4. Probability II - random walks

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Last time

- Random numbers
- Frequencies and relative frequencies
- Random variables
- Probability distribution

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- When they are in contact they can transmit infection
- And they can recover

Goals for today

- Random motion: Random walks
- Characterising variability

Random walks

Random walks

Brownian motion

- Watch a particle in water under microscope.
- Follows a random path: Brownian motion.
- Fundamental dynamical process in many domains:
 - Biology protein inside cell
 - Chemistry reactant in
 - Physics particle in fluid
 - Engineering jet noise
 - Economics stock price
 - Environmental sciences pollutant spreading out
 - Mathematics fundamental random process

Modelling random motion: Random walk

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- Simplest model: simple random walk:
 - 1 particle moving on integers in 1D
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lacksquare How can we generate jumps ± 1 with uniform probability?

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- Another solution: generate random Boolean (true / false) and convert:

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r = rand(Bool)
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■ How convert this to ± 1 ? Which is faster?

Simple random walk

■ Random walk: sequence of random jumps!

Simple random walk

- Random walk: sequence of random jumps!
- Don't use global scope; immediately *make a function*:

```
function walk(N)
    x = 0 # initial position
    positions = [x] # store the positions
    for i in 1:N
        x += jump()
        push!(positions, x)
    end
    return positions
end
```

Interactive animation of walker position

First instinct by now: Plot data and make it interactive

Interactive animation of walker position

- First instinct by now: Plot data and make it interactive
- Key trick:
- Pre-generate data so don't have different randomness each time:

```
using Interact

N = 100
positions = walk(N)

@manipulate for n in 1:N
    plot(positions[1:n], xlim=(0, N), ylim=(-20, 20), m=:o,
end
```

Shape of random walk

- Plot several walks in single figure using for
- Since for returns nothing, evaluate graph to plot:

```
p = plot(leg=false) # empty plot
N = 100

for i in 1:10 # number of walks
    plot!(walk(N))
end

p # or plot!()
```

■ Exercise: Animate position of several walkers simultaneously

Distribution of walker position

- \blacksquare Fix a time n, e.g. n=10 and think about X_n
- Can ask same questions as before:
 - What is mean position $\langle X_n \rangle$?
 - What is spread of X_n ?
 - What does probability distribution of X_n look like?

Random processes

- Notation:
 - \blacksquare Steps $S_i = \pm 1$
 - Position X_n at step n

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- Notation:
 - Steps $S_i = \pm 1$
 - $\hspace{-0.5cm} \hspace{-0.5cm} \hspace{-0cm} \hspace{-0.5cm} \hspace{-0.$
- $X_n = S_1 + S_2 + \dots + S_n = \sum_{i=1}^n S_i$
- lacksquare S_i are random variables; X_n is also random variable

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 - \blacksquare Steps $S_i = \pm 1$
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- $X_n = S_1 + S_2 + \dots + S_n = \sum_{i=1}^n S_i$
- lacksquare S_i are random variables; X_n is also random variable
- Collection $(X_n)_{n=1}^N$ is **random process** i.e. random variable at each time

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 - What is dynamics as a function of time?
 - How does mean position change as function of time?
 - How does spread change as function of time?
 - Number of sites visited up to time n
 - First time to reach certain position
- Last two questions cannot be answered by looking at single time n

Probability distribution of X_n

- $lacksquare X_n$ is discrete random variable
- Run "cloud" ("ensemble") of independent walkers, i.e. don't interact with one another
- To generate data, could use walk(N), but only need final position:

```
jump() = rand( (-1, +1) )
walk_position(N) = sum(jump() for i in 1:N)
```

■ Faster to generate all random numbers at once: julia walk_position2(N) = sum(rand((-1, +1), N))

Variability

- We have **finite sample** from ideal **population**
- If we repeat experiment, get different sample with different counts.
- How characterize this variability?

Shape of distribution

- See that position "clusters around" central value: expected value
- Values near extremes "never" occur

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- Characterise using summary statistics: numbers that summarise aspects of distribution
- Simplest: sample mean = average value

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- Characterise using summary statistics: numbers that summarise aspects of distribution
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■ Shape is "bell curve": **Gaussian** or **normal** distribution

Mean

 \blacksquare Given outcomes x_i for $i=1,\ldots,N$, (arithmetic) mean is

$$\bar{x} := \frac{1}{N} \sum_{i=1}^{N} x_i$$

Calculate in Julia:

```
mean(data) = sum(data) / length(data)
m = sum(n1_data) / length(n1_data)
```

- NB: mean is in Statistics standard library (no need to install)
- Add to plot using vline!([m])

Centre the data

■ Distribution "spreads out" from mean

Centre the data

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- Want to know **how far** it spreads

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■ Centre data by subtracting mean:

```
centered_data = data .- m
```

Spread

■ Measure spread as "average *distance from mean"

Spread

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- If just take mean of new data, get tiny result near 0:
 mean(data)

 \blacksquare (1e-14 means $1\times 10^{-14},$ i.e. a value that is effectively 0.)

Spread

- Measure spread as "average *distance from mean"
- If just take mean of new data, get tiny result near 0:
 mean(data)
- \blacksquare (1e-14 means 1×10^{-14} , i.e. a value that is effectively 0.)
- Why? Negative values *cancel out* positive values.
- Need to avoid cancellation. How?

- Options to avoid cancellation of displacements from mean:
 - take absolute value
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 - take absolute value
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```
spread = mean(abs.(centered_data)) # no standard name? variance = mean(centered_data .^ 2) \sigma = \sqrt{\text{variance}} @show spread, variance
```

- (Sample) variance defined by squaring
- \blacksquare So must take $\sqrt{}$ for "correct units" (metres vs. metres^2)

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- So must take $\sqrt{}$ for "correct units" (metres vs. metres^2)
- σ is called standard deviation
- For this distribution, both measures of spread give similar result

- Most data is in interval $[\mu 2\sigma, \mu + 2\sigma]$
- How much? Calculate!:

```
count(-2\sigma \ . < \ centered\_data \ . < \ 2\sigma) \ / \ length(centered\_data)
```

- Most data is in interval $[\mu 2\sigma, \mu + 2\sigma]$
- How much? Calculate!:

```
count(-2\sigma .< centered_data .< 2\sigma) / length(centered_data)
```

Approx. 95%: "universal" in many (but *not all* situations)

Summary

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Most data within 2 standard deviations of mean in common distributions that are result of adding many effects up