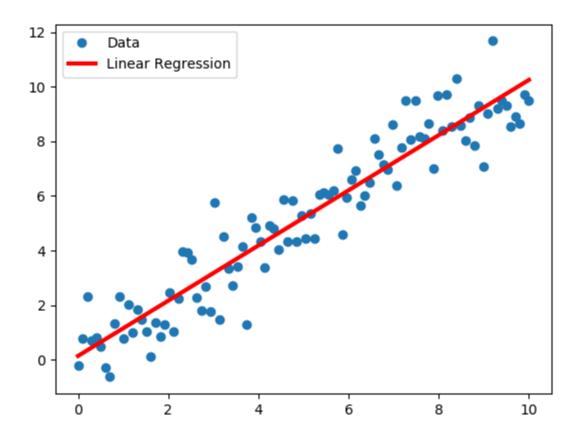
Optimisation

Motivation



We want to find a and b which minimize the sum square errors J which is given by

$$J(a,b) = rac{1}{2} \sum_{i=1}^n (y_i - (ax_i + b))^2$$

Next

We are going to find a and b which minimize J(a,b) in three different ways:

- Numerically with Excel + Solver
- Analytically with Python Numpy
- Gradient Descent (will be calculated by you)

Numerically with Excel

• One variable linear regression

Matrix Representation

Recall that we would like to minimize

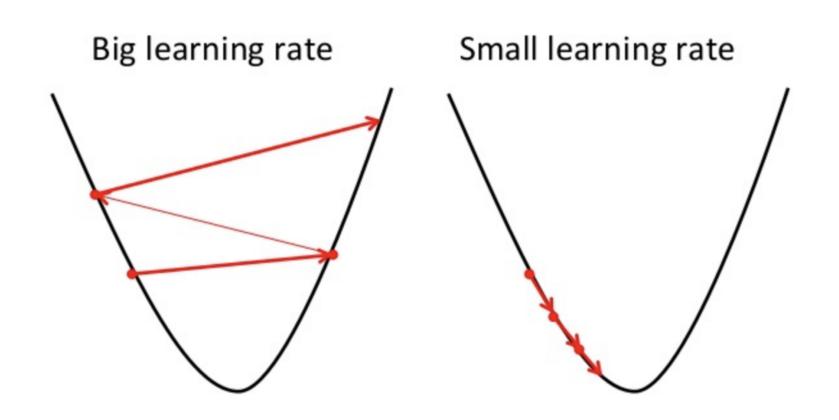
$$J(a,b) = rac{1}{2} \sum_{i=1}^n (y_i - (ax_i + b))^2$$

Suppose that we have n observations and m features. We can stack these observations in a matrix X with size $n \times m$.

If $J(eta)=rac{1}{2}(y-Xeta)^T(y-Xeta)$, then \hat{eta} which minimize J is given by

$$\beta = (X^T X)^{-1} X^T y$$

Gradient Descent - Intuition



Gradient Descent - algorithm

For one variable, the iteration logic is given by:

$$x_{n+1} = x_n - \eta Df(x_n)$$

where $Df(x_0)$ means $rac{df(x)}{dx}$ evaluated at $x=x_0$

If it is extended to multi-variable scheme, then the iteration logic becomes:

$$eta_{n+1} = eta_n - \eta
abla J(eta_n)$$

Remarks: η is called *learning rate*.

Gradient Descent - algorithm

Recall the cost function of the original problem

$$J(a,b) = rac{1}{2} \sum_{i=1}^n (y_i - (ax_i + b))^2$$

Partial derivaties with respect to a and b are given by

$$rac{\partial J}{\partial a} = \sum_{i=1}^n (y_i - (ax_i + b))(-x_i)$$

and

$$rac{\partial J}{\partial b} = \sum_{i=1}^n (y_i - (ax_i + b))(-1)$$

** Graph of J as function of a and b **

Differences between Convex vs Non-Convex

** Picture here **

Appendix

Derivation of linear regression MLE

Using the previous notation, we would like to minimize

$$J(eta) = (y - Xeta)^T (y - Xeta)$$

Calculating the gradient of J gives us

$$abla J = 2 imes
abla (y - Xeta)^T imes (y - Xeta)
onumber$$
 $abla J = 2 imes (
abla y^T -
abla (Xeta)^T) imes (y - Xeta)
onumber$

Knowing $abla(Xeta)^T=X^T$ and setting gradient to be zero, we get

$$0=2 imes -X^T imes (y-Xeta)=-X^Ty+X^TXeta$$

Moving $-X^T\beta$ to the left hand side and multiplying both sides by $(X^TX)^{-1}$ gives us the solution

$$\hat{Q} = (\mathbf{Y}^T \mathbf{Y})^{-1} \mathbf{Y}^T$$