# **Facial expression detection using Machine Learning**

#### Introduction

Facial expressions are used by human beings to convey their emotions and feelings without saying anything. Nowadays, Facial Expression Detection has got its applications in many fields such as Robotics, Driver Fatigue Monitoring Systems, Medical treatment and many other human-computer interaction systems. In this article, facial expression detection of the most important and universal facial expressions are illustrated using machine learning.

## **Machine Learning Problem Formulation**

We will use Tensorflow to build Convolutional Neural Network model for conducting image classification. CNN is a class of deep neural networks which is used mainly in computer vision. Our main objective here is to categorize each image on the basis of the emotion shown into one of the seven classes (0 for Angry, 1 for Disgust, 2 for Fear, 3 for Happy, 4 for Sad, 5 for Surprise, 6 for Neutral).

#### **Data Set Source**

The data set can be downloaded through the following link:

https://www.kaggle.com/c/challenges-in-representation-learning-facial-expression-recognition-challenge/data

The dataset consists of 48x48 pixel grayscale images of face expressions. The images have been taken such that the face is center aligned and occupies about the same amount of space in each image.

## **Prerequisites**

Software and important libraries needed are Python 3, Jupyter Notebook, numpy, pandas, matplotlib, scikit-learn and seaborn.

### **Working Code:**

Step 1: Importing the necessary libraries.

```
import pandas as pd
import numpy as np
import tensorflow as tf
%matplotlib inline
import matplotlib.pyplot as plt
import matplotlib.cm as cm
```

Step 2: Now we read the data and get relevant information regarding the data.

```
data = pd.read_csv("/home/Desktop/fer2013/fer2013.csv")
#check the number of images and each image data variable
data.shape
data.head()
np.unique(data["Usage"].values.ravel())
train_data = data[data.Usage == "Training"]
pixels_values = train_data.pixels.str.split(" ").tolist()
pixels_values = pd.DataFrame(pixels_values, dtype=int)
images = pixels_values.values
images = images.astype(np.float)
```

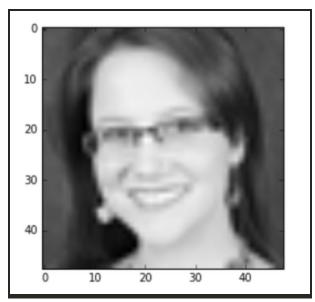
The following function is used to to show image through 48\*48 pixels

```
def show(img):
     show_image = img.reshape(48,48)

plt.imshow(show_image, cmap='gray')
```

For example, we show the following image.

```
show(images[7])
```



Step 3: Now preprocessing of data has to be done which involves converting flattened data to 48\*48 matrix. In data preprocessing, we transform the data into a useful format.

```
images = images - images.mean(axis=1).reshape(-1,1)
images = np.multiply(images,100.0/255.0)
each_pixel_mean = images.mean(axis=0)
each_pixel_std = np.std(images, axis=0)
images = np.divide(np.subtract(images,each_pixel_mean), each_pixel_std)
image_pixels = images.shape[1]
print 'Flat pixel values is %d'%(image_pixels)
image_width = image_height =
np.ceil(np.sqrt(image_pixels)).astype(np.uint8)
labels_flat = train_data["emotion"].values.ravel()
labels_count = np.unique(labels_flat).shape[0]
```

To get one hot encoding outputs, we convert the dense format to one hot encoding format. One hot encoding is basically used to represent categorical values as binary vectors.

```
def dense to one hot(labels dense, num classes):
    num_labels = labels_dense.shape[0]
    index_offset = np.arange(num_labels) * num_classes
    labels_one_hot = np.zeros((num_labels, num_classes))
    labels_one_hot.flat[index_offset + labels_dense.ravel()] = 1
    return labels_one_hot
labels = dense_to_one_hot(labels_flat, labels_count)
```

```
labels = labels.astype(np.uint8)
```

We now split the data into training & validation data sets.

```
VALIDATION_SIZE = 1709
validation_images = images[:VALIDATION_SIZE]
validation_labels = labels[:VALIDATION_SIZE]

train_images = images[VALIDATION_SIZE:]

train_labels = labels[VALIDATION_SIZE:]
```

Step 4: This is the most important step where we build the Tensorflow CNN Model.

First of all we initialize the weights.

```
def weight_variable(shape):
    initial = tf.compat.v1.truncated_normal(shape, stddev=1e-4)
    return tf.Variable(initial)

def bias_variable(shape):
    initial = tf.compat.v1.constant(0.1, shape=shape)
    return tf.Variable(initial)
```

Now we define the functions *conv2d* and *max\_pool\_2x2* for convolution and pooling. Convolution is used to extract features from an input image. Pooling is basically used to reduce the dimensions of the data where the combination of clusters of neurons at one layer merge to form a single neuron in the successive layer.

```
def conv2d(x, W, padd):
    return tf.nn.conv2d(x, W, strides=[1, 1, 1, 1], padding=padd)
def max_pool_2x2(x):
    return tf.nn.max_pool(x, ksize=[1, 3, 3, 1], strides=[1, 2, 2, 1],
padding='SAME')
```

We define the input & output of Neural Network.

```
tf.compat.v1.disable_eager_execution()
# images
x = tf.compat.v1.placeholder(tf.float32, shape=(None, image_pixels))
# labels
y_ = tf.compat.v1.placeholder(tf.float32, shape=(None, labels_count))
```

We define the first convolutional layer which is the building block for a CNN.

```
W_conv1 = weight_variable([5, 5, 1, 64])
b_conv1 = bias_variable([64])
# (27000, 2304) => (27000, 48, 48, 1)
image = tf.reshape(x, [-1, image_width , image_height, 1])
#print (image.get_shape()) # => (27000, 48, 48, 1)
h_conv1 = tf.nn.relu(conv2d(image, W_conv1, "SAME") + b_conv1)
#print (h_conv1.get_shape()) # => (27000, 48, 48, 64)
h_pool1 = max_pool_2x2(h_conv1)
#print (h_pool1.get_shape()) # => (27000, 24, 24, 1)
h_norm1 = tf.nn.lrn(h_pool1, 4, bias=1.0, alpha=0.001/9.0, beta=0.75)
```

Now we define the second convolutional layer.

```
W_conv2 = weight_variable([5, 5, 64, 128])
b_conv2 = bias_variable([128])
h_conv2 = tf.nn.relu(conv2d(h_norm1, W_conv2, "SAME") + b_conv2)
#print (h_conv2.get_shape()) # => (27000,24,24,128)
h_norm2 = tf.nn.lrn(h_conv2, 4, bias=1.0, alpha=0.001/9.0, beta=0.75)
h_pool2 = max_pool_2x2(h_norm2)
```

The local layer weight initialization is done using the following functions.

```
def local_weight_variable(shape):
    initial = tf.compat.v1.truncated_normal(shape, stddev=0.04)
```

```
return tf.Variable(initial)
def local_bias_variable(shape):
    initial = tf.compat.v1.constant(0.0, shape=shape)
    return tf.Variable(initial)
```

The densely connected layer local 3 is added which gives relevant features from all the combinations of features of the previous layer.

```
W_fc1 = local_weight_variable([12 * 12 * 128, 3072])
b_fc1 = local_bias_variable([3072])
# (27000, 12, 12, 128) => (27000, 12 * 12 * 128)
h_pool2_flat = tf.reshape(h_pool2, [-1, 12 * 12 * 128])
h_fc1 = tf.nn.relu(tf.matmul(h_pool2_flat, W_fc1) + b_fc1)
#print (h_fc1.get_shape()) # => (27000, 1024)
```

We now add another densely connected layer.

```
W_fc2 = local_weight_variable([3072, 1536])
b_fc2 = local_bias_variable([1536])
# (40000, 7, 7, 64) => (40000, 3136)
h_fc2_flat = tf.reshape(h_fc1, [-1, 3072])
h_fc2 = tf.nn.relu(tf.matmul(h_fc2_flat, W_fc2) + b_fc2)
#print (h fc1.get shape()) # => (40000, 1024)
```

Now the dropout layer is added. It is used to avoid overfitting as it sets input units to 0 with a frequency rate at each step during training of data.

```
keep_prob = tf.compat.v1.placeholder('float')
h_fc2_drop = tf.nn.dropout(h_fc2, keep_prob)
```

We define the readout layer for deep network.

```
W_fc3 = weight_variable([1536, labels_count])
b_fc3 = bias_variable([labels_count])
y = tf.nn.softmax(tf.matmul(h_fc2_drop, W_fc3) + b_fc3)
#print (y.get_shape()) # => (40000, 10)
```

Now, we set the learning rate which is a hyperparameter which shows how quickly the model adjusts to the given problem.

```
LEARNING RATE = 1e-4
```

The cost function, optimization function, evaluation and prediction function are defined below.

```
# cost function
cross_entropy = -tf.reduce_sum(y_*tf.compat.v1.log(y))
# optimisation function
train_step =
tf.compat.v1.train.AdamOptimizer(LEARNING_RATE).minimize(cross_entropy)
# evaluation
correct_prediction = tf.equal(tf.argmax(y,1), tf.argmax(y_,1))
accuracy = tf.reduce_mean(tf.cast(correct_prediction, 'float'))
# prediction function
#[0.1, 0.9, 0.2, 0.1, 0.1 0.3, 0.5, 0.1, 0.2, 0.3] => 1
predict = tf.argmax(y,1)
```

Now, we set the training iterations to 3000.

```
TRAINING_ITERATIONS = 3000
DROPOUT = 0.5
BATCH_SIZE = 50
```

The following function serves the data by batches. When all training data gets used, it is reordered randomly.

```
epochs completed = 0
index in epoch = 0
num examples = train images.shape[0]
# serve data by batches
def next batch(batch size):
   global train images
   global train labels
   global index in epoch
  global epochs_completed
   start = index in epoch
   index in epoch += batch size
   # when all trainig data have been already used, it is reorder randomly
  if index_in_epoch > num_examples:
       # finished epoch
       epochs completed += 1
       # shuffle the data
       perm = np.arange(num examples)
       np.random.shuffle(perm)
       train images = train images[perm]
       train labels = train labels[perm]
       # start next epoch
       start = 0
       index in epoch = batch size
       assert batch size <= num examples
 end = index in epoch
return train images[start:end], train labels[start:end]
```

We now start the TensorFlow session and initialize visualization variables.

```
# start TensorFlow session
init = tf.compat.v1.initialize_all_variables()
sess = tf.compat.v1.InteractiveSession()
sess.run(init)
# visualisation variables
train_accuracies = []
validation_accuracies = []
x_range = []
display_step=1
```

The following function checks progress on every 1st,2nd,...,10th,20th,...,100th... step and prints training and validation accuracy for each step.

```
for i in range(TRAINING ITERATIONS):
   #get new batch
   batch xs, batch ys = next batch(BATCH SIZE)
     # check progress on every 1st,2nd,...,10th,20th,...,100th... step
   if i%display step == 0 or (i+1) == TRAINING ITERATIONS:
        train accuracy = accuracy.eval(feed dict={x:batch xs,
                                                  y : batch ys,
                                                  keep prob: 1.0})
        if (VALIDATION SIZE):
            validation accuracy = accuracy.eval(feed_dict={ x:
validation images[0:BATCH SIZE],
validation labels[0:BATCH SIZE],
                                                            keep prob:
1.0})
           print('training_accuracy / validation_accuracy => %.2f / %.2f
for step %d'%(train accuracy, validation accuracy, i))
           validation accuracies.append(validation accuracy)
        else:
             print('training accuracy => %.4f for step
%d'%(train accuracy, i))
        train accuracies.append(train accuracy)
       x range.append(i)
        # increase display step
        if i%(display step*10) == 0 and i and display step<100:
           display step *= 10
    # train on batch
 sess.run(train step, feed dict={x: batch xs, y : batch ys, keep prob:
DROPOUT } )
```

Step 5: This step involves analyzing the results and visualizing it for the purpose of performance metrics.

First of all, we import the necessary libraries.

```
import seaborn as sns
from sklearn.metrics import accuracy_score
from sklearn.metrics import confusion_matrix
import itertools
```

The following function checks the accuracy on validation set.



Now we read the test data from csv file and extract the relevant information about data.

```
saver = tf.compat.v1.train.Saver(tf.compat.v1.all_variables())
saver.save(sess, 'my-model1', global_step=0)
# read test data from CSV file
test_data = data[data.Usage == "PublicTest"]
test_data.head()
len(test_data)
test_pixels_values = test_data.pixels.str.split(" ").tolist()
test_pixels_values = pd.DataFrame(test_pixels_values, dtype=int)
test_images = test_pixels_values.values
test_images = test_images.astype(np.float)
test_images = test_images - test_images.mean(axis=1).reshape(-1,1)
test_images = np.multiply(test_images,100.0/255.0)
test_images = np.divide(np.subtract(test_images,each_pixel_mean),
each_pixel_std)
```

We now predict the test set. Here, using batches is more resource efficient. We also get the confusion matrix of the same.

```
predicted lables = np.zeros(test images.shape[0])
for i in range(0,test images.shape[0]//BATCH SIZE):
   predicted lables[i*BATCH SIZE : (i+1)*BATCH SIZE]
predict.eval(feed dict={x: test images[i*BATCH SIZE
keep prob: 1.0})
test data.emotion.values
confusion matrix(test data.emotion.values, predicted lables)
array([[178,
              3, 43, 79, 89, 13, 62],
       [ 13, 17, 7, 3, 11, 0, 5],
       [ 47, 0, 158, 70, 104, 52,
       [ 39, 0, 22, 702, 45, 18, 69],
       [81, 1, 43, 121, 266, 13, 128],
       [ 21, 1, 30, 40, 14, 286, 23],
               0, 40, 119, 106, 10, 293]])
       39,
```

Confusion Matrix is also known as error matrix and is used as a performance metric for classification based models where the true values are already known. The following function prints and plots the confusion matrix. Normalization can be applied by setting `normalize=True`.

```
def plot confusion matrix(cm, classes,
                          normalize=False,
                          title='Confusion matrix',
                          cmap=plt.cm.Blues):
   plt.imshow(cm, interpolation='nearest', cmap=cmap)
   plt.title(title)
   plt.colorbar()
   tick marks = np.arange(len(classes))
   plt.xticks(tick marks, classes, rotation=45)
   plt.yticks(tick_marks, classes)
    if normalize:
       cm = cm.astype('float') / cm.sum(axis=1)[:, np.newaxis]
       print("Normalized confusion matrix")
   else:
       print('Confusion matrix, without normalization')
   print(cm)
```

plt.xlabel('Predicted label')

