

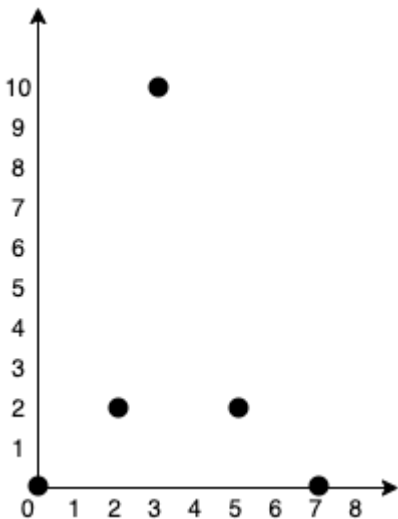
# 1584. Min Cost to Connect All Points

You are given an array `points` representing integer coordinates of some points on a 2D-plane, where `points[i] = [xi, yi]`.

The cost of connecting two points `[xi, yi]` and `[xj, yj]` is the **manhattan distance** between them:  $|x_i - x_j| + |y_i - y_j|$ , where  $|val|$  denotes the absolute value of `val`.

Return *the minimum cost to make all points connected*. All points are connected if there is **exactly one** simple path between any two points.

## Example 1:



Input: `points = [[0,0],[2,2],[3,10],[5,2],[7,0]]`

Output: 20

Explanation:

``

We can connect the points as shown above to get the minimum cost of 20. Notice that there is a unique path between every pair of points.

## Example 2:

Input: `points = [[3,12],[-2,5],[-4,1]]`

Output: 18

## Constraints:

- `1 <= points.length <= 1000`
- `-106 <= xi, yi <= 106`

- All pairs  $(x_i, y_i)$  are distinct.

```
from collections import defaultdict
import heapq
class Solution:
    def minCostConnectPoints(self, points: List[List[int]]) -> int:
        graph = defaultdict(list)

        for i in range(len(points)):
            for j in range(len(points)):
                if i!=j:
                    dis = abs(points[i][0]-points[j][0])+abs(points[i][1]-
points[j][1])
                    graph[i].append((j,dis))
        heap = [[0,0]]
        amount = 0
        visited = [False]*len(points)
        while len(heap)>0:
            cost,point = heapq.heappop(heap)
            if visited[point] == True:
                continue
            visited[point] = True
            amount=cost+amount
            for nbr in graph[point]:
                pt,wght = nbr
                if visited[pt] == False:
                    heapq.heappush(heap, (wght,pt))
        return amount
```