## **EN2550 Assignment 2 on Fitting and Alignment**

- by Rajapaksha R.M.P.A.P. 190484T
- Github Repository -
- Email -

## Question 1 - Using RANSAC method for finding the best fitting circle

- step 1 randomly choose a set of 3 points from the data set.
- step 2 find the *circumscribed circle* of the triangle formed by the selected 3 points.
- step 3 finding the *Inlier* count of the model.
  - Here, the Inliers are the points that reside within a certain threshold distance t from the circumference of the estimated circle. As given in the code snippet Listing 1, these inliers are distributed according to a Gaussian distribution with a variance value  $\sigma$  equal to 1/16 times the radius of the original circle.
  - Therefore, an expression for the threshold value t can be found in terms of the radius of the estimated circle r, such that 95% of the points of inliers are covered by the threshold limit as  $t=1.96\sigma$  (from Standard Normal Distribution Tables)  $\Longrightarrow t=1.96\times r/16=0.1225~r$ .
  - Furthermore, if we assume that the estimated circle has a radius around length 10 (as given in the code), then a single value can be given as a common threshold for all estimations.  $t_{common} = 0.1225 \times 10 = 1.225$
- step 4 if there are *d* or more inliers, accept the estimation.
  - To decide whether an estimation is exactly a good fitting model, its inlier count must exceed a certain limit, which is known as the *consensus set size d*.
  - Since there are 50 inliers for the circle, and a good fitting model is expected to cover at least a 95% of those points, the consensus set size d can be found as  $d = 0.95 \times halfn = 0.95 \times 50 = 47.5 \simeq 47$ .

Store the data about the estimated circle and its inliers in a dictionary.

This above process has to be repeated over a number of times to ensure that there is a sufficient probability that at least one sample would be free of any outlier. If the targeted probability of having at least one successful uncontaminated estimation is p and the outlier ratio is e, then the number of repetition required to achieve p can be found by the equation;  $N = log(1-p)/log(1-(1-e)^s)$ .

Let us assume a reasonably higher p value as 0.99 [i.e. a 99% success rate]. And it is easier to see that the outlier ratio e is equal to 50%. Thus, a minimum value for N can be found out as follows.  $N = log(1-0.99)/log(1-(1-0.5)^3) \Longrightarrow N = 34.48 \backsimeq 35$ 

Finally, the circle with the maximum inlier count is chosen as the **best estimated circle** for the point distribution. Then using the *Least-Squares Circle Fit* method proposed by *Randy Bullock*, the **best-fit circle** will be determined for the inlier points of the best estimation. If there are more than one estimation with the maximum inlier count, then the refitted circle with the smallest mean error will be considered to be the best fit.

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In [ ]:
          def leastSquaresFitCircle(points):
              "finds the best fitting circle for a set of inlier points using the Least-Square Fitting Algorithm"
              N = len(points); x_ = sum(points[:, 0])/N; y_ = sum(points[:, 1])/N # mean values
               u = np.array([(xi-x_{-}) \ for \ xi \ in \ points[:, \ 0]]); \ v = np.array([(yi-y_{-}) \ for \ yi \ in \ points[:, \ 1]]) 
              Suu = sum([ui**2 for ui in u]); Svv = sum([vi**2 for vi in v])
              Suv = Svu = sum([ui*vi for ui in u for vi in v])
              Suuu = sum([ui**3 for ui in u]); Svvv = sum([vi**3 for vi in v])
              Suvv = sum([ui*vi**2 for ui in u for vi in v]); Svuu = sum([vi*ui**2 for ui in u for vi in v])
              A = np.array([[Suu, Suv],
                             [Svu, Svv]])
              B = np.array([[1/2 * (Suuu + Suvv)],
                             [1/2 * (Svvv + Svuu)]])
              (uc, vc) = ((np.linalg.inv(A) @ B).T).reshape(2)
                                                                 # center
              (xc, yc) = (uc + x_, vc + y_)
              R = np.sqrt(uc**2 + vc**2 + (Suu+Svv)/N)
                                                                 # radius
              mean\_Error = sum([abs((xi-xc)**2 + (yi-yc)**2 - R**2) for (xi, yi) in points])/N
              return (xc, yc, R, mean Error)
          def RANSACcircle(points, N, t, d):
               "finds the best fitting circle for a given point set using RANSAC method"
               trial = 0; CircleDict = {}
               while (trial < N): # perform N number of estimations.
                     # ------ randomly choose a set of 3 points from the point set -----
                     (i1, i2, i3) = np.random.randint(0, len(points), 3)  # finding 3 random indices in 'points' array
if (len(set((i1, i2, i3))) < 3): N += 1; continue  # if the points are not distinct, then reject the sample</pre>
                     x1, y1 = points[i1]; x2, y2 = points[i2]; x3, y3 = points[i3]
                     # ----- finding the circumscribed circle of the triangle formed by the 3 points -----
                     A = np.array([[(x1-x2), (y1-y2)],
                                   [(x1-x3), (y1-y3)]])
                     B = np.array([[1/2 * (x1**2-x2**2 + y1**2-y2**2)],
                                    [1/2 * (x1**2-x3**2 + y1**2-y3**2)]])
                     center = ((np.linalg.inv(A) @ B).T).reshape(2)
                     x0 = center[0]; y0 = center[1]
                                                            # circumcenter
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r = np.sqrt((x1-x0)**2 + (y1-y0)**2) # radius
    if (r > 12) or not (-12 \le x0 \le 12) or not (-12 \le y0 \le 12): continue # rejecting the circle if out of the region
    # ----- finding the Inliers -----
    inliers = []
    for point in points:
         (x, y) = point
         if (np.abs(np.sqrt((x-x0)**2 + (y-y0)**2) - r) <= t): inliers.append(point)
    # ------ storing the data about the estimated circle ------
    inliers = np.array(inliers)
    if (len(inliers) >= d): # if inlier count exceeds the consensus set size d, accept the estimation.
         CircleDict[(x0, y0, r, i1, i2, i3)] = inliers
    trial += 1 # process is complete for the selected sample.
max_inlier_count = max([len(inliers) for inliers in CircleDict.values()])
best estimations = [circle for circle in CircleDict if len(CircleDict[circle]) == max inlier count]
best_fit_circles = [leastSquaresFitCircle(CircleDict[circle]) for circle in best_estimations]
if len(best_fit_circles) == 1: return (best_estimations[0] + best_fit_circles[0]), CircleDict[best_estimations[0]]
else: # if there are more than one estimations with max inlier count, chose the one with min error.
    i = min(range(len(best_fit_circles)), key = lambda j: best_fit_circles[j][3])
    return (best_estimations[i] + best_fit_circles[i]), CircleDict[best_estimations[i]]
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