

# A Complete Course in Physics ( Graphs ) - 4th Edition

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# Initiation



# Preface

This book is a plethora on Graphs. Usually this topic , i.e. GRAPHS is studied with lots of hype in Coachings, but unfortunately , not lots of good study material is available. This book fulfills a long felt need by students and teachers for an authoritative text on graphs.

This book contains only reviewed material already being used by millions of professors in universities. Reason being, to keep the correctness and homogeneity intact.

The source of most graphs in this book is either internet or already published books , proper bibliography has been added to give credit to seemingly original creators.



# Acknowledgements

I would like to thank my son Manas for his love and support. Moreover , to my father for the day to day needs.



# Prelims



# **Part I**

# **Introduction**



# Chapter 1

## Theory

### 1.1 Introduction 2016

A graph is an accurate pictorial representation of data. The accuracy of data in physics requires that graphs be made on good quality graph paper. Nearly all graphs in physics are smooth line graphs; broken line (connect the dots) graphs and bar graphs are seldom appropriate.

The style and format of a graph will depend upon its intended purpose. Three types are common in physics

1. PICTORIAL GRAPHS. These are the kind found in mathematics and physics textbooks. Their purpose is to simply and clearly illustrate a mathematical relation. No attempt is made to show data points or errors on such a graph.

2. DISPLAY GRAPHS. These present the data from an experiment. They are found in laboratory reports, research journals, and sometimes in textbooks. They show the data points as well as a smooth line representing the mathematical relation.

3. COMPUTATIONAL GRAPHS. These are drawn for the purpose of extracting a numerical result from the data. An example is the calculation of the slope of a straight line graph, or its intercepts.

### 1.2 Elements of a good Graph

Certain informational and stylistic features are required in all graphs:

1. The graph must have a descriptive title or caption, clearly stating what the graph illustrates.
2. Data points are plotted as small dots with a sharp pencil, or as pinpricks. Some method should be used to emphasize the location of the points, for example, a neat circle drawn around each point.

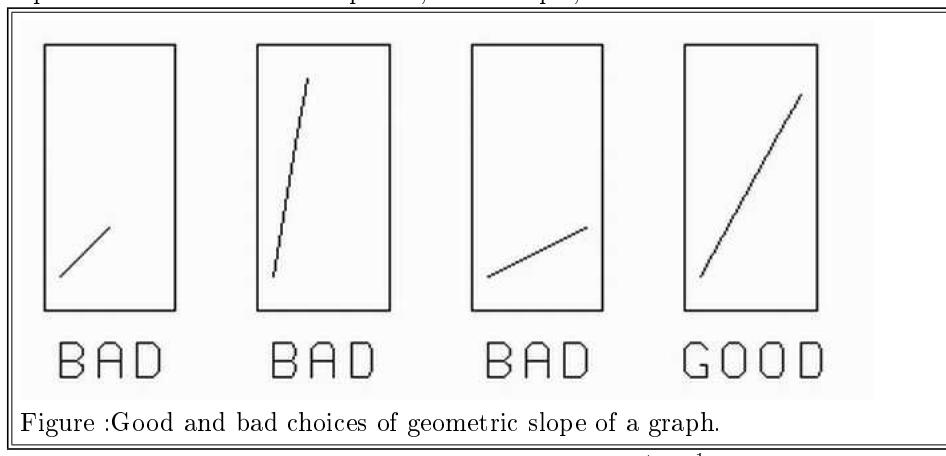


Figure :Good and bad choices of geometric slope of a graph.

3. Curves drawn through the points should be smooth (use <sup>1</sup> French curves if your hand is not steady). The curve should stand out clearly.
4. Choose scales that are convenient to plot and easy to read.

<sup>1</sup>A French curve is a template usually made from metal, wood or plastic composed of many different curves. It is used in manual drafting to draw smooth curves of varying radii. The shapes are segments of the Euler spiral or clothoid curve. The curve is placed on the drawing material, and a pencil, knife or other implement is traced around its curves to produce the desired result.

Modern computer-aided design (CAD) systems use vector-based graphics to achieve a precise radius, so no template is required. Digital computers can also be used to generate a set of coordinates that accurately describe an arbitrary curve, and the points can be connected with line segments to approximate the curve with a high degree of accuracy. Some computer-graphics systems make use of Bézier curves, which allow a curve to be bent in real time on a display screen to follow a set of coordinates, much in the way a French curve would be placed on a set of three or four points on paper.

5. Choose scales such that the graph occupies most of the page. The two scales need not have the same size units. Also, the scales need not begin at zero.
6. Indicate the name, letter symbol and units of each variable plotted on each axis.
7. All text (title, labels, etc.) should be printed.

#### PHYSICAL SLOPE AND GEOMETRIC SLOPE

Slope. When textbooks refer to the "slope" of a plotted graph line we mean the "physical slope"

$$\text{physical slope} = \frac{\Delta y}{\Delta x}$$

where  $\Delta y$  and  $\Delta x$  are expressed in the physical units of the x and y axes. This slope has physical significance in describing the physical data.

Geometric slope. A line which makes a  $45^\circ$  angle with an axis will not necessarily have a physical slope of size 1. Some authors introduce the term "geometric slope" to describe the tilt of the line on the page. This is a ratio of lengths of the legs of the triangle, without reference to the units plotted on the axes.

There is seldom (probably never) any need to calculate the geometric slope of a line on a graph. The idea is only useful when describing the appearance of the graph on the page. One rule of graph construction states that the graph should occupy most of the page. For square graph paper this suggests a geometric slope of  $45^\circ$ . See Fig for examples of good and bad choices of geometric slope.

#### THE APPEARANCE OF THE GRAPH

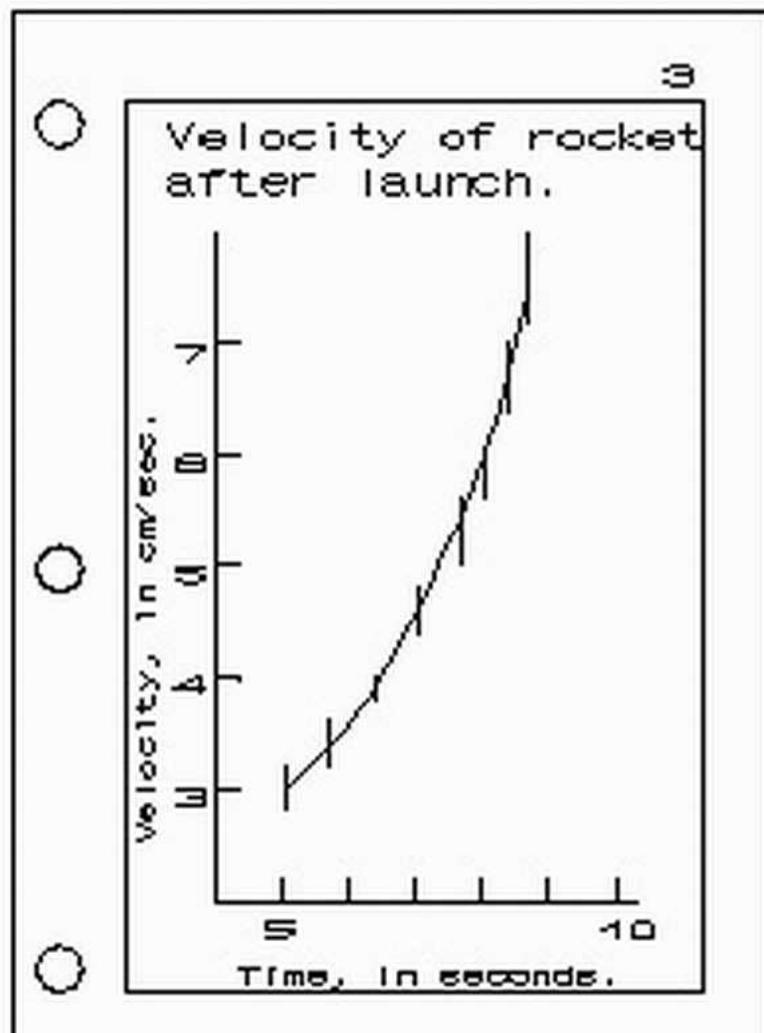


Figure : Elements of a graph.

Use quality graph paper, size 8.5 by 11 inches only.

The left margin is largest, for binding or stapling.

Nothing should be in the white margins except a page number. Axes, lettering and labeling should all be within the printed grid area. [The grid lines serve as guide lines for neat, uniform printed lettering.]

The title must be descriptive.

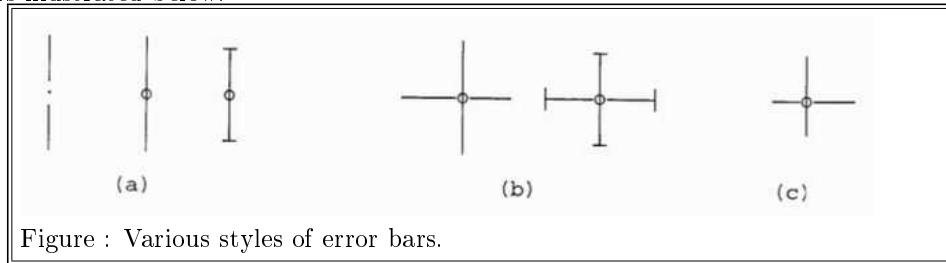
Both axes are labeled with the full name of the quantity (not merely its symbol), and its units.

The plotted points and curve should occupy most (more than half) of the area of the graph paper.

Sometimes a small sketch of the experimental situation may be included, located where it will not confuse the interpretation of the graph. In the same manner an equation, or short explanatory comment, may be included.

## 1.3 Graphical Representation of Uncertainties

Display graphs and computational graphs should clearly show the size of the experimental uncertainties (errors) in each plotted point. There are several conventional ways to do this, the commonest being the use of error bars illustrated below:



The plotted point is represented as a dot, and the range of uncertainty is shown by the extent of the bars on either side. The types shown in (a) are suitable where the error is entirely in one variable, or where the errors in both variables have been lumped together. The types shown in (b) are preferred where it is necessary to show the error in each variable explicitly.

When the uncertainties have a symmetric distribution about the mean, the error bars extend equally on either side of the points. If the data distributions are not symmetric, the plotted points will not be centrally located in the range of uncertainty and the error bars might look like those in Figure. part (c).

Error bars may not be necessary when the data points are so numerous that their scatter is clearly shows the uncertainty. In these cases error bars would clutter the graph making it difficult to interpret. Another situation where error bars are inappropriate is when the scale of the graph is such that the bars would be very small. In this case, it may be possible to indicate the uncertainty by the size of the circle or rectangle surrounding each point.

## 1.4 Curve Fitting

The curve drawn through plotted data need not pass exactly through every data point. But usually the curve should pass within the uncertainty range of each point, that is, within the error bars, if the bars represent limits of error.

One principle of curve fitting is also a fundamental rule of science itself:

Assume the simplest relation consistent with the data. We are not justified in assuming a more complex relation than can be demonstrated by the data. If a curve were drawn with detail smaller than the data uncertainty, that detail would be only a guess.

This rule of simplicity may also be expressed mathematically. The mathematical relations encountered in physics may often be represented by power series such as

$$y = A + Bx + Cx^2 + Dx^3 + Ex^4 + \dots$$

where A, B, C, ... are constants.

For very "wiggly" curves, many terms of this equation, including high powers of x, might be required to express the equation of the relation. The simplest relations are those which contain the smallest powers of x. The simplest relations of all are

$$y = a \text{ or } y = a + bx$$

which describe straight lines. Many relations in physics are, fortunately, of this form. Others only include the  $x^2$  term, describing a parabolic curve. Note that double valued curves, sometimes encountered in physics, cannot be represented by Equation.

When sizable amounts of data are taken, standard mathematical methods are available which generate the equation of the simplest curve which statistically "best fits" the data.

The student may wonder how one can be certain that the curve fitted to the data is the "correct" curve. The answer is that relations are never known with certainty. The uncertainty of available data always limits the certainty of the results. Someday someone may obtain more accurate data and be able to show that the old relations are slightly incorrect, and provide us with better ones. As data improves, so does our understanding of relations—this is the way of scientific progress. But we never should claim to know a relation better than the data allows.

## 1.5 Uncertainty in a Slope

One use of a computational graph is to determine the slope of a straight line. This is illustrated in Figure. Eight data points are shown with error bars on each. If these bars represent maximum error, any line drawn to represent this data should pass within all bars.

If the error bars represent error estimates smaller than the maximum (average deviation, standard deviation, etc.), then the fitted curve need not pass within all of the error bars, just most of them.

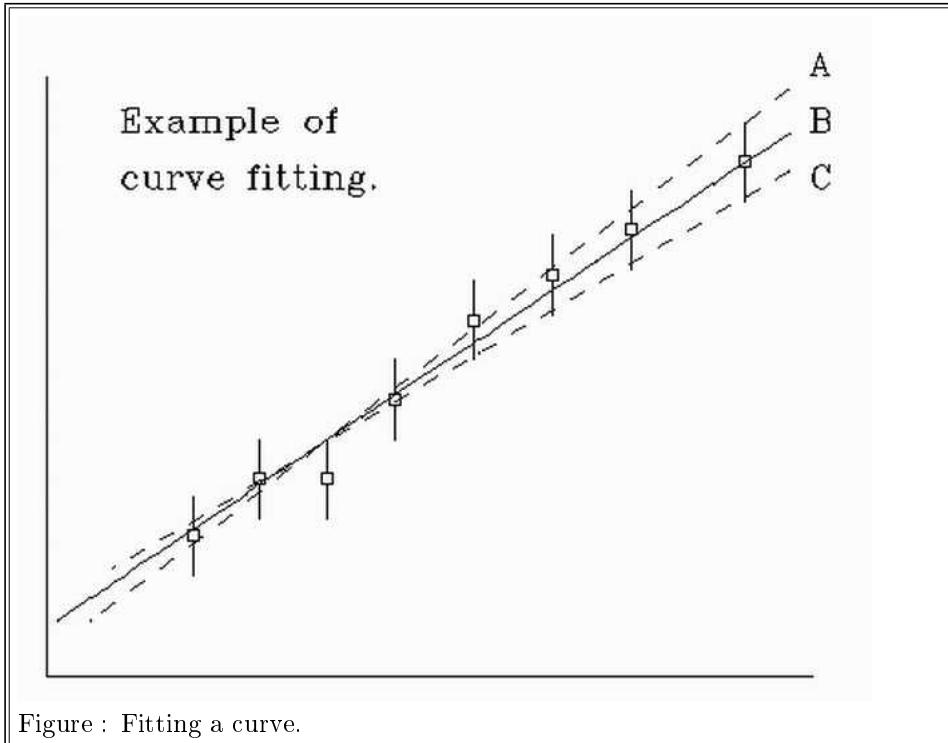


Figure : Fitting a curve.

Even a simple "manual" curve fit with a ruler can reveal the uncertainties in the slope resulting from uncertainties in the data. Figure. illustrates this process.

The dotted lines A and C fall within the error bars, and represent the maximum and minimum slope one could justify from this data. The "best" value of slope might be that of solid line B.

The third point from the left seems to limit the slope the most, and would appear to be "suspect." But one ought not to "throw it out" without better reason, based on further investigation.

## 1.6 Graphical Analysis of Data

Graphs can be a valuable tool for determining or verifying functional relations between variables. Many special types of graph paper are available for handling the most frequently encountered relations. You are probably already familiar with linear graph paper and polar coordinate paper.

You may have purchased a packet of graph paper for this course. It includes samples of graph papers you will use in this course, and a few other types. As you read the material below, examine the corresponding papers from your packet.

LINEAR RELATIONS are those which satisfy the equation

$$y = mx + b$$

where the variables are x and y, and m and b are constants. When y is plotted against x on ordinary Cartesian (linear) graph paper, the points fall on a straight line with slope m and a y-intercept b, as shown in Fig. 1.5.

The slope of an experimental relation is often physically significant. It is obtained by choosing two well-separated points on the line  $(x_1, y_1)$  and  $(x_2, y_2)$ . From Eq. 7-3:

$$y_1 = mx_1 + b$$

$$\text{and } y_2 = mx_2 + b$$

Subtract the first from the second.

$$(y_2 - y_1) = m(x_2 - x_1).$$

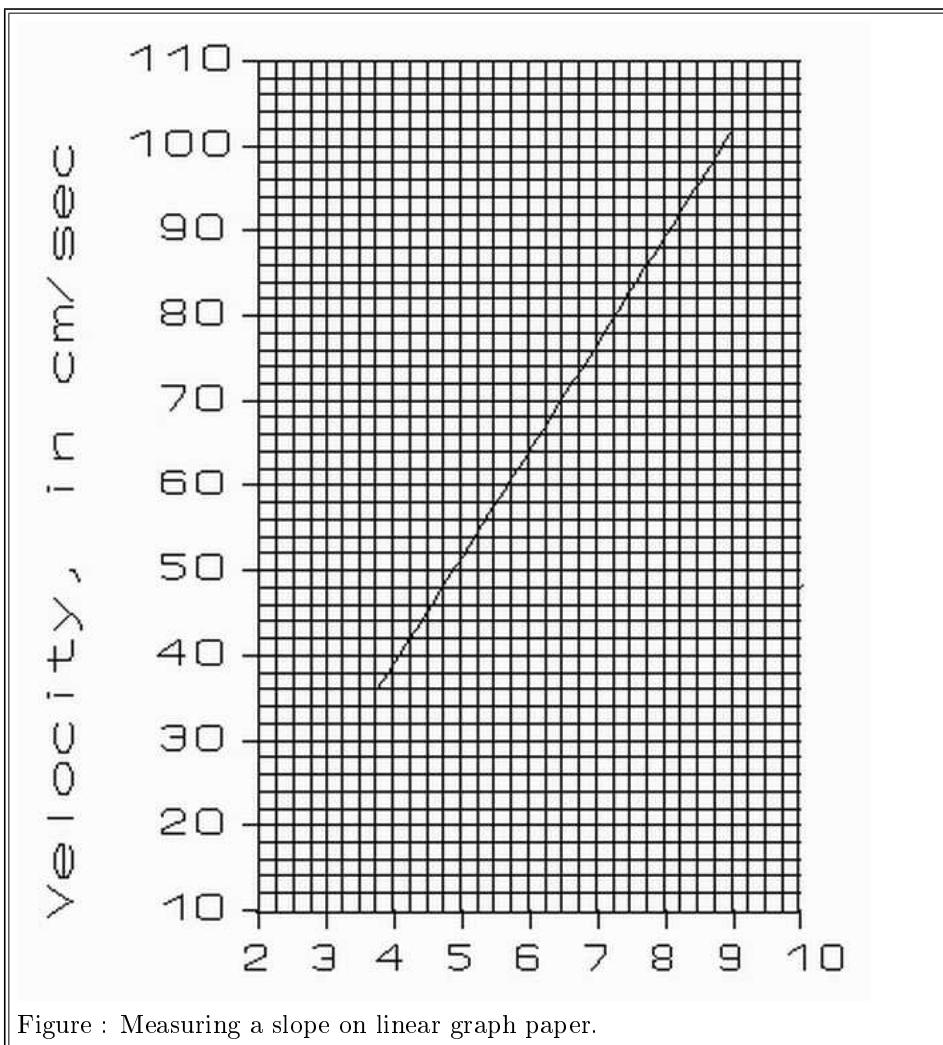


Figure : Measuring a slope on linear graph paper.

Therefore,

$$m = \frac{y_2 - y_1}{x_2 - x_1} = \frac{\Delta y}{\Delta x}$$

The slope of a straight line is a ratio of the "lengths" of two legs of a right triangle constructed with the legs parallel to the graph axes and with the graph line along the hypotenuse. Figure. illustrates this, the slope being  $\Delta y/\Delta x$ .

So far this discussion has been strictly mathematical. Now let's consider a fairly realistic physical example. Figure. shows the curve from measurements of the velocity of a moving body as a function of time.

If we use letters  $v$  for velocity and  $t$  for time, we'd expect this curve to be described by the relation:

$$v = v_o + at$$

Here the constant  $a$  (acceleration) is the slope of the line, while  $v_o$  plays the role of  $b$  in Equation. These two constants are physically significant, and we wish to find their values from the graph.

We choose two points on the line at  $t = 4.25$  and  $8.75$ , with corresponding values of velocity:  $42 \text{ cm/s}$  and  $98 \text{ cm/s}$ . Mark these points on Figure. , to confirm these values. The slope of the line is therefore:

$$a = \frac{(98 \text{ cm/s} - 42 \text{ cm/s})}{8.75 \text{ s} - 4.25 \text{ s}} = \frac{56}{4.5} \text{ cm/s}^2 = 56/4.5 \text{ cm/s}^2 = 12.44 \text{ cm/s}^2$$

When calculating this ratio do not use ruler-measured lengths. The lengths are expressed in the units marked on the graph axes. The calculated slope is therefore independent of the particular choice of units, or the way you choose to label the graph scale divisions, and is also independent of the size of the graph paper.

**INTERCEPTS:** The values of the intercepts are often physically significant. They can be simply read from the graph—if the  $x = 0$  and  $y = 0$  axes happen to be within the graph's boundaries. In the equation  $y = mx + b$ , the  $y$  intercept is  $b$ .

The  $v$  intercept of Figure. is the value of  $v$  when  $t = 0$ . It has the same units and dimensions as  $y$ . If, as in this case, the  $v$  intercept does not lie within the area of the graph, it may be calculated using the slope and one value taken from a point on the fitted line. Take the point  $v = 98 \text{ cm/s}$  when  $t = 8.75 \text{ sec}$ .

$$v = v_o + at, \text{ in our case, } v = v_o + 12.44 t$$

so,

$$v = v_o - 12.44 t = 98 - 12.44(8.75) = -10.89 \text{ cm/s}$$

A check of the graph, Figure. , shows that this looks reasonable.

**STRAIGHTENING A CURVE.** When it is possible to convert an experimental relation to a straight line graph it is usually useful to do so. Look for such opportunities. For example, when studying gases at constant temperature we find that

$$PV = C$$

where P is pressure, V is the gas volume and C is constant. The graph of P vs. V is a branch of an hyperbola. But if we graph P vs.  $1/V$ , or V vs.  $1/P$ , the data would fall on a straight line.

$$P = \left(\frac{1}{V}\right)C$$

One reason for doing this is that it is easier to fit the experimental data with a ruler-drawn straight line, than to draw the best hyperbola on a PV graph. Another advantage is that the P vs.  $1/V$  graph has a slope

$$C = \frac{\Delta P}{\Delta \left(\frac{1}{V}\right)}$$

Therefore the constant C is easily determined from the straight line. This constant was not evident, nor was it easy to determine from the PV graph!

Inexpensive electronic calculators make it so easy to manipulate data that there is no good excuse to pass up an opportunity to "linearize" experimental graphs.

## 1.7 EXERCISES.

In each case state how you could plot (x,y) data on linear paper to obtain a straight line graph. What quantity in the equation is determinable from the slope of the straight line? What quantity is determinable from an intercept?

$$(1.1) x(y+1) = 3$$

$$(1.2) 1/x + 1/y = 5$$

$$(1.3) y = Ae^{-x}$$

$$(1.4) y = \sqrt{A-x}$$

$$(1.5) y^2 + x^2 = 7$$

# Chapter 2

## Common Graph Forms in Physics

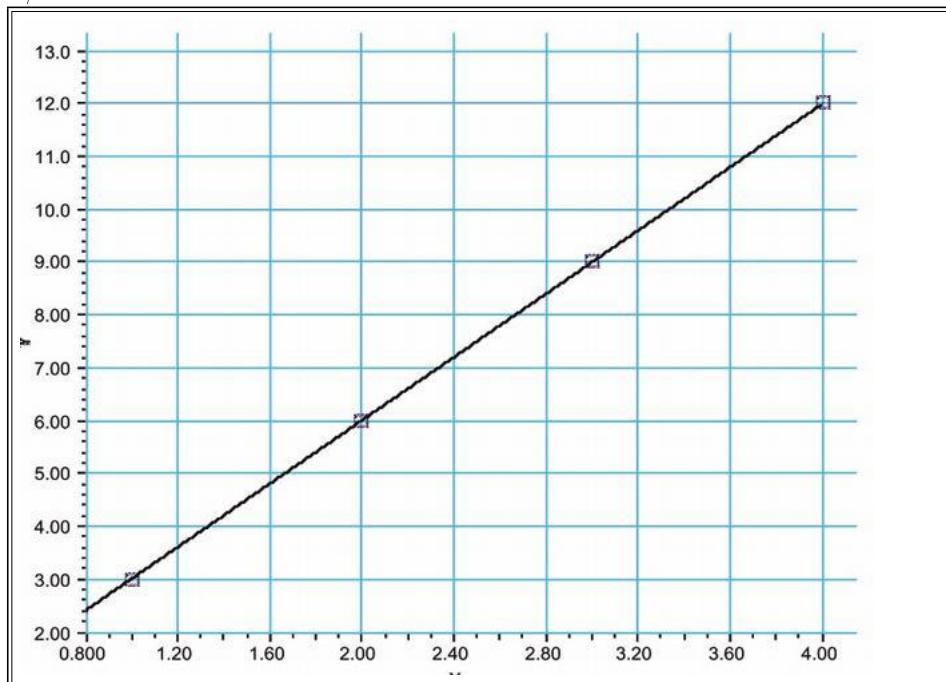
Working with graphs – interpreting, creating, and employing – is an essential skill in the sciences, and especially in physics where relationships need to be derived. As an introductory physics student you should be familiar with the typical forms of graphs that appear in physics. Below are a number of typical physical relationships exhibited graphically using standard X-Y coordinates (e.g., no logarithmic, power, trigonometric, or inverse plots, etc.). Study the forms of the graphs carefully, and be prepared to use the program Graphical Analysis to formulate relationships between variables by using appropriate curve-fitting strategies. Note that all non-linear forms of graphs can be made to appear linear by “linearizing” the data. Linearization consists of such things as plotting X versus  $Y^2$  or X versus  $1/Y$  or Y versus  $\log(X)$ , etc. Note: While a 5th order polynomial might give you a better fit to the data, it might not represent the simplest model.

### 2.1 Linear Relationship

What happens if you get a graph of data that looks like this? How does one relate the X variable to the Y variable? It's simple,  $Y = A + BX$  where B is the slope of the line and A is the Y-intercept. This is characteristic of Newton's second law of motion and of Charles' law:

$$F = ma$$

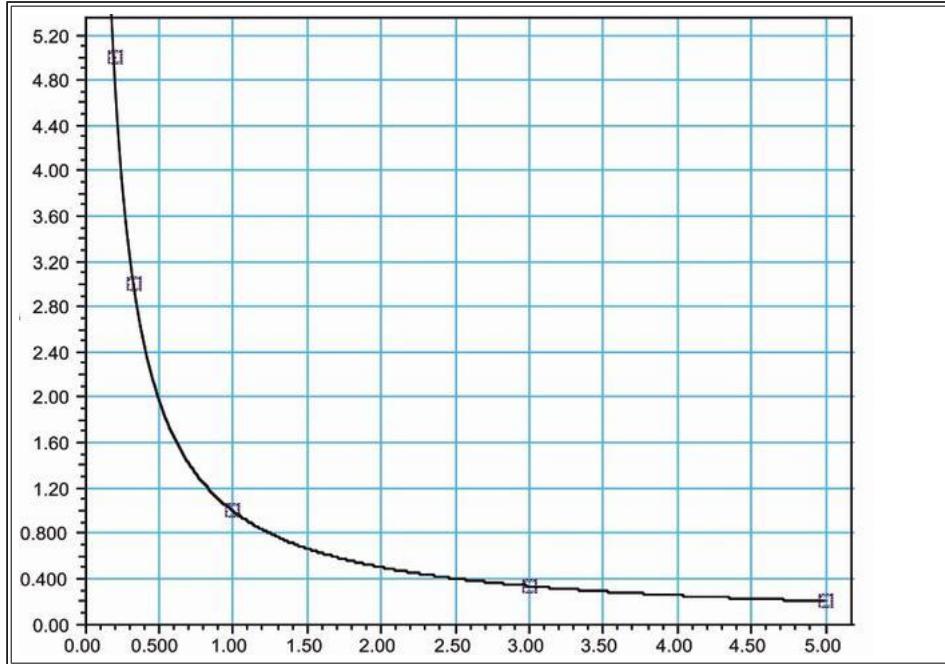
$$P/T = \text{const.}$$



### 2.2 Inverse Relationship

This might be a graph of the pressure and temperature for a changing volume constant temperature gas. How would you find this relationship short of using a computer package? The answer is to simplify the plot by manipulating the data. Plot the Y variable versus the inverse of the X variable. The graph becomes a straight line. The resulting formula will be  $Y = A/X$  or  $XY = A$ . This is typical of Boyle's law:

$PV = \text{const}$

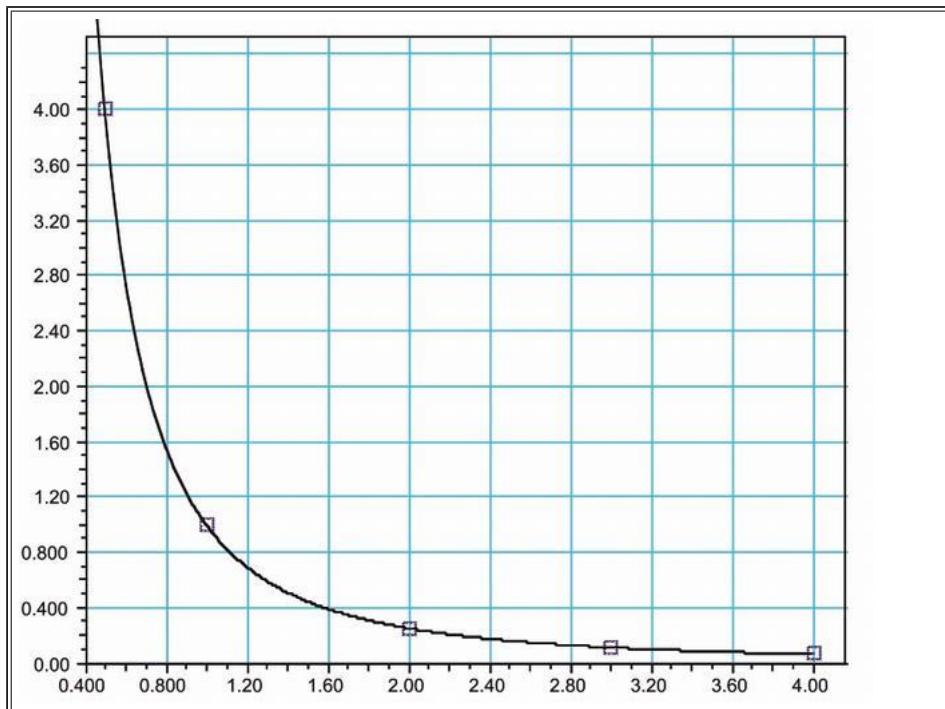


### 2.3 Inverse-Square Relationship

Of the form  $Y = A/X^2$ . Characteristic of Newton's law of universal gravitation, and the electrostatic force law:

$$F = \frac{Gm_1 m_2}{r^2}$$

$$F = \frac{kq_1 q_2}{r^2}$$



In the latter two examples above there are only subtle differences in form. Many common graph forms in physics appear quite similar. Only by looking at the "RMSE" (root mean square error provided in Graphical Analysis) can one conclude whether one fit is better than another. The better fit is the one with the smaller RMSE. See below for more examples of common graph forms in physics.

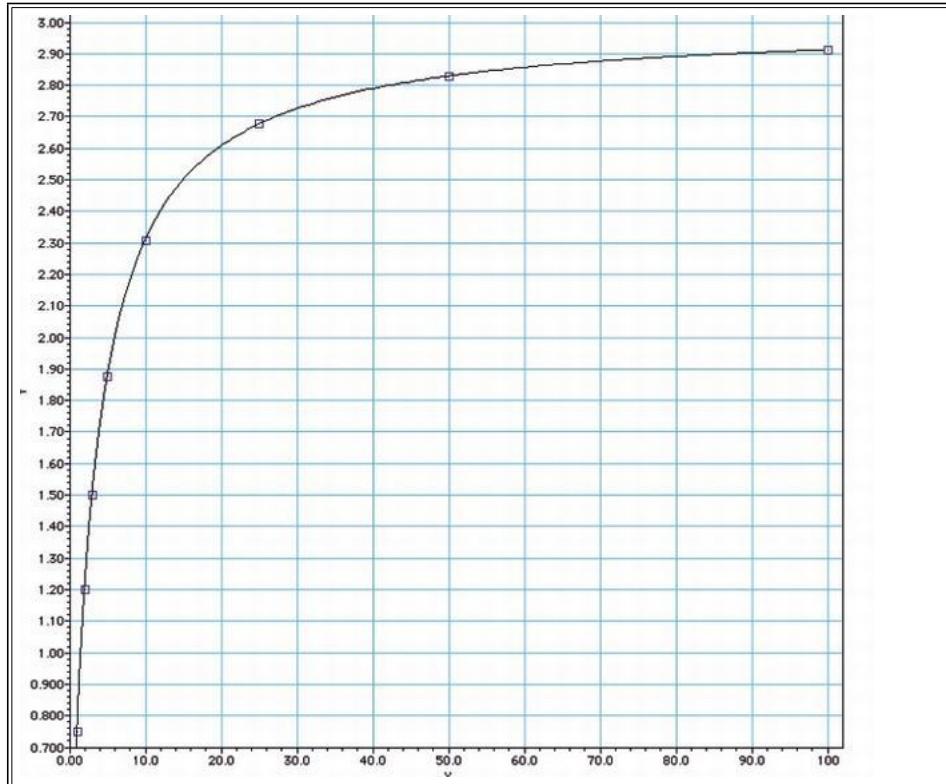
## 2.4 Double-Inverse Relationship

Of the form  $1/Y = 1/X + 1/A$ . Most readily identified by the presence of an asymptotic boundary ( $y = A$ ) within the graph. This form is characteristic of the thin lens and parallel resistance formulas.

$$\frac{1}{f} = \frac{1}{d_i} + \frac{1}{d_o}$$

and

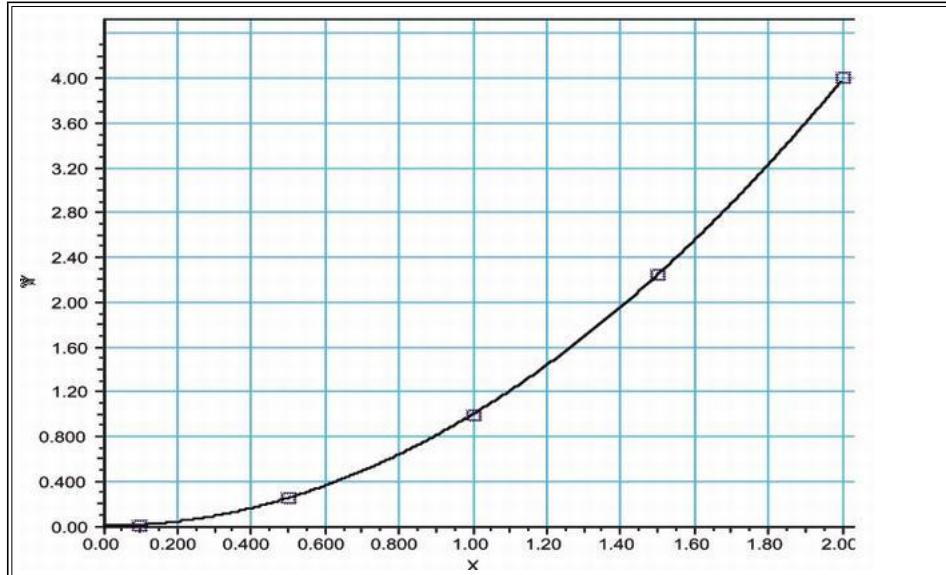
$$\frac{1}{R_t} = \frac{1}{R_1} + \frac{1}{R_2}$$



## 2.5 Power Relationship

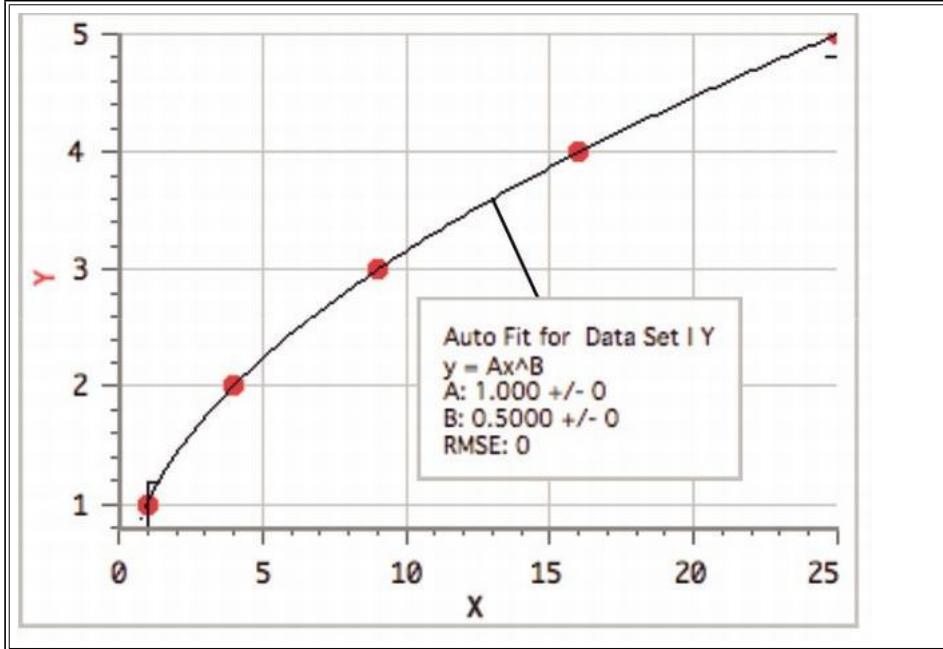
Top opening parabola. Of the form  $Y = AX^2$ . Typical of the distance-time relationship:

$$d = \frac{1}{2}at^2$$



## 2.6 Power Relationship 2

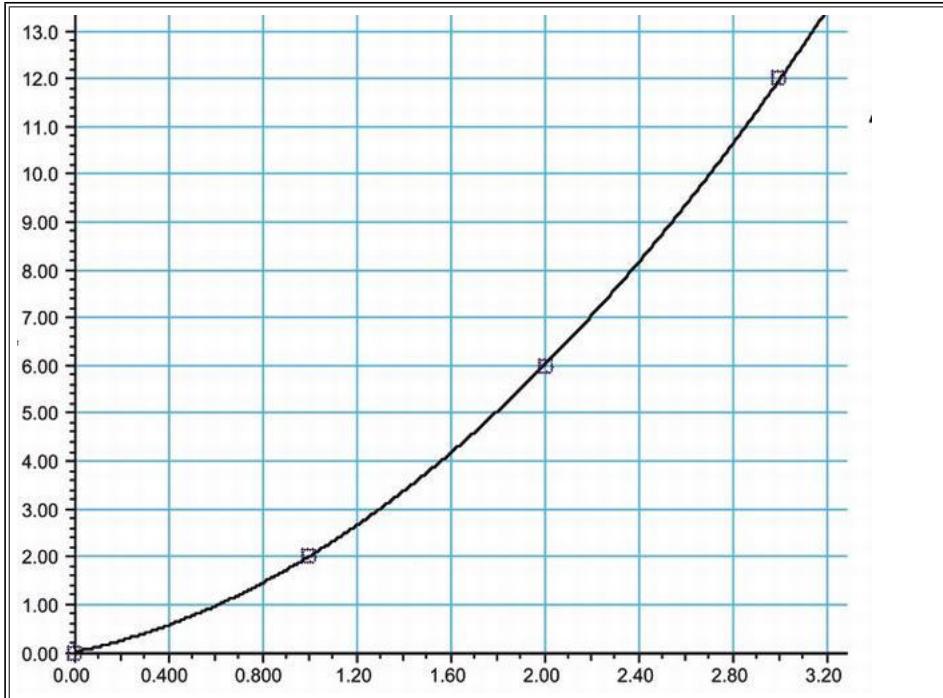
Side opening parabola. Of the form  $Y^2 = A_1X$  or  $Y = A_2X^{1/2}$ . Typical of the simple pendulum relationship:  $P^2 = k_1l$  or  $P = k_2\sqrt{l}$



## 2.7 Polynomial of Second Degree

Of the form  $Y = AX + BX^2$ . Typical of the kinematics equation:

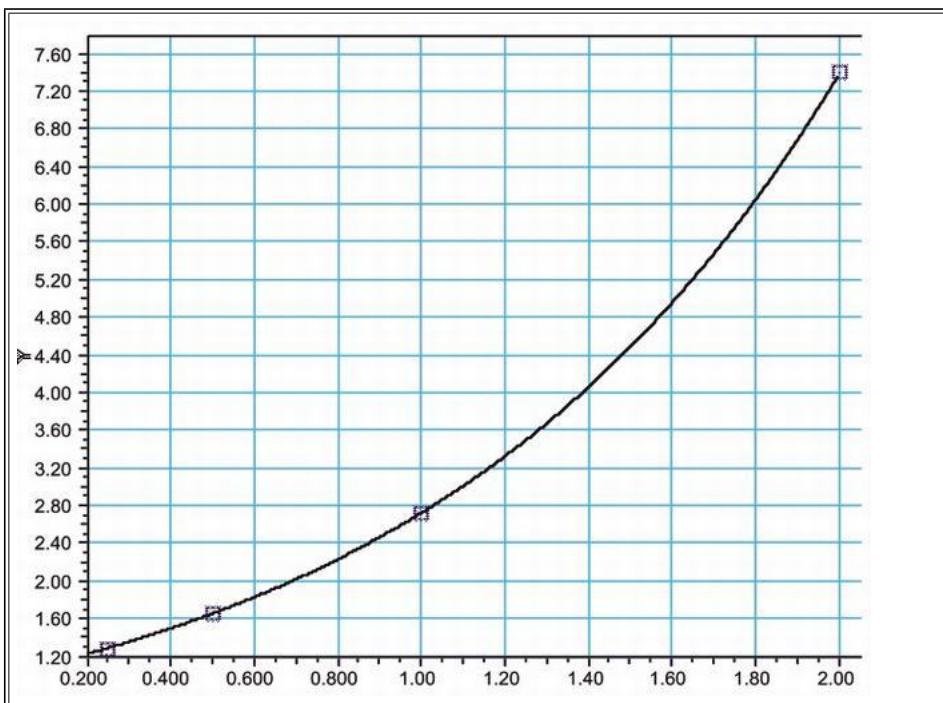
$$d = v_0t + \frac{1}{2}at^2$$



## 2.8 Exponential Relationship

Of the form  $Y = A * \exp(BX)$ . Characteristic of exponential growth or decay. Graph to left is exponential growth. The graph of exponential decay would look not unlike that of the inverse relationship. Characteristic of radioactive decay.

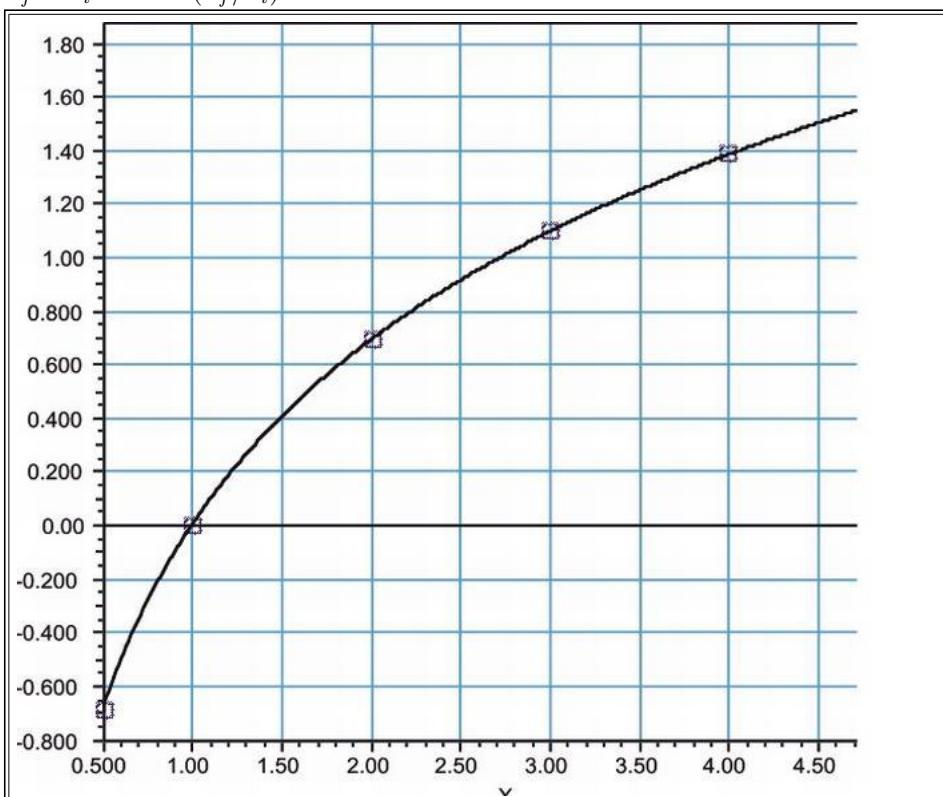
$$N = Noe^{-\lambda t}$$



## 2.9 Natural Log (LN) Relationship

Of the form  $Y = A \ln(BX)$ . Characteristic of entropy change during a free expansion:

$$S_f - S_i = nR \ln(V_f/V_i)$$





# Bibliography

(2016). URL: <https://www.lhup.edu/~dsimanek/scenario/errorman/graphs.htm>.



# Mechanics



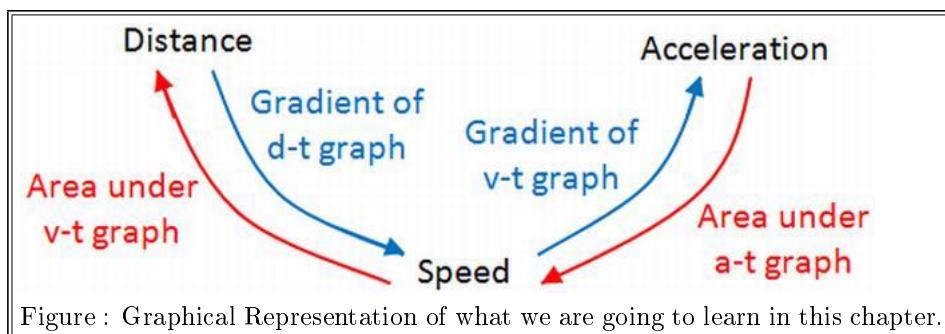
# Part II

# Kinematics



## Chapter 3

# Abstract Introduction



Motion of object	Distance-Time graph	Speed-Time graph	Acceleration-Time graph
At rest	$\frac{d}{m}$ ↑  $t$ → gradient = 0	$\frac{v}{ms^{-1}}$ ↑  $t$ → speed = 0 gradient = 0	$\frac{a}{ms^{-2}}$ ↑  $t$ → acceleration = 0
At constant speed or uniform speed	$\frac{d}{m}$ ↑  $t$ → gradient = constant, k	$\frac{v}{ms^{-1}}$ ↑  $k$ → $t$ → speed = constant, k gradient = 0	$\frac{a}{ms^{-2}}$ ↑  $t$ → acceleration = 0

Figure : Some Graphs

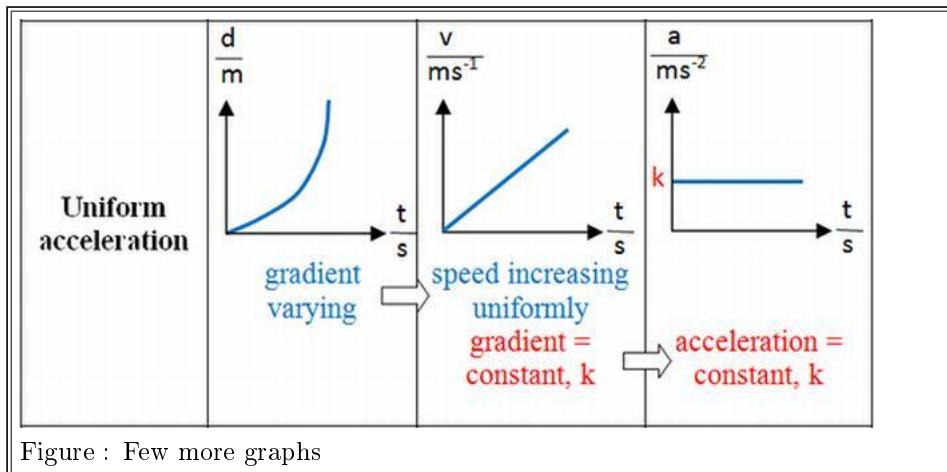


Figure : Few more graphs

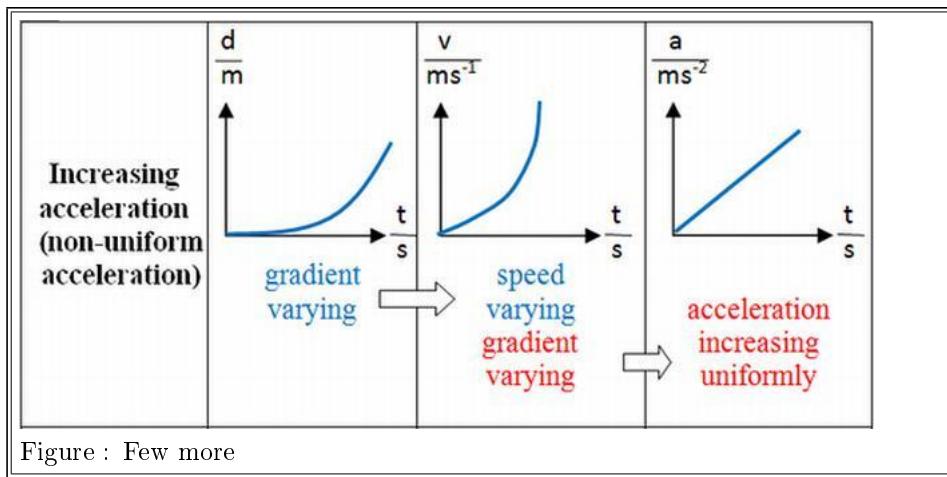


Figure : Few more

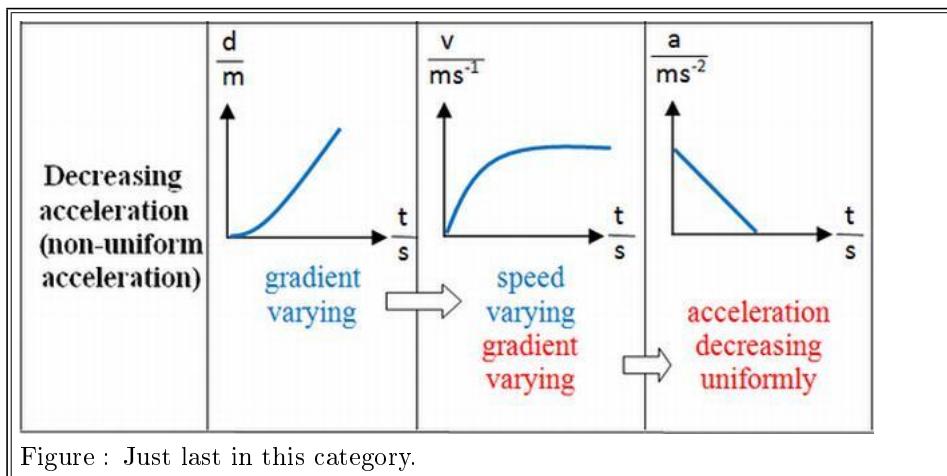


Figure : Just last in this category.

If we have a high velocity, the graph has a steep slope. If we have a low velocity the graph has a shallow slope (assuming the vertical and horizontal scale of each graph is the same).

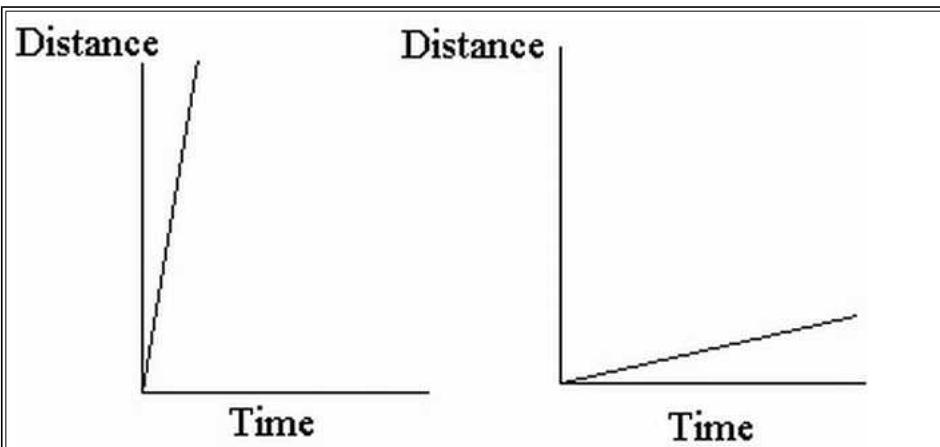


Figure : Graph comparision of high speed vs low speed. [ It may be noted that in Distance-Time Graphs , the slope is Speed (Distance and corresponding Speed both being Scalars), while in Displacement-Time Graphs, the slope is velocity(Displacement and corresponding Velocity both being Vectors).]

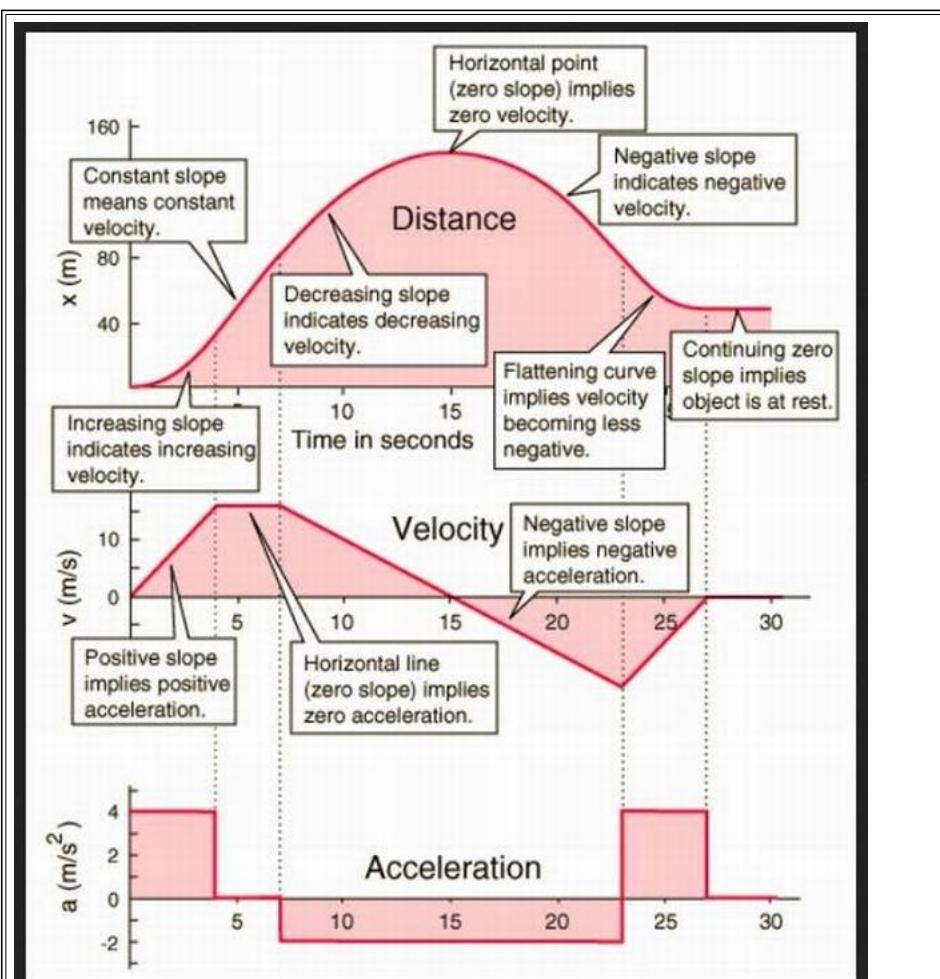


Figure : Graphical representation of the paradigms of this chapter.

### 3.1 Displacement-Time Graph

A displacement-time graph shows the positions of a moving object at different times. Fig. shows the displacement-time graph of a car. From time  $t = 0$  to  $t = 5\text{s}$ , the car moves forward, and at  $t = 5\text{s}$  it has a displacement of  $60\text{ m}$ . Then it remains stationary there for  $5\text{ s}$ , and finally moves back to its starting position in another  $5\text{ s}$ . n.d.

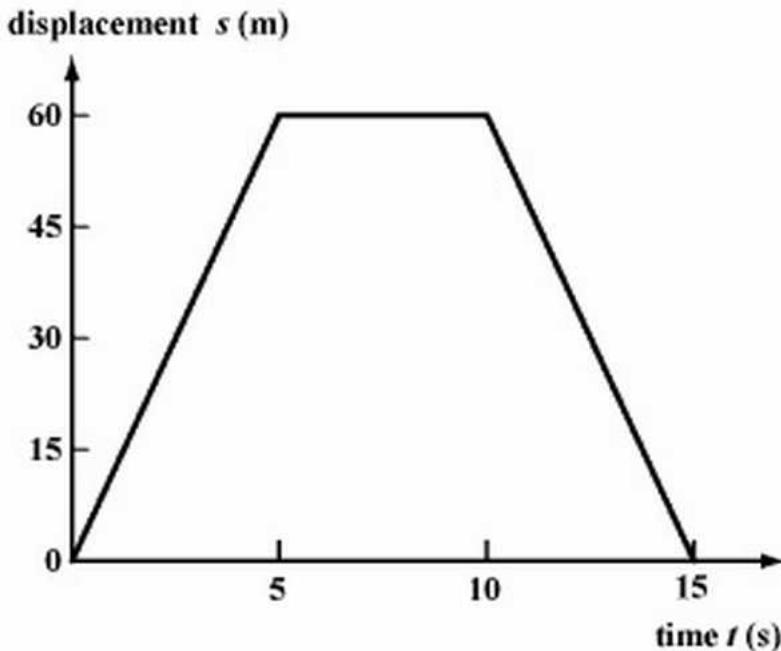
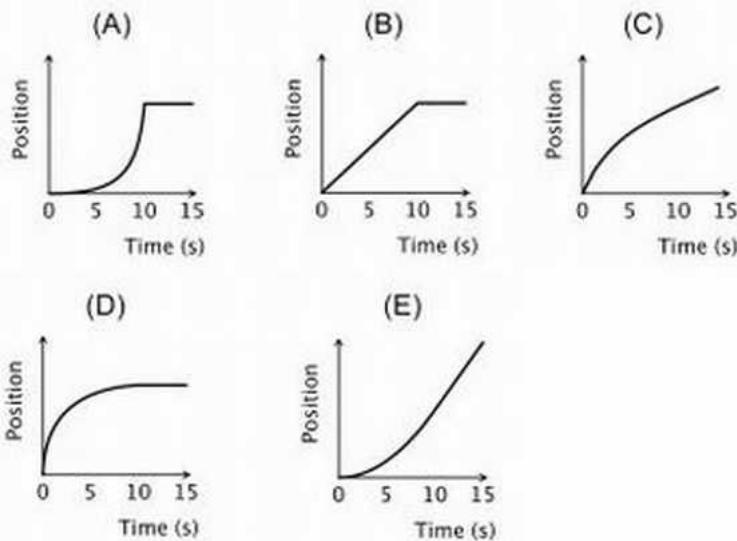


Figure : Displacement-Time Graph of the problem being discussed.

The velocity of motion can be determined from the slope of the displacement-time graph. The velocity of the car is  $\frac{60}{5} = 12 \text{ m/s}$  from  $t=0$  to  $t=5\text{s}$ , it is zero (the car is at rest) from  $t=5\text{s}$  to  $t=10\text{s}$  and is  $(0-60)/(15-10)$  from  $t=10\text{s}$  to  $t=15\text{s}$ . The negative slope in the last 5 s indicates that the car is moving backwards. Note that the slope of the graph in each of the time intervals is a constant, showing that the car is in a uniform motion (constant velocity) in each interval.

**Question :** An object starts from rest and undergoes a positive, constant acceleration for ten seconds, it then continues on with constant velocity. Which of the following graphs correctly describes the situation?



n.d.

### 3.2 Velocity-time graph

A velocity-time graph shows the velocities of a moving object at different times. Figure. shows three velocity-time graphs. n.d.

Fig. (a) represents motion at a constant velocity, the acceleration is zero and thus the slope of the graph is zero. Fig. represents a uniform acceleration given by

$$a = \frac{v - u}{t} = \frac{6 - 0}{15} = 0.4 \text{ ms}^{-2}$$

,

This is represented by the slope of the velocity-time graph. Fig. represents a uniform deceleration given by

$$a = \frac{v - u}{t} = \frac{0 - 4}{15} \approx -0.27 \text{ ms}^{-2}$$

which is also represented by the slope of the graph. The negative slope indicates that the object decelerates. Note that the steeper the slope, the larger is the magnitude of the acceleration.

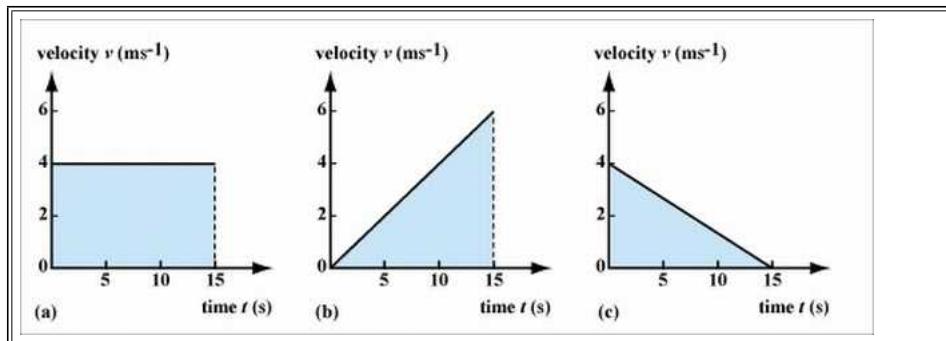
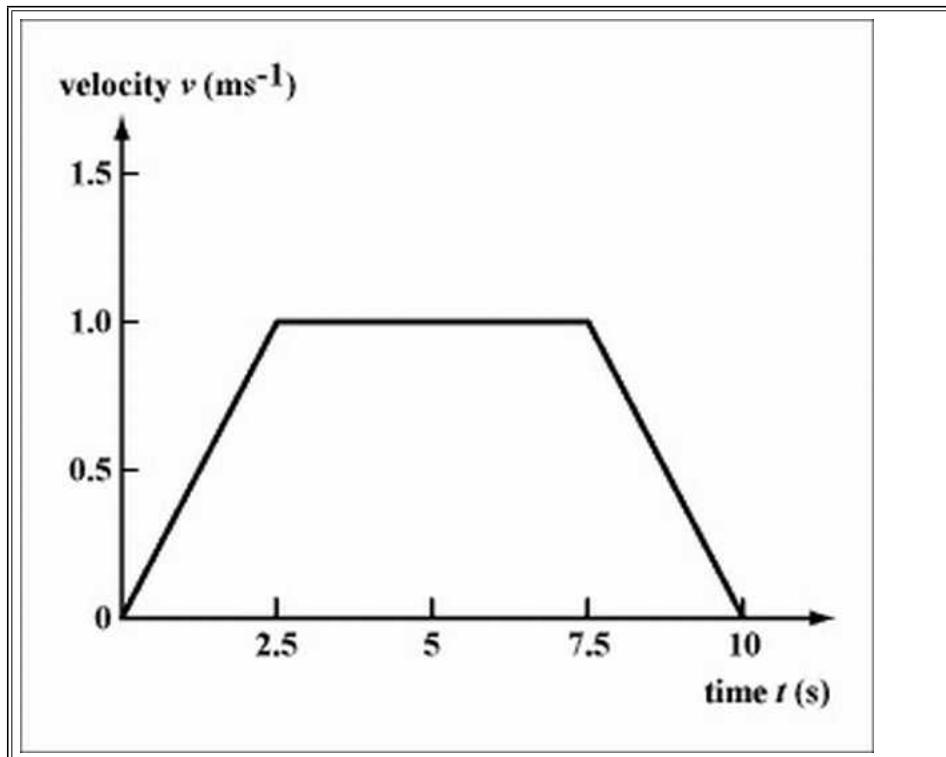


Fig. For the uniform motion shown in Fig. (a), the displacement is given by  $\text{velocity} \times \text{time} = 4 \times 15 = 60$ . This is represented by the area of the rectangle under the graph. In fact, for any velocity-time graph, the displacement at a certain time can be calculated from the area under the graph. Following this rule, we can work out the displacement for an object in uniform acceleration or deceleration. For Fig. (b), the displacement is  $6 \times 15/2 = 45 \text{ m}$ , while for Fig. (c), the displacement is  $4 \times 15/2 = 30 \text{ m}$

Fig. shows the velocity-time graph of an elevator moving upwards. The elevator is initially at rest on the ground floor. It accelerates from rest for 2.5 s, reaching a velocity of  $1 \text{ ms}^{-1}$ , then it moves at this constant velocity for 5 s, and finally decelerates to rest in 2.5 s.

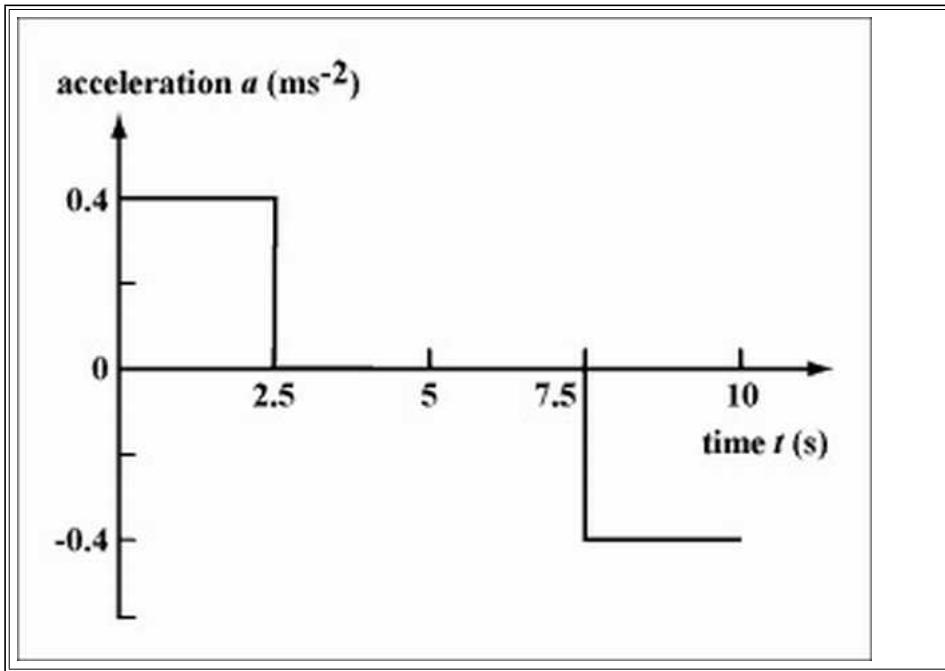


The acceleration of the elevator at each time interval can be deduced from the slope of the graph. In the first 2.5 s, the elevator accelerates at  $1/2.5 = 0.4 \text{ ms}^{-2}$ . The acceleration is zero for the next 5 s, and in the last 2.5 s the elevator decelerates at  $(0-1)/(10-7.5) = -0.4 \text{ ms}^{-2}$  to rest (the negative slope indicates a deceleration). Note that for the whole trip, the elevator is going upwards.

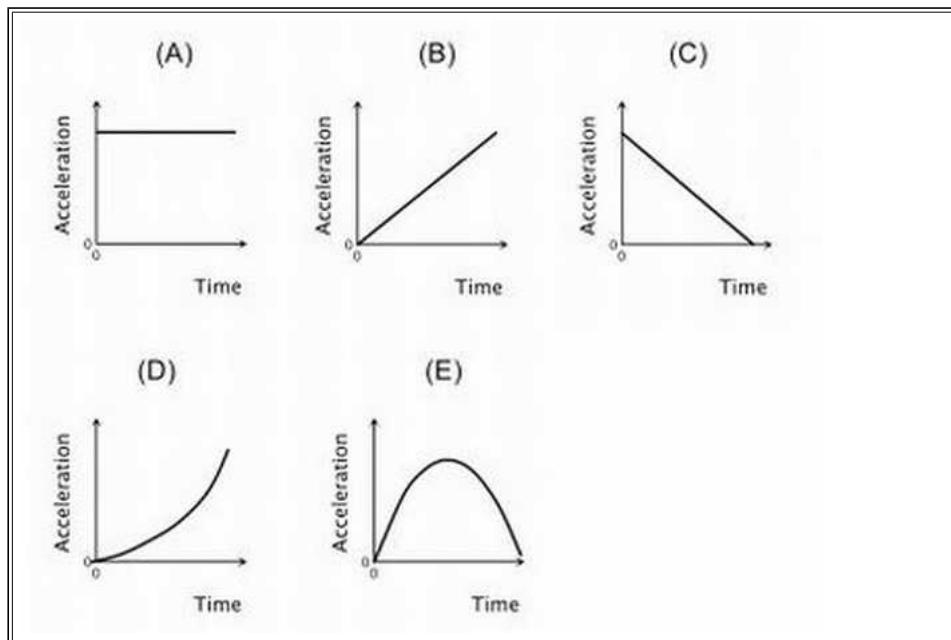
The total displacement can be calculated from the area under the graph. In this example, the total displacement of the elevator is the area of the trapezium under the graph, i.e., total displacement  $= (5+10) \times 1/2 = 7.5 \text{ m}$ .

### 3.3 Acceleration-time graph

Fig. An acceleration-time graph shows the accelerations of a moving object at different times. Fig. shows the acceleration-time graph constructed from the velocity-time graph in Fig. . It can be seen that during the first 2.5 s and the last 2.5 s, the elevator is moving with a constant acceleration and deceleration respectively, and in between it moves at a constant velocity (zero acceleration).



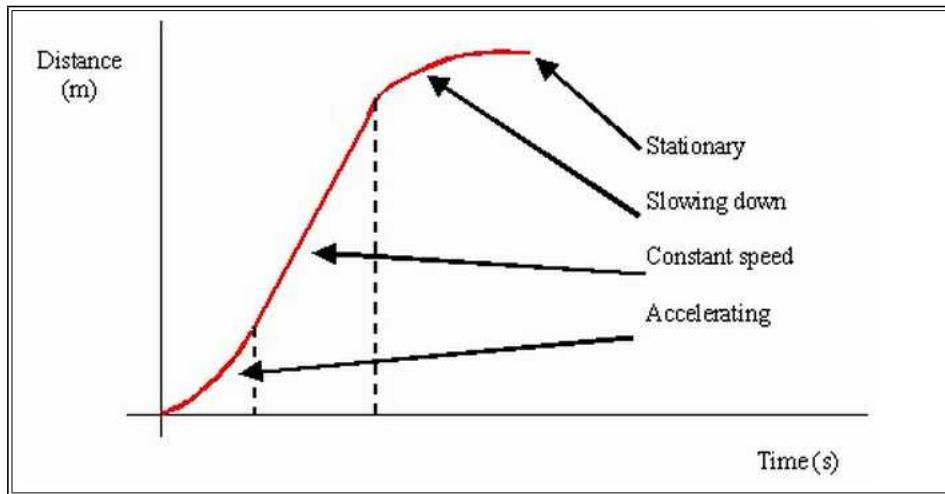
**Question :** Acceleration vs time graphs for five objects are shown below. All axis have the same scale. Which object has the greatest change in velocity during the interval?



n.d.

## 3.4 One More Go in a different perspective

### 3.4.1 Distance-Time Graphs

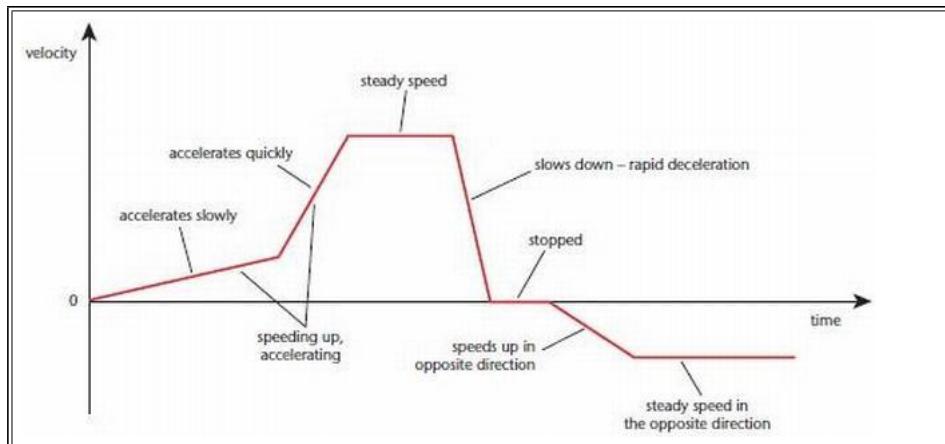


For a distance-time graph, the distance never decreases. When the object is stationary, the distance-time graph will be horizontal. The gradient of a distance-time graph is the instantaneous speed of the object. For straight line with positive gradient, it means that the object is travelling at uniform speed. There is no straight line with negative gradient (as the distance never decreases). For curves, it means that the object is travelling at non-uniform speed. n.d.

### 3.4.2 Displacement-time graphs

The details are similar as distance-time graphs, except that the distance is now displacement, and speed is now velocity. One minor difference: There is a straight line with negative gradient, it means that the object is travelling at uniform velocity in the opposite direction. n.d.

### 3.4.3 Velocity-time graphs

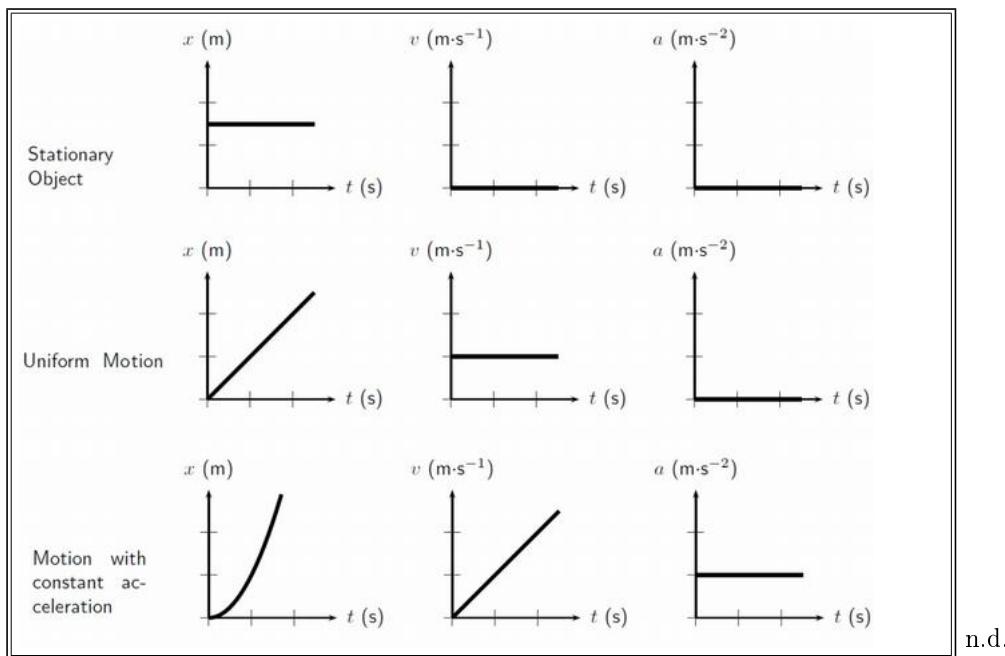


When the object is stationary, it is a straight horizontal line at 0. When the object is undergoing uniform motion, it is a straight horizontal line at  $v \text{ m s}^{-1}$ , where  $v$  is the velocity of the object. For straight line with positive gradient, it means that the object is accelerating. For straight line with negative gradient, it means that the object is decelerating. For curves, it means that the acceleration of the object is changing. The area under the graph is the change in displacement of the object.

### 3.4.4 Acceleration-time graphs

Area under graph is the change in velocity n.d.

The figure below shows the displacement-time graph, velocity-time graph and acceleration-time graph for the respective state of motion. It serves as a summary of the text above.



### 3.4.5 Self-Test Questions n.d.

Q Can you tell from a displacement-time graph whether an object is stationary?

Answer Yes. If the object is stationary, it will appear as a horizontal line on a displacement-time graph.

Q How can you obtain the average velocity and instantaneous velocity from a displacement-time graph?

Answer The average velocity can be found by using  $\frac{\text{total displacement}}{\text{total time taken}}$

The instantaneous velocity at a point in time can be found from the gradient of the tangent to that point in time.

Q Can you tell from a velocity-time graph whether an object is stationary?

Answer Yes. If the object is stationary, the velocity-time graph will be a horizontal line at  $v=0$ .

Q How would you obtain the acceleration of an object from a velocity-time graph? What does the area under a velocity-time graph represent?

Answer The acceleration of an object at a point in time can be obtained from the gradient of the tangent to that point in time.

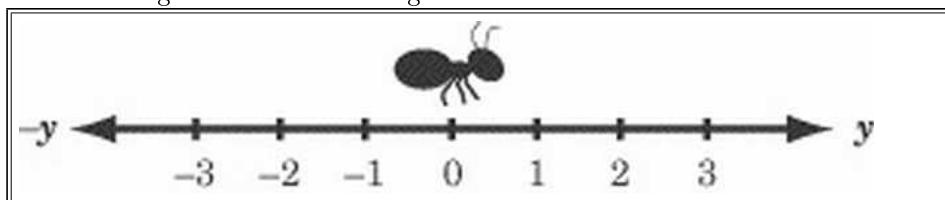
The area under a velocity-time graph represents the total distance traveled.

Q Can you tell from an acceleration-time graph whether an object is stationary?

Answer No, you cannot. Do you know why?

## 3.5 Revision

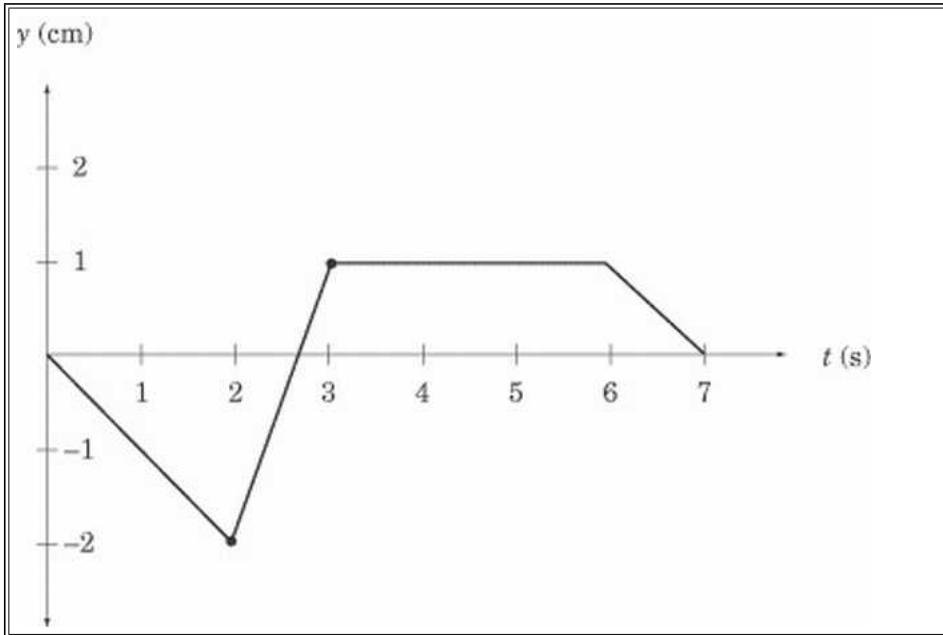
Since you are not allowed to use calculators, SAT II Physics places a heavy emphasis on qualitative problems. A common way of testing kinematics qualitatively is to present you with a graph plotting position vs. time, velocity vs. time, or acceleration vs. time and to ask you questions about the motion of the object represented by the graph. Because SAT II Physics is entirely made up of multiple-choice questions, you won't need to know how to draw graphs; you'll just have to interpret the data presented in them. Knowing how to read such graphs quickly and accurately will not only help you solve problems of this sort, it will also help you visualize the often-abstract realm of kinematic equations. In the examples that follow, we will examine the movement of an ant running back and forth along a line. n.d.



### 3.5.1 Position vs. Time Graphs

Position vs. time graphs give you an easy and obvious way of determining an object's displacement at any given time, and a subtler way of determining that object's velocity at any given time. Let's put these concepts

into practice by looking at the following graph charting the movements of our friendly ant. n.d.



Any point on this graph gives us the position of the ant at a particular moment in time. For instance, the point at  $(2, -2)$  tells us that, two seconds after it started moving, the ant was two centimeters to the left of its starting position, and the point at  $(3, 1)$  tells us that, three seconds after it started moving, the ant is one centimeter to the right of its starting position. Let's read what the graph can tell us about the ant's movements. For the first two seconds, the ant is moving to the left. Then, in the next second, it reverses its direction and moves quickly to  $y = 1$ . The ant then stays still at  $y = 1$  for three seconds before it turns left again and moves back to where it started. Note how concisely the graph displays all this information. Calculating Velocity We know the ant's displacement, and we know how long it takes to move from place to place. Armed with this information, we should also be able to determine the ant's velocity, since velocity measures the rate of change of displacement over time. If displacement is given here by the vector  $y$ , then the velocity of the ant is

$$v = \frac{\Delta y}{\Delta t}$$

If you recall, the slope of a graph is a measure of rise over run; that is, the amount of change in the  $y$  direction divided by the amount of change in the  $x$  direction. In our graph,  $y$  is the change in the  $y$  direction and  $x$  is the change in the  $x$  direction, so  $v$  is a measure of the slope of the graph. For any position vs. time graph, the velocity at time  $t$  is equal to the slope of the line at  $t$ . In a graph made up of straight lines, like the one above, we can easily calculate the slope at each point on the graph, and hence know the instantaneous velocity at any given time. We can tell that the ant has a velocity of zero from  $t = 3$  to  $t = 6$ , because the slope of the line at these points is zero. We can also tell that the ant is cruising along at the fastest speed between  $t = 2$  and  $t = 3$ , because the position vs. time graph is steepest between these points. Calculating the ant's average velocity during this time interval is a simple matter of dividing rise by run, as we've learned in math class.

### 3.5.2 Average Velocity

$$\begin{aligned} \text{velocity} &= \frac{y_{\text{final}} - y_{\text{initial}}}{t_{\text{final}} - t_{\text{initial}}} \\ &= \frac{1 - (-2) \text{ cm}}{3 - 2 \text{ s}} \\ &= 3 \text{ cm/s to the right} \end{aligned}$$

How about the average velocity between  $t = 0$  and  $t = 3$ ? It's actually easier to sort this out with a graph in front of us, because it's easy to see the displacement at  $t = 0$  and  $t = 3$ , and so that we don't confuse displacement and distance.

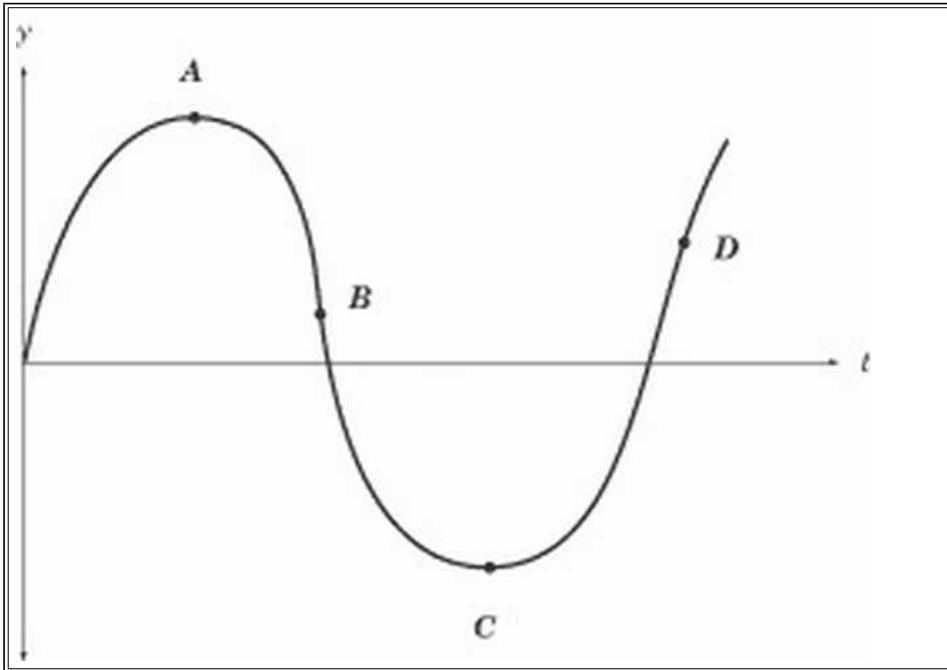
### 3.5.3 Average Speed

Although the total displacement in the first three seconds is one centimeter to the right, the total distance traveled is two centimeters to the left, and then three centimeters to the right, for a grand total of five centimeters. Thus, the average speed is not the same as the average velocity of the ant. Once we've calculated the total distance traveled by the ant, though, calculating its average speed is not difficult:

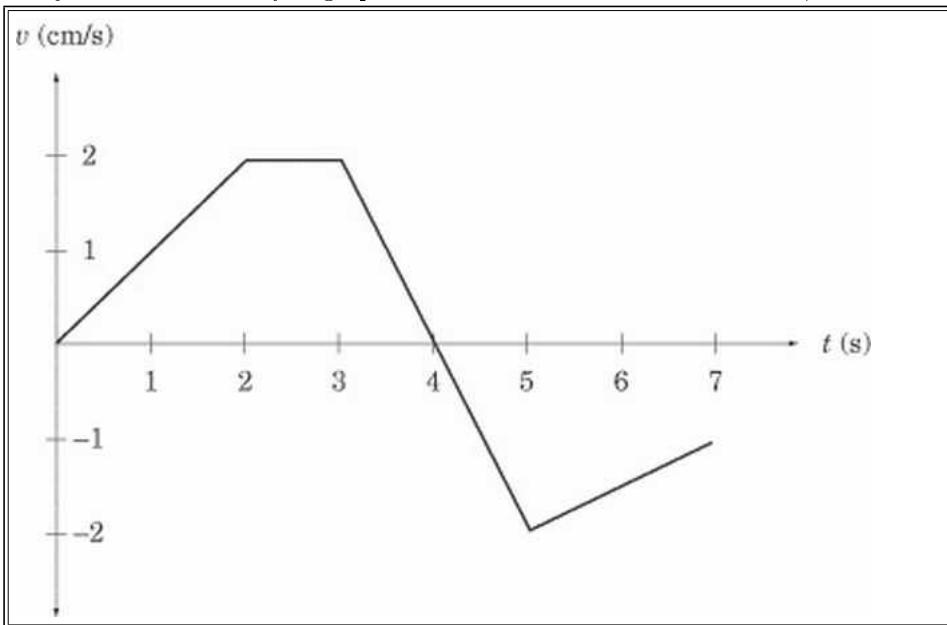
$$5 \text{ cm} / 3 \text{ s} = 1.67 \text{ cm/s}$$

### 3.5.4 Curved Position vs. Time Graphs

This is all well and good, but how do you calculate the velocity of a curved position vs. time graph? Well, the bad news is that you'd need calculus. The good news is that SAT II Physics doesn't expect you to use calculus, so if you are given a curved position vs. time graph, you will only be asked qualitative questions and won't be expected to make any calculations. A few points on the graph will probably be labeled, and you will have to identify which point has the greatest or least velocity. Remember, the point with the greatest slope has the greatest velocity, and the point with the least slope has the least velocity. The turning points of the graph, the tops of the "hills" and the bottoms of the "valleys" where the slope is zero, have zero velocity. n.d.



In this graph, for example, the velocity is zero at points A and C, greatest at point D, and smallest at point B. The velocity at point B is smallest because the slope at that point is negative. Because velocity is a vector quantity, the velocity at B would be a large negative number. However, the speed at B is greater even than the speed at D: speed is a scalar quantity, and so it is always positive. The slope at B is even steeper than at D, so the speed is greatest at B. Velocity vs. Time Graphs Velocity vs. time graphs are the most eloquent kind of graph we'll be looking at here. They tell us very directly what the velocity of an object is at any given time, and they provide subtle means for determining both the position and acceleration of the same object over time. The "object" whose velocity is graphed below is our ever-industrious ant, a little later in the day.



We can learn two things about the ant's velocity by a quick glance at the graph. First, we can tell exactly how fast it is going at any given time. For instance, we can see that, two seconds after it started to move, the ant is moving at 2 cm/s. Second, we can tell in which direction the ant is moving. From  $t = 0$  to  $t = 4$ , the velocity is positive, meaning that the ant is moving to the right. From  $t = 4$  to  $t = 7$ , the velocity is negative,

meaning that the ant is moving to the left. Calculating Acceleration We can calculate acceleration on a velocity vs. time graph in the same way that we calculate velocity on a position vs. time graph. Acceleration is the rate of change of the velocity vector, , which expresses itself as the slope of the velocity vs. time graph. For a velocity vs. time graph, the acceleration at time  $t$  is equal to the slope of the line at  $t$ . What is the acceleration of our ant at  $t = 2.5$  and  $t = 4$ ? Looking quickly at the graph, we see that the slope of the line at  $t = 2.5$  is zero and hence the acceleration is likewise zero. The slope of the graph between  $t = 3$  and  $t = 5$  is constant, so we can calculate the acceleration at  $t = 4$  by calculating the average acceleration between  $t = 3$  and  $t = 5$ :

$$\begin{aligned} \text{velocity} &= \frac{y_{\text{final}} - y_{\text{initial}}}{t_{\text{final}} - t_{\text{initial}}} \\ &= \frac{-2 - (2) \text{ cm/s}}{5 - 3 \text{ s}} \\ &= -2 \text{ cm/s}^2 \end{aligned}$$

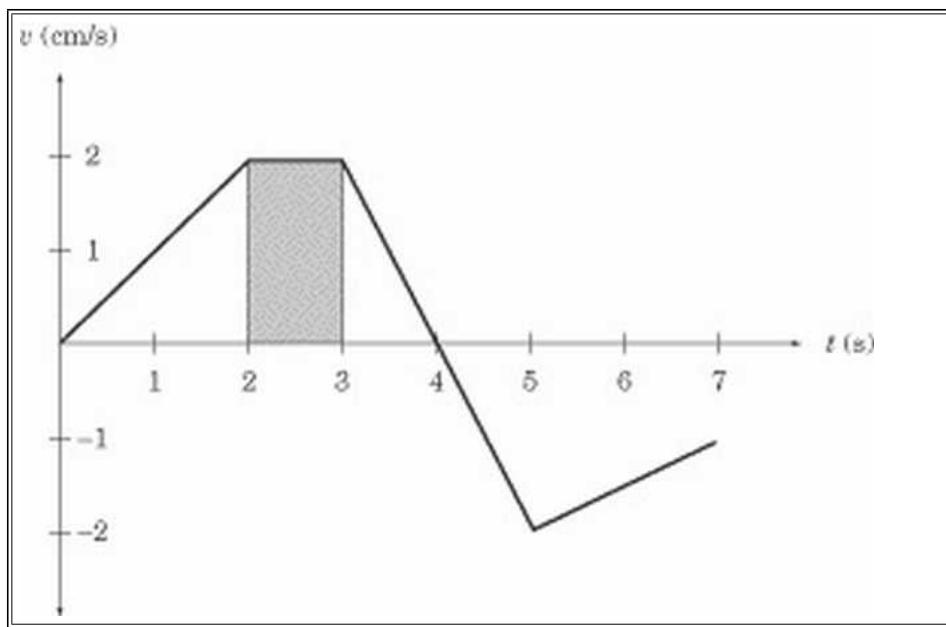
The minus sign tells us that acceleration is in the leftward direction, since we've defined the y-coordinates in such a way that right is positive and left is negative. At  $t = 3$ , the ant is moving to the right at 2 cm/s, so a leftward acceleration means that the ant begins to slow down. Looking at the graph, we can see that the ant comes to a stop at  $t = 4$ , and then begins accelerating to the right. n.d.

### 3.5.5 Calculating Displacement

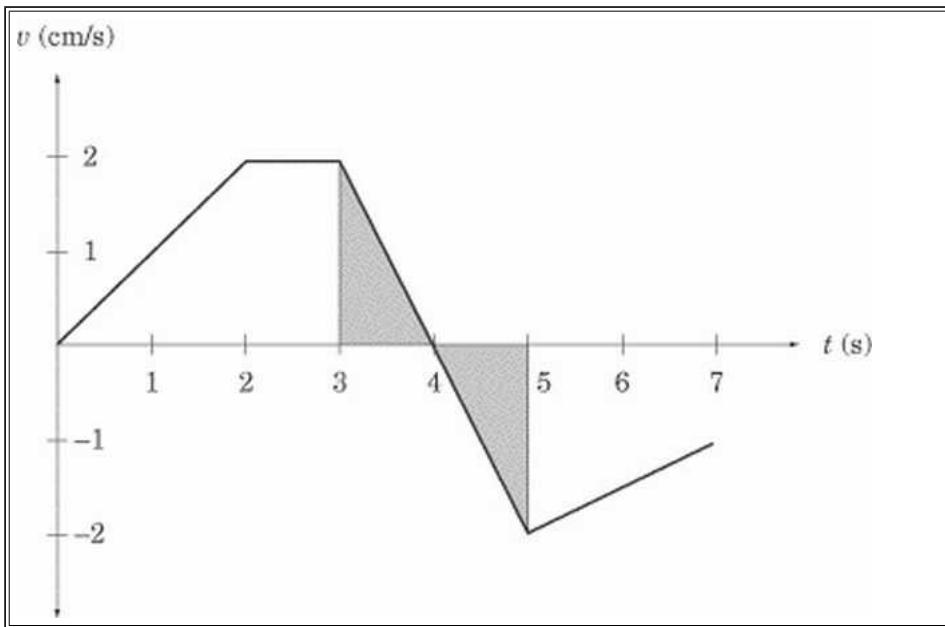
Velocity vs. time graphs can also tell us about an object's displacement. Because velocity is a measure of displacement over time, we can infer that:

$$\text{displacement} = \text{velocity} \times \text{time}$$

Graphically, this means that the displacement in a given time interval is equal to the area under the graph during that same time interval. If the graph is above the t-axis, then the positive displacement is the area between the graph and the t-axis. If the graph is below the t-axis, then the displacement is negative, and is the area between the graph and the t-axis. Let's look at two examples to make this rule clearer. First, what is the ant's displacement between  $t = 2$  and  $t = 3$ ? Because the velocity is constant during this time interval, the area between the graph and the t-axis is a rectangle of width 1 and height 2.



The displacement between  $t = 2$  and  $t = 3$  is the area of this rectangle, which is  $2 \text{ cm/s} \cdot 1 \text{ s} = 2 \text{ cm}$  to the right. Next, consider the ant's displacement between  $t = 3$  and  $t = 5$ . This portion of the graph gives us two triangles, one above the t-axis and one below the t-axis.



Both triangles have an area of  $1/2(1\text{ s})(2\text{ cm/s}) = 1\text{ cm}$ . However, the first triangle is above the  $t$ -axis, meaning that displacement is positive, and hence to the right, while the second triangle is below the  $t$ -axis, meaning that displacement is negative, and hence to the left. The total displacement between  $t = 3$  and  $t = 5$  is **ZERO**.

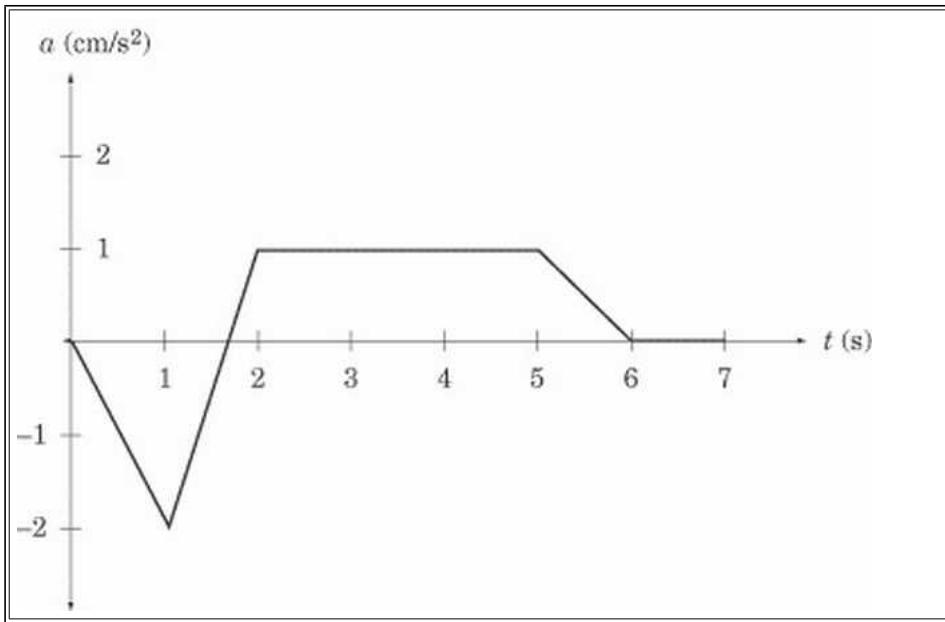
In other words, at  $t = 5$ , the ant is in the same place as it was at  $t = 3$ . n.d.

### 3.5.6 Curved Velocity vs. Time Graphs

As with position vs. time graphs, velocity vs. time graphs may also be curved. Remember that regions with a steep slope indicate rapid acceleration or deceleration, regions with a gentle slope indicate small acceleration or deceleration, and the turning points have zero acceleration.

### 3.5.7 Acceleration vs. Time Graphs

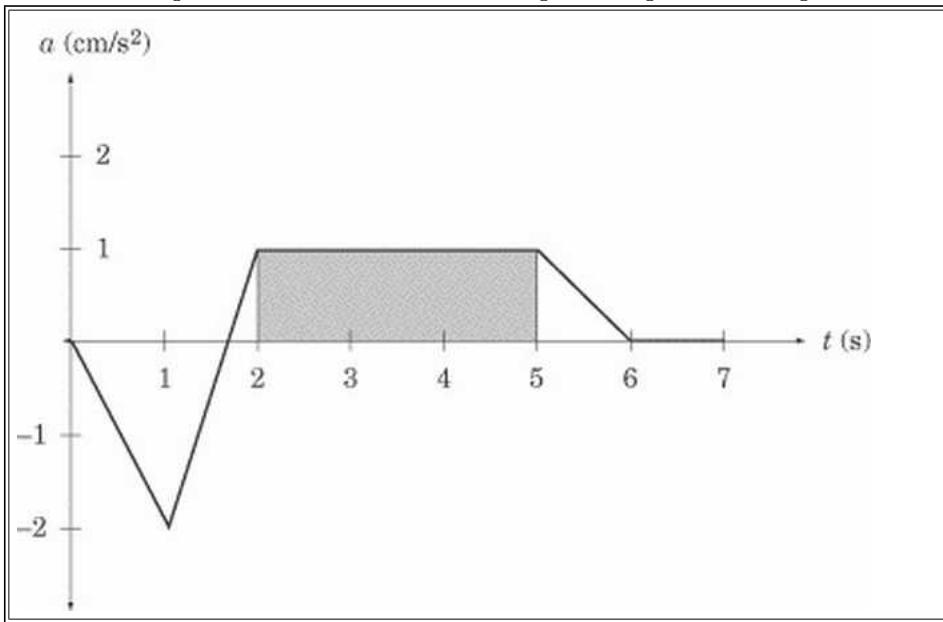
After looking at position vs. time graphs and velocity vs. time graphs, acceleration vs. time graphs should not be threatening. Let's look at the acceleration of our ant at another point in its dizzy day.



Acceleration vs. time graphs give us information about acceleration and about velocity. SAT II Physics generally sticks to problems that involve a constant acceleration. In this graph, the ant is accelerating at  $1\text{ m/s}^2$  from  $t = 2$  to  $t = 5$  and is not accelerating between  $t = 6$  and  $t = 7$ ; that is, between  $t = 6$  and  $t = 7$  the ant's velocity is constant. n.d.

### 3.5.8 Calculating Change in Velocity

Acceleration vs. time graphs tell us about an object's velocity in the same way that velocity vs. time graphs tell us about an object's displacement. The change in velocity in a given time interval is equal to the area under the graph during that same time interval. Be careful: the area between the graph and the t-axis gives the change in velocity, not the final velocity or average velocity over a given time period. What is the ant's change in velocity between  $t = 2$  and  $t = 5$ ? Because the acceleration is constant during this time interval, the area between the graph and the t-axis is a rectangle of height 1 and length 3. n.d.



The area of the shaded region, and consequently the change in velocity during this time interval, is  $1 \text{ cm/s}^2 \cdot 3 \text{ s} = 3 \text{ cm/s}$  to the right. This doesn't mean that the velocity at  $t = 5$  is  $3 \text{ cm/s}$ ; it simply means that the velocity is  $3 \text{ cm/s}$  greater than it was at  $t = 2$ . Since we have not been given the velocity at  $t = 2$ , we can't immediately say what the velocity is at  $t = 5$ .

**Summary of Rules for Reading Graphs**

You may have trouble recalling when to look for the slope and when to look for the area under the graph. Here are a couple handy rules of thumb: The slope on a given graph is equivalent to the quantity we get by dividing the y-axis by the x-axis. For instance, the y-axis of a position vs. time graph gives us displacement, and the x-axis gives us time. Displacement divided by time gives us velocity, which is what the slope of a position vs. time graph represents. The area under a given graph is equivalent to the quantity we get by multiplying the x-axis and the y-axis. For instance, the y-axis of an acceleration vs. time graph gives us acceleration, and the x-axis gives us time. Acceleration multiplied by time gives us the change in velocity, which is what the area between the graph and the x-axis represents. We can summarize what we know about graphs in a table:

Graph	Slope	Area under the graph
position vs. time	velocity	-----
velocity vs. time	acceleration	displacement
acceleration vs. time	-----	change in velocity

## 3.6 Exercises

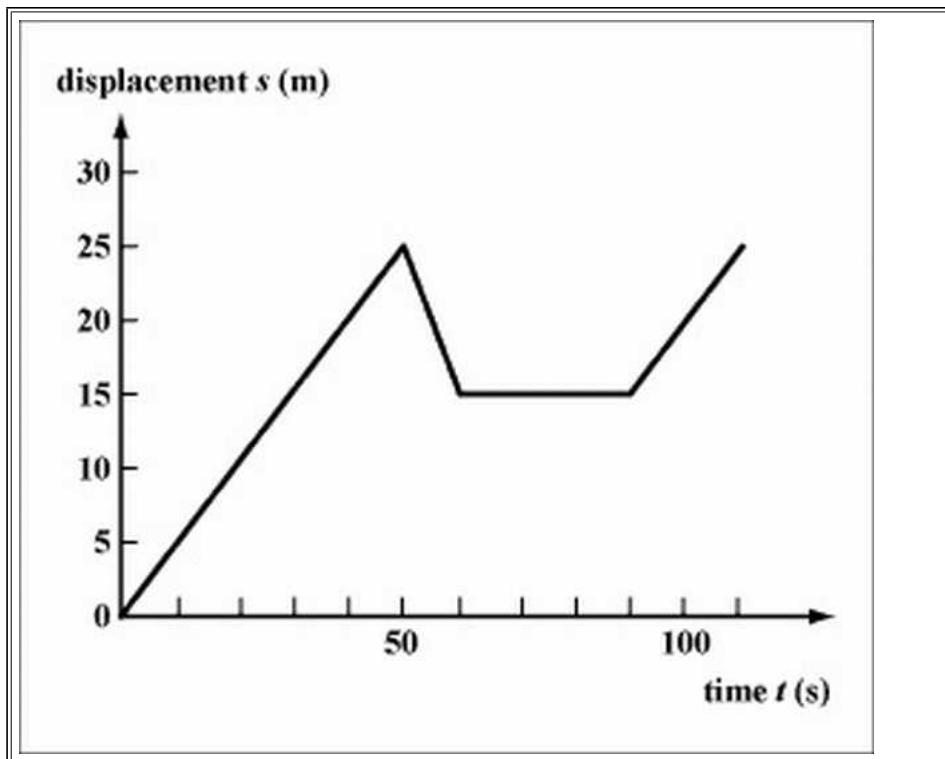
### 3.6.1 Problems on Position-Time Graph

#### 3.6.1.1 Subjectives

**Example :** A boy walks at a velocity of  $0.5 \text{ m/s}$  along a street for  $50 \text{ s}$ , suddenly he remembers that he has to buy something in a shop that he has passed by, so he turns around and walks at a velocity of  $-1 \text{ m/s}$  for

10 s. He then stops for 30 s at the shop, and finally walks forward again at 0.5 m/s for another 20 s. Plot a displacement-time graph for the motion of the boy. n.d.

**Solution :** See Fig. 5-4.

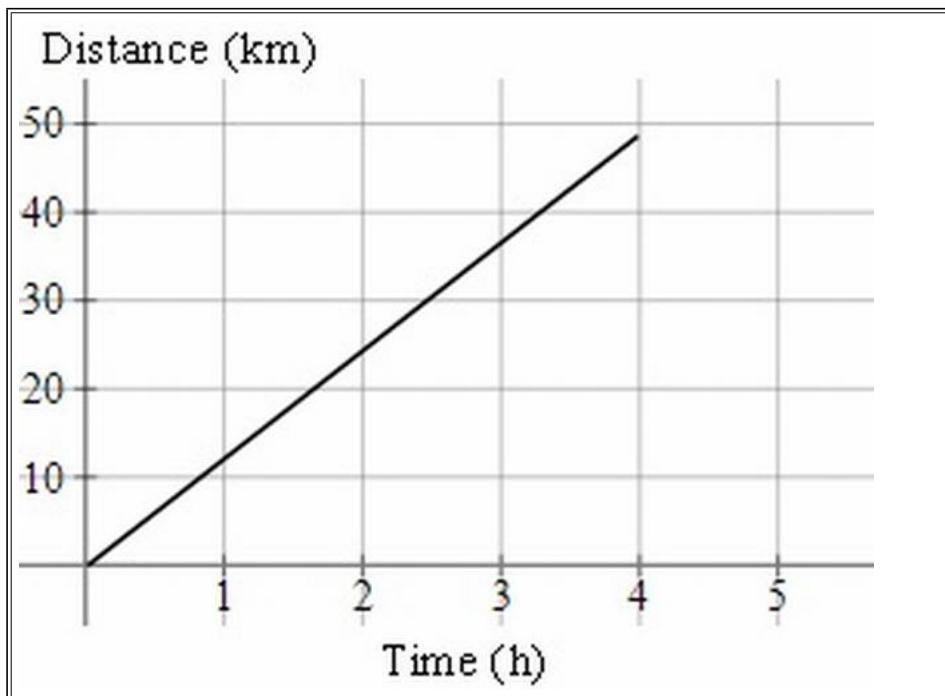


**Example :** A marathon runner runs at a constant 12 km/h. n.d.

- Express her displacement travelled as a function of time.
- Graph the motion for  $0 \leq t \leq 4h$

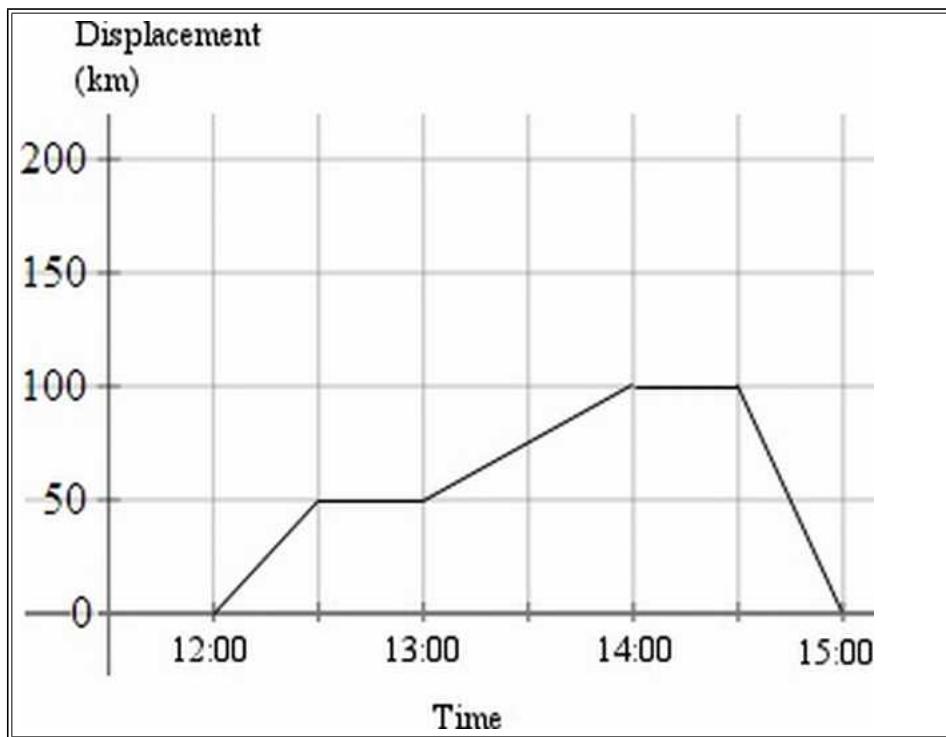
**Solution :** a.  $s = 12t$ , for displacement  $s$  and time  $t$ .

- b. Graph of  $s = 12t$ .



We stop the graph at (4, 48).

**Example :** This is the graph of a journey by sports car: n.d.



- a. What is the velocity for each stage of the journey?  
 b. What is the average (mean) velocity for the whole journey?

**Solution :** a. This table outlines the stages of the journey.

12:00 to 12:30	Travelled 50 km in 30 minutes, so 100 km/h
12:30 to 13:00	Stopped
13:00 to 14:00	Travelled 50 km in 60 minutes, so 50 km/h
14:00 to 14:30	Stopped
14:30 to 15:00	Travelled 100 km back towards the starting point in 30 minutes, so -200 km/h

- b. Even though the whole journey was 200 km (100 km out and 100 km back) in 3 hours, the displacement for the journey (the distance from the starting point) is 0km.

So the average velocity is 0 km/h.

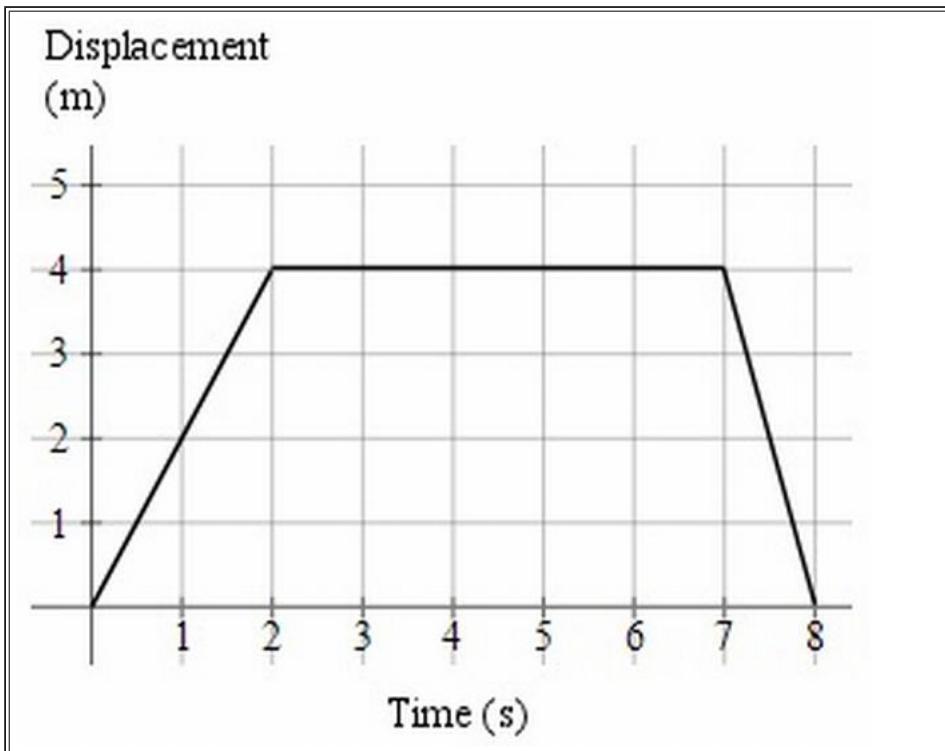
On the other hand, the average speed was  $\frac{200}{3} = 66.7 \text{ km/h}$

In summary,

$$\text{ave velocity} = \frac{\text{displacement}}{\text{time}}$$

$$\text{ave speed} = \frac{\text{distance}}{\text{time}}$$

**Example :** A particle in a magnetic field moves as follows: n.d.



Find the velocity for each part of the motion.

**Solution :**

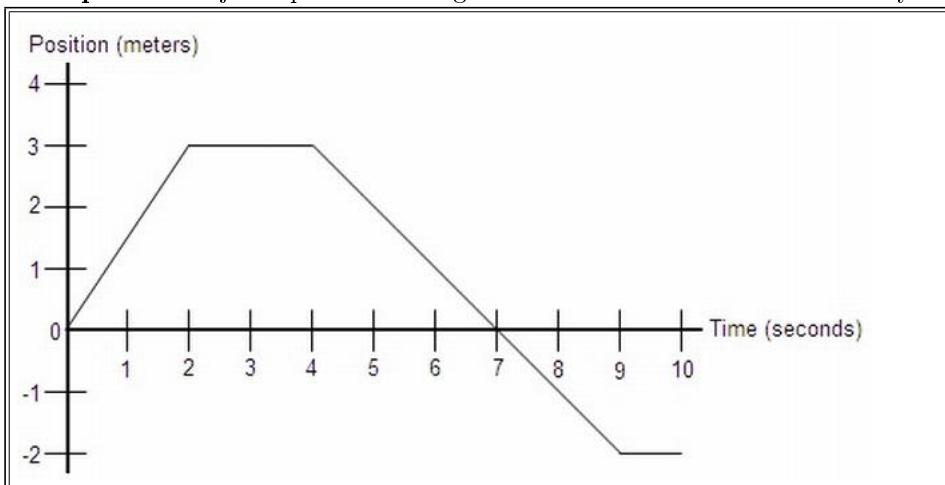
$$\text{For } t=0 \text{ to } 2: \frac{\Delta s}{\Delta t} = \frac{4}{2} = 2 \text{ ms}^{-1}$$

$$\text{For } t=2 \text{ to } 7: \frac{\Delta s}{\Delta t} = \frac{0}{5} = 0 \text{ ms}^{-1}$$

$$\text{For } t=7 \text{ to } 8: \frac{\Delta s}{\Delta t} = \frac{-4}{2} = -4 \text{ ms}^{-1}$$

(The velocity is negative, since the particle is going in the opposite direction.)

**Example :** An object's position during a 10 second time interval is shown by the graph below:



- Determine the object's total distance traveled and displacement.
- What is the object's velocity at the following times:  $t = 1$ ,  $t = 3$ , and  $t = 6$ .
- Determine the object's average velocity and average speed from  $t = 0$  to  $t = 10$ .
- What is the object's acceleration at  $t = 5$ ?

**Solution :** a.) The total distance traveled by the object is the sum of all the distances it traveled during the time interval. In the first two seconds it traveled 3 m. Then it traveled 0 m in the next two seconds. Then over the next five seconds, the object moved 5 m, then remained at rest. so the total distance is  $3 + 5 = 8$  m. The displacement of the object is simply the final position minus the initial position, or  $-2 - 0 = -2$  m.

b.) Notice that each of these points is in the middle of a line segment on the graph. Because of this, the instantaneous velocity at these points is the same as the average velocity over the time intervals represented by each segment, so:  $v(t) = (x_f - x_i)/(t_f - t_i)$   $v(1) = (3 - 0)/(2 - 0) = 3/2 = 1.5 \text{ m/s}$   $v(3) = (3 - 3)/(4 - 2) = 0/2 = 0 \text{ m/s}$   $v(6) = (-2 - 3)/(9 - 4) = -5/5 = -1 \text{ m/s}$

Notice that the formula  $(x_f - x_i)/(t_f - t_i)$  is the same as the slope formula for this graph. The velocity at

any point on a position vs. time graph is simply the slope of the graph at that point. By this definition, we also know that the velocity of any position function is its derivative with respect to time. You can also go from a velocity function to a position function using integration. Go to calculus notes

c.) Average velocity is displacement divided by time. We found in part a that the object's displacement is -2 m, so:  $v_{avg} = -2/10 = -0.2 \text{ m/s}$

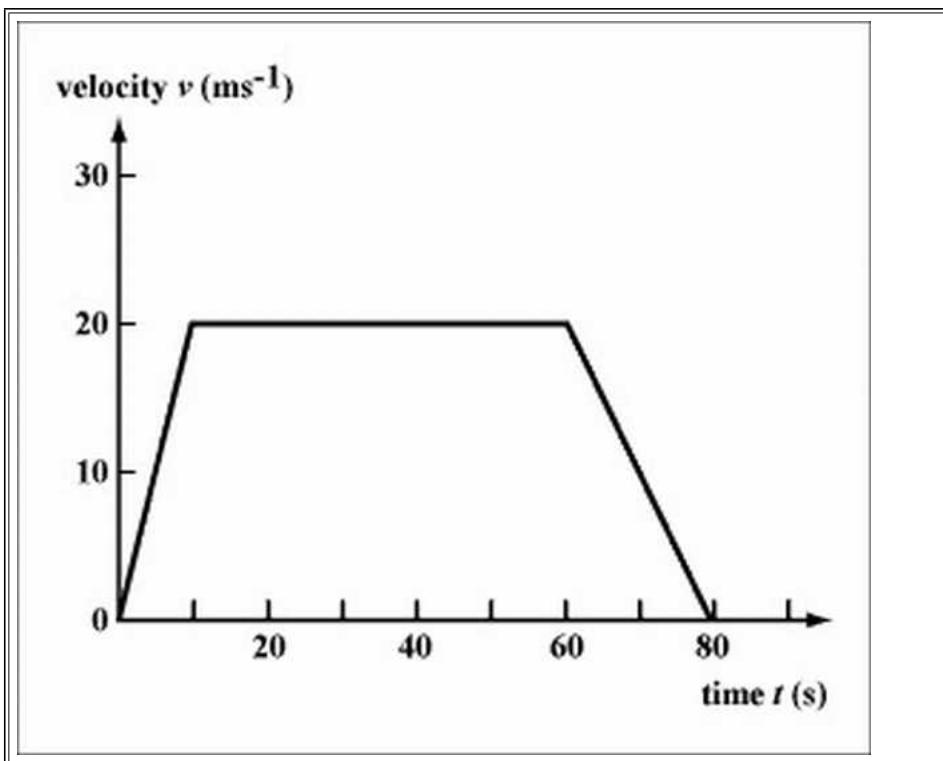
Average speed is total distance divided by time, and we found in part a that the object's total distance traveled is 8 m. so:  $8/10 = 0.8 \text{ m/s}$

d.) We determined in part b that the object's velocity is represented by the slope of the line segment on the graph. Since the slope of this segment is constant, the object's velocity at  $t = 5$  is constant. Since constant velocity means there is no acceleration,  $a = 0$ .

### 3.6.2 Problems on Velocity-Time Graph

#### 3.6.2.1 Subjective

**Example :** Fig. shows the velocity-time graph of a train travelling from station 1 to station 2. The train moves along a straight railway.



Describe the motion of the train, stating the acceleration and velocity in each stage. What is the displacement of station 2 from station 1?

**Solution :** From  $t=0$  to  $t=10\text{s}$ , the train accelerates from  $v=0$  to  $v=20\text{m/s}$ .

$$a=20/10=2 \text{ m s}^{-2}$$

From  $t=10\text{s}$  to  $t=60\text{s}$ , the train moves at a constant velocity  $v=20\text{m/s}$ .  $a=0$ .

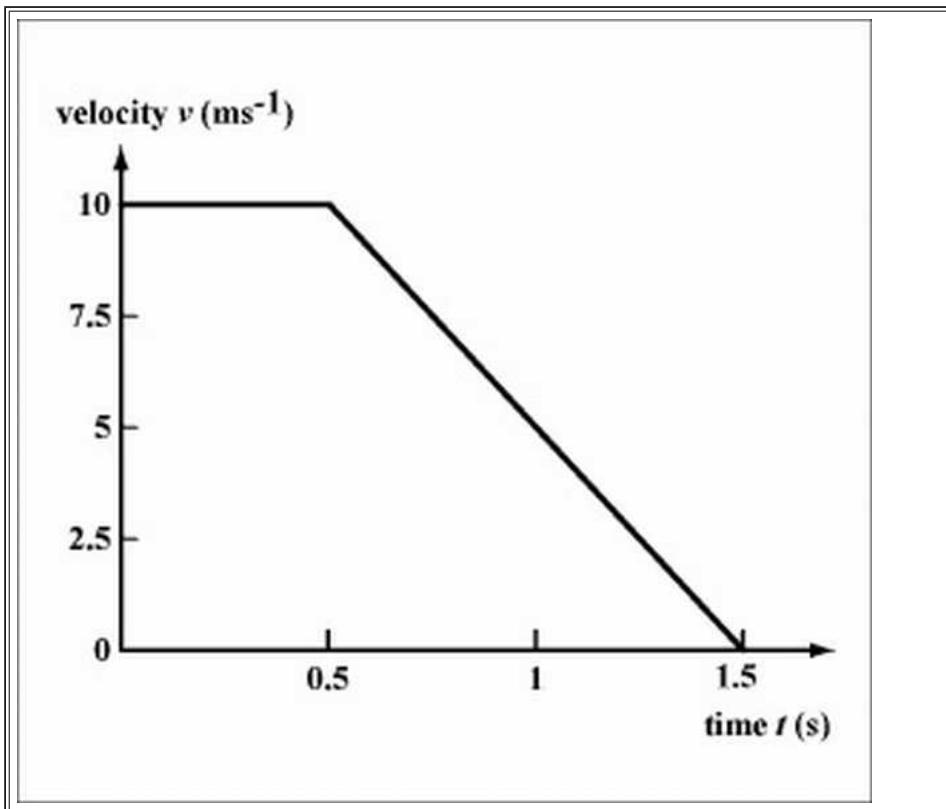
From  $t=60\text{s}$  to  $t=80\text{s}$ , the train decelerates from  $v=20\text{m/s}$  back to  $v=0\text{m/s}$ .

$$a=(0-20)/(80-60)=-1 \text{ m s}^{-2}$$

Total displacement = the area under the velocity-time graph

$$s = \frac{(80+50)}{2} \times 20 = 1300 \text{ m}$$

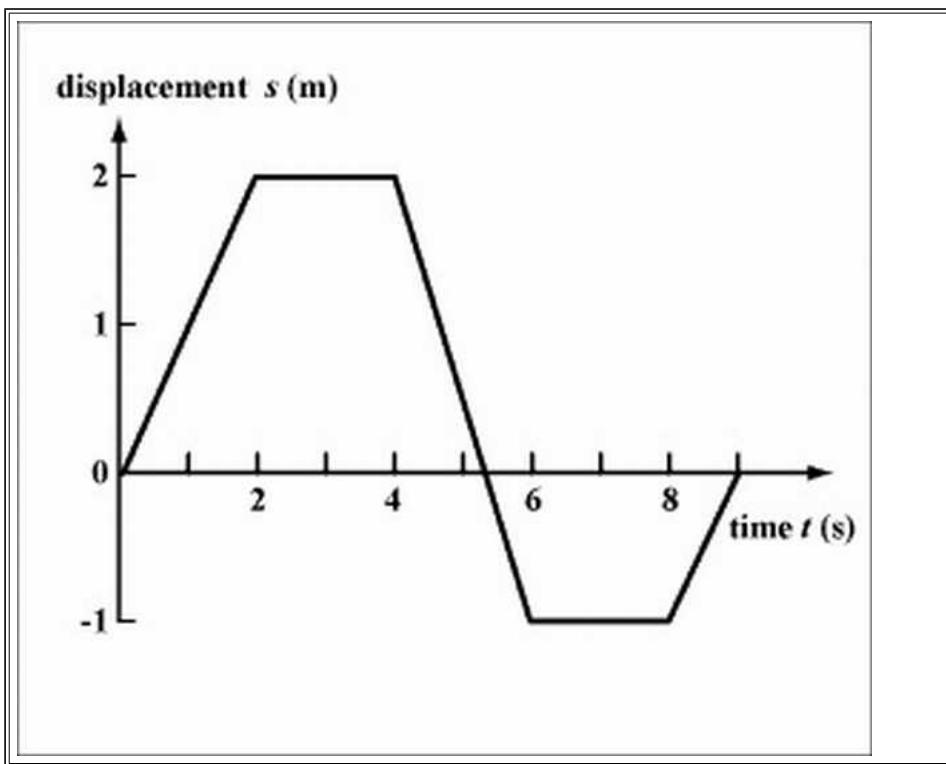
**Example :** A car is initially moving at a velocity of 36 . Suddenly the driver sees a girl running across of the road at 13 m in front of the car. It takes 0.5 s for the driver to react and start braking the car. The car then takes one more second to stop. Plot the velocity-time graph for the car, starting from the time when the driver sees the girl. What is the deceleration of the car? Would the car hit the girl?



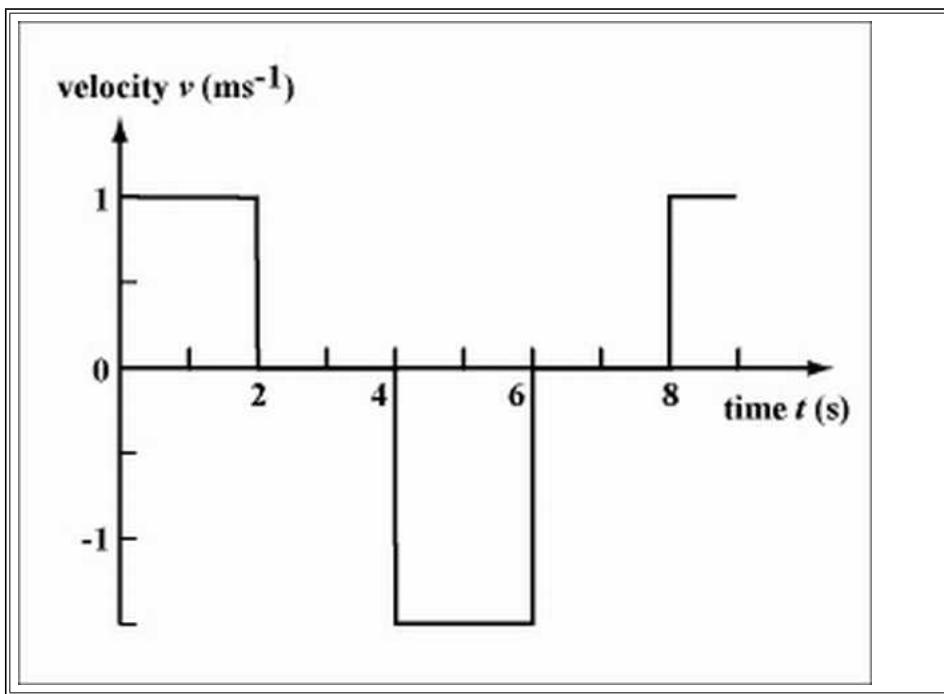
**Solution :** See Fig. . The car decelerates at  $10 \text{ ms}^{-2}$ . It travels a total distance of  $(0.5+1.5)*10/2=10\text{m}$  , so it would not hit the girl, but stop at a distance of 3 m from the girl.

**Note:** The total distance travelled by the car after the driver seeing the danger is called the stopping distance. See the next chapter for more analysis on car braking.

**Example ;** Fig. shows the displacement-time graph of an object. Plot its velocity-time graph. Find the average velocity of the object.



**Solution :** See Fig. .



Since the total displacement of the object is zero, the average velocity is also zero.

Note: The object moves backwards from  $t=4\text{ s}$  to  $t=6\text{ s}$ . In this interval, the area bounded by the velocity-time graph is negative (i.e., the area is under the time axis), indicating that the object has a displacement in the opposite direction.

**Example :** A particle in a generator is accelerated from rest at the rate of  $55 \text{ ms}^{-2}$ .

- What is the velocity at  $t=3 \text{ s}$ ?
- What is the acceleration at  $t=3 \text{ s}$ ?
- What is the distance travelled in 3 seconds?
- Graph the acceleration (as a  $v$ - $t$  graph) for  $0 \leq t \leq 3 \text{ s}$ ,  $0 \leq t \leq 3\text{s}$ .

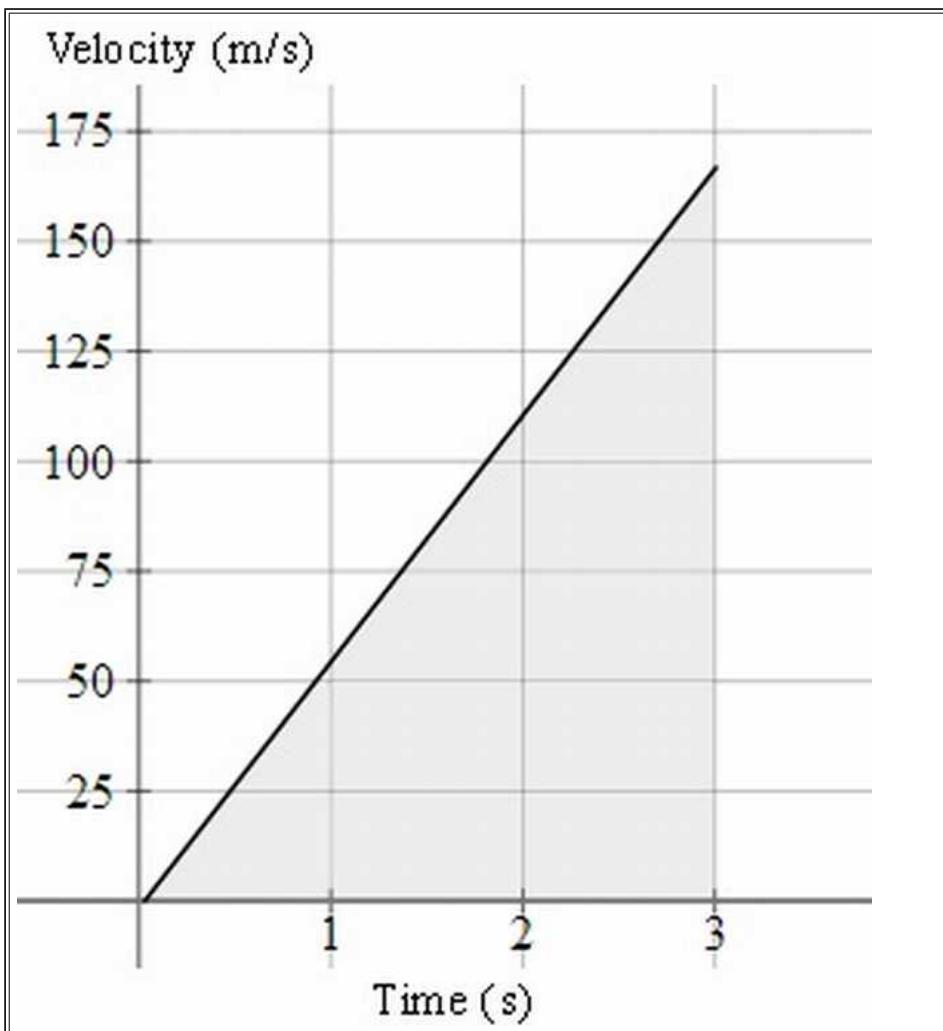
**Solution :** a. Velocity =  $55 \times 3 = 165 \text{ ms}^{-1}$

b. The acceleration is a constant  $55 \text{ ms}^{-2}$ , so at  $t=3 \text{ s}$ , the acceleration will be  $55 \text{ ms}^{-2}$ .

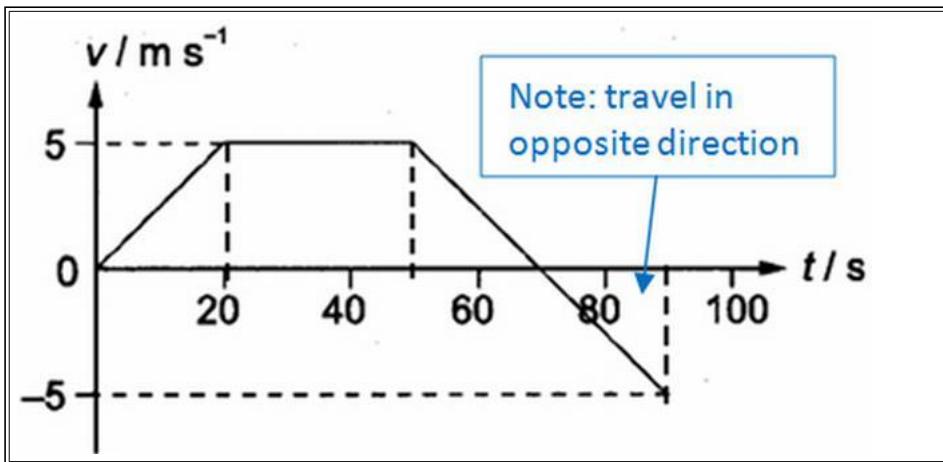
c. The distance travelled in 3 seconds is  $165 \times 1.5 = 247.5 \text{ m}$ . We obtain this from the area under the line between 0 and 3 (i.e. the area of the shaded triangle below).

d. Note in the graph that we have velocity on the vertical axis, and the units are m/s.

The graph finishes at  $(3, 165)$ .



**Example :** A girl starts from rest and travels along a straight line. The diagram below shows the velocity-time graph of the girl from 0 s to 90 s.

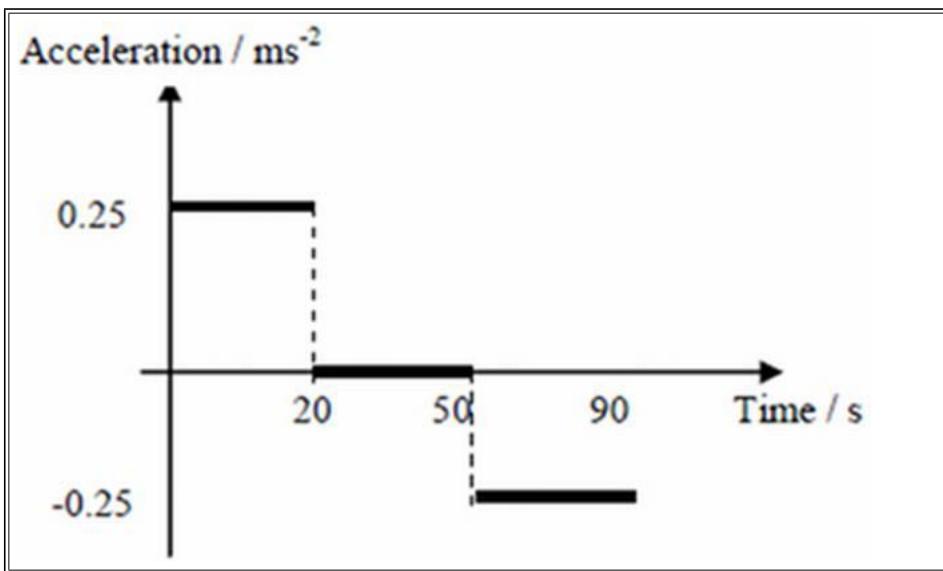


- (a) Describe the motion of the girl from 0 s to 40 s.
- (b) Find the average velocity of the girl in the first 70 s.
- (c) Draw the acceleration-time graph of the girl from 0 s to 90 s.
- (d) Find the displacement of the girl from the starting point to the position at 90 s.

**Solution :** (a) From 0 s to 20 s, she travels with constant acceleration of  $0.25 \text{ ms}^{-2}$ ; From 20 s to 40 s, she travels at constant velocity of 5 m/s.

(b) Total displacement = area under v-t graph =  $\frac{1}{2} (30 + 70) * 5 = 250 \text{ m}$  Average velocity =  $250/70 = 3.57 \text{ m/s}$

- (c) Acceleration is the gradient of v-t graph.



$$(d) \text{ Displacement} = \text{area under v-t graph} = 250 - \frac{1}{2} * 20 * 5 = 200 \text{ m}$$

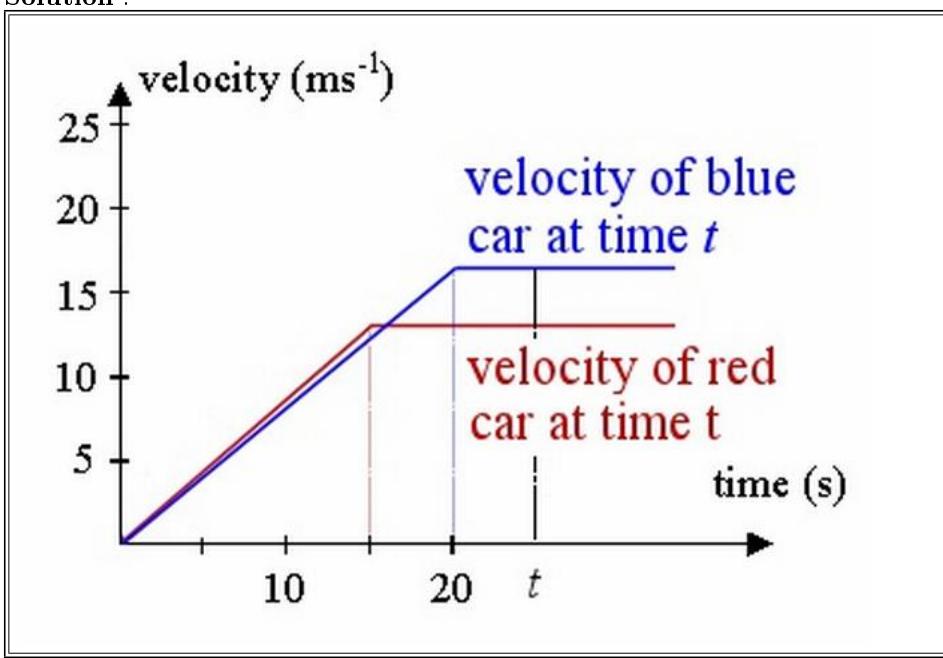
Tips: (1) It is very easy to mix up kinematics graphs. The only way to differentiate these graphs is to look at the y-axis!

(2) When describing the motion, do it region by region! And always talk about acceleration or speed / velocity with values if applicable. Refer to example above.

**Example :** Two sport cars start from rest at the same place. One of them, colored red, accelerates at  $0.90 \text{ ms}^{-2}$  for 15 s, and continues at constant speed thereafter. The other car, colored blue, accelerates at  $0.85 \text{ ms}^{-2}$  for 20 s and then remains at that speed.

Draw both journeys on the same velocity-time graph and determine the time and distance that the second car overtakes the first car.

**Solution :**



The velocities they reach are  $0.9 \times 15 = 13.5 \text{ ms}^{-1}$  and  $0.85 \times 20 = 17 \text{ ms}^{-1}$  respectively.

Similar to the problem above, we have:

First car's (red) distance at time  $t$  is found by finding the area of the trapezoid whose boundary is the t-axis, the red lines and the vertical line representing time at  $t$  seconds. This of course assumes  $t > 15$  (otherwise, we have negative distances, and the trapezoid only starts at  $t=15$ .)

$$\text{So the distance (at time } t\text{)} = \frac{1}{2} \times 13.5(t + t - 15)$$

= The distance of the second car (blue) is found by finding the area of the blue trapezoid, bounded by the blue lines, the t-axis and the vertical line. (And this one assumes  $t > 20$ , for the same reasons as above.)

$$\text{So the distance (at time } t\text{)} = \frac{1}{2} \times 17(t + t - 20)$$

The distance when they meet is the same, so:

$$\frac{1}{2} \times 13.5 \times (2t - 15) = \frac{1}{2} \times 17 \times (2t - 20)$$

Solving gives:

Time = 19.643 s

Distance = 163.93 m

Dilemma

However, this solution gives us a dilemma. As mentioned above, the expressions we found for the area of the trapezoids required  $t$  to be more than 15 s and 20 s, respectively.

We can confirm the blue car overtakes the red car before 20 seconds, by calculating the distances travelled at that time.

After 20 seconds:

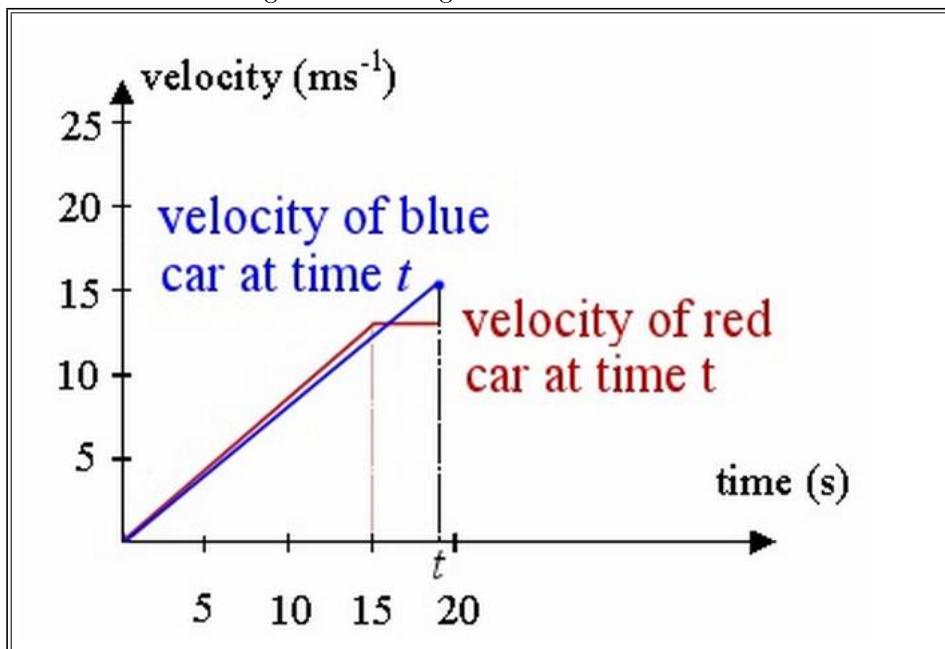
Red car has travelled  $0.5 \times (20+5) \times 13.5 = 168.75$  m

Blue car has travelled  $0.5 \times 20 \times 17 = 170$  m The blue car has travelled further than the red car, so it means it has already overtaken the red car.

Back to the drawing board

So, in fact, for this question we need to consider the area of the blue triangle, not the blue trapezoid.

This is the correct diagram for finding  $t$ :



The red car's distance is fine from before (it's a trapezoid):

$$d = \frac{1}{2} \times 13.5 \times (t + t - 15)$$

But the blue car's distance at  $t$  is the area of the triangle (not trapezoid) bounded by the blue line and the vertical line at  $t$  (we are taking  $\frac{1}{2}$  base times height):

$$\text{distance} = \frac{1}{2} \times t \times 0.85 \times t$$

Equating these gives:

$$6.75(2t - 15) = 0.425t^2$$

Solving gives:

$$t = 12.14 \text{ s}, t = 19.63 \text{ s}$$

The first solution has no practical meaning, since  $t > 15$  for the expression to work.

So we conclude the time taken for the blue car to overtake the red car is 19.63 s and the distance travelled at that time is 163.7 m.

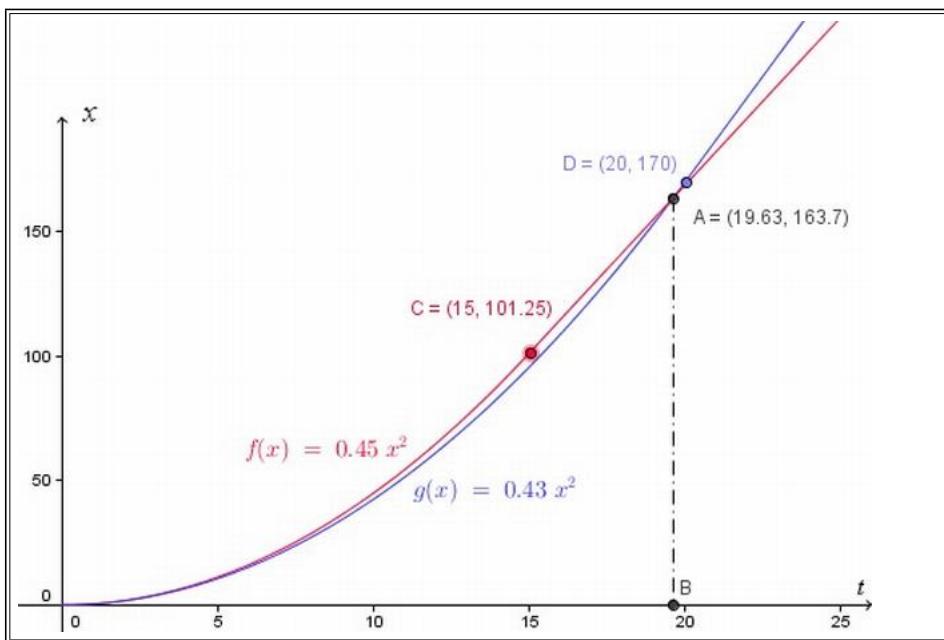
Further Information

To illustrate we have found the correct answer, below is the graph of distance against time. Labelling of axes is very important in this work!

The red curve corresponds to the acceleration portion of the first race car. At  $t=15$ , or point C(15,101.25), the red car stops accelerating and continues at a constant speed (CA is no longer a curve, but a straight line).

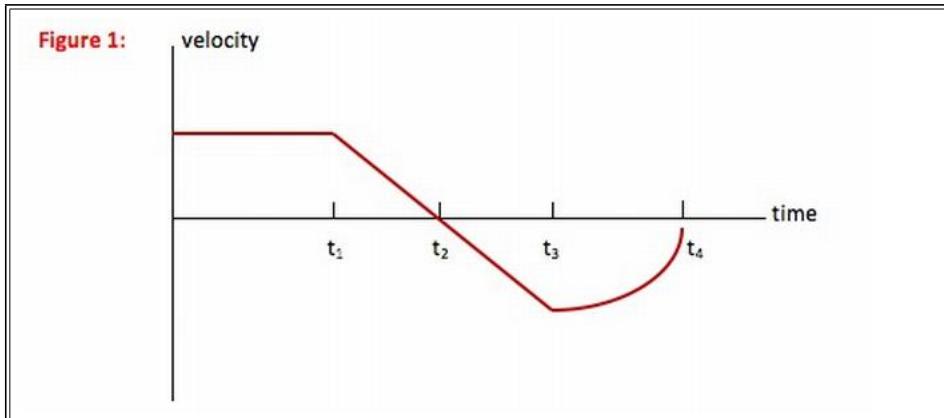
The blue curve corresponds to the second (blue) car. It doesn't accelerate as hard (its curve is below the red curve, indicating it covers less distance in the same time), but it accelerates for longer. At  $t=20$ , or point D(20,170), it stops accelerating and its graph is now a straight line.

We can see the curves intersect at time  $t=19.63$  s, or point A (19.63, 163.7), as we found in the calculation above. This means they have covered the same distance (163.7 m) at that time, so that's when the blue car passes the red car.



### 3.6.2.2 Miscellaneous

**Example :** You drive a car in such a way that its motion is described by the velocity-time graph shown here. Draw the displacement-time and acceleration-time graphs that correspond to this motion, and describe in words how the car moves. n.d.



**Solution :** (Hint : In this problem, you are asked to describe the motion of the car. Whenever you are asked to describe the motion of an object without worrying about the cause of that motion, you have a kinematics problem. This problem is different from most kinematics problems, however, in that you are not asked for a numerical description but rather to use words and graphs to describe how the car moves.)

(Queries : How did you know that  $x = 0$  at  $t = 0$ ?

You don't! If you are given a velocity-time graph, you know the initial speed but not the initial location of the object. (Calculus students, remember  $v = dx/dt$ , and the derivative of a constant—your initial location—is zero.) I chose to call the location of the car at  $t = 0$  the origin, but you could start your graph at any point. The shape of the graph, however, should look the same.

Why can't I treat the straight line from  $t_1$  to  $t_3$  in a single step?

Any time velocity is above the t-axis, it has a positive value and so slope of the x-t graph is also positive. A positive slope means that the line or curve is in such a direction as to make between a 0 and a 90° angle above the +x axis. Any time velocity is below the t-axis, it has a negative value and so the slope of the x-t graph is also negative. A negative slope means that the line or curve is in such a direction as to make between a 0 and a 90° angle below the +x axis.

Why doesn't the line from  $t_3$  to  $t_4$  look more curved?

As the velocity-time curve gets closer and closer to  $v = 0$  (the t-axis), velocity's value is getting smaller regardless of direction. As the value of  $v$  decreases, so does the slope of the x-t graph. A decreasing slope means that the slope gets smaller and smaller—the line gets becomes more horizontal.

The curve from  $t_3$  to  $t_4$  on the x-t graph shown here doesn't look very curved. This is because its slope goes from the same value as it ended with on the  $t_2$  to  $t_3$  curve to almost zero (a horizontal line) and so not a lot of change as I have drawn it. Any line you draw that curves down and to the right becoming more horizontal as it goes is fine.)

Select a relation

To go between a velocity-time graph and a displacement-time or acceleration-time graph, you need to understand how velocity, displacement and acceleration are related to each other. In other words, you need to use the definitions of velocity and acceleration:

$v = \Delta x / \Delta t$  In words, the value of velocity = the slope of the x-t graph.

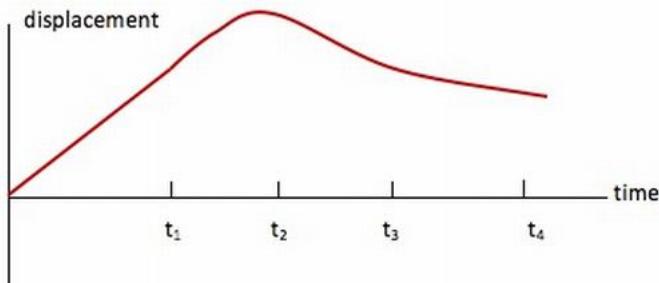
$a = \Delta v / \Delta t$  In words, the value of acceleration = the slope of the v-t graph.

Hint: Graphing problems seem like they should be straightforward, and the equations that you need are only those given above. It is very, very common, however, to make mistakes on these problems because it feels like the graphs should be pictures of the motion and they are not. In order to avoid those mistakes, make a table based on the sentences above and then draw the graph from the table.

Displacement-Time Graph

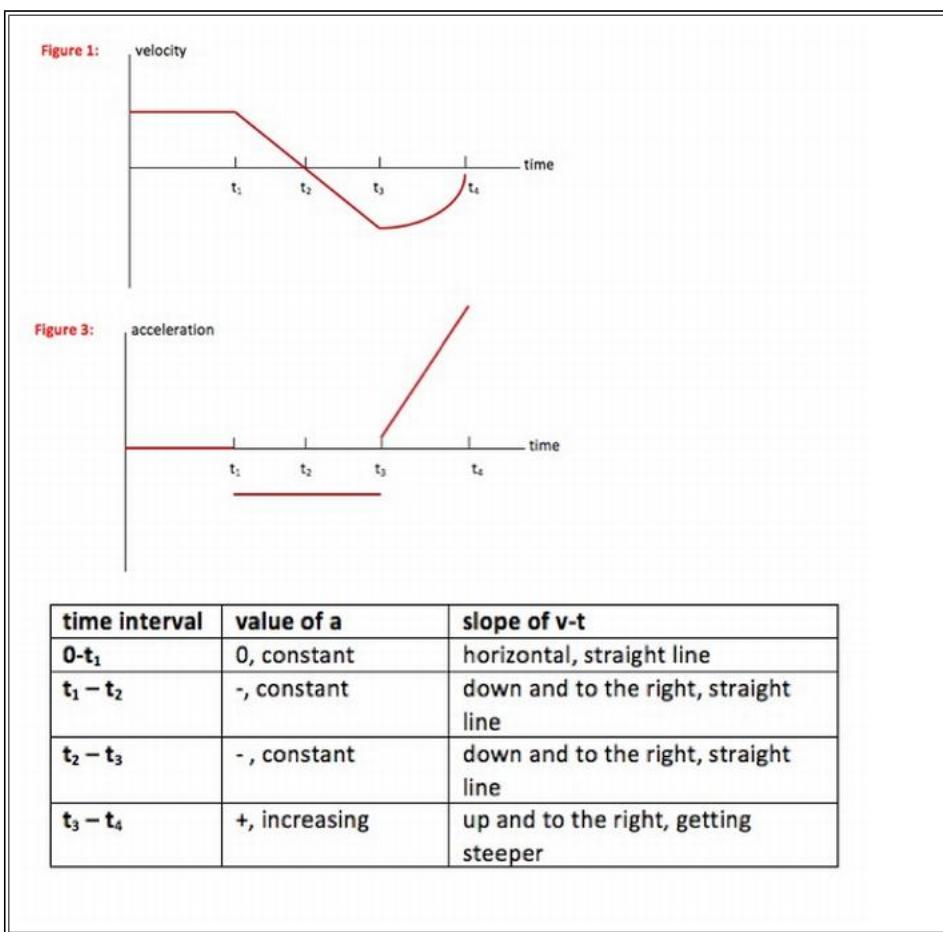
time interval	value of v	slope of x-t
$0-t_1$	+, constant	up and to the right, straight line
$t_1 - t_2$	+, decreasing	up and to the right, getting shallower
$t_2 - t_3$	-, increasing	down and to the right, getting steeper
$t_3 - t_4$	-, decreasing	down and to the right, getting shallower

Figure 2:



Once you understand the displacement-time graph, continue down to the acceleration-time graph.

Acceleration-time Graph



### Understand

In this problem, you are given the velocity-time graph for the motion of a car. By relating the value of velocity to the slope of the x-t graph (this is just the definition of velocity) you are able to draw the x-t graph corresponding to this motion.

By relating the slope of the v-t graph to the value of acceleration (this is just the definition of acceleration) you are able to draw the a-t graph corresponding to this motion.

You can describe the motion looking at any of the three graphs. From  $t = 0$  to  $t_1$  : The car travels forward (+ direction) with a constant speed. There is no acceleration and the car moves away from its starting point at a constant rate.

From  $t_1$  to  $t_2$  : The car slows to a stop at a constant rate. It is still moving forward, but the amount of distance it covers in each second is decreasing. Acceleration acts against the motion of the car, or in the negative direction.

From  $t_2$  to  $t_3$  : The car reverses direction, moving faster and faster (at a constant acceleration) in the negative direction. Acceleration is acting with the motion of the car, so it is also in the negative direction. The amount of distance the car covers each second increases.

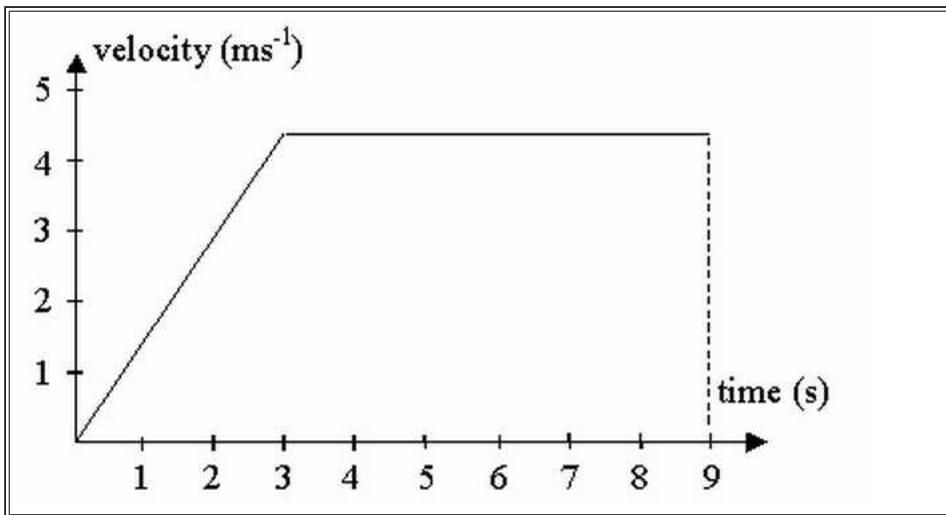
From  $t_3$  to  $t_4$  : The car continues to move in the negative direction but at a decreasing speed. The rate at which the speed decreases is getting greater—the driver is braking harder as the car stops—and so acceleration increases. Acceleration is acting against the motion of the car, or in the positive direction. The car covers less and less distance each second.

### 3.6.3 Problems on Area Under v-t graph

**Example :** A charged particle in an accelerator starts from rest, accelerates at  $1.5 \text{ ms}^{-2}$  for 3 s and then continues at a steady speed for a further 6 s.

Draw the v-t graph and find the total distance travelled.

**Solution:**



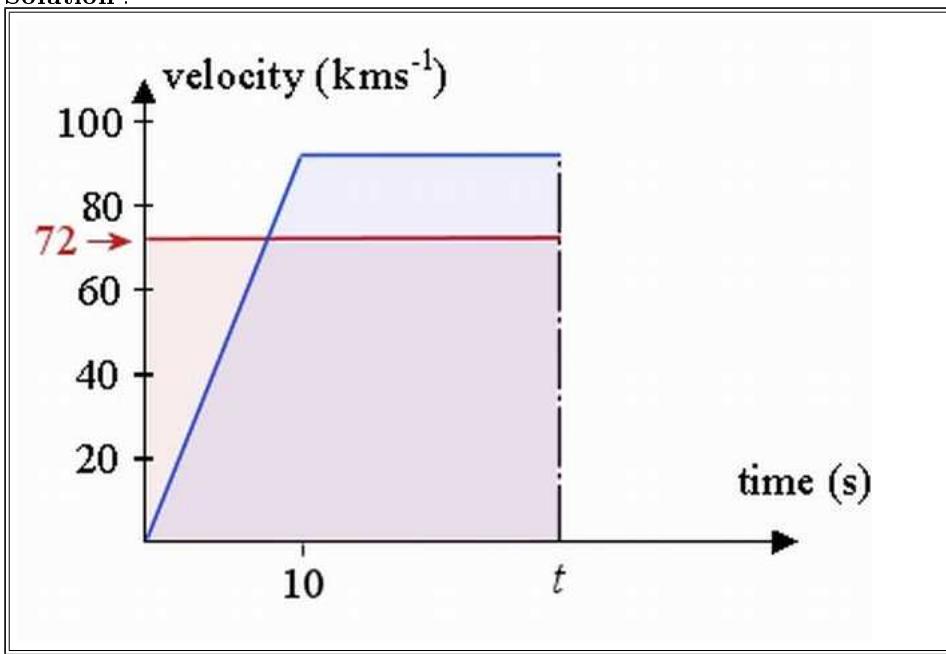
Total distance travelled is the area under the graph (in this case we need to find the area of a trapezium).

$$\begin{aligned} \text{distance} &= \frac{(a+b)h}{2} \\ &= \frac{(9+6) \times 4.5}{2} \\ &= 33.75 \text{ m} \end{aligned}$$

**Example :** A car is travelling at a constant speed of 72 km/h and passes a stationary police car. The police car immediately gives chase, accelerating uniformly to reach a speed of 90 km/h in 10 s and continues at this speed until he overtakes the other car. Find:

- (a) the time taken by the police to catch up with the car,
- (b) the distance travelled by the police car when this happens.

**Solution :**



The v-t curve for the car is represented by the red line, while that v-t curve for the police car is the blue line.

We need to find the unknown time  $t$  (in seconds), when the police catch up to the car. We find this by comparing the distance travelled by each (it will be the same distance at the overtaking point.) So we need to set the area under the v-t curve for the car (the pink shaded area) to be equal to the area under the v-t curve for the police car (the blue shaded area).

- a. The area under the curve for the car at time  $t$  (in seconds) is simply  $72t$ . (It is a rectangle, 72 high and width  $t$ ).

The area under the trapezoid (trapezoid) for the police car at unknown time  $t$ , using  $A = (a+b) \frac{h}{2}$  is:

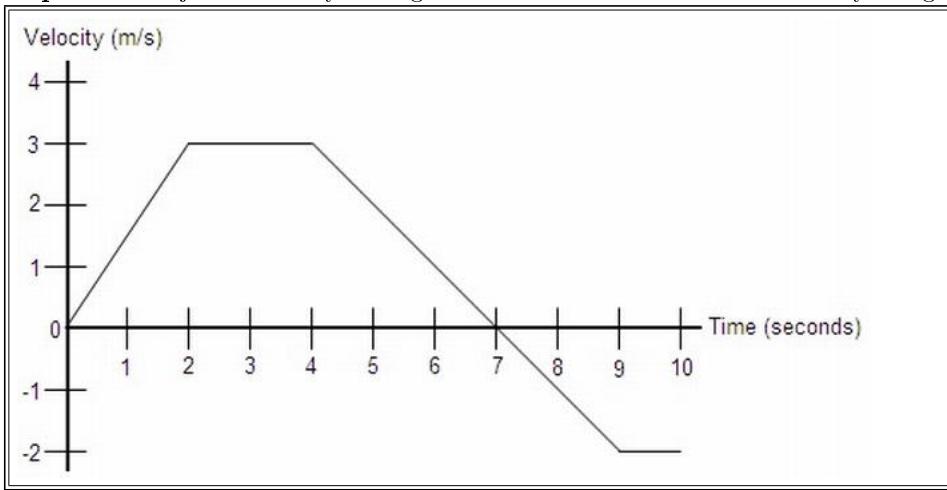
$$(t+t-10) \times \frac{90}{2} = 45(2t-10)$$

We set these equal to find the required time:  $72t = 45(2t-10)$  That is, when  $72t = 90t - 450$  So  $t = 25$  s will be the time the police car catches up.

- b. Both of the cars have travelled  $72 \times (\frac{25}{3600}) \times 1000 = 500$  m during those 25 s.  
 [We have used  $d=s \times t$  and converted from seconds to hours (since the velocities are given in km/h).]

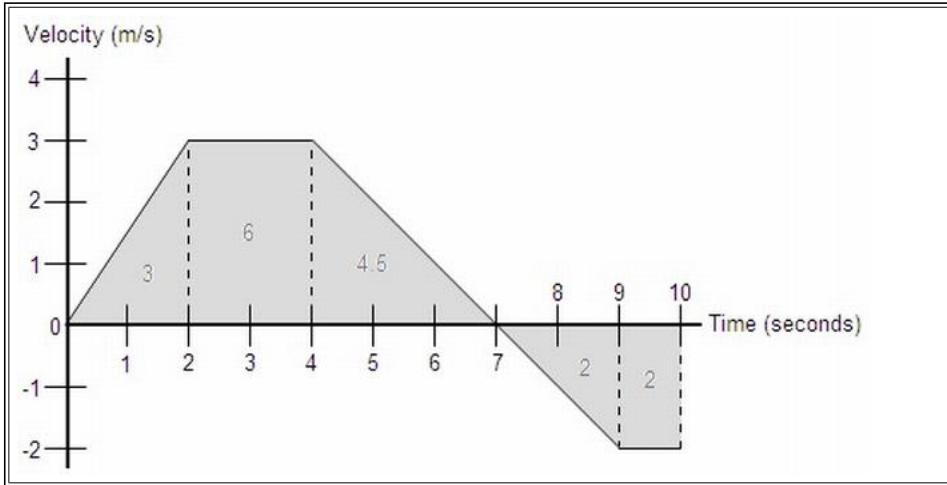
### 3.6.4 Problems on Average Velocity

**Example :** An object's velocity during a 10 second time interval is shown by the graph below:



- a.) Determine the object's total distance traveled and displacement.
- b.) At  $t = 0$ , the object's position is  $x = 2$  m. Find the object's position at  $t = 2$ ,  $t = 4$ ,  $t = 7$ , and  $t = 10$ .
- c.) What is the object's acceleration at the following times:  $t = 1$ ,  $t = 3$ , and  $t = 6$ .
- d.) Sketch the corresponding acceleration vs. time graph from  $t = 0$  to  $t = 10$ .

**Solution :** a.) Recall that the equation for velocity is  $v = x/t$ . If we solve this for  $x$ , we get  $x = vt$ . Notice that this is the same as the area of a rectangle whose sides are lengths  $v$  and  $t$ , so we can determine that the displacement is the area enclosed by the velocity vs. time graph. So, we will find the area of each section under the graph:



The total distance traveled by the object is simply the sum of all these areas:  $3 + 6 + 4.5 + 2 + 2 = 17.5$  m. The displacement is found in a similar fashion, except areas below the x-axis are considered negative:  $3 + 6 + 4.5 - 2 - 2 = 9.5$  m. Interestingly enough, the area enclosed by any function can be represented by a definite integral. For example, if this graph were defined as a function  $v(t)$ , then the displacement would be the integral from 0 to 10 of  $v(t)dt$ , and the total distance traveled would be the integral from 0 to 10 of  $|v(t)|dt$ . Go to calculus notes

b.) The position of the object at a given point in time can be found in much the same way we found the displacement in part a, except this time we must also add in the initial value given. So:  $x(2) = 2 + 3 = 5$  m  $x(4) = 2 + 3 + 6 = 11$  m  $x(7) = 2 + 3 + 6 + 4.5 = 15.5$  m  $x(10) = 2 + 3 + 6 + 4.5 - 2 - 2 = 11.5$  m

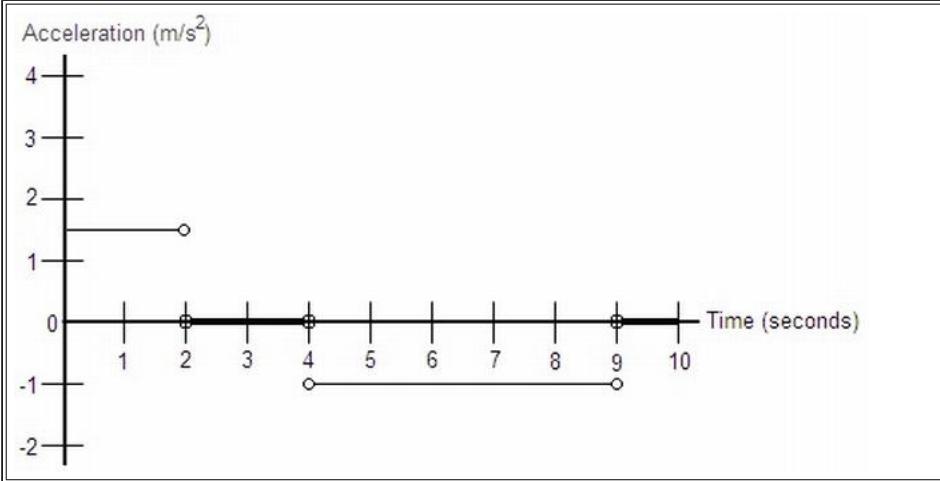
Notice that this can also be done by adding the integral from 0 to  $t$  of  $v(t)dt$  to the initial value of 2. Go to calculus notes

c.) Like velocity in part b of problem 22, the instantaneous acceleration at any point along one of the graph's line segments is the same as the average acceleration across that line segment. The formula for acceleration is  $a_{avg} = \Delta v / \Delta t = (v_f - v_i) / (t_f - t_i)$ , so:  $a(1) = (3 - 0) / (2 - 0) = 3/2 = 1.5$  m/s<sup>2</sup>  $a(3) = (3 - 3) / (4 - 2) = 0/2 = 0$  m/s<sup>2</sup>  $a(6) = (-2 - 3) / (9 - 4) = -5/5 = -1$  m/s<sup>2</sup>

Similarly to the relationship between velocity and position, the formula for acceleration is the same as the slope formula for a velocity vs. time graph. So, we can say that the slope of any velocity vs. time graph is its

acceleration. Notice that this definition defines acceleration as the derivative of velocity. So, it is true that for any velocity function  $v(t)$ , its derivative is an acceleration function  $a(t)$ . Also, integration can be used to go from an acceleration function to a position function. Go to calculus notes

d.) We know that the acceleration along each line segment of this velocity vs. time graph is equal to the slope of the line segment. We determined these slopes in part c, so the acceleration graph would look like:

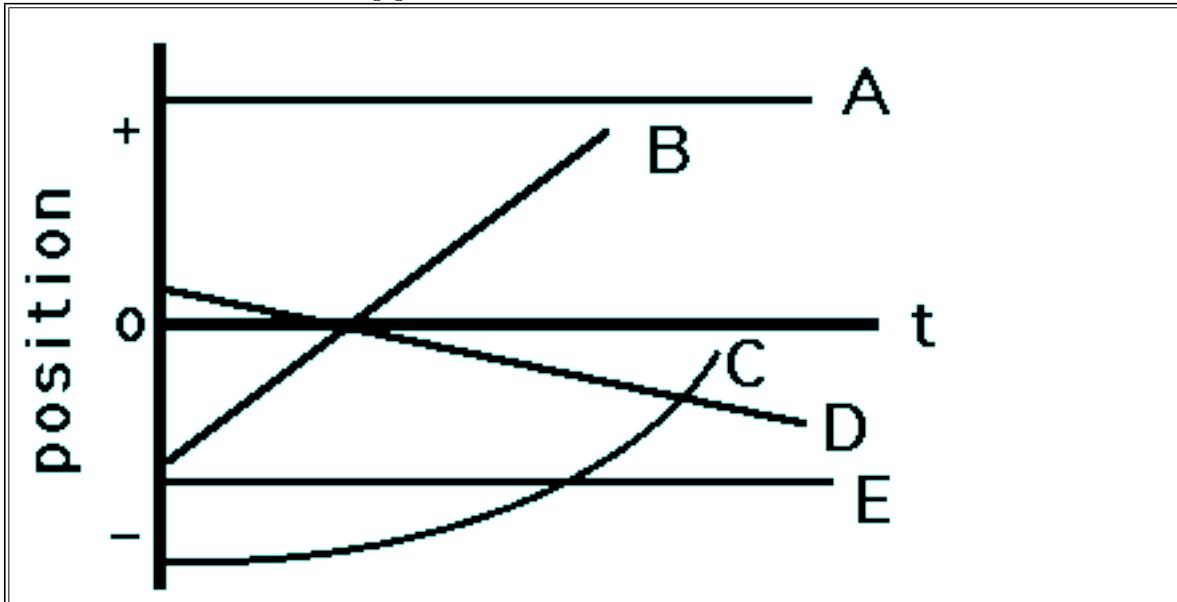


This graph uses horizontal lines instead of points to represent that the acceleration is defined at that value at any point along that section. The open circles at the end of each line segment simply indicate that at those time values, acceleration is not defined at either value represented by the horizontal lines. At these points, acceleration is undefined because it changes instantaneously from one value to the next, which cannot be represented numerically.

# Chapter 4

## Few Basic Problems

**Problem Set 1** Use the following graph to answer Questions #1 - #7.



1. Which object(s) is(are) maintaining a state of motion (i.e., maintaining a constant velocity)?

Answer : Objects A, B, D, and E.

Objects A, B, D, and E are maintaining a state of motion (i.e., remaining with constant velocity) as demonstrated by the constant slope. If the slope is constant, then the velocity is constant.

2. Which object(s) is(are) accelerating?

Answer : Object C

Object C is accelerating. An accelerating object has a changing velocity. Since the slope of a p-t graph equals the velocity, an accelerating object is represented by a changing slope.

3. Which object(s) is(are) not moving?

Answer : Objects A and E.

Objects A and E are not moving. An object which is not moving has a zero velocity; this translates into a line with zero slope on a p-t graph.

4. Which object(s) change(s) its direction?

Answer : None of the objects change direction.

None of these objects change direction. An object changes its direction if it changes from a + to a - velocity (or vice versa). This translates into a p-t graph with a + slope and then a - slope (or vice versa).

5. On average, which object is traveling fastest?

Answer : Object B.

Object B is traveling fastest. To be traveling fastest is to have the greatest speed (or greatest magnitude of velocity). This translates into the line on a p-t graph with the greatest slope.

6. On average, which moving object is traveling slowest?

Answer : Object D.

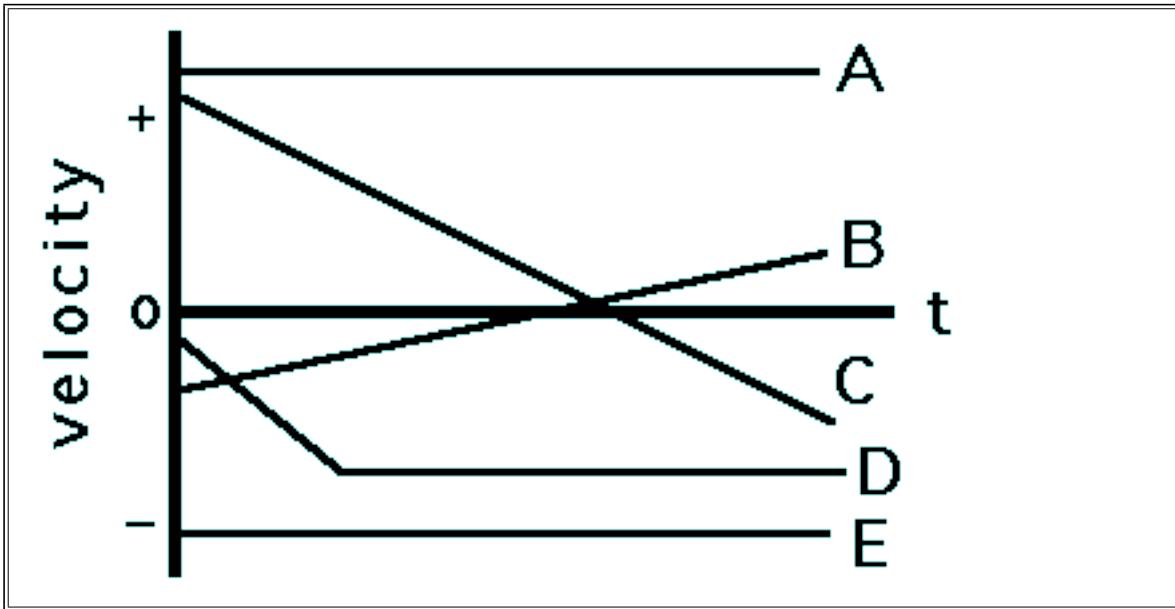
Object D is traveling slowest. To be traveling slowest is to have the smallest speed (or smallest magnitude of velocity). This translates into the line on a p-t graph with the smallest slope.

7. Which object has the greatest acceleration?

Answer ; Object C.

Object C has the greatest acceleration. It is the only object with an acceleration. Accelerated motion on a p-t graph is represented by a curved line.

**Problem Set 2** Use the following graph to answer Questions #8 - #13.



8. Which object(s) is(are) maintaining its state of motion?

Answer : Objects A and E.

Objects A and E are maintaining their state of motion. To maintain the state of motion is to keep a constant velocity (i.e., to have a zero acceleration). This translates into a zero slope on a v-t graph.

9. Which object(s) is(are) accelerating?

Answer : Objects B and C (and D during the first part of its motion).

Objects B and C are accelerating (and for a while, object D). Accelerated motion is indicated by a sloped line on a v-t graph.

10. Which object(s) is(are) not moving?

Answer : Each of the objects are moving.

Each of the objects are moving. If an object were not moving, then the v-t graph would be a horizontal line along the axis ( $v = 0 \text{ m/s}$ ).

11. Which object(s) change(s) its direction?

Answer : Objects B and C.

Objects B and C change their direction. An object that is changing its direction is changing from a + to a - velocity. Thus, the line on a v-t graph will pass from the + to the - region of the graph. Object D is not changing its direction; object D first moves in the - direction with increasing speed and then maintains a constant speed.

12. Which accelerating object has the smallest acceleration?

Answer : Object B.

Object B has the smallest acceleration. Acceleration is indicated by the slope of the line. The object with the smallest acceleration is the object with the smallest slope.

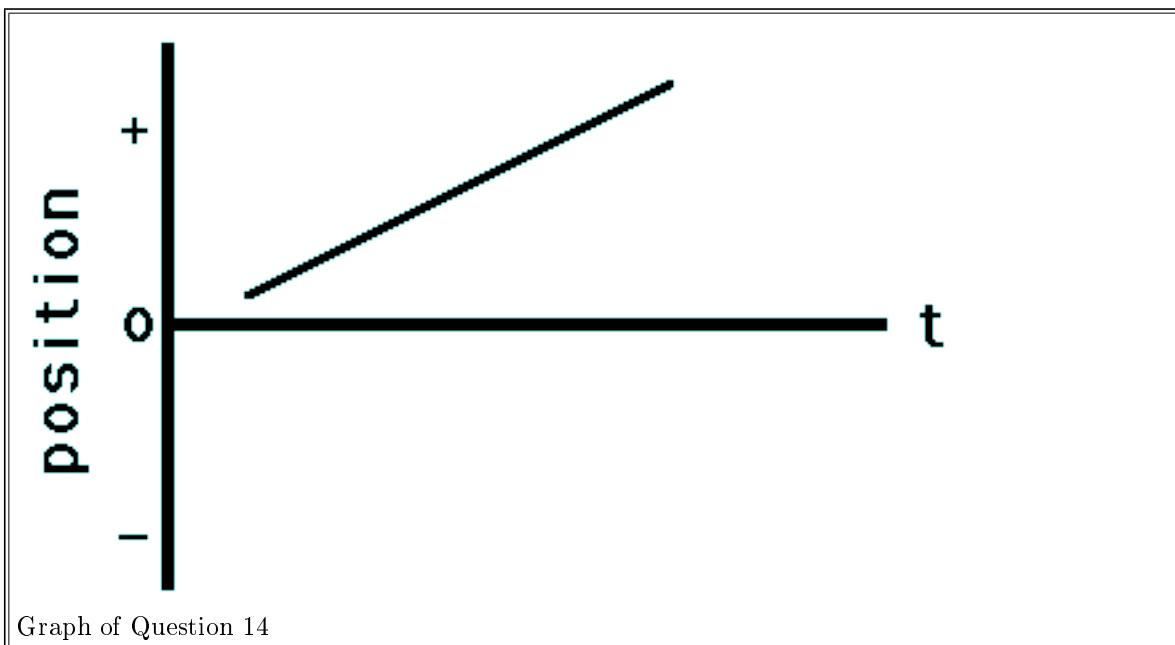
13. Which object has the greatest velocity?

Answer : Object A (E is a close second place).

Object A has the greatest velocity (and object E is a "close second"). The velocity is indicated by how far above or how far below the axis the line is. Object A has a large + velocity. Object E has a large (but not as large) - velocity.

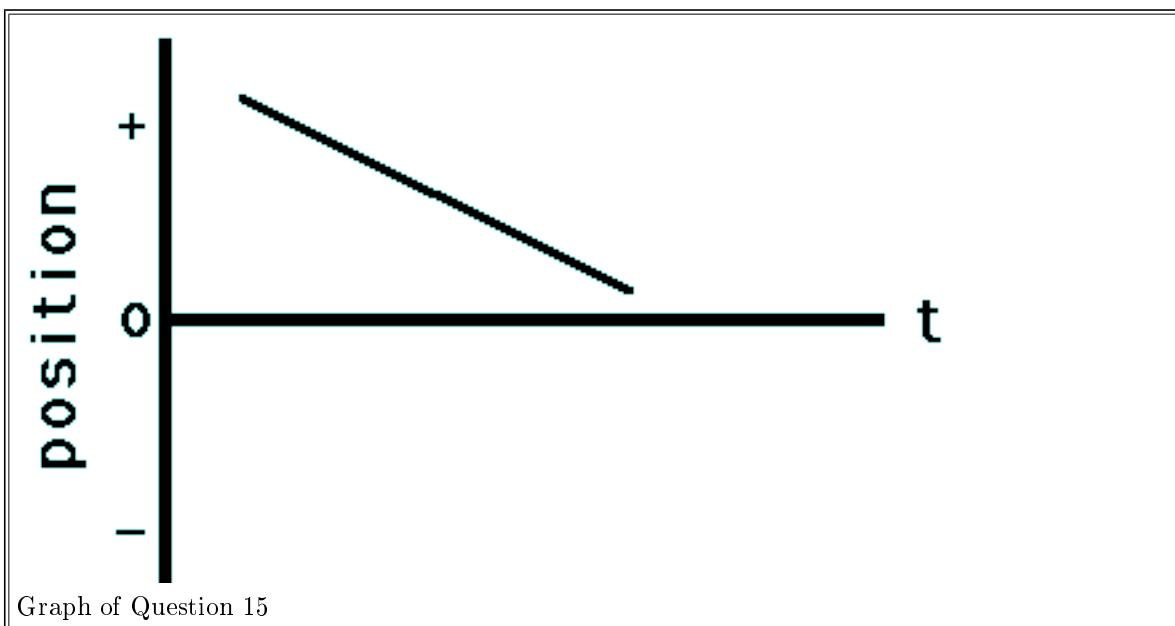
**Problem Set 3** 14. Sketch a position-time graph for an object which is moving with a constant, positive velocity.

Answer : A position-time graph for an object which is moving with a constant, positive velocity is shown below. A positive, constant velocity is represented by a line with constant slope (straight) and positive slope (upwards sloping).



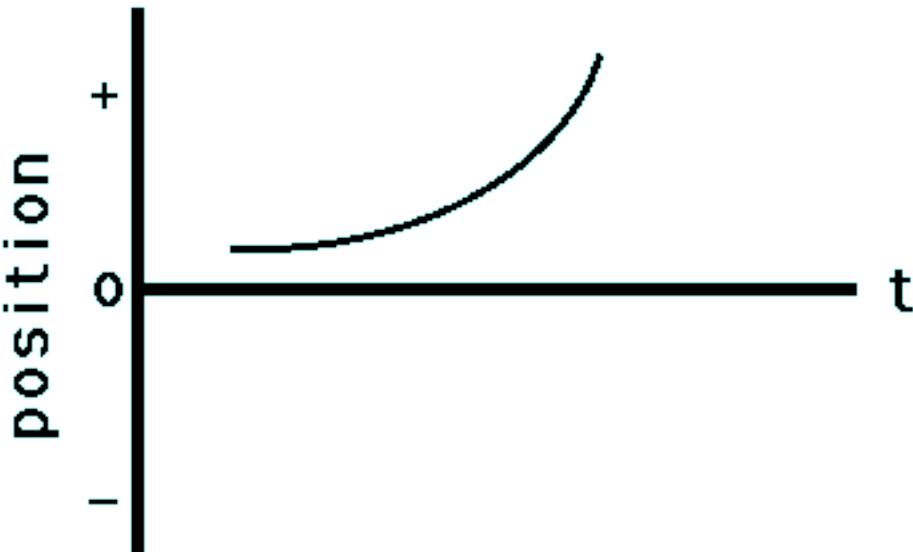
15. Sketch a position-time graph for an object which is moving with a constant, negative velocity.

Answer : A position-time graph for an object which is moving with a constant, negative velocity is shown below. A negative, constant velocity is represented by a line with constant slope (straight) and negative slope (downwards sloping).



16. Sketch a position-time graph for an object moving in the + dir'n and accelerating from a low velocity to a high velocity.

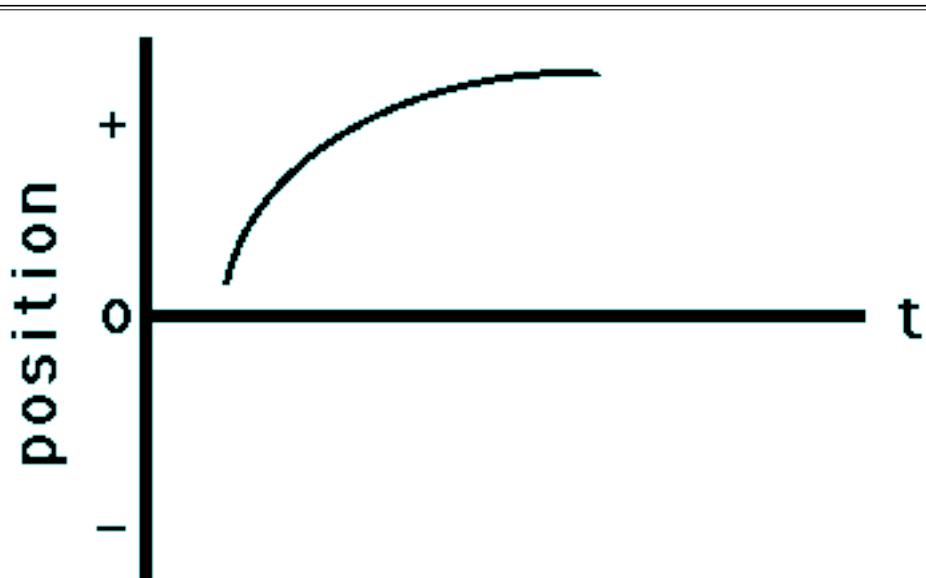
Answer : A position-time graph for an object moving in the + dir'n and accelerating from a low velocity to a high velocity is shown below. If the object is moving in the + dir'n, then the slope of a p-t graph would be +. If the object is changing velocity from small to large values, then the slope must change from small slope to large slope.



Graph of Question 16

17. Sketch a position-time graph for an object moving in the + dir'n and accelerating from a high velocity to a low velocity.

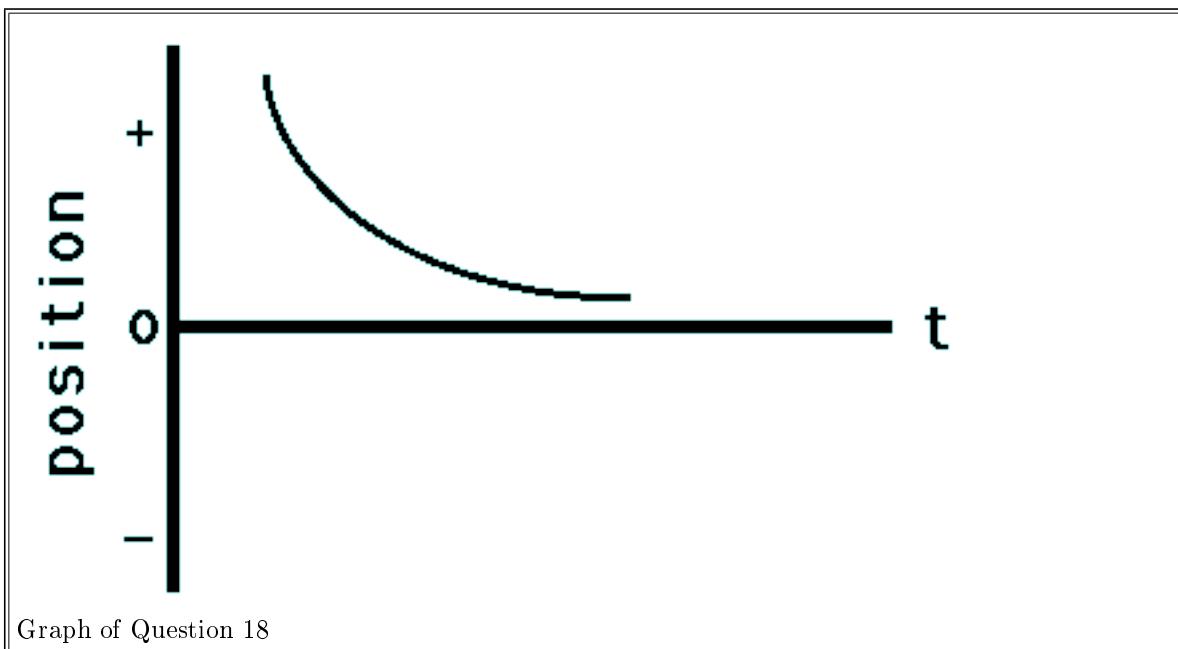
Answer : A position-time graph for an object moving in the + dir'n and accelerating from a high velocity to a low velocity is shown below. If the object is moving in the + dir'n, then the slope of a p-t graph would be +. If the object is changing velocity from high to low values, then the slope must change from high slope to low slope.



Graph of Question 17

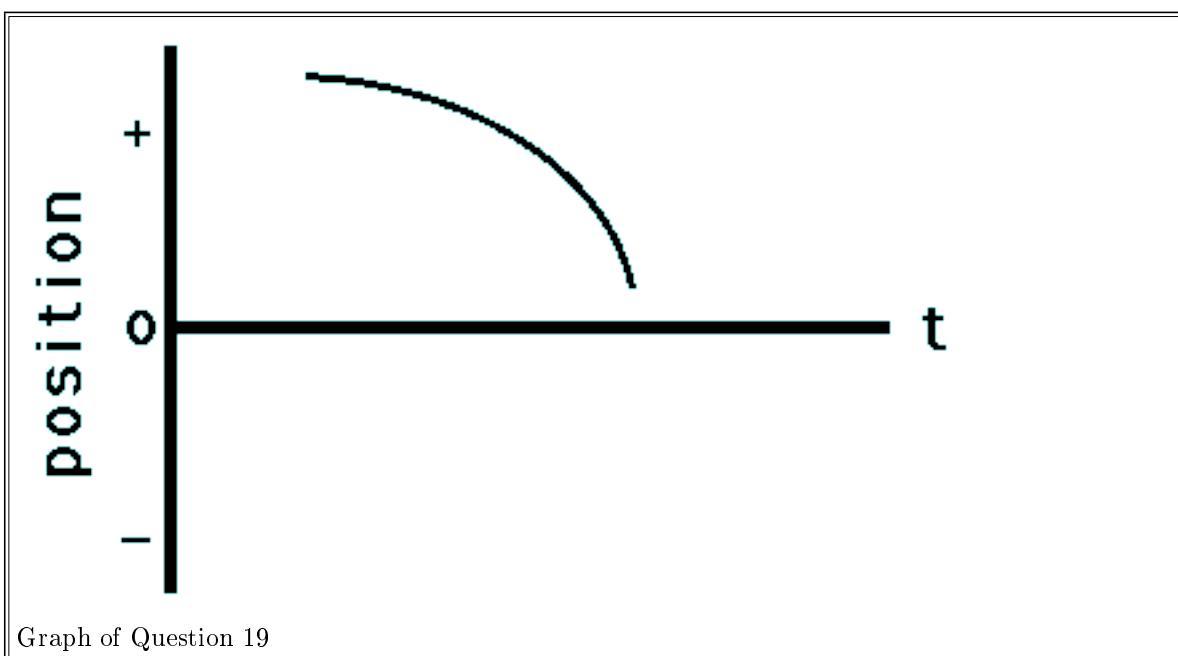
18. Sketch a position-time graph for an object moving in the - dir'n and accelerating from a high velocity to a low velocity.

Answer : A position-time graph for an object moving in the - dir'n and accelerating from a high velocity to a low velocity is shown below. If the object is moving in the - dir'n, then the slope of a p-t graph would be -. If the object is changing velocity from high to low values, then the slope must change from high slope to low slope.



19. Sketch a position-time graph for an object moving in the - dir'n and accelerating from a low velocity to a high velocity.

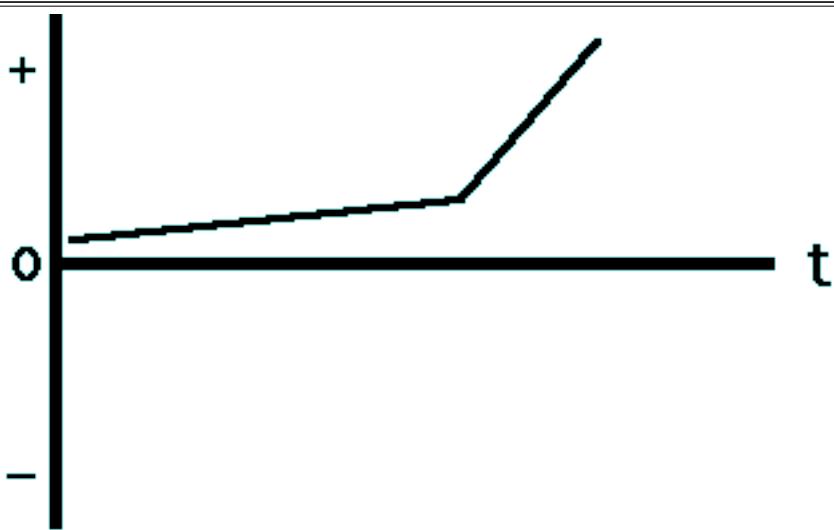
Answer : A position-time graph for an object moving in the - dir'n and accelerating from a low velocity to a high velocity is shown below. If the object is moving in the - dir'n, then the slope of a p-t graph would be -. If the object is changing velocity from low to high values, then the slope must change from low slope to high slope.



20. Sketch a position-time graph for an object moving in the + dir'n with constant speed; first a slow constant speed and then a fast constant speed.

Answer : A position-time graph for an object moving in the + dir'n with constant speed; first a slow constant speed and then a fast constant speed is shown below. If an object is moving in the + dir'n, then the slope of the line on a p-t graph would be +. At first, the line has a small slope (corresponding to a small velocity) and then the line has a large slope (corresponding to a large velocity).

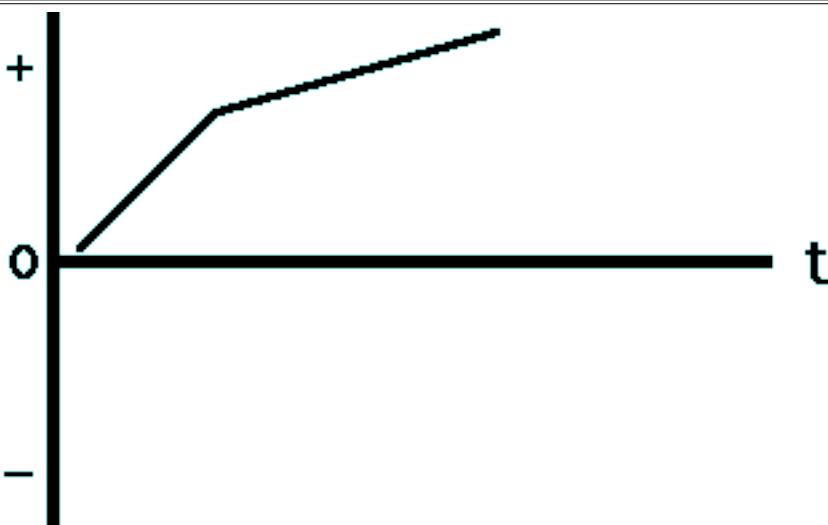
Graph of Question 20



21. Sketch a position-time graph for an object moving in the + dir'n with constant speed; first a fast constant speed and then a slow constant speed.

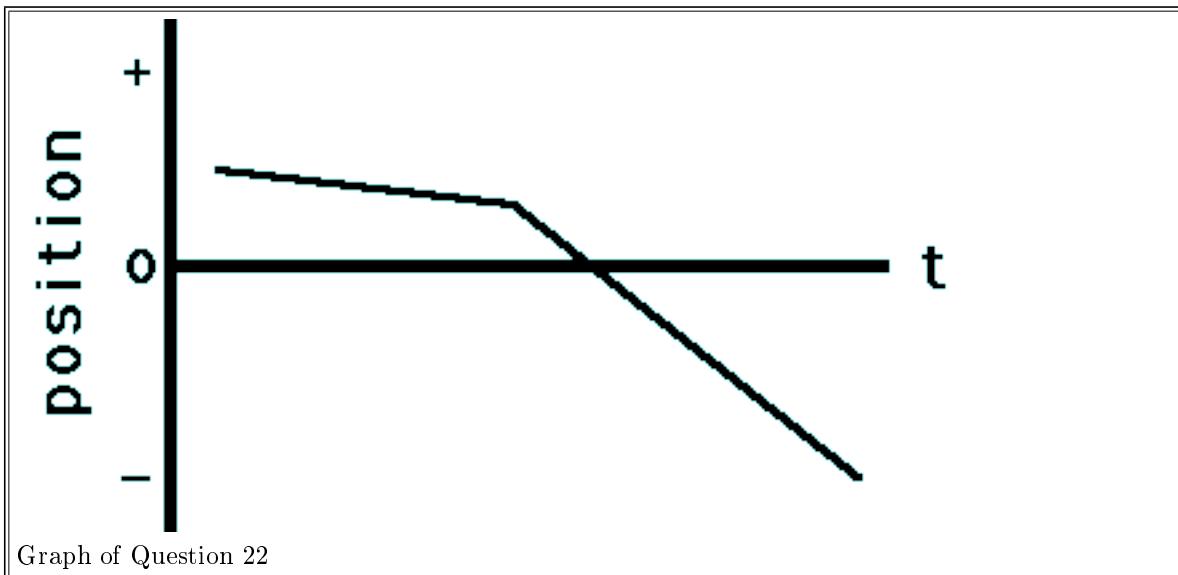
Answer : A position-time graph for an object moving in the + dir'n with constant speed; first a fast constant speed and then a slow constant speed is shown below. If an object is moving in the + dir'n, then the slope of the line on a p-t graph would be +. At first, the line has a large slope (corresponding to a large velocity) and then the line has a small slope (corresponding to a small velocity).

Graph of Question 21



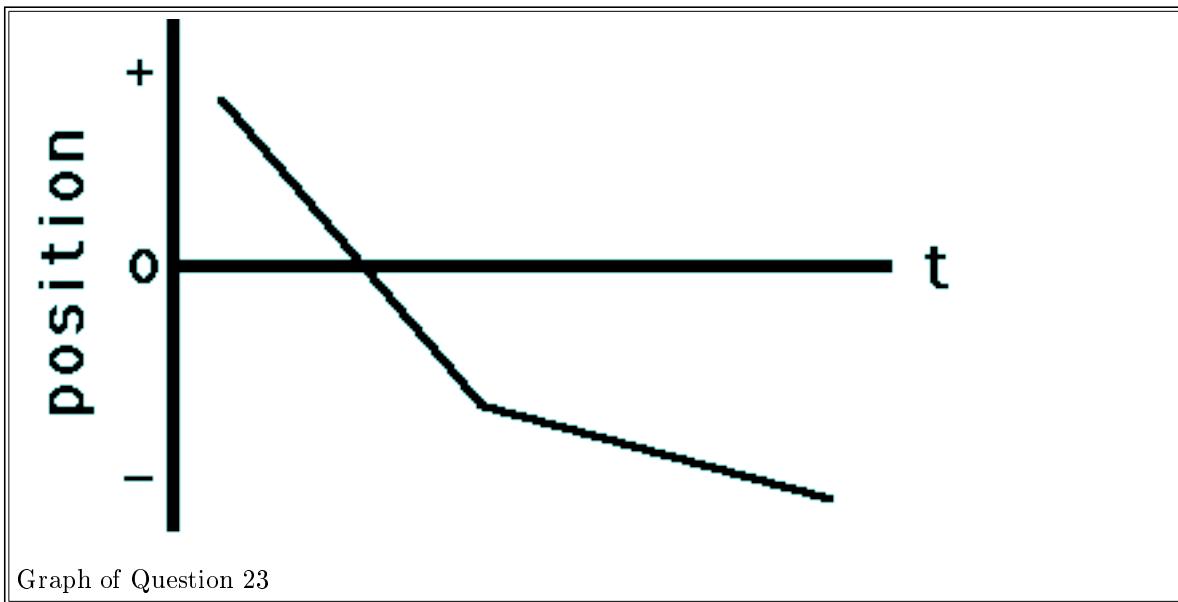
22. Sketch a position-time graph for an object moving in the - dir'n with constant speed; first a slow constant speed and then a fast constant speed.

Answer : A position-time graph for an object moving in the - dir'n with constant speed; first a slow constant speed and then a fast constant speed is shown below. If an object is moving in the - dir'n, then the slope of the line on a p-t graph would be -. At first, the line has a small slope (corresponding to a small velocity) and then the line has a large slope (corresponding to a large velocity).



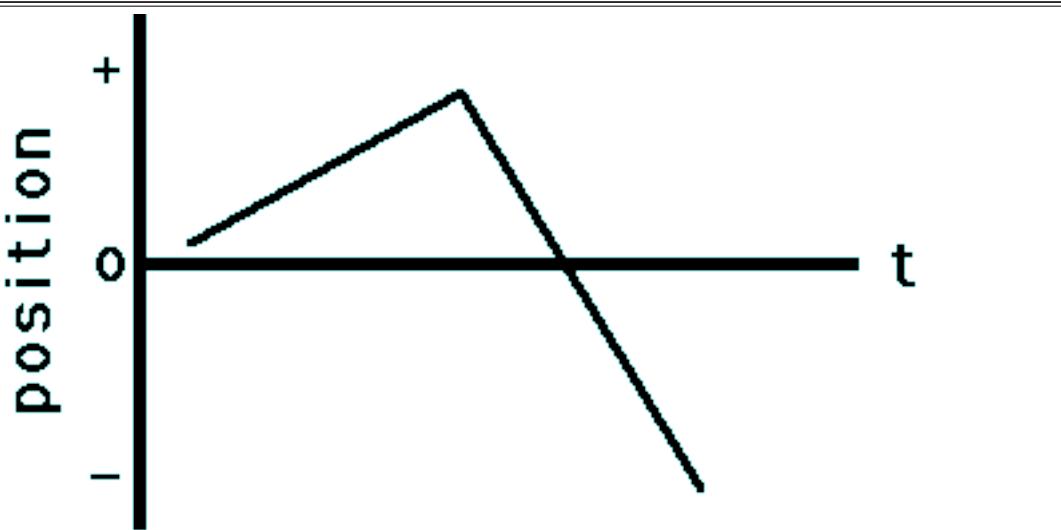
23. Sketch a position-time graph for an object moving in the - dir'n with constant speed; first a fast constant speed and then a slow constant speed.

Answer : A position-time graph for an object moving in the - dir'n with constant speed; first a fast constant speed and then a slow constant speed is shown below. If an object is moving in the - dir'n, then the slope of the line on a p-t graph would be -. At first, the line has a large slope (corresponding to a large velocity) and then the line has a small slope (corresponding to a small velocity).



24. Sketch a position-time graph for an object which moves in the + direction at a slow constant speed and then in a - direction at a fast constant speed.

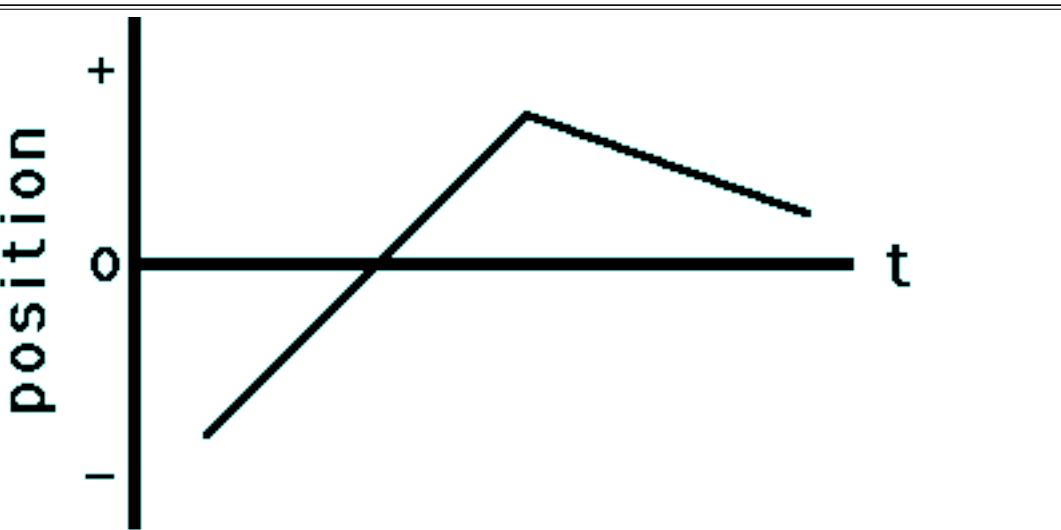
Answer : A position-time graph for an object which moves in the + direction at a slow constant speed and then in a - direction at a fast constant speed is shown below. The object must first have a + slope (corresponding to its + velocity) then it must have a - slope (corresponding to its - velocity). Initially, the slope is small (corresponding to a small velocity) and then the slope is large (corresponding to a large velocity).



Graph of Question 24

25. Sketch a position-time graph for an object which moves in the + direction at a fast constant speed and then in a - direction at a slow constant speed.

Answer : A position-time graph for an object which moves in the + direction at a fast constant speed and then in a - direction at a slow constant speed is shown below. The object must first have a + slope (corresponding to its + velocity) then it must have a - slope (corresponding to its - velocity). Initially, the slope is large (corresponding to a large velocity) and then the slope is small (corresponding to a small velocity).



Graph of Question 25

26. Sketch a position-time graph for an object which moves in the - direction at a slow constant speed and then in a + direction at a fast constant speed.

Answer : A position-time graph for an object which moves in the - direction at a slow constant speed and then in a + direction at a fast constant speed is shown below. The object must first have a - slope (corresponding to its - velocity) then it must have a + slope (corresponding to its + velocity). Initially, the slope is small (corresponding to a small velocity) and then the slope is large (corresponding to a large velocity).

position



Graph of Question 26

27. Sketch a velocity-time graph for an object moving with a constant speed in the positive direction.

Answer : A velocity-time graph for an object moving with a constant speed in the positive direction is shown below. To have "a constant speed in the positive direction" is to have a + velocity which is unchanging. Thus, the line on the graph will be in the + region of the graph (above 0). Since the velocity is unchanging, the line is horizontal. Since the slope of a line on a v-t graph is the object's acceleration, a horizontal line (zero slope) on a v-t graph is characteristic of a motion with zero acceleration (constant velocity).

velocity



Graph of Question 27

28. Sketch a velocity-time graph for an object moving with a constant speed in the negative direction.

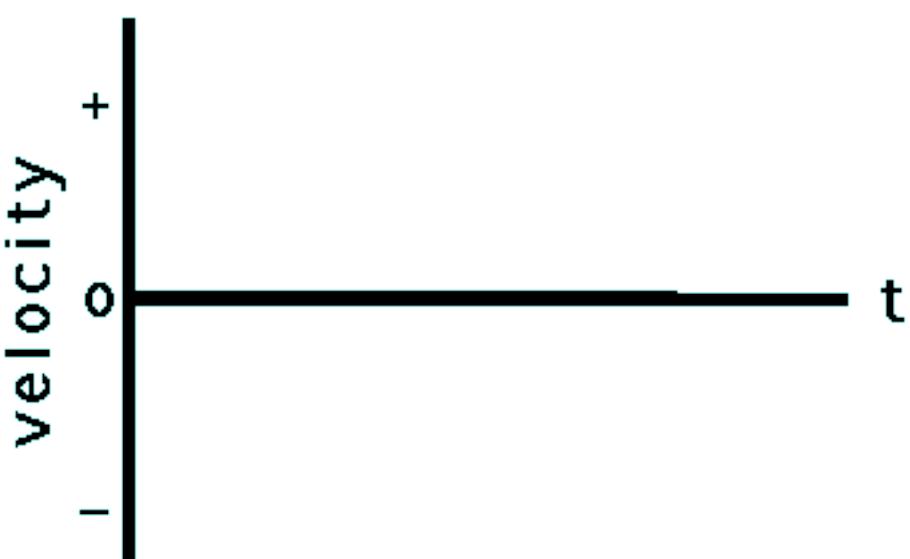
Answer : A velocity-time graph for an object moving with a constant speed in the negative direction is shown below. To have "a constant speed in the negative direction" is to have a - velocity which is unchanging. Thus, the line on the graph will be in the - region of the graph (below 0). Since the velocity is unchanging, the line is horizontal. Since the slope of a line on a v-t graph is the object's acceleration, a horizontal line (zero slope) on a v-t graph is characteristic of a motion with zero acceleration (constant velocity).



Graph of Question 28

29. Sketch a velocity-time graph for an object which is at rest.

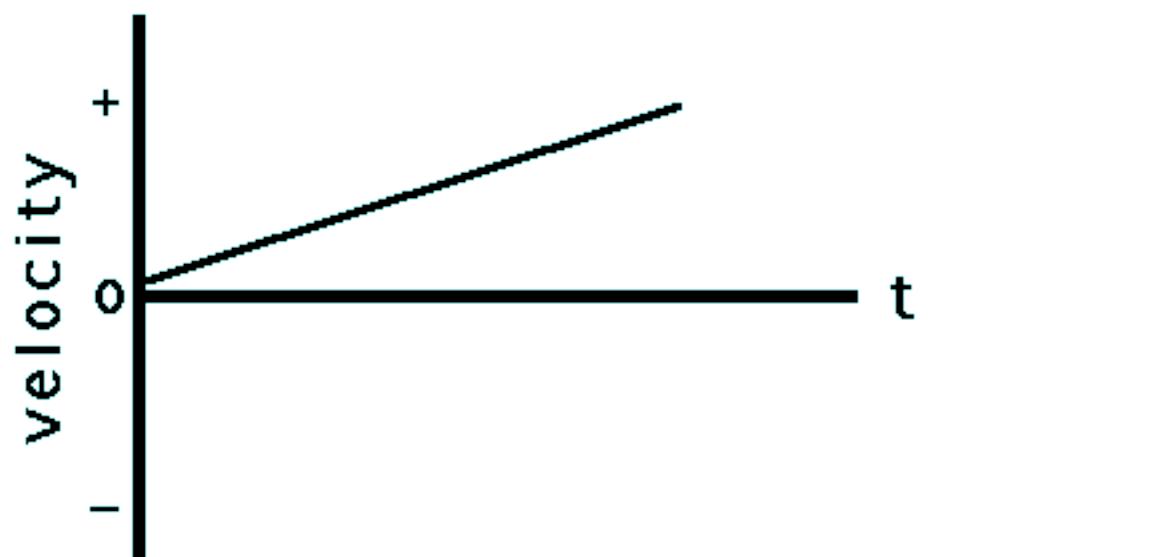
Answer : A velocity-time graph for an object which is at rest is shown below. To be "at rest" is to have a zero velocity. Thus the line is drawn along the axis ( $v=0$ ).



Graph of Question 29

30. Sketch a velocity-time graph for an object moving in the + direction, accelerating from a slow speed to a fast speed.

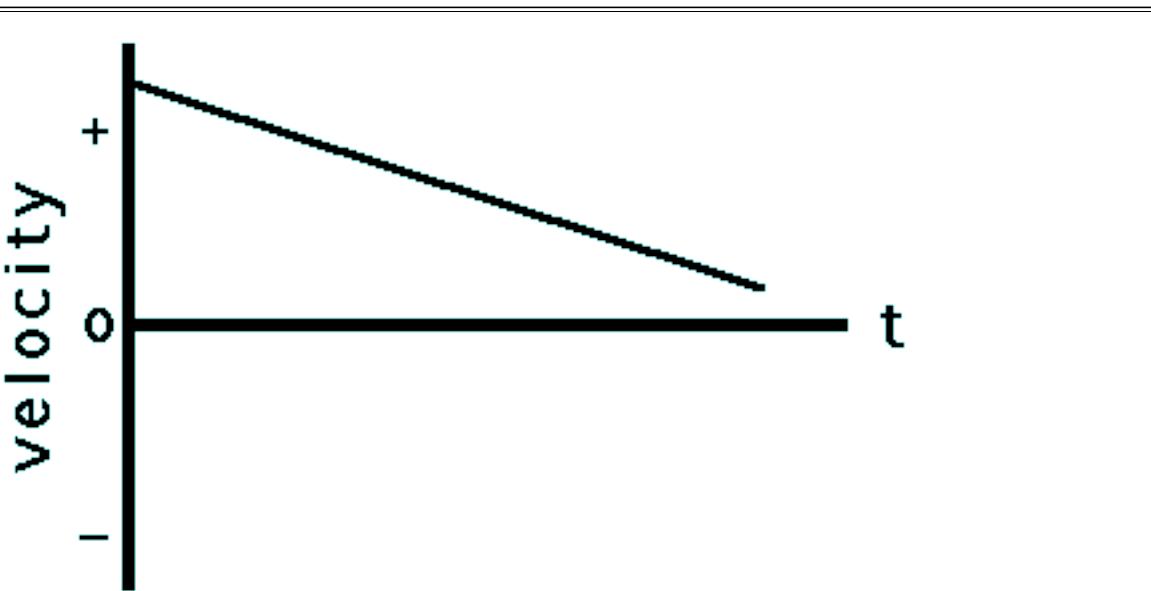
Answer : A velocity-time graph for an object moving in the + direction, accelerating from a slow speed to a fast speed is shown below. An object which is moving in the + direction and speeding up (slow to fast) has a + acceleration. (If necessary, review the dir'n of the acceleration vector in the Physics Classroom Tutorial.) Since the slope of a line on a v-t graph is the object's acceleration, an object with + acceleration is represented by a line with + slope. Thus, the line is a straight diagonal line with upward (+) slope. Since the velocity is +, the line is plotted in the + region of the v-t graph.



Graph of Question 30

31. Sketch a velocity-time graph for an object moving in the + direction, accelerating from a fast speed to a slow speed.

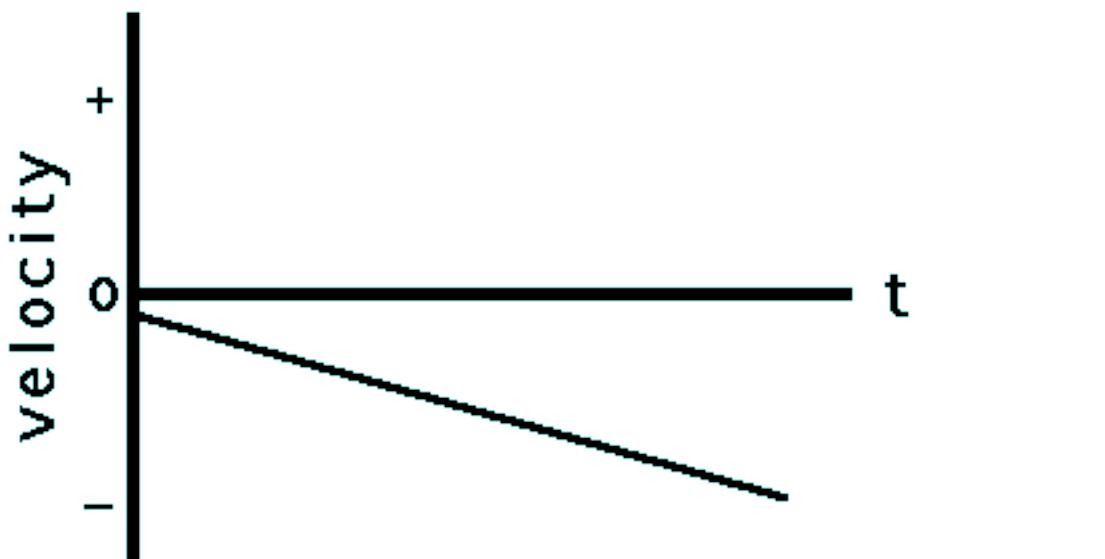
Answer : A velocity-time graph for an object moving in the + direction, accelerating from a fast speed to a slow speed is shown below. An object which is moving in the + direction and slowing down (fast to slow) has a - acceleration. (If necessary, review the dir'n of the acceleration vector in the Physics Classroom Tutorial.) Since the slope of a line on a v-t graph is the object's acceleration, an object with - acceleration is represented by a line with - slope. Thus, the line is a straight diagonal line with downward (-) slope. Since the velocity is +, the line is plotted in the + region of the v-t graph.



Graph of Question 31

32. Sketch a velocity-time graph for an object moving in the - direction, accelerating from a slow speed to a fast speed.

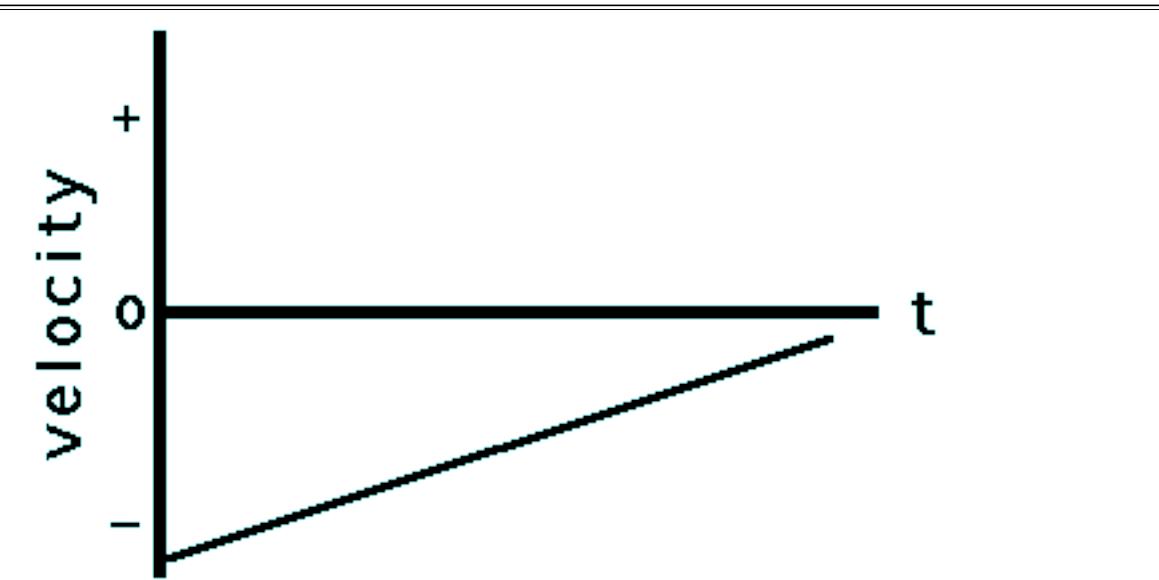
Answer : A velocity-time graph for an object moving in the - direction, accelerating from a slow speed to a fast speed is shown below. An object which is moving in the - direction and speeding up (slow to fast) has a - acceleration. (If necessary, review the dir'n of the acceleration vector in the Physics Classroom Tutorial.) Since the slope of a line on a v-t graph is the object's acceleration, an object with - acceleration is represented by a line with - slope. Thus, the line is a straight diagonal line with downward (-) slope. Since the velocity is -, the line is plotted in the - region of the v-t graph.



Graph of Question 32

33. Sketch a velocity-time graph for an object moving in the - direction, accelerating from a fast speed to a slow speed.

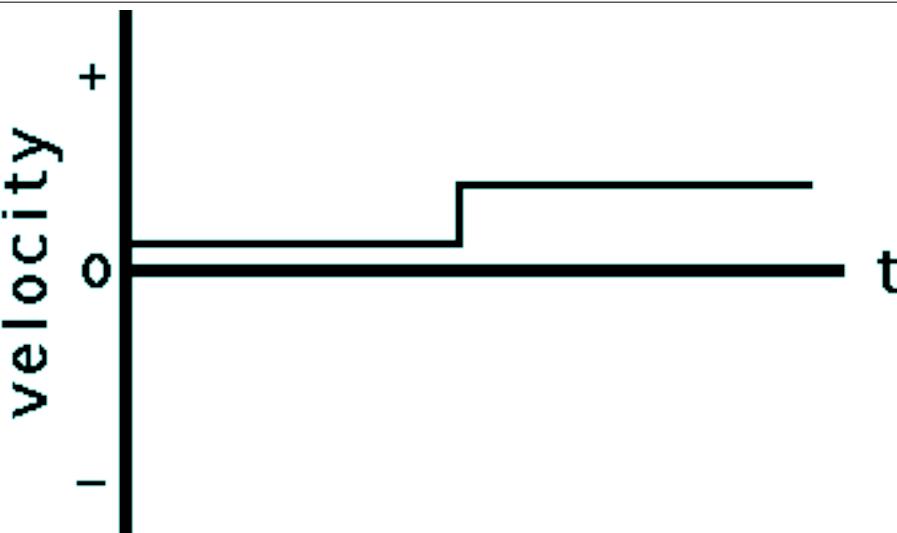
Answer : A velocity-time graph for an object moving in the - direction, accelerating from a fast speed to a slow speed is shown below. An object which is moving in the - direction and slowing down (fast to slow) has a + acceleration. (If necessary, review the dir'n of the acceleration vector in the Physics Classroom Tutorial.) Since the slope of a line on a v-t graph is the object's acceleration, an object with + acceleration is represented by a line with + slope. Thus, the line is a straight diagonal line with upward (+) slope. Since the velocity is -, the line is plotted in the - region of the v-t graph.



Graph of Question 33

34. Sketch a velocity-time graph for an object which first moves with a slow, constant speed in the + direction, and then with a fast constant speed in the + direction.

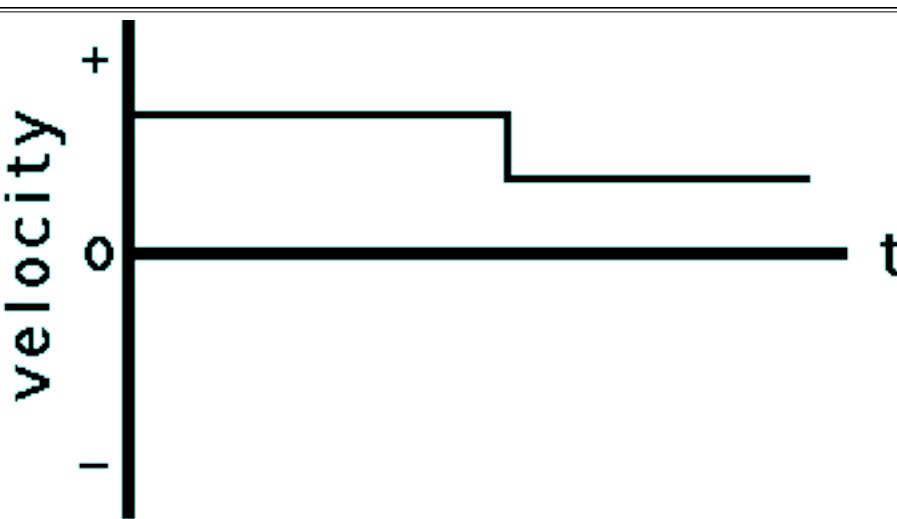
Answer : A velocity-time graph for an object which first moves with a slow, constant speed in the + direction, and then with a fast constant speed in the + direction is shown below. Since there are two parts of this object's motion, there will be two distinct parts on the graph. Each part is in the + region of the v-t graph (above 0) since the velocity is +. Each part is horizontal since the velocity during each part is constant (constant velocity means zero acceleration which means zero slope). The second part of the graph will be higher since the velocity is greater during the second part of the motion.



Graph of Question 34

35. Sketch a velocity-time graph for an object which first moves with a fast, constant speed in the + direction, and then with a slow constant speed in the + direction.

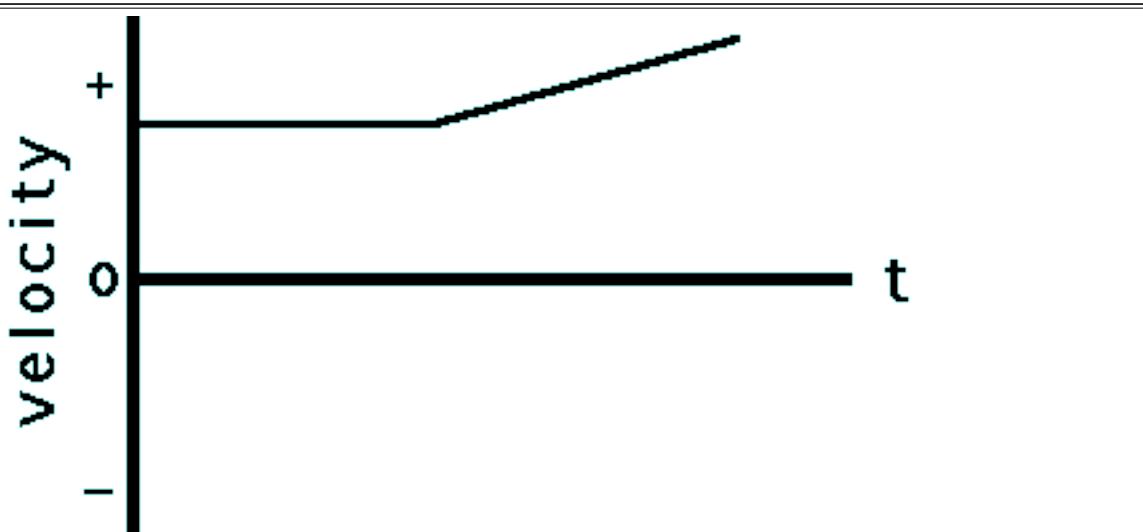
Answer : A velocity-time graph for an object which first moves with a fast, constant speed in the + direction, and then with a slow constant speed in the + direction is shown below. Since there are two parts of this object's motion, there will be two distinct parts on the graph. Each part is in the + region of the v-t graph (above 0) since the velocity is +. Each part is horizontal since the velocity during each part is constant (constant velocity means zero acceleration which means zero slope). The first part of the graph will be higher since the velocity is greater during the first part of the motion.



Graph of Question 35

36. Sketch a velocity-time graph for an object which first moves with a constant speed in the + direction, and then moves with a positive acceleration.

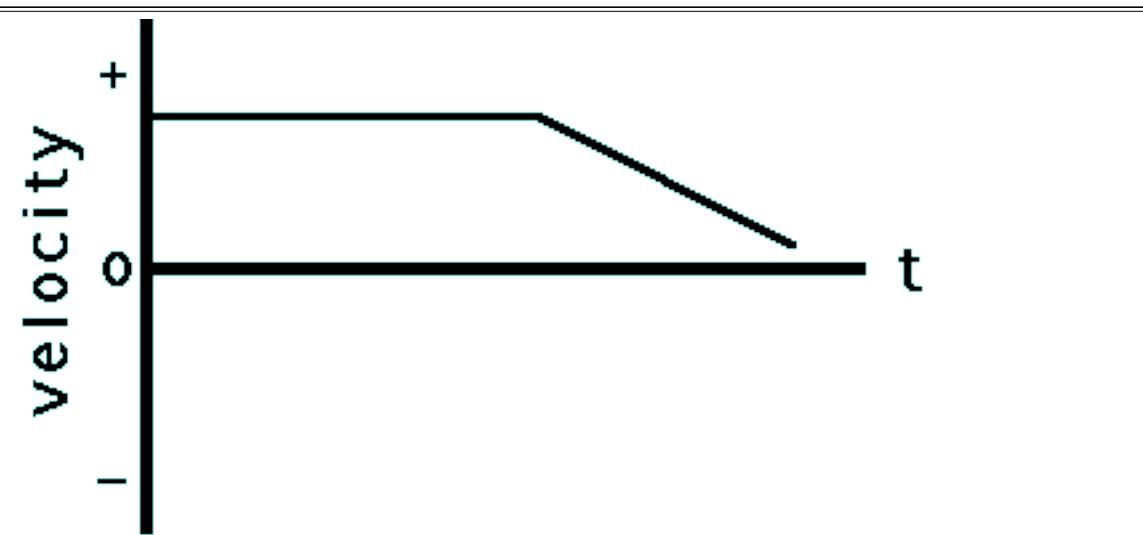
Answer : A velocity-time graph for an object which first moves with a constant speed in the + direction, and then moves with a positive acceleration is shown below. Since there are two parts of this object's motion, there will be two distinct parts on the graph. Each part is in the + region of the v-t graph (above 0) since the velocity is +. The slope of the first part is zero since constant velocity means zero acceleration and zero acceleration is represented by a horizontal line on a v-t graph (slope = acceleration for v-t graphs). The second part of the graph is an upward sloping line since the object has + acceleration (again, the slope = acceleration for v-t graphs).



Graph of Question 36

37. Sketch a velocity-time graph for an object which first moves with a constant speed in the + direction, and then moves with a negative acceleration.

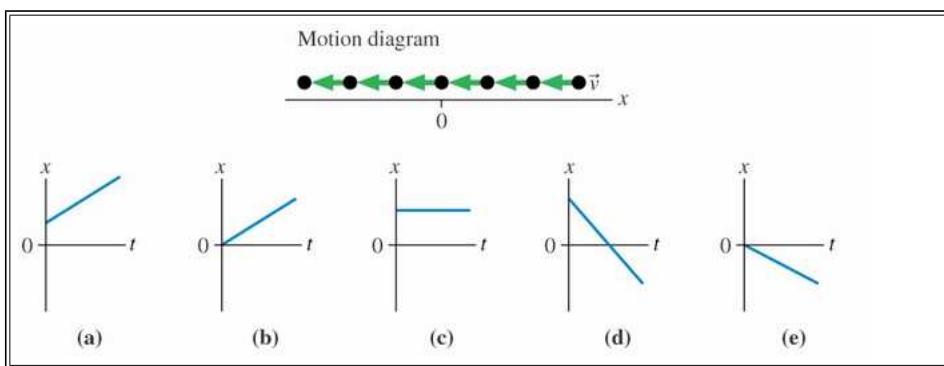
Answer : A velocity-time graph for an object which first moves with a constant speed in the + direction, and then moves with a negative acceleration is shown below. Since there are two parts of this object's motion, there will be two distinct parts on the graph. Each part is in the + region of the v-t graph (above 0) since the velocity is +. The slope of the first part is zero since constant velocity means zero acceleration and zero acceleration is represented by a horizontal line on a v-t graph (slope = acceleration for v-t graphs). The second part of the graph is an downward sloping line since the object has - acceleration (again, the slope = acceleration for v-t graphs)



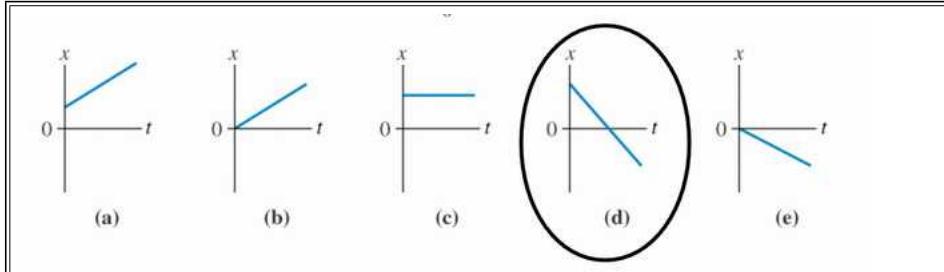
Graph of Question 37

## 4.1 Exercises

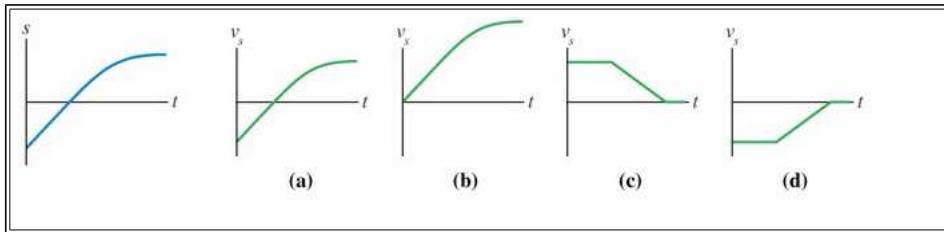
Example : Which position-versus-time graph represents the motion shown in the motion diagram?



Solution :

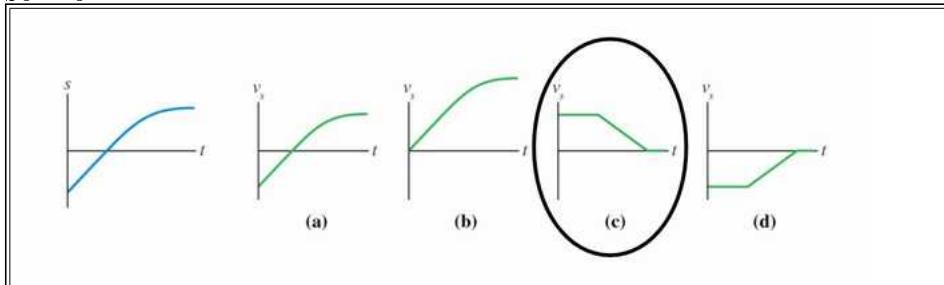


Example : Which velocity-versus-time graph goes with this position-versus-time graph on the left?

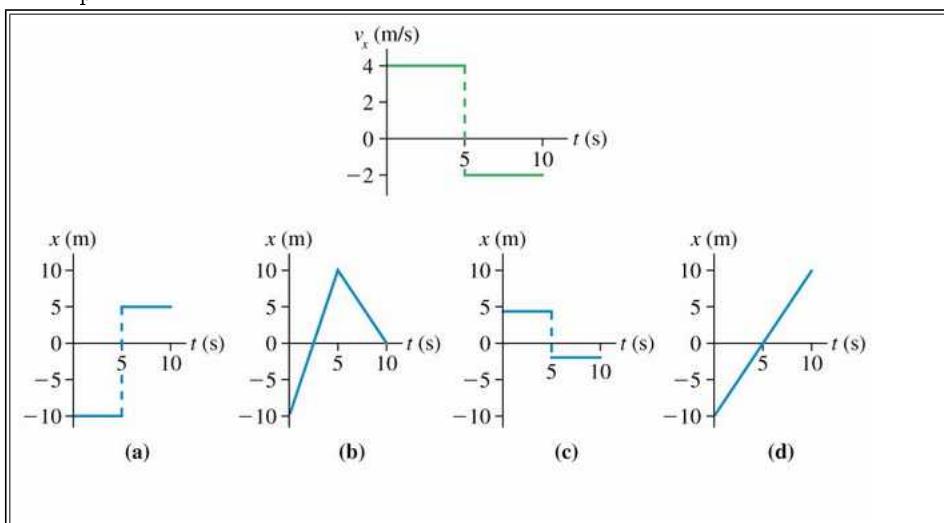


Note that the variable "s" denotes a generic Cartesian coordinate. It could be x or y.

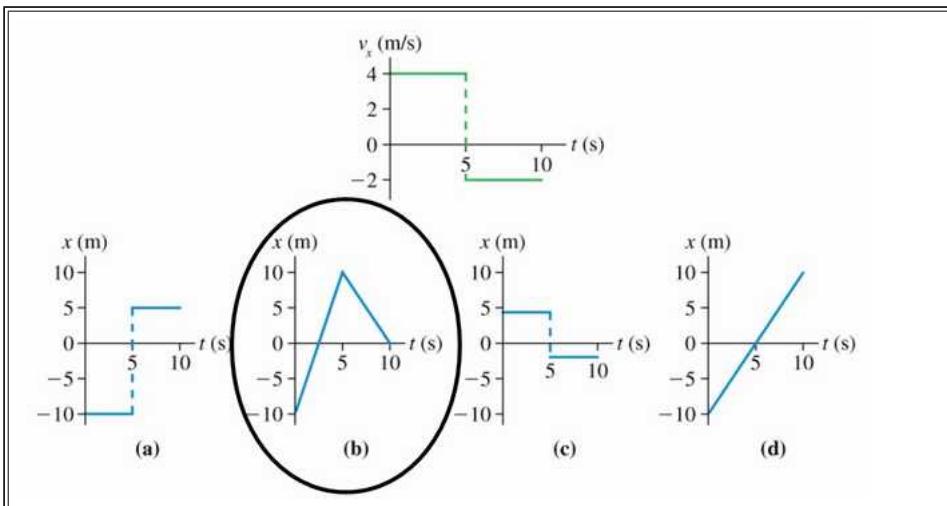
Solution :



The velocity graph must match the slope of the position graph. The position graph starts with a constant positive slope. Then the slope decreases to zero.

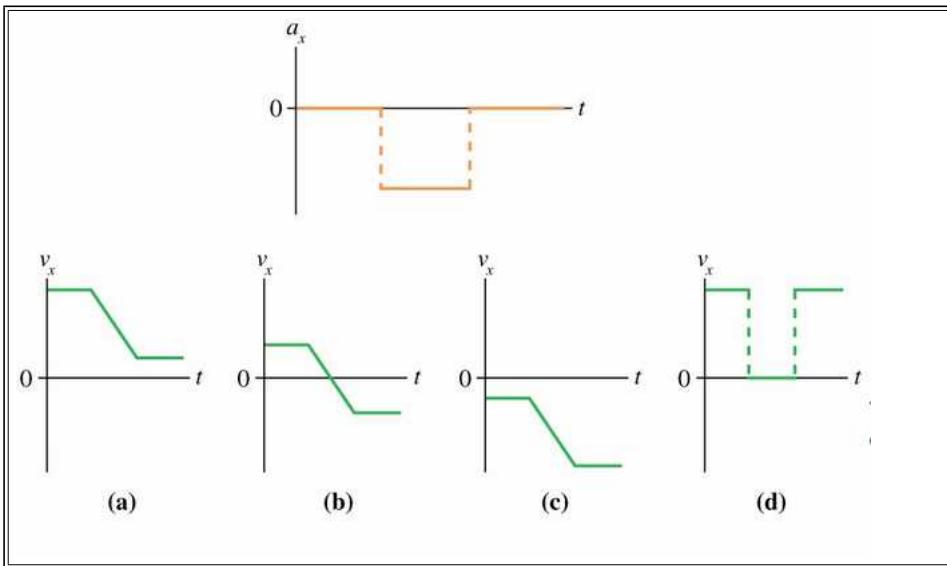
Example : Which position-versus-time graph goes with this velocity-versus-time graph on the left? The particle's position at  $t_i = 0 \text{ s}$  is  $x_i = -10 \text{ m}$ .

Solution :

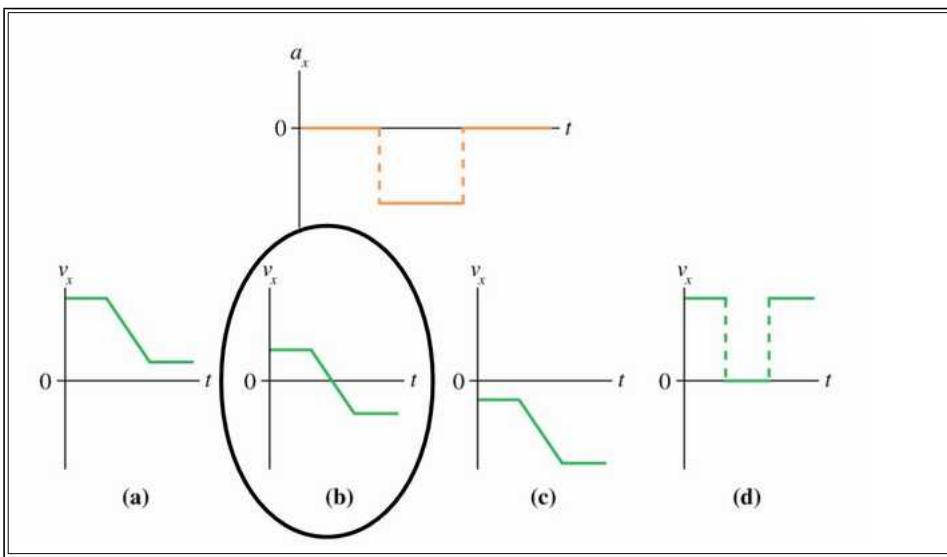


The velocity graph must match the slope of the position graph. The intercept of the position graph is arbitrary.

**Example :** Which velocity-versus-time graph or graphs goes with this acceleration-versus-time graph? The particle is initially moving to the right and eventually to the left.

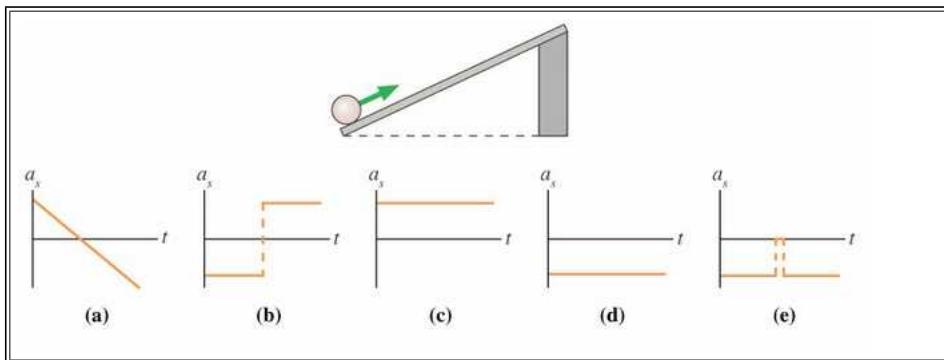


Solution :

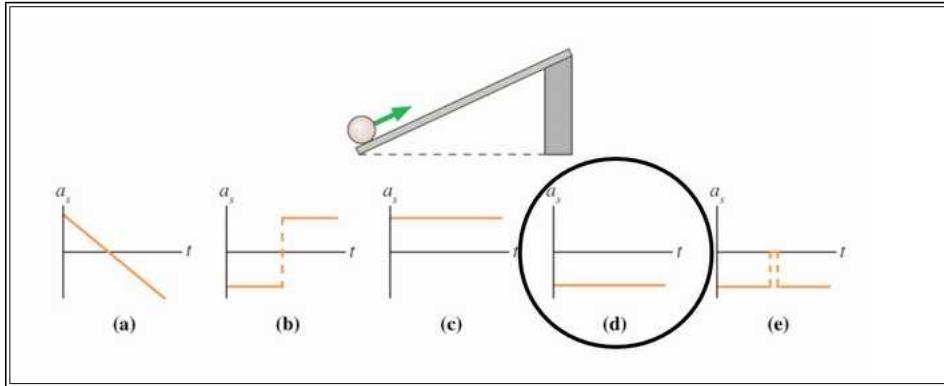


The slope of the velocity graph must match the acceleration graph. The intercept is based on the direction information.

**Example :** The ball rolls up the ramp, then back down. Which is the correct acceleration graph?



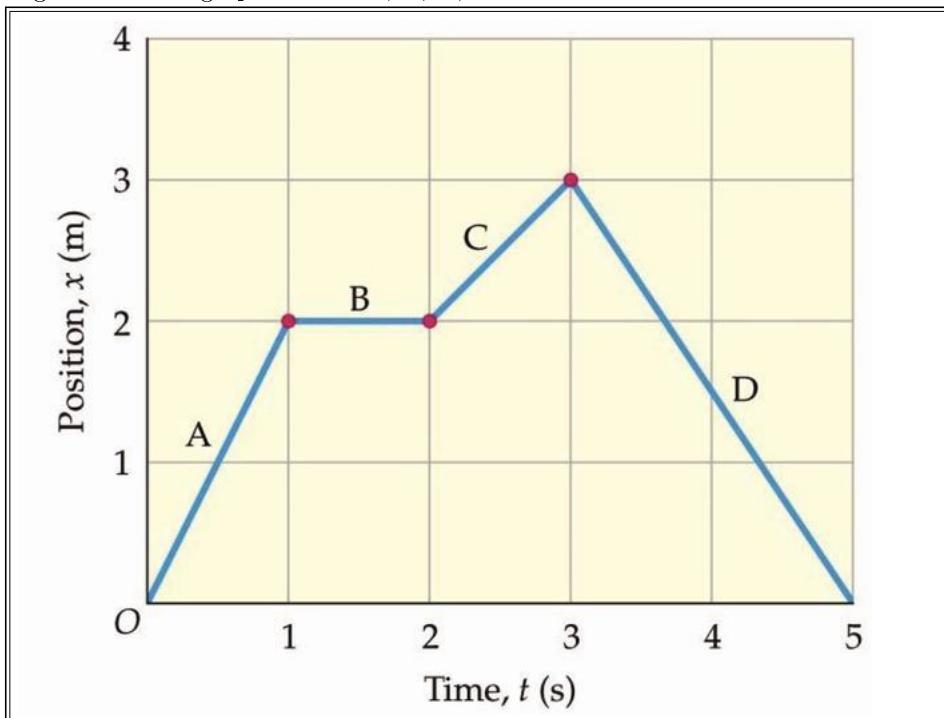
Solution :



The ball will move up the ramp while slowing down, then it will reach a turnaround point and begin to move down the ramp with increasing speed. The velocity graph at right is consistent with that description. The acceleration graph shown in graph d is consistent with the requirement that it match the slope of the velocity graph.

**Example :** An expectant father paces back and forth producing the position-versus-time graph shown here.

(a) Without performing a calculation indicate whether the father's velocity is positive, negative, or zero on the segments of the graph labeled A, B, C, and D.



Segment A:

Segment B:

Segment C:

Segment D:

(b) Calculate the average velocity for each segment and show that your results verify your answers to part (a).

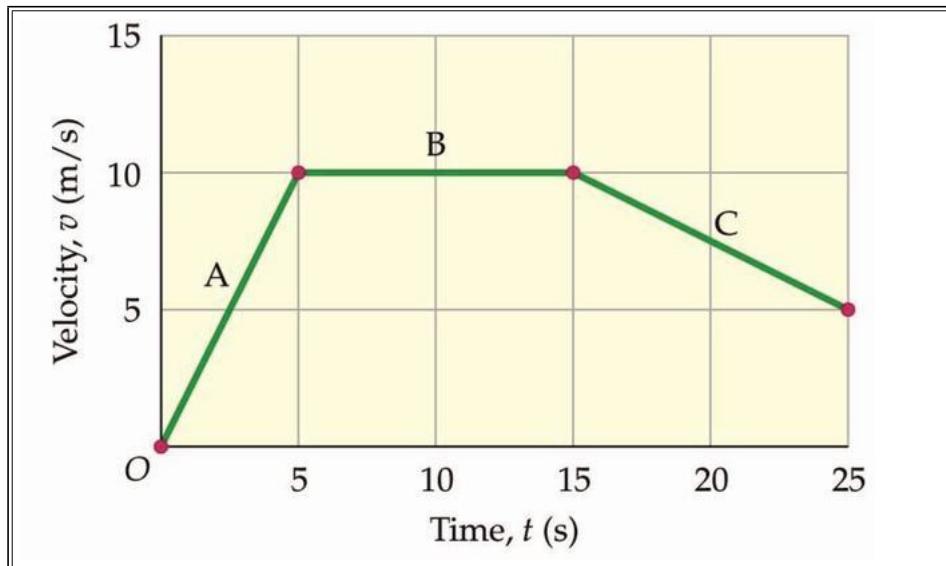
Segment A:

Segment B:

Segment C:

Segment D:

**Example :** 2. A motorcycle moves according to the velocity-versus-time graph shown. Find the displacement of the motorcycle for each of the segments A, B, and C.

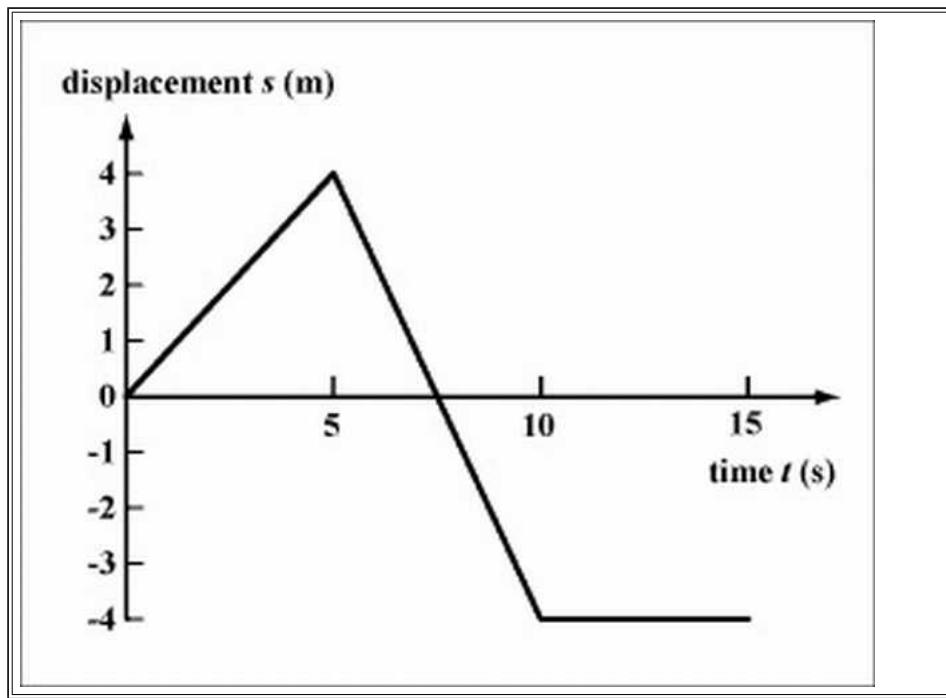


Segment A:

Segment B:

Segment C:

**Example :** Fig. shows the displacement-time graph of a car during parking. Describe the motion of the car and find the velocity in each time interval. n.d.



**Solution:** Stage 1: The car moves forwards from the origin to  $s=4$ m in the first 5 s.

$$v = 4/5 = 0.8 \text{ m/s} \text{ (forwards)}$$

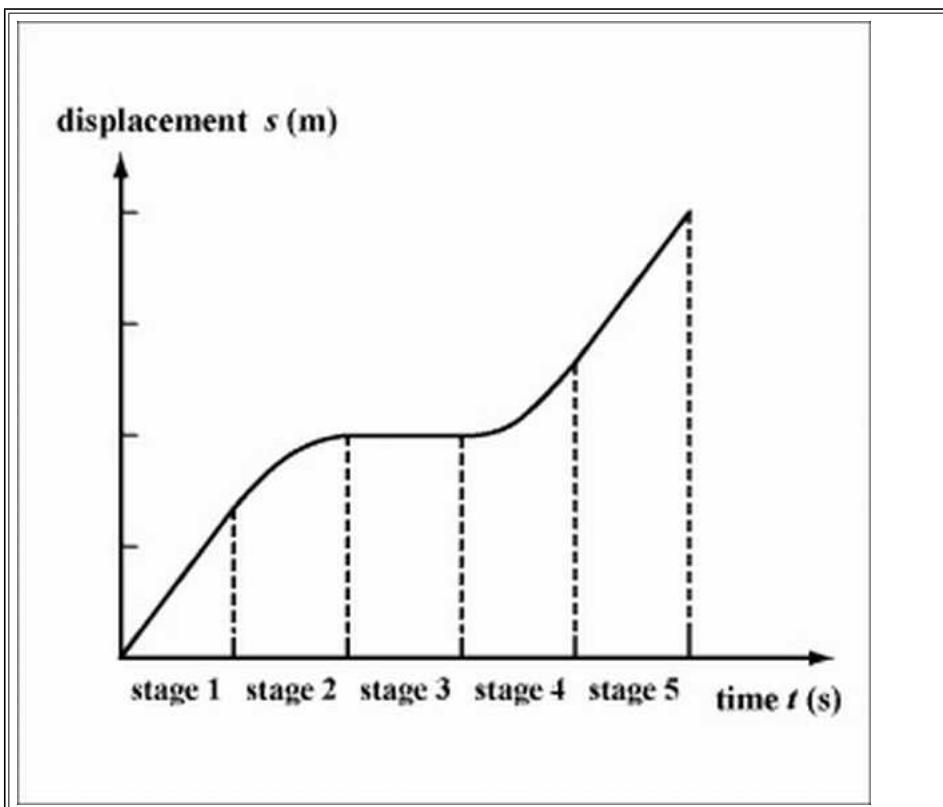
Stage 2: The car moves backwards, passes the origin, to  $s=-4$ m in the next 5 s.

$$v = (-4-4)/(10-5) = -1.6 \text{ m/s} \text{ (backwards)}$$

Stage 3: The car remains at rest in the last 5 s.

$$v = 0 \text{ m/s}$$

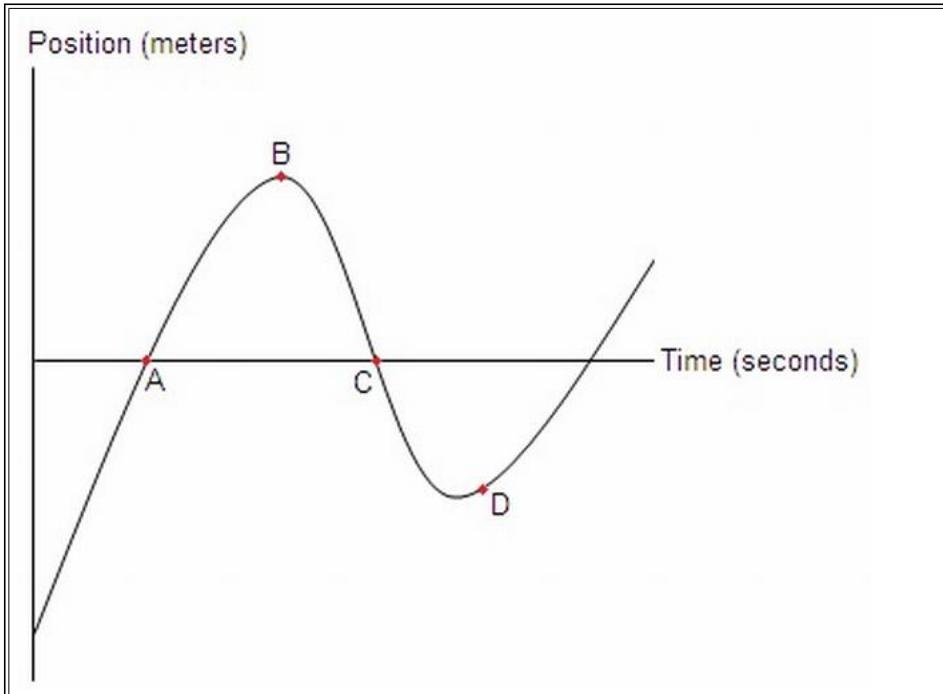
**Example :** Fig. is the displacement-time graph for a car encountering a traffic light. Describe the motion of the car at each stage qualitatively. n.d.



**Solution :** Stage 1: moving with constant velocity; stage 2: decelerating; stage 3: at rest; stage 4: accelerating; stage 5: moving with the same constant velocity as in stage 1.

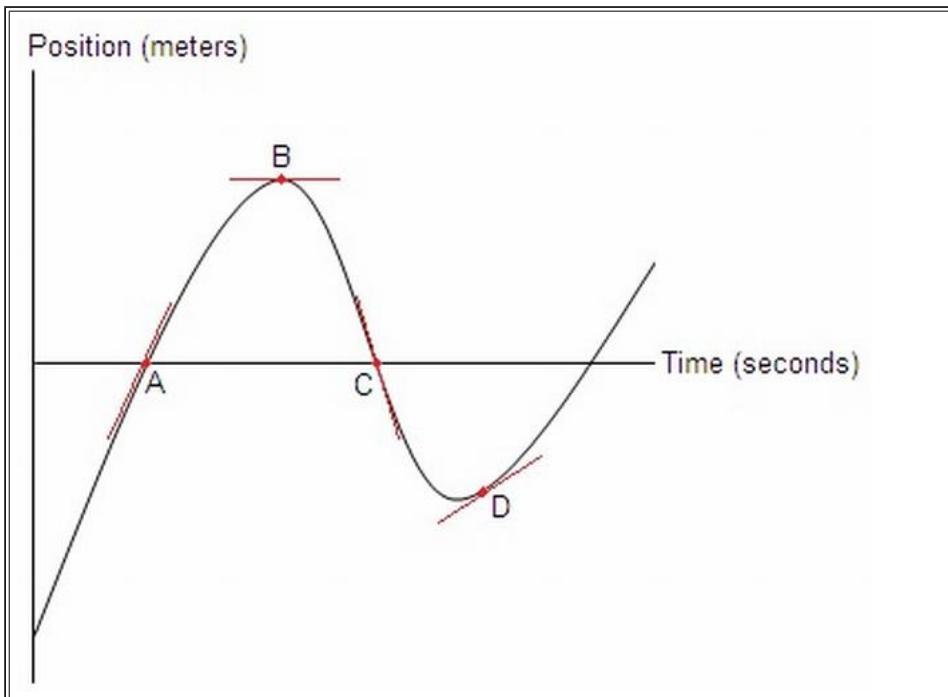
Note: In stage 2 the slope of the curve is decreasing, while in stage 4 the slope is increasing. This indicates that the car is decelerating in stage 2 and accelerating in stage 4.

**Example :** An object's position during a given time interval is shown by the graph below:



- At which of the marked points is the object's velocity the greatest? The least?
- Is the object's acceleration positive or negative between points A and B?
- Suppose this curve can be modeled by the function  $x(t) = t^3 - 9.5t^2 + 23t - 9$ . Find the object's velocity and acceleration at  $t = 1$ ,  $t = 3$ , and  $t = 5$ .
- Using the function from part c, determine the object's maximum and minimum positions and velocities within the interval from  $t = 1$  to  $t = 6$ .

**Solution :** a.) Remember from problem 22 that velocity is the slope of a position vs. time graph such as this. By looking at lines tangent to the curve, we can see which point has the highest and lowest slope:



Looking at the red tangent lines, we can immediately eliminate point B as a candidate for both the maximum and minimum velocity, as its tangent is horizontal and thus has a slope of 0. Point C is the only marked point whose tangent line has a negative slope, so point C has the lowest velocity. Looking at points A and D, point A's tangent line has a steeper positive slope so point A has the highest velocity.

b.) We know that acceleration is a change in velocity, so by asking whether acceleration is positive or negative, we are asking if the velocity is increasing or decreasing. Since velocity is the slope of this graph, we must determine how the slope of the curve is changing between points A and B. Looking at the diagram in part a, we see that the slope at point A is positive, and the slope at point B is 0. As such, the slope, and thus the velocity, must be decreasing. Therefore, the object's acceleration is negative in this interval.

c.) We know from problem 22 that velocity is the derivative of position, and from problem 23 that acceleration is the derivative of velocity. So, we will begin by differentiating the position function twice:  $x(t) = t^3 - 9.5t^2 + 23t - 9$   $v(t) = 3t^2 - 19t + 23$   $a(t) = 6t - 19$

Now that we know the velocity and acceleration functions, all that is left is to plug the values of  $t$  into these functions and simplify:  $v(1) = 3 * 1^2 - 19 * 1 + 23 = 3 - 19 + 23 = 7 \text{ m/s}$   $v(3) = 3 * 3^2 - 19 * 3 + 23 = 27 - 57 + 23 = -7 \text{ m/s}$   $v(5) = 3 * 5^2 - 19 * 5 + 23 = 75 - 95 + 23 = 3 \text{ m/s}$

$a(1) = 6 * 1 - 19 = 6 - 19 = -13 \text{ m/s}^2$   $a(3) = 6 * 3 - 19 = 18 - 19 = -1 \text{ m/s}^2$   $a(5) = 6 * 5 - 19 = 30 - 19 = 11 \text{ m/s}^2$

d.) Thinking logically about the graph, the possible candidates for maximum and minimum position are at the end points of the interval and at the spots, like point B, where the slope of the graph is 0. So, first we set the velocity function from part c equal to 0 and solve for  $t$ :  $v(t) = 3t^2 - 19t + 23 = 0$   $t = 1.63008 \text{ s}$  or  $t = 4.70326 \text{ s}$

Note that this was solved using a graphing calculator. The AP exam will not ask you to solve a quadratic this complicated by hand, however you may have to solve a simpler function using the quadratic formula. Also, we keep as many decimal places as we can at this stage in order to maintain accuracy. Now that we know all the possible times at which the position could be at a maximum or minimum within the interval, we simply plug these  $t$  values into  $x(t)$ . Don't forget to check the end points:  $x(t) = t^3 - 9.5t^2 + 23t - 9$   $x(1) = 5.5 \text{ m}$   $x(1.63008) = 7.58 \text{ m}$   $x(4.70326) = -6.93 \text{ m}$   $x(6) = 3 \text{ m}$

We see that the minimum position is  $-6.93 \text{ m}$ , and the maximum position is  $7.58 \text{ m}$ . Finding the maximum and minimum velocities is achieved in the same manner, except we set the acceleration function equal to 0 and plug the  $t$  values into the velocity function:  $a(t) = 6t - 19 = 0$   $6t = 19$   $t = 19/6 = 3.16667 \text{ s}$

$$v(t) = 3t^2 - 19t + 23 \quad v(1) = 7 \text{ m/s} \quad v(3.16667) = -7.08 \text{ m/s} \quad v(6) = 17 \text{ m/s}$$

So the minimum velocity is  $-7.08 \text{ m/s}$ , and the maximum velocity is  $17 \text{ m/s}$ .

# Chapter 5

## Classical Approach

### 5.1 The Equations of motion and the origin of Graph Handling

#### 5.1.1 The First Equation

The Equation  $v = \frac{dx}{dt}$  in linear motion implies

- i) The **Slope of Position-Time Graph** is **Instantaneous Velocity**.
- ii) The **Area under the Velocity-Time Graph** is **Change in Position**.  
{ The second one requires the manipulation ,  $dx = vdt$  i.e.  $\int dx = \int vdt$  }

The equations can be further manipulated to obtain the Speed Time Graph , where

speed = rate of change of distance wrt time

Few of the following examples illustrate this concept:

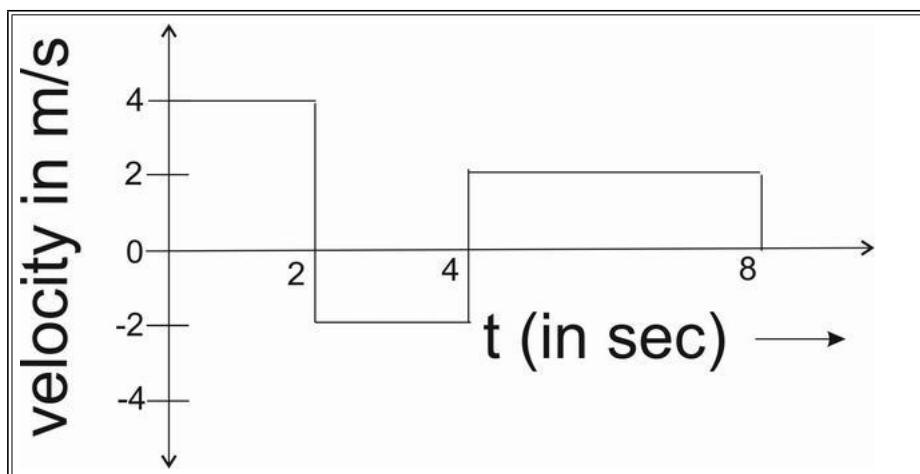
**Example 1:** On a displacement-time graph, two straight lines make angles of  $30^\circ$  and  $60^\circ$  with the time-axis.  
The ratio of the velocities represented by them is

- a)  $1 : \sqrt{3}$
- b) 1:3
- c)  $\sqrt{3} : 1$
- d) 3:1

{ Hint: The velocity in a displacement-time graph is given by the slope of the curve. Slope =  $\tan(\text{gent})$  of angle of inclination of s-t graph. This gives the respective ratios  $\tan 30^\circ / \tan 60^\circ$

Answer: b) is the correct answer. }

**Example 2:** A body is moving in a straight line as shown in velocity-time graph. The displacement and distance travelled by body in 8 second are respectively:

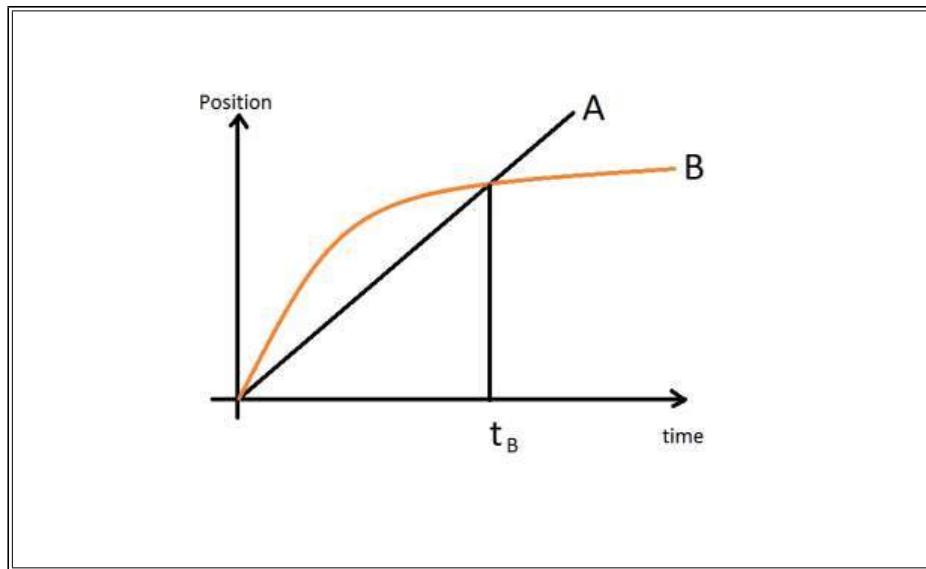


- a) 12 m, 20 m
- b) 20 m, 12 m
- c) 12 m, 12 m
- d) 20 m, 20 m

{ Hint: The displacement in a velocity-time graph is given by the area under the graph with proper signs. From 0s - to 2s , the area is 8m . From 2s - to 4s , the area is -4m . From 4s - to 8s , the area is 8m. Adding these 3 values , we get  $8m + (-4m) + 8m = 12m$ . } The distance in a v-t graph is given by the absolute area under the graph. So, taking the absolute values of individual area divisions, we get  $8m + 4m + 8m = 20m$

Answer: a) is the correct answer. }

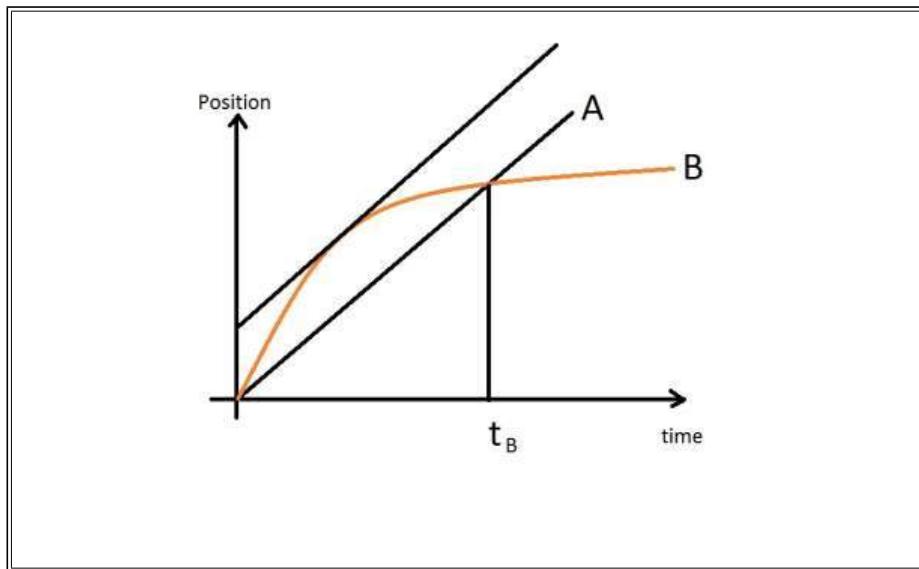
**Example 3:** The graph shows position as a function of time for two trains running on parallel tracks. Which statement is true?



- a) At time  $t_B$  both trains have the same velocity.
- b) Both trains have the same velocity at some time after  $t_B$  .
- c) Both trains have the same velocity at some time before  $t_B$  .
- d) Somewhere on the graph, both trains have the same acceleration.

{ Hint: Depending on the question requirements, we'll have to check all the assertions one by one.

- a) In a position time graph, the slope gives velocity. It can be clearly seen that Graph B has a much lower slope than Graph A at time  $t_B$ . So, the assertion is wrong.
- b,c) By drawing a line parallel to the line A which is a tangent to Graph B , it can be seen where the two graphs have same slope. It is clear that the graphs have same slope between 0 and  $t_B$  as noted from the figure. So, assertion b is wrong while c is correct.

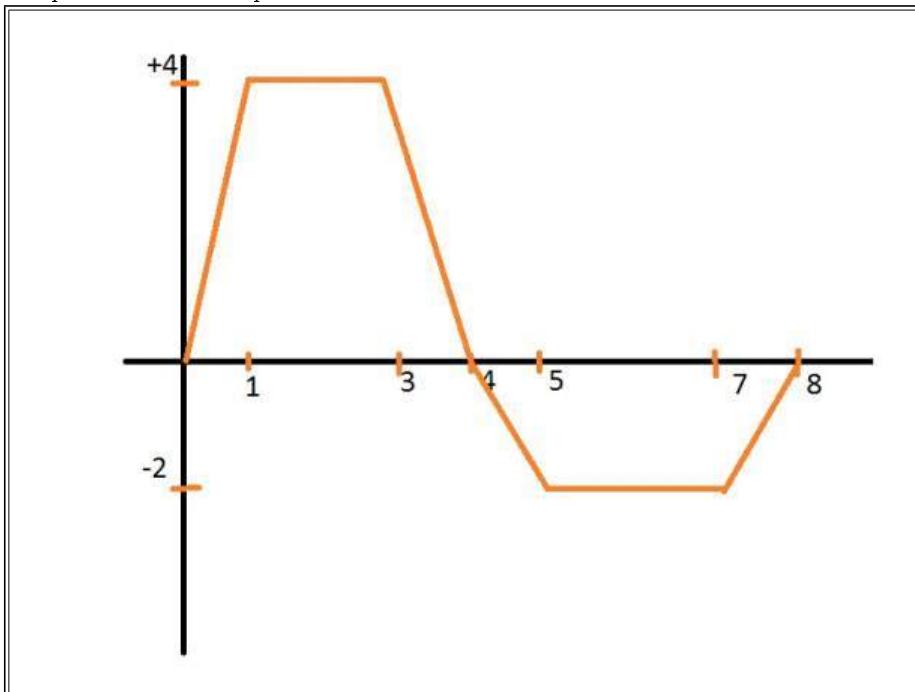


d) As the Graph A has a constant slope, so the acceleration of body A is zero. Whereas Graph B is constantly turning, so the slope can be assumed to be non-zero throughout. According to some revelations, however it is noted that the figure is not clear enough to show whether Graph B is straight after  $t_B$  or bending. In case it is assumed to be straight, then after  $t_B$  both trains will have same (zero) acceleration. Also at start both have large (infinite) acceleration, in which case the ratio of the two large ( infinite ) values may be calculated if initial conditions are mentioned and is required.

At our level we would assume this assertion to be wrong, however making a note that the image should have been more clearly presented.

Answer: c) is the correct assertion. }

**Example 4:** The velocity-time graph of a particle in linear motion is as shown. Both v and t are in SI units. The displacement of the particle is



- a) 6 m
- b) 8 m
- c) 16 m
- d) 18 m

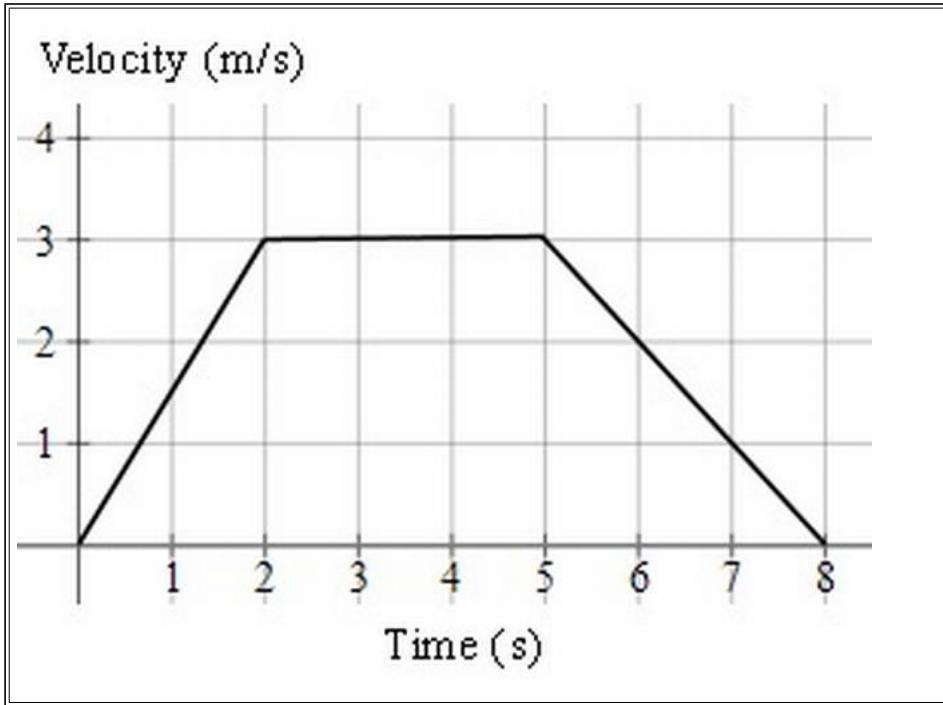
{ Hint : For displacement calculations, between 0 - to 4 , area of the positive trapezium =  $(4+2) \times 4 = 24$

between 4 - to 8, area of negative trapezium =  $(2+4)X(-2) = -12$ .

So , the answer is +12 , which is not in the options.

So , the answer is None of these. }

**Example 5 :** A body moves as described by the following v-t graph.



- a) Describe the motion.
- b) What is the distance travelled during the motion?
- c) What is the average speed for the motion?

**Solution :** a) From  $t=0$  to  $2$ , the acceleration was  $a = \frac{\Delta v}{\Delta t} = \frac{3}{2} = 1.5 \text{ ms}^{-2}$

From  $t=2$  to  $5$ , the acceleration was  $0 \text{ ms}^{-1}$ .

The body was neither speeding up nor slowing down.

From  $t=5$  to  $8$ , the acceleration was  $a = \frac{\Delta v}{\Delta t} = \frac{-3}{3} = -1 \text{ ms}^{-2}$

The body was slowing down, so the acceleration was negative.

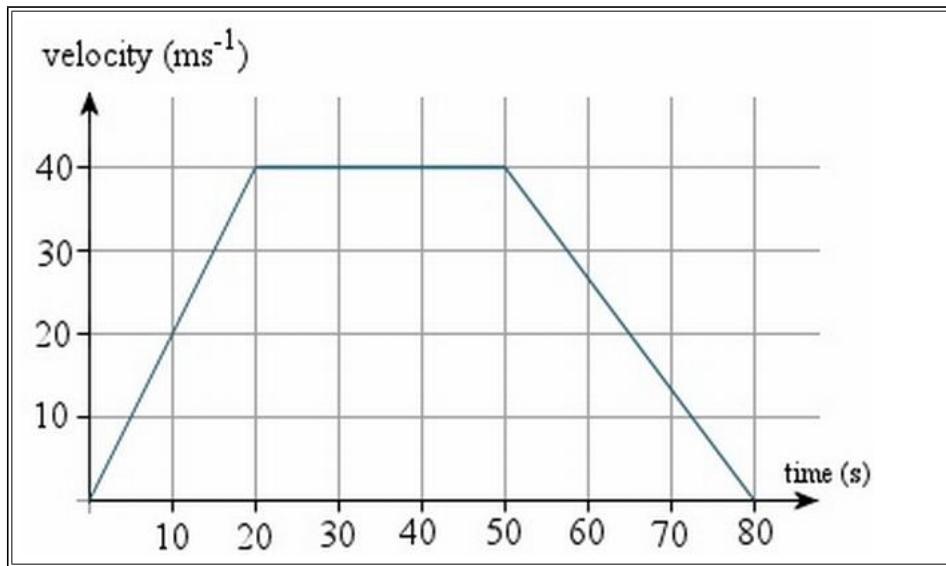
b) The distance travelled is the area of the trapezoid (trapezium).

$$\text{distance} = \frac{(a+b)h}{2} = \frac{(8+3)(3)}{2} = 16.5 \text{ m}$$

$$\text{c) average speed} = \frac{\text{distance travelled}}{\text{time taken}} = \frac{16.5}{8} \\ = 2.1 \text{ ms}^{-1}$$

**Example 6 :** A speedboat starts from rest, accelerating at  $2 \text{ ms}^{-2}$  for  $20 \text{ s}$ . It then continues at a steady speed for a further  $30 \text{ s}$  and decelerates to rest in  $30 \text{ s}$ . Find:

- (a) the distance travelled in m,
- (b) the average speed in  $\text{ms}^{-1}$  and,
- (c) the time taken to cover half the distance.



**Solution :** a) distance = area of trapezium =  $\frac{(a+b)h}{2}$

$$= \frac{(80+30)(40)}{2}$$

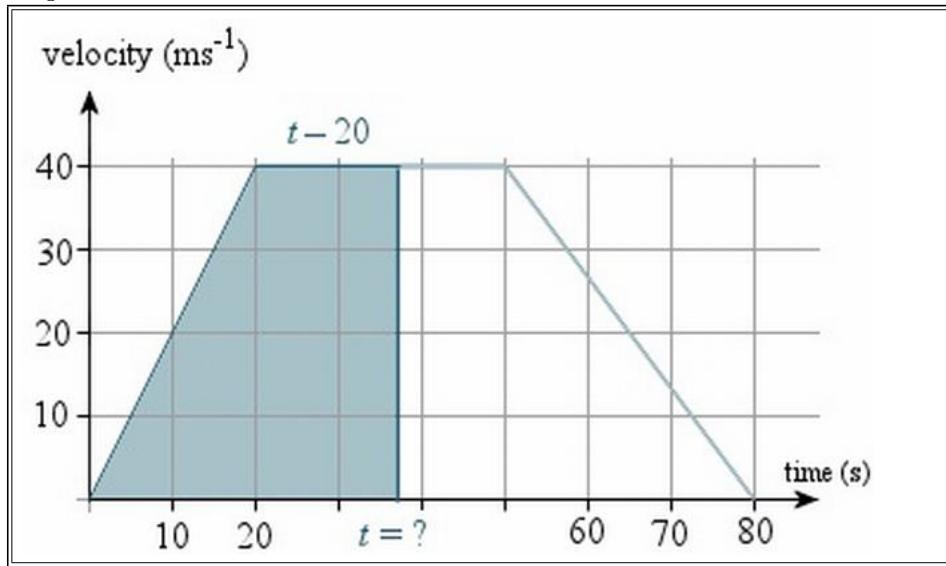
$$= 2200 \text{ m}$$

b) average speed =  $\frac{\text{distance travelled}}{\text{time taken}}$

$$= \frac{2200}{80}$$

$$= 27.5 \text{ ms}^{-1}$$

c) We need to find the time when the area of the trapezium is half of its original area, or 1100m, as shown in the graph.



The base of this unknown trapezium has length  $t$ , and the top of the trapezium will have length  $t-20$ . So we have:

$$\text{area of trapezium} = \frac{(a+b)h}{2}$$

$$1100 = \frac{(t + [t - 20]) 40}{2} = 20(2t - 20)$$

$$55 = 2t - 20$$

$$75 = 2t$$

$$t = 37.5 \text{ s}$$

So it will take 37.5 s to cover half the distance.

### 5.1.2 The Second Equation

Proceeding similar to above, the equation  $a = \frac{dv}{dt}$  implies

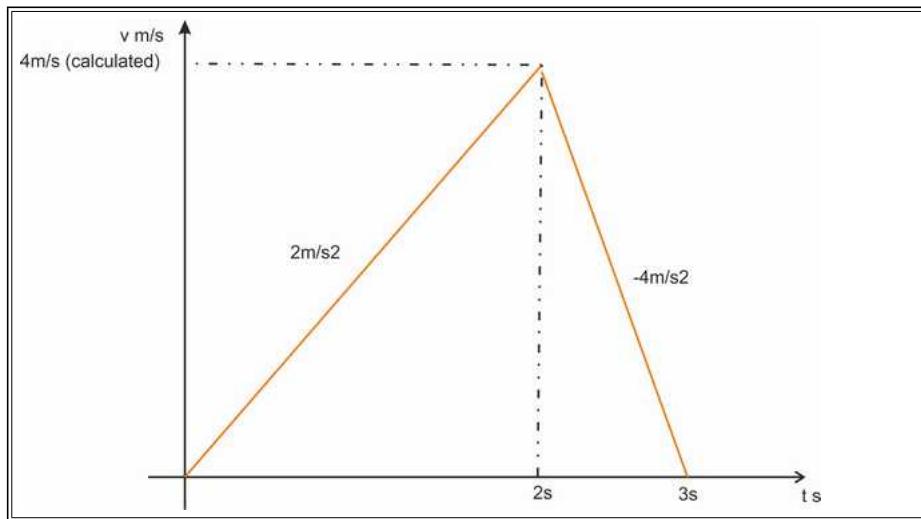
- i) The Slope of Velocity-Time Graph is Instantaneous Acceleration.
- ii) The Area under Acceleration-Time Graph is Change in Velocity.  
 { The second one requires the manipulation ,  $dv = adt$  i.e.  $\int dv = \int adt$  }

A few of the following examples illustrate it.

**Example 1:** A car starts from rest acquires a velocity  $v$  with uniform acceleration  $2ms^{-2}$  then it comes to stop with uniform retardation  $4ms^{-2}$ . If the total time for which it remains in motion is 3 sec, the total distance travelled is:

- a) 2 m
- b) 3 m
- c) 4 m
- d) 6 m

{Hint: For solving this problem, we draw the graph of the problem,



According to graph, let the time when it reaches maximum velocity be  $T$ , and the maximum velocity be  $V$ .

$$\Rightarrow V = 2XT \text{ and also } V = 4X(3-T)$$

Equating the equations,

$$2T = 12 - 4T = V$$

$$\Rightarrow 6T = 12$$

$$\Rightarrow T = 2$$

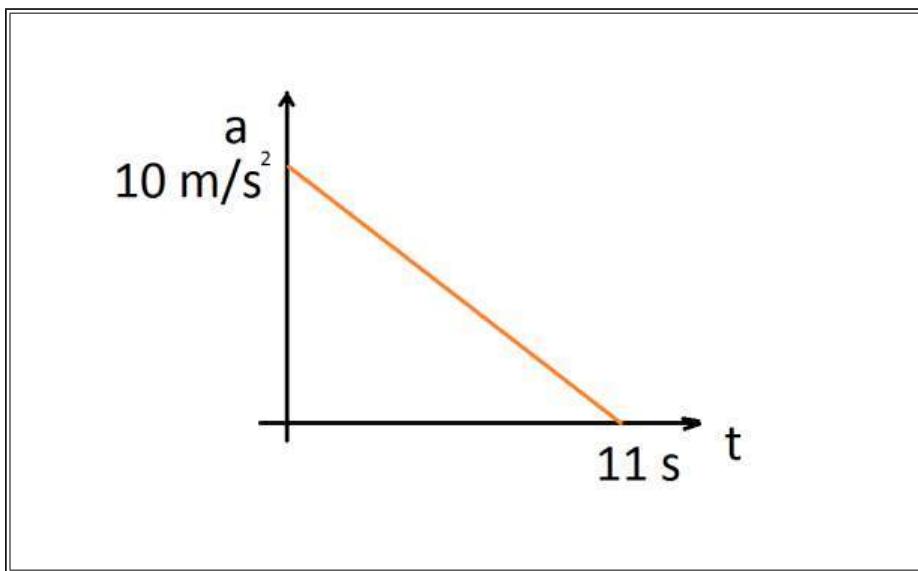
$$\Rightarrow V = 2T = 4$$

Calculating the area under the graph using the calculated parameters, Area =  $1/2 \times 4 \times 3 = 6$  m

So , area under the graph is 6m = displacement . Also, as all the area is on the positive side, so distance = 6m.

}

**Example 2:** A particle starts from rest. Its acceleration ( $a$ ) vs time ( $t$ ) is as shown in the Figure. The maximum speed of the particle will be



- a) 110  $\text{m/s}$
- b) 55  $\text{m/s}$
- c) 550  $\text{m/s}$
- d) 660  $\text{m/s}$

{ Hint : Writing the equation of the graph , we get  $\frac{a}{10} + \frac{t}{11} = 1$

$$\Rightarrow a = \frac{10}{11}(11 - t)$$

Integrating, ( we will assume initial velocity to be zero as the body starts from rest. )

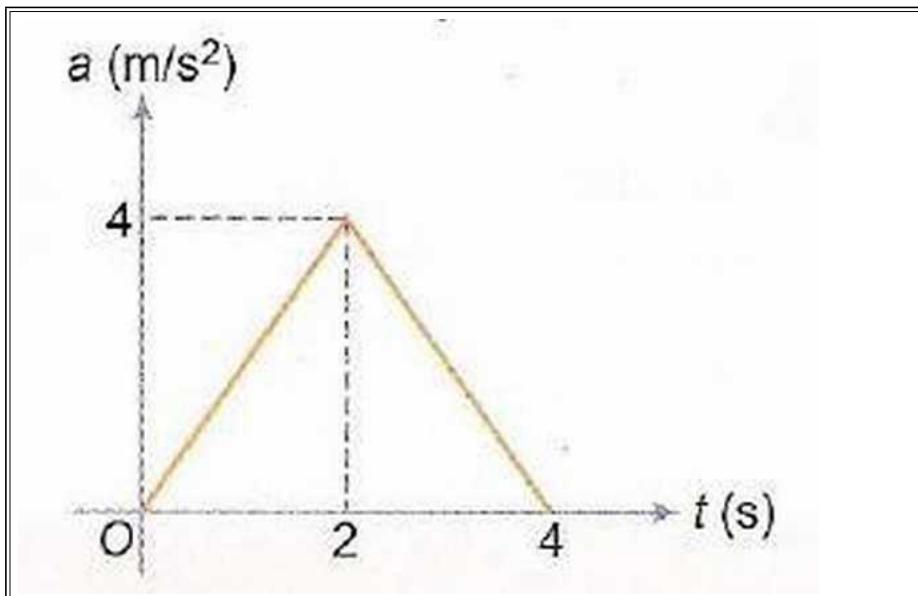
$$v = \frac{10}{11}\left(11t - \frac{1}{2}t^2\right)$$

Substituting  $t = 11\text{s}$

$$v_{11\text{s}} = 55\text{m/s}$$

Answer: b) is the correct answer }

**Example 3:** Acceleration-time graph of a particle moving in a straight line is shown in Figure. The velocity of particle at time  $t = 0$  is 2  $\text{m/s}$ . Velocity at the end of fourth second is



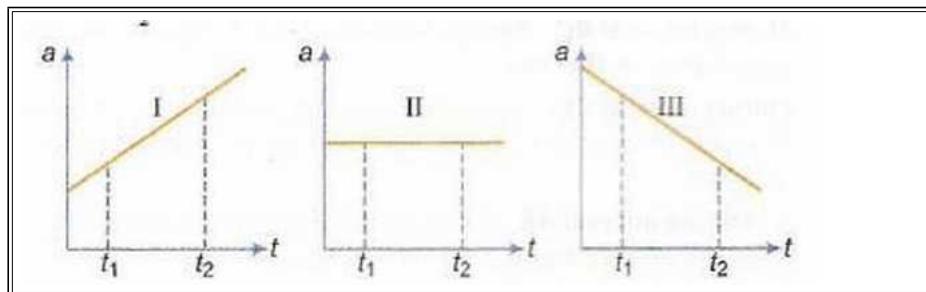
- a) 8  $\text{m/s}$
- b) 10  $\text{m/s}$
- c) 12  $\text{m/s}$

d) 14 m/s

{ Hint: Area under the acceleration-time graph is change in velocity. Area of the triangle is Half ( into ) base ( into ) altitude = 8m/s. Adding the initial value of 2m/s , we get  $2 + 8 = 10\text{m/s}$ .

Answer: b) is the correct answer }

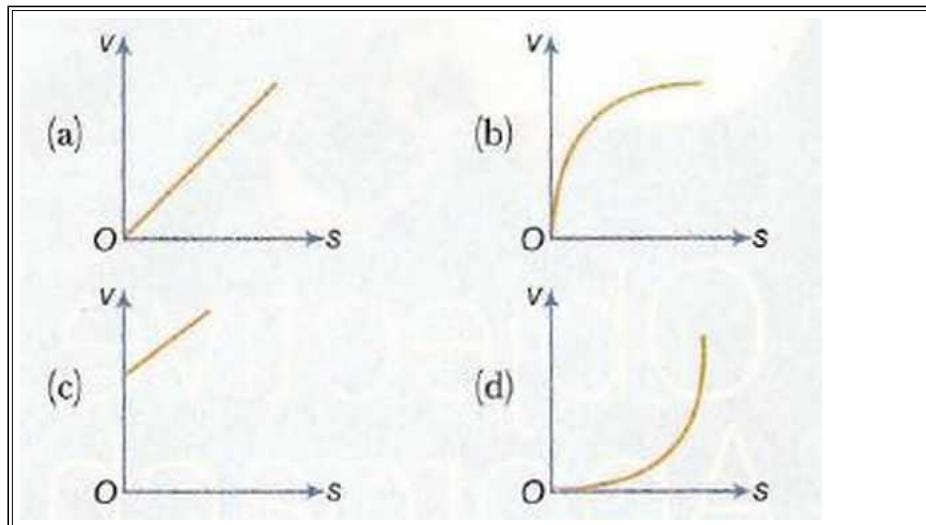
**Example 4:** Each of the three graphs represents acceleration vs time for an object that already has a positive velocity at time  $t_1$ . Which graph/graphs show an object whose speed is increasing for the entire time interval between  $t_1$  and  $t_2$ ?



- a) Graph I only
- b) Graphs I and II
- c) Graphs I and III
- d) Graphs I, II and III

{Hint: Area under the acceleration time graphs give change in velocity. In all the three figures, the area under the graphs are +ve, hence velocity is increasing in all cases. As the initial velocity is +ve , in all three cases the velocity remains throughout positive. So , the speed is also increasing in all cases.}

**Example 5:** A body starts from rest and moves along a straight line with constant acceleration. The variation of speed  $v$  with distance  $s$  is given by the graph



{ Hint: The problem given has  $v_o= 0$

$$\text{Now acceleration} = \text{constant} \text{ ( lets say } k \text{ )} = \frac{dv}{dt}$$

$$\Rightarrow k = v \frac{dv}{ds}$$

$$\Rightarrow \int_0^v v dv = \int_0^s k ds$$

$$\Rightarrow v = \sqrt{2ks}$$

The graph is proportional to square root function

Hence , b (as it is the only graph with such a property )

Answer : b) is the correct graph }

### 5.1.3 The Acceleration-Position Graph Variate

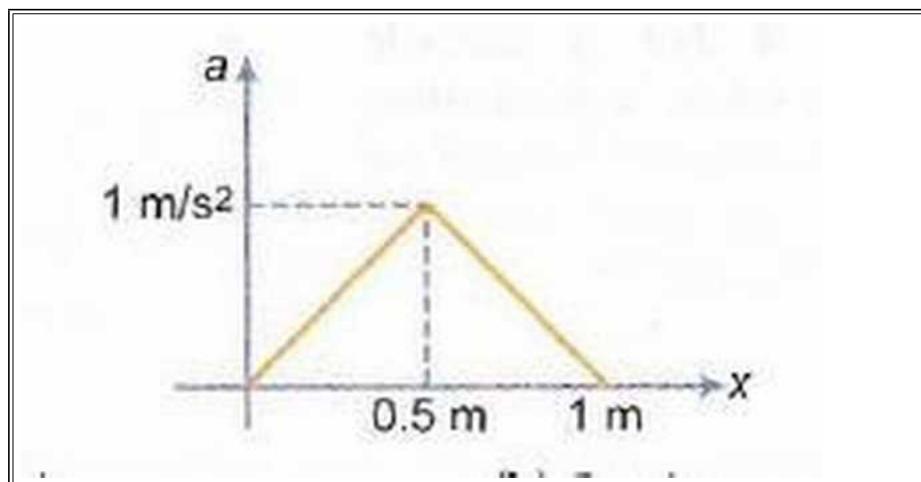
This kind of graph requires the manipulation of the Equation  $a = \frac{dv}{dt}$  as follows

$$a = \frac{dv}{dx} \cdot \frac{dx}{dt}$$

$$\Rightarrow a = \frac{dv}{dx} \cdot v$$

$\Rightarrow adx = vdv$  and integration can be performed to further solve it.

**Example 1:** A body, initially at rest, starts moving along x-axis in such a way that its acceleration vs displacement plot is as shown in the Figure. The maximum velocity of the particle is



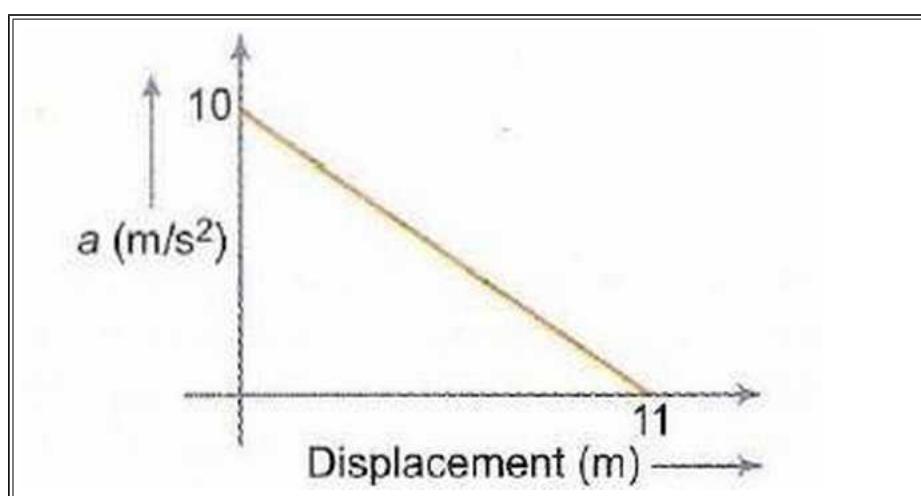
- a) 1 m/s
- b) 6 m/s
- c) 2 m/s
- d) None of these

{ Hint : The area under the a-x graph gives change in  $\frac{v^2}{2}$  as can be evaluated by Integration method.  
The area of triangle is  $(0.5) \times (1) \times (1) = 0.5$

$\Rightarrow v = 1\text{m/s}$ . Initial position is given to be 0 in the graph. Hence, we take only the positive sign.

Answer : a) is the correct answer. }

**Example 2 :** A particle initially at rest, it is subjected to a non-uniform acceleration a, as shown in the gure. The maximum speed attained by the particle is



- a) 605 m/s
- b) 110 m/s

- c) 55 m/s  
d) 110 m/s

{ Hint: The answer is 55m/s as calculated in the example above (In the second equation section). Hence, c) is the correct response.

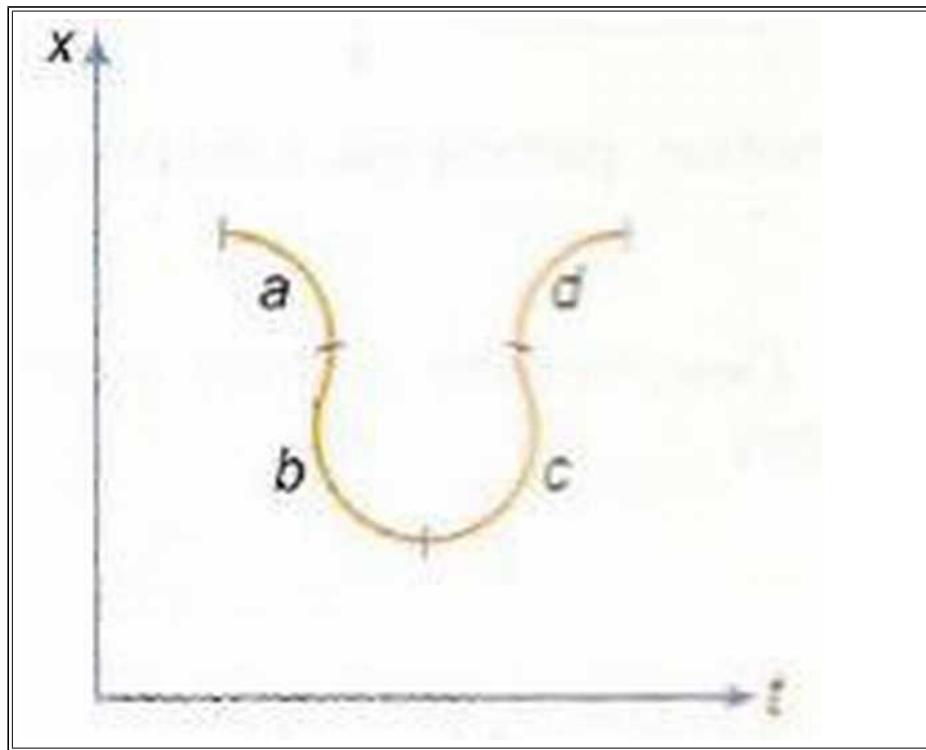
Answer : c) is the correct answer. }

#### 5.1.4 Sign of Acceleration from Position-Time Graph

The sign of Acceleration can be determined from the Position-Time Graph. The methodology involves of looking at the Concavity of the Graph

- i) If the graph is Concave-Up, the Acceleration is Positive.
- ii) If the graph is Concave-Down, the Acceleration is Negative.
- iii) If the graph is a straight line, the Acceleration is ZERO. { Irrespective of any other factor , such as the slope or direction of line}

**Example 1:** The graph given below is a plot of distance vs time. For which labelled region is the “Velocity Positive and the Acceleration Negative”



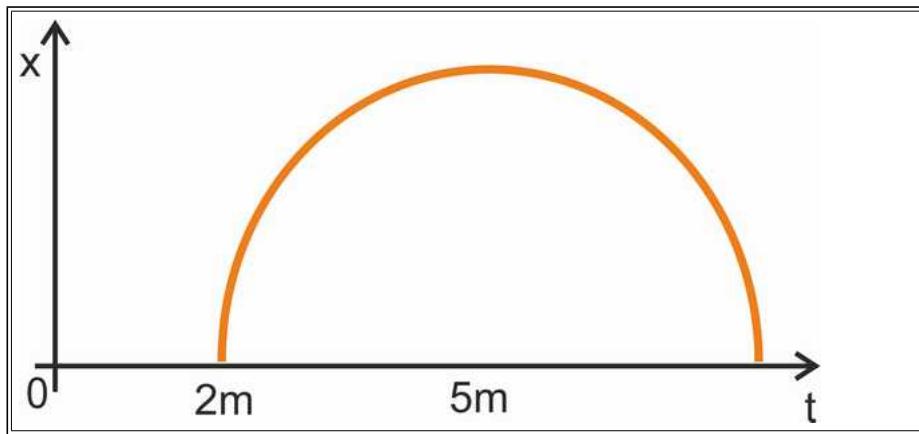
- a) a  
b) b  
c) c  
d) d

{ Hint: By the above mentioned propositions, d) is the required section with positive velocity and negative acceleration. }

#### 5.1.5 The Average-Velocity / Instantaneous Velocity , Equal Case

We know , that ( in a x-t graph) the slope of the Secant is the Average Velocity , whereas the slope of Tangent is the Instantaneous Velocity. The point where these two lines coincide, is the point where Average Velocity is equal to Instantaneous Velocity.

**Example 1:** Position-time graph is shown which is a semicircle from  $t = 2$  to  $t = 8$  s. Find time  $t$  at which the instantaneous velocity is equal to average velocity over first  $t$  seconds,



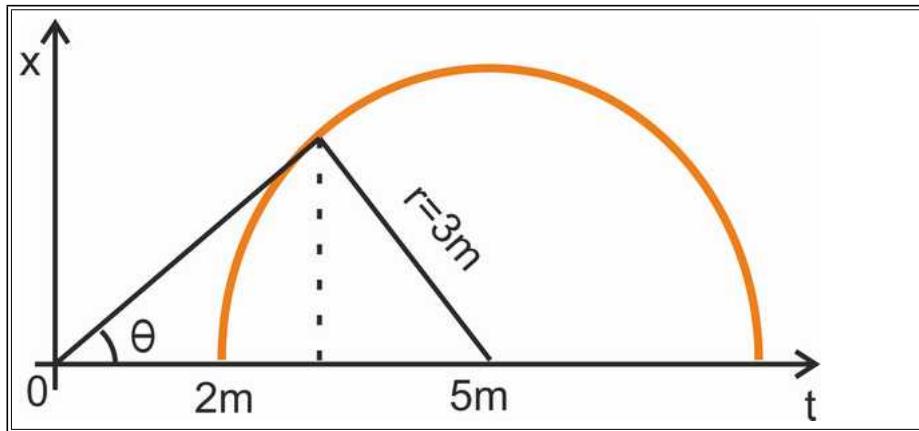
- a) 4.8 s
- b) 3.2 s
- c) 2.4 s
- d) 5 s

{ Hint: The tangent from 0 to the circle is drawn. Its normal passes through the center of the circle. Time at this instant needs to be calculated.

If  $H=5$ ,  $R = 3$ , Length of tangent = 4. (By Pythagoras.)

Angle which the tangent makes with the t axis is  $\theta = \sin^{-1}(3/5)$

So, the projection of tangent on t axis ( i.e. the required time ) =  $4 \cos \theta = 4 \times \frac{4}{5} = 3.2$



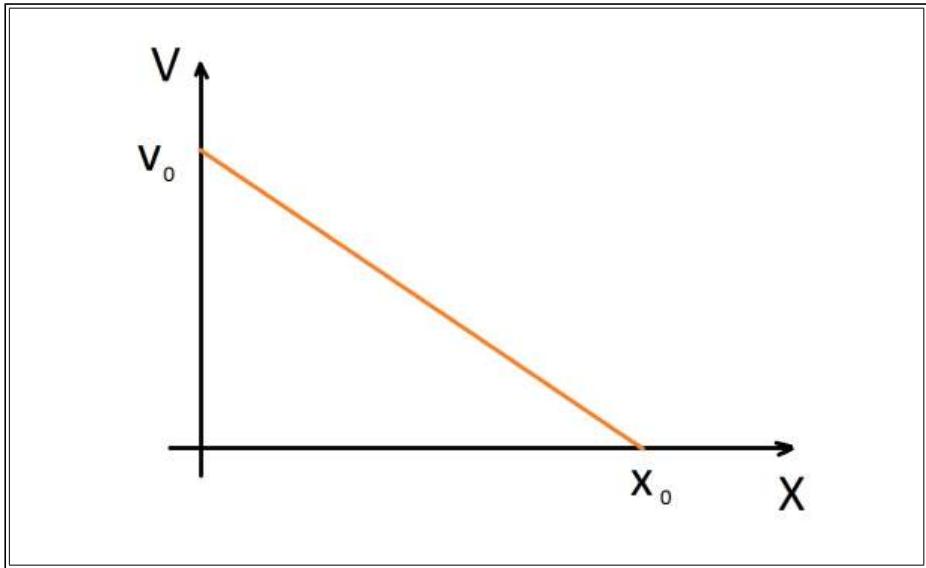
}

### 5.1.6 The Velocity-Displacement Case

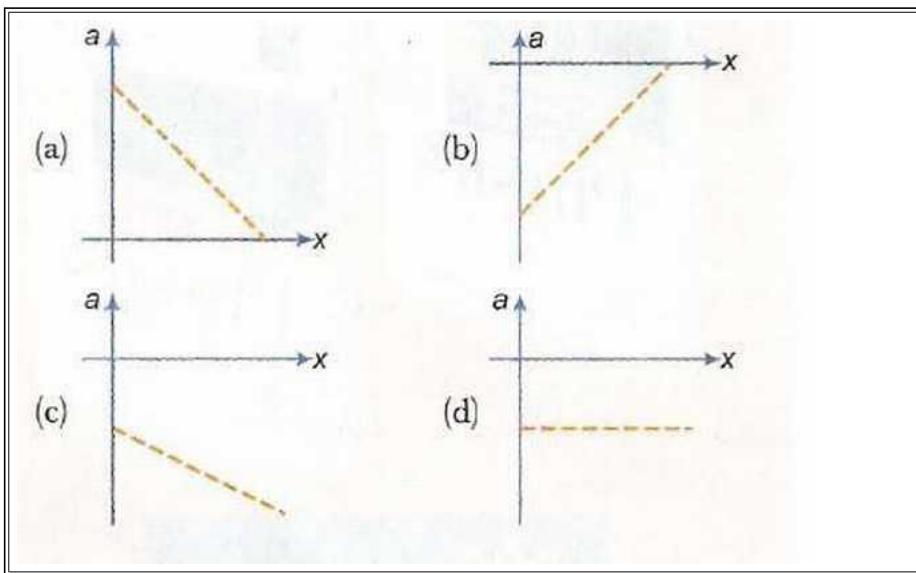
This can be handled in a similar way as Acceleration-Displacement case by integrating the respective equation. Here the problem is of  $v = f(x)$  type, which can be integrated by writing  $\frac{dx}{dt} = f(x)$

i.e.  $dx = f(x)dt$

**Example 1:** The velocity-displacement graph of a particle moving along a straight line is shown here.



The most suitable acceleration-displacement graph will be



{Hint: Using Co-Ordinate Geometry Result studied in +1 Mathematics, we get the equation of the graph

$$\frac{v}{v_o} + \frac{x}{x_o} = 1$$

We are supposed to find the a-x graph from this.

So, we rewrite this equation as  $v = v_o(1 - \frac{x}{x_o})$

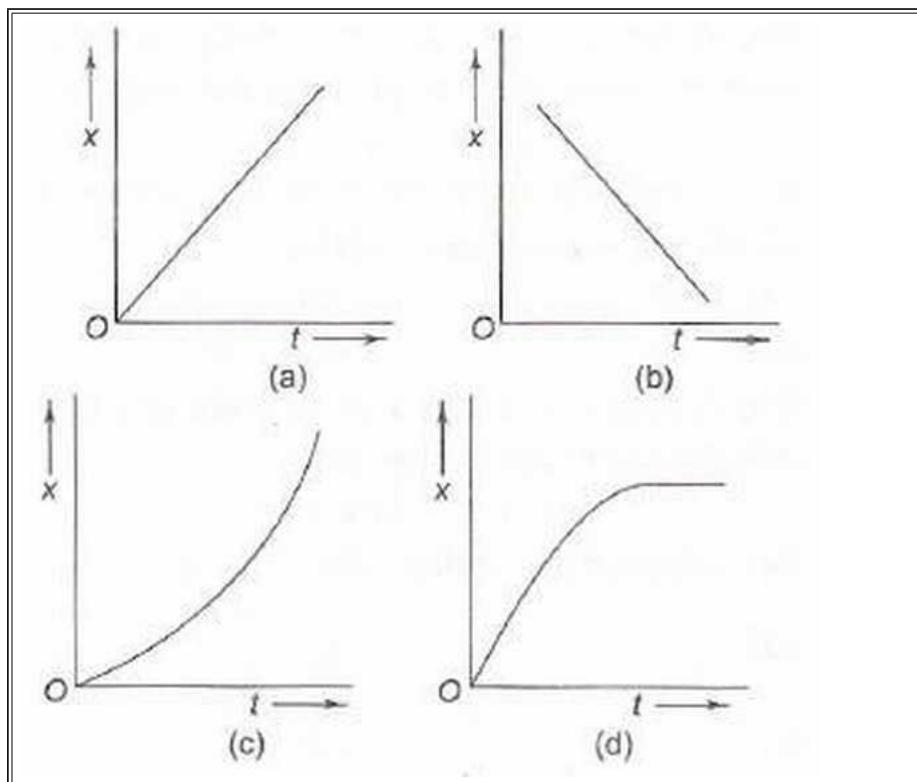
Differentiating, we get  $a = -\frac{v_o}{x_o}v = -\frac{v_o^2}{x_o}(1 - \frac{x}{x_o})$

Hence b) is the requisite graph, the only graph with a +ve slope, a negative y intercept and a positive x intercept.

Answer: b) is the correct answer. } <sup>1</sup>

**Example 2:** The velocity (v) of a body moving along the positive x-direction varies with displacement (x) from the origin as  $v = kx$ , where k is a constant. Which of the graphs shown in Fig. correctly represents the displacement-time (x - t) graph of the motion?

<sup>1</sup>The problem has been solved wrong in the Extended First Edition and Third Edition released earlier this month. The date is 23-March-2017 today, as of this writing. So, a useful Errata.



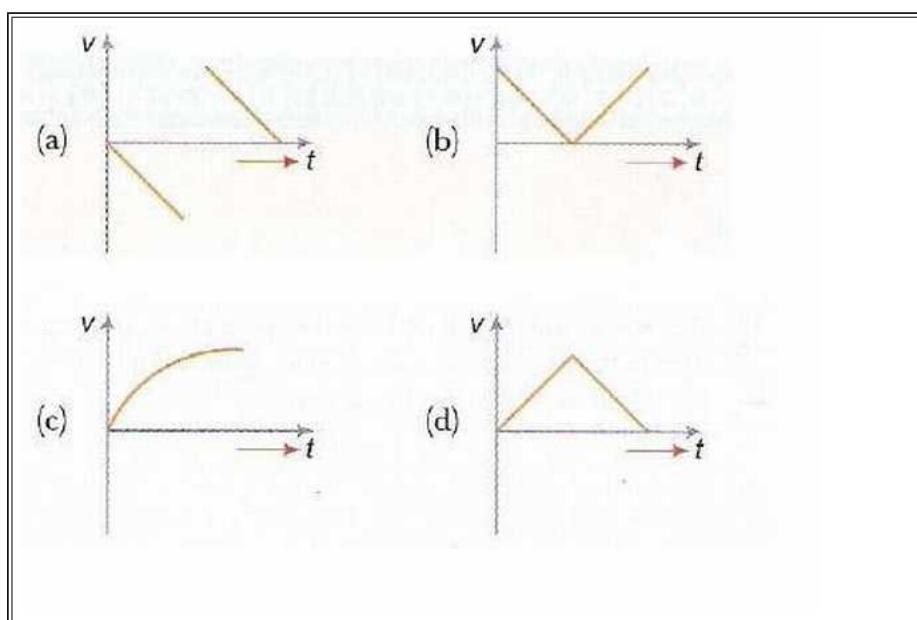
{Hint: The variable  $p$  removes the dependence of  $v$  on  $x$  and gives emphasis only on the first condition that body is moving along positive  $x$ -direction. In Graphs a), c) body is moving along positive  $x$ -direction, However, a) is a specific case when  $p$  is proportional to  $x$  and not the general case. Only c) covers the general case of all possible  $p$  and still moving in positive  $x$ -direction. Hence c) is the correct answer}

Answer: c) is the required answer. }

### 5.1.7 Motion Under Free Fall due to Gravity

In such examples, the governing equations rule and the coordinate system needs to be properly chosen.

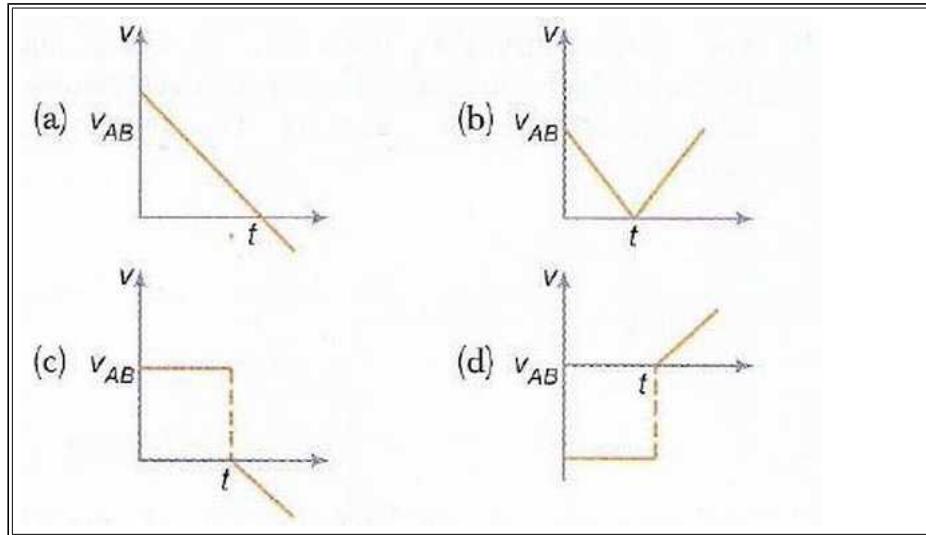
**Example 1:** Which of the following graphs correctly represents velocity-time relationship for a particle released from rest to fall freely under gravity?



{ Hint: If we take the downward axis as positive,  $v$  will keep on increasing till the object hits something.}

So, a) is the correct answer.}

**Example 2:** A body A is thrown vertically upwards with such a velocity that it reaches a maximum height of  $h$ . Simultaneously another body B is dropped from height  $h$ . It strikes the ground and doesn't rebound. The velocity of A relative to B vs time graph is best represented by (upward direction is positive.)

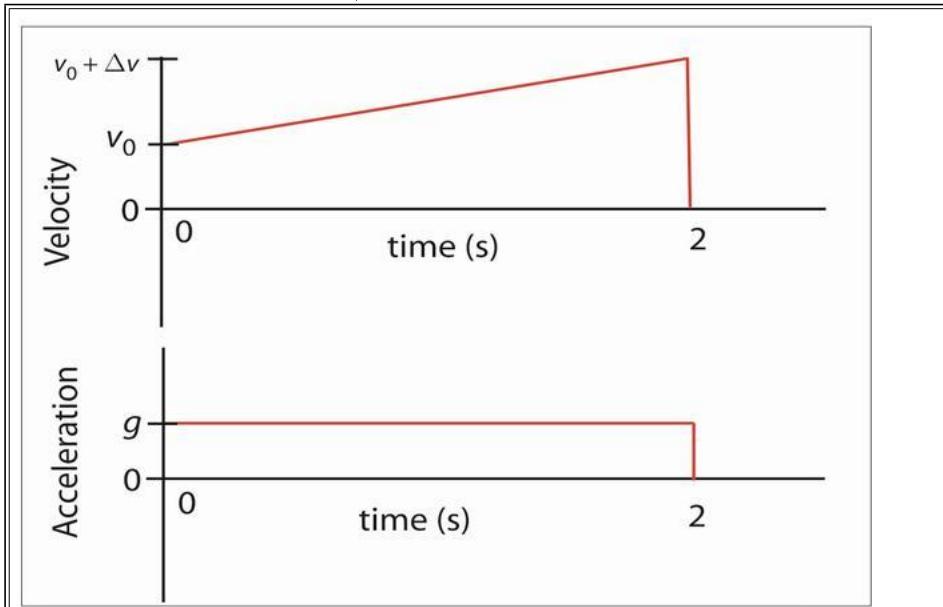


{ Hint: Before the strike, body A has velocity  $u - gt$  whereas body B has velocity  $-gt$ . So, a constant difference of  $u$  remains. Before strike,  $u - gt_o + gt_o = u$ . However, after that it is  $u - gt$ , the time being  $t_o = u/g$  of strike. So, the negative slope line starts from the x-axis and a discontinuity comes into picture.

So, C) is the required graph.}

**Example 3 :** A ball is thrown vertically downward from a 120-m high building. The ball hits the ground in 2 seconds. How fast was the ball thrown?

Sketches of the velocity and acceleration graphs are shown in Fig. 1. For simplicity, the downward direction is assumed to be positive, and, for ease of calculations, the freefall acceleration  $g$  is taken to be 10 m/s<sup>2</sup>. Knowing that the area under the acceleration graph is equal to the change in velocity ( $\Delta v$ ) of the object yields  $\Delta v = gt = 10 \text{ m/s}^2 \times 2 \text{ s} = 20 \text{ m/s}$ .

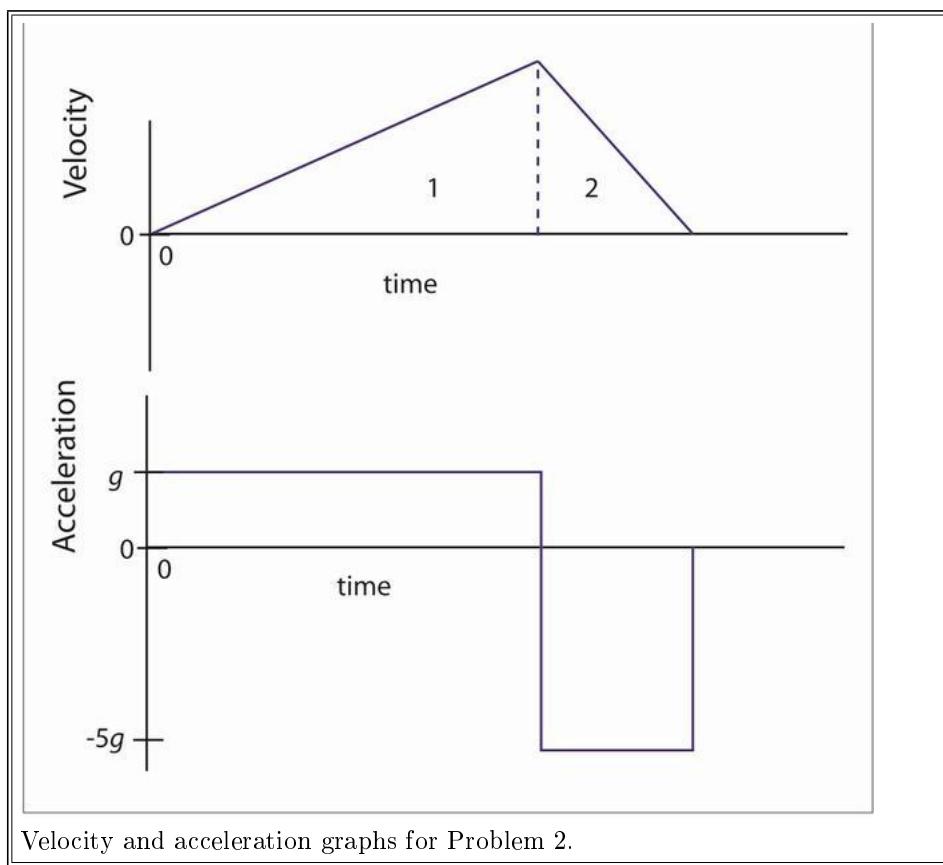


Velocity and acceleration graphs for Problem 1.

The area under the velocity graph is the displacement, which was given to be 120 m. Breaking the area under graph into a rectangle and a triangle yields  $120 \text{ m} = v_0 3 \text{ s} + \frac{1}{2} 2 \Delta v 3 \text{ s} = 2 \text{ s} 3 v_0 + 12 20 \text{ m/s} 3 2 \text{ s}$ . (2) One can easily solve this for the initial velocity of the object, thus obtaining the answer to the problem (50 m/s is a quite unrealistic initial velocity for a thrown ball). No explicit use of the standard kinematic equations is made; the solution is based on only the graphs. The above problem is relatively simple; to see the real power of the method requires a more difficult 1-D kinematics problem.

**Example 4 :** Determined to test gravity, a student walks off the cN Tower in Toronto, which is 553 m high, and falls freely. His initial velocity is zero. The rocketeer arrives at the roof of the building 5 seconds later to save the student. The rocketeer leaves the roof with an initial velocity downward and then is in freefall. In order both to catch the student and to prevent injury to him, the rocketeer should catch the student at a sufficiently great height and arrive at the ground with zero velocity. The upward acceleration that accomplishes this is provided by the rocketeer's jet pack, which he turns on just as he catches the student; before then the student is in freefall. To prevent discomfort to the student, the magnitude of the acceleration is limited to five times gravity. How high above the ground must the rocketeer catch the student?

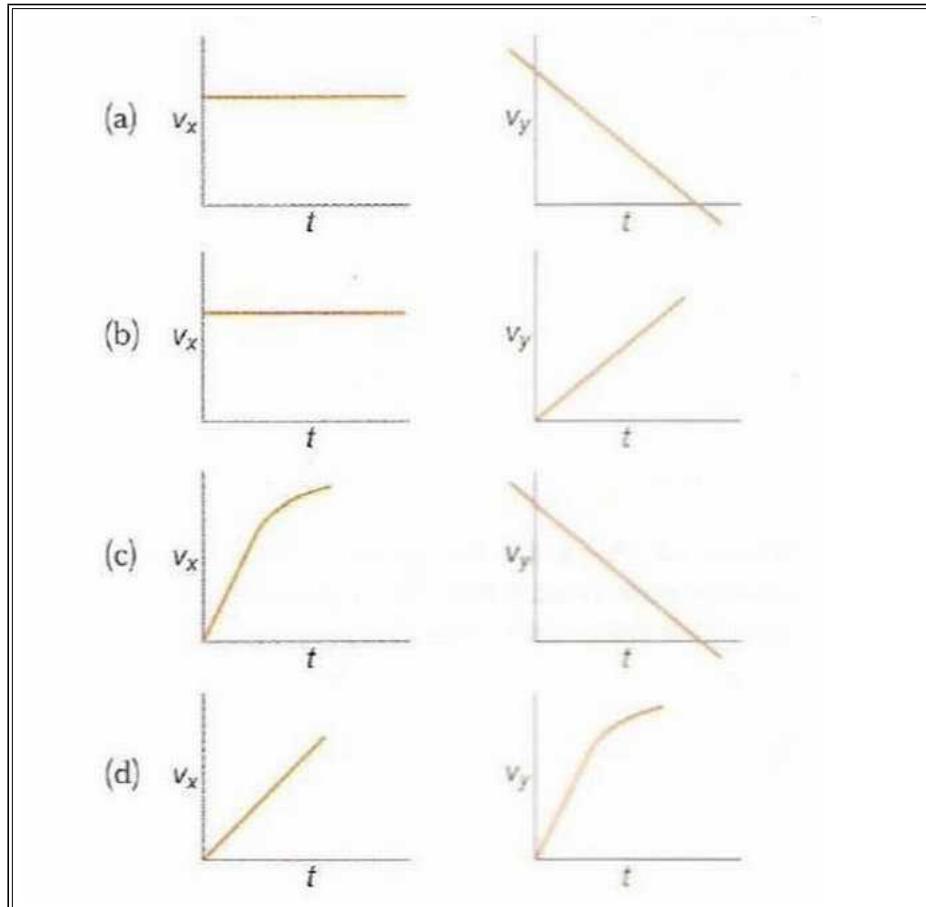
**Solution :** As I was grading the assignment, one student's solution stuck out. When I first saw it, I was convinced that something must be wrong as the problem had been difficult for me and could not be that simple. I was wrong. The simple solution consists of sketching the velocity and acceleration graphs for the falling student (Fig. 2; down is taken as the positive direction) and using a bit of reasoning. Since the overall change in the student's velocity during his motion is zero, the total area under the acceleration-versus-time graph must equal zero. This area consists of a positive part (above the time axis) and a negative part (below the time axis). The two rectangular areas must have equal magnitude, and since their heights differ by a factor of 5, so must their widths (the two corresponding times). Therefore, the freefall time is five times longer than the time for slow-down to rest. Now, looking at the velocity graph, the area labeled 1 corresponds to the displacement while in freefall, and the area labeled 2 represents the displacement after the Rocketeer has caught the student. The triangles forming areas 1 and 2 have the same height, and the base (time) for area 1 is five times the base (time) for area 2. Therefore, area 1 must be five times larger than area 2. This means that area 2 must be  $1/6$  the total height of the building, or 92.2 m.



After studying this solution for a long time and finding no flaws in the physics, I pulled out my physics book and tried solving other one-dimensional kinematics problems in a similar manner. It quickly became obvious that they could be done using graphs, and in most cases this is the easier method. I was hooked and began teaching one-dimensional problem solving this way in all my classes. The next class period I asked the student whose solution this was why he chose to do the problem this way. He explained that we had emphasized graphs so much in class that they must be more useful than something we are simply supposed to sketch for the problems. I was amazed and appreciative as I now had a new way to teach problem solving. This kind of solution is more visual and helps get students away from hunting for the "correct equation." It has worked well for me at all levels of introductory physics, conceptual through calculus based. If you find other interesting problems that are especially suited to the above method, I would appreciate your sharing them.

### 5.1.8 Projectile Motion

**Example 1:** A shell is fired from a gun at an angle to the horizontal. Graphs are drawn for its horizontal component of velocity  $v_x$  and its vertical component of velocity  $v_y$ .

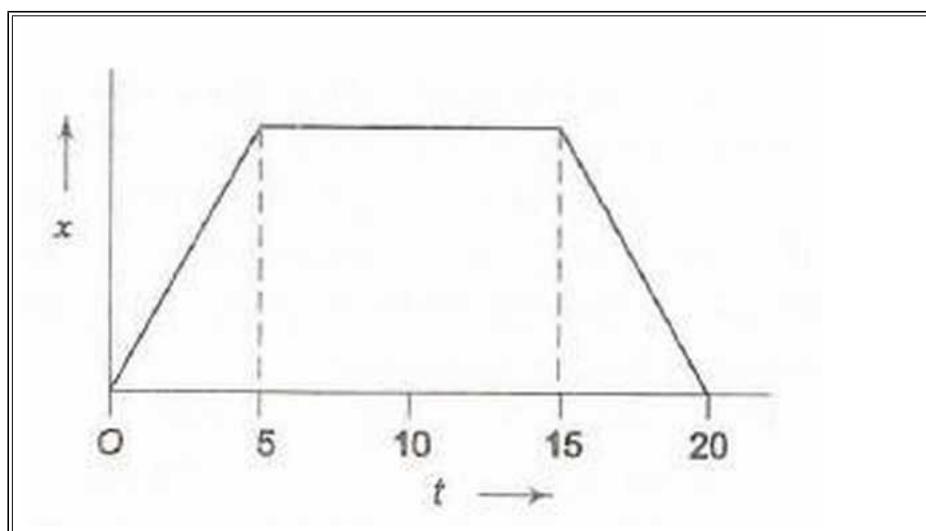


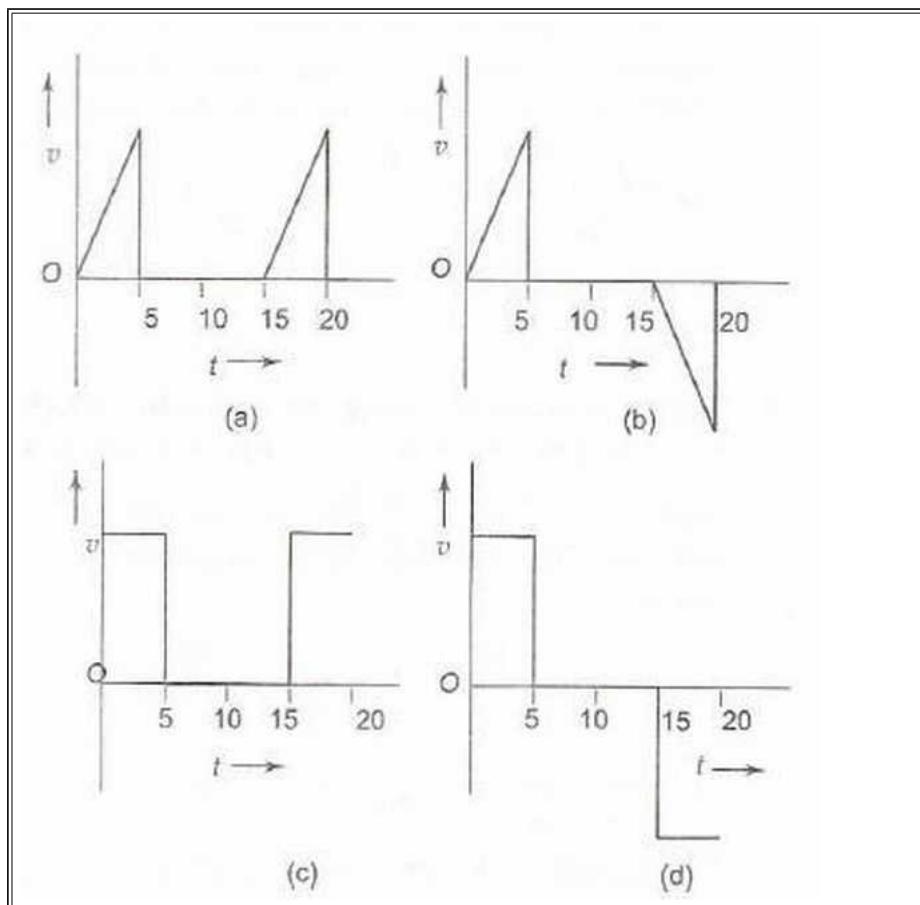
{ Hint:  $v_x$  would remain constant as  $ucos\theta$  and  $v_y$  would linearly decrease and go negative after maximum height is attained (if the fire angle is +ve).

So, a) is the requisite graph. }

### 5.1.9 Miscellaneous

**Example 1:** Figure shows the displacement-time (  $x-t$  ) graph of body moving in a straight line. Which one of the graphs shown in Fig. represents the velocity-time (  $v-t$  ) graph of the motion of the body.

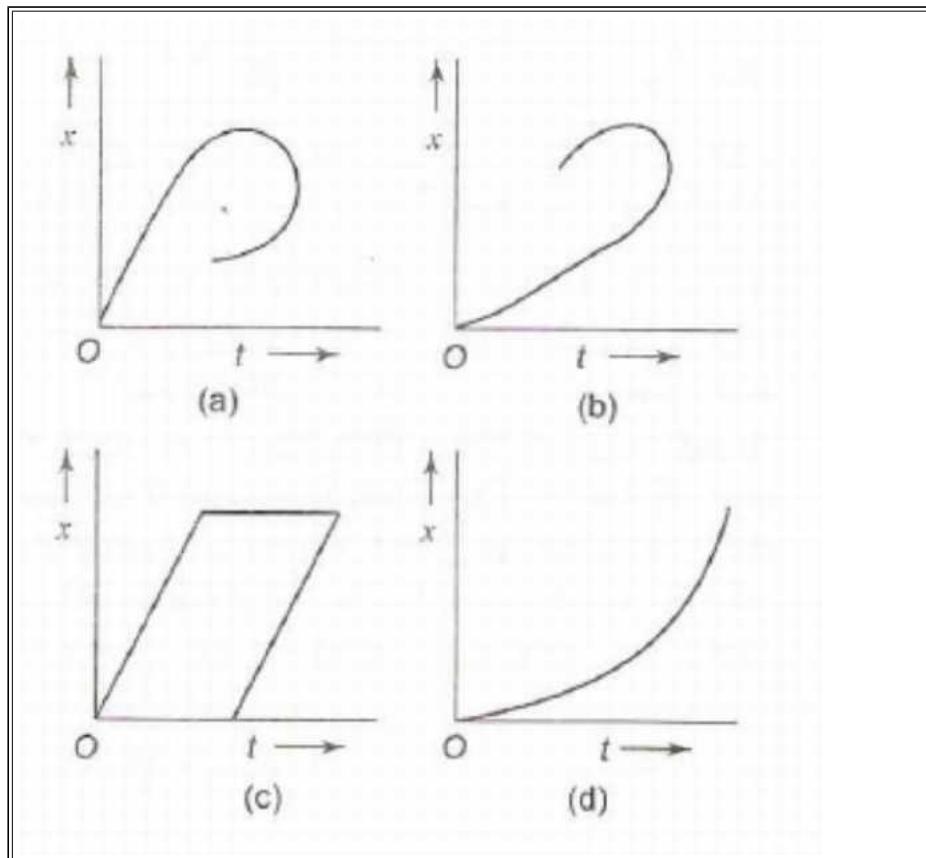




{ Hint: The graph has initially (0-5) a +ve slope, then zero slope and then (15-20) an equal -ve slope }

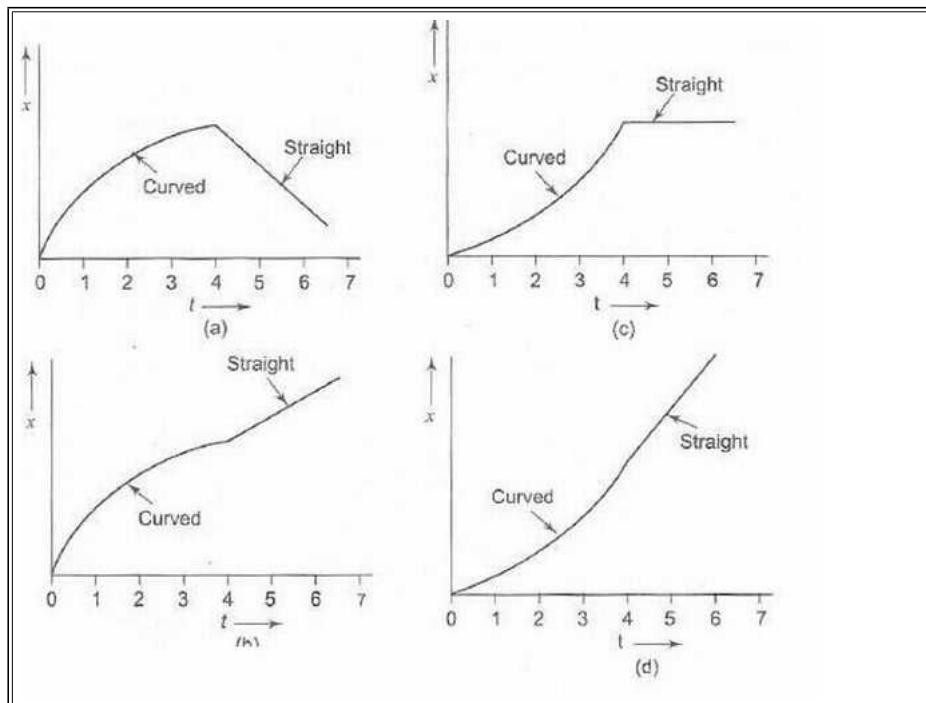
So, d) is the correct answer. }

**Example 2:** Which of the displacement-time ( $x-t$ ) graphs shown in Fig. can possibly represent one dimensional motion of a particle?



{ Hint: The object cannot be at two positions on a single time instant,  
So, d) is the correct option. }

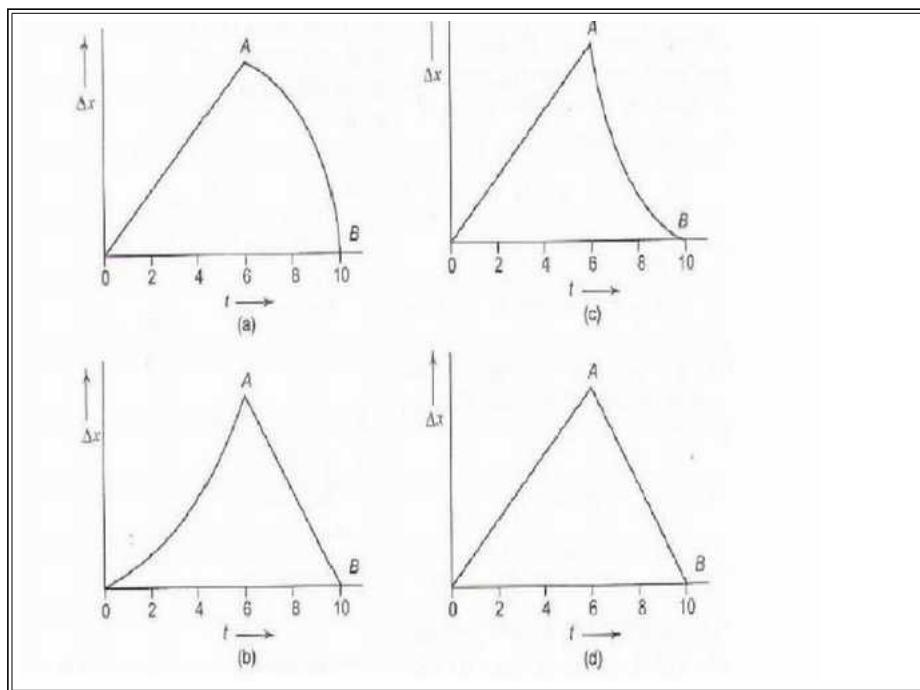
**Example 3:** A car starts from rest, accelerates uniformly for 4 seconds and then moves with uniform velocity.  
Which of the (x-t) graphs shown in Fig. represents the motion of the car upto  $t = 7$  s?



{ Hint: As the car is accelerating upto 4 seconds, the graph should be concave up. Further ahead , it moves with constant velocity , so a positive slope ahead of 4 seconds.

d) is the correct answer. }

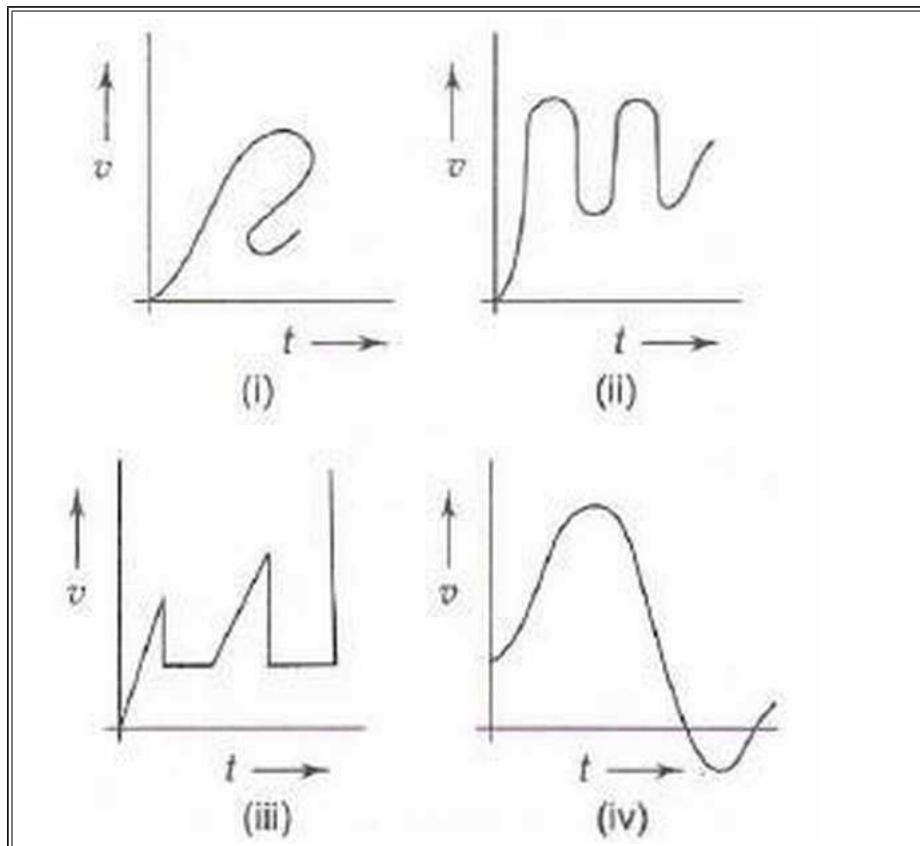
**Example 4:** Two stones are thrown up simultaneously with initial speeds of  $u_1$  and  $u_2$ , ( $u_2 > u_1$ ) . They hit the ground after 6 s and 10 s respectively. Which graph in Fig. correctly represents the time variation of  $\Delta x = x_2 - x_1$ , the relative position of the second stone with respect to the first upto  $t = 10$  s? Assume that the stones do not rebound after hitting the ground.



{ Hint : While both are in air, the difference of their velocity vectors would be a constant vector , so  $\Delta x = c_1 t$  . Also, after the first stone hits ground,  $\Delta x = c_2 t - x_o$  as the velocity component in x direction of second stone is constant. There is no discontinuity. So, both before and after one hits the ground , it would be a straight line.

Hence, d) is the correct answer. }

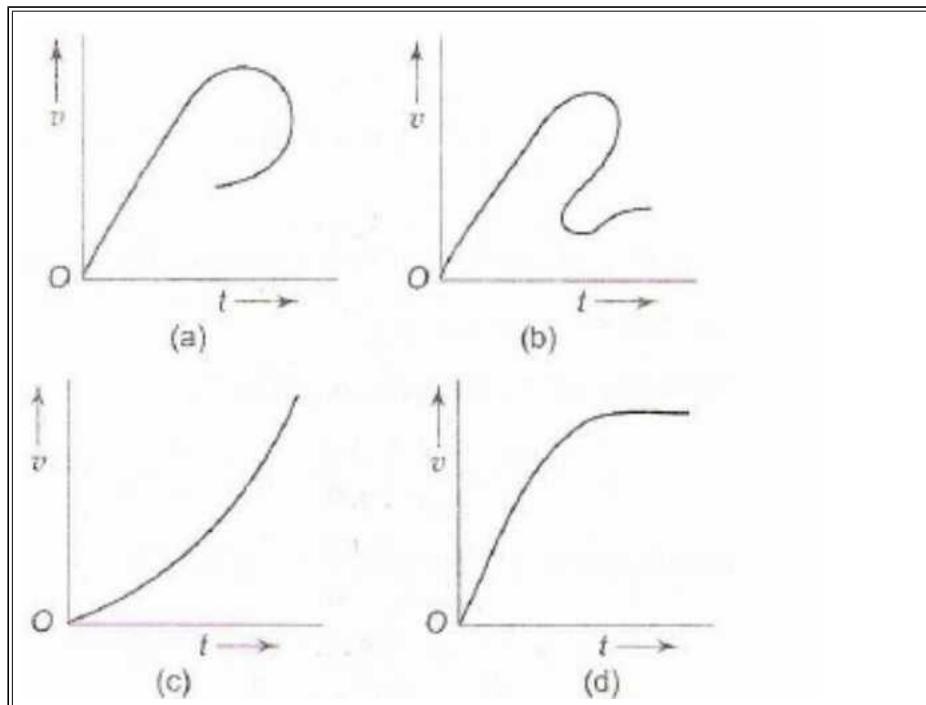
**Example 5:** Figure shows the velocity-time ( $v$  -  $t$ ) graphs for one dimensional motion. But only some of these can be realized in practice. These are



- a) (i), (ii) and (iv) only
- b) (i), (ii) and (iii) only
- c) (ii) and (iv) only
- d) all

{ Hint: At one particular instant, the object cannot have two different velocities.  
Hence, c) is the correct answer. }

**Example 6:** Which of the velocity-time ( $v-t$ ) graphs shown in Fig. can possibly represent one-dimensional motion of a particle?

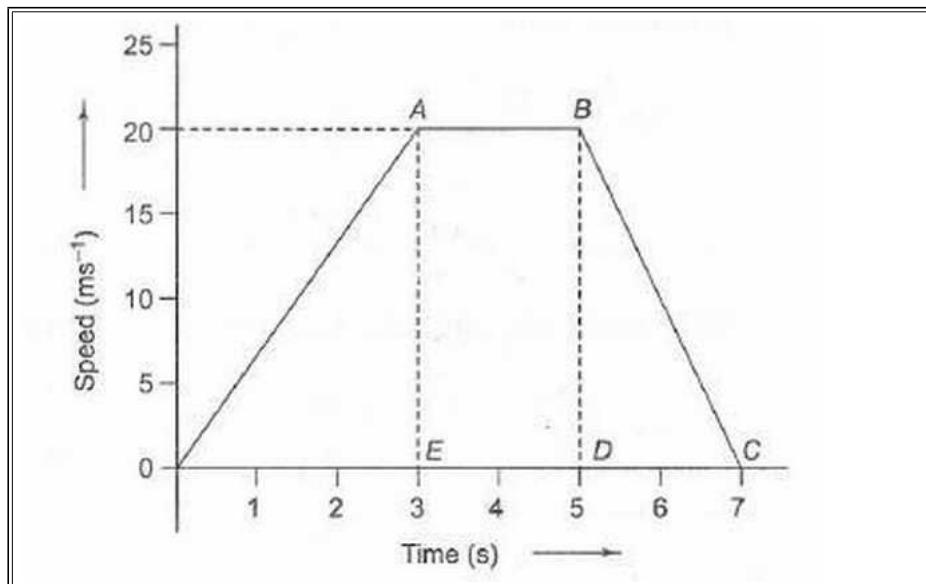


{Hint: In c) , the particle is constantly increasing in one dimension, In d) , it stops near the end.  
c),d) are the correct answers. }

## 5.2 Question Types

### 5.2.1 Passage Type

**Example:** The speed-time graph of the motion of a body is shown in Fig.



1. The accelerations of the body during the last 2 second is

a)  $\frac{20}{3} \text{ ms}^{-2}$

b)  $-\frac{20}{7} \text{ ms}^{-2}$

c)  $-10 \text{ ms}^{-2}$

d) Zero

2. The ratio of distance travelled by the body during the last 2 seconds to the total distance travelled by it is

a)  $1/9$

b)  $2/9$

c)  $3/9$

d)  $4/9$

3. The average speed of the car during the whole journey is

a)  $10 \text{ m/s}$

b)  $20 \text{ m/s}$

c)  $90/7 \text{ m/s}$

d)  $40/7 \text{ m/s}$

{Hint: 1. As no contradictory statements are present, we would take velocity as the value of speed only. Actually velocity is required for calculation of acceleration but here , speed doesn't contradict anything so we'll use it's value for velocity.

-10 from slope, c)}

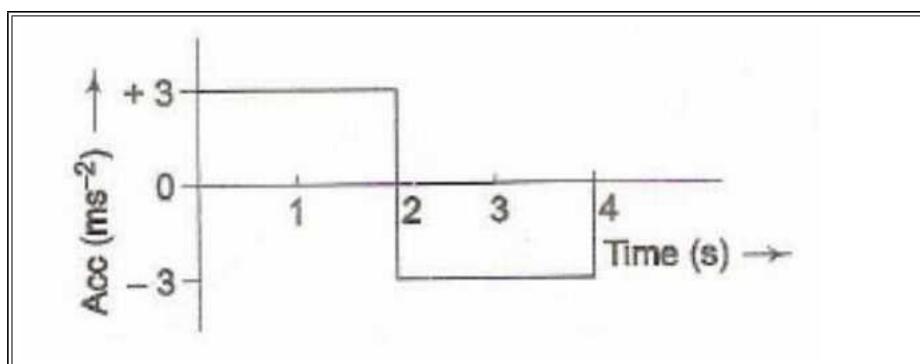
2. Speed time graph's area is distance. From area calculation, in last 2 seconds, the area is 20 and total area is 90.

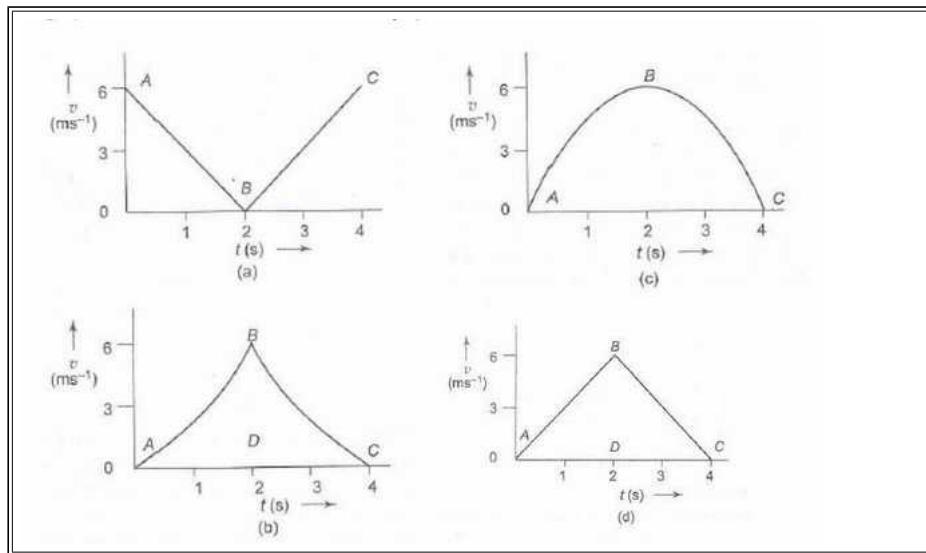
So,  $2/9$  is the required ration b)

3. Total distance from area is 90, and total time is 7.

So,  $90/7$ . c)}

**Example:** A body starts from rest at time  $t = 0$  and undergoes an acceleration as shown in Fig. Which of the graphs shown in Fig. represents the velocity-time (v-t) graph of the motion of the body from  $t = 0 \text{ s}$  to  $t = 4 \text{ s}$ ?





{Hint: d) is the v-t graph by calculating area function.}

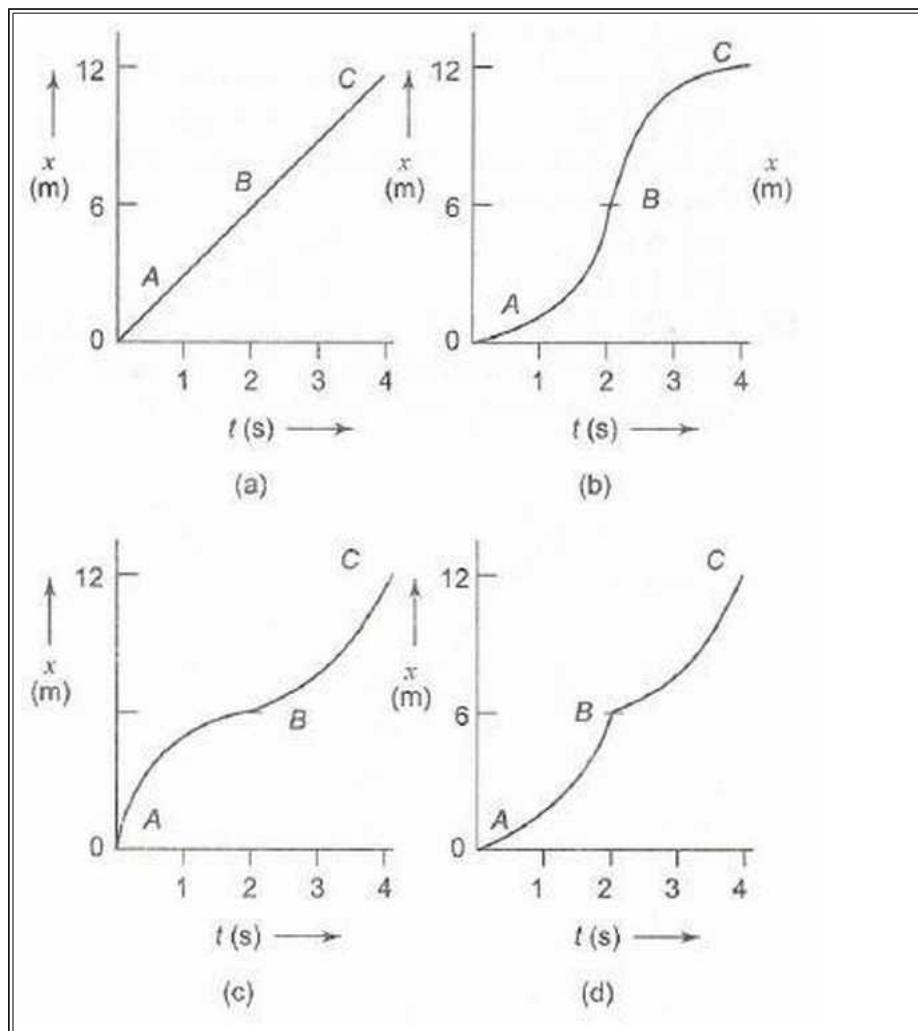
1. In Question above, what is the velocity of the body at time  $t = 2.5 \text{ s}$ ?

- a) 2.5 m/s
- b) 3.5 m/s
- c) 4.5 m/s
- d) 5.5 m/s

2. In above question, how much distance does the body cover from  $t = 0 \text{ s}$  to  $t = 4 \text{ s}$ ?

- a) 6 m
- b) 9 m
- c) 12 m
- d) 15 m

- 3 In above question, which of the graphs shown in Fig. represents the displacement-time ( $x$ - $t$ ) graph of the motion of the body from  $t = 0 \text{ s}$  to  $t = 4 \text{ s}$ ?



{ Hint: 1. The area under the accln-time graph gives change in velocity. Till 2.5s,  $6-1.5=4.5$  is the required area.

So, c)

2. Area under the v-t graph d) is 12 till 4 seconds.

So, c)

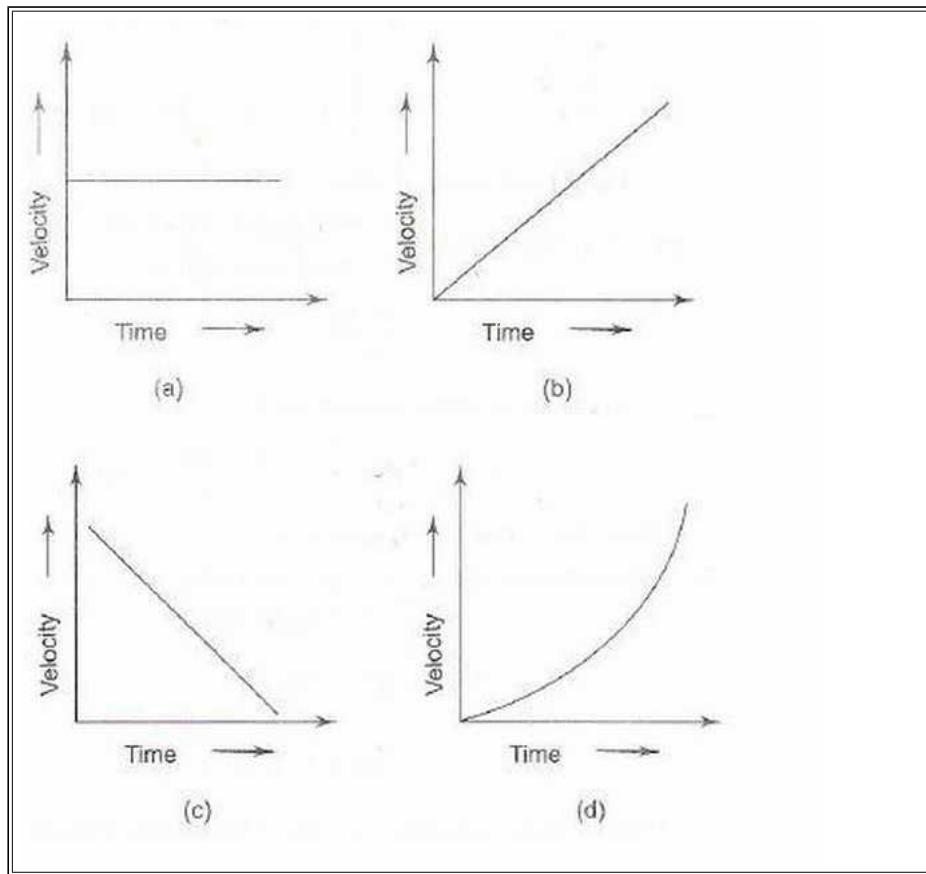
3. Till 2 seconds , the graph should be concave-up while from 2 to 4 it should be concave-down.

So, b)

}

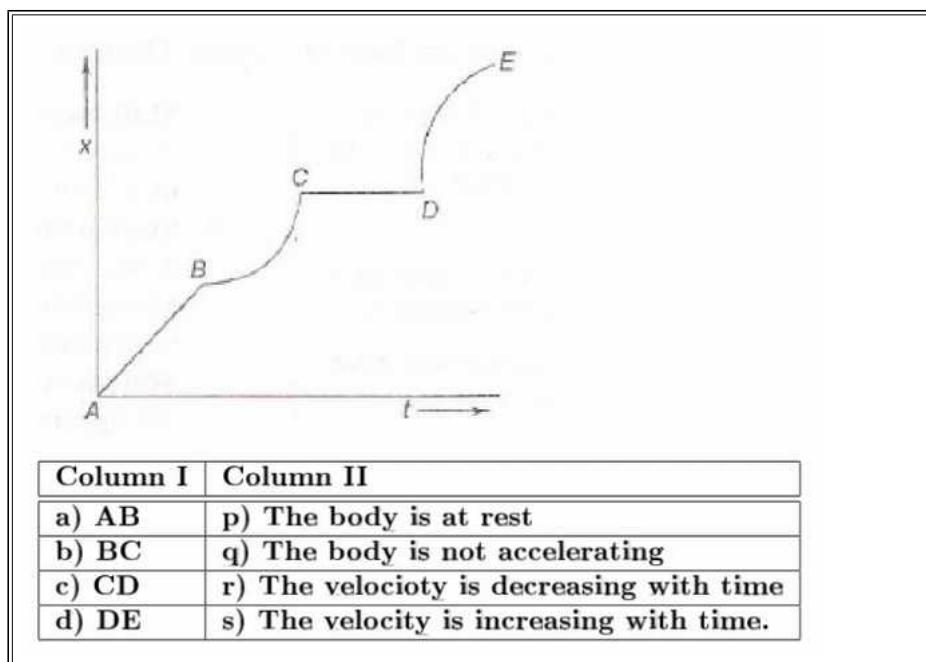
### 5.2.2 Matching

- Match the graphs (a), (b), (c) and (d) shown in Fig. with the types of motions (p), (q), (r) and (s) that they represent



- p) Motion with non-uniform acceleration  
 q) Motion of a body covering equal distances in equal intervals of time  
 r) Motion having a constant retardation  
 s) Uniformly accelerated motion.  
 { Hint: p->d , q->a , r ->c , s->a,b,c }

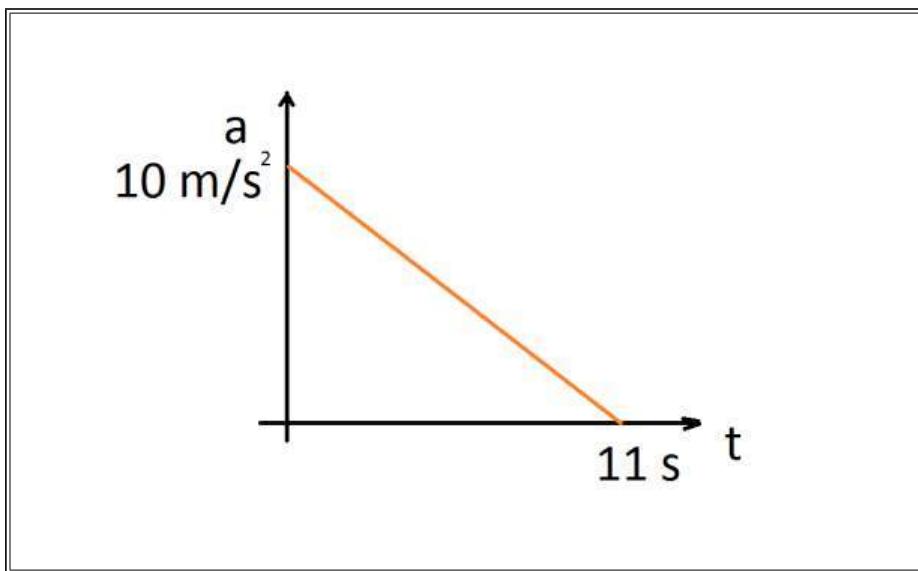
2. Figure shows the displacement -time ( $x - t$ ) graph of the motion of a body.



{ Hint p->c , q->a,c , r-> d , s->b }

### 5.3 Previous Years IIT Problems

**Q1:** A particle starts from rest. Its acceleration (  $a$  ) versus time (  $t$  ) is as shown in the figure. The maximum speed of the particle will be



a )  $110 \text{ m/s}$

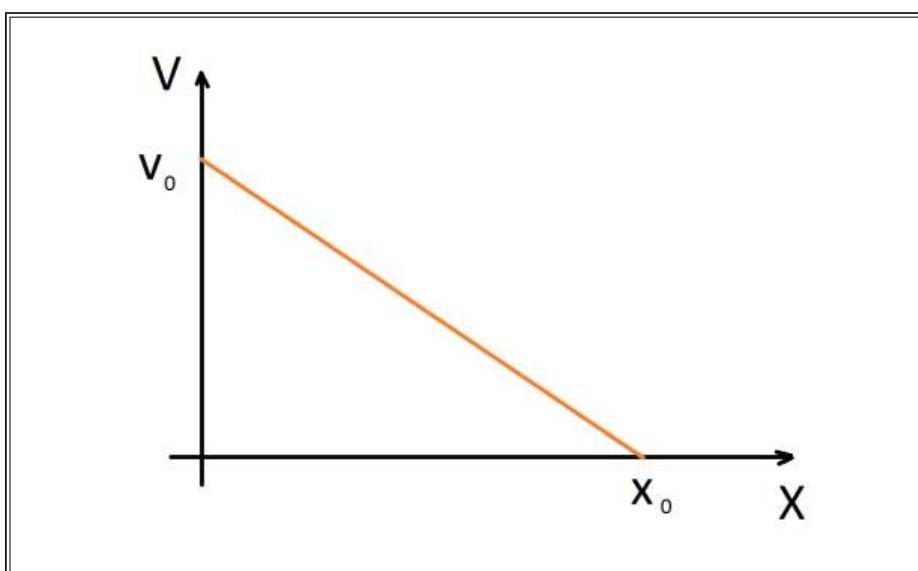
b )  $55 \text{ m/s}$

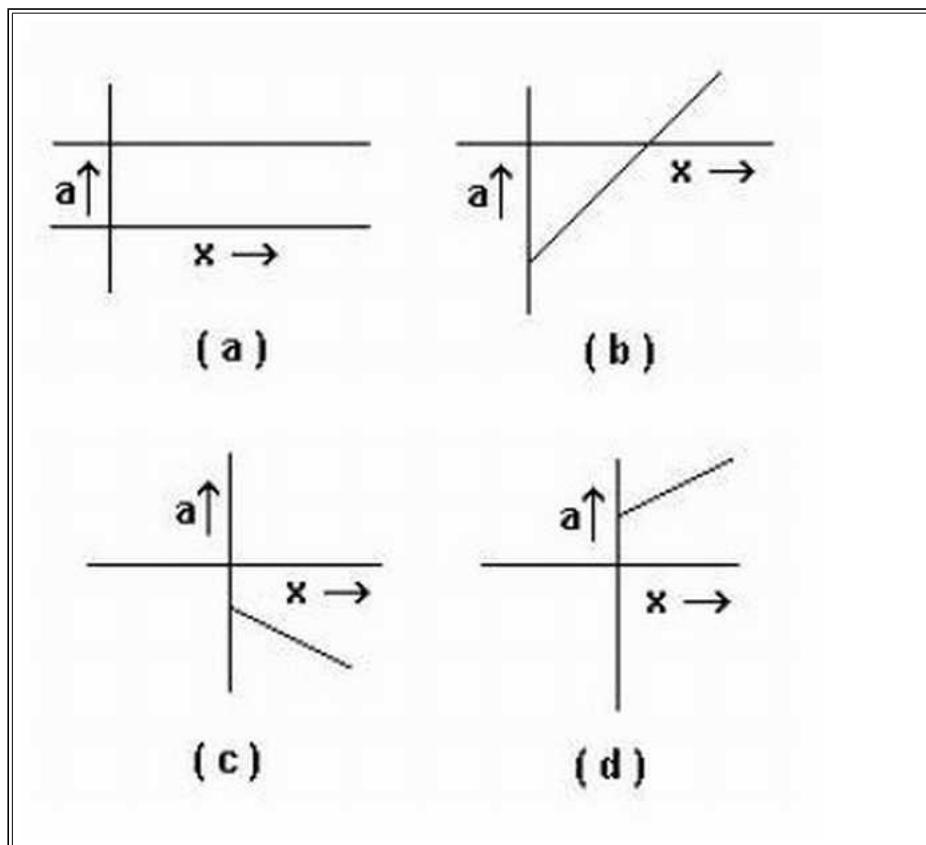
c )  $550 \text{ m/s}$

d )  $660 \text{ m/s}$

{ Hint : See In chapter examples for solution. }

**Q2:** If graph of velocity vs. distance is as shown, which of the following graphs correctly represents the variation of acceleration with displacement ?





{ Hint : The graph of the question is a straight line with the equation,  $\frac{x}{x_o} + \frac{v}{v_o} = 1$

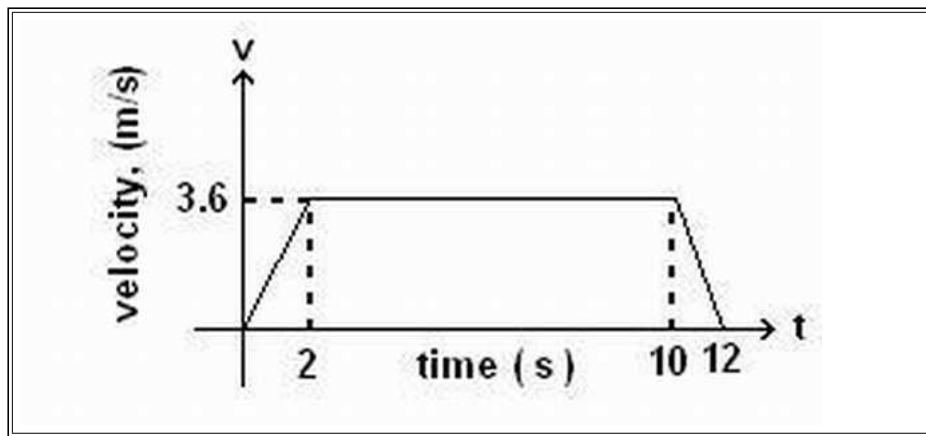
This gives ,  $v = v_o(1 - x/x_o)$

So, differentiating it, we get

$a = -v_o/x_o$  which is a constant. Only in a) it is shown to be a constant.

So, a) }

**Passage** A lift is going up. The variation in the speed of the lift is as given in the graph.



**Q3:** What is the height to which the lift takes the passengers ?

- a ) 3.6 m
- b ) 28.8 m
- c ) 36 m
- d ) cannot be calculated from the above graph

**Q4:** In the above graph, what is the average velocity of the lift?

- a ) 1 m/s
- b ) 2.88 m/s
- c ) 3.24 m/s
- d ) 3 m/s

**Q5:** In the above graph , what is the average acceleration of the lift?

- a )  $1.8m/s^2$
- b )  $-1.8m/s^2$
- c )  $0.3m/s^2$
- d ) zero

{Hint: Q3: Area under the graph is 36. Taking initial position as zero, c) is the best fit answer.

Q4. For av. velocity, total displacement / total time should be calculated. which is  $36/12 = 3m/s$ . d ) is the required answer.

Q5. The accln is 1.8 from 0s to 2s, 0 from 2s to 10s and -1.8 from 10s to 12s. So, area under the a-t graph is zero. So av. accln is zero d)

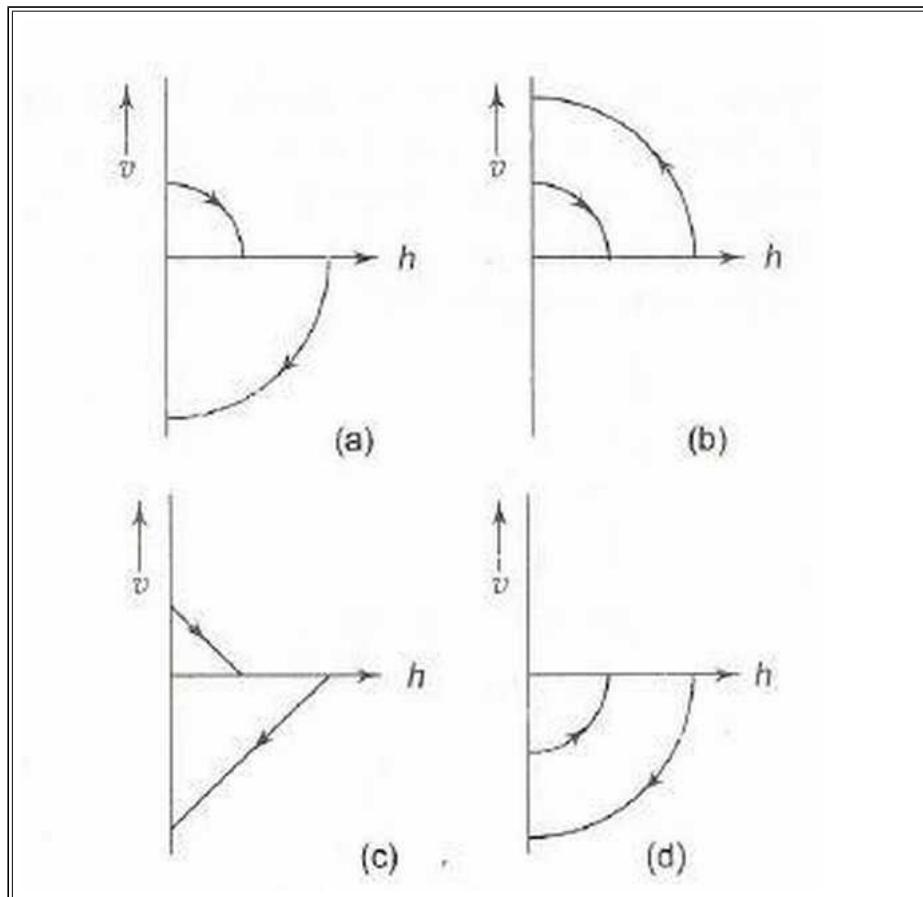
}

**Q6:** Four persons K, L, M and N are initially at the corners of a square of side of length  $d$ . If every person starts moving with velocity  $v$  such that K is always headed towards L, L towards M, M towards N and N towards K, then the four persons will meet after

- a )  $d/v s$
- b )  $d^2/v s$
- c )  $d / 2v s$
- d )  $d / 2v s$

{Hint: Not a graphs question, we'll discuss it in kinematics book. Although an easy one. It was mistakenly added to graphs book. Let's use it to signify the fact that even if a diagram is made, it is still not a graph.}

**Example.** A ball is dropped vertically from a height  $h$  above the ground. It hits the ground and bounces up vertically to a height  $h/2$ . Neglecting subsequent motion and air resistance, its velocity  $v$  varies with the height  $h$  as (see Fig.) (I.I.T. 2000)



{ Hint : Case 1: Thrown from height  $h$  with zero initial velocity,  $v=-gt$  and  $h = h_o - 1/2gt^2$ , so eliminating  $t$ , we get  $h = h_o - v^2/2g$ . So,  $v = -\sqrt{2g(h_o - h)}$

Case 2: We assume the opposite for solving purpose that the ball is now thrown from a height  $h_o/2$  and replace  $h_o$  only and see the effect. Taking upward velocity as positive , we get  $v = \sqrt{2g(h_o/2 - h)}$

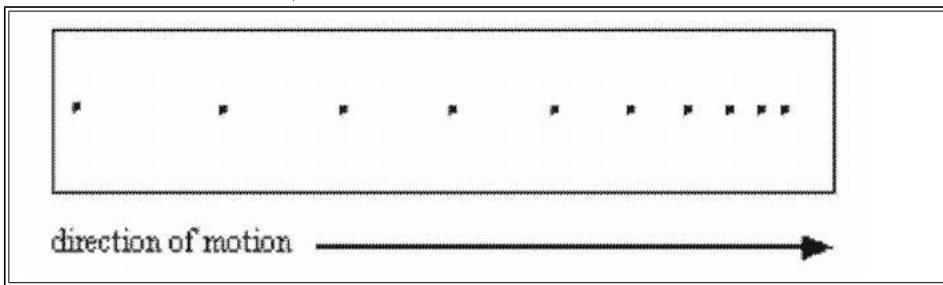
a) is the required answer. }

# Chapter 6

## Exercises

### 6.1 Review Exercise I

**Question 1.** A spark timer/air table produced the tape pictured below.

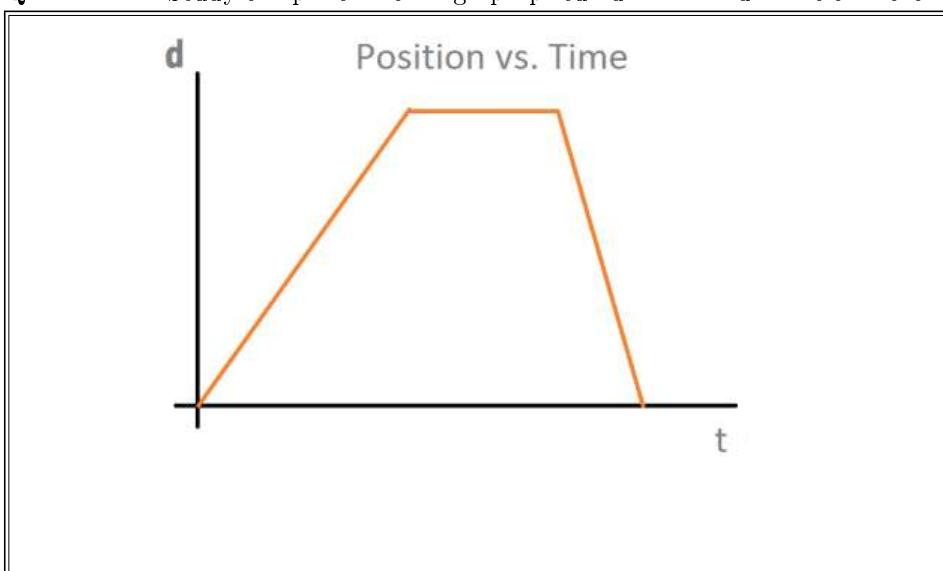


The object, moving to the right, was

- a. moving with uniform motion
- b. speeding up
- c. slowing down
- d. travelling with constant speed

{ Hint: c }

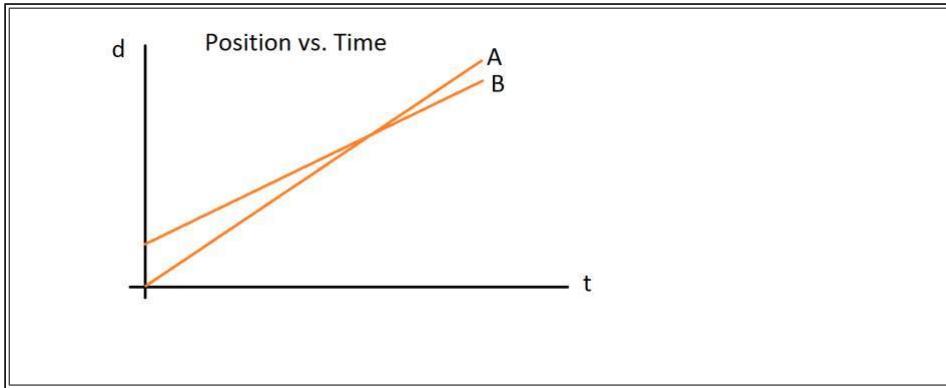
**Question 2.** Study the position-time graph pictured below and select the statement that is true.



- a. The object accelerates, stops, then accelerates in the opposite direction.
- b. The object's speed is greatest during the first segment.
- c. The object's acceleration is greatest during the last segment.
- d. The object's average velocity is zero.
- e. The object travels a greater distance in the first segment than in the last segment.

{ Hint : D }

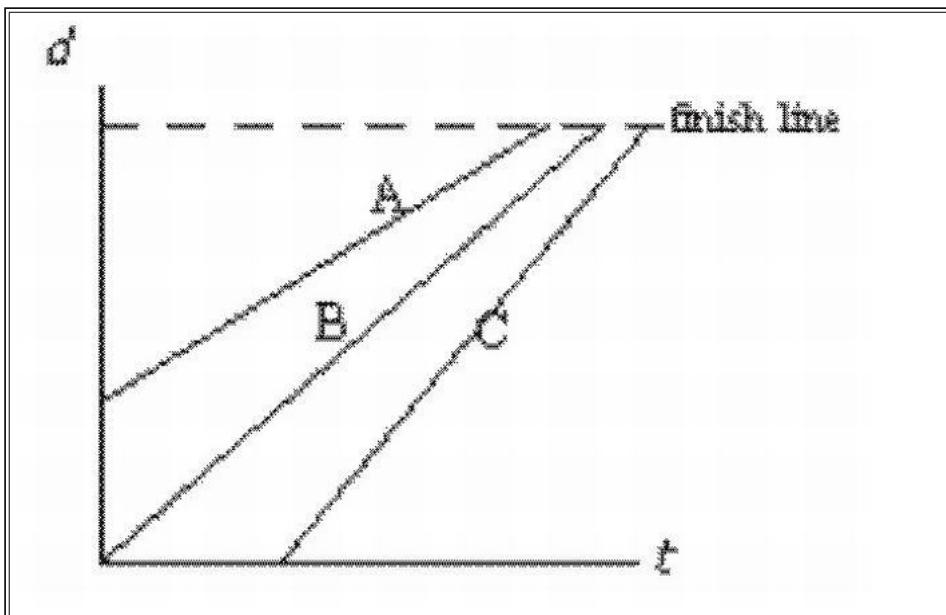
**Question 3.** The position-time graph pictured below represents the motions of two objects, A and B. Which of the following statements concerning the objects' motions is true?



- a. Object B travels the greater distance.
- b. Object A has the greater speed.
- c. Object A leaves the reference point at an earlier time.
- d. Both objects have the same speed at the point where the lines cross.
- e. Object A is travelling for a longer period of time.

{ Hint : B }

**Question 4.** The position-time graph pictured below represents a race between three contestants A, B, and C. The race begins at time zero at the sound of the starter's pistol. Which of the following statements is true?

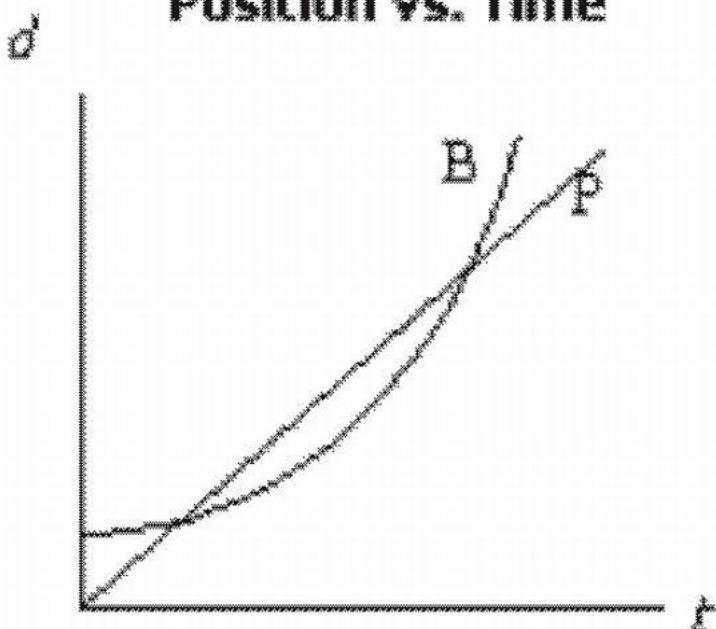


- a. The runner who started last finished first.
- b. The fastest runner won the race.
- c. The runner with a head start won the race.
- d. Only one runner began at the sound of the starter's pistol.
- e. All runners ran the same distance.

{ Hint : C }

**Question 5.** The position-time graph pictured below depicts a person, P, running to catch a bus, B, that has just begun to pull away. Which of the following statements is true?

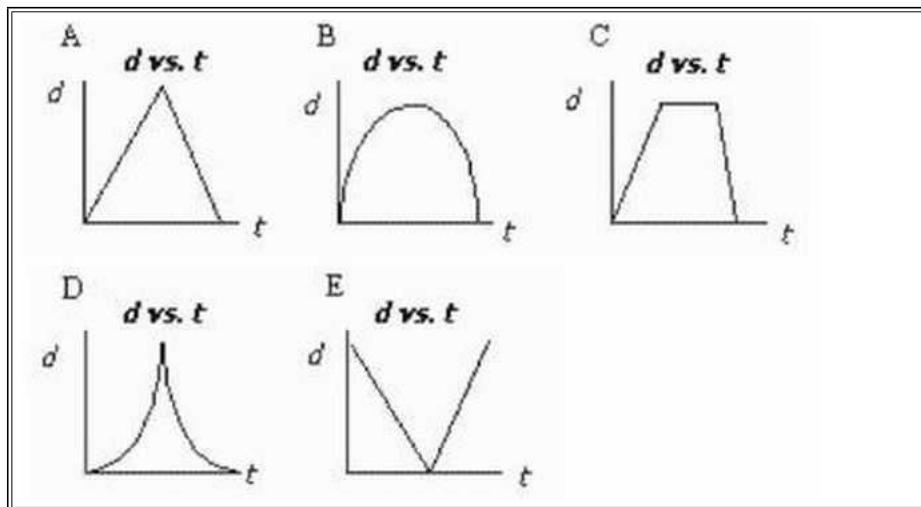
## Position vs. Time



- a. The person has no chance of catching the bus.
- b. The person's acceleration is greater than that of the bus.
- c. The person has two opportunities to catch up to the bus.
- d. The speed of the bus is always greater than that of the person.
- e. The person's speed is always greater than that of the bus.

{ Hint : C }

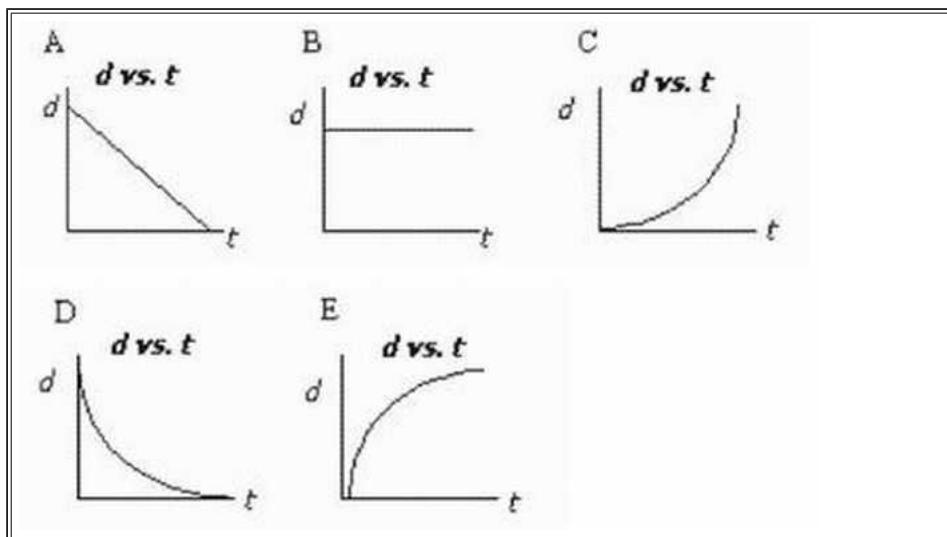
**Question 6.** The position-time graph that depicts a ball thrown vertically upward that returns to the same position is



- a. A
- b. B
- c. C
- d. D
- e. E

{ Hint : B }

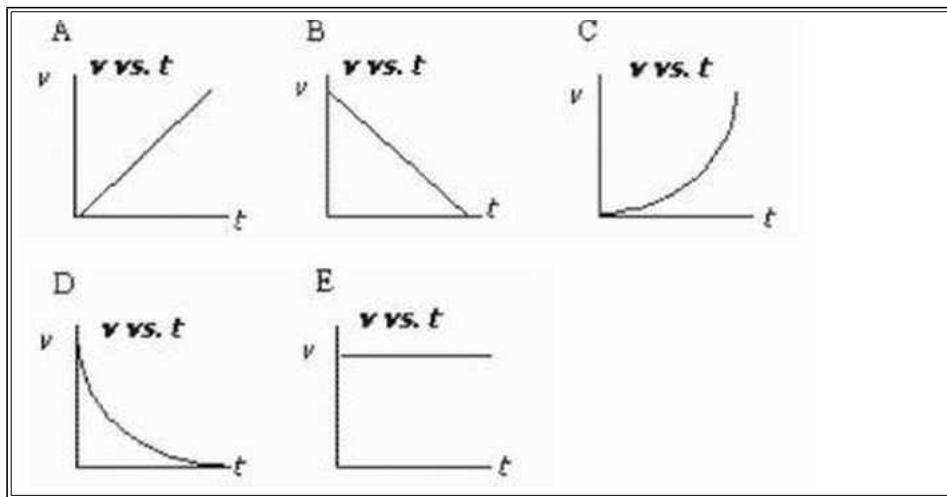
**Question 7.** The position-time graph that represents "uniform motion" is



- A
- B
- C
- D
- E

{ Hint : A }

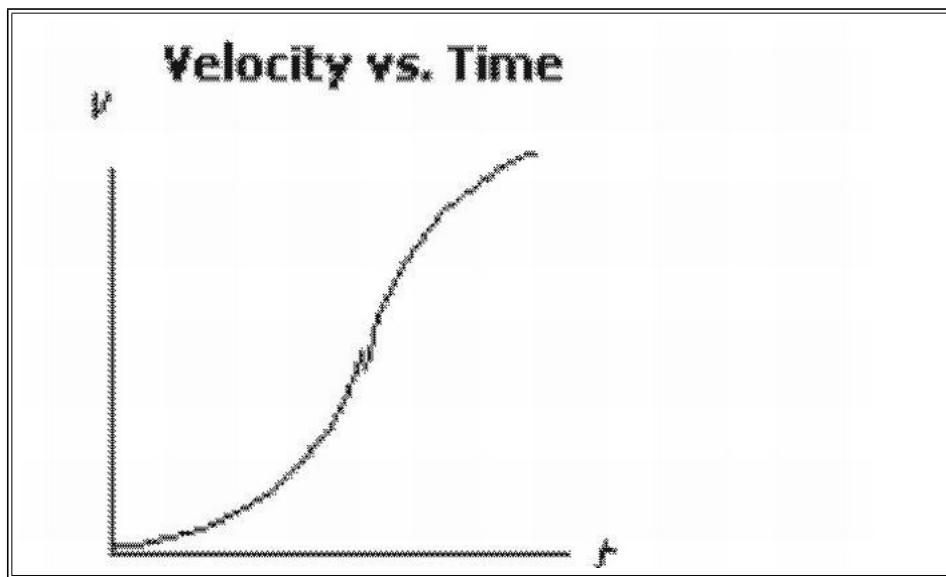
**Question 8.** The velocity-time graph that represents "uniform motion" is



- A
- B
- C
- D
- E

{ Hint : E }

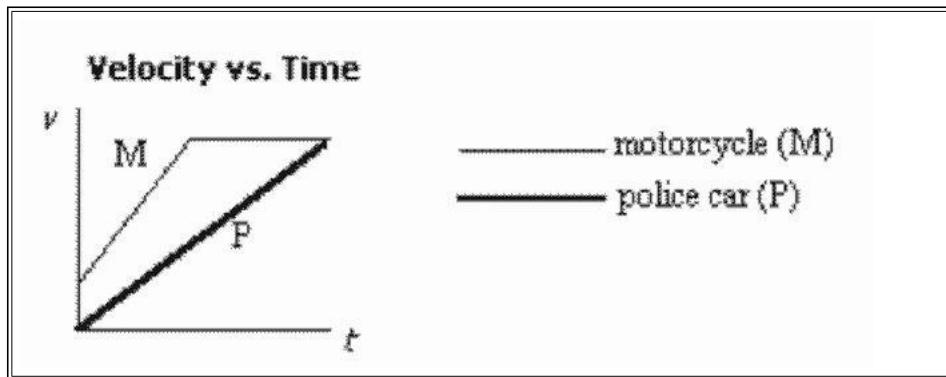
**Question 9.** The velocity-time graph pictured below depicts the motion of a motorcycle. Which of the following statements is true?



- The motorcycle is always experiencing an acceleration.
- The motorcycle's greatest speed occurs toward the end of the recorded time interval.
- The motorcycle's average acceleration is zero.
- The motorcycle eventually reaches uniform motion.
- The motorcycle accelerates until it reaches a constant speed.

{ Hint : A }

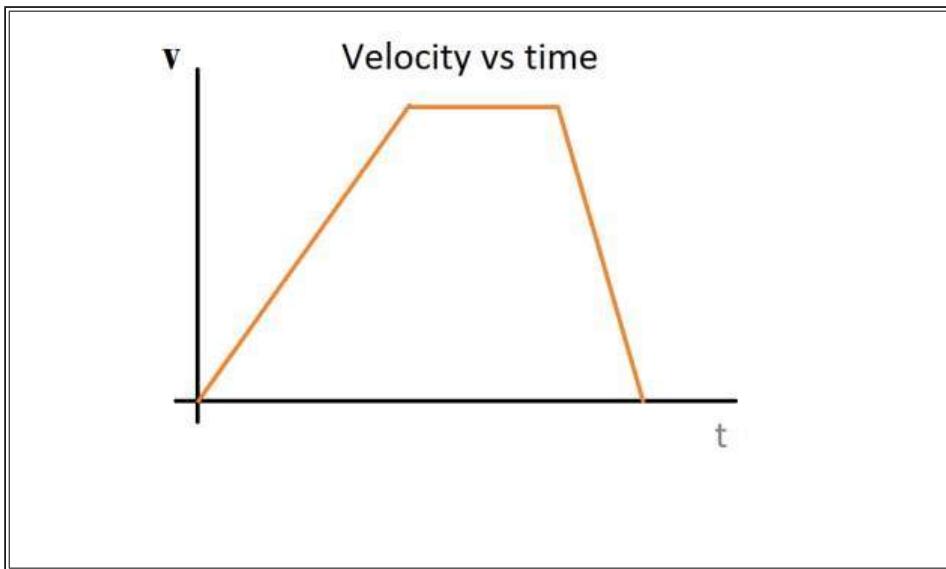
**Question 10.** The velocity-time graph pictured below represents the motion of a police car, P, in pursuit of a motorcycle, M. The motorcycle has just passed the police car. Which of the following statements is true?



- Both vehicles are at rest when the pursuit begins.
- The police car eventually catches the motorcycle.
- The motorcycle accelerates and then slows down.
- At the end of the recorded time interval, the police car has yet to catch the motorcycle.
- The police car passes the motorcycle.

{ Hint : D }

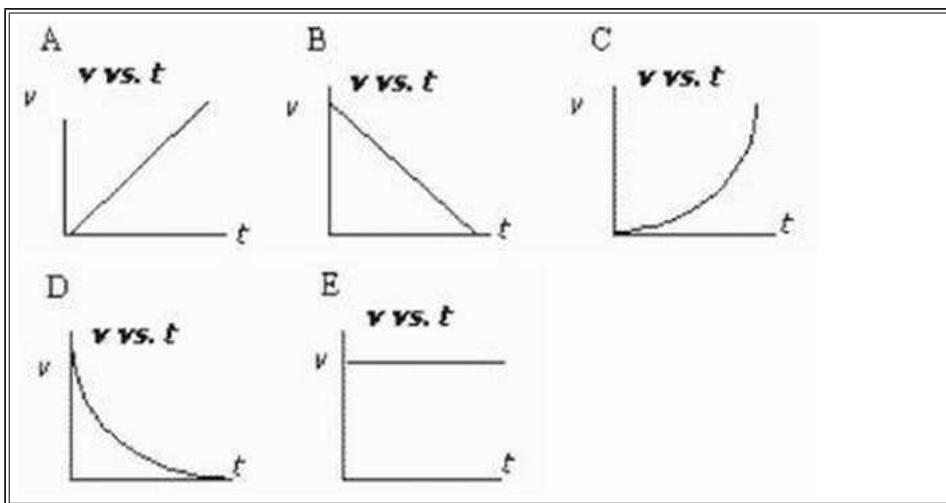
**Question 11.** Consider the following velocity-time graph and select the statement that is true.



- a. At no time can the motion be considered "uniform."
- b. The object returns to its original position.
- c. The object travels in one direction and then the other.
- d. The object is accelerating throughout the entire recorded time.
- e. The object speeds up and later slows down.

{ Hint : E }

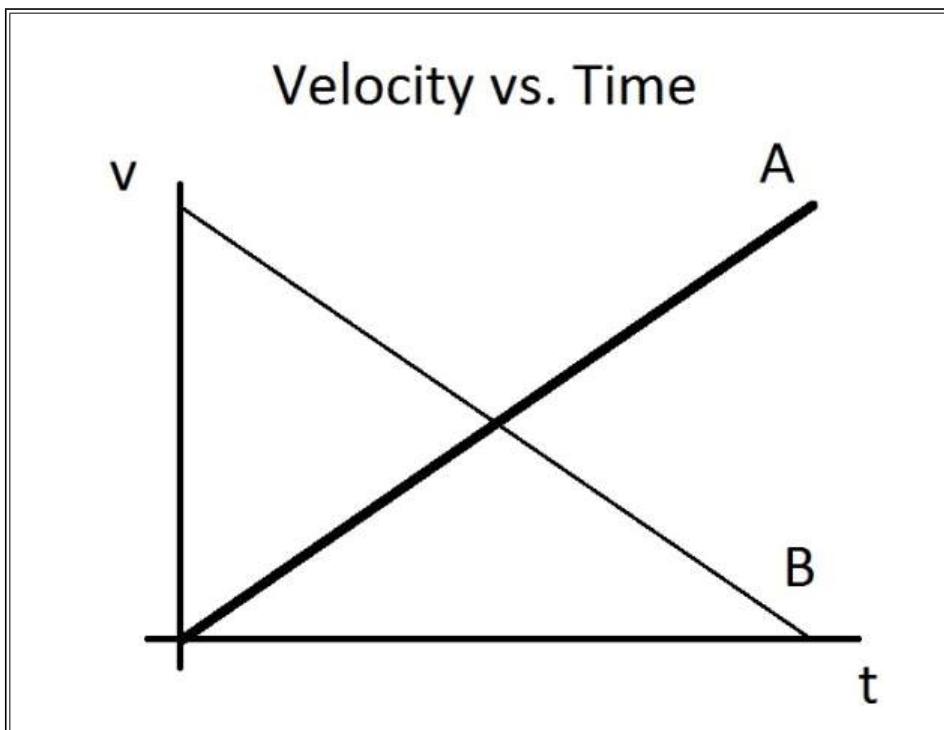
41. Which of the following velocity-time graphs represents the motion of a ball thrown vertically upward?



- a. A
- b. B
- c. C
- d. D
- e. E

{ Hint : B }

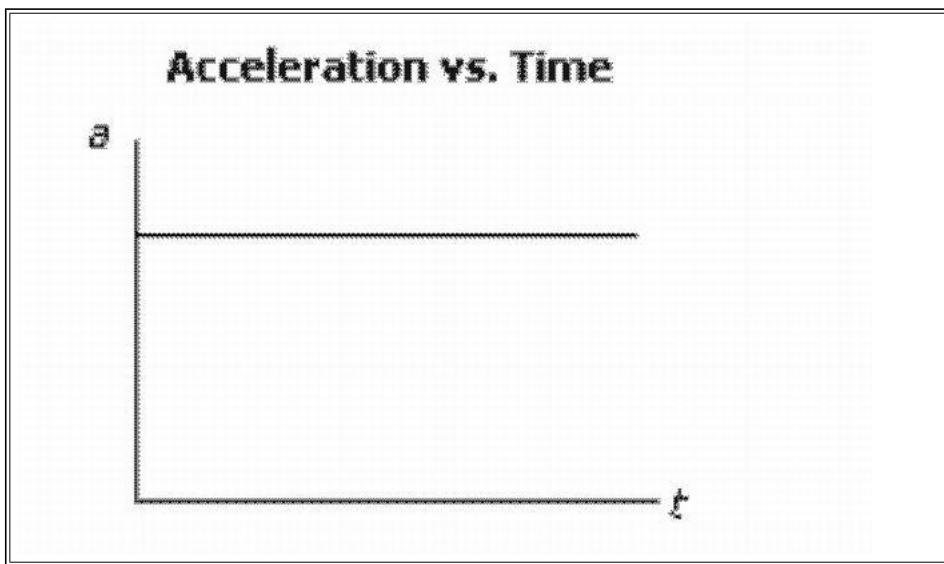
42. The following velocity-time graph depicts the motions of two objects, A and B. Which of the statements describing the graph is true?



- a. Both objects are accelerating uniformly.
- b. The two objects are travelling in opposite directions.
- c. Both objects start from rest.
- d. Object A travels farther than object B.
- e. Object B travels farther than object A.

{ Hint : A }

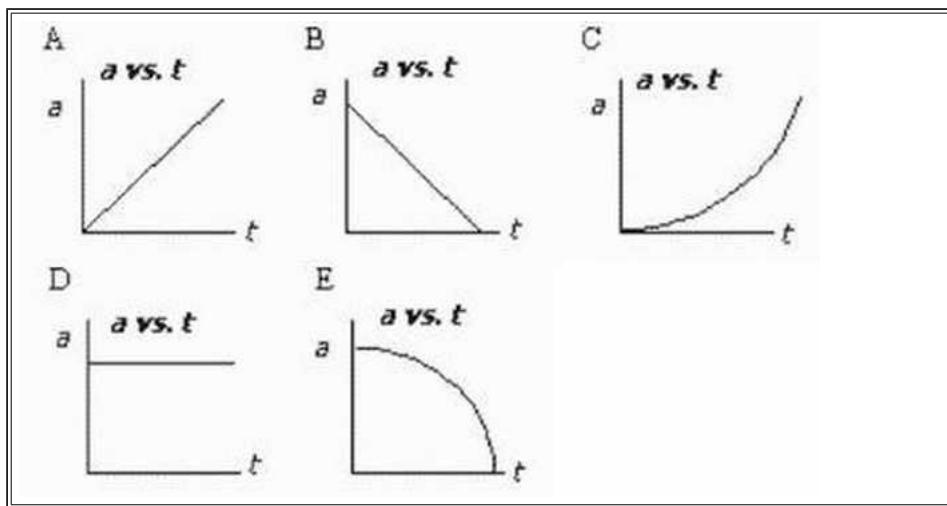
43. Which statement describes the motion represented by the following acceleration-time graph?



- a. The object is moving with uniform motion.
- b. The object has a constant velocity.
- c. The object has a uniform acceleration.
- d. The object is stopped.
- e. The object has a changing acceleration.

{ Hint : C }

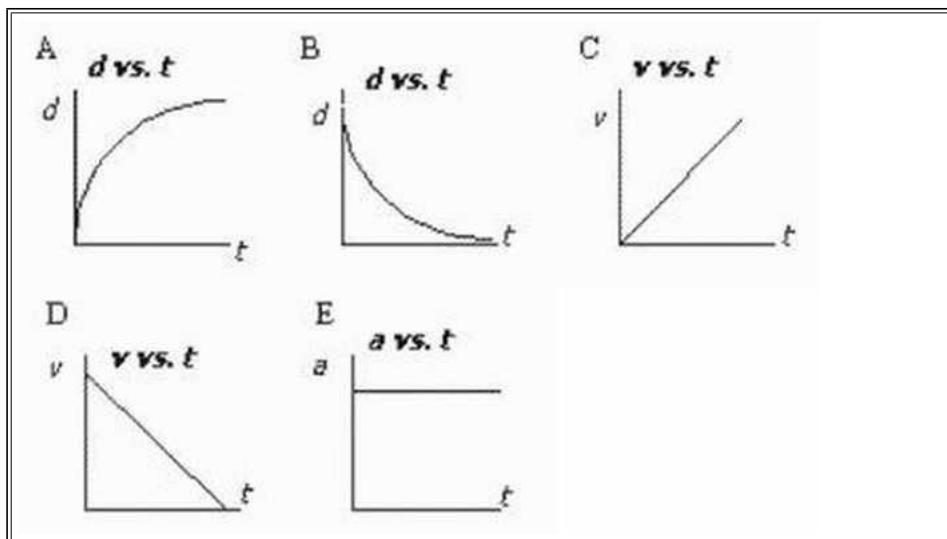
44. A ball is thrown vertically upward into the air. Which of the following acceleration-time graphs represents the ball's motion?



- a. A
- b. B
- c. C
- d. D
- e. E

{ Hint : D }

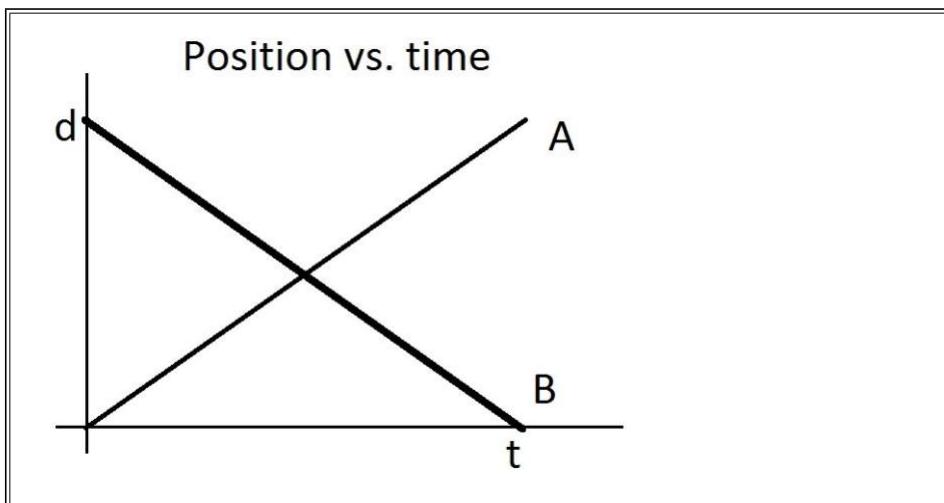
45. Four of the five graphs pictured below could all represent the same motion. Which graph does not belong to this group?



- a. A
- b. B
- c. C
- d. D
- e. E

{ Hint : C }

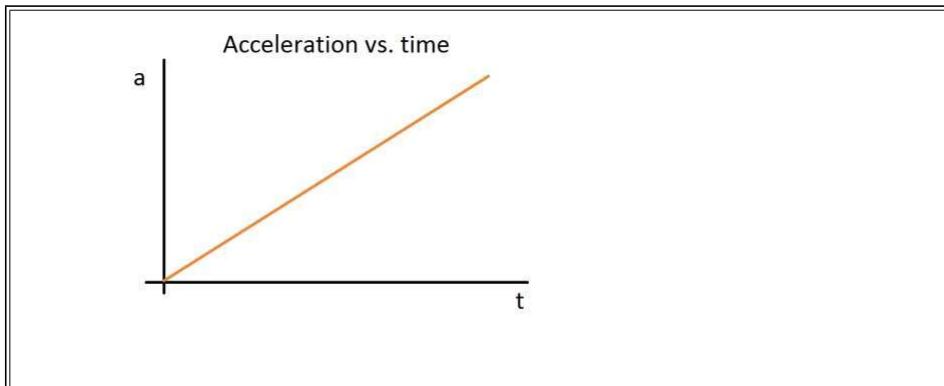
49. The position-time graph below depicts the motions of two objects, A and B. Which of the following statements concerning the objects' motions is NOT true?



- a. The two objects have the same speed.
- b. The two objects travel the same distance.
- c. The two objects travel with uniform motion.
- d. The two objects travel for the same amount of time.
- e. The two objects have the same velocity.

{ Hint : E }

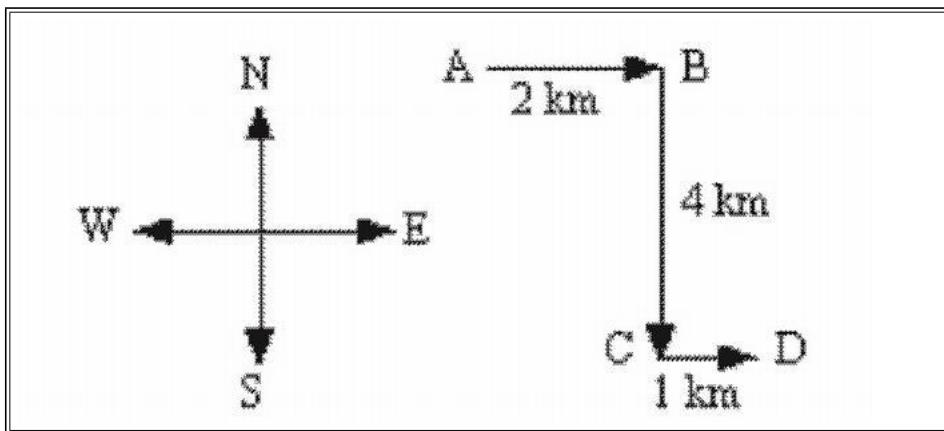
— 50. What type of motion is depicted by the following acceleration-time graph?



- a. constant velocity
- b. non-uniformly changing acceleration
- c. constant acceleration
- d. uniformly changing acceleration
- e. uniform motion

{ Hint: D }

— 51. The diagram below shows the first three legs of a trip: A to B, B to C, and C to D. If a person returns from point D to point A, what is the displacement for this fourth and final leg?

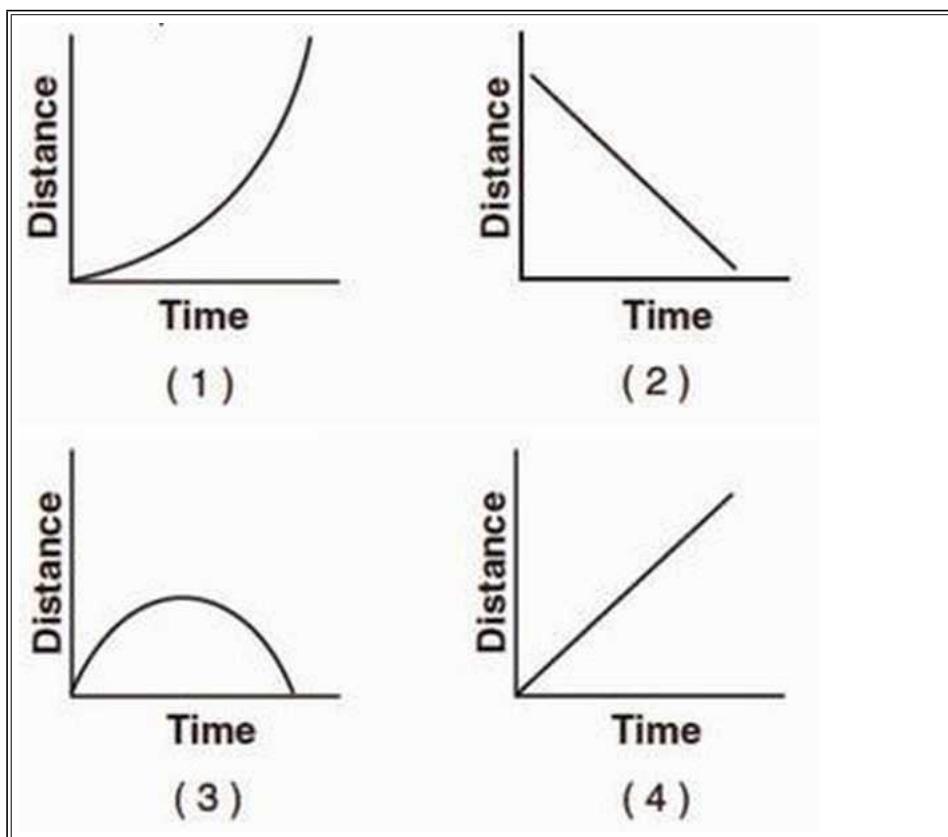


- a. 7 km [37° W of N]
- b. 5 km [37° W of N]
- c. 5 km [37° E of S]
- d. 7 km [37° E of S]
- e. 5 km [37° N of E]

{ Hint : B }

## 6.2 Review Exercise II

1. A cart travels with a constant nonzero acceleration along a straight line. Which graph best represents the relationship between the distance the cart travels and time of travel?



{ Hint: First of all the graph should be a parabola. Secondly, it can't be (3) as distance can only increase.  
}

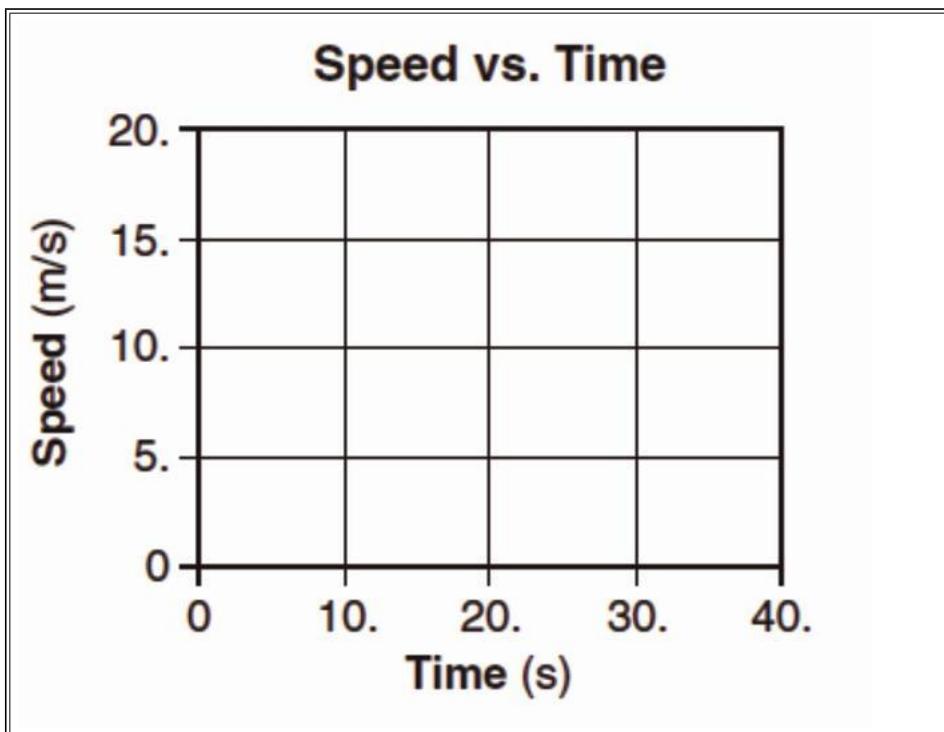
Base your answers to questions 2 through 4 on the information below.

A car on a straight road starts from rest and accelerates at 1.0 meter per second<sup>2</sup> for 10 seconds. Then the car continues to travel at constant speed for an additional 20 seconds.

2. Determine the speed of the car at the end of the first 10 seconds.

{ Hint :  $v=at$ , so  $v$  at 10 s = 10 m/s }

3. On the grid at below, use a ruler or straightedge to construct a graph of the car's speed as a function of time for the entire 30-second interval.

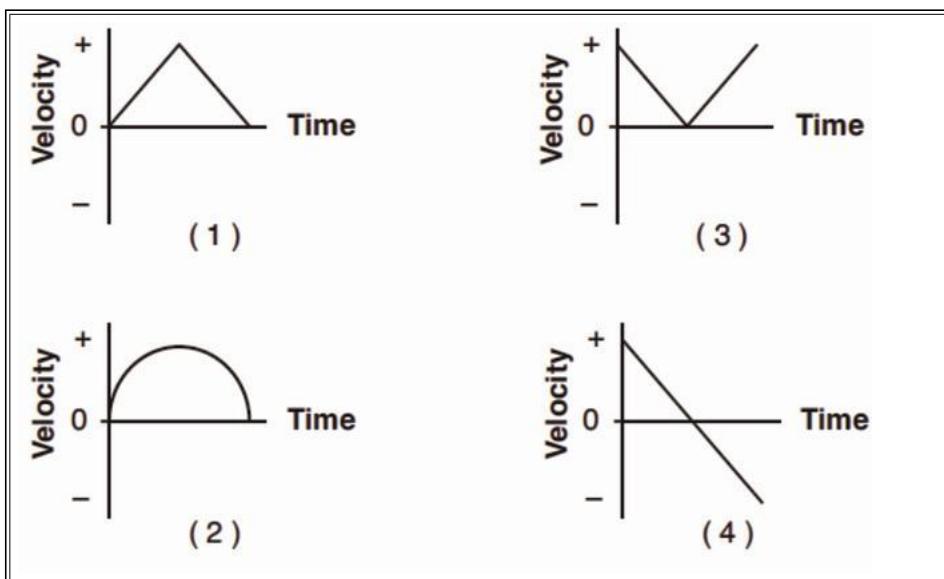


{ Hint: Try out yourself. }

4. Calculate the distance the car travels in the first 10 seconds. [Show all work, including the equation and substitution with units.]

{ Hint:  $s=1/2at^2 = 50\text{m}$  }

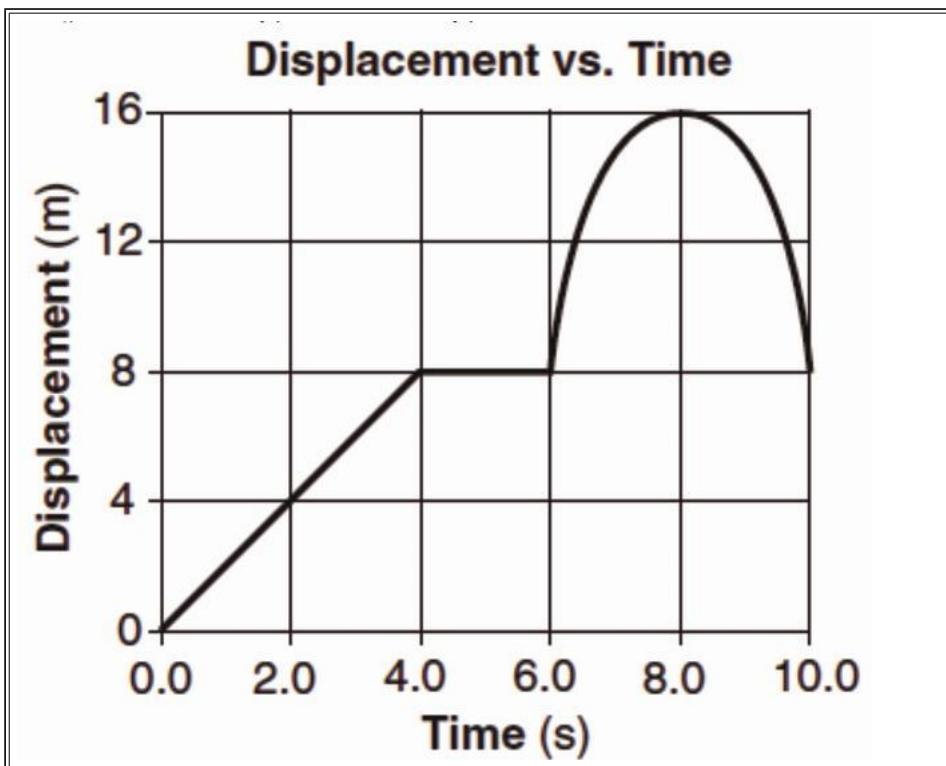
5. A student throws a baseball vertically upward and then catches it. If vertically upward is considered to be the positive direction, which graph best represents the relationship between velocity and time for the baseball? [Neglect friction.]



{ Hint :  $v=u-gt$ , so velocity is continually decreasing with  $9.81 \text{ m/s}^2$  and even turns negative, equal to the initial value in magnitude on return and opposite direction if air drag is neglected. }

D) is the correct option. }

6. The graph below represents the displacement of an object moving in a straight line as a function of time.



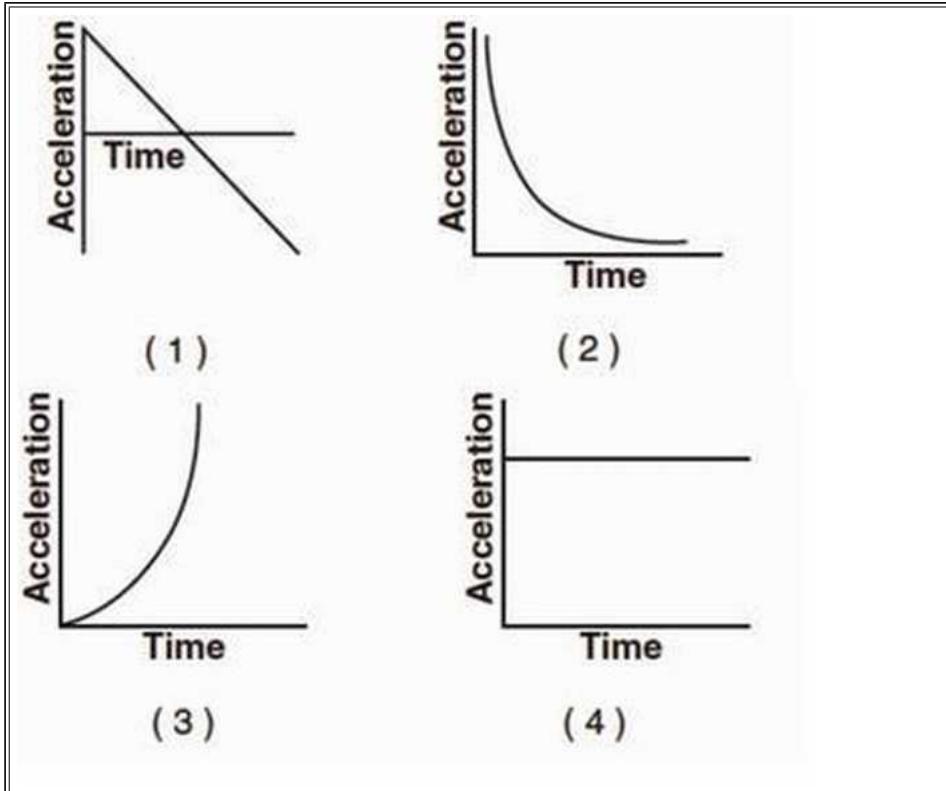
What was the total distance traveled by the object during the 10-second time interval?

1. 0 m
2. 8 m
3. 16 m
4. 24 m

{ Hint: The object moves 16m forward and 8m backward. So, distance is 24 m. }

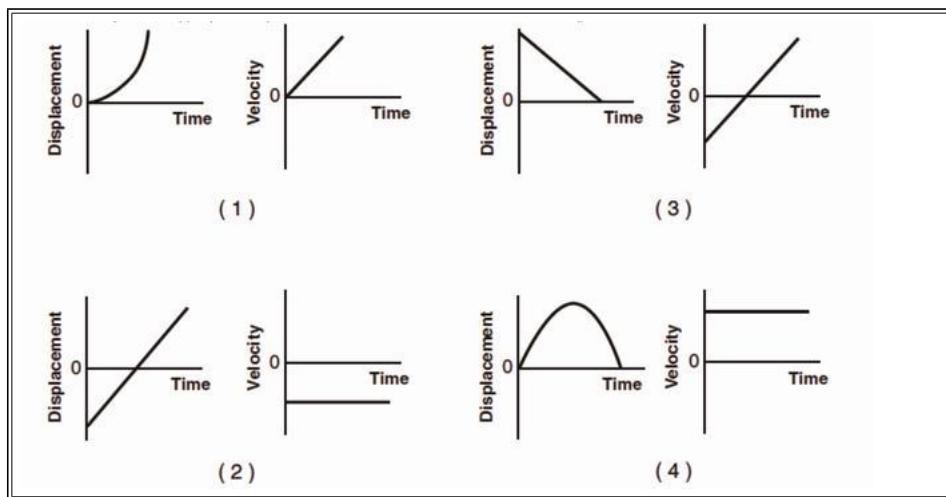
4) is the correct option. }

7. Which graph best represents the relationship between the acceleration of an object falling freely near the surface of Earth and the time that it falls?



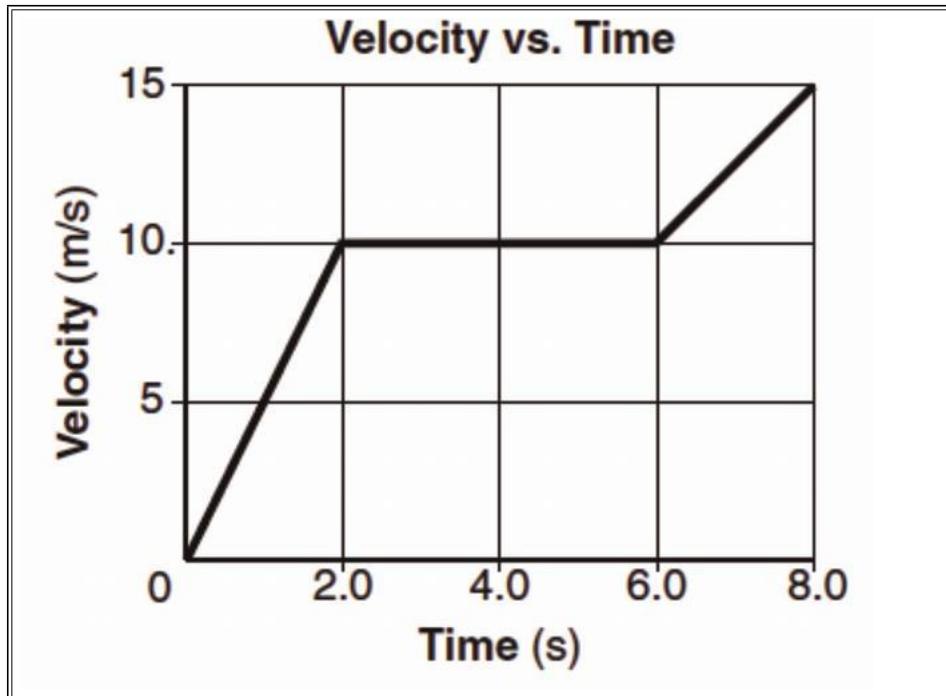
{ Hint : Acceleration due to gravity near the earth surface is constant, being  $9.81 \text{ m/s}^2$  }

8. Which pair of graphs represent the same motion of an object?



{ Hint : A) }

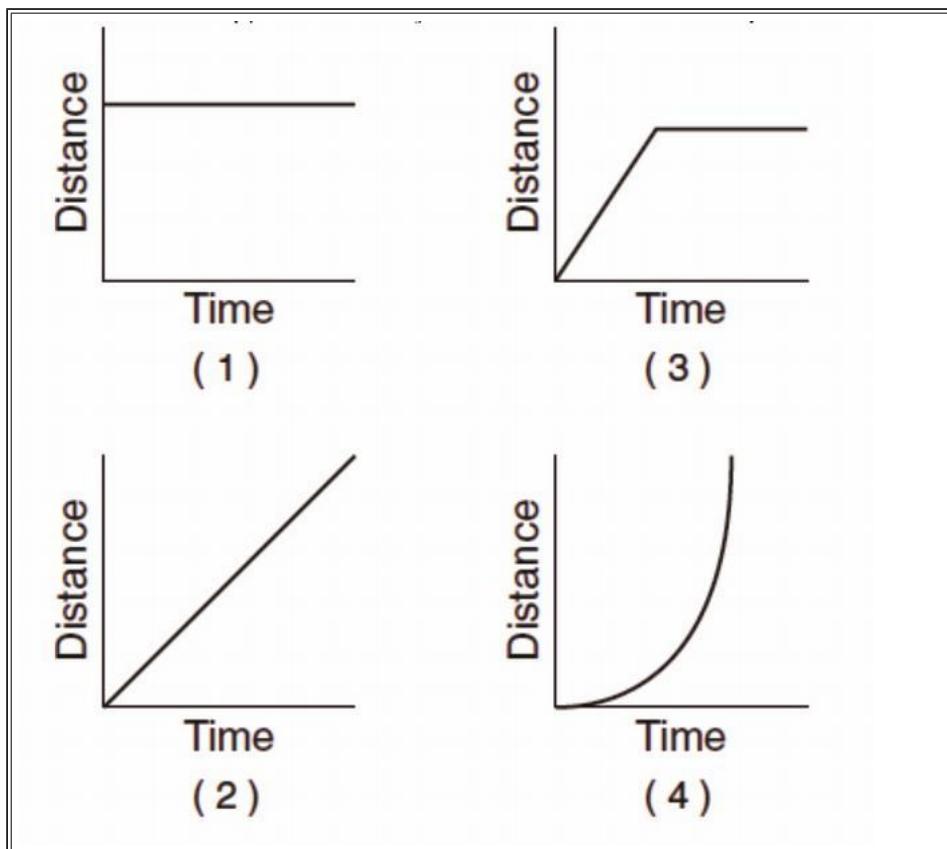
9. The graph below represents the velocity of an object traveling in a straight line as a function of time.



Determine the magnitude of the total displacement of the object at the end of the first 6 seconds.

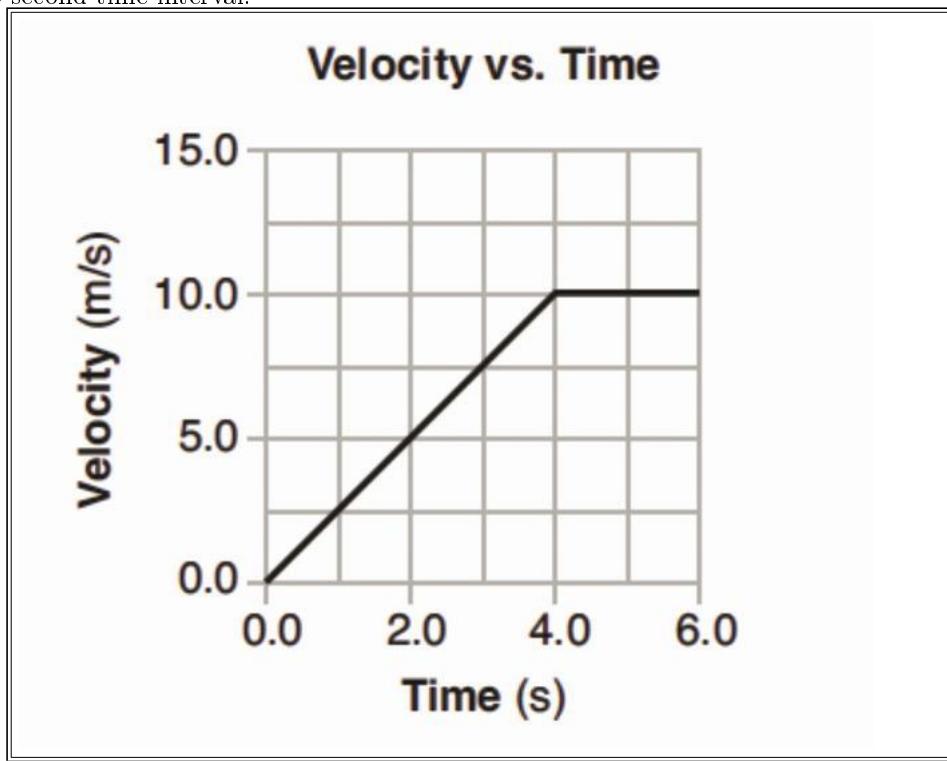
{Hint 50m, area under the graph till 6s.: }

10. Which graph best represents the motion of a block accelerating uniformly down an inclined plane?



{Hint: (4) as the graph would be a function of  $t^2$ , calculated via the usual equations of motion for uniformly accelerated motion.}

Base your answers to questions 11 and 12 on the graph below, which represents the motion of a car during a 6-second time interval.



11. What is the acceleration of the car at  $t=5.0$  seconds?

1.  $0.0 \text{ m/s}^2$
2.  $2.0 \text{ m/s}^2$
3.  $2.5 \text{ m/s}^2$
4.  $10 \text{ m/s}^2$

{Hint : It is the slope of v-t graph, at  $t=5.0$ , the graph has zero slope. So, (1)}

12. What is the total distance traveled by the car during this 6-second interval?

1. 10 m

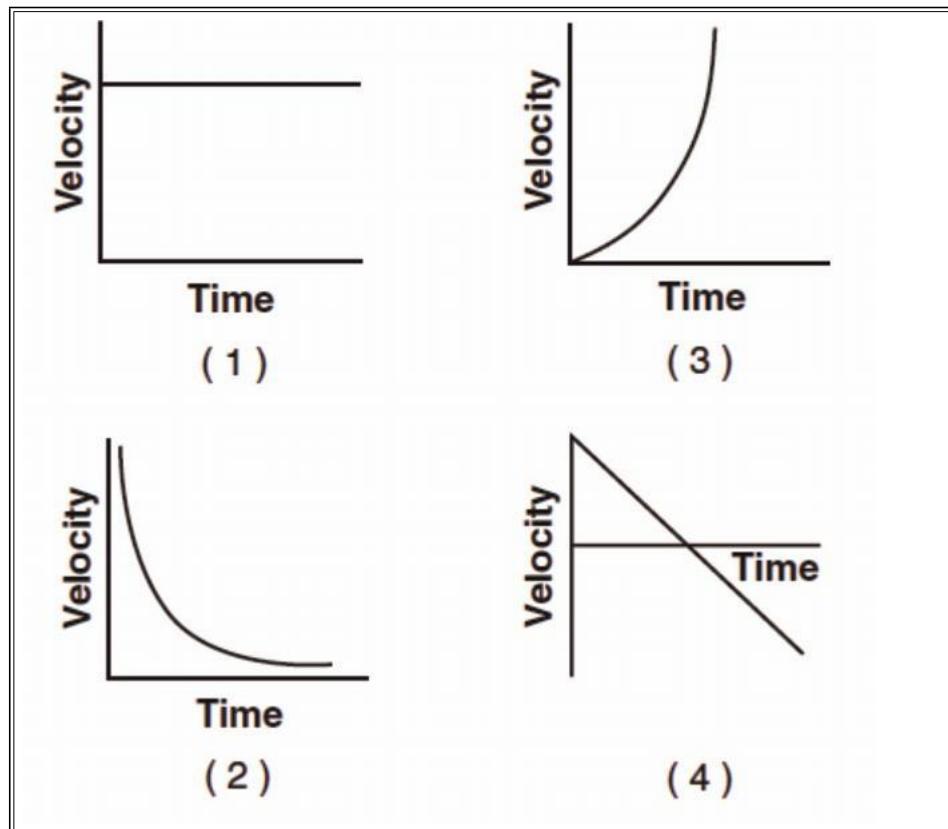
2. 20 m

3. 40 m

4. 60 m

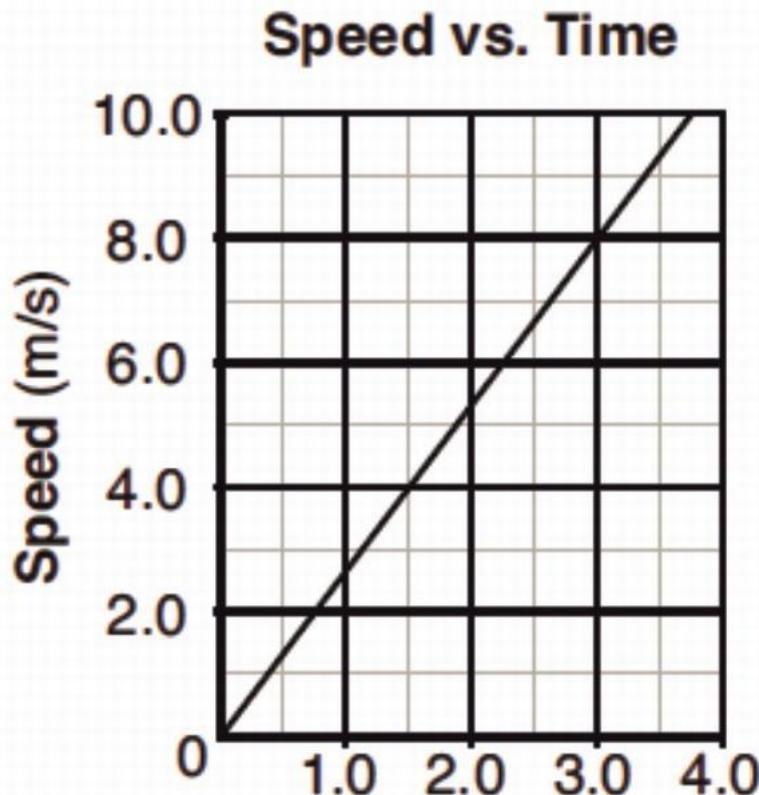
{ Hint : Area under the v-t curve, 40m, So, (3) }

13. Which graph best represents the relationship between the velocity of an object thrown straight upward from Earth's surface and the time that elapses while it is in the air? [Neglect friction.]



{ Hint : (4) }

14. The graph below shows the relationship between the speed and elapsed time for an object falling freely from rest near the surface of a planet.

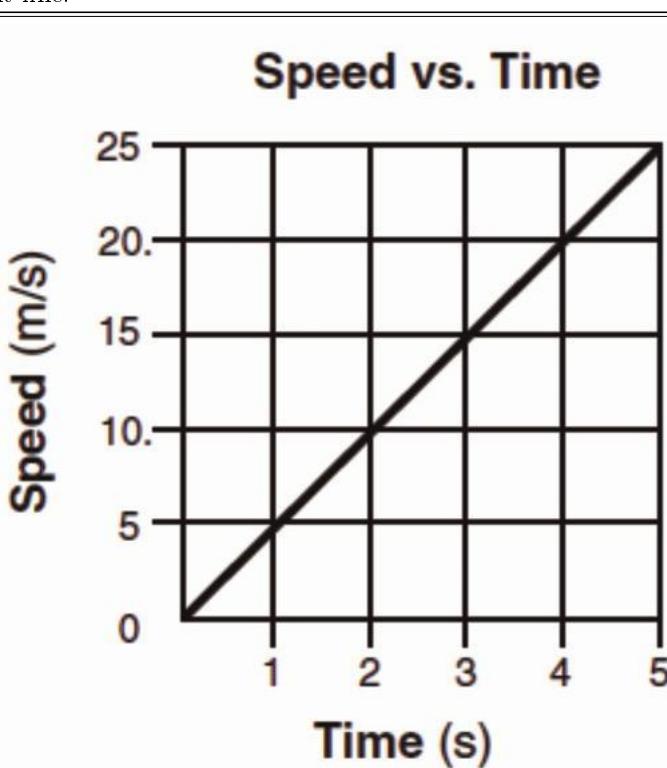


What is the total distance the object falls during the first 3 seconds?

1. 12 m
2. 24 m
3. 44 m
4. 72 m

{ Hint : Area under the graph between 0 and 3, 12m }

15. The graph below represents the relationship between speed and time for an object moving along a straight line.

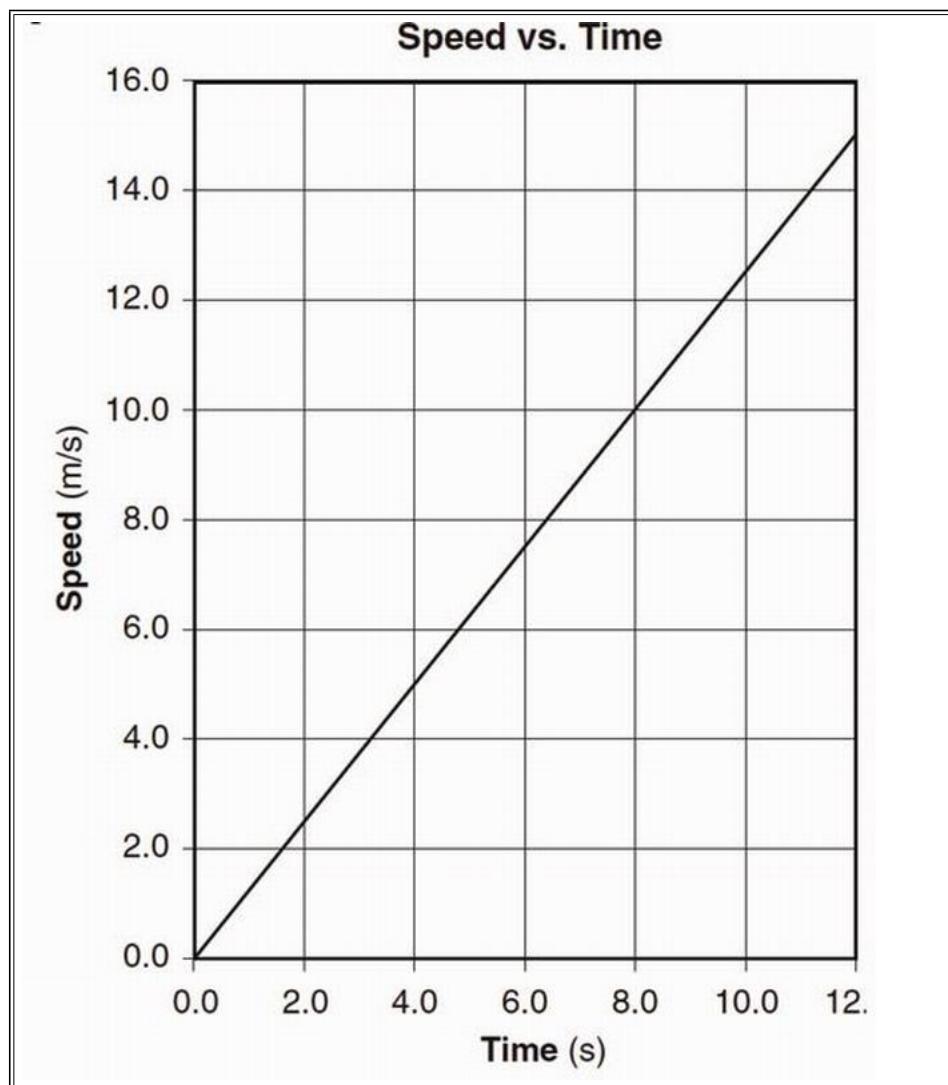


What is the total distance traveled by the object during the first 4 seconds?

1. 5 m
2. 20 m
3. 40 m
4. 80 m

{ Hint : 40m , So, 3}

Base your answers to questions 16 and 17 on the graph below, which shows the relationship between speed and elapsed time for a car moving in a straight line.



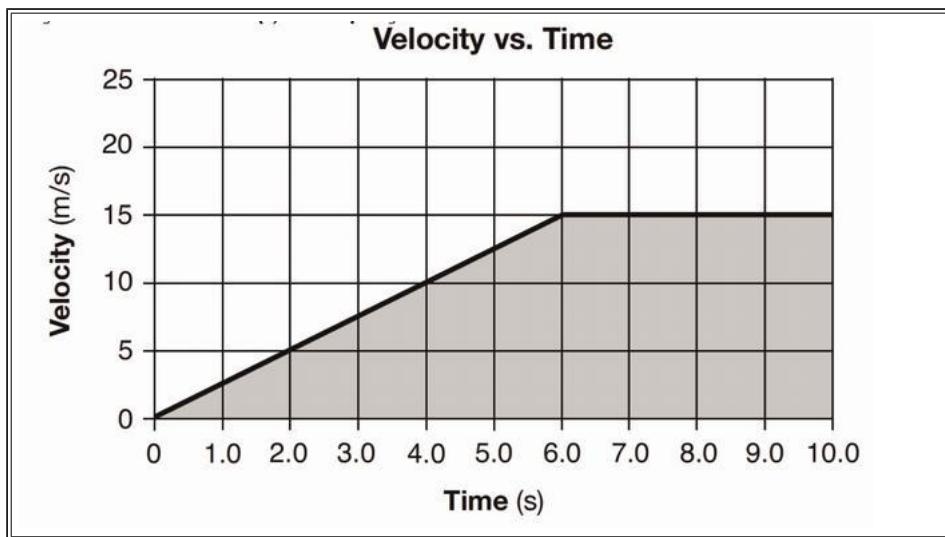
16. Determine the magnitude of the acceleration of the car.

{ Hint : Slope of the line ,  $1.25\text{m/s}^2$  }

17. Calculate the total distance the car traveled during the time interval 4.0 seconds to 8.0 seconds. [Show all work, including the equation and substitution with units.]

{ Hint : It's the area of trapezium with parallel sides , 5 and 10 and distance between them as 4 , = 30m }

Base your answers to questions 18 through 20 on the graph below, which represents the relationship between velocity and time for a car moving along a straight line, and your knowledge of physics.



18. Determine the magnitude of the average velocity of the car from  $t=6.0$  seconds to  $t=10.0$  seconds.  
{ Hint : Velocity is constant between 6 and 10 , ie 15 m/s}
19. Determine the magnitude of the car's acceleration during the first 6.0 seconds.  
{ Hint : Slope of the graph is 1.5 m/s<sup>2</sup>}
20. Identify the physical quantity represented by the shaded area on the graph.  
{ Hint : Displacement of the car from initial position by  $t=10.0$ s , calculated to be 105m}

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# **Part III**

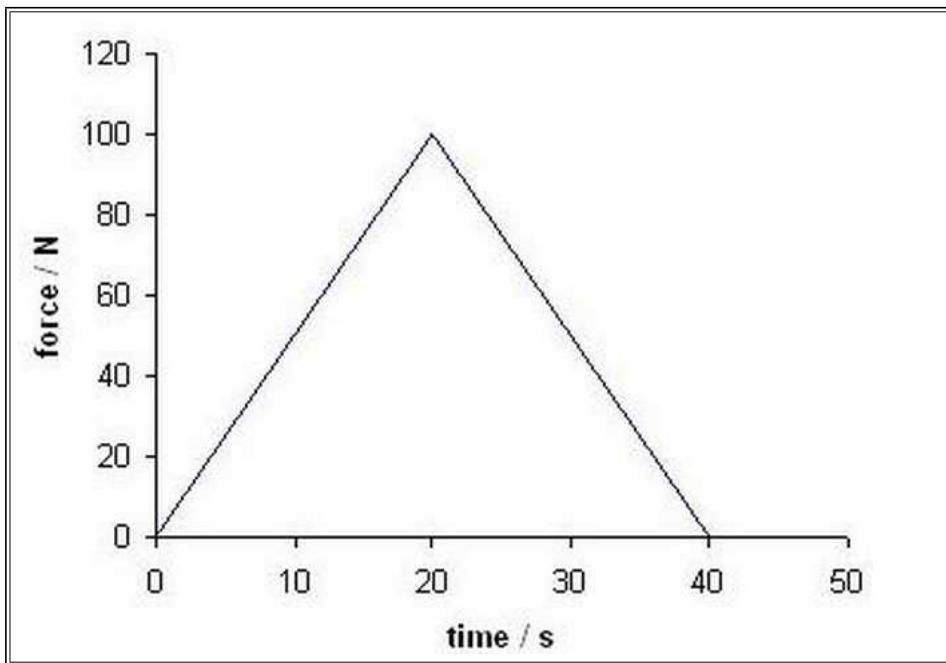
## **Laws of Motion**



# Chapter 7

## Abstract Introduction

### 7.1 Force – Time Graphs



The area under a force – time graph gives us the impulse of the force applied (and hence the change in momentum of the object). For this graph the impulse (the area under the graph) is  $2000 \text{ kg ms}^{-1}$ . n.d.

### 7.2 Change in Momentum or the "Impulse"

The change in the momentum of a system (or the impulse delivered by the net force) is given mathematically by the Momentum Principle,

$$\Delta \vec{p} = \overrightarrow{F_{net}} \Delta t \text{ n.d.}$$

In this form, the change in momentum is calculated over a “discrete” time step. That is, the calculation is done over a known or determined time interval. If the force is non-constant (i.e., depends on location or velocity), this calculation is not exact. In fact, in this case, the net force is the average net force over the time interval. So that a better definition is this:

$$\Delta \vec{p} = \overrightarrow{F_{net,avg}} \Delta t$$

This definition works well for cases where you might use iterative procedures to determine the change in momentum over small time intervals. If on the other hand, you can analytically integrate the force (e.g., it is or can be put into a form which is time dependent), then you can use the derivative form of the Momentum Principle,

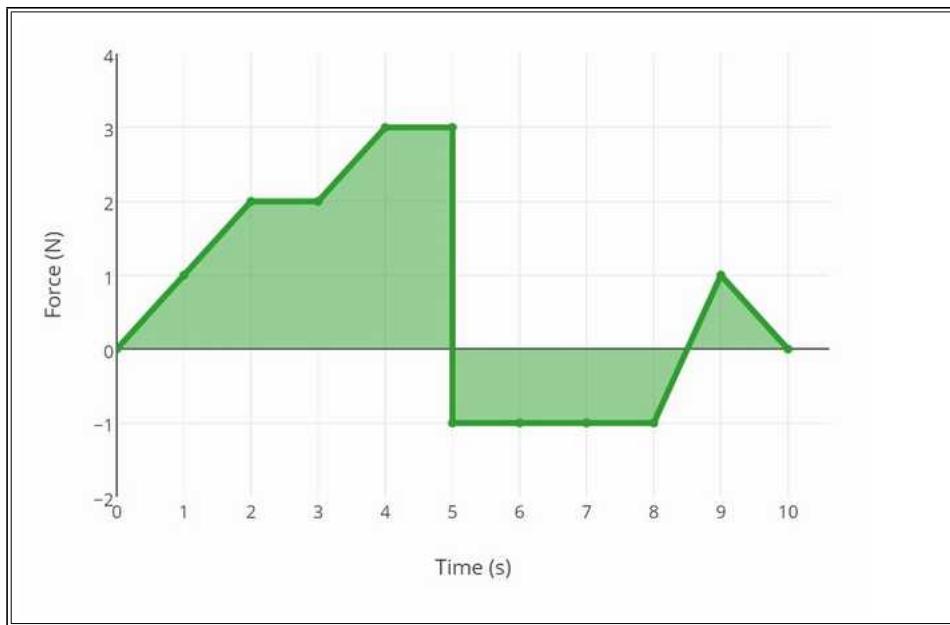
$$\Delta \vec{p} = \int_{t_i}^{t_f} \overrightarrow{F_{net}} dt$$

In any event, either (or both) can be useful to think about graphs of force vs time.

### 7.2.1 Force vs Time Graphs

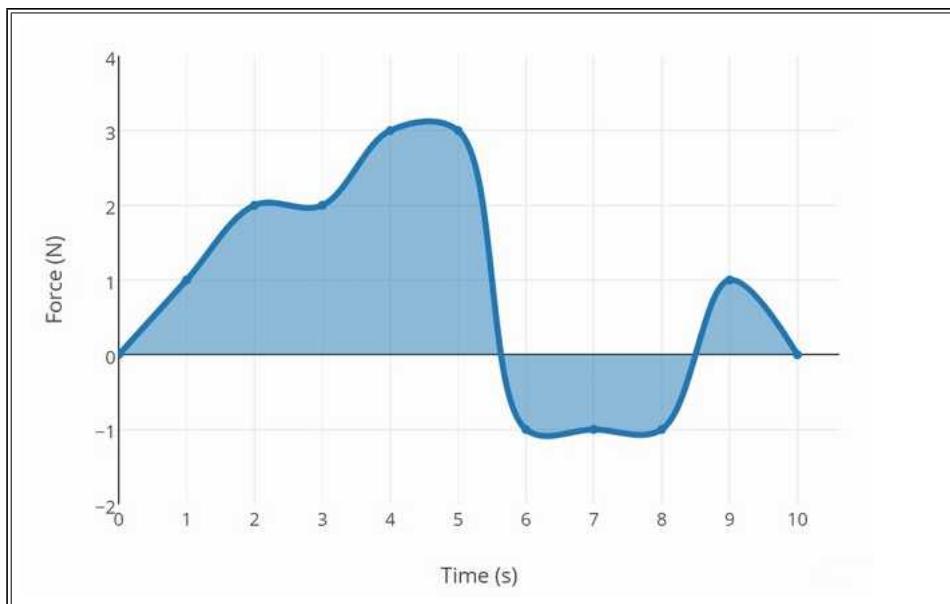
In some situations, it is easier to empirically measure force versus time graphs because the situations lend themselves more easily to these empirical measurements rather than what might be more complex physical theories. This is true in different engineering contexts (e.g., impact design and the flow of fluids). In these cases, you are interested in determining the change in momentum (and thus the velocity) of the system in question<sup>1</sup>.

Below is a force vs time graph where the “area under the curve” has been highlighted. In this example, we are only looking at the component of the net force in the  $xx$ -direction. Such graphs can be produced for each component of the net force, but let’s say that for this system, there was a non-zero component of the net force only in the  $x$ -direction.



For the above figure, the momentum change over the complete time interval can be determined in a straightforward way due to the simple geometric shapes produced. Area above the zero line are positive momentum changes, and area below are negative. By adding up the “area under the curve” in this way, we obtain a momentum change of 7 Ns.

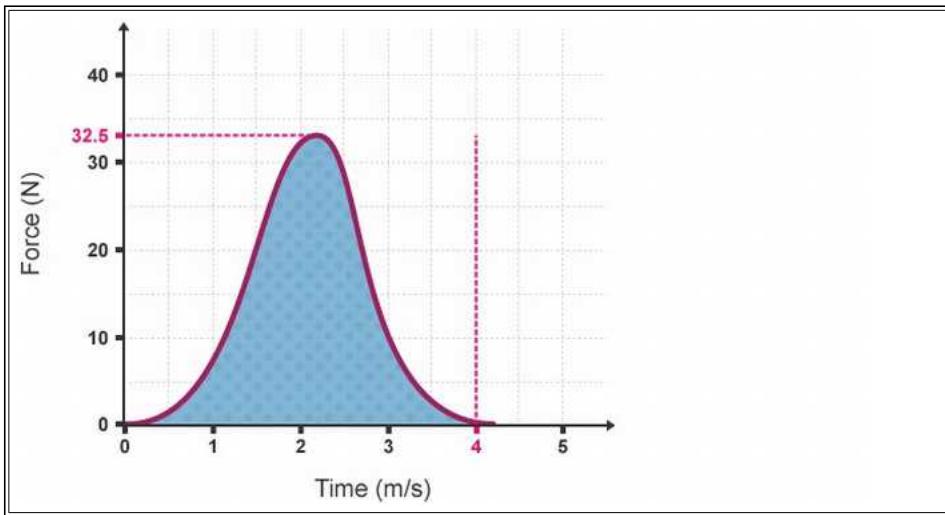
The figure below shows the force vs time graph for another system. In this case, the graph has a smooth form, which doesn’t appear to be analytic. The “area under the curve” for this graph could be analyzed computationally, by taking small steps (i.e., Riemann Sum), and the change in momentum could be determined.



- 1) It is possible to determine the displacement of such systems as well. This can be done using velocity vs time graphs that are produced from the analysis of force vs time graphs.

### 7.3 Impulse graphs ( A Case Study) n.d.

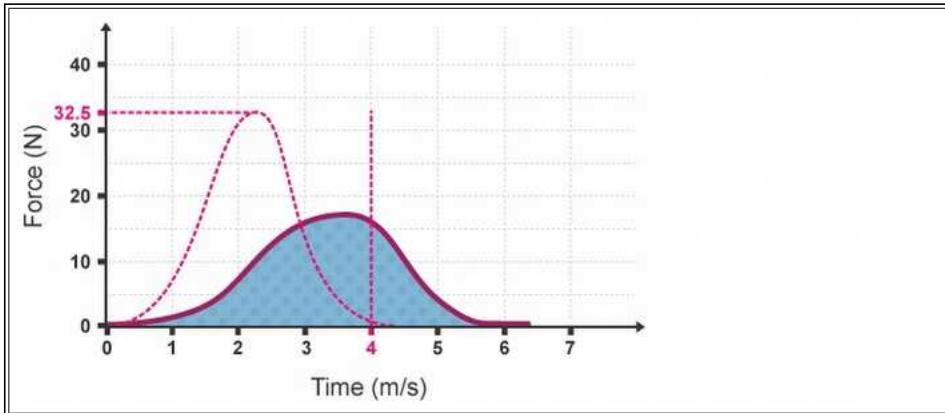
The force on the squash ball in the previous question is an average force and often the force changes during the collision. For this example the force-time graph could look like this.



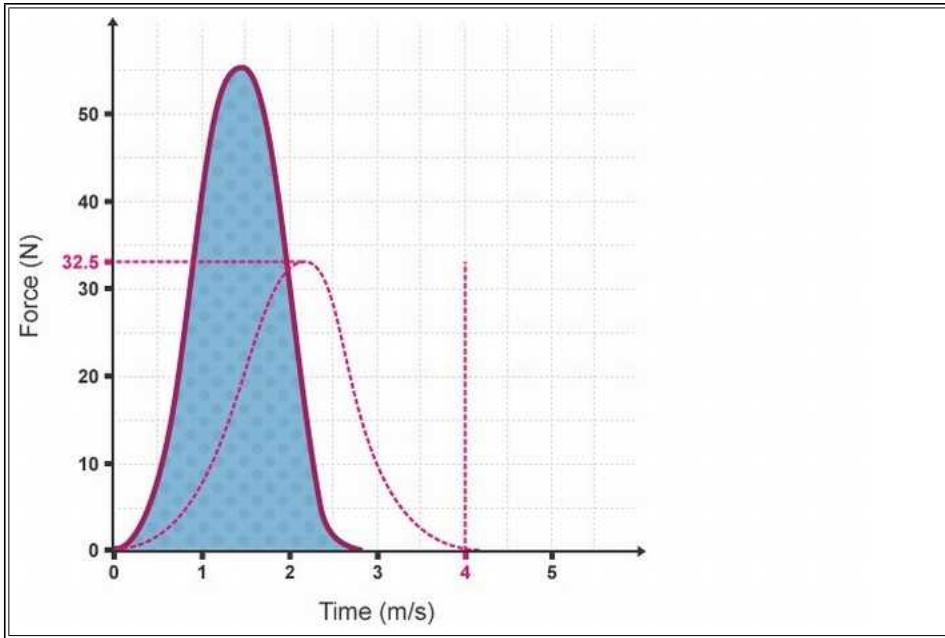
Notice the peak force is greater than the average force calculated.

The area under a force time graph is equal to the impulse. For any collision with a fixed change in momentum, if the time of contact can be increased, the peak force is reduced:

For example if the squash ball was replaced with a softer version of same mass the collision graph would look like this:



If the squash ball was replaced with a harder version of same mass the collision graph would look like this:



Question Modern cars are designed to crumple on impact in a collision. How does this help to protect the occupants from harm?

**Answer** The change in momentum (area under the force time graph) can't be changed at the time of the accident (mass is fixed and it is too late for the driver to slow down!) By increasing the time of collision the peak force is less and hopefully lets the occupants come to less harm as a result.

**Question** : How do I find "Velocity" from "Force vs. Time" graph?

**Solution** : You need two additional pieces of information: the mass of the object and its initial velocity. Given those, the relation is:

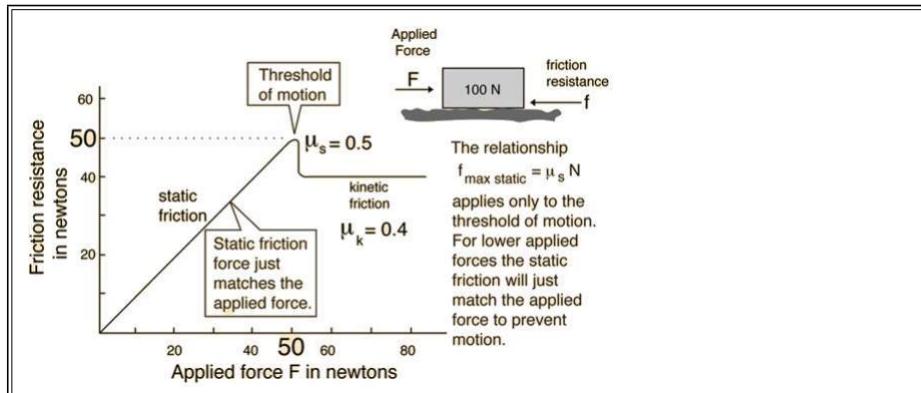
$$v(t) = v_o + \frac{1}{m} \int_0^t F(t) dt$$

# Chapter 8

## Friction

### 8.1 Static Friction 2017

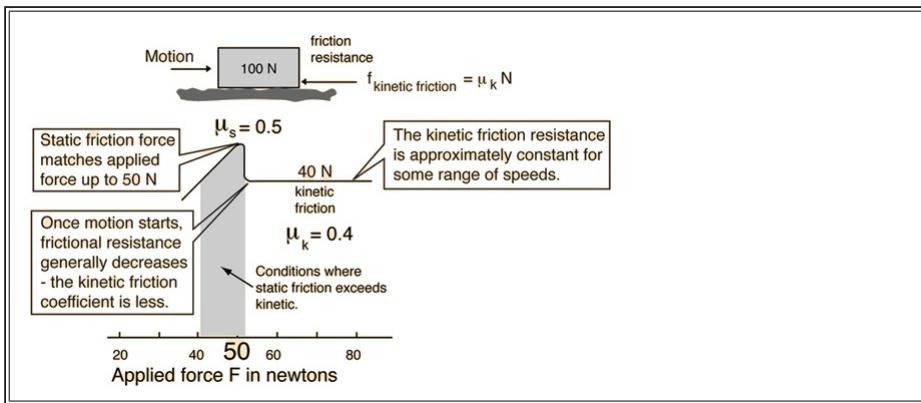
Static frictional forces from the interlocking of the irregularities of two surfaces will increase to prevent any relative motion up until some limit where motion occurs. It is that threshold of motion which is characterized by the coefficient of static friction. The coefficient of static friction is typically larger than the coefficient of kinetic friction.



In making a distinction between static and kinetic coefficients of friction, we are dealing with an aspect of "real world" common experience with a phenomenon which cannot be simply characterized. The difference between static and kinetic coefficients obtained in simple experiments like wooden blocks sliding on wooden inclines roughly follows the model depicted in the friction plot from which the illustration above is taken. This difference may arise from irregularities, surface contaminants, etc. which defy precise description. When such experiments are carried out with smooth metal blocks which are carefully cleaned, the difference between static and kinetic coefficients tends to disappear. When coefficients of friction are quoted for specific surface combinations are quoted, it is the kinetic coefficient which is generally quoted since it is the more reliable number.

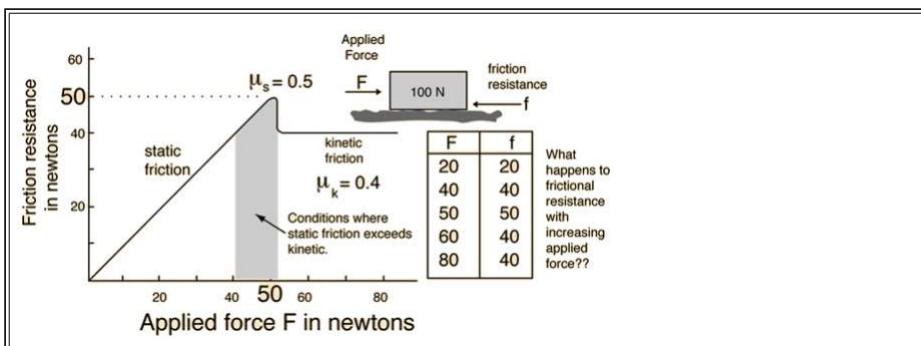
### 8.2 Kinetic Friction

When two surfaces are moving with respect to one another, the frictional resistance is almost constant over a wide range of low speeds, and in the standard model of friction the frictional force is described by the relationship below. The coefficient is typically less than the coefficient of static friction, reflecting the common experience that it is easier to keep something in motion across a horizontal surface than to start it in motion from rest.

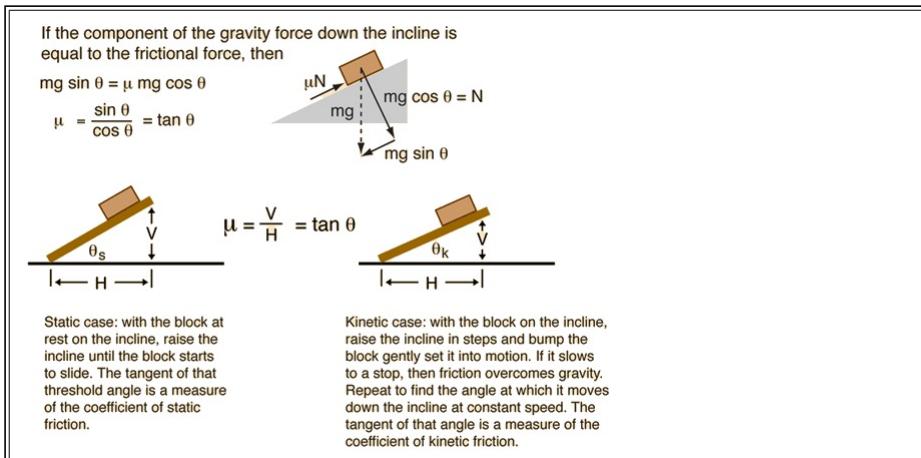


### 8.3 Friction Plot

Static friction resistance will match the applied force up until the threshold of motion. Then the kinetic frictional resistance stays about constant. This plot illustrates the standard model of friction.



The above plot, though representing a simplistic view of friction, agrees fairly well with the results of simple experiments with wooden blocks on wooden inclines. The experimental procedure described below equates the vector component of the weight down the incline to the coefficient of friction times the normal force produced by the weight on the incline.



Having taken a large number of students through this experiment, I can report that the coefficient of static friction obtained is almost always greater than the coefficient of kinetic friction. Typical results for the woods I have used are 0.4 for the static coefficient and 0.3 for the kinetic coefficient.

When carefully standardized surfaces are used to measure the friction coefficients, the difference between static and kinetic coefficients tends to disappear, indicating that the difference may have to do with irregular surfaces, impurities, or other factors which can be frustratingly non-reproducible. To quote a view counter to the above model of friction: "Many people believe that the friction to be overcome to get something started (static friction) exceeds the force required to keep it sliding (sliding friction), but with dry metals it is very hard to show any difference. The opinion probably arises from experiences where small bits of oil or lubricant are present, or where blocks, for example, are supported by springs or other flexible supports so that they appear to bind." R. P. Feynman, R. P. Leighton, and M. Sands, *The Feynman Lectures on Physics*, Vol. I, p. 12-5, Addison-Wesley, 1964.

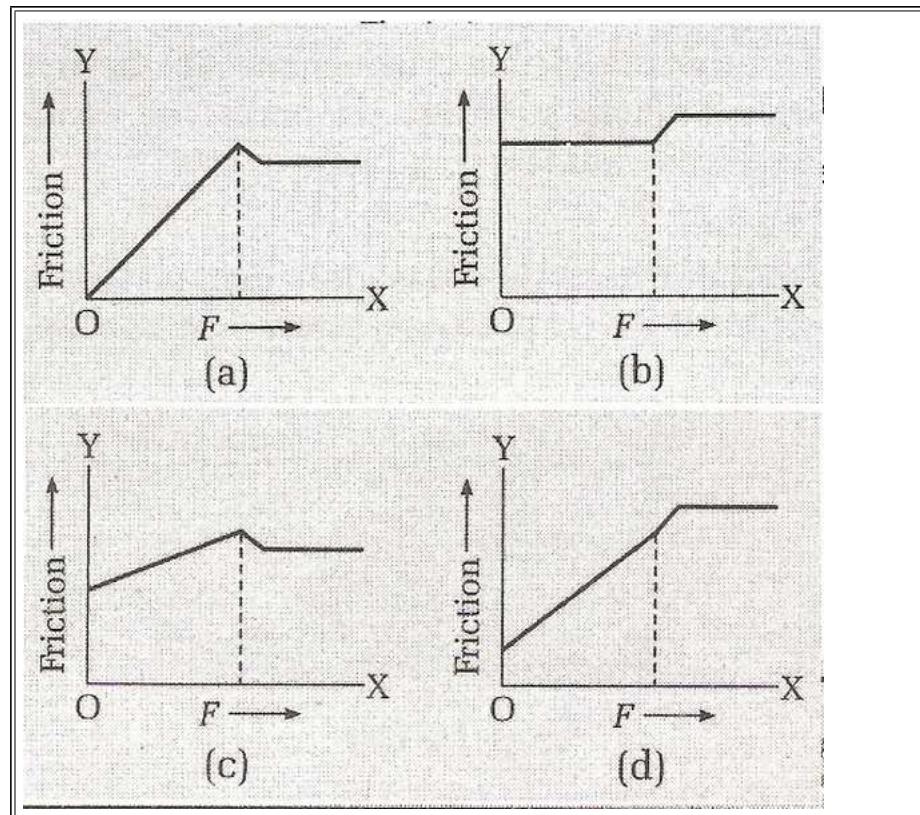
## 8.4 Rolling Friction

A rolling wheel requires a certain amount of friction so that the point of contact of the wheel with the surface will not slip. The amount of traction which can be obtained for an auto tire is determined by the coefficient of static friction between the tire and the road. If the wheel is locked and sliding, the force of friction is determined by the coefficient of kinetic friction and is usually significantly less.

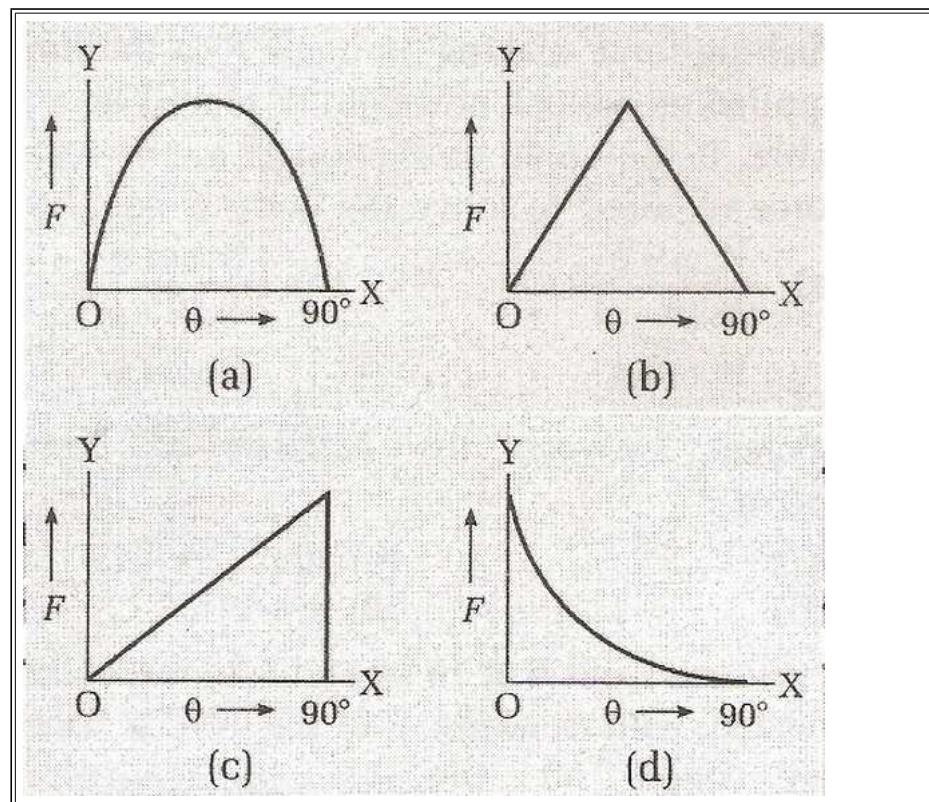
Assuming that a wheel is rolling without slipping, the surface friction does no work against the motion of the wheel and no energy is lost at that point. However, there is some loss of energy and some deceleration from friction for any real wheel, and this is sometimes referred to as rolling friction. It is partly friction at the axle and can be partly due to flexing of the wheel which will dissipate some energy. Figures of 0.02 to 0.06 have been reported as effective coefficients of rolling friction for automobile tires, compared to about 0.8 for the maximum static friction coefficient between the tire and the road.

## 8.5 Few problems related to Friction

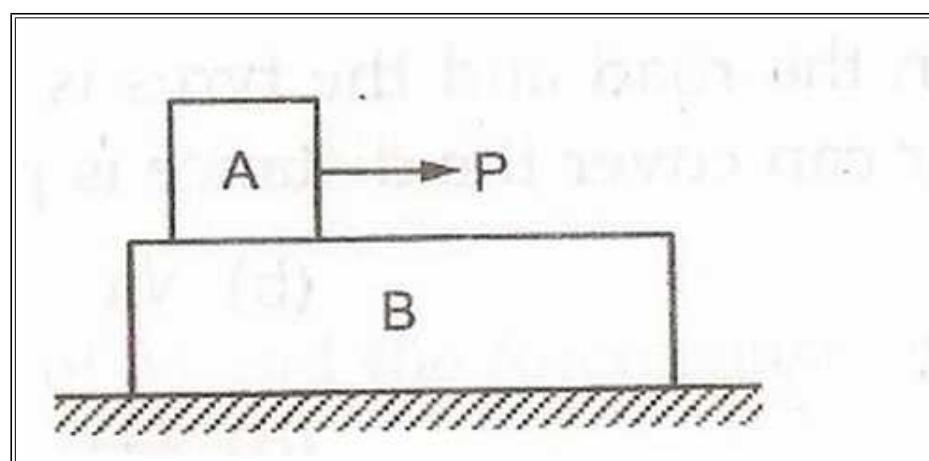
**Example :** A block on the horizontal table is acted upon by a force  $F$ . The graph of frictional force against  $F$  is



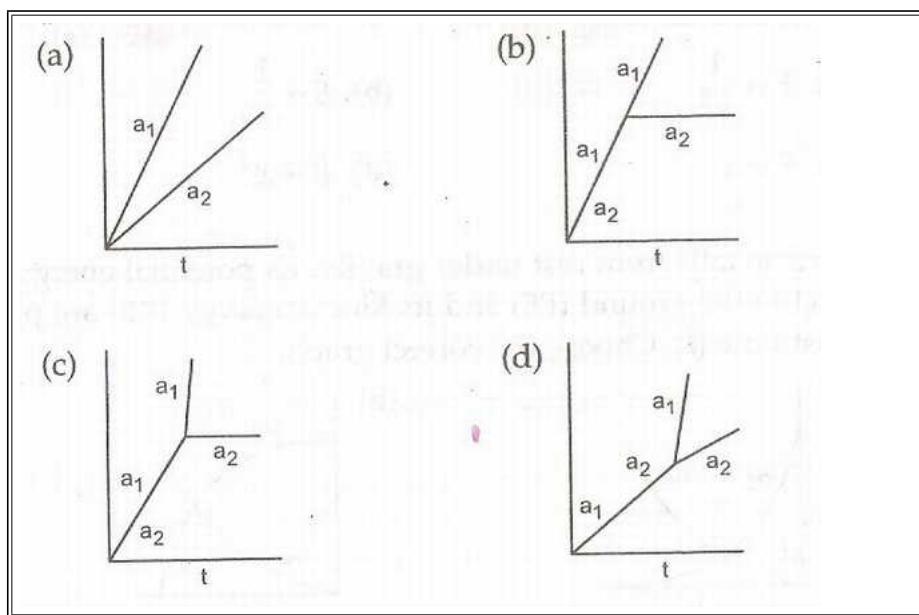
**Example:** A block rests on a rough plane whose inclination  $\theta$  to the horizontal can be varied. Which of the following graphs indicates how the frictional force  $F$  between the block and plane varies as  $\theta$  is increased?



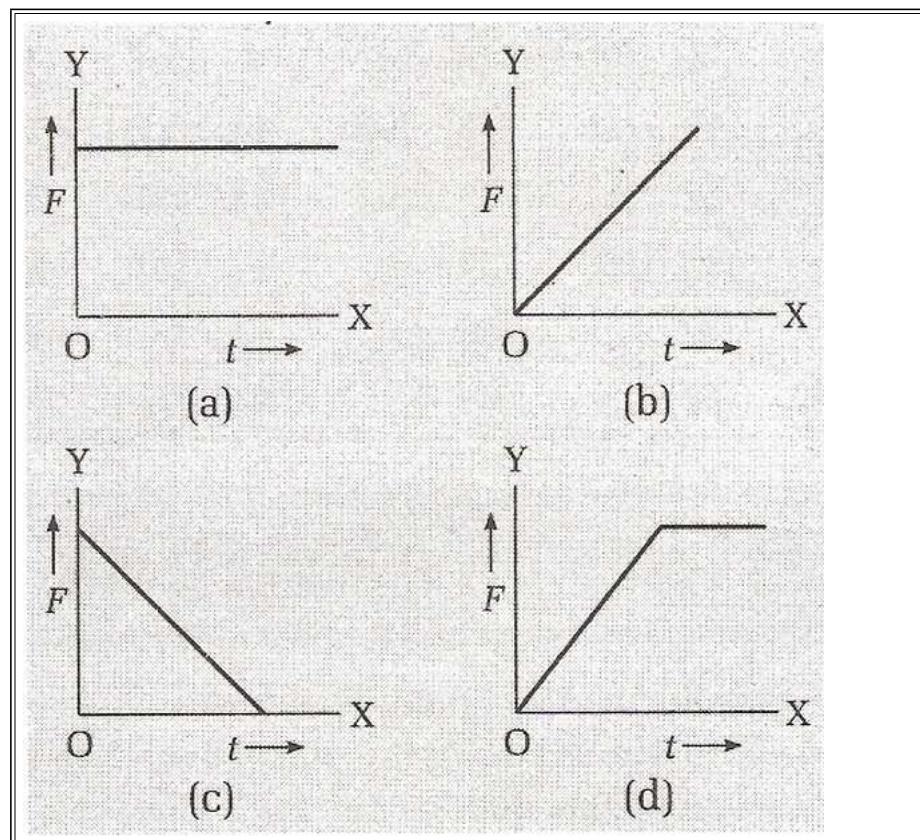
**Example :** Block A is placed on block B, whose mass is greater than that of A.



There is friction between the blocks, while the ground is smooth. A horizontal force  $P$ , increasing linearly with time, begins to act on A. The accelerations  $a_1$  and  $a_2$  of A and B respectively are plotted against time ( $t$ ). Choose the correct graph.



**Example :** A body moves with uniform speed on a rough surface. If force  $F$  of dynamic friction is plotted with time  $t$  as shown in figure, the graph will be



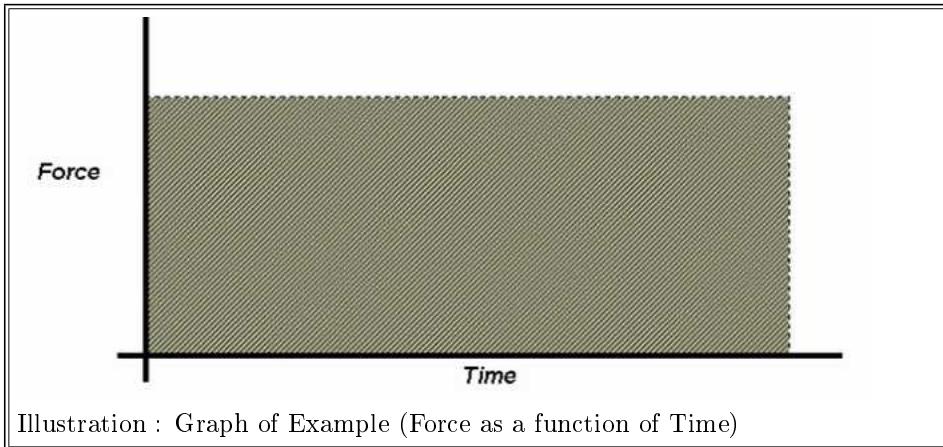


# Chapter 9

## Theory and Problems

### 9.1 Impulse as Force-time Graph

**Example :** For the graph shown above, assume that it shows a constant force of 25 N acting over a 10 s period of time. Determine the impulse.



**Solution :** (Theory : So far we've implied some things about what is constant and what can change in the impulse formula  $F \Delta t = m \Delta v$ .

We look at situations where we expect the mass of the object will stay constant. • The velocity will change, and that's why we put a delta in front of it. • Time is changing (sort of) as we measure it over a period of time. • Force must be a constant. We assume that the force being exerted on the object was always the same, causing a constant acceleration. If we are looking at a simple impulse question (where the force is constant), we can figure out exactly what we can interpret from a graph. • Later this may help us to figure out a more complicated question, like if the force changes. The following graph is an example of one of those simple situations where the force remains constant during the entire time. • If we look at what the slope might represent, we get...

$$\text{slope} = \text{rise} / \text{run}$$

$$\text{slope} = F / \Delta t$$

Since nothing in the impulse formula can be rearranged to give us force over time, the slope doesn't mean anything to us in this situation.

If we look at the area under the line, we get something a bit better...

$$\text{Area} = lw = F\Delta t = \Delta p$$

Since area under the line is equal to impulse...

$$\text{Area} = lw$$

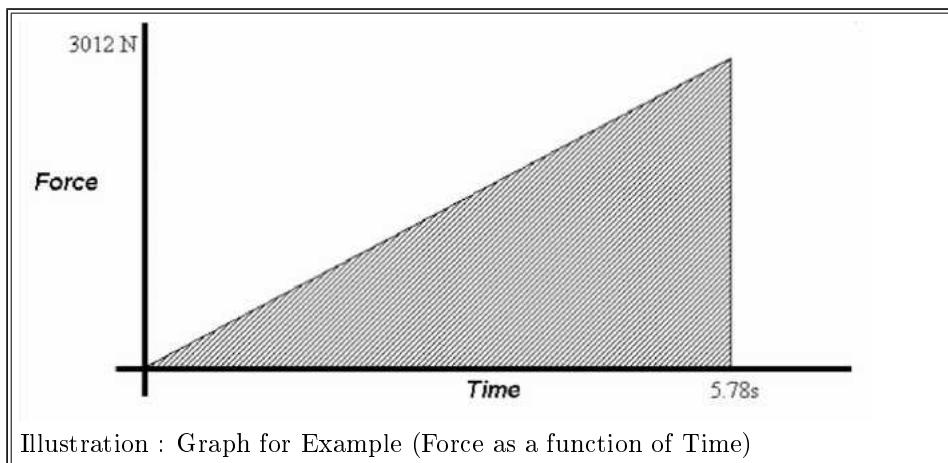
$$\text{Area} = 25 \times 10$$

$$\text{Area} = 2.5e2$$

$$p = 2.5e2\text{Ns}$$

If we really wanted to, we could have simply use  $\Delta p = F\Delta t$  to figure out the impulse. We could do this in this situation because the force is constant. • If we need to do a question where the force is not constant, we can still use the area under the line to get the impulse, even though the formula  $\Delta p = F\Delta t$  can not be used.

**Example :** I am in a car that is accelerating from rest at a red light. I want to calculate the impulse that is acting on the car during the first 5.78s. If I know that the force on the car steadily increases from 0 N to 3012 N over this time, determine the impulse. If the mass of the car is 1500 kg, also determine the final velocity of the car.



**Solution :** Let's start by graphing the information we were given. We will get a nice linear graph, since it said that the force steadily increases.

If we calculate the area under the graph (a triangle) we will know what the impulse is.

$$\begin{aligned} A &= \frac{1}{2}bh \\ &= \frac{1}{2}(5.78\text{ s})(3012\text{ N}) \\ &= 8704.68\text{ A} \\ &= 8.70\text{e}3\text{ kgm/s} \end{aligned}$$

To calculate the final velocity, we can use the value for the impulse we just got with the right hand side of the impulse formula. Remember that the initial velocity (sitting at the light) is zero...

$$\begin{aligned} \Delta p &= m\Delta v \\ \Delta p &= m(v_f - v_i) \\ \Delta p &= mv_f \\ v_f &= \Delta p/m \\ v_f &= 8704.68/1500 \\ v_f &= 5.80312 \\ v_f &= 5.80\text{m/s} \end{aligned}$$

The graph that we make does not have to be a pretty right angle triangle either. We can also do some crazy stuff with what we are looking for in the question, as the next example shows.

**Example :** This graph shows the result of applying 500 kgm/s of impulse to an object as it moved across the floor for 10.0 s. Determine the maximum force that was exerted.

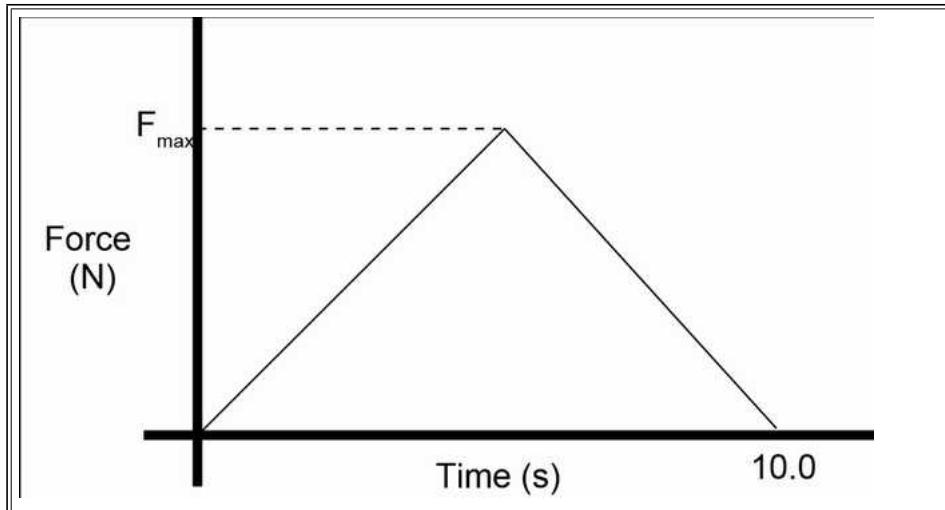


Illustration 3: Pushing object across the floor.

**Solution :** Even though it is not a right angle triangle, this graph still shows a triangle that we can use the regular area formula with. In this case, we already know the area (the impulse is 500 kgm/s) and we know the base (10.0 s). All we want is the height of the triangle, since that is the magnitude of the maximum force.

$$\begin{aligned} \text{Area} &= bh/2 \\ \Delta p &= F\Delta t/2 \\ F = 2\Delta p/t &= 2 \times 500/10.0 \text{ F} = 100\text{N} \end{aligned}$$

Even if the graph is a curved line, you can still at least estimate the area under the graph. • Although this will only be an approximate area, without getting into calculus it's as good as you'll get and as good as you need. ◦ On the graph shown below we have an s-curve that would be difficult to calculate the exact area of. ◦

Instead, we just look at the triangle drawn in red. For the little bit extra it has near the beginning, it misses a bit later on. These two parts should more or less make up for each other, so that the area of the triangle will be about the same as the area under the curve.

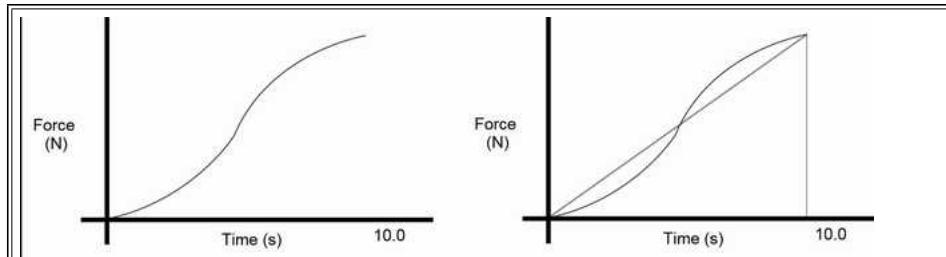
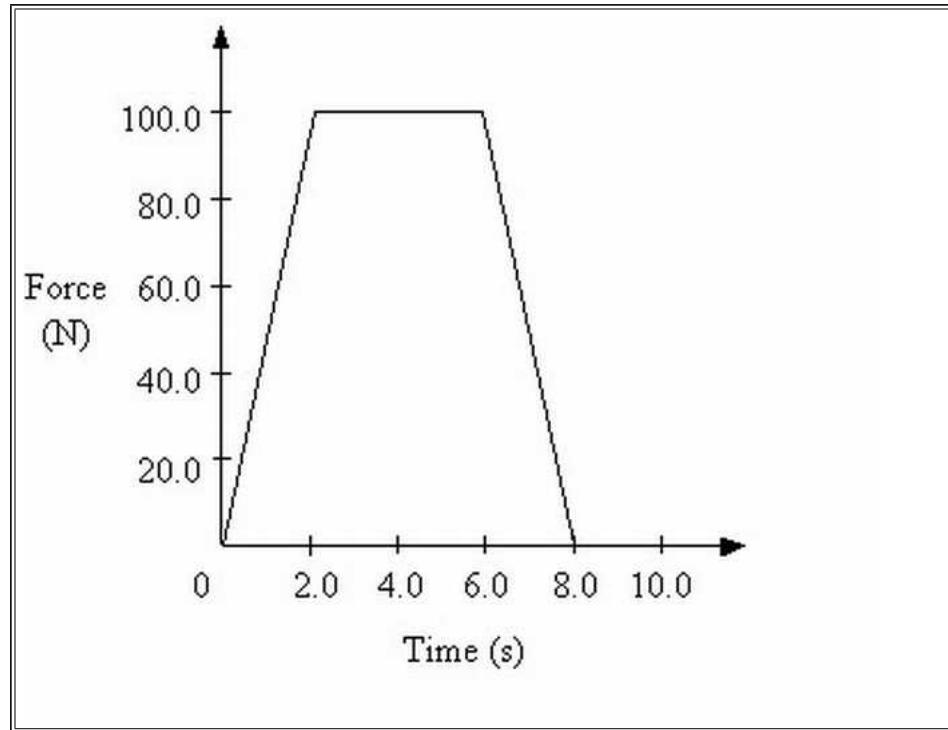


Illustration 4: Instead of trying to figure out the area of the curve exactly, we just use the area of the triangle as an approximation.

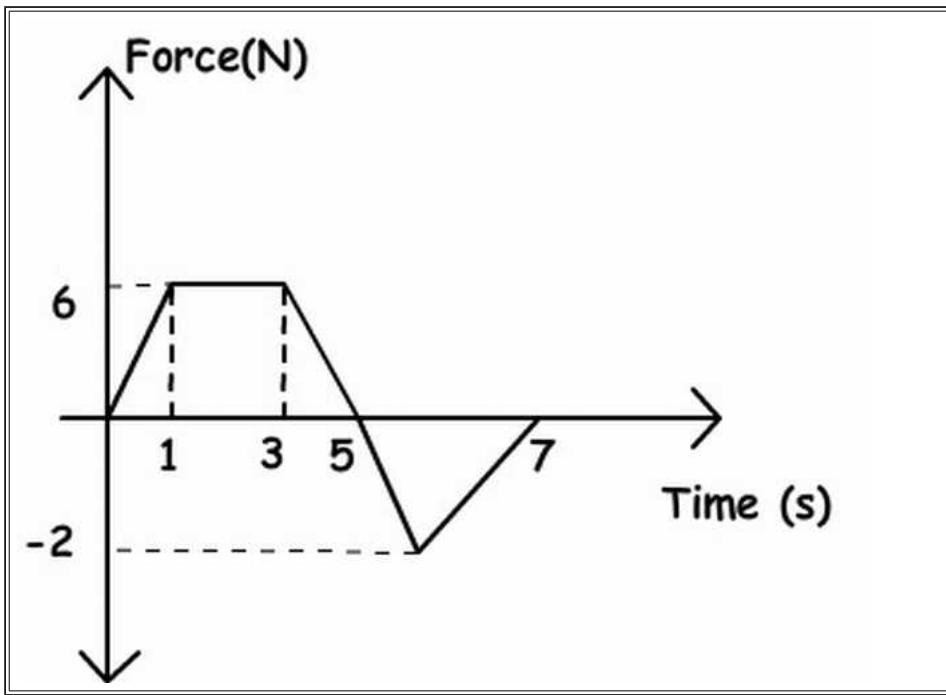
## 9.2 Force Time graph with respect to momentum



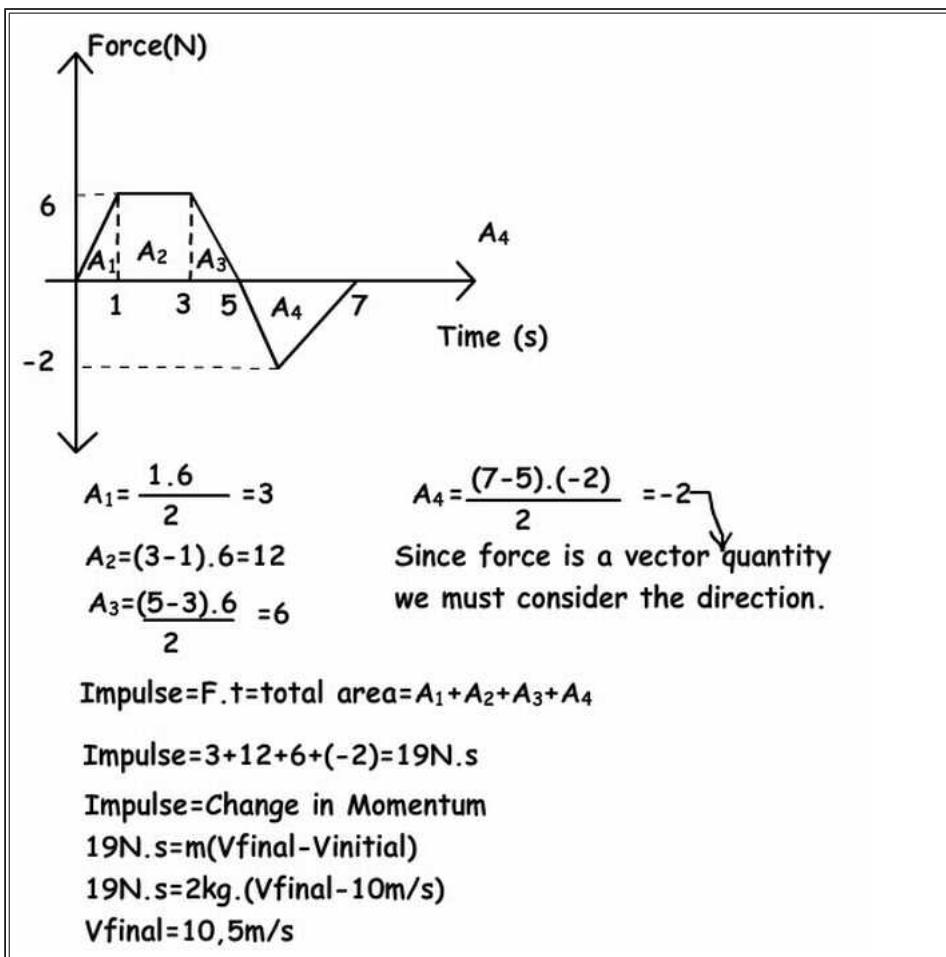
**Example :** If the mass of the object is 3.0 kg, what is its final velocity over the 8.0 s time period? n.d.

**Solution :** You need the area under the curve, and you do not need calculus, as that is a trapezoid. The area of a trapezoid is the average of the bases times the height, which is  $(4 + 8)\text{seconds}/2 * 100 \text{ N} = 600 \text{ N*s}$ . Set this to  $mv - mv_o$ , and assuming  $v_o$  is zero get  $v_{\text{final}} = 200 \text{ m/s}$ .

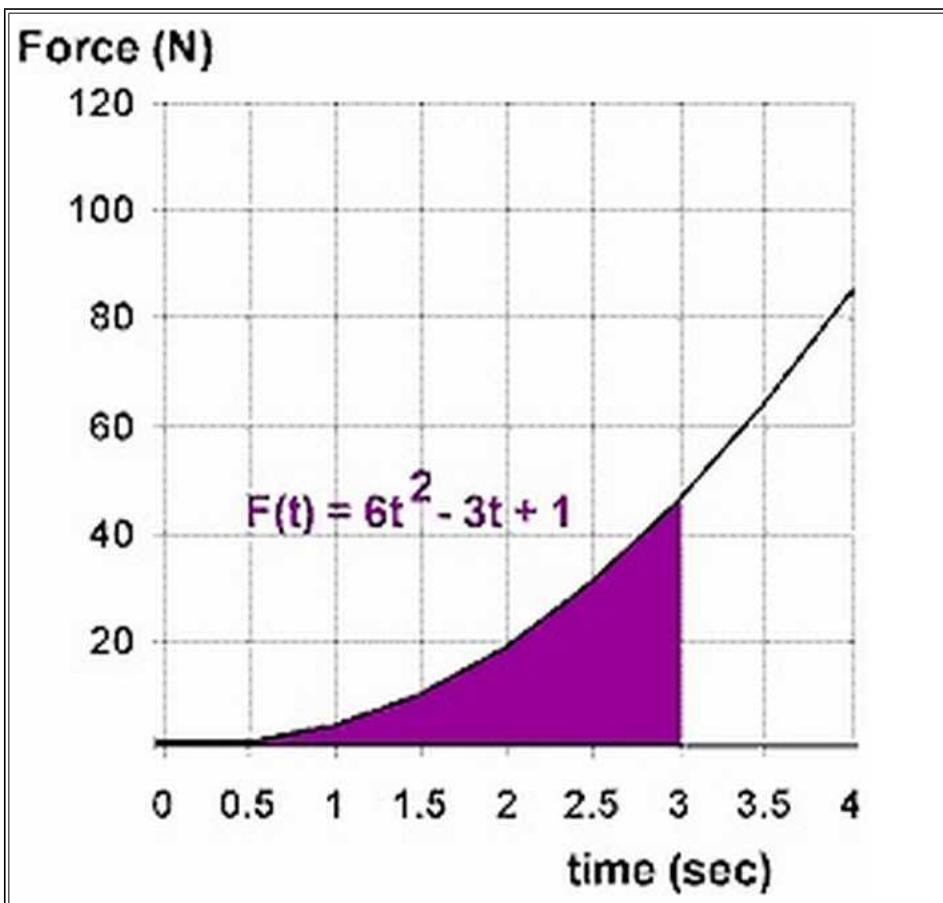
**Example :** The graph given below belongs to an object having mass 2kg and velocity 10m/s. It moves on a horizontal surface. If a force is applied to this object between (1-7) seconds find the velocity of the object at 7 seconds. n.d.



**Solution :** Area under the graph gives us impulse. First, we find the total impulse with the help of graph given above then total impulse gives us the momentum change. Finally, we find the final velocity of the object from the momentum change.



**Example :** Suppose a force,  $F(t) = 6t^2 - 3t + 1$ , acts on an 7-kg mass for three seconds.



a) What impulse will the 7-kg object receive in the first three seconds?

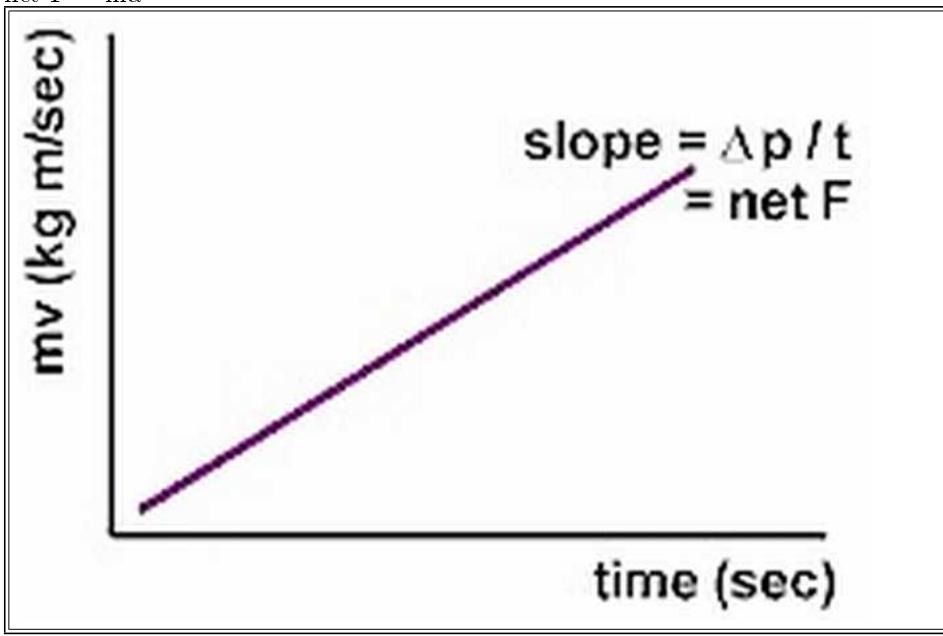
b) If the mass started from rest, what is its final velocity?

Solution : Force as the rate of change of momentum The impulse equation  $J = (\text{net } F)t = \Delta p$  where  $p = mv$  can be rearranged to state that the applied net force applied to an object equals the rate of change of its momentum.

$$\text{net } F = \frac{\Delta p}{\Delta t}$$

$$\text{net } F = \frac{m\Delta v}{\Delta t}$$

$$\text{net } F = ma$$

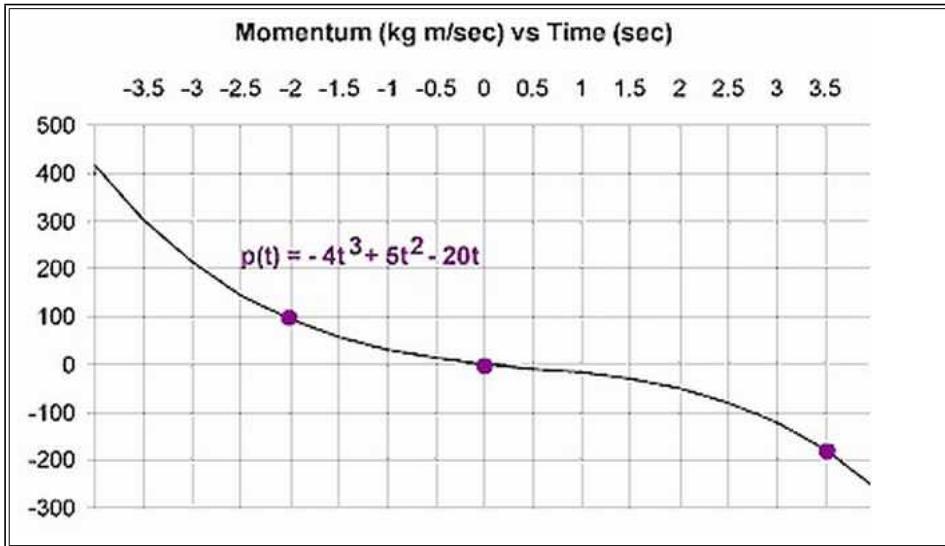


That is, the net force acting on an object can be calculated as the slope of a momentum vs time graph. In terms of the calculus, this result equates to taking the derivative.

$$\frac{dp(t)}{dt} = F(t)$$

Notice that force must be expressed as a function in terms of time, not displacement. Calculus will allow us to determine expressions for instantaneous, non-constant forces and thus is applicable to a wider range of situations. Let's work an example using this relationship.

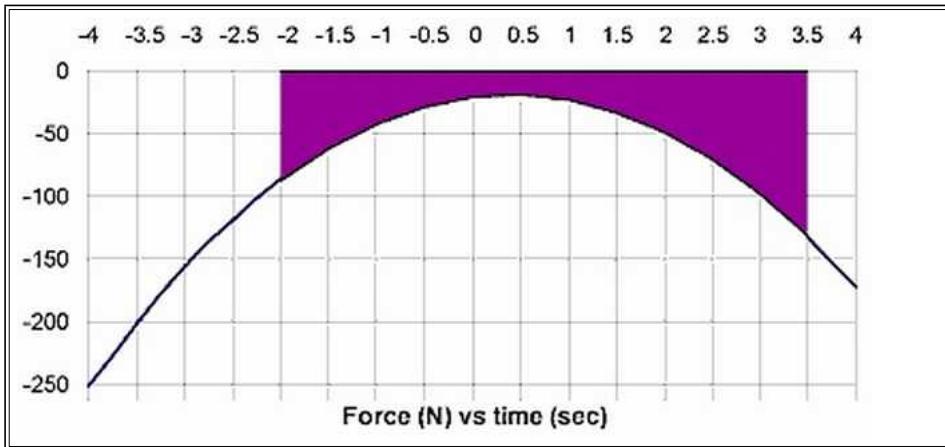
Using the graph provided below, determine the instantaneous force acting on the 7-kg mass at each of the specified times:



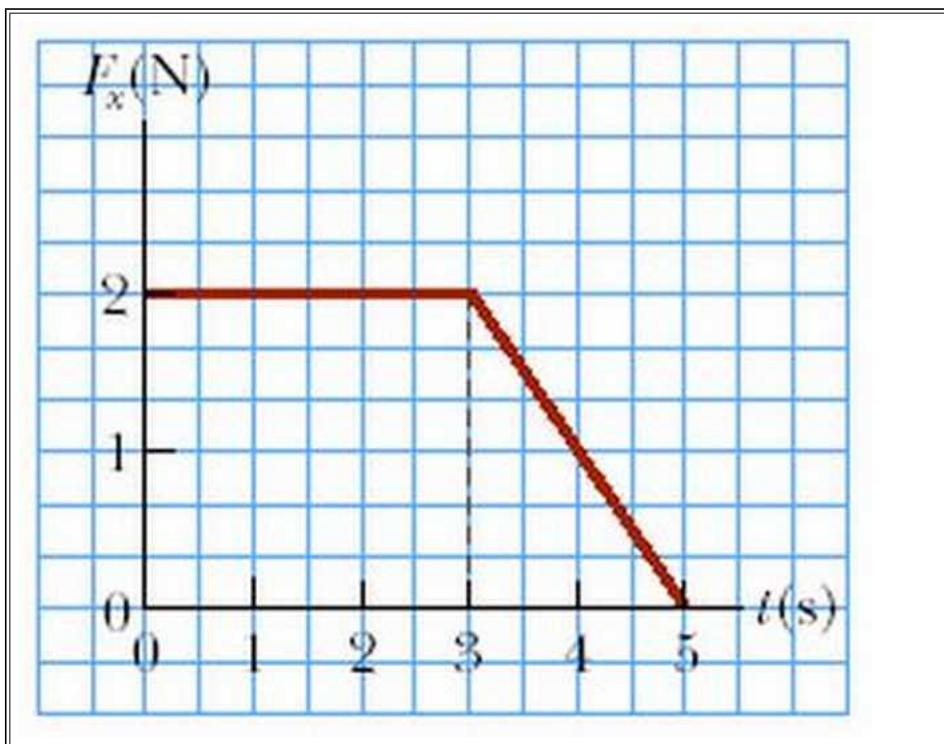
$$t = -2 \text{ seconds},$$

$$t = 0 \text{ seconds},$$

$$t = 3.5 \text{ seconds}.$$



**Example :** The force shown in the force vs time graph below acts on a 1.7 kg object.



(a) Find the magnitude of the impulse of the force.

Ans : 8 kg m/s.

(b) Find the final velocity of the object if the object was initially at rest.

Ans : 2.76 m/s

(c) Find the final velocity of the object if the object was initially moving along the x axis with a velocity of -1.7 m/s.

Ans : “ ”

Note : The force shown in the force vs time graph below acts on a 1.7 kg object. Find the final velocity of the object if the object was initially at rest. Find the final velocity of the object if the object was initially moving along the x axis with a velocity of -1.7 m/s.

**Example :** Relating Momentum and Impulse

**EXPLORATION –** An impulsive bike ride Suki is riding her bicycle, in a straight line, along a flat road. Suki and her bike have a combined mass of 50 kg. At  $t = 0$ , Suki is traveling at 8.0 m/s. Suki coasts for 10 seconds, but when she realizes she is slowing down, she pedals for the next 20 seconds. Suki pedals so that the static friction force exerted on the bike by the road increases linearly with time from 0 to 40 N, in the direction Suki is traveling, over that 20-second period. Assume there is constant 10 N resistive force, from air resistance and other factors, acting on her and the bicycle the entire time. Step 1 - Sketch a diagram of the situation. The diagram is shown in Figure 6.2, along with the free-body diagram that applies for the first 10 s and the free-body diagram that applies for the 20second period while Suki is pedaling.

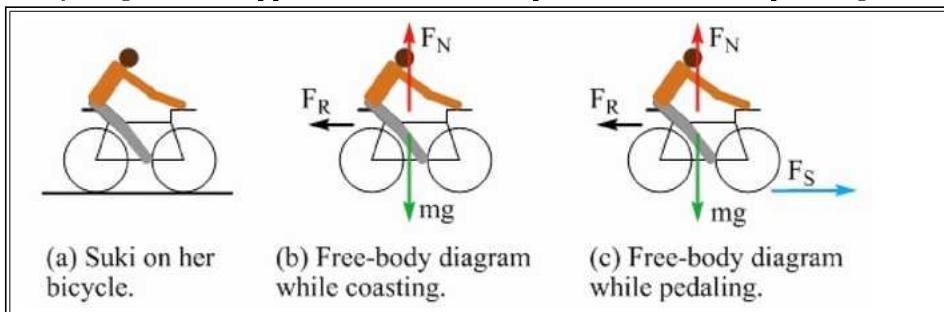


Figure : A diagram of (a) Suki on her bike, as well as free-body diagrams while she is (b) coasting and while she is (c) pedaling. Note that in free-body diagram (c), the static friction force  $\vec{F}_S$  gradually increases because of the way Suki pedals.

Step 2 - Sketch a graph of the net force acting on Suki and her bicycle as a function of time. Take the positive direction to be the direction Suki is traveling. In the vertical direction, the normal force exactly balances the force of gravity, so we can focus on the horizontal forces. For the first 10 seconds, we have only the 10 N resistive force, which acts to oppose the motion and is thus in the negative direction. For the next 20 seconds, we have to account for the friction force that acts in the direction of motion and the resistive force. We can account for

their combined effect by drawing a straight line that goes from  $-10 \text{ N}$  at  $t = 10 \text{ s}$ , to  $+30 \text{ N}$  ( $40 \text{ N} - 10\text{N}$ ) at  $t = 30 \text{ s}$ . The result is shown in Figure 6.3.

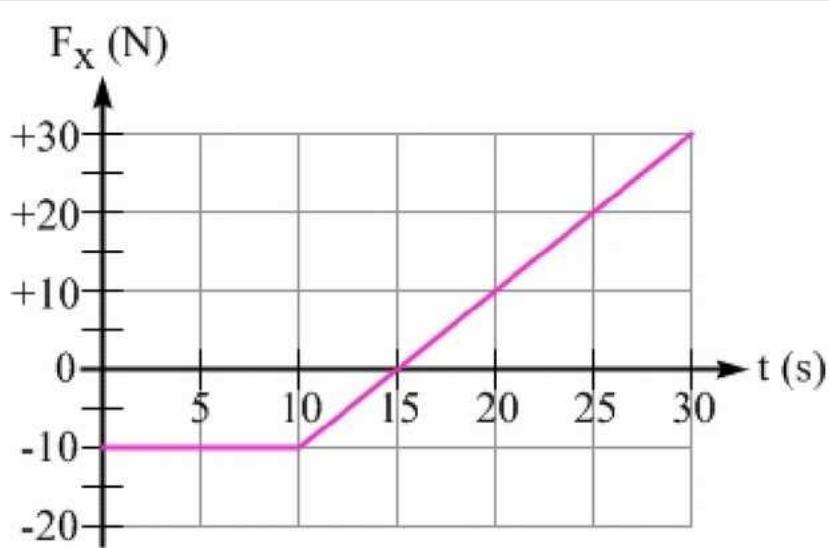


Figure 6.3: A graph of the net force acting on Suki and her bicycle as a function of time.

Step 3 - What is Suki's speed at  $t = 10 \text{ s}$ ? Let's apply Equation 6.3, which we can write as:

$$\vec{F}_{\text{net}} \Delta t = \Delta(m\vec{v}) = m\Delta\vec{v} = m(\vec{v}_{10s} - \vec{v}_i)$$

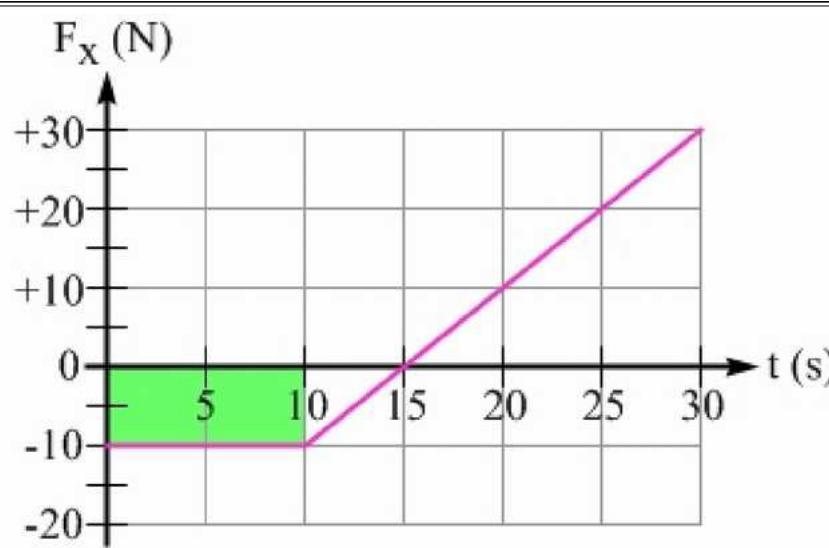
Solving for the velocity at  $t = 10 \text{ s}$  gives:

$$\vec{v}_{10s} = \vec{v}_i + \frac{\vec{F}_{\text{net}} \Delta t}{m} = \vec{v}_i + \frac{(-10\text{N})(10s)}{50\text{kg}} = \vec{v}_i - 2.0\text{m/s} = +6.0\text{m/s}$$

Thus, Suki's speed at  $t = 10 \text{ s}$  is  $6.0 \text{ m/s}$ . We can also obtain this result from the forceversus-time graph, by recognizing that the impulse,  $\vec{F}_{\text{net}} \Delta t$ , represents the area under this graph over some time interval  $\Delta t$ . Let's find the area under the graph, over the first 10 seconds, shown highlighted in green in Figure 6.4. The area is negative, because the net force is negative over that time interval. The area under the graph is the impulse:

$$\vec{F}_{\text{net}} \Delta t = -10\text{N} \times 10\text{s} = -100\text{Ns} = -100\text{kg m/s}$$

Figure 6.4: The green rectangle represents the area under the graph for the first 10 s. The area is negative, because the force is negative. From Equation 6.3, we know the impulse is equal to the change in momentum.



Suki's initial momentum is

$m\vec{v}_i = 50\text{kg} \times 8.0\text{m/s} = +400\text{kg m/s}$ . Her momentum at  $t = 10 \text{ s}$  is therefore  $+400\text{kg m/s} - 100\text{kg m/s} = +300\text{kg m/s}$ . Dividing this by the mass to find the velocity at  $t = 10 \text{ s}$  confirms what we found above:

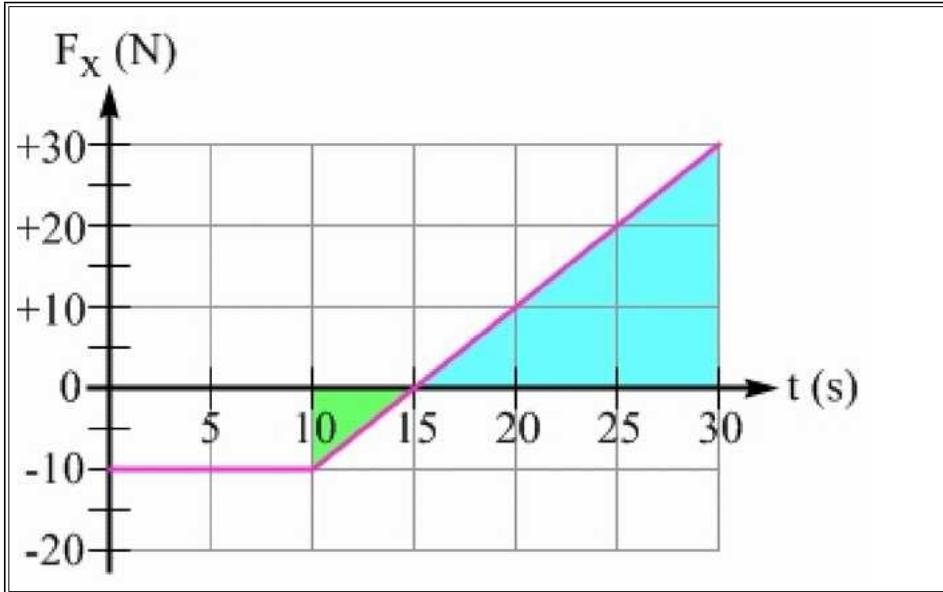
$$\vec{v}_{10s} = \frac{\vec{p}_{10s}}{m} = \frac{\vec{p}_i + \Delta\vec{p}}{m} = \frac{+300\text{kgm/s} - 100\text{kgm/s}}{50\text{kg}} = \frac{+300\text{kgm/s}}{50\text{kg}} = +6.0\text{m/s}$$

Step 4 - What is Suki's speed at  $t = 30 \text{ s}$ ? Let's use the area under the force-versus-time graph, between  $t = 10 \text{ s}$  and  $t = 30 \text{ s}$ , to find Suki's change in momentum over that 20-second period. This area is highlighted in Figure 6.5, split into a negative area for the time between  $t = 10 \text{ s}$  and  $t = 15 \text{ s}$ , and a positive area between

$t = 15 \text{ s}$  and  $t = 30 \text{ s}$ . These regions are triangles, so we can use the equation for the area of a triangle,  $0.5 \times \text{base} \times \text{height}$ . The area under the curve, between  $10 \text{ s}$  and  $15 \text{ s}$ , is  $0.5 \times (5.0\text{s}) \times (-10 \text{ N}) = -25 \text{ kg m/s}$ . The area between  $15 \text{ s}$  and  $30 \text{ s}$  is  $0.5 \times (15\text{s}) \times (30 \text{ N}) = +225 \text{ kg m/s}$ . The total area (total change in momentum) is  $+200 \text{ kg m/s}$ .

Note that another approach is to multiply the average net force acting on Suki and the bicycle ( $+10 \text{ N}$ ) over this interval, by the time interval ( $20 \text{ s}$ ), for a  $+200 \text{ kg m/s}$  change in momentum.

Figure 6.5: The shaded regions correspond to the area under the curve for the time interval from  $t = 10 \text{ s}$  to  $t = 30 \text{ s}$ .



In step 3, we determined that Suki's momentum at  $t = 10 \text{ s}$  is  $+300 \text{ kg m/s}$ . With the additional  $200 \text{ kg m/s}$ , the net momentum at  $t = 10 \text{ s}$  is  $+500 \text{ kg m/s}$ . Dividing by the  $50 \text{ kg}$  mass gives a velocity at  $t = 30 \text{ s}$  of  $+10 \text{ m/s}$ .

Key idea for the graphical interpretation of impulse: The area under the net force versus time graph for a particular time interval is equal to the change in momentum during that time interval.



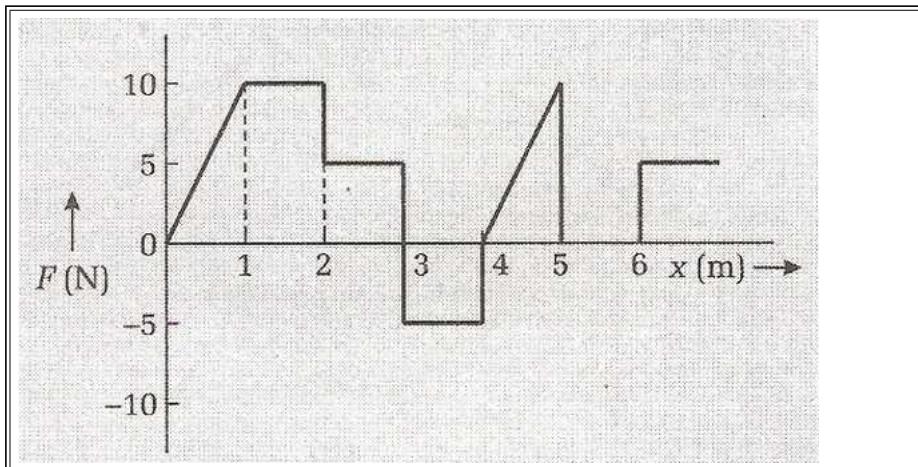
# Chapter 10

## Problems for Practice

### 10.1 General Problem Set

#### 10.1.1 Single Answer Type

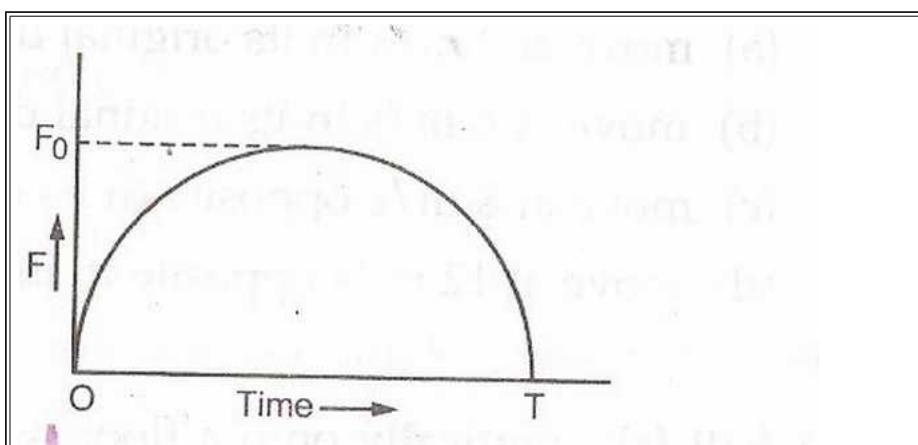
**Example :** The relationship between the force  $F$  and position  $x$  of a body is as shown in figure. The work done in displacing the body from  $x=1\text{m}$  to  $x=5\text{m}$  will be



- a) 30 J
- b) 15 J
- c) 25 J
- d) 20 J

{ Hint : Area under the graph from 1 to 5 taking signs , 15 J }

**Example:** A particle of mass  $m$ , initially at rest, is acted upon by a variable force  $F$  for a brief interval of time  $T$ . It begins to move with a velocity  $u$  after the force stops acting.  $F$  is shown in the graph as a function of time. The curve is a semicircle



a)  $u = \frac{\pi F_0^2}{2m}$

b)  $u = \frac{\pi T^2}{8m}$

c)  $u = \frac{\pi F_0 T}{4m}$

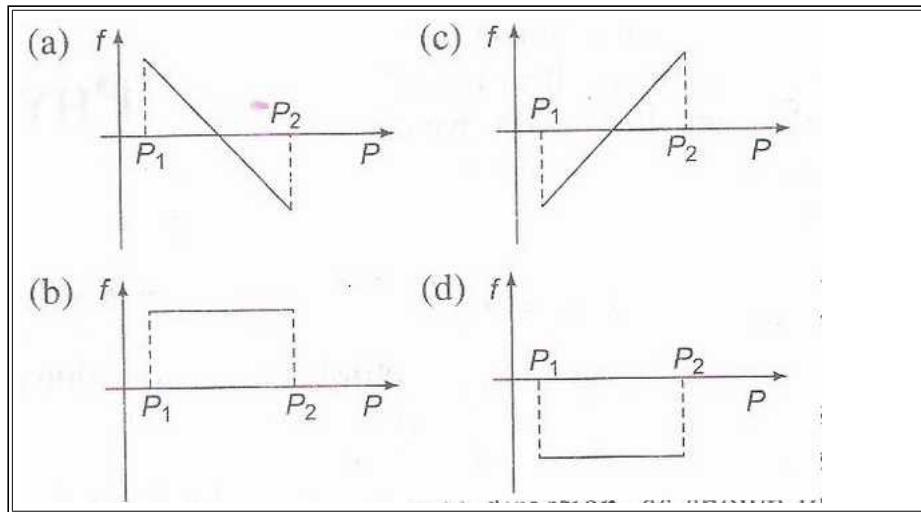
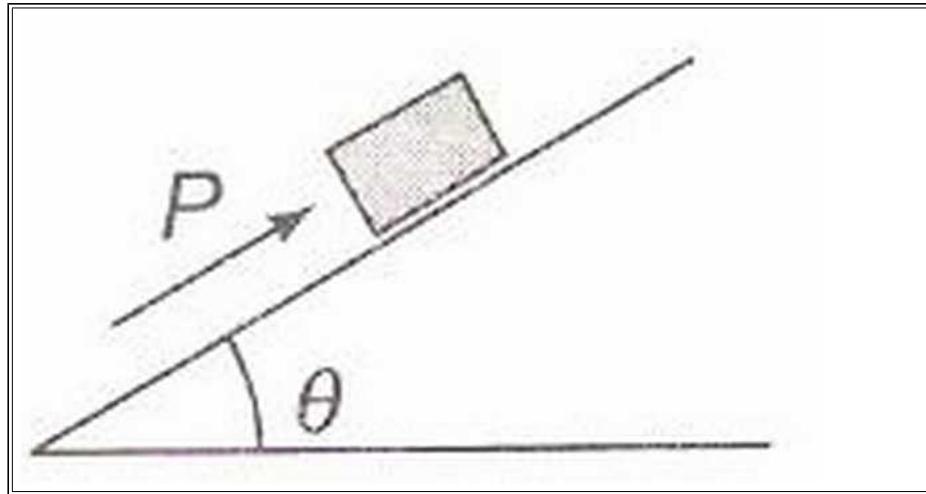
d)  $u = \frac{F_0 T}{2m}$

{ Hint : From impulse relation ,  $mv_f = \frac{\pi F_0^2}{2}$ . So, a, b,c }

## 10.2 Previous Years IIT Problems

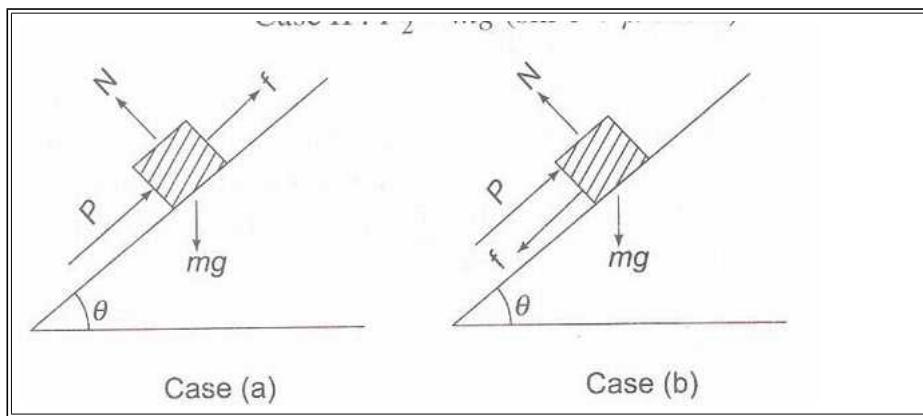
### 10.2.1 Single Answer

**Example:** A block of mass  $m$  is on an inclined plane of angle  $\theta$ . The coefficient of friction between the block and the plane is  $\mu$  and  $\tan\theta > \mu$ . The block is held stationary by applying a force  $P$  parallel to the plane. The direction of force pointing up the plane is taken to be positive. As  $P$  is varied from  $P_1 = mg(\sin\theta - \mu\cos\theta)$  to  $P_2 = mg(\sin\theta + \mu\cos\theta)$ , the frictional force  $f$  versus  $P$  graph will look like



{ Solution: Case I :  $P_1 = mg(\sin\theta - \mu\cos\theta)$

Case II:  $P_2 = mg(\sin\theta + \mu\cos\theta)$



In case a), frictional force  $f$  is positive and in case b),  $f$  is negative. When  $P = mgsin\theta, f = \mu mgcos\theta = 0$

When  $P < mgsin\theta, f = mgsin\theta - P$

When  $P > mgsin\theta, f = P - mgsin\theta$

Thus  $f$  varies linearly with  $P$ , is positive when  $P = P_1$  and negative when  $P = P_2$ . So the correct option is a)

}



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## Part IV

# Energy Conservation



# Chapter 11

## Abstract Introduction

### 11.1 KINETIC ENERGY

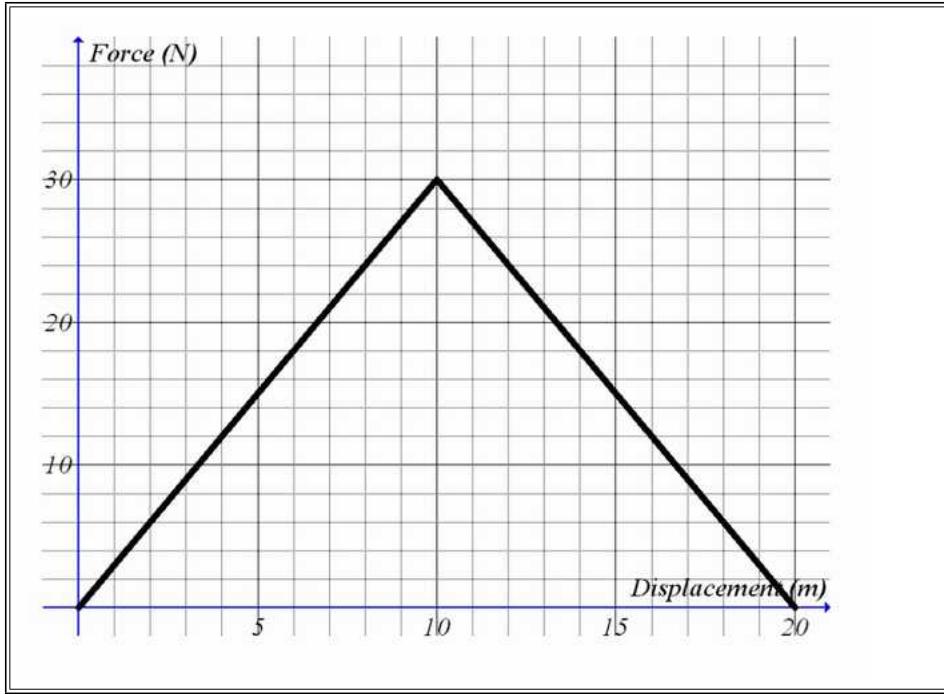
Objects have energy because of their motion; this energy is called kinetic energy. Kinetic energy of the objects having mass  $m$  and velocity  $v$  can be calculated with the formula given below;

$$E_k = \frac{1}{2}mv^2$$

As you see from the formula, kinetic energy of the objects is only affected by the mass and velocity of the objects. The unit of the  $E_k$  is again from the formula  $\text{kg}\cdot\text{m}^2/\text{s}^2$  or in general use joule.

### 11.2 Work Done by a Variable Force

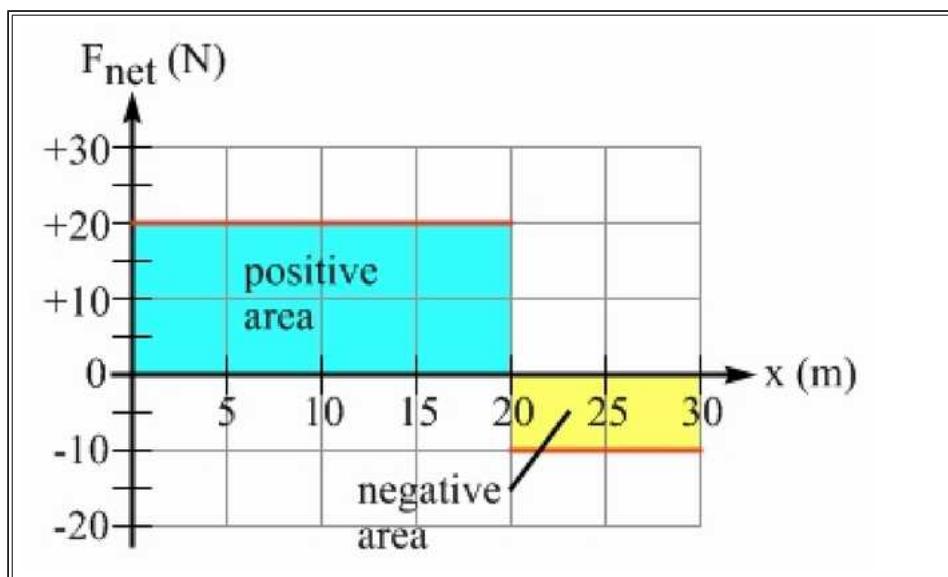
Graphically, the work done on an object or system is equal to the area under a Force vs. displacement graph:



The area under the graph from zero to 20 meters is 300 N m. Thus, the force represented by the graph does 300 J of work. This work is also a measure of the energy which was transferred while the force was being applied

### 11.3 The net force vs. position graph

The area under the net force vs. position graph represents the change in kinetic energy (also known as the net work).

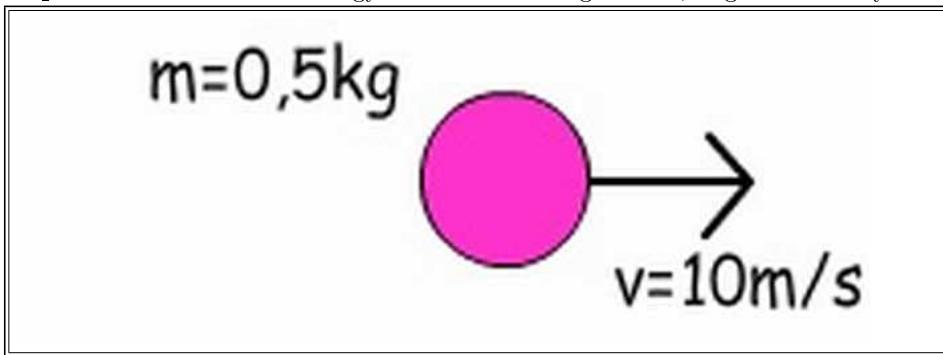


## Chapter 12

# Theory and Problems

### 12.1 Force vs. Distance graph.

Example : Find the kinetic energy of the ball having mass 0,5 kg and velocity 10m/s.

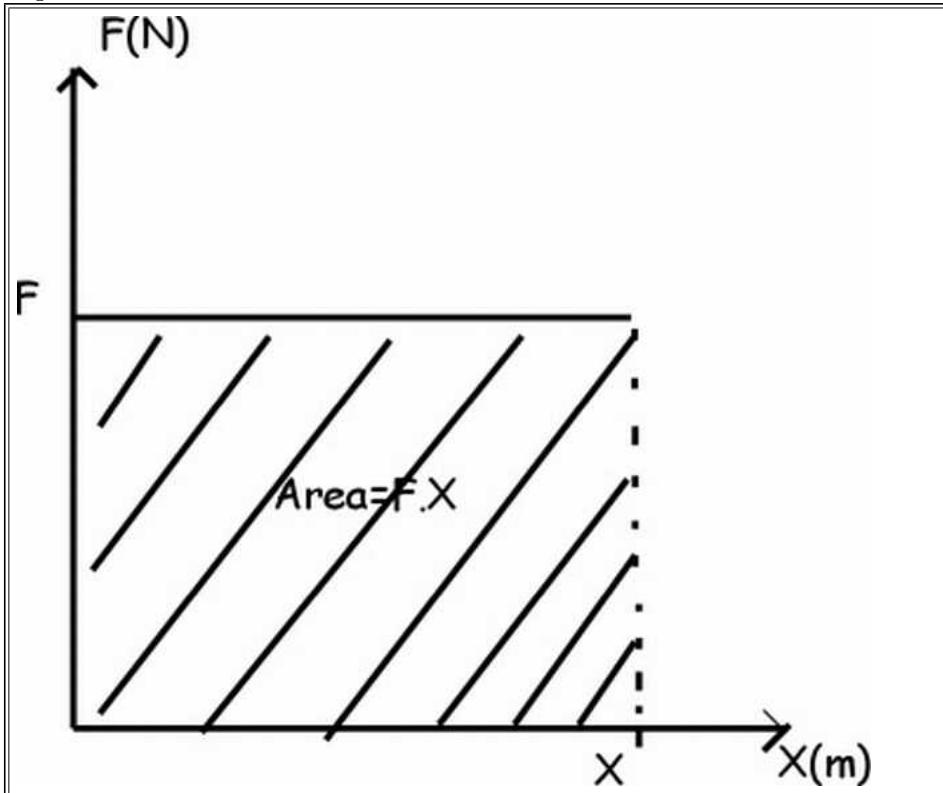


$$E_k = \frac{1}{2}mv^2$$

$$E_k = \frac{1}{2} \cdot 0,5 \cdot (10)^2$$

$$E_k = 25 \text{ joule}$$

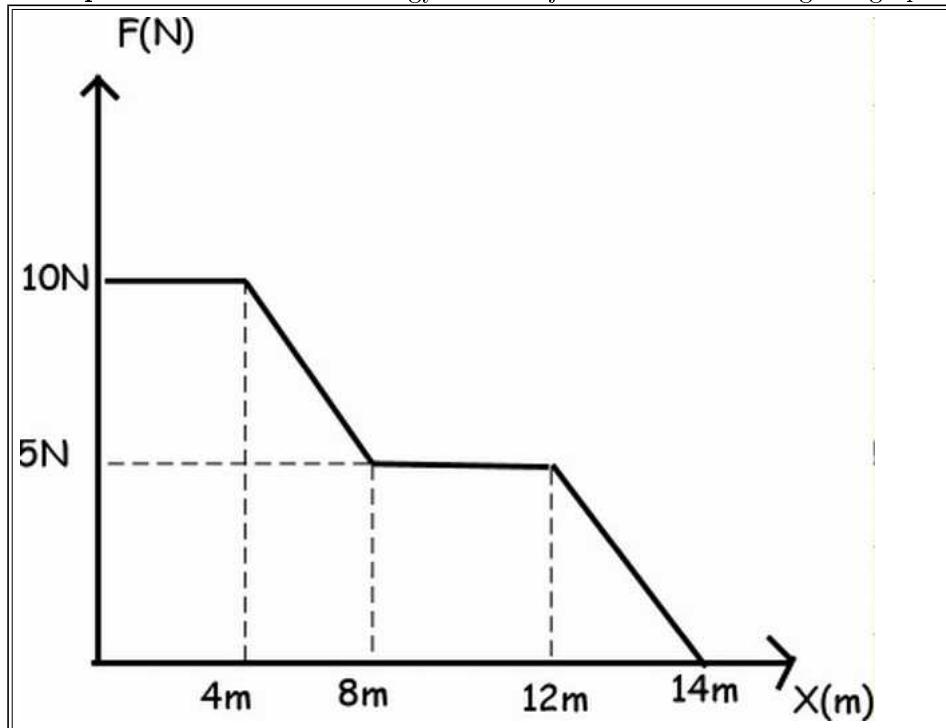
As in the case of Kinematics we can use graphs to show the relations of the concepts here. Look at the given graph of



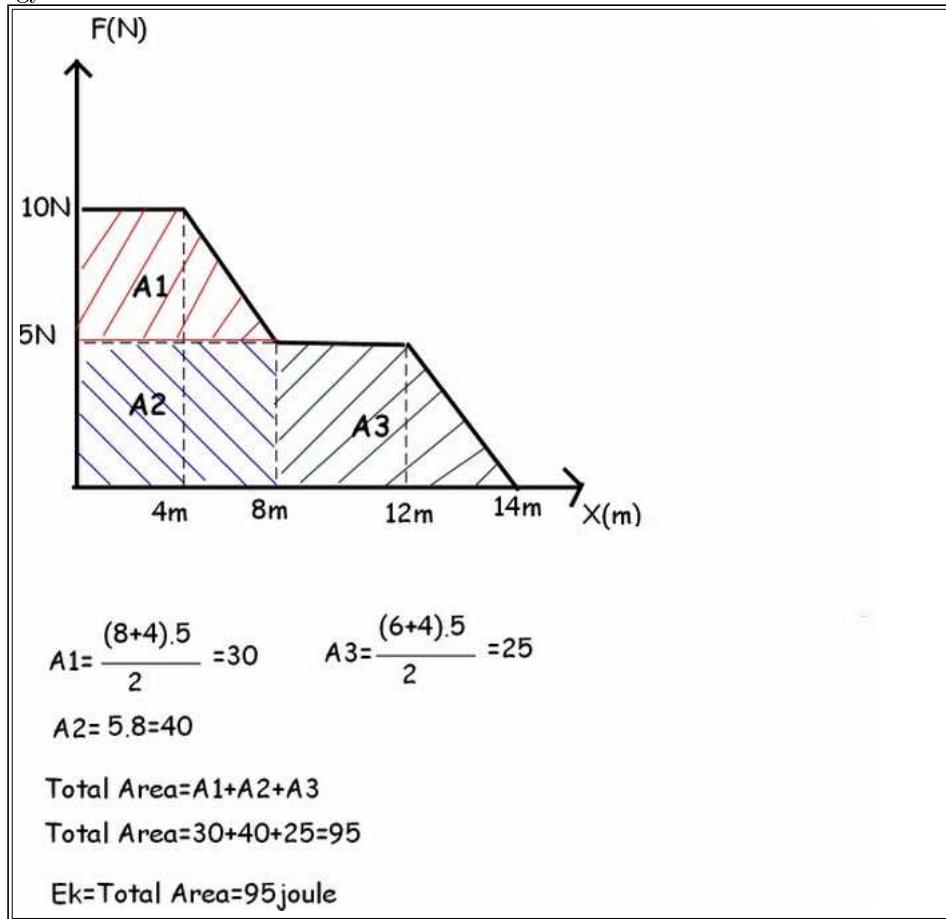
Area under the force vs. distance graph gives us work  
Work=Force. Distance=Area=F.X (distance)

We can find energy of the objects from their Force vs. Distance graph.

**Example :** Find the Kinetic Energy of the object at 14m from the given graph below.



We can find the total kinetic energy of the object after 14m from the graph; we use area under it to find energy.

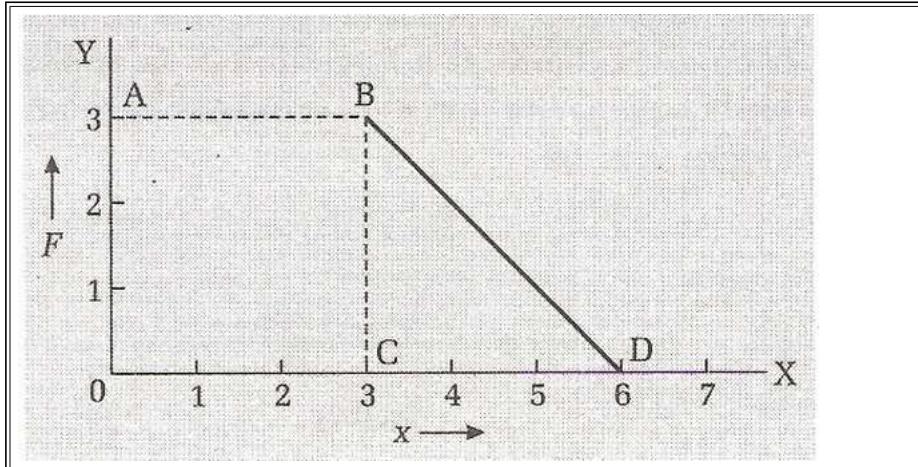


# Chapter 13

## Practice Problems

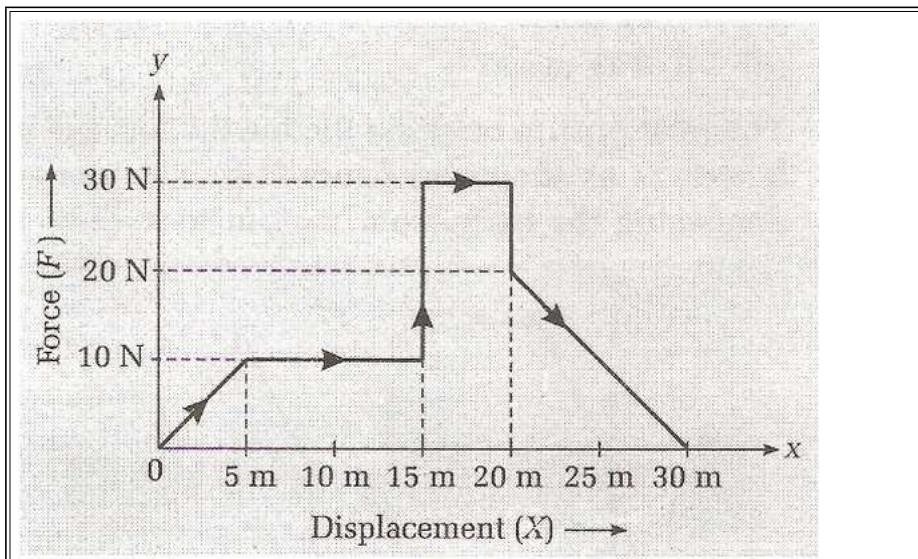
### 13.1 General Problem Set

**Example :** A force  $F$  acting on an object varies with distance  $x$  as shown in Figure. The force is in newton (N) and the distance ( $x$ ) in metre. The work done by the force in moving from  $x=0$  to  $x=6\text{m}$  is



- a) 4.5 J
- b) 9.0 J
- c) 14.5 J
- d) 15 J

**Example :** Given below is a graph between a variable force ( $F$ ) (along y-axis) and the displacement ( $X$ ) (along x-axis) of a particle in one dimension. The work done by the force in the displacement interval between 0 m and 30 m is

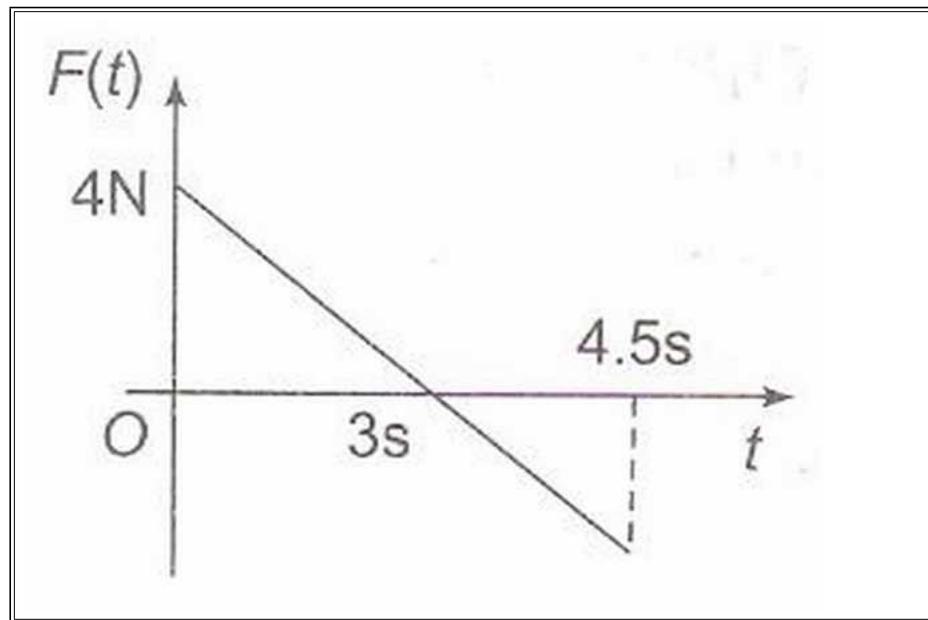


- a) 275 J
- b) 375 J
- c) 400 J
- d) 300 J

## 13.2 Previous Years IIT Problems

### 13.2.1 Single Answer

**Example:** A block of mass 2 kg is free to move along the x-axis. It is at rest and from  $t=0$  onwards it is subjected to a time-dependent force  $F(t)$  in the x direction. The force  $F(t)$  varies with  $t$  as shown in the figure. The kinetic energy of the block after 4.5 seconds is



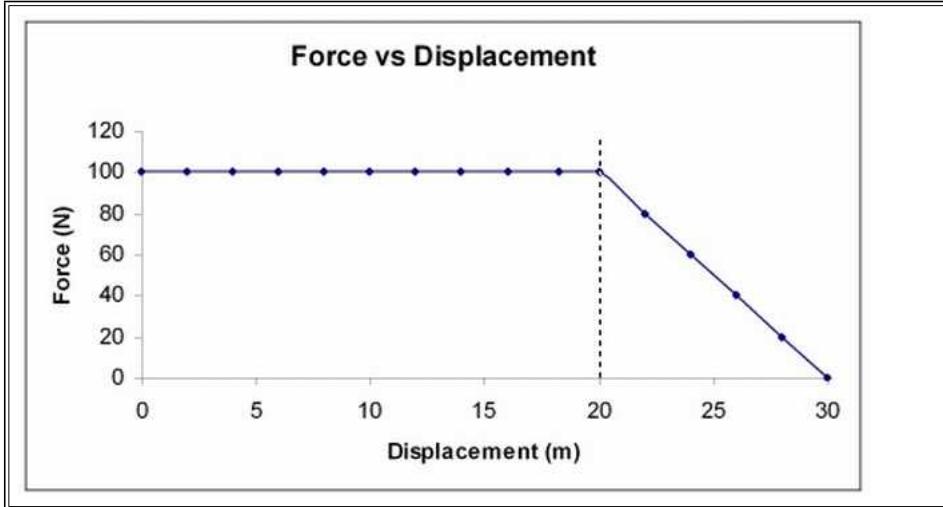
- a) 4.50J
- b) 7.50J
- c) 5.06J
- d) 14.06J

# Chapter 14

## Review Questions I

Refer to the following information for the next thirteen questions. n.d.

A 5.0-kg mass is pushed along a straight line by a net force described in the graph below. The object is at rest at  $t = 0$  and  $x = 0$ .



- a) During which displacement interval was the object's acceleration uniform?
- b) What acceleration did the object experience when  $x = 10$  meters?
- c) How much work was done on the object during the first 20 meters?
- d) How much kinetic energy did the object gain during the first 20 meters?
- e) What was the object's instantaneous velocity at  $x = 20$  meters?
- f) How much time was required to move it through the first 20 meters?
- g) How much did the object's momentum change in the first 20 meters?
- h) What was the object's instantaneous acceleration at  $x = 22$  meters?
- i) Why can't the kinematics equations for uniformly accelerated motion be used to calculate the object's instantaneous velocity at  $x = 30$  meters? What method should be used?
- j) How much work was done to move the object from 20 meters to 30 meters?
- k) What was the object's instantaneous speed at  $x = 30$  meters?
- l) What was the total impulse delivered to the object from  $x = 0$  to  $x = 30$  meters?
- m) What percent of the impulse was delivered in the last 10 meters?



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# Part V

## Rotatory Motion



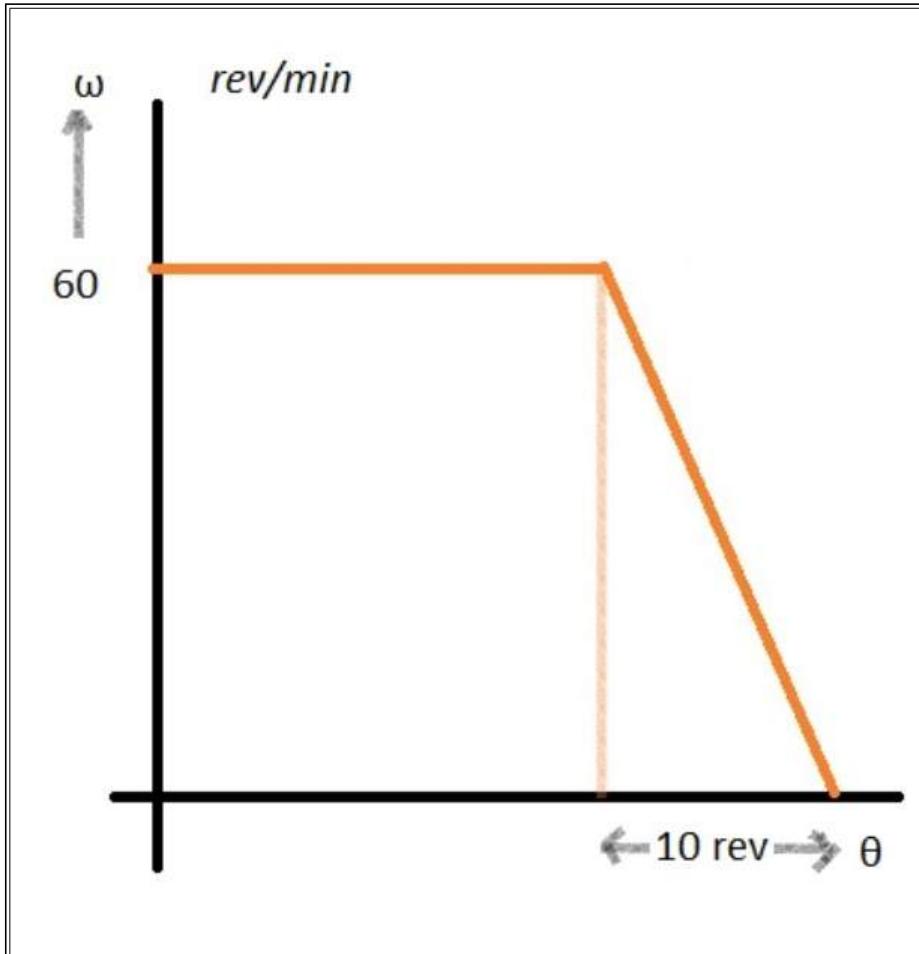
# Chapter 15

## Problems for Practice

### 15.1 General Problem Set

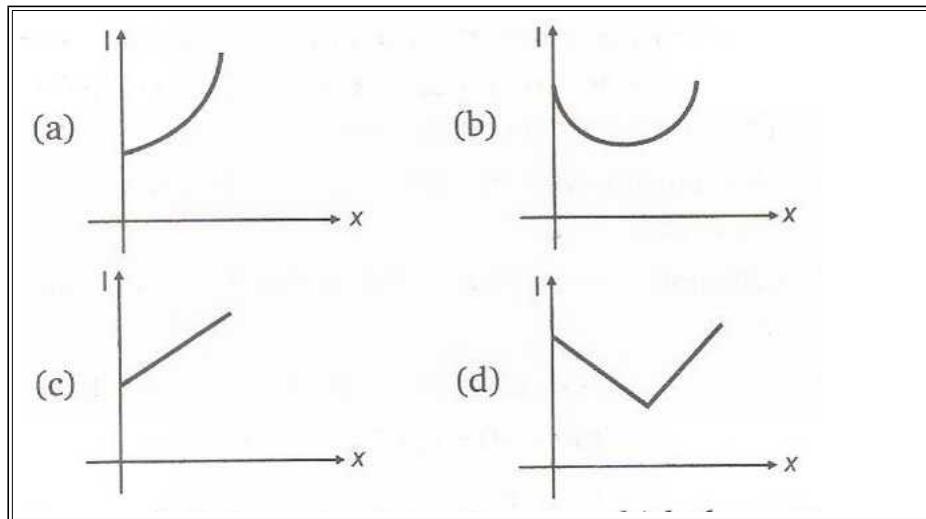
#### 15.1.1 Single Answer Type

**Example :** The angular velocity of a rotating disc decreases linearly with angular displacement from 60 rev/min. to zero during 10 rev as shown. Determine the angular velocity of the disc 3 sec after it begins to slow down

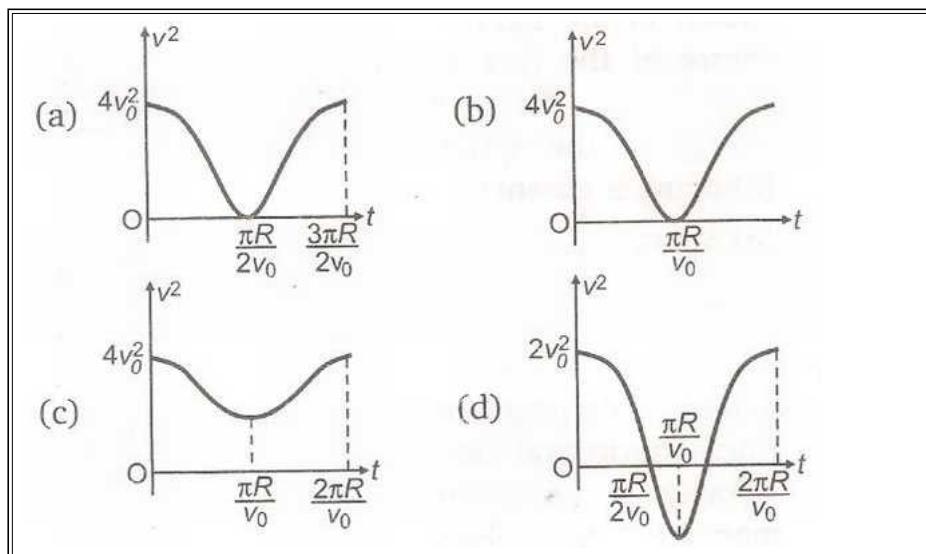


- (a)  $\frac{20\pi}{10}$
  - (b)  $\frac{17\pi}{10}$
  - (c)  $\frac{7\pi}{3}$
  - (d)  $\frac{10\pi}{3}$
- { Hint: Answer C }

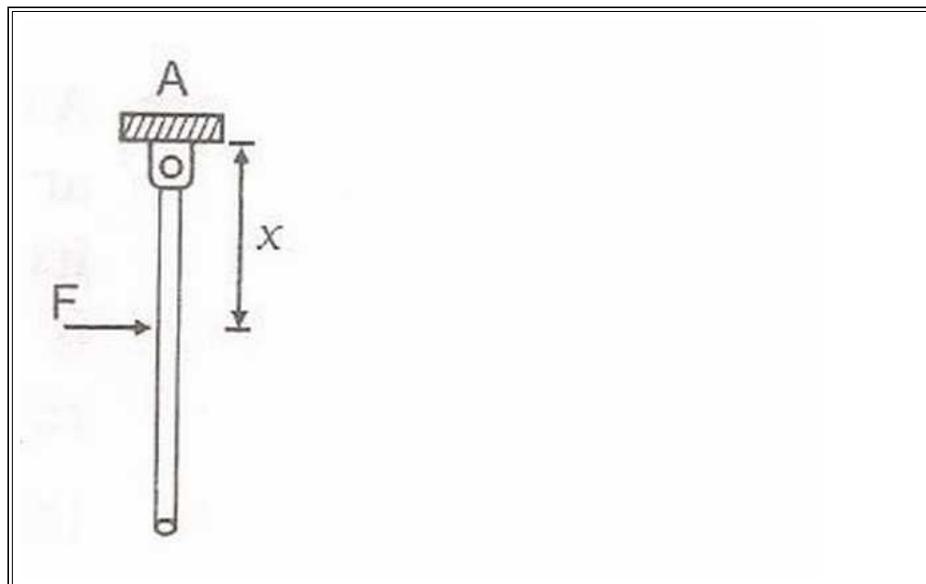
**Example:** Moment of Inertia  $I$  of a solid sphere about an axis parallel to a diameter and at a distance  $x$  from its centre of mass varies as



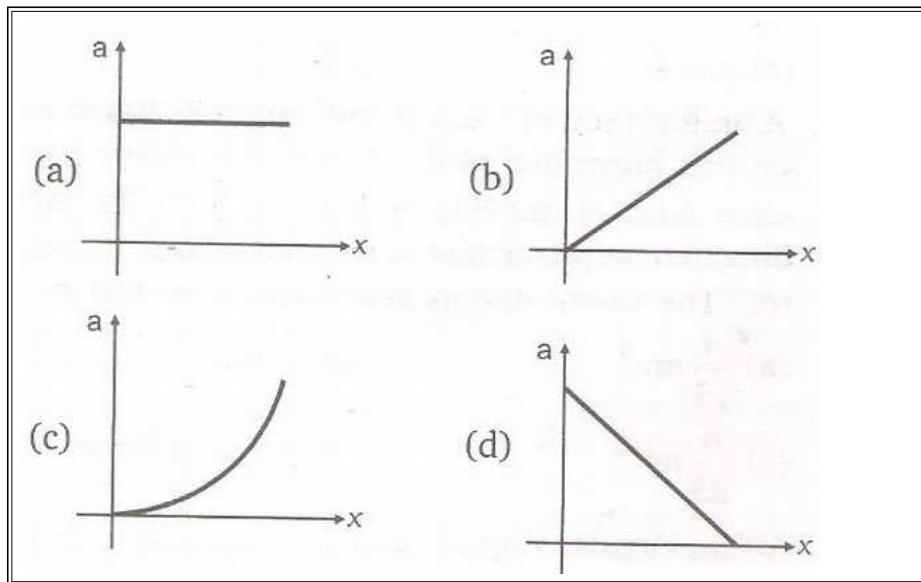
**Example:** A wheel is rolling without sliding on a horizontal surface. The centre of the wheel moves with a constant speed  $v_0$ . Consider a point P on the rim which is at the top at time  $t=0$ . The square of speed of point P is plotted against time  $t$ . The correct plot is (  $R$  is radius of the wheel )



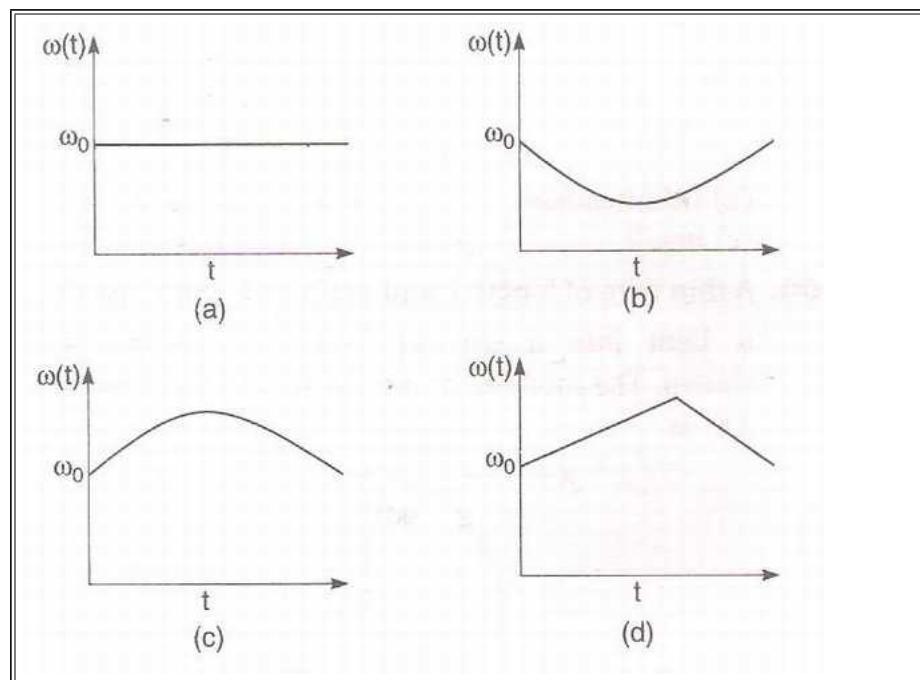
**Example:** A rod of mass  $m$  and length  $l$  is hinged at one of its end A as shown in figure.



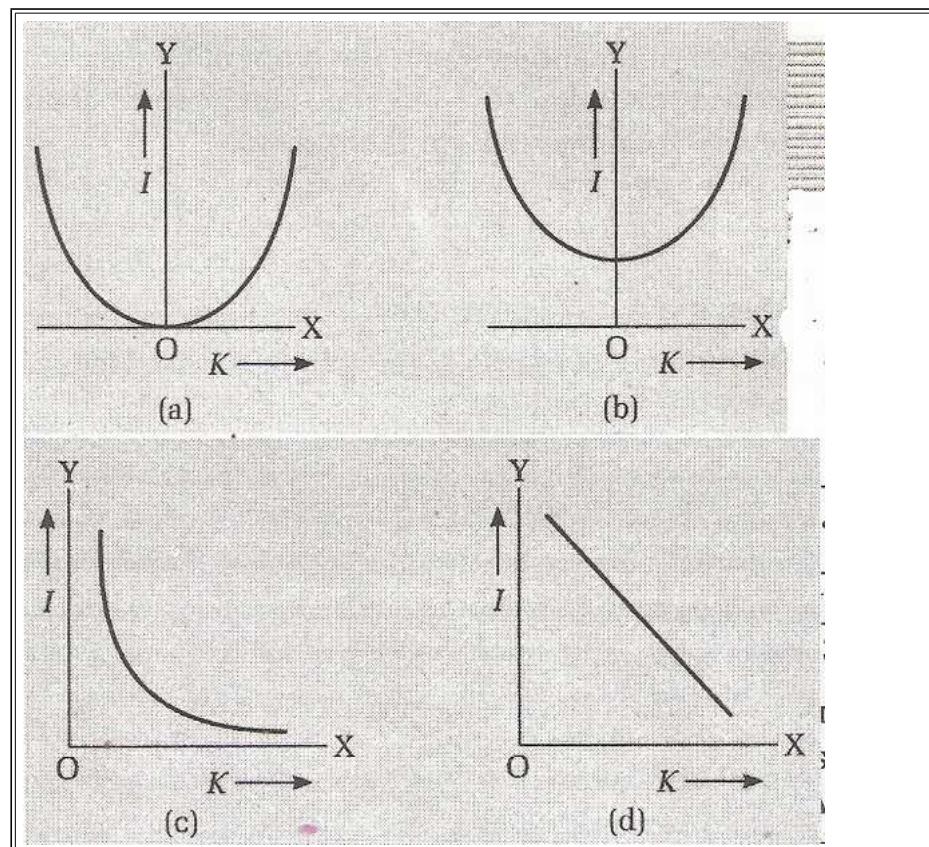
A force  $F$  is applied at a distance  $x$  from A. The acceleration of centre of mass (a) varies with  $x$  as



**Example:** A circular platform is free to rotate in a horizontal plane about a vertical axis passing through its centre. A tortoise is sitting at the edge of the platform. Now the platform is given an angular velocity  $\omega_0$ . When the tortoise moves along a chord of the platform with a constant velocity (with respect to the platform). The angular velocity of the platform  $\omega(t)$  will vary with time  $t$  as

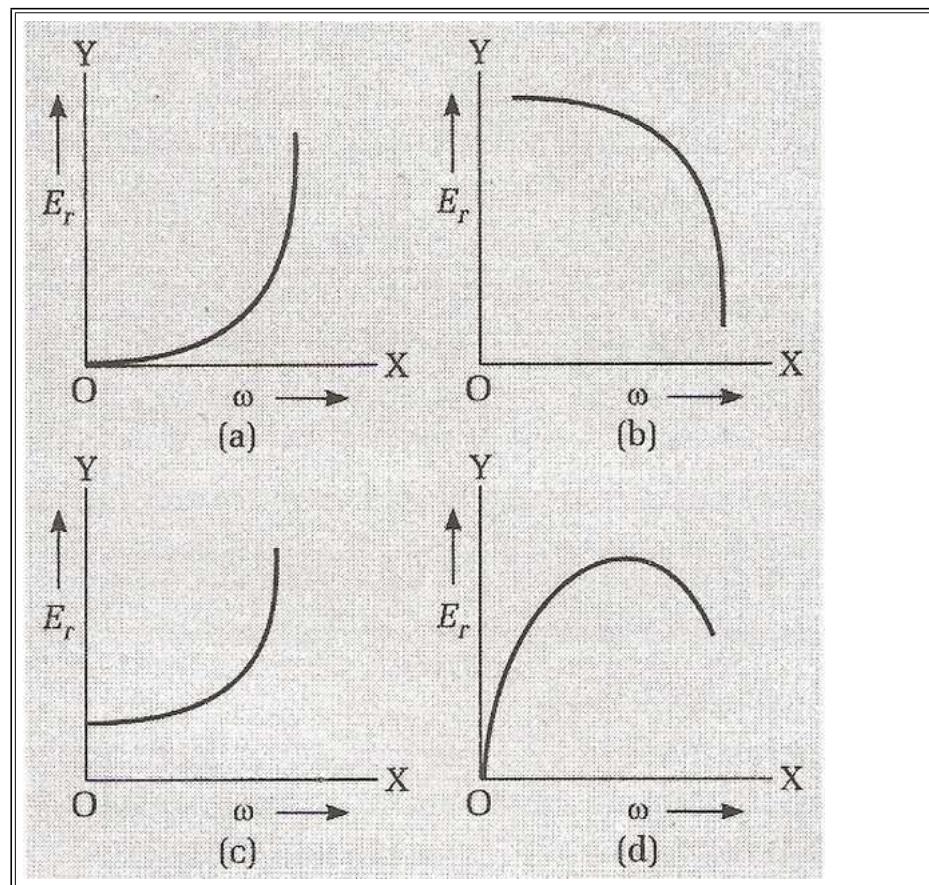


**Example:** The curve for the moment of inertia of a sphere of constant mass  $M$  versus its radius of gyration  $K$  will be



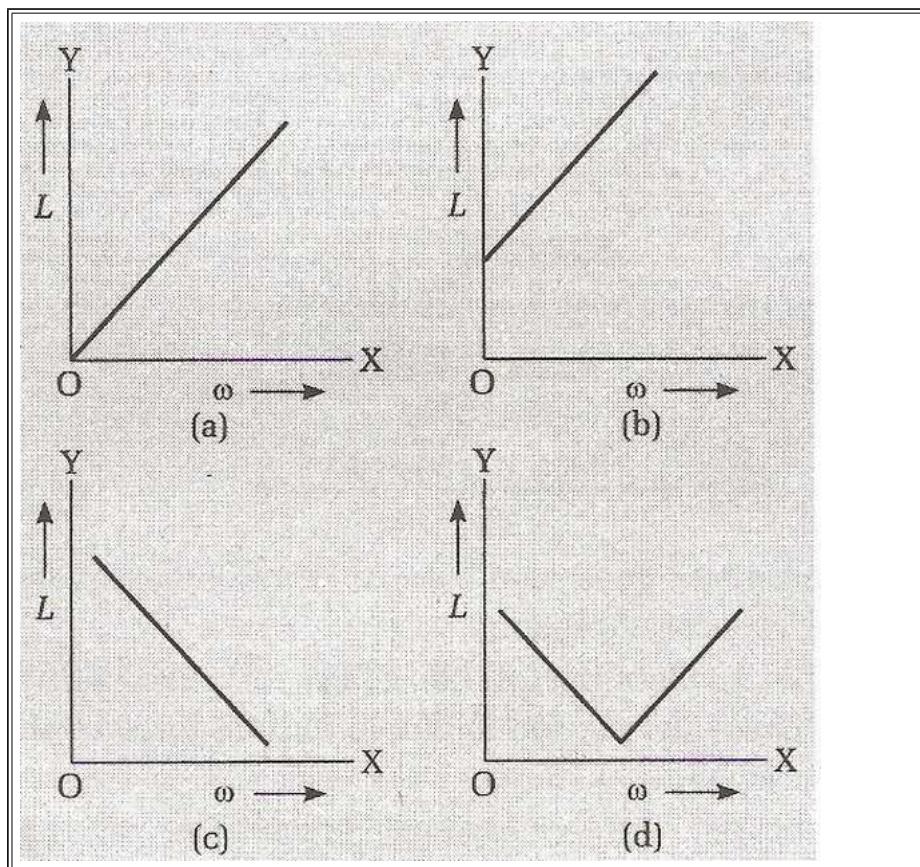
{ Hint : a ) }

**Example :** The graph between rotational energy  $E_r$  and angular velocity  $\omega$  is represented by which curve



{ Hint : a ) }

**Example :** The curve between angular momentum  $L$  and angular velocity  $\omega$  will be



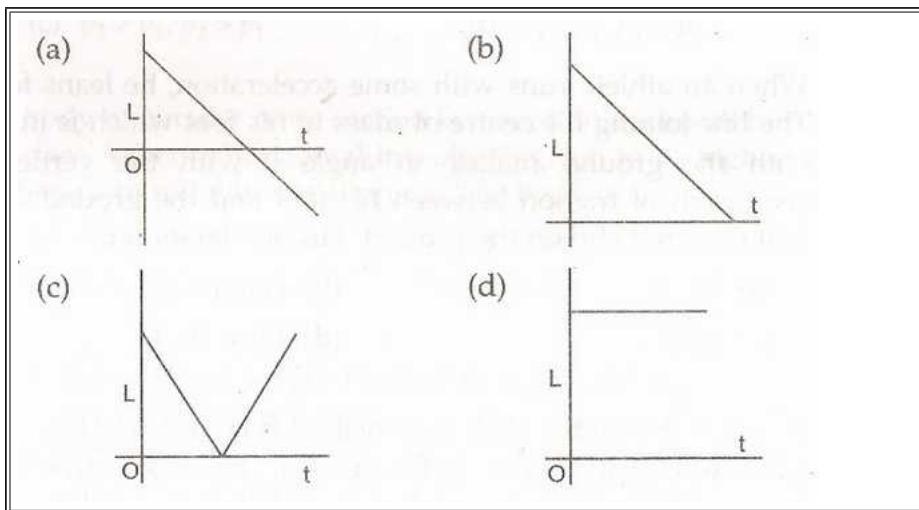
{ Hint : a) }



## Chapter 16

# Angular Momentum Conservation

**Example :** A block slides on a rough horizontal ground from point A to point B. Point C is midway between A and B. The coefficient of friction between the block and the ground is constant. Its angular momentum L about C is plotted against time t. Which of the following curves is correct?





# **Part VI**

# **Gravitation**



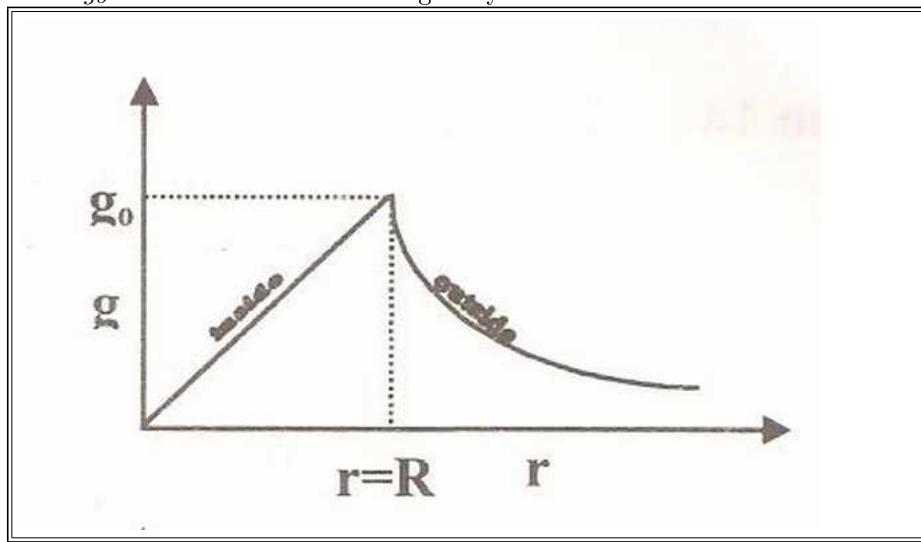
# Chapter 17

## Basics

### 17.1 Variation of “g”

$$\text{Outside the earth } g = g_o \left( \frac{R}{r} \right)^2$$

where  $g_o$  is the acceleration due to gravity at the surface of earth.



$$g_o = \frac{GM}{R^2}, R = \text{radius of earth}$$



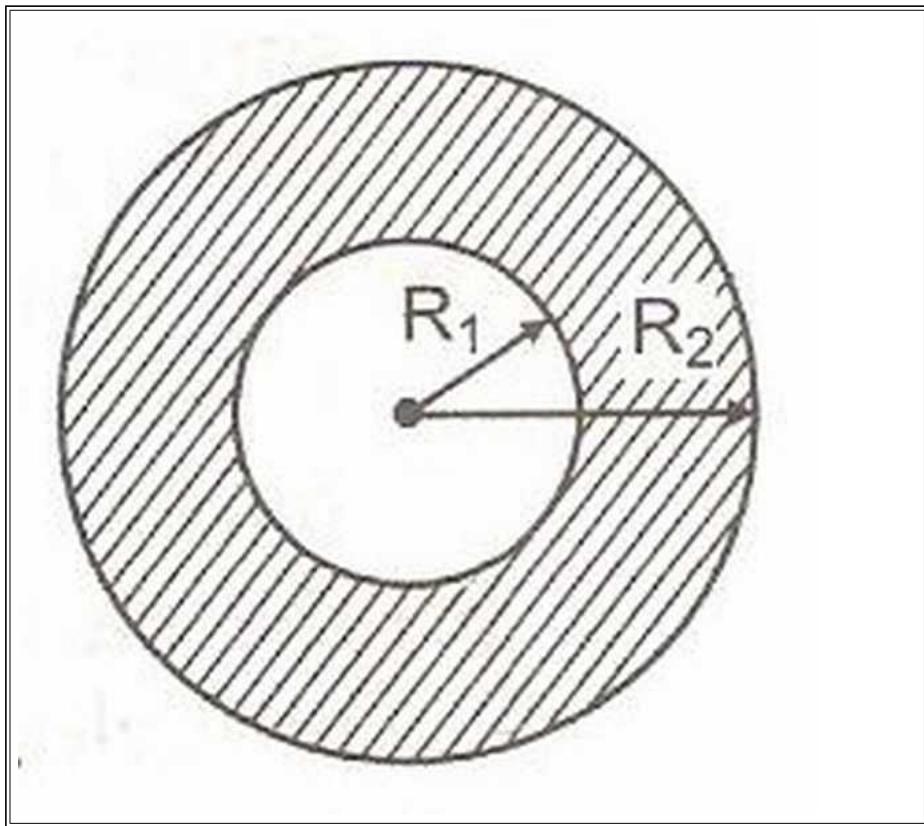
# Chapter 18

## Problems for Practice

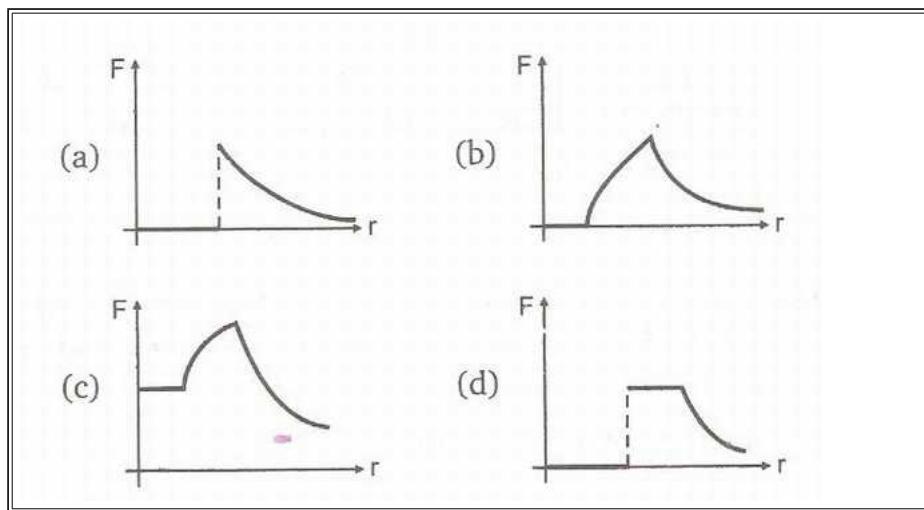
### 18.1 General Problem Set

#### 18.1.1 Single Answer

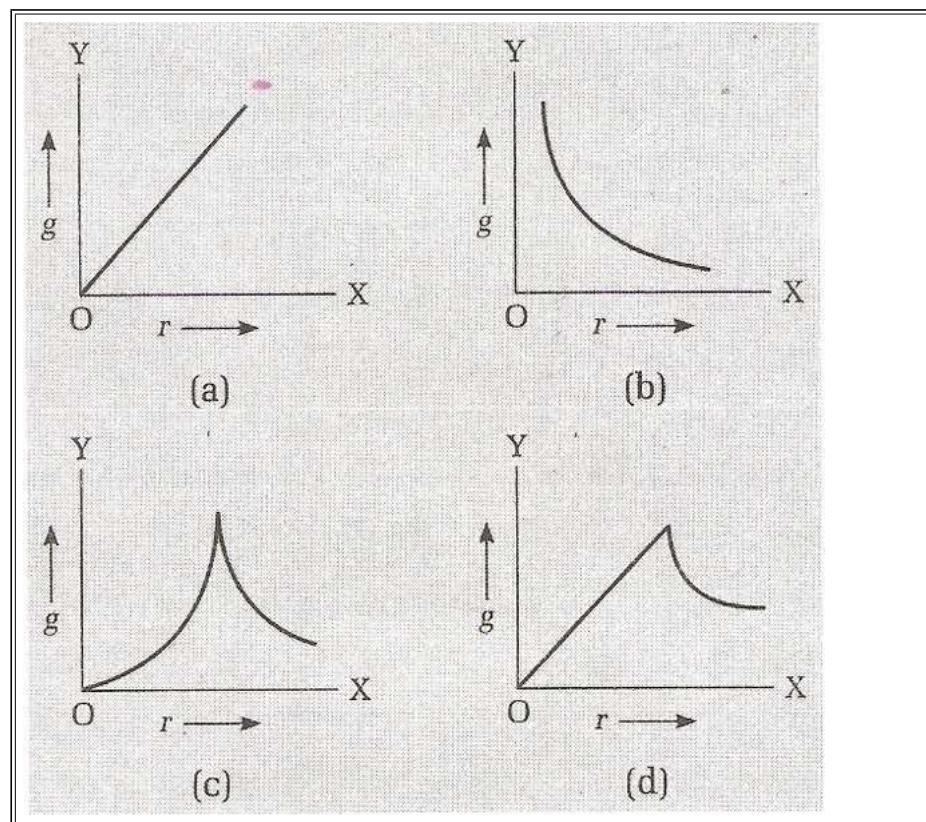
**Example:** A sphere of mass  $M$  and radius  $R_2$  has a concentric cavity of radius  $R_1$  as shown in figure.



The force  $F$  exerted by the sphere on a particle of mass  $m$  located at a distance  $r$  from the centre of sphere varies as ( $0 \leq r \leq \infty$ )

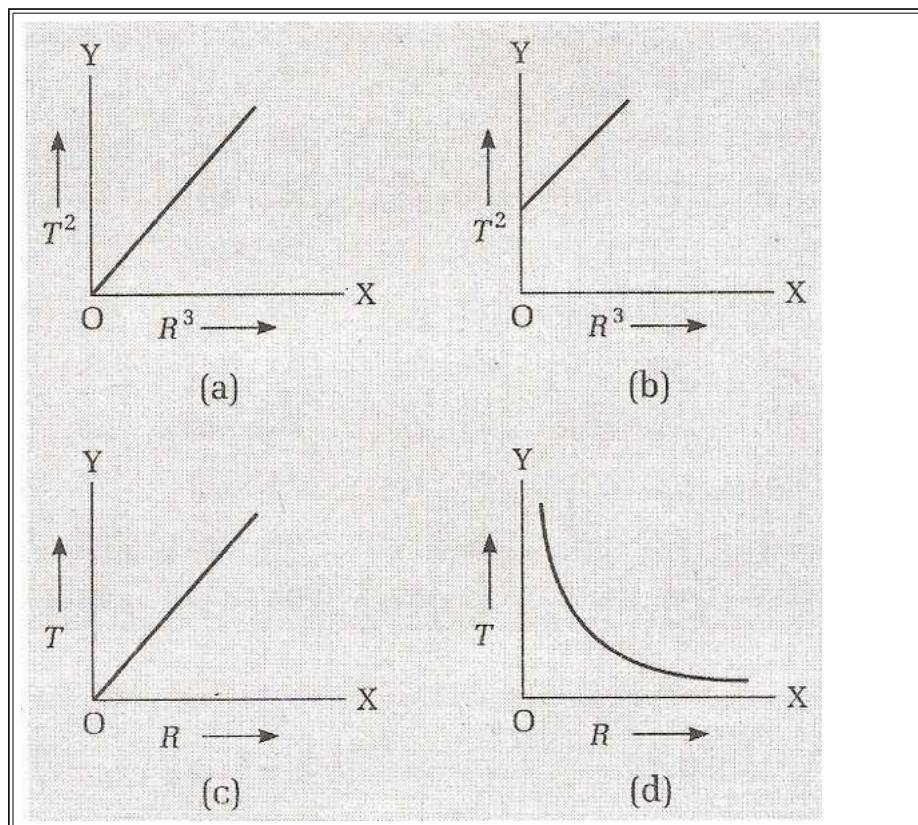


**Example :** The variation of acceleration due to gravity as one moves away from earth's centre is given by the graph



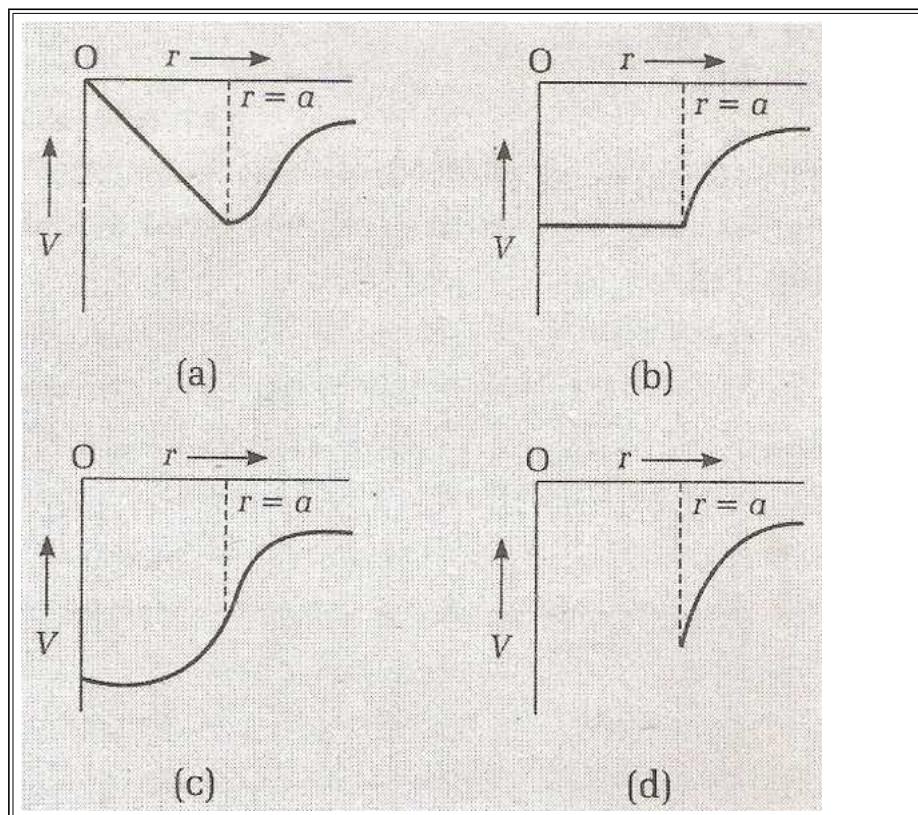
{ Hint: c) }

**Example :** Which of the following graphs represents the motion of a planet moving about the sun?



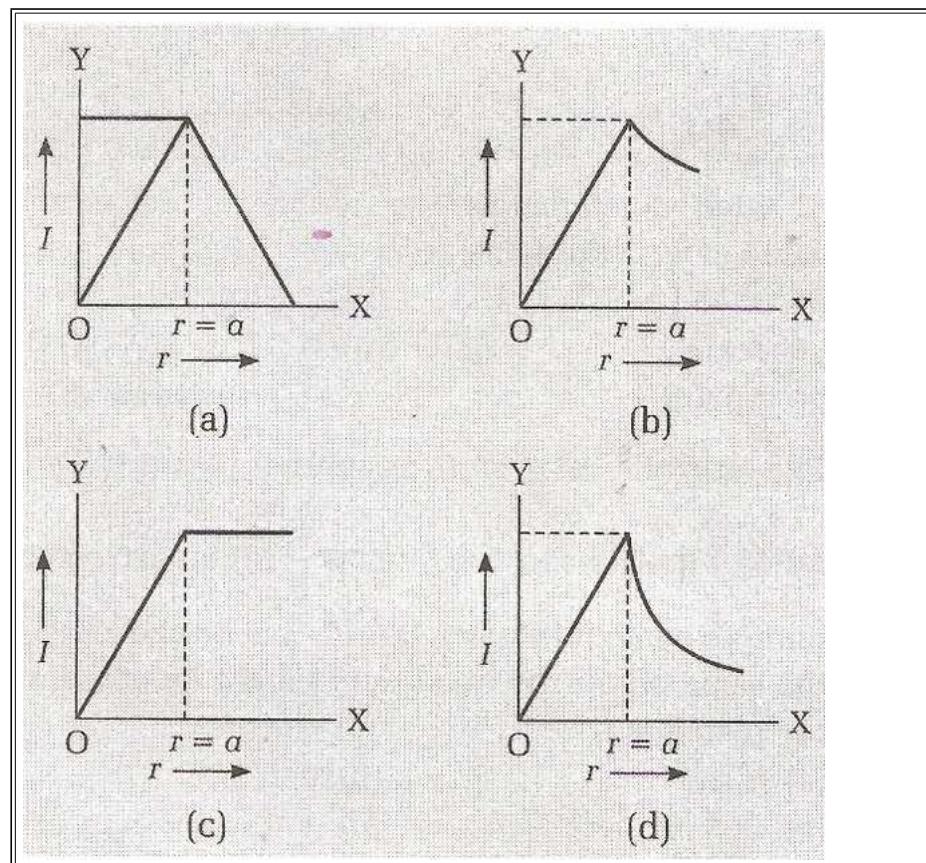
{ Hint : a ) }

**Example :** P is a point at a distance  $r$  from the centre of a solid sphere of radius  $a$ . The gravitational potential at P is  $V$ . If  $V$  is plotted as a function of  $r$ , which is the correct curve?



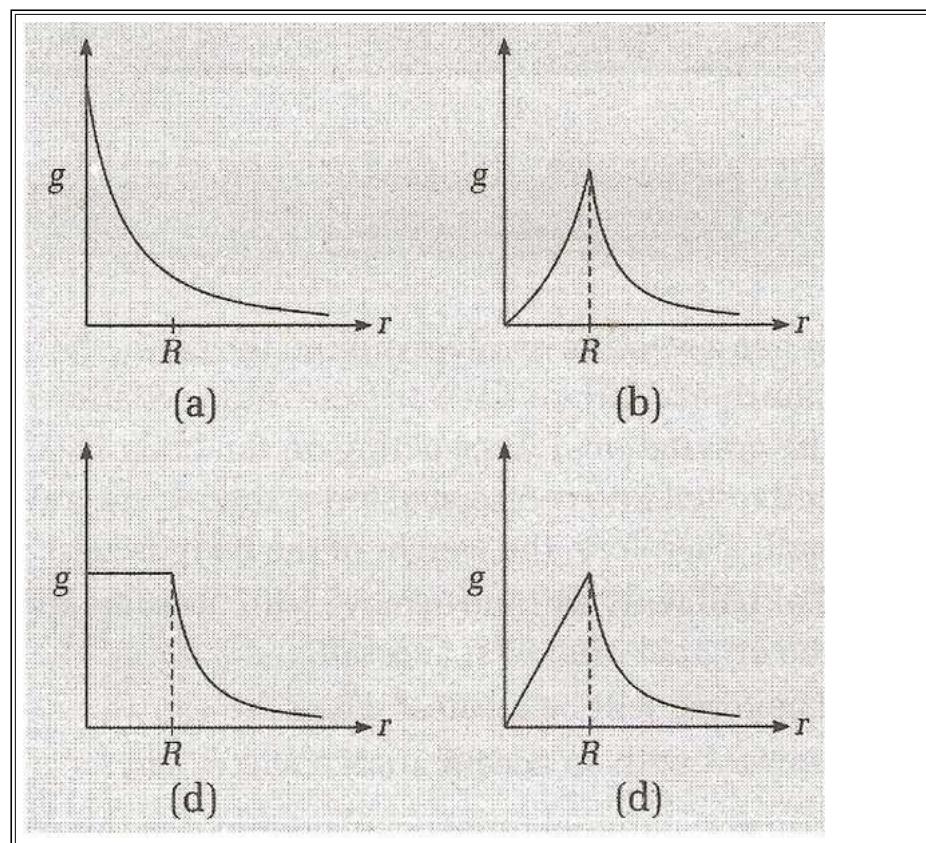
{ Hint : c ) }

**Example :** Which of the graphs represents correctly the variation of intensity of gravitational field  $I$  with the distance  $r$  from the centre of a spherical shell of mass  $M$  and radius  $a$ ?



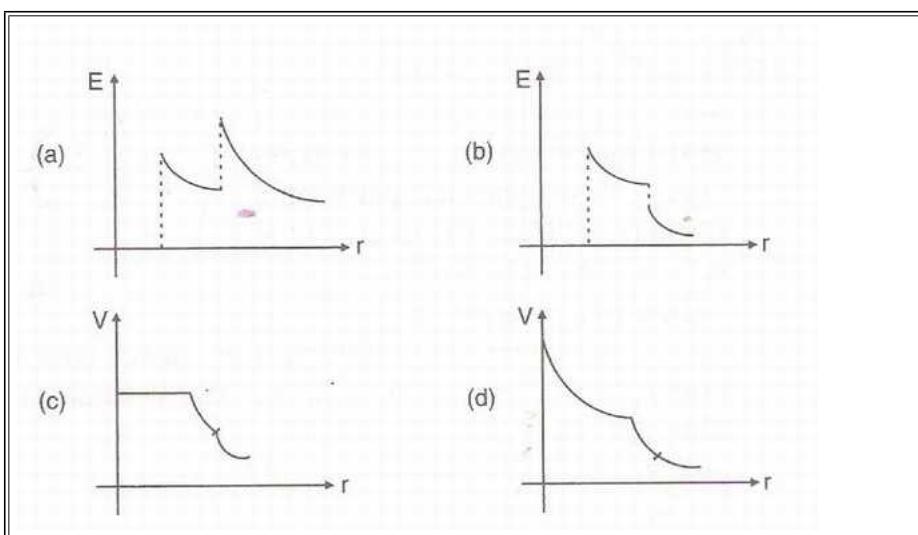
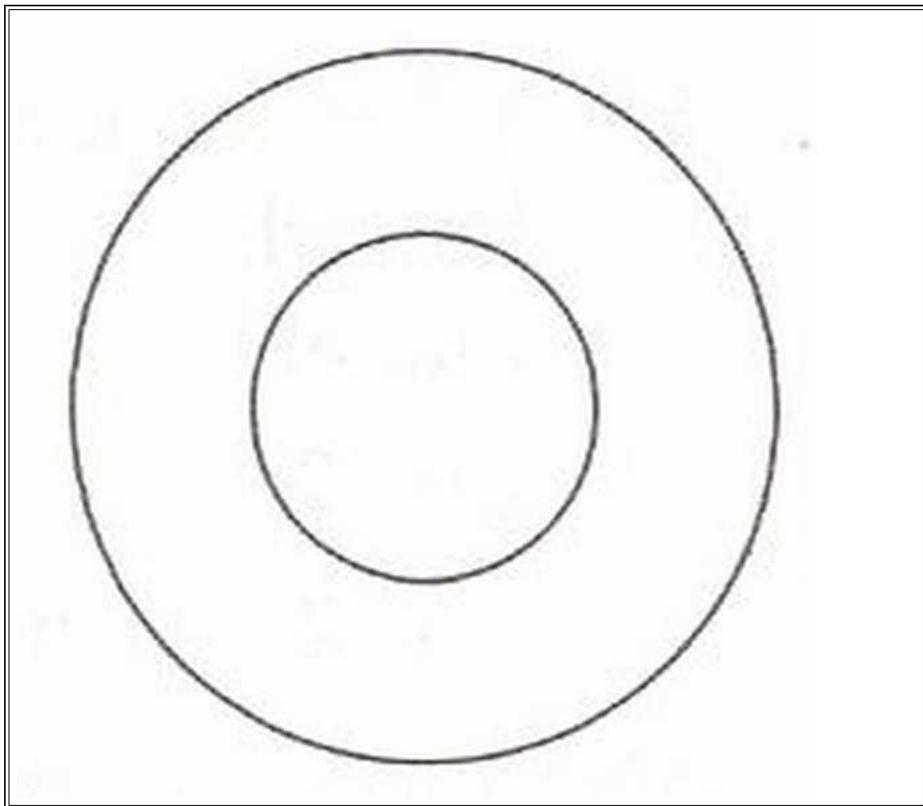
{ Hint : d) }

**Example :** The dependence of acceleration due to gravity  $g$  on the distance  $r$  from the center of the earth, assumed to be a sphere of radius  $R$  of uniform density is as shown in figure below



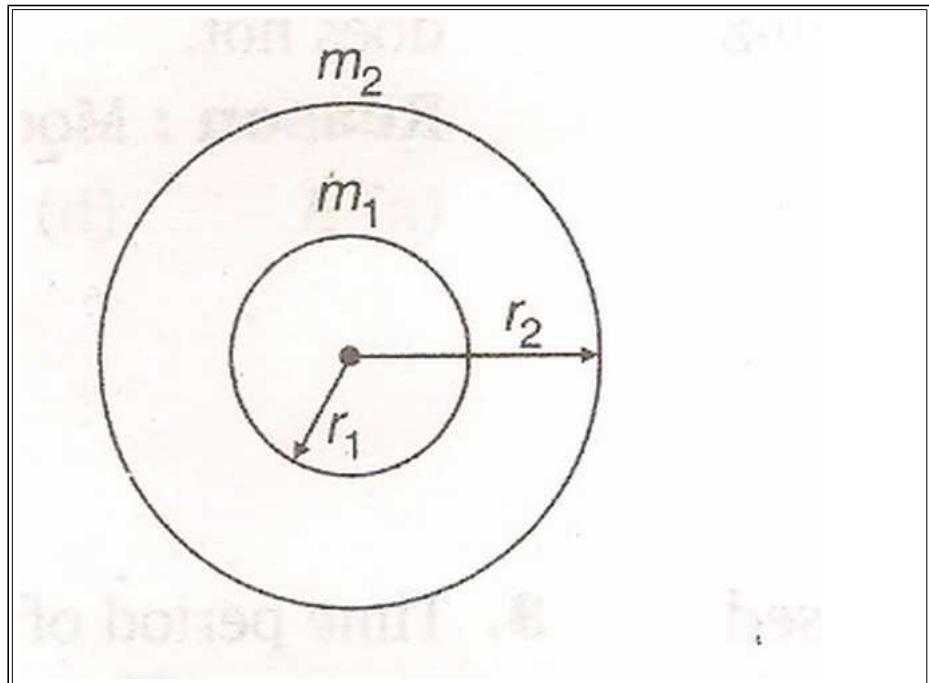
**18.1.2 Multiple Answer**

**Example:** Two concentric spherical shells are as shown in figure. The magnitude of gravitational potential ( $V$ ) and field strength ( $E$ ) vary with distance ( $r$ ) from centre as

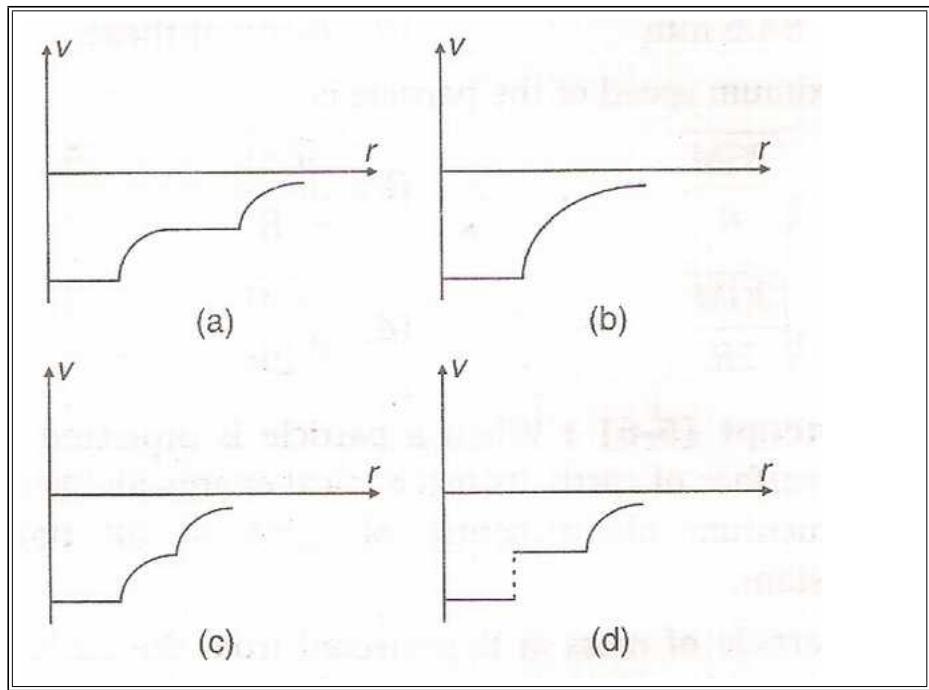


### 18.1.3 Comprehension Type

- 18.1.3.1 Concept 1 Gravitational potential inside a spherical shell is constant and outside the shell it varies as  $V \propto \frac{1}{r}$  (with negative sign). Here  $r$  is the distance from centre.



**Example1:** Two concentric spherical shells are as shown in figure. The V-r graph will be as



Statement : 1: Gravitational Field at distance  $x$  from the centre on the axis of a ring is given as

$$E = \frac{Gmx}{(R^2 + x^2)^{3/2}}$$

Here  $m$  is the mass of ring and  $R$  its radius.

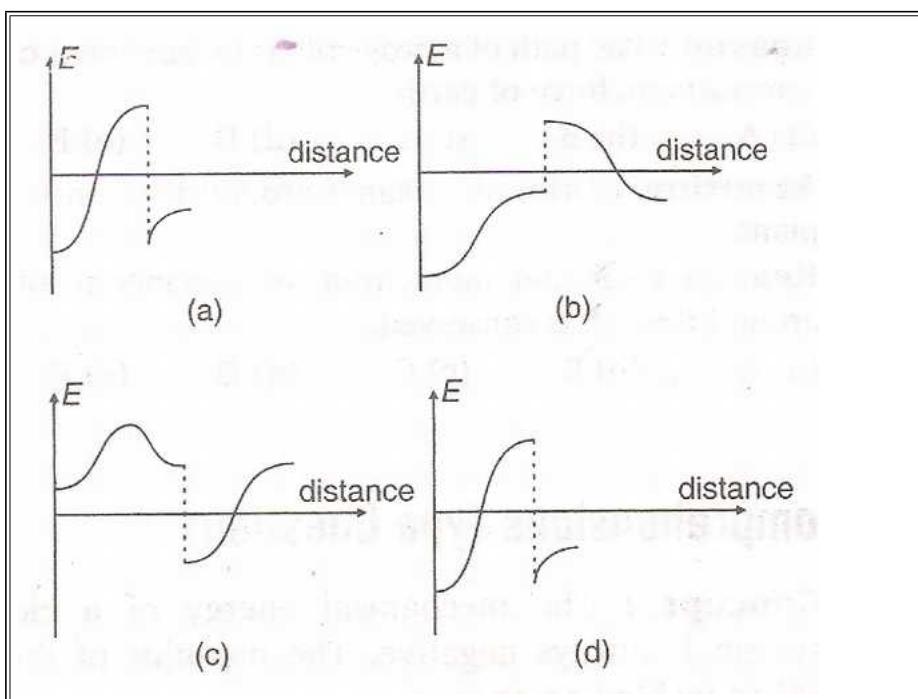
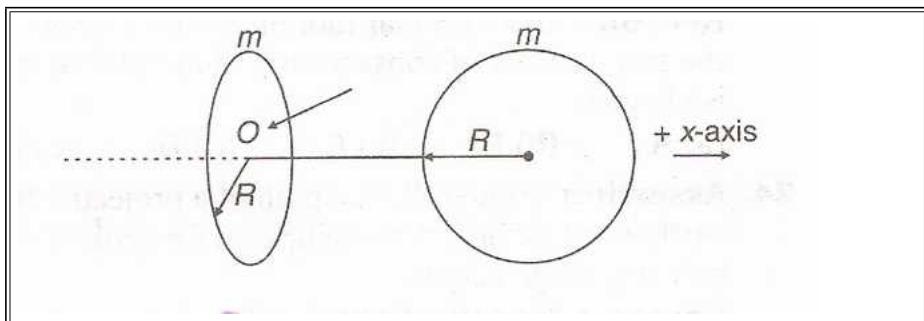
2: Gravitational field at distance  $x (\geq R)$  from centre of a solid sphere is given as,

$$E = \frac{Gm}{x^2}$$

Here  $m$  is the mass of solid sphere.

**Example2:** One ring of radius  $R$  and mass  $m$  and one solid sphere of same mass  $m$  and same radius  $R$  are placed with their centres on positive x-axis. We are moving from some finite distance on negative x-axis

towards positive x-axis. Plane of the ring is perpendicular to x-axis. How will the net gravitational field vary with distance moved on x-axis. We move only up to surface of solid sphere. O is the origin,



**Statement:** Change in potential energy when a mass  $m$  is taken to a height  $h$  from the surface of earth is given by

$$\Delta U = \frac{mgh}{1 + h/R}$$

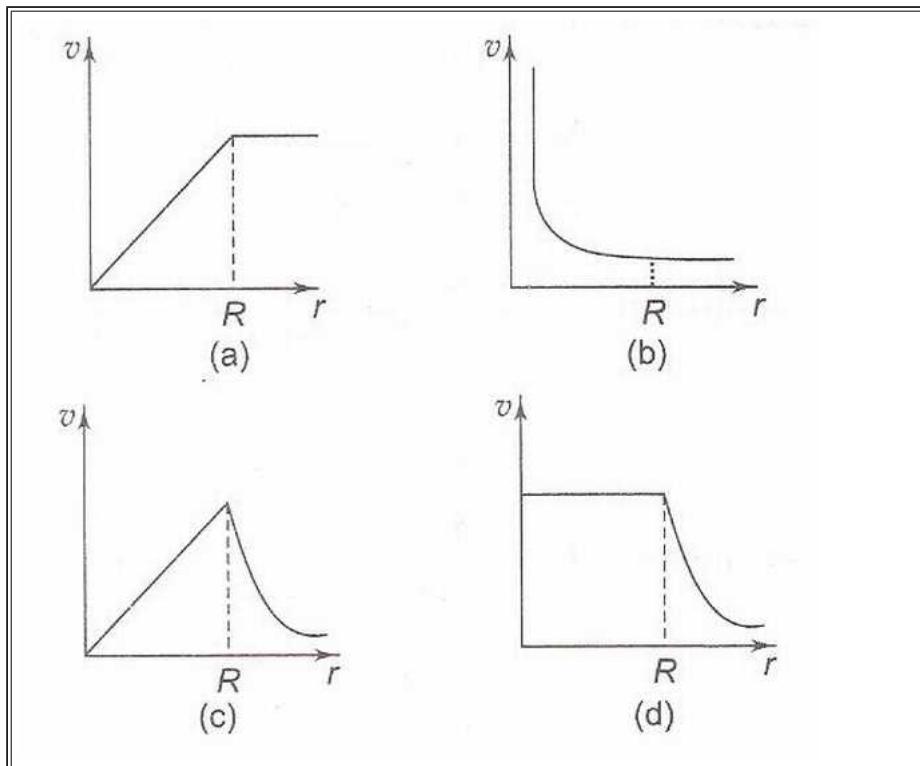
## 18.2 Previous Years IIT Problems

### 18.2.1 Single Answer

A spherically symmetric gravitational system of particles has a mass density

$$\rho = \begin{cases} \rho_o & \text{for } r \leq R \\ 0 & \text{for } r > R \end{cases}$$

where  $\rho_o$  is a constant. A test mass can undergo circular motion under the influence of the gravitational field of particles. Its speed  $v$  as a function of distance  $r$  ( $0 < r < \infty$ ) from the centre of the system is represented by



{Solution: If  $M$  is the total mass of the system of particles, the orbital speed of the test mass is

$$v = \sqrt{\frac{GM}{r}}$$

$$\text{For } r \leq R, v = \sqrt{\frac{G \times \frac{4\pi}{3} r^3 \rho_o}{r}}$$

which gives  $v \propto r$

i.e.  $v$  increases linearly with  $r$  up to  $r=R$ . Hence choices b) and d) are wrong.

For  $r > R$ , the whole mass of the system is  $M = \frac{4\pi}{3} R^3 \rho_o$ , which is constant. Hence for  $r > R$ ,

$$v = \sqrt{\frac{GM}{r}}$$

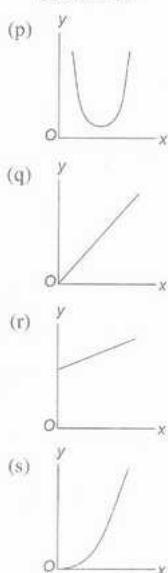
i.e.,  $v \propto \frac{1}{\sqrt{r}}$ . Hence, the correct choice is c). }

### 18.2.2 Matching

*Column I*

- (a) Potential energy of a simple pendulum (y axis) as a function of displacement (x axis)
- (b) Displacement (y axis) as a function of time (x axis) for a one dimensional motion at zero or constant acceleration when the body is moving along the positive x-direction
- (c) Range of a projectile (y axis) as a function of its velocity (x axis) when projected at a fixed angle
- (d) The square of the time period (y-axis) of a simple pendulum as a function of its length (x axis).

*Column II*



# **Part VII**

## **Periodic Motion**

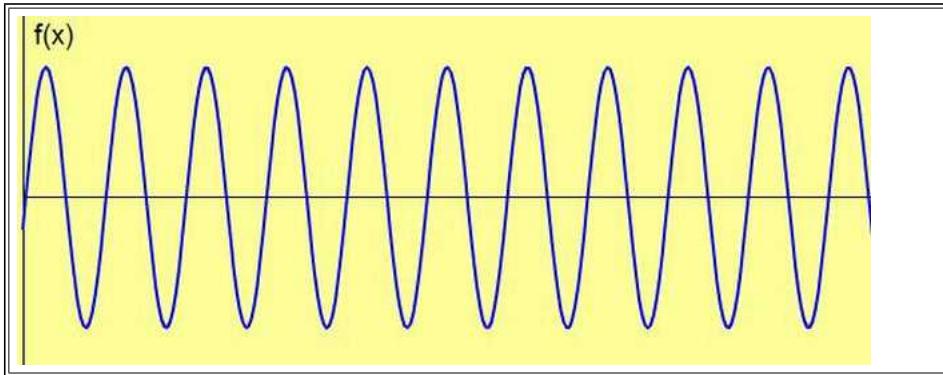


# Chapter 19

## Abstract Introduction (SHM)

### 19.1 Position vs time

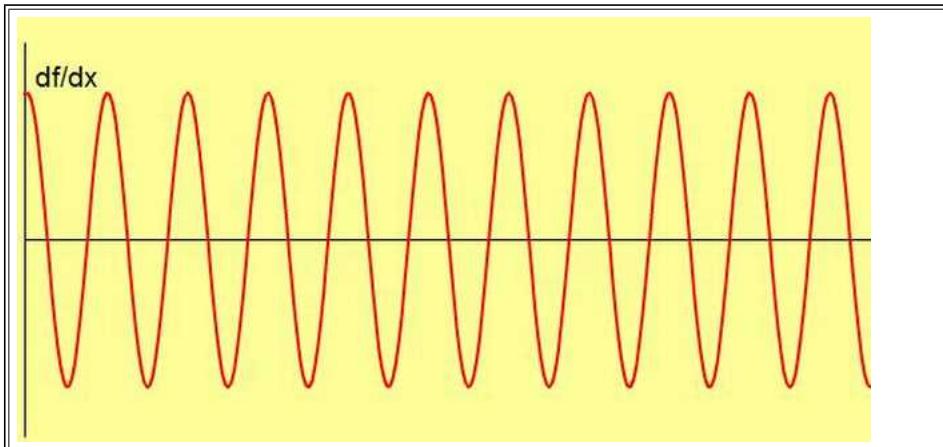
The graph of position verse time is a sine wave with a possible phase shift. The phase shift is how much the ahead or behind the position is on the sine wave. n.d.



Consider this graph, if the "clock" is started at 0.05 (where the mass is at it's maximum stretch) seconds then there would be a phase shift of 90 degrees (or we could replace the sine function for a cosine). If the "clock" is started at 0.1 seconds (where mass moves down instead of up; left instead of right) then the phase shift would be 180 degrees (a negative sine function).

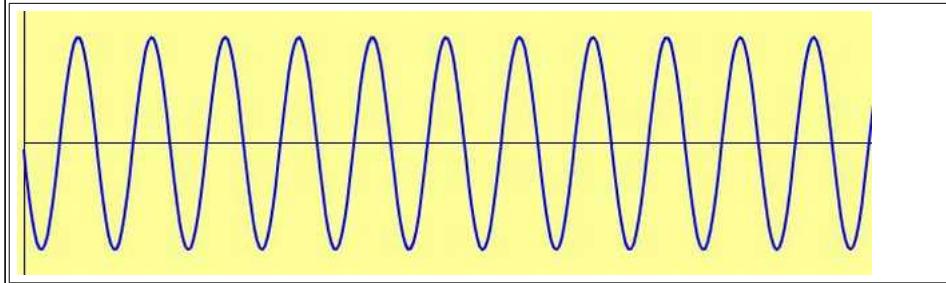
### 19.2 Velocity vs time

Consider the position verses time graph, at any point were the mass has reached the amplitude (maximum distance from from the equilibrium point) the speed of the mass at these point is zero. When the position is at zero then the speed is at a maximum (if you don't believe it, consider conservation of energy). This "shifts" the position graph by 90 degrees "creating" a cosine graph for velocity. The other way of thinking about is velocity is the change in position with respect to time, the change in a sine wave with respect to time is a cosine graph.



### 19.3 Acceleration vs time

The acceleration verse time graph is the easiest of the graphs to make. The simple harmonic motion is based on a relationship between position and acceleration;  $x = -Ka$ . So the graph of position and acceleration should look alike, except for the negative sign. In fact position and acceleration are the same shape just mirror copies of each other.

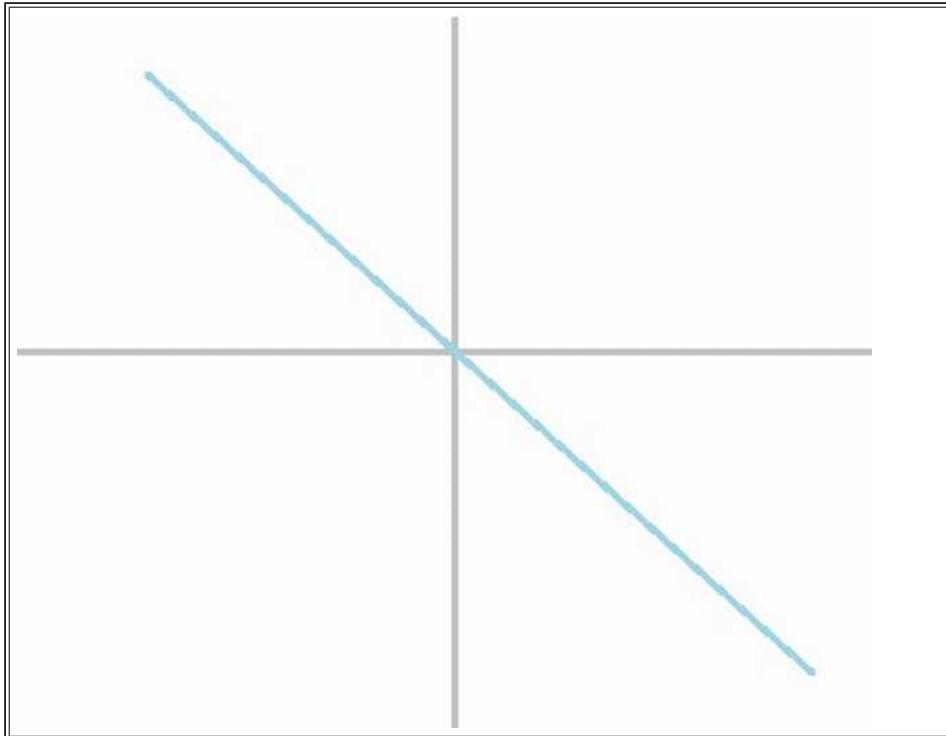


#### 19.3.1 Peak Height

It is important to note that the shapes of each graph is similar, that each graph has the same frequency, period and wavelength, but they don't have the same amplitude, for common simple harmonic motion, the height of the peak of the function (not to confused with the amplitude, amplitude refers to the height of the position graph alone, i'm talking about the height of the position, velocity and acceleration graphs) tend to get smaller and smaller starting with the position graph being the tallest and the acceleration being the shortest.

### 19.4 Graphing position, velocity, and acceleration with respect to each other

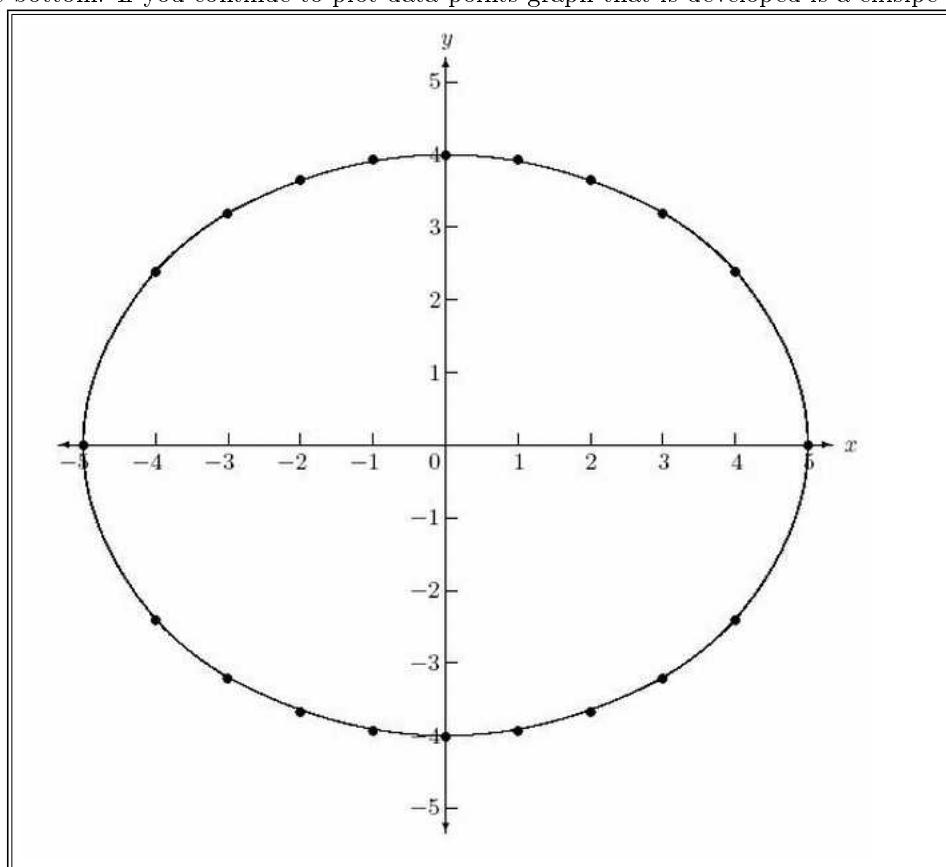
Graphing position to the other functions can be complicated and when tested on it, most student are unable to give the right answer. First consider this, for simple harmonic motion position and acceleration are proportional.  $x = -k a$  this is a linear relationship so the graph is a line, the slope is negative so the line is heading down.



### 19.5 Position and acceleration verses velocity

The position and acceleration verse velocity graph look entirely different. First off the straight line test fails when plotting position vs velocity or acceleration verse velocity. Take the point were  $x$  and  $a$  are zero, there are two possible answers for the point (the speed maybe at maximum) the object could be moving down or up at the point. That means the velocity can be a positive maximum or a negative maximum, two separate values.

Looking at the points where the velocity is equal to zero, there are two possible answers, either at the top or at the bottom. If you continue to plot data points graph that is developed is a ellipse.





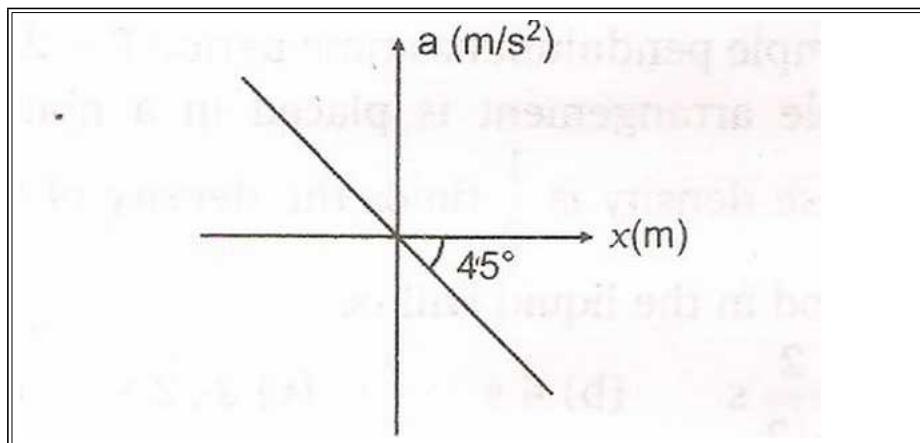
# Chapter 20

## Problems

### 20.1 General Problem Set

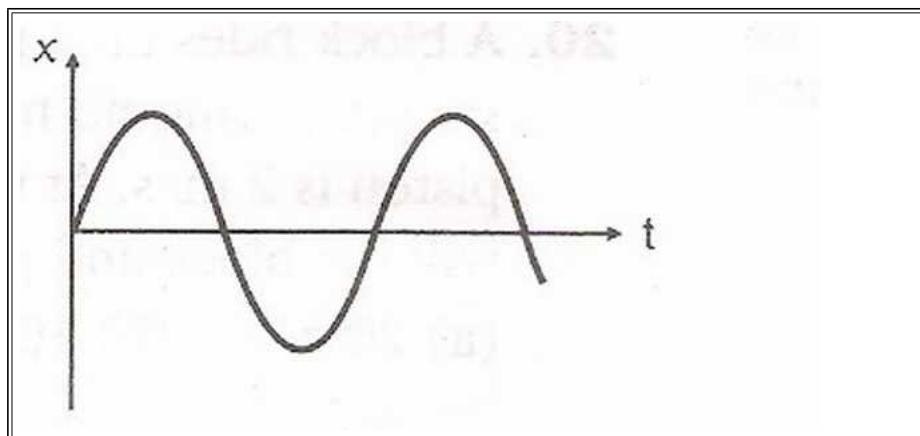
#### 20.1.1 Single Answer Type

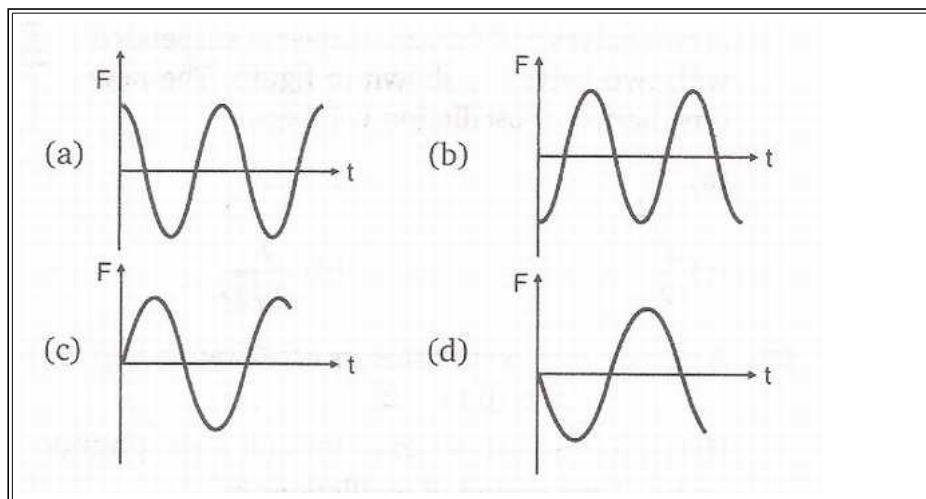
**Example 1:** Acceleration-displacement graph of a particle executing SHM is as shown in given figure. The time period of its oscillation is ( in sec )



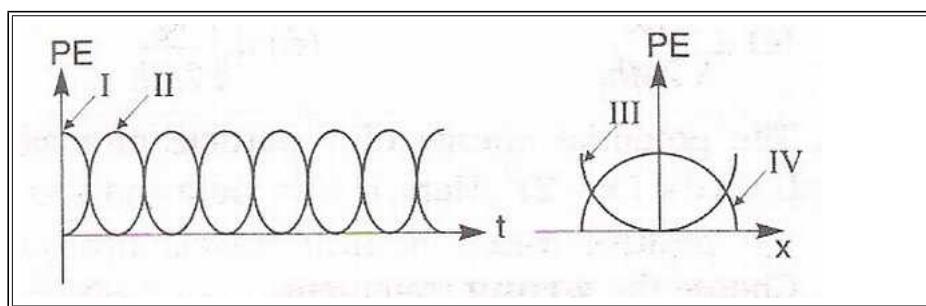
- a)  $\pi/2$
- b)  $2\pi$
- c)  $\pi$
- d)  $\pi/4$

**Example 2:** Displacement-time graph of a particle executing SHM is as shown.





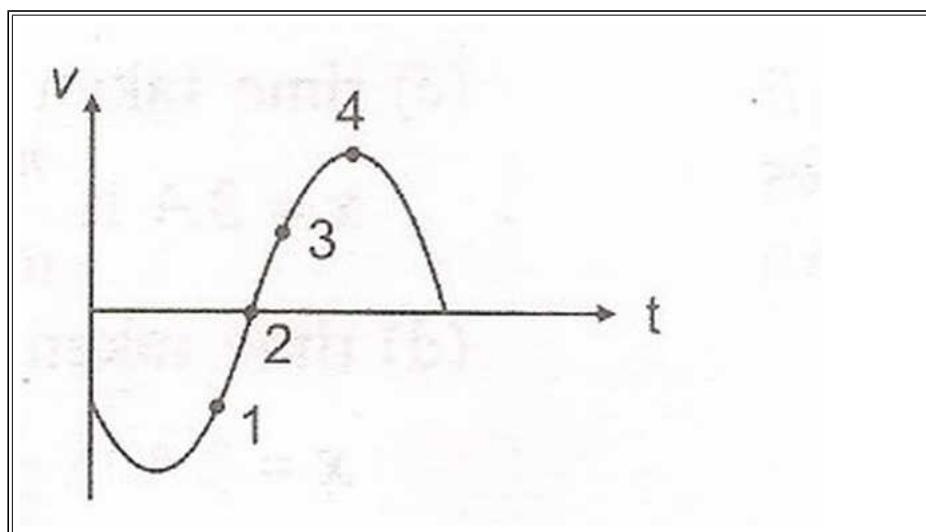
**Example 3:** For a particle executing SHM the displacement  $x$  is given by  $x = A \cos \omega t$ . Identify the graph which represents the variation of potential energy (PE) as a function of time  $t$  and displacement  $x$



- a) I, III
- b) II, IV
- c) II, III
- d) I, IV

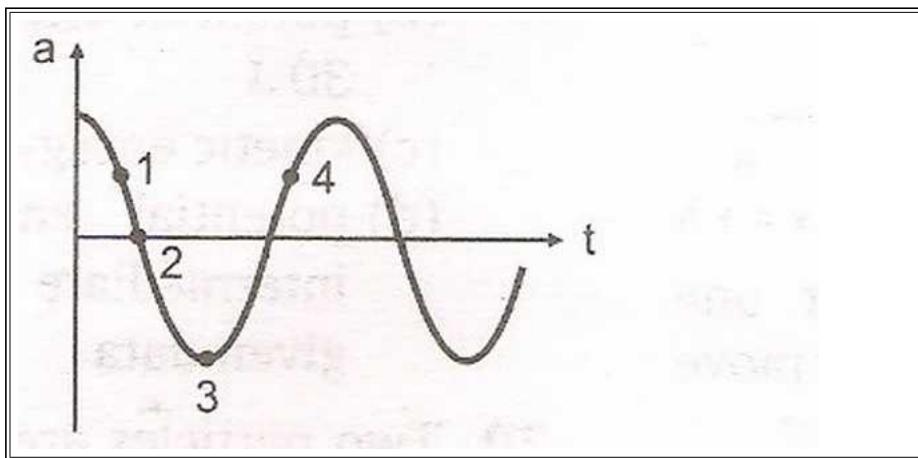
### 20.1.2 Multiple Answer Type

**Example 1:** Velocity-time graph of a particle executing SHM is shown in figure. Select the correct alternative(s).



- a) At position 1 displacement of particle may be positive or negative.
- b) At position 2 displacement of particle is negative.
- c) At position 3 acceleration of particle is positive.
- d) At position 4 acceleration of particle is positive.

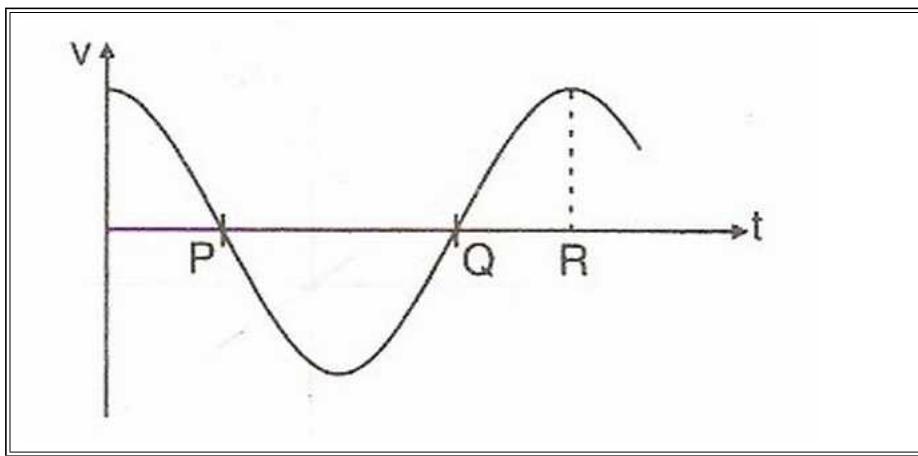
**Example 2:** Acceleration-time graph of a particle executing SHM is as shown in figure. Select the correct alternative(s).



- a) Displacement of particle at 1 is negative.
- b) Velocity of particle at 2 is positive.
- c) Potential energy of particle at 3 is maximum.
- d) Speed of particle at 3 is decreasing.

### 20.1.3 Matching Type Questions

**Example 1:** Velocity-time graph of a particle in SHM is as shown in figure. Match the following



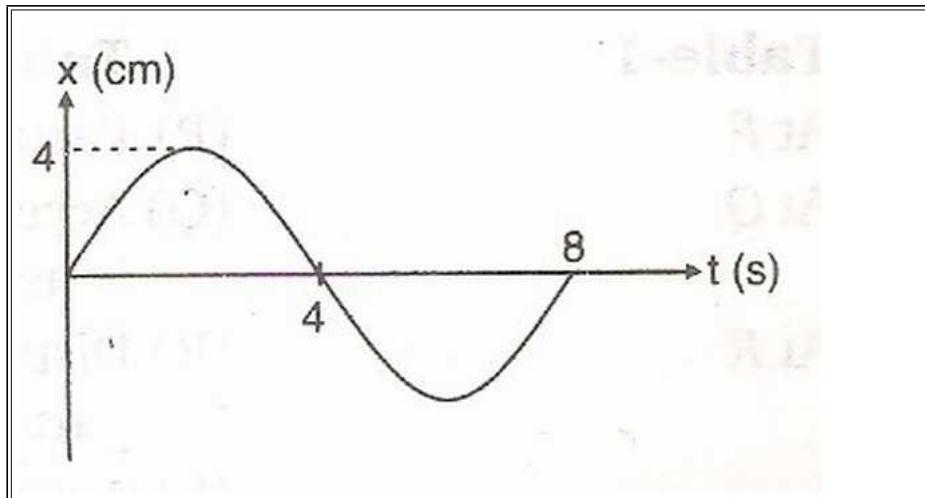
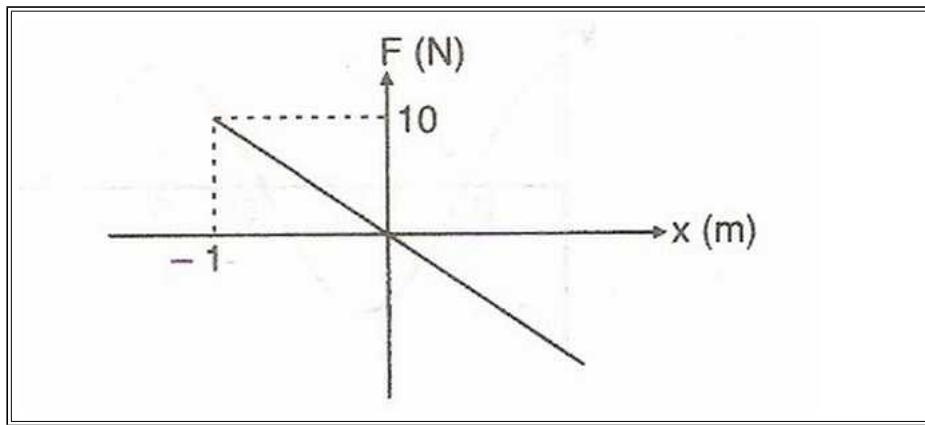
**Table-1**

- (A) At P
- (B) At Q
- (C) At R

**Table-2**

- (P) Particle is at  $x = -A$
- (Q) Acceleration of particle is maximum
- (R) Displacement of particle is zero
- (S) Acceleration of particle is zero
- (T) None

**Example 2:** F-x and x-t graph of a particle in SHM are as shown in figure. Match the following

**Table-1**

- (A) Mass of the particle (P)  $\pi/2$  SI unit
- (B) Maximum kinetic energy of particle (Q)  $(160/\pi^2)$  SI unit
- (C) Angular frequency of particle (R)  $(8.0 \times 10^{-3})$  SI unit

**Table-2**

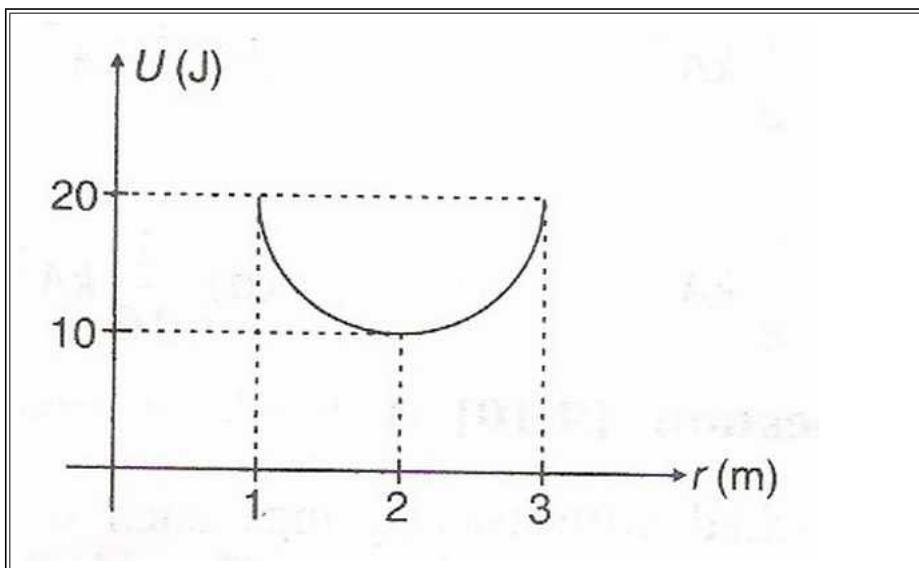
(T) None

#### 20.1.4 Comprehension Type Questions

##### 20.1.4.1 Comprehension 1

Concept : In SHM, force  $\left( F = -\frac{dU}{dr} \right)$  on the particle at mean position is zero. Potential energy at extreme position is maximum

Example: U-r graph of a particle which can be under SHM is as shown in figure. What conclusion cannot be drawn from the graph?

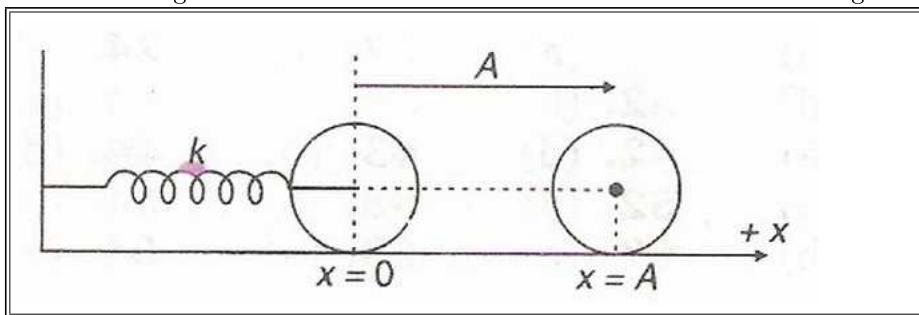


- a) Mean position of the particle is at  $r=2\text{ m}$ .  
 b) Potential energy of particle at mean position is  $10\text{ J}$ .  
 c) Amplitude of oscillation is  $1\text{ m}$ .  
 d) None of these.

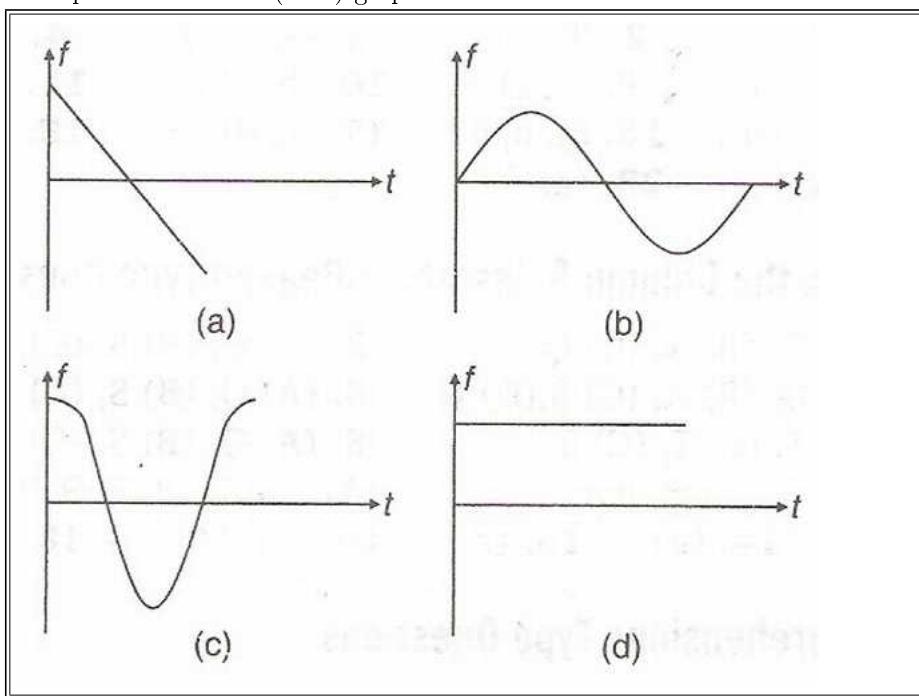
#### 20.1.4.2 Comprehension 2

Statement : In case of pure rolling  $a = R\alpha$ , where  $a$  is the linear acceleration and  $\alpha$  the angular acceleration.

Question : A disc of mass  $m$  and radius  $R$  is attached with a spring of force constant  $k$  at its centre as shown in figure. At  $x=0$ , spring is unstretched. The disc is moved to  $x=A$  and then released. There is no slipping between disc and ground. Let  $f$  be the force of friction on the disc from the ground.



Example 1 :  $f$  versus  $t$  (time) graph will be as



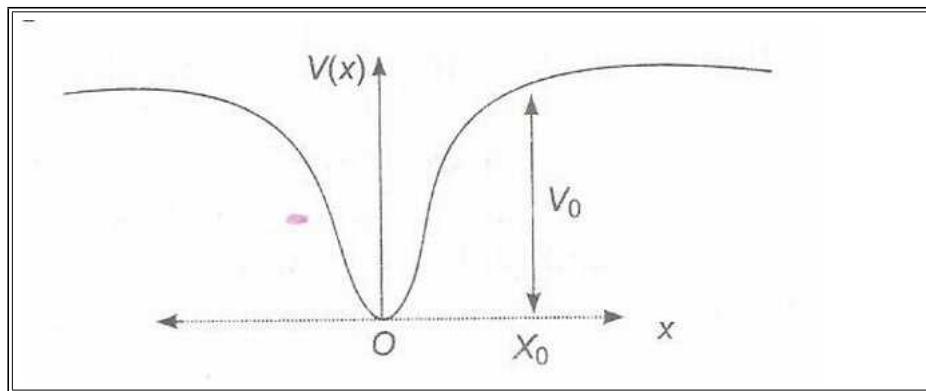
Example 2 : In the problem if  $k = 10 \text{ N/m}$ ,  $m = 2 \text{ kg}$ ,  $R = 1 \text{ m}$  and  $A = 2 \text{ m}$ . Find linear speed of the disc at mean position

- a)  $\sqrt{\frac{40}{3}} \text{ m/s}$
- b)  $\sqrt{20} \text{ m/s}$
- c)  $\sqrt{\frac{10}{3}} \text{ m/s}$
- d)  $\sqrt{\frac{50}{3}} \text{ m/s}$

## 20.2 Previous Years IIT Problems

### 20.2.1 Paragraph

**Paragraph 1:** When a particle of mass  $m$  moves on the  $x$ -axis in a potential of the form  $V(x) = kx^2$  it performs simple harmonic motion. The corresponding time period is proportional to  $\sqrt{\frac{m}{k}}$ , as can be seen easily using dimensional analysis. However, the motion of a particle can be periodic even when its potential energy increases on both sides of  $x=0$  in a way different from  $kx^2$  and its total energy is such that the particle does not escape to infinity. Consider a particle of mass  $m$  moving on the  $x$ -axis. Its potential energy is  $V(x) = \alpha x^4$  ( $\alpha > 0$ ) for  $|x|$  near the origin and becomes a constant equal to  $V_0$  for  $|x| \geq X_0$  (see figure)



1. If the total energy of the particle is  $E$ , it will perform periodic motion only if

- a)  $E < 0$
- b)  $E > 0$
- c)  $V_0 > E > 0$
- d)  $E > V_0$

2. For periodic motion of small amplitude  $A$ , the time period  $T$  of this particle is proportional to

- a)  $A\sqrt{\frac{m}{\alpha}}$
- b)  $\frac{1}{A}\sqrt{\frac{m}{\alpha}}$
- c)  $A\sqrt{\frac{\alpha}{m}}$
- d)  $\frac{1}{A}\sqrt{\frac{\alpha}{m}}$

3. The acceleration of this particle for  $|x| > X_0$  is

- a) Proportional to  $V_0$
- b) Proportional to  $V_0/mX_0$
- c) Proportional to  $\sqrt{V_0/mX_0}$
- d) Zero

# Bibliography

(N.d.). URL: <http://ipodphysics.com/harmonic-graphing-position-velocity-acceleration.php>.



## **Part VIII**

### **Statics**



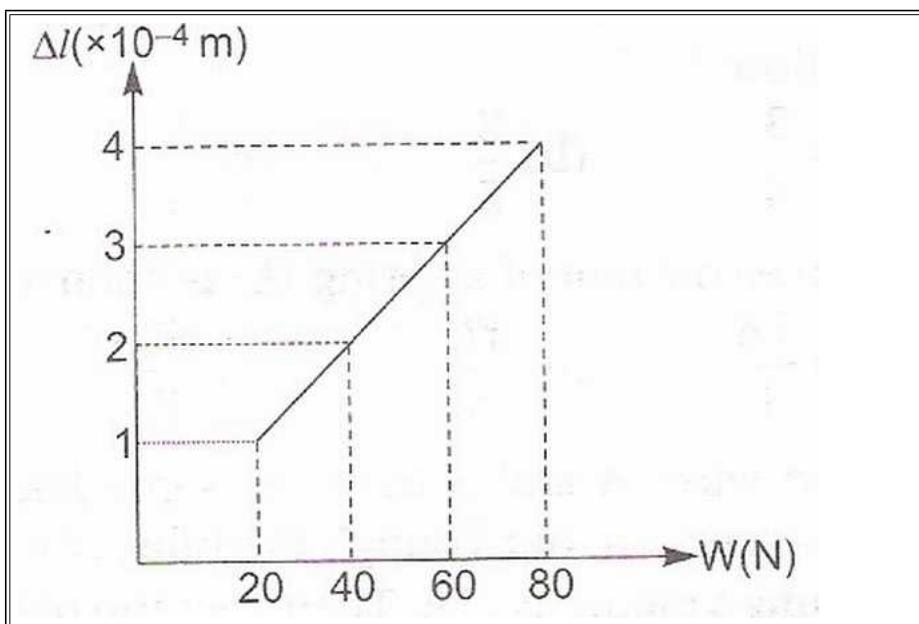
# Chapter 21

## Modulii of Elasticity

### 21.1 General Problem Set

#### 21.1.1 Single Answer Type

Example 1 : The graph shows the extension ( $\Delta l$ ) of a wire of length 1.0m suspended from the top of a roof at one end and with a load  $W$  connected to the other end. If the cross-sectional area of the wire is  $10^{-6} m^2$ , calculate the Young's modulus of the material of the wire



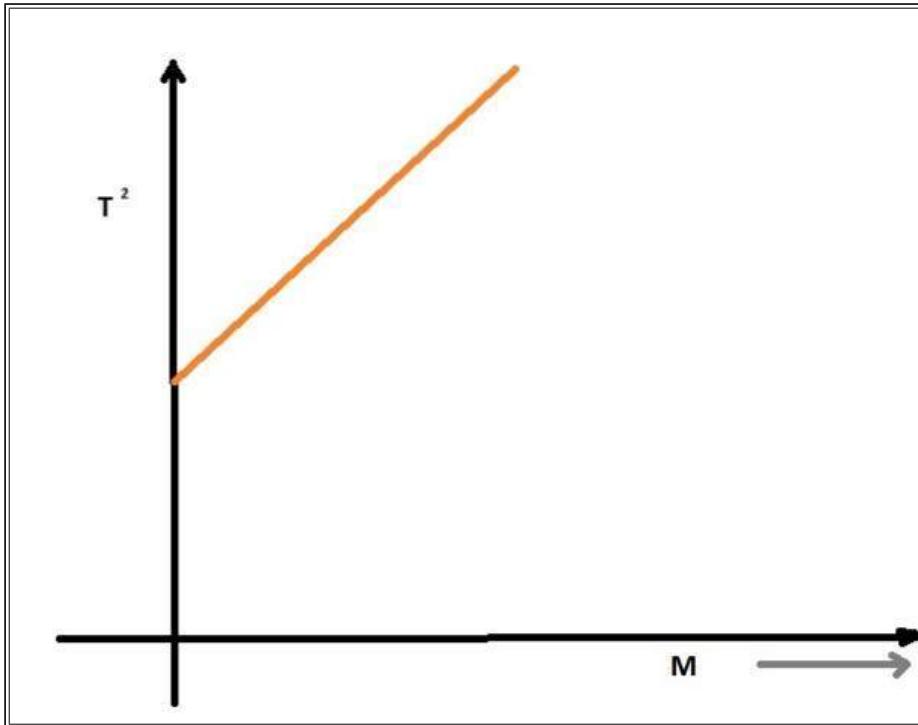
a)  $2 \times 10^{11} \text{ N/m}^2$

b)  $2 \times 10^{10} \text{ N/m}^2$

c)  $2 \times 10^{12} \text{ N/m}^2$

d)  $2 \times 10^{13} \text{ N/m}^2$

**Example :** The graph shown was obtained from experimental measurements of the period of oscillation  $T$  for different masses  $M$  placed in the scale pan on the lower end of the spring balance. The most likely reason for the line not passing through the origin is that the



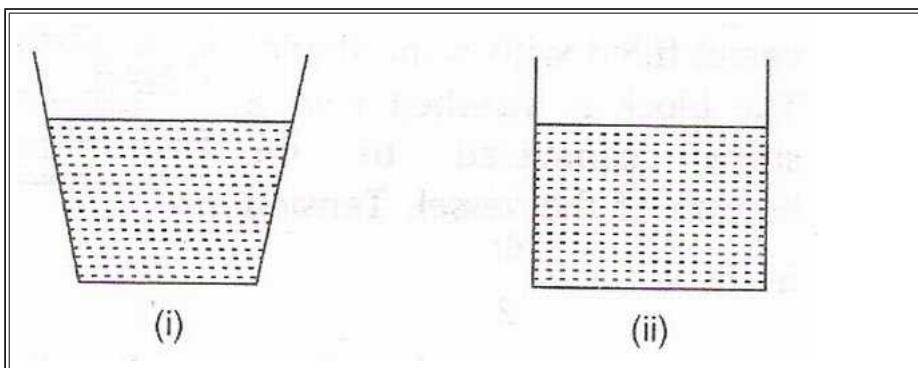
- (a) Spring did not obey Hooke's law  
 (b) Amplitude of oscillation was too large  
 (c) Clock used needed regulating  
 (d) Mass of the pan was neglected  
 { Hint: Answer D }

### 21.1.2 Comprehension Type

#### 21.1.2.1 Comprehension 1

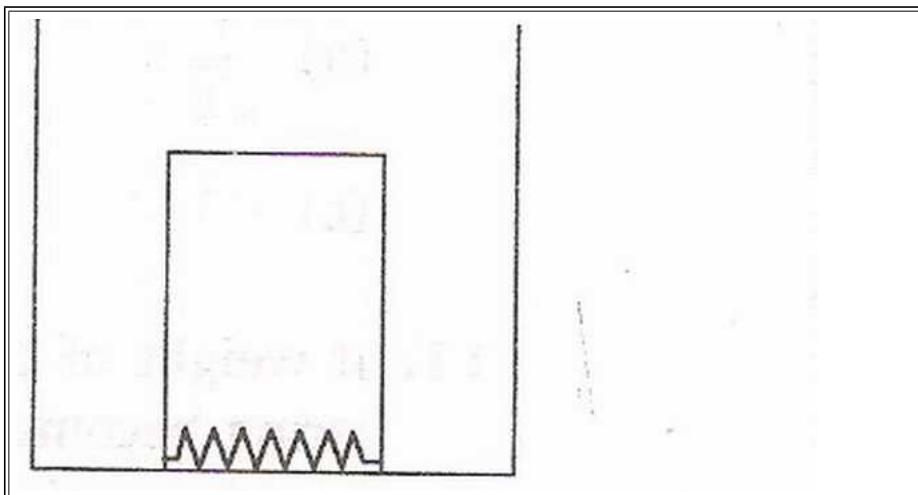
**Concept :** Free body diagram of liquid can be drawn in similar manner as we draw the free body diagram of a solid. The only difference is, what we call the normal reaction between solid-solid boundary, we here call it pressure  $X$  area in case of liquids. Both are perpendicular to the surface.

**Example :** Equal amounts of liquid are filled in two vessels of different shapes as shown in figure. Let  $F_1$  be the force by the base on liquid in case (i) and  $F_2$  in case (ii). Then

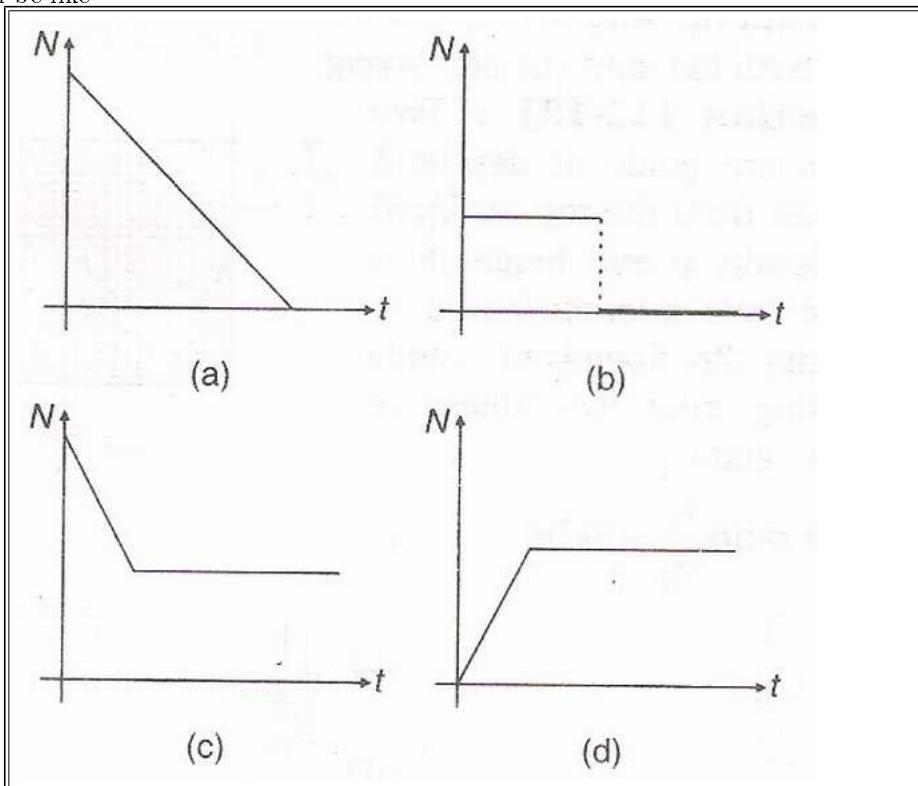


- a)  $F_1 > F_2$   
 b)  $F_1 < F_2$   
 c)  $F_1 = F_2$   
 d) Data insufficient

**Question :** A cube (side = 10 cm) of density  $0.5 \text{ g/cm}^3$  is placed in a vessel of base area  $20 \text{ cm} \times 20 \text{ cm}$ . A liquid of density  $1.0 \text{ g/cm}^3$  is gradually filled in the vessel at a constant rate  $Q = 50 \text{ cm}^3/\text{s}$ .



Example : If we plot a graph between the normal reaction on cube by the vessel versus time. The graph will be like



Example: The cube will leave contact with the vessel after time  $t = \dots \text{ s}$

- a) 30
- b) 40
- c) 60
- d) 20



# **Heat**



# Part IX

## Thermodynamics



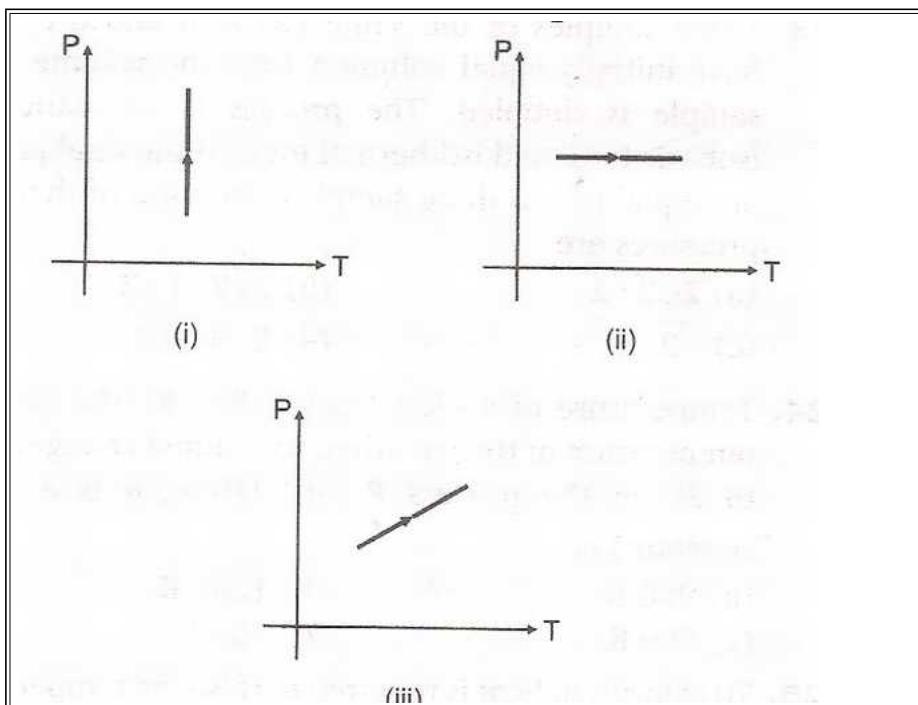
# Chapter 22

## Practice Problems

### 22.1 General Problem Set

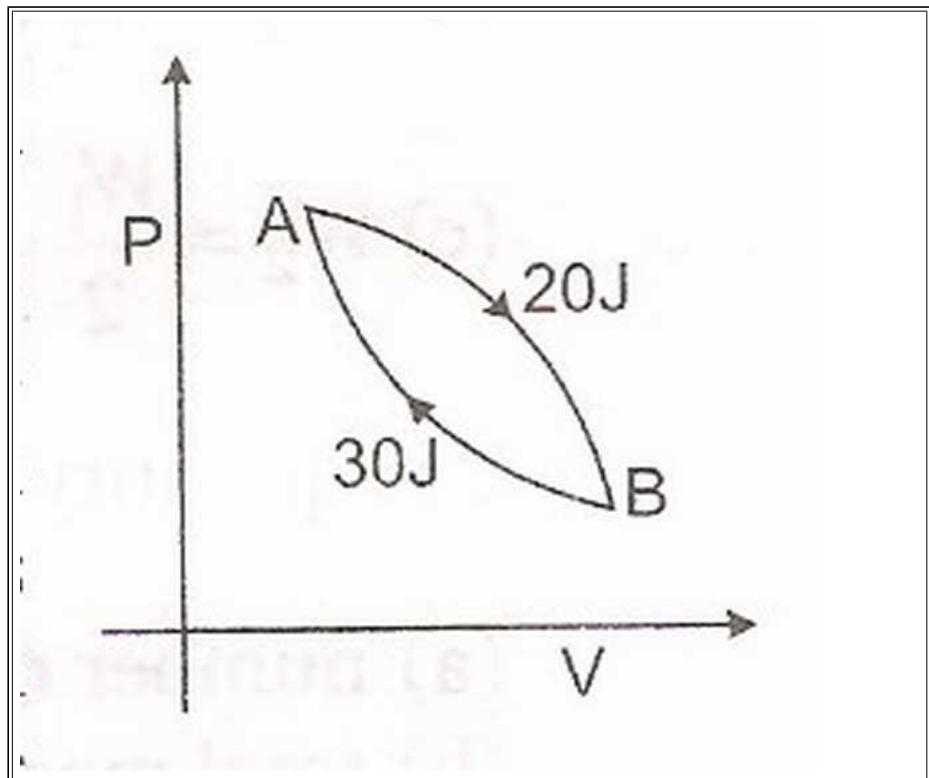
#### 22.1.1 Single Answer Type

**Example :** Pressure versus temperature graphs of an ideal gas are as shown in figure. Choose the wrong statement

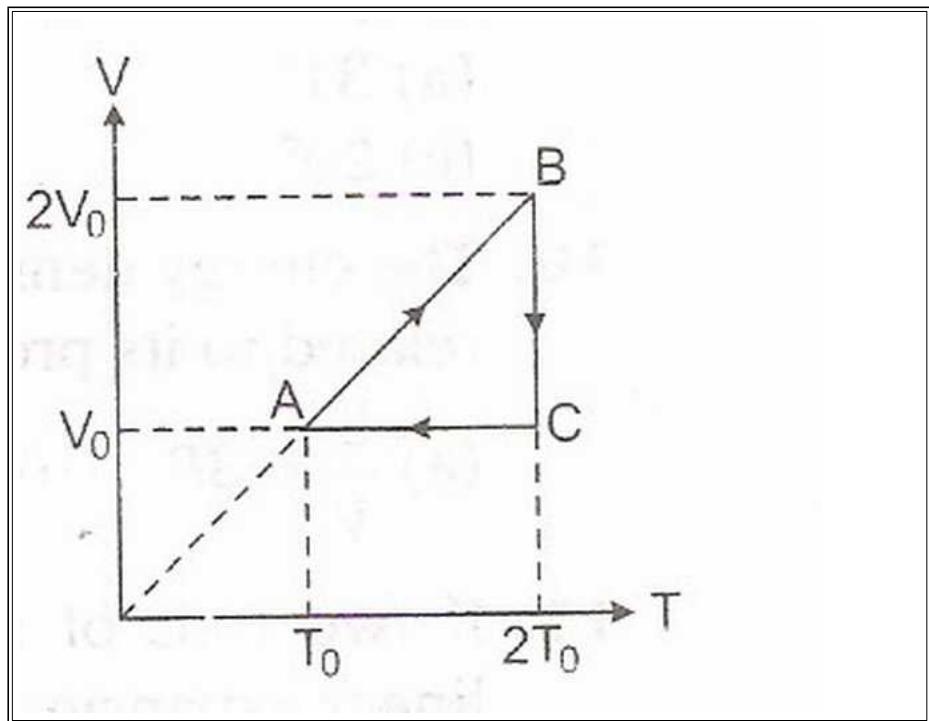


- a) Density of gas is increasing in graph (i)
- b) Density of gas is decreasing in graph (ii)
- c) Density of gas is constant in graph (iii)
- d) None of the above

**Example :** In a cyclic process shown in the figure an ideal gas is adiabatically taken from B to A, the work done on the gas during the process B->A is 30J, when the gas is taken from A->B the heat absorbed by the gas is 20 J. The change in internal energy of the gas in the process A-> B is

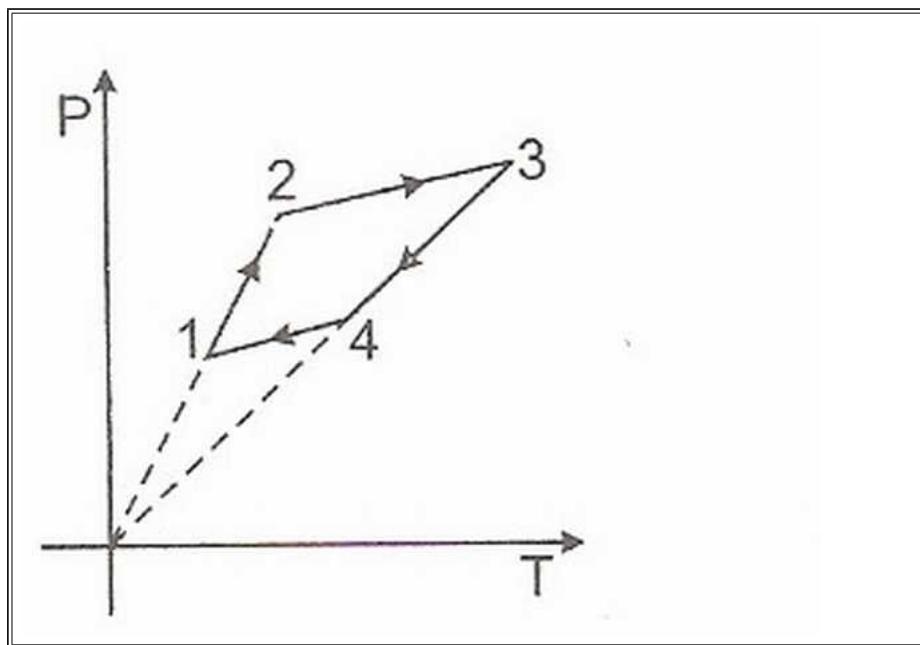


**Example :** An ideal monoatomic gas undergoes a cyclic process ABCA as shown in the figure. The ratio of heat absorbed during AB to the work done on the gas during BC is



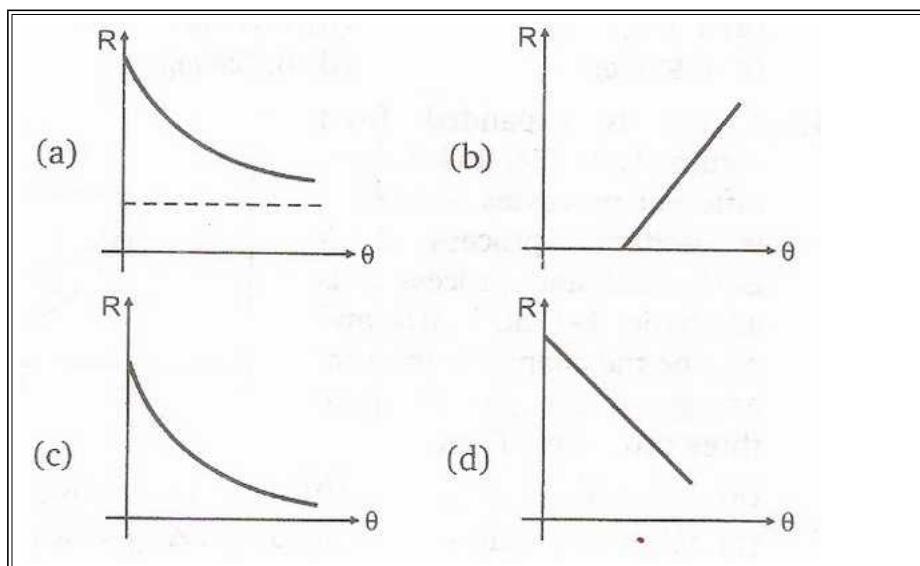
- a)  $5 / 2\ln 2$
- b)  $5 / 3$
- c)  $5 / 4\ln 2$
- d)  $5 / 6$

**Example :** Three moles of an ideal monoatomic gas performs a cycle 1->2->3->4->1 as shown. The gas temperatures in different states are  $T_1=400K$ ,  $T_2=800K$ ,  $T_3=2400K$  and  $T_4=1200K$ . The work done by the gas during the cycle is (2-3 and 4-1 are isobaric)

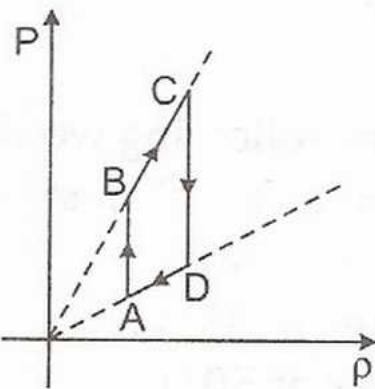


- a) 1200 R
- b) 3600 R
- c) 2400 R
- d) 2000 R

**Example :** Temperature of a body  $\theta$  is slightly more than the temperature of the surrounding  $\theta_o$ . Its rate of cooling ( $R$ ) versus temperature of body ( $\theta$ ) is plotted, its shape would be

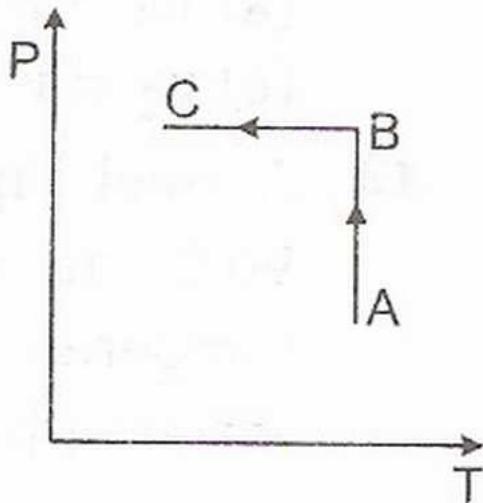


**Example :** Pressure versus density graph of an ideal gas is shown in figure



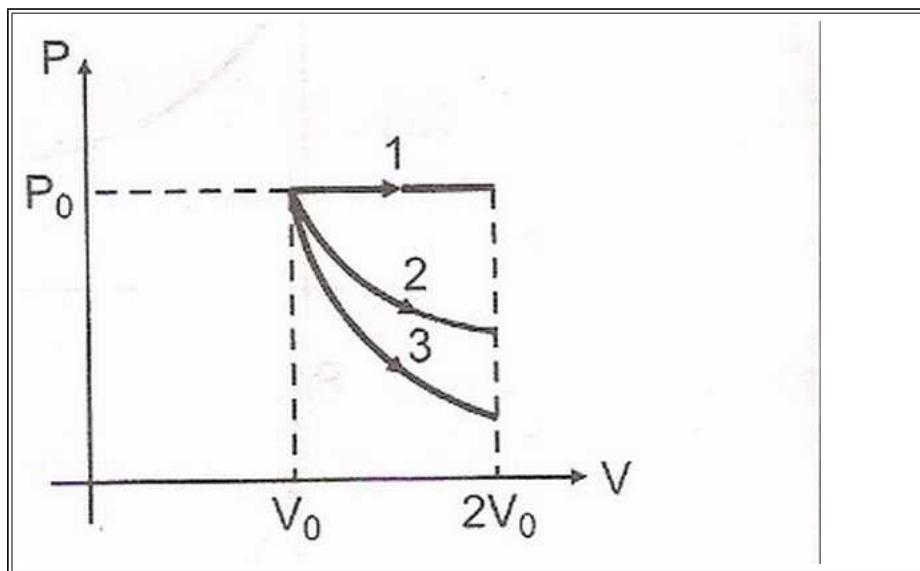
- a) during the process AB work done by the gas is positive
- b) during the process AB work done by the gas is negative
- c) during the process BC internal energy of the gas is increasing
- d) None of the above

**Example :** Ideal gas is taken through the process shown in the figure



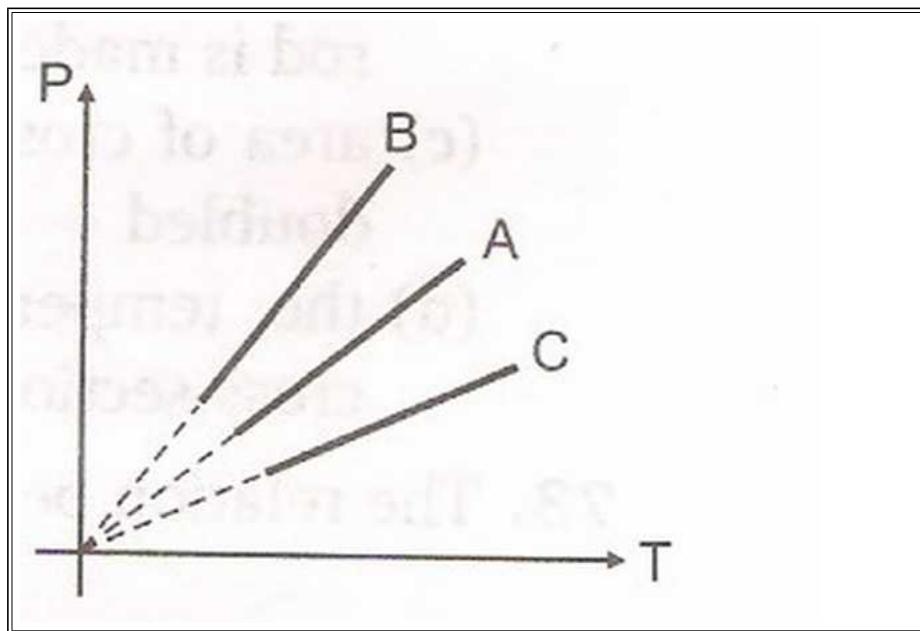
- a) In process AB, work done by system is positive
- b) In process AB, heat is rejected
- c) In process AB, internal energy increases
- d) In process AB internal energy decreases and in process BC, internal energy increases

**Example :** A gas is expanded from volume  $V_0$  to  $2V_0$  under three different processes. Process 1 is isobaric, process 2 is isothermal and process 3 is adiabatic. Let  $\Delta U_1, \Delta U_2$  and  $\Delta U_3$  be the change in internal energy of the gas in these three processes. Then



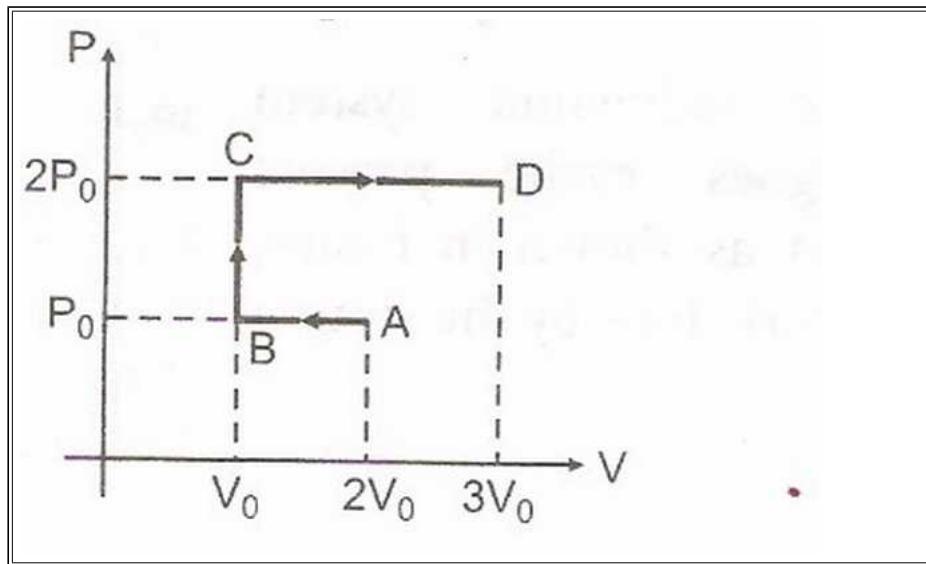
- a)  $\Delta U_1 > \Delta U_2 > \Delta U_3$
- b)  $\Delta U_1 < \Delta U_2 < \Delta U_3$
- c)  $\Delta U_2 < \Delta U_1 < \Delta U_3$
- d)  $\Delta U_2 < \Delta U_3 < \Delta U_1$

**Example :** Pressure versus temperature graph of an ideal gas at constant volume  $V$  is shown by the straight line A. Now mass of the gas is doubled and the volume is halved, then the corresponding pressure versus temperature graph will be shown by the line



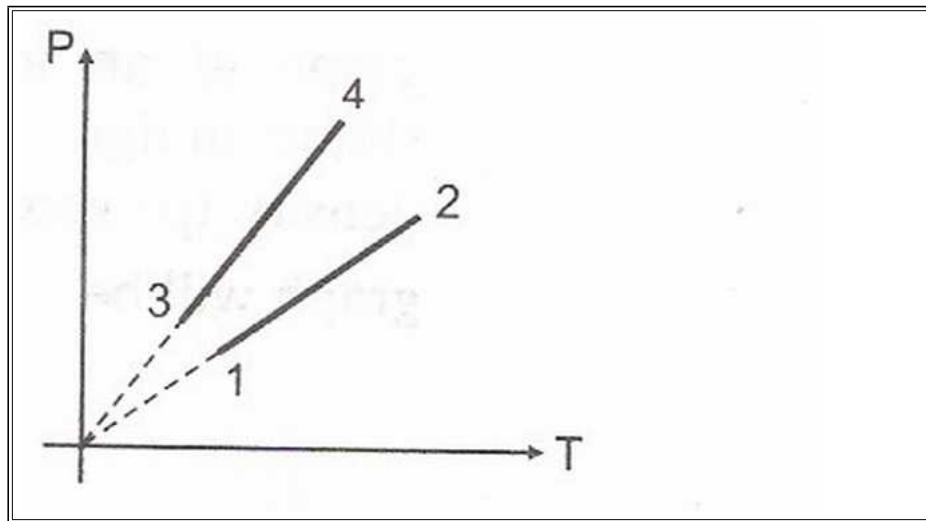
- a) A
- b) B
- c) C
- d) None of these

**Example :** P-V diagram of an ideal gas is as shown in figure. Work done by the gas in the process ABCD is



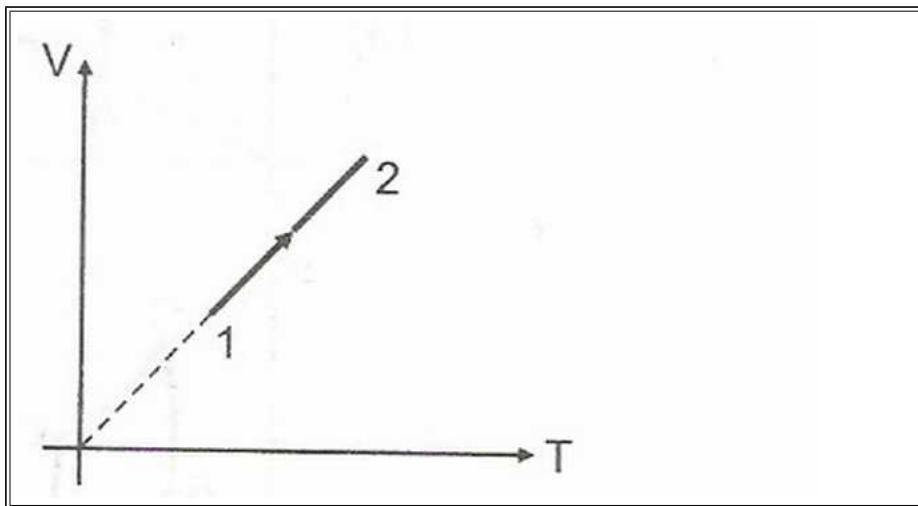
- a)  $4P_0V_0$
- b)  $2P_0V_0$
- c)  $3P_0V_0$
- d)  $P_0V_0$

**Example :** Pressure versus temperature graph of an ideal gas of equal number of moles of different volumes are plotted as shown in figure. Choose the correct alternatives.



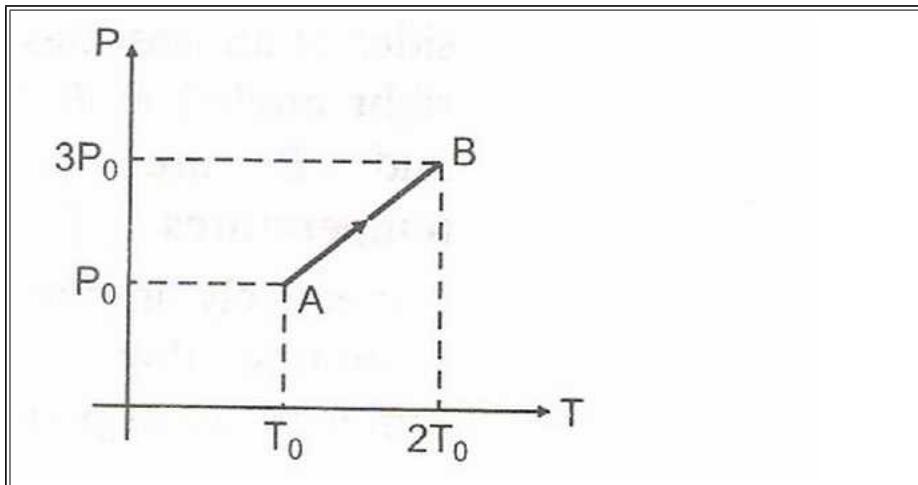
- a)  $V_1 = V_2, V_3 = V_4$  and  $V_2 > V_3$
- b)  $V_1 = V_2, V_3 = V_4$  and  $V_2 < V_3$
- c)  $V_1 = V_2 = V_3 = V_4$
- d)  $V_4 > V_3 > V_2 > V_1$

**Example :** Volume versus temperature graph of two moles of helium gas is as shown in figure. The ratio of heat absorbed and the work done by the gas in process 1-2 is



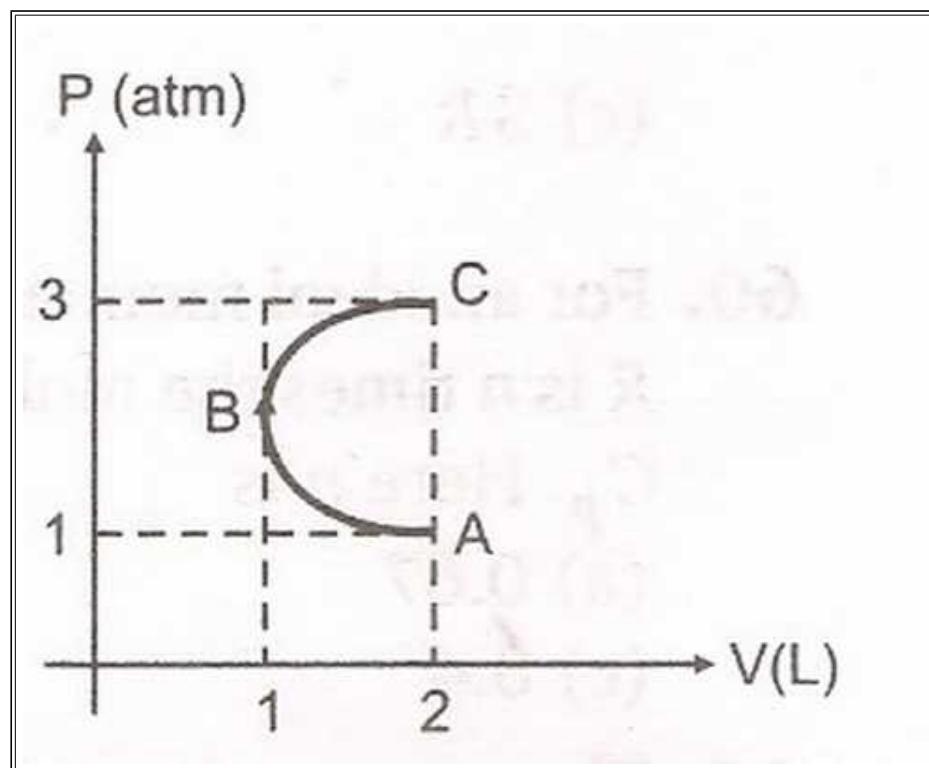
- a) 3
- b) 5/2
- c) 5/3
- d) 7/2

**Example :** Pressure versus temperature graph of an ideal gas is as shown in figure. Density of the gas at point A is  $\rho_o$ . Density at B will be



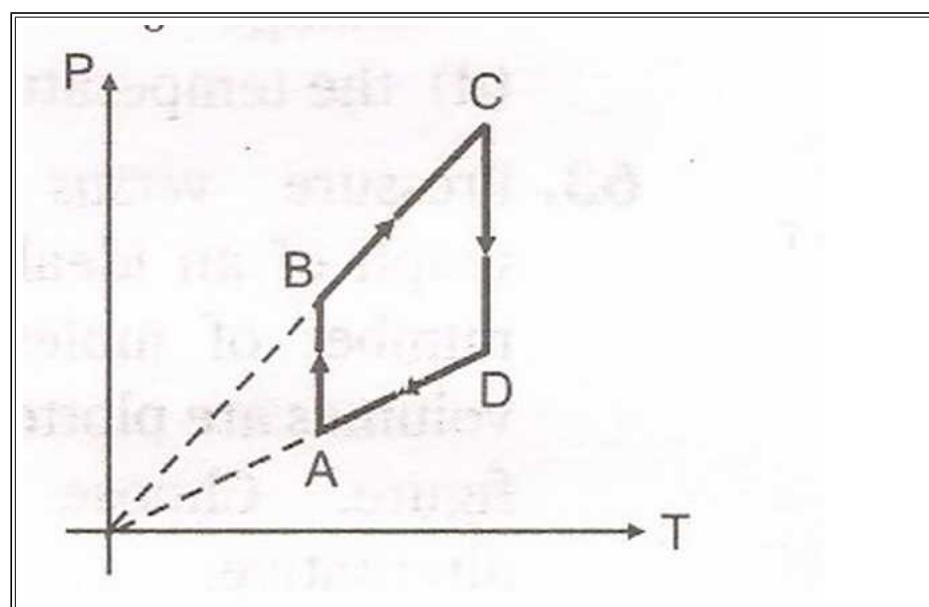
- a)  $\frac{3}{4}\rho_o$
- b)  $\frac{3}{2}\rho_o$
- c)  $\frac{4}{3}\rho_o$
- d)  $2\rho_o$

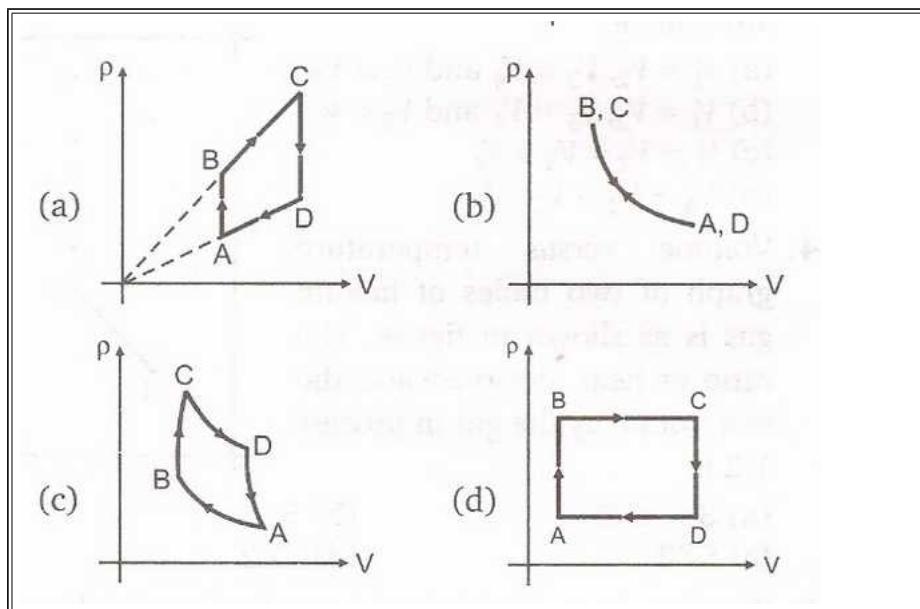
**Example :** In the P-V diagram shown in figure ABC is a semicircle. The work done in the process ABC is



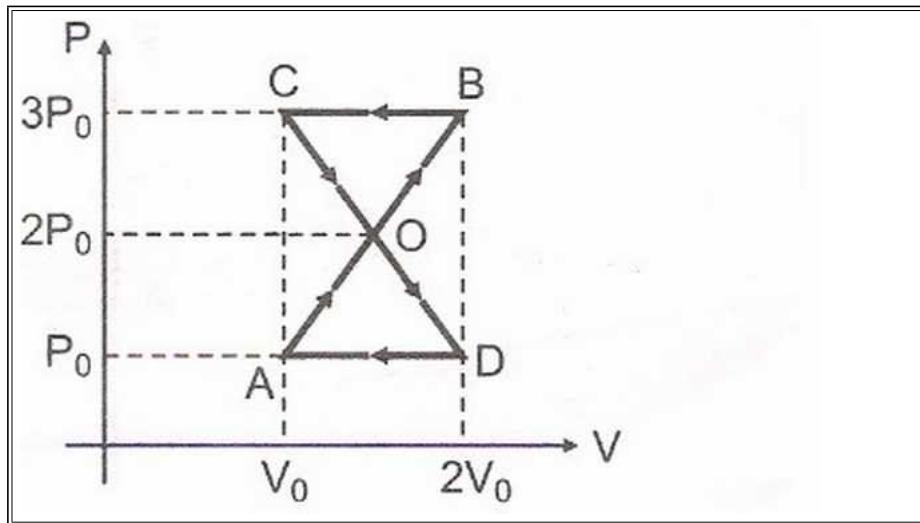
- a) zero
- b)  $\frac{\pi}{2}$  atm-L
- c)  $-\frac{\pi}{2}$  atm-L
- d) 4 atm-L

**Example :** Pressure versus temperature graph of an ideal gas is as shown in figure corresponding density ( $\rho$ ) versus volume ( $V$ ) graph will be





**Example:** A thermodynamic system undergoes cyclic process ABCDA as shown in figure. The work done by the system is



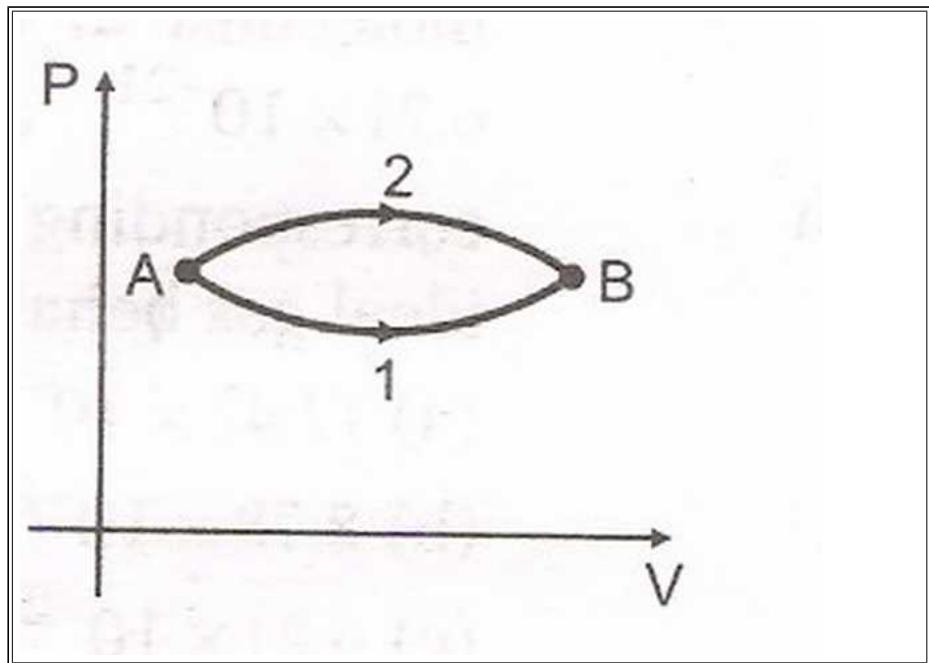
a)  $P_0 V_0$

b)  $2P_0 V_0$

c)  $P_0 V_0 / 2$

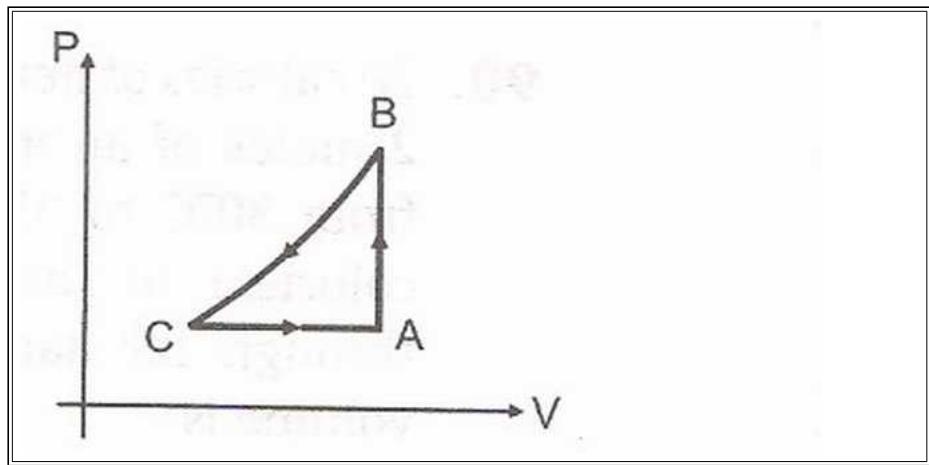
d) zero

**Example :** The figure shows two paths for the change of state of a gas from A to B. The ratio of molar heat capacities in path 1 and path 2 is



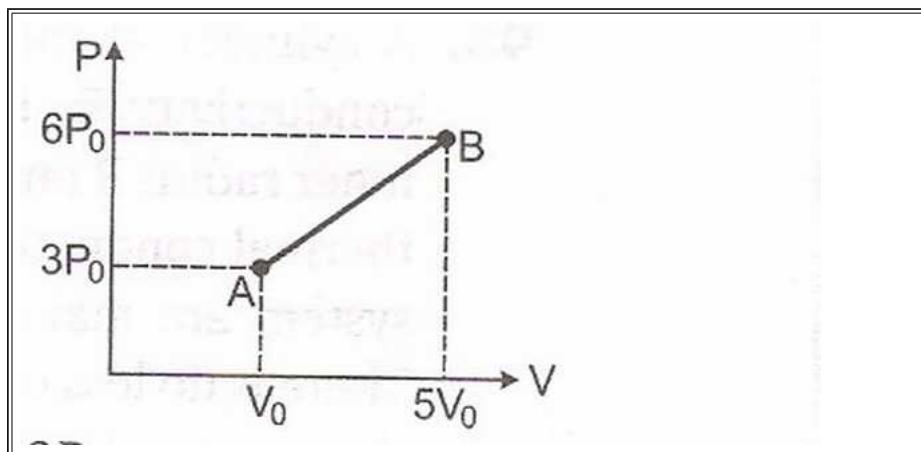
- a)  $> 1$
- b)  $< 1$
- c) 1
- d) Data insufficient

**Example :** A sample of an ideal gas is taken through a cycle as shown in figure. It absorbs 50 J of energy during the process AB, no heat during BC, rejects 70J during CA. 40 J of work is done on the gas during BC. Internal energy of gas at A is 1500 J, the internal energy at C would be



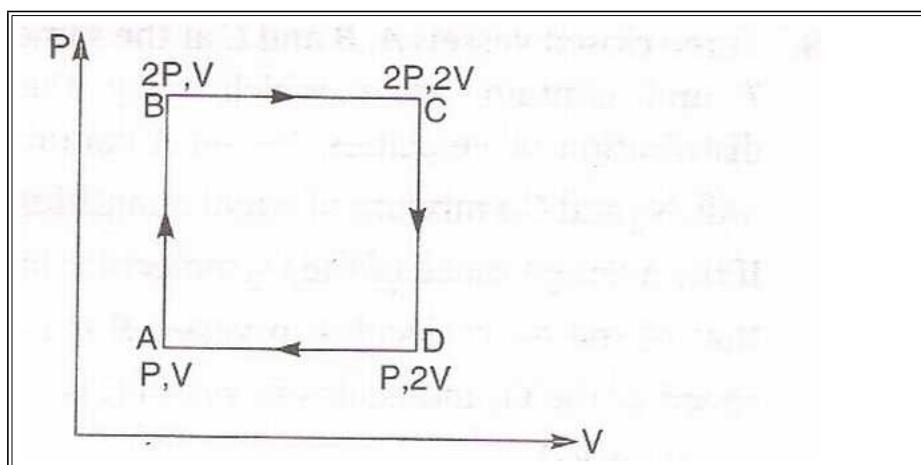
- a) 1590 J
- b) 1620 J
- c) 1540 J
- d) 1570 J

**Example :** One mole of a monoatomic ideal gas undergoes the process A  $\rightarrow$  B in the given P-V diagram. The specific heat for this process is



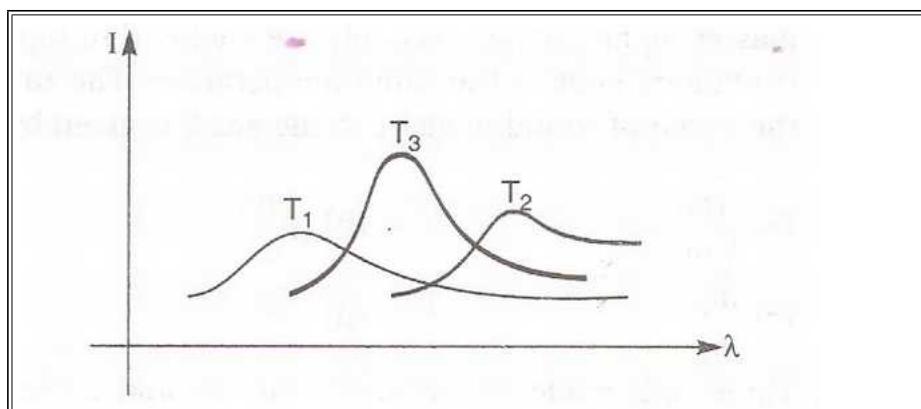
- a)  $3R/2$
- b)  $13R/6$
- c)  $5R/2$
- d)  $2R$

**Example :** An ideal monoatomic gas is taken round the cycle ABCDA as shown in the P-V diagram (see figure). The work done during the cycle is



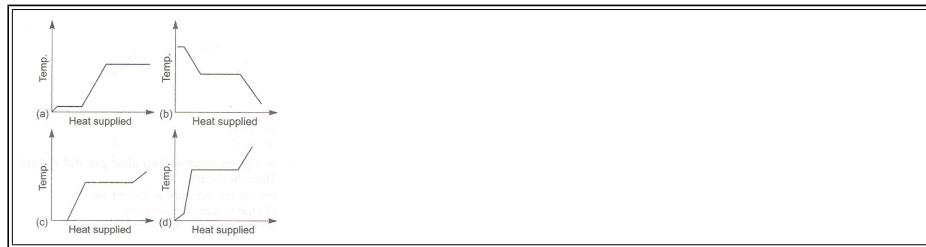
- a)  $PV$
- b)  $2PV$
- c)  $PV/2$
- d) zero

**Example :** The plots of intensity versus wavelength for three black bodies at temperatures  $T_1$ ,  $T_2$  and  $T_3$  respectively are as shown. Their temperatures are such that

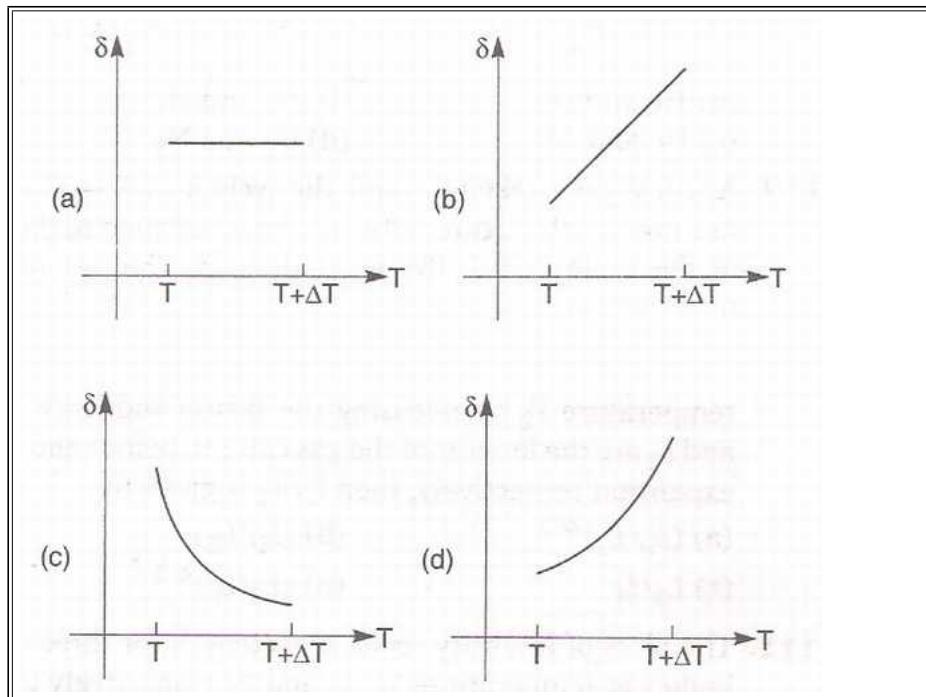


- a)  $T_1 > T_2 > T_3$
- b)  $T_1 > T_3 > T_2$
- c)  $T_2 > T_3 > T_1$
- d)  $T_3 > T_2 > T_1$

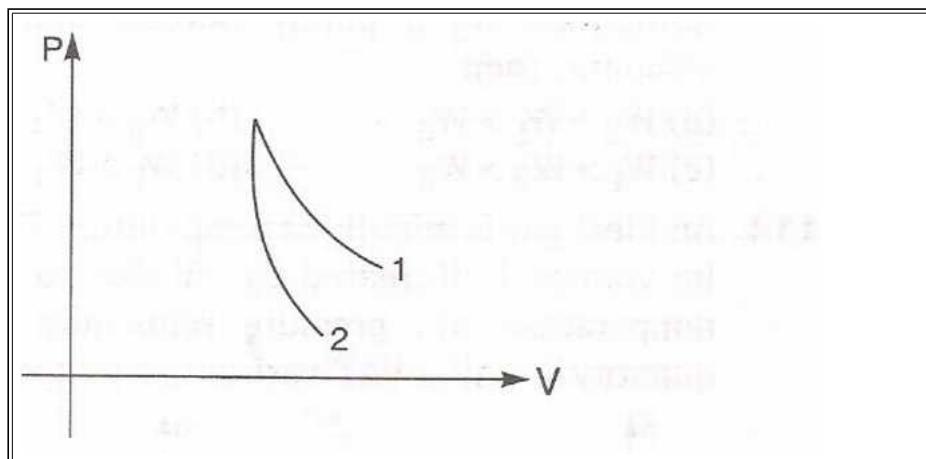
**Example :** A block of ice at  $-10^{\circ}\text{C}$  is slowly heated and converted to steam at  $100^{\circ}\text{C}$ . Which of the following curves represents the phenomenon?



**Example :** An ideal gas is initially at temperature  $T$  and volume  $V$ . Its volume is increased by  $\Delta V$  due to an increase in temperature  $\Delta T$ , pressure remaining constant. The quantity  $\delta = \frac{\Delta V}{V\Delta T}$  varies with temperature as

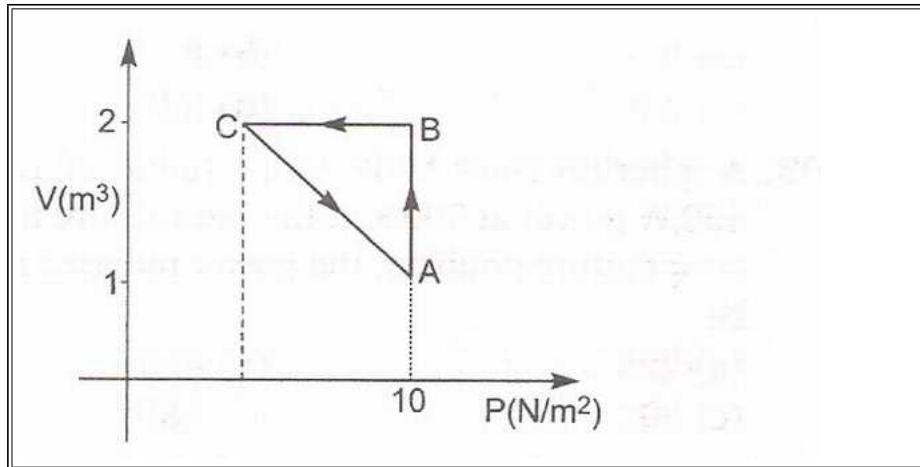


**Example :** P-V plots for two gases during adiabatic processes are shown in the figure. Plots 1 and 2 should correspond respectively to



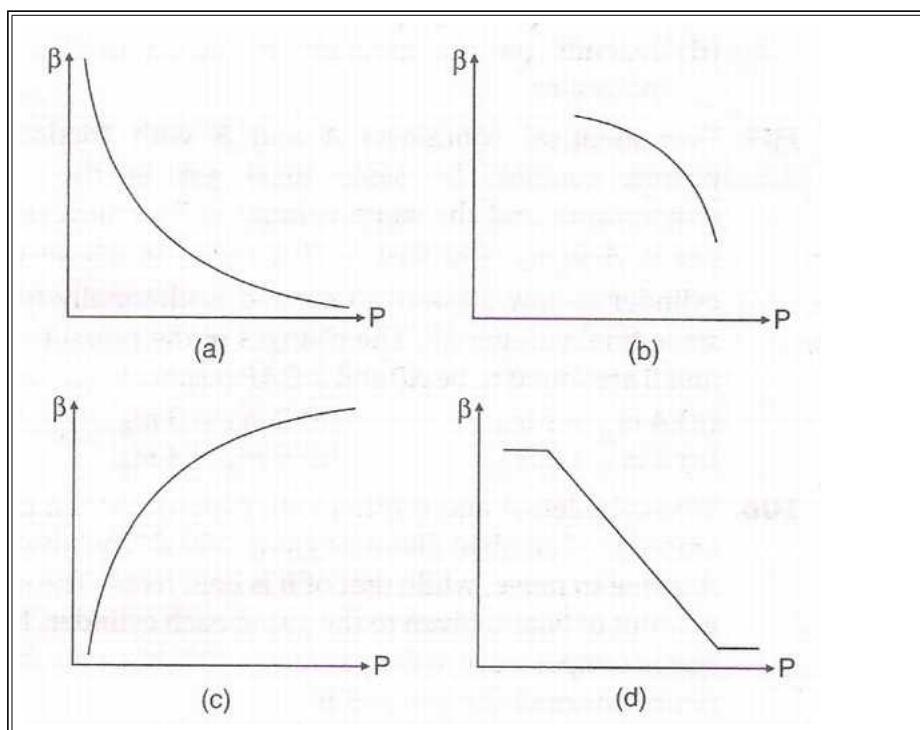
- a) He and  $O_2$
- b)  $O_2$  and He
- c) He and Ar
- d)  $O_2$  and  $N_2$

**Example :** An ideal gas is taken through the cycle A->B->C->A as shown in the figure. If the net heat supplied to the gas in the cycle is 5 J, the work done by the gas in the process C->A is

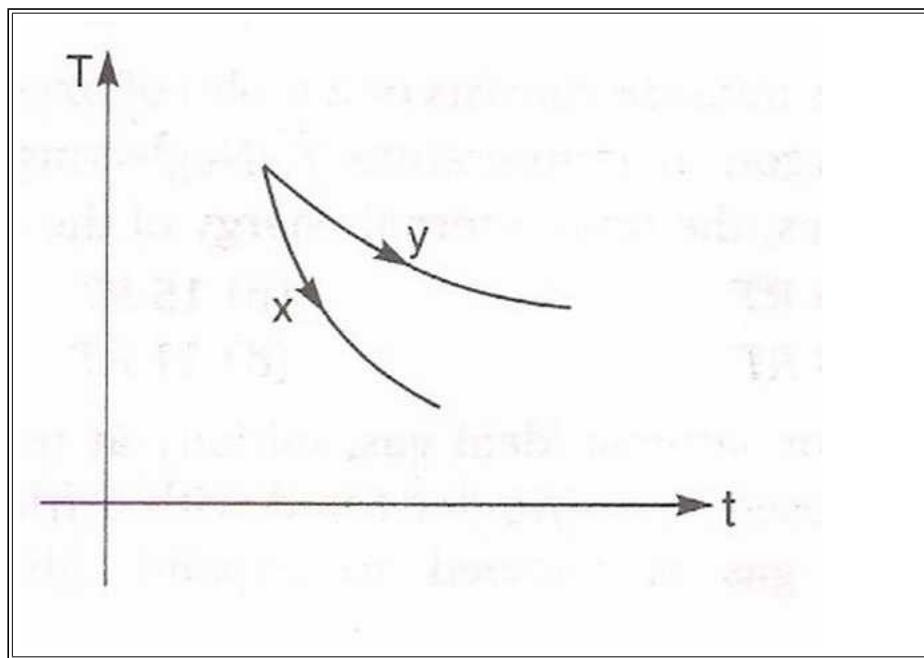


- a) -5 J
- b) -10 J
- c) -15 J
- d) -20 J

**Example :** Which of the following graphs correctly represents the variation of  $\beta = -\frac{dV/dP}{V}$  with P for an ideal gas at constant temperature?

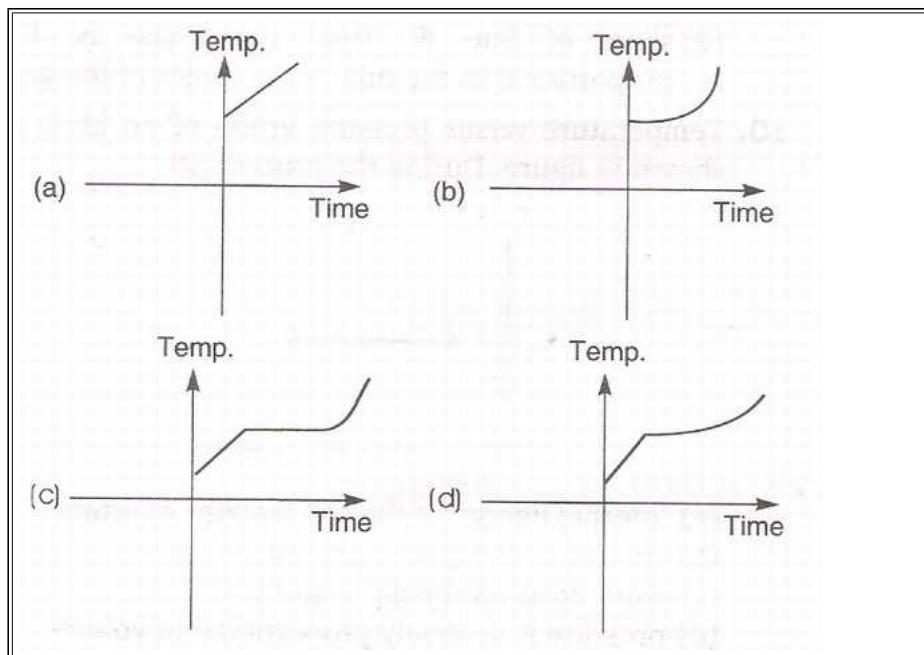


**Example :** The graph, shown in the diagram, represents the variation of temperature (T) of the bodies, x and y having same surface area, with time (t) due to the emission of radiation. Find the correct relation between the emissivity and absorptivity of the two bodies



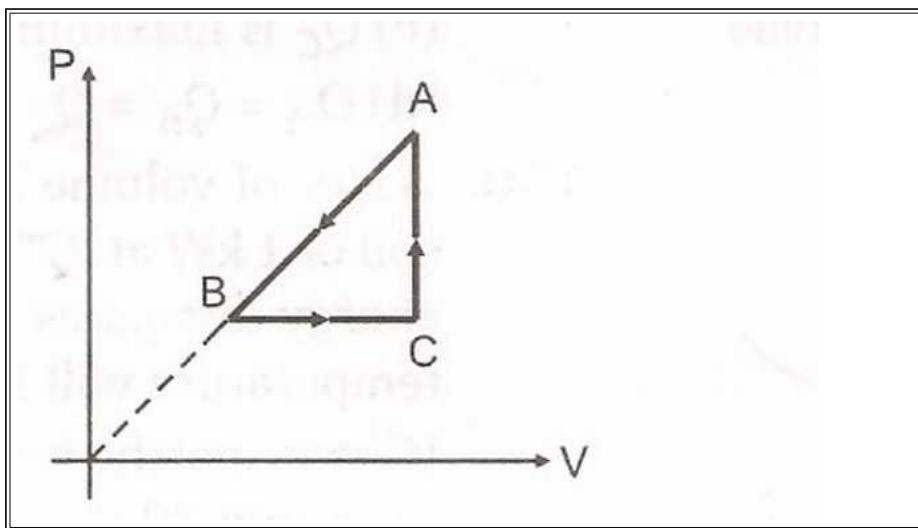
- a)  $E_x > E_y$  and  $a_x < a_y$
- b)  $E_x < E_y$  and  $a_x > a_y$
- c)  $E_x > E_y$  and  $a_x > a_y$
- d)  $E_x < E_y$  and  $a_x < a_y$

**Example :** Liquid oxygen at 50 K is heated to 300K at constant pressure of 1 atm. The rate of heating is constant. Which of the following graphs represent the variation of temperature with time?



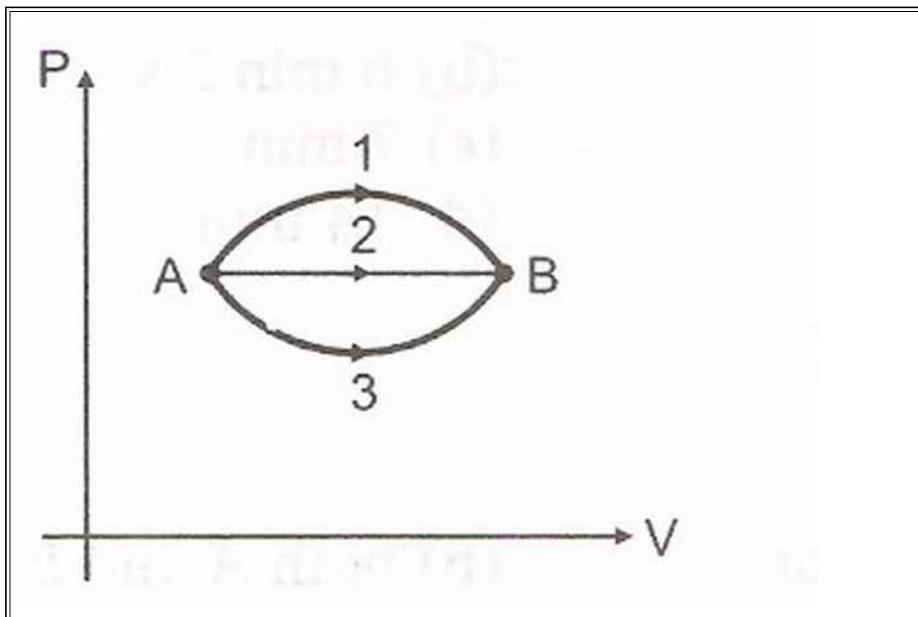
### 22.1.2 Multiple Answer Type

**Example :** P-V diagram of a cyclic process ABCA is as shown in figure. Choose the correct statement (s)



- a)  $\Delta Q_{A \rightarrow B}$  = negative
- b)  $\Delta U_{B \rightarrow C}$  = positive
- c)  $\Delta U_{C \rightarrow A}$  = negative
- d)  $\Delta W_{CAB}$  = negative

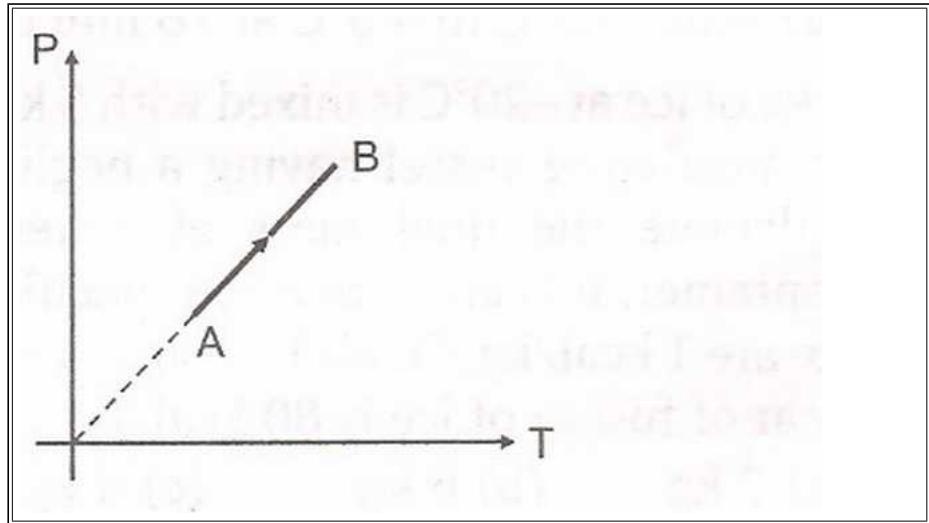
**Example :** A gas undergoes the change in its state from position A to position B via three different paths as shown in figure.



Select the correct alternative (s).

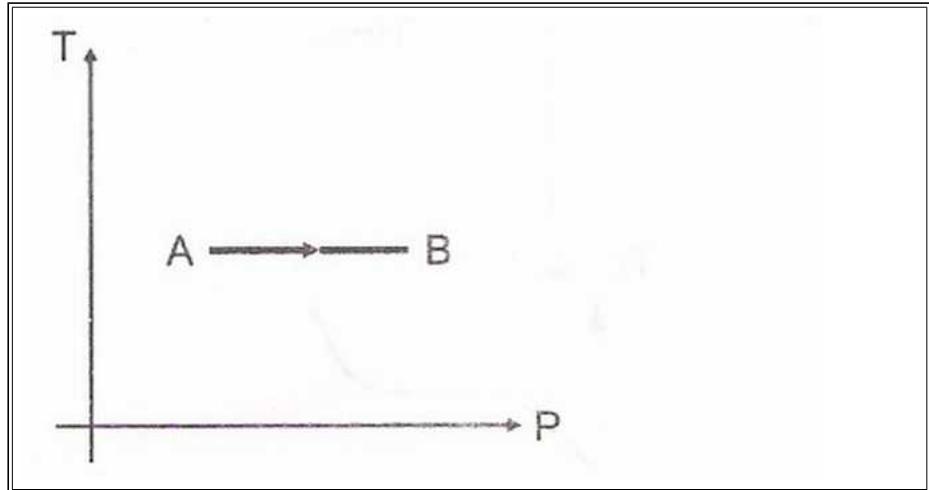
- a) Change in internal energy in all the three paths is equal.
- b) In all the three paths heat is absorbed by the gas.
- c) Heat absorbed / released by the gas is maximum in path 1
- d) Temperature of the gas first increases and then decreases in path 1

**Example :** During the process A-B of an ideal gas



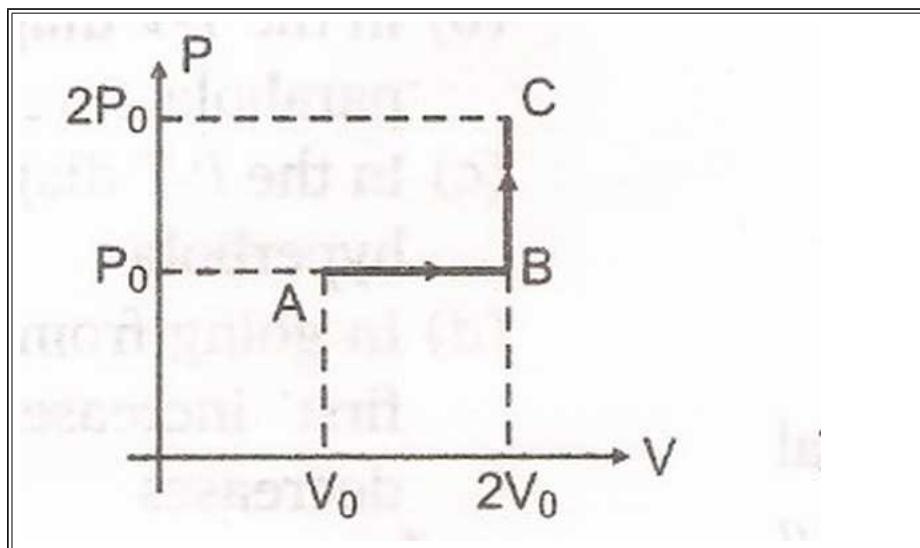
- a) work done on the gas is zero
- b) density of the gas is constant
- c) slope of line AB from the T-axis is inversely proportional to the number of moles of the gas
- d) slope of line AB from the T-axis is directly proportional to the number of moles of the gas

**Example :** Temperature versus pressure graph of an ideal gas is shown in figure. During the process AB



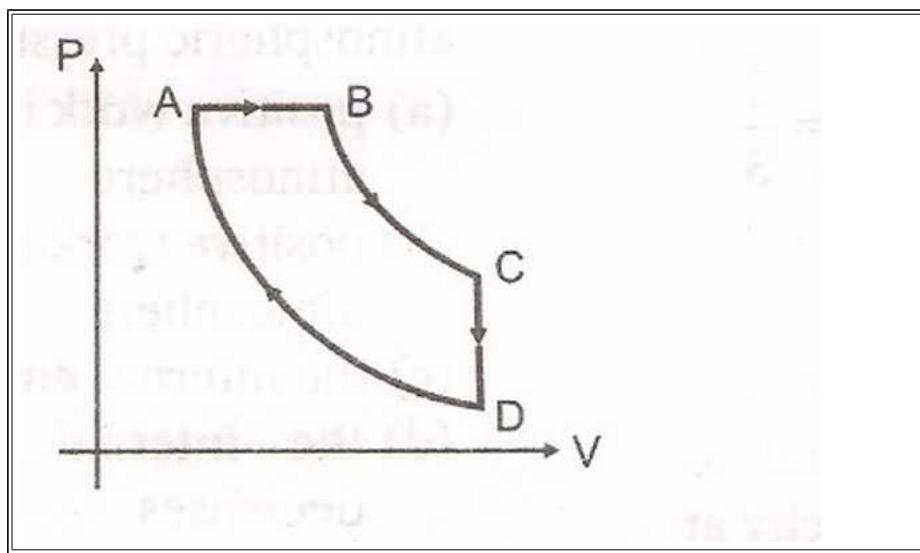
- a) internal energy of the gas remains constant
- b) value of the gas is increased
- c) work done on the gas is positive
- d) pressure is inversely proportional to volume

**Example :** One mole of an ideal monochromatic gas is taken from A to C along the path ABC. The temperature of the gas at A is  $T_o$ . For the process ABC



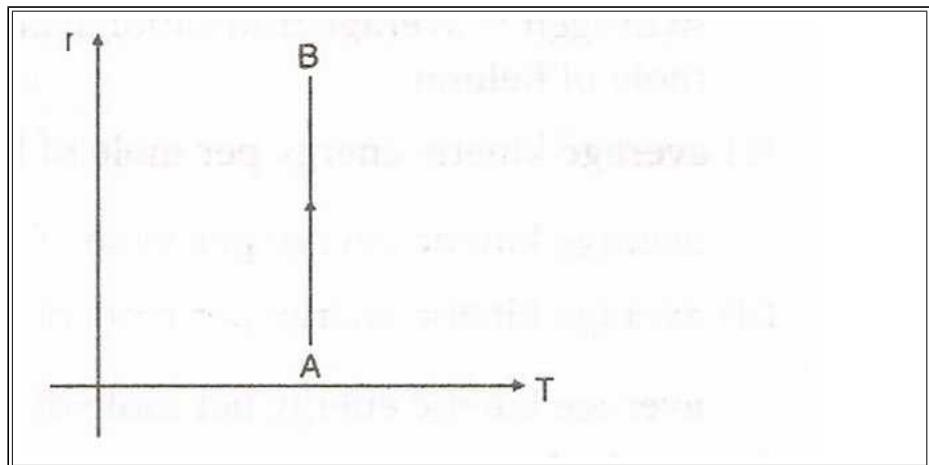
- a) work done by the gas is  $RT_o$
- b) change in internal energy of the gas is  $\frac{11}{2}RT_o$
- c) heat absorbed by the gas is  $\frac{11}{2}RT_o$
- d) heat absorbed by the gas is  $\frac{13}{2}RT_o$

**Example :** n moles of a monoatomic gas undergo a cyclic process ABCDA as shown in figure. Process AB is isobaric, BC is adiabatic, CD is isochoric and DA is isothermal. The maximum and minimum temperature in the cycle are  $4T_o$  and  $T_o$  respectively. Then



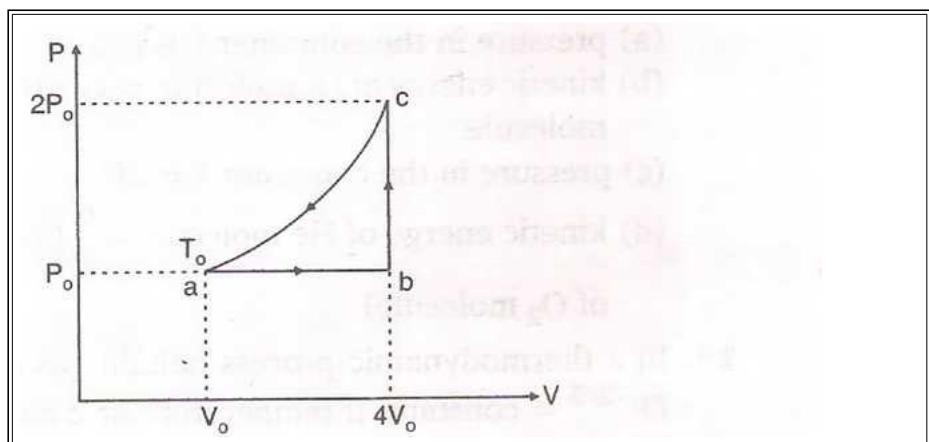
- a)  $T_B > T_C > T_D$
- b) heat is released by the gas in the process CD
- c) heat is supplied to the gas in the process AB
- d) total heat supplied to the gas is  $2nRT_o \ln(2)$

**Example :** The density ( $\rho$ ) of an ideal gas varies with temperature T as shown in figure. Then



- a) the product of  $P$  &  $V$  at A is equal to the product of  $P$  &  $V$  at B
- b) pressure at B is greater than the pressure at A
- c) work done by the gas during the process AB is negative
- d) the change in internal energy from A to B is zero

**Example :** One mole of an ideal monoatomic gas ( initial temperature  $T_o$  ) is made to go through the cycle abc<sub>a</sub> shown in the figure. If U denotes the internal energy, then choose the correct alternatives

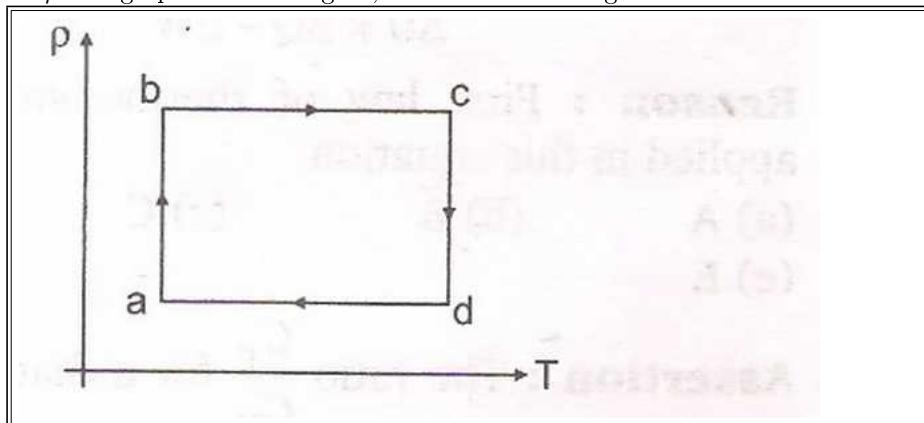


- a)  $U_c - U_a = 10.5RT_o$
- b)  $U_b - U_a = 4.5RT_o$
- c)  $U_c > U_b > U_a$
- d)  $U_c - U_b = 6RT_o$

### 22.1.3 Matching Type

#### 22.1.3.1 Matrix Match 1

In the  $\rho - T$  graph shown in figure, match the following



**Table-1**

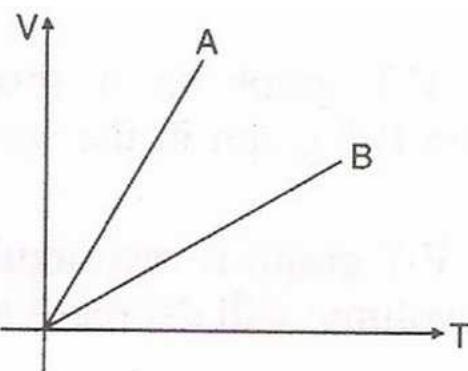
- (A) Process  $a-b$   
 (B) Process  $b-c$   
 (C) Process  $c-d$   
 (D) Process  $d-a$

**Table-2**

- (P) Isochoric process  
 (Q)  $\Delta U = 0$   
 (R)  $P$  increasing  
 (S)  $P$  decreasing

**22.1.3.2 Matrix Match 2**

In the V-T graph shown in figure match the following

**Table-1**

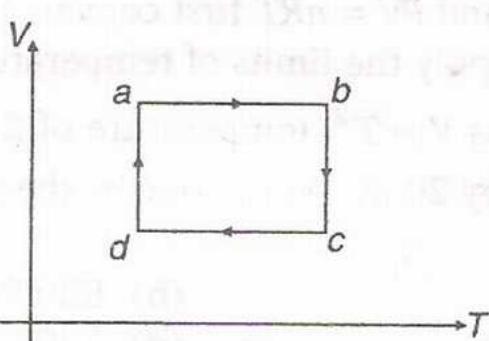
- (A) Gas A and Gas B are ...  
 (B)  $P_A/P_B$  is  
 (C)  $n_A/n_B$  is

**Table-2**

- (P) monoatomic,  
 diatomic  
 (Q) diatomic,  
 monoatomic  
 (R)  $> 1$   
 (S)  $< 1$   
 (T) Cannot say any thing

**22.1.4 Comprehension Type****22.1.4.1 Comprehension 1**

Statement : V-T graph of an ideal gas is as shown in figure.



Question : Work done by the gas in complete cyclic process abcd is

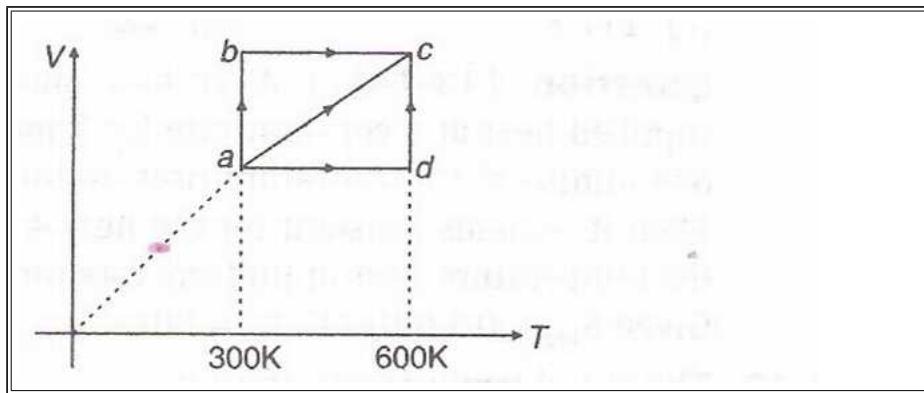
- a) zero
- b) positive
- c) negative
- d) Data is insufficient

**Question :** Heat is supplied to the gas in process (es)

- a) da, ab and bc
- b) da and ab only
- c) da only
- d) ab and bc only

#### 22.1.4.2 Comprehension 2

Two moles of a monoatomic gas are taken from a to c, via three paths abc, ac and adc.



**Question :** Work done by the gas in process ac is

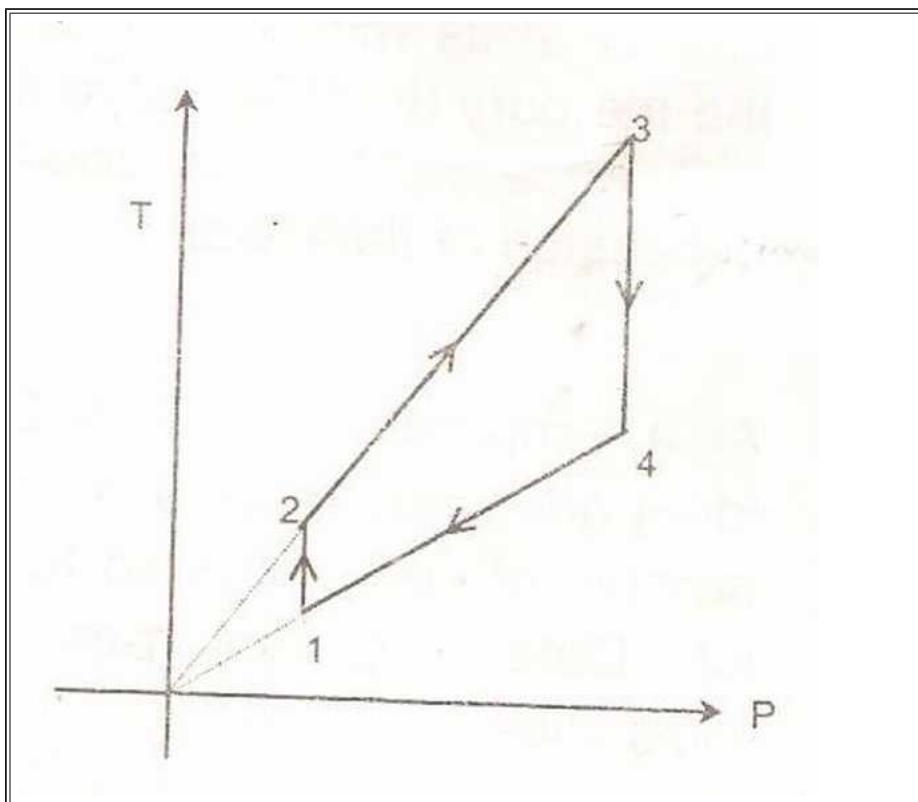
- a) 1000 R
- b) 900 R
- c) 600 R
- d) 1500 R

**Question :** If work done by the gas in abc is  $W_1$ , in ac work done is  $W_2$  and in adc work done is  $W_3$ , then

- a)  $W_2 > W_3 > W_1$
- b)  $W_1 > W_2 > W_3$
- c)  $W_2 > W_1 > W_3$
- d)  $W_3 > W_2 > W_1$

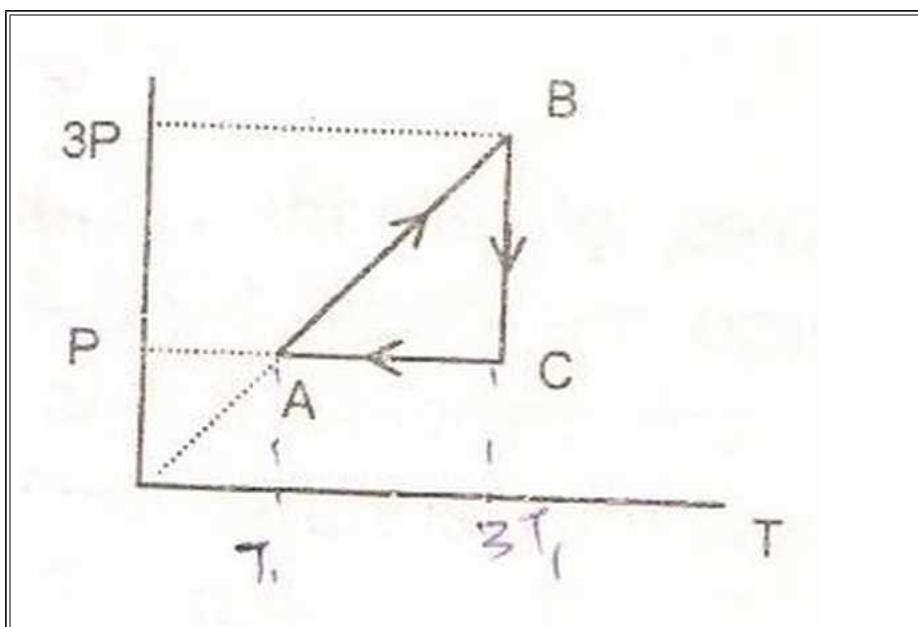
#### 22.1.5 Subjective Problems

**Example:** The moles of an ideal monoatomic gas undergoes a cyclic process as shown in the figure.

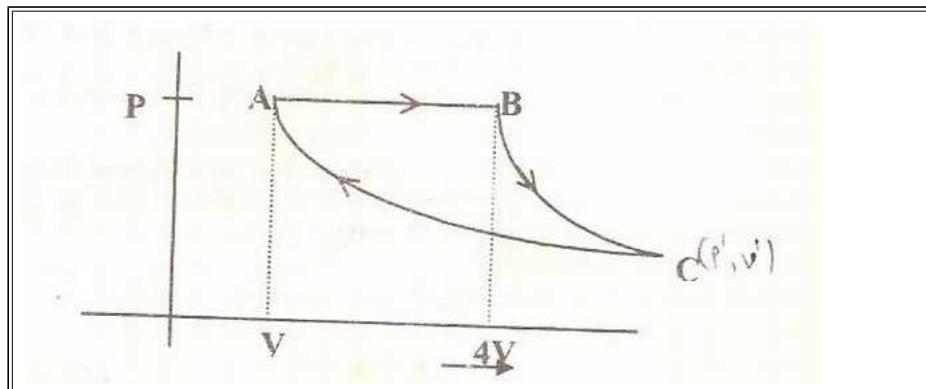


The temperatures in different states are  $6T_1 = 3T_2 = 2T_4 = T_3 = 1800\text{K}$ . Determine the work done by the gas during the cycle.

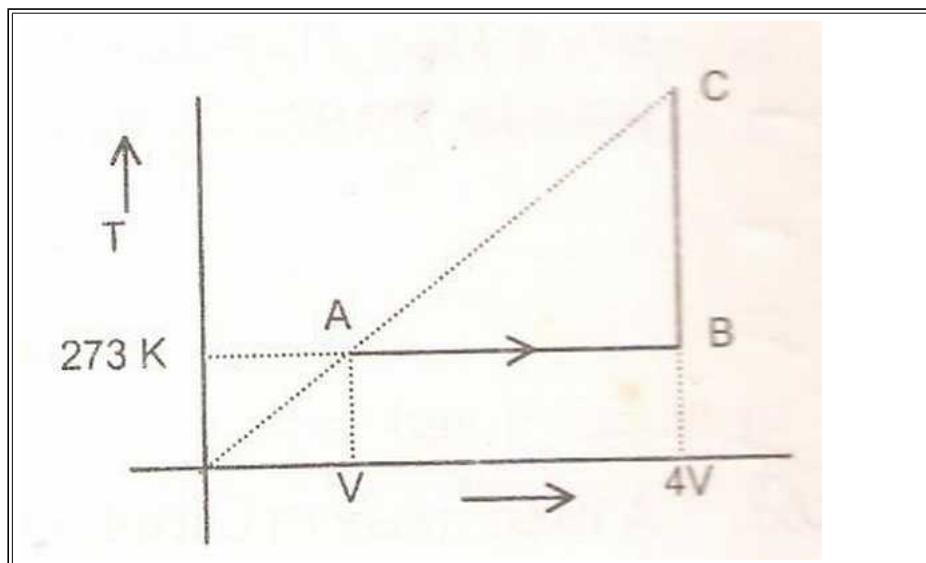
**Example:** A fixed mass of oxygen gas performs a cycle ABCA as shown. Find efficiency of the process.



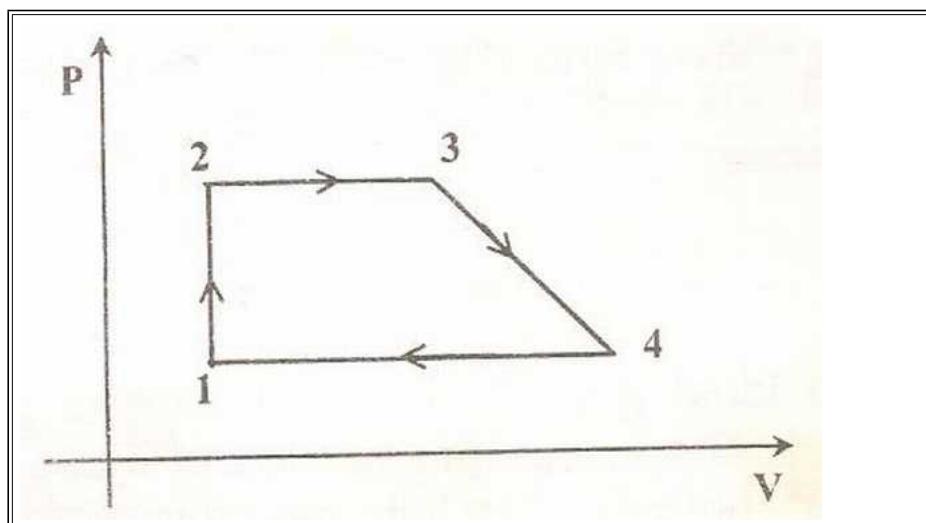
**Example:** A fixed mass of gas is taken through a process  $A \rightarrow B \rightarrow C \rightarrow A$ . Here  $A \rightarrow B$  is isobaric.  $B \rightarrow C$  is adiabatic and  $C \rightarrow A$  is isothermal. Find efficiency of process. (Take  $\gamma = 1.5$ )



**Example:** At a temperature of  $T_o = 273^{\circ}K$ , two moles of an ideal gas undergoes a process as shown. The total amount of heat imparted to the gas equals  $Q = 27.7\text{ kJ}$ . Determine the ratio of molar specific heat capacities.



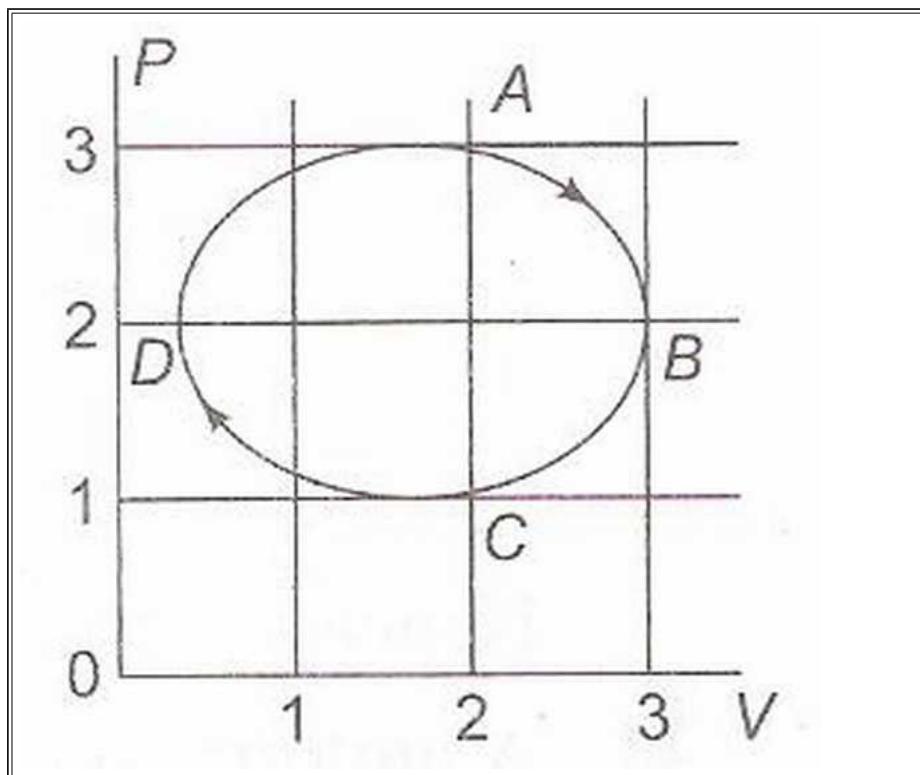
**Example:**  $n$  moles of an ideal gas is made to undergo the cycle 1-2-3-4-1 as shown in the figure. Process 3-4 is a straight line. The gas temperatures in states 1, 2 and 3 are  $T_1$ ,  $T_2$  and  $T_3$  respectively. Temperature at 3 and 4 are equal. Determine the work done by the gas during the cycle.



## 22.2 Previous Years IIT Problems

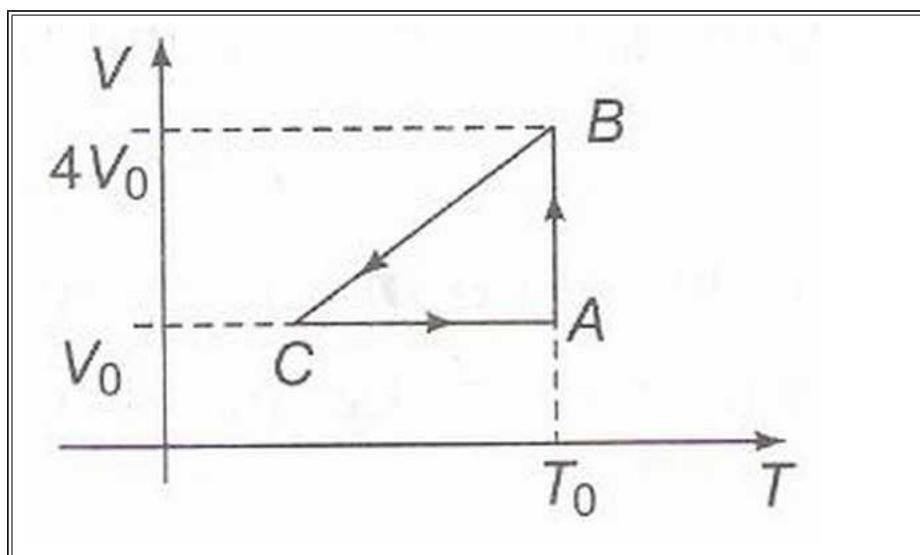
### 22.2.1 Multiple Answer

**Example:** The figure shows the P-V plot of an ideal gas taken through a cycle ABCDA. The part ABC is a semi-circle and CDA is half of an ellipse. Then,



- a) the process during the path A->B is isothermal.
- b) heat flows out of the gas during the path B->C->D
- c) work done during the path A->B->C is zero.
- d) positive work is done by the gas in the cycle ABCDA

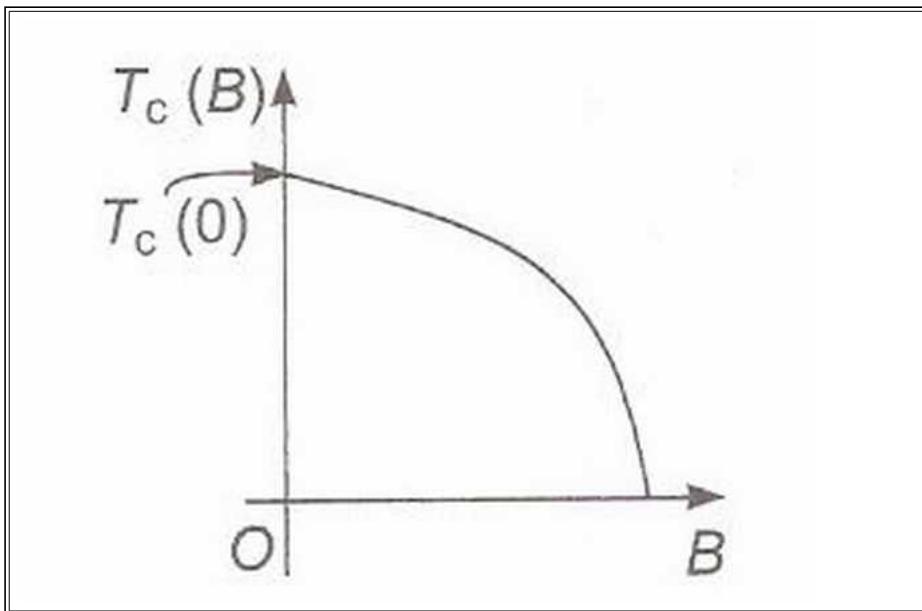
**Example:** One mole of an ideal gas in initial state A undergoes a cyclic process ABCA, as shown in the figure. Its pressure at A is  $P_0$ . Choose the correct option(s) from the following



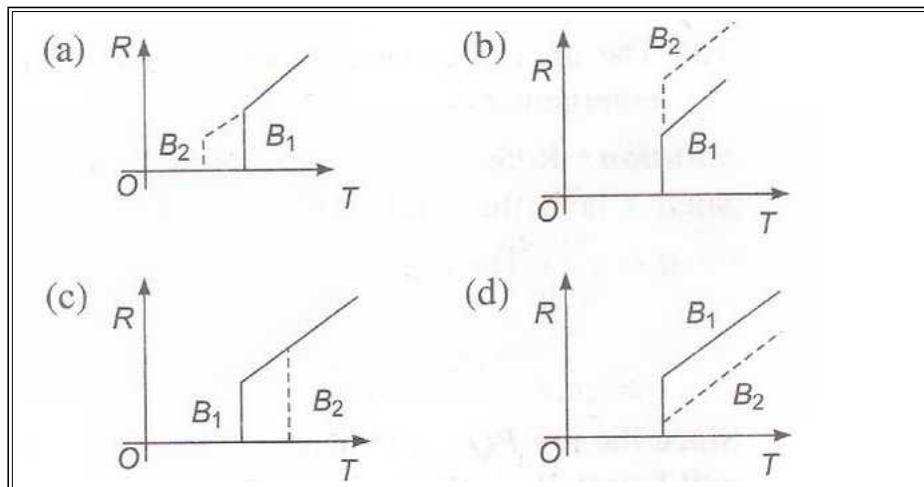
- a) Internal energies at A and B are the same
- b) Work done by the gas in process AB is  $P_0 V_0 \ln 4$
- c) Pressure at C is  $\frac{P_0}{4}$ .
- d) Temperature at C is  $\frac{T_0}{4}$ .

### 22.2.2 Paragraph

Paragraph 1: Electrical resistance of certain materials, known as superconductors, changes abruptly from a nonzero value to zero as their temperature is lowered below a critical temperature  $T_c(0)$ . An interesting property of superconductors is that their critical temperature becomes smaller than  $T_c(0)$  if they are placed in a magnetic field, i.e., the critical temperature  $T_c(B)$  is a function of the magnetic field strength  $B$ . The dependence of  $T_c(B)$  on  $B$  is shown in the figure.



- 1: In the graphs below, the resistance  $R$  of a superconductor is shown as a function of its temperature  $T$  for two different magnetic fields  $B_1$  (solid line) and  $B_2$  (dashed line). If  $B_2$  is larger than  $B_1$  which of the following graphs shows the correct variation of  $R$  with  $T$  in these fields?



- 2: A superconductor has  $T_c(0) = 100\text{K}$ . When a magnetic field of 7.5 Tesla is applied, its  $T_c$  decreases to 75 K. For this material one can definitely say that when

- a)  $B = 5 \text{ Tesla}, T_c(B) = 80 \text{ K}$
- b)  $B = 5 \text{ Tesla}, 75 \text{ K} < T_c(B) < 100\text{K}$
- c)  $B = 10 \text{ Tesla}, 75\text{K} < T_c < 100\text{K}$
- d)  $B = 10 \text{ Tesla}, T_c = 70 \text{ K}$

### 22.2.3 Matching

**Example:**

Column I contains a list of processes involving expansion of an ideal gas. Match this with Column II describing the thermodynamic change during this process.

**Column I**

- (a) An insulated container has two chambers separated by a valve. Chamber I contains an ideal gas and the chamber II has vacuum. The valve is opened.

**Column II**

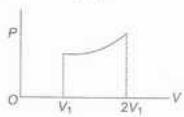
- (p) The temperature of the gas decreases

- (b) An ideal monoatomic gas expands to twice its original volume such that its pressure  $P \propto \frac{1}{V^2}$ . where  $V$  is the volume of the gas.
- (c) An ideal monoatomic gas expands to twice its original volume such that its pressure  $P \propto \frac{1}{V^{4/3}}$ , where  $V$  is its volume.
- (d) An ideal monoatomic gas expands such that its pressure  $P$  and volume  $V$  follow the behaviour shown in the graph.

- (q) The temperature of the gas increases or remains constant

- (r) The gas loses heat

- (s) The gas gains heat





# Waves



# Part X

## Mechanical Waves

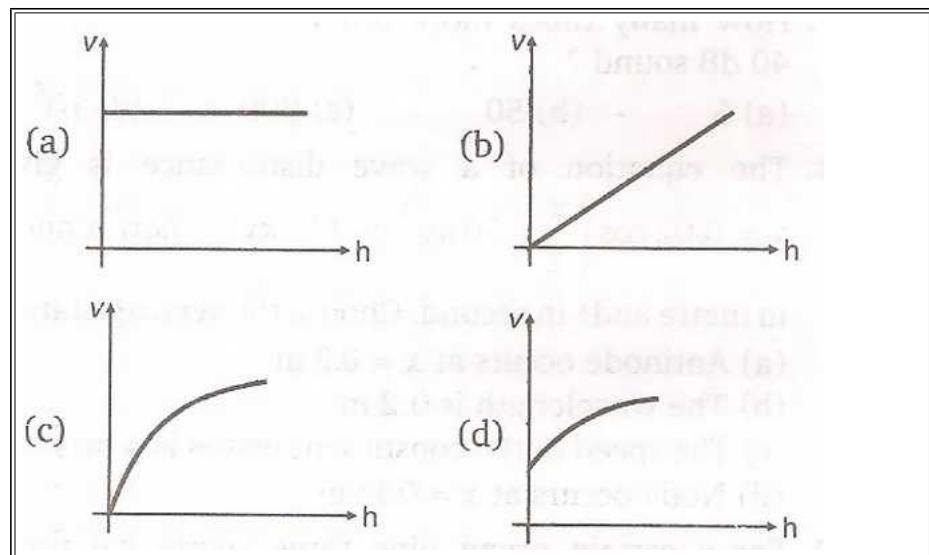


# Chapter 23

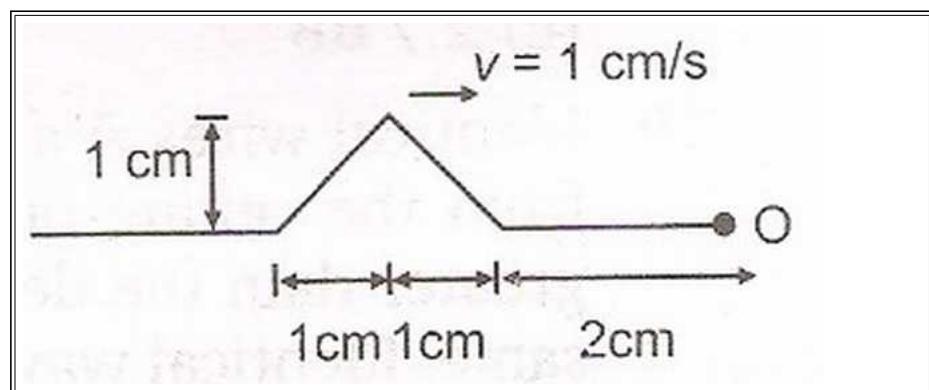
## General Problem Set

### 23.1 Single Answer Questions

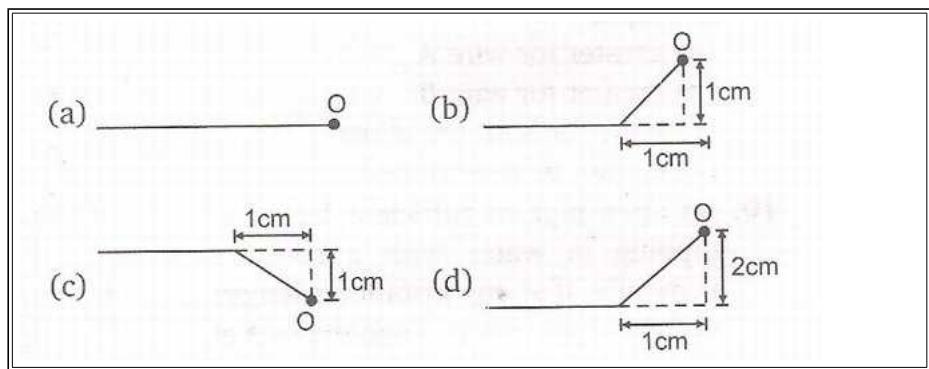
**Example 1:** A uniform rope having mass  $m$  hangs vertically from a rigid support. A transverse wave pulse is produced at the lower end. The speed  $v$  of wave pulse varies with height  $h$  from the lower end as



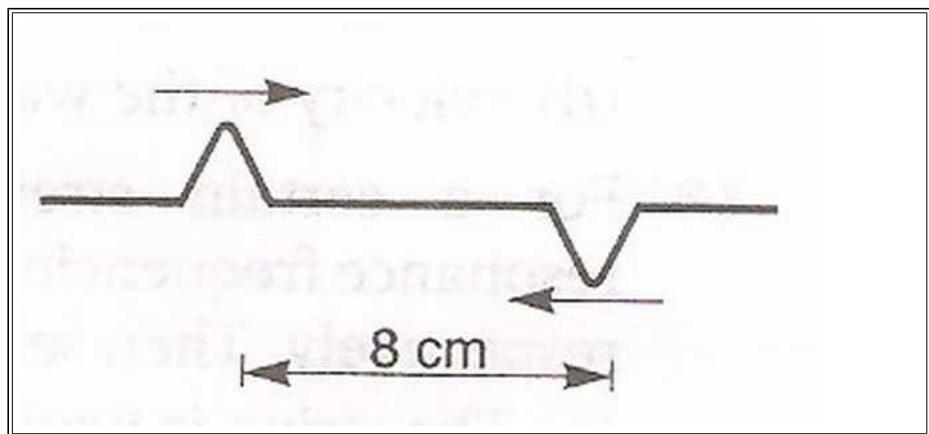
**Example 2:** A wave pulse on a string has the dimension shown in figure. The wave speed is  $v=1 \text{ cm/s}$ . If point O is a free end.



- The shape of wave at time  $t=3\text{s}$  is
- The shape of the wave at time  $t=3\text{s}$  if O is a fixed end will be  
{ Both answers from the image below }



**Example 3 :** Two pulses in a stretched string, whose centres are initially 8 cm apart, are moving towards each other as shown in the figure. The speed of each pulse is 2 cm/s. After 2s the total energy of the pulses will be



- a) zero
- b) purely kinetic
- c) purely potential
- d) partly kinetic and partly potential

## **Part XI**

### **Sound**



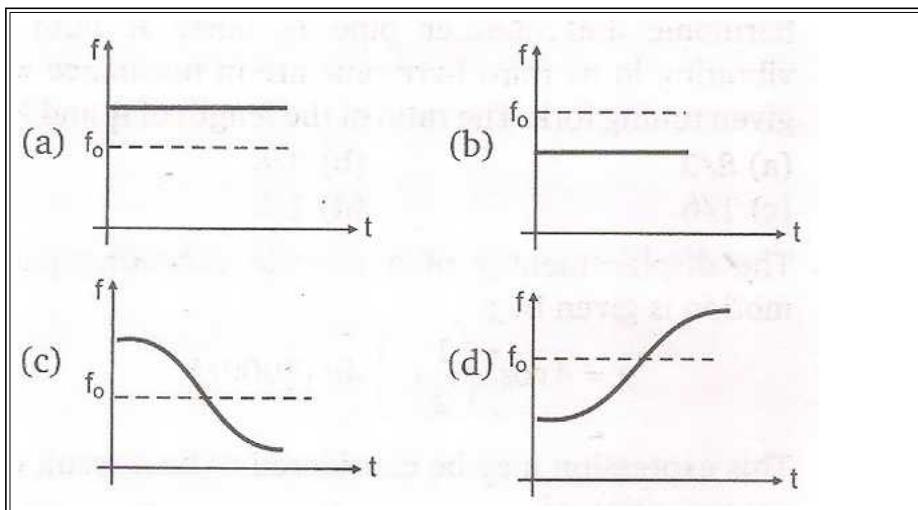
# Chapter 24

## Practice Problems

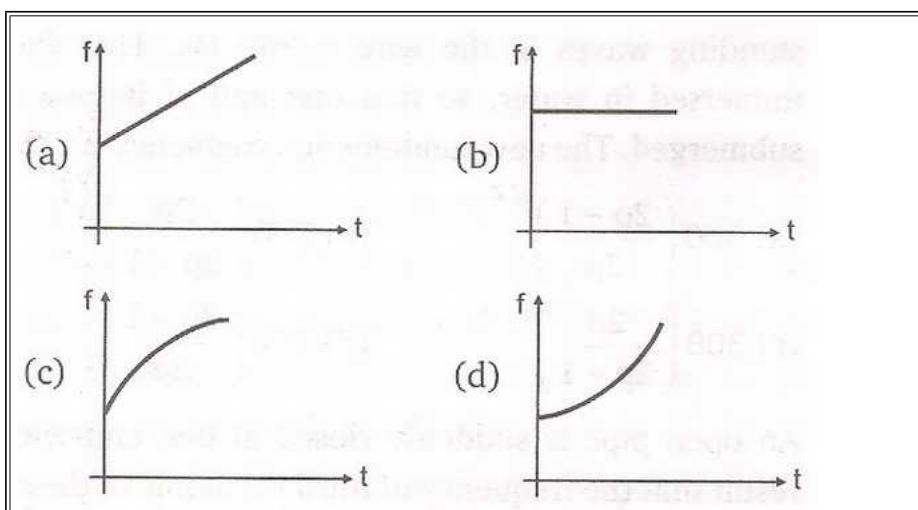
### 24.1 General Problem Set

#### 24.1.1 Single Answer Type

**Example 1 :** Source and observer both start moving simultaneously from origin one along x-axis and the other along y-axis with speed of source = 2 (speed of observer). The graph between the apparent frequency observed by observer ( $f$ ) and time ( $t$ ) would be



**Example 2:** An observer starts moving with uniform acceleration  $a$  towards a stationary sound source of frequency  $f_0$ . As the observer approaches the source, the apparent frequency  $f$  heard by the observer varies with time  $t$  as



### 24.1.2 Multiple Answer Type

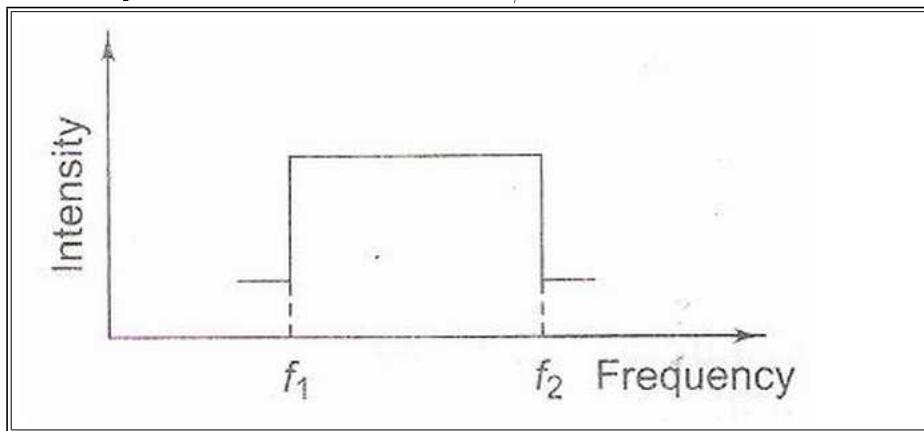
**Example 1 :** A stationary observer receives a sound of frequency  $f_o = 2000$  Hz. Source is moving with constant velocity on a road at some non-zero perpendicular distance from observer. The apparent frequency  $f$  varies with time as shown in figure. Speed of sound = 300 m/s. Choose the correct alternative(s).

- a) Speed of source is 66.7 m/s
- b)  $f_m$  shown in figure cannot be greater than 2500 Hz
- c) Speed of source is 33.33 m/s
- d)  $f_m$  shown in figure cannot be greater than 2250 Hz

## 24.2 Previous Years IIT Problems

### 24.2.1 Passage

Two trains A and B are moving with speed 20 m/s and 30 m/s respectively in the same direction on the same straight track, with B ahead of A. The engines are at the front ends. The engine of train A blows a long whistle. Assume that the sound of the whistle is composed of components varying in frequency from  $f_1 = 800$  Hz to  $f_2 = 1120$  Hz, as shown in the figure. The spread in the frequency (highest frequency-lowest frequency) is thus 320 Hz. The speed of sound in still air is 340 m/s.

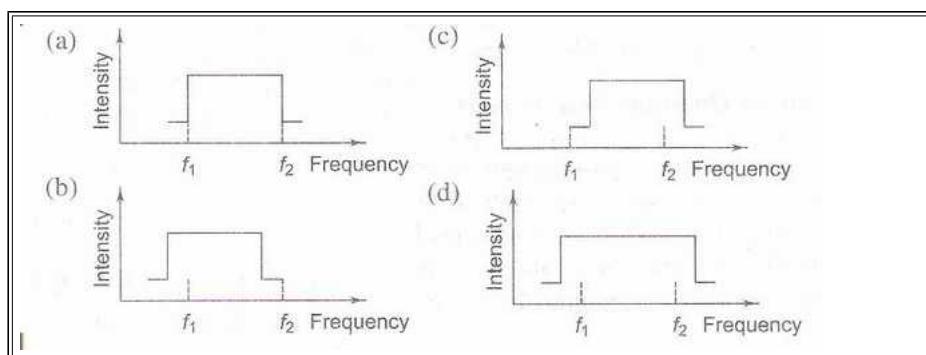


1: The speed of sound of the whistle is

- a) 340 m/s for passengers in A and 310 m/s for passenger in B
- b) 360 m/s for passengers in A and 310 m/s for passenger in B
- c) 310 m/s for passengers in A and 360 m/s for passenger in B
- d) 340 m/s for passengers in both the trains

{ Solution: The speed of sound depends only on the modulus of elasticity and the density of the medium in which it travels. The speed of sound does not depend on the speed of the source of sound or of the observer. Hence the correct option is d) }

2: The distribution of the sound intensity of the whistle as observed by the passengers in train A is best represented by



{ Solution: For train A, there is no relative motion between the source and the passengers. Hence the frequency of sound heard by passengers in train A will be the same as the frequency of sound emitted by the whistle. Therefore, the correct choice is a). }

**3:** The spread of frequency as observed by the passenger in train B is

- a) 310 Hz
- b) 330 Hz
- c) 350 Hz
- d) 290 Hz

{ Solution: The apparent frequency of sound as heard by passengers in train B is given by

$$f' = f_o \left( \frac{v - u_B}{v - u_A} \right)$$

where  $f_o$  = actual frequency,  $v$  = speed of sound,  $u_B$  = speed of train B and  $u_A$  = speed of train A.

$$f' (\text{For } f_o = 800 \text{ Hz}) = 800 \times \left( \frac{340 - 30}{340 - 20} \right) = 775 \text{ Hz}$$

$$f' (\text{For } f_o = 1120 \text{ Hz}) = 1120 \times \left( \frac{340 - 30}{340 - 20} \right) = 1085 \text{ Hz}$$

$\therefore$  Spread of frequency =  $1085 - 775 = 310$  Hz Hence the correct choice is a) }



# Electromagnetism



## **Part XII**

# **Electrostatics**



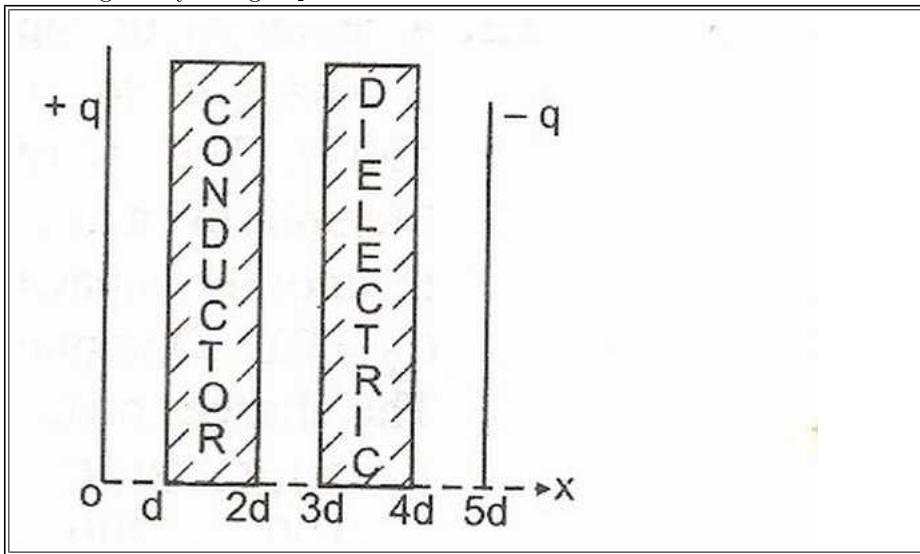
# Chapter 25

## Problems for Practice

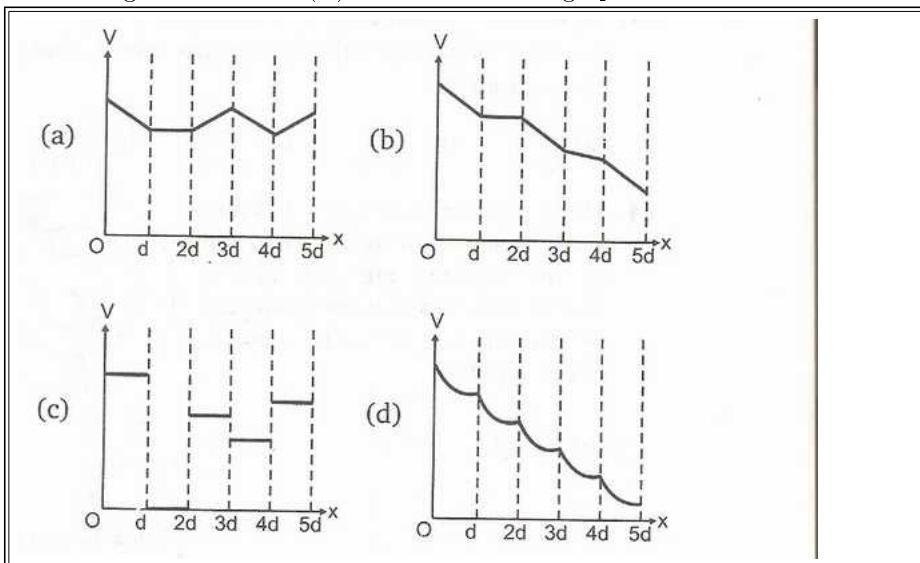
### 25.1 General Problem Set

#### 25.1.1 Single Answer Type

Example : The distance between plates of a parallel plate capacitor is  $5d$ . The positively charged plate is at  $x=0$  and negatively charged plate is at  $x=5d$ .

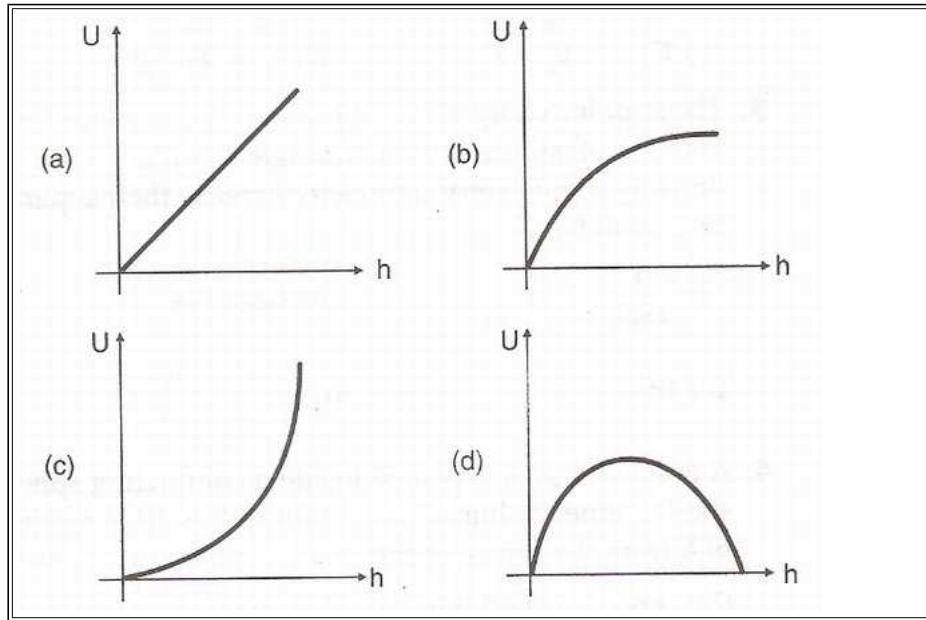


Two slabs one of conductor and the other of a dielectric of same thickness  $d$  are inserted between the plates as shown in figure. Potential ( $V$ ) versus distance  $x$  graph will be

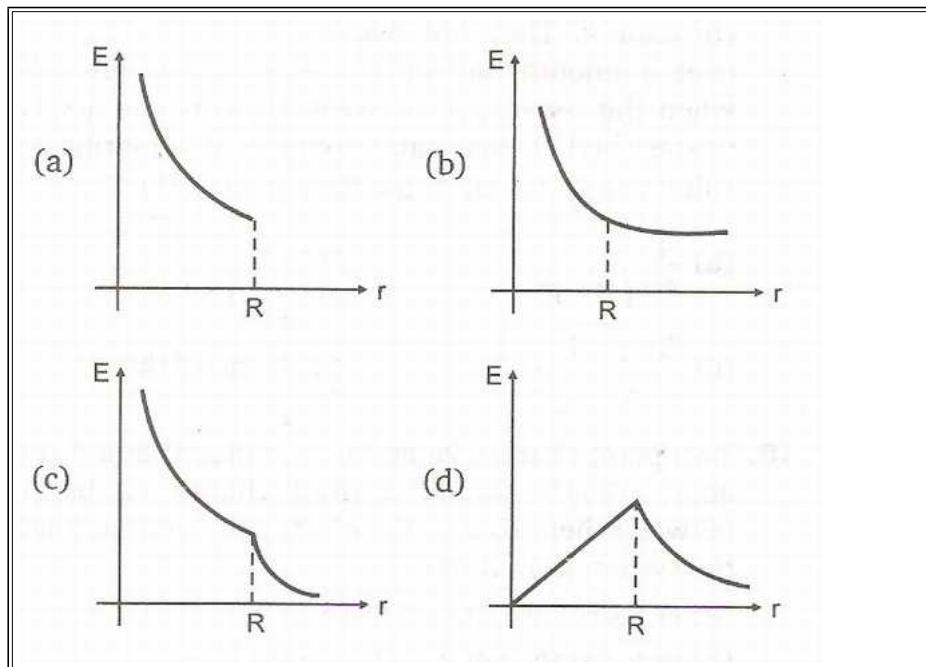


**Example :** A particle of mass  $m$  and charge  $q$  is projected vertically upwards. A uniform electric field  $\vec{E}$  is acted vertically downwards. The most appropriate graph between potential energy  $U$  ( gravitational plus

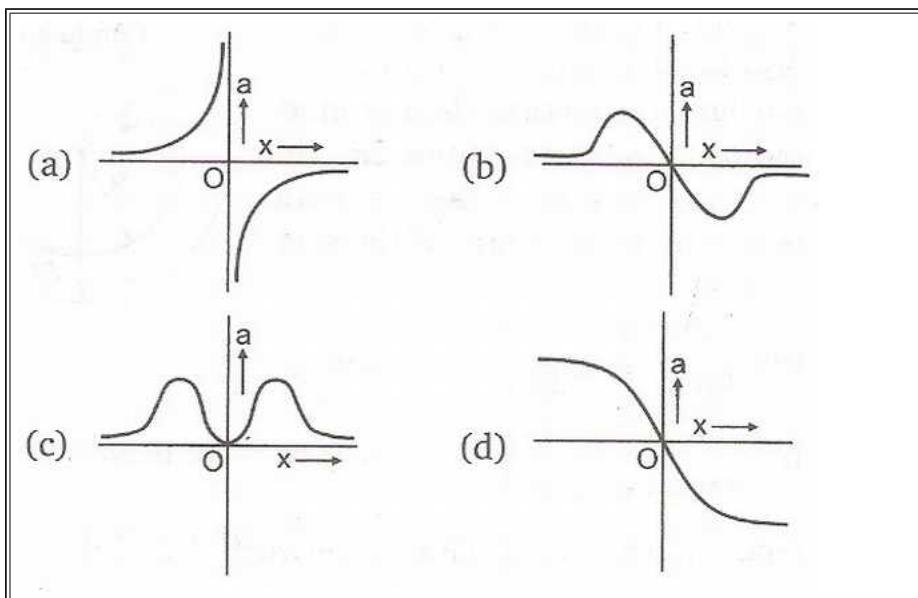
electrostatic) and height  $h$  ( $\ll$  radius of earth) is (assume  $U$  to be zero on surface of earth)



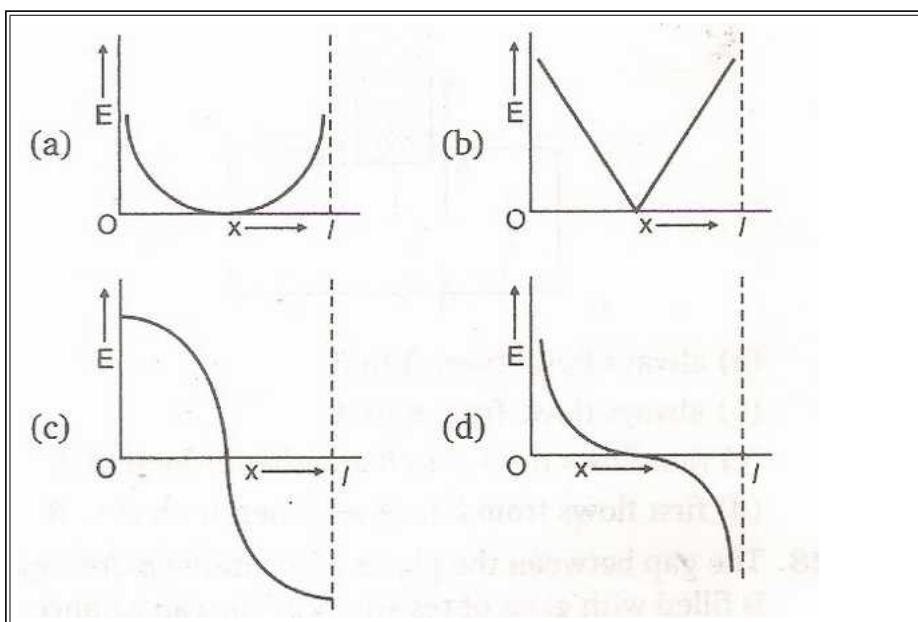
**Example :** A conducting shell of radius  $R$  carries charge  $-Q$ . A point charge  $+Q$  is placed at the centre. The electric field  $E$  varies with distance  $r$  (from the centre of the shell) as



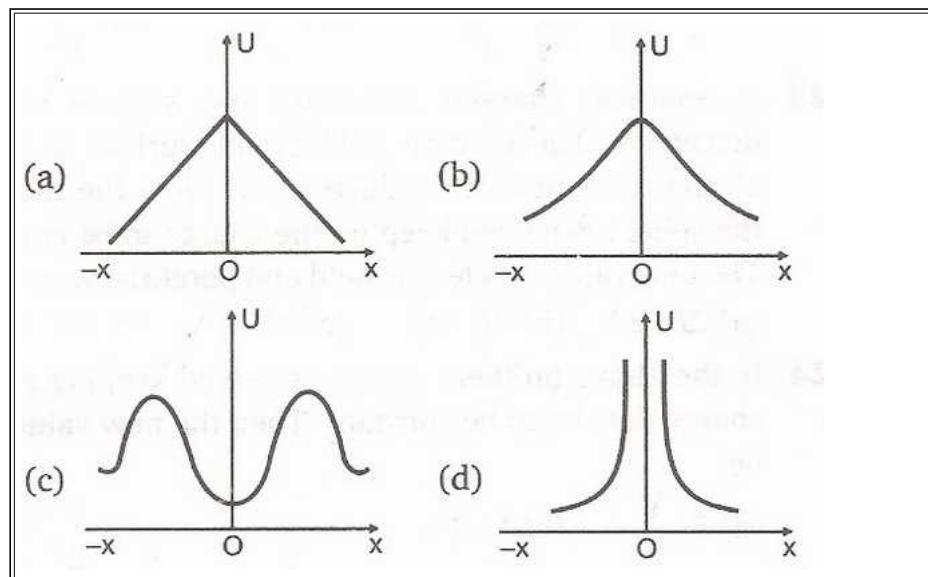
**Example :** Two identical positive charges are fixed on the  $y$ -axis, at equal distances from the origin  $O$ . A particle with a negative charge starts on the negative  $x$ -axis at a large distance from  $O$ , moves along the  $x$ -axis, passed through  $O$  and moves far away from  $O$ . Its acceleration  $a$  is taken as positive along its direction of motion. The particle's acceleration  $a$  is plotted against its  $x$ -coordinate. Which of the following best represents the plot ?



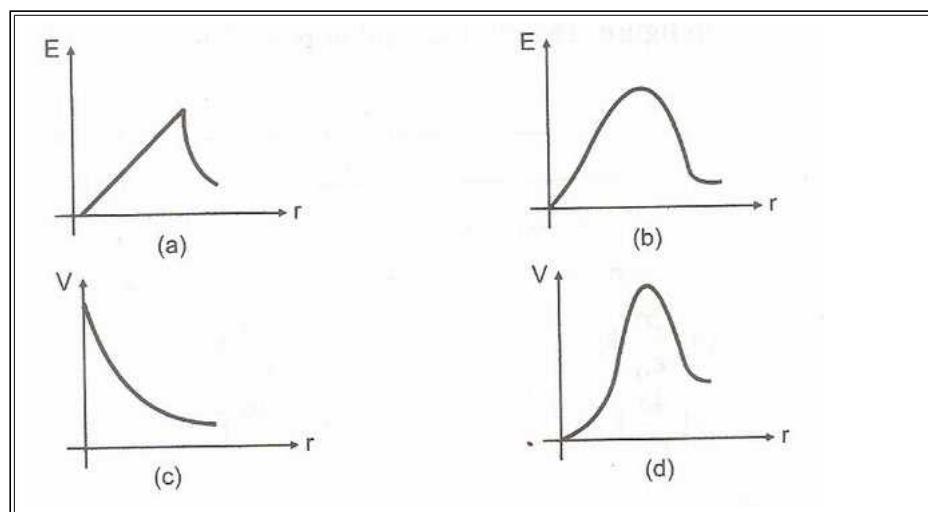
**Example:** Two identical point charges are placed at a separation of  $l$ .  $P$  is a point on the line joining the charges, at a distance  $x$  from any one charge. The field at  $P$  is  $E$ .  $E$  is plotted against  $x$  for values of  $x$  from close to zero to slightly less than  $l$ . Which of the following best represents the resulting curve?



**Example :** Four equal charges of magnitude  $q$  each are placed at four corners of a square with its centre at origin and lying in  $y$ - $z$  plane. A fifth charge  $+Q$  is moved along  $x$ -axis. The electrostatic potential energy ( $U$ ) varies on  $x$ -axis as



**Example :** A circular ring carries a uniformly distributed positive charge. The electric field ( $E$ ) and potential ( $V$ ) varies with distance ( $r$ ) from the centre of the ring along its axis as



## **Part XIII**

# **Current Electricity**



# Chapter 26

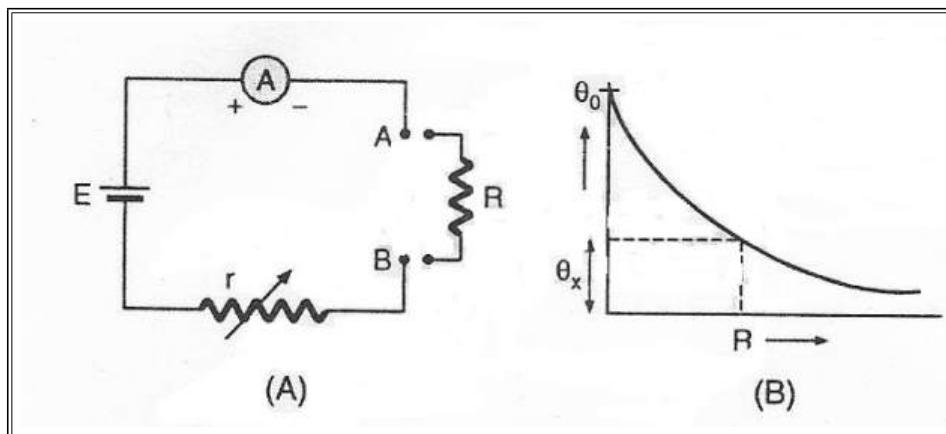
## Basics

### 26.1 Theory

#### 26.1.1 Ohm-meter

It is an instrument designed to measure resistance. It contains an Ammeter, a Battery and a Rheostat as shown in Figure. The terminals A and B are first short circuited and the Rheostat is adjusted to show full deflection on Ammeter. The full scale deflection corresponds to zero external resistance.

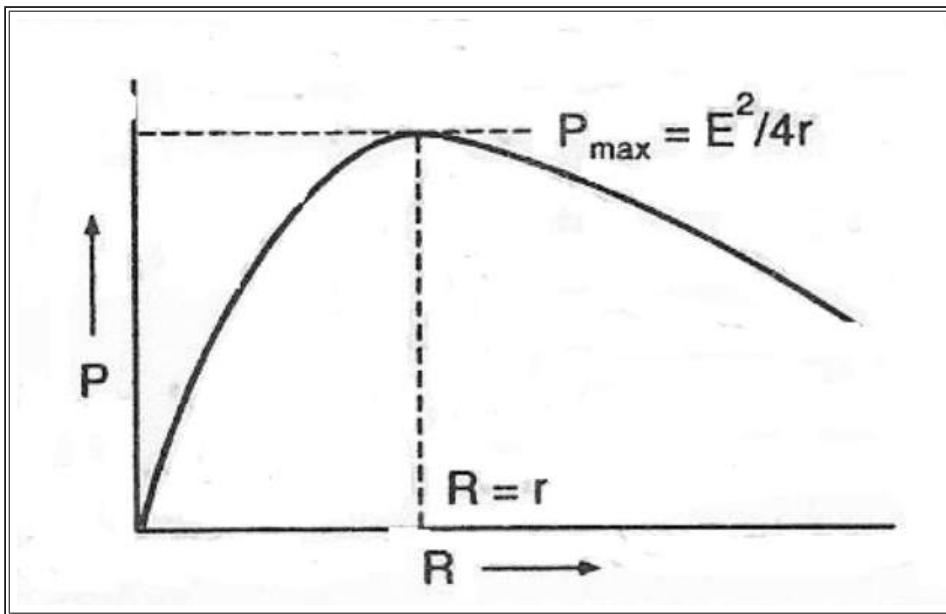
Now, connecting a resistance box between points A and B, ammeter deflection  $\theta$  is noted for different values of R and a graph is plotted between  $\theta$  and R. The graph is called Calibration Curve and is shown in Figure. Now the resistance box is removed and an unknown resistance is connected to the circuit. The deflection is noted down and from the calibration curve, the value of R is found out.



#### 26.1.2 Power Transfer to a load

The power transfer to the load by the cell will be  $P = I^2R = \frac{E^2R}{(R+r)^2}$

From the equation, it is clear that Power would be zero, if  $R=0$  or  $\infty$  and gives the minima.



$\frac{dP}{dR} = 0$  i.e.  $\frac{d}{dR} \left[ \frac{E^2 R}{(R+r)^2} \right] = 0$  will give any other local maxima / local minima

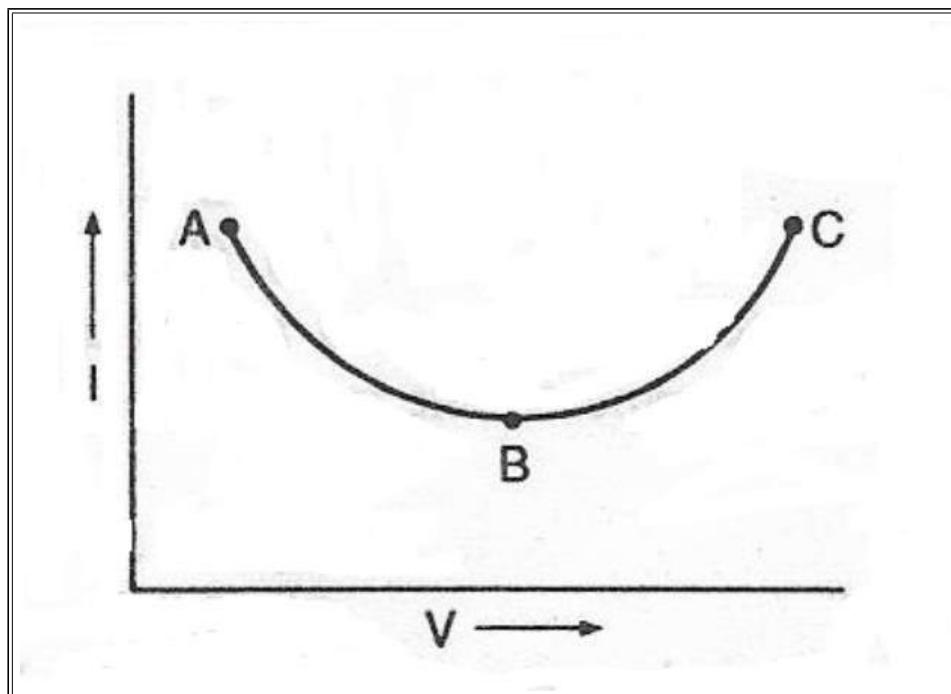
It is zero at  $R=r$  which gives a maxima

i.e. power transfer to the load by a cell is maximum when  $R=r$  and  $P_{max} = \frac{E^2}{4r}$

## 26.2 Problems

### 26.2.1 Objective Type Questions

**Example:** Resistance as shown in Figure is negative at

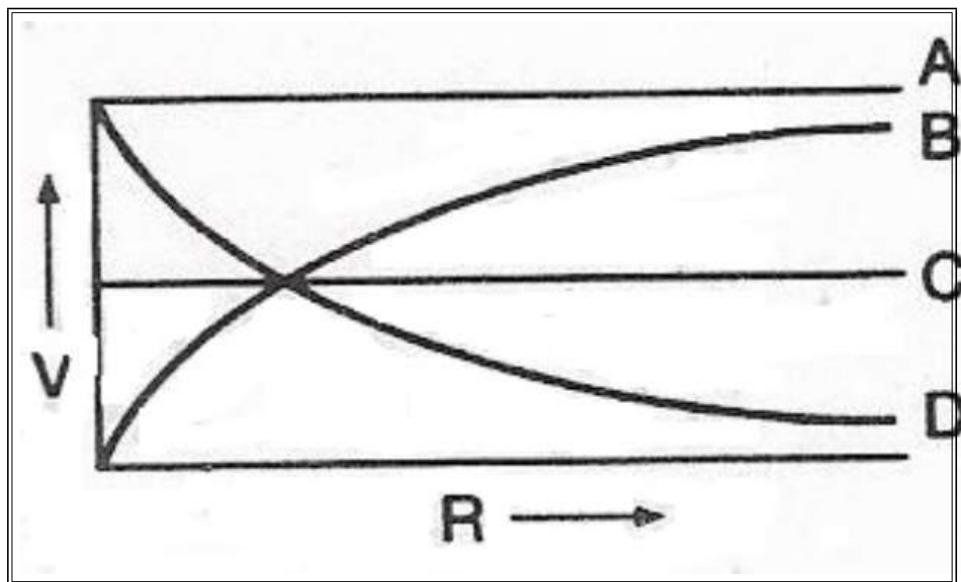


- a) A
- b) B
- c) C
- d) None of these

{Hint: The resistance is given by  $V/I$  and NOT  $dV/dI$ .  $V$  and  $I$  are shown positive, so  $R$  (their ratio) is also +ve.

d) is the correct answer. }

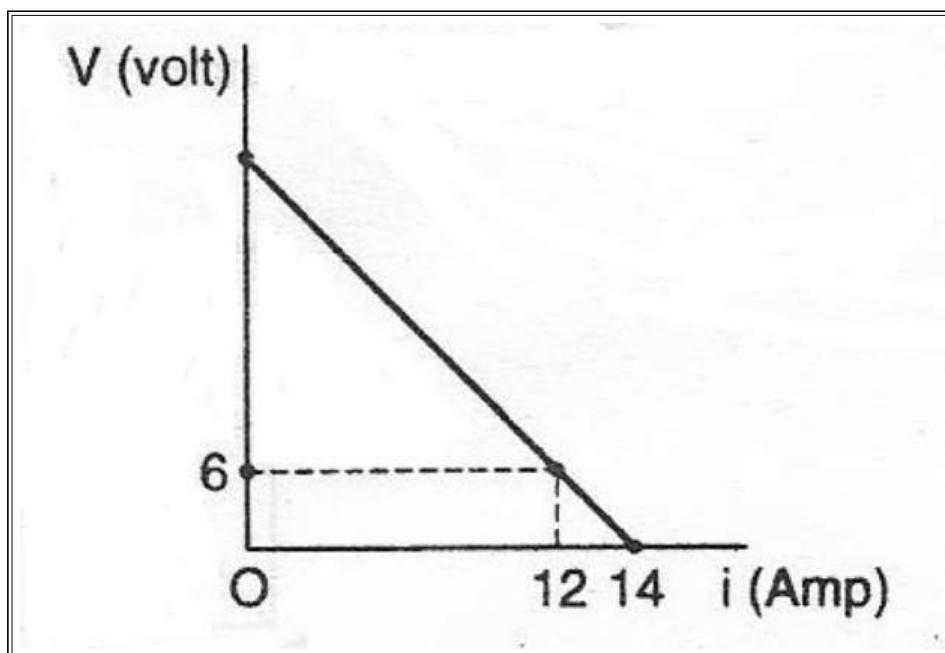
**Example:** A cell of EMF E having an Internal Resistance  $r$  is connected to an External Resistance  $R$ . The potential difference  $V$  across the resistance  $R$  varies with  $R$  as the curve :



- a) A
- b) B
- c) C
- d) D

{ Hint:  $V = ER/(r+R)$ , So, B is the required curve as of  $y = xc'/(x+c'')$  }

**Example:** 10 cells , each of EMF  $E$  and internal resistance  $r$  are connected in series to a variable external resistance. Figure shows the variation of terminal potential difference with the current drawn from the combination. EMF of each cell is :



- a) 1.6 V
- b) 3.6 V
- c) 1.4 V
- d) 4.2 V

{Hint : The equation of the line is  $V/42 + i/14 = 1$

Also,  $V = 10ER/10r+R$

$$\text{So, } 10ER/42(10r+R) + i/14 = 1$$

$$10ER + 3i(10r+R) = 42(10r+R)$$

As R is Variable, setting R as infinity

$$10E + 3i = 42$$

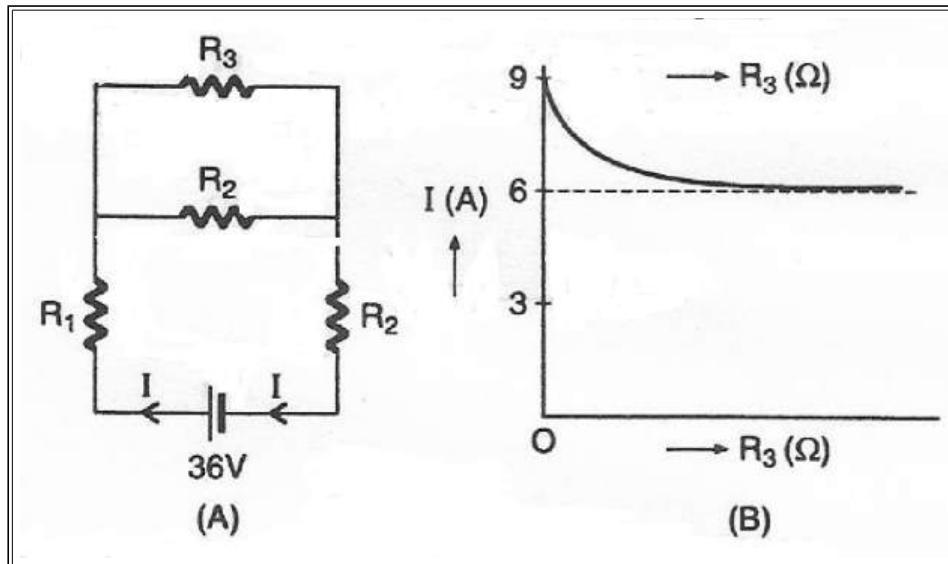
$$E = (42 - 3i) / 10 = 4.2 - 0.3i$$

Also at R infinity i would be zero as it is a series connected circuit

$$\text{So, } E = 4.2 \text{ V}$$

d) is the correct answer }

**Example:** In the circuit shown in figure,  $R_3$  is a variable resistance. As the value of  $R_3$  is changed, current I through the cell varies as shown. Obviously, the variation is asymptotic, i.e.  $I \rightarrow 6\text{A}$  as  $R_3 \rightarrow \infty$ . Resistance  $R_1$  and  $R_2$  are respectively, :



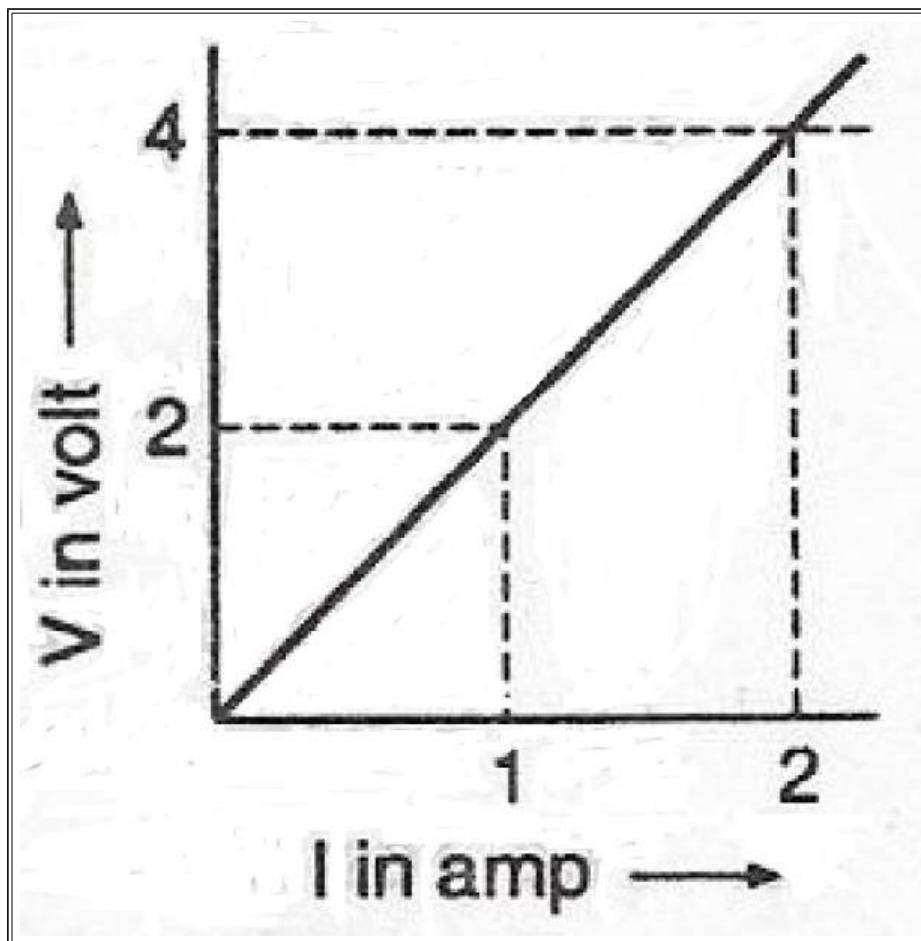
a)  $4\Omega, 2\Omega$

b)  $2\Omega, 4\Omega$

c)  $2\Omega, 2\Omega$

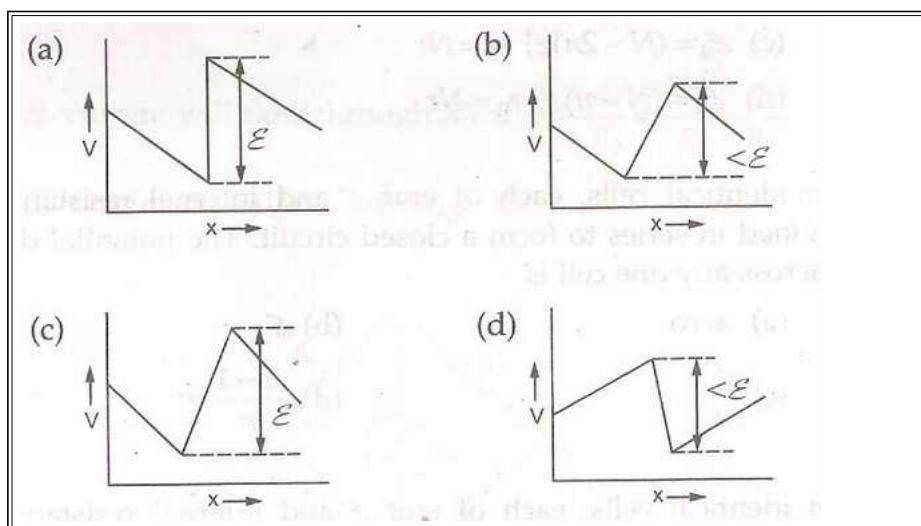
d)  $1\Omega, 4\Omega$

**Example:** The variation of current with potential difference is as shown in Figure. The resistance of the conductor is :



- a)  $1\Omega$
- b)  $2\Omega$
- c)  $3\Omega$
- d)  $4\Omega$

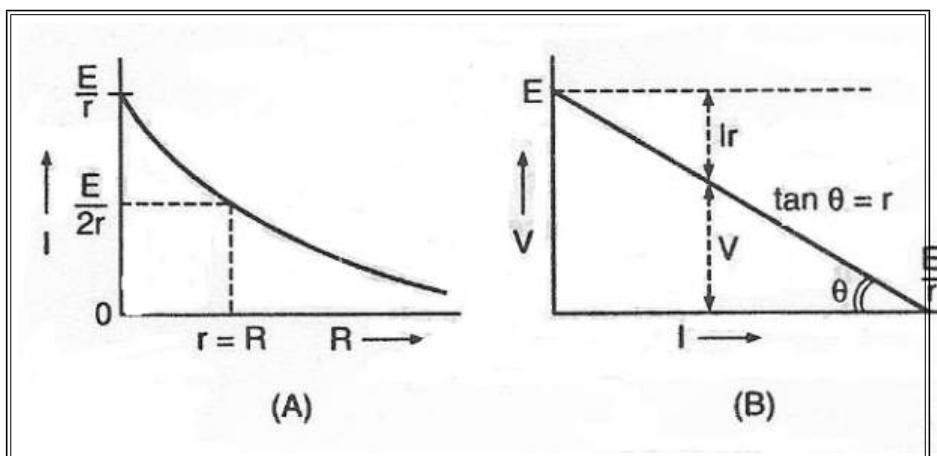
**Example :** The two ends of a uniform conductor are joined to a cell of emf  $E$  and some internal resistance. Starting from the midpoint P of the conductor, we move in the direction of the current and return to P. The potential  $V$  at every point on the path is plotted against the distance covered ( $x$ ). Which of the following best represents the resulting curve?



### 26.2.2 Subjective

**Example:** Draw a)  $I$  vs  $R$  b)  $V$  vs  $I$ , characteristics for a cell.

{ Hint: For a cell, as  $I = E/(R+r)$  and  $V = E - Ir$ ,

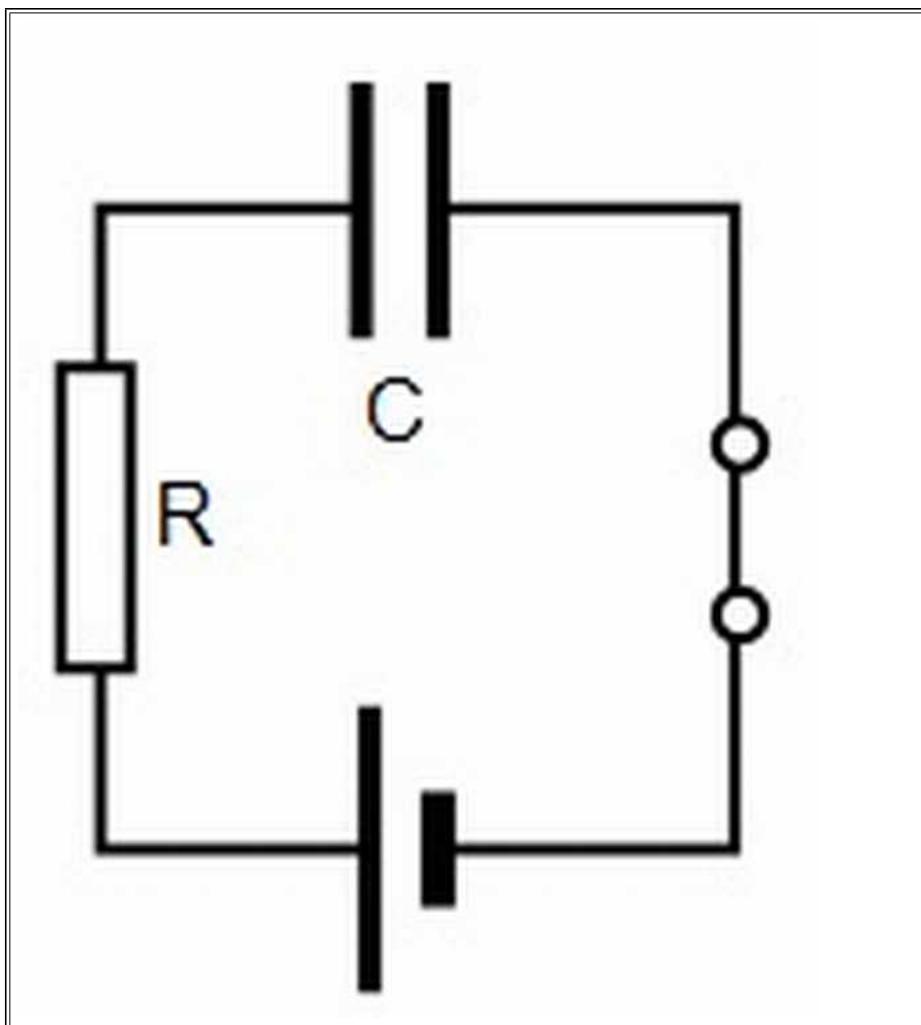


}

# Chapter 27

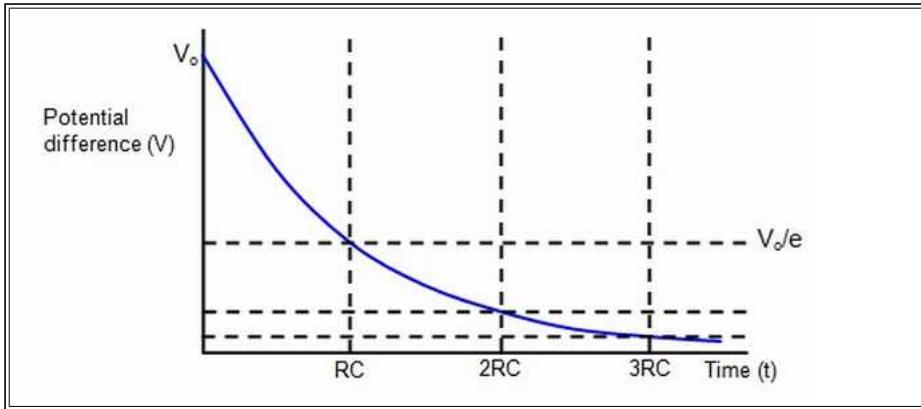
## Capacitors

Mathematical treatment of charging and discharging a capacitor n.d.



### 27.1 Discharge of a capacitor

The area under the current-time discharge graph gives the charge held by the capacitor. The gradient of the charge-time graph gives the current flowing from the capacitor at that moment.



In Figure let the charge on a capacitor of capacitance C at any instant be  $q$ , and let  $V$  be the potential difference across it at that instant.

The current ( $I$ ) in the discharge at that instant is therefore:  $I = -dq/dt$

But  $V = IR$  and  $q = CV$  so  $dq/dt = d(CV)/dt = C dV/dt$ . Therefore we have  $V = -CR dV/dt$ . Rearranging and integrating gives:

$$\text{Capacitor discharge (voltage decay): } V = V_o e^{-(t/RC)}$$

where  $V_o$  is the initial voltage applied to the capacitor. A graph of this exponential discharge is shown below in Figure

Since  $Q = CV$  the equation for the charge ( $Q$ ) on the capacitor after a time  $t$  is therefore:

$$\text{Capacitor discharge (charge decay): } Q = Q_o e^{-(t/RC)}$$

$$V = V_o e^{-(t/RC)} \text{ and also } I = I_o e^{-(t/RC)} \quad Q = Q_o e^{-(t/RC)}$$

You should realise that the term  $RC$  governs the rate at which the charge on the capacitor decays.

When  $t = RC$ ,  $V = V_o/e = 0.37 V_o$  and the product  $RC$  is known as the time constant for the circuit. The bigger the value of  $RC$  the slower the rate at which the capacitor discharges.

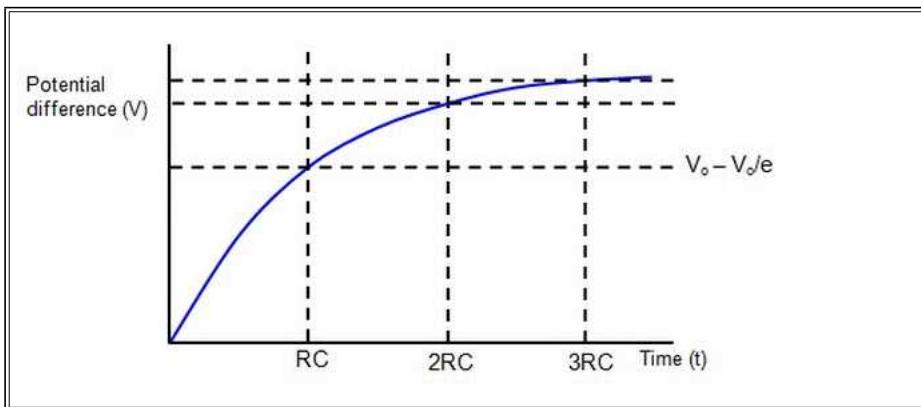
The value of  $C$  can be found from this discharge curve if  $R$  is known.

## 27.2 Charging a capacitor

When a capacitor ( $C$ ) is being charged through a resistance ( $R$ ) to a final potential  $V_o$  the equation giving the voltage ( $V$ ) across the capacitor at any time  $t$  is given by:

$$\text{Capacitor charging (potential difference): } V = V_o [1 - e^{-(t/RC)}]$$

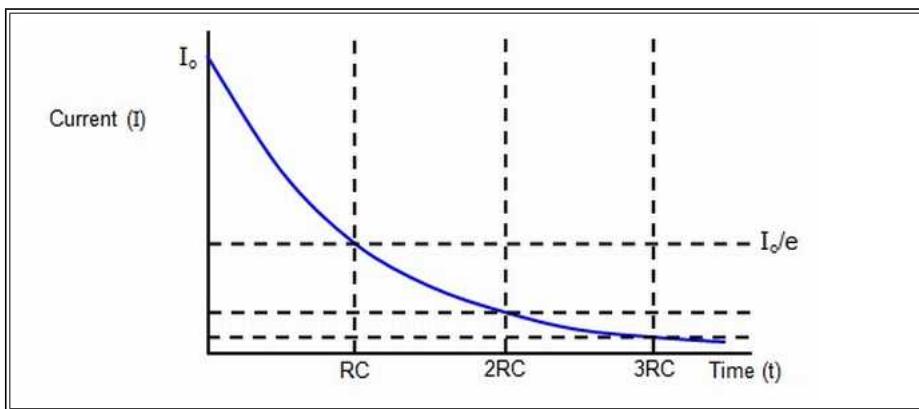
and the variation of potential with time is shown in Figure



As the capacitor charges the charging current decreases since the potential across the resistance decreases as the potential across the capacitor increases.

Figure shows how both the potential difference across the capacitor and the charge on the plates vary with time during charging.

The charging current would be given by the gradient of the curve in Figure at any time and the graph of charging current against time is shown in next Figure.



The area below the current-time curve in both charging and discharging represents the total charge held by the capacitor.



# Bibliography

(N.d.). URL: [http://www.schoolphysics.co.uk/age16-19/Electricity%20and%20magnetism/Electrostatics/text/Capacitor\\_charge\\_and\\_discharge\\_mathematics/index.html](http://www.schoolphysics.co.uk/age16-19/Electricity%20and%20magnetism/Electrostatics/text/Capacitor_charge_and_discharge_mathematics/index.html).



# **Part XIV**

## **Magnetic Field**

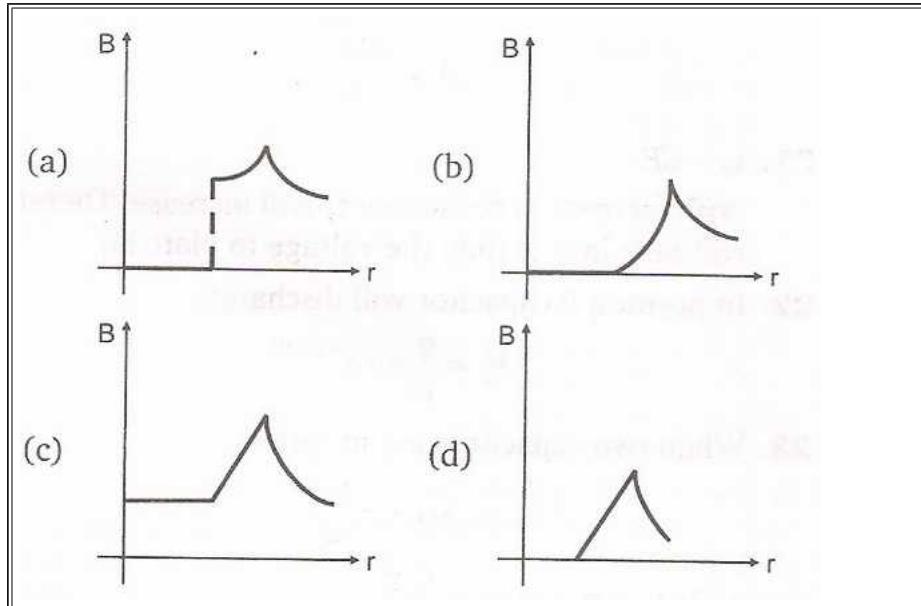


# Chapter 28

## Problems for Practice

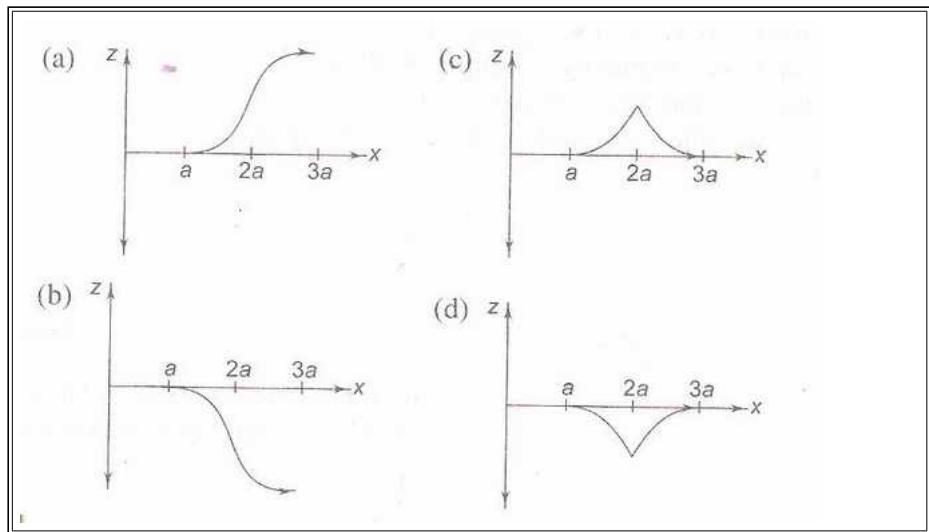
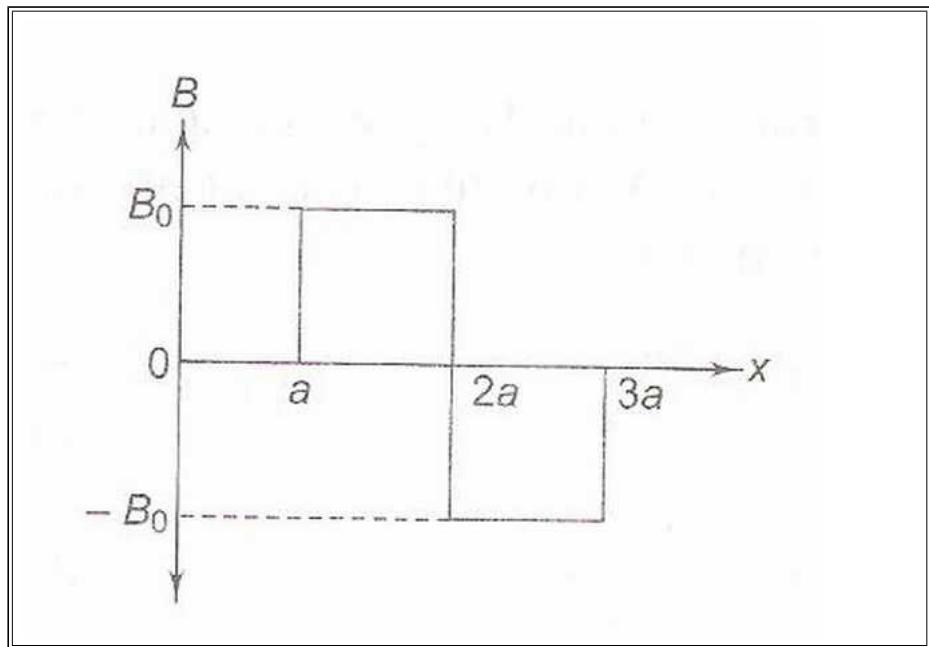
### 28.1 General Problem Set

**Example :** A current  $i$  is uniformly distributed over the cross section of a long hollow cylindrical wire of inner radius  $R_1$  and outer radius  $R_2$ . Magnetic field  $B$  varies with distance  $r$  from the axis of the cylinder as



### 28.2 IIT Previous Years Problems

**Example:** A magnetic field  $\vec{B} = B_o \hat{j}$  exists in the region  $a < x < 2a$  and  $\vec{B} = -B_o \hat{j}$  in the region  $2a < x < 3a$  where  $B_o$  is a positive constant. A positive point charge moving with a velocity  $\vec{v} = v_o \hat{i}$ , where  $v_o$  is a positive constant, enters the magnetic field at  $x=a$ . The trajectory of the charge in this region can be like



**Solution:** Force experienced by the charge  $q$  is given by

$$\vec{F} = q(\vec{v} \times \vec{B})$$

In the region from  $x=a$  to  $x=2a$ , the force is  $\vec{F}_1 = q(v_o \hat{i} \times B_o \hat{j}) = qv_o B_o \hat{k}$  directed along the positive  $z$ -axis.

In the region from  $x=a$  to  $x=2a$  to  $x=3a$ , the force is

$$\vec{F}_2 = q(v_o \hat{i} \times (-B_o) \hat{j}) = -qv_o B_o \hat{k}$$

directed along the negative  $z$ -axis.

Since force  $\vec{F}_1$  and  $\vec{F}_2$  are perpendicular to velocity  $\vec{v}$ , the correct trajectory is as shown in option a).

# Matter



## **Part XV**

### **Lattice**



# Chapter 29

## Experiments

### 29.1 Photoelectric Effect

#### 29.1.1 An Experiment n.d.

Aim:

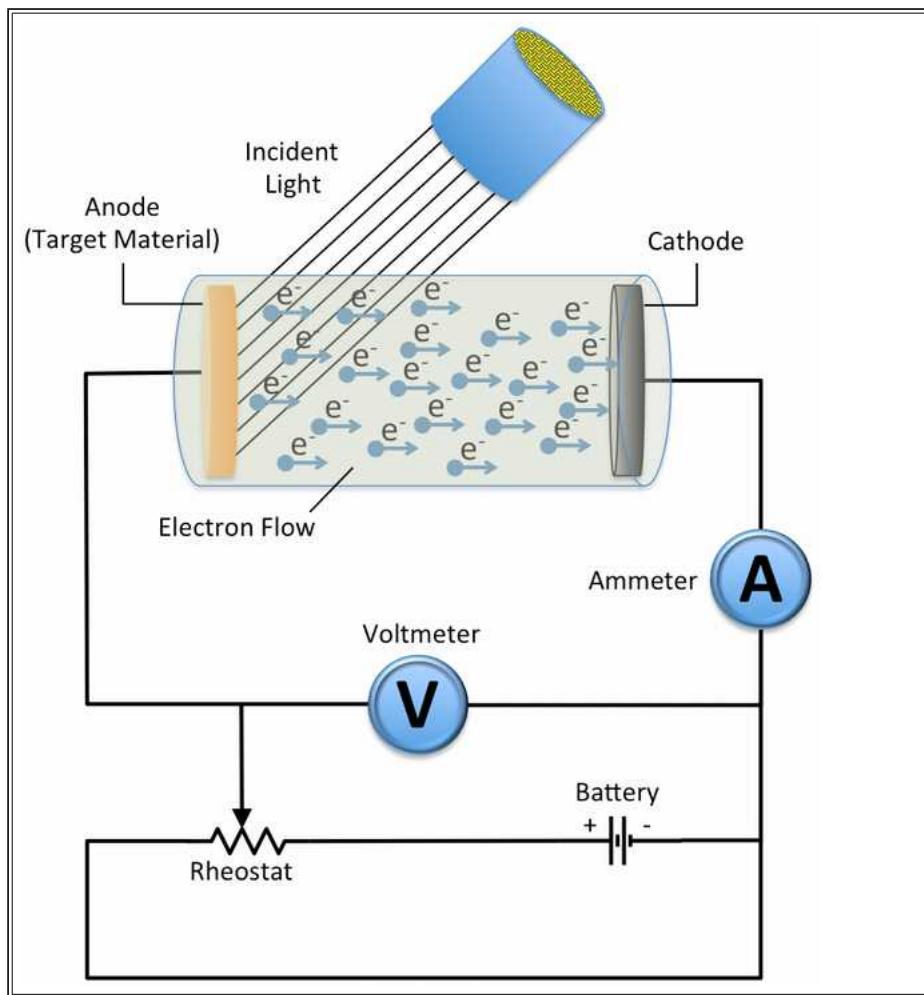
1. To understand the phenomenon Photoelectric effect as a whole.
2. To draw kinetic energy of photoelectrons as a function of frequency of incident radiation.
3. To determine the Planck's constant from kinetic energy versus frequency graph.
4. To plot a graph connecting photocurrent and applied potential.
5. To determine the stopping potential from the photocurrent versus applied potential graph.

Theory:

During his experiments on electromagnetic radiation (to demonstrate light consists of e-m waves), Hertz noticed a spark between the two metallic balls when a high frequency radiation incident on it. This is called photoelectric effect. Photoelectric effect is the emission of electrons when electromagnetic radiations having sufficient frequency incident on certain metal surfaces. We call the emitted electrons as photoelectrons and the current they constitute as photocurrent. The phenomenon was first observed by Heinrich Hertz in 1880 and explained by Albert Einstein in 1905 using Max Planck's quantum theory of light. As the first experiment which demonstrated the quantum theory of energy levels, photoelectric effect experiment is of great historical importance.

The important observations on Photoelectric effect which demand quantum theory for its explanation are:

1. The Photoelectric effect is an instantaneous phenomenon. There is no time delay between the incidence of light and emission of photoelectrons.
2. The number of photoelectrons emitted is proportional to the intensity of incident light. Also, the energy of emitted photoelectrons is independent of the intensity of incident light.
3. The energy of emitted photoelectrons is directly proportional to the frequency of incident light. The basic experimental set up which explains Photoelectric effect is as given below,



It has been observed that there must be a minimum energy needed for electrons to escape from a particular metal surface and is called work function ' $W$ ' for that metal. The work function can be expressed in terms of frequency as,

$$W = h\nu_o \dots \dots \dots \quad (1)$$

Where  $h$  is the Planck's constant and

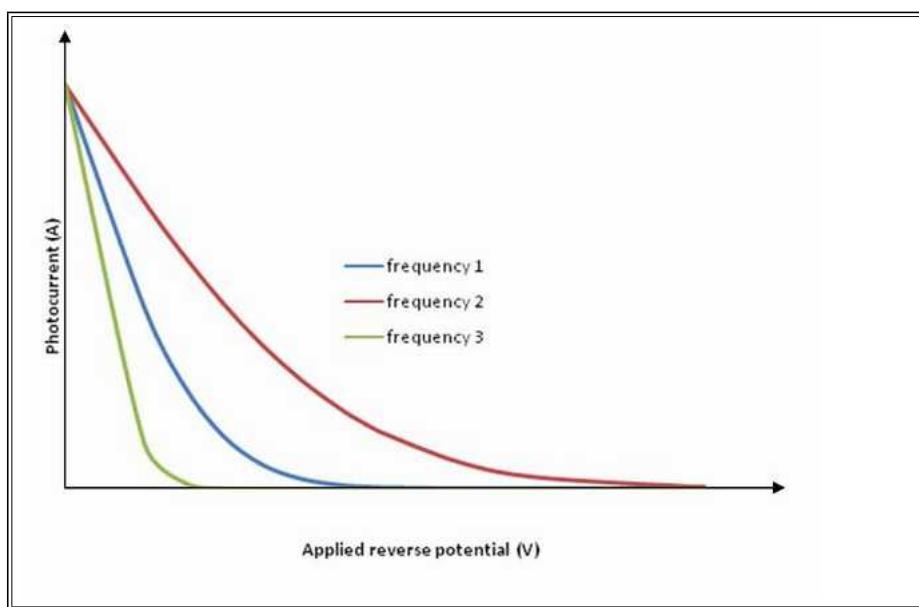
$\nu_o$  is the threshold frequency (minimum frequency for photoelectric effect).

29.1.1.1 The work function for some metals are listed in the table.

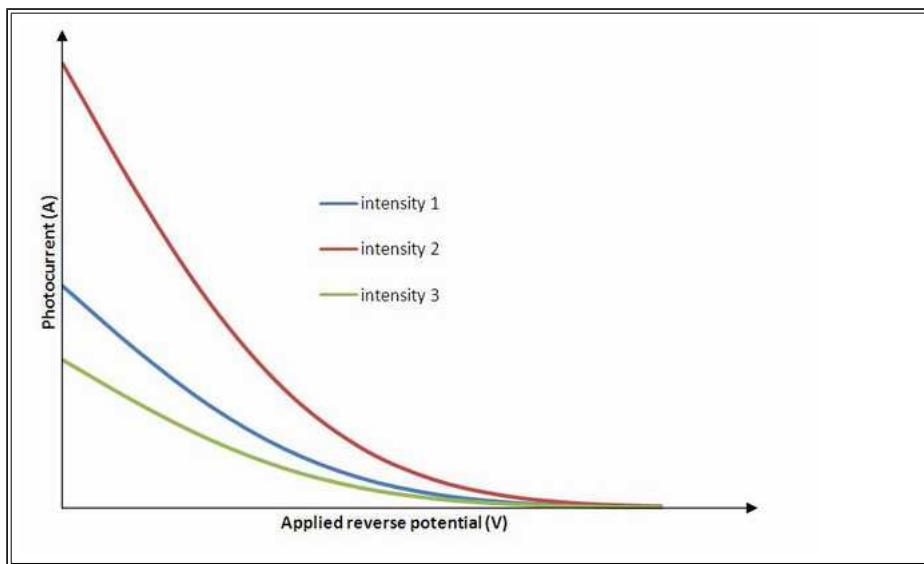
Metal	Work function (eV)
Platinum(Pt)	6.4
Silver(Ag)	4.7
Sodium(Na)	2.3
Potassium(K)	2.2
Cesium(Cs)	1.9

29.1.1.2 Graph connecting photocurrent and applied reverse potential :

For constant intensity and different frequencies



For constant frequency and different intensities



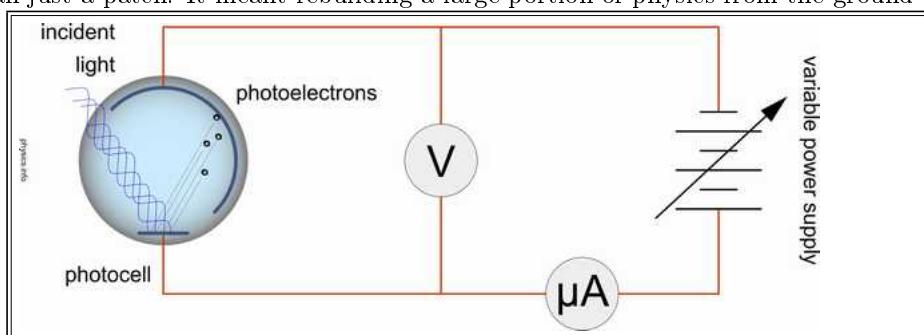
### 29.1.2 Original Einstein Experiment n.d.

#### 29.1.2.1 Discussion

**dilemma** Under the right circumstances light can be used to push electrons, freeing them from the surface of a solid. This process is called the photoelectric effect (or photoelectric emission or photoemission), a material that can exhibit this phenomena is said to be photoemissive, and the ejected electrons are called photoelectrons; but there is nothing that would distinguish them from other electrons. All electrons are identical to one another in mass, charge, spin, and magnetic moment.

The photoelectric effect was first observed in 1887 by Heinrich Hertz (1857–1894) during experiments with a spark-gap generator (the earliest form of radio receiver). In these experiments, a spark is generated between two small metal spheres in the transmitter to induce a similar spark to jump between two different metal spheres in the receiver. Compared to later radio devices, the spark-gap generator was notoriously difficult to work with. The air gap would often have to be smaller than a millimeter for a receiver to consistently reproduce the spark of the transmitter. Hertz found that he could increase the sensitivity of his spark-gap device by illuminating it with visible or ultraviolet light. Later studies by J.J. Thomson (1856–1940) showed that this increased sensitivity was the result of light pushing on electrons (which he discovered in 1897).

While this is interesting, it is hardly amazing. All forms of electromagnetic radiation transport energy and it is quite easy to imagine this energy being used to push tiny particles of negative charge free from the surface of a metal where they are not all that strongly confined in the first place. The era of modern physics is one of completely unexpected and inexplicable discoveries, however. Subsequent investigations into the photoelectric effect yielded results that did not fit with the classical theory of electromagnetic radiation. When it interacted with electrons, light just didn't behave like it was supposed to. Repairing this tear in theory required more than just a patch. It meant rebuilding a large portion of physics from the ground up.



It was Philipp Lenard (1862–1947), an assistant of Hertz, who performed the earliest, definitive studies of the photoelectric effect. Lenard used metal surfaces that were first cleaned and then held under a vacuum so that the effect might be studied on the metal alone and not be affected by any surface contaminants or oxidation. The metal sample was housed in an evacuated glass tube with a second metal plate mounted at the opposite end. The tube was then positioned or constrained in some manner so that light would only shine on the first metal plate — the one made out of photoemissive material under investigation. Such a tube is called a photocell (formally) or an electric eye (informally). Lenard connected his photocell to a circuit with a variable power supply, voltmeter, and microammeter as shown in the schematic diagram above. He then illuminated the photoemissive surface with light of differing frequencies and intensities.

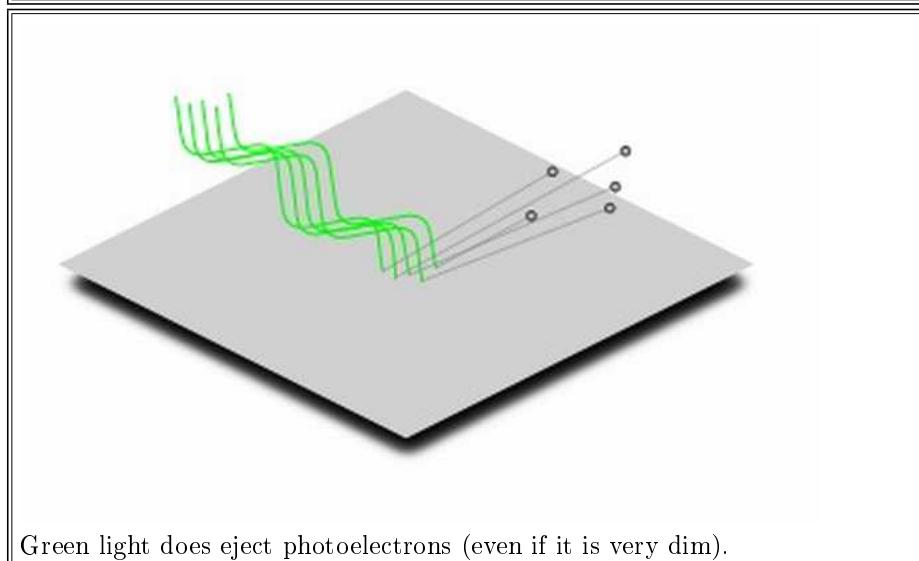
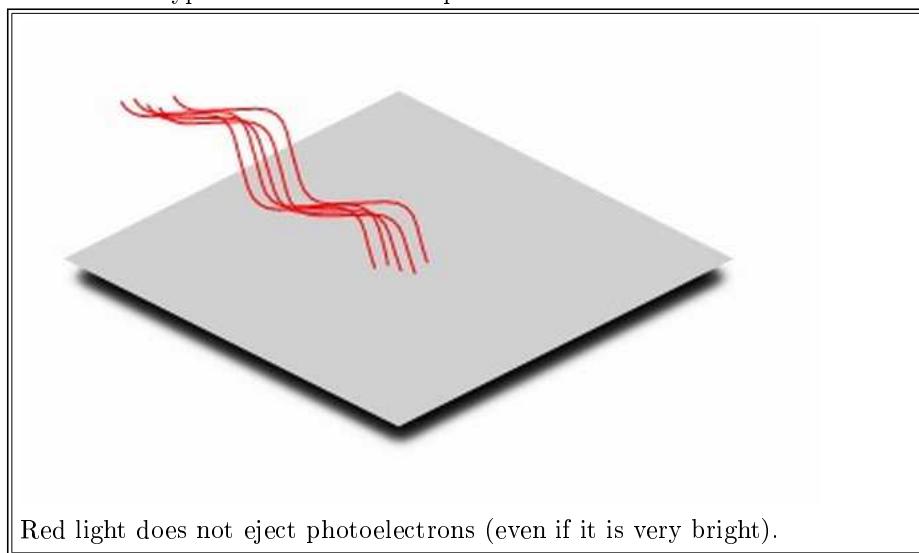
Knocking electrons free from the photoemissive plate would give it a slight positive charge. Since the second plate was connected to the first by the wiring of the circuit, it too would become positive, which would then attract the photoelectrons floating freely through the vacuum where they would land and return back to the plate from which they started. Keep in mind that this experiment doesn't create electrons out of light, it just uses the energy of the light to push electrons that are already there around the circuit. The photoelectric current generated by this means was quite small, but could be measured with the microammeter (a sensitive galvanometer with a maximum deflection of only a few microamps). It also serves as a measure of the rate at which photoelectrons are leaving the surface of the photoemissive material.

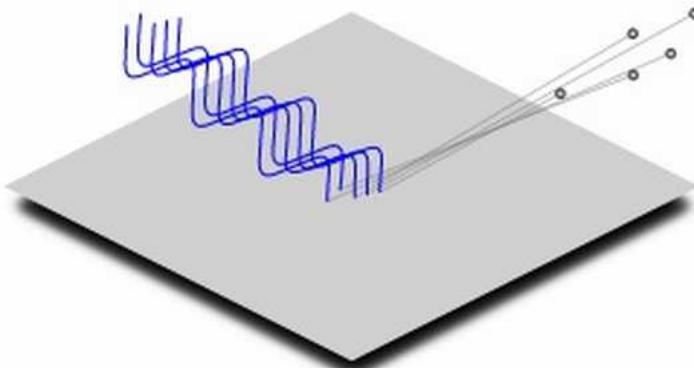
Note how the power supply is wired into the circuit — with its negative end connected to the plate that isn't illuminated. This sets up a potential difference that tries to push the photoelectrons back into the photoemissive surface. When the power supply is set to a low voltage it traps the least energetic electrons, reducing the current through the microammeter. Increasing the voltage drives increasingly more energetic electrons back until finally none of them are able to leave the metal surface and the microammeter reads zero. The potential at which this occurs is called the stopping potential. It is a measure of the maximum kinetic energy of the electrons emitted as a result of the photoelectric effect.

What Lenard found was that the intensity of the incident light had no effect on the maximum kinetic energy of the photoelectrons. Those ejected from exposure to a very bright light had the same energy as those ejected from exposure to a very dim light of the same frequency. In keeping with the law of conservation of energy, however, more electrons were ejected by a bright source than a dim source.

Later experiments by others, most notably the American physicist Robert Millikan (1865–1953), found that light with frequencies below a certain cutoff value, called the threshold frequency, would not eject photoelectrons from the metal surface no matter how bright the source. These results were completely unexpected. Given that it is possible to move electrons with light and given that the energy in a beam of light is related to its intensity, classical physics would predict that a more intense beam of light would eject electrons with greater energy than a less intense beam no matter what the frequency. This was not the case, however.

#### Results of a Typical Photoelectric Experiment





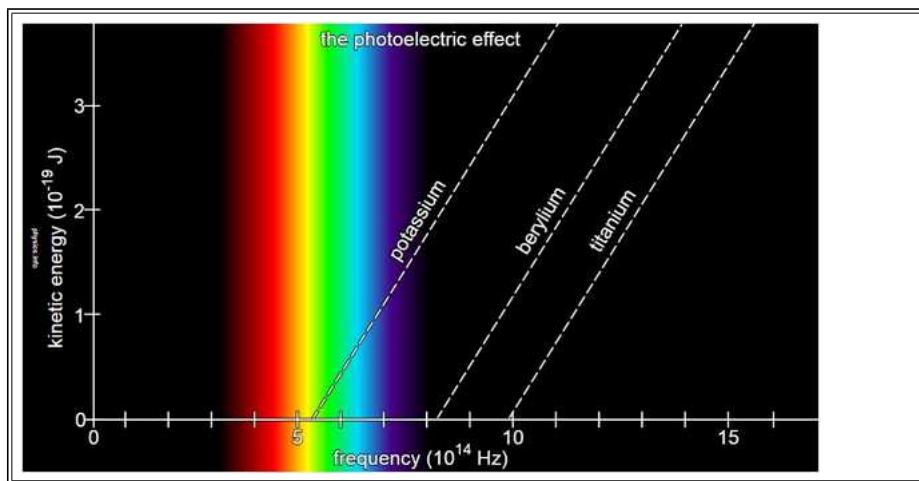
Blue light ejects photoelectrons with more energy than green light (even if it is very dim).

Actually, maybe these results aren't all that typical. Most elements have threshold frequencies that are ultraviolet and only a few dip down low enough to be green or yellow like the example shown above. The materials with the lowest threshold frequencies are all semiconductors. Some have threshold frequencies in the infrared region of the spectrum.

The classical model of light describes it as a transverse, electromagnetic wave. Of this there was very little doubt at the end of the Nineteenth Century. The wave nature of light was confirmed when it was applied successfully to explain such optical phenomena as diffraction, interference, polarization, reflection and refraction. If we can imagine light as waves in an electromagnetic ocean and be quite successful at it, then it wouldn't be much of a stretch for us to image electrons in a metal surface as something like tethered buoys floating in an electromagnetic harbor. Along come the waves (light) which pull and tug at the buoys (electrons). Weak waves have no effect, but strong ones just might yank a buoy from their mooring and set it adrift. A wave model of light would predict an energy-amplitude relationship and not the energy-frequency relationship described above. Photoelectric experiments describe an electromagnetic ocean where monstrous swells wouldn't tip over a canoe, but tiny ripples would fling you into the air.

If that wasn't enough, the photoelectrons seem to pop out of the surface too quickly. When light intensities are very low, the rate at which energy is delivered to the surface is downright sluggish. It should take a while for any one particular electron to capture enough of this diffuse energy to free itself. It should, but it doesn't. The instant that light with an appropriate frequency of any intensity strikes a photoemissive surface, at least one electron will always pop out immediately ( $t < 10^{-9}$  s). Continuing with the ocean analogy, imagine a harbor full of small boats (electrons). The sea is calm except for tiny ripples on the surface (low intensity, short wavelength light). Most of the boats in the harbor are unaffected by these waves, but one is ripped from the harbor and sent flying upward like a jet aircraft. Something just ain't right here. No mechanical waves behave like this, but light does.

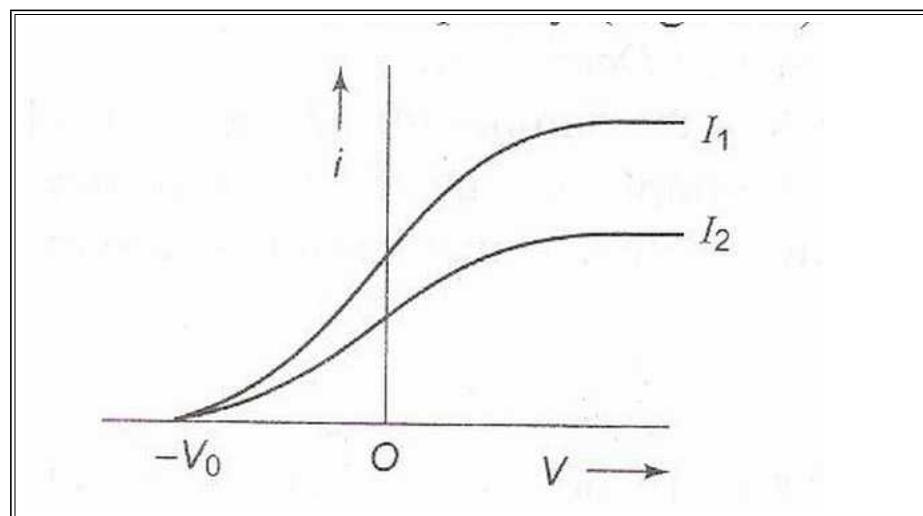
**new idea** The two factors affecting maximum kinetic energy of photoelectrons are the frequency of the incident radiation and the material on the surface. As shown in the graph below, electron energy increases with frequency in a simple linear manner above the threshold. All three curves have the same slope (equal to Planck's constant) which shows that the energy-frequency relation is constant for all materials. Below the threshold frequency photoemission does not occur. Each curve has a different intercept on the energy axis, which shows that threshold frequency is a function of the material.



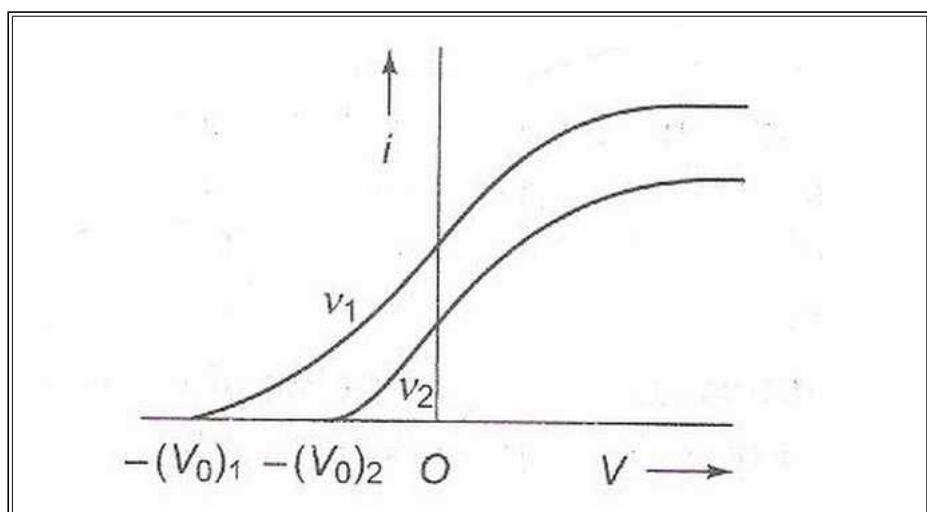
The genius that figured out what was going on here was none other than the world's most famous physicist Albert Einstein. In 1905, Einstein realized that light was behaving as if it was composed of tiny particles (initially called quanta and later called photons) and that the energy of each particle was proportional to the frequency of the electromagnetic radiation that it was a part of. Recall from the previous section of this book that Max Planck invented the notion of quantized electromagnetic radiation as a way to solve a technical problem with idealized sources of electromagnetic radiation called blackbodies. Recall also that Planck did not believe that radiation was actually broken up into little bits as his mathematical analysis showed. He thought the whole thing was just a contrivance that gave him the right answers. The genius of Einstein was in recognizing that Planck's contrivance was in fact a reasonable description of reality. What we perceive as a continuous wave of electromagnetic radiation is in reality a stream of discrete particles.

### 29.1.3 Graphs of Photoelectric Current vs Voltage

#### 29.1.3.1 For radiation of different Intensities ( $I_1 > I_2$ ) but the same frequency.



29.1.3.2 For radiation of different frequencies ( $\nu_1 > \nu_2$ ) but of the same intensity.



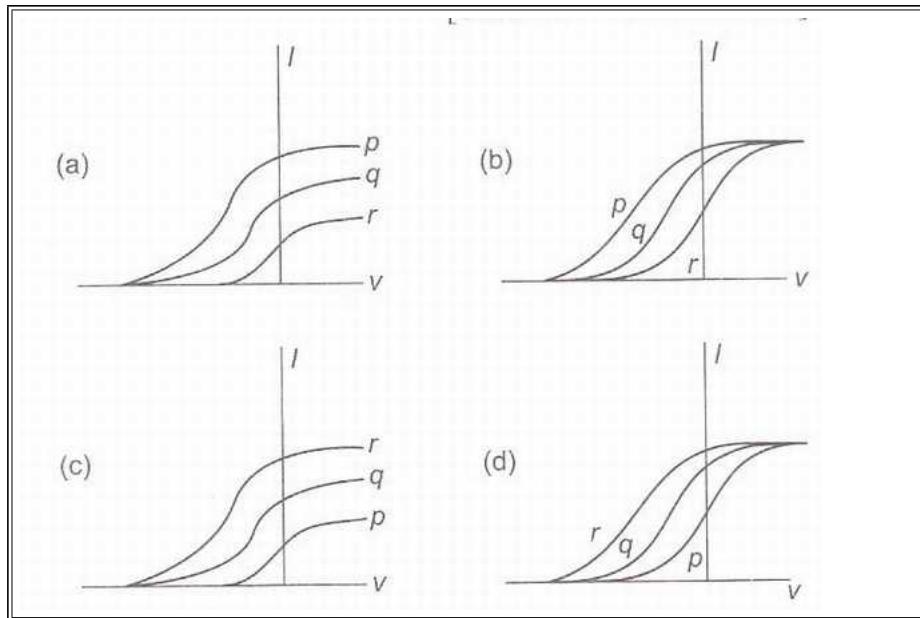
# Chapter 30

## Problems

### 30.1 Previous Years IIT Problems

#### 30.1.1 Single Answer Questions

**Example:** Photoelectric effect experiments are performed using three different metal plates p,q and r having work functions  $\phi_p = 2.0\text{eV}$ ,  $\phi_q = 2.5\text{eV}$ ,  $\phi_r = 3.0\text{eV}$  respectively. A light beam containing wavelengths of 550nm, 450nm and 350nm with equal intensities illuminates each of the plates. The correct I-V graph for the experiment is [Take  $hc=1240 \text{ eV nm}$ ]





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(N.d.). URL: <http://physics.info/photoelectric/>.



## **Part XVI**

### **Nucleus**



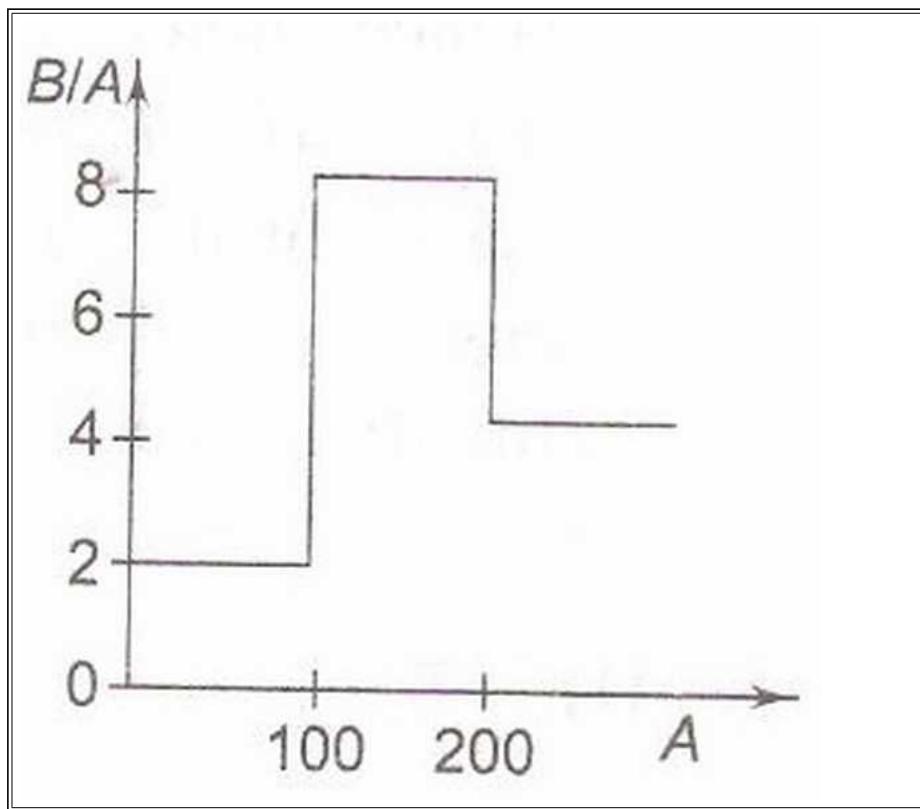
# Chapter 31

## Problems

### 31.1 Previous Years IIT Problems

#### 31.1.1 Multiple Answer

**Example:** Assume that the nuclear binding energy per nucleon ( $B/A$ ) versus mass number is as shown in the figure. Use this plot to choose the correct choice (s) given below.

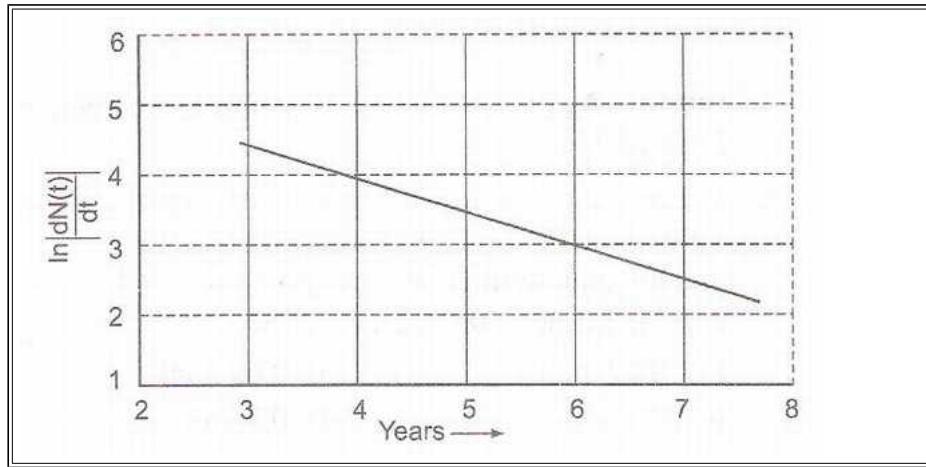


- a) Fusion of two nuclei with mass numbers lying in the range  $1 < A < 50$  will release energy
  - b) Fusion of two nuclei with mass numbers lying in the range of  $51 < A < 100$  will release energy
  - c) Fission of a nucleus lying in the mass number range of  $100 < A < 200$  will release energy when broken into equal fragments
  - d) Fission of a nucleus lying in the mass number range of  $200 < A < 260$  will release energy when broken into equal fragments
- { Solution: Energy is released if the total binding energy of the products is greater than the total binding energy of the reactants. This is not possible in choices a) and c). The correct choices are b) and d). }

#### 31.1.2 Integer Type

**Question :** To determine the half life of radioactive element, a student plots a graph of  $\ln \left| \frac{dN(t)}{dt} \right|$  vs t. Here  $\frac{dN(t)}{dt}$  is the rate of radioactive decay at time t. If the number of radioactive nuclei of this element

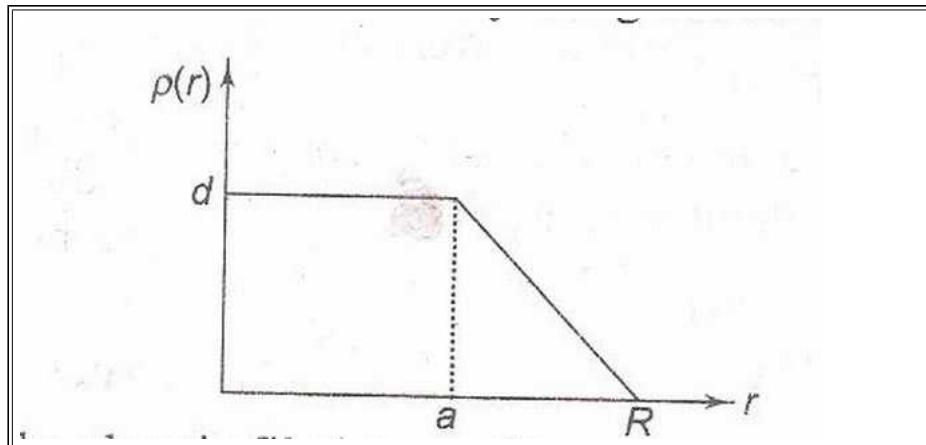
decreases by a factor of p after 4.16 years, find the value of p.



{ Answer: 8 }

### 31.1.3 Paragraph

**Question:** The nuclear charge ( $Ze$ ) is non-uniformly distributed within a nucleus of radius  $R$ . The charge density ( $\rho$ ) (charge per unit volume) is dependent only on the radial distance  $r$  from centre of the nucleus as shown in figure. The electric field is only along the radial direction.



1. The electric field at  $r=R$  is

- a) independent of a
- b) directly proportional to a
- c) directly proportional to  $a^2$
- d) inversely proportional to a

{ Solution: The charge  $q=Ze$  can be assumed to be concentrated at the centre of the nucleus. The electric field at  $r=R$  is

$$E = \frac{q}{4\pi\epsilon_0 R^2} = \frac{Ze}{4\pi\epsilon_0 R^2}$$

which is a constant. Hence the correct choice is a) . }

2. For  $a=0$ , the value of  $d$  ( maximum value of  $\rho$  as shown in the figure ) is

- a)  $\frac{3Ze}{4\pi R^3}$
- b)  $\frac{3Ze}{\pi R^3}$
- c)  $\frac{4Ze}{3\pi R^3}$
- d)  $\frac{Ze}{3\pi R^3}$

{ Solution: Total charge is

$$\begin{aligned} q &= \int_0^R 4\pi r^2 \left( d - \frac{d}{R} r \right) dr \\ &= 4\pi \left[ d \int_0^R r^2 dr - \frac{d}{R} \int_0^R r^3 dr \right] \\ &= \frac{\pi d R^3}{3} \end{aligned}$$

Now that  $d = \frac{3Ze}{\pi R^3}$

So, the correct choice is b) }

3. The electric field within the nucleus is generally observed to be linearly dependent on r. This implies

- a)  $a=0$
- b)  $a=R/2$
- c)  $a=R$
- d)  $a=2R/3$

{ Solution: For spherical charge distribution, the electric field is linearly dependent on r if the charge density  $\rho$  is uniform, i.e.  $a=R$ . Hence the correct choice is c). }



# Optics



## **Part XVII**

# **Ray Optics**



# Chapter 32

## Theory

### 32.1 Graphs for convex and concave lenses

(Real is positive sign convention) n.d.

Figure shows a graph where the reciprocal of the image distance is plotted against the reciprocal of the object distance. The graph is a straight line that intercepts both axes at  $1/f$  where  $f$  is the focal length of the lens. Since the object is real this graph is for a convex lens.

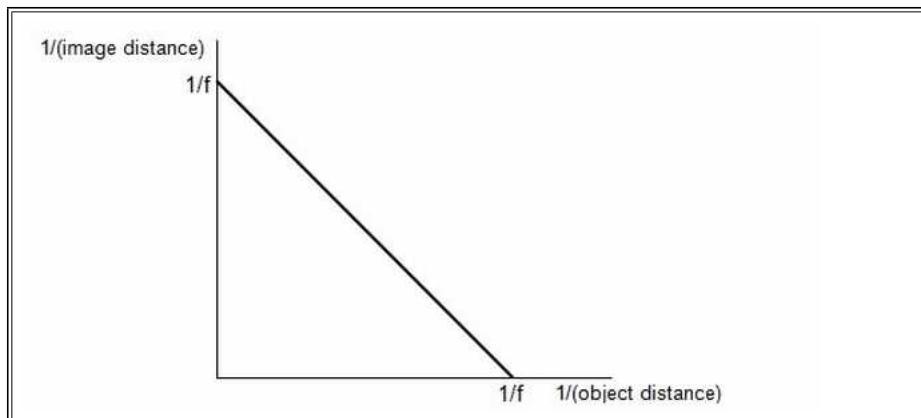
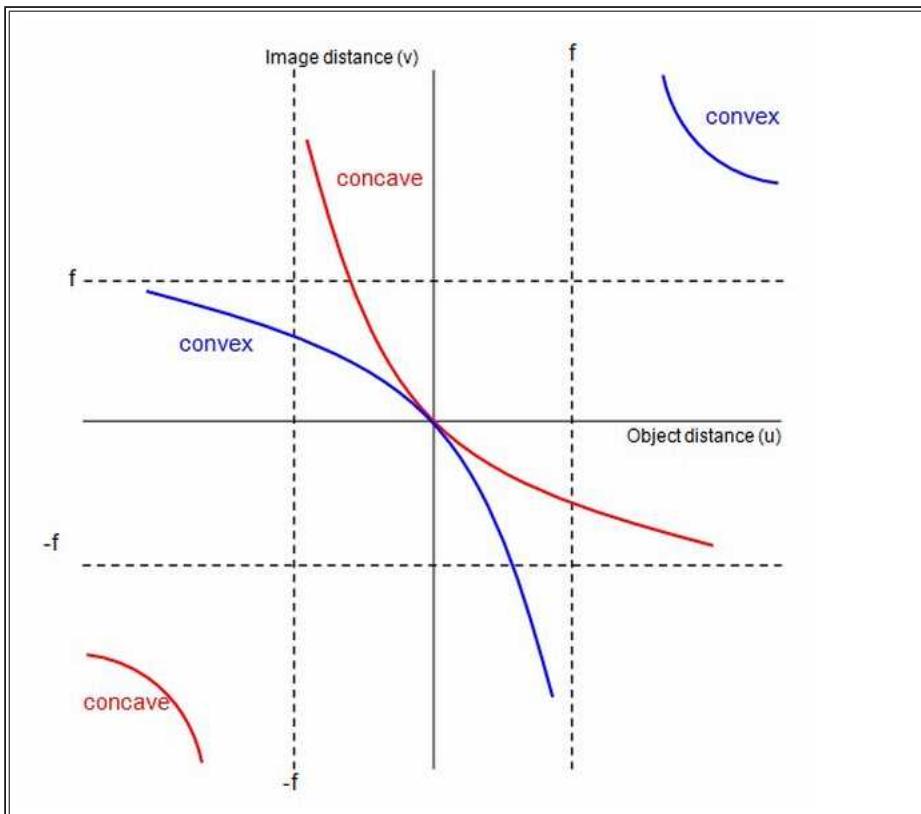


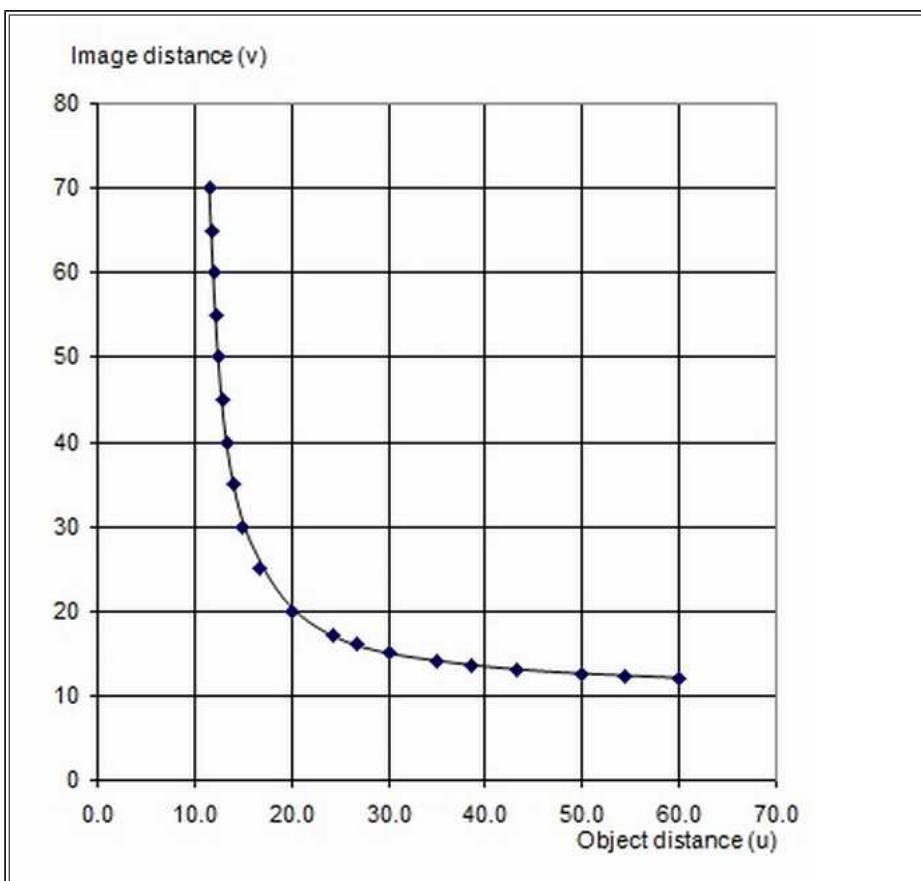
Figure shows a graph of the object distance plotted against the image distance for both convex and concave lenses. Both real and virtual objects and images are shown.



### 32.1.1 Enlarged view of an object distance (u) against image distance (v) graph

The focal length of the lens is 10 cm.

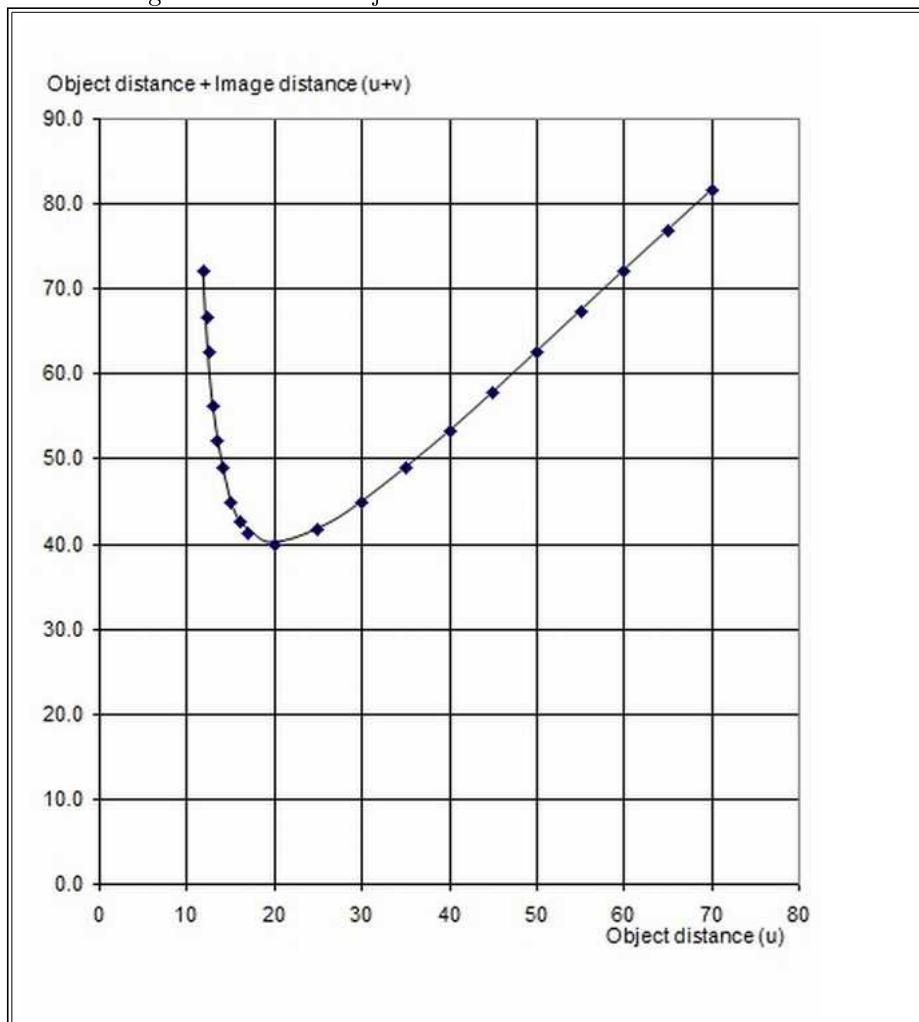
The graph is completely symmetrical so that when  $u = 2f$ ,  $v$  also equals  $2f$ .



### 32.1.2 Minimum distance

The next graph shows the distance between the object and image ( $u+v$ ) plotted against the object distance ( $u$ ) (it could equally well have been  $v$ ).

The minimum value for  $(u+v)$  is  $4f$  when  $u=v=2f$ . This means that no image can be formed with a convex lens of focal length 10 cm if the object and the screen are closer than 40 cm.





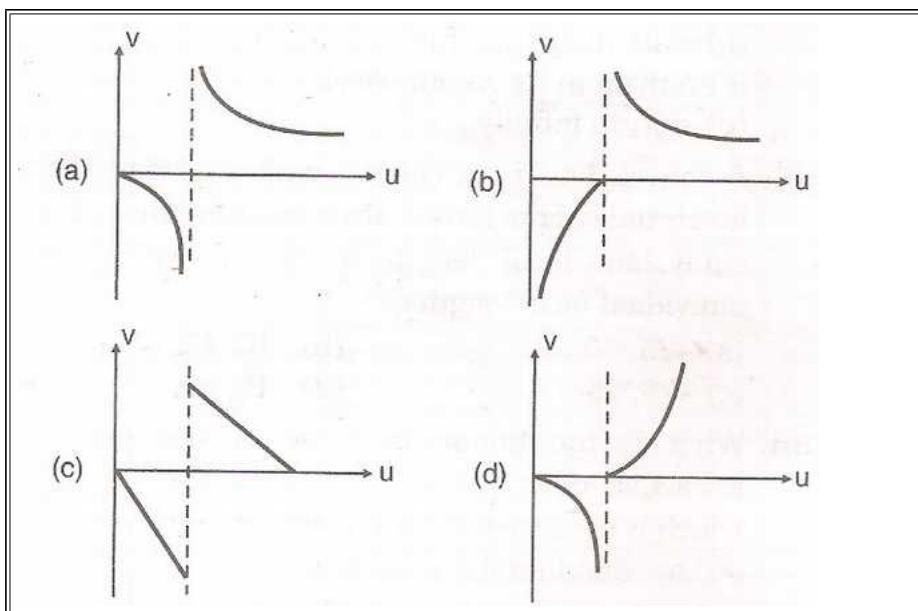
# Chapter 33

## Problems for Practice

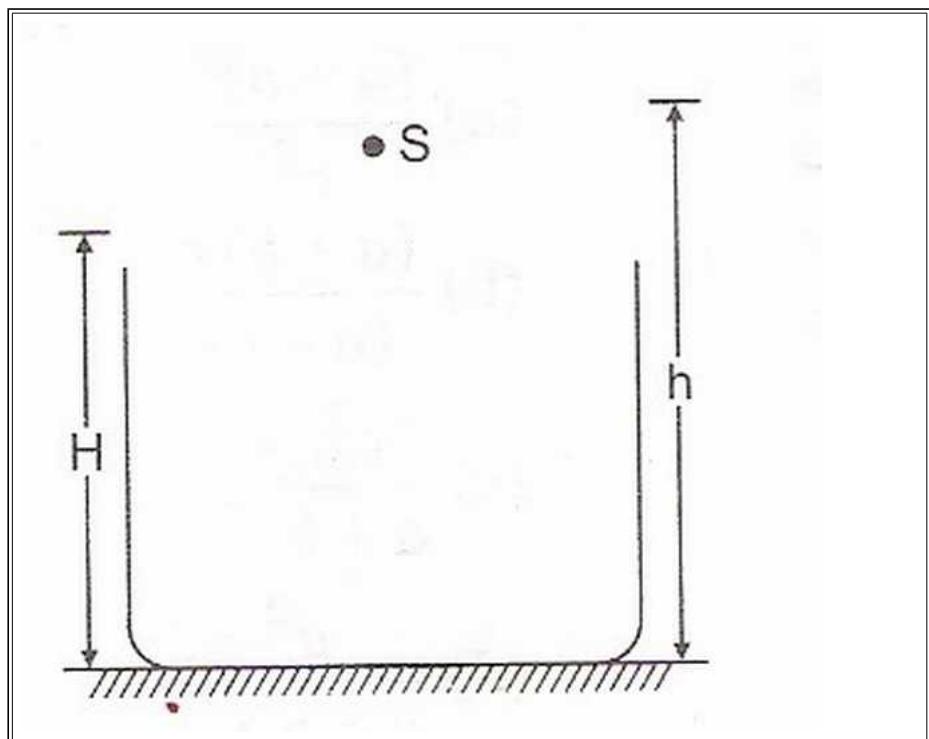
### 33.1 General Problem Set

#### 33.1.1 Single Answer Type

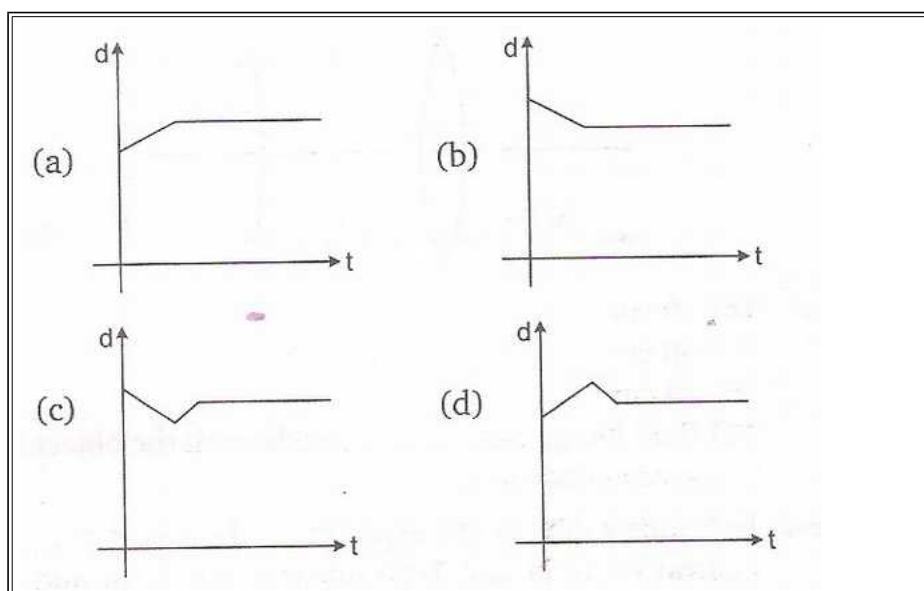
**Example :** As the position of an object ( $u$ ) reflected from a concave mirror is varied, the position of the image ( $v$ ) also varies. By letting the  $u$  change from 0 to  $+\infty$  the graph between  $v$  versus  $u$  will be



**Example :** A point source  $S$  is placed at a height  $h$  from the bottom of a vessel of height  $H$  ( $< h$ ). The vessel is polished at the base. Water is gradually filled in the vessel at a constant rate  $\alpha m^3/s$ .

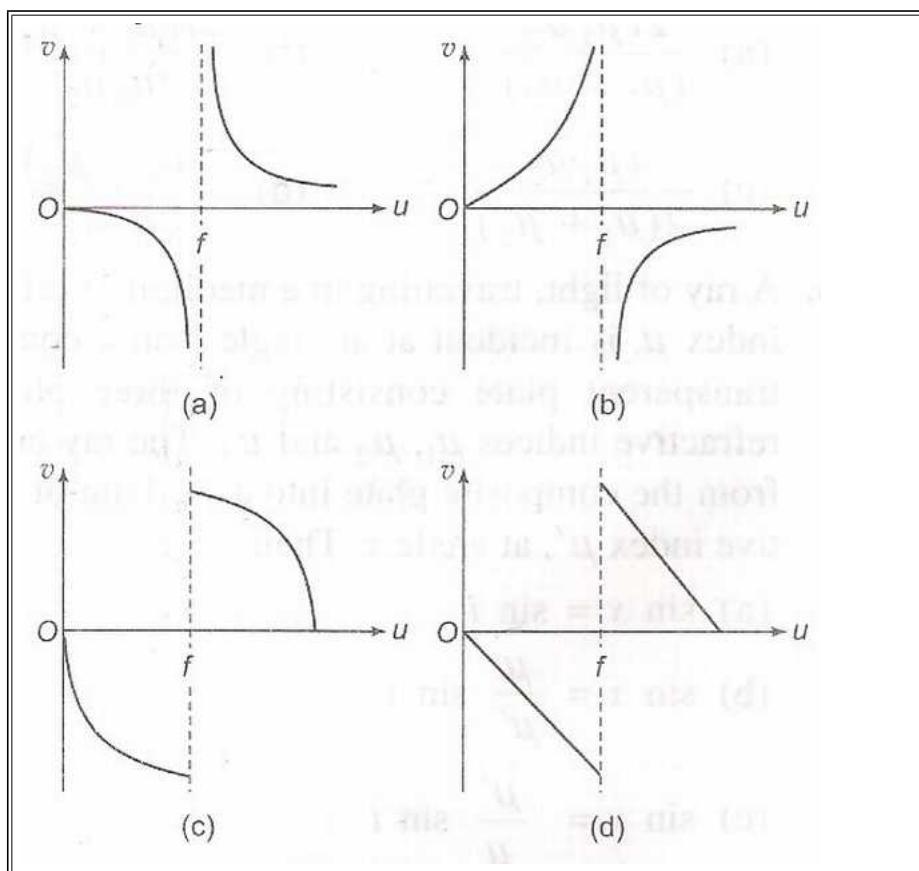


The distance  $d$  of image of the source after reflection from mirror from the bottom of the vessel varies with time  $t$  as

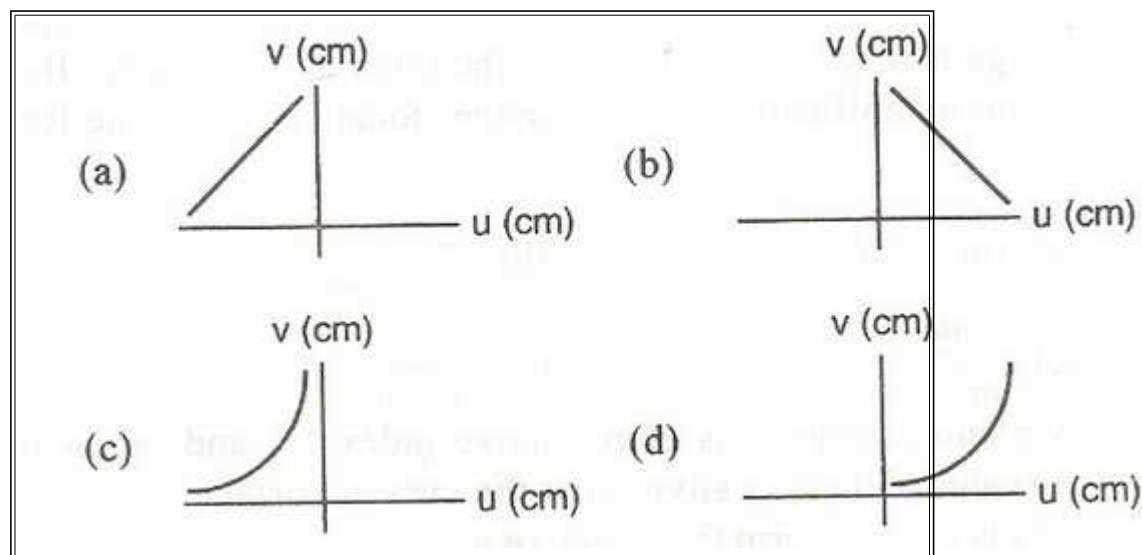


### 33.1.2 Multiple Answer Type

**Example 1:** The image distance ( $v$ ) is plotted against the object distance ( $u$ ) for a concave mirror of focal length  $f$ . Which of the graphs shown in Figure represents the variation of  $v$  versus  $u$  as  $u$  is varied from zero to infinity?



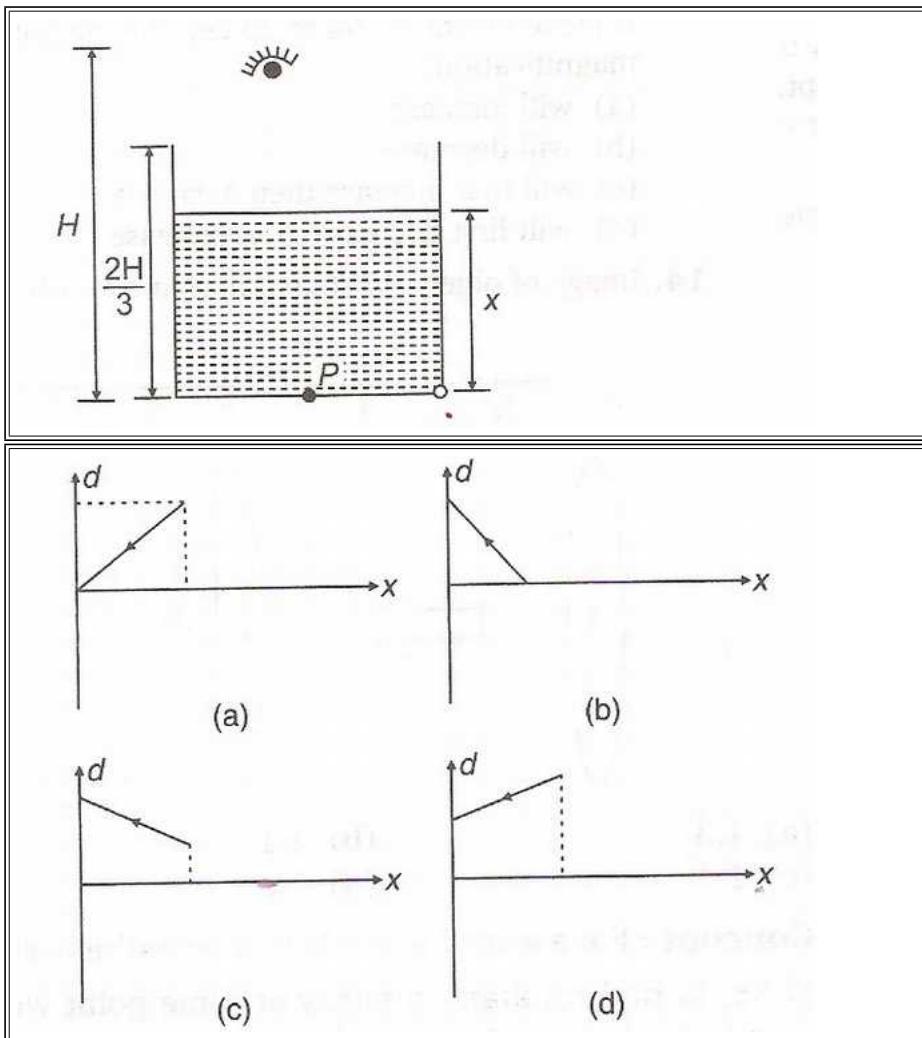
**Example :** A student measures the focal length of a convex lens by putting an object pin at a distance  $U$  from the lens and measuring the distance  $v$  of the image pin. Graph between  $u$  and  $v$  plotted by the student should look like :



### 33.1.3 Comprehension Type

#### 33.1.3.1 Comprehension 1

Liquid is filled in a vessel of height  $2H/3$ . At the bottom of the vessel there is a spot P and a hole from which liquid is coming out. Let  $d$  be the distance of image of P from an eye at height  $H$  from bottom at an instant when level of liquid in the vessel is  $x$ . If we plot a graph between  $d$  and  $x$  it will be like



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## Part XVIII

# Semiconductors

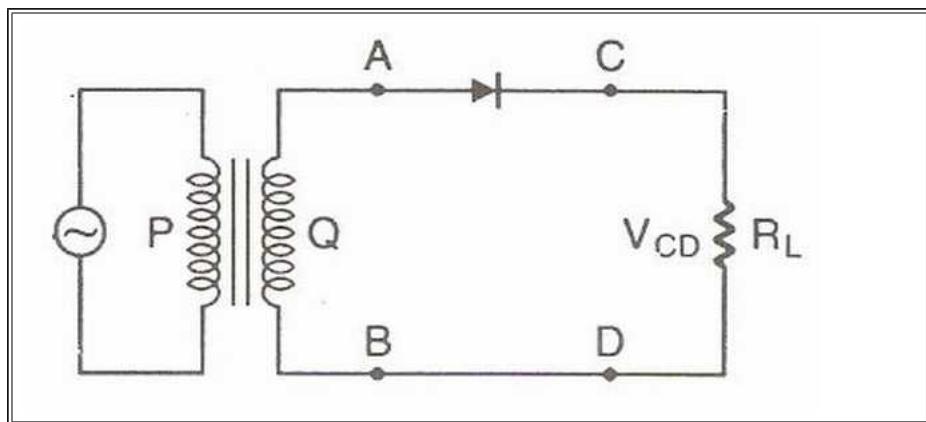


# Chapter 34

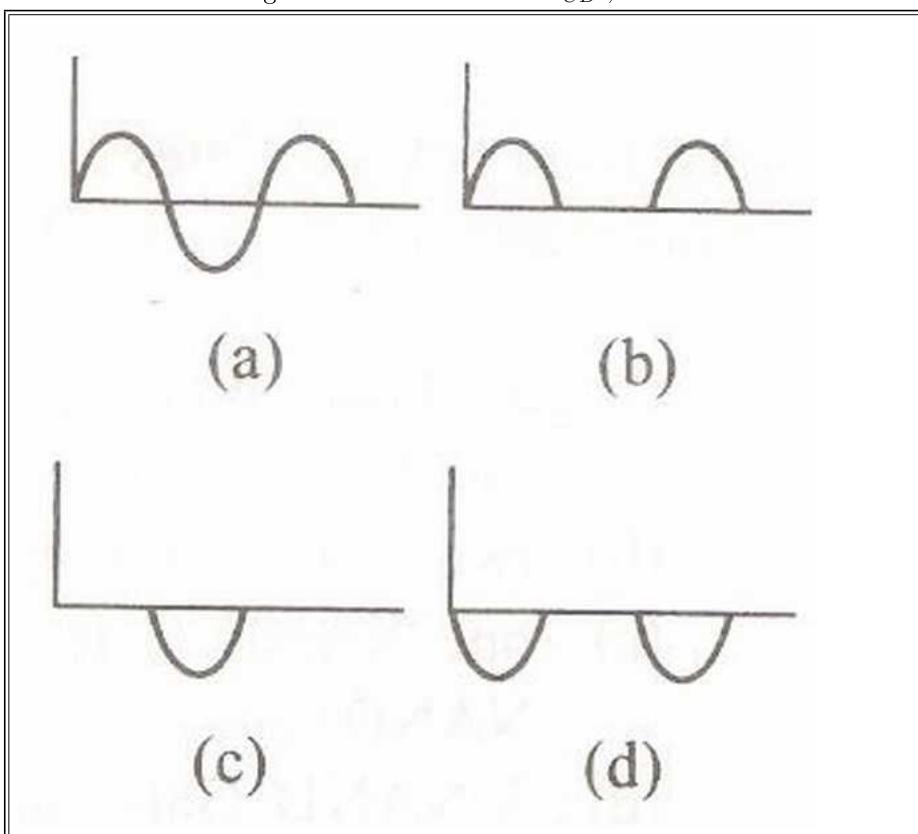
## Diode

### 34.1 Rectifier

**Example:** In the half-wave rectifier circuit shown:

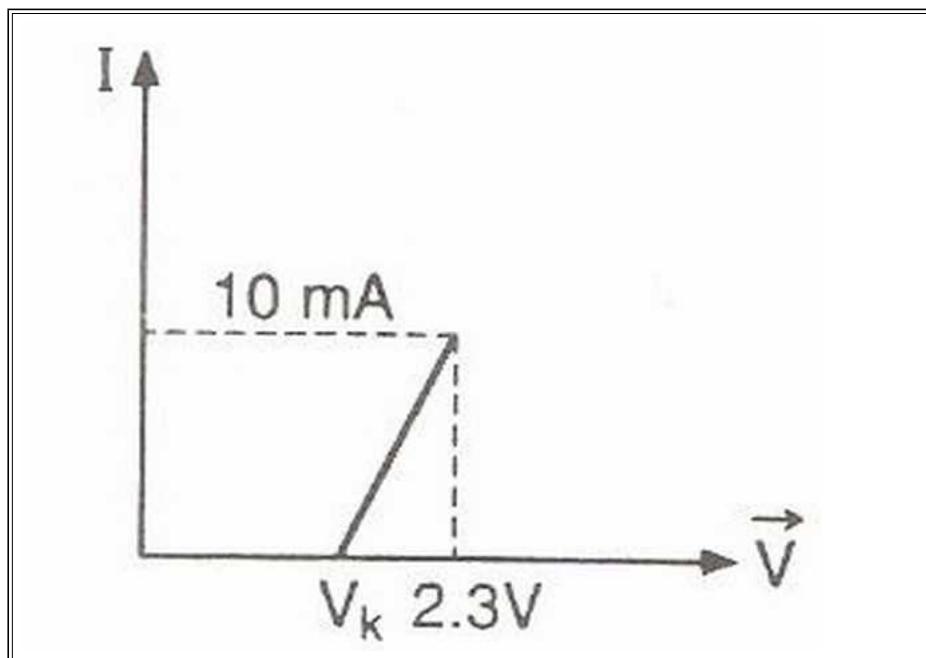


Which one of the following wave forms is true for  $V_{CD}$ , the



## 34.2 Junction Diode

**Example:** The resistance of a germanium junction diode, whose V-I is shown in figure is: ( $V_k = 0.3V$ )

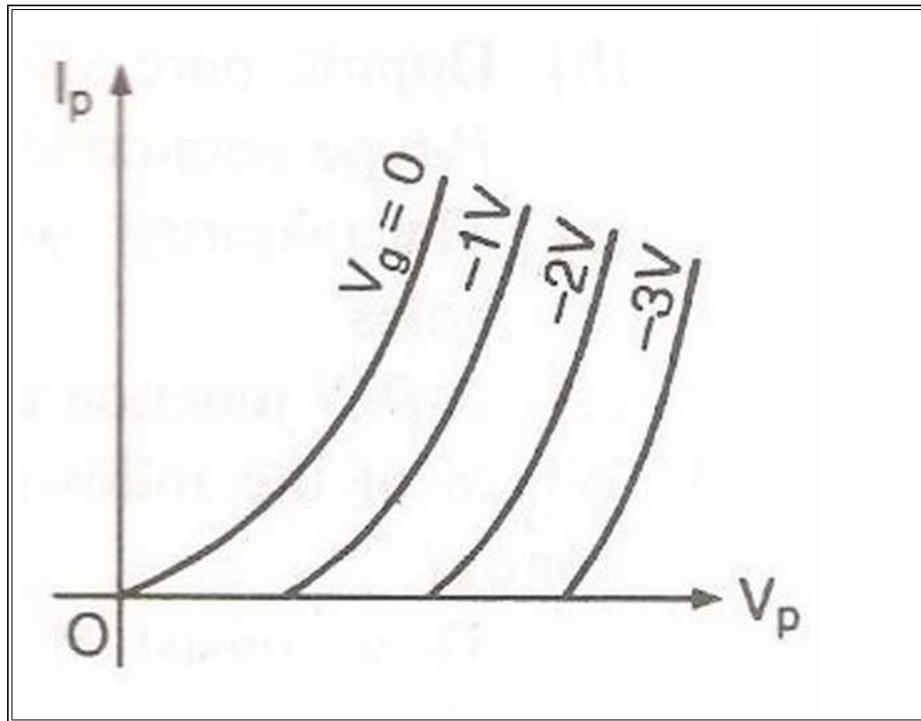


- a)  $5 \text{ k}\Omega$
- b)  $0.2 \text{ k}\Omega$
- c)  $2.3 \text{ k}\Omega$
- d)  $\left(\frac{10}{2.3}\right) \text{ k}\Omega$

## Chapter 35

### Triode

**Example:** The characteristic of triode shown in Figure. is known as :



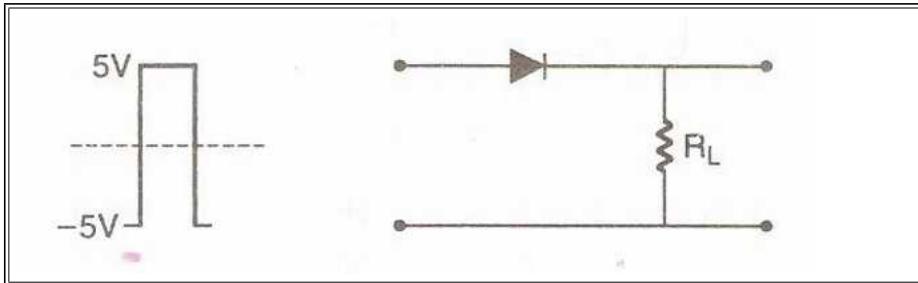
- a) mutual characteristic
- b) transfer characteristic
- c) static plate characteristic
- d) voltage transfer characteristic



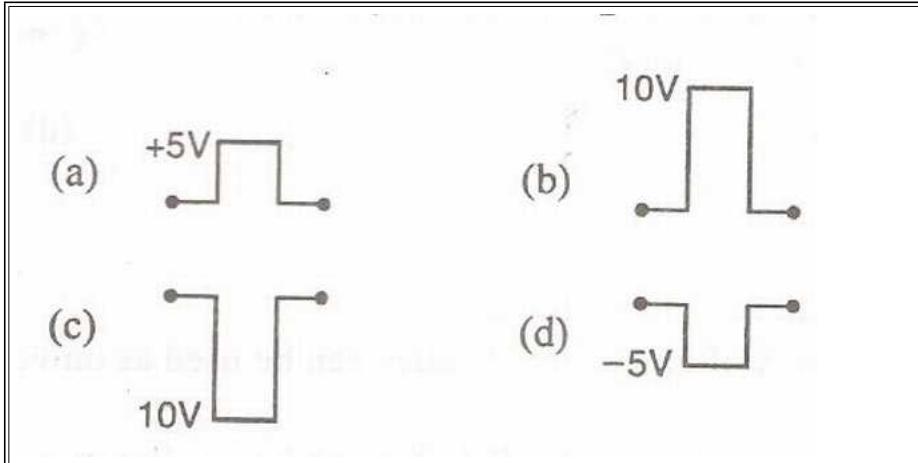
# Chapter 36

## p-n Junction

If in a p-n junction diode, a square input signal of 10 V is applied as shown



Then the output signal across  $R_L$  will be:



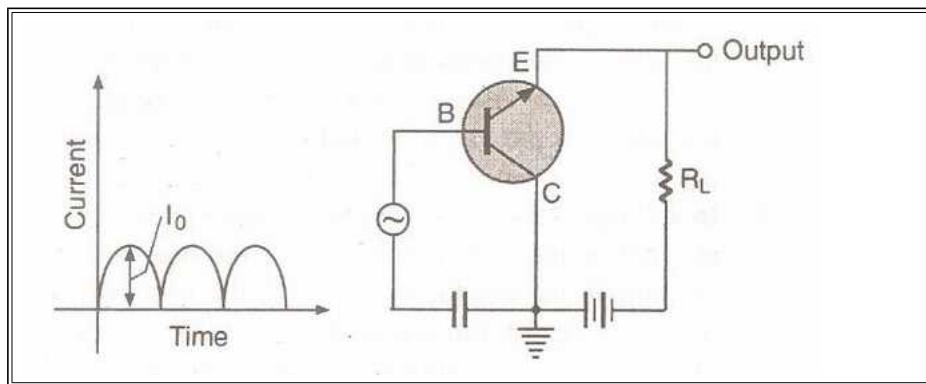
{Answer: a) }



# Chapter 37

## Transistors

**Example:** The output current versus time curve of a rectifier is shown in figure. The average value of the output current in this case is:



- a) 0
- b)  $\frac{I_0}{2}$
- c)  $\frac{2I_0}{\pi}$
- d)  $I_0$



# Part XIX

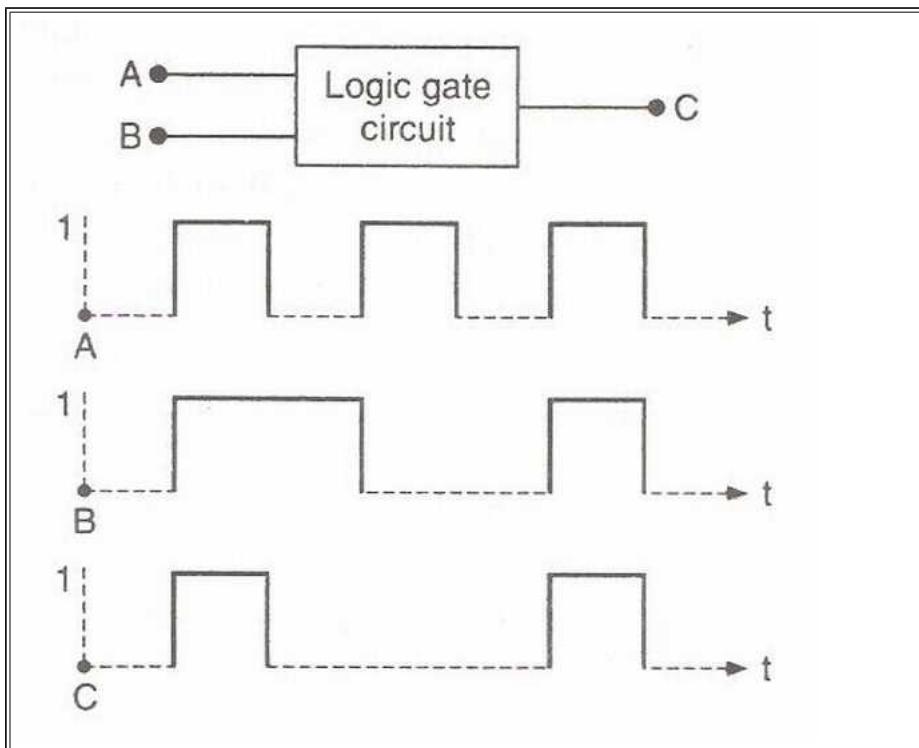
## Logic Gates



# Chapter 38

## Problems

**Example:** The following figure shows a logic gate circuit with two inputs A and B and the output C. The voltage wave forms of A, B and C are as shown below:



The logic circuit gate is

- a) AND gate
  - b) NAND gate
  - c) NOR gate
  - d) OR gate
- { Answer: a ) }

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