Object Detection: Sliding Windows

ECS797 Machine Learning for Visual Analysis
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Most slides from Jon Hays (adapted from Kristen Grauman)

Past lectures

- Category recognition
 - Bag of words using not-so-invariant local features.
- Instance recognition
 - Manifold learning with dimensionality reduction

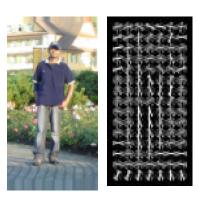
Today

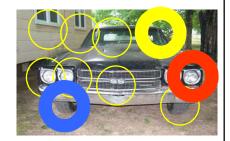
- Window-based generic object detection
 - basic pipeline
 - boosting classifiers
 - face detection as case study

Object category recognition: basic framework

- Build/train object model
 - Choose a representation
 - Learn or fit parameters of model / classifier
- Generate candidates in new image
- · Score the candidates

Object category recognition: representation choice



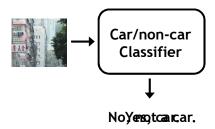


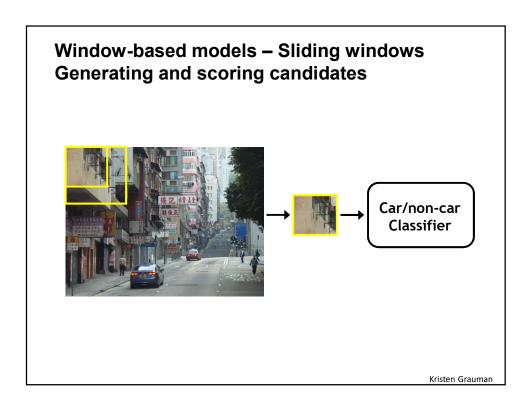
Window-based

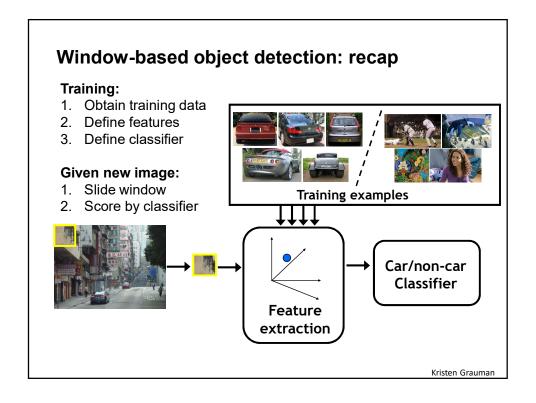
Part-based

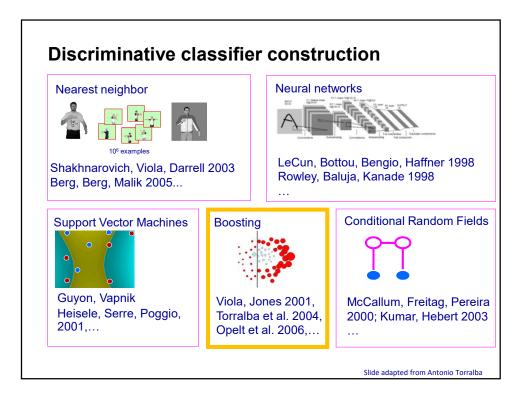
Window-based models Building an object model

Given the representation, train a binary classifier





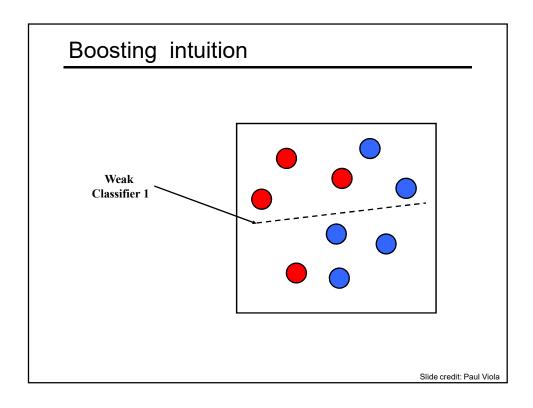


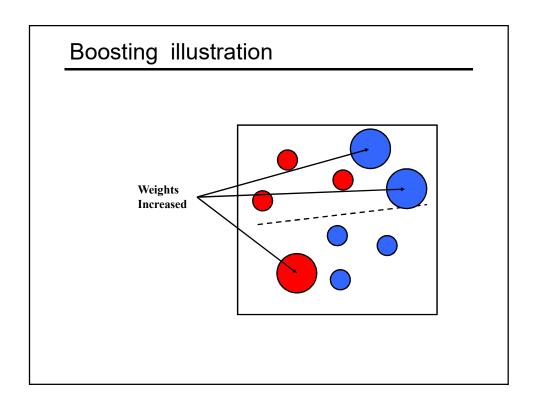


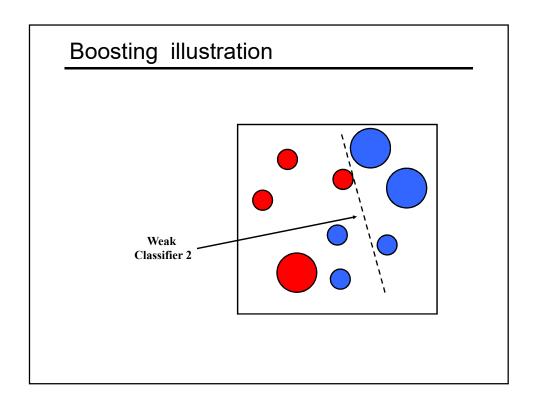
Influential Works in Detection

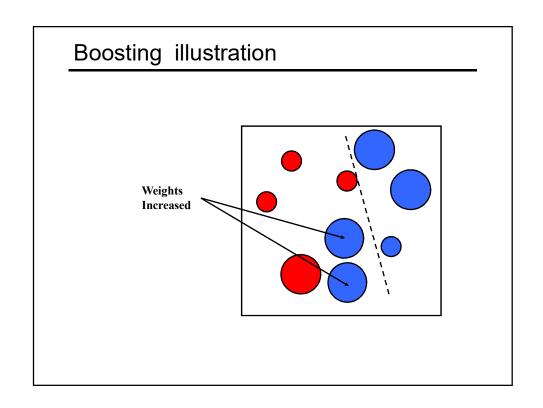
- Sung-Poggio (1994, 1998): ~1800 citations
 - Basic idea of statistical template detection (I think), bootstrapping to get "face-like" negative examples, multiple whole-face prototypes (in 1994)
- Rowley-Baluja-Kanade (1996-1998) : ~3700
 - "Parts" at fixed position, non-maxima suppression, simple cascade, rotation, pretty good accuracy, fast
- Schneiderman-Kanade (1998-2000,2004): ~1750
 - Careful feature engineering, excellent results, cascade
- Viola-Jones (2001, 2004): ~8500
 - Haar-like features, Adaboost as feature selection, hyper-cascade, very fast, easy to implement
- Dalal-Triggs (2005): ~4700
 - Careful feature engineering, excellent results, HOG feature, online code
- Felzenszwalb-Huttenlocher (2000): ~950
 - Efficient way to solve part-based detectors
- Felzenszwalb-McAllester-Ramanan (2008)? ~1300
 - Excellent template/parts-based blend

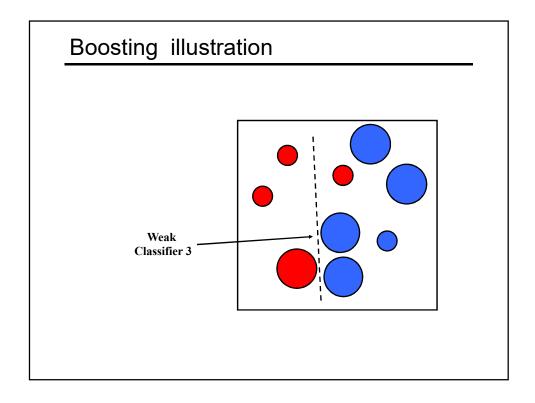
Slide: Derek Hoiem

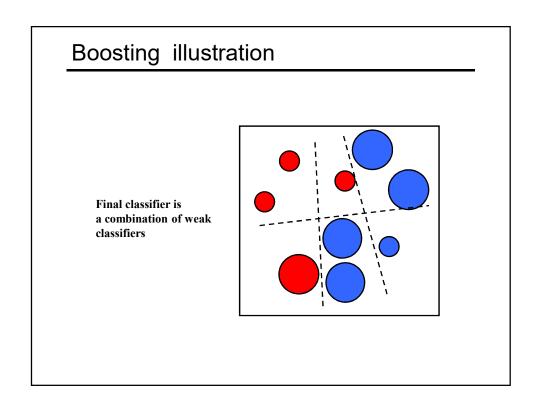












Boosting: training

- Initially, weight each training example equally
- In each boosting round:
 - Find the weak learner that achieves the lowest weighted training error
 - Raise weights of training examples misclassified by current weak learner
- Compute final classifier as linear combination of all weak learners (weight of each learner is directly proportional to its accuracy)
- Exact formulas for re-weighting and combining weak learners depend on the particular boosting scheme (e.g., AdaBoost)

Slide credit: Lana Lazebnik

Viola-Jones face detector

ACCEPTED CONFERENCE ON COMPUTER VISION AND PATTERN RECOGNITION 2001

Rapid Object Detection using a Boosted Cascade of Simple Features

Paul Viola viola@merl.com Mitsubishi Electric Research Labs 201 Broadway, 8th FL Cambridge, MA 02139 Michael Jones
mjones@crl.dec.com
Compaq CRL
One Cambridge Center
Cambridge, MA 02142

Abstract

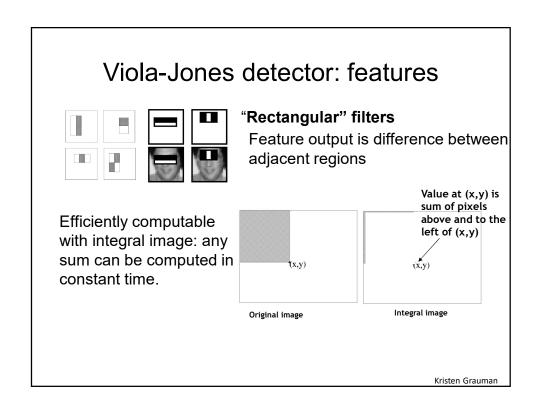
This paper describes a machine learning approach for vi-

tected at 15 frames per second on a conventional 700 MHz Intel Pentium III. In other face detection systems, auxiliary information, such as image differences in video sequences,

Viola-Jones face detector

Main idea:

- Represent local texture with efficiently computable "rectangular" features within window of interest
- Select discriminative features to be weak classifiers
- Use boosted combination of them as final classifier
- Form a cascade of such classifiers, rejecting clear negatives quickly

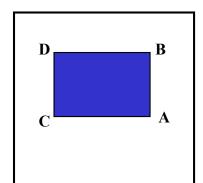


Computing sum within a rectangle

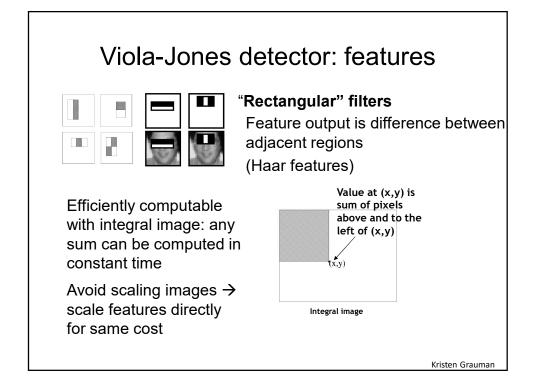
- Let A,B,C,D be the values of the integral image at the corners of a rectangle
- Then the sum of original image values within the rectangle can be computed as:

$$sum = A - B - C + D$$

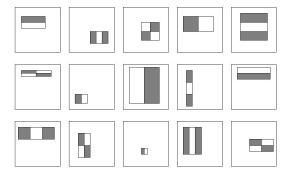
 Only 3 additions are required for any size of rectangle!



Lana Lazebnik



Viola-Jones detector: features



Considering all possible filter parameters: position, scale, and type:

180,000+ possible features associated with each 24 x 24 window

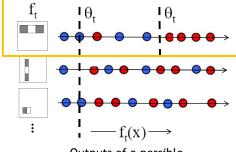
Which subset of these features should we use to determine if a window has a face?

Use AdaBoost both to select the informative features and to form the classifier

Kristen Grauman

Viola-Jones detector: AdaBoost

 Want to select the single rectangle feature and threshold that best separates positive (faces) and negative (nonfaces) training examples, in terms of weighted error.



Outputs of a possible rectangle feature on faces and non-faces.

Resulting weak classifier:

$$h_t(x) \ = \begin{cases} +1 & \text{if} \ f_t(x) > \theta_t \\ -1 & \text{otherwise} \end{cases}$$

For next round, reweight the examples according to errors, choose another filter/threshold combo.

- Given example images $(x_1, y_1), \ldots, (x_n, y_n)$ where $y_i = 0,1$ for negative and positive examples respectively.
- Initialize weights $w_{1,i}=\frac{1}{2m},\frac{1}{2l}$ for $y_i=0,1$ respectively, where m and l are the number of negatives and positives respectively.
- For t = 1, ..., T:
 - 1. Normalize the weights,

$$w_{t,i} \leftarrow \frac{w_{t,i}}{\sum_{j=1}^{n} w_{t,j}}$$

so that w_t is a probability distribution.

- 2. For each feature, j, train a classifier h_j which is restricted to using a single feature. The error is evaluated with respect to w_t , ϵ_j $\sum_{i} w_i |h_j(x_i) - y_i|.$
- 3. Choose the classifier, h_t , with the lowest error ϵ_t .
- 4. Update the weights:

$$w_{t+1,i} = w_{t,i}\beta_t^{1-e_i}$$

where $e_i=0$ if example x_i is classified correctly, $e_i=1$ otherwise, and $\beta_t=\frac{\epsilon_t}{1-\epsilon_t}$.

• The final strong classifier is:

$$h(x) = \begin{cases} 1 & \sum_{t=1}^{T} \alpha_t h_t(x) \ge \frac{1}{2} \sum_{t=1}^{T} \alpha_t \\ 0 & \text{otherwise} \end{cases}$$

where $\alpha_t = \log \frac{1}{\beta_t}$

AdaBoost Algorithm

Start with uniform weights on training examples



For T rounds

← Evaluate weighted error for each feature, pick best.

Re-weight the examples:

← Incorrectly classified -> more weight Correctly classified -> less weight

Final classifier is combination of the weak ones, weighted according to error they had.

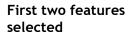
Freund & Schapire 1995

Viola-Jones Face Detector: Results





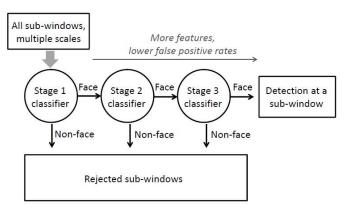






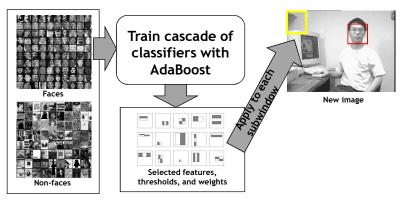
- Even if the filters are fast to compute, each new image has a lot of possible windows to search.
- · How to make the detection more efficient?

Cascading classifiers for detection



- Form a cascade with low false negative rates early on
- Apply less accurate but faster classifiers first to immediately discard windows that clearly appear to be negative





Train with 5K positives, 350M negatives Real-time detector using 38 layer cascade 6061 features in all layers

[Implementation available in OpenCV: http://www.intel.com/technology/computing/opencv/]

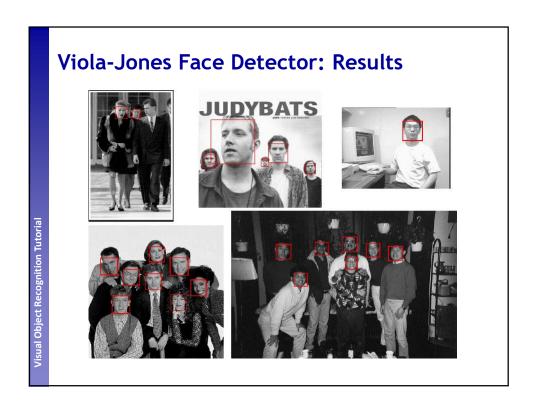
Kristen Grauman

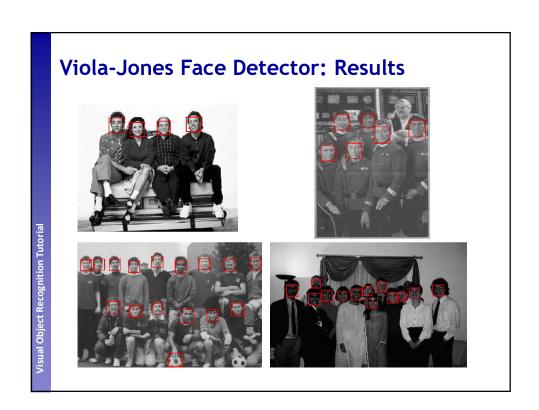
Viola-Jones detector: summary

- A seminal approach to real-time object detection
- Training is slow, but detection is very fast
- Key ideas
 - Features which can be evaluated very quickly with Integral Images
 - · Cascade model which rejects unlikely faces quickly
 - Mining hard negatives

P. Viola and M. Jones. *Rapid object detection using a boosted cascade of simple features*. CVPR 2001.

P. Viola and M. Jones. Robust real-time face detection. IJCV 57(2), 2004.





Viola-Jones Face Detector: Results



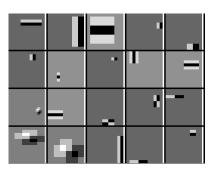


Visual Object Rec

Detecting profile faces?

Can we use the same detector?





Fund Object Becognition

Viola-Jones Face Detector: Results





Viola Jones Results





False detections							
Detector	10	31	50	65	78	95	167
Viola-Jones	76.1%	88.4%	91.4%	92.0%	92.1%	92.9%	93.9%
Viola-Jones (voting)	81.1%	89.7%	92.1%	93.1%	93.1%	93.2 %	93.7%
Rowley-Baluja-Kanade	83.2%	86.0%	-	-	-	89.2%	90.1%
Schneiderman-Kanade	0.00	1 7 81	10	94.4%	9 1	lue.	-
Roth-Yang-Ahuja	()=1	(40)	-	-	(94.8%)	mer I	-

MIT + CMU face dataset

Slide: Derek Hoiem

Schneiderman later results

Schneiderman 2004

Viola-Jones 2001 Roth et al. 1999 Schneiderman-Kanade 2000

	89.7%	93.1%	94.4%	94.8%	95.7%
Bayesian Network *	1	8	19	36	56
Semi- Naïve Bayes*	6	19	29	35	46
[6]	31	65			
[7]*				78	
[16]*			65		

Table 2. False alarms as a function of recognition rate on the MIT-CMU Test Set for Frontal Face Detection. * indicates exclusion of the 5 images of hand-drawn faces.

Slide: Derek Hoiem

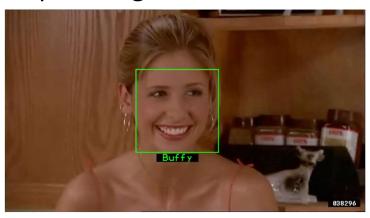
Speed: frontal face detector

• Schneiderman-Kanade (2000): 5 seconds

• Viola-Jones (2001): 15 fps

Slide: Derek Hoiem

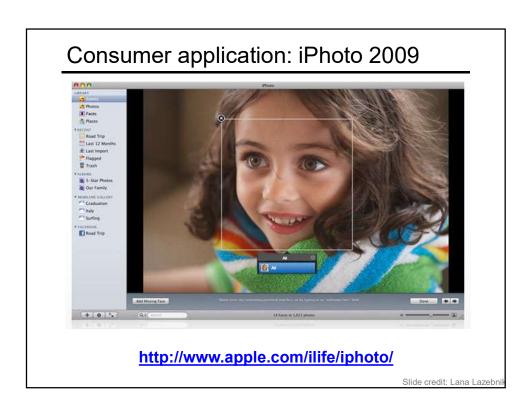
Example using Viola-Jones detector



Frontal faces detected and then tracked, character names inferred with alignment of script and subtitles.

Everingham, M., Sivic, J. and Zisserman, A. "Hello! My name is... Buffy" - Automatic naming of characters in TV video, BMVC 2006. http://www.robots.ox.ac.uk/~vgg/research/nface/index.html

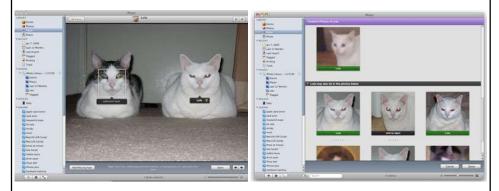




Consumer application: iPhoto 2009 Things iPhoto thinks are faces Slide credit: Lana Lazebnik

Consumer application: iPhoto 2009

Can be trained to recognize pets!



http://www.maclife.com/article/news/iphotos faces recognizes cats

Slide credit: Lana Lazebni

Discussion

What other categories are amenable to *window-based representation*?

Pedestrian detection

Detecting upright, walking humans also possible using sliding window's appearance/texture; e.g.,



SVM with Haar wavelets [Papageorgiou & Poggio, IJCV 2000]



Space-time rectangle features [Viola, Jones & Snow, ICCV 2003]



SVM with HoGs [Dalal & Triggs, CVPR 2005]

Kristen Grauman

Boosting: pros and cons

· Advantages of boosting

- · Integrates classification with feature selection
- Complexity of training is linear in the number of training examples
- · Flexibility in the choice of weak learners, boosting scheme
- · Testing is fast
- · Easy to implement

Disadvantages

- · Needs many training examples
- Often found not to work as well as an alternative discriminative classifier, support vector machine (SVM)
 - especially for many-class problems

Slide credit: Lana Lazebni

Window-based detection: strengths

Sliding window detection and global appearance descriptors:

- · Simple detection protocol to implement
- · Good feature choices critical
- · Past successes for certain classes

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Window-based detection: Limitations

High computational complexity

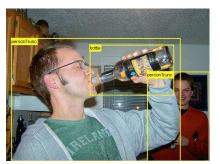
- For example: 250,000 locations x 30 orientations x 4 scales = 30,000,000 evaluations!
- If training binary detectors independently, means cost increases linearly with number of classes

With so many windows, false positive rate better be low

Limitations (continued)

Not all objects are "box" shaped



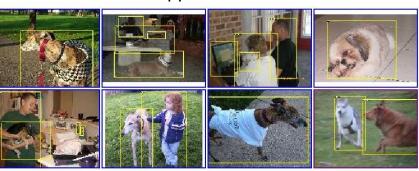


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Limitations (continued)

Non-rigid, deformable objects not captured well with representations assuming a fixed 2d structure; or must assume fixed viewpoint

Objects with less-regular textures not captured well with holistic appearance-based



Limitations (continued)

If considering windows in isolation, context is lost





Sliding window

Detector's view

Figure credit: Derek Hoiem

Kristen Grauman

Limitations (continued)

In practice, often entails large, cropped training set (expensive)

Requiring good match to a global appearance description can lead to sensitivity to partial occlusions





Image credit: Adam, Rivlin, & Shimshoni

Summary

Basic pipeline for window-based detection

- Model/representation/classifier choice
- · Sliding window and classifier scoring

Viola-Jones face detector

- Exemplar of basic paradigm
- Plus key ideas: rectangular features, Adaboost for feature selection, cascade, hard negatives.

Pros and cons of window-based detection