

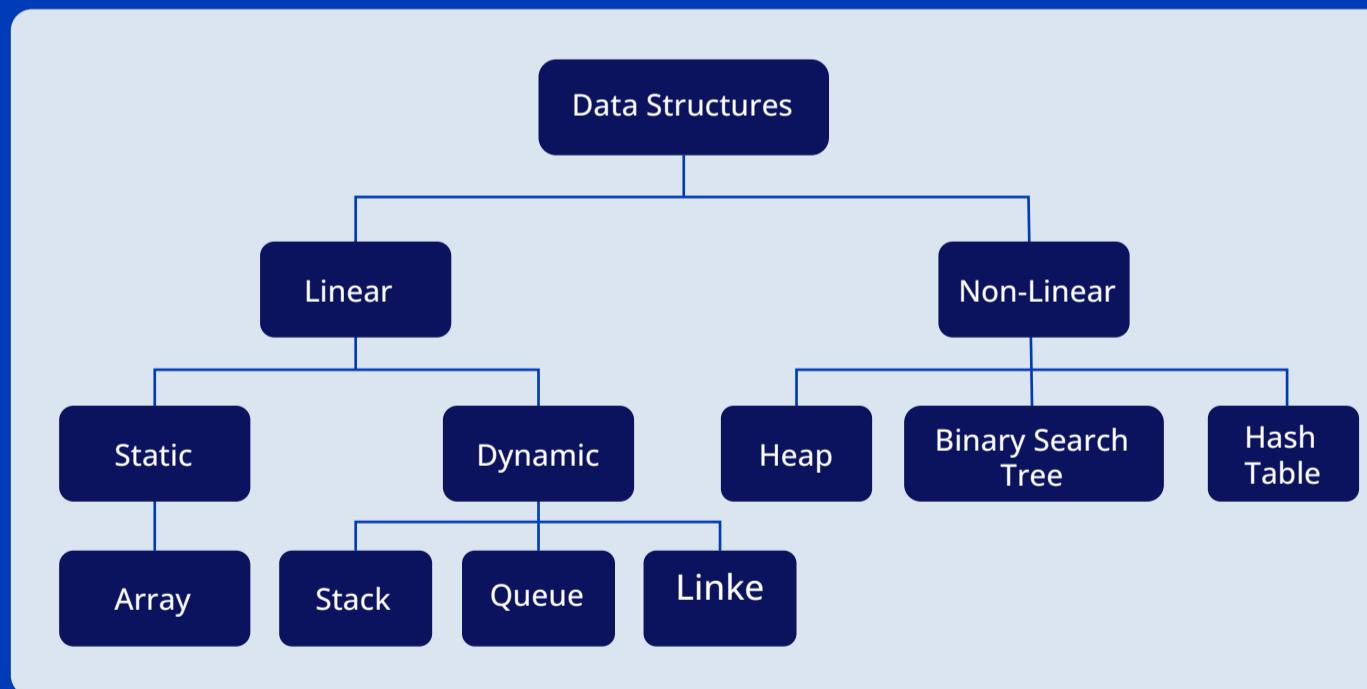
# 7 ESSENTIAL DATA STRUCTURES FOR CODING INTERVIEWS

1. Array
2. Linked List
3. Hash Table
4. Stack
5. Queue
6. Heap
7. Binary Search Tree

## What is a Data Structure?

A data structure organizes collections of data to store it efficiently to make the process of accessing or modifying the data easier.

## Data Structure Categories



## Time and Space Complexity

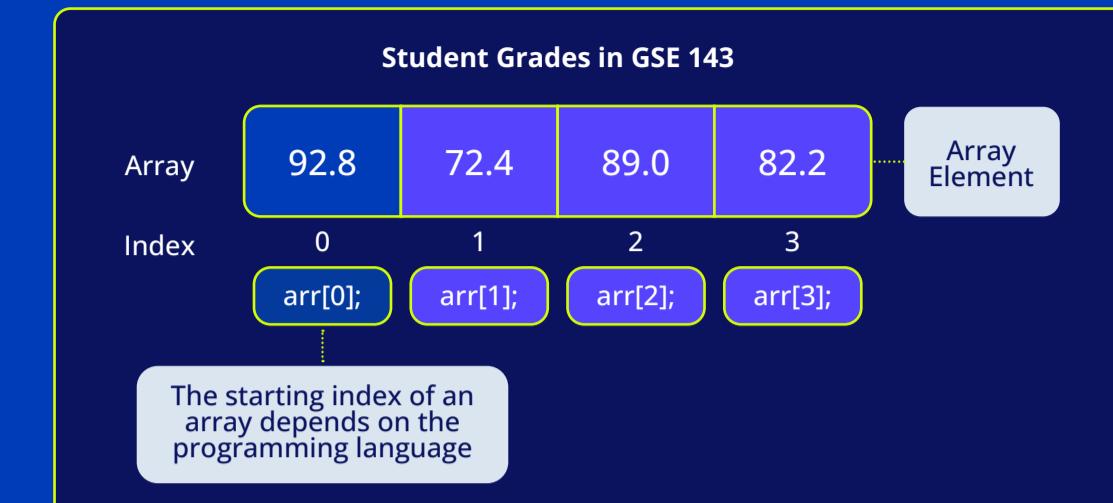
- **Time complexity:** The amount of time required to run an algorithm, corresponding to an input of a specific size not including the space taken by the input.

**Space complexity:** The amount of space required to run an algorithm, corresponding to an input of a specific size, not including the space taken by the input.

## Different types of complexities

Complexity	Performance	Type
O(1)	Best	Constant
O(log n)	Excellent	Logarithmic
O(n)	Good	Linear (Polynomial)
O(n log n)	Fair	Polynomial
O(n <sup>2</sup> )	Bad	Quadratic (Polynomial)
O(2n)	Poor	Exponential
O(n!)	Worst	Factorial

## Array example



Array Operations	Time Complexity (Average)	Time Complexity (Worst Case Scenario)	Space Complexity (Worst Case Scenario)
Search	$\theta(n)$	$O(n)$	$O(n)$
Insert	$\theta(n)$	$O(n)$	
Delete	$\theta(n)$	$O(n)$	

## Code example

```

// C++ code to print an array:
#include <iostream>
using namespace std;
// This function prints an array
void printArray(int *arr, int size)
{
    cout<<"The contents of the array are:\n";
    for(int i=0; i<size; i++)
        cout<<arr[i]<< " ";
    cout<<endl;
}
// Driver Code
int main()
{
    // Considering inputs given are valid
    int arr[5]={10,20,30,40,50};
    printArray(arr,5);
    return 0;
}
  
```

Code to print an array in C++

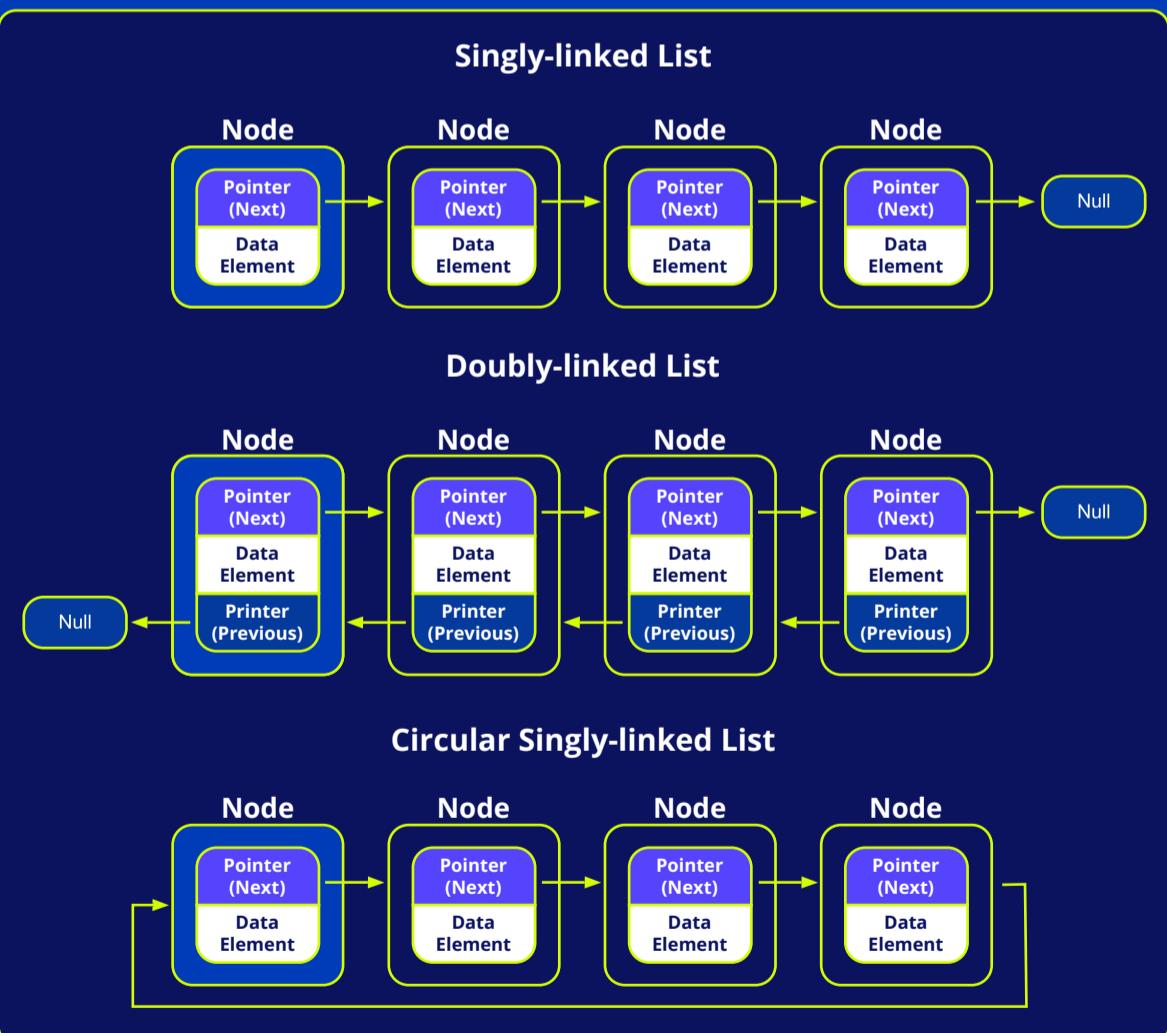


Pros	Cons
<ul style="list-style-type: none"> <li>Dynamic data structure: adding and deleting nodes is easier</li> <li>More efficient for data of arbitrary length whose size is not known in advance</li> <li>Can store data even when no contiguous memory is available</li> </ul>	<ul style="list-style-type: none"> <li>Retrieving nodes takes more time as it doesn't support direct access to individual elements via index positions in constant time</li> <li>Searching data is slow as techniques such as binary search cannot be employed</li> <li>Nodes with pointers use up some memory</li> </ul>

### Types of linked lists

- Singly-linked list:** Only allows forward navigation
- Doubly-linked list:** Allows forward and backward navigation  
Unlike a typical linked list, a doubly-linked list maintains two
- Circular linked list:** The node in this list has the next pointer to the first node

### Linked list example



Linked List * Operations	Time Complexity (Average)	Time Complexity (Worst Case Scenario)	Space Complexity (Worst Case Scenario)
Search	$\theta(n)$	$O(n)$	
Insert	$\theta(1)$	$O(1)$	
Delete	$\theta(n)$	$O(n)$	

Singly-Linked and Doubly-Linked

### 2. Linked list

A linked list is a linear data structure that stores data as a chain of nodes at non-contiguous memory locations linked together by pointers. Each node contains a data element and pointer to the next node.

- Data:** Heterogeneous data can be stored in each node
- Pointer:** It is used to store the address of the next node

#### Code Example

```
#include <iostream>
using namespace std;

// Making a node struct containing an int data and a pointer
// to next node
struct Node
{
    int data;
    Node *next;
    // Parameterised constructor with default argument
    Node(int val=0) :data(val),next(nullptr){}
    // Parameterise constructor
    Node(int val, Node *tempNext):data(val),next(tempNext){}
};

class LinkedList
{
    // Head pointer
    Node* head;
public:
    // default constructor. Initializing head pointer
    LinkedList():head(nullptr)
    {
    }

    // inserting elements (At start of the list)
    void insert(int val)
    {
        // make a new node
        Node *new_node = new Node(val);
        // If list is empty, make the new node, the head
        if (head == nullptr)
        {
            head = new_node;
        }
        // else, make the new_node the head and its next, the previous
        // head
        else
        {
            new_node->next = head;
            head = new_node;
        }
    }

    void display()
    {
        Node* temp = head;
        while(temp != nullptr)
        {
            cout << temp->data << " ";
            temp = temp->next;
        }
        cout << endl;
    }
};

int main()
{
    LinkedList l;
    // inserting elements
    l.insert(6);
    l.insert(9);
    l.insert(1);
    l.insert(3);
    l.insert(7);
    cout << "Current Linked List: ";
    l.display();
}
```

Linked list class in C++

```
# A single node of a singly linked list
class Node:
    # constructor
    def __init__(self, data=None, next=None):
        self.data = data
        self.next = next
```

```
# A Linked List class with a single head node
class LinkedList:
    def __init__(self):
        self.head = None
```

```
# insertion method for the linked list
def insert(self, data):
    newNode = Node(data)
    if self.head:
        current = self.head
        while current.next:
            current = current.next
        current.next = newNode
    else:
        self.head = newNode
```

```
# print method for the linked list
def printLL(self):
    current = self.head
    while(current):
        print(current.data)
        current = current.next
```

```
# Singly Linked List with insertion and print methods
LL = LinkedList()
LL.insert(6)
LL.insert(9)
LL.insert(1)
LL.insert(3)
LL.insert(7)
LL.printLL()
```

Linked list class in Python

### 3. Hash table

A **hash table** is an **unordered** collection of **key-value pairs** where a **hash key** is mapped to a **hash value** (data element), typically as an array of linked lists. A hash function takes arbitrary-length data as an input and generates a fixed-length output. The output is the **hash key** of the given data. A value is stored at a location based on its hash key. This process is known as **hashing**.

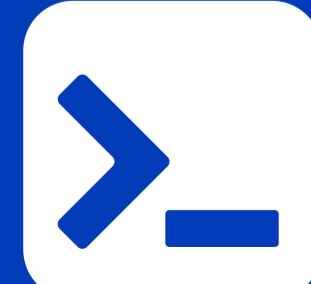
#### In summary

**Hash function:** Takes an arbitrary length input and produces a fixed-length output

**Hash value:** Input of a hash function

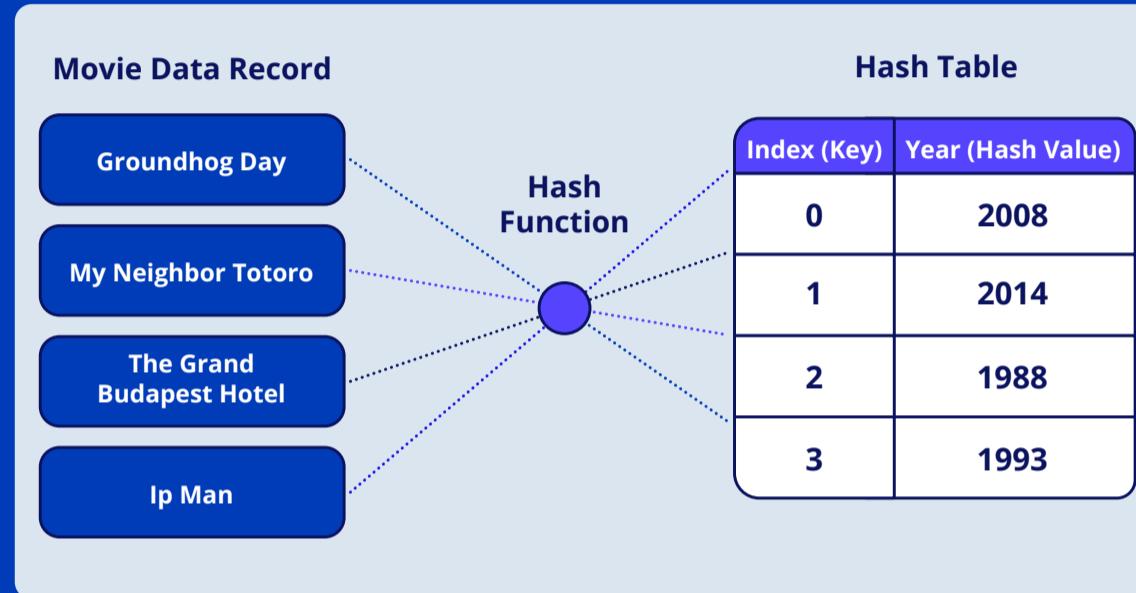
**Hash key:** Output of a hash function

If the hash function generates the same hash keys for multiple hash values, then a conflict known as a hash collision occurs, where two pieces of data in a hash table share the same hash value.



Pros	Cons
<ul style="list-style-type: none"> <li>Constant time lookup, insertion and deletion (as long as there is no hash collision)</li> <li>May store heterogeneous data</li> </ul>	<ul style="list-style-type: none"> <li>Complex to implement</li> <li>Hash collisions can cause performance issues when accessing or searching items in a hash table</li> <li>Hash keys require some extra computational</li> </ul>

## Hash table example



Hash Table Operations	Time Complexity (Average)	Time Complexity (Worst Case Scenario)	Space Complexity (Worst Case Scenario)
Search	$\theta(1)$	$O(n)$	
Insert	$\theta(1)$	$O(n)$	
Delete	$\theta(1)$	$O(n)$	

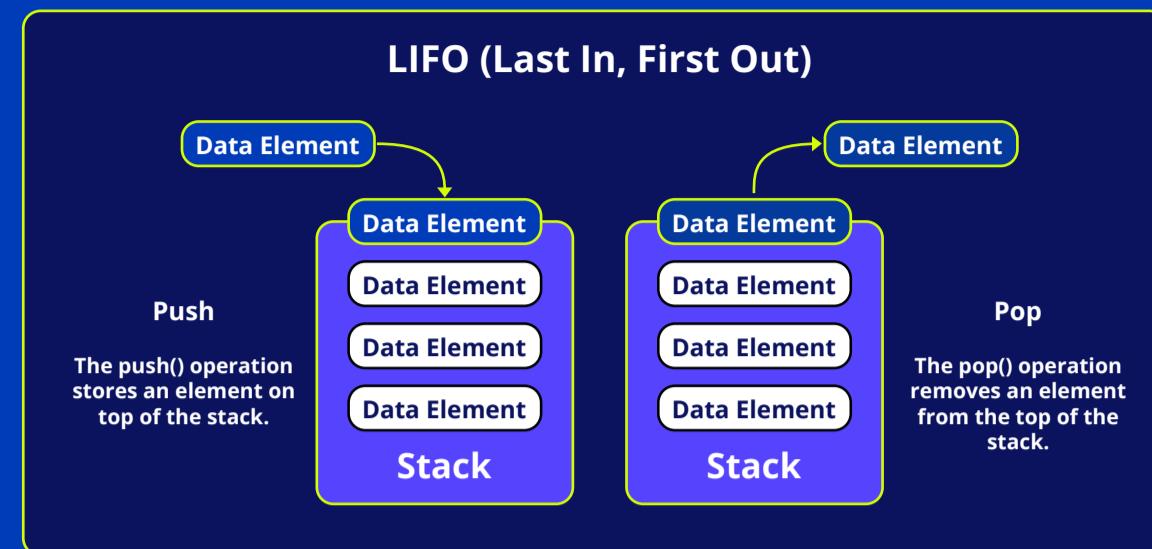
## 4. Stack

**Stack** and **queue** data structures are often mentioned in the same breath because of their similar characteristics, but they behave differently when adding or removing data.

**Stacks** store elements in a Last-In, First-Out (LIFO) order, meaning that the last element added to the stack is the first one removed.

Pros	Cons
<ul style="list-style-type: none"> <li>Great for depth-first search (DFS)</li> <li>Efficient addition/removal of items</li> <li>Used in recursive function calls and also by the call-stack of programming languages</li> </ul>	<ul style="list-style-type: none"> <li>Limited use cases compared to some other data structures</li> </ul>

## Stack example



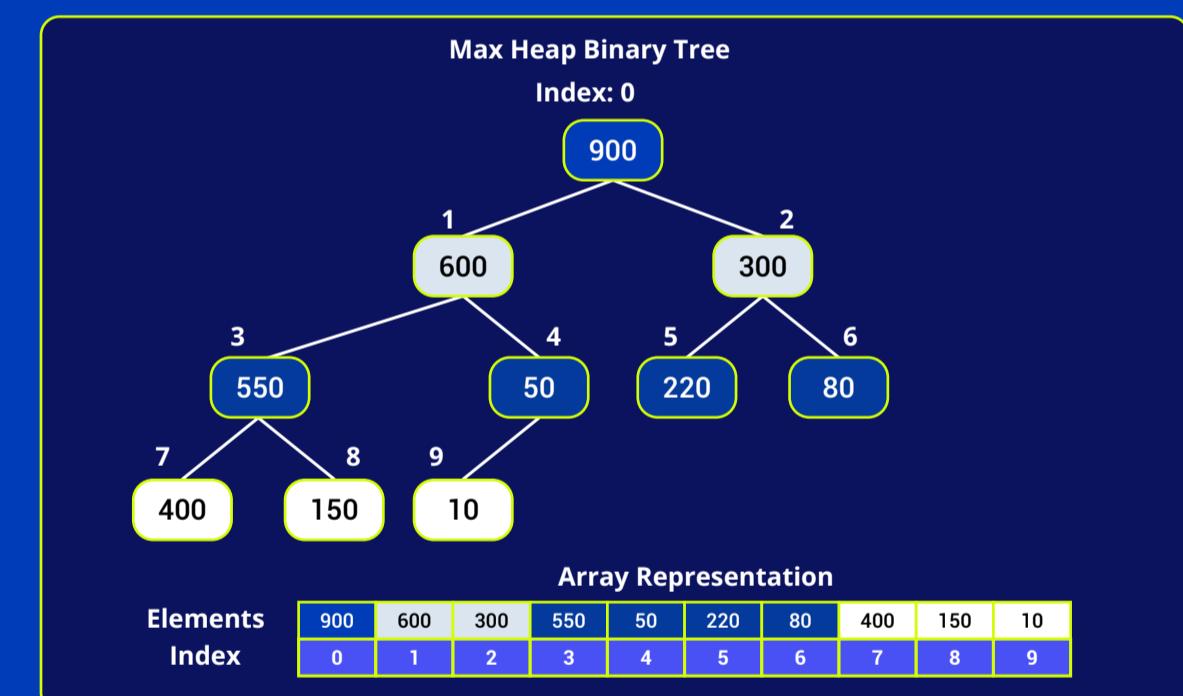
## 6. Heap

A **heap** is a complete binary tree where each node is associated with a key that satisfies a **heap property**. Heap data structures are particularly useful for finding the minimum or maximum value in a data set, and are effectively used as priority queues.

**Max Heap Property:** In the case of a **max heap**, the key of a parent node must be **greater than or equal to** the key of the child node.

**Min Heap Property:** In the case of a **min heap**, the key of a parent node must be **less than or equal to** the key of the child node.

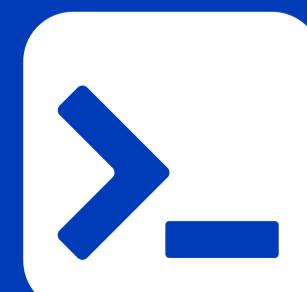
Pros	Cons
<ul style="list-style-type: none"> <li>Time complexity of insertion or deletion is just <math>O(\log n)</math></li> <li>A binary heap is a complete binary tree</li> <li>Simple to implement, can be done with just an array</li> </ul>	<ul style="list-style-type: none"> <li>Not the best data structure to traverse or search data</li> </ul>

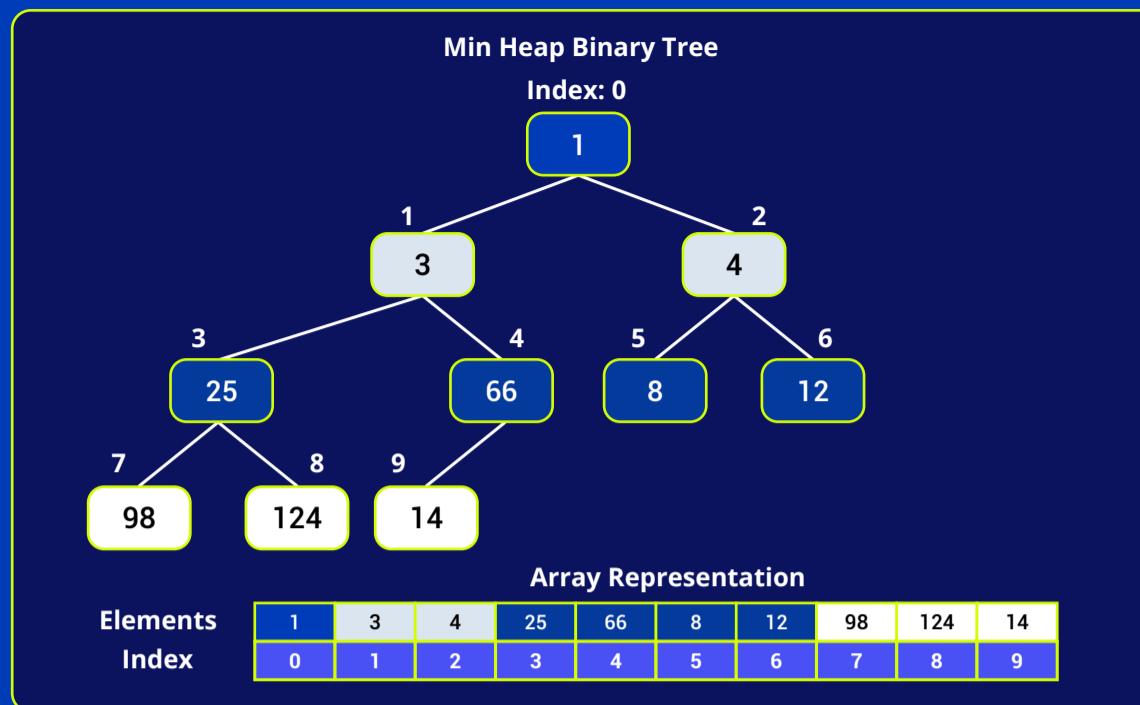


## Queue example



Queue Operations	Time Complexity (Average)	Time Complexity (Worst Case Scenario)	Space Complexity (Worst Case Scenario)
Search	$\theta(n)$	$O(n)$	
Insert	$\theta(1)$	$O(1)$	$O(n)$
Delete	$\theta(1)$	$O(1)$	





Heap Operations	Time Complexity (Average)	Time Complexity (Worst Case Scenario)	Space Complexity (Worst Case Scenario)
Search	$\theta(n)$	$O(n)$	$O(\log n)$
Insert	$\theta(\log n)$	$O(\log n)$	
Delete	$\theta(\log n)$	$O(\log n)$	

## Application of Heap Data Structures

- Priority queues
- Heapsort
- Order statistics

## 7. Binary Search Trees

**Binary search trees (BST)** are non-linear data structures that store data elements in nodes. Each node contains one or more data items and two pointers that branch off to child nodes called the **left child** and the **right child**.

- The key of the left child must be less than or equal to the key of the parent node.
- The key of the right child must be greater than the key of the parent node.

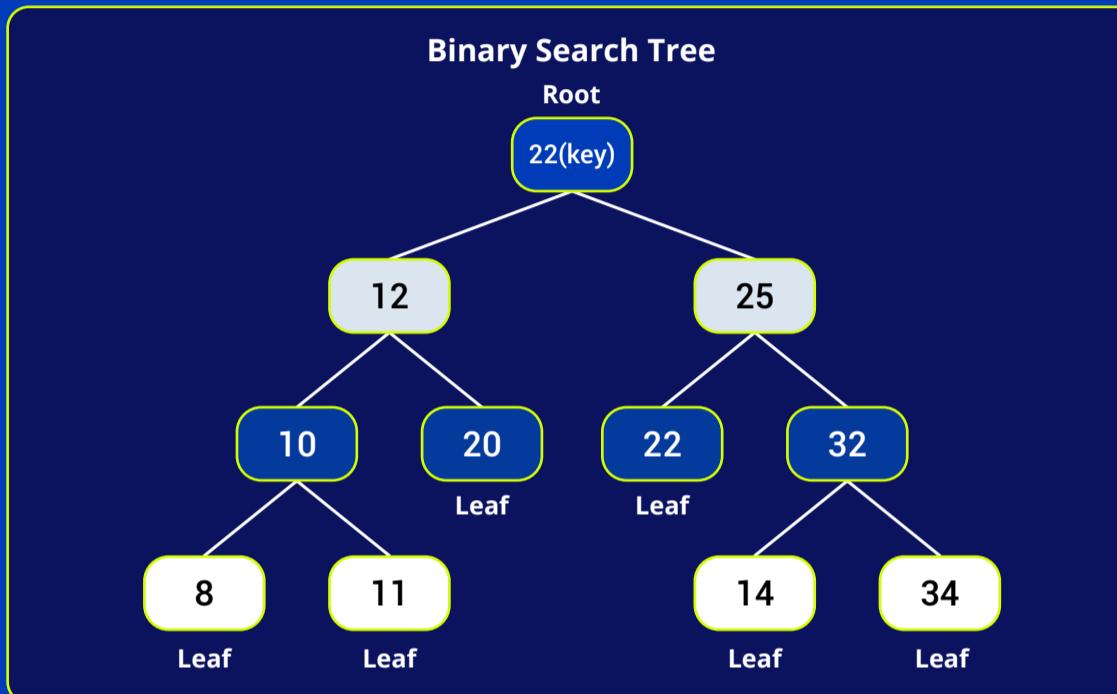
This allows you to use relational operators to efficiently find items in a binary search tree.

That is, we compare a key ( $x$ ) stored in a node  $x$  with the value to search  $y$ , using the following three conditions:

1. When  $x$  is equal to  $y$ ,  $x==y$ , end the search
2. When  $x$  is less than or equal to  $y$ ,  $x\leq y$ , go to the right child
3. When  $x$  is greater than  $y$ ,  $x>y$ , go to the left child

Pros	Cons
<ul style="list-style-type: none"> <li>○ Insertion and deletion can be fast and efficient</li> <li>○ Supports range queries - Relatively simple compared to other data structures</li> <li>○ Easy to implement</li> </ul>	<ul style="list-style-type: none"> <li>○ Implementing a balanced binary search tree is necessary to avoid degradation of performance</li> <li>○ Accessing elements from a BST is slower than in an array</li> </ul>

## Binary search tree example



Binary Search Tree Operations	Time Complexity (Average)	Time Complexity (Worst Case Scenario)	Space Complexity (Worst Case Scenario)
Search	$\theta(\log n)$	$O(n)$	
Insert	$\theta(\log n)$	$O(n)$	$O(n)$
Delete	$\theta(\log n)$	$O(n)$	

A key issue with BST is that they are not self-balancing hence leading to compromised time-complexity. To mitigate this, several self-balancing BST variants can be used, such as **AVL Trees** and **Red Black Trees**.

## Advanced Data Structures

We've covered 7 essential data structures that every developer should learn.

Some advanced data structures that software engineers can get familiar with include:

1. Tries
2. Self-Balancing BSTs
3. Disjoint Sets
4. Segment Trees
5. Queaps
6. Binary Indexed Trees
7. Succinct Data Structures

