

“Classifiers”

Under the guidance of

R & D project by

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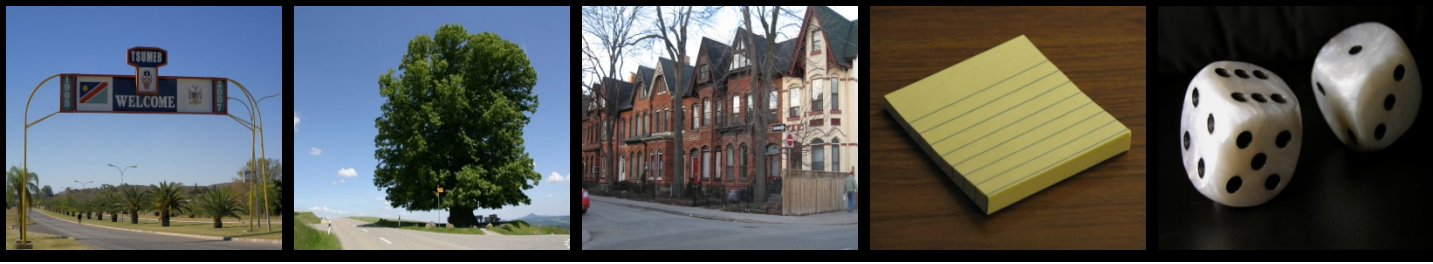
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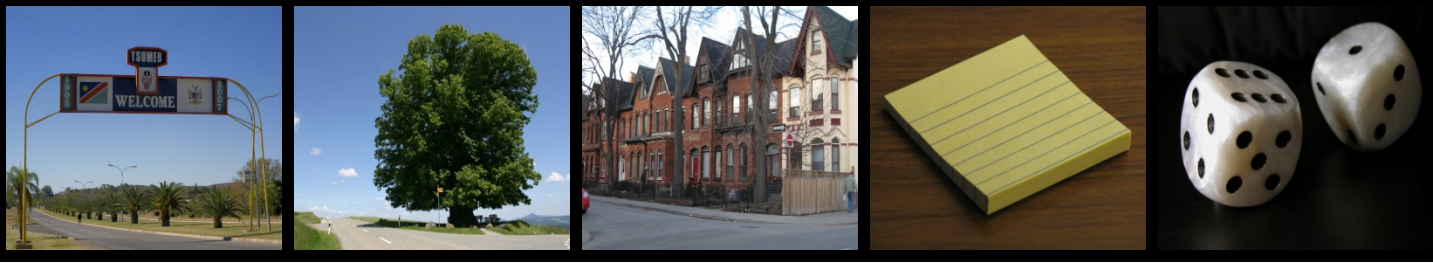
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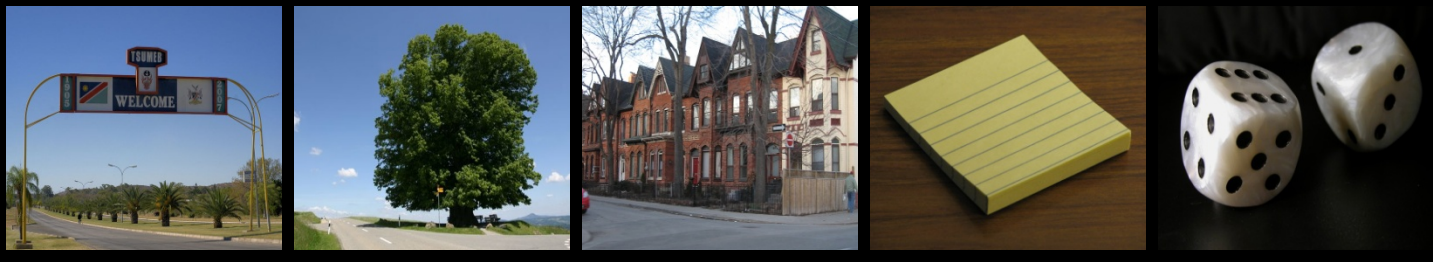
Overview





Introduction to Classification



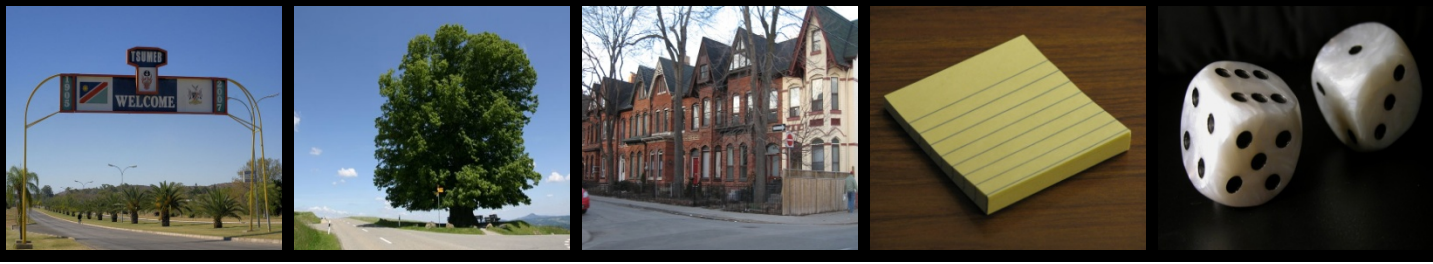


What is classification?

A machine learning task that deals with identifying the class to which an instance belongs

A classifier performs classification





Classification learning

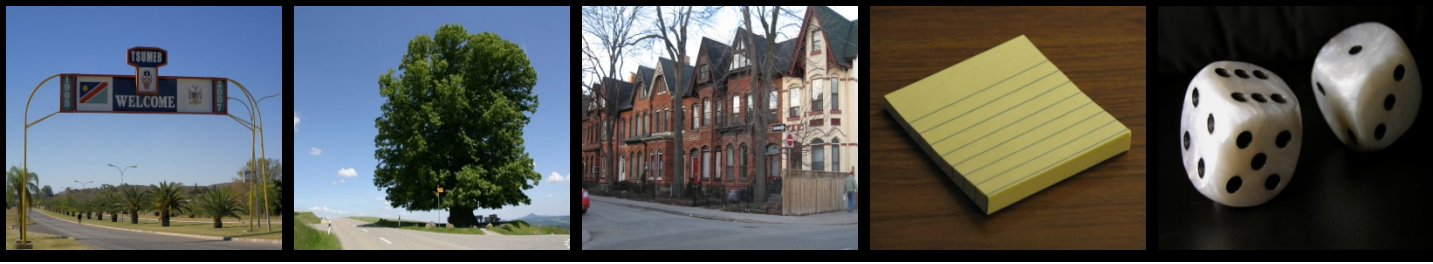
Training
phase

Learning the classifier
from the available data
'Training set'
(Labeled)



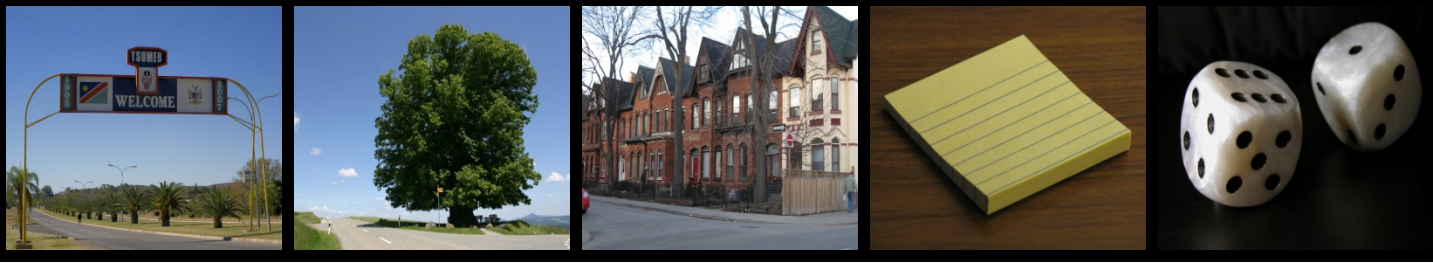
Testing
phase

Testing how well the classifier
performs
'Testing set'



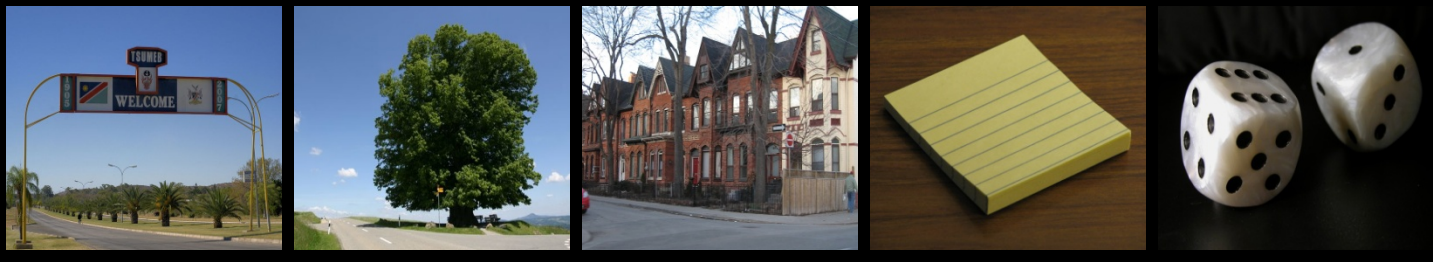
Generating datasets

- Methods:
 - Holdout ($2/3^{\text{rd}}$ training, $1/3^{\text{rd}}$ testing)
 - Cross validation (n – fold)
 - Divide into n parts
 - Train on (n-1), test on last
 - Repeat for different combinations
 - Bootstrapping
 - Select random samples to form the training set

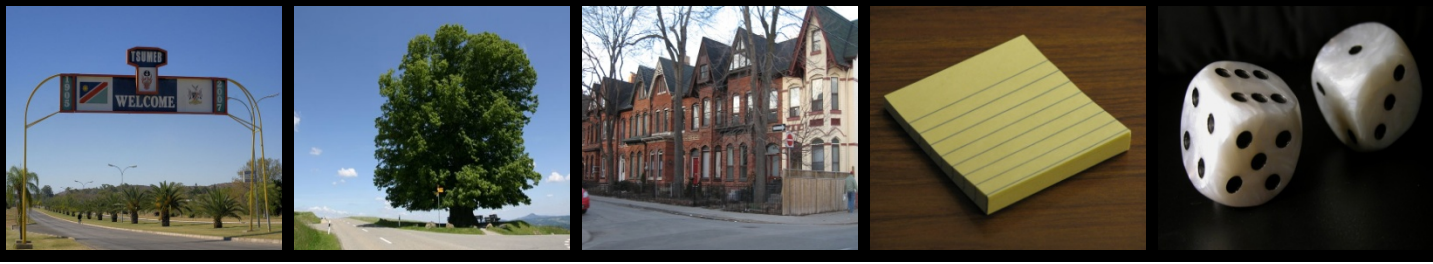


Evaluating classifiers

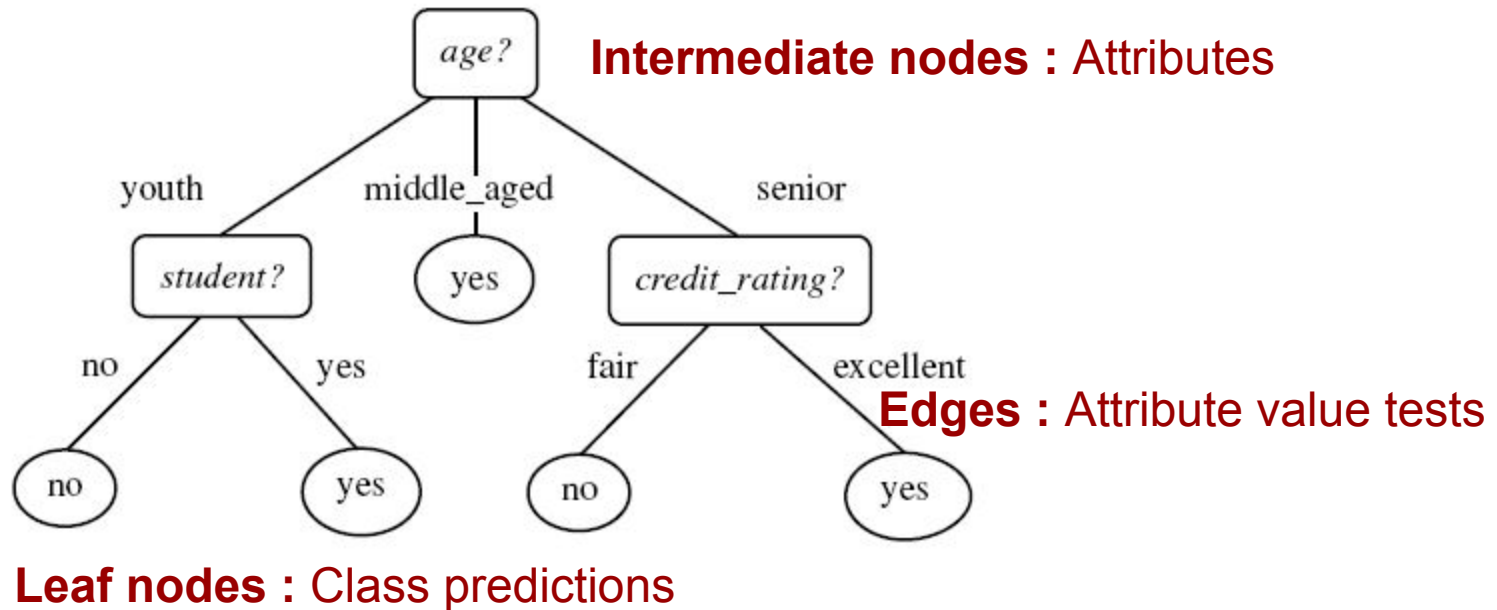
- Outcome:
 - Accuracy
 - Confusion matrix
 - If cost-sensitive, the expected cost of classification (attribute test cost + misclassification cost)
- etc.



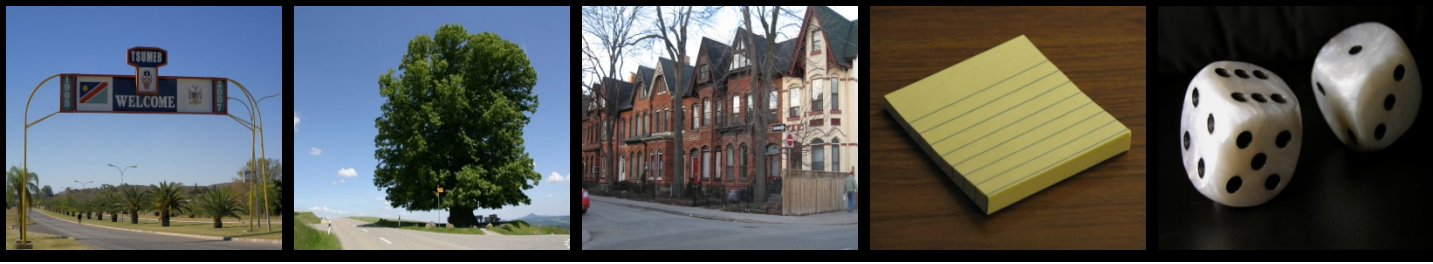
Decision Trees



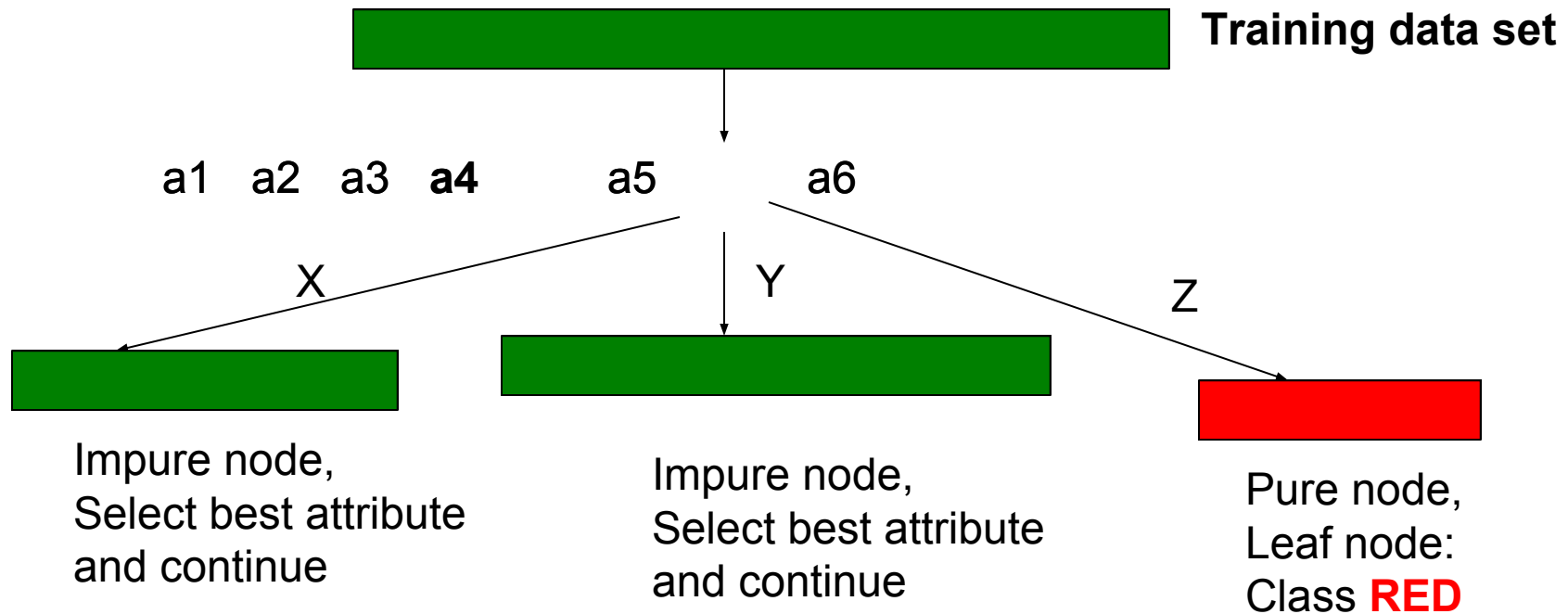
Example tree

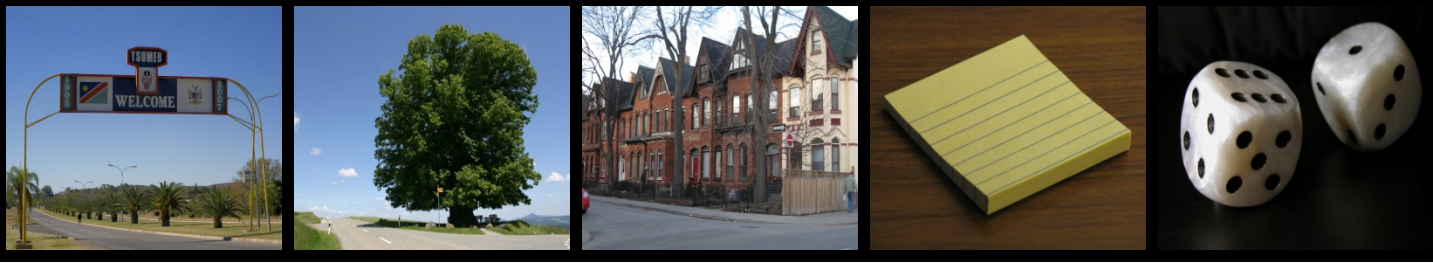


Example algorithms: ID3, C4.5, SPRINT, CART



Decision Tree schematic





Decision Tree Issues

How to determine the attribute for split?

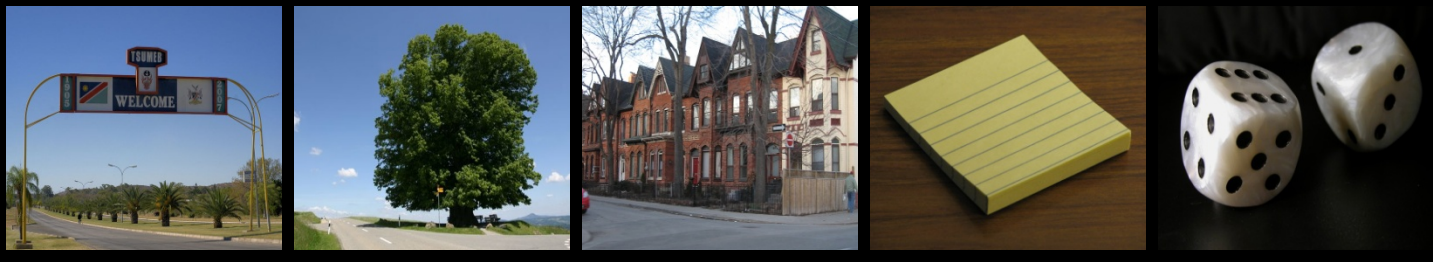
Alternatives:

1. Information Gain

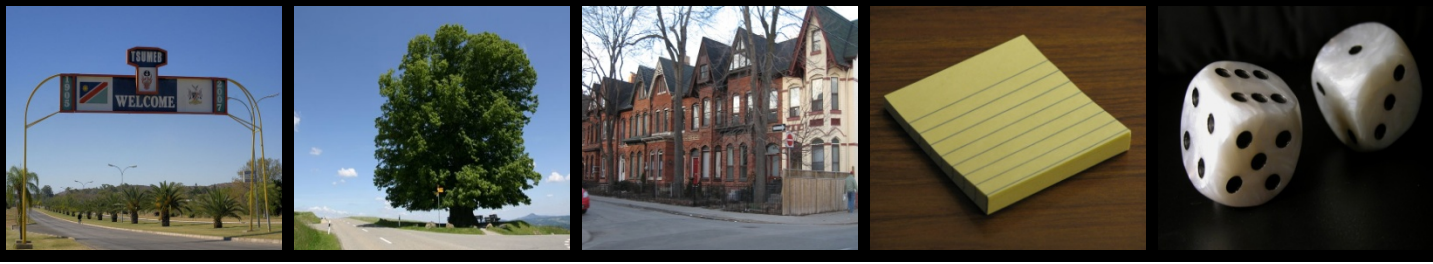
$$\text{Gain (A, S)} = \text{Entropy (S)} - \sum ((S_j/S) * \text{Entropy}(S_j))$$

Other options:

Gain ratio, etc.



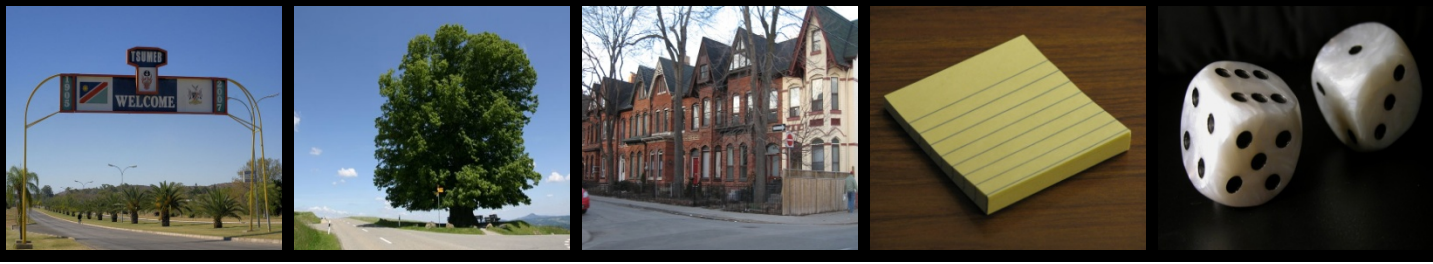
Lazy learners



Lazy learners

- **‘Lazy’**: Do not create a model of the training instances in advance
- When an instance arrives for testing, runs the algorithm to get the class prediction
- Example, K – nearest neighbour classifier
(K – NN classifier)
“One is known by the company
one keeps”





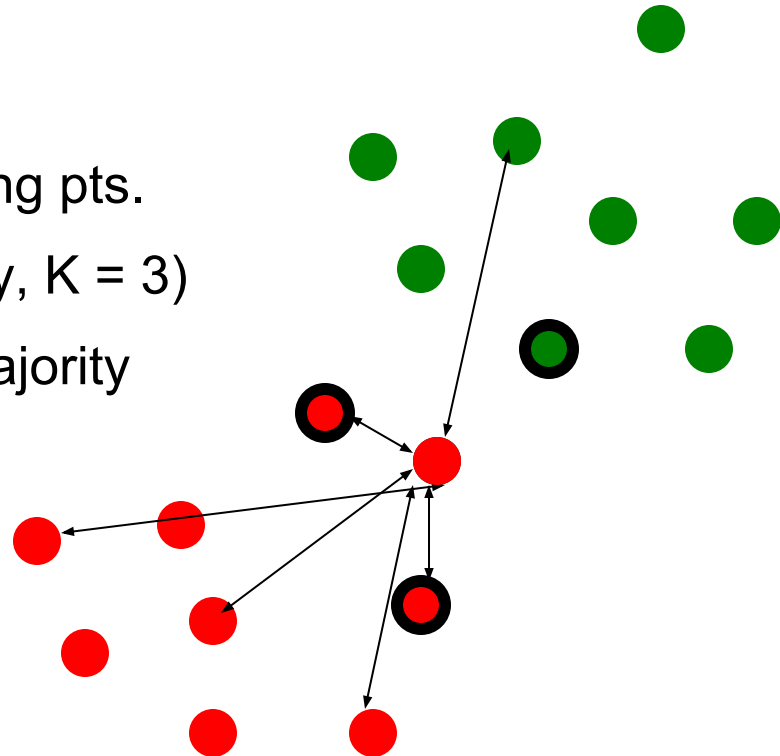
K-NN classifier schematic

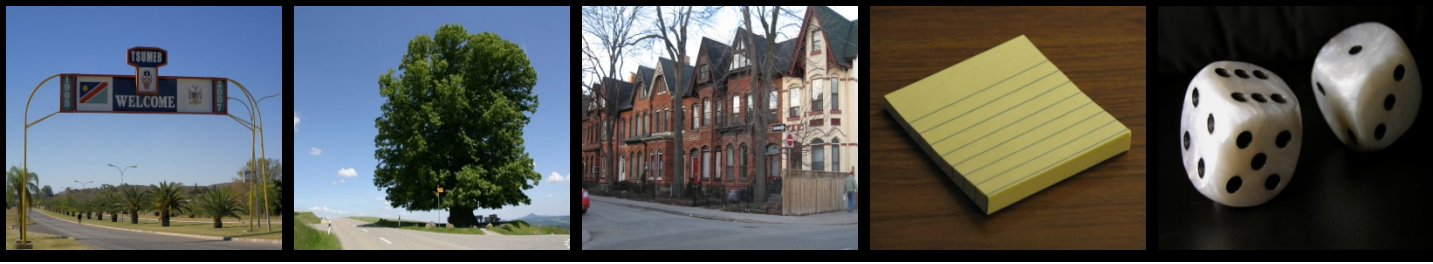
For a test instance,

- 1) Calculate distances from training pts.
- 2) Find K-nearest neighbours (say, K = 3)
- 3) Assign class label based on majority

$$\text{dist}(X_1, X_2) = \sqrt{\sum_{i=1}^n (x_{1i} - x_{2i})^2}.$$

$$v' = \frac{v - \min_A}{\max_A - \min_A},$$



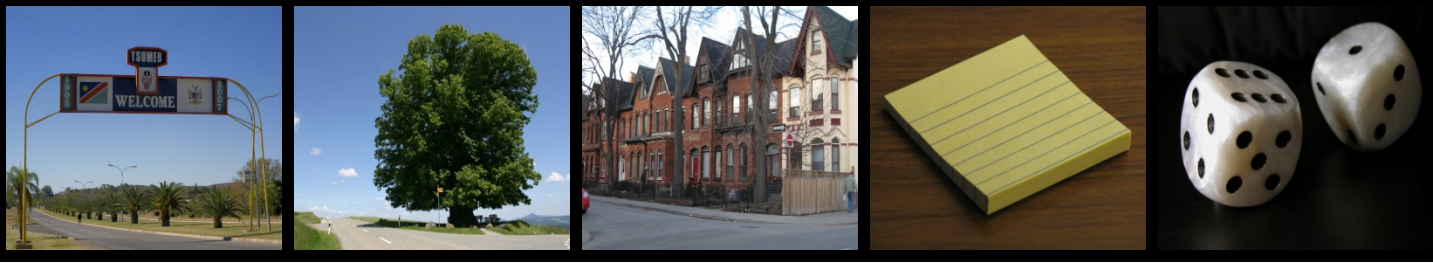


K-NN classifier Issues

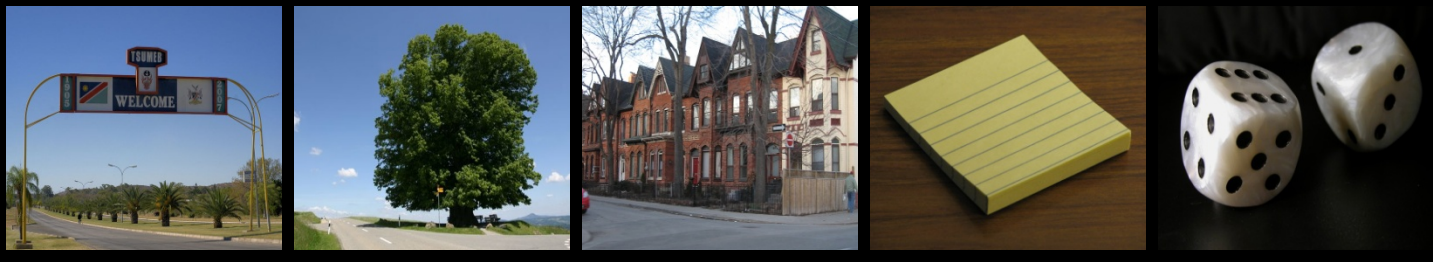
How to determine distances between values of categorical attributes?

Alternatives:

1. Boolean distance (1 if same, 0 if different)
2. Differential grading (e.g. weather – 'drizzling' and 'rainy' are closer than 'rainy' and 'sunny')



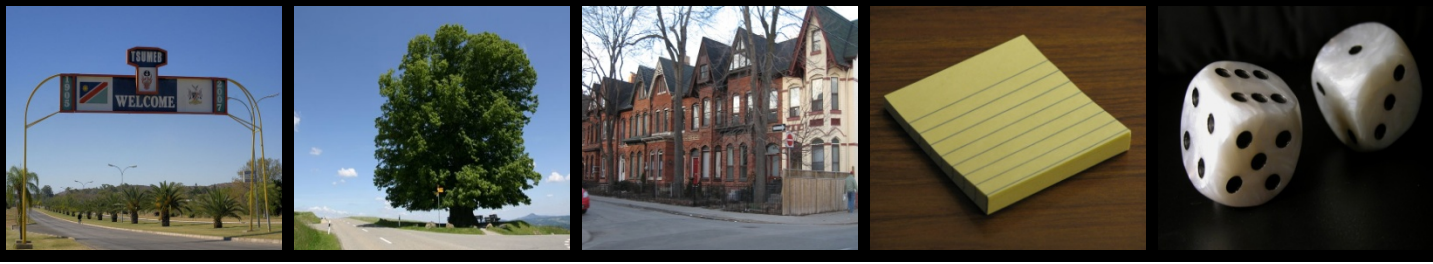
Decision Lists



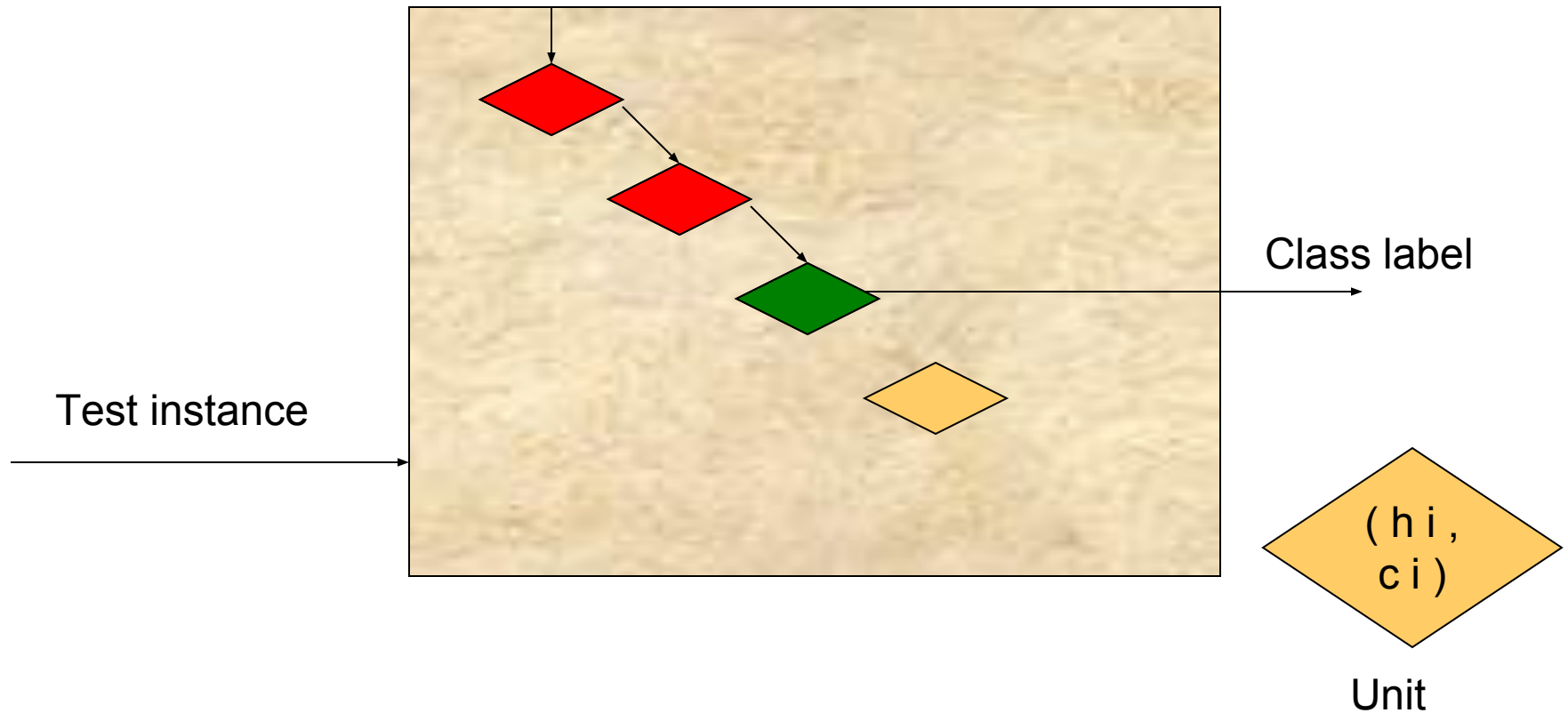
Decision Lists

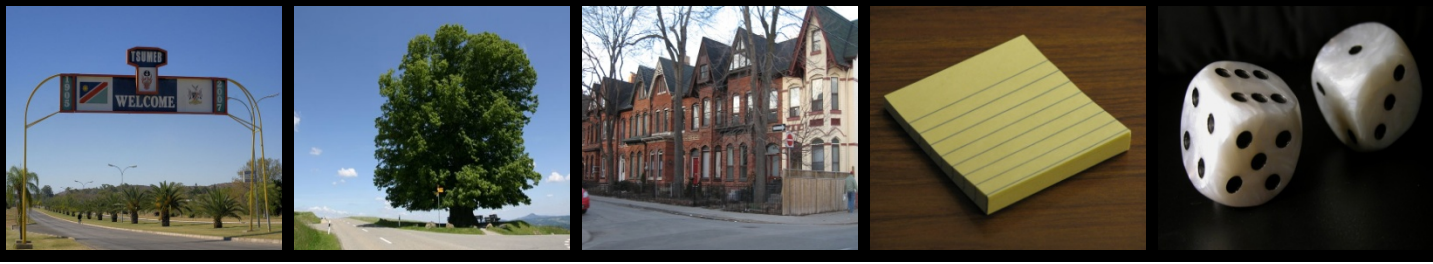
- A sequence of boolean functions that lead to a result

$$f(y) = \begin{cases} c_j, & \text{if } j = \min \{ i \mid h_i(y) = 1 \} \text{ exists} \\ 0 & \text{otherwise} \end{cases}$$



Decision List example





Decision List learning

$$\mathcal{R} = \{(h_i, b_i)\}_{i=1}^r$$

($h_k, 1/0$)

$$S' = S - Q_k$$

training set $S = P \cup N$

$$\mathcal{H} = \{h_i(\mathbf{x})\}_{i=1}^{|\mathcal{H}|}$$

Set of candidate
feature functions

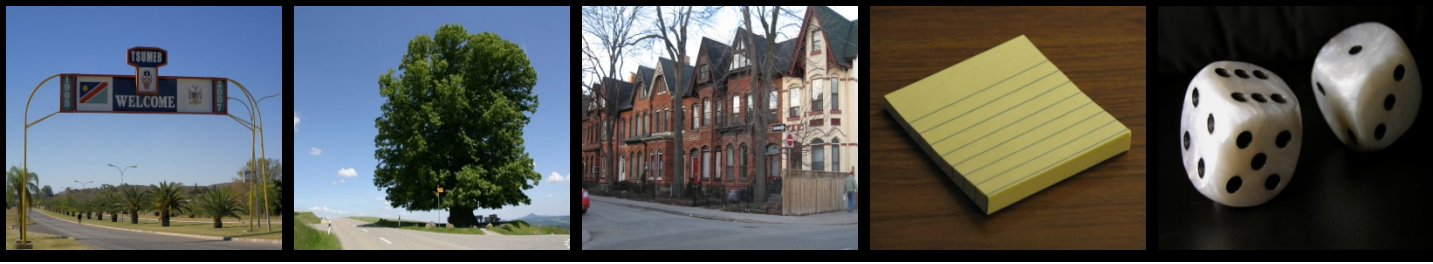
For each h_i ,
 $Q_i = P_i \cup N_i$
($h_i = 1$)

Select h_k , the
feature
with
highest utility

If
($|P_i| - p_n * |N_i|$
>
 $|N_i| - p_p * |P_i|$)
then 1

else 0

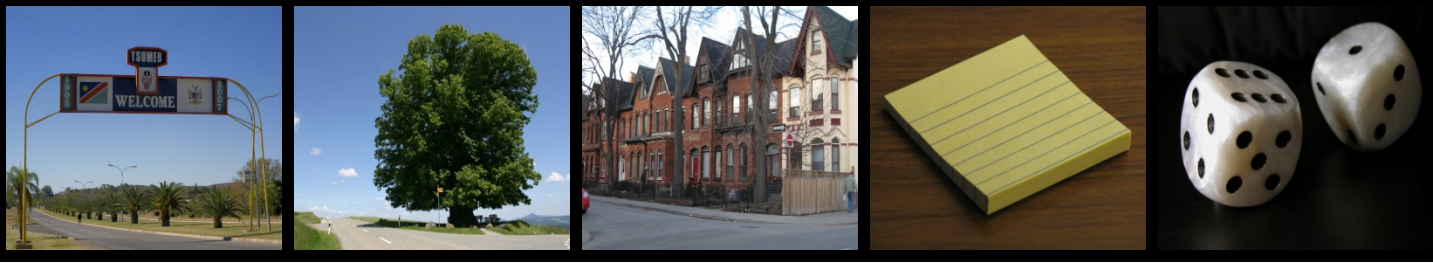
$$U_i = \max \{ |P_i| - p_n * |N_i|, |N_i| - p_p * |P_i| \}$$



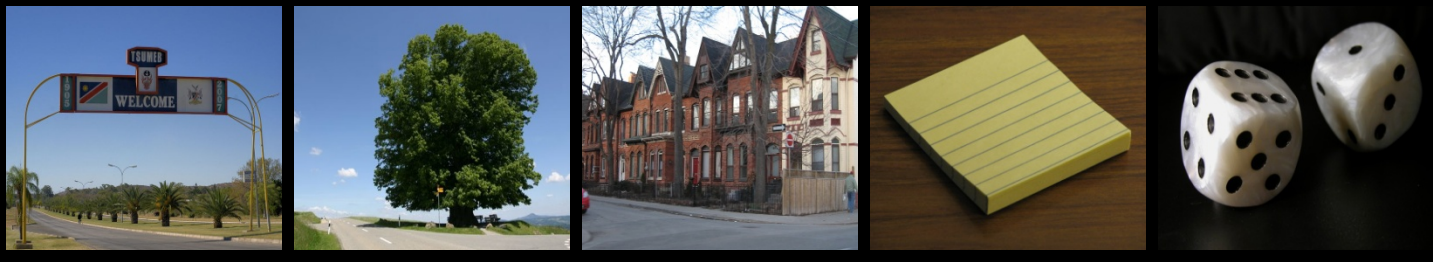
Decision list Issues

What is the terminating condition?

1. Size of R (an upper threshold)
2. $Q_k = \text{null}$
3. S' contains examples of same class



Probabilistic classifiers

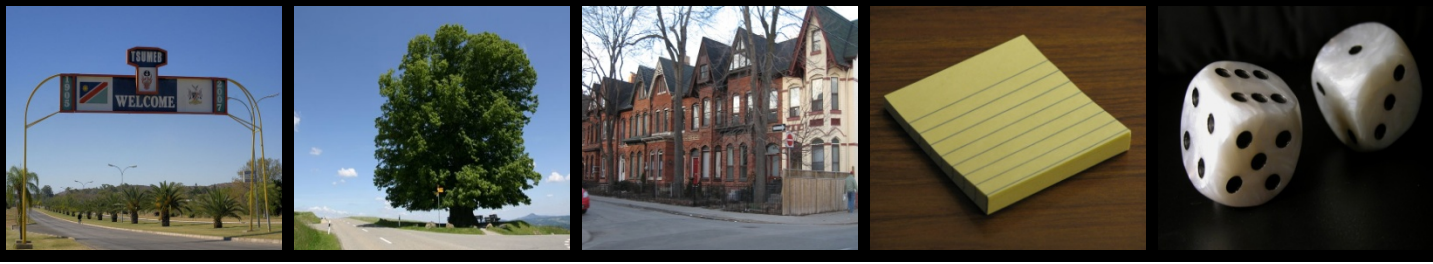


Probabilistic classifiers : NB

- Based on Bayes rule
- Naïve Bayes : Conditional independence assumption

$$P(C_i | X) = \frac{P(X | C_i) \cdot P(C_i)}{P(X)}$$

$$P(X | C_i) = \prod_{k=1}^d P(x_k | C_i)$$



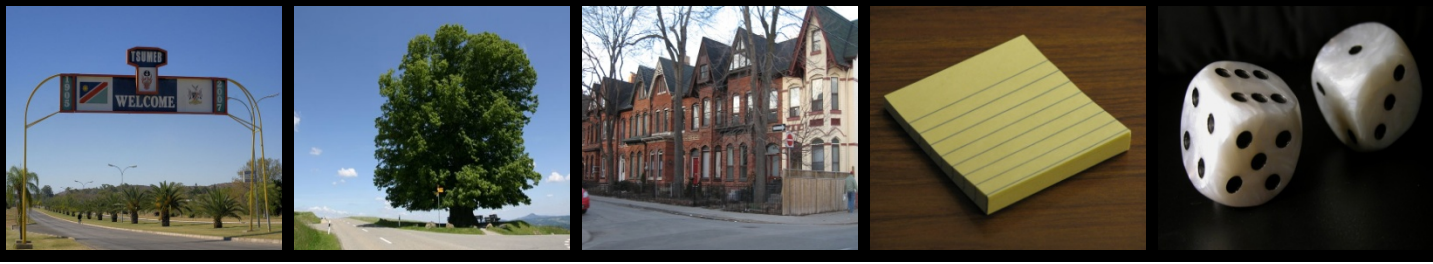
Naïve Bayes Issues

Problems due to sparsity of data?

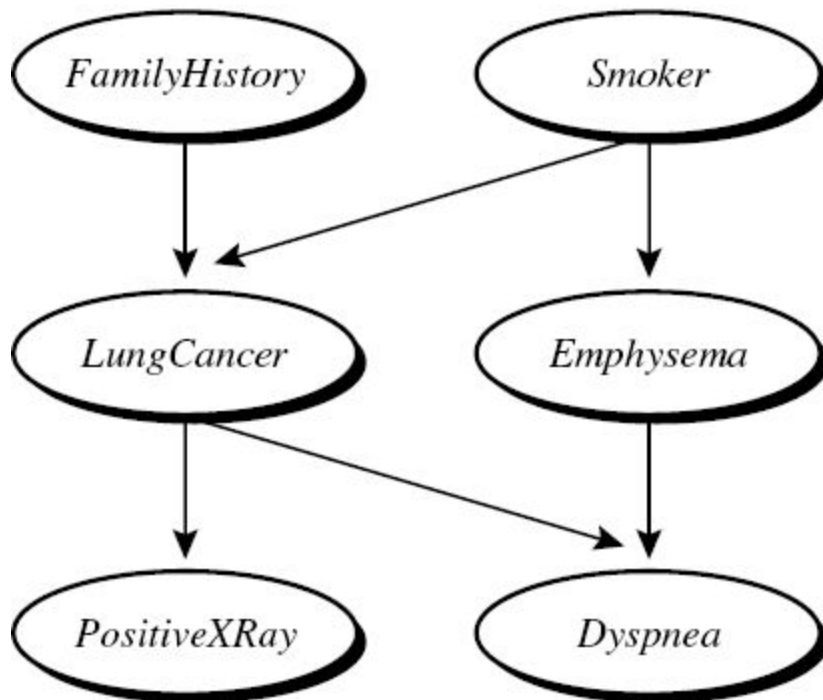
Problem : Probabilities for some values may be zero

Solution : Laplace smoothing

For each attribute value,
update probability m / n as : $(m + 1) / (n + k)$
where k = domain of values



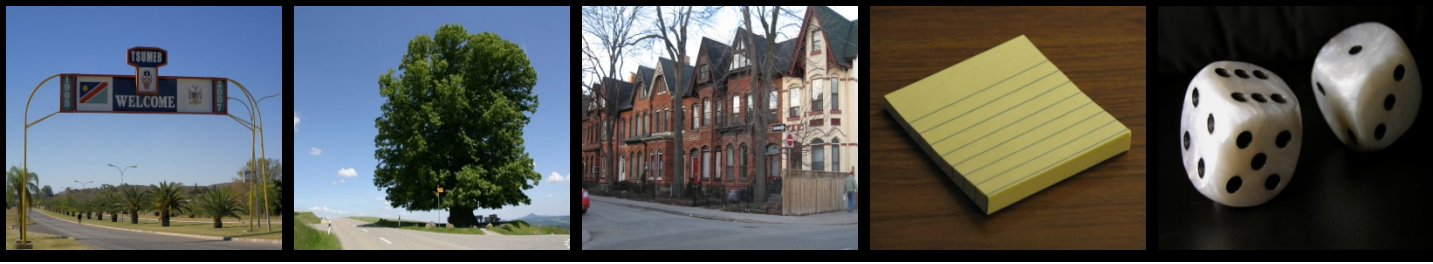
Probabilistic classifiers : BBN



	FH, S	$FH, \sim S$	$\sim FH, S$	$\sim FH, \sim S$
LC	0.8	0.5	0.7	0.1
$\sim LC$	0.2	0.5	0.3	0.9

An added term for conditional probability between attributes:

$$P(x_1, \dots, x_n) = \prod_{i=1}^n P(x_i | Parents(Y_i))$$



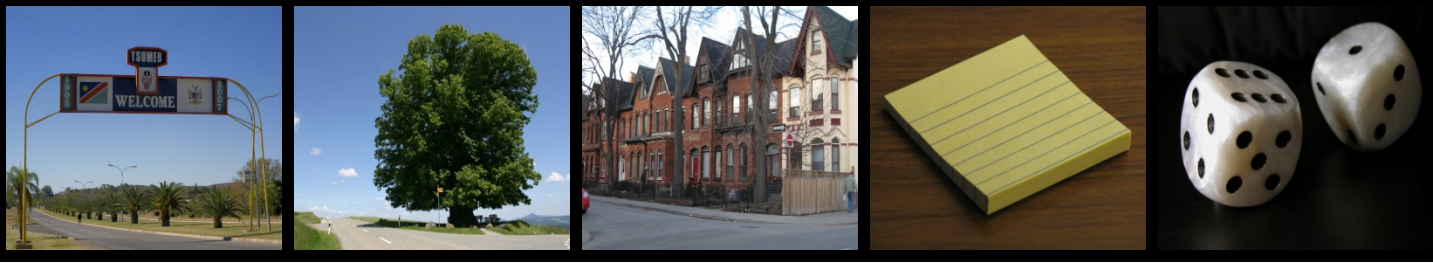
BBN learning

(when network structure known)

- Input : Network topology of BBN
- Output : Calculate the entries in conditional probability table

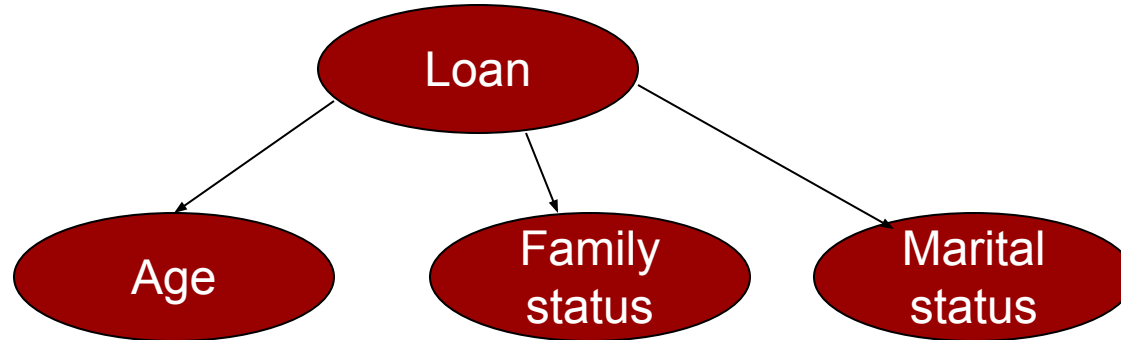
(when network structure not known)

- ???

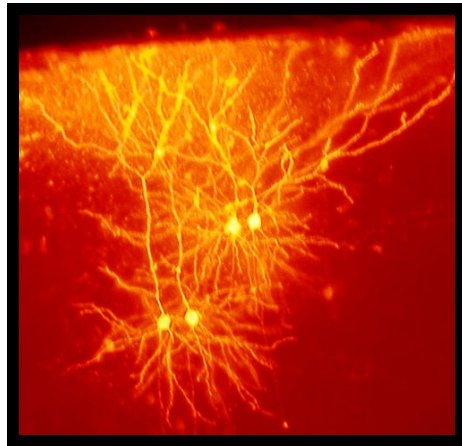
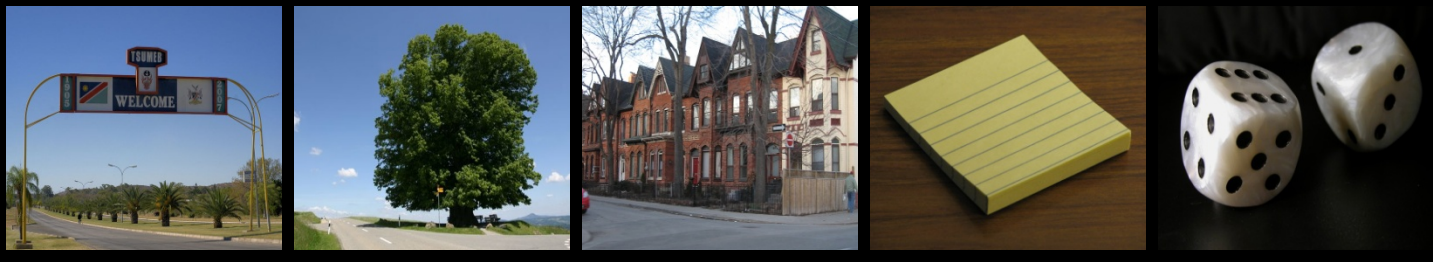


Learning structure of BBN

- Use Naïve Bayes as a basis pattern



- Add edges as required
- Examples of algorithms: TAN, K2

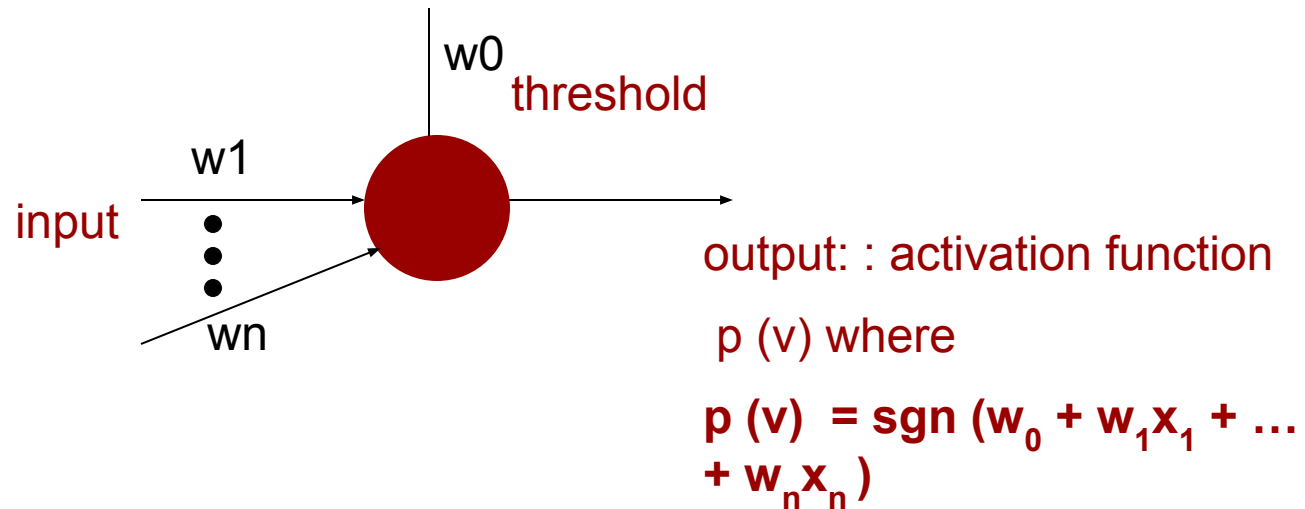


Artificial Neural Networks



Artificial Neural Networks

- Based on biological concept of neurons
- Structure of a fundamental unit of ANN:



Perceptron learning algorithm

- Initialize values of weights
- Apply training instances and get output
- Update weights according to the update rule:

η : learning rate

$$w_i \leftarrow w_i + \Delta w_i$$

t : target output

o : observed output

- Repeat till converges $\Delta w_i = \eta(t - o)x_i$

- Can represent linearly separable functions only



Sigmoid perceptron

- Basis for multilayer feedforward networks

$$\sigma(y) = \frac{1}{1 + e^{-y}}$$

$$\frac{d\sigma(y)}{dy} = \sigma(y) \cdot (1 - \sigma(y))$$



Multilayer feedforward networks

- Multilayer? Feedforward?

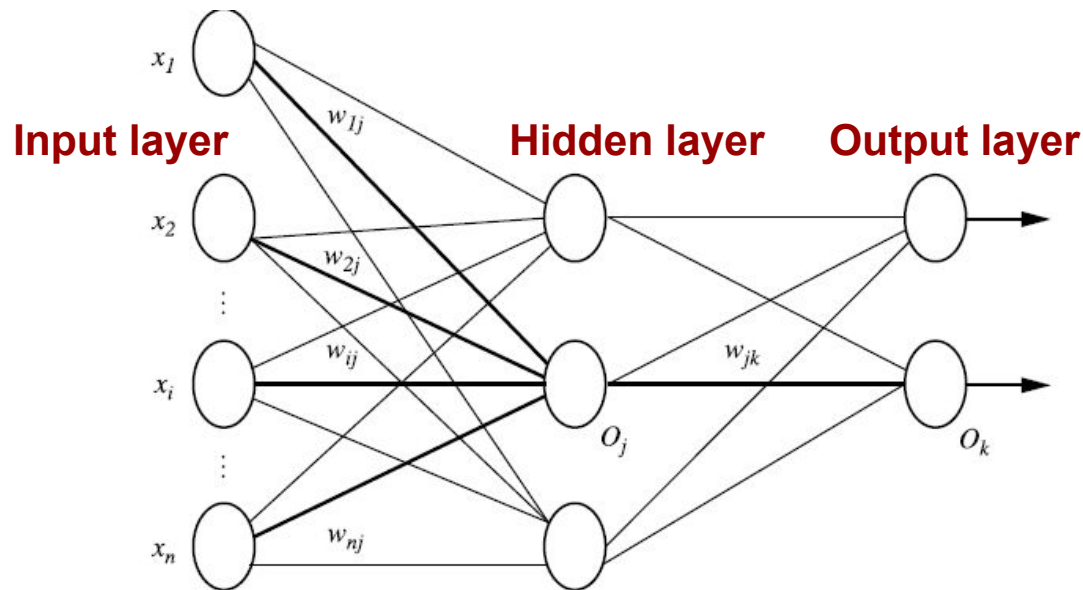


Diagram from Han-Kamber

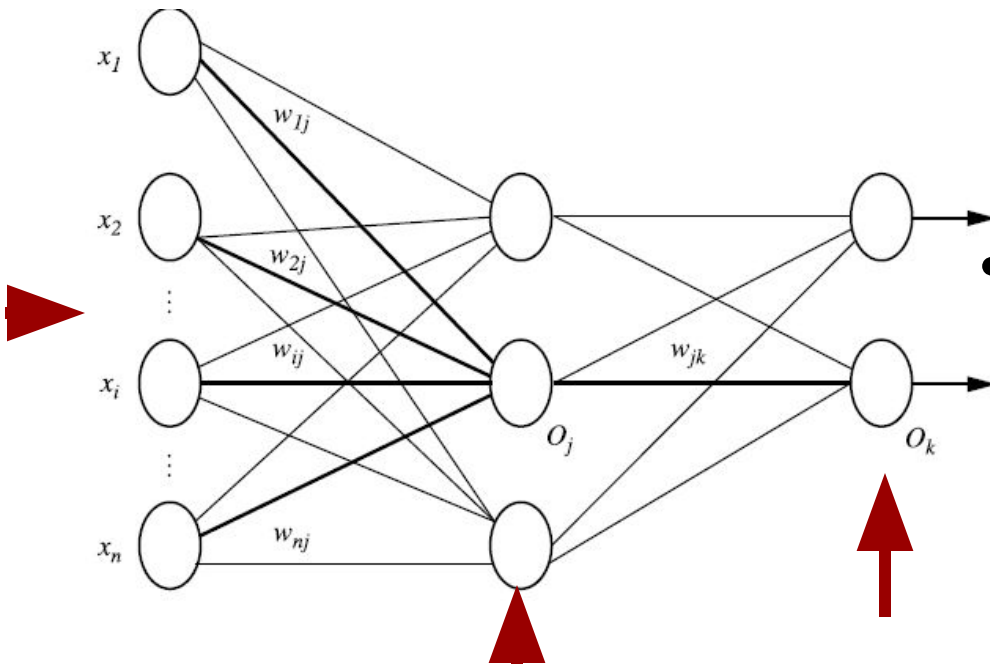


Backpropagation

- Apply training instances as input and produce output
- Update weights in the 'reverse' direction as follows:

$$\Delta w_{ji} = \eta \delta_j o_i$$

Diagram from Han-Kamber



$$\delta_h \leftarrow o_h(1 - o_h) \sum_{k \in \text{outputs}} w_{kh} \delta_k$$



ANN Issues

Learning the structure of the network

1. Construct a complete network
2. Prune using heuristics:
 - Remove edges with weights nearly zero
 - Remove edges if the removal does not affect accuracy

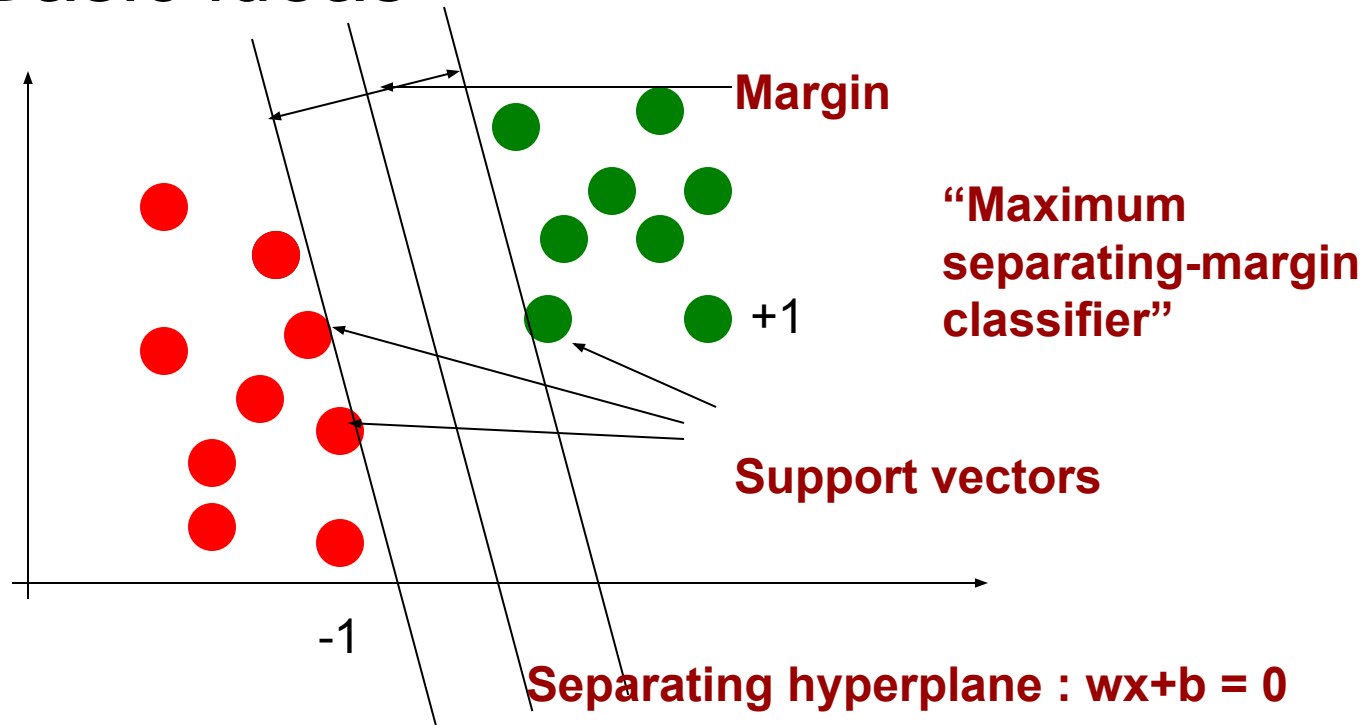


Support vector machines



Support vector machines

- Basic ideas



SVM training

$$\text{Maximize } \sum_{k=1}^R \alpha_k - \frac{1}{2} \sum_{k=1}^R \sum_{l=1}^R \alpha_k \alpha_l Q_{kl} \text{ where } Q_{kl} = y_k y_l (\mathbf{x}_k \cdot \mathbf{x}_l)$$

Subject to these constraints:

$$0 \leq \alpha_k \leq C \quad \forall k$$

$$\sum_{k=1}^R \alpha_k y_k = 0$$

Then define:

$$\mathbf{w} = \sum_{k=1}^R \alpha_k y_k \mathbf{x}_k$$

$$b = y_K (1 - \varepsilon_K) - \mathbf{x}_K \cdot \mathbf{w}_K$$

where $K = \arg \max_k \alpha_k$

Lagrangian multipliers are

Dot product of \mathbf{x}_k and \mathbf{x}_l



Focussing on dot product

$$\text{Maximize } \sum_{k=1}^R \alpha_k - \frac{1}{2} \sum_{k=1}^R \sum_{l=1}^R \alpha_k \alpha_l Q_{kl} \text{ where } Q_{kl} = y_k y_l (\Phi(\mathbf{x}_k) \cdot \Phi(\mathbf{x}_l))$$

- For non-linear separable points, we plan to map them to a higher dimensional (and linearly separable) space
- The product $\Phi(\mathbf{x}_k) \cdot \Phi(\mathbf{x}_l)$ can be time-consuming. Therefore, we use kernel functions



Kernel functions

$$\text{Maximize } \sum_{k=1}^R \alpha_k - \frac{1}{2} \sum_{k=1}^R \sum_{l=1}^R \alpha_k \alpha_l Q_{kl} \text{ where } Q_{kl} = y_k y_l k(\mathbf{x}, \mathbf{x}')$$

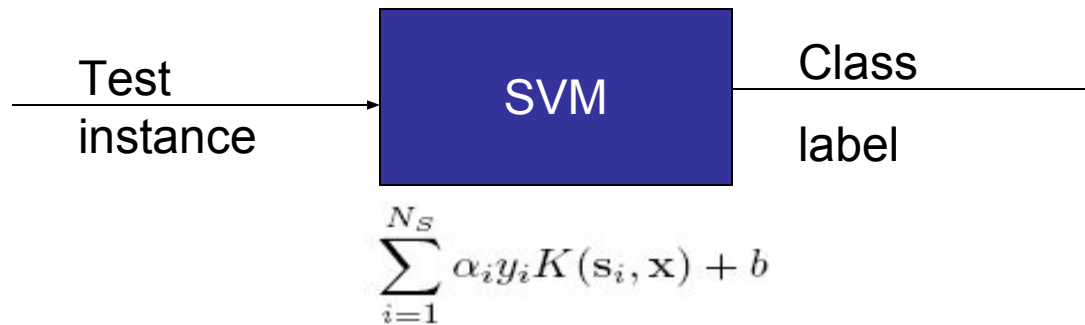
- Without having to know the non-linear mapping, apply kernel function, say,

$$k(\mathbf{x}, \mathbf{x}') = (\text{scale} \cdot \langle \mathbf{x}, \mathbf{x}' \rangle + \text{offset})^{\text{degree}}$$

- Reduces the number of computations required to generate Q_{kl} values.



Testing SVM



SVM Issues

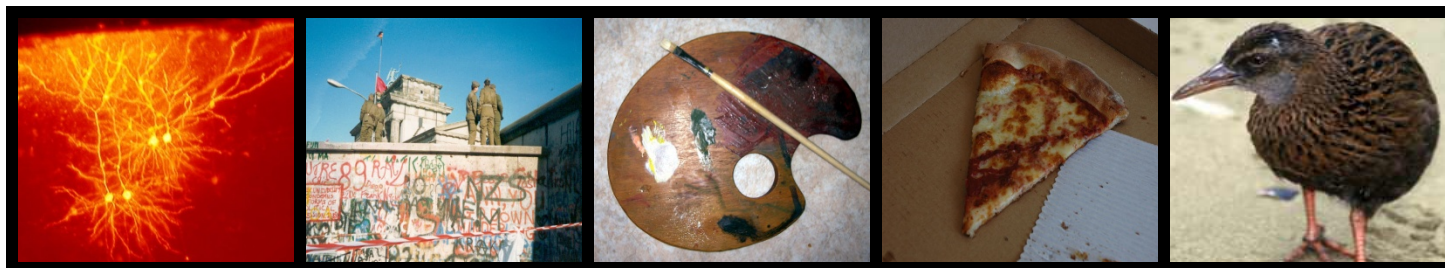
What if n-classes are to be predicted?

Problem : SVMs deal with two-class classification

Solution : Have multiple SVMs each for one class



Combining classifiers

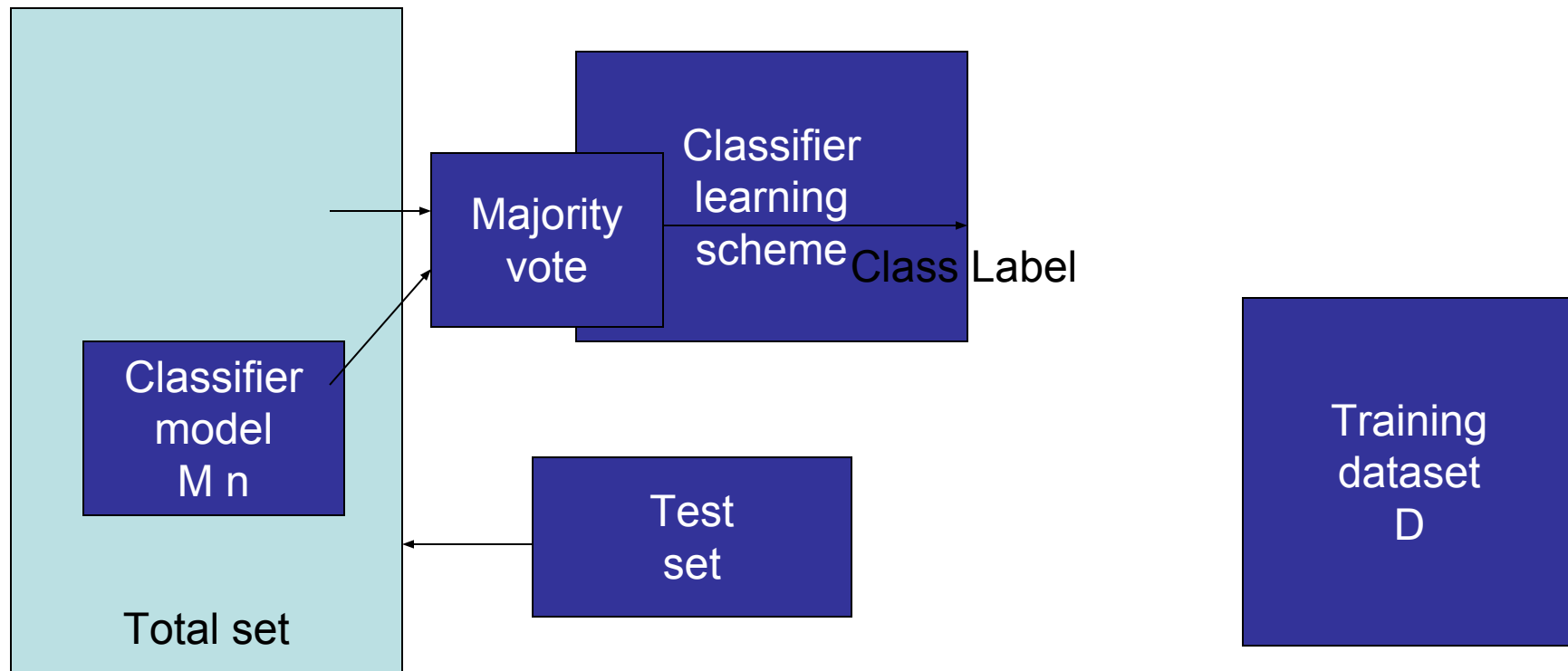


Combining Classifiers

- ‘Ensemble’ learning
- Use a combination of models for prediction
 - Bagging : Majority votes
 - Boosting : Attention to the ‘weak’ instances
- Goal : An improved combined model



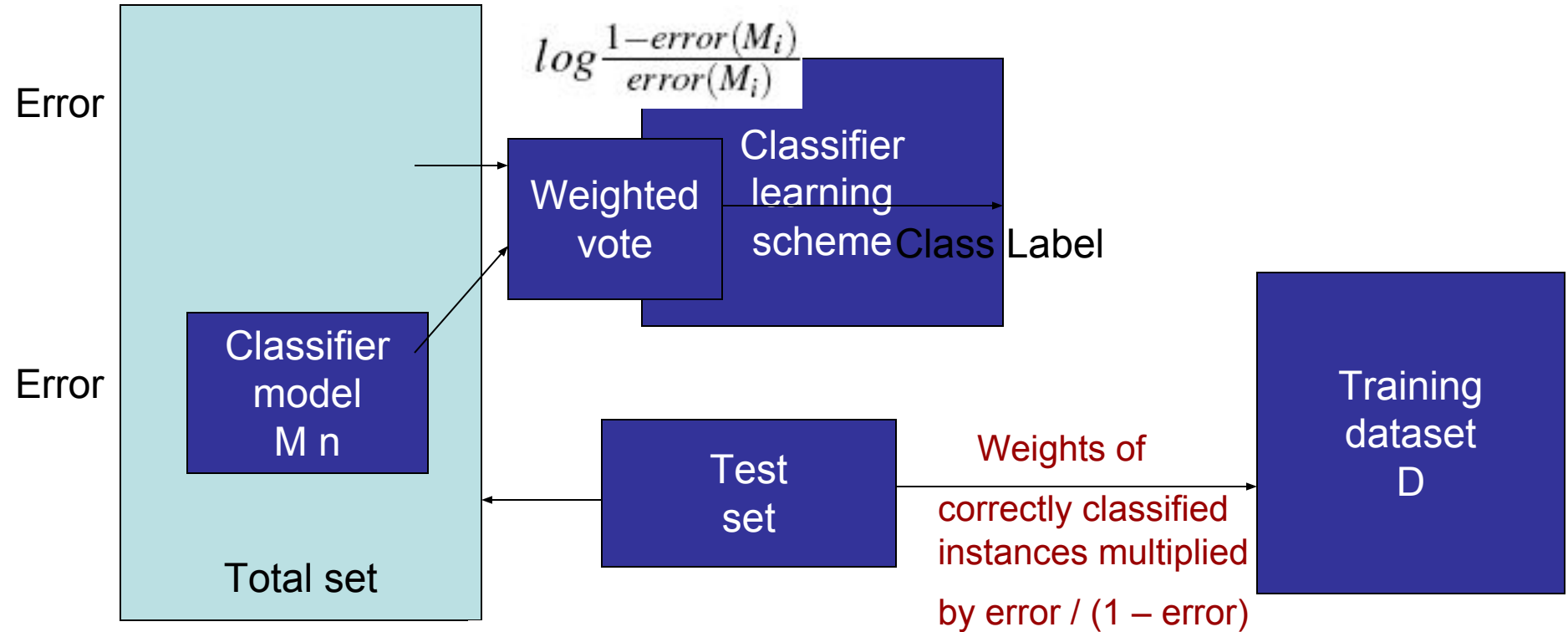
Bagging



At random. May use bootstrap sampling with replacement



Boosting (AdaBoost)



~~Set~~ $\text{error}(M_i) = \sum_j w_j \times \text{err}(X_j)$ ~~box~~ ~~May use~~ ~~placement~~ ~~if error > 0.5?~~



The last slice



Data preprocessing

- Attribute subset selection
 - Select a subset of total attributes to reduce complexity
- Dimensionality reduction
 - Transform instances into 'smaller' instances



Attribute subset selection

- Information gain measure for attribute selection in decision trees
- Stepwise forward / backward elimination of attributes



Dimensionality reduction

- High dimensions : Complexity

Number of attributes of
a data instance



instance x in
 p -dimensions



$$s = Wx$$

W is $k \times p$ transformation matrix.



instance x in
 k -dimensions

$$k < p$$



Principal Component Analysis

- Computes k orthonormal vectors :
Principal components
- Essentially provide a new set of axes – in decreasing order of variance

$$S = U^T X.$$

$$w_1 = \arg \max_{||w=1||} \text{Var}\{x^T w\}$$

$$s = Wx$$

$$(k \times n) \quad (p \times n) \quad (k \times p)$$

Eq

F

$$(p \times n) \quad (p \times n)$$

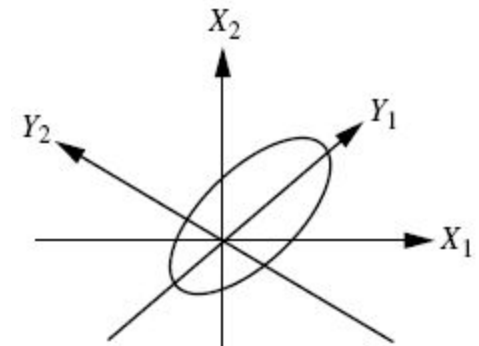
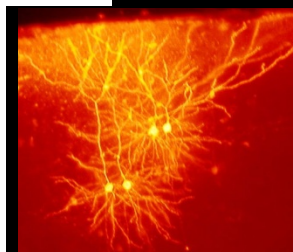


Diagram from Han-Kamber

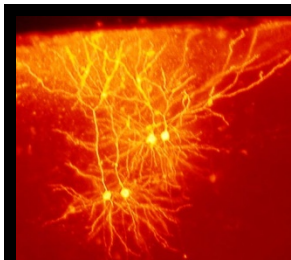
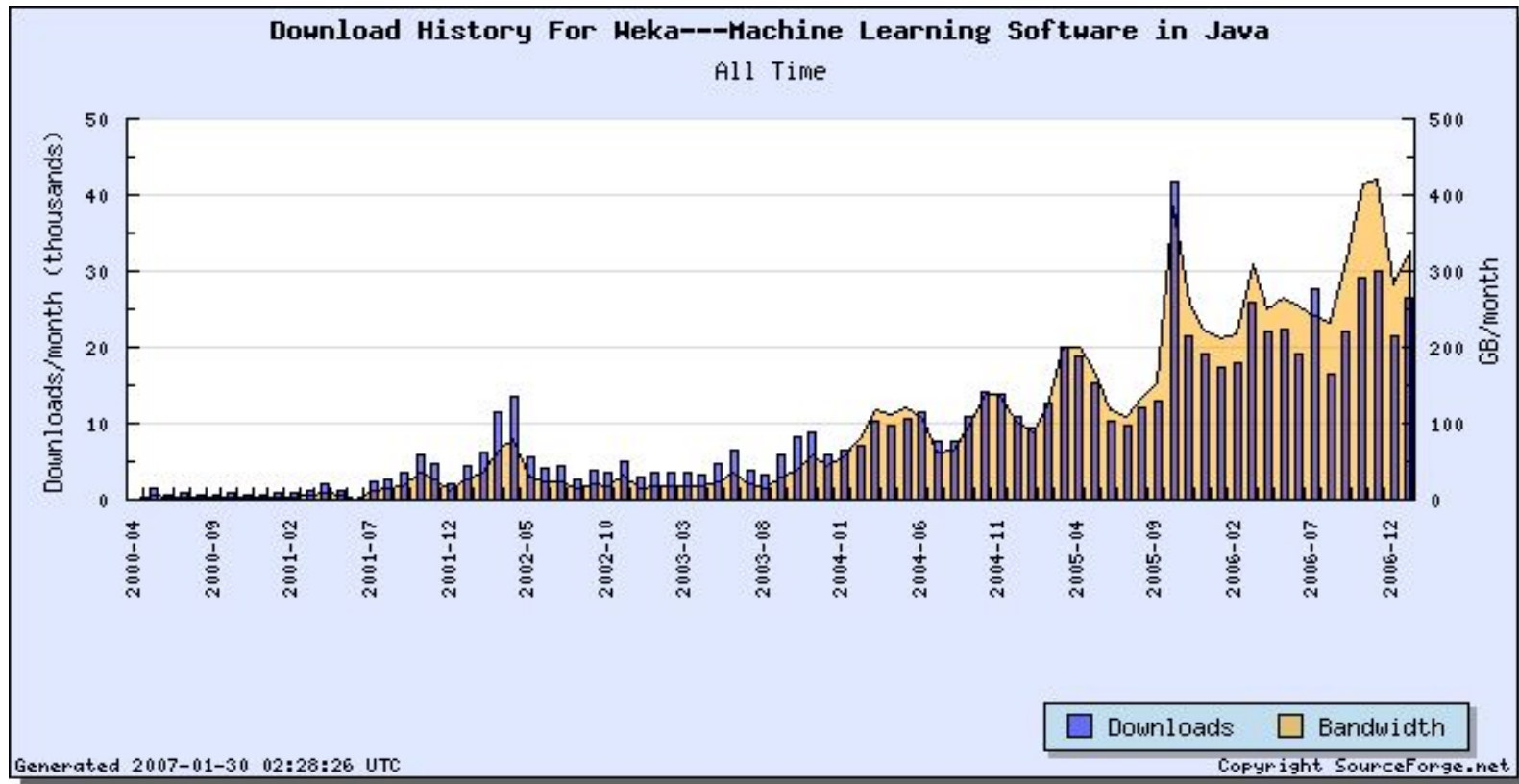




Weka & Weka Demo



Weka & Weka Demo



ARFF file format

@RELATION nursery *Name of the relation*

@ATTRIBUTE children numeric *Attribute definition*

@ATTRIBUTE housing {convenient, less_conv, critical}

@ATTRIBUTE finance {convenient, inconv}

@ATTRIBUTE social {nonprob, slightly_prob, problematic}

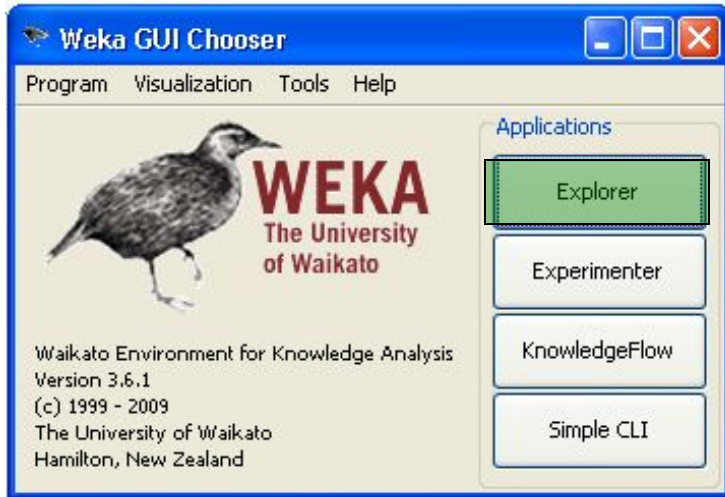
@ATTRIBUTE health {recommended, priority, not_recom}

@ATTRIBUTE pr_val
{recommend,priority,not_recom,very_recom,spec_prior}

@DATA *Data instances : Comma separated, each on a new line*
3,less_conv,convenient,slightly_prob,recommended,spec_prior



Parts of weka

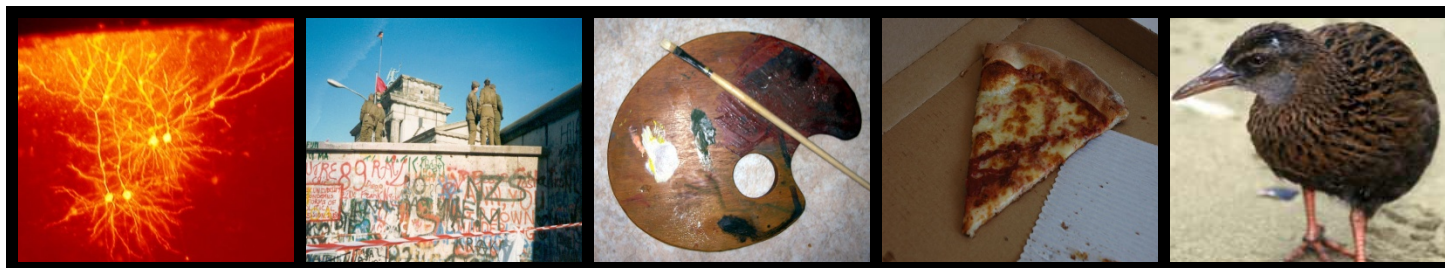


Knowledge Flow

Similar to Work Flow
'Customized' to one's needs



Weka demo



Key References

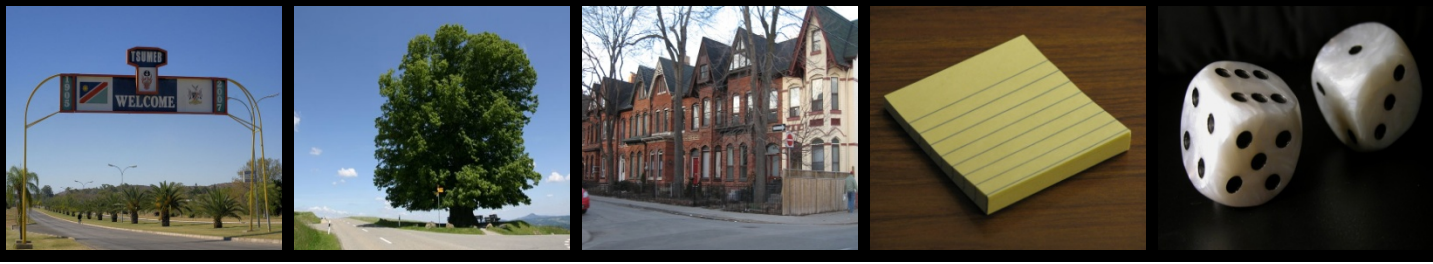
- Data Mining – Concepts and techniques; Han and Kamber, Morgan Kaufmann publishers, 2006.
- Machine Learning; Tom Mitchell, McGraw Hill publications.
- Data Mining – Practical machine learning tools and techniques; Witten and Frank, Morgan Kaufmann publishers, 2005.

end of slideshow

Extra slides 1

Difference between decision lists and decision trees:

1. Lists are functions tested sequentially (More than one attributes at a time)
Trees are attributes tested sequentially
2. Lists may not require a 'complete' coverage for values of an attribute.
All values of an attribute correspond to atleast one branch of the attribute split.



Learning structure of BBN

- K2 Algorithm :
 - Consider nodes in an order
 - For each node, calculate utility to add an edge from previous nodes to this one
- TAN :
 - Use Naïve Bayes as the baseline network
 - Add different edges to the network based on utility
- Examples of algorithms: TAN, K2

Delta rule

- Delta rule enables to converge to a best fit if points are not linearly separable
- Uses gradient descent to choose the hypothesis space

$$\Delta w_i = \eta \sum_{d \in D} (t_d - o_d) x_{id}$$

