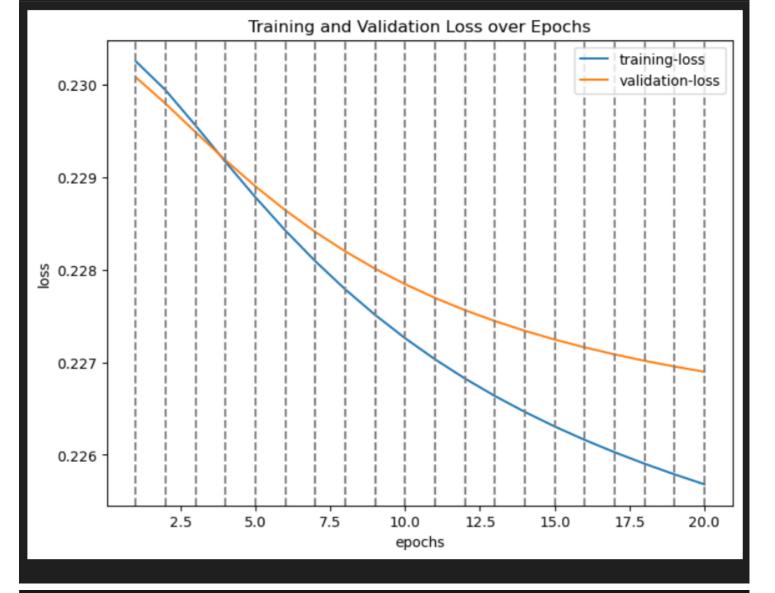
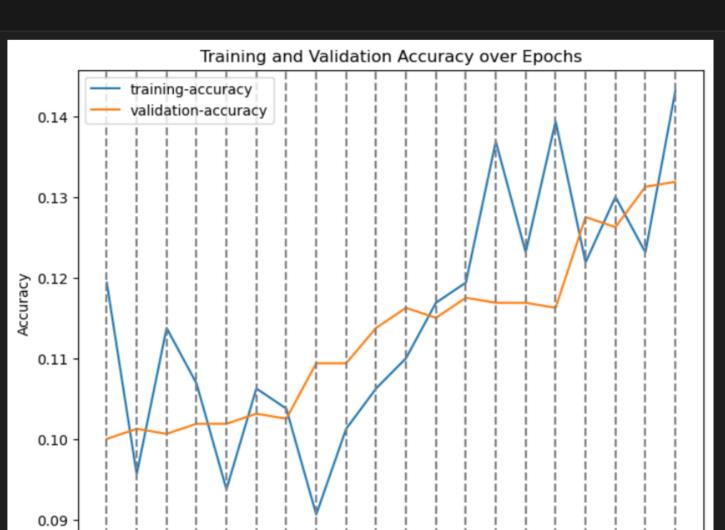
# **Machine learning Assignment - 4**

Part - 3





```
2.5 5.0 7.5 10.0 12.5 15.0 17.5 20.0 epochs
```

```
Accuracy for class: plane is 0.0 %
Accuracy for class: car is 61.6 %
Accuracy for class: bird is 0.0 %
Accuracy for class: cat is 0.0 %
Accuracy for class: deer is 72.6 %
Accuracy for class: dog is 0.0 %
Accuracy for class: frog is 0.0 %
Accuracy for class: horse is 0.0 %
Accuracy for class: ship is 0.0 %
Accuracy for class: truck is 0.0 %
```

The model was taking a lot of time to train therefore i have trained for 5k samples and taken validation over 1k samples

#### Part 4

# 4.1 Hyperparameter tuning

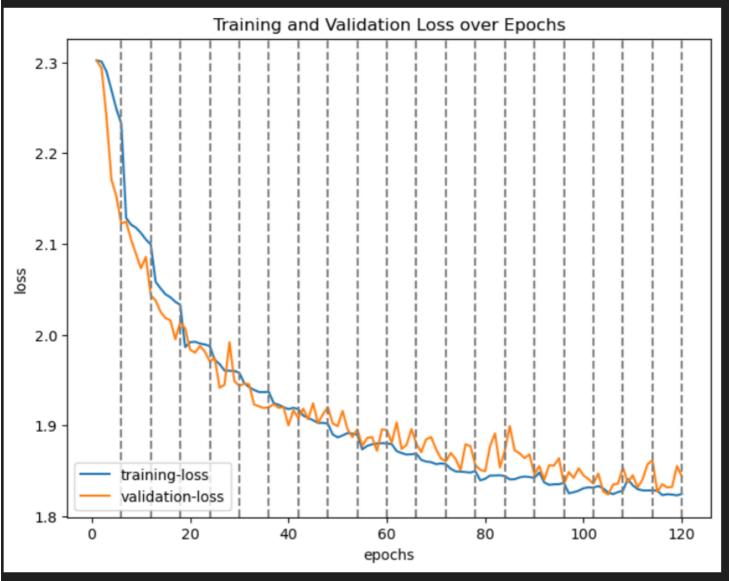
#### SGD optimizer is used

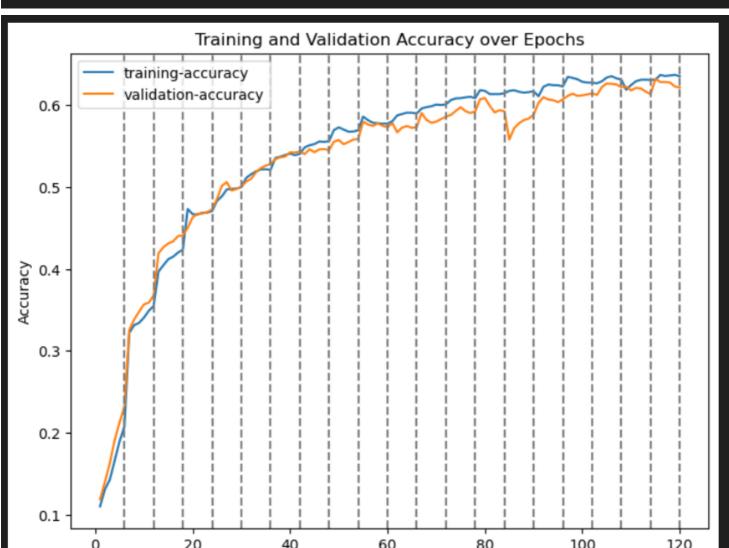
#### Data augmentation->

```
transform = transforms.Compose(
[transforms.ToTensor(),
transforms.Normalize((0.5, 0.5, 0.5), (0.5, 0.5, 0.5)),
transforms.RandomHorizontalFlip(p=0.5)
])
```

## **Learning Rate**

LR = 0.001

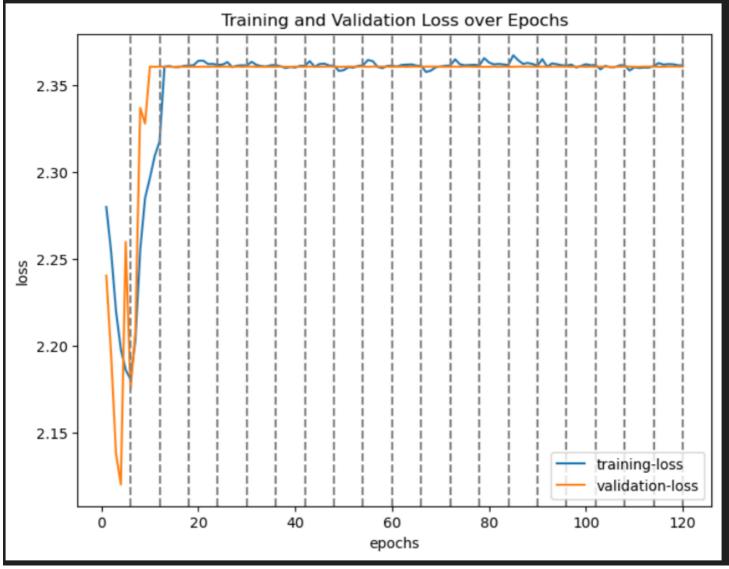


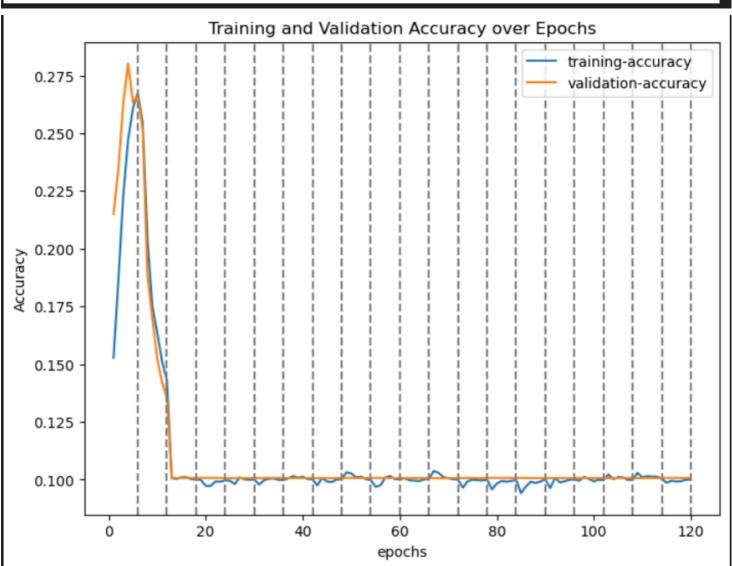


epochs

```
Accuracy for class: plane is 77.5 %
Accuracy for class: car is 74.0 %
Accuracy for class: bird is 0.0 %
Accuracy for class: cat is 53.7 %
Accuracy for class: deer is 58.8 %
Accuracy for class: dog is 46.4 %
Accuracy for class: frog is 73.6 %
Accuracy for class: horse is 81.6 %
Accuracy for class: ship is 74.9 %
Accuracy for class: truck is 72.4 %
```

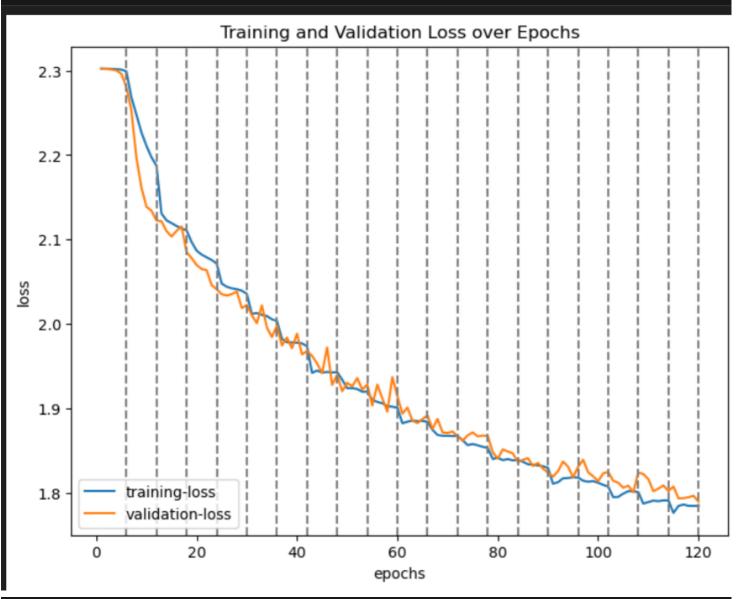
LR = 0.005

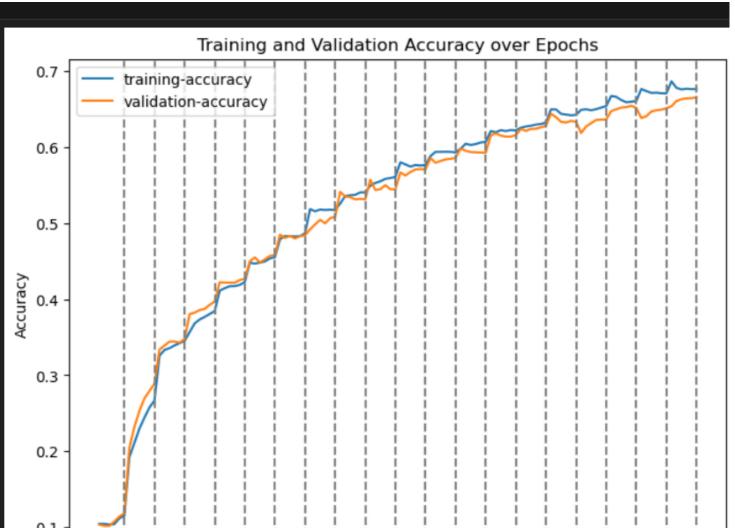




```
Accuracy for class: plane is 99.9 %
Accuracy for class: car is 0.0 %
Accuracy for class: bird is 0.0 %
Accuracy for class: cat is 0.0 %
Accuracy for class: deer is 0.0 %
Accuracy for class: dog is 0.0 %
Accuracy for class: frog is 0.0 %
Accuracy for class: horse is 0.0 %
Accuracy for class: ship is 0.0 %
Accuracy for class: truck is 0.0 %
```

LR = 0.0005



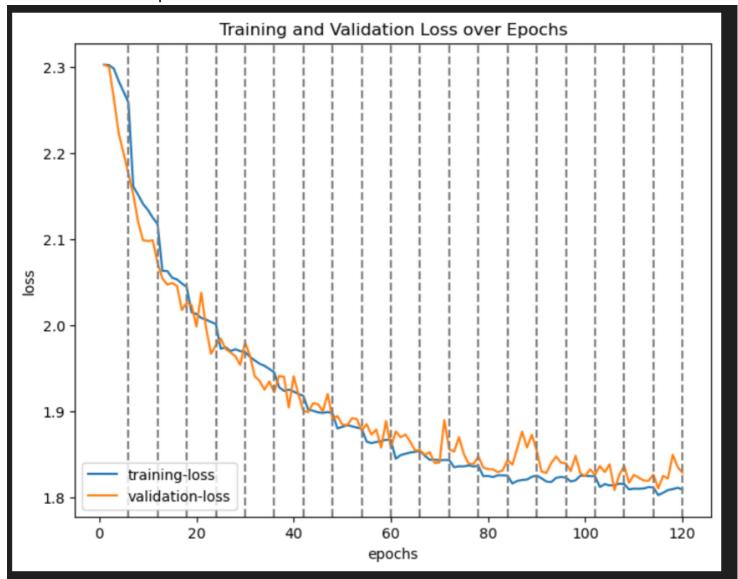


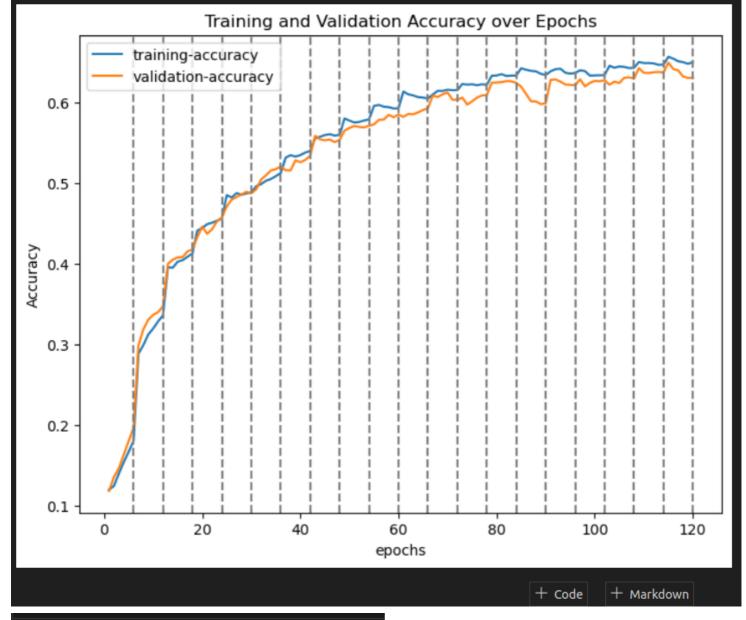
```
20
                           40
                                     60
                                               80
                                                         100
                                                                   120
                                    epochs
Accuracy for class: plane is 63.4 %
Accuracy for class: car
                          is 80.4 %
Accuracy for class: bird is 44.0 %
Accuracy for class: cat is 56.8 %
Accuracy for class: deer is 52.9 %
Accuracy for class: dog
                          is 53.8 %
Accuracy for class: frog is 75.9 %
Accuracy for class: horse is 79.4 %
Accuracy for class: ship is 76.0 %
Accuracy for class: truck is 79.6 %
```

We can see that the learning rate of 0.005 is bad since the model diverges. Also 0.0005 will take a lot of time to converge therefore 0.001 is the best learning rate

#### **Variation in LR**

I have chosen StepLR Scheduler

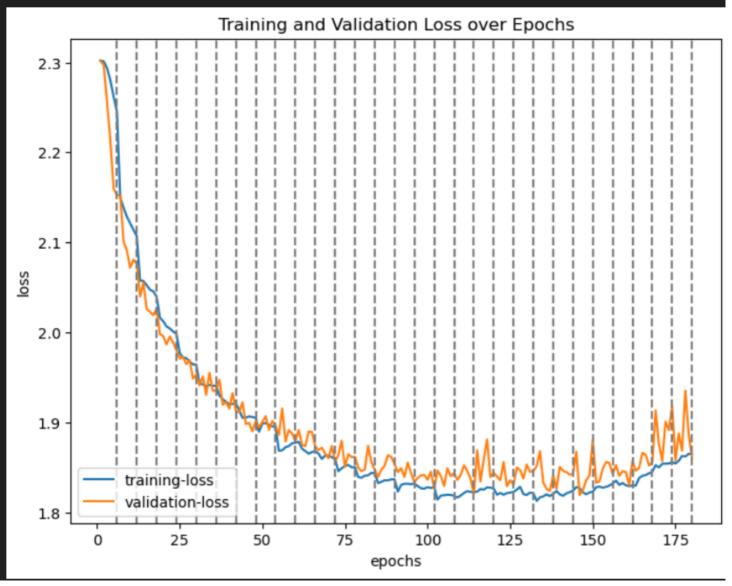


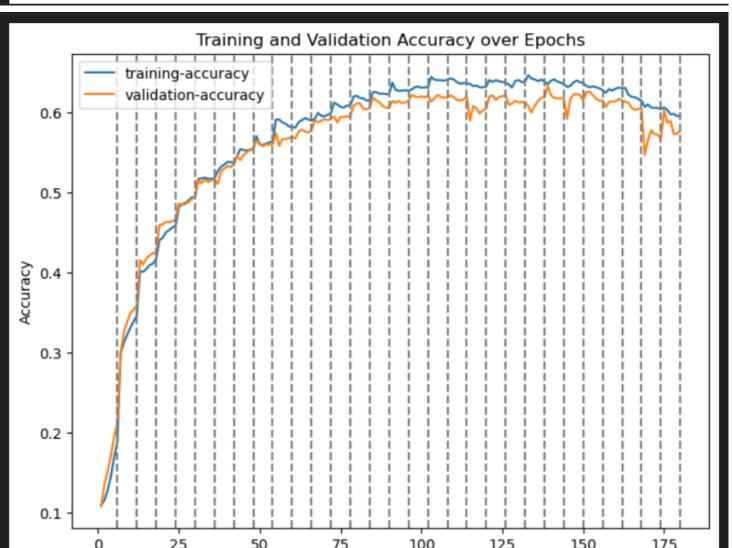


```
Accuracy for class: plane is 67.7 %
Accuracy for class: car
                         is 61.0 %
Accuracy for class: bird
                        is 23.9 %
Accuracy for class: cat
                         is 53.1 %
Accuracy for class: deer
                         is 74.1 %
Accuracy for class: dog
                         is 53.2 %
Accuracy for class: frog
                         is 57.8 %
Accuracy for class: horse is 73.9 %
Accuracy for class: ship is 58.6 %
Accuracy for class: truck is 62.3 %
```

We can see that the accuracy for some classes have improved a lot. Scheduler helps the error to converge espacially when near to minima. Scheduler is used to improve the performance of a model by adjusting the learning rate over the course of the training process.

## **Number of epochs**



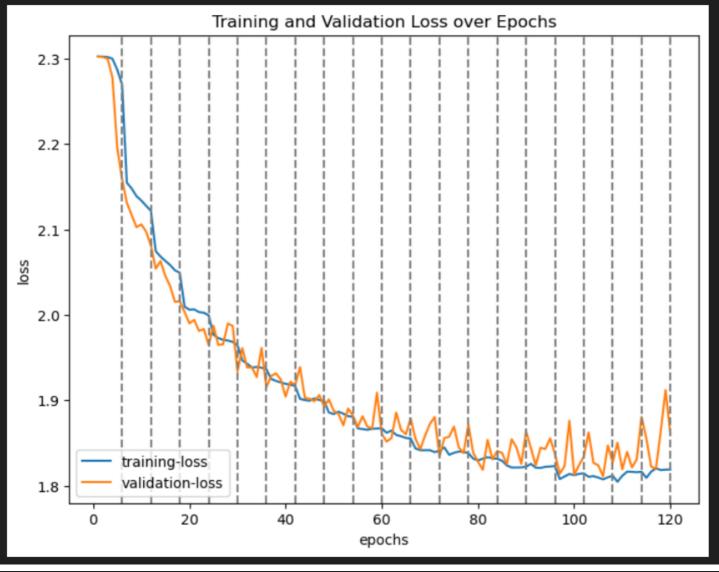


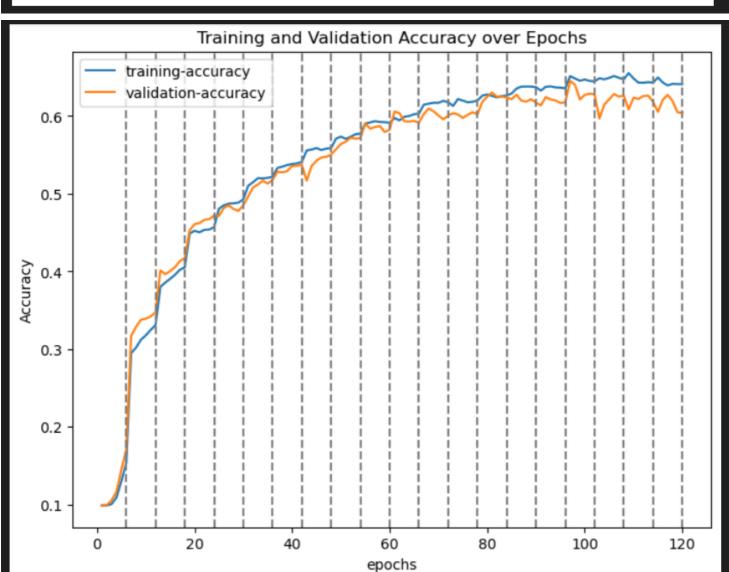
epochs

```
Accuracy for class: plane is 69.0 %
Accuracy for class: car is 73.4 %
Accuracy for class: bird is 0.0 %
Accuracy for class: cat is 57.9 %
Accuracy for class: deer is 64.0 %
Accuracy for class: dog is 32.9 %
Accuracy for class: frog is 86.1 %
Accuracy for class: horse is 66.7 %
Accuracy for class: ship is 82.4 %
Accuracy for class: truck is 61.1 %
```

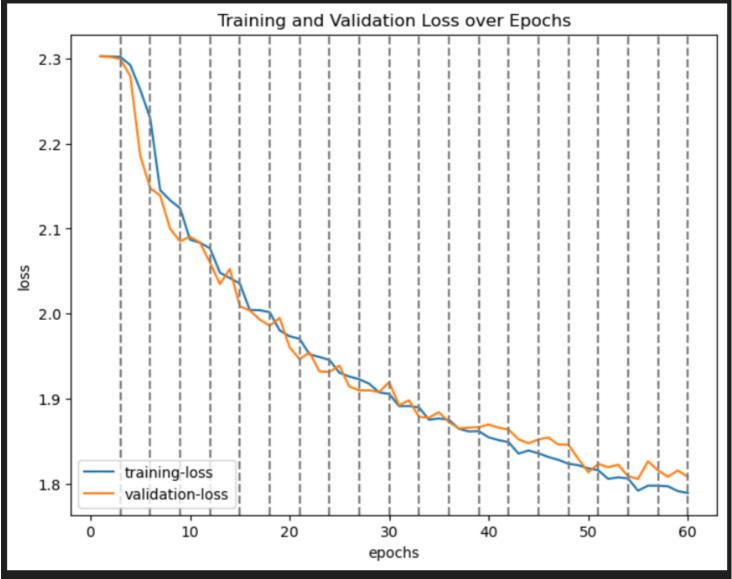
Increasing the number of epochs have done no good to the error convergence since after some time it started to diverge. It is better to limit the number of epochs to prevent overfitting

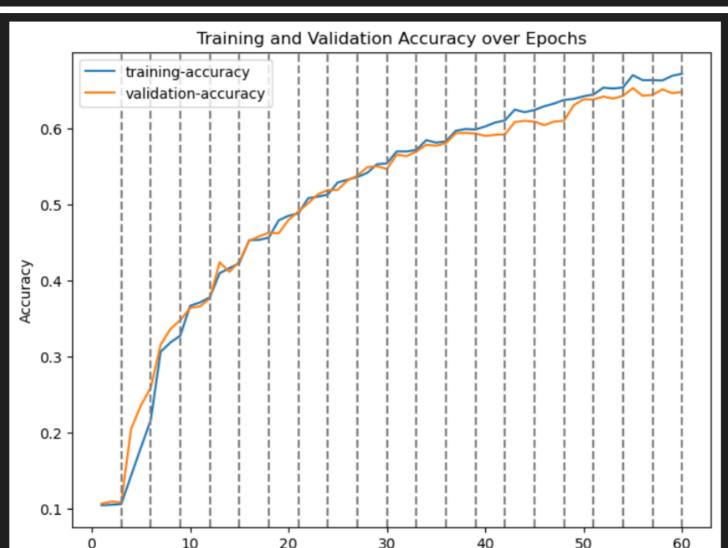
#### **Batch Size**





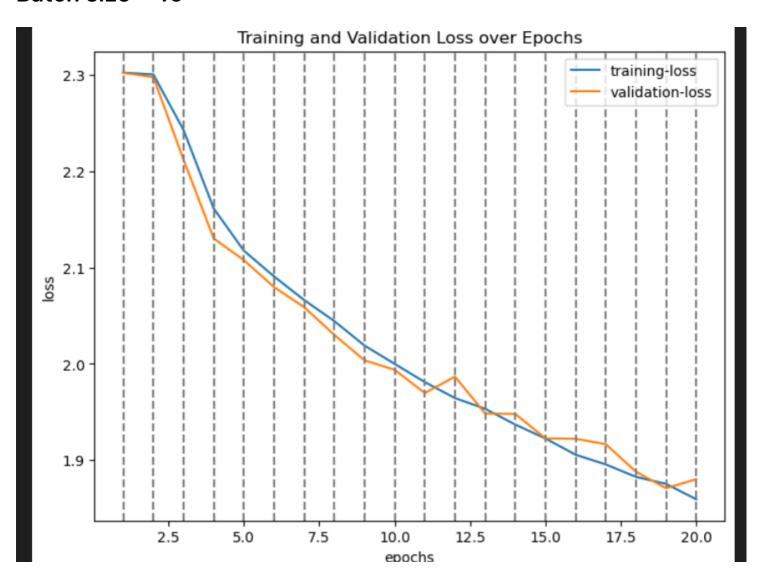
```
Accuracy for class: plane is 65.3 % Accuracy for class: car is 77.1 % Accuracy for class: bird is 55.0 % Accuracy for class: cat is 40.9 % Accuracy for class: deer is 53.6 % Accuracy for class: dog is 62.5 % Accuracy for class: frog is 85.7 % Accuracy for class: horse is 61.4 % Accuracy for class: ship is 57.9 % Accuracy for class: truck is 66.1 %
```

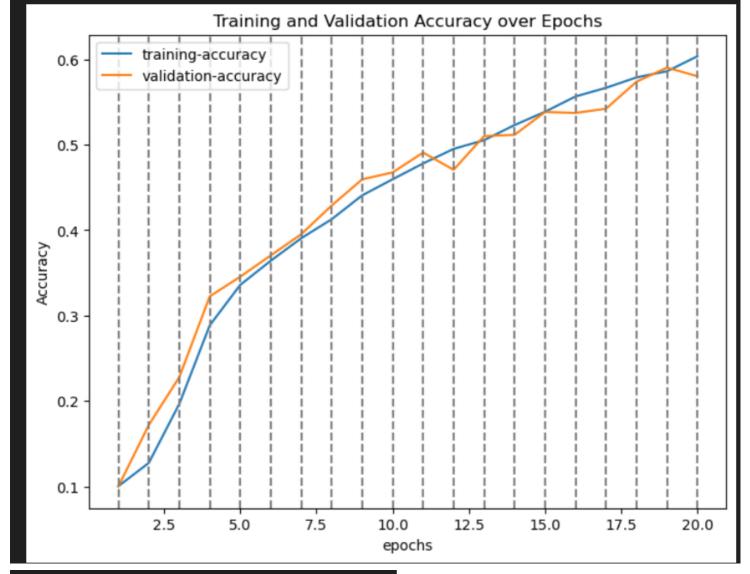




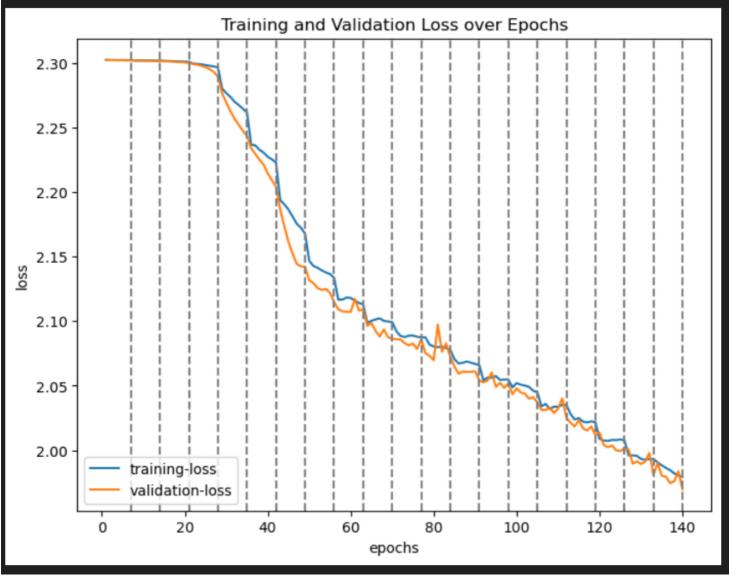
epochs

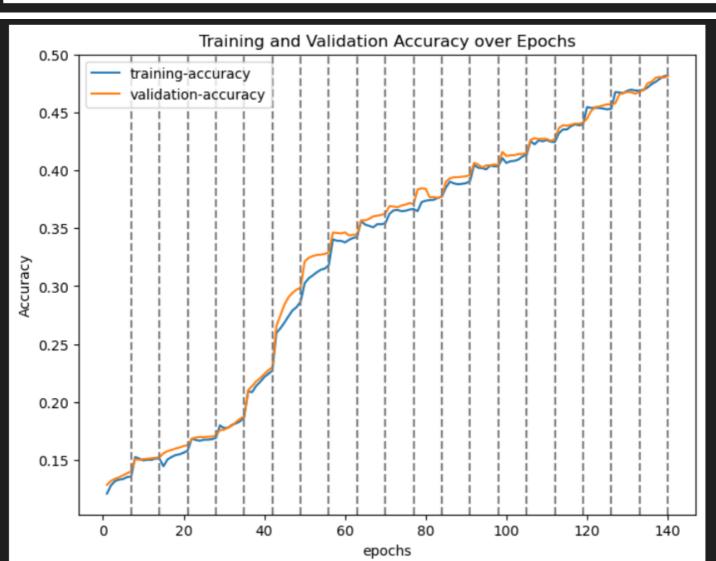
```
Accuracy for class: plane is 67.3 % Accuracy for class: bird is 37.3 % Accuracy for class: bird is 37.3 % Accuracy for class: cat is 47.7 % Accuracy for class: deer is 56.7 % Accuracy for class: dog is 50.7 % Accuracy for class: frog is 64.6 % Accuracy for class: horse is 82.6 % Accuracy for class: ship is 76.2 % Accuracy for class: truck is 83.0 %
```





```
Accuracy for class: plane is 63.3 %
Accuracy for class: car is 66.9 %
Accuracy for class: bird is 39.9 %
Accuracy for class: cat is 30.5 %
Accuracy for class: deer is 49.6 %
Accuracy for class: dog is 60.0 %
Accuracy for class: frog is 79.1 %
Accuracy for class: horse is 59.2 %
Accuracy for class: ship is 73.0 %
Accuracy for class: truck is 76.7 %
```



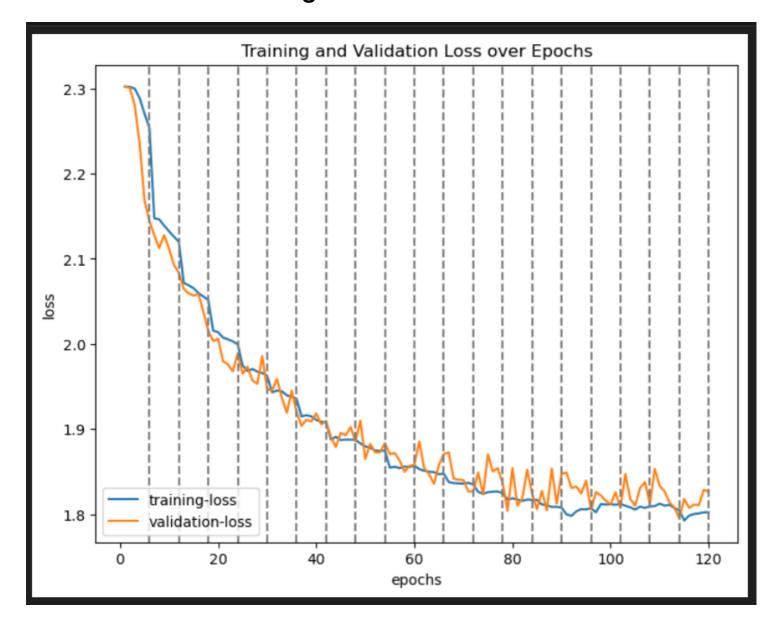


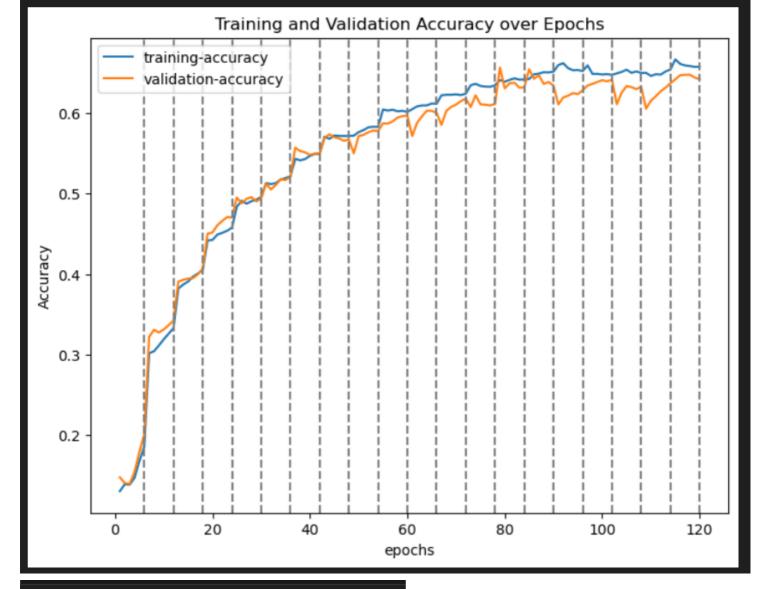
```
Accuracy for class: plane is 61.5 %
Accuracy for class: car is 66.1 %
Accuracy for class: bird is 18.6 %
Accuracy for class: cat is 32.3 %
Accuracy for class: deer is 32.3 %
Accuracy for class: dog is 33.4 %
Accuracy for class: frog is 55.0 %
Accuracy for class: horse is 66.1 %
Accuracy for class: ship is 44.3 %
Accuracy for class: truck is 68.8 %
```

#### Observation

We can see that increasing batch size decreases the amount of time the model takes to train but there is a tradeoff between the accuracy. Increasing the batch size may lead to poorer performance. We might need more number of epochs to train.

# **Loss function - KL Divergence Loss**





```
Accuracy for class: plane is 78.4 %
Accuracy for class: car is 84.1 %
Accuracy for class: bird is 51.3 %
Accuracy for class: cat is 52.9 %
Accuracy for class: deer is 50.0 %
Accuracy for class: dog is 51.6 %
Accuracy for class: frog is 69.0 %
Accuracy for class: horse is 68.8 %
Accuracy for class: ship is 64.5 %
Accuracy for class: truck is 69.1 %
```

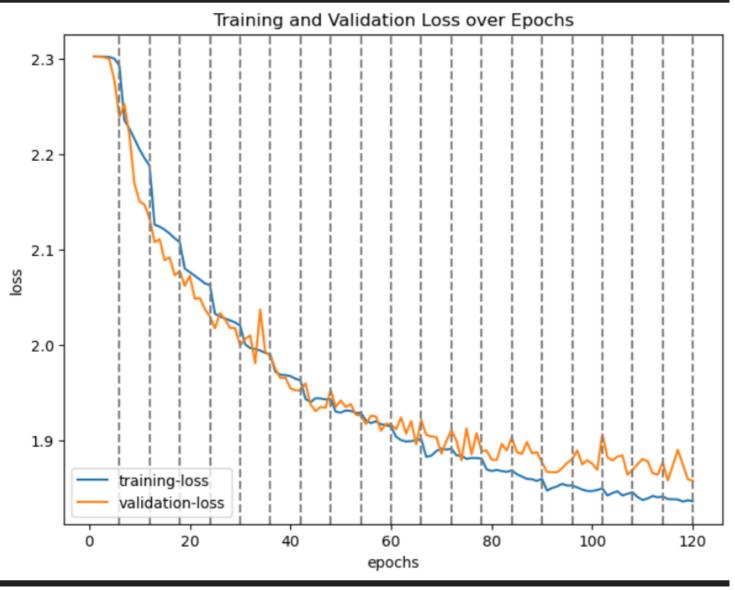
We can see that the model started to recognize some classes. Its accuracy is almost the same but the accuracy for some classes have improved a lot

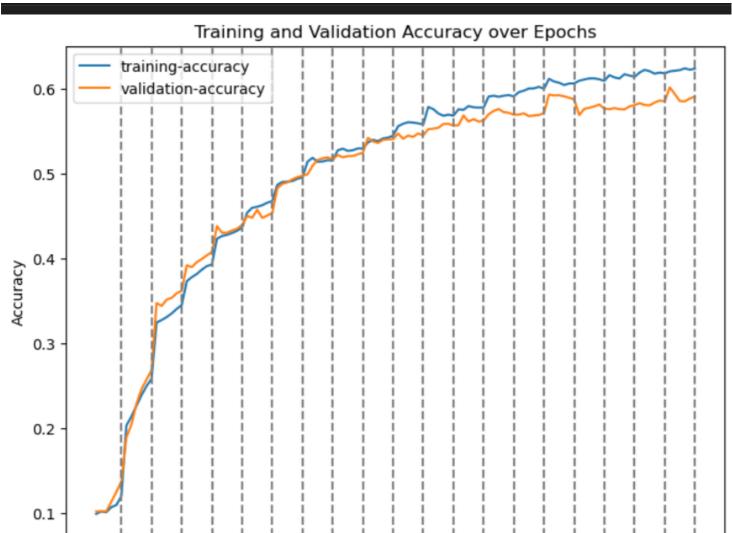
#### Accuracy for cross entropy for same params

```
Accuracy for class: plane is 77.5 %
Accuracy for class: car is 74.0 %
Accuracy for class: bird is 0.0 %
Accuracy for class: cat is 53.7 %
Accuracy for class: deer is 58.8 %
Accuracy for class: dog is 46.4 %
Accuracy for class: frog is 73.6 %
Accuracy for class: horse is 81.6 %
Accuracy for class: ship is 74.9 %
Accuracy for class: truck is 72.4 %
```

We can see that model started to recoganize birds with 50%+ accuracy

# **Data Augmentation ->**





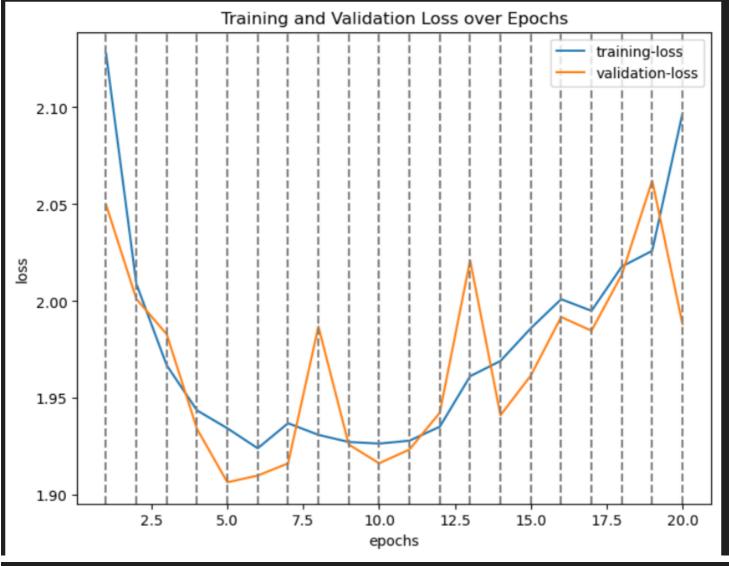
```
0 20 40 60 80 100 120
epochs
```

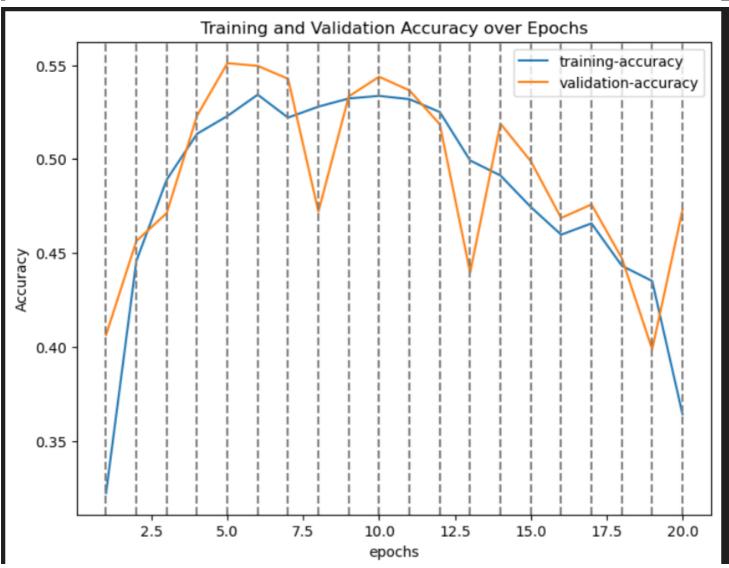
```
Accuracy for class: plane is 62.5 %
Accuracy for class: car
                          is 72.4 %
Accuracy for class: bird
                          is 0.0 %
Accuracy for class: cat
                          is 51.5 %
Accuracy for class: deer
                          is 57.1 %
Accuracy for class: dog
                          is 47.9 %
Accuracy for class: frog
                          is 74.0 %
Accuracy for class: horse is 72.3 %
Accuracy for class: ship is 88.1 %
Accuracy for class: truck is 75.8 %
```

The model trained trained very fast but its accuracy is little bit poorer than the original model.

Adding augmentation is similar to z-transformation. When there are limited number of features, we introduce new features via z-transformation. This is similar to that since we are adding new features by changing the shape/cropping/flpping image etc.

#### Adam optimizer





```
Accuracy for class: plane is 15.0 %
Accuracy for class: car is 89.2 %
Accuracy for class: bird is 2.1 %
Accuracy for class: cat is 1.5 %
Accuracy for class: deer is 29.7 %
Accuracy for class: dog is 81.8 %
Accuracy for class: frog is 39.4 %
Accuracy for class: horse is 15.9 %
Accuracy for class: ship is 48.4 %
Accuracy for class: truck is 33.5 %
```

We can see that we need to lower the learning rate for Adam optimser to work.

# 5. Improving the model

#### data augmentation->

```
transform = transforms.Compose(
[transforms.ToTensor(),
transforms.Normalize((0.5, 0.5, 0.5), (0.5, 0.5, 0.5)),
transforms.RandomHorizontalFlip(p=0.5)
])
new layers
self.conv1 = nn.Conv2d(3, 32, 3)
self.bn1 = nn.BatchNorm2d(32)
self.pool1 = nn.MaxPool2d(2, 2)
self.dropout1 = nn.Dropout2d(0.25)
```

```
self.conv2 = nn.Conv2d(32, 64, 5)
self.bn2 = nn.BatchNorm2d(64)
self.pool2 = nn.MaxPool2d(2, 2)
self.dropout2 = nn.Dropout2d(0.25)

self.conv3 = nn.Conv2d(64, 64, 3)
self.bn3 = nn.BatchNorm2d(64)

self.fc1 = nn.Linear(64 * 3 * 3, 64)
self.dropout3 = nn.Dropout(0.5)
self.fc2 = nn.Linear(64, 10)
```

#### BatchNormal2d ->

This layer normalises the data before passing it to the next layer.

# Dropout2d ->

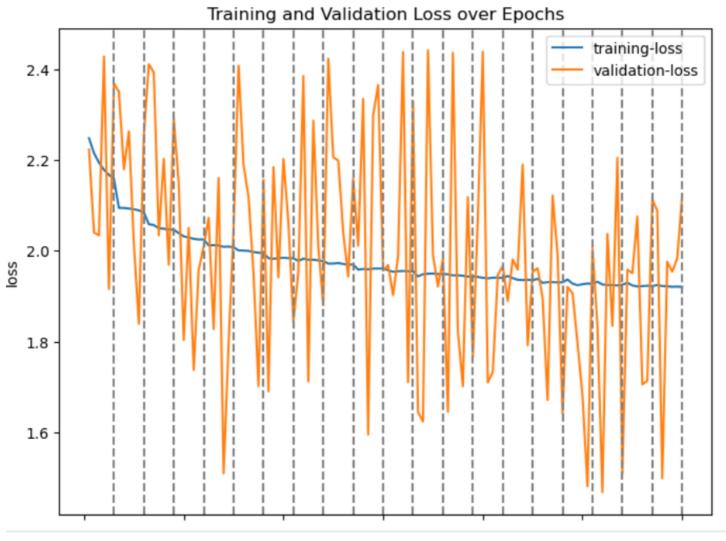
To avoid over fitting I have added another layer that randomly drops out (sets to zero) some of the neurons in a convolutional layer. I helps in regularization.

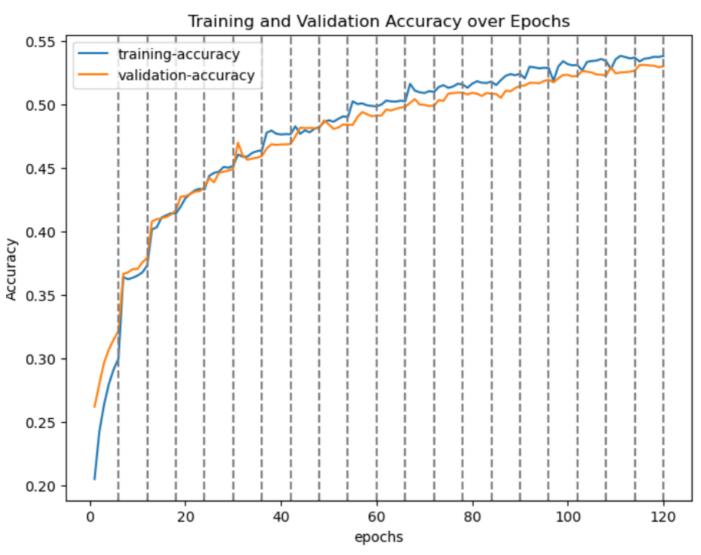
# Optimizer ->

I have used adam optimizer

# Learning rate ->

I have set the learning rate to 0.0001 since adam optimizer performs better with lower learning rate





```
Accuracy for class: plane is 55.9 % Accuracy for class: car is 68.3 % Accuracy for class: bird is 37.4 % Accuracy for class: cat is 30.8 % Accuracy for class: deer is 43.7 % Accuracy for class: dog is 41.9 % Accuracy for class: frog is 57.6 % Accuracy for class: horse is 60.2 % Accuracy for class: ship is 67.4 % Accuracy for class: truck is 61.9 %
```