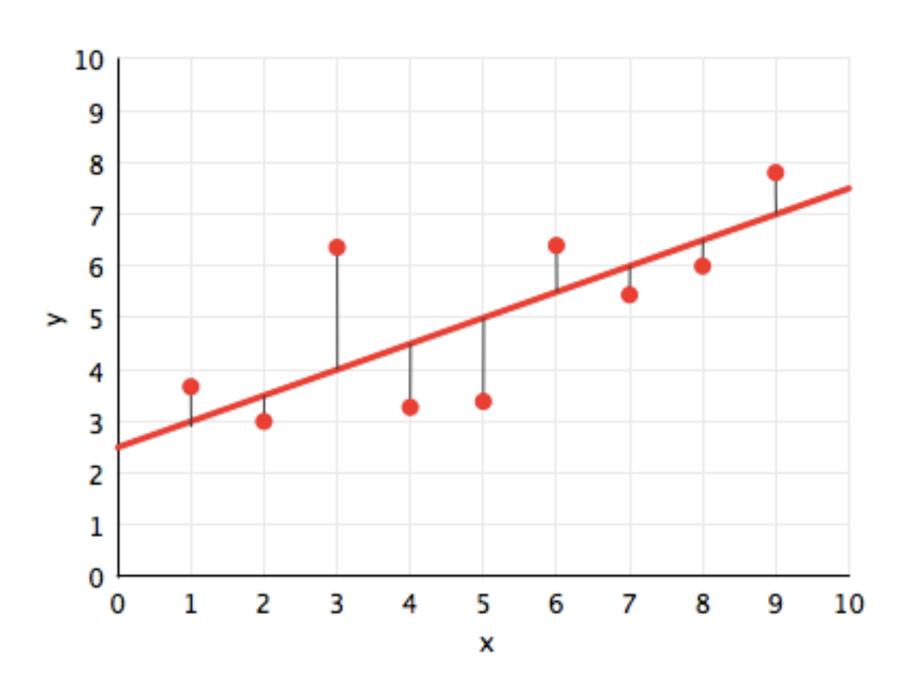
As we let $M \to \infty$, the distribution induced on $\hat{\mu}$ is the empirical sampling distribution of the estimator.

 μ could be λ , our parameter, or a mean, a variance, etc

We could use the sampling distribution to get confidence intervals on λ .

But we dont have M samples. What to do?

REGRESSION

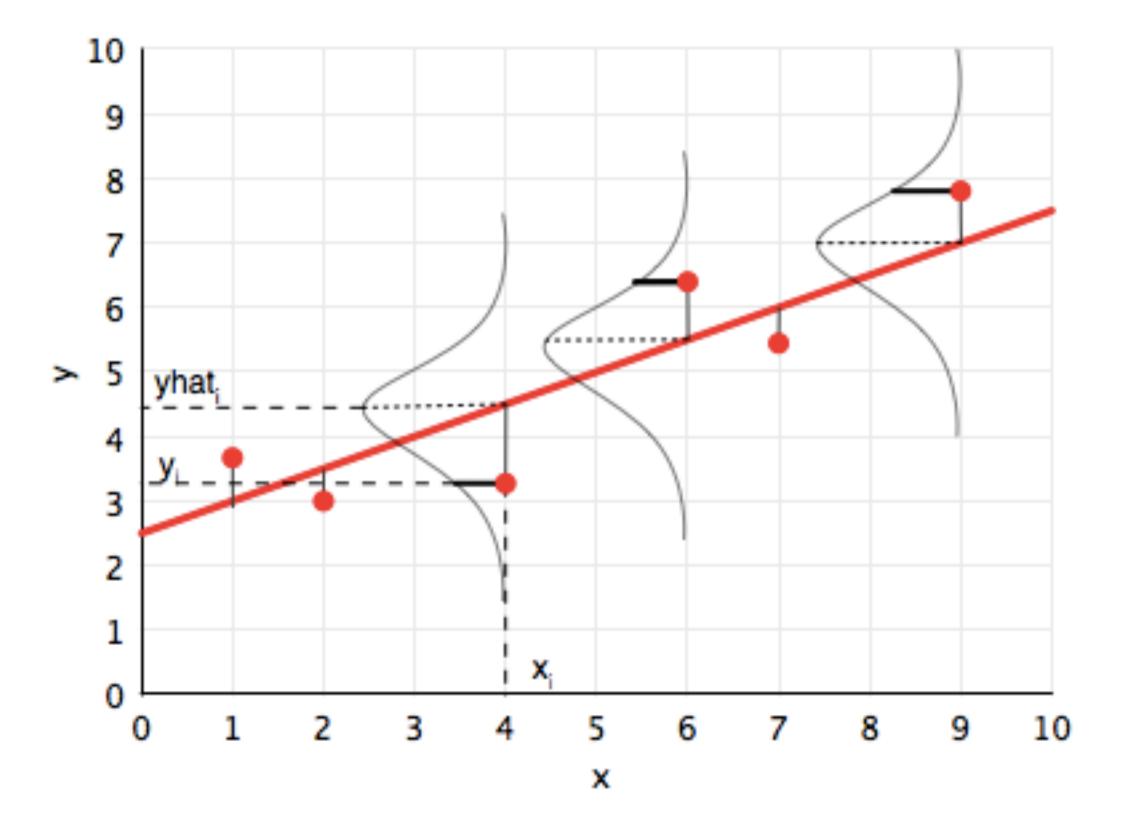


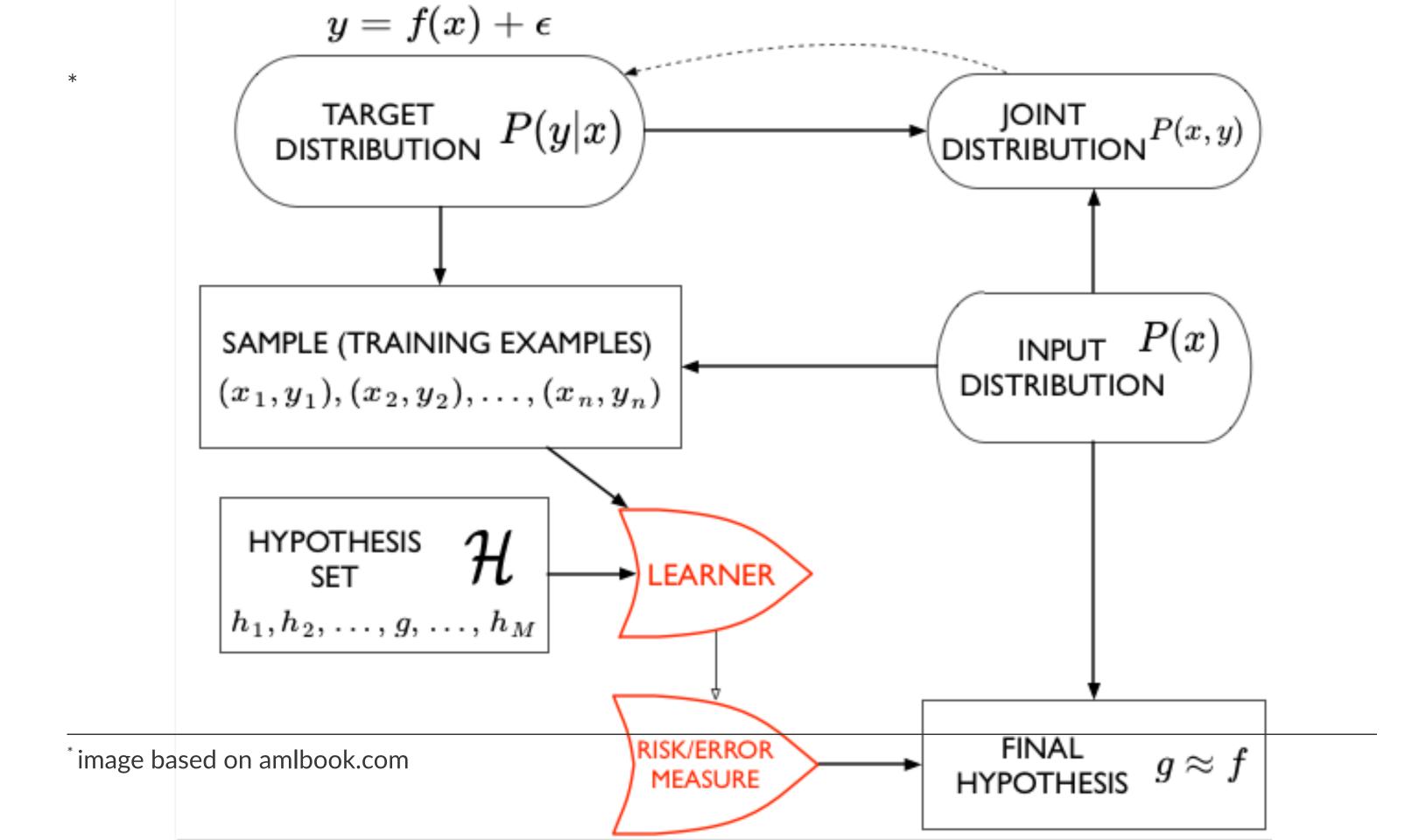
Regression Noise Sources

- lack of knowledge of the true generating process
- sampling
- measurement error
- lack of knowledge of x

No more y = f(x). Need $y = f(x) + \epsilon$.

or a $P(y \mid x)$





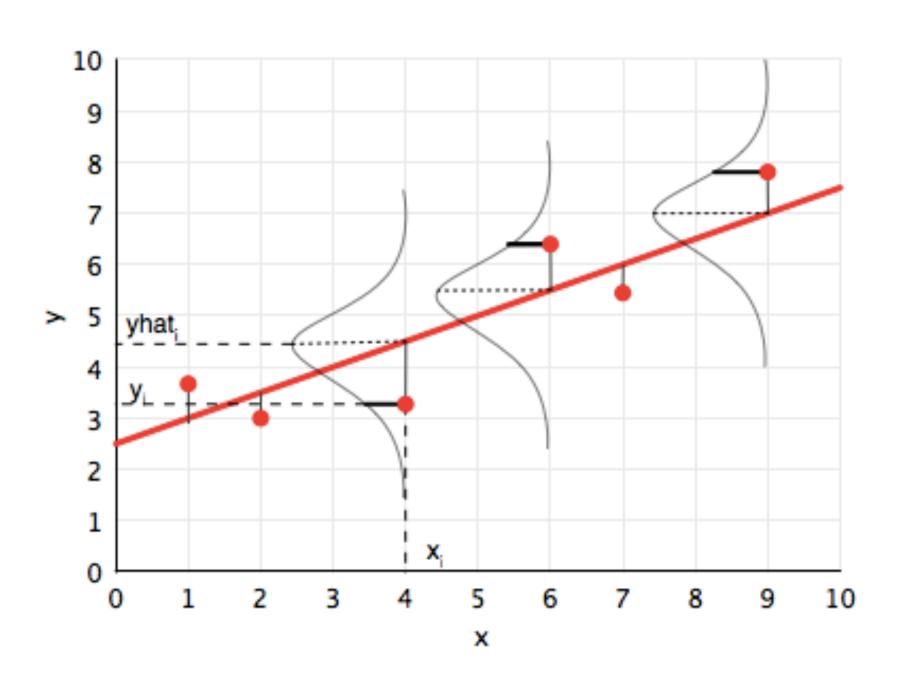
Gaussian Distribution assumption

Each y_i is gaussian distributed with mean $\mathbf{w} \cdot \mathbf{x}_i$ (the y predicted by the regression line) and variance σ^2 :

$$y_i \sim N(\mathbf{w} \cdot \mathbf{x}_i, \sigma^2).$$

$$N(\mu,\sigma^2) = rac{1}{\sigma\sqrt{2\pi}}e^{-(y-\mu)^2/2\sigma^2},$$

Linear Regression MLE



We can then write the likelihood:

$$\mathcal{L} = p(\mathbf{y}|\mathbf{x},\mathbf{w},\sigma) = \prod_i p(\mathbf{y}_i|\mathbf{x}_i,\mathbf{w},\sigma)$$

$$\mathcal{L} = (2\pi\sigma^2)^{(-n/2)}e^{\frac{-1}{2\sigma^2}\sum_i(y_i-\mathbf{w}\cdot\mathbf{x}_i)^2}$$
.

The log likelihood ℓ then is given by:

$$\ell = rac{-n}{2}log(2\pi\sigma^2) - rac{1}{2\sigma^2}\sum_i (y_i - \mathbf{w}\cdot\mathbf{x}_i)^2.$$

Maximizing gives:

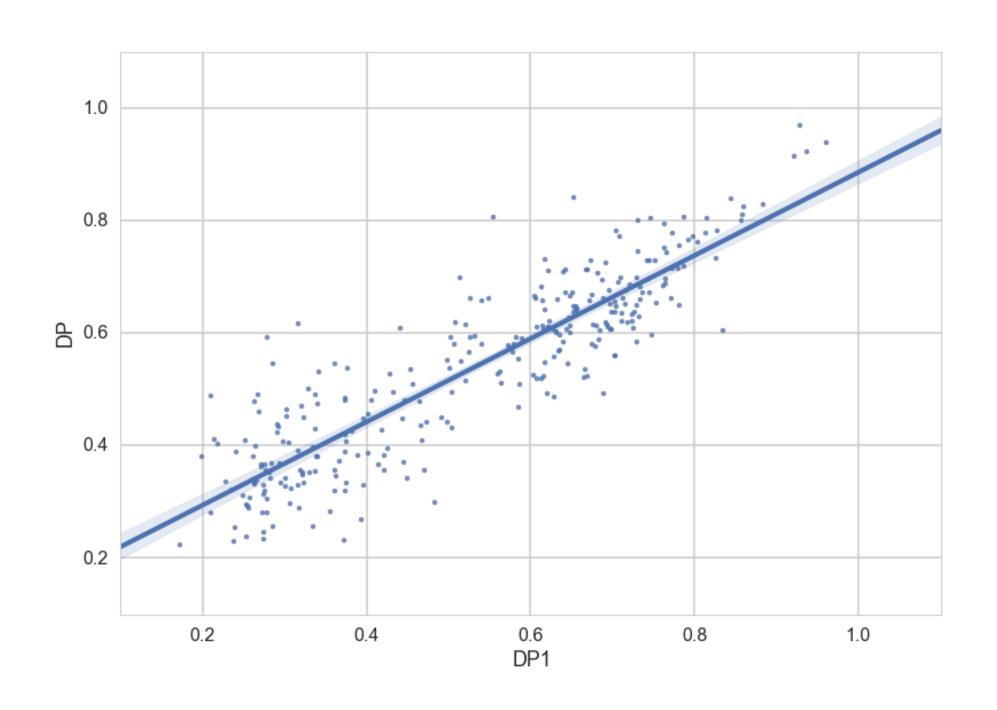
$$\mathbf{w}_{MLE} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y},$$

where we stack rows to get:

$$\mathbf{X} = stack(\{\mathbf{x}_i\})$$

$$\sigma_{MLE}^2 = rac{1}{n} \sum_i (y_i - \mathbf{w} \cdot \mathbf{x}_i)^2.$$

Example: House Elections



From Likelihood to Predictive Distribution

- the band on the previous graph is the sampling distribution of the regression line, or a representation of the sampling distribution of the w.
- $p(y|\mathbf{x}, \mu_{MLE}, \sigma^2_{MLE})$ is a probability distribution
- thought of as $p(y^*|\mathbf{x}^*, {\mathbf{x}_i, y_i}, \mu_{MLE}, \sigma_{MLE}^2)$, it is a predictive distribution for as yet unseen data y^* at \mathbf{x}^* , or the sampling distribution for data, or the data-generating distribution, at the new covariates \mathbf{x}^* . This is a wider band.

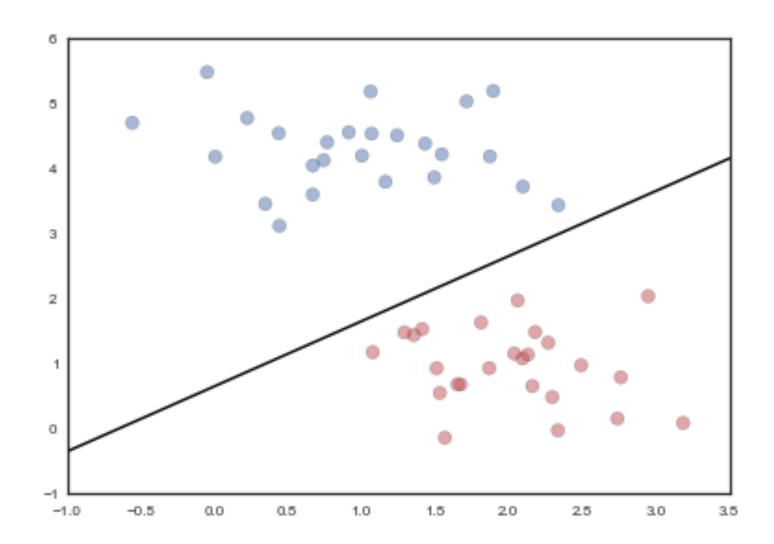
| Dep. Variable: | DP | R-squared: | 0.806 |
|-------------------|------------------|---------------------|-----------|
| Model: | OLS | Adj. R-squared: | 0.804 |
| Method: | Least Squares | F-statistic: | 612.0 |
| Date: | Tue, 13 Oct 2015 | Prob (F-statistic): | 1.04e-105 |
| Time: | 16:33:01 | Log-Likelihood: | 368.81 |
| No. Observations: | 298 | AIC: | -731.6 |
| Df Residuals: | 295 | BIC: | -720.5 |
| Df Model: | 2 | | |
| Covariance Type: | nonrobust | | |

| | coef | std err | t | P> t | [95.0% Conf. Int.] |
|-----------|--------|---------|--------|-------|--------------------|
| Intercept | 0.2326 | 0.020 | 11.503 | 0.000 | 0.193 0.272 |
| DP1 | 0.5622 | 0.040 | 14.220 | 0.000 | 0.484 0.640 |
| I | 0.0429 | 0.008 | 5.333 | 0.000 | 0.027 0.059 |

| Omnibus: | 7.465 | Durbin-Watson: | 1.728 |
|----------------|-------|-------------------|--------|
| Prob(Omnibus): | 0.024 | Jarque-Bera (JB): | 7.316 |
| Skew: | 0.374 | Prob(JB): | 0.0258 |
| Kurtosis: | 3.174 | Cond. No. | 13.1 |

Dem_Perc(t) ~ Dem_Perc(t-2) + I

- done in statsmodels
- From Gelman and Hwang

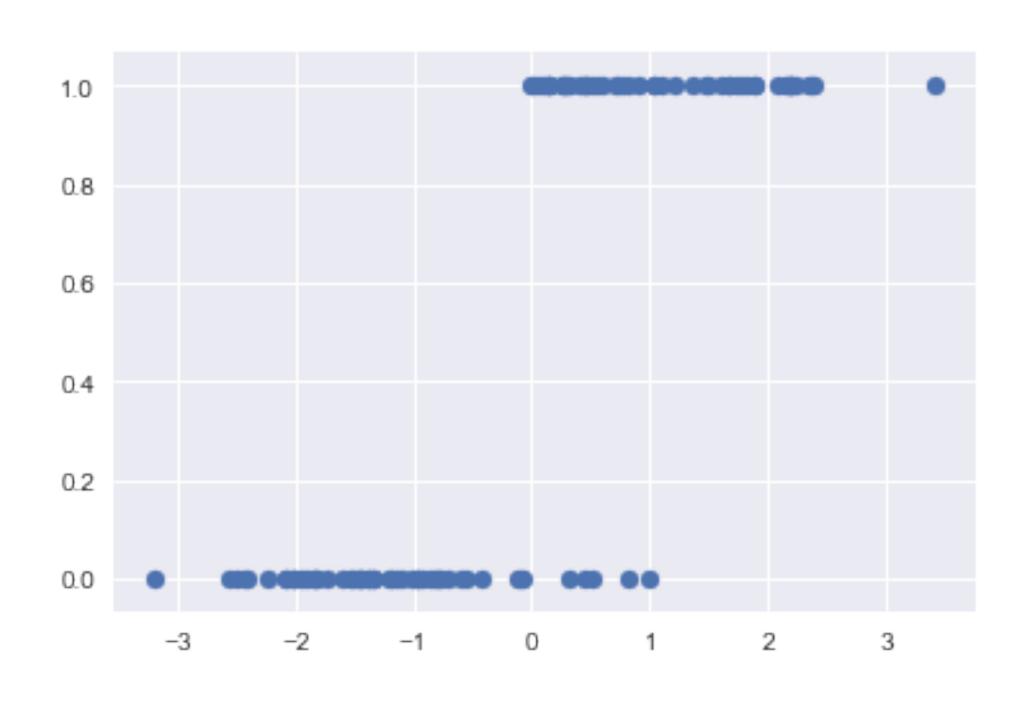


CLASSIFICATION

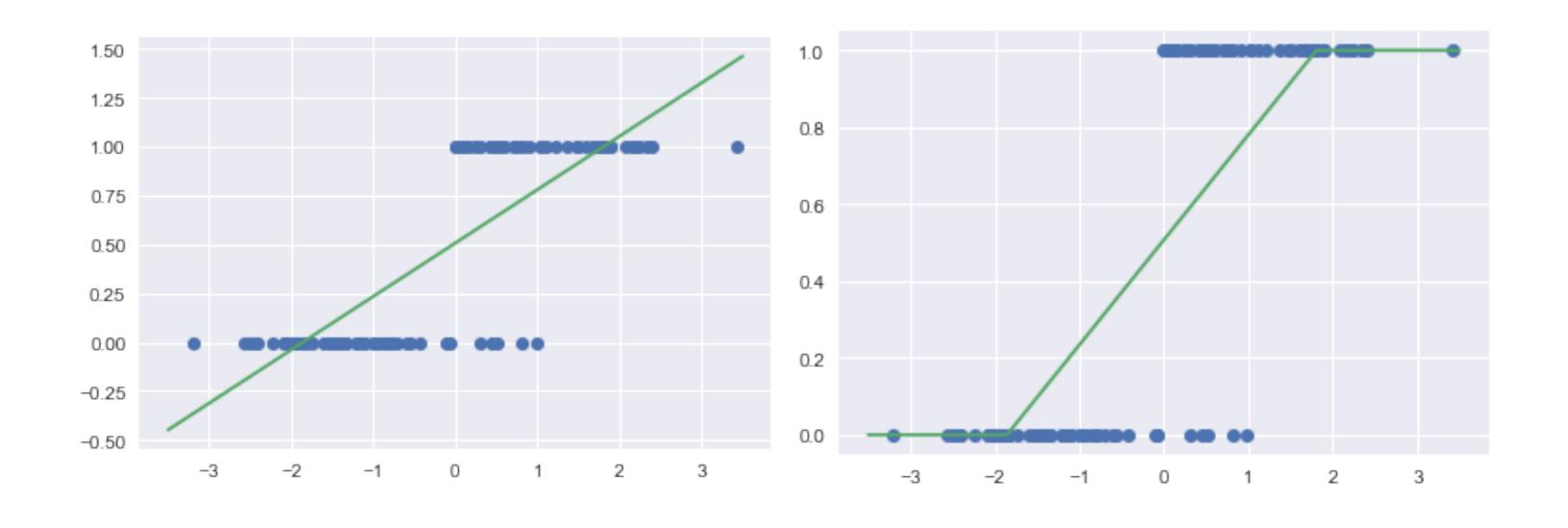
- will a customer churn?
- is this a check? For how much?
- a man or a woman?
- will this customer buy?
- do you have cancer?
- is this spam?
- whose picture is this?
- what is this text about?^j

image from code in http://bit.ly/1Azg29G

1-D classification problem



1-D Using Linear regression



MLE for Logistic Regression

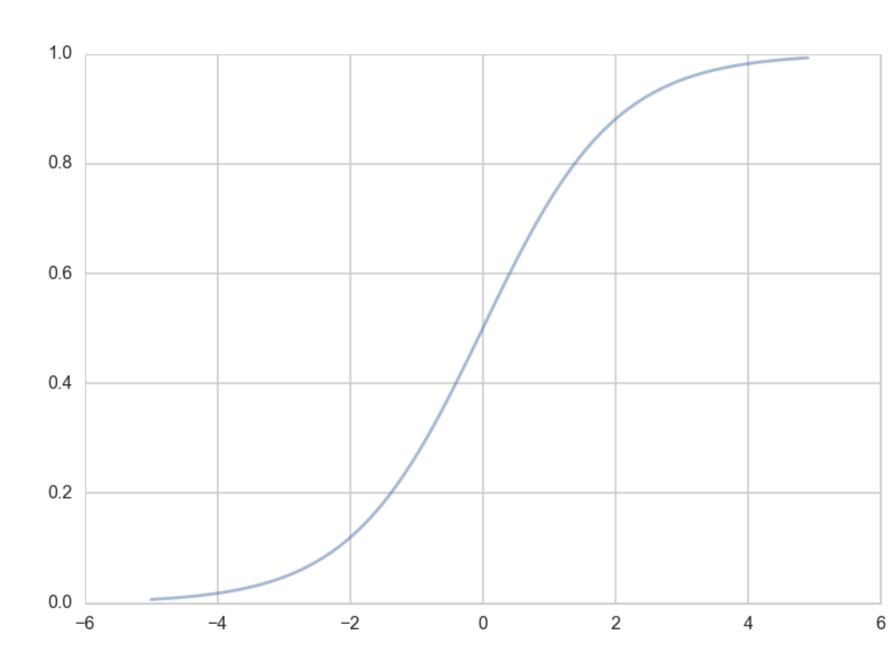
- example of a Generalized Linear Model (GLM)
- "Squeeze" linear regression through a **Sigmoid** function
- this bounds the output to be a probability
- What is the sampling Distribution?

Sigmoid function

This function is plotted below:

```
h = lambda z: 1./(1+np.exp(-z))
zs=np.arange(-5,5,0.1)
plt.plot(zs, h(zs), alpha=0.5);
```

Identify: $z = \mathbf{w} \cdot \mathbf{x}$ and $h(\mathbf{w} \cdot \mathbf{x})$ with the probability that the sample is a '1' (y = 1).



Then, the conditional probabilities of y=1 or y=0 given a particular sample's features \mathbf{x} are:

$$P(y = 1|\mathbf{x}) = h(\mathbf{w} \cdot \mathbf{x})$$

 $P(y = 0|\mathbf{x}) = 1 - h(\mathbf{w} \cdot \mathbf{x}).$

These two can be written together as

$$P(y|\mathbf{x},\mathbf{w}) = h(\mathbf{w}\cdot\mathbf{x})^y(1-h(\mathbf{w}\cdot\mathbf{x}))^{(1-y)}$$

BERNOULLI!!

Bernoulli Distribution

Multiplying over the samples we get:

$$P(y|\mathbf{x},\mathbf{w}) = P(\{y_i\}|\{\mathbf{x}_i\},\mathbf{w}) = \prod_{y_i \in \mathcal{D}} P(y_i|\mathbf{x}_i,\mathbf{w}) = \prod_{y_i \in \mathcal{D}} h(\mathbf{w} \cdot \mathbf{x}_i)^{y_i} (1 - h(\mathbf{w} \cdot \mathbf{x}_i))^{(1-y_i)}$$

A noisy y is to imagine that our data \mathcal{D} was generated from a joint probability distribution P(x,y). Thus we need to model y at a given x, written as $P(y \mid x)$, and since P(x) is also a probability distribution, we have:

$$P(x,y) = P(y \mid x)P(x),$$

Indeed its important to realize that a particular sample can be thought of as a draw from some "true" probability distribution.

maximum likelihood estimation maximises the likelihood of the sample y,

$$\mathcal{L} = P(y \mid \mathbf{x}, \mathbf{w}).$$

Again, we can equivalently maximize

$$\ell = log(P(y \mid \mathbf{x}, \mathbf{w}))$$

Thus

$$egin{aligned} \ell &= log \left(\prod_{y_i \in \mathcal{D}} h(\mathbf{w} \cdot \mathbf{x}_i)^{y_i} (1 - h(\mathbf{w} \cdot \mathbf{x}_i))^{(1 - y_i)}
ight) \ &= \sum_{y_i \in \mathcal{D}} log \left(h(\mathbf{w} \cdot \mathbf{x}_i)^{y_i} (1 - h(\mathbf{w} \cdot \mathbf{x}_i))^{(1 - y_i)}
ight) \ &= \sum_{y_i \in \mathcal{D}} log h(\mathbf{w} \cdot \mathbf{x}_i)^{y_i} + log \left(1 - h(\mathbf{w} \cdot \mathbf{x}_i)
ight)^{(1 - y_i)} \ &= \sum_{y_i \in \mathcal{D}} \left(y_i log (h(\mathbf{w} \cdot \mathbf{x})) + (1 - y_i) log (1 - h(\mathbf{w} \cdot \mathbf{x}))
ight) \end{aligned}$$

Use Convex optimization!

1-D Using Logistic regression

