

#### Merge-Sort

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#### Coverage

Merge-Sort

#### Divide-and-Conquer

- Divide-and conquer is a general algorithmic design paradigm:
  - Divide: divide the input data S in two disjoint subsets  $S_1$  and  $S_2$
  - Recur: solve the subproblems associated with  $S_1$  and  $S_2$
  - Conquer: combine the solutions for  $S_1$  and  $S_2$  into a solution for S
- The base case for the recursion are subproblems of size 0 or 1. In these cases the problem can be solved directly.

#### Merge-Sort

- Merge-sort uses divideand-conquer to perform the sorting operation.
- Merge-sort on an input sequence S with n elements consists of three steps:
  - Divide: partition S into two sequences  $S_1$  and  $S_2$  of about n/2 elements each
  - Recur: recursively sort S<sub>1</sub> and S<sub>2</sub>
  - Conquer: merge S<sub>1</sub> and S<sub>2</sub>
     into a unique sorted
     sequence

#### Algorithm mergeSort(S, C)

**Input** sequence *S* with *n* elements, comparator *C* 

**Output** sequence *S* sorted according to *C* 

if 
$$S.size() > 1$$
  
 $(S_1, S_2) \leftarrow partition(S, n/2)$   
 $mergeSort(S_1, C)$   
 $mergeSort(S_2, C)$ 

$$S \leftarrow merge(S_1, S_2)$$

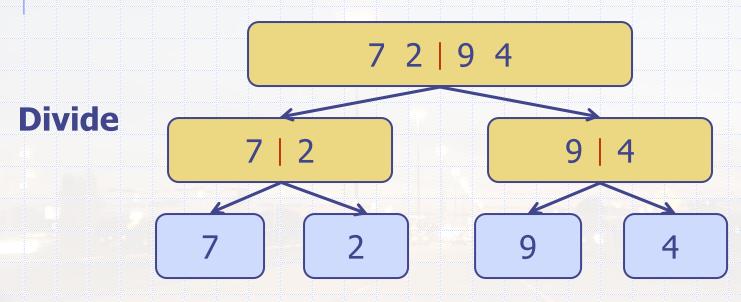
#### Merging Two Sorted Sequences

- The conquer step of merge-sort consists of merging two sorted sequences A and B into a sorted sequence S containing the union of the elements of A and B.
- Merging two sorted sequences, each with n/2 elements and implemented by means of a doubly linked list, takes
   O(n) time.

```
Algorithm merge(A, B)
   Input sequences A and B with
        n/2 elements each
   Output sorted sequence of A \cup B
   S \leftarrow empty sequence
   while \neg A.isEmpty() \land \neg B.isEmpty()
       if A.first().element() < B.first().element()
           S.addLast(A.remove(A.first()))
       else
           S.addLast(B.remove(B.first()))
   while \neg A.isEmpty()
       S.addLast(A.remove(A.first()))
   while \neg B.isEmpty()
       S.addLast(B.remove(B.first()))
    return S
```

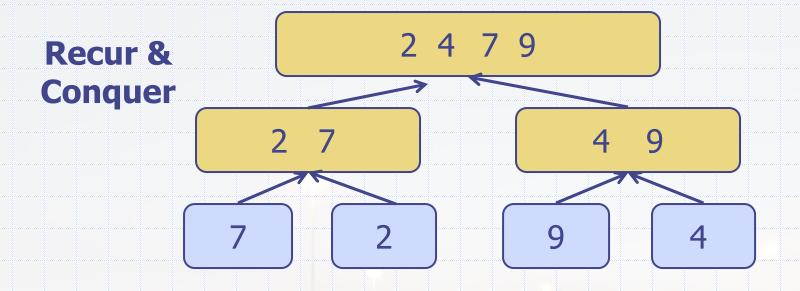
#### Merge-Sort Tree

- An execution of merge-sort is depicted by a binary tree
  - each node represents a recursive call of merge-sort and stores
    - unsorted sequence before the execution and its partition
    - sorted sequence at the end of the execution
  - the root is the initial call
  - the leaves are calls on subsequences of size 0 or 1



Merge Sort

# Merge-Sort Tree



### Merge-Sort Tree

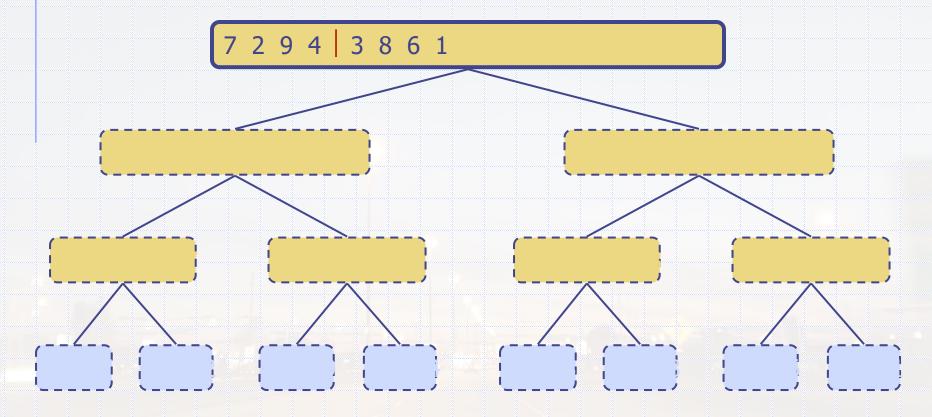
**Example\*:** 

6 5 3 1 8 7 2 4

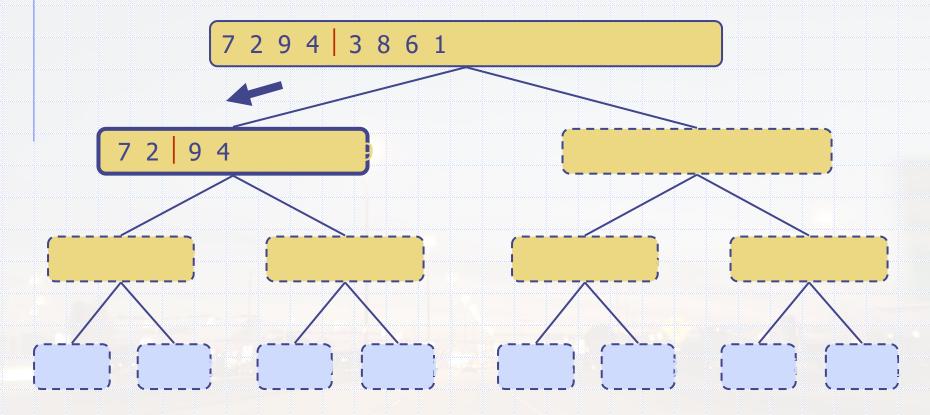
<sup>\*</sup>Reference: http://en.wikipedia.org/wiki/Merge\_sort

### **Execution Example**

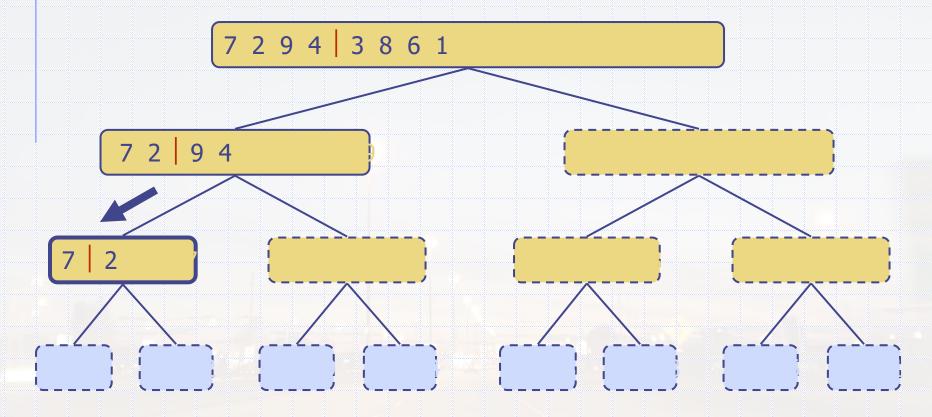
Partition



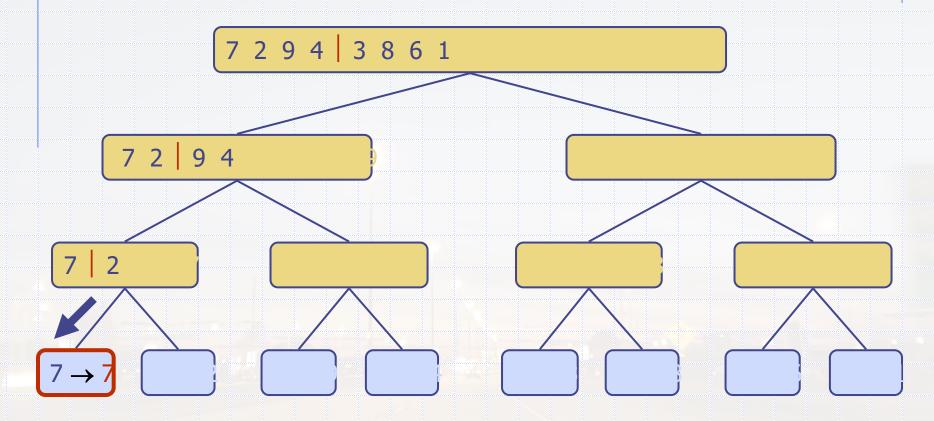
□ Recursive call, partition



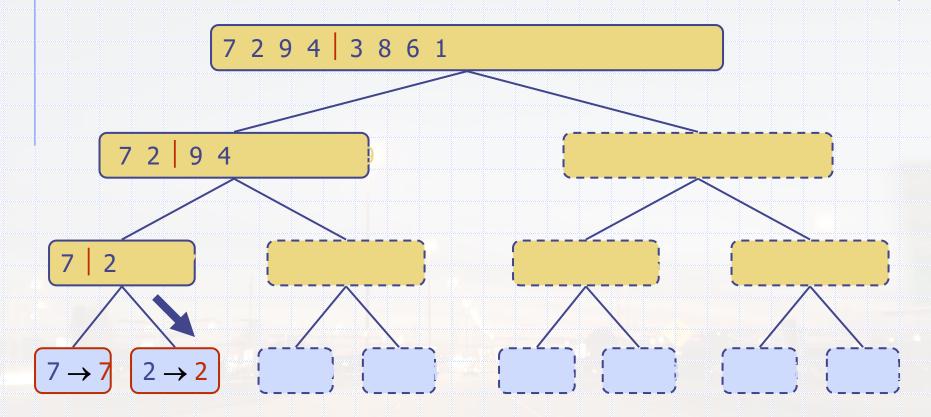
□ Recursive call, partition



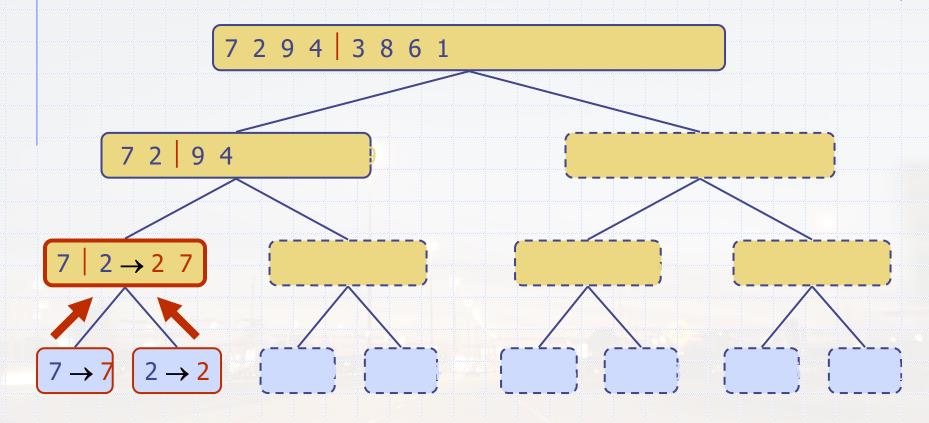
□ Recursive call, base case



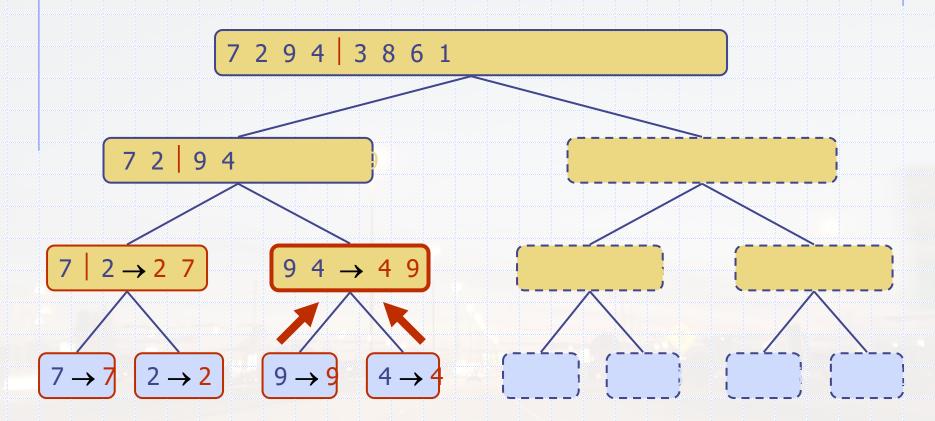
□ Recursive call, base case



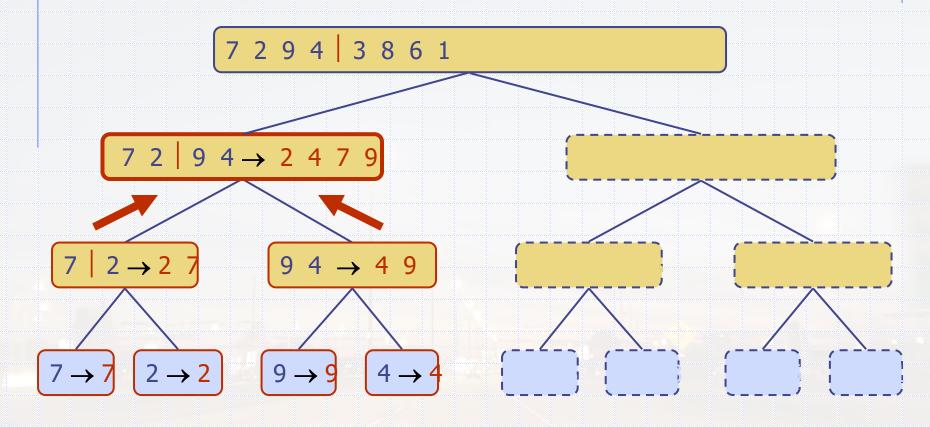
Merge



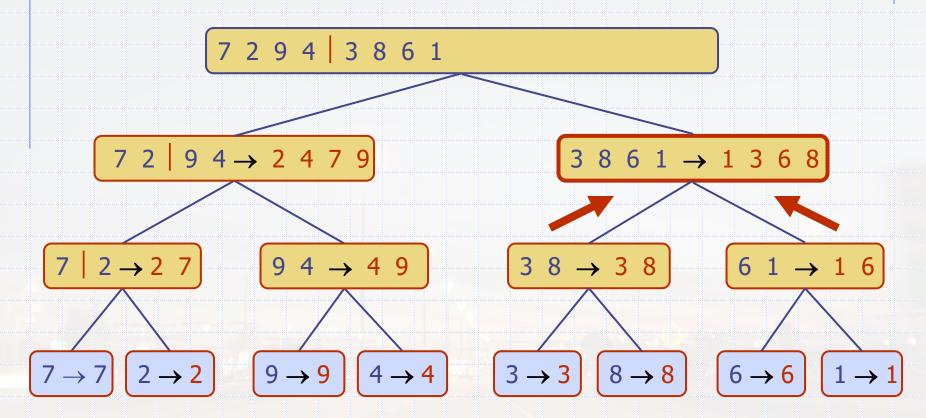
□ Recursive call, ..., base case, merge



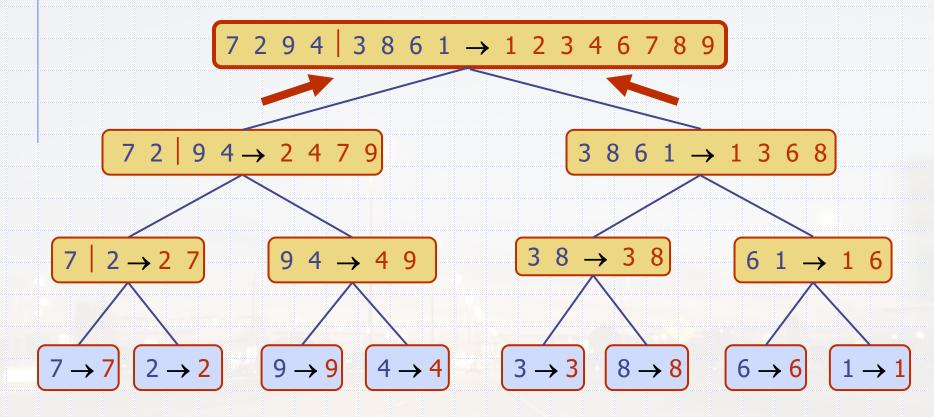
■ Merge



□ Recursive call, ..., merge, merge



Merge

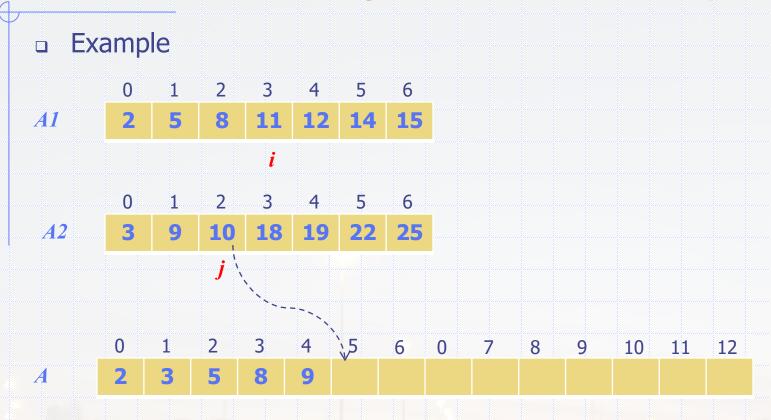


#### The Cost of Sorting Two Sorted Arrays

The algorithm to merge 2 sorted arrays (possibly of different sizes) can be as follows:

```
Algorithm merge(A1, A2, A)
    Input sorted sequences A 1 and A2 and empty
            sequence A with sufficient size; all are
           implemented as arrays
    Output sorted sequence A containing A1 \cup A2
    i \leftarrow j \leftarrow 0
    while i < A1.size() \land j < A2.size() do
        if A1.get(i) \le A2.get(j) then
            S.addLast(A1.get(i))
             i \leftarrow i + 1
        else
            S.addLast(A2.get(i))
            j \leftarrow j + 1
    while i < A1.size() do
            S.addLast(A1.get(i))
             i \leftarrow i + 1
    while j < A2.size() do
            S.addLast(A2.get(j))
            j \leftarrow j + 1
                                                       19
```

#### The Cost of Sorting Two Sorted Arrays



- We compare the two current elements at the head of the two arrays (which are pointed by i & j) then insert the smaller one in the final array.
- Hence, actual cost is O(n1) + O(n2), where A1 has n1 elements and A2 has n2 elements  $\rightarrow$  total cost is hence O(n).

  Merge Sort

#### The Cost of Sorting Two Sorted Lists

The algorithm is quite similar to the one for arrays (see Page 5 of these slides).

#### Simply:

- As long as the two lists are not empty, compare the two entries pointed by the head of the lists,
- Pickup the smaller one and insert it at the tail/end of the new list;
   remove this item afterwards
- If any of the two lists is still not empty, iterate on it and insert its remaining items at the tail of the
- Again, the actual cost is O(n1) + O(n2), where n1 and n2 are the number of elements in the two lists.
- $\Box$  Consequently, total cost to sort the two sorted lists is O(n).

#### Analysis of Merge-Sort

- □ The height h of the merge-sort tree is  $O(\log n)$ 
  - at each recursive call we divide in half the sequence,
- $\Box$  The overall amount or work done at the nodes of depth *i* is O(n)
  - we partition and merge  $2^i$  sequences of size  $n/2^i$
  - we make  $2^{i+1}$  recursive calls
- □ Thus, the total running time of merge-sort is  $O(n \log n)$

depth	# of	size	
	sequences		
0	1	n	
1	2	<b>n</b> /2	
i	2 <sup>i</sup>	n/2 <sup>i</sup>	

#### Merge-Sort vs. Heap-Sort

- Like heap-sort
  - It uses a comparator
  - It has  $O(n \log n)$  running time.
    - The cost to sort the elements at each level is O(n) and we do that log n times.
- Unlike heap-sort
  - It does not use an auxiliary priority queue
  - It accesses data in a sequential manner (suitable to sort data on a disk)

## **Summary of Sorting Algorithms**

Algorithm	Time	Notes
selection-sort	$O(n^2)$	<ul><li>slow</li><li>in-place</li><li>for small data sets (&lt; 1K)</li></ul>
insertion-sort	$O(n^2)$	<ul><li>slow</li><li>in-place</li><li>for small data sets (&lt; 1K)</li></ul>
heap-sort	$O(n \log n)$	<ul><li>fast</li><li>in-place</li><li>for large data sets (1K — 1M)</li></ul>
merge-sort	$O(n \log n)$	<ul><li>fast</li><li>sequential data access</li><li>for huge data sets (&gt; 1M)</li></ul>