

State of Art in AI

Generative Deep Learning

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<https://sites.google.com/view/aforeveryone/>

Generative Deep Learning

Networks that generate

The future of AI

1. Deep Learning



“Biggest leap since invention of computers”

Output of AI: Scalar values (numbers)

Output =

2. Generative Deep Learning



GAN “the most interesting idea in the last 10 years in ML.”

Output of AI: Vectors , Images

Output =



3. AI that creates another AI



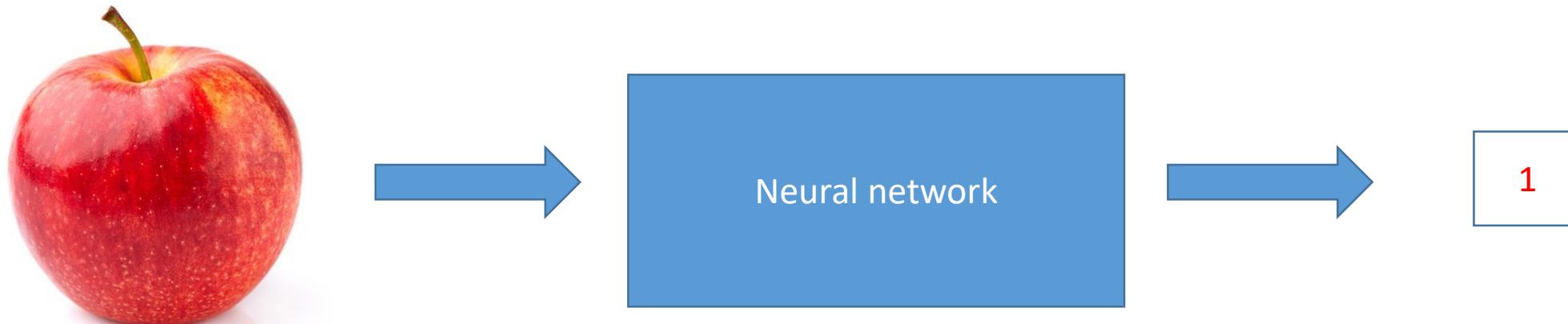
Progressive, AutoML

Output of AI: Neural networks

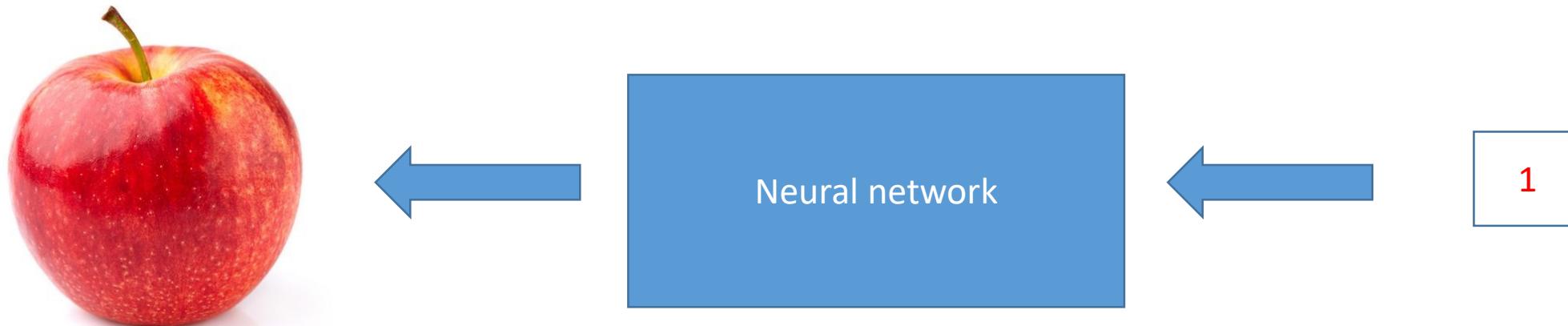
Output =



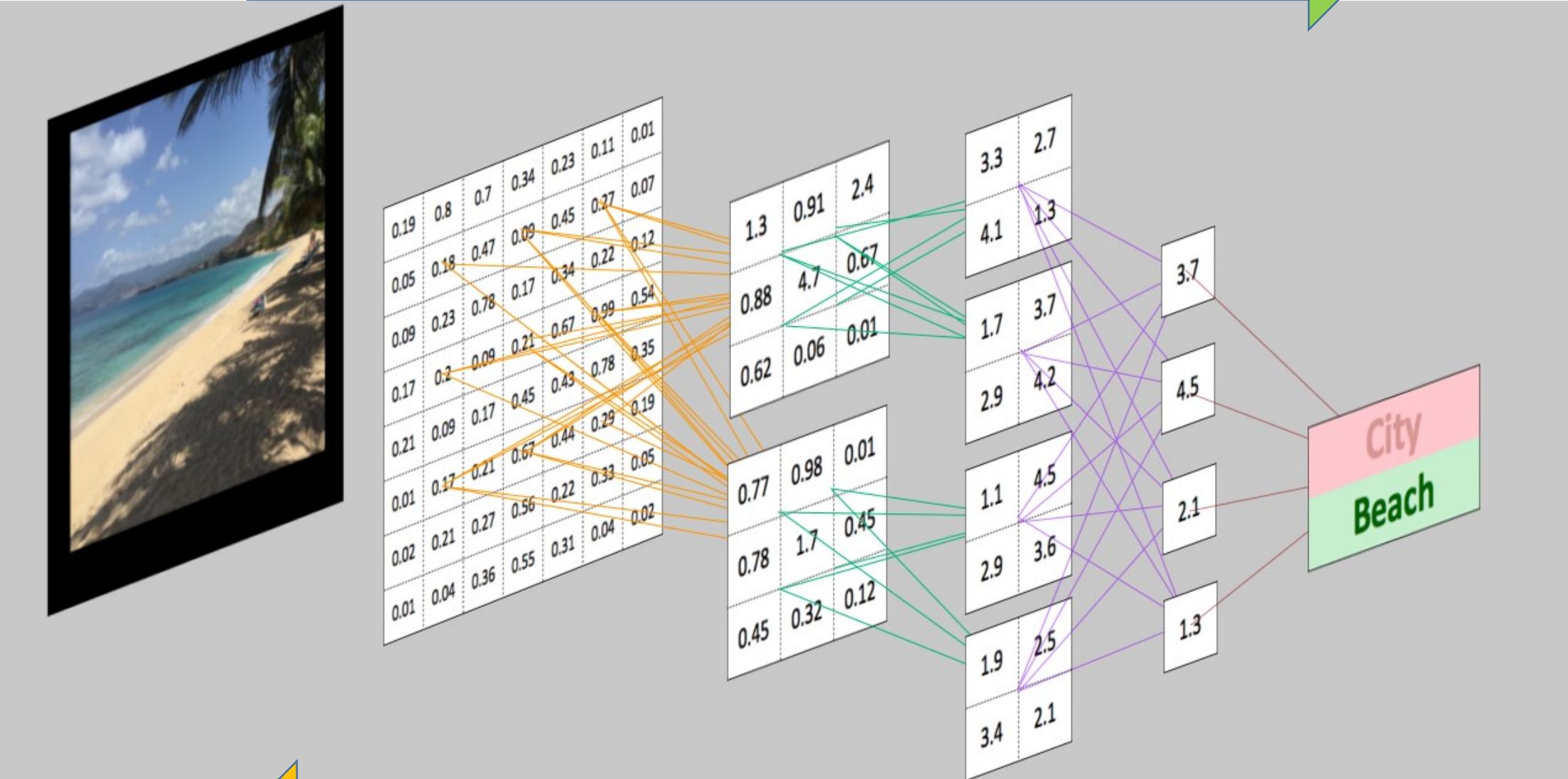
A neural network learns the patterns about apple and oranges



So how can we use the learning made by a neural network?

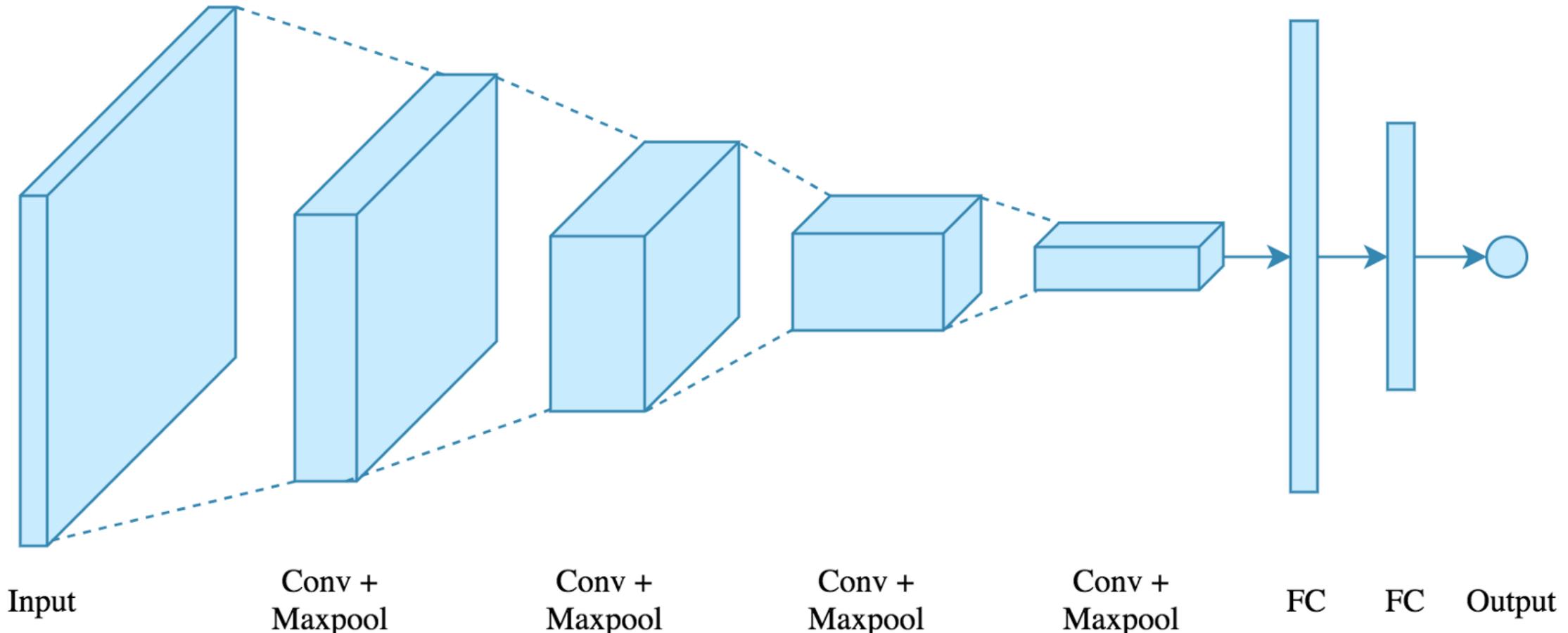


Each layer is a way to represent the image

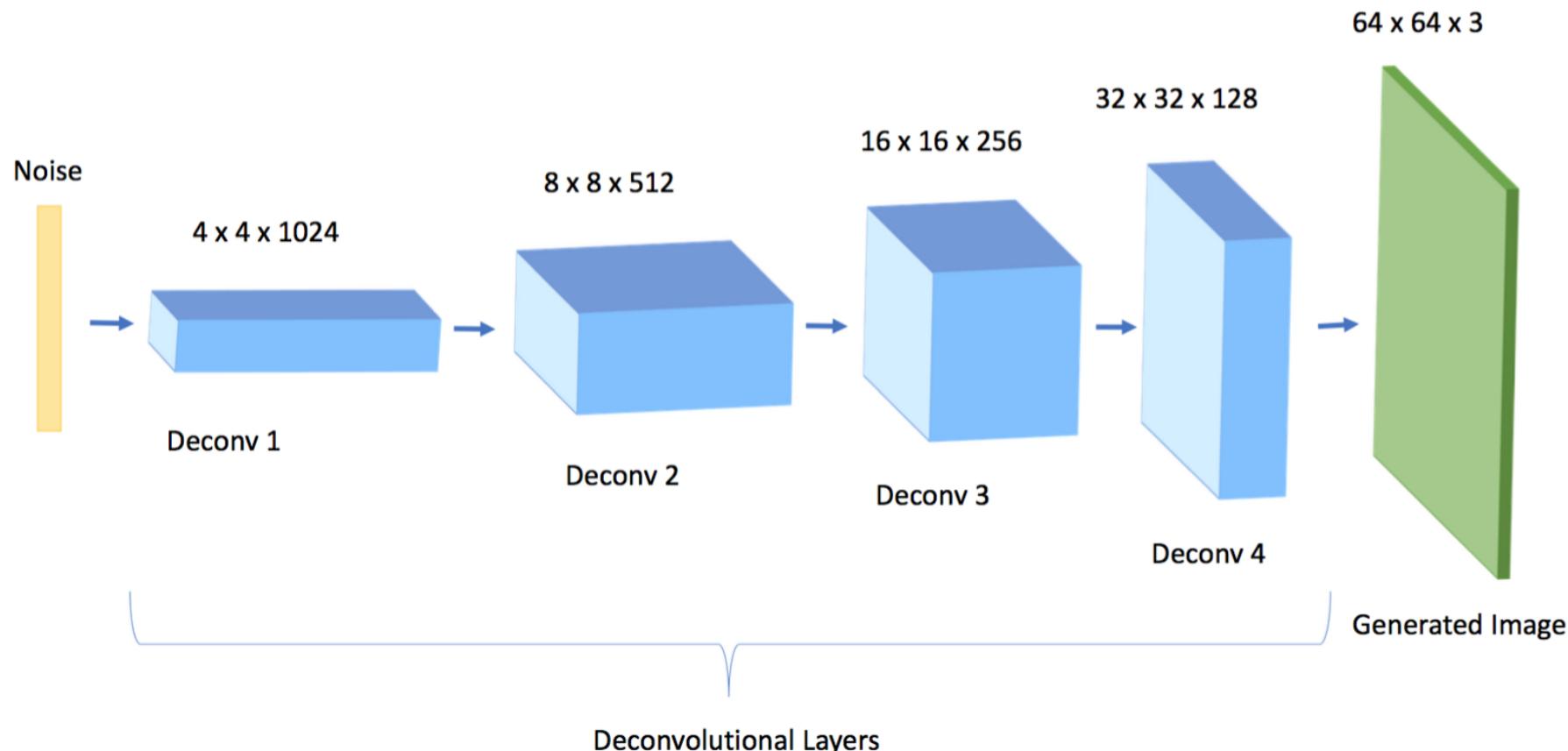


Is it possible to represent an integer as array ?

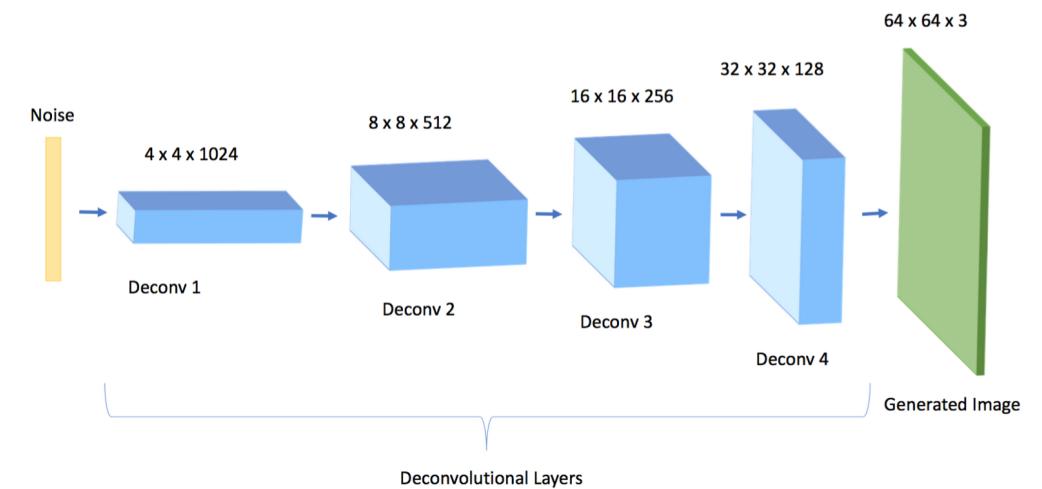
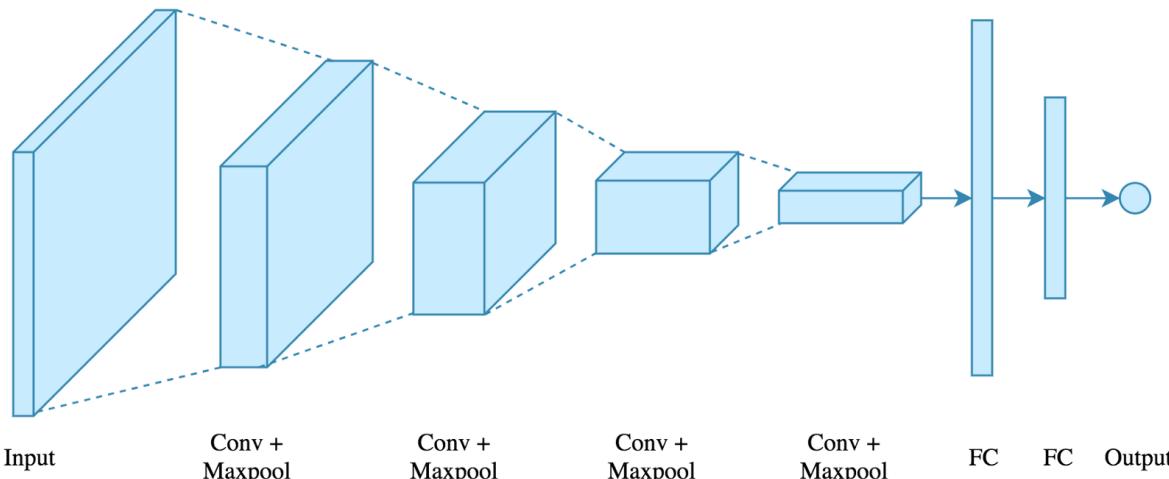
A image can be transformed to a integer
(representation learning)



A integer can be transformed to a image
(representation learning)



A image can be transformed to a integer (representation learning)



Input Image



Bottleneck Layer

Output Image

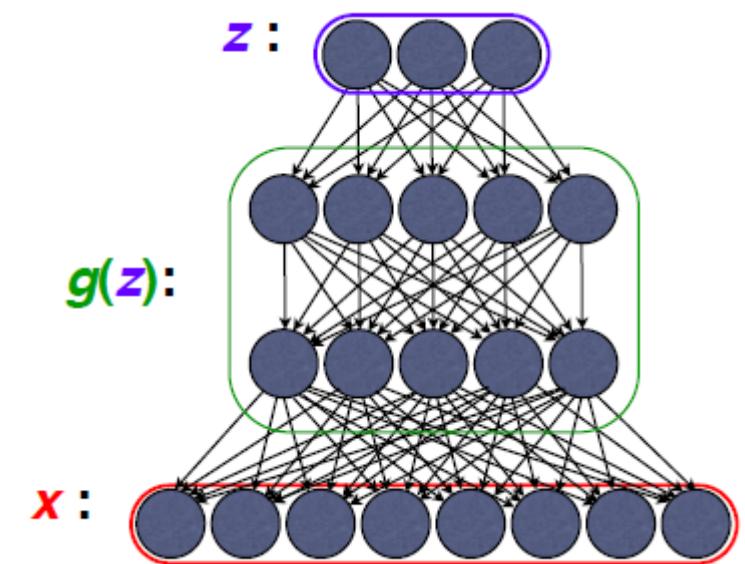
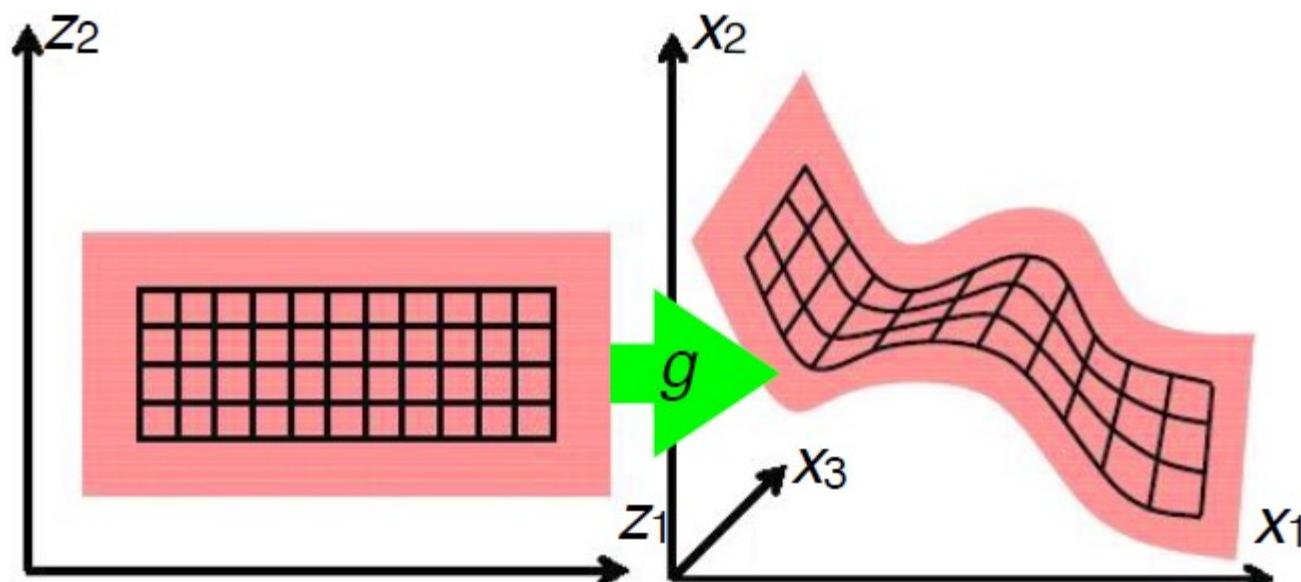


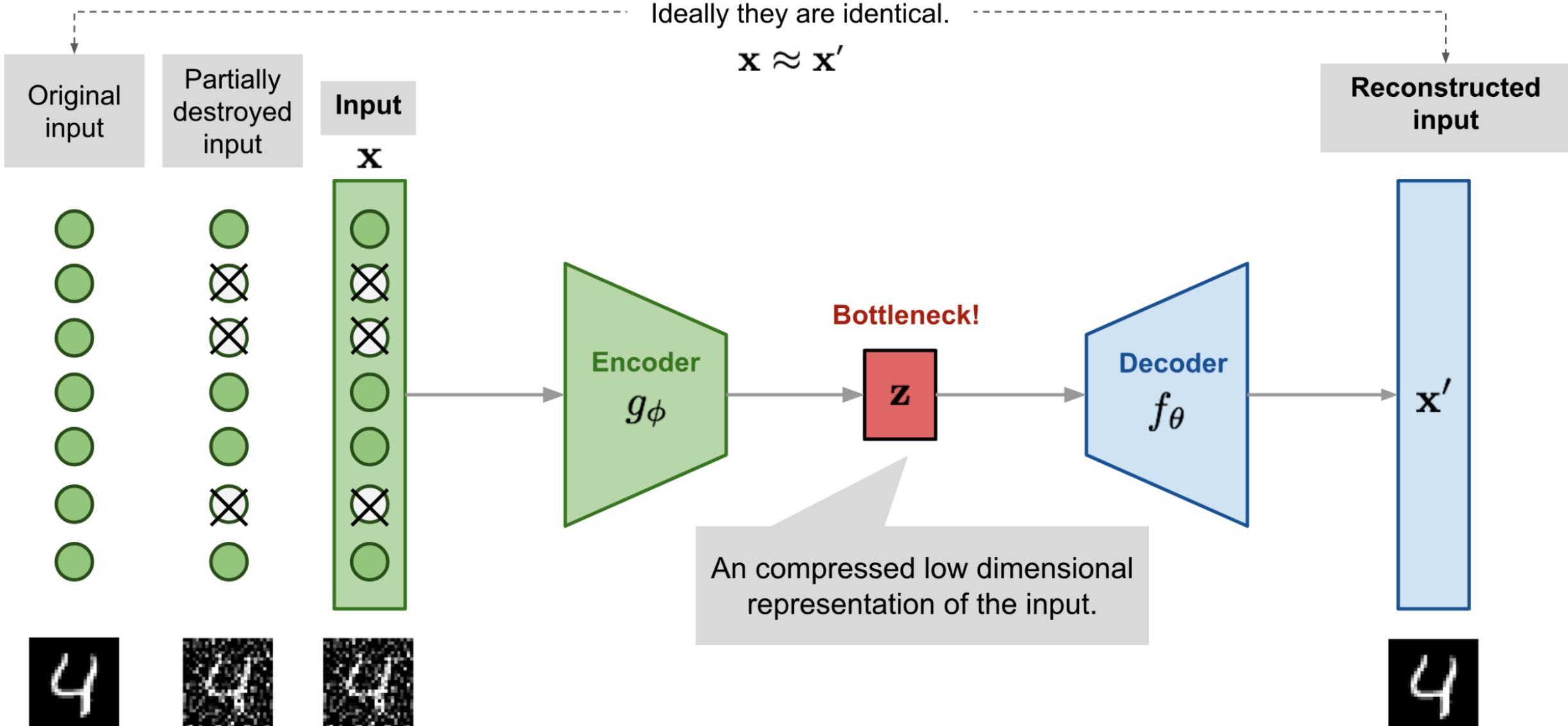
Encoder

Decoder

Latent variable models

- Remember representation learning
- Transform by moving in latent space





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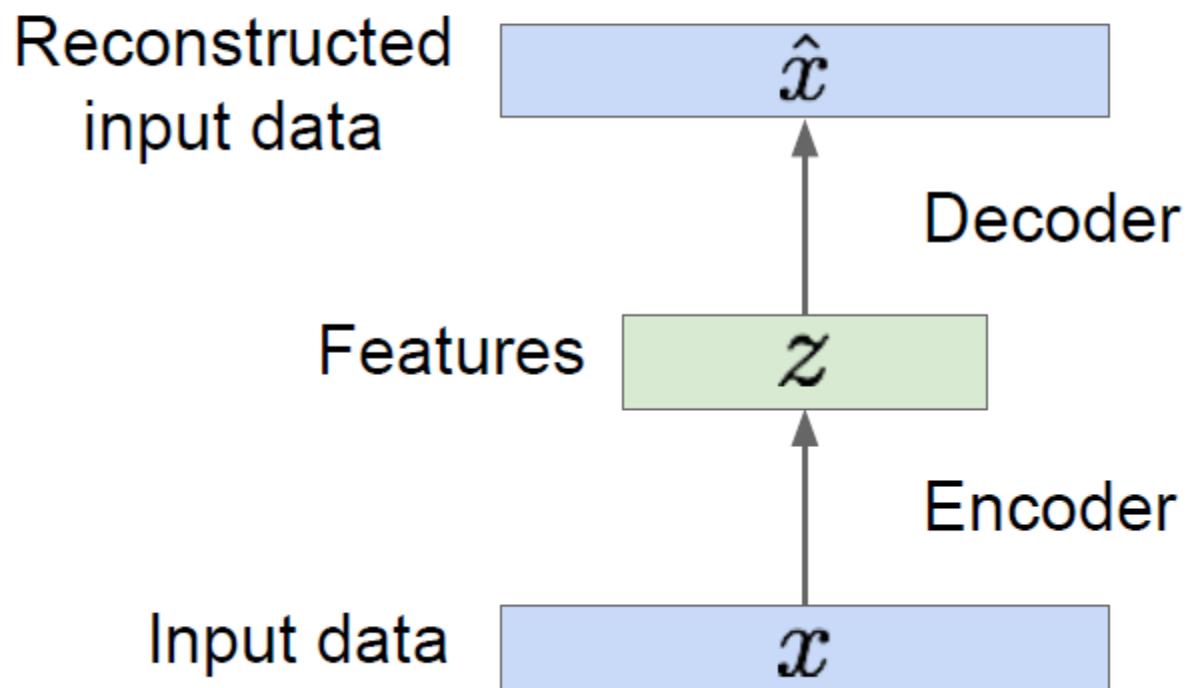
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Auto encoders

How to learn this feature representation?

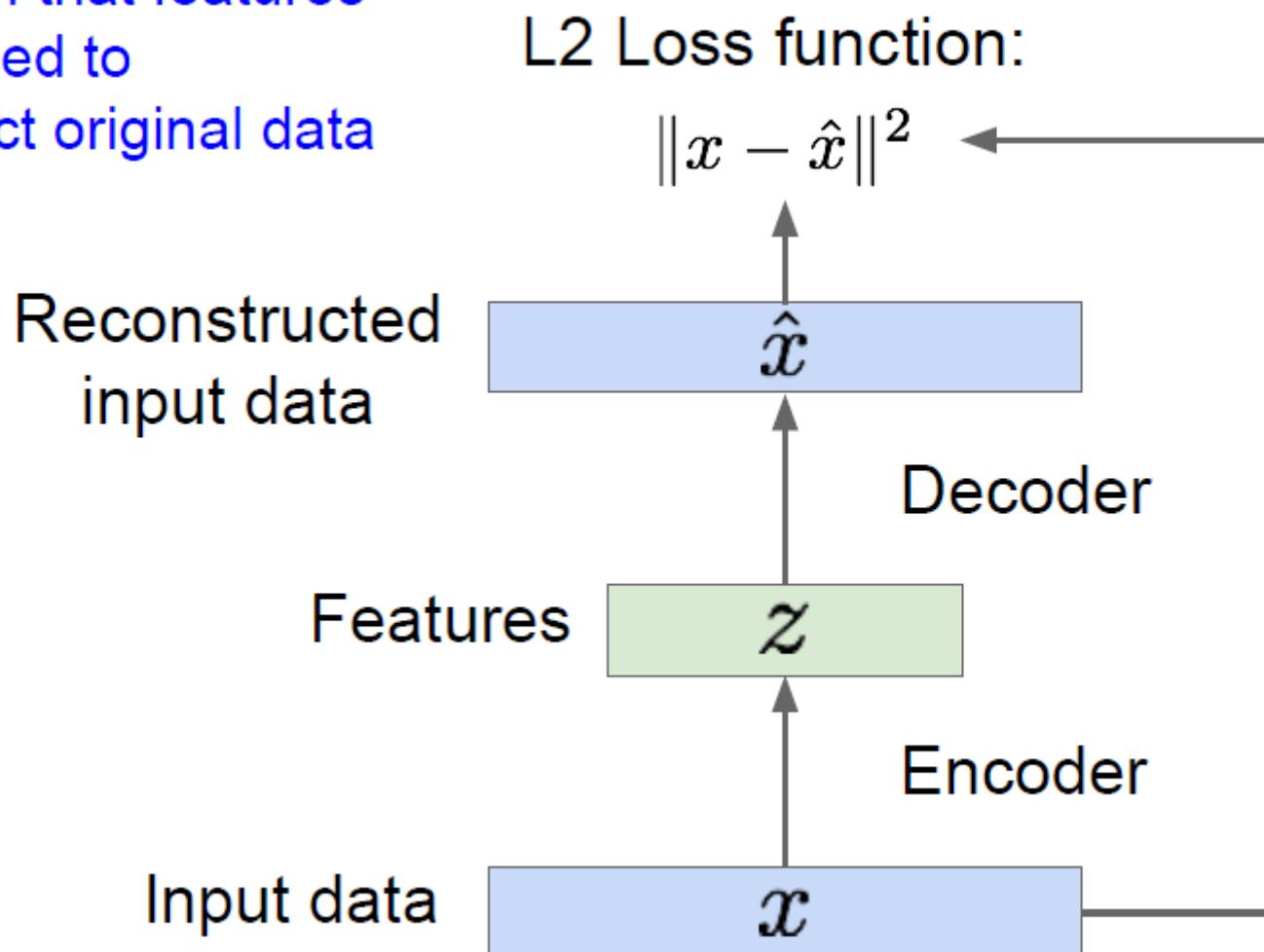
Train such that features can be used to reconstruct original data

“Autoencoding” - encoding itself



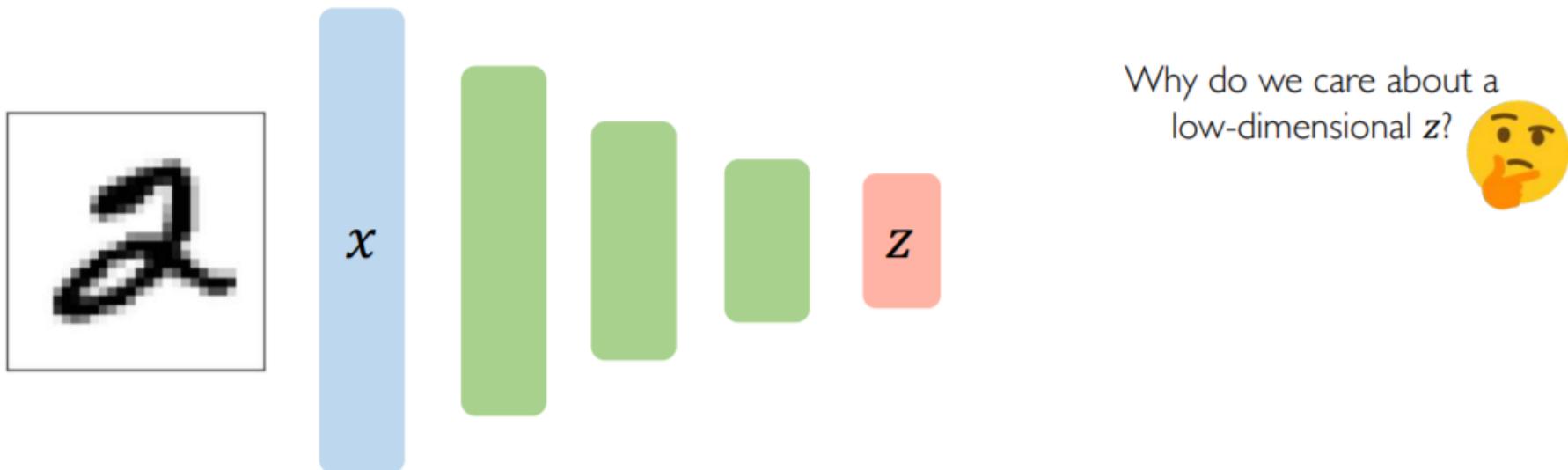
Auto encoders

Train such that features can be used to reconstruct original data



Autoencoders: background

Unsupervised approach for learning a **lower-dimensional** feature representation from unlabeled training data

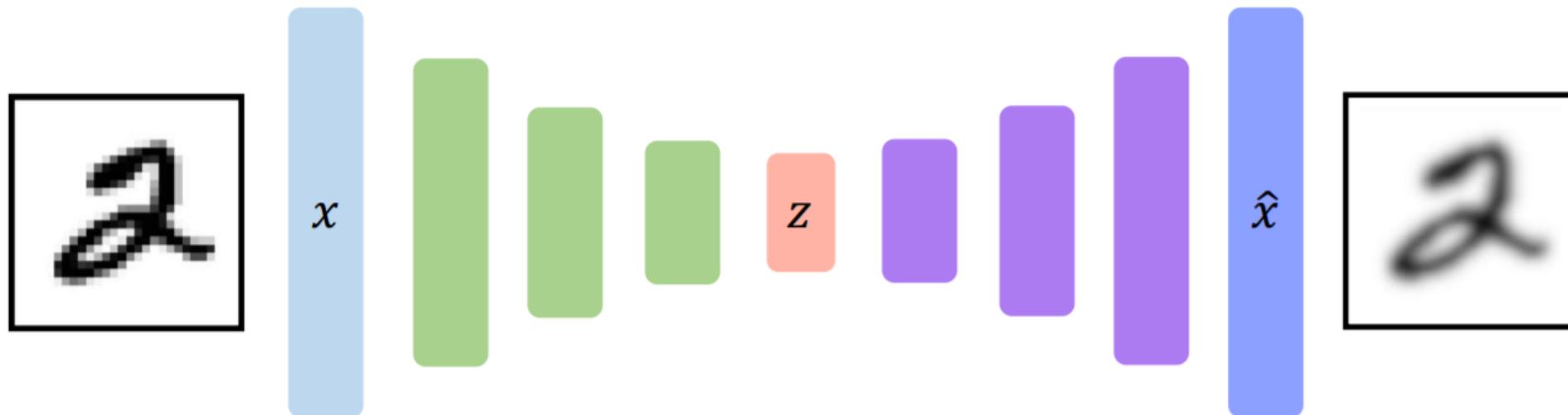


“Encoder” learns mapping from the data, x , to a low-dimensional latent space, z

Autoencoders: background

How can we learn this latent space?

Train the model to use these features to **reconstruct the original data**

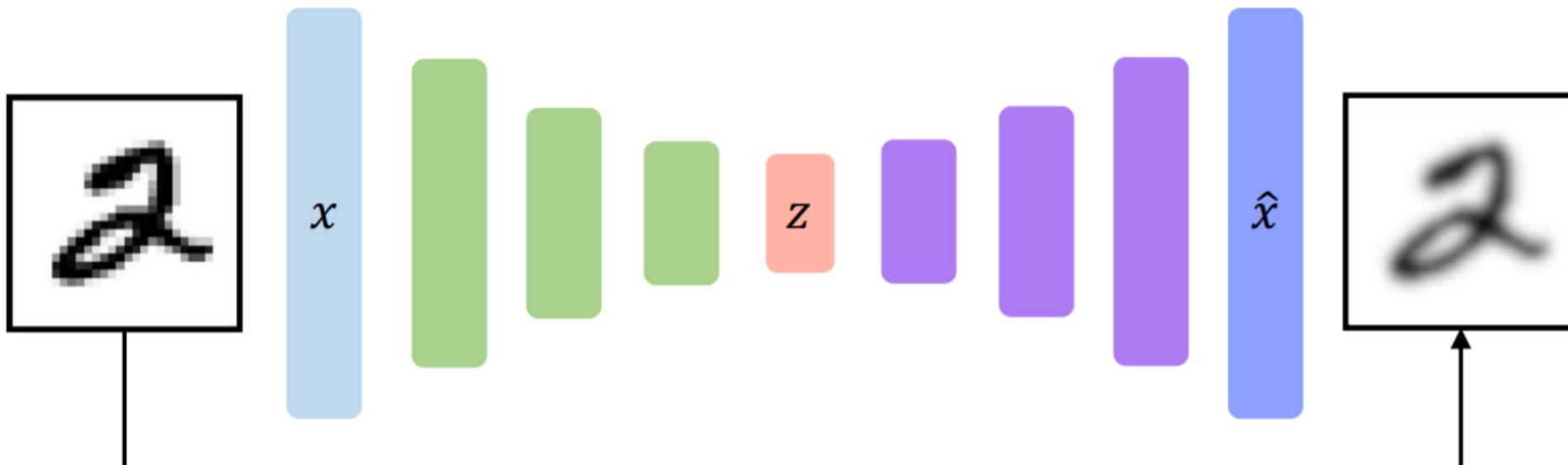


“Decoder” learns mapping back from latent, z , to a reconstructed observation, \hat{x}

Autoencoders: background

How can we learn this latent space?

Train the model to use these features to **reconstruct the original data**



$$\mathcal{L}(x, \hat{x}) = \|x - \hat{x}\|^2$$

Loss function doesn't
use any labels!!

Bottleneck hidden layer forces network to learn a compressed latent representation

Reconstruction loss forces the latent representation to capture (or encode) as much “information” about the data as possible

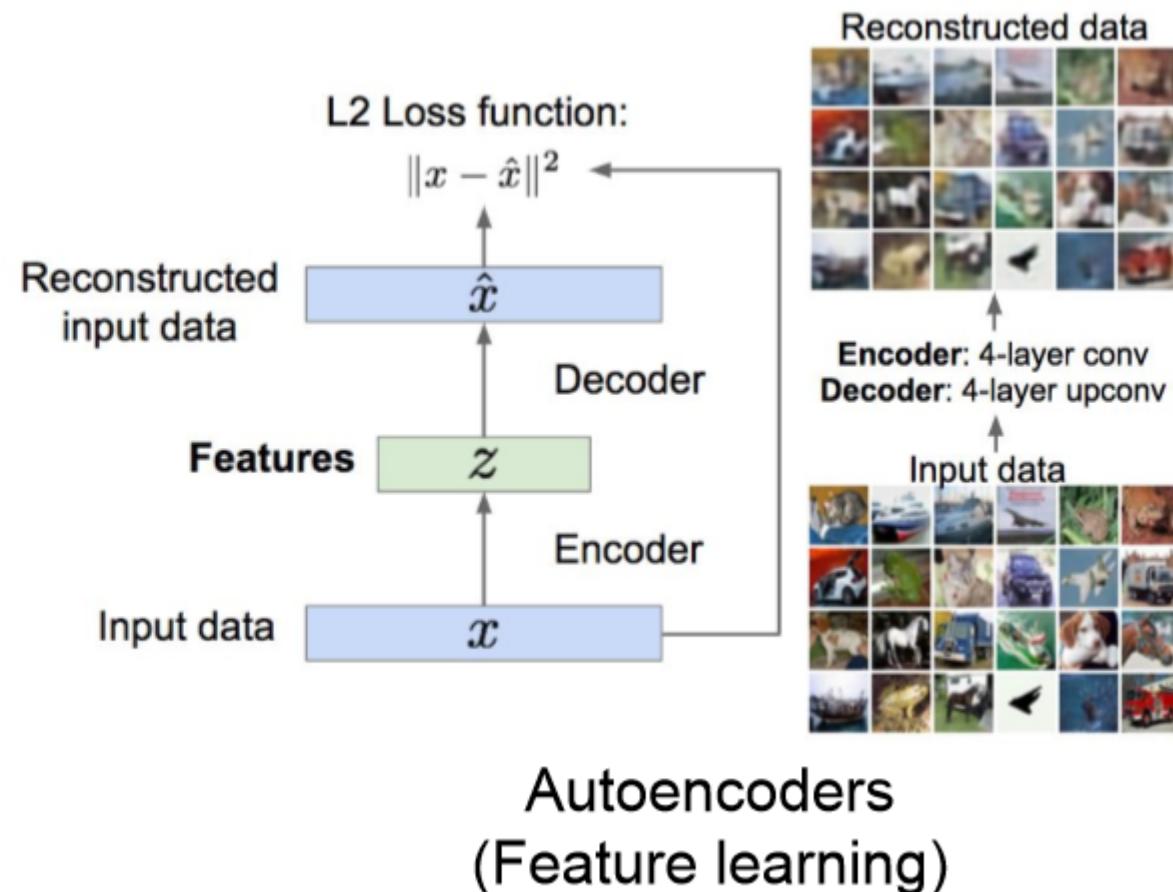
Unsupervised Learning

Data: x

Just data, no labels!

Goal: Learn some underlying hidden *structure* of the data

Examples: Clustering, dimensionality reduction, feature learning, density estimation, etc.



Generative Adversarial Networks (GANs)

Supervised vs Unsupervised Learning

Supervised Learning

Data: (x, y)
 x is data, y is label

Goal: Learn a *function* to map $x \rightarrow y$

Unsupervised Learning

Training data is cheap

Data: x
Just data, no labels!

Goal: Learn some underlying
hidden *structure* of the data

Holy grail: Solve
unsupervised learning
=> understand structure
of visual world

Supervised vs unsupervised learning

Supervised Learning

Data: (x, y)

x is data, y is label

Goal: Learn function to map
 $x \rightarrow y$

Examples: Classification,
regression, object detection,
semantic segmentation, etc.

Unsupervised Learning

Data: x

x is data, no labels!

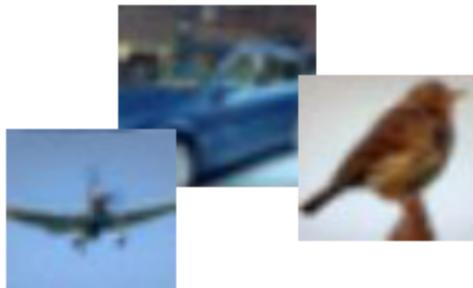
Goal: Learn some *hidden* or
underlying structure of the data

Examples: Clustering, feature or
dimensionality reduction, etc.



Generative Models

Given training data, generate new samples from same distribution



Training data $\sim p_{\text{data}}(x)$



Generated samples $\sim p_{\text{model}}(x)$

Want to learn $p_{\text{model}}(x)$ similar to $p_{\text{data}}(x)$

Sample Generation



Input samples

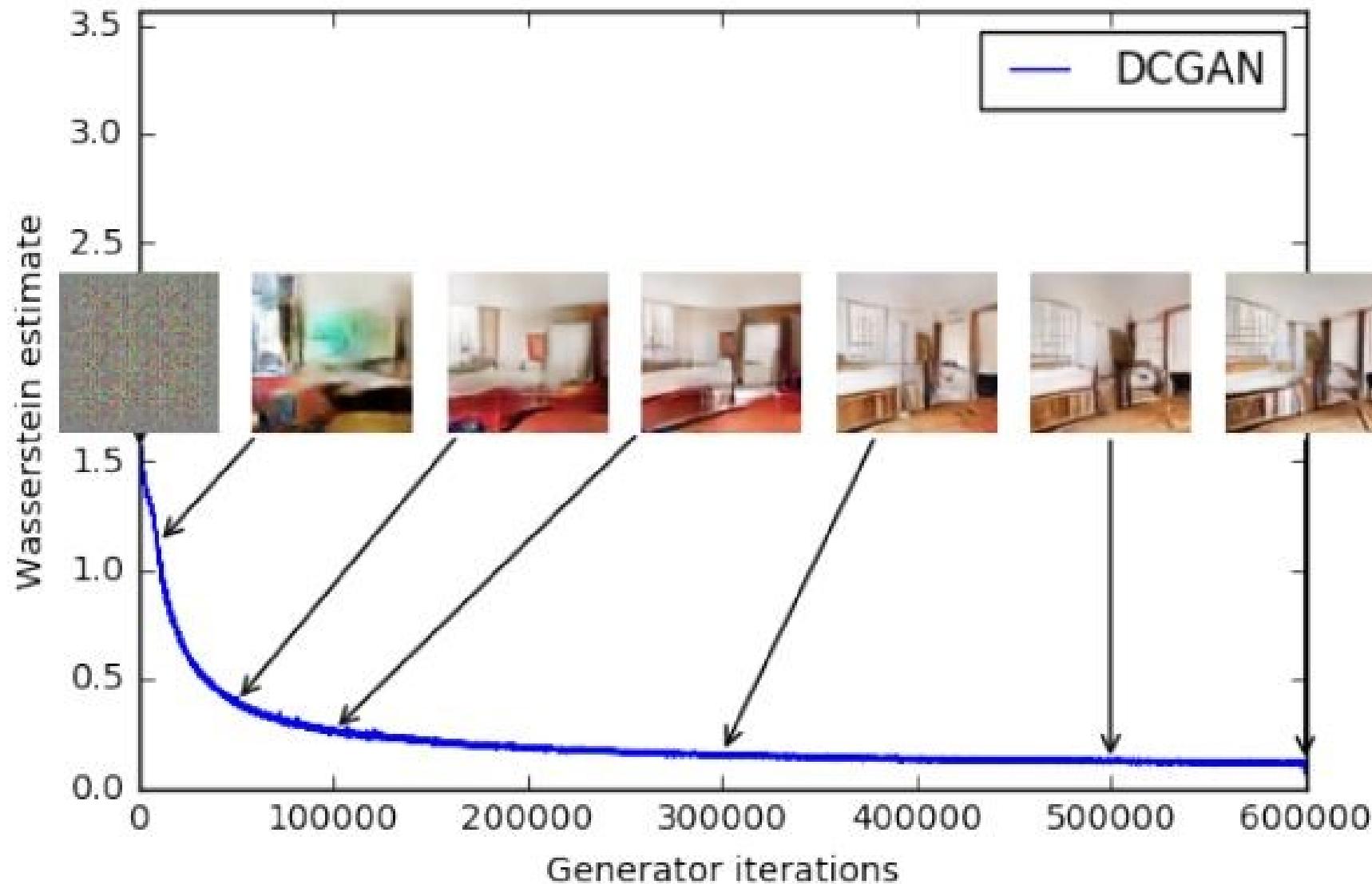
Training data $\sim P_{data}(x)$

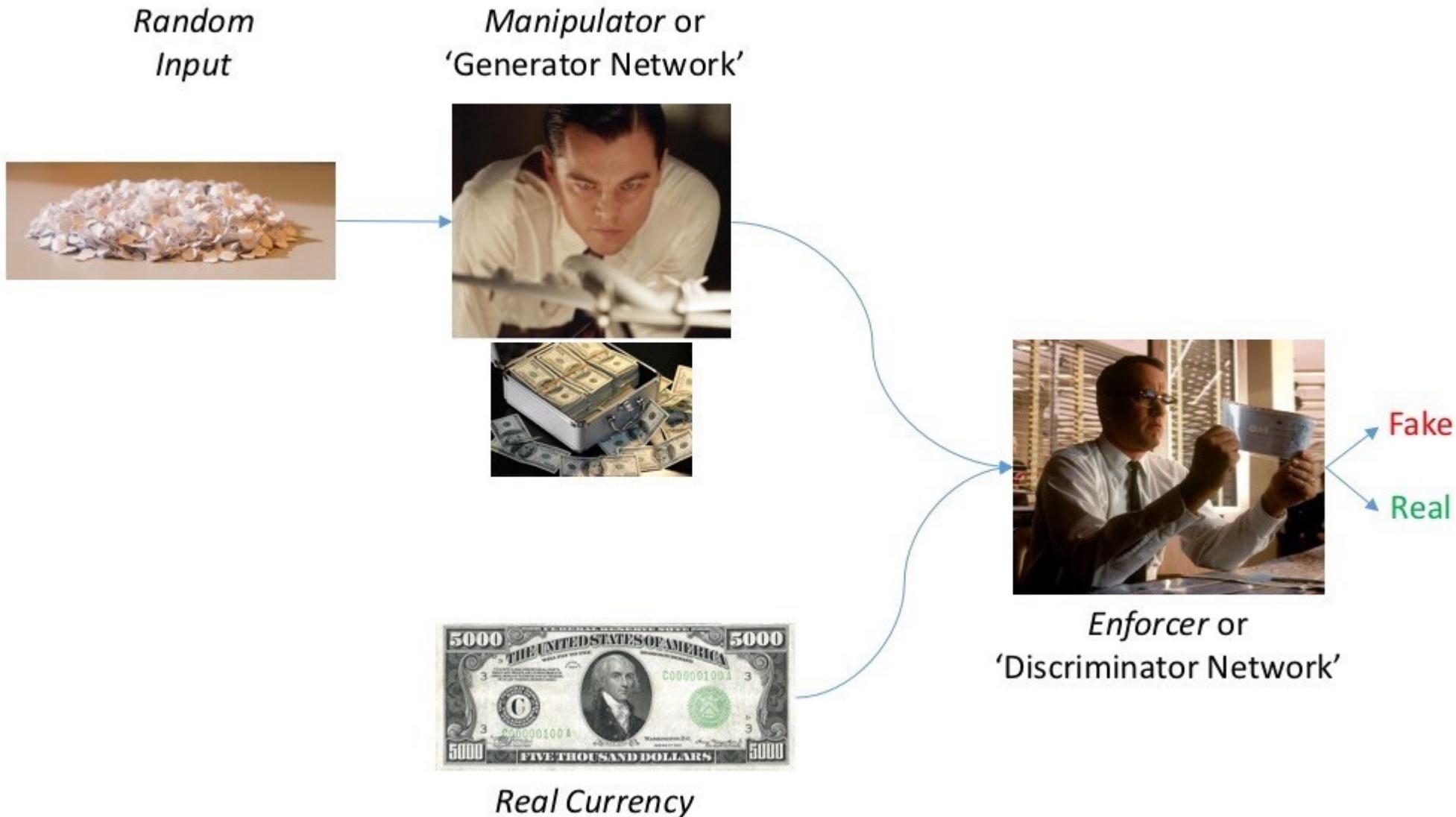


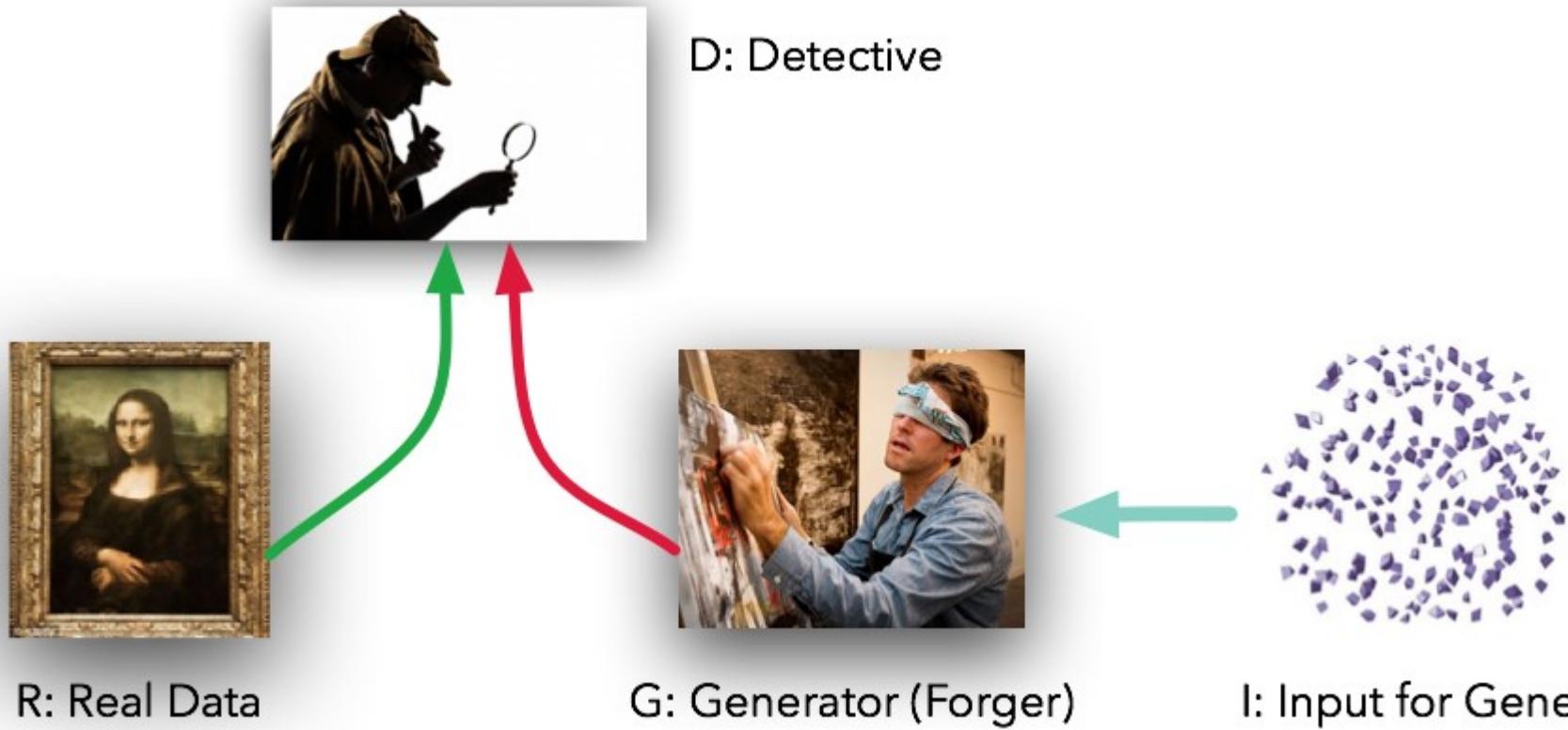
Generated samples

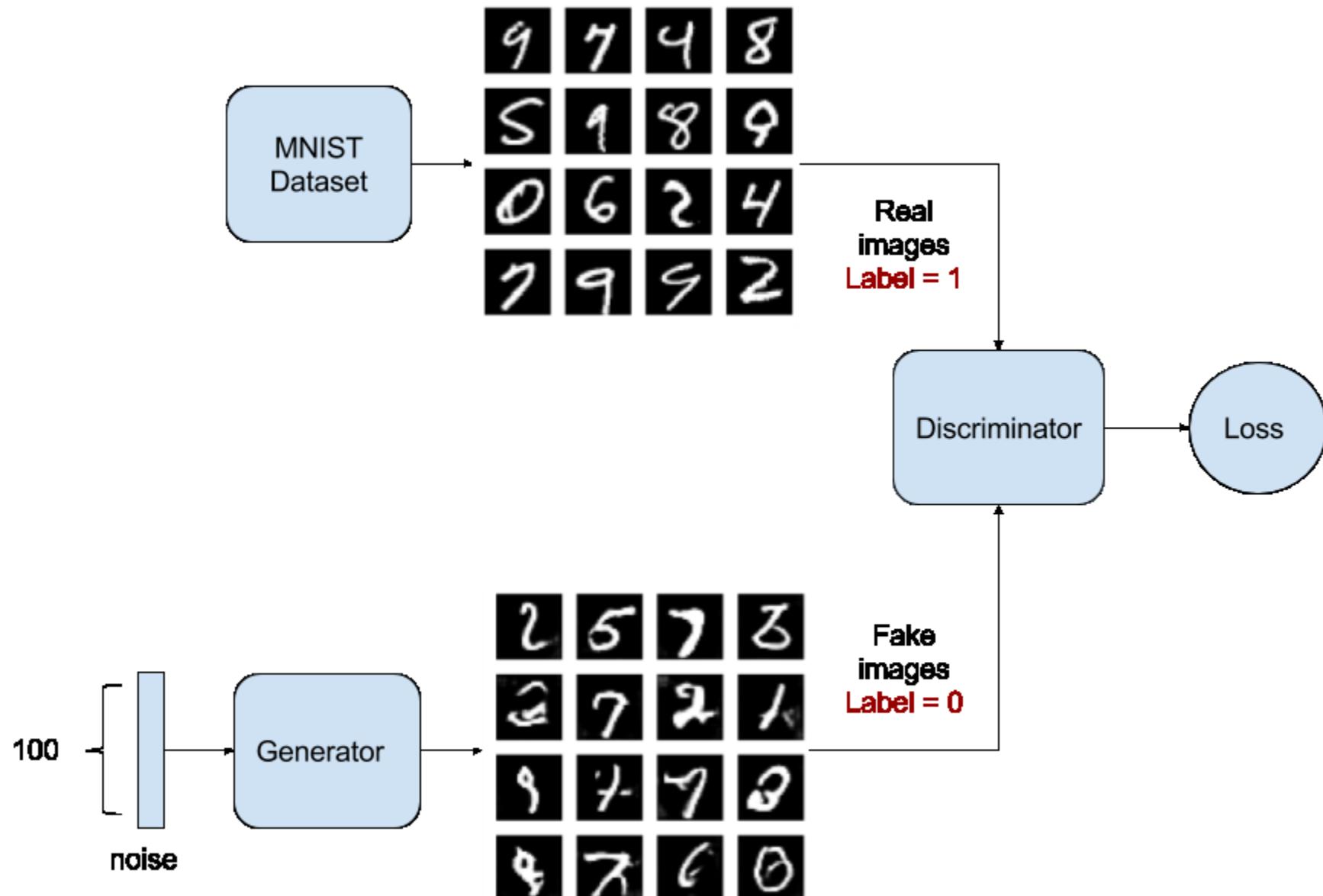
Generated $\sim P_{model}(x)$

How can we learn $P_{model}(x)$ similar to $P_{data}(x)$?





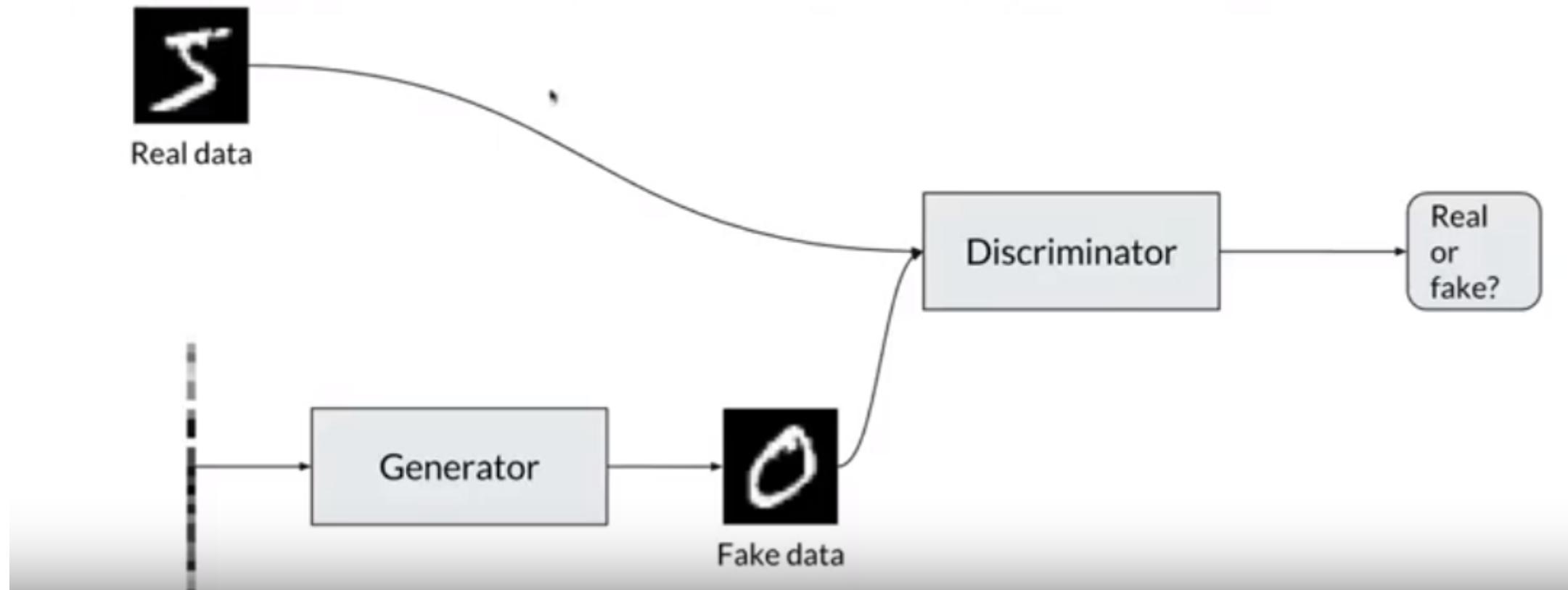




Generative modeling

Goal: Take as input training samples from some distribution and learn a model that represents that distribution

Generative Adversarial Networks (GANs)



Generative Adversarial Networks

Ian Goodfellow et al., "Generative Adversarial Nets", NIPS 2014

Problem: Want to sample from complex, high-dimensional training distribution. No direct way to do this!

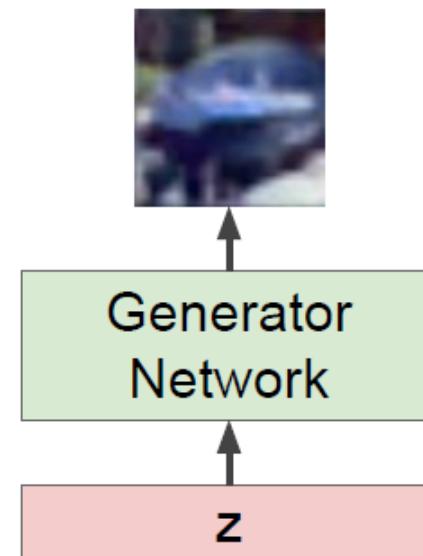
Solution: Sample from a simple distribution, e.g. random noise. Learn transformation to training distribution.

Q: What can we use to represent this complex transformation?

A: A neural network!

Output: Sample from training distribution

Input: Random noise

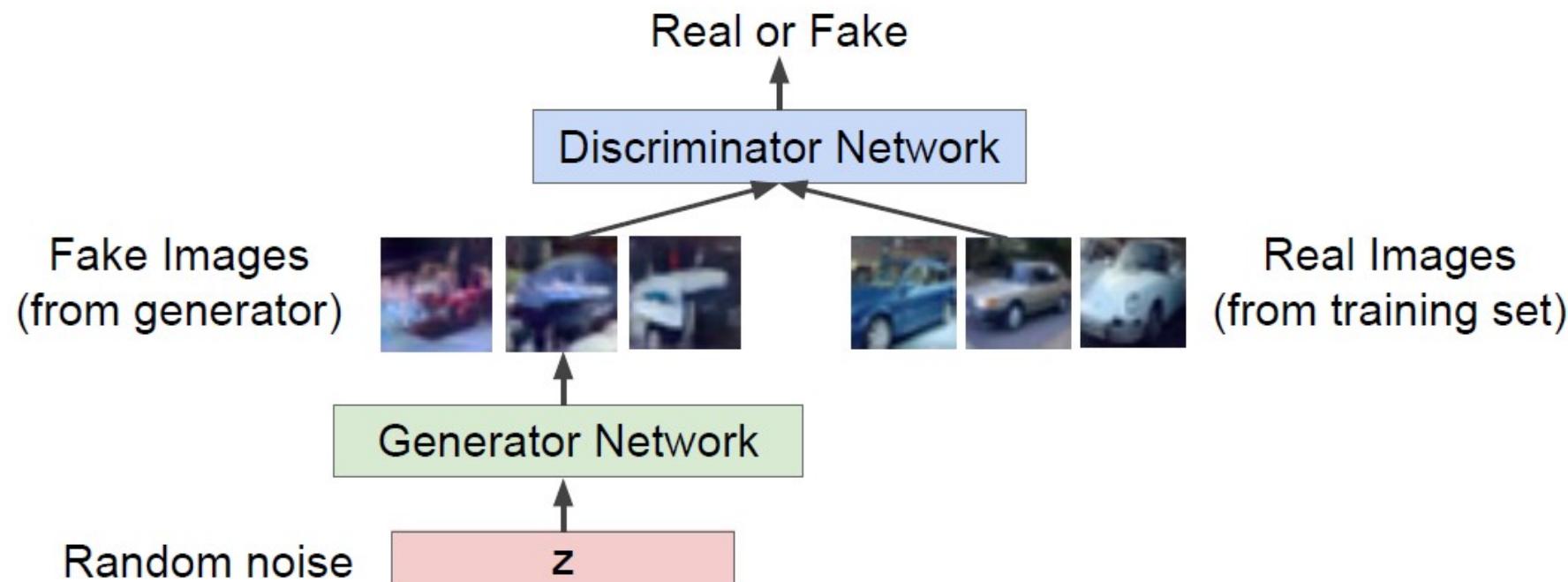


Training GANs: Two-player game

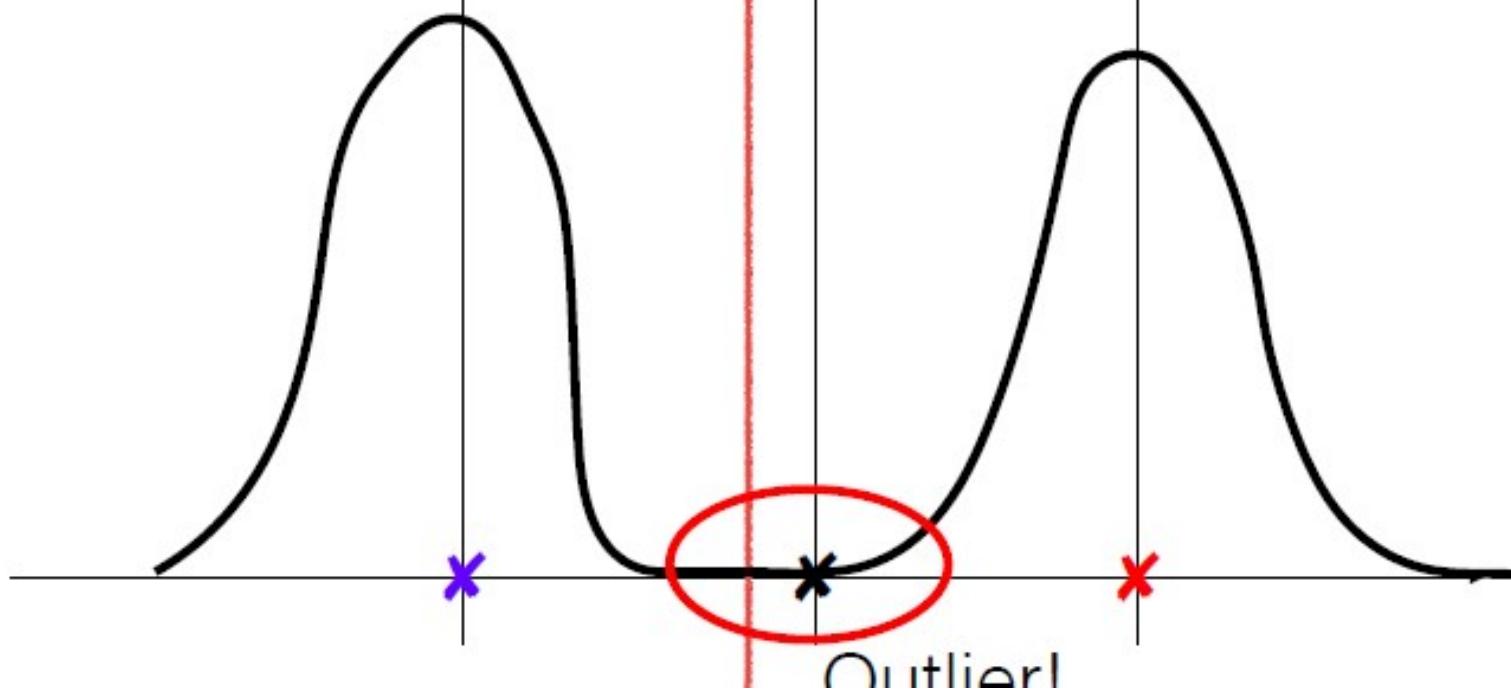
Ian Goodfellow et al., "Generative Adversarial Nets", NIPS 2014

Generator network: try to fool the discriminator by generating real-looking images

Discriminator network: try to distinguish between real and fake images



cars | wheelchairs

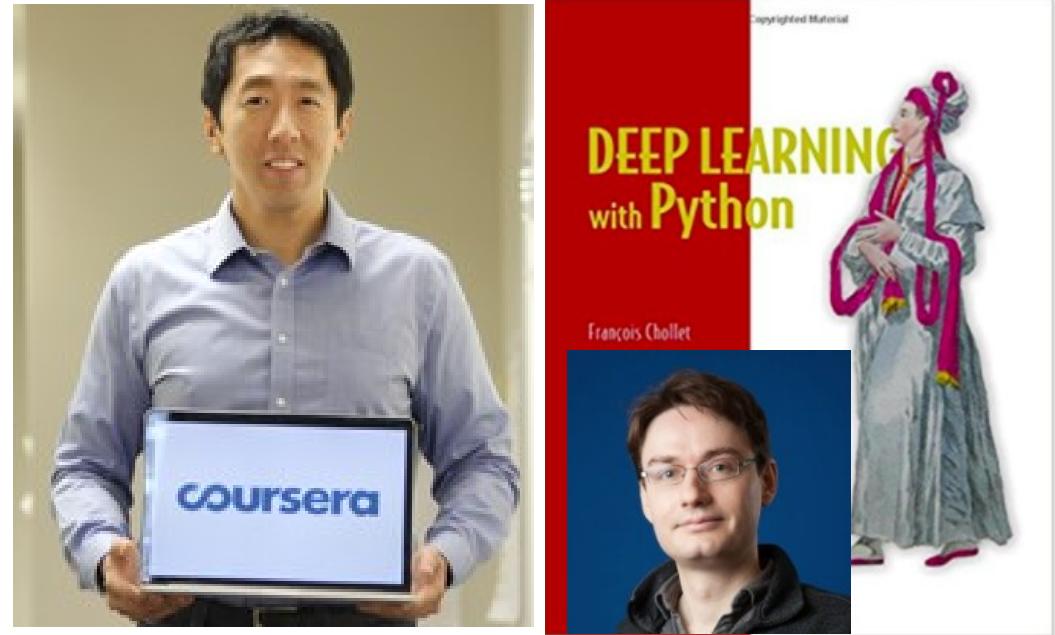


Our inspiration

Friendly approaches :

1) KERAS.io

François Chollet's
Book on "Deep Learning with Python"



2) Deeplearning.ai (Coursera.org)

Andrew Ng

3) Fast.ai

Jeremy



More inspiration

Excellent Resources

- **Stanford cs231 n**

<http://cs231n.stanford.edu>

- **MIT Deep Learning**

<http://introtodeeplearning.com/>

<https://deeplearning.mit.edu>

- **IIT Madras**

my classes notes with Prof. Anurag (**Deep Learning**)