CGC ASSIGNMENT – 1

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Roll No: S20200010212

Motion Detection Assignment:

Motion detection is a technique used to detect changes in the position of an object or group of objects over time. It is typically used in security systems, surveillance cameras, and other applications where it is important to detect the presence or movement of objects in a scene.

There are several methods for motion detection, including:

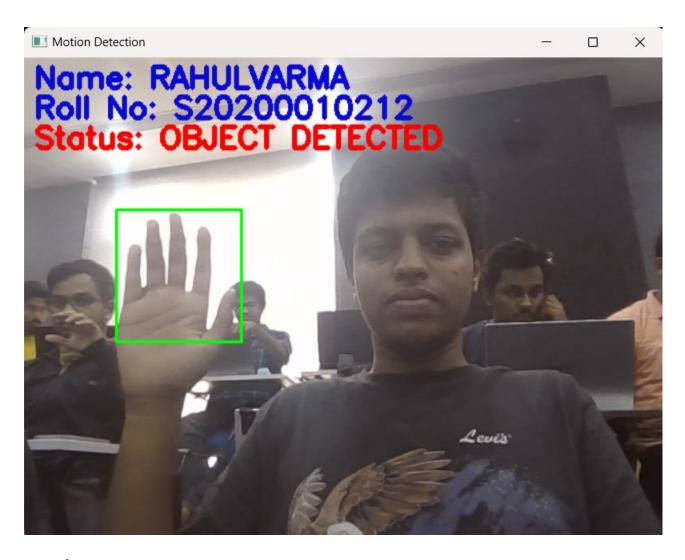
• Frame differencing: This method involves comparing consecutive frames of a video and identifying areas where there are significant differences between the two frames. These areas are likely to correspond to moving objects.

- Background subtraction: This method involves creating a static background model and subtracting it from each frame to identify areas of the frame that contain moving objects.
- Optical flow: This method involves tracking the movement of individual pixels within a frame to detect overall motion in the scene.
- Blob detection: This method involves identifying connected regions of pixels that have similar properties (such as color or intensity) and tracking their movement over time.

All these methods have their own advantages and disadvantages and the choice of method depends on the specific application and the type of data.

Threshold is changed accordingly for only the object detection which is moving the frames from one second to another second.

Motion Detected:



Code:

```
4 cap = cv2.VideoCapture(0)
       ret, frame1 = cap.read()
       gray1 = cv2.cvtColor(frame1, cv2.COLOR_BGR2GRAY)
       ret, frame2 = cap.read()
       gray2 = cv2.cvtColor(frame2, cv2.COLOR_BGR2GRAY)
       diff = cv2.absdiff(gray1, gray2)
       thresh = cv2.threshold(diff, 25, 255, cv2.THRESH_BINARY)[1]
       dilated = cv2.dilate(thresh, None, iterations=2)
       cnts, _ = cv2.findContours(dilated, cv2.RETR_EXTERNAL, cv2.CHAIN_APPROX_SIMPLE)
       for c in cnts:
           if cv2.contourArea(c) < 2500:
           (x, y, w, h) = cv2.boundingRect(c)
           cv2.rectangle(frame1, (x, y), (x + w, y + h), (0, 255, 0), 2)
           cv2.putText(frame1, "Status: {}".format('OBJECT DETECTED'), (10, 90), cv2.FONT_HERSHEY_SIMPLEX, 1, (0, 0, 255), 3)
       cv2.putText(frame1, "Name: {}".format('RAHULVARMA'), (10, 30), cv2.FONT_HERSHEY_SIMPLEX, 1, (215, 10, 10), 3)
       cv2.putText(frame1, "Roll No: {}".format('520200010212'), (10, 60), cv2.FONT_HERSHEY_SIMPLEX, 1, (215, 10, 10), 3)
       # Show the frame
       cv2.imshow("Motion Detection", frame1)
       gray1 = gray2
       if cv2.waitKey(1) & 0xFF == ord('q'):
48 cv2.destroyAllWindows()
```

Code:

```
import cv2
# Initialize webcam
cap = cv2.VideoCapture(0)
while True:
    # Read first frame
   ret, frame1 = cap.read()
   gray1 = cv2.cvtColor(frame1, cv2.COLOR_BGR2GRAY)
    # Read next frame
   ret, frame2 = cap.read()
   gray2 = cv2.cvtColor(frame2, cv2.COLOR BGR2GRAY)
   # Calculate difference between frames
   diff = cv2.absdiff(gray1, gray2)
    # Threshold the difference to identify motion
    thresh = cv2.threshold(diff, 25, 255, cv2.THRESH_BINARY)[1]
   # Dilate the thresholded image to fill in holes
    dilated = cv2.dilate(thresh, None, iterations=2)
   # Find contours in the dilated image
   cnts, _ = cv2.findContours(dilated, cv2.RETR_EXTERNAL, cv2.CHAIN_APPROX_SIMPLE)
    for c in cnts:
        if cv2.contourArea(c) < 2500:</pre>
            continue
```

```
(x, y, w, h) = cv2.boundingRect(c)
        cv2.rectangle(frame1, (x, y), (x + w, y + h), (0, 255, 0), 2)
        cv2.putText(frame1, "Status: {}".format('OBJECT DETECTED'), (10, 90), cv2.FONT_HERSHEY_SIMPLEX, 1, (0,
0, 255), 3)
    cv2.putText(frame1, "Name: {}".format('RAHULVARMA'), (10, 30), cv2.FONT_HERSHEY_SIMPLEX, 1, (215, 10, 10),
3)
    cv2.putText(frame1, "Roll No: {}".format('S20200010212'), (10, 60), cv2.FONT HERSHEY SIMPLEX, 1, (215, 10,
10), 3)
    # Show the frame
   cv2.imshow("Motion Detection", frame1)
    # Update the previous frame
    gray1 = gray2
   if cv2.waitKey(1) & 0xFF == ord('q'):
       break
cap.release()
cv2.destroyAllWindows()
```