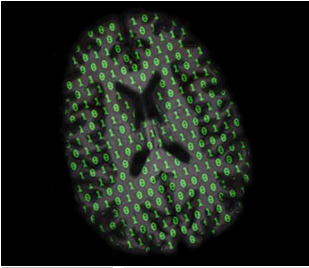


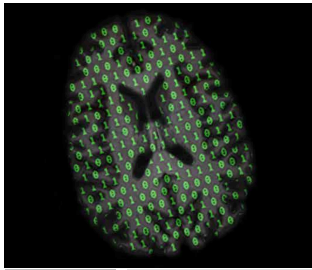


THEME 3 / LECTURE 2: REGISTRATION

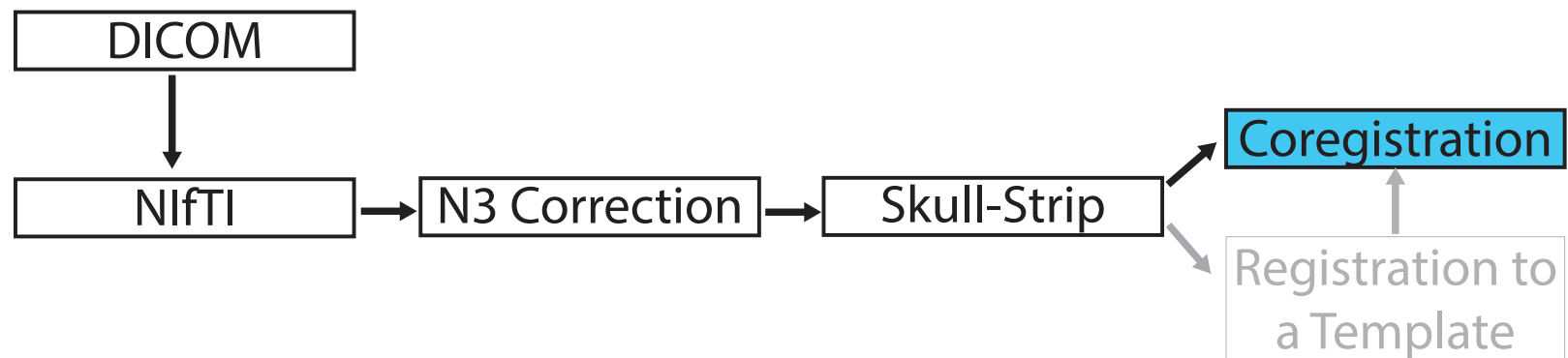


Registration

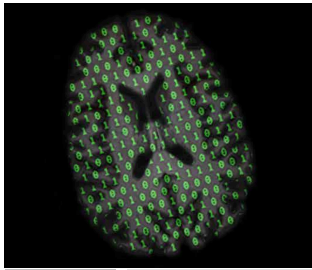
Registration is a spatial transformation of one or multiple images with the goal of making locations (voxels, ROIs) have the same or similar interpretation



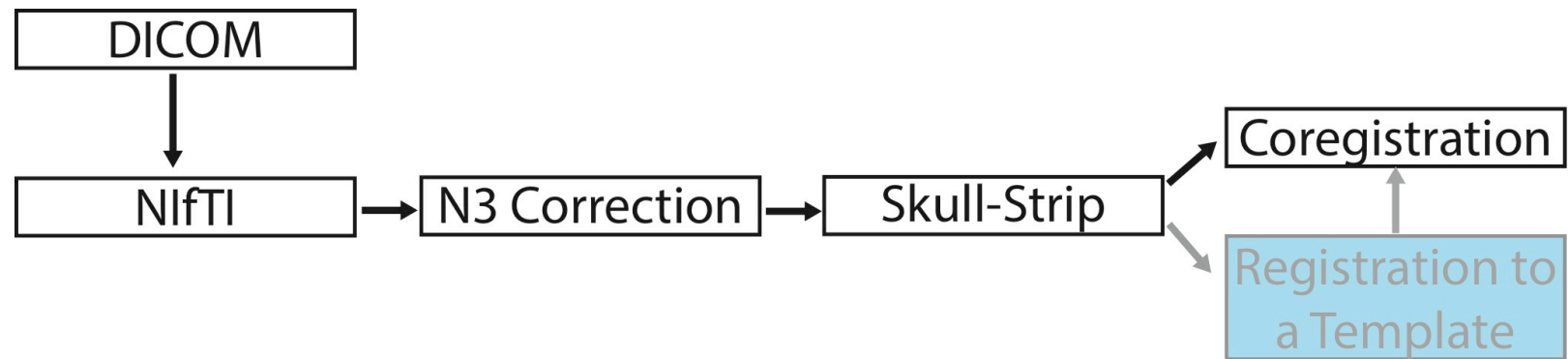
Co-Registration



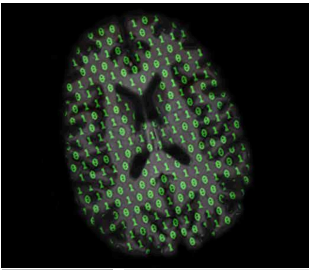
Coregister volumes from different modalities to one another (for example, register the FLAIR to the T1-w volume or register a baseline to a follow-up study)



Registration to a Template

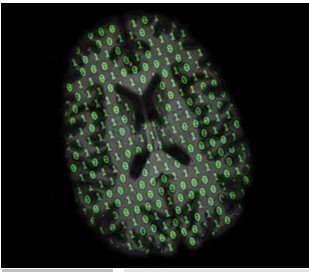


You can also register to a group template (such as the MNI T1-w template)



Types of registration

- Complexity
 - rigid (6df)
 - affine (12df)
 - nonlinear ($>12df$)
- Co-registration (within the same person)
 - Cross-sectional between-modalities
 - Longitudinal within-modality
 - Longitudinal between-modalities
- Registration to a template
 - A template image is necessary (e.g. MNI template stored in `.../data/MNI152_T1_1mm.nii.gz`)
 - There are many different templates
- One subject to another



Linear Registration: Rigid

- Rigid registration has 6 degrees of freedom and consists of a translation and a rotation.

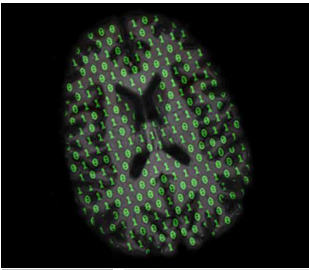
$$T_{\text{rigid}}(v) = Rv + t$$

- Rotation Matrix

$$R = \begin{bmatrix} \cos \beta \cos \gamma & \cos \alpha \sin \gamma + \sin \alpha \sin \beta \cos \gamma & \sin \alpha \sin \gamma - \cos \alpha \sin \beta \cos \gamma \\ -\cos \beta \sin \gamma & \cos \alpha \cos \gamma - \sin \alpha \sin \beta \sin \gamma & \sin \alpha \cos \gamma + \cos \alpha \sin \beta \sin \gamma \\ \sin \beta & -\sin \alpha \cos \beta & \cos \alpha \cos \beta \end{bmatrix}$$

- Translation vector

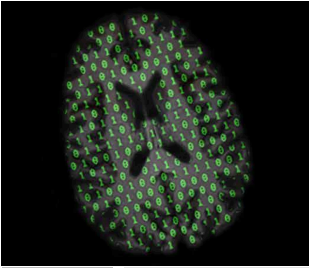
$$t = (t_x, t_y, t_z)$$



Linear Registration: Affine

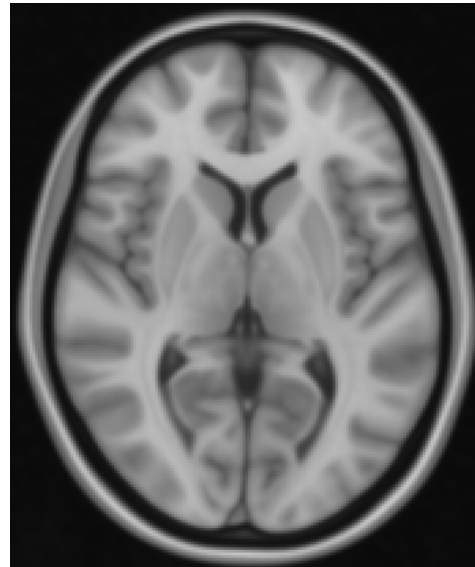
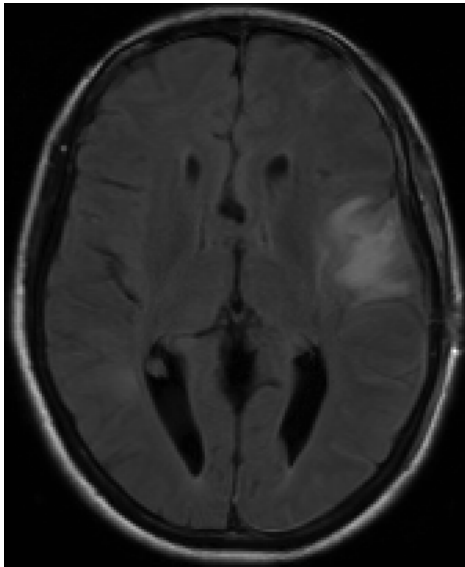
- Affine registration has 12 degrees of freedom
- Same form as the rigid, but the matrix A is not constrained to be a rotation matrix
- A has 9 entries (3×3 matrix) and the translation vector has 3 entries: total “12 degrees of freedom”

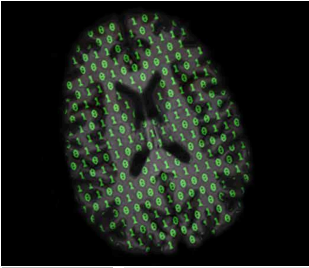
$$T_{\text{affine}}(v) = Av + t$$



Nonlinear registration

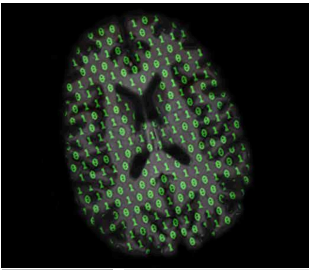
- Co-registration, registration to a template, or from one subject to another





Co-Registration

- Works better and requires fewer degrees of freedom
- Easier to register the same brain
- Analysis examples that do not require a reference template
 - Identify location-specific longitudinal changes
 - Segmentation
 - Analysis of intensities



Registration to a Template

- Assumes that brains can reasonably be morphed to a template space
- Gain anatomical information from the template
- Analysis examples that require a reference template
 - Presenting population level results (e.g. location of lesions)
 - Describing findings at the anatomic level (e.g. the ICH covered more than 30% of thalamus in more than 50% of the patients)
 - Segmentation using multi-atlas label fusion