

→ Random Process

- It is also known as stochastic process.
- Consider a random experiment with sample space, S , if a time function $X(t, s)$ is assigned to each outcome $s \in S$ and where $t \in T$, then the family of all such functions denoted $X(t, s)$ is called Random process,

$$X(t), t \in [0, \infty]$$

- ↙ • For a fixed $t = z$ or $t \in Z$ where Z is any moment,

$$X(t, s) = \underbrace{X(z, s)}$$

random variable

As s varies over the sample space S

- ↙ • On the other hand for fixed $s = s_0$ is a single function of time t , called as 'sample function' OR '~~ensemble member~~' OR 'realisation of the random process'

- ↙ • If both t and s are fixed, then $X(t, s)$ is a real number.

M	T	W	T	F	S
Page No.:					
Date:					

→ Classification of Random Process.

- Let E be the state space of the random process.
- Let T be the index set or parameter set dependent on time.

- If the index set T is discrete then the process is called discrete parameter or discrete time process. It is also called a random sequence and denoted by,

$$\{x_n : n = 1, 2, 3, \dots\}$$

- If T and E are both discrete, the random process is called as discrete random process or discrete random sequence.

eg 1 → If x_n represents the number of heads obtained in the n^{th} toss of two 2 fair coins then,

$$\begin{aligned} &\rightarrow x_n, n \geq 1 \text{ is a discrete random process} \\ &\rightarrow E = \{0, 1, 2\} \\ &\rightarrow T = \{1^{\text{st}}, 2^{\text{nd}}, 3^{\text{rd}}, \dots, n^{\text{th}}, \dots\} \end{aligned}$$

eg 2 → If x_n represents the temperature at the end of the n^{th} hour of a day, then the state

$\rightarrow x_n = \{1, 2, \dots, 12^{\text{th}}\}$ can take any value in an interval is continuous

2b.

random process
event dependent

→ Continuous Random Process

- If T is discrete and E is continuous then random process is called continuous random sequence

The process
a time process
and denoted by
}

discrete
process

obtained in

our process

nth ... }

the end of the

we take any
continuous

eg 3 → Let $N(t)$ be the number of customers who have visited the bank from $t = 9$ until t , the random variable $N(t)$ is a discrete random variable thus $N(t)$ is a discrete valued random process however since t can take any value between 9 to 16, $N(t)$ is a continuous time random process.



• A continuous time random process is a random process where J is an interval on the real line such as $[-1, 1]$, $[0, \infty)$, $(-\infty, \infty)$ where $\{X(t) : t \in J\}$



• A discrete time random process is a random process X_n where J is a countable set such as \mathbb{N} or \mathbb{Z}

→ Deterministic and Non-Deterministic Random Process

- A random process is called a deterministic random process if future values of any sample function can be predicted exactly from past observations or past value.

eg → $x_c(t) = (\cos \omega t) A$

$$\rightarrow x_{c1} = A \cos \omega_1 t$$

$$\rightarrow x_{c2} = A \cos \omega_2 t$$

- Otherwise called as non-deterministic.

eg → share market, exchange rates, etc.

→ Description of Random Process

- Consider a random process $X(t) : t \in T$ for a fixed t_1 , $X(t_1) = x_1$ is a random variable and it's cumulative distribution function (CDF denoted by $F_x(x_1, t_1)$) and defined as

$$F_x$$

$$F_x(x_1, t_1) = P(X(t_1) \leq x_1)$$

and called as first order distribution of random process $X(t)$.

• For given

$$F_x$$

is called process

eg → comp You ha intere

$$X_1 \in$$

$$X_2 =$$

There you p change abun where

$$U(a$$

$$E(x$$

$$V(x$$

- a) Find
b) Find

- For given t_1 and t_2 if your $x(t_1) = x_1$ and $x(t_2) = x_2$
 $F_x(x_1, t_1)$

$F_x(x_1, t_1, t_2) = P(x(t_1) \leq x_1, x(t_2) \leq x_2)$
 is called second order distribution of random process $x(t)$

\rightarrow compound interest

You have \$1000 to put in an account with interest rate R compounded annually i.e. if X_R is the value of the account at year n , then $X_R = 1000(1+R)^n$ for $n = 0, 1, 2, \dots$

Then the value of R is a random variable when you put the money in the bank but it does not change after a while. Then in particular assume that R follows uniform distribution where limits are $R \sim U(0.04, 0.05)$

$$U(a, b) \quad f(x) = \begin{cases} \frac{1}{b-a}, & a \leq x \leq b \\ 0, & \text{otherwise} \end{cases}$$

$$\begin{aligned} E(x) &= \text{mean} \\ &= \frac{a+b}{2} \end{aligned}$$

$$V(x) = \frac{(b-a)^2}{12}$$

- Find all possible sample functions for the random process $\{X_{R^n}\}_{n=0,1,2,3,\dots}$
- Find the expected value of your account at

year 3 i.e. $E[x_3]$.

$E[x_3]$

ANS → here the randomness is if x_n comes from the random variable R as soon as we know R , the entire sequence will be known i.e. $x_{n>N} = 0, 1, 2, 3$

In particular if $R = r$, then this

$$x_n = 1000(1+r)^n, n=0, 1, 2, \dots$$

Thus here sample functions are of the form

$$f(n) = 1000(1+r)^n, n=0, 1, 2, 3, \dots$$

where $r \in [0.04, 0.05]$ for an

we obtain a sample function for the random x_r .

$$\rightarrow x_r = 1000(1+R)^r, r=0, 1, 2, \dots$$

$$x_3 = 1000(1+R)^3$$

$$\text{put } Y = 1+R$$

here $R \sim U[0.04, 0.05]$

$$\therefore 1+R \sim U[1.04, 1.05]$$

$$F_Y(y) = \begin{cases} \frac{1}{1.05 - 1.04} = \frac{1}{0.01} = 100 & 1.04 < y < 1.05 \\ 0 & \text{otherwise} \end{cases}$$

$$E(X_3) = E[1000(1+R^3)]$$

$$= E[1000y^3]$$

$$= 1000 E[y^3]$$

$$= 1000 \int_{1.04}^{1.05} 100y^3 dy$$

$$= 1000 \times 100 \left[\frac{y^4}{4} \right]_{1.04}^{1.05}$$

$$= 1000 \times 100 [y^4]_{1.04}^{1.05}$$

$$= 1141.19225 \approx 1141.2$$

influenced by $E(x_0) + 0.05x_0$

about $E(x_0) + 0.05x_0 + 0.05^2 x_0 = 1.05x_0$

addition of base loss to premium

$0.05x_0$

$(1.05, 0.05)$ $\rightarrow (1.1, 0.05)$

cruise

number of entries given below in bold

total $x = 4$ & addition of base premium

$\times 0.999$

total $x = 5$ & addition of base premium

→ Discrete and Continuous Random Process

- If the state space E of a random process is discrete, then the random process is called as a discrete random process also called as "chain". In this the state space E is assumed to be $\{0, 1, 2, 3\}$.

eg → If $x(t)$ represent the number of SMS received in a cell in the interval $(0, t)$, then $\{x(t)\}$ is a discrete random process.

- If the state space E of a random process is continuous, then the random process is called as a continuous random process OR continuous state space.

eg → If $x(t)$ is the minimum temperature recorded in a city in a interval $(0, t)$ then $\{x(t)\}$ is a continuous random process.

Q2 Let $\{x(t), t \in [0, \infty]\}$ be defined as

$x(t) = A + Bt, \forall t \in [0, \infty]$ where A and B are independent normal random variables.

$$N(1, 1) \rightarrow N(\mu, \sigma^2) \text{ or } N(\mu_2, \sigma^2)$$

- Find all possible sample functions for this random process
- Define the random variable $y = x(1)$ find the PDF of y
- Also find Let also $z = x(2)$, find $E[yz]$

a) ANS → Here we get from the variable x can take the values

In particular then we get x

b) If random variable $f(x) =$

Given μ , mean σ^2 , variance

$y = x + \epsilon$
∴ $y =$

here x and y also

a)

ANS → Here we note that the randomness in $\{x(t)\}$ comes from the two random variables A and B. The random variable A can take any real value $A \in \mathbb{R}$ and also B can take any real value $B \in \mathbb{R}$. As soon as we know the values of A and B the entire process $\{x(t)\}$ is known.

In particular if $A = a$ and $B = b$ where $a, b \in \mathbb{R}$ then we obtain a sample function for $\{x(t)\}$

$$x(t) = a + bt, \forall t \in [0, \infty)$$

b) If normal distribution is given $N(\mu, \sigma^2)$, then

$$f(x) = \frac{1}{\sqrt{2\pi}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

Given

$$A, B \sim N(1, 1)$$

∴ mean = 1

variance = 1

$$Y = x(1)$$

$$\therefore Y = x(1) = A + B(1)$$

$$= A + B$$

here $x(t)$ follows normal distribution, therefore Y also follows normal distribution

$$A + B \sim N(\mu, \sigma^2)$$

~~$$\therefore Y = x(1) = A + B$$~~

$$\text{i.e. } Y = A + B$$

$$\therefore Y \sim N(\mu, \sigma^2)$$

$$\begin{aligned}
 \text{mean} &= E[Y] = E[A+B] \\
 &= E[A] + E[B] \\
 &= 1 + 1 \\
 &= 2
 \end{aligned}$$

$$\therefore E[Y] = 2$$

$$\begin{aligned}
 \text{var}(Y) &= \text{var}(A+B) \\
 &= \text{var}(A) + \text{var}(B) \\
 &= 1 + 1 \\
 &= 2
 \end{aligned}$$

$$\text{var}(Y) = 2$$

This means $Y = x(1) = A+B \sim N(2, 2)$

$$f_Y(y) = \frac{1}{6\sqrt{2\pi}} e^{-\frac{(y-2)^2}{2\sigma^2}}$$

$$= \frac{1}{(\sqrt{2})\sqrt{2\pi}} e^{\frac{(y-2)^2}{4}}$$

$$= \frac{1}{2\sqrt{\pi}} e^{\frac{(y-2)^2}{4}}$$

c) $Z = x(2)$
 $Z = A + B(2)$
 $Z = A + 2B$

$$\begin{aligned}
 E[YZ] &= E[x(1)x(2)] \\
 &= E[(A+B)(A+2B)] \\
 &= E[A^2 + 3AB + 2B^2]
 \end{aligned}$$

$$= E[A^2] + 3E[A]E[B] + 2E[B^2]$$

$$[A=1, 3, 4, 6, 7, 9] \\ [B=1, 2, 3, 4, 5, 6]$$

$$\therefore \text{var}(A) = E[A^2] - \{E[A]\}^2$$

$$I = E[A^2] - I$$

$$E[A^2] = 2$$

Similarly

$$\text{var}(B) = E[B^2] - \{E[B]\}^2$$

$$E[B^2] = 2$$

~~$E[A^2]$~~

$$E[YZ] = 2 + 3(2) + 2(2)$$

$$= 2 + 3 + 4$$

~~$= 12$~~

$$= 9$$

$$(2 \times 3)$$

base $(+, \times)$ is $\{+, \times\}$, it also contains $\{+, \times\}$ and $\{+, \times\}$

so total answer will be $\{+, \times\}$ so base $\{+, \times\}$

as required so result is correct

$$[(+, \times), (+, \times)] = \{+, \times\}$$

$$[Y \times] = 2 \leftarrow$$

total answer is $\{+, \times\}$ so base $\{+, \times\}$

so required answer is $\{+, \times\}$ so required answer is $\{+, \times\}$

~~$$\text{mean} = E[y] = E[A+B]$$

$$= E[A] + E[B]$$

$$= 1 + 1$$

$$= 2$$~~

→ Mean, Autocorrelation and Auto-covariance

- For a fixed value of t , $x(t)$ is a random variable thus mean of $x(t)$ denoted by

$$\mu_x(t) = E[x(t)]$$

$$= \sum x_p(t)$$

for discrete $E(x) = \sum x_p(x)$

Here $\mu(t)$ is a function of time and it is often called as 'ensemble mean' or 'ensemble average of $x(t)$ '

- For two time intervals t_1 and t_2 , $x(t_1)$ and $x(t_2)$ are random variables. The correlation between them is defined as

$$R_{xx}(t_1, t_2) = E[x(t_1) \cdot x(t_2)]$$

$$\Rightarrow g = E[xy]$$

and called as autocorrelation or correlation of the process $\{x(t)\}$.

Autocorrelation serves as a measure of dependence among the random variables of $x(t)$

- The autocovariance or covariance of the process $x(t)$ is defined as

$$C_{xx}(t_1, t_2) = E[(x(t_1) - \mu_x(t_1))(x(t_2) - \mu_x(t_2))]$$

$$\begin{aligned} \therefore C_{xx}(t_1, t_2) &= E[x(t_1)x(t_2) - x(t_1)\mu_x(t_2) \\ &\quad - x(t_2)\mu_x(t_1) + \mu_x(t_1)\mu_x(t_2)] \\ &= E[x(t_1)x(t_2)] - \mu_x(t_2)E[x(t_1)] \\ &\quad - \mu_x(t_1)E[x(t_2)] + \mu_x(t_1)\mu_x(t_2) \\ &= E[x(t_1)x(t_2)] - \cancel{\mu_x(t_2)\mu_x(t_1)} \\ &\quad - \cancel{\mu_x(t_1)\mu_x(t_2)} + \cancel{\mu_x(t_1)\mu_x(t_2)} \\ &= E[x(t_1)x(t_2)] - \mu_x(t_2)\mu_x(t_1) \end{aligned}$$

Total marks _____
Date _____ / _____ / _____
Page No. _____

$$0 > t < 0 \} = (+\Delta T) (+)$$

$$0 > t < 0 \} = (+\Delta T) (+)$$

$$t < + \} = (+\Delta T) (+)$$

$$+ > (+) > 0$$

Q Let $\{x(t) : t \in [0, 1]\}$ be defined as
 $x(t) = T + C(1-t)$ where T is a uniform random variable in interval $(0, 1)$

- a) Find the CDF of $x(t)$.
- b) Find $E[x(t)]$ and $C_{xx}(t_1, t_2)$

→ For uniform distribution
 $x \sim U(a, b)$

$$\text{pdf} \rightarrow f(x) = \begin{cases} \frac{1}{b-a} & , a < x < b \\ 0 & \text{otherwise} \end{cases}$$

$$\text{cdf} \rightarrow F_x(x) = \begin{cases} 0 & , x < a \\ \frac{x-a}{b-a} & , a \leq x < b \\ 1 & , x \geq b \end{cases}$$

Given that,

$x(t) = T + C(1-t)$, as T follows uniform distribution. Therefore the CDF of $x(t)$

$$F_x(t) (T \leq t) = \begin{cases} 0 & , t < 0 \\ \frac{t}{1} & , 0 < t < 1 \\ 1 & , t > 1 \end{cases}$$

~~$x(t) \leq t$~~

$$\mathbb{1}_{\{x(t) \leq t\}} = \begin{cases} 0, & T + c(1-t) < 0 \\ T - c(1-t), & 0 < T + c(1-t) < 1 \\ 1, & T + c(1-t) > 1 \end{cases}$$

$$= \begin{cases} 0, & T < t - 1 \\ T - c(1-t), & 0 < T < t \\ 1, & T > t \end{cases}$$

$$(x(t) \leq x) = P[T + c(1-t) \leq x]$$

$$= P[T \leq (x-1+t)]$$

$$= P[T \leq t']$$

where $t' = x-1+t$

$$= \begin{cases} 0, & x-1+t = t' < 0 \\ t', & 0 < t' = (x-1+t) < 1 \\ 1, & t' = x-1+t > 1 \end{cases}$$

$$= \begin{cases} 0, & x < t = 1-t \\ t', & 0 < x < 2-t \\ 1, & x < 2-t \end{cases}$$

which is the required CDF.

and pdf $x(t) = \begin{cases} \frac{1}{1-t} & 0 < t < 1 \\ 0 & \text{otherwise} \end{cases}$

$$E(x(t)) =$$

Since $x(t) \sim U(1-t, 2-t)$
here

$$a = 1-t$$

$$b = 2-t$$

$$x(t) = T + C(1-t)$$

$$\therefore \text{mean, } E(x(t)) = \frac{a+b}{2}$$

$$= \frac{1-t+2-t}{2}$$

$$= \frac{3-2t}{2}$$

Correlation

$$R_{xx}(t_1, t_2) = E[x(t_1)x(t_2)]$$

$$= E[(T+C(1-t_1))(T+C(1-t_2))]$$

$$= E[T^2 + T - Tt_2 + T + 1 - t_2 - t_1 T - t_1 + t_1 t_2]$$

$$= E[T^2 + 2T - T(t_1 + t_2) + t_1 t_2 + 1] \\ - t_1 - t_2$$

$$= E[\tau^2] + [2-t_1-t_2]E[\tau] + (1-t_1)(1-t_2)$$

$$\tau \sim U(0,1)$$

$$\therefore \text{Mean } E[\tau] = \frac{1}{2} + \left(-\frac{1}{2}\right) =$$

$$\text{Var}(\tau) = E[\tau^2] - E[\tau]^2$$

$$\hookrightarrow \frac{(b-a)^2}{12}$$

$$\therefore \frac{1}{12} = E[\tau^2] - (E[\tau])^2$$

$$\begin{aligned} E[\tau^2] &= \frac{1}{12} + \frac{1}{4} \\ &= \frac{4+12}{48} = \frac{16}{48} = \frac{2}{3} = \frac{1}{3} \end{aligned}$$

$$\therefore R_{xx}(t_1, t_2) = \frac{1}{12} + (2-t_1-t_2) \frac{1}{2} + (1-t_1)(1-t_2)$$

\therefore Covariance

$$\begin{aligned} C_{xx}(t_1, t_2) &= R_{xx}(t_1, t_2) - \mu_x(t_1)\mu_x(t_2) \\ &= \frac{1}{3} + \frac{(2-t_1-t_2)}{2} + (1-t_1)(1-t_2) \\ &\quad - \left(\frac{3}{2} - t_1\right) \left(\frac{3}{2} - t_2\right) \end{aligned}$$

$$= \frac{1}{3} + 1 - \frac{t_1}{2} - \frac{t_2}{2} + 1 - t_1 - t_2 + t_1 t_2 - \frac{9}{4}$$

$$+ \frac{3}{2} t_1 + \frac{3}{2} t_2 - \cancel{t_1 t_2}$$

$$= \left(\frac{1}{3} + 2 \right) + t_1 + t_2 - t_1 - t_2 - \frac{9}{4}$$

$$= \frac{7}{3} - \frac{9}{4}$$

$$= \frac{28}{12} - \frac{27}{12} = \frac{1}{12}$$

$$= \frac{-9}{12} - \frac{1}{4} = \frac{1}{12}$$

$$\frac{1}{4} + \frac{1}{5} = \frac{9}{20}$$

$$\frac{1}{5} = \frac{9}{20} - \frac{1}{5} = \frac{1}{20}$$

$$\frac{1}{5} = \frac{9}{20} - \frac{1}{5} = \frac{1}{20}$$

9
4

Q

Consider a random process $x(t)$ where $x(t) = A \cos(Cwt + \theta)$ where A and θ are independent and uniform random variable from $(-K, K)$ and $(-\pi, \pi)$. Find the mean, auto-correlation, and auto-variance and

$$\rightarrow A \sim U(-K, K)$$

$$f(A) = \begin{cases} \frac{1}{2K} & -K < A < K \\ 0 & \text{otherwise} \end{cases}$$

$$f(\theta) = \begin{cases} \frac{1}{2\pi} & -\pi < \theta < \pi \\ 0 & \text{otherwise} \end{cases}$$

$$\text{mean } E[A] = \frac{a+b}{2} = K + \frac{(-K)}{2} = 0$$

$$\text{var}[A] = \frac{(b-a)^2}{12} = \frac{4K^2}{12} = \frac{K^2}{3}$$

similarly

$$E[\theta] = 0$$

$$\text{var}[\theta] = \frac{\pi^2}{3}$$

$$\text{mean of } x(t) \rightarrow \mu_x(t) = E[x(t)]$$

$$= E[A \cos(\omega t + \theta)]$$

$$= E[A] E[\cos(\omega t + \theta)]$$

$$= 0 \quad (\text{since } E[A] = 0)$$

$$R_{xx}(t_1, t_2) = E[x(t_1)x(t_2)]$$

$$= E[A \cos(\omega t_1 + \theta) A \cos(\omega t_2 + \theta)]$$

$$= E[A^2] \cos(\omega t_1 + \theta) \cos(\omega t_2 + \theta)$$

$$= E[A^2] E[\cos(\omega t_1 + \theta) \cos(\omega t_2 + \theta)]$$

But

$$\text{var}(A) = E[A^2] - E[A]^2$$

$$\frac{E[A^2]}{3} = E[A^2] - 0 \quad \left. \right\}$$

$$E[A^2] = \frac{E[A]^2}{3}$$

$$\therefore R_{xx}(t_1, t_2) = \frac{E[A^2]}{3} E[\cos(\omega t_1 + \theta) \cos(\omega t_2 + \theta)]$$

→ ①

for

$$E[\cos(\omega t_1 + \theta) \cos(\omega t_2 + \theta)]$$

$$E[x] = \int_a^b x f(x) dx \rightarrow \text{for continuous distribution}$$

$$= \frac{1}{2\pi} \int_{-\pi}^{\pi} \cos(\omega t_1 + \theta) \cos(\omega t_2 + \theta) d\theta$$

$$= \frac{1}{2\pi} \int_{-\pi}^{\pi} \frac{z}{2} \cos(\omega t_1 + \theta) \cos(\omega t_2 - \theta) d\theta$$

$$[\because z \cos A \cos B = \cos(A+B) + \cos(A-B)]$$

$$= \frac{1}{4\pi} \int_{-\pi}^{\pi} \cos(\omega t_1 + \theta + \omega t_2 - \theta) + \cos(\omega(t_1 - t_2)) d\theta$$

$$= \frac{1}{4\pi} \int_{-\pi}^{\pi} \cos(\omega(t_1 + t_2) + 2\theta) + \cos(\omega(t_1 - t_2)) d\theta$$

$$= \frac{1}{4\pi} \left[\frac{\sin(\omega(t_1 + t_2) + 2\theta)}{2} + \theta \cos(\omega(t_1 - t_2)) \right]_{-\pi}^{\pi}$$

$$= \frac{1}{4\pi} \left[\frac{\sin(\omega(t_1 + t_2) + 2\pi) + \pi \cos(\omega(t_1 - t_2))}{2} \right. \\ \left. - \frac{\sin(\omega(t_1 + t_2) - 2\pi) + \pi \cos(\omega(t_1 - t_2))}{2} \right]$$

$$= \frac{1}{4\pi} \left[2\pi \cos(\omega(t_1 - t_2)) + \frac{\sin(\omega(t_1 + t_2))}{2} \right. \\ \left. - \frac{\sin(\omega(t_1 + t_2))}{2} \right]$$

$$[\because \sin(2\pi + \theta) = \sin \theta \\ \sin(2\pi - \theta) = -\sin \theta]$$

$$= \frac{1}{4\pi} (2\pi \cos(\omega(t_1 - t_2)))$$

$$= \frac{\cos(\omega(t_1 - t_2))}{2}$$

$$R_{xx}(t_1, t_2) = \frac{k^2}{6} (\cos(\omega(t_1 - t_2)))$$

$$\begin{aligned} C_{xx}(t_1, t_2) &= R_{xx}(t_1, t_2) - \mu_x(t_1)\mu_x(t_2) \\ &= \frac{k^2}{6} (\cos(\omega(t_1 - t_2))) \end{aligned}$$

→ when mean = 0, i.e. $x(t) = 0$

$$R_{xx}(t_1, t_2) = C_{xx}(t_1, t_2)$$

$$C_{xx}(t, t) = \frac{k^2}{6} (\cos(\omega(t - t)))$$

$$C_{xx}(t^2) = \frac{k^2}{6} = \sigma^2 x(t)$$

Q

$x(t) = B \cos(50t + \phi)$ where B and ϕ are independent random variables, where B is a random variable with $B=0$ and variance = 1 and ϕ is $\phi \sim [-\pi, \pi]$. Find the mean and auto-correlation of the process.

$$\rightarrow E[B] = 0$$

$$\text{var}[B] = 1$$

$$f(\phi) = \begin{cases} \frac{1}{2\pi}, & -\pi < \phi < \pi \\ 0, & \text{otherwise} \end{cases}$$

$$E[\phi] = \frac{a+b}{2} = \frac{\pi - \pi}{2} = 0$$

$$\text{var}(\phi) = \frac{2\pi^2}{12} = \frac{\pi^2}{6}$$

$$\begin{aligned}\text{mean of } x(t) &= E[x(t)] \\ &= E[B \cos(50t + \phi)] \\ &= E[B] \cos(50t + \phi) \\ &= 0\end{aligned}$$

$$\begin{aligned}R_{xx}(t_1, t_2) &= E[x(t_1)x(t_2)] \\ &= E[B^2 \cos(50t_1 + \phi) \cos(50t_2 + \phi)] \\ &= E[B^2] E[\cos(50t_1 + \phi) \cos(50t_2 + \phi)] \\ &\xrightarrow{\text{---} \textcircled{1}}\end{aligned}$$

$$\text{var}(B) = E[B^2] - [E[B]]^2$$

$$\begin{aligned}E[B^2] &= 1 + 0 \\ &= 1\end{aligned}$$

$$E[\cos(50t_1 + \phi) \cos(50t_2 + \phi)]$$

$$\begin{aligned}E[x] &= \frac{1}{2\pi} \int_{-\pi}^{\pi} \cos(50t_1 + \phi) \cos(50t_2 + \phi) d\phi \\ &= \frac{1}{2\pi} \int_{-\pi}^{\pi} \frac{1}{2} [\cos(50(t_1+t_2) + 2\phi) + \cos(50(t_1-t_2))] d\phi \\ &= \frac{1}{2\pi} \int_{-\pi}^{\pi} \cos(50(t_1+t_2) + 2\phi) d\phi + \frac{1}{2\pi} \int_{-\pi}^{\pi} \cos(50(t_1-t_2)) d\phi\end{aligned}$$

$$= \frac{1}{4\pi} \int_{-\pi}^{\pi} \frac{\sin(\cos(\omega t_1 + t_2) + 2\phi)}{2} + \cos(\cos(\omega t_1 + t_2) - \pi)$$

$$= \frac{1}{4\pi} \left[\frac{\sin(\cos(\omega t_1 + t_2) + 2\pi)}{2} + \pi \cos(\cos(\omega t_1 + t_2) - \pi) \right. \\ \left. + \sin(\cos(\omega t_1 + t_2) - \pi) + \pi \cos(\cos(\omega t_1 + t_2) - \pi) \right]$$

$$= \frac{1}{4\pi} \left(2\pi \cos(\cos(\omega t_1 - t_2)) \right)$$

$$= \cos(\frac{\cos(\omega t_1 - t_2)}{2})$$

$$C_{xx}(t_1, t_2) = \cos(\frac{\cos(\omega t_1 - t_2)}{2})$$

Q

Suppose $x(t)$ is a random process with mean = 3 and auto-correlation $R(t_1, t_2) = 9 + 4e^{-0.2|t_1 - t_2|}$. Determine the mean, variance and covariance of the random variable $z = x(5)$ and $w = \frac{x(8)}{t_1}$.

Given

$$\rightarrow \mu_x(t) = E(x(t)) = 3 - \forall t \in T$$

∴ mean of z & w = 3

$$\therefore E[z] = E[x(5)] = 3$$

$$E[\bar{z}] = E[x(8)] = 3$$

$$R(z, w) = E[x(t_1)x(t_2)] = 9 + 4e^{-0.2|t_1 - t_2|}$$

$$= E[zw]$$

$$C_{xx}(z, w) = E[x(t_1)x(t_2) - \mu_x(t_1)\mu_x(t_2)]$$

$$= E[zw] - E[z]E[w]$$

$$= 9 + 4e^{-0.2|t_1 - t_2|} - 9$$

$$= 4e^{-0.2(5-8)}$$

$$C_{xx}(z, w) = 4e^{-0.2/3}$$

$$= 4e^{-0.6}$$

when $z = w$

is converted

$$C_{xx}(z, w) = \text{variance}(z, w)$$

Now

$$\begin{aligned} \text{var}(z) &= C_{xx}(z, z) \\ &= R_{zz}(5, 5) - E[z]E[z] \\ &= 9 - 9 + 4e^{-0.2|5-5|} \\ &= 4 \end{aligned}$$

similarly,

$$\text{var}(w) = 4$$

66R

→ Stationary Random Process (Strict Sense)

- A random process is stationary if it's statistical properties (PDF, CDF) do not change by time i.e. for stationary process $x(t)$ and $x(t + \Delta t)$ have the same probability distribution have the same probability distribution

$$f_x(t) = f_x(t + \Delta t) \quad \forall t, t + \Delta t$$

$$F_x(t) = F_x(t + \Delta t) \quad \forall t, t + \Delta t$$

- ∴ A random process is stationary if the time shift does not change its statistical properties

- $\{x(t) : t \in T\}$ is strict sense stationary or simply stationary if for all t_1, t_2, \dots, t_r belong to T and all Δ belong to Real Number

$$\begin{aligned} \rightarrow F_x(t_1) \times F_x(t_2) \times F_x(t_3) \dots \times F_x(t_r) (x_1, x_2, \dots, x_r) \\ = F_x(t_1 + \Delta) \times F_x(t_2 + \Delta) \dots \times F_x(t_r + \Delta) \\ (x_1, x_2, \dots, x_r) \end{aligned}$$

OR

$$\begin{aligned} \rightarrow f_{x_1}(t_1) \times f_{x_2}(t_2) \dots f_{x_r}(t_r, t_2, \dots, t_r) \\ = f_{x_1}(x_1, x_2, \dots, x_r, t_1 + \Delta, t_2 + \Delta, \dots, t_r + \Delta) \end{aligned}$$

Q

The mean and variance of a first order stationary process are constant.

→ Let $\{x(t)\}$ be a first order stationary process.

$$f_{x(t)} = f$$

$$f_{x(x; t)} = f_{x(x; t+\Delta t)}$$

Our target is to show $E[x(t+\Delta t)] = E[x(t)]$ and
 $\text{var}[x(t+\Delta t)] = \text{var}[x(t)]$

$$\begin{aligned} E[x(t+\Delta t)] &= \int_{-\infty}^{\infty} x f_{x(x; t+\Delta t)} dx \\ &= \int_{-\infty}^{\infty} x f_{x(x; t)} dx \\ &= E[x(t)] \end{aligned}$$

∴ mean is constant

Let $E[x(t)] = \mu_x = \text{constant}$

$$\text{var}(t+\Delta t) = E[(x(t+\Delta t) - \mu_x)^2]$$

$$\Rightarrow \boxed{E[x] = E[(x-\mu)^2]}$$

$$\begin{aligned} &= \int_{-\infty}^{\infty} (x - \mu_x)^2 f_{x(x; t+\Delta t)} dx \\ &= \int_{-\infty}^{\infty} (x - \mu_x)^2 f_{x(x; t)} dx \end{aligned}$$

$$= \text{var}(x^*, t)$$

\therefore variance is constant

~~$\therefore \text{let } \text{var}(x(t)) =$~~

- Q If $\{x(t) = A \cos \lambda t + B \sin \lambda t; t \geq 0\}$ is a random process, where A and B are independent random variables, each of which assumes the value -2 and 1 with probabilities $\frac{1}{3}$ and $\frac{2}{3}$ respectively. Show that $\{x(t)\}$ is not strict sense stationary

→ For not strict sense we need to show one of moments is not constant

E	A / B	-2		1
	$p(x)$	$\frac{1}{3}$		$\frac{2}{3}$

$$\text{mean} = \sum x p(x)$$

$$\begin{aligned} E[A] &= -\frac{2}{3} + \frac{2}{3} & (\because \sum A p(A)) \\ &= 0 \end{aligned}$$

$$\therefore E[B] = 0 \quad (\because \sum B p(B))$$

$$E[A^2] = \sum A^2 P(A)$$

$$= \frac{4}{3} + \frac{2}{3}$$

$$= \frac{6}{3} = 2$$

$$E[B^2] = 2$$

$$\therefore E[AB] = E[A]E[B] = 0 \quad (\text{because } A \text{ & } B \text{ are independent})$$

$$E[x(t)] = \int_{-\infty}^{\infty} x(t) f E[A \cos \lambda t + B \sin \lambda t]$$

$$= E[A]E[\cos \lambda t] + E[B]E[\sin \lambda t]$$

$$= 0$$

= constant

$$E[x^2(t)] = E[(A \cos \lambda t + B \sin \lambda t)^2]$$

$$= E[A^2 \cos^2 \lambda t + B^2 \sin^2 \lambda t + 2AB \sin \lambda t \cos \lambda t]$$

$$= E[A^2]E[\cos^2 \lambda t] + E[B^2]E[\sin^2 \lambda t]$$

$$+ 2E[A]E[B]E[\sin \lambda t \cos \lambda t]$$

$$= 2 \cos^2 \lambda t + 2 \sin^2 \lambda t + 0$$

$$= 2$$

= constant

Q.

Consider a random process $x(t) = \cos(t + \phi)$ where ϕ is a random variable with density function $f(\phi) = \frac{1}{\pi}$ for $-\frac{\pi}{2} < \phi < \frac{\pi}{2}$. Check whether or not the process is stationary.

$$E[x(t)] = E[\cos(t + \phi)]$$

$$= \int_{-\pi/2}^{\pi/2} \cos(t + \phi) f(\phi) d\phi$$

$$= \frac{\pi/2}{\pi} \int_{-\pi/2}^{\pi/2} \cos(t + \phi) \frac{1}{\pi} d\phi$$

$$= \frac{1}{\pi} \left[\sin(t + \phi) \right]_{-\pi/2}^{\pi/2}$$

$$= \frac{1}{\pi} \left[\sin(t + \frac{\pi}{2}) - \sin(t - \frac{\pi}{2}) \right]$$

$$= \frac{1}{\pi} \left[\sin(t + \frac{\pi}{2}) + \sin(\frac{\pi}{2} - t) \right]$$

$$= \frac{1}{\pi} [\cos t + \cos t]$$

$$= \frac{2 \cos t}{\pi} \rightarrow \text{which depends on } t$$

∴ the process is not stationary.

Q Examine whether the Poisson process p if
 $p[x(t) = k] = e^{-\lambda t} \frac{(\lambda t)^k}{k!}, k=0,1,2,3,\dots$

→ For poisson process,

mean of $x(t) = \lambda t \rightarrow$ depends on t , hence not constant

∴ The given process is not constant stationary.

Q For the sine wave process $x(t) = Y \cos \omega_0 t, -\infty < t < \infty$
 ω_0 is constant, the amplitude Y is a random variable with uniform distribution in the interval 0 to 1. Check whether the process is stationary or not.

$$Y \sim U[0,1]$$

$$f(y) = \begin{cases} 1 & , 0 < y < 1 \\ 0 & \text{otherwise} \end{cases}$$

$$E[Y] = \frac{1}{2} \quad \text{var}[Y] = \frac{1}{12}$$

$$\begin{aligned} E[x(t)] &= E[Y \cos \omega_0 t] \\ &= E[Y] E[\cos \omega_0 t] \\ &= \frac{1}{2} E[\cos \omega_0 t] \rightarrow \text{depends on } t, \text{ hence not constant} \end{aligned}$$

∴ The given process is not stationary

→ 3 → Weak Sense Stationary Process

OR

Wide Sense Stationary Process (WSS)

- A random process $x(t)$ where $t \in T$ is called wide sense stationary if its mean function and correlation functions do not change by shift in time, i.e. $\{x(t) : t \in T\}$ is said to be WSS if for all t_1, t_2 belongs to T we have,

$$\text{i)} E[x(t)] = E[x(t+\Delta)]$$

$$\text{ii)} R_{xx}(t_1, t_2) = R_{xx}(t_1 + \Delta, t_2 + \Delta) \\ = R_{xx}(t_1 - t_2)$$

Q

Consider the random process $\{x(t) : t \in T\}$
 $x(t) = \cos(t + A)$ where $A \sim U[0, 2\pi]$
 Show that $x(t)$ is WSS.

$$\rightarrow f(A) = \int_{-\pi}^{\pi} \frac{1}{2\pi} \rightarrow 0 < A < 2\pi$$

0, otherwise

$$\text{mean of } A E[A] = \pi$$

$$\text{var}[A] = \frac{\pi^2}{3}$$

$$\begin{aligned}
 E[x(t)] &= E[\cos(\omega t + A)] \\
 &= \frac{1}{2\pi} \int_0^{2\pi} \cos(\omega t + A) f(A) dA \\
 &= \frac{1}{2\pi} \int_0^{2\pi} \cos(\omega t + A) dA \\
 &= \frac{1}{2\pi} \left[\sin(\omega t + A) \right]_0^{2\pi} \\
 &= \frac{1}{2\pi} [\sin(2\pi t) - \sin t] \\
 &= \frac{1}{2\pi} [0 - \sin t] \\
 &= \frac{1}{2\pi} (0) \\
 &= 0
 \end{aligned}$$

$\therefore E[x(t)]$ is constant
 $\therefore E[x(t)] = E[x(t+\Delta t)]$

$$\begin{aligned}
 R_{xx}(t_1, t_2) &= E[x(t_1)x(t_2)] \\
 &= E[\cos(\omega t_1 + A) \cos(\omega t_2 + A)] \\
 &= \frac{1}{2\pi} \int_0^{2\pi} \cos(\omega t_1 + A) \cos(\omega t_2 + A) f(A) dA \\
 &= \frac{1}{2\pi} \int_0^{\pi} \cos(\omega t_1 + \underline{A}) \cos(\omega t_2 + \underline{A}) dA
 \end{aligned}$$

$$= \frac{1}{2\pi} \int_0^{2\pi} \cos(t_1 + t_2 + 2A) + \sin(t_1 - t_2) dA$$

$$= \frac{1}{2\pi} \left[\sin(t_1 + t_2 + 2A) + [\cos(t_1 - t_2)] A \right]_0^{2\pi}$$

$$= \frac{1}{2\pi} \left[\sin(t_1 + t_2 + 2\pi) + 2\pi \cos(t_1 - t_2) - \sin(t_1 + t_2) - 0 \right]$$

$$= \frac{1}{2\pi} \left[\cancel{\sin(t_1 + t_2)} - \cancel{\sin(t_1 + t_2)} + 2\pi \cos(t_1 - t_2) \right]$$

$$= \frac{1}{2} \cos(t_1 - t_2) \rightarrow \text{depends on } t_1 - t_2$$

$$\therefore R_{xx}(t_1, t_2) = R_{xx}(t_1 - t_2)$$

Hence, the given process is WSS

Q

Given a random variable Y with characteristic function $\phi(w) = E[e^{iwY}]$ and a random process defined by $x(t) = \cos(\lambda t + Y)$. S.T. $x(t)$ is WSS if $\phi(1) = \phi(2) = 0$.

$$\rightarrow \phi(1) = E[e^{iY}]$$

$$e^{i\theta} = \cos\theta + i\sin\theta$$

$$\therefore \phi(1) = E[\cos Y + i\sin Y]$$

$$0 + i0 = E[\cos Y + i\sin Y]$$

$$0 + i0 = E[\cos Y] + iE[\sin Y]$$

$$\Rightarrow \cos Y E[\cos Y] = 0 \quad \& \quad E[\sin Y] = 0$$

similarly

$$E[\cos 2Y] = 0 \quad \& \quad E[\sin 2Y] = 0$$

$$E[x(t)] = E[\cos(\lambda t + Y)]$$

$$= E[\cos \lambda t \cos Y - \sin \lambda t \sin Y]$$

$$= E[\cos \lambda t] E[\cos Y] - E[\sin \lambda t] E[\sin Y]$$

$$= 0, \forall Y$$

$\therefore E[x(t)]$ is constant $\forall t$

$$\begin{aligned}
 R_{xx}(t_1, t_2) &= E[x(t_1)x(t_2)] \\
 &= E[\cos(\lambda t_1 + Y)\cos(\lambda t_2 + Y)] \\
 &= E\left[\frac{\cos(\lambda t_1 + \lambda t_2 + 2Y) + \cos(\lambda t_1 - \lambda t_2)}{2}\right] \\
 &= E\left[\frac{\cos(\lambda t_1 + \lambda t_2)\cos 2Y - \sin(\lambda t_1 + \lambda t_2)\sin 2Y + \cos(\lambda t_1 - \lambda t_2)}{2}\right] \\
 &= \frac{E[\cos(\lambda t_1 + \lambda t_2)]E[\cos 2Y]}{2} \\
 &\quad - \frac{\sin(\lambda t_1 + \lambda t_2)E[\sin 2Y]}{2} \\
 &\quad + \frac{E[\cos(\lambda t_1 - \lambda t_2)]}{2} \\
 &= \frac{\cos(\lambda t_1 - \lambda t_2)}{2} \rightarrow \text{depends on } t_1 - t_2
 \end{aligned}$$

$$\therefore R_{xx}(t_1, t_2) = R_{xx}(t_1 - t_2)$$