K.G.C.E. Page No.: Date: Karjat - Raigad TUTORIAL 23- To understand State space probl. formy. Name :- Rahul Bavindra Shinde Roll No. 8-64 Class &- BE-IT Subject :- Is Lab Maxk DOP

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	10	To understand State Space problem formultion
) 40	1.00	Linksperial Island of Alleria
( writer	*	Aim &- to understand state space based
		problem formulation of Al problems so
		that Problem solving Agent can be applied
pithon	p* 37	The Commence of South and is I had in
	*	Theory &- STADIOS
		- First we understand the problem solving
		agent. Algorithm show in Figure & shows
		agent program for problem solving
		agent
	1	- Agent first formulates goal and problem
		then determines or rather searches an
		action sequence after which it returns
		the next action to be executed in a
		Sequential manner.
		1 cl 1 And 1 And 1
	*	Function SIMPLE-PROBLEM-SOLVING-AGENT
		(percept) returns an action .
	·	static : seq, an action seq., initially empty
		state some descrp, of the current
/		world state
1		goal, a goal, initially null
		problem a problem formulation
		State < UPDATE - STATE (State, percept)
		if seg is empty then do
		goal & Formulate - GOPL (State)
d =		problem FORMULATE - PROBLEM (State goal)
		seq < SIEHRCH CProblem)
		action < FIRST ( seq)
1.		seq < REST (seq

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	٧,	Defining the Problem is referred to as		
100	*	problem formulation. It involves		
		problem tormulation, it morres		
	1	defining following Five things:-		
<i>b</i> ,	3	Tool crandia it is the chartene state		
	$ \mathcal{U} $	Instial State &- it is the Starting State		
-	<u>(C)</u>	that the problem is in.		
her T	(2)	Actions-It defines all possible actions		
41 + 77	Y-1	available to the agent, given it Psin		
	7 5 1	some state's currently. It is function		
	2 1	Action (s) that returns list of all		
	60	possible actionsistall		
11 .	(3)	Transition Model &- also known as		
1 . 1' + + 1 °	- 1	successor function which define		
4 - 3 - 1/ -	1.5%	Which		
37.5		to when a particular action is executed		
-1 PS		by the agent. Successive application		
10 F 7111	,	of transition model gives rise to		
1 0 24 1 1	116	What 95 know as state-space.		
3_1	(4)	Goal Test 8-This ar act as a Stopping		
11-1	14	condition when the state passed to		
73.16	4	this function is goal state it will! return true and searching would stop.		
Light from the		return true and searching would stop.		
A CHO PA	(5)	Path cost o It is accumulated cost		
21 1 July 1	_1 1:	of performing certain sequence of actions. This can help in determining		
1		actions. This can help in determining		
1.	1 :-	weather the action sequence under		
		consideration is optimal.		
1		11 2000		
CRV - 1 T		Thus a problem can formally specified by identifying initial State, actions,		
1 18 - Para - j	1 1	by identifying initial State, actions,		

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1 <u>-</u>		transition model, goal test and path
		cost. In term of problem solving agent
		solytion is the path from initial state to
		a goal state is the lowest path cost of
		a goal state is the lowest path cost of all solutions. Process of finding a solution is called search.
- 1		solution is called search.
		47 - The state of
5 4.	*	Working 8-
14 7	ì	1 Navigate to KGCIE WORKShop From HOD IT
. N. A. M.	<b>/-</b>	cabin with minimum no of moves, moves can
	17	be climbing, turning left, sight, walking
		through a corridor
	*-	@ 8 Puzzle problem
	ا ا	3 The missionaries and cannibals problem.
277	-	There are three missionaries and three
24. 3	) F	cannibals who must cross a river
- gen		using a boat which can carry at most
		two people, under the constraint that for
		both banks, if there are missionaries
prefer	•1 - 2 ]	present on the bank, they cannot be
L.		cannibats. If they were, the cannibals
11/70	j.	would put the Missionaries. The boat
1.00/2 /	IAIC.	i cannot the river by itself with no people on bea
1 10		a) N queen's problem, Arrange N queens ona
÷,	330	N cross Nchess board where no two queens
321N41 e 1 1 .	99	rattack each other.
t. 5-191.	1.1	5 Two room Vacuum Cleaner would.
1 - 7		D Water Jug Problèm
		, 3
Line E.	*	Resources 2- Refer to second chapter from
	11	Resources 2 - Refer to second chapter from Artificial Intelligence 3 A modern Approach
7. 1		