

$$\Delta P_{GWL} = \Delta P_{dwl} \times \frac{1}{1 + S T_{WD1}} \times K_{W1}$$

$$\Delta P_{GWL} + S \Delta P_{GWL} T_{WD1} = K_{W1} \Delta P_{dwl}$$

$$\frac{\Delta P_{GWL}}{\Delta P_{dwl}} = \frac{K_{W1}}{1 + S T_{WD1}}$$

$$\textcircled{I} \Delta P_{GWL} + d(\Delta P_{GWL}) T_{WD1} = K_{W1} \Delta P_{dwl}$$

$$d(\Delta P_{GWL}) = \frac{+K_{W1} P_{dwl}}{T_{WD1}} - \frac{\Delta P_{GWL}}{T_{WD1}}$$

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$$[\Delta \dot{P}_{GWL}] = \left[\frac{K_{W1}}{T_{WD1}} \quad -\frac{1}{T_{WD1}} \right] \begin{bmatrix} \Delta P_{GWL} \\ \Delta P_{dwl} \end{bmatrix}$$

ΔP_{GWL}

P_{dwl}

ΔP_{GWL}

ΔP_{dwl}
 ΔP_{GWL} 26

ΔP_{dwl} belongs to C

ΔP_{GWL} belongs to A

$$\begin{bmatrix} \Delta P_{G1} \\ \Delta P_{G2} \\ \Delta P_{G3} \end{bmatrix} = \begin{bmatrix} \frac{1}{T_{G1}} & \frac{K_{G1}K_{T1}}{T_{G1}T_{T1}} & \frac{K_{G1}K_{T1}}{T_{G1}T_{T1}} \\ 0 & -\frac{1}{T_{H1}} & \frac{1}{T_{H1}} \\ 0 & 0 & \frac{1}{T_{G2}} \end{bmatrix} \begin{bmatrix} \Delta P_{G1} \\ \Delta P_{G2} \\ \Delta P_{G3} \end{bmatrix}$$

$$+ \begin{bmatrix} 0 \\ 0 \\ \frac{1}{T_{G1}} \end{bmatrix} \Delta P_{G1} + \begin{bmatrix} 0 & 1 \\ 0 & 1 \\ -\frac{1}{R_1 T_{G1}} \end{bmatrix} \begin{bmatrix} \Delta F_1 \\ \Delta F_2 \end{bmatrix}$$

ΔP_{G1} output

straight is present

in Ambsin itself

$\Rightarrow \Delta F_1$ is also an output of
later stage

$$\begin{bmatrix} \Delta P_{Gh1} \\ \Delta X_{h1} \\ \Delta X_{Rn1} \end{bmatrix} = \begin{bmatrix} -2/TW2 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} \left(\frac{2W_{R1}}{T_{uR1}} + \frac{2W_{h1}}{T_{Gh1}} \right) & \left(\frac{2W_{h1}TR1}{T_{Gh1}T_{en}} - \frac{2W_{h1}}{T_{Gh1}} \right) \\ -\frac{1}{T_{Gh1}} & \left(\frac{1}{T_{Gh1}} - \frac{T_{R1}}{T_{Gh1}T_{en}} \right) \\ 0 & -\frac{1}{T_{Rn1}} \end{bmatrix}$$

$$+ \begin{bmatrix} \frac{TR1}{T_{Rn1}T_{Gh1}} \\ \frac{TR1}{T_{Rn1}T_{Gh1}} \\ \frac{TR1}{T_{Rn1}T_{Gh1}} \end{bmatrix} \Delta P_{C1}$$

$$\Delta F_1 \begin{bmatrix} \left(\frac{2W_{h1}}{T_{Gh1}} \right) \frac{TR1}{T_{Rn1}} \\ \frac{TR1}{T_{Rn1}T_{Gh1}} \\ \frac{TR1}{T_{Rn1}T_{Gh1}} \end{bmatrix}$$

$$\begin{bmatrix} \Delta P_{Gh1} \\ \Delta X_{h1} \\ \Delta X_{Rn1} \end{bmatrix}$$

$$\begin{bmatrix} \Delta P_{G1} \\ \Delta P_{FC1} \\ \Delta P_{V1} \\ \Delta x_{g1} \end{bmatrix} = \begin{bmatrix} -\frac{1}{T_{CD1}} & 10,10 \\ 0 & \\ 0 & \\ 0 & \end{bmatrix} + \begin{bmatrix} 0 & \\ 0 & \\ \frac{x_1}{y_1} & \frac{x_1}{y_1} \\ \frac{1}{y_1} & \frac{x_1}{y_1} \end{bmatrix} \begin{bmatrix} \Delta P_{C1} \\ b_{12,1} \\ b_{13,1} \end{bmatrix} + \begin{bmatrix} 0 & \\ 0 & \\ -x_1 & \frac{x_1}{y_1} \\ \frac{1}{y_1} & \frac{x_1}{y_1} \end{bmatrix} \begin{bmatrix} \Delta F_1 \\ R_1 \\ a_{13,1} \end{bmatrix}$$

$$\begin{bmatrix} \frac{K_{g2} \cdot 10,11}{T_{CD1}} & -\frac{(T_{CD1})(K_{g2}) \cdot 10,12}{(T_{F1})(T_{CD1})} & 0 \\ \frac{1}{T_{F1}} & \frac{1}{T_{F1}} + \frac{T_{CD1} \cdot 12,12}{T_{F12}} & 0 \\ 0 & -\frac{G_1}{b_1} \cdot 12,12 & 12,13 \\ 0 & 0 & -\frac{1}{y_1} \end{bmatrix}$$