K-means Clustering

Partitioning Clustering Approach

- a typical clustering analysis approach via iteratively partitioning training data set to learn a partition of the given data space
- learning a partition on a data set to produce several non-empty clusters (usually, the number of clusters given in advance)
- in principle, optimal partition achieved via <u>minimising</u> the sum of squared distance to its "representative object" in each cluster

$$E = \sum_{k=1}^{K} \sum_{\mathbf{x} \in C_k} d^2(\mathbf{x}, \mathbf{m}_k)$$

e.g., Euclidean distance
$$d^2(\mathbf{x}, \mathbf{m}_k) = \sum_{n=1}^{N} (x_n - m_{kn})^2$$

- Given a K, find a partition of K clusters to optimise the chosen partitioning criterion (cost function)
 - global optimum: exhaustively search all partitions
- The K-means algorithm: a heuristic method
 - K-means algorithm (MacQueen'67): each cluster is represented by the centre of the cluster and the algorithm converges to stable centriods of clusters.
 - K-means algorithm is the simplest partitioning method for clustering analysis and widely used in data mining applications.

K-means Algorithm

 Given the cluster number K, the K-means algorithm is carried out in three steps after initialisation:

Initialisation: set seed points (randomly)

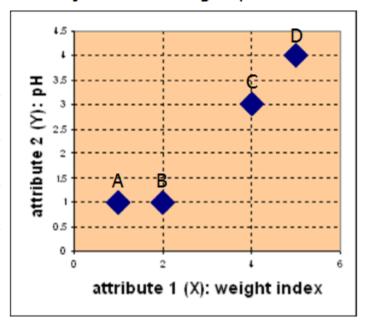
- Assign each object to the cluster of the nearest seed point measured with a specific distance metric
- 2)Compute new seed points as the centroids of the clusters of the current partition (the centroid is the centre, i.e., mean point, of the cluster)
- 3)Go back to Step 1), stop when no more new assignment (i.e., membership in each cluster no longer changes)

Example

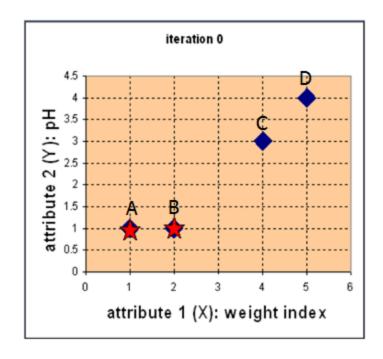
Problem

Suppose we have 4 types of medicines and each has two attributes (pH and weight index). Our goal is to group these objects into K=2 group of medicine.

Medicine	Weight	pH- Index
Α	1	1
В	2	1
С	4	3
D	5	4



Example



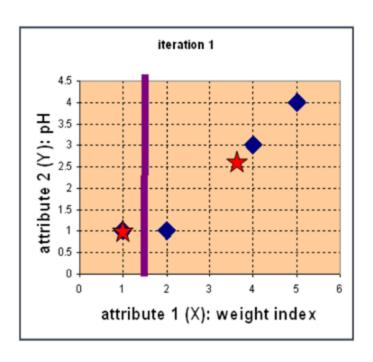
Step 1: Use initial seed points for partitioning

$$c_1 = A, c_2 = B$$

Step 2 Assign each object to the cluster with the nearest seed point

$$d(D,c_1) = \sqrt{(5-1)^2 + (4-1)^2} = 5$$
$$d(D,c_2) = \sqrt{(5-2)^2 + (4-1)^2} = 4.24$$

Step 3 Compute new centroids of the current partition



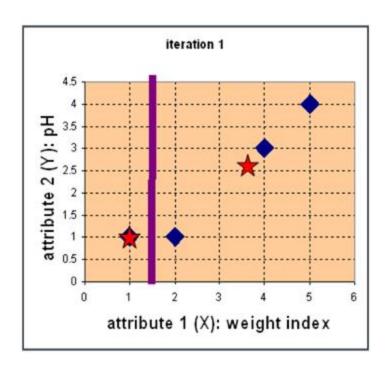
Knowing the members of each cluster, now we compute the new centroid of each group based on these new memberships.

$$c_1 = (1, 1)$$

$$c_2 = \left(\frac{2+4+5}{3}, \frac{1+3+4}{3}\right)$$
$$= \left(\frac{11}{3}, \frac{8}{3}\right)$$

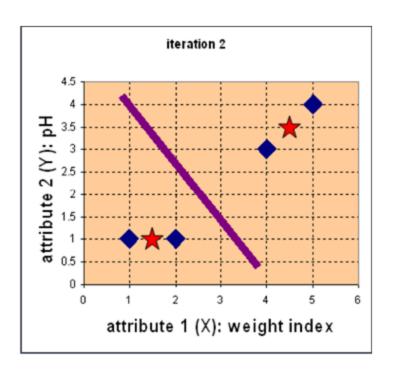
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Renew membership based on new centroids



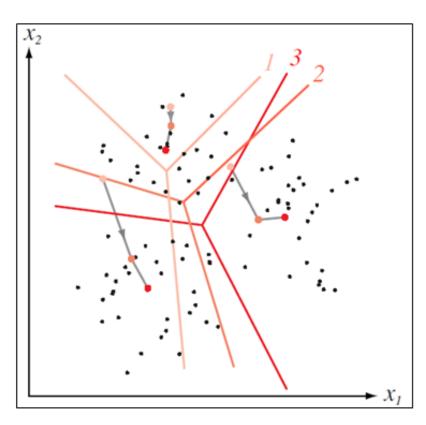
Step 3 Compute new centroids of the current partition

Repeat until its convergence



$$c_1 = \left(\frac{1+2}{2}, \frac{1+1}{2}\right) = \left(1\frac{1}{2}, 1\right)$$
$$c_2 = \left(\frac{4+5}{2}, \frac{3+4}{2}\right) = \left(4\frac{1}{2}, 3\frac{1}{2}\right)$$

How K-means partitions?



When K centroids are set/fixed, they partition the whole data space into K mutually exclusive subspaces to form a partition.

A partition amounts to a

Voronoi Diagram

Changing positions of centroids leads to a new partitioning.

Relevant Issues

Efficient in computation

O(tKn), where n is number of objects, K is number of clusters,
and t is number of iterations. Normally, K, t << n.

Local optimum

- sensitive to initial seed points
- converge to a local optimum: maybe an unwanted solution

Other problems

- Need to specify K, the number of clusters, in advance
- Unable to handle noisy data and outliers (K-Medoids algorithm)
- Not suitable for discovering clusters with non-convex shapes
- Applicable only when mean is defined, then what about categorical data? (K-mode algorithm)
- how to evaluate the K-mean performance?

Summary

- K-means algorithm is a simple yet popular method for clustering analysis
- Its performance is determined by initialisation and appropriate distance measure
- There are several variants of K-means to overcome its weaknesses
 - K-Medoids: resistance to noise and/or outliers
 - K-Modes: extension to categorical data clustering analysis
 - CLARA: extension to deal with large data sets
 - Mixture models (EM algorithm): handling uncertainty of clusters