

5/11/21

VECTOR CALCULUS

Vector field:

Def: Let R be a region in the xy plane. A vector field F assigns to every point (x, y) in R a vector $F(x, y)$ with two components

$$F(x, y) = M(x, y) \mathbf{i} + N(x, y) \mathbf{j}$$

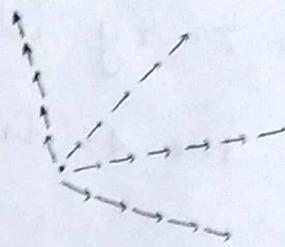
$$F(x, y, z) = M(x, y, z) \mathbf{i} + N(x, y, z) \mathbf{j} + P(x, y, z) \mathbf{k}$$

Ex: Position vector at (x, y) is

$$\mathbf{R} = x\mathbf{i} + y\mathbf{j}$$

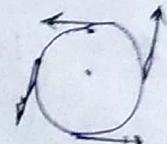
$$|\mathbf{R}| = r = \sqrt{x^2 + y^2}$$

$$\frac{|\mathbf{R}|}{r} = \frac{x}{r}\mathbf{i} + \frac{y}{r}\mathbf{j}$$



Ex: Spin field or rotation field or turning field

$$\mathbf{s} = -y\mathbf{i} + x\mathbf{j} \quad |s| = r$$



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Directional Derivatives

$$f(x, y)$$

$\frac{\partial f}{\partial x} \rightarrow$ keeps y constant and provides slope in x direction.

$\frac{\partial f}{\partial y} \rightarrow x$ constant & gives slope in y direction

Many other directions are possible, such as 45° line

Given $f(x,y)$ around $P(x_0, y_0)$ and a direction \vec{u} (unit vector) Find the derivative of f in the direction of \vec{u}

$$45^\circ \rightarrow \vec{u} = \frac{i}{\sqrt{2}} + \frac{j}{\sqrt{2}}$$

Ex1 $z = xy$ when (x,y) moves a ^{distance} ~~direction~~ as in the 45° direction from $(1,1)$ what is $\frac{\Delta z}{\Delta s}$

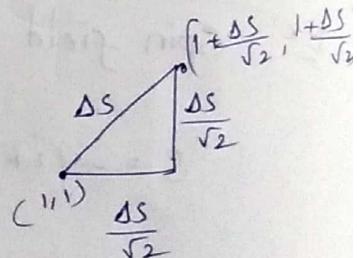
Soln: The step is Δs times unit vector \vec{u} starting from $x=y=1$, the step ends at $x=y=1 + \frac{\Delta s}{\sqrt{2}}$

$z = xy$ is then

$$z = \left(1 + \frac{\Delta s}{\sqrt{2}}\right)^2$$

$$= 1 + \sqrt{2} \Delta s + \frac{1}{2} (\Delta s)^2$$

$$\Delta z = \sqrt{2} \Delta s + \frac{1}{2} (\Delta s)^2$$



$$\frac{\Delta z}{\Delta s} \rightarrow \sqrt{2} \text{ as } \Delta s \rightarrow 0 \text{ (slope in } 45^\circ \text{ direction)}$$

Defⁿ: The derivative of f in the direction \vec{u} at the point P is

$$D_u f(P) = \lim_{\Delta s \rightarrow 0} \frac{\Delta f}{\Delta s} = \lim_{\Delta s \rightarrow 0} \frac{f(P + \vec{u} \Delta s) - f(P)}{\Delta s}$$

↓
Directional derivative

in the direction u of the function f at point P

$$\vec{u} = u_1 i + u_2 j$$

↑
unit
vector

$$P(x_0, y_0) \quad \text{step } \Delta s \rightarrow Q(x_0 + u_1 \Delta s, y_0 + u_2 \Delta s)$$

$$u = (1, 0) \quad Q \rightarrow (x_0 + \Delta s, y_0)$$

$$D_{(1,0)} f = \frac{\partial f}{\partial x}$$

$$\lim_{\Delta s \rightarrow 0} \frac{\Delta f}{\Delta s} \rightarrow \frac{\partial f}{\partial x}$$

The directional derivative $D_u f$ in the direction

$\vec{u} = (u_1, u_2)$ equals $D_u f = \frac{\partial f}{\partial x} u_1 + \frac{\partial f}{\partial y} u_2$

$(u_1 i + u_2 j)$

Slopes in all directions are known from slopes in two directions.

Ex. $f = xy$ and $P = (1, 1)$ and $u = (\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}})$. Find

$$D_u f(P)$$

Sol $f_x = y$, $f_y = x$ Both equal to 1 at P .

$$D_u f(P) = f_x u_1 + f_y u_2 \\ = 1\left(\frac{1}{\sqrt{2}}\right) + 1\left(\frac{1}{\sqrt{2}}\right) = \sqrt{2} \text{ as } \cancel{\text{stop}} \text{ before}$$

* Directional derivative of a scalar function gives scalar values.

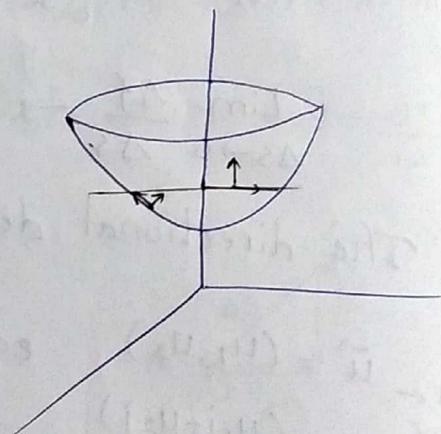
Ex 3 $f = 3x + y + 1$

Slope in (u_1, u_2) direction

$$D_u f = 3u_1 + u_2$$

Slope in x direction $\rightarrow D_{(1,0)}f = 3$

In which direction slope is maximum?



Gradient:

The direction of the gradient vector is the direction of maximum slope

$$\Delta f = f_x u_1 + f_y u_2$$

$$(u_1, u_2) \cdot (f_x, f_y)$$

↓
direction

↓
Gradient vector

Gradient vector

$$[f_x i + f_y j]$$

Defⁿ The gradient $f(x,y)$ is the vector whose components are $\frac{\partial f}{\partial x}$ and $\frac{\partial f}{\partial y}$.

$$\text{grad } f = \nabla f = \frac{\partial f}{\partial x} i + \frac{\partial f}{\partial y} j \quad (\text{Add } \frac{\partial f}{\partial z} k \text{ in 3D})$$

↑
Nyabla/
Gradient

Gradient of a function is a vector quantity

But function is scalar.

For plane $3x+y+1$, the gradient is constant vector $(3,1)$

If the way to climb the plane

$$\text{Consider } f = x^2 + xy$$

$$\nabla f = (2x + y, x)$$

Gradient is in the xy plane and tells us which way on the surface is up (steepest ascent)

The directional derivative is $D_u f = (\text{grad } f) \cdot \vec{u}$

The steepest slope $D_u f$ is largest when \vec{u} is parallel to $\text{grad } f$.

The maximum slope (steepness) is the length

$$|\text{grad } f| = \sqrt{f_x^2 + f_y^2} \quad (\text{ste})$$

$$u = \frac{\nabla f}{|\nabla f|}, \text{ the slope is } \nabla f \cdot \vec{u} = \frac{|\nabla f|^2}{|\nabla f|} = |\nabla f|$$

$$\underline{\text{Ex3}} \quad f(x, y) = 3x + y + 1$$

$$\nabla f = (3, 1)$$

Its the steepest slope is in the direction

$$\vec{u} = \left(\frac{3}{\sqrt{10}}, \frac{1}{\sqrt{10}} \right)$$

The maximum slope is $|\nabla f| = \sqrt{10}$

Divergence:

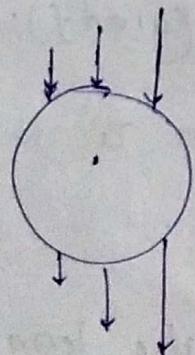
Defined on vector field

$$F(x, y, z) = P \hat{i} + Q \hat{j} + R \hat{k}$$

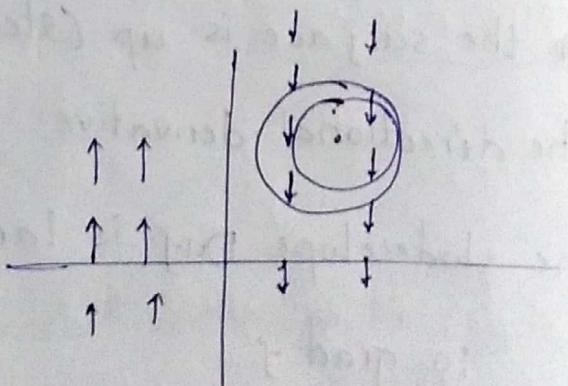
$$\nabla = \frac{\partial}{\partial x} \hat{i} + \frac{\partial}{\partial y} \hat{j} + \frac{\partial}{\partial z} \hat{k}$$

$$\text{Div } F = \nabla \cdot F = \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z} \rightarrow \text{scalar}$$

$$\underline{\text{Ex:}} \quad F(x, y, z) = -x \hat{j}$$



$$\begin{aligned} P &= 0 \\ Q &= -x \\ R &= 0 \end{aligned}$$



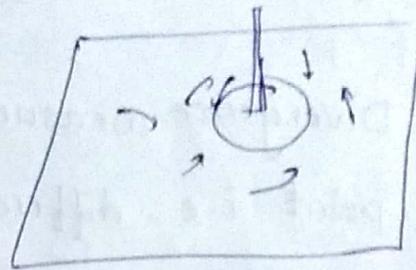
$$\begin{aligned} \text{Div } F &= \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z} \\ &= 0 + 0 + 0 \\ &= 0 \end{aligned}$$

- If inflow = outflow divergence = 0
 inflow > outflow divergence < 0
 inflow < outflow divergence > 0

Curl:

The measurement of rotation of the vector \vec{f} in the neighbourhood of P.

curl(\vec{f}) at P, then the paddle would rotate counter clockwise



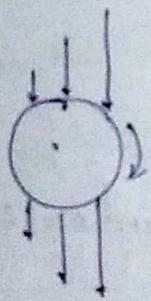
curl < 0 → anticlockwise

curl > 0 → anticlockwise

curl = 0 → no rotation.

$$\text{curl } \vec{F} = \nabla \times \vec{F}$$

$$= \begin{vmatrix} i & j & k \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ P & Q & R \end{vmatrix}$$



→ spins clockwise
since vector increasing as we go right

curl < 0

$$\vec{F} = -xj, P=0, Q=-x, R=0$$

$$\vec{F} = \begin{vmatrix} i & j & k \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 0 & -x & 0 \end{vmatrix} = -\hat{k}$$

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Operator	Symbol	Field taken as input	Output Field
Gradient	∇	scalar	vector
Divergence	$\nabla \cdot (\vec{F})$	vector	scalar
Curl	$\nabla \times (\text{curl})$	vector	vector

Divergence measures "Spreading" of \vec{F} around a point i.e., difference between the amount of \vec{F} existing from an infinitesimally small ball around the point and the amount entering it.

The curl is in some way a measure of "rotation" of the field. If we imagine to place a microscopic paddle wheel at a point in fluid moving with velocity \vec{F} , will it rotate or not?

Ex: $F(x, y, z) = \frac{x}{\sqrt{x^2+y^2}} i + \frac{y}{\sqrt{x^2+y^2}} j$

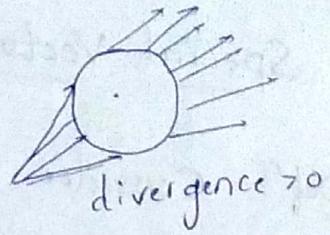
Find divergence and curl.

* curl is only defined on 3 dimensional coordinates.

$$\begin{aligned} \text{Div } \vec{F} &= \vec{\nabla} \cdot \vec{F} = \frac{\partial}{\partial x} \left[\frac{x}{\sqrt{x^2+y^2}} \right] + \frac{\partial}{\partial y} \left[\frac{y}{\sqrt{x^2+y^2}} \right] + \frac{\partial}{\partial z} [0] \\ &= \frac{1}{\sqrt{x^2+y^2}} > 0 \end{aligned}$$

$$\text{curl}(\vec{F}) = \vec{\nabla} \times \vec{F}$$

$$= \begin{vmatrix} i & j & k \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \frac{x}{\sqrt{x^2+y^2}} & \frac{y}{\sqrt{x^2+y^2}} & 0 \end{vmatrix}$$



$$= (0-0)i - (0-0)j + \left[-\frac{1}{2}(2x)y(x^2+y^2)^{-3/2} - \left(-\frac{1}{2}2y\right)x(x^2+y^2)^{-3/2} \right] \\ = 0$$

Laplacian Operator

The Laplacian Δf ($\nabla^2 f$) of a scalar field is obtained by $\Delta f = \nabla^2 f = \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2}$

[Trace of Hessian matrix]

A scalar field whose laplacian vanishes everywhere is called harmonic function.

A vector laplacian $\vec{\Delta}$ is the laplacian operator applied componentwise to vectorfields \vec{F}

$$\vec{\Delta} \vec{F} = (\Delta F_1)i + (\Delta F_2)j + (\Delta F_3)k$$

Ex: $f = x^2 - y^2$ Compute the Laplacian

$$\Delta f = 2 - 2 = 0$$

Special Vector field and potentials:

Defn: Consider a vector field \vec{F} defined on DCR^3

If $\vec{\nabla} \times \vec{F} = \vec{0}$, then \vec{F} is called irrotational (or curl free)

If $\vec{\nabla} \cdot \vec{F} = 0$, then \vec{F} is called solenoidal (or divergence free
or incompressible) +

If $\vec{F} = \vec{\nabla} \phi$ for some field ϕ , then \vec{F} is called
conservative and ϕ is called scalar potential of \vec{F}

If $\vec{F} = \vec{\nabla} \times \vec{A}$ for some vector field \vec{A} then \vec{A} is
called vector potential of \vec{F}

$$\text{Ex: } \vec{F} = 2x\mathbf{i} - 2y\mathbf{j}$$

Is \vec{F} irrotational or solenoidal?

Is \vec{F} conservative?

$$\vec{\nabla} = 2\mathbf{i} - 2\mathbf{j}$$

$$\vec{\nabla} \cdot \vec{F} = \frac{\partial F_x}{\partial x} + \frac{\partial F_y}{\partial y} + \frac{\partial F_z}{\partial z} = 2 - 2 + 0 = 0 \quad [\text{solenoidal}]$$

$$\vec{\nabla} \times \vec{F} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 2x & -2y & 0 \end{vmatrix} = 0 \quad [\text{irrotational}]$$

$$\vec{F} = \vec{\nabla} (x^2 - y^2) = \vec{\nabla} \times (2xy\mathbf{k})$$

\vec{F} admit both scalar and vector potentials
so is conservative.

Ex 2 $\vec{G} = yz\mathbf{i} + xz\mathbf{j} + xy\mathbf{k}$

$$P = yz \quad Q = xz \quad R = xy$$

$$\nabla \cdot \vec{F} = \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z}$$

$$\nabla \cdot \vec{F} = 0 \quad [\text{solenoidal}]$$

$$\vec{\nabla} \times \vec{F} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ yz & xz & xy \end{vmatrix}$$

$$= \mathbf{i}(x - x) - \mathbf{j}(y - y) + \mathbf{k}(z - z)$$
$$= 0 \quad [\text{irrotational}]$$

$$\vec{G} = \vec{\nabla} (xyz\mathbf{i} + xyz\mathbf{j} + xyz\mathbf{k})$$

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Identities (Vector-differential)

Let f be a scalar field and \vec{F} be a vector field both defined in a domain $D \subset \mathbb{R}^3$. Then the following identities hold true:

i) $\vec{\nabla} \cdot (\vec{\nabla} f) = \Delta f$ (Divergence of $\text{grad } f$ is Laplacian)

$$\vec{\nabla} \cdot (\vec{\nabla} f) = \frac{\partial (\vec{\nabla} f)_1}{\partial x} + \frac{\partial (\vec{\nabla} f)_2}{\partial y} + \frac{\partial (\vec{\nabla} f)_3}{\partial z}$$

$$[\vec{\nabla} f = (\nabla f)_1 \mathbf{i} + (\nabla f)_2 \mathbf{j} + (\nabla f)_3 \mathbf{k}]$$

$$= \frac{\partial}{\partial x} \frac{\partial f}{\partial x} + \frac{\partial}{\partial y} \frac{\partial f}{\partial y} + \frac{\partial}{\partial z} \frac{\partial f}{\partial z}$$

$$\vec{\nabla} \cdot (\vec{\nabla} f) = \Delta f$$

ii) $\vec{\nabla} \cdot (\vec{\nabla} \times \vec{F}) = 0$ (Divergence of $\text{curl } f$ is zero)

$$\vec{\nabla} \cdot (\vec{\nabla} \times \vec{F}) = \frac{\partial ((\nabla \times \vec{F})_1)}{\partial x} + \frac{\partial ((\nabla \times \vec{F})_2)}{\partial y} + \frac{\partial ((\nabla \times \vec{F})_3)}{\partial z}$$

$$= \frac{\partial \left(\frac{\partial F_3}{\partial y} - \frac{\partial F_2}{\partial z} \right)}{\partial x} + \frac{\partial \left(\frac{\partial F_1}{\partial z} - \frac{\partial F_3}{\partial x} \right)}{\partial y} + \frac{\partial \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right)}{\partial z}$$

$$= \frac{\partial^2 F_1}{\partial y \partial z} - \frac{\partial^2 F_1}{\partial z \partial y} + \dots$$

$$= 0$$

$$\text{iii) } \vec{\nabla} \times (\vec{\nabla} f) = \vec{0}$$

curl of grad f is zero vector

$$\begin{aligned} (\vec{\nabla} \times (\vec{\nabla} f))_1 &= \frac{\partial(\nabla f)_3}{\partial y} - \frac{\partial(\nabla f)_2}{\partial z} \\ &= \frac{\partial}{\partial y} \left(\frac{\partial f}{\partial z} \right) - \frac{\partial}{\partial z} \left(\frac{\partial f}{\partial y} \right) \\ &= 0 \end{aligned}$$

similar to other components too.

$$\text{iv) } \vec{\nabla} \times (\vec{\nabla} \times \vec{F}) = \vec{\nabla} (\vec{\nabla} \cdot \vec{F}) - \vec{\Delta} \vec{F}$$

Vector differential identities for two fields,

product rules for differential operators

Let f & g be scalar fields, \vec{F} & \vec{G} be vector fields, all defined in $D \subset \mathbb{R}^3$. Then the following identities hold true.

$$\vec{\nabla}(fg) = f \vec{\nabla} g + g \vec{\nabla} f$$

$$\vec{\nabla} \cdot (\vec{F} \times \vec{G}) = (\vec{\nabla} \times \vec{F}) \cdot \vec{G} - \vec{F} \cdot (\vec{\nabla} \times \vec{G})$$

$$\vec{\Delta}(fg) = (\vec{\Delta}f)g + 2 \vec{\nabla}f \cdot \vec{\nabla}g + f (\vec{\Delta}g)$$

Note:

1. From the definition of the curl operator, we note

that \vec{F} is irrotational precisely when

$$\frac{\partial F_2}{\partial z} = \frac{\partial F_3}{\partial y}, \quad \frac{\partial F_3}{\partial x} = \frac{\partial F_1}{\partial z} \quad \text{and} \quad \frac{\partial F_1}{\partial y} = \frac{\partial F_2}{\partial x}$$

2. If \vec{F} admits a scalar or a vector potential, then the potential is not unique for all constant scalars $\lambda \in \mathbb{R}$ and for all scalar fields g

$$\text{if } \vec{F} = \vec{\nabla} \phi \text{ then } \vec{F} = \vec{\nabla} (\phi + \lambda)$$

$$\text{if } \vec{G} = \vec{\nabla} \times \vec{A} \text{ then } \vec{G} = \vec{\nabla} \times (\vec{A} + \vec{\nabla} g)$$

Ex: Consider the field $\vec{F} = z\hat{i} + x\hat{k}$

it is irrotational and solenoidal.

If ϕ is a scalar potential of \vec{F}

$$\vec{F} = \vec{\nabla} \phi \Rightarrow \frac{\partial \phi}{\partial x} = z \Rightarrow \phi = xz + f(y, z)$$

$$\frac{\partial \phi}{\partial y} = 0 \Rightarrow \frac{\partial (xz + f(y, z))}{\partial y} = \frac{\partial f(y, z)}{\partial y} = 0$$

$$\Rightarrow \phi = xz + g(z)$$

$$\frac{\partial \phi}{\partial z} = x \Rightarrow \frac{\partial (xz + g(z))}{\partial z} = x + \frac{\partial g(z)}{\partial z} = x$$

$$\Rightarrow \phi = xz + \lambda$$

So for every real constant λ , the fields

$xz + \lambda$ are scalar potentials of \vec{F} .

$$\vec{F} = z\hat{i} + x\hat{k}$$

$$\vec{F} = \vec{\nabla} \times \vec{A}$$

$$\text{Let } \vec{A} = A_1 \hat{i} + A_2 \hat{j} + A_3 \hat{k}$$

$$\frac{\partial A_3}{\partial y} - \frac{\partial A_2}{\partial z} = z$$

$$\frac{\partial A_1}{\partial z} - \frac{\partial A_3}{\partial x} = 0$$

$$\frac{\partial A_2}{\partial x} - \frac{\partial A_1}{\partial y} = x$$

Many choices for \vec{A}

$$\vec{A}_1 = \vec{0} = \vec{A}_3$$

$$\frac{\partial A_2}{\partial z} = -z \rightarrow ①$$

$$\frac{\partial A_2}{\partial x} = x \rightarrow ② \Rightarrow A_2 = \frac{x^2}{2} + b(z)$$

$$A_2 = \frac{x^2}{2} - \frac{z^2}{2}$$

$$① \Rightarrow \frac{\partial \left(\frac{x^2}{2} + b(z) \right)}{\partial z} = -z$$

$$\frac{\partial b(z)}{\partial z} = -z$$

$$b(z) = -\frac{z^2}{2}$$

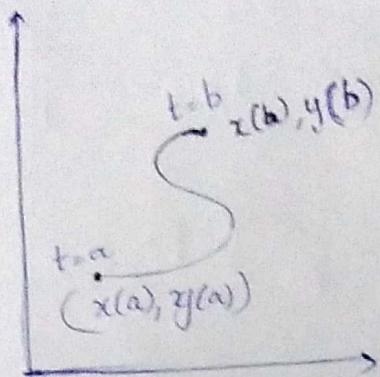
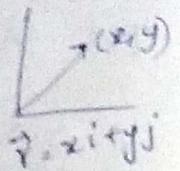
$\vec{\nabla} \times (\vec{\nabla} \phi) = \vec{0}$

$$\vec{\nabla} \cdot (\vec{\nabla} \times \vec{A}) = 0$$

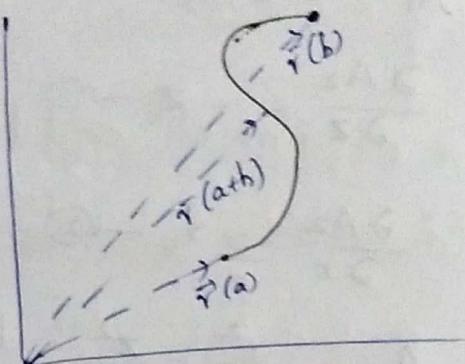
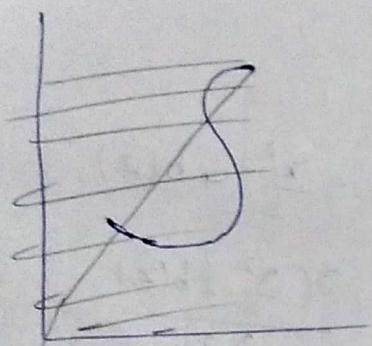
All conservative fields are irrotational.

All fields admitting a vector potential are solenoidal.

Position Vector:



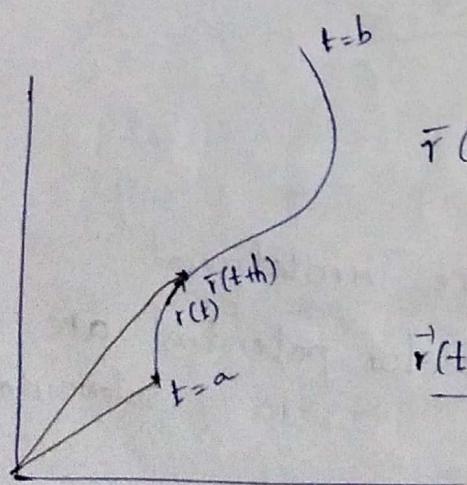
$$\text{Curve } C: \begin{aligned} x &= x(t) \\ y &= y(t) \end{aligned} \quad a \leq t \leq b$$



$$\vec{r}(t) = x(t)\mathbf{i} + y(t)\mathbf{j} \quad a \leq t \leq b$$

$$\vec{r}(a) = x(a)\mathbf{i} + y(a)\mathbf{j}$$

$$\vec{r}(a+h) = x(a+h)\mathbf{i} + y(a+h)\mathbf{j}$$



$$\vec{r}(t+h) - \vec{r}(t)$$

$$= x(t+h)\mathbf{i} + y(t+h)\mathbf{j} - (x(t)\mathbf{i} + y(t)\mathbf{j})$$

$$\frac{\vec{r}(t+h) - \vec{r}(t)}{h} = \frac{x(t+h) - x(t)}{h}\mathbf{i} + \frac{y(t+h) - y(t)}{h}\mathbf{j}$$

$$h \leftrightarrow \Delta t$$

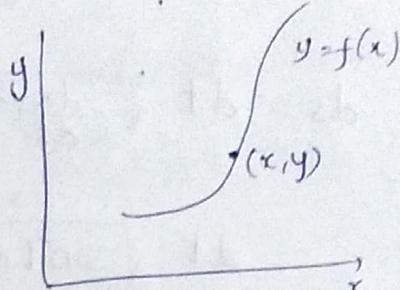
$$\lim_{h \rightarrow 0} \rightarrow \vec{r}'(t) \text{ or } \frac{d\vec{r}}{dt} = \frac{dx}{dt} \mathbf{i} + \frac{dy}{dt} \mathbf{j}$$

Displacement vector along the curve

$$d\vec{s} = dx \mathbf{i} + dy \mathbf{j}$$

$$ds = |d\vec{s}| = \sqrt{(dx)^2 + (dy)^2}$$

$$y = f(x) \quad \frac{ds}{dx} = \sqrt{1 + \left(\frac{dy}{dx}\right)^2}$$



Parametric form $(x(t), y(t))$

$$\frac{ds}{dt} = \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2}$$

$$a \leq t \leq b \quad \int_c^b ds = \int_a^b \frac{ds}{dt} \cdot dt$$

Ex: Find the length of the curve described by

$$y(x) = \frac{1}{2}x^2 + x - 3, \quad 1 \leq x \leq 3$$

Distance between two infinitesimally nearly points

on the curve is

$$ds = dx \sqrt{1 + \left(\frac{dy}{dx}\right)^2} = dx \sqrt{1 + (x+1)^2}$$

$$ds = dx \sqrt{x^2 + 2x + 2}$$

$$\int ds = \int_1^3 \sqrt{x^2 + 2x + 2} dx \approx 6.34$$

Ex² The curves $x = \cos t$
 $y = \sin t$ $0 \leq t \leq 6\pi$
 $z = t$

$$\frac{dx}{dt} = -\sin t, \quad \frac{dy}{dt} = \cos t, \quad \frac{dz}{dt} = 1$$

$$ds = dt \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2 + \left(\frac{dz}{dt}\right)^2}$$

$$= dt \sqrt{\sin^2 t + \cos^2 t + 1}$$

$$ds = dt \sqrt{2}$$

$$\int_C ds = \int_0^{6\pi} \sqrt{2} dt = 6\pi \sqrt{2}$$

Line integral (scalar)

A line integral in two dimensions may be written as

$$\int_C f(x, y) dw$$

$f(x, y) \rightarrow$ scalar function to be integrated

$$Ex: f(x, y) = x^2 + 4y^2$$

$C \rightarrow$ This is the curve along which integration takes place

$$Ex: y = x^2 \text{ or } x = \sin y$$

$$\text{or } x = t-1; y = t^2$$

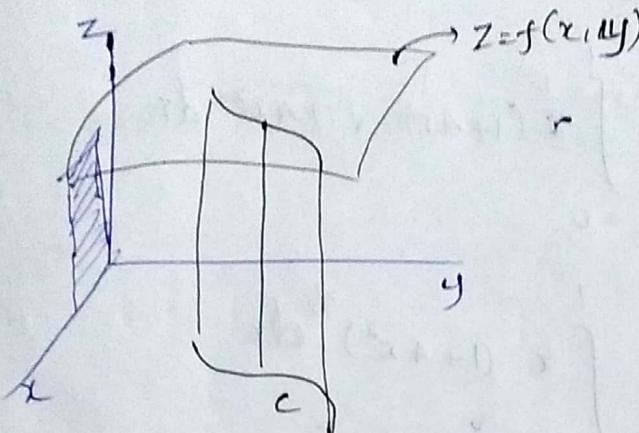
$$\vec{r}(t) = xi + yj = (t-1)i + t^2 j$$

$dw \rightarrow$ variable of integration
may be dx, dy or ds .

$$ds = \sqrt{(dx)^2 + (dy)^2}$$

The integral $\int_C f(x, y) ds$ represents the area

beneath the surface $z = f(x, y)$ but above the curve c .



The curve can be given in x, y form or parametric form with limits.

For calculating line integrals, express all quantities in terms of a single variable.

Ex 3 Find $\int_C x(1+4y) dx$ where c is the curve

$y = x^2$, starting from $x=0, y=0$ and ending $x=1, y=1$

$$\begin{aligned} \text{Soln. } \int_C x(1+4y) dx &= \int_{x=0}^1 x(1+4x^2) dx = \int_0^1 (x+4x^3) dx \\ &= \left[\frac{x^2}{2} + \frac{x^4}{4} \right]_0^1 \\ &= \frac{3}{2} \end{aligned}$$

$$\# \int_C x(1+4y) ds \quad c: y = x^2 \\ x=0, y=0 \rightarrow x=1, y=1$$

$$ds = dx \sqrt{1 + \left(\frac{dy}{dx}\right)^2}$$

$$= dx \sqrt{1 + (2x)^2}$$

$$ds = dx \sqrt{1+4x^2}$$

$$\int_C x(1+4y) ds = \int_{x=0}^1 x(1+4x^2) \sqrt{1+4x^2} dx$$

$$= \int_0^1 x (1+4x^2)^{3/2} dx$$

$$= \frac{1}{20} (5^{5/2} - 1)$$

Ex 4 Find $\int_C xy ds$ $c: x=3t^2, y=t^3-1$ for t varying from 0 to 1

$$\int_C xy ds = \int_{t=0}^1 (3t^2)(t^3-1) ds$$

$$ds = dt \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2} = dt \sqrt{(6t)^2 + (3t^2)^2}$$

$$\int_C xy ds = \int_{t=0}^1 (3t^2)(t^3-1) \sqrt{36t^2 + 9t^4} dt$$

Line integral (vector)

Work done = $\vec{F} \cdot d\vec{r}$

$$\vec{F} = F_x i + F_y j + F_z k$$

$$d\vec{r} = dx i + dy j + dz k$$

$$\int_C \vec{F} \cdot d\vec{r} = \int (F_x dx + F_y dy + F_z dz)$$

Ex4: $\vec{F} = 2xy i - 5x j$ & $C: y = x^3, 0 \leq x \leq 1$

$$\int_C \vec{F} \cdot d\vec{r} = \int (2xy dx - 5x dy) \quad dy = 3x^2 dx$$

$$= \int (2x x^3 dx - 5x \cdot 3x^2 dx)$$

$$= \int (2x^4 - 15x^3) dx$$

$$= -\frac{67}{20}$$

Ex5: Consider the vector field $\vec{F} = y^2 z^3 \hat{i} + 2xy z^3 \hat{j} + 3xy^2 z^2 \hat{k}$

$$C_1: x = t, y = t, z = t \quad (0 \leq t \leq 1)$$

$$C_2: x = t^2, y = t, z = t^2 \quad (0 \leq t \leq 1)$$

$O(0,0,0)$ to $A(1,1,1)$

$$\begin{aligned}
 \int_{C_1} \vec{F} \cdot d\vec{x} &= \int_{C_1} (yz^3 dx + 2xyz^3 dy + 3xy^2 z^2 dz) \\
 &= \int_0^1 (t^5 dt + 2t^5 dt + 3t^5 dt) && \begin{aligned} x &= t \\ dx &= dt \\ y &= t \\ dy &= dt \\ z &= t \\ dz &= dt \end{aligned} \\
 &= \int_0^1 (t^5 + 2t^5 + 3t^5) dt \\
 &= \frac{1}{6} + \frac{5}{6} \\
 &= \cancel{\frac{1}{6}} + \cancel{\frac{5}{6}}
 \end{aligned}$$

$$\begin{aligned}
 \int_{C_2} \vec{F} \cdot d\vec{x} &= \int_{C_2} (yz^3 dx + 2xyz^3 dy + 3xy^2 z^2 dz) \\
 &= \int_0^1 t^2 (t^2)^3 2t dt + 2t^2 + (t^2)^3 dt + && \begin{aligned} x &= t^2 \\ dx &= 2t dt \\ y &= t \\ dy &= dt \\ z &= t^2 \\ dz &= 2t dt \end{aligned} \\
 &\quad 3t^2 t^2 t^4 2t dt \\
 &= \int_0^1 (2t^9 + 2t^9 + 6t^9) dt \\
 &= \int_0^1 10t^9 dt \\
 &= 1
 \end{aligned}$$

Work done by both paths is same.

Ex: Evaluate $\int_C (x^1 + y^1) d\vec{r}$

Over $C_1 \quad 0 \leq x \leq 1, y = 0$

$$\vec{r}(t) = t \hat{i}, \quad 0 \leq t \leq 1$$

$$\frac{d\vec{r}}{dt} = \hat{i}$$

$$I_{C_1} = \int_0^1 (t^1 \hat{i}) \cdot \hat{i} dt = \int_0^1 t dt = \frac{1}{2}$$

Over $C_2 \quad x+y=1 \text{ in 1st quadrant}$

$$\vec{r}(t) = t \hat{i} + (1-t) \hat{j}; \quad 0 \leq t \leq 1$$

$$\frac{d\vec{r}}{dt} = \hat{i} - \hat{j}$$

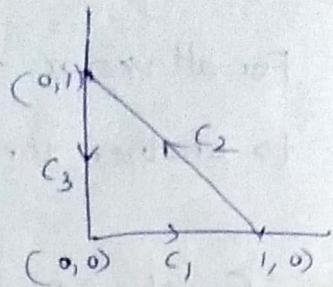
$$\begin{aligned} I_{C_2} &= \int_0^1 (t \hat{i} + (1-t) \hat{j}) \cdot (\hat{i} - \hat{j}) dt \\ &= \int_0^1 (t - (1-t)) dt = \int_0^1 (2t-1) dt \\ &= [t^2 - t]_0^1 = 0 \end{aligned}$$

Over $C_3 \quad y \text{ is from } 1 \text{ to } 0$

$$0 \leq y \leq 1; \quad x \geq 0$$

$$\vec{r}(t) = (1-t) \hat{j} \quad 0 \leq t \leq 1$$

$$\frac{d\vec{r}(t)}{dt} = -\hat{j}$$



piecewise
smooth curve/loop

$$\begin{aligned}
 I_{C_3} &= \int_0^1 (1-t) \hat{j} \cdot (-\hat{j}) dt \\
 &= - \int_0^1 (1-t) dt = \left(-t + \frac{t^2}{2} \right)_0^1 \\
 &= -1 + \frac{1}{2} = -\frac{1}{2}
 \end{aligned}$$

$$I_C = I_{C_1} + I_{C_2} + I_{C_3} = \frac{1}{2} + 0 - \frac{1}{2} = 0$$

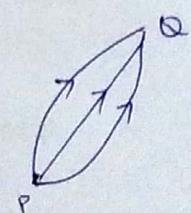
Work done in case of conservative vector field \vec{F}

Let \vec{F} be a conservative vector field. Hence, there exists a scalar function $\phi(x, y, z)$ such that

$$\vec{F} = \text{grad}(\phi) \text{ . Now, } \vec{F} = \frac{\partial \phi}{\partial x} i + \frac{\partial \phi}{\partial y} j + \frac{\partial \phi}{\partial z} k$$

$$\vec{F} = F_1 i + F_2 j + F_3 k$$

$$\begin{aligned}
 W &= \int_P^Q \vec{F} \cdot d\vec{r} = \int_P^Q (F_1 dx + F_2 dy + F_3 dz) \\
 &= \int_P^Q \left(\frac{\partial \phi}{\partial x} dx + \frac{\partial \phi}{\partial y} dy + \frac{\partial \phi}{\partial z} dz \right) \\
 &= \int_P^Q d\phi \\
 &= [\phi(x, y, z)]_P^Q \\
 &= \phi(Q) - \phi(P)
 \end{aligned}$$

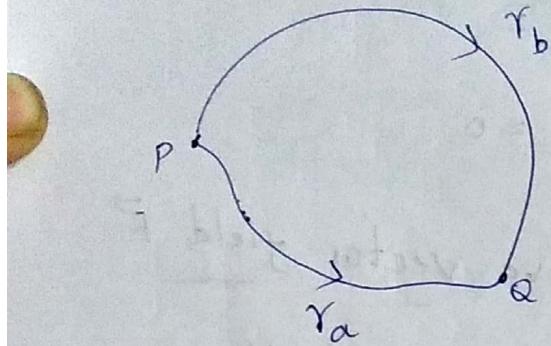


Work done is independent of path
in case of conservative

$$\# \vec{F} = \vec{\nabla} \phi \Leftrightarrow \int_P^Q \vec{F} \cdot d\vec{r} \Leftrightarrow \oint_{\text{path}} \vec{F} \cdot d\vec{r} = 0$$

conservative path independent & loops \Downarrow

$\Rightarrow x \vec{F} = 0$
(irrotational)



$$\gamma = r_a - r_b$$

↓
loop
path

Show that $\vec{F} = (yz-1)\hat{i} + (z+xz+z^2)\hat{j} + (y+xy+2yz)\hat{k}$ is conservative. Also find the work done by \vec{F} in moving a particle from $(1, 2, 2)$ to $(2, 3, 4)$.

Soln

$$\text{curl } \vec{F} = \begin{vmatrix} i & j & k \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ yz-1 & z+xz+z^2 & y+xy+2yz \end{vmatrix} = \hat{i}(1+x+2z-1-x-2z) + \hat{j}(y-y) + \hat{k}(z-z) = 0$$

$$\vec{F} = \vec{\nabla} \phi$$

$$\phi = xyz - x + yz + yz^2 + C$$

$$\text{Work done} = \int_{(1,2,2)}^{(2,3,4)} \vec{F} \cdot d\vec{r} = \phi(2,3,4) - \phi(1,2,2) = 67$$

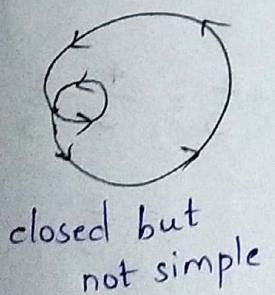
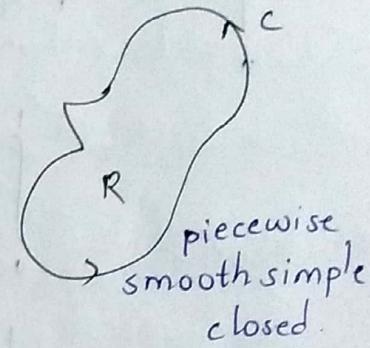
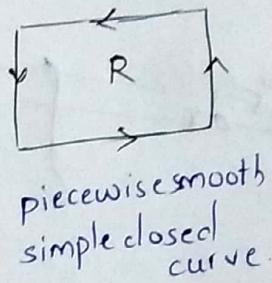
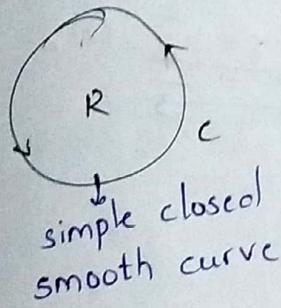
Green's Theorem:

It connects line integral to double integral

Let c be a piecewise smooth simple curve closed curve bounding a region R . If $f, g, \frac{\partial f}{\partial y}$ and $\frac{\partial g}{\partial x}$ are continuous on R then

$$\oint_C f(x,y) dx + g(x,y) dy = \iint_R \left(\frac{\partial g}{\partial x} - \frac{\partial f}{\partial y} \right) dx dy$$

Integration being carried out in the positive direction on c counter clockwise



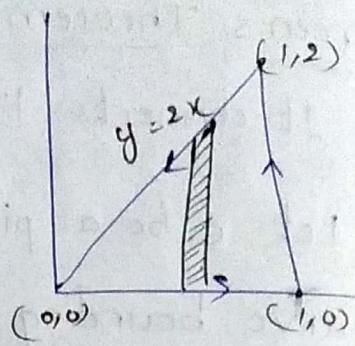
$$\text{Line integral} = \text{Line integral}$$

The left side shows a rectangle with a counter-clockwise arrow around its perimeter. The right side shows the same rectangle with a grid of arrows indicating the direction of integration along each side.

Ex: Evaluate $\oint_C xy dx + x^2 y^3 dy$, where c is the curve that is the boundary of the triangle having vertices $(0,0), (1,0), (1,2)$

$$f = xy \quad \frac{\partial f}{\partial y} = x$$

$$g = x^2 y^3 \quad \frac{\partial g}{\partial x} = 2xy^3$$



$$\iint_R (2xy^3 - x) dx dy$$

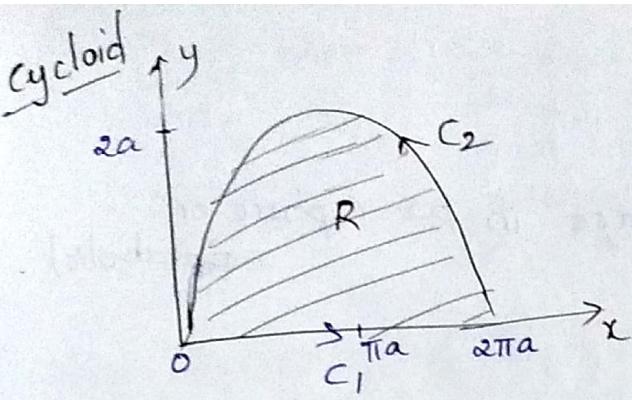
$$\int_0^1 \int_0^{2x} (2xy^3 - x) dy dx$$

$$\int_0^1 \left(2x \frac{y^4}{4} - x \right) \Big|_0^{2x} dx = \int_0^1 \left(\frac{x}{2} \cdot 16x^4 - x^2 \right) dx$$

$$= \int_0^1 8x^5 dx = \int_0^1 8 \frac{1}{6} = \frac{4}{3}$$

$$= \int_0^1 (8x^5 - x^2) dx$$

$$= \left[\frac{8x^6}{6} - \frac{x^3}{3} \right]_0^1 = \frac{8}{6} - \frac{2}{3} = \frac{4}{3} - \frac{2}{3} = \frac{2}{3}$$



$$C_2 \quad x = a(\theta - \sin \theta) \quad \theta \text{ runs from } 2\pi \text{ to } 0$$

$$y = a(1 - \cos \theta)$$

$$\frac{\partial g}{\partial x} - \frac{\partial f}{\partial y} = 1$$

↳ $\vec{F} = -y \hat{i}$

$$C_1 \quad y = 0, \quad x = t \quad 0 \leq t \leq 2\pi a$$

$$\int_C \vec{F} \cdot d\vec{r} = 0$$

$$dx = a(1 - \cos \theta) d\theta$$

$$\int_{C_2} \vec{F} \cdot d\vec{r} = \int (-y) dx$$

$$= \int_{2\pi}^0 -a^2(1 - \cos \theta)^2 d\theta$$

$$= a^2 \int_0^{2\pi} (1 - \cos \theta)^2 d\theta$$

$$= 3\pi a^2$$

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Surface integral:

Integration over a surface in R^3 (sphere or parabolic)

Points (x, y, z) on curve

$$x = x(t), y = y(t), z = z(t) \quad a \leq t \leq b$$

Parameterization is transformation

a subset of R into a curve

Parameterization of surfaces to define a surface integral

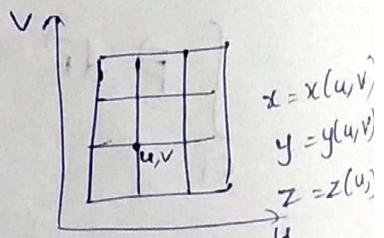
we will use 2 variables u & v to parameterize a

surface Σ in R^3

$$x = x(u, v)$$

$$y = y(u, v)$$

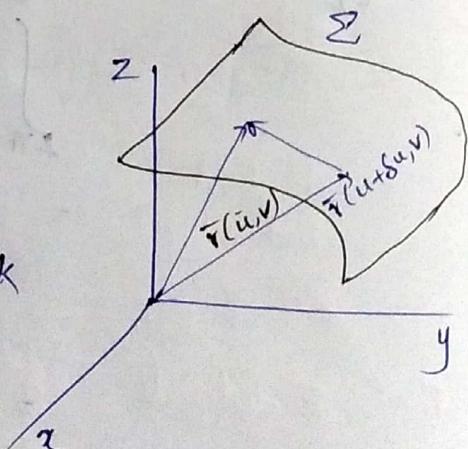
$z = z(u, v)$ for (u, v) in some region R in R^2



Position vector of a point
on Σ

$$\vec{r}(u, v) = x(u, v)\mathbf{i} + y(u, v)\mathbf{j} + z(u, v)\mathbf{k}$$

for (u, v) in R



$$\frac{\partial \vec{r}}{\partial u}(u,v) = \frac{\partial x}{\partial u}(u,v)i + \frac{\partial y}{\partial u}(u,v)j + \frac{\partial z}{\partial u}(u,v)k$$

$$\frac{\partial \vec{r}}{\partial v}(u,v) = \frac{\partial x}{\partial v}(u,v)i + \frac{\partial y}{\partial v}(u,v)j$$

Parameterization of Σ \equiv transforming a region of R^2
(in uv plane)

into a 2 dimensional surface
in R^3

Vertical line gridlines in R (u is constant) \rightarrow mapped to curves on Σ and the variable u is constant along $\vec{r}_0(u,v)$. So the tangent vector to those curves at a point (u,v) is $\frac{\partial \vec{r}}{\partial v}$.

Similarly horizontal lines (v is constant) \rightarrow mapped to curves on Σ and the variable v is constant along $\vec{r}(u,v)$. So the tangent vector to those curves at a point (u,v) is $\frac{\partial \vec{r}}{\partial u}$.

Consider the pt (u,v) in R . Suppose the rectangle drawn has a small width and a height of Δu and Δv respectively.

Corner points (u,v) , $(u+\Delta u, v)$, $(u+\Delta u, v+\Delta v)$, and $(u, v+\Delta v)$

Area of the rectangle. $A = \Delta u \Delta v$.

Mapped to surface area $d\sigma$ which is close to the area of the parallelogram which has adjacent sides

$$\vec{r}(u+\Delta u, v) - \vec{r}(u, v) \text{ and } \vec{r}(u, v+\Delta v) - \vec{r}(u, v)$$

$$\frac{\partial \vec{r}}{\partial u} = \frac{\vec{r}(u+\Delta u) - \vec{r}(u, v)}{\Delta u} \text{ and } \frac{\partial \vec{r}}{\partial v} = \frac{\vec{r}(u, v+\Delta v) - \vec{r}(u, v)}{\Delta v}$$

$$d\sigma = \left\| \left(\sin \frac{\partial \vec{r}}{\partial u} \right) \times \left(\partial v \frac{\partial \vec{r}}{\partial v} \right) \right\| = \left\| \frac{\partial \vec{r}}{\partial u} \times \frac{\partial \vec{r}}{\partial v} \right\| du dv$$

Total surface area S of Σ

$$S = \iint_R \left\| \frac{\partial \vec{r}}{\partial u} \times \frac{\partial \vec{r}}{\partial v} \right\| du dv$$



$$S = \iint_{\Sigma} 1 \cdot d\sigma$$

Replace 1 by a general real valued function $f(x, y, z)$ in R^3 .

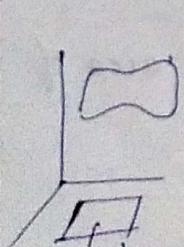
Let Σ be a surface in R^3 parameterized by

$x = x(u, v)$, $y = y(u, v)$, $z = z(u, v)$ for (u, v) in some region R in R^2 . Let $\vec{r}(u, v) = x(u, v)i + y(u, v)j + z(u, v)k$

be the position vector for any point in Σ and

Let $f(x, y, z)$ be a real valued f defined on some subset of R^3 that contains Σ . The surface integral

of $f(x, y, z)$ over Σ is



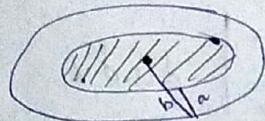
$$\iint_{\Sigma} f(x, y, z) d\sigma = \iint_R f(x(u, v), y(u, v), z(u, v)) \left\| \frac{\partial \vec{r}}{\partial u} \times \frac{\partial \vec{r}}{\partial v} \right\| du dv$$

Not only flat can be any surface
it flat can directly done by double integral.

Particular case, for surface area

$$S \text{ of } \Sigma \text{ is } S = \iint_{\Sigma} 1 \cdot d\sigma.$$

Ex



Torus T obtained by revolving a circle of radius a in the yz plane

around the z -axis, circle's centre is at a distance b from the z -axis ($0 < a < b$). Find the surface area of T .

Sol Torus can be parameterized as

$$x = (b + a \cos u) \cos v \quad 0 \leq u \leq 2\pi$$

$$y = (b + a \cos u) \sin v \quad 0 \leq v \leq 2\pi$$

$$z = a \sin u$$

Position vector

$$\vec{r}(u, v) = x(u, v)\mathbf{i} + y(u, v)\mathbf{j} + z(u, v)\mathbf{k}$$

$$= (b + a \cos u) \cos v \mathbf{i} + (b + a \cos u) \sin v \mathbf{j} + a \sin u \mathbf{k}$$

$$\frac{\partial \vec{r}}{\partial u} = -a \sin u \cos v \mathbf{i} - a \sin u \sin v \mathbf{j} + a \cos u \mathbf{k}$$

$$\frac{\partial \vec{r}}{\partial v} = -(b + a \cos u) \sin v \mathbf{i} + (b + a \cos u) \cos v \mathbf{j} + 0 \mathbf{k}$$

$$\frac{\partial \vec{r}}{\partial u} \times \frac{\partial \vec{r}}{\partial v} = -a(b + a \cos u) \cos v \cos u \mathbf{i} - a(b + a \cos u) \cos u \sin v \mathbf{j} - a(b + a \cos u) \sin v \mathbf{k}$$

$$\left| \frac{\partial \vec{r}}{\partial u} \times \frac{\partial \vec{r}}{\partial v} \right| = a(b + a \cos u)$$

Surface area of Σ is

$$S = \iint_{\Sigma} f \, d\sigma = \int_0^{2\pi} \int_0^{2\pi} \left| \frac{\partial \vec{r}}{\partial u} \times \frac{\partial \vec{r}}{\partial v} \right| du dv$$

$$= \int_0^{2\pi} \int_0^{2\pi} ab(b + a \cos u) du dv$$

$$= \int_0^{2\pi} (abu + a^2 \sin u) \Big|_0^{2\pi} dv$$

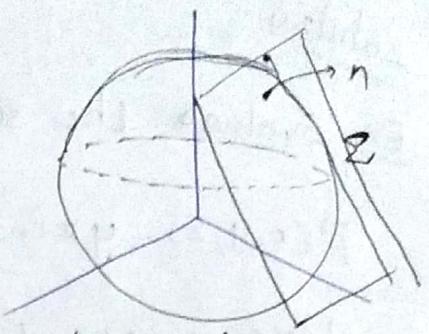
$$= \int_0^{2\pi} 2\pi ab dv$$

$$= 4\pi^2 ab.$$

Since $\frac{\partial \vec{r}}{\partial u}$ and $\frac{\partial \vec{r}}{\partial v}$ are tangent to the surface Σ (i.e., lie in the tangent plane to Σ at each point on Σ), then $\frac{\partial \vec{r}}{\partial u} \times \frac{\partial \vec{r}}{\partial v}$ is perpendicular to the tangent plane to the surface at each point of Σ .

$$\iint_{\Sigma} f(x, y, z) d\sigma = \iint_R f(x(u, v), y(u, v), z(u, v)) \|\vec{n}\| dudv$$
$$\left(\vec{n} = \left(\frac{\partial \vec{r}}{\partial u} \times \frac{\partial \vec{r}}{\partial v} \right) \right)$$

\hat{n} is normal vector to Σ



Surface integral of a 3-dimensional vector field over a surface:

Let Σ be a surface in \mathbb{R}^3 and let

$\vec{F}(x, y, z) = f_1(x, y, z) \mathbf{i} + f_2(x, y, z) \mathbf{j} + f_3(x, y, z) \mathbf{k}$ be a vector field defined on some subset of \mathbb{R}^3 that contains Σ . The surface integral of \vec{F} over Σ is

$$\iint_{\Sigma} \vec{F} \cdot d\vec{\sigma} = \iint_{\Sigma} \underbrace{\vec{F} \cdot \hat{n}}_{\text{real valued } f^n} d\sigma$$

where at any point on Σ , \hat{n} is the outward unit normal vector to Σ .

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Ex: Evaluate the surface integral $\iint_{\Sigma} \vec{F} \cdot d\vec{\sigma}$ where

$\vec{F}(x, y, z) = yz\mathbf{i} + xz\mathbf{j} + xy\mathbf{k}$ and Σ is the part of the plane $x+y+z=1$ with $x \geq 0, y \geq 0$ and $z \geq 0$.

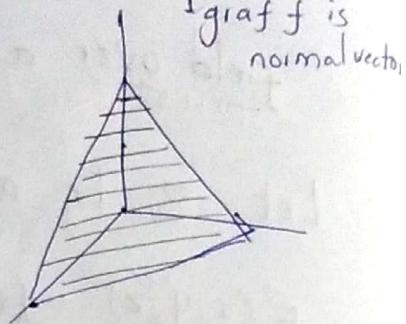
Sol: unit normal vector

$$\hat{n} = \left(\frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}} \right)$$

$$(1, 1, 1)$$

↓
Normal
vector

$$f(x, y, z) = c$$



Parameterize Σ over R

$$\frac{1}{\hat{n} \cdot \mathbf{x}} = \sqrt{3}$$

$$x = u, \quad y = v, \quad z = 1 - (u+v) \quad \text{for} \quad 0 \leq u \leq 1 \\ 0 \leq v \leq 1-u.$$

$$\vec{F} \cdot \hat{n} = (yz, xz, xy) \cdot \left(\frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}} \right)$$

$$= \frac{1}{\sqrt{3}} (yz + xz + xy)$$

$$= \frac{1}{\sqrt{3}} ((x+y)z + xy)$$

$$= \frac{1}{\sqrt{3}} ((u+v)(1-(u+v)) + uv)$$

$$= \frac{1}{\sqrt{3}} ((u+v) - (u+v)^2 + uv)$$

for (u, v) in R and $\vec{r}(u, v) = ui + vj + (1-(u+v))k$

$$\frac{\partial \vec{r}}{\partial u} \times \frac{\partial \vec{r}}{\partial v} = (1, 0, -1) \times (0, 1, -1) = (1, 1, 1)$$

thus integrating over R gives

$$\begin{aligned} & \iint_{\Sigma} \vec{F} \cdot \hat{n} d\sigma \\ &= \iint_R (\vec{F}(x(u,v), y(u,v), z(u,v)) \cdot \hat{n}) \left| \frac{\partial \vec{r}}{\partial u} \times \frac{\partial \vec{r}}{\partial v} \right| du dv \\ &= \int_0^1 \int_0^{1-u} \frac{1}{\sqrt{3}} (u+v - (u+v)^2 + uv) \cdot \sqrt{3} \cdot dv du \\ &= \int_0^1 \left[\frac{(u+v)^2}{2} - \frac{(u+v)^3}{3} + \frac{uv^2}{2} \right]_{v=0}^{v=1-u} du \\ &= \int_0^1 \left(\frac{1}{6} + \frac{u}{2} - \frac{3u^2}{2} + \frac{5u^3}{6} \right) du \\ &= \left[\frac{u}{6} + \frac{u^2}{4} - \frac{u^3}{2} + \frac{5u^4}{24} \right]_0^1 \\ &= \frac{1}{8} \end{aligned}$$

If the eqn of Σ is given as $z = f(x, y)$

$$x = u, \quad y = v, \quad z = f(u, v)$$

$$\vec{r}(u, v) = ui + vj + f(u, v)k$$

$$\frac{\partial \vec{r}}{\partial u} = i + f_u k, \quad \frac{\partial \vec{r}}{\partial v} = j + f_v k$$

$$\frac{\partial \vec{r}}{\partial u} \times \frac{\partial \vec{r}}{\partial v} = \begin{vmatrix} i & j & k \\ 1 & 0 & fu \\ 0 & 1 & fv \end{vmatrix}$$

$$= -fui + -fvj + k.$$

$$\left| \frac{\partial \vec{r}}{\partial u} \times \frac{\partial \vec{r}}{\partial v} \right| = \sqrt{1+f_u^2+f_v^2}$$

$$= \sqrt{1+f_x^2+f_y^2}$$

Surface area of Σ $A = \iint_{R^+} \sqrt{1+f_x^2+f_y^2} dx dy$

R^+ is the region in the xy plane obtained by the projection of the surface Σ .

Surface integral of $g(x, y, z)$ over Σ is

$$I = \iint_{\Sigma} g(x, y, z) d\sigma$$

$$= \iint_{R^+} g(x, y, f(x, y)) d\sigma$$

$$= \iint_{R^+} \sqrt{1+f_x^2+f_y^2} dx dy.$$

$$\text{If } x = f_1(y, z) \quad = \iint_{R^+} \sqrt{1+f_g^2+f_z^2} dy dz$$

$$\text{if } y = m(x, z) \quad = \iint_{R^+} \sqrt{1+m_x^2+m_z^2} dx dz$$

E1 Find the surface area of hemisphere

$$x^2 + y^2 + z^2 = a^2, z \geq 0.$$

soln $z = \sqrt{a^2 - x^2 - y^2} = f(x, y)$

$$f_x = z_x = \frac{1}{2} (a^2 - x^2 - y^2)^{-\frac{1}{2}} (-2x)$$

$$z_x = \frac{-x}{(a^2 - x^2 - y^2)^{\frac{1}{2}}}$$

$$f_y = z_y = \frac{1}{2} (a^2 - x^2 - y^2)^{-\frac{1}{2}} (-2y)$$

$$z_y = \frac{-y}{(a^2 - x^2 - y^2)^{\frac{1}{2}}}$$

$$1 + z_x^2 + z_y^2 = 1 + \frac{x^2}{a^2 - x^2 - y^2} + \frac{y^2}{a^2 - x^2 - y^2}$$

$$= \frac{a^2}{a^2 - x^2 - y^2}$$

$$A = \iint_{R^+} \sqrt{1 + z_x^2 + z_y^2} \, dx \, dy \quad R^+: x^2 + y^2 \leq a^2.$$

$$= a \iint_{R^+} (\sqrt{a^2 - x^2 - y^2})^{-1} \, dx \, dy$$

$$= a \int_0^{2\pi} \int_0^a \frac{1}{\sqrt{a^2 - r^2}} r \, dr \, d\theta$$

$$= 2\pi a^3.$$

If S is piecewise smooth having smooth surfaces

S_1, S_2, \dots, S_k

$$\iint_S g(x, y, z) dA = \left(\iint_{S_1} + \iint_{S_2} + \dots + \iint_{S_k} \right) g(x, y, z) dA$$

Vector field (Surface integral)

$$\Sigma : x = f(y, z)$$

$$\iint_{\Sigma} \vec{v} \cdot \hat{n} d\sigma = \iint_R \vec{v} \cdot \hat{n} \frac{dy dz}{\sqrt{1 + f_y^2}}$$

R is the projection of Σ onto yz plane.

Computing surface integrals can often be tedious.

The following theorem provides an easier way in the case when Σ is a closed surface, that is when Σ encloses a bounded solid in \mathbb{R}^3 .

For example, spheres, cubes and ellipsoids are closed surfaces but planes and paraboloids are not.

Gauss's Divergence theorem: Let Σ be a closed surface in \mathbb{R}^3 which bounds a solid D , and let

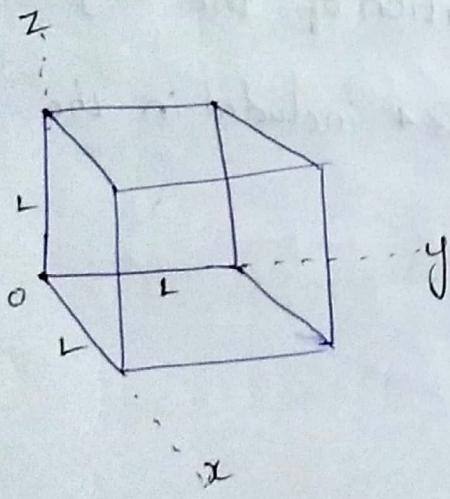
$\vec{F}(x, y, z) = F_1(x, y, z)i + F_2(x, y, z)j + F_3(x, y, z)k$ be a vector field defined on some subset of \mathbb{R}^3

that contains Σ

$$\text{Then } \iint_{\Sigma} \vec{F} \cdot d\vec{\sigma} = \iiint_D \operatorname{div} \vec{F} \, dv$$

$\operatorname{div} \vec{F} = \frac{\partial F_1}{\partial x} + \frac{\partial F_2}{\partial y} + \frac{\partial F_3}{\partial z}$ is called the divergence of \vec{F} .

Test: $\vec{F} = xy\hat{i} + yz\hat{j} + zx\hat{k}$ defined over a cube of side L lying in the first octant with a vertex at the origin.



$$\vec{F} = y\hat{i} + z\hat{j} + x\hat{k}$$

$$\iiint_D \vec{F} \cdot d\vec{v} = \int_0^L \int_0^L \int_0^L (x+y+z) dx dy dz$$

The flux integral only has non zero contributions from the three sides located $x=L$, $y=L$, $z=L$ corresponding unit normal vectors: $\hat{n} = i$, $\hat{n} = j$, $\hat{n} = k$

$$\begin{aligned}
 \iint_{\Sigma} \vec{F} \cdot \hat{n} d\sigma &= \int_0^L \int_0^L Ly dy dz + \int_0^L \int_0^L Lz dx dz \\
 &\quad + \int_0^L \int_0^L Lx dx dy \\
 &= \frac{L^4}{2} + \frac{L^4}{2} + \frac{L^4}{2} \\
 &= \frac{3L^4}{2}
 \end{aligned}$$

Evaluate $\iint_S \vec{v} \cdot \hat{n} d\sigma$ where $\vec{v} = z^2 \mathbf{i} + xy \mathbf{j} + y^2 \mathbf{k}$

and surface S is the portion of the surface of cylinder $x^2 + y^2 = 36$, $0 \leq z \leq 4$ included in the first octant.

Stoke's theorem: (line & surface integral)

i) orientable surface (piecewise smooth) Σ

bounded by piecewise
smooth simple closed curve C .

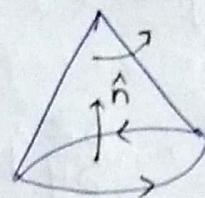
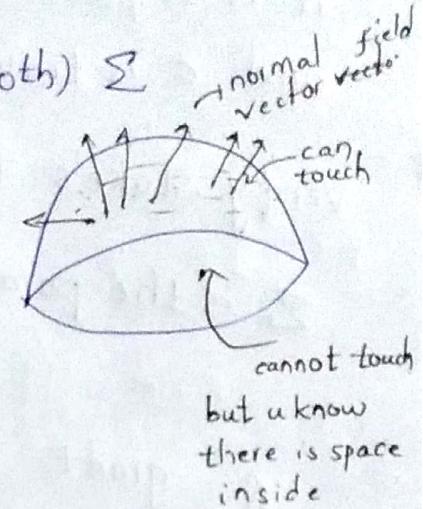
Walk along C with your

head pointing in direction

of \hat{n} , then the surface
would be on your left

Then we say \hat{n} is
positive vector and

C is traversed \hat{n} -positively.



Nonorientable
Ex: Möbius strip

Let Σ be an orientable piecewise smooth surface

in \mathbb{R}^3 whose boundary is a simple closed curve C ,

and let $\vec{F}(x, y, z) = P(x, y, z)i + Q(x, y, z)j + R(x, y, z)k$

be smooth vector field defined on some subset of \mathbb{R}^3

that contains Σ then

$$\oint_C \vec{F} \cdot d\vec{x} = \iint_{\Sigma} (\operatorname{curl} \vec{F}) \cdot \hat{n} \, d\sigma$$

$$\text{where } \operatorname{curl} \vec{F} = \left(\frac{\partial R}{\partial y} - \frac{\partial Q}{\partial z} \right) i + \left(\quad \right) j + \left(\quad \right) k$$

\hat{A} is a positive unit normal vector over Σ
and c is traversed A -positively

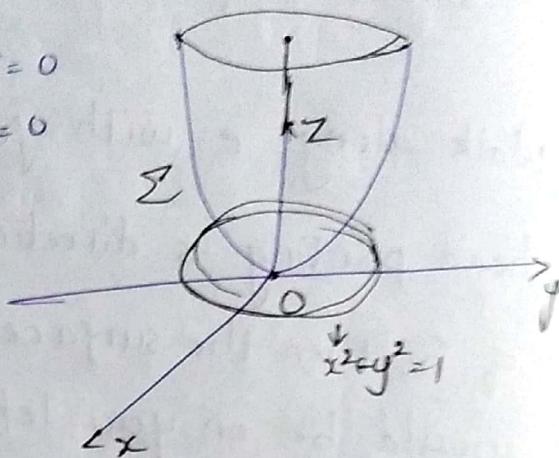
Verify Stoke's theorem for $\vec{F} = z\mathbf{i} + x\mathbf{j} + y\mathbf{k}$ when

Σ is the paraboloid $z = x^2 + y^2$ such that $z \leq 1$

Sol:

$$\hat{A} = \frac{\text{grad } F}{|\text{grad } F|}$$

$$z^2 - x^2 - y^2 = 0 \\ f(x, y, z) = 0$$



$$\hat{A} = \frac{-\frac{\partial z}{\partial x} \mathbf{i} - \frac{\partial z}{\partial y} \mathbf{j} + \mathbf{k}}{\sqrt{1 + \left(\frac{\partial z}{\partial x}\right)^2 + \left(\frac{\partial z}{\partial y}\right)^2}}$$

$$= \frac{-2x\mathbf{i} - 2y\mathbf{j} + \mathbf{k}}{\sqrt{1 + 4x^2 + 4y^2}}$$

$$\text{curl } \vec{F} = (1-0)\mathbf{i} + (1-0)\mathbf{j} + (1-0)\mathbf{k} = \mathbf{i} + \mathbf{j} + \mathbf{k}$$

$$\Sigma: \vec{r}(x, y) = x\mathbf{i} + y\mathbf{j} + (x^2 + y^2)\mathbf{k}$$

$$\text{for } (x, y) \text{ in } D: \{ (x, y) : x^2 + y^2 \leq 1 \}$$

$$x = u \\ y = v \\ z = u^2 + v^2$$

$$\text{curl } \vec{F} \cdot \hat{A} = \frac{-2x - 2y + 1}{\sqrt{1 + 4x^2 + 4y^2}}$$

$$\iint_{\Sigma} (\text{curl } \vec{F}) \cdot \hat{A} \, d\sigma = \iint_D \frac{-2x - 2y + 1}{\sqrt{1 + 4x^2 + 4y^2}} \sqrt{1 + 4x^2 + 4y^2} \, dA$$

$$= \iint_D (-2x - 2y + 1) \, dA$$

$$= \int_0^{2\pi} \int_0^1 (-2r\cos\theta - 2r\sin\theta + 1) r dr d\theta$$

$$= \pi.$$

The boundary curve C

$$d\vec{r} = \left(\frac{dx}{dt} i + \frac{dy}{dt} j + \frac{dz}{dt} k \right) dt$$

$$x^2 + y^2 = 1, \text{ in } z = 1$$

$$x = \cos t, y = \sin t, z = 1, 0 \leq t \leq 2\pi$$

$$\oint_C \phi \vec{F} \cdot d\vec{r} = \int_0^{2\pi} \left[1(-\sin t) + (\cos t)(\cos t) + (\sin t)(0) \right] dt$$

$$= \int_0^{2\pi} \left(-\sin t + 1 + \frac{\cos 2t}{2} \right) dt$$

$$= \pi$$

Volume Integrals

① V bounded by S

ϕ is a scalar f^n

$$\delta V_1, \delta V_2, \dots, \delta V_n$$

$$\delta V_i \rightarrow P_i(x_i, y_i, z_i)$$

$$\sum \phi(P_i) \cdot \delta V_i \quad \text{where } \phi(P_i) = \phi(x_i, y_i, z_i)$$

Limit of sum as $n \rightarrow \infty$: Volume integral of ϕ over V .

$$\iiint_V \phi \, dv \quad dv = dx dy dz$$

② Vector volume integral: $\iiint_V \vec{F} dv$
 ↓
 vector.

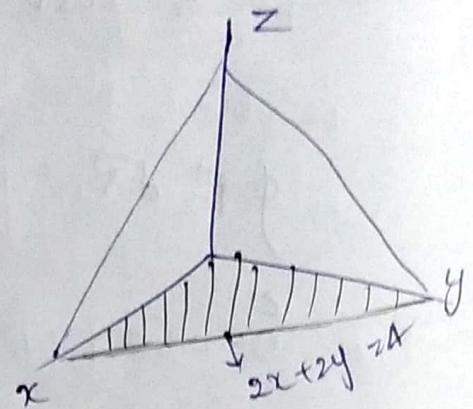
Ex: If $\vec{F} = (2x^2 - 3x)\hat{i} - 2xy\hat{j} - 4x\hat{k}$

Find $\iiint_V (\vec{\nabla} \times \vec{F}) dv$, V is the region R

bounded by the coordinate planes and the
 plane $2x + 2y + z = 4$.

sol

$$\iiint_V \vec{\nabla} \times \vec{F} dv$$



$$\vec{\nabla} \times \vec{F} = \hat{j} - 2y\hat{k}$$

$$R: 2x \leq 4, 2x+2y \leq 4, 2x+2y+z \leq 4, x \leq 2, y \leq 2-x, z \leq 4-2x$$

$$\iiint_V \vec{\nabla} \times \vec{F} dv = \int_{x=0}^2 \int_{y=0}^{2-x} \int_{z=0}^{4-2x-2y} (\hat{j} - 2y\hat{k}) dz dy dx$$

Ex: Evaluate $\iiint_V \phi dV$, where $\phi(x, y, z) = 45x^2y^2$

and V is the volume / closed region bounded by
the planes $4x + 2y + z = 8$, $x = 0$, $y = 0$, $z = 0$.

$$\iiint_V \phi dV = \int_{x=0}^2 \int_{y=0}^{4-2x} \int_{z=0}^{8-4x-2y} 45x^2y^2 dz dy dx$$