# COP 5615 Project 2

## **Bonus Report**

Submitted By:
Rajat Koujalagi
rkouj@ufl.edu
6138-2944

#### Largest network

1. For gossip -:

a. Full: 4000

b. 2D: 4000

c. Imp2D: 4000

d. Line: 1000

2. For push-sum-:

a. Full: 3000

b. 2D: 200

c. Imp2D: 200

d. Line: 100

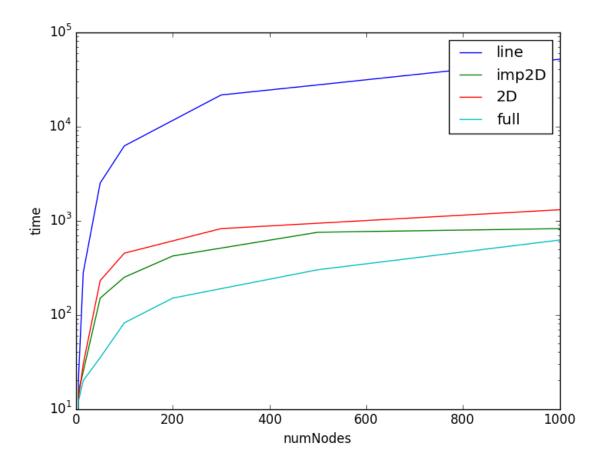
#### **Implementation**

Initially I tried permanently shutting down a single node randomly. There was not much difference seen for the different topologies except for the line where if I shut down a node who had not yet received the message, convergence is never achieved since the message is never propagated to the last node.

Next I permanently shut down first half of the nodes after any half of the nodes have achieved convergence. Again for full topology it did not make much of a difference, however for grid and imperfect grid, time taken to converge increased. For line, the problem still remained the same as above.

Finally, I decided to shut down each node temporarily and test the network. I have set each node to receive a Fail message every 250ms. During this interval (specific to each node), a node stops communicating. The trend of the different topologies remain the same as the ones without the failure however, time taken for convergence is increased, though convergence is always achieved.

### Gossip with failure -:



#### Push Sum with fail -:

