

实验目标

实现斐波拉契堆并与二叉堆比较效率（Dijkstra算法）

设计思路

二叉堆

数据存储设计

基本和之前写过的二叉堆一样

- 用数组来存储堆中元素
- 数组下标为元素的序号
 - 左儿子为 $2*i+1$,右儿子为 $2*i+2$

```
template <class T>
class MinHeap{
private:
    T *mHeap;           // 数据
    int mCapacity;       // 总的容量
    int mSize;           // 实际容量

private:
    // 最小堆的向下调整算法
    void filterdown(int start, int end);
    // 最小堆的向上调整算法(从start开始向上直到0, 调整堆)
    void filterup(int start);
public:
    MinHeap();
    MinHeap(int capacity);
    ~MinHeap();

    int getIndex(T data); // 返回data在二叉堆中的索引
    int remove(T data); // 即extract_min
    int insert(T data); // 将data插入到二叉堆中
    int decrease_key(T pos, T data);
    int empty();
    T find_min();
};
```

函数实现

- decrease_key
 - 该元素存在的情况下，将元素key值减小，再从该元素开始向上调整（调用filterup）

```
template <class T>
int MinHeap<T>::decrease_key(T pos,T data){
    int index = getIndex(pos);
    if(index == -1)return -1;
    if(mHeap[index] <= data)return -1;
    mHeap[index] = data;
    filterup(index);
    return 0;
}
```

- filterdown
 - 根据左右儿子的有无分类讨论
 - 右儿子不存在时，只比较左儿子
 - 右儿子存在时，选左右儿子中最小的，与父节点比较判断是否需要交换并进一步向下调整

```
template <class T>
void MinHeap<T>::filterdown(int start, int end)
{
    T temp;
    int left = 2*start + 1;
    int right = 2*start + 2;
    if(left > end)return;
    if(right > end)
    {
        if(mHeap[left] < mHeap[start])
        {
            temp = mHeap[left];
            mHeap[left] = mHeap[start];
            mHeap[start] = temp;
            filterdown(left,end);
            return;
        }else{
            return;
        }
    }else{
        if(mHeap[right] <= mHeap[left]&& mHeap[right] < mHeap[start])
        {
            temp = mHeap[right];
            mHeap[right] = mHeap[start];
            mHeap[start] = temp;
            filterdown(right,end);
            return;
        }else if(mHeap[left] < mHeap[right]&& mHeap[left] < mHeap[start])
```

```

    {
        temp = mHeap[left];
        mHeap[left] = mHeap[start];
        mHeap[start] = temp;
        filterdown(left, end);
        return;
    }
    else
    {
        return;
    }
}
}

```

- filterup

- 不断的比较当前节点与其父节点的key值大小来判断是否需要调整，直到当前节点key值>=父节点的key值为止或者是当前节点是root

```

template <class T>
void MinHeap<T>::filterup(int start){
    int father = (start - 1) / 2;
    while(father >= 0 && mHeap[father] > mHeap[start] )
    {
        T temp = mHeap[father];
        mHeap[father] = mHeap[start];
        mHeap[start] = temp;
        start = father;
        father = (start - 1) / 2;
    }
}

```

斐波那契堆

基本按照给的模板完成，略作修改，将map<T, Node*> mp换作vector<Node*>mp;

并在一些函数的参数中作了修改。

节点设置

```

struct Node {
    T key;
    int degree;
    bool mark;
    Node *p, *child, *left, *right;
    Node(T k) : key(k), degree(0), mark(false) {
        p = child = nullptr;
        left = right = this;
    }
};

```

数据存储

用Node* Min来寻找根链表

用vector<Node*>mp来保证在O(1)时间内寻找到某节点

n记录节点个数

```

template <class T>
class Fibonacci_Heap {
private:
    struct Node {
        T key;
        int degree;
        bool mark;
        Node *p, *child, *left, *right;
        Node(T k) : key(k), degree(0), mark(false) {
            p = child = nullptr;
            left = right = this;
        }
    };

    Node *Min;
    int n;
    //map<T, Node*> mp;
    vector<Node*> mp;
    void Del_Tree(Node *root);
    void Consolidate();
    void Link(Node *y, Node *x);
    void Cut(Node *x, Node *y);
    void Cascading_Cut(Node *y);
public:
    Fibonacci_Heap();
    ~Fibonacci_Heap();

    void Push(int id, T x);
    bool Empty();
    T Top();

```

```

void Pop();
void Decrease_Key(int id, T k);
};

```

函数实现

- Push
 - 将x放在mp中，为了以后实现decrease_key
 - 将x插入到根链表中
 - 更新Min

```

template <class T>
void Fibonacci_Heap<T>::Push(int id,T x) {
    while(id >= mp.size()){
        mp.push_back(nullptr);
    }
    Node* point = new Node(x);
    mp[id] = point;

    if(n == 0){
        Min = point;
    }else{
        Node* tmp = Min->left;
        tmp->right = point;
        Min->left = point;
        point->left = tmp;
        point->right = Min;
        if(Min->key > point->key)
        {
            Min = point;
        }
    }
    n++;
}

```

- Pop
 - 先判断是否有最小节点可以pop
 - 只有一个节点，pop掉它就好
 - 有多个节点，pop以后要维护斐波那契堆堆性质
 - 将Min的每一个子节点添加到根链表中
 - 将Min移除
 - 重置Min节点
 - 调用consolidate

```

template <class T>
void Fibonacci_Heap<T>::Pop() {

    if(n == 0) return;
    n--;
    if(n == 0) {
        delete Min;
        Min = nullptr;
        return;
    }
    Node *tmp = Min -> child;
    vector <Node *> chdlist;
    if(tmp != nullptr)
        do{
            chdlist.push_back(tmp);
            tmp = tmp -> right;
        }while(tmp != Min -> child);
    for(int i = 0; i < chdlist.size(); i++){
        Node *iterat = chdlist[i];
        Node *Mleft = Min -> left;
        iterat -> p = nullptr;
        Mleft -> right = iterat;    Min -> left = iterat;
        iterat -> left = Mleft;    iterat -> right = Min;
    }
    Node *l = Min -> left;
    Node *r = Min -> right;
    l -> right = r;
    r -> left = l;
    delete Min;
    Min = l;
    Consolidate();
}

```

- Decrease_key
 - 判断是否可以使用此操作
 - 调用cut和cascading-cut来维护斐波那契堆的性质
 - 更新Min

```

template<class T>
void Fibonacci_Heap<T>::Decrease_Key(int id, T k) {

    if(id>=mp.size() || mp[id] == nullptr){
        cout<<"The target doesn't exist"<<endl;
        return;
    }
    if(mp[id]->key < k){

```

```

        cout<<"The key of target  is higher than you thought"
<<endl;return;
    }
    Node* target = mp[id];
    target->key = k;
    Node* fa = target->p;
    if(fa!=nullptr && target->key < fa->key)
    {
        Cut(target,fa);
        Cascading_Cut(fa);
    }
    if(target->key < Min->key)
        Min = target;
}

```

- Consolidate

- 用vector<Node*>A来按照度的大小存储根节点中的元素
 - 几处的while循环是为了保证vector足够大，能够满足度数不会大于A.size()

```

while(cur->degree+1 > A.size())
    { A.push_back(nullptr); }

```

- 将根链表中每一个元素取出，放在root_list里面
- 用for循环实现 对每一个root_list中元素进行判断：是否有元素具有与它相同的degree
 - 若具有相同的degree,合并两个元素，调用Link将key值较小的节点插在Key值较大节点的子链表中；插入后可能新生成的节点与其他节点degree相同，故重复此过程直到不相同为止。（while实现）
- 用A中的元素创建一个新的根链表

```

template <class T>
void Fibonacci_Heap<T>::Consolidate() {
    //cout<<"consolidate"<<endl;
    vector<Node*>root_list;
    vector<Node*>A;
    Node* cur = Min->right;
    root_list.push_back(Min);
    while(cur != Min)
    {
        while(cur->degree+1 > A.size())
            { A.push_back(nullptr); }
        root_list.push_back(cur);
        cur = cur->right;
    }

    for(int i = 0;i < root_list.size();i++)

```

```

{
    Node* x = root_list[i];
    int d = x->degree;
    while(d + 10 > A.size()){A.push_back(nullptr);}
    //cout<<d<<endl;
    //cout<<A.size()<<endl;
    while(A[d] != nullptr)
    {
        Node* y = A[d];
        if(x->key > y->key)
        {
            Node* swap = x;
            x = y;
            y = swap;
        }
        Link(y,x);
        A[d] = nullptr;
        d++;
    }
    while(d+5 > A.size()){ A.push_back(nullptr);}
    A[d] = x;
}
Min = nullptr;
for(int j = 0; j < A.size(); j++)
{
    if(A[j] != nullptr){
        if(Min == nullptr)
        {
            Min = A[j];
            Min->left = Min; Min->right = Min;
        }
        else
        {
            Node* le = Min->left;
            le -> right = A[j];
            Min -> left = A[j];
            A[j]->right = Min;
            A[j]->left = le;
            if(Min->key > A[j]->key) Min = A[j];
        }
    }
}
}
}

```

- Link

- 将y从根链表中移除
- 将y添加到x的子节点中，跟新x的degree
- 置y的mark为false

```
template <class T>
void Fibonacci_Heap<T>::Link(Node *y, Node *x) {
    //remove y from the root list
    Node* l = y->left;
    Node* r = y->right;
    l->right = r;
    r->left = l;

    //make y a child of x, incrementing x.degree
    x->degree++;
    y->p = x;
    y->mark = false;
    if(x->child != nullptr){
        Node* t = x->child->right;
        t->left = y;
        y->left = x->child;
        y->right = t;
        x->child->right = y;
    }else
    {
        x->child = y;
        y->left = y; y->right = y;
    }
}
```

● Cut

- 将x从y的子链表中移除，更新y的degree
- 将x添加到根链表中
- 跟新x的p和mark

```
template <class T>
void Fibonacci_Heap<T>::Cut(Node *x, Node *y) {
    y->degree--;

    //remove x from child list of y
    Node* tmp = x;
    if(y->degree == 0){y->child = nullptr;}
    else{
        if(y->child == x)
            y->child = x->right;
```

```

        Node* left = x->left;
        Node* right = x->right;
        right->left = left;
        left->right = right;

    }

    //add x to the root list
    x->p = nullptr;
    x->mark = false;
    Node* temp = Min->left;
        temp->right = x;
        Min->left = x;
        x->left = temp;
        x->right = Min;
}

```

- Cascading_Cut
 - y的mark未被标记
 - 标记y
 - y的mark被标记
 - 递归查看y的父节点
 - cut (y, z)
 - cascading-cut (z)

```

template <class T>
void Fibonacci_Heap<T>::Cascading_Cut(Node *y) {
    Node* z = y->p;
    if(z!=nullptr){
        if(y->mark == false)
        {
            y->mark = true;
        }else
        {
            Cut(y,z);
            Cascading_Cut(z);
        }
    }
}

```

实验结果截图

```
2002 [329] 0->643->390->998
2003 [488] 0->643->88->495->999
2004 -----
2005 Time binary heap: 0.209971 s
2006 Time fibonacci heap: 0.048829 s
```

总结

斐波那契堆的时间复杂度小于二项堆的时间复杂度。但是斐波那契堆的编程复杂性远高于二项堆的编程复杂性。