

CGC ASSIGNMENT – 6

Name: RAHUL VARMA

Roll No: S20200010212

combine motion and haar cascade:

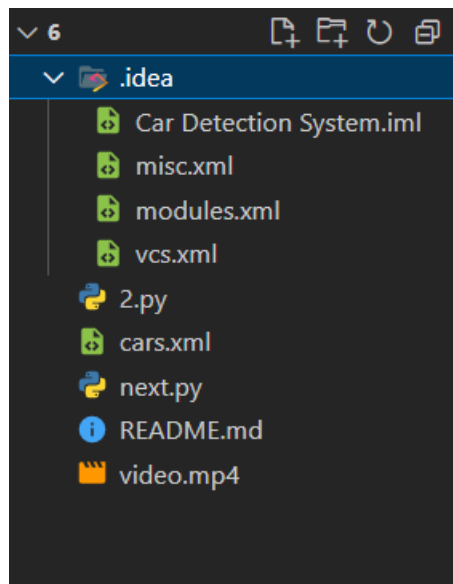
In this assignment we are using the last assignment haar cascade code and combining the haar cascade code with the motion code which we did in the 3rd and 4th assignments.

or case (disjunction).

Motion	Haar	Output
0	1	1
1	0	1
1	1	1
0	0	0

1, 0 means detected and not detected.

Folder Structure:



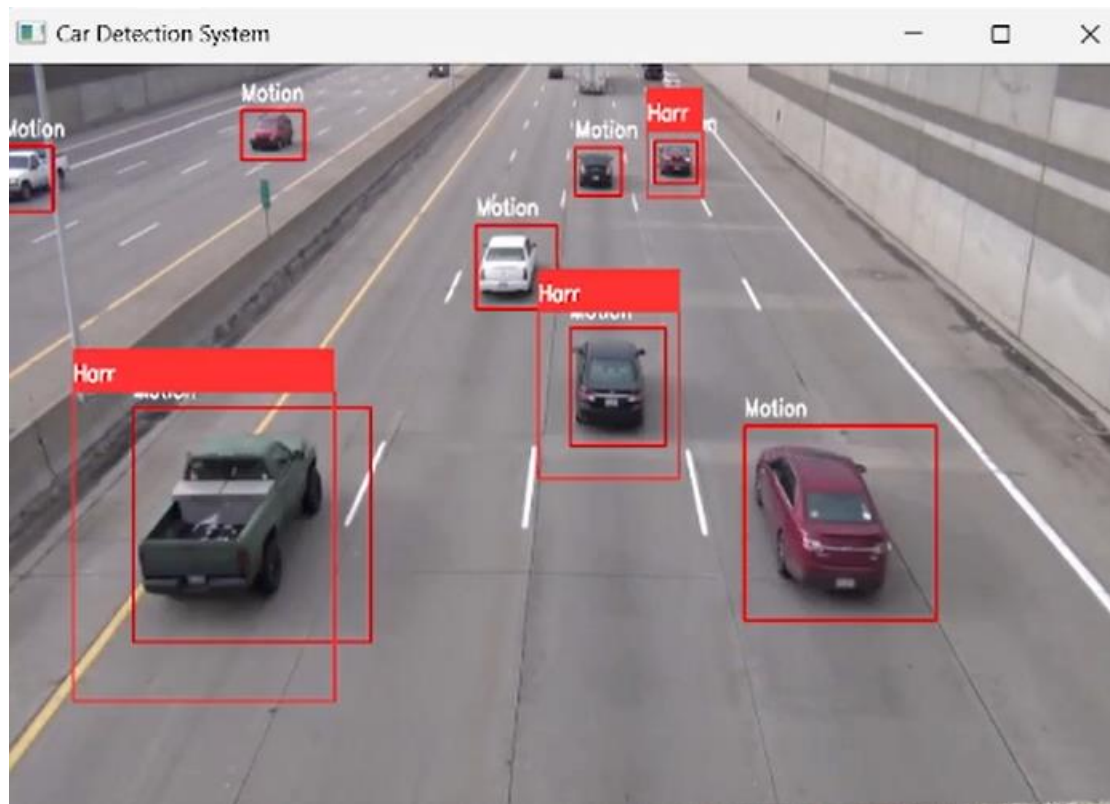
We Use cars.xml file for detecting the object as the car.

Output 1:

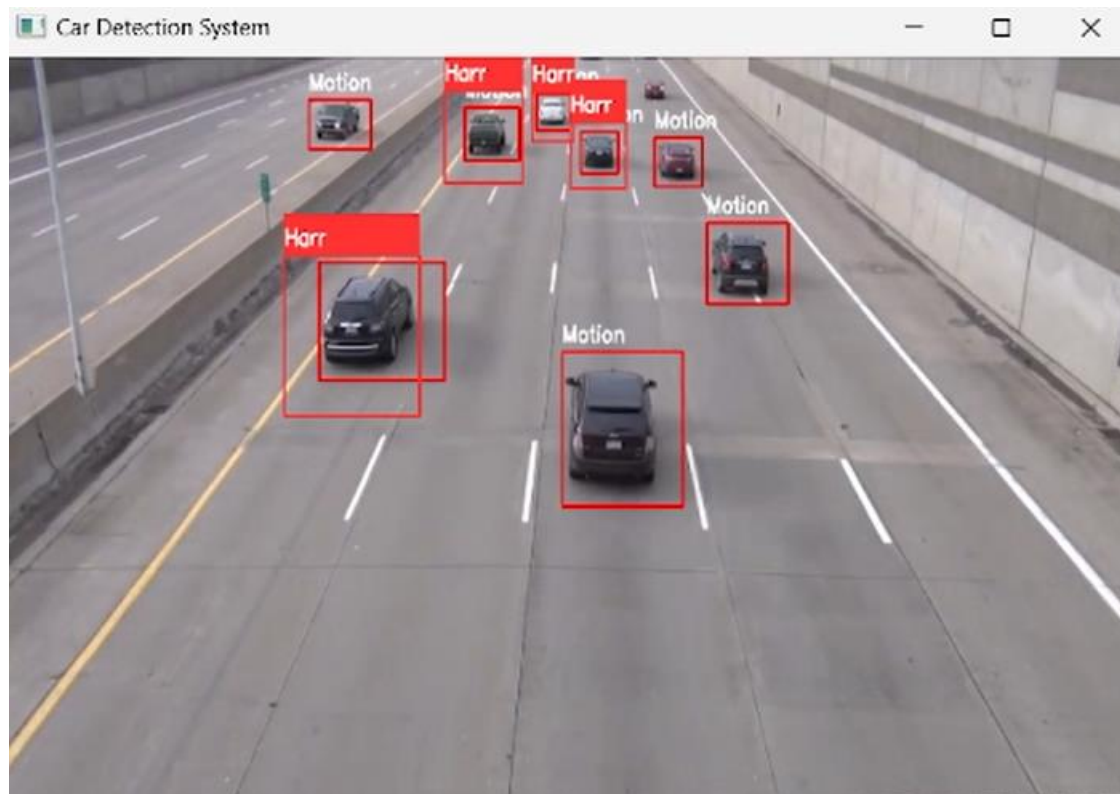
Here White car is due to only motion detection right corner red car also.

Whereas Black and green car are due to both Harr and Motion.

According to the above table if one is active so we can display that car.

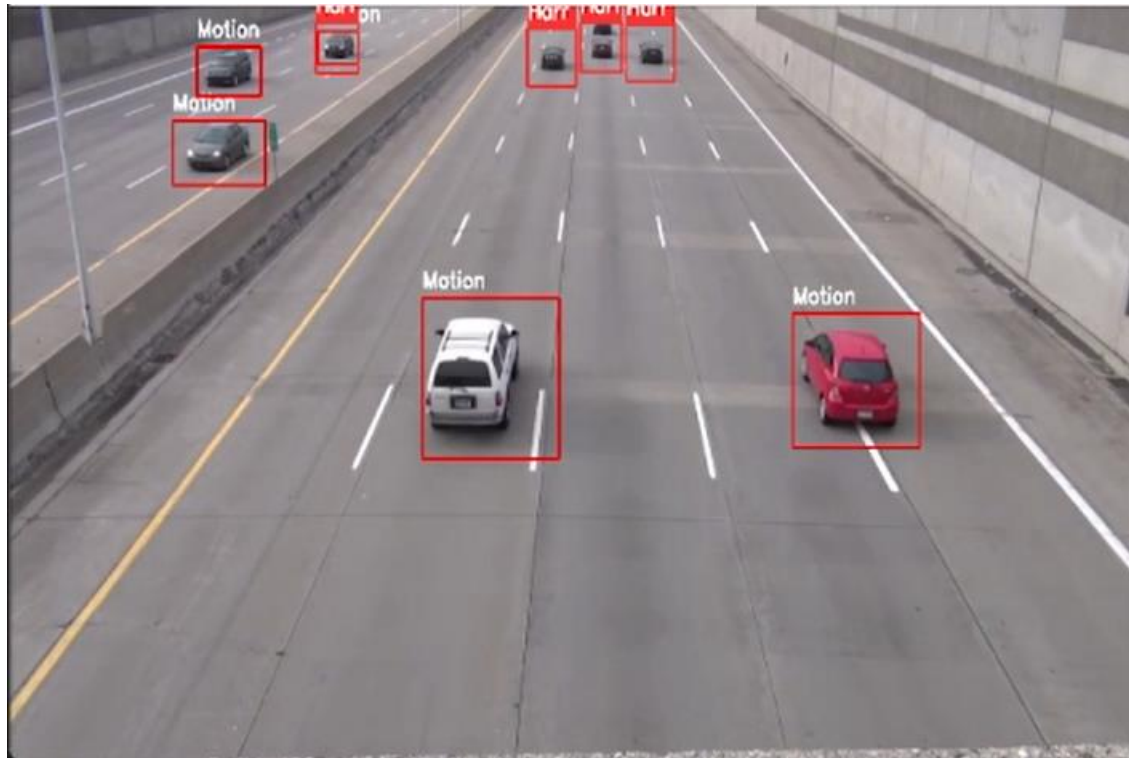


Output 2:



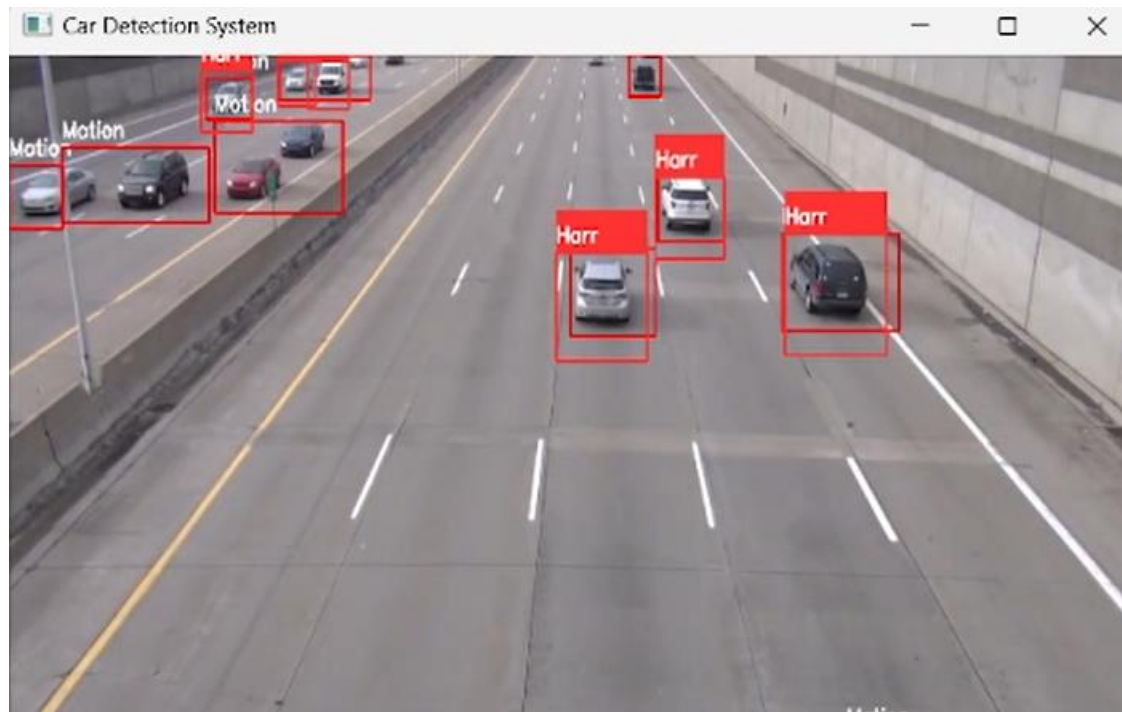
Some are detected due to only motion and some are detected using both motion and harr.

Output 3:



These all due to only motion.

Output 4:



Right side due to Harr and Left Side due to Motion.

Code:

```
1 import cv2
2 import numpy as np
3
4 cap = cv2.VideoCapture('video.mp4')
5 car_cascade = cv2.CascadeClassifier('cars.xml')
6
7 while True:
8     ret, frames1 = cap.read()
9     ret, frames2 = cap.read()
10    gray = cv2.cvtColor(frames1, cv2.COLOR_BGR2GRAY)
11
12    # For Motion:
13    cars = car_cascade.detectMultiScale(gray, 1.1, 9)
14    diff = cv2.absdiff(frames1, frames2)
15
16    # For Motion:
17    diff_gray = cv2.cvtColor(diff, cv2.COLOR_BGR2GRAY)
18    blur = cv2.GaussianBlur(diff_gray, (5, 5), 0)
19
20    # For Car:
21    _, thresh = cv2.threshold(blur, 20, 255, cv2.THRESH_BINARY)
22    dilated = cv2.dilate(thresh, None, iterations=3)
23
24    contours, _ = cv2.findContours(dilated, cv2.RETR_TREE, cv2.CHAIN_APPROX_SIMPLE)
25
26    # For Motion:
27    for contour in contours:
28        (x, y, w, h) = cv2.boundingRect(contour)
29        if cv2.contourArea(contour) < 1000:
30            continue
31        cv2.rectangle(frames1, (x, y), (x + w, y + h), (0, 0, 255), 2)
32        cv2.putText(frames1, 'Motion', (x, y - 10),
33                    cv2.FONT_HERSHEY_SIMPLEX, 0.7, (255, 255, 255), 2)
34
35    # For Car:
36    for (x, y, w, h) in cars:
37        plate = frames1[y:y + h, x:x + w]
38        cv2.rectangle(frames1, (x, y), (x + w, y + h), (51, 51, 255), 2)
39        cv2.rectangle(frames1, (x, y - 40), (x + w, y), (51, 51, 255), -2)
40        cv2.putText(frames1, 'Harr', (x, y - 10),
41                    cv2.FONT_HERSHEY_SIMPLEX, 0.7, (255, 255, 255), 2)
42        cv2.imshow('car', plate)
43
44    frames1 = cv2.resize(frames1, (600, 400))
45    cv2.putText(frames1, "Name: {}".format('RAHUL VARMA'), (10, 570), cv2.FONT_HERSHEY_SIMPLEX, 1, (0, 255, 255), 3)
46    cv2.putText(frames1, "Roll No: {}".format('S20200010212'), (10, 600), cv2.FONT_HERSHEY_SIMPLEX, 1, (0, 255, 255), 3)
47
48    cv2.imshow('Car Detection System', frames1)
49    if cv2.waitKey(25) & 0xFF == ord('q'):
50        break
51
52 cap.release()
53 cv2.destroyAllWindows()
```

```

import cv2
import numpy as np

cap = cv2.VideoCapture('video.mp4')
car_cascade = cv2.CascadeClassifier('cars.xml')

while True:
    ret, frames1 = cap.read()
    ret, frames2 = cap.read()
    gray = cv2.cvtColor(frames1, cv2.COLOR_BGR2GRAY)

    # For Motion:
    cars = car_cascade.detectMultiScale(gray, 1.1, 9)
    diff = cv2.absdiff(frames1, frames2)

    # For Motion:
    diff_gray = cv2.cvtColor(diff, cv2.COLOR_BGR2GRAY)
    blur = cv2.GaussianBlur(diff_gray, (5, 5), 0)

    # For Car:
    _, thresh = cv2.threshold(blur, 20, 255, cv2.THRESH_BINARY)
    dilated = cv2.dilate(thresh, None, iterations=3)

    contours, _ = cv2.findContours(dilated, cv2.RETR_TREE, cv2.CHAIN_APPROX_SIMPLE)

    # For Motion:
    for contour in contours:
        (x, y, w, h) = cv2.boundingRect(contour)
        if cv2.contourArea(contour) < 1000:
            continue
        cv2.rectangle(frames1, (x, y), (x + w, y + h), (0, 0, 255), 2)
        cv2.putText(frames1, 'Motion', (x, y - 10),

```



```

        cv2.FONT_HERSHEY_SIMPLEX, 0.7, (255, 255, 255), 2)

# For Car:
for (x, y, w, h) in cars:
    plate = frames1[y:y + h, x:x + w]
    cv2.rectangle(frames1, (x, y), (x + w, y + h), (51, 51, 255), 2)
    cv2.rectangle(frames1, (x, y - 40), (x + w, y), (51, 51, 255), -2)
    cv2.putText(frames1, 'Harr', (x, y - 10),
                cv2.FONT_HERSHEY_SIMPLEX, 0.7, (255, 255, 255), 2)
    cv2.imshow('car', plate)

frames1 = cv2.resize(frames1, (600, 400))
cv2.putText(frames1, "Name: {}".format('RAHUL VARMA'), (10, 570), cv2.FONT_HERSHEY_SIMPLEX, 1, (0, 255,
255), 3)
cv2.putText(frames1, "Roll No: {}".format('S20200010212'), (10, 600), cv2.FONT_HERSHEY_SIMPLEX, 1, (0, 255,
255), 3)

cv2.imshow('Car Detection System', frames1)
if cv2.waitKey(25) & 0xFF == ord('q'):
    break

cap.release()
cv2.destroyAllWindows()

```

Detailed Explanation:

- The code uses the OpenCV library for computer vision and image processing. It starts by reading in a video file using `cv2.VideoCapture()`. Then it initializes a `cv2.CascadeClassifier` object with an XML file containing the trained Haar cascade for car detection.
- Inside the while loop, it reads the frames from the video file using `cap.read()` and applies some preprocessing. For motion detection, it computes the absolute difference between two consecutive frames using `cv2.absdiff()`, converts the result to grayscale using `cv2.cvtColor()`, applies a Gaussian blur using `cv2.GaussianBlur()`, and applies thresholding using `cv2.threshold()`. Then it dilates the resulting binary image using `cv2.dilate()`, and finds the contours using `cv2.findContours()`.
- For car detection, it uses the Haar cascade to detect cars in the frames using `car_cascade.detectMultiScale()`. Then it extracts the region of interest for each car using array slicing, and draws a rectangle around it using `cv2.rectangle()`. It also adds a label using `cv2.putText()`.
- Finally, it resizes the frames, adds some text information, and displays them using `cv2.imshow()`. If the user presses the 'q' key, the loop exits.

- Overall, this code combines two different techniques for detecting objects in a video: motion detection and Haar cascades. By combining these techniques, it is possible to achieve better detection performance and reduce false positives.