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Comp 352
Assignment 3
Friday, June 12 2020

Question 1

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a)
```

```
Algorithm depth (position)
Input: Position position in a tree T
Output: Depth of position
If isRoot(position) then
return 0
else
return 1+depth(parent(position))
```

Algorithm ComputeDepths(T) **Input:** Tree T with n nodes

Output: Depths of all nodes of a tree T

temp_iterator ← new iterator of all positions() in tree T

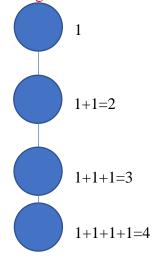
for each Position position in tree T do

Print the element stored in the node (this step is unnecessary, but clearer to user)

Call method depth on the node

Time Complexity: Let n be the number of nodes of T. The time complexity of depth algorithm depends on the depth of the position. It runs in O(d+1) time where d is the depth of pos in T. It is a recursive algorithm. The worst-case scenario for depth would be if we tried to calculate the depth of the most external node with depth n-1. This would result in depth running in O(n) time. This worst-case scenario would occur if the nodes were organized in one single long branch. In that case, the method ComputeDepths would run 1+2+3+n times, giving a time complexity of $O(n^2)$. To understand this better, refer to the figure below where the number of operations are listed for each node in this hypothetical tree.

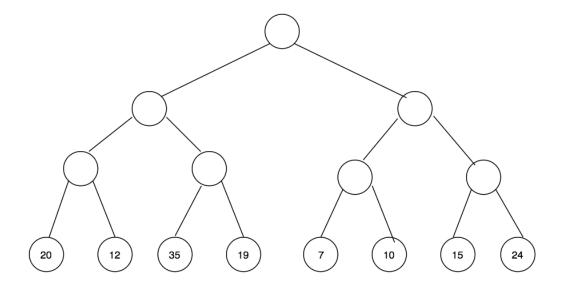
Space Complexity: (*I am not sure if this part is needed, so if not kindly skip it*). The space complexity of my algorithm is also O(n) because we need to allocate space for every node when using the iterable collection positions().

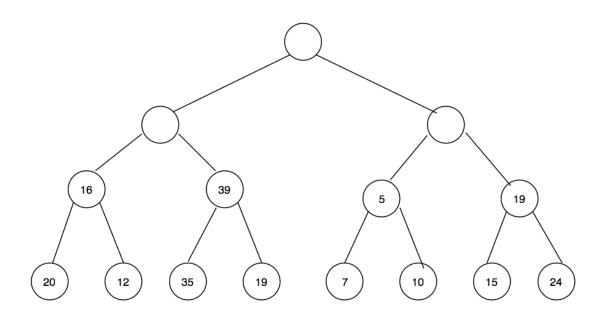


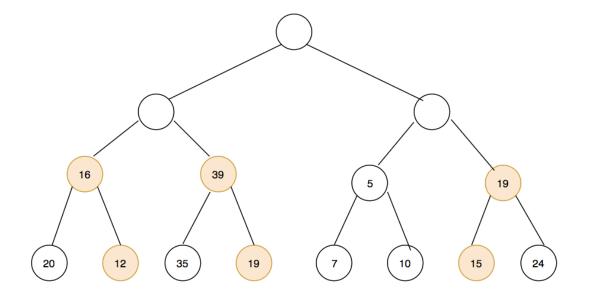
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b)
Algorithm Count-Full-Nodes(t)
Input: Binary search tree rooted at t
Output: Number of full nodes in the tree
       temp_queue ← new queue of type Node
      if t≠null then
              add t to temp_queue
       count_full←0
       while ! temp_queue.isEmpty() do
             temp_node ← temp_queue.dequeue()
              if temp node.right≠null ∧ temp node.left ≠null then
                     increment count
              if temp_node.left ≠null then
                     add temp_node.left to temp_queue
              if temp_node.right ≠null then
                     add temp_node.right to temp_queue
       return count_full
```

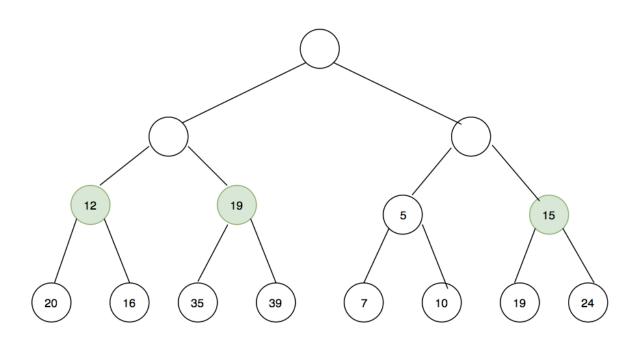
Time Complexity: Let n be the number of nodes in the binary search tree. In the while loop, we will have to check every single node in the tree. The operations inside the while loop all run in O(1) time, and since we have n nodes in the tree, the algorithm runs in O(n) time.

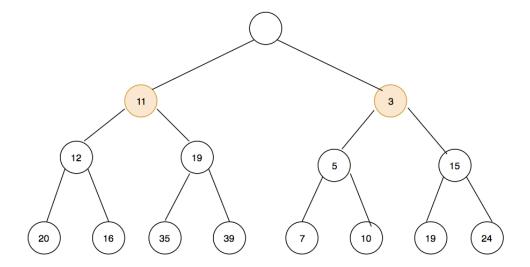
Space Complexity: (*I am not sure if this part is needed, so if not kindly skip it*). The space complexity of my algorithm is also O(n) because we have to allocate n spaces in the temp_queue for every node in the tree.

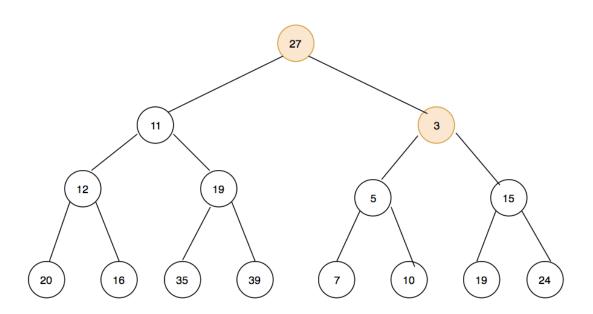


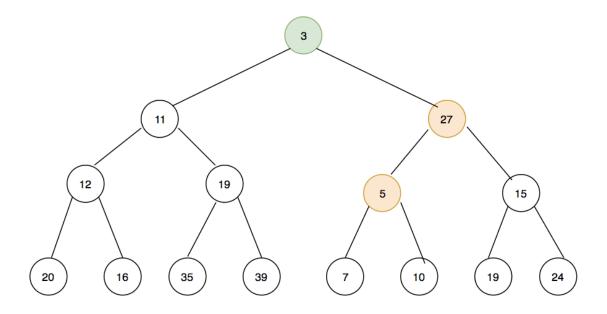


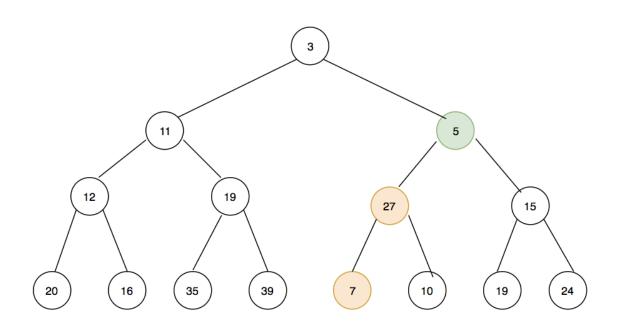


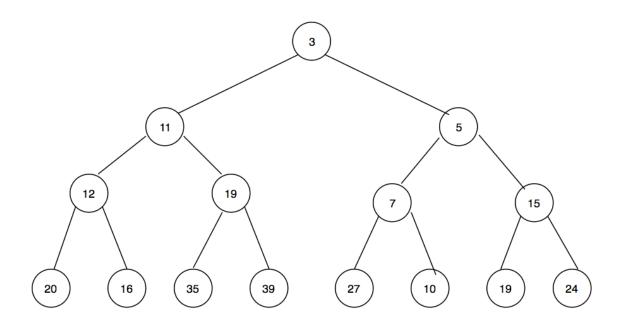




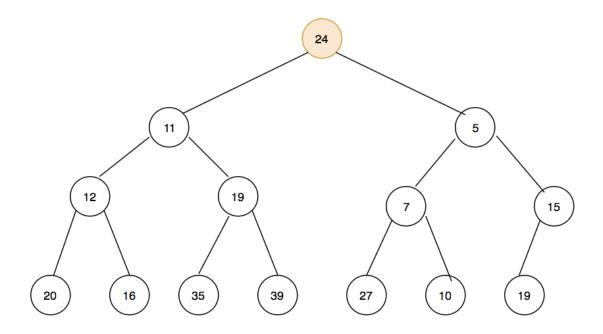


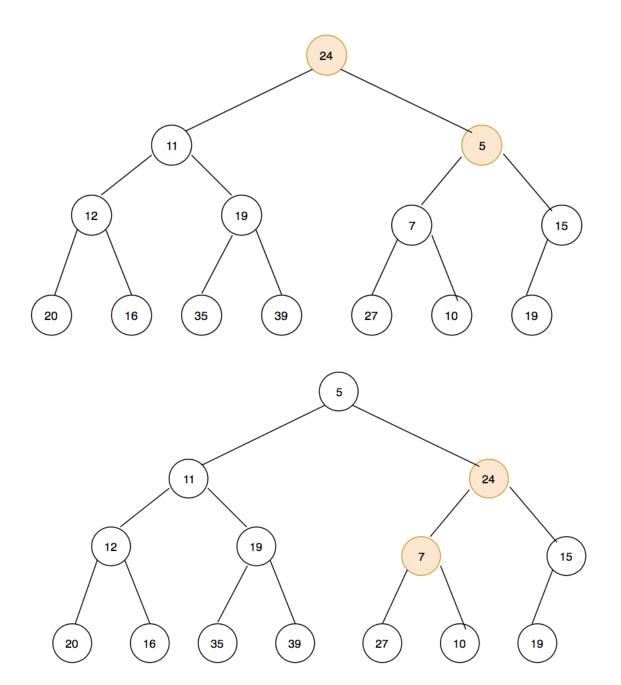


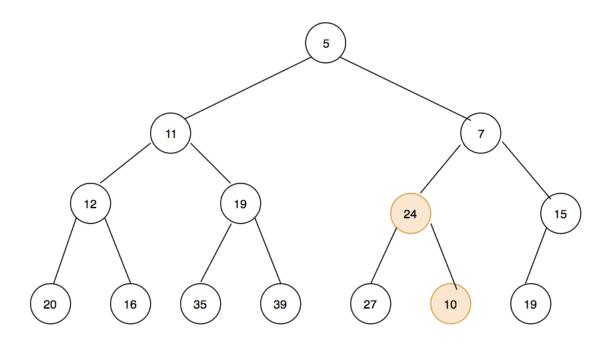


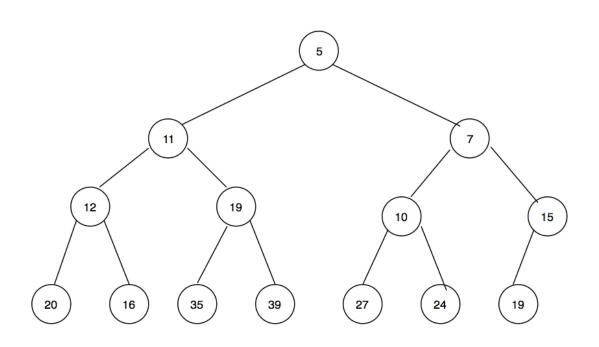


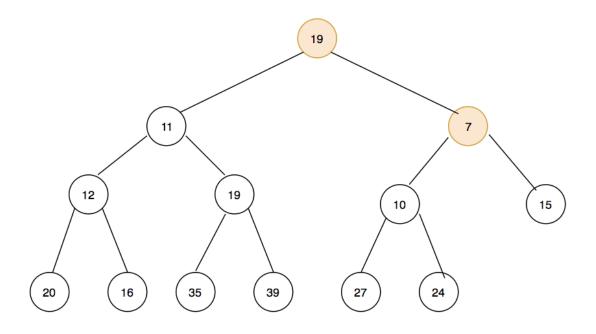
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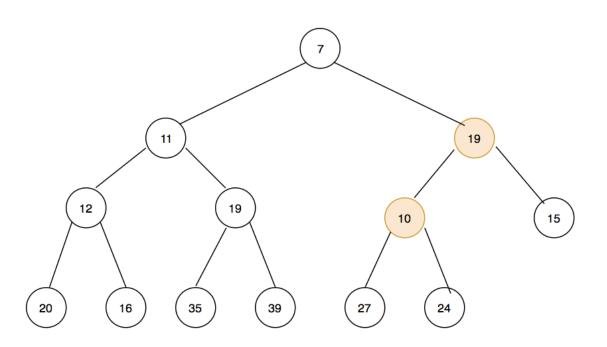


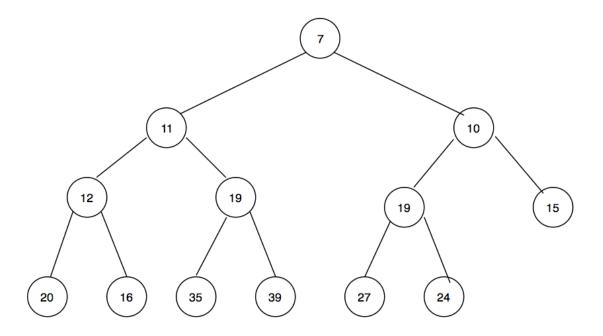


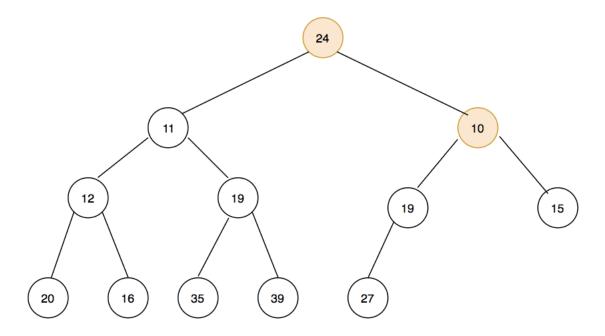


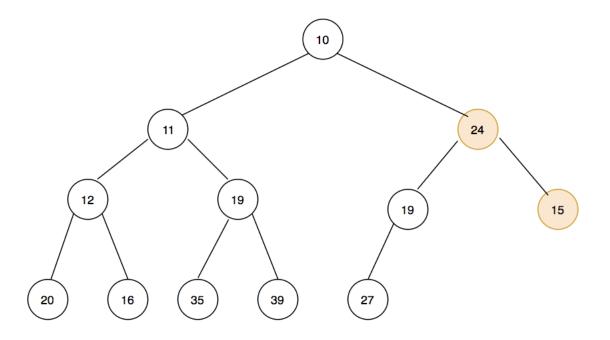


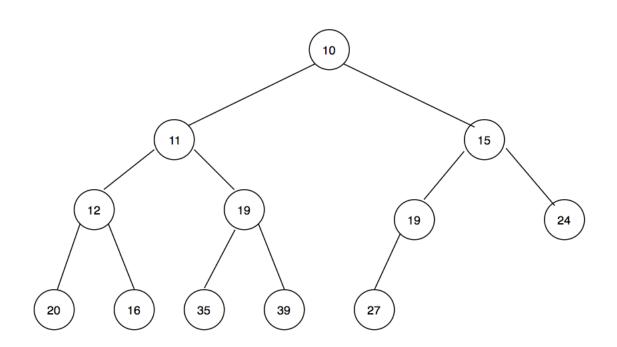


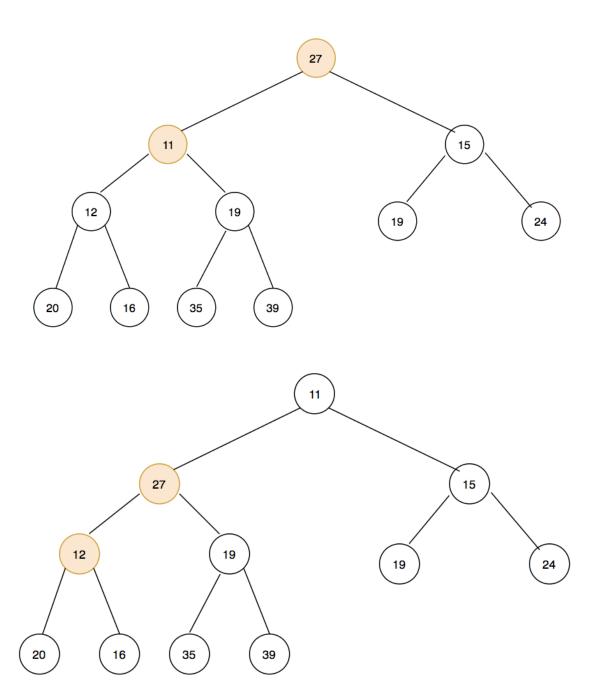


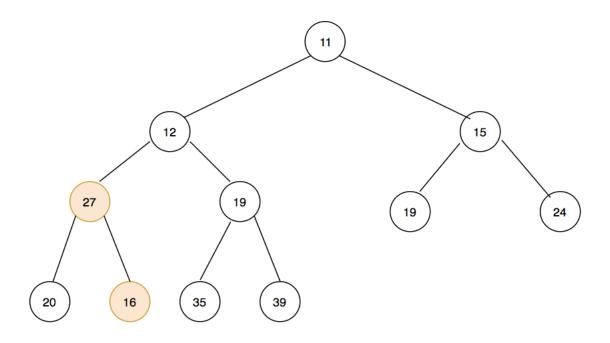


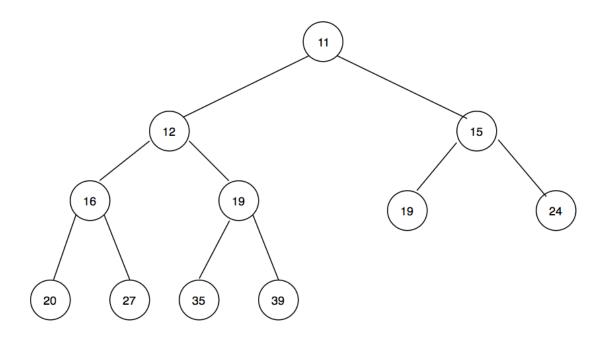


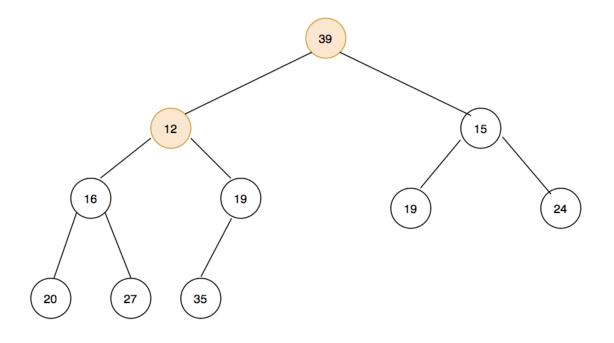


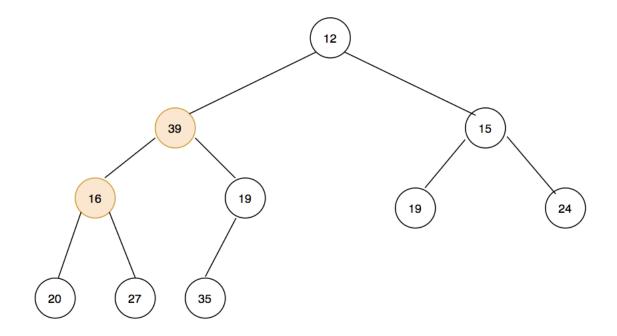


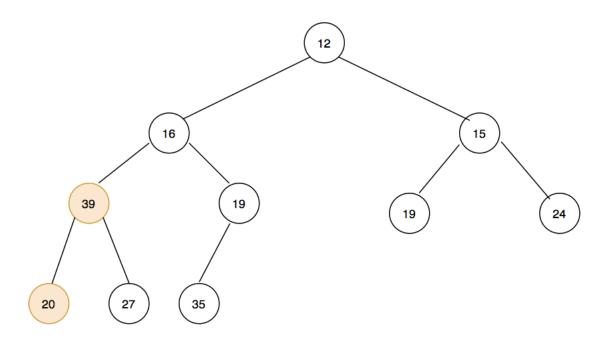


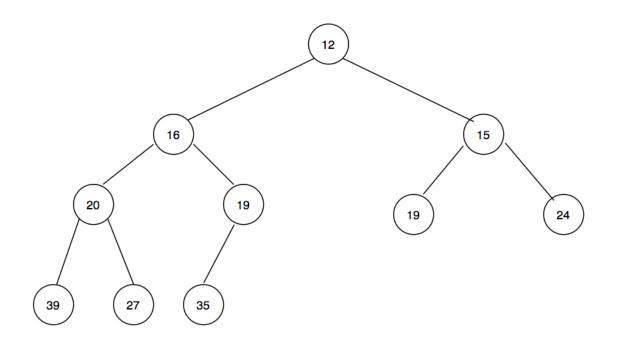


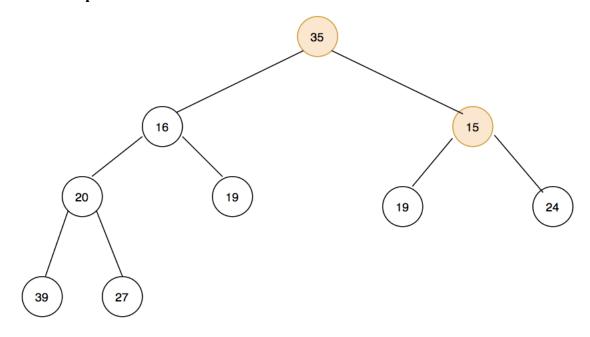


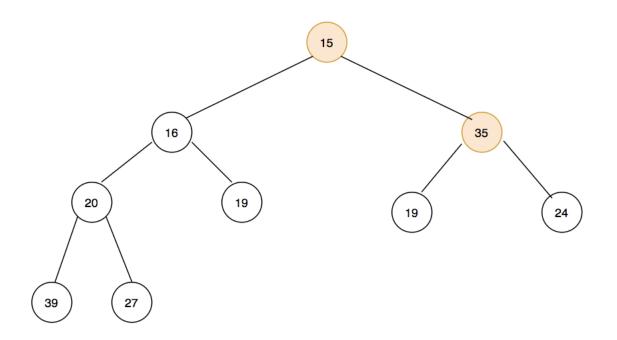


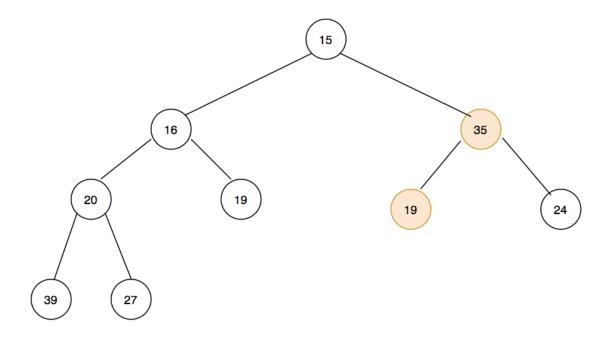


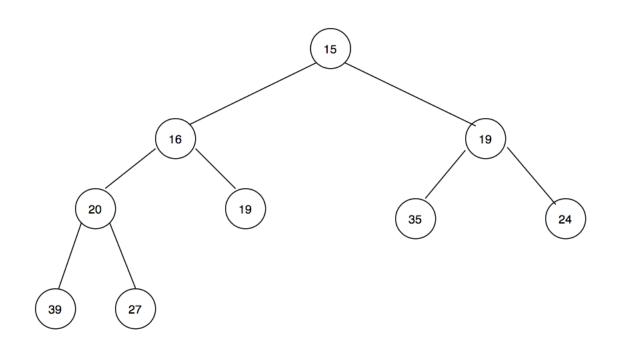








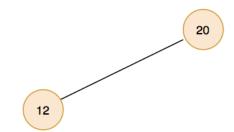


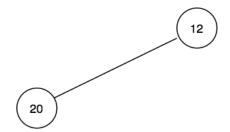


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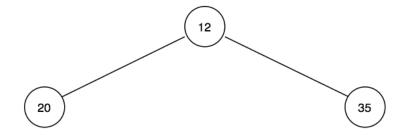


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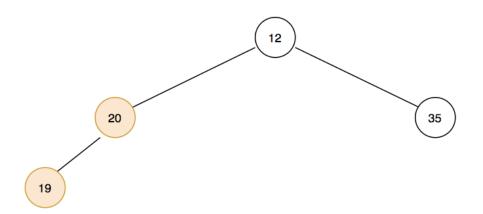


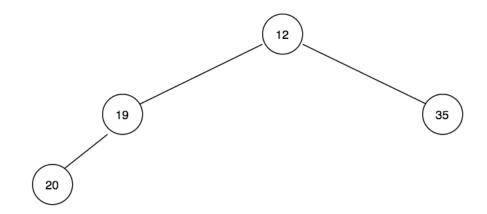


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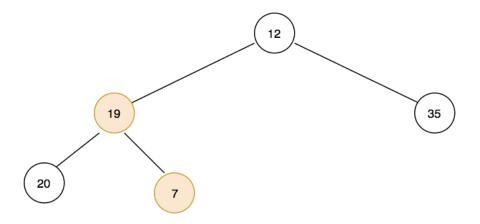


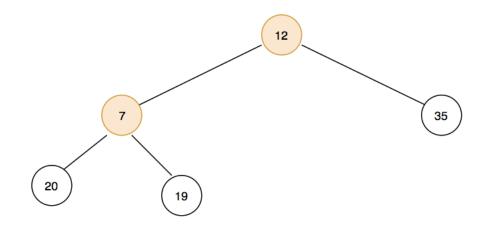
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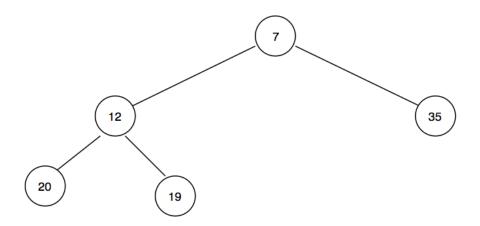




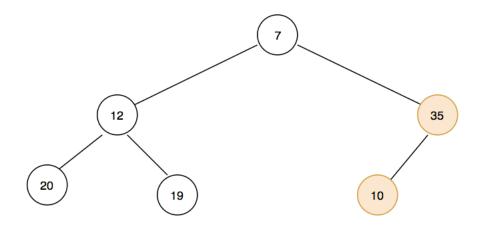
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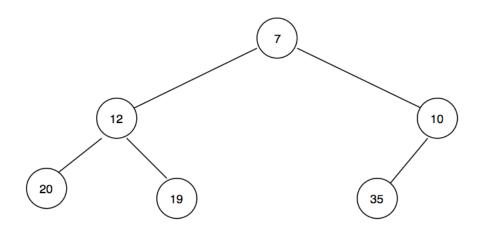




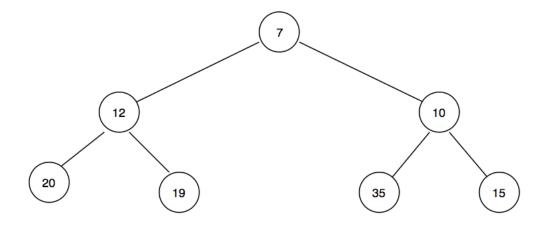


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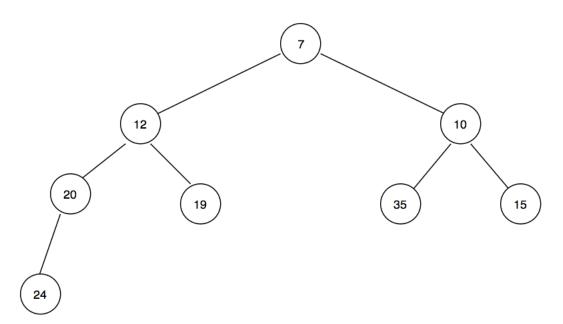




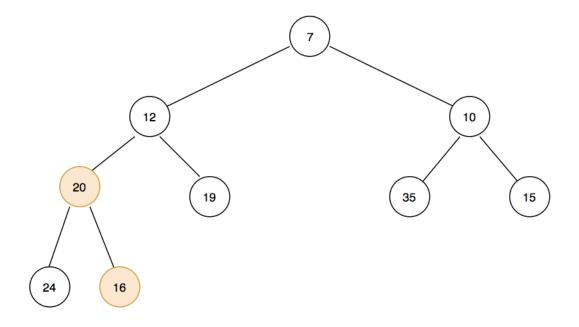
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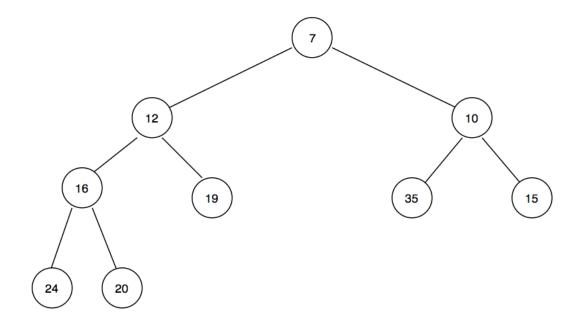


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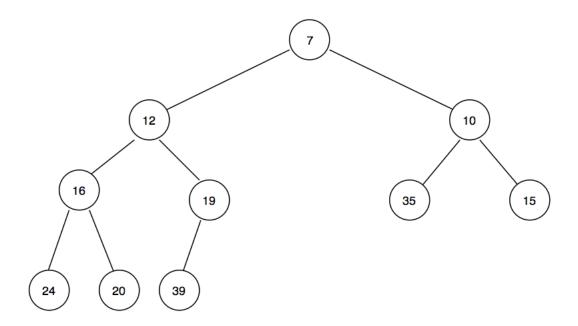


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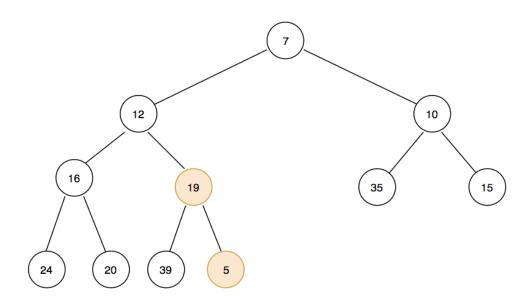


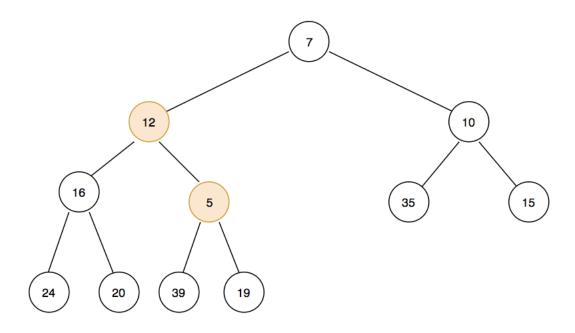


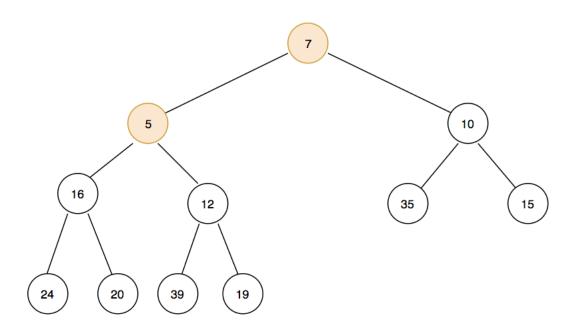
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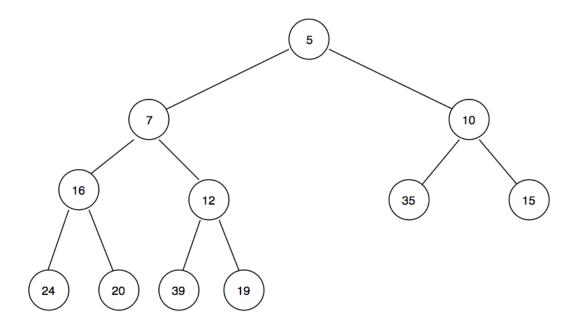


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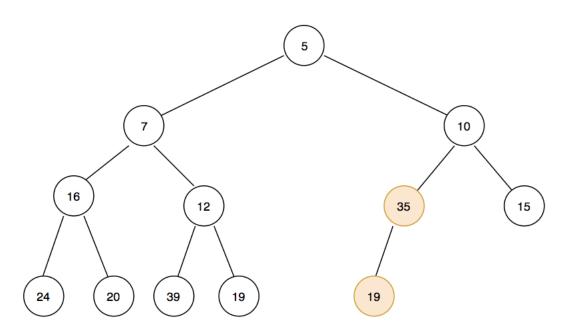


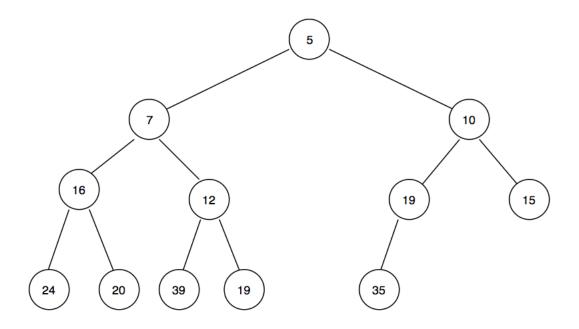




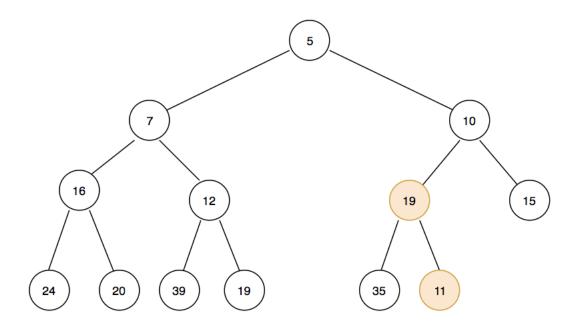


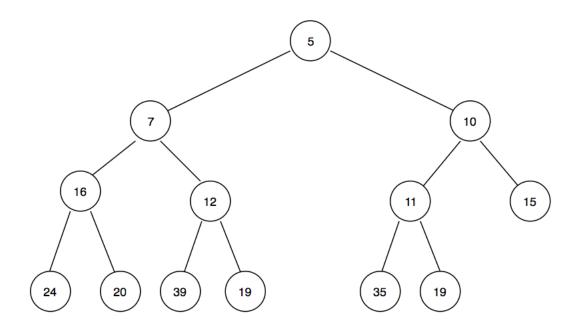
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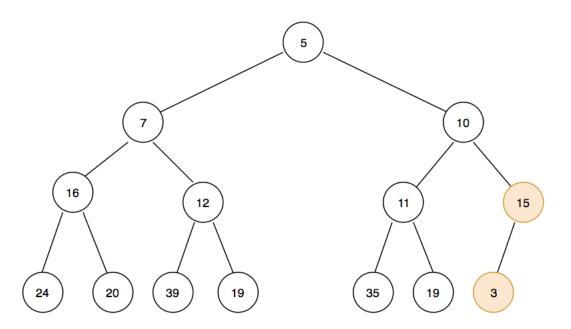


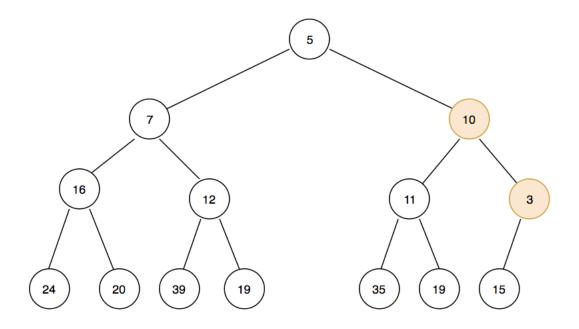
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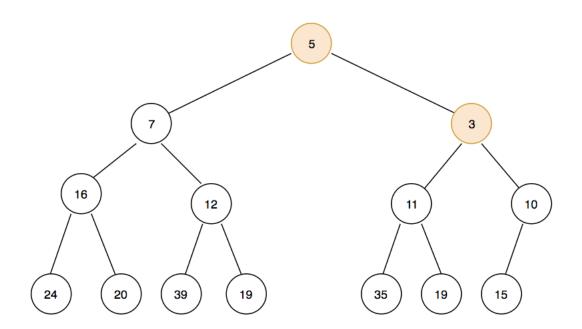


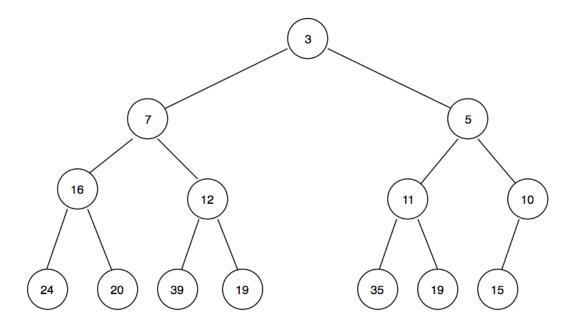


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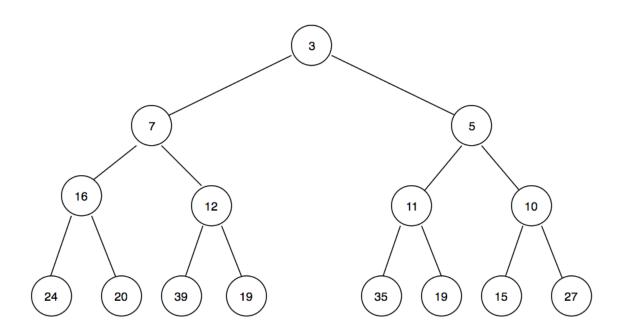


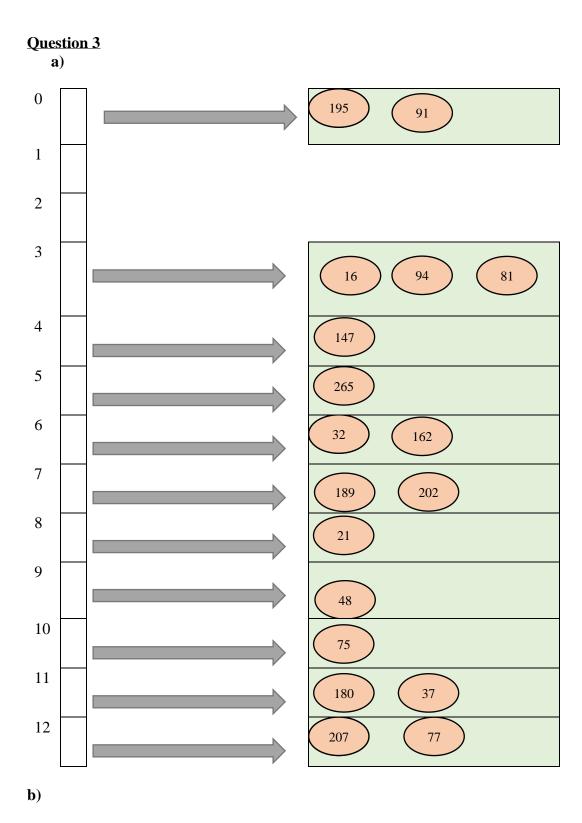






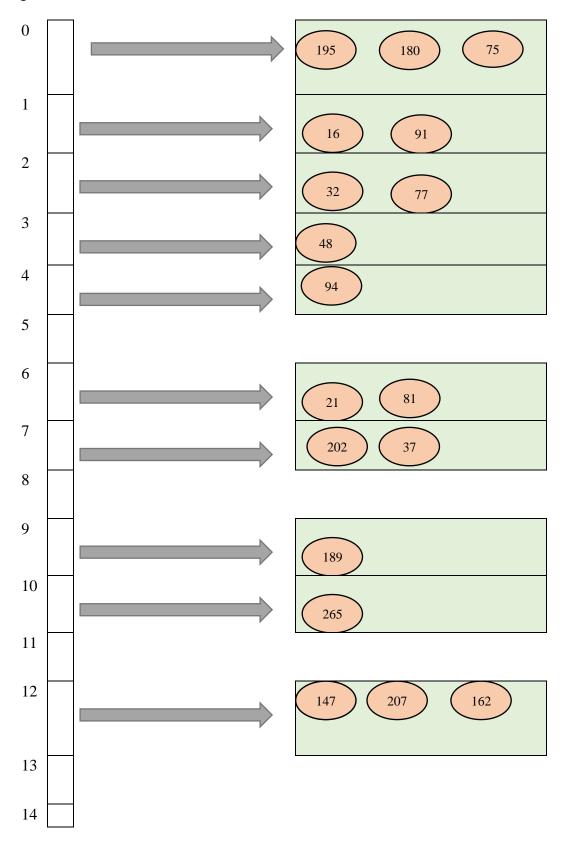
insert 27





Collisions occur on the indices 0,3,6,7,11,12. Collisions occur when there is already a key present and we try to insert another one. Hence, we have 1+2+1+1+1=7 max collisions.

Question 4



The load factor is defined as the number of keys stored in the hash table divided by the capacity. The number of keys is in this new hash table is held constant, but the capacity is increased by 15.38%. The load factor is smaller. The greater the capacity, the less occupied the hash table might be, and hence the less the probability of collisions occurring. For this particular example, the number of collisions actually increases! Number of collisions is: 2+1+1+1+1+2=8>7. The proposal does hold validity to it, but for this particular example, it might be better to increase the array even more. In the first example, the load factor is = 18/13 and in the second example, 18/15. For separate chaining it is advised that the load factor be less than 0.9. So, perhaps the array size should be at least 20. Increasing it to 15 will not have a big impact. Also be careful, if the load factor approaches 0, then the separate chaining may actually be wasteful in terms of space.

Question 5

i)

k=25

h(k)=6

0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18
						25												

k=12

h(k)=12

0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18
						25						12						

k=42

h(k)=4

Ī	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18
					42		25						12						

k=31

h(k)=12

d(k)=4

Probe: 12, 16 Collisions: 1

0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18
				42		25						12				31		

k=35

h(k)=16

d(k)=7

Probe: 16, 4, 11 Collisions: 1+2=3

0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18
				42		25					35	12				31		

k=39

h(k)=1

ſ	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18
		39			42		25					35	12				31		

Remove (31)

Ī	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18
Ī		39			42		25					35	12						

k=48 h(k)=10

0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18
	39			42		25				48	35	12						

Remove (25)

0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18
	39			42						48	35	12						

k=18 h(k)=18

()	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18
		39			42						48	35	12						18

k=29 h(k)=10

d(k)=6

Probe: 10,16 Collisions: 3+1=4

0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18
	39			42						48	35	12				29		18

k=29 h(k)=10

d(k)=6

Probe: 10,16,3 Collisions: 4+2=6

0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18
	39		29	42						48	35	12				29		18

k=35

h(k)=16

d(k)=7

Probe: 16, 4, 11, 18, 6 Collisions: 6+4=10

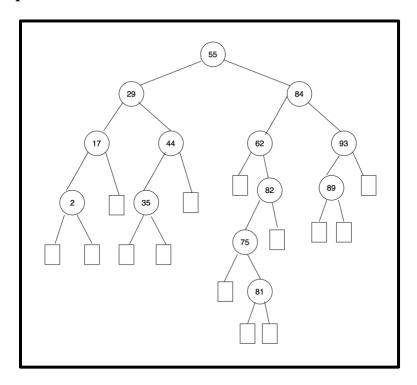
(0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18
		39		29	42		35				48	35	12				29		18

- ii) The longest cluster is of size 3. This occurs at indices 10,11,12. This cluster is obtained after we put 12,35, then 48.
- We have 10 total collisions as a result of the above insertions. I have indicated the number of cumulative collisions above, for every step in which the collisions increase. Interestingly, the last step yields the highest number of collisions (4).
- iv) The load factor is defined as the number of keys stored in the hash table divided by the capacity. At the end, it is 9/19=0.474.

Question 6

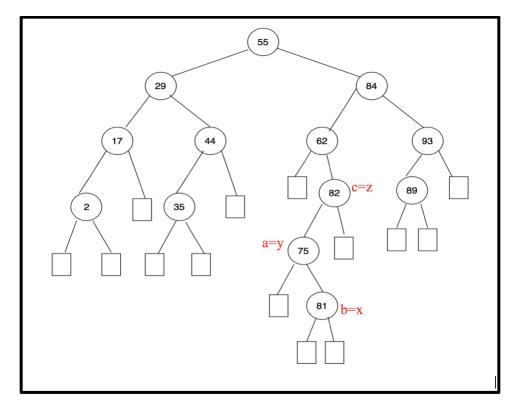
- i) Yes, there are errors with the given AVL tree.
 - 1) The location of 2 is incorrect. 2 is placed in the right subtree of 55, implying that it is larger than 55, which is wrong. It must be placed at the far left side of the tree.
 - 2) The height balance property is not maintained. The tree rooted at 82 is not balanced because the left subtree has height 2 while the right has height 0. The tree rooted at 62 is not balanced because the left subtree has height 1 while the right subtree has height 3. The tree rooted at 84 is not balanced because the left subtree has height 4 and the right subtree has height 2. The tree rooted at 55 is not balanced because the left subtree has height 3 and the right subtree has height 5. To fix the AVL tree, I will not delete any items. I will simply change the location of 2. Then, restructure the subtree.

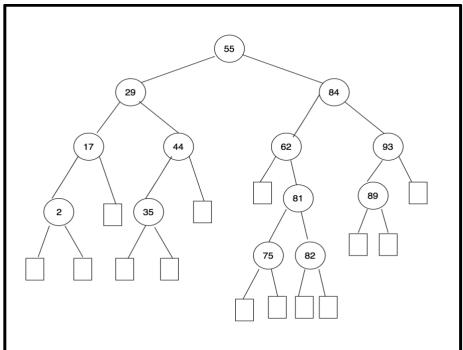
Step 1: Correct location of 2



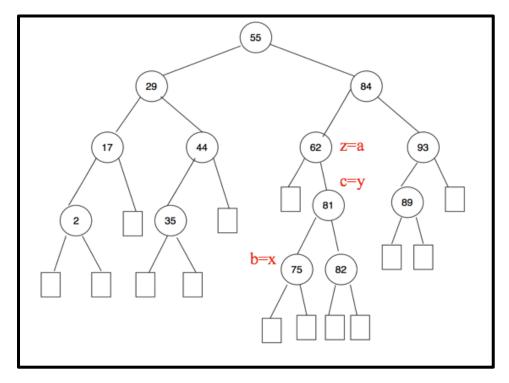
Step 2: Now, notice that the subtree rooted at 82 is not balanced. The left subtree has height 2 while the right subtree has height 0.

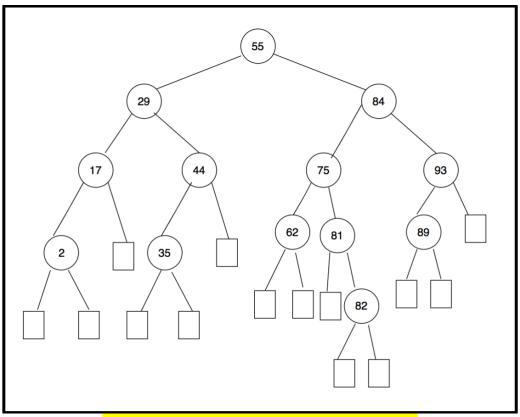
Z is the 1_{st} encountered node causing unbalance (82). Y is the child of z with the higher height (75). X is the child of Y with the higher height (81). So set c=z (82), a=y (75), b=x (81), and apply a double rotation for this subtree. In other words replace z with b, take a and c and make them children of b. Maintain in-order traversal of subtrees.





Step 3: Now, notice that the subtree rooted at 62 is not balanced. The left subtree has height 0 while the right subtree has height 2. Here I can either perform a single rotation or a double rotation. I will choose the latter. Z is the 1_{st} encountered node causing unbalance (62). Y is the child of z with the higher height (81). X is the child of Y with the higher height (75) (or 82) I will set z=a (62), c=y (81), b=x (75).



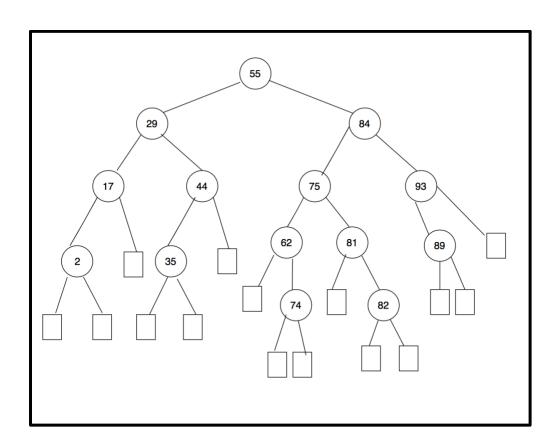


Now work with this properly balanced AVL tree.

ii) **put**(74)

74 will be placed in the right subtree of 62 because it is greater than 62. Now let's study the new height of the subtree rooted at 75. The left subtree has height 2 and the right subtree has height 2. Study the height of the subtree rooted at 84. The left subtree has height 3 and the right subtree has height 2. Now let's study the height of the tree rooted at 55. The left subtree has height 3 and the right subtree has height 4. So, we do not need to apply any rotations, because the height balance property of this AVL tree is not violated.

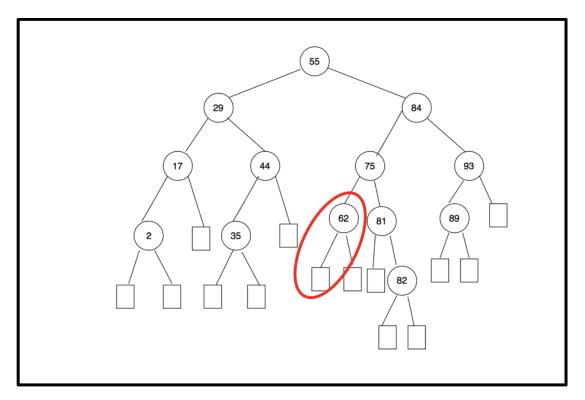
Time Complexity: Let n be the number of keys the AVL tree stores. Now, the height of an AVL tree that stores n keys is O(log n). The insertion depends on the height of the AVL tree, so put(74) runs in O(log n).

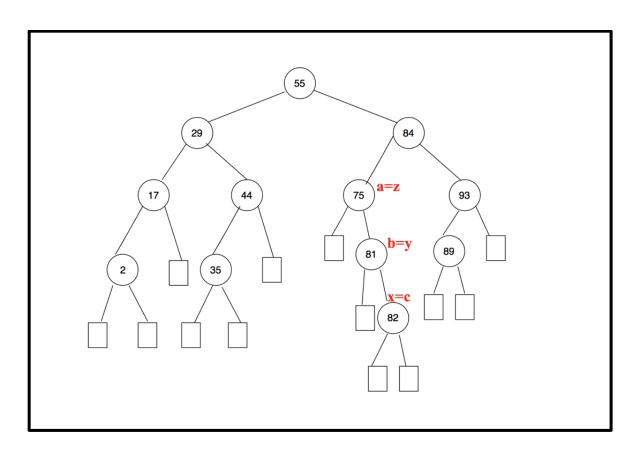


iii) remove(62)

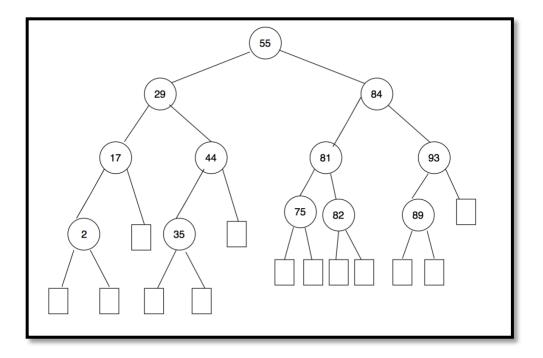
Since 62 has 2 leaf children, we delete 62 and a leaf child, and replace 62 with the leaf child.

Time Complexity: Let n be the number of keys the AVL tree stores. Now, the height of an AVL tree that stores n keys is O(log n). The deletion depends on the height of the AVL tree, so remove(62) runs in O(log n). Restructuring takes O(1) time.





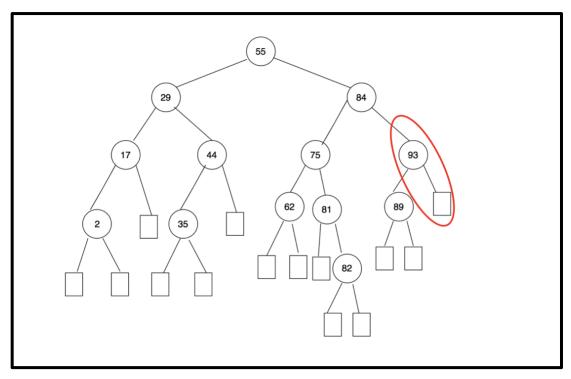
Let's study the height of the subtree rooted at 75. The left subtree has height 0 and the right subtree has height 2. So we must restructure the tree rooted at 75. Z is the 1_{st} encountered node causing unbalance (75). Y is the child of z with the higher height (81). X is the child of Y with the higher height (82). Perform a single rotation. In other words replace z with b, take a and c and make them children of b. Maintain in-order traversal of subtrees.

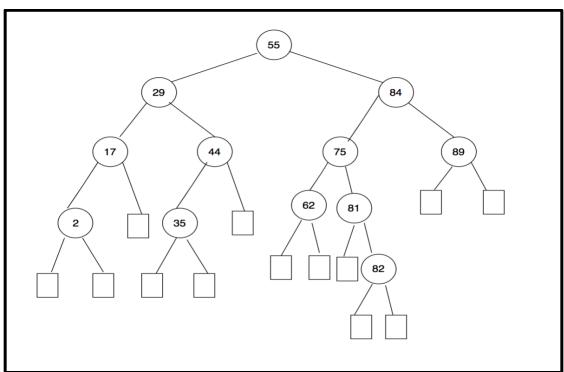


After we restructured the tree, let's study the heights. The trees rooted at 75 and 82 have heights 1. The tree rooted at 81 has height 2 and the tree rooted at 93 has height 2. The tree rooted at 84 has height 3 and the tree rooted at 29 also has a height of 3. Clearly, the height-balance property is restored.

iv) remove(93)

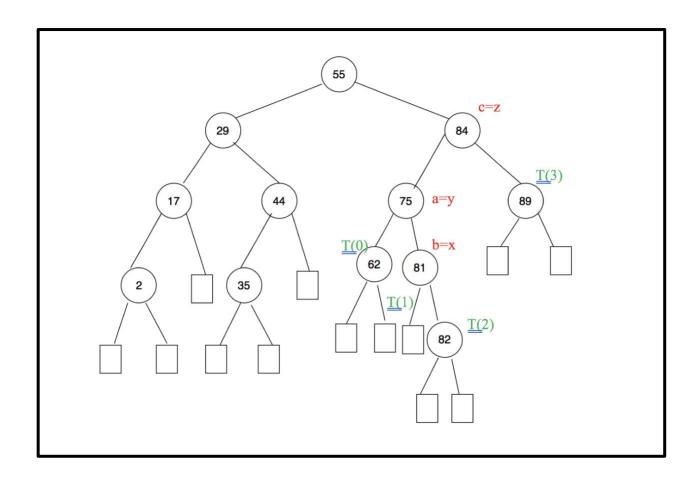
Since 93 has a leaf child, we delete 93 and the leaf child, and replace 93 with the internal node child (89).

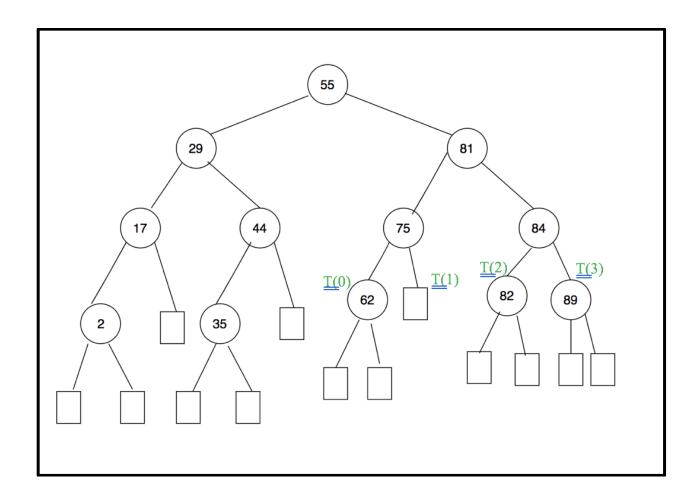




After deleting 93, let us study the heights of the tree. The tree rooted at 75 is not changed and has a height of 3. The tree rooted at 89, however, has a height of 1. There is a height difference of 2 between 89 and 75. Therefore, the tree rooted at 84 is no longer balanced.

Z is the 1_{st} encountered node causing unbalance (84). Y is the child of z with the higher height (75). X is the child of Y with the higher height (81). Perform a double rotation. In other words replace z with b, take a and c and make them children of b. Maintain in-order traversal of subtrees.





Now, let's study the height of this tree, after restructuring it.

The tree rooted at 62 has height 1, and its sibling has height 0.

The tree rooted at 82 and the tree rooted at 89 have heights 1.

The tree rooted at 75 has height 2 and the tree rooted at 84 has height 2.

The tree rooted at 81 has height 3, and the tree rooted at 29 is unchanged so has height 3.

The tree rooted at 55 has height 4.

The height balance property is restored.

Time Complexity: Let n be the number of keys the AVL tree stores. Now, the height of an AVL tree that stores n keys is $O(\log n)$. The deletion depends on the height of the AVL tree, so remove(93) runs in $O(\log n)$. Note that rotations run in O(1) so even if we performed one rotation it will not significantly affect the log n time complexity.



```
declare integer variables threshold, keyLength, size, max_size
size \leftarrow 0
constant String alphaNumeric,
constant String arrays owners, brands
records_1 ← new DoublyLinkedList()
records_2←new TreeMap<String, Vehicle>()
Algorithm CVR ()
      Input None
      Output None
      Default constructor
Algorithm CVR ( int n)
      Input size of CVR
      Output None
      max_size←n
Algorithm GreaterThanThreshold (size_pass)
      Input number of entries
      Output If we should use ADT TreeMap
      if size_pass >= threshold then
              return true
      else
              return false
```

Algorithm setThreshold (threshold_pass)

Input threshold

```
Output nothing
      if threshold_pass < 100 or threshold_pass > 900000 then
             display error and exit program
      else
             threshold← threshold_pass
Algorithm getThreshold ()
      Input None
      Output threshold
      return threshold
Algorithm getKeyLength ()
      Input None
      Output keyLength
      return keyLength
Algorithm setKeyLength (length)
      Input key length
      Output nothing
      if length < 10 or length > 17 then
             display error and exit program
      else
             keyLength← length
Algorithm generate (n)
      Input how many keys to generate
      Output nothing
      if size+n>max_size then
             display error and return
      if GreatherThanThreshold(n + size) then
```

```
if sequence_first=true then
              changeADT()
       for i \leftarrow 0 to n-1 do
              owner ← owners [((int) (Math.random() * owners.length))]
              brand ← brands[((int) (Math.random() * brands.length))]
              price ← 55555*Math.random()
              acc←new Stack<Date>()
              acc← new Date().randomDates()
              temp← new Vehicle (owner, brand, price, acc)
              temp_vin←generateVIN(keyLength)
              if ! records_2.containsKey(temp_vin) then
                     records_2.put(temp_vin, temp)
                     increment size
              else if records_2.containsKey(temp_vin) then
                     decrement i
                     continue
else if! GreatherThanThreshold(n + size) then
       sequence first←true
       for i \leftarrow 0 to n-1 do
              owner ← owners[((int) (Math.random() * owners.length))]
              brand ← brands[((int) (Math.random() * brands.length))]
              price←55555*Math.random()
              acc←new Stack<Date>()
              acc← new Date().randomDates()
              temp← new Vehicle (owner, brand, price, acc)
              temp_vin←generateVIN(keyLength)
              if size=0 then
                     records_1.addFirst(temp_vin, temp)
                     increment size
              else if ! records_1.contains(temp_vin) then
                     records_1.addFirst(temp_vin, temp)
```

```
else if records_1.contains(temp_vin) then
                            decrement i
                            continue
      sort()
Algorithm generateVIN (keyLength)
      Input length of key to be generated
      Output random key with inputted length
      sb←new StringBuilder()
       while keyLength-- !=0 do
              ch← (int) (Math.random() * alphaNumeric.length())
              sb.append (alphaNumeric.charAt(ch))
      return sb.toString()
Algorithm allKeys ()
      Input nothing
      Output String LinkedList with keys lexicographically sorted
      if GreatherThanThreshold(size) then
              keys←records_2.keySet()
              sorted.addAll(keys)
      else
              sorted←records_1.allKeys()
      return sorted
Algorithm sort ()
      Input nothing
      Output nothing, just sorts the CVR keys lexicographically
      if ! GreatherThanThreshold(size) then
              records_1 ← records_1.sortList()
```

increment size

```
Algorithm add (key_pass, owner_pass, brand_pass, price_pass, accidents_pass)
       Input the VIN (key_pass) and the vehicle properties
       Output nothing
       if size=max_size then
              Display error and return
       vehicle_pass \(\begin{align*}\) new Vehicle (owner_pass, brand_pass, price_pass, accidents_pass)
       if GreatherThanThreshold(size) then
              if records_2.containsKey(key_pass) then
                     Display that key already is there
              else
                     if sequence_first=true then
                            changeADT()
                     records_2.put(key_pass, vehicle_pass)
                     increment size
       else if ! GreatherThanThreshold(size) then
              sequence_first←true
              if records_1.contains(key_pass) then
                     Display that key already is there
              records_1.addHere (key_pass, vehicle_pass)
              increment size
Algorithm remove (key_pass)
       Input the VIN whose vehicle will be deleted from CVR
       Output nothing
       if GreatherThanThreshold(size) then
              if records_2.remove(key_pass)!=null then
                     decrement size
              else
```

```
else if ! GreatherThanThreshold(size) then
              if records_1.delete(key_pass) then
                     decrement size
              else
                     display error has occurred
Algorithm getValue (key_pass)
      Input the VIN whose vehicle will be returned
      Output vehicle of the given VIN
      if GreatherThanThreshold(size) then
              return records_2.get (key_pass)
      else
              return records_1.getValueFromKey (key_pass)
Algorithm nextKey (key_pass)
      Input the VIN
      Output the VIN after the given VIN
      if GreatherThanThreshold(size) then
              if records_2.higherEntry(key_pass) = null then
                     return null
              return records_2.higherEntry(key_pass).getKey()
      else
             return records_1.nextKey(key_pass)
Algorithm prevKey (key_pass)
      Input the VIN
      Output the VIN before the given VIN
      if GreatherThanThreshold(size) then
              if records_2.lowerEntry(key_pass) = null then
                     return null
              return records_2.lowerEntry(key_pass).getKey()
```

display error has occurred

```
else
```

```
return records_1.prevKey(key_pass)
```

```
Algorithm changeADT ()
      Input nothing
      Output nothing
       while ! records_1.isEmpty() do
              key_temp←records_1.firstKey()
              vehicle_temp←records_1.firstValue()
              records_1.removeFirst()
              records_2.put(key_temp, vehicle_temp)
       sequence_first←false
Algorithm prevAccids (key_pass)
      Input the key whose previous accidents will be found
      Output previous accidents as an array list
       accidents \(\lefta\) this.getValue(key_pass).getAccidents()
      tmpStack1 ←new Stack<Date>()
      tmpStack3←new Stack<Date>()
       while! accidents.isEmpty() do
              tmp←accidents.pop()
              tmpStack3.push(temp)
              while (!tmpStack1.isEmpty() and (tmp.year > tmpStack1.peek().year
              or
              (tmp.year = tmpStack1.peek().year and tmp.month >
              tmpStack1.peek().month)
              or
```

```
(tmp.year == tmpStack1.peek().year and tmp.month =
    tmpStack1.peek().month and tmp.day > tmpStack1.peek().day))) do
        accidents.push(tmpStack1.pop())
    tmpStack1.push(tmp)

temp←newStack<Date>()
while! tmpStack1.isEmpty() do
    temp.push(tmpStack1.pop())

tmpStack2 ←new Stack<Date>()
while! temp.isEmpty() do
    tmpStack2.push(temp.pop())
while! tmpStack3.isEmpty() do
    accidents.push(tmpStack3.pop())
return tmpStack2
```



How does the program work?

Before generating the keys, the user must set the size of the CVR, threshold, and the key length. Throughout the code the variable size keeps of track of how many entries are in the CVR. If the number of entries is less than the threshold, then we use a sequence: a double linked list. I chose to modify the doubly linked list class and make use of the node class for some of my methods. In fact, while reading the pseudocode, you may have noticed some unfamiliar methods that are being called with a doubly linked list. These methods were introduced to the DoublyLinkedList. Now, if the number of entries exceeds the threshold, then we must switch the ADT and use a TreeMap. This is already given by Java and I did not have to explicitly define the set and get methods for this class. Note that if we generate more keys than the threshold, then we would not have to use the sequence at all! However, if we start with a small number of entries, then exceed the threshold, the Boolean variable sequence_first will indicate that I have to switch my ADT using an auxiliary method called changeADT().

Why did you choose those Data Structures?

"if a CVR contains only a small number of entries (e.g., few hundreds), it might use less memory overhead but slower (sorting) algorithms. On the other hand, if the number of contained entries is large (greater than 1000 or even in the range of tens of thousands of elements or more), it might have a higher memory requirement but faster (sorting) algorithms"-assignment 3

In my program, the doubly linked list is a perfect match for the first data structure. Why? Well because the space needed is exactly equal to the number of entries stored in the CVR. In this case, it is at a bare minimum. And for the second data structure, a TreeMap is a perfect implementation because it provides an effective way of storing key-value pairs in a sorted order. In fact, I don't even have to sort the keys myself. The treemap automatically does that! For me, that was the main reason I favored the treemap over other data structures, like an AVL tree. In addition, the memory taken is quite low! We space needed is also exactly the same as the number of entries.

What is the time complexity of your methods? (DoublyLinkedList)

Let n be the number of entries in the CVR

operations applicable to a complete CVR \leq O(n) operations applicable to a single CVR entry \leq O(n^2)

Method	T.C	Justification
setThreshold(Threshold)	O(1)	because we are simply initializing the variable threshold
setKeyLength(Length)	O(1)	because we are simply initializing the variable keylength
generate(n)	$O(n^2)$	Since we have a for loop the generate method runs in O(n) time. Note, however, that it would make sense to sort the elements after generating the keys and adding them. Since the sort() method runs in O(n^2) time, the generate method, overall, runs in O(n^2)
allKeys()	O(n)	To return all the keys will have to traverse over all the elements of the list and so this method runs in O(n)
add(key,value)	O(n)	We have to traverse over the elements of the list to know where to add the key while maintaining the lexicographic order. So the worst case scenario would be if the key were to be added at the very end (last in lexicographic order). In this case we'd have to traverse all the elements n, hence O(n)
remove(key)	O(n)	The worst case scenario here would be that we have to remove the last key in the list. In that case we would have to traverse over all the elements of the list (n), hence O(n)
getValues(key)	O(n)	The worst scenario would be that the key is the last element. Hence, we have to traverse over the entire list with a for loop O(n)
nextKey(key)	O(n)	The worst scenario would be that the key is the before-to- last element. Hence, we have to traverse over the entire array with a for loop O(n)
prevKey(key)	O(n)	The worst scenario would be that the key is the last element. Hence, we have to traverse over the entire array with a for loop O(n)
prevAccids(key)	O(n)	The worst case scenario would be that the key is the last element of the list. After we reach the last element we simply have to return the accidents of that key using a stack. Note that even if we use a while loop, returning the accidents of a key takes a constant time, because we have a constant number of accidents in every key, in my case, 3. Hence, time complexity is O(n). Of course, if we wanted to consider n' as the number of accidents, then the time complexity would be O(n'^2), (2 while loops).

What is the time complexity of your methods? (TreeMap)

Method	T.C	Justification					
setThreshold(Threshold)	O(1)	O(1) because we are simply initializing the variable threshold					
setKeyLength(Length)	O(1)	O(1) because we are simply initializing the variable keylength					
generate(n)	O(n log n)	Since we have a for loop the generate method runs n times. Time to insert first element = O(1) Time to insert second element = O(Log 1) = 0 = O(1) Time to insert third element = O(Log 2) Total time = Log 1 + Log 2 + Log 3 + + Log (n-1) And we don't have to sort the keys after that, that is					
		automatic					
allKeys()	O(1)	To return all the keys we call the method entrySet() which runs in O(1)					
add(key,value)	O(1)	We call the method put (key,value) which runs in O(1)					
remove(key)	O(1)	We call the method remove(key) which runs in O(1)					
getValues(key)	O(1)	We call the method get(key) which runs in O(1)					
nextKey(key)	O(1)	We call the method higherEntry(key).getKey(), which runs in O(1)					
prevKey(key)	O(1)	We call the method lowerEntry(key).getKey(), which runs in O(1)					
prevAccids(key)	O(1)	Note that even if we use a while loop, returning the accidents of a key takes a constant time, because we have a constant number of accidents in every key, in my case, 3. Hence, time complexity is O(1). Of course, if we wanted to consider n' as the number of accidents, then the time complexity would be O(n'^2), (2 while loops).					

Comparison

Method	DoublyLinkedList	TreeMap	Meets
			Requirements?
setThreshold(Threshold)	O(1)	O(1)	Yes
setKeyLength(Length)	O(1)	O(1)	Yes
generate(n)	$O(n^2)$	$O(n \log n)$	Yes
allKeys()	O(n)	O(1)	Yes
add(key,value)	O(n)	O(1)	Yes
remove(key)	O(n)	O(1)	Yes
getValues(key)	O(n)	O(1)	Yes
nextKey(key)	O(n)	O(1)	Yes
prevKey(key)	O(n)	O(1)	Yes
prevAccids(key)	O(n)	O(1)	Yes

Conclusion

Both the sequence and the ADT meet the time requirements of the assignments: "operations applicable to a single CVR entry should be between O(1) and $O(\log n)$ but never worse than O(n). Operations applicable to a complete CVR should not exceed $O(n^2)$ ".

Clearly, the treemap is a much faster implementation of the CVR. In fact most of its methods run in O(1) except for the generate method. The worst time complexity recorded is the generate method for the DoublyLinkedList, which runs in $O(n^2)$.



Discuss how both the time and space complexity change for each of the methods above if the underlying structure of your CVR is an array or a linked list?

Case 1- Array

Let n be the number of entries of the CVR

Constructor

Time Complexity: O(1), because we are simply creating an initializing an array with the given length.

Space Complexity: O(n), because we are allocating space for all n elements of the array

Sort()

```
String array[] = new String[n];
Fill array with the elements of the CVR
for i ← 0 to n-1 do

for j ← i + 1 to n-1 do

if (array[i].compareTo(array[j]) > 0) then

temp_string ← array[i]
array[i] ← array[j]
array[j] ← temp
```

Time Complexity: $O(n^2)$, because 2 for loops are needed to sort the VINS lexiciographically Space Complexity: O(n), because we are allocating space for all n elements of the array array

setThreshold(Threshold)

Time Complexity: O(1), because we are simply initializing the variable threshold Space Complexity: O(1), because we are simply initializing one variable threshold

setKeyLength(Length)

Time Complexity: O(1), because we are simply initializing the variable keyLength Space Complexity: O(1), because we are simply initializing one variable keyLength

generate(n)

Time Complexity: Like my code, I will require a for loop that runs from 0 to n-1, and generated a random VIN. Generating 1 random VIN takes O(1) time, and adding it to the array also takes O(1) time. However since we have a for loop the generate method runs in O(n) time. Note, however, that it would make sense to sort the elements after generating the keys and adding them. Since the sort() method runs in $O(n^2)$ time, the generate method, overall, runs in $O(n^2)$.

Space Complexity: The generate method itself needs a constant space, because we use a limited number of variables. However, since we are calling the method sort(), technically speaking this method takes O(n) space.

allKeys()

Time Complexity: Assume that the array is already sorted lexicographically after generating the keys (see above). Now, to return all the keys will have to traverse over all the elements of the array and so this method runs in O(n).

Space Complexity: Assume that the array is already sorted lexicographically after generating the keys (see above). Now, to return all the keys will have to traverse over all the elements of the array and perhaps store in them in a sequence of some sort (array list, list, another array). Since this sequence will have the same space as the array itself, this method has O(n) space complexity.

add(key,value)

Time Complexity: The worst case scenario here would be that we have to add the key at the very beginning, and there are already the maximum number of elements in the array minus 1. In this case, we would have to shift all the elements of the array by 1 unit to the right, most easily with a for loop. Hence, O(n) time complexity.

Space Complexity: Since we can operate on the array itself, we do not need an auxiliary array. We simply need to allocate space for a constant number of variables, hence O(1).

remove(key)

Time Complexity: The worst case scenario here would be that we have to add the remove the key from the very beginning. In that case we would have to shift all elements of the array one unit to the left, most easily with a for loop. Hence O(n) time complexity. Note that even if the key is the last entry, we still have to traverse over the entire array: O(n).

Space Complexity: Since we can operate on the array itself, we do not need an auxiliary array. We simply need to allocate space for a constant number of variables, hence O(1).

getValues(key)

Time Complexity: The worst scenario would be that the key is the last element. Hence, we have to traverse over the entire array with a for loop O(n).

Space Complexity: Since we are using the array itself, we don't need an auxiliary data structure. We simply need to allocate space for a constant number of variables, hence O(1).

nextKey(key)

Time Complexity: The worst scenario would be that the key is the before-to-last element. Hence, we have to traverse over the entire array with a for loop O(n).

Space Complexity: Since we are using the array itself, we don't need an auxiliary data structure. We simply need to allocate space for a constant number of variables, hence O(1)

prevKey(key)

Time Complexity: The worst scenario would be that the key is the last element. Hence, we have to traverse over the entire array with a for loop O(n).

Space Complexity: Since we are using the array itself, we don't need an auxiliary data structure. We simply need to allocate space for a constant number of variables, hence O(1)

prevAccids(key)

Recall: Let n be the number of entries of the CVR, NOT the number of accidents of the key

Time Complexity: The worst case scenario would be that the key is the last element of the array. After we reach the last element we simply have to return the accidents of that key using a stack. Note that even if we use a while loop, returning the accidents of a key takes a constant time, because we have a constant number of accidents in every key, in my case, 3. Hence, time complexity is O(n).

Space Complexity: We are allocating space in a stack for the accidents. However, we have a constant number of accidents in every key, in my case, 3. Hence the space complexity is constant regardless of the inputted key, so O(1).

Of course, if we wanted to consider n' as the number of accidents, then the time complexity would be $O(n'^2)$, and the space complexity would be O(n').

Case 2- LinkedList

Let n be the number of entries of the CVR

Constructor

Time Complexity: O(1), because we are simply creating an initializing a linked list with the given length.

Space Complexity: O(n), because we are allocating space for all n elements of the list

Sort()

Time Complexity: O(n^2), because 2 for loops are needed to sort the VINS lexiciographically Space Complexity: O(1), because we are working on the list itself. (see code below in my java files: class DoublyLinkedList)

```
if (header == null) {
    return this;
} else {
    for (current = header.next; current.next != null && current.key != null; current = current.next) {
    for (index = current.next; index != null && index.key != null; index = index.next) {

        if (current.getKey().compareTo(index.getKey()) > 0) {
            key_tempo = current.getKey();
            value_tempo = current.getValue();

            current.key = index.getKey();
            current.value = index.getValue();

            index.key = key_tempo;
            index.value = value_tempo;
        }
}
```

setThreshold(Threshold)

return this:

Time Complexity: O(1), because we are simply initializing the variable threshold Space Complexity: O(1), because we are simply initializing one variable threshold

setKeyLength(Length)

Time Complexity: O(1), because we are simply initializing the variable keyLength Space Complexity: O(1), because we are simply initializing one variable keyLength

generate(n)

Time Complexity: Like my code, I will require a for loop that runs from 0 to n-1, and generated a random VIN. Generating 1 random VIN takes O(1) time, and adding it to the list also takes O(1) time. However since we have a for loop the generate method runs in O(n) time. Note, however, that it would make sense to sort the elements after generating the keys and adding them. Since the sort() method runs in $O(n^2)$ time, the generate method, overall, runs in $O(n^2)$.

Space Complexity: The generate method itself needs a constant space, because we use a limited number of variables. So O(1) space. We are allocating space in a stack for the accidents. However, we have a constant number of accidents in every key, in my case, 3. Hence the space complexity is constant regardless of the inputted key, so O(1).

allKeys()

Time Complexity: Assume that the list is already sorted lexicographically after generating the keys (see above). Now, to return all the keys will have to traverse over all the elements of the list and so this method runs in O(n).

Space Complexity: Assume that the list is already sorted lexicographically after generating the keys (see above). Now, to return all the keys will have to traverse over all the elements of the list and perhaps store in them in a sequence of some sort (array list, list, array). Since this sequence will have the same space as the array itself, this method has O(n) space complexity.

add(key,value)

Time Complexity: We have to traverse over the elements of the list to know where to add the key while maintaining the lexicographic order. So the worst case scenario would be if the key were to be added at the very end (last in lexicographic order). In this case we'd have to traverse all the elements n, hence O(n)

Space Complexity: Since we can operate on the list itself, we do not need an auxiliary list. We simply need to allocate space for a constant number of variables, hence O(1).

remove(key)

Time Complexity: The worst case scenario here would be that we have to remove the last key in the list. In that case we would have to traverse over all the elements of the list (n), hence O(n) time complexity. Unlike the array, we do not have to shift any elements here, just "redirect" the header and trailer, if necessary.

Space Complexity: Since we can operate on the list itself, we do not need an auxiliary list. We simply need to allocate space for a constant number of variables, hence O(1).

getValues(key)

Time Complexity: The worst scenario would be that the key is the last element. Hence, we have to traverse over the entire list with a for loop O(n).

Space Complexity: Since we are using the list itself, we don't need an auxiliary data structure. We simply need to allocate space for a constant number of variables, hence O(1).

nextKey(key)

Time Complexity: The worst scenario would be that the key is the before-to-last element. Hence, we have to traverse over the entire list with a for loop O(n).

Space Complexity: Since we are using the list itself, we don't need an auxiliary data structure.

We simply need to allocate space for a constant number of variables, hence O(1)

prevKey(key)

Time Complexity: The worst scenario would be that the key is the last element. Hence, we have to traverse over the entire list with a for loop O(n).

Space Complexity: Since we are using the list itself, we don't need an auxiliary data structure.

We simply need to allocate space for a constant number of variables, hence O(1)

prevAccids(key)

Recall: Let n be the number of entries of the CVR, NOT the number of accidents of the key

Time Complexity: The worst case scenario would be that the key is the last element of the list. After we reach the last element we simply have to return the accidents of that key using a stack. Note that even if we use a while loop, returning the accidents of a key takes a constant time, because we have a constant number of accidents in every key, in my case, 3. Hence, time complexity is O(n).

Space Complexity: We are allocating space in a stack for the accidents. However, we have a constant number of accidents in every key, in my case, 3. Hence the space complexity is constant regardless of the inputted key, so O(1).

Of course, if we wanted to consider n' as the number of accidents, then the time complexity would be $O(n'^2)$, and the space complexity would be O(n').