source	: http://	bigoche	eatshee	et.com/					
Search									
Algorithm Data Structure		Time Complexity		Space Complex	xity				
		Average	Worst	Worst					
Depth First Search (DFS)	Graph of V vertices and E edges	-	O(E + V)	O(V)					
Breadth First Search (BFS)	Graph of V vertices and E edges	-	O(E + V)	O(V)					
Binary search	Sorted array of n elements	O(log(n))	O(log(n))	O(1)					
Linear (Brute Force)	Array	O(n)	O(n)	O(1)					
Shortest path by Dijkstra,using a Min-heap as priority queue	Graph with V vertices and E edges	O((V + E) I	O((V + E) I	O(V)					
Shortest path by Dijkstra,using an unsorted array as priority queue	Graph with V vertices and E edges	O(V ^2)	O(V ^2)	O(V)					
Shortest path by Bellman- Ford	Graph with V vertices and E edges	O(V E)	O(V E)	O(V)					
Sorting	J								
Algorithm	Data Structure	Data Structure Time Complexity		Worst Case Auxiliary Space Complexity					
		Best	Average	Worst	Worst				
Quicksort	Array	O(n log(n))	O(n log(n))	O(n^2)	O(n)				
Mergesort	Array	O(n log(n))	O(n log(n))	O(n log(n))	O(n)				
Heapsort	Array	O(n log(n))	O(n log(n))	O(n log(n))	O(1)				
Bubble Sort	Array	O(n)	O(n^2)	O(n^2)	O(1)				
Insertion Sort	Array	O(n)	O(n^2)	O(n^2)	O(1)				
Select Sort	Array	O(n^2)	O(n^2)	O(n^2)	O(1)				
Bucket Sort	Array	O(n+k)	O(n+k)	O(n^2)	O(nk)				

Radix Sort	Array	O(nk)	O(nk)	O(nk)	O(n+k)						
Data S	tructure	es									
Data Structure Complexity								Space Comple	xity	1	
	Average			Wo			prst		Worst		
	Indexing	Search	Insertion	Deletion	Indexing	Search	Insertion	Deletion			
Basic Array	O(1)	O(n)	-	-	O(1)	O(n)	-	-	O(n)		
Dynamic Array	O(1)	O(n)	O(n)	O(n)	O(1)	O(n)	O(n)	O(n)	O(n)		
Singly-Linked List	O(n)	O(n)	O(1)	O(1)	O(n)	O(n)	O(1)	O(1)	O(n)		
Doubly-Linked List	O(n)	O(n)	O(1)	O(1)	O(n)	O(n)	O(1)	O(1)	O(n)		
Skip List	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(n)	O(n)	O(n)	O(n)	O(n log(n))		
Hash Table	-	O(1)	O(1)	O(1)	-	O(n)	O(n)	O(n)	O(n)		
Binary Search Tree	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(n)	O(n)	O(n)	O(n)	O(n)		
Cartresian Tree	-	O(log(n))	O(log(n))	O(log(n))	-	O(n)	O(n)	O(n)	O(n)		
B-Tree	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(n)		
Red-Black Tree	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(n)		
Splay Tree	-	O(log(n))	O(log(n))	O(log(n))	-	O(log(n))	O(log(n))	O(log(n))	O(n)		
AVL Tree	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(n)		
Heaps											
Heaps	Time Complexity										
	Heapify	Find Max	Extract Max	Increase Key	Insert	Delete	Merge				
Linked List (sorted)	-	O(1)	O(1)	O(n)	O(n)	O(1)	O(m+n)				
Linked List (unsorted)	-	O(n)	O(n)	O(1)	O(1)	O(1)	O(1)				
Binary Heap	O(n)	O(1)	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(m+n)				
Binomial Heap	-	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))				

Fibonacci Heap	-	O(1)	O(log(n))*	O(1)*	O(1)	O(log(n))*	O(1)			
Graphs										
Node / Edge Management Storage		Add Vertex	1	Remove Vertex						
Adjacency list	O(V + E)	O(1)	O(1)	O(V + E)	O(E)	O(V)				
Incidence list	O(V + E)	O(1)	O(1)	O(E)	O(E)	O(E)				
Adjacency matrix	O(V ^2)	O(V ^2)	O(1)	O(V ^2)	O(1)	O(1)				
Incidence matrix	O(V · E)	O(V · E)	O(V · E)	O(V · E)	O(V · E)	O(E)				