K-means Clustering using CUDA

Problem Description

- K-means is the clustering algorithm which assigns each datapoint to nearest cluster among K clusters.
- In this Project, we will parallelize following two steps of K-means algorithm using CUDA:
 - 1. Assignment of scalar data points to the clusters.
 - 2. Updating centroids.

Each of the two steps are iterated until the cluster assignment converges or upto certain number of iterations which will give the final result.

Applications

- Document Clustering:
 - Clustering helps to group similar douments together
- Image segmentation:
 - To club similar pixels in the image together we can apply clustering to create clusters having similar pixels in the same group.

- Recommendation Systems:
 - Clustering to find similar songs liked by a friend and finally recommend the most similar songs.



K-means Algorithm

- K-means algorithm is iterative algorithm and is divided into two distinct, alternating steps: the *assignment* step and the *update* step.
- The **pseudocode** is as follows:
 - 1. Given cluster centroids μi initialized in some way,
 - 2. For iteration **t=1..T**
 - 1. Compute the distance from each point x to each cluster centroid μ ,
 - 2. Assign each point to the centroid it is closest to,
 - 3. Recompute each centroid μ as the mean of all points assigned to it,

where T is the number of iterations we wish to run this algorithm for. In each iteration, (1) and (2) are the assignment step and (3) is the update step.

• The time complexity of this approach is O(n×k×Txd) where d is dimension of data

Expected Input and Output

Inputs:

N: Number of datapoints to be clustered

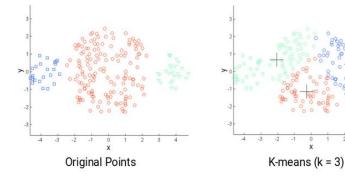
K: Number of clusters

Points: Set of datapoints which are randomly initialized

Iterations: Number of iterations for the algorithm to run for

Output:

Final Centroids/ Cluster Means: Final set of cluster centroids



Output Screenshots - Serial and Parallel

Serial Code Output

```
For 10000 datapoints
For 10 clusters
and for 10 iterations
Serial Time required is 20.000000 ms
Final centroid: 0:94.953766
Final centroid: 1:67.764412
Final centroid: 2:35.032383
Final centroid: 3:46.871479
Final centroid: 4:14.169797
Final centroid: 5:77.689804
Final centroid: 6:57.664452
Final centroid: 7:24.251581
Final centroid: 8:86.165039
Final centroid: 9:4.526030
```

Parallel Code Output

```
Iteration 9: centroid 0: 19.446245
Iteration 9: centroid 1: 40.706402
Iteration 9: centroid 2: 100.300133
Iteration 9: centroid 3: 65.292175
Iteration 9: centroid 4: 12.755508
Iteration 9: centroid 5: 91.270485
Iteration 9: centroid 6: 20.131657
Iteration 9: centroid 7: 8.170594
Iteration 9: centroid 8: 2.825983
Iteration 9: centroid 9: 0.545912
Block Size: 32
Input Size: 1000
Number of clusters: 10
Iteration: 10
Time taken is 1.394272 ms
```

Parallelization strategy

- Assignment of data points to nearest cluster is parallelized by independently computing the distance for each datapoint. So each data point is handled per thread.
- We bring cluster assignments and data points to shared memory for centroid re-computations since global memory access is slow.
- Next Step is partitioning inputs into blocks and one thread in each block i.e thread 0 will add the data points to the corresponding clusters sums stored in local variables.
- Finally, we update the centroids in the global variables by using atomic add operations to avoid race conditions.
- Centroid recomputation step uses reduction operation for calculating sums.
- The Time complexity for the algorithm is $O(n \times k \times T / p)$ where p is no. of processors.

Profiling

For n = 10k

For n = 1000k

```
Time is 1.309344==27349== Profiling application: ./a.out
==27349== Profiling result:
            Type Time(%)
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GPU activities:
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                                                                                 cudaEventElapsedTime
```

Input Size	K	Iterations	Serial	Parallel	Speedup
10000	3	10	0	0.622	0
10000	3	20	10	1.2263	8.1546
10000	3	50	30	3.144	9.542
10000	3	100	60	6.242	9.612
100000	5	10	80	2.221	36.019
100000	5	20	150	4.17	35.971
100000	5	50	360	11.511	31.274
100000	5	100	670	23.17	28.916

Input Size	K	Iterations	Serial	Parallel	Speedup
10000	10	10	20	0.819	24.42
10000	10	20	30	1.498	20.026
10000	10	50	70	3.423	20.450
10000	10	100	140	6.806	20.57
100000	20	10	230	3.934	58.464
100000	20	20	430	7.997	53.77
100000	20	50	1100	20.068	54.813
100000	20	100	1850	40.29	45.917

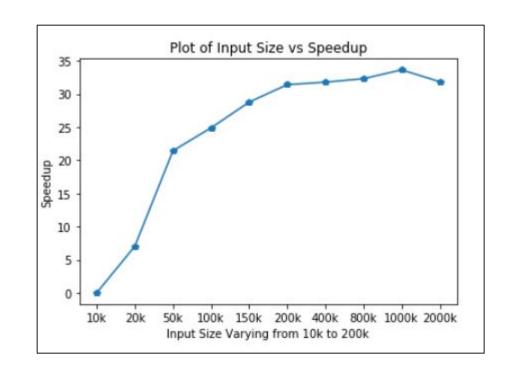
Input Size	K	Iterations	Serial	Parallel	Speedup
1000000	3	10	450	15.769	28.537
1000000	3	20	540	33.204	16.263
1000000	3	50	850	85.547	9.936
1000000	3	100	1930	171.928	11.225
10000000	5	10	6200	172.98	35.842
10000000	5	20	12110	341.19	35.493
10000000	5	50	30870	840.06	36.747
10000000	5	100	59810	1673.83	35.732

Input Size	K	Iterations	Serial	Parallel	Speedup
1000000	10	10	1240	22.72	54.577
1000000	10	20	2070	46.46	44.554
1000000	10	50	5170	117.44	44.022
1000000	10	100	10070	229.19	43.937
10000000	20	10	17250	327.67	52.644
10000000	20	20	33490	650.99	51.444
10000000	20	50	83290	1616.49	51.525
10000000	20	100	170150	3216.35	52.901

Plots - Input Size vs Speedup

K = 3 Iterations = 10 Block Size = 32

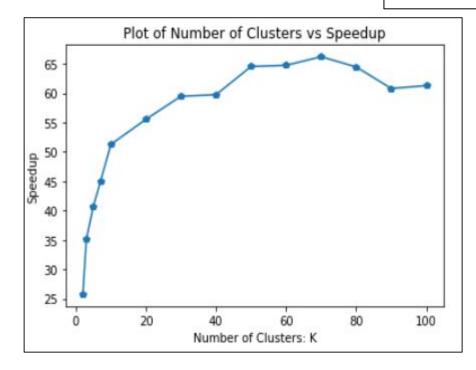
As the memory bottleneck hit in serial case with increasing number of N, and parallel computing doesn't have that memory bottleneck the increase in the speedup in the figure can observed. After speedup of 34 at 1000k the threshold limit is reached. the decrease in speedup can be due to scheduling cost, atomic operations, and synchronization of threads in parallel computation.



Plots - Number of Clusters vs Speedup

N = 100000 Iterations = 10 Block Size = 32

In this figure, as shown by the number of clusters increase the numbers of data-points also increase and thus speed up goes up. After 70 clusters the speedup reach threshold limit where it is consistent with the increase in number of data-points.



Conclusion and Future Work

- We observe significant speedup as number of the clusters increases.
- Using shared memory helps in achieving speedup and also reducing memory access time.
- Use of atomic operations helps to avoid data race conditions but they are slow in nature since the atomic counter increment will be greatly contended and serialize all thread's accesses.
- The Algorithm can further be optimized using various other strategies like Parallel Reduction can be used during centroid recomputation.
- Further optimization could include using fully parallelised mean computation
- Generalise k means algorithm for N=(2, 3) dimensional data points

References

- http://alexminnaar.com/2019/03/05/cuda-kmeans.html
- http://www.goldsborough.me/c++/python/cuda/2017/09/10/20-32-46-exploring_k-means_in_python_c++ and_cuda/
- https://www.analyticsvidhya.com/blog/2019/08/comprehensive-guide-k-means-clustering/