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No Oops, You Won't Do It Again: Mechanisms for Self-correction in Crowdsourcing Nihar Shah, Dengyong Zhou

Crowdsourcing is a very popular means of obtaining the large amounts of labeled data that modern machine learning methods require. Although cheap and fast to ob tain, crowdsourced labels suffer from significant amounts of error, thereby degr ading the performance of downstream machine learning tasks. With the goal of imp roving the quality of the labeled data, we seek to mitigate the many errors that occur due to silly mistakes or inadvertent errors by crowdsourcing workers. We propose a two-stage setting for crowdsourcing where the worker first answers the questions, and is then allowed to change her answers after looking at a (noisy) reference answer. We mathematically formulate this process and develop mechanis ms to incentivize workers to act appropriately. Our mathematical guarantees show that our mechanism incentivizes the workers to answer honestly in both stages, and refrain from answering randomly in the first stage or simply copying in the second. Numerical experiments reveal a significant boost in performance that such "self-correction" can provide when using crowdsourcing to train machine learning algorithms.

Stochastically Transitive Models for Pairwise Comparisons: Statistical and Computational Issues

Nihar Shah, Sivaraman Balakrishnan, Aditya Guntuboyina, Martin Wainwright There are various parametric models for analyzing pairwise comparison data, incl uding the Bradley-Terry-Luce (BTL) and Thurstone models, but their reliance on s trong parametric assumptions is limiting. In this work, we study a flexible mode l for pairwise comparisons, under which the probabilities of outcomes are requir ed only to satisfy a natural form of stochastic transitivity. This class include s parametric models including the BTL and Thurstone models as special cases, but is considerably more general. We provide various examples of models in this bro ader stochastically transitive class for which classical parametric models provi de poor fits. Despite this greater flexibility, we show that the matrix of proba bilities can be estimated at the same rate as in standard parametric models. On the other hand, unlike in the BTL and Thurstone models, computing the minimax-op timal estimator in the stochastically transitive model is non-trivial, and we ex plore various computationally tractable alternatives. We show that a simple sing ular value thresholding algorithm is statistically consistent but does not achie ve the minimax rate. We then propose and study algorithms that achieve the minim ax rate over interesting sub-classes of the full stochastically transitive class . We complement our theoretical results with thorough numerical simulations.

Uprooting and Rerooting Graphical Models Adrian Weller

We show how any binary pairwise model may be "uprooted" to a fully symmetric model, wherein original singleton potentials are transformed to potentials on edges to an added variable, and then "rerooted" to a new model on the original number of variables. The new model is essentially equivalent to the original model, with the same partition function and allowing recovery of the original marginals or a MAP configuration, yet may have very different computational properties that allow much more efficient inference. This meta-approach deepens our understanding, may be applied to any existing algorithm to yield improved methods in practice, generalizes earlier theoretical results, and reveals a remarkable interpretation of the triplet-consistent polytope.

A Deep Learning Approach to Unsupervised Ensemble Learning

Uri Shaham, Xiuyuan Cheng, Omer Dror, Ariel Jaffe, Boaz Nadler, Joseph Chang, Yu val Kluger

We show how deep learning methods can be applied in the context of crowdsourcing and unsupervised ensemble learning. First, we prove that the popular model of D awid and Skene, which assumes that all classifiers are conditionally independent

, is \em equivalent to a Restricted Boltzmann Machine (RBM) with a single hidden node. Hence, under this model, the posterior probabilities of the true labels c an be instead estimated via a trained RBM. Next, to address the more general cas e, where classifiers may strongly violate the conditional independence assumptio n, we propose to apply RBM-based Deep Neural Net (DNN). Experimental results on various simulated and real-world datasets demonstrate that our proposed DNN appr oach outperforms other state-of-the-art methods, in particular when the data vio lates the conditional independence assumption.

Revisiting Semi-Supervised Learning with Graph Embeddings

Zhilin Yang, William Cohen, Ruslan Salakhudinov

We present a semi-supervised learning framework based on graph embeddings. Given a graph between instances, we train an embedding for each instance to jointly p redict the class label and the neighborhood context in the graph. We develop bot h transductive and inductive variants of our method. In the transductive variant of our method, the class labels are determined by both the learned embeddings a nd input feature vectors, while in the inductive variant, the embeddings are defined as a parametric function of the feature vectors, so predictions can be made on instances not seen during training. On a large and diverse set of benchmark tasks, including text classification, distantly supervised entity extraction, and entity classification, we show improved performance over many of the existing models.

Guided Cost Learning: Deep Inverse Optimal Control via Policy Optimization Chelsea Finn, Sergey Levine, Pieter Abbeel

Reinforcement learning can acquire complex behaviors from high-level specifications. However, defining a cost function that can be optimized effectively and encodes the correct task is challenging in practice. We explore how inverse optimal control (IOC) can be used to learn behaviors from demonstrations, with applications to torque control of high-dimensional robotic systems. Our method addresses two key challenges in inverse optimal control: first, the need for informative features and effective regularization to impose structure on the cost, and second, the difficulty of learning the cost function under unknown dynamics for high-dimensional continuous systems. To address the former challenge, we present an algorithm capable of learning arbitrary nonlinear cost functions, such as neural networks, without meticulous feature engineering. To address the latter challenge, we formulate an efficient sample-based approximation for MaxEnt IOC. We evaluate our method on a series of simulated tasks and real-world robotic manipulation problems, demonstrating substantial improvement over prior methods both in terms of task complexity and sample efficiency.

Diversity-Promoting Bayesian Learning of Latent Variable Models Pengtao Xie, Jun Zhu, Eric Xing

In learning latent variable models (LVMs), it is important to effectively captur e infrequent patterns and shrink model size without sacrificing modeling power. Various studies have been done to "diversify" a LVM, which aim to learn a divers e set of latent components in LVMs. Most existing studies fall into a frequentis t-style regularization framework, where the components are learned via point est imation. In this paper, we investigate how to "diversify" LVMs in the paradigm o f Bayesian learning, which has advantages complementary to point estimation, suc h as alleviating overfitting via model averaging and quantifying uncertainty. We propose two approaches that have complementary advantages. One is to define div ersity-promoting mutual angular priors which assign larger density to components with larger mutual angles based on Bayesian network and von Mises-Fisher distri bution and use these priors to affect the posterior via Bayes rule. We develop t wo efficient approximate posterior inference algorithms based on variational inf erence and Markov chain Monte Carlo sampling. The other approach is to impose di versity-promoting regularization directly over the post-data distribution of com ponents. These two methods are applied to the Bayesian mixture of experts model to encourage the "experts" to be diverse and experimental results demonstrate th

e effectiveness and efficiency of our methods.

Additive Approximations in High Dimensional Nonparametric Regression via the SAL SA

Kirthevasan Kandasamy, Yaoliang Yu

High dimensional nonparametric regression is an inherently difficult problem wit h known lower bounds depending exponentially in dimension. A popular strategy to alleviate this curse of dimensionality has been to use additive models of \emph first order, which model the regression function as a sum of independent functio ns on each dimension. Though useful in controlling the variance of the estimate, such models are often too restrictive in practical settings. Between non-additi ve models which often have large variance and first order additive models which have large bias, there has been little work to exploit the trade-off in the midd le via additive models of intermediate order. In this work, we propose salsa, wh ich bridges this gap by allowing interactions between variables, but controls mo del capacity by limiting the order of interactions. salsas minimises the residua 1 sum of squares with squared RKHS norm penalties. Algorithmically, it can be vi ewed as Kernel Ridge Regression with an additive kernel. When the regression fun ction is additive, the excess risk is only polynomial in dimension. Using the Gi rard-Newton formulae, we efficiently sum over a combinatorial number of terms in the additive expansion. Via a comparison on 15 real datasets, we show that our method is competitive against 21 other alternatives.

Hawkes Processes with Stochastic Excitations

Young Lee, Kar Wai Lim, Cheng Soon Ong

We propose an extension to Hawkes processes by treating the levels of self-excit ation as a stochastic differential equation. Our new point process allows better approximation in application domains where events and intensities accelerate ea ch other with correlated levels of contagion. We generalize a recent algorithm f or simulating draws from Hawkes processes whose levels of excitation are stochas tic processes, and propose a hybrid Markov chain Monte Carlo approach for model fitting. Our sampling procedure scales linearly with the number of required even ts and does not require stationarity of the point process. A modular inference p rocedure consisting of a combination between Gibbs and Metropolis Hastings steps is put forward. We recover expectation maximization as a special case. Our gene ral approach is illustrated for contagion following geometric Brownian motion and exponential Langevin dynamics.

Data-driven Rank Breaking for Efficient Rank Aggregation Ashish Khetan, Sewoong Oh

Rank aggregation systems collect ordinal preferences from individuals to produce a global ranking that represents the social preference. To reduce the computati onal complexity of learning the global ranking, a common practice is to use rank -breaking. Individuals' preferences are broken into pairwise comparisons and the n applied to efficient algorithms tailored for independent pairwise comparisons. However, due to the ignored dependencies, naive rank-breaking approaches can re sult in inconsistent estimates. The key idea to produce unbiased and accurate estimates is to treat the paired comparisons outcomes unequally, depending on the topology of the collected data. In this paper, we provide the optimal rank-breaking estimator, which not only achieves consistency but also achieves the best er ror bound. This allows us to characterize the fundamental tradeoff between accuracy and complexity in some canonical scenarios. Further, we identify how the accuracy depends on the spectral gap of a corresponding comparison graph.

Dropout distillation

Samuel Rota Bulò, Lorenzo Porzi, Peter Kontschieder

Dropout is a popular stochastic regularization technique for deep neural network s that works by randomly dropping (i.e. zeroing) units from the network during t raining. This randomization process allows to implicitly train an ensemble of ex ponentially many networks sharing the same parametrization, which should be aver

aged at test time to deliver the final prediction. A typical workaround for this intractable averaging operation consists in scaling the layers undergoing dropo ut randomization. This simple rule called 'standard dropout' is efficient, but m ight degrade the accuracy of the prediction. In this work we introduce a novel a pproach, coined 'dropout distillation', that allows us to train a predictor in a way to better approximate the intractable, but preferable, averaging process, w hile keeping under control its computational efficiency. We are thus able to con struct models that are as efficient as standard dropout, or even more efficient, while being more accurate. Experiments on standard benchmark datasets demonstrate the validity of our method, yielding consistent improvements over conventional dropout.

Metadata-conscious anonymous messaging

Giulia Fanti, Peter Kairouz, Sewoong Oh, Kannan Ramchandran, Pramod Viswanath Anonymous messaging platforms like Whisper and Yik Yak allow users to spread mes sages over a network (e.g., a social network) without revealing message authorsh ip to other users. The spread of messages on these platforms can be modeled by a diffusion process over a graph. Recent advances in network analysis have reveal ed that such diffusion processes are vulnerable to author deanonymization by adversaries with access to metadata, such as timing information. In this work, we a sk the fundamental question of how to propagate anonymous messages over a graph to make it difficult for adversaries to infer the source. In particular, we study the performance of a message propagation protocol called adaptive diffusion in troduced in (Fanti et al., 2015). We prove that when the adversary has access to metadata at a fraction of corrupted graph nodes, adaptive diffusion achieves as ymptotically optimal source-hiding and significantly outperforms standard diffusion. We further demonstrate empirically that adaptive diffusion hides the source effectively on real social networks.

The Teaching Dimension of Linear Learners

Ji Liu, Xiaojin Zhu, Hrag Ohannessian

Teaching dimension is a learning theoretic quantity that specifies the minimum t raining set size to teach a target model to a learner. Previous studies on teach ing dimension focused on version-space learners which maintain all hypotheses co nsistent with the training data, and cannot be applied to modern machine learner s which select a specific hypothesis via optimization. This paper presents the f irst known teaching dimension for ridge regression, support vector machines, and logistic regression. We also exhibit optimal training sets that match these tea ching dimensions. Our approach generalizes to other linear learners.

Truthful Univariate Estimators

Ioannis Caragiannis, Ariel Procaccia, Nisarg Shah

We revisit the classic problem of estimating the population mean of an unknown s ingle-dimensional distribution from samples, taking a game-theoretic viewpoint. In our setting, samples are supplied by strategic agents, who wish to pull the e stimate as close as possible to their own value. In this setting, the sample mean gives rise to manipulation opportunities, whereas the sample median does not. Our key question is whether the sample median is the best (in terms of mean squa red error) truthful estimator of the population mean. We show that when the underlying distribution is symmetric, there are truthful estimators that dominate the median. Our main result is a characterization of worst-case optimal truthful estimators, which provably outperform the median, for possibly asymmetric distributions with bounded support.

Why Regularized Auto-Encoders learn Sparse Representation?

Devansh Arpit, Yingbo Zhou, Hung Ngo, Venu Govindaraju

Sparse distributed representation is the key to learning useful features in deep learning algorithms, because not only it is an efficient mode of data represent ation, but also - more importantly - it captures the generation process of most real world data. While a number of regularized auto-encoders (AE) enforce sparsi

ty explicitly in their learned representation and others don't, there has been little formal analysis on what encourages sparsity in these models in general. Our objective is to formally study this general problem for regularized auto-encoders. We provide sufficient conditions on both regularization and activation functions that encourage sparsity. We show that multiple popular models (de-noising and contractive auto encoders, e.g.) and activations (rectified linear and sigmoid, e.g.) satisfy these conditions; thus, our conditions help explain sparsity in their learned representation. Thus our theoretical and empirical analysis toge ther shed light on the properties of regularization/activation that are conductive to sparsity and unify a number of existing auto-encoder models and activation functions under the same analytical framework.

k-variates++: more pluses in the k-means++

Richard Nock, Raphael Canyasse, Roksana Boreli, Frank Nielsen

k-means++ seeding has become a de facto standard for hard clustering algorithms. In this paper, our first contribution is a two-way generalisation of this seedi ng, k-variates++, that includes the sampling of general densities rather than ju st a discrete set of Dirac densities anchored at the point locations, *and* a ge neralisation of the well known Arthur-Vassilvitskii (AV) approximation guarantee , in the form of a *bias+variance* approximation bound of the *global* optimum. This approximation exhibits a reduced dependency on the "noise" component with r espect to the optimal potential - actually approaching the statistical lower bou nd. We show that k-variates++ *reduces* to efficient (biased seeding) clustering algorithms tailored to specific frameworks; these include distributed, streamin g and on-line clustering, with *direct* approximation results for these algorith ms. Finally, we present a novel application of k-variates++ to differential priv acy. For either the specific frameworks considered here, or for the differential privacy setting, there is little to no prior results on the direct application of k-means++ and its approximation bounds - state of the art contenders appear t o be significantly more complex and / or display less favorable (approximation) properties. We stress that our algorithms can still be run in cases where there is *no* closed form solution for the population minimizer. We demonstrate the ap plicability of our analysis via experimental evaluation on several domains and s ettings, displaying competitive performances vs state of the art.

Multi-Player Bandits - a Musical Chairs Approach

Jonathan Rosenski, Ohad Shamir, Liran Szlak

We consider a variant of the stochastic multi-armed bandit problem, where multip le players simultaneously choose from the same set of arms and may collide, rece iving no reward. This setting has been motivated by problems arising in cognitive radio networks, and is especially challenging under the realistic assumption to hat communication between players is limited. We provide a communication-free algorithm (Musical Chairs) which attains constant regret with high probability, as well as a sublinear-regret, communication-free algorithm (Dynamic Musical Chairs) for the more difficult setting of players dynamically entering and leaving the roughout the game. Moreover, both algorithms do not require prior knowledge of the number of players. To the best of our knowledge, these are the first communication-free algorithms with these types of formal guarantees.

The Information Sieve

Greg Ver Steeg, Aram Galstyan

We introduce a new framework for unsupervised learning of representations based on a novel hierarchical decomposition of information. Intuitively, data is passe d through a series of progressively fine-grained sieves. Each layer of the sieve recovers a single latent factor that is maximally informative about multivariat e dependence in the data. The data is transformed after each pass so that the re maining unexplained information trickles down to the next layer. Ultimately, we are left with a set of latent factors explaining all the dependence in the original data and remainder information consisting of independent noise. We present a practical implementation of this framework for discrete variables and apply it

to a variety of fundamental tasks in unsupervised learning including independent component analysis, lossy and lossless compression, and predicting missing values in data.

Deep Speech 2: End-to-End Speech Recognition in English and Mandarin Dario Amodei, Sundaram Ananthanarayanan, Rishita Anubhai, Jingliang Bai, Eric Ba ttenberg, Carl Case, Jared Casper, Bryan Catanzaro, Qiang Cheng, Guoliang Chen, Jie Chen, Jingdong Chen, Zhijie Chen, Mike Chrzanowski, Adam Coates, Greg Diamos, Ke Ding, Niandong Du, Erich Elsen, Jesse Engel, Weiwei Fang, Linxi Fan, Christ opher Fougner, Liang Gao, Caixia Gong, Awni Hannun, Tony Han, Lappi Johannes, Bing Jiang, Cai Ju, Billy Jun, Patrick LeGresley, Libby Lin, Junjie Liu, Yang Liu, Weigao Li, Xiangang Li, Dongpeng Ma, Sharan Narang, Andrew Ng, Sherjil Ozair, Yiping Peng, Ryan Prenger, Sheng Qian, Zongfeng Quan, Jonathan Raiman, Vinay Rao, Sanjeev Satheesh, David Seetapun, Shubho Sengupta, Kavya Srinet, Anuroop Sriram, Haiyuan Tang, Liliang Tang, Chong Wang, Jidong Wang, Kaifu Wang, Yi Wang, Zhijian Wang, Zhiqian Wang, Shuang Wu, Likai Wei, Bo Xiao, Wen Xie, Yan Xie, Dani Yogatama, Bin Yuan, Jun Zhan, Zhenyao Zhu

We show that an end-to-end deep learning approach can be used to recognize eithe r English or Mandarin Chinese speech-two vastly different languages. Because it replaces entire pipelines of hand-engineered components with neural networks, en d-to-end learning allows us to handle a diverse variety of speech including nois y environments, accents and different languages. Key to our approach is our application of HPC techniques, enabling experiments that previously took weeks to now run in days. This allows us to iterate more quickly to identify superior architectures and algorithms. As a result, in several cases, our system is competitive with the transcription of human workers when benchmarked on standard datasets. Finally, using a technique called Batch Dispatch with GPUs in the data center, we show that our system can be inexpensively deployed in an online setting, delivering low latency when serving users at scale.

On the Consistency of Feature Selection With Lasso for Non-linear Targets Yue Zhang, Weihong Guo, Soumya Ray

An important question in feature selection is whether a selection strategy recovers the "true" set of features, given enough data. We study this question in the context of the popular Least Absolute Shrinkage and Selection Operator (Lasso) feature selection strategy. In particular, we consider the scenario when the model is misspecified so that the learned model is linear while the underlying real target is nonlinear. Surprisingly, we prove that under certain conditions, Lasso is still able to recover the correct features in this case. We also carry out numerical studies to empirically verify the theoretical results and explore the necessity of the conditions under which the proof holds.

Minimum Regret Search for Single- and Multi-Task Optimization Jan Hendrik Metzen

We propose minimum regret search (MRS), a novel acquisition function for Bayesia n optimization. MRS bears similarities with information-theoretic approaches such as entropy search (ES). However, while ES aims in each query at maximizing the information gain with respect to the global maximum, MRS aims at minimizing the expected simple regret of its ultimate recommendation for the optimum. While empirically ES and MRS perform similar in most of the cases, MRS produces fewer outliers with high simple regret than ES. We provide empirical results both for a synthetic single-task optimization problem as well as for a simulated multi-task robotic control problem.

CryptoNets: Applying Neural Networks to Encrypted Data with High Throughput and Accuracy

Ran Gilad-Bachrach, Nathan Dowlin, Kim Laine, Kristin Lauter, Michael Naehrig, John Wernsing

Applying machine learning to a problem which involves medical, financial, or oth er types of sensitive data, not only requires accurate predictions but also care

ful attention to maintaining data privacy and security. Legal and ethical requir ements may prevent the use of cloud-based machine learning solutions for such ta sks. In this work, we will present a method to convert learned neural networks to CryptoNets, neural networks that can be applied to encrypted data. This allows a data owner to send their data in an encrypted form to a cloud service that ho sts the network. The encryption ensures that the data remains confidential since the cloud does not have access to the keys needed to decrypt it. Nevertheless, we will show that the cloud service is capable of applying the neural network to the encrypted data to make encrypted predictions, and also return them in encry pted form. These encrypted predictions can be sent back to the owner of the secr et key who can decrypt them. Therefore, the cloud service does not gain any information about the raw data nor about the prediction it made. We demonstrate CryptoNets on the MNIST optical character recognition tasks. CryptoNets achieve 99% accuracy and can make around 59000 predictions per hour on a single PC. Therefor e, they allow high throughput, accurate, and private predictions.

The Variational Nystrom method for large-scale spectral problems Max Vladymyrov, Miguel Carreira-Perpinan

Spectral methods for dimensionality reduction and clustering require solving an eigenproblem defined by a sparse affinity matrix. When this matrix is large, one seeks an approximate solution. The standard way to do this is the Nystrom method, which first solves a small eigenproblem considering only a subset of landmark points, and then applies an out-of-sample formula to extrapolate the solution to the entire dataset. We show that by constraining the original problem to satisfy the Nystrom formula, we obtain an approximation that is computationally simple and efficient, but achieves a lower approximation error using fewer landmarks and less runtime. We also study the role of normalization in the computational cost and quality of the resulting solution.

Multi-Bias Non-linear Activation in Deep Neural Networks Hongyang Li, Wanli Ouyang, Xiaogang Wang

As a widely used non-linear activation, Rectified Linear Unit (ReLU) separates n oise and signal in a feature map by learning a threshold or bias. However, we ar gue that the classification of noise and signal not only depends on the magnitud e of responses, but also the context of how the feature responses would be used to detect more abstract patterns in higher layers. In order to output multiple r esponse maps with magnitude in different ranges for a particular visual pattern, existing networks employing ReLU and its variants have to learn a large number of redundant filters. In this paper, we propose a multi-bias non-linear activati on (MBA) layer to explore the information hidden in the magnitudes of responses. It is placed after the convolution layer to decouple the responses to a convolu tion kernel into multiple maps by multi-thresholding magnitudes, thus generating more patterns in the feature space at a low computational cost. It provides gre at flexibility of selecting responses to different visual patterns in different magnitude ranges to form rich representations in higher layers. Such a simple an d yet effective scheme achieves the state-of-the-art performance on several benc hmarks.

Asymmetric Multi-task Learning Based on Task Relatedness and Loss Giwoong Lee, Eunho Yang, Sung Hwang

We propose a novel multi-task learning method that can minimize the effect of ne gative transfer by allowing asymmetric transfer between the tasks based on task relatedness as well as the amount of individual task losses, which we refer to a s Asymmetric Multi-task Learning (AMTL). To tackle this problem, we couple multi ple tasks via a sparse, directed regularization graph, that enforces each task p arameter to be reconstructed as a sparse combination of other tasks, which are s elected based on the task-wise loss. We present two different algorithms to solv e this joint learning of the task predictors and the regularization graph. The f irst algorithm solves for the original learning objective using alternative opti mization, and the second algorithm solves an approximation of it using curriculu

m learning strategy, that learns one task at a time. We perform experiments on m ultiple datasets for classification and regression, on which we obtain significa nt improvements in performance over the single task learning and symmetric multi task learning baselines.

Accurate Robust and Efficient Error Estimation for Decision Trees Lixin Fan

This paper illustrates a novel approach to the estimation of generalization erro r of decision tree classifiers. We set out the study of decision tree errors in the context of consistency analysis theory, which proved that the Bayes error can be achieved only if when the number of data samples thrown into each leaf node goes to infinity. For the more challenging and practical case where the sample size is finite or small, a novel sampling error term is introduced in this paper to cope with the small sample problem effectively and efficiently. Extensive experimental results show that the proposed error estimate is superior to the well known K-fold cross validation methods in terms of robustness and accuracy. More over it is orders of magnitudes more efficient than cross validation methods.

Fast Stochastic Algorithms for SVD and PCA: Convergence Properties and Convexity Ohad Shamir

We study the convergence properties of the VR-PCA algorithm introduced by (Shami r, 2015) for fast computation of leading singular vectors. We prove several new results, including a formal analysis of a block version of the algorithm, and co nvergence from random initialization. We also make a few observations of independent interest, such as how pre-initializing with just a single exact power iteration can significantly improve the analysis, and what are the convexity and non-convexity properties of the underlying optimization problem.

Convergence of Stochastic Gradient Descent for PCA Ohad Shamir

We consider the problem of principal component analysis (PCA) in a streaming sto chastic setting, where our goal is to find a direction of approximate maximal va riance, based on a stream of i.i.d. data points in R^d. A simple and computation ally cheap algorithm for this is stochastic gradient descent (SGD), which incrementally updates its estimate based on each new data point. However, due to the non-convex nature of the problem, analyzing its performance has been a challenge. In particular, existing guarantees rely on a non-trivial eigengap assumption on the covariance matrix, which is intuitively unnecessary. In this paper, we provide (to the best of our knowledge) the first eigengap-free convergence guarantees for SGD in the context of PCA. This also partially resolves an open problem posed in (Hardt & Price, 2014). Moreover, under an eigengap assumption, we show that the same techniques lead to new SGD convergence guarantees with better dependence on the eigengap.

Dealbreaker: A Nonlinear Latent Variable Model for Educational Data Andrew Lan, Tom Goldstein, Richard Baraniuk, Christoph Studer

Statistical models of student responses on assessment questions, such as those in homeworks and exams, enable educators and computer-based personalized learning systems to gain insights into students' knowledge using machine learning. Popul ar student-response models, including the Rasch model and item response theory models, represent the probability of a student answering a question correctly using an affine function of latent factors. While such models can accurately predict student responses, their ability to interpret the underlying knowledge structure (which is certainly nonlinear) is limited. In response, we develop a new, non linear latent variable model that we call the dealbreaker model, in which a student's success probability is determined by their weakest concept mastery. We develop efficient parameter inference algorithms for this model using novel methods for nonconvex optimization. We show that the dealbreaker model achieves comparable or better prediction performance as compared to affine models with real-world educational datasets. We further demonstrate that the parameters learned by the

e dealbreaker model are interpretable—they provide key insights into which conce pts are critical (i.e., the "dealbreaker") to answering a question correctly. We conclude by reporting preliminary results for a movie-rating dataset, which ill ustrate the broader applicability of the dealbreaker model.

A Kernelized Stein Discrepancy for Goodness-of-fit Tests Qiang Liu, Jason Lee, Michael Jordan

We derive a new discrepancy statistic for measuring differences between two prob ability distributions based on combining Stein's identity and the reproducing ke rnel Hilbert space theory. We apply our result to test how well a probabilistic model fits a set of observations, and derive a new class of powerful goodness-of-fit tests that are widely applicable for complex and high dimensional distribut ions, even for those with computationally intractable normalization constants. B oth theoretical and empirical properties of our methods are studied thoroughly.

Variable Elimination in the Fourier Domain

Yexiang Xue, Stefano Ermon, Ronan Le Bras, Carla, Bart Selman

The ability to represent complex high dimensional probability distributions in a compact form is one of the key insights in the field of graphical models. Facto red representations are ubiquitous in machine learning and lead to major computa tional advantages. We explore a different type of compact representation based on discrete Fourier representations, complementing the classical approach based on conditional independencies. We show that a large class of probabilistic graphical models have a compact Fourier representation. This theoretical result opens up an entirely new way of approximating a probability distribution. We demonstrate the significance of this approach by applying it to the variable elimination algorithm. Compared with the traditional bucket representation and other approximate inference algorithms, we obtain significant improvements.

Low-Rank Matrix Approximation with Stability

Dongsheng Li, Chao Chen, Qin Lv, Junchi Yan, Li Shang, Stephen Chu

Low-rank matrix approximation has been widely adopted in machine learning applic ations with sparse data, such as recommender systems. However, the sparsity of the data, incomplete and noisy, introduces challenges to the algorithm stability—small changes in the training data may significantly change the models. As a result, existing low-rank matrix approximation solutions yield low generalization performance, exhibiting high error variance on the training dataset, and minimizing the training error may not guarantee error reduction on the testing dataset. In this paper, we investigate the algorithm stability problem of low-rank matrix approximations. We present a new algorithm design framework, which (1) introduces new optimization objectives to guide stable matrix approximation algorithm design, and (2) solves the optimization problem to obtain stable low-rank approximation solutions with good generalization performance. Experimental results on real-world datasets demonstrate that the proposed work can achieve better prediction accuracy compared with both state-of-the-art low-rank matrix approximation methods and ensemble methods in recommendation task.

Linking losses for density ratio and class-probability estimation Aditya Menon, Cheng Soon Ong

Given samples from two densities p and q, density ratio estimation (DRE) is the problem of estimating the ratio p/q. Two popular discriminative approaches to DR E are KL importance estimation (KLIEP), and least squares importance fitting (LS IF). In this paper, we show that KLIEP and LSIF both employ class-probability estimation (CPE) losses. Motivated by this, we formally relate DRE and CPE, and demonstrate the viability of using existing losses from one problem for the other. For the DRE problem, we show that essentially any CPE loss (eg logistic, exponential) can be used, as this equivalently minimises a Bregman divergence to the true density ratio. We show how different losses focus on accurately modelling different ranges of the density ratio, and use this to design new CPE losses for D

RE. For the CPE problem, we argue that the LSIF loss is useful in the regime whe

re one wishes to rank instances with maximal accuracy at the head of the ranking . In the course of our analysis, we establish a Bregman divergence identity that may be of independent interest.

Stochastic Variance Reduction for Nonconvex Optimization

Sashank J. Reddi, Ahmed Hefny, Suvrit Sra, Barnabas Poczos, Alex Smola

We study nonconvex finite-sum problems and analyze stochastic variance reduced g radient (SVRG) methods for them. SVRG and related methods have recently surged i nto prominence for convex optimization given their edge over stochastic gradient descent (SGD); but their theoretical analysis almost exclusively assumes convex ity. In contrast, we prove non-asymptotic rates of convergence (to stationary po ints) of SVRG for nonconvex optimization, and show that it is provably faster th an SGD and gradient descent. We also analyze a subclass of nonconvex problems on which SVRG attains linear convergence to the global optimum. We extend our anal ysis to mini-batch variants of SVRG, showing (theoretical) linear speedup due to minibatching in parallel settings.

Hierarchical Variational Models

Rajesh Ranganath, Dustin Tran, David Blei

Black box variational inference allows researchers to easily prototype and evalu ate an array of models. Recent advances allow such algorithms to scale to high d imensions. However, a central question remains: How to specify an expressive var iational distribution that maintains efficient computation? To address this, we develop hierarchical variational models (HVMs). HVMs augment a variational appro ximation with a prior on its parameters, which allows it to capture complex structure for both discrete and continuous latent variables. The algorithm we develop is black box, can be used for any HVM, and has the same computational efficiency as the original approximation. We study HVMs on a variety of deep discrete latent variable models. HVMs generalize other expressive variational distributions and maintains higher fidelity to the posterior.

Hierarchical Span-Based Conditional Random Fields for Labeling and Segmenting Events in Wearable Sensor Data Streams

Roy Adams, Nazir Saleheen, Edison Thomaz, Abhinav Parate, Santosh Kumar, Benjami n Marlin

The field of mobile health (mHealth) has the potential to yield new insights int o health and behavior through the analysis of continuously recorded data from we arable health and activity sensors. In this paper, we present a hierarchical span-based conditional random field model for the key problem of jointly detecting discrete events in such sensor data streams and segmenting these events into high-level activity sessions. Our model includes higher-order cardinality factors and inter-event duration factors to capture domain-specific structure in the label space. We show that our model supports exact MAP inference in quadratic time via dynamic programming, which we leverage to perform learning in the structured support vector machine framework. We apply the model to the problems of smoking and eating detection using four real data sets. Our results show statistically significant improvements in segmentation performance relative to a hierarchical pairwise CRF.

Binary embeddings with structured hashed projections

Anna Choromanska, Krzysztof Choromanski, Mariusz Bojarski, Tony Jebara, Sanjiv K umar, Yann LeCun

We consider the hashing mechanism for constructing binary embeddings, that involves pseudo-random projections followed by nonlinear (sign function) mappings. The pseudo-random projection is described by a matrix, where not all entries are independent random variables but instead a fixed "budget of randomness" is distributed across the matrix. Such matrices can be edfficiently stored in sub-quadratic or even linear space, provide reduction in randomness usage (i.e. number of required random values), and very often lead to computational speed ups. We prove several theoretical results showing that projections via various structured mat

rices followed by nonlinear mappings accurately preserve the angular distance be tween input high-dimensional vectors. To the best of our knowledge, these result s are the first that give theoretical ground for the use of general structured m atrices in the nonlinear setting. We empirically verify our theoretical findings and show the dependence of learning via structured hashed projections on the pe rformance of neural network as well as nearest neighbor classifier.

A Variational Analysis of Stochastic Gradient Algorithms Stephan Mandt, Matthew Hoffman, David Blei

Stochastic Gradient Descent (SGD) is an important algorithm in machine learning. With constant learning rates, it is a stochastic process that, after an initial phase of convergence, generates samples from a stationary distribution. We show that SGD with constant rates can be effectively used as an approximate posterio r inference algorithm for probabilistic modeling. Specifically, we show how to a djust the tuning parameters of SGD such as to match the resulting stationary distribution to the posterior. This analysis rests on interpreting SGD as a continu ous-time stochastic process and then minimizing the Kullback-Leibler divergence between its stationary distribution and the target posterior. (This is in the sp irit of variational inference.) In more detail, we model SGD as a multivariate O rnstein-Uhlenbeck process and then use properties of this process to derive the optimal parameters. This theoretical framework also connects SGD to modern scala ble inference algorithms; we analyze the recently proposed stochastic gradient F isher scoring under this perspective. We demonstrate that SGD with properly chos en constant rates gives a new way to optimize hyperparameters in probabilistic m odels

Adaptive Sampling for SGD by Exploiting Side Information Siddharth Gopal

This paper proposes a new mechanism for sampling training instances for stochast ic gradient descent (SGD) methods by exploiting any side-information associated with the instances (for e.g. class-labels) to improve convergence. Previous meth ods have either relied on sampling from a distribution defined over training instances or from a static distribution that fixed before training. This results in two problems a) any distribution that is set apriori is independent of how the optimization progresses and b) maintaining a distribution over individual instances could be infeasible in large-scale scenarios. In this paper, we exploit the side information associated with the instances to tackle both problems. More specifically, we maintain a distribution over classes (instead of individual instances) that is adaptively estimated during the course of optimization to give the maximum reduction in the variance of the gradient. Intuitively, we sample more from those regions in space that have a \textitlarger gradient contribution. Our experiments on highly multiclass datasets show that our proposal converge significantly faster than existing techniques.

Learning from Multiway Data: Simple and Efficient Tensor Regression Rose Yu, Yan Liu

Tensor regression has shown to be advantageous in learning tasks with multi-dire ctional relatedness. Given massive multiway data, traditional methods are often too slow to operate on or suffer from memory bottleneck. In this paper, we intro duce subsampled tensor projected gradient to solve the problem. Our algorithm is impressively simple and efficient. It is built upon projected gradient method w ith fast tensor power iterations, leveraging randomized sketching for further ac celeration. Theoretical analysis shows that our algorithm converges to the corre ct solution in fixed number of iterations. The memory requirement grows linearly with the size of the problem. We demonstrate superior empirical performance on both multi-linear multi-task learning and spatio-temporal applications.

A Distributed Variational Inference Framework for Unifying Parallel Sparse Gauss ian Process Regression Models

Trong Nghia Hoang, Quang Minh Hoang, Bryan Kian Hsiang Low

This paper presents a novel distributed variational inference framework that unifies many parallel sparse Gaussian process regression (SGPR) models for scalable hyperparameter learning with big data. To achieve this, our framework exploits a structure of correlated noise process model that represents the observation no ises as a finite realization of a high-order Gaussian Markov random process. By varying the Markov order and covariance function for the noise process model, different variational SGPR models result. This consequently allows the correlation structure of the noise process model to be characterized for which a particular variational SGPR model is optimal. We empirically evaluate the predictive performance and scalability of the distributed variational SGPR models unified by our framework on two real-world datasets.

Online Stochastic Linear Optimization under One-bit Feedback Lijun Zhang, Tianbao Yang, Rong Jin, Yichi Xiao, Zhi-hua Zhou

In this paper, we study a special bandit setting of online stochastic linear opt imization, where only one-bit of information is revealed to the learner at each round. This problem has found many applications including online advertisement a nd online recommendation. We assume the binary feedback is a random variable gen erated from the logit model, and aim to minimize the regret defined by the unkno wn linear function. Although the existing method for generalized linear bandit c an be applied to our problem, the high computational cost makes it impractical f or real-world applications. To address this challenge, we develop an efficient o nline learning algorithm by exploiting particular structures of the observation model. Specifically, we adopt online Newton step to estimate the unknown paramet er and derive a tight confidence region based on the exponential concavity of the logistic loss. Our analysis shows that the proposed algorithm achieves a regre t bound of O(d\sqrtT), which matches the optimal result of stochastic linear ban dits.

Adaptive Algorithms for Online Convex Optimization with Long-term Constraints Rodolphe Jenatton, Jim Huang, Cedric Archambeau

We present an adaptive online gradient descent algorithm to solve online convex optimization problems with long-term constraints, which are constraints that nee d to be satisfied when accumulated over a finite number of rounds T, but can be violated in intermediate rounds. For some user-defined trade-off parameter β in (0, 1), the proposed algorithm achieves cumulative regret bounds of $O(T^{\max}\beta,1_{\beta})$ and $O(T^{1}_{\beta}/2)$, respectively for the loss and the constraint violations. Our re sults hold for convex losses, can handle arbitrary convex constraints and rely on a single computationally efficient algorithm. Our contributions improve over the best known cumulative regret bounds of Mahdavi et al. (2012), which are respectively $O(T^{1}/2)$ and $O(T^{3}/4)$ for general convex domains, and respectively $O(T^{2}/3)$ and $O(T^{2}/3)$ when the domain is further restricted to be a polyhedral set. We supplement the analysis with experiments validating the performance of our algorithm in practice.

Actively Learning Hemimetrics with Applications to Eliciting User Preferences Adish Singla, Sebastian Tschiatschek, Andreas Krause

Motivated by an application of eliciting users' preferences, we investigate the problem of learning hemimetrics, i.e., pairwise distances among a set of n items that satisfy triangle inequalities and non-negativity constraints. In our application, the (asymmetric) distances quantify private costs a user incurs when sub stituting one item by another. We aim to learn these distances (costs) by asking the users whether they are willing to switch from one item to another for a giv en incentive offer. Without exploiting structural constraints of the hemimetric polytope, learning the distances between each pair of items requires $\Theta(n^2)$ quer ies. We propose an active learning algorithm that substantially reduces this sam ple complexity by exploiting the structural constraints on the version space of hemimetrics. Our proposed algorithm achieves provably-optimal sample complexity for various instances of the task. For example, when the items are embedded into K tight clusters, the sample complexity of our algorithm reduces to $O(n \ K)$. Ext

ensive experiments on a restaurant recommendation data set support the conclusions of our theoretical analysis.

Learning Simple Algorithms from Examples

Wojciech Zaremba, Tomas Mikolov, Armand Joulin, Rob Fergus

We present an approach for learning simple algorithms such as copying, multi-dig it addition and single digit multiplication directly from examples. Our framework consists of a set of interfaces, accessed by a controller. Typical interfaces are 1-D tapes or 2-D grids that hold the input and output data. For the controller, we explore a range of neural network-based models which vary in their ability to abstract the underlying algorithm from training instances and generalize to test examples with many thousands of digits. The controller is trained using Q-learning with several enhancements and we show that the bottleneck is in the capabilities of the controller rather than in the search incurred by Q-learning.

Learning Physical Intuition of Block Towers by Example

Adam Lerer, Sam Gross, Rob Fergus

Wooden blocks are a common toy for infants, allowing them to develop motor skill s and gain intuition about the physical behavior of the world. In this paper, we explore the ability of deep feed-forward models to learn such intuitive physics. Using a 3D game engine, we create small towers of wooden blocks whose stabilit y is randomized and render them collapsing (or remaining upright). This data all ows us to train large convolutional network models which can accurately predict the outcome, as well as estimating the trajectories of the blocks. The models ar e also able to generalize in two important ways: (i) to new physical scenarios, e.g. towers with an additional block and (ii) to images of real wooden blocks, w here it obtains a performance comparable to human subjects.

Structure Learning of Partitioned Markov Networks

Song Liu, Taiji Suzuki, Masashi Sugiyama, Kenji Fukumizu

We learn the structure of a Markov Network between two groups of random variable s from joint observations. Since modelling and learning the full MN structure may be hard, learning the links between two groups directly may be a preferable option. We introduce a novel concept called the \emphartitioned ratio whose factorization directly associates with the Markovian properties of random variables a cross two groups. A simple one-shot convex optimization procedure is proposed for learning the \empharties factorizations of the partitioned ratio and it is the oretically guaranteed to recover the correct inter-group structure under mild conditions. The performance of the proposed method is experimentally compared with the state of the art MN structure learning methods using ROC curves. Real applications on analyzing bipartisanship in US congress and pairwise DNA/time-series alignments are also reported.

Tracking Slowly Moving Clairvoyant: Optimal Dynamic Regret of Online Learning with True and Noisy Gradient

Tianbao Yang, Lijun Zhang, Rong Jin, Jinfeng Yi

This work focuses on dynamic regret of online convex optimization that compares the performance of online learning to a clairvoyant who knows the sequence of lo ss functions in advance and hence selects the minimizer of the loss function at each step. By assuming that the clairvoyant moves slowly (i.e., the minimizers c hange slowly), we present several improved variation-based upper bounds of the d ynamic regret under the true and noisy gradient feedback, which are \it optimal in light of the presented lower bounds. The key to our analysis is to explore a regularity metric that measures the temporal changes in the clairvoyant's minimi zers, to which we refer as path variation. Firstly, we present a general lower b ound in terms of the path variation, and then show that under full information or gradient feedback we are able to achieve an optimal dynamic regret. Secondly, we present a lower bound with noisy gradient feedback and then show that we can achieve optimal dynamic regrets under a stochastic gradient feedback and two-point bandit feedback. Moreover, for a sequence of smooth loss functions that admit

a small variation in the gradients, our dynamic regret under the two-point band it feedback matches that is achieved with full information.

Beyond CCA: Moment Matching for Multi-View Models

Anastasia Podosinnikova, Francis Bach, Simon Lacoste-Julien

We introduce three novel semi-parametric extensions of probabilistic canonical correlation analysis with identifiability guarantees. We consider moment matching techniques for estimation in these models. For that, by drawing explicit links between the new models and a discrete version of independent component analysis (DICA), we first extend the DICA cumulant tensors to the new discrete version of CCA. By further using a close connection with independent component analysis, we introduce generalized covariance matrices, which can replace the cumulant tensors in the moment matching framework, and, therefore, improve sample complexity and simplify derivations and algorithms significantly. As the tensor power method or orthogonal joint diagonalization are not applicable in the new setting, we use non-orthogonal joint diagonalization techniques for matching the cumulants. We demonstrate performance of the proposed models and estimation techniques on experiments with both synthetic and real datasets.

Fast methods for estimating the Numerical rank of large matrices $\mbox{\it Shashanka Ubaru}$, Yousef Saad

We present two computationally inexpensive techniques for estimating the numeric al rank of a matrix, combining powerful tools from computational linear algebra. These techniques exploit three key ingredients. The first is to approximate the projector on the non-null invariant subspace of the matrix by using a polynomia lilter. Two types of filters are discussed, one based on Hermite interpolation and the other based on Chebyshev expansions. The second ingredient employs stoc hastic trace estimators to compute the rank of this wanted eigen-projector, which yields the desired rank of the matrix. In order to obtain a good filter, it is necessary to detect a gap between the eigenvalues that correspond to noise and the relevant eigenvalues that correspond to the non-null invariant subspace. The third ingredient of the proposed approaches exploits the idea of spectral density, popular in physics, and the Lanczos spectroscopic method to locate this gap.

Unsupervised Deep Embedding for Clustering Analysis Junyuan Xie, Ross Girshick, Ali Farhadi

Clustering is central to many data-driven application domains and has been studi ed extensively in terms of distance functions and grouping algorithms. Relativel y little work has focused on learning representations for clustering. In this paper, we propose Deep Embedded Clustering (DEC), a method that simultaneously learns feature representations and cluster assignments using deep neural networks. DEC learns a mapping from the data space to a lower-dimensional feature space in which it iteratively optimizes a clustering objective. Our experimental evaluations on image and text corpora show significant improvement over state-of-the-art methods.

Efficient Private Empirical Risk Minimization for High-dimensional Learning Shiva Prasad Kasiviswanathan, Hongxia Jin

Dimensionality reduction is a popular approach for dealing with high dimensional data that leads to substantial computational savings. Random projections are a simple and effective method for universal dimensionality reduction with rigorous theoretical guarantees. In this paper, we theoretically study the problem of differentially private empirical risk minimization in the projected subspace (comp ressed domain). We ask: is it possible to design differentially private algorith ms with small excess risk given access to only projected data? In this paper, we answer this question in affirmative, by showing that for the class of generalized linear functions, given only the projected data and the projection matrix, we can obtain excess risk bounds of $0(w(Theta)^2/3/n^1/3)$ under eps-differential privacy, and $0(w(Theta)/n^1/2)$ under (eps,delta)-differential privacy, where n is the sample size and w(Theta) is the Gaussian width of the parameter space t

hat we optimize over. A simple consequence of these results is that, for a large class of ERM problems, in the traditional setting (i.e., with access to the ori ginal data), under eps-differential privacy, we improve the worst-case risk boun ds of Bassily et al. (FOCS 2014).

Parameter Estimation for Generalized Thurstone Choice Models Milan Vojnovic, Seyoung Yun

We consider the maximum likelihood parameter estimation problem for a generalize d Thurstone choice model, where choices are from comparison sets of two or more items. We provide tight characterizations of the mean square error, as well as n ecessary and sufficient conditions for correct classification when each item bel ongs to one of two classes. These results provide insights into how the estimati on accuracy depends on the choice of a generalized Thurstone choice model and the structure of comparison sets. We find that for a priori unbiased structures of comparisons, e.g., when comparison sets are drawn independently and uniformly a t random, the number of observations needed to achieve a prescribed estimation a ccuracy depends on the choice of a generalized Thurstone choice model. For a broad set of generalized Thurstone choice models, which includes all popular instances used in practice, the estimation error is shown to be largely insensitive to the cardinality of comparison sets. On the other hand, we found that there exist generalized Thurstone choice models for which the estimation error decreases m uch faster with the cardinality of comparison sets.

Large-Margin Softmax Loss for Convolutional Neural Networks

Weiyang Liu, Yandong Wen, Zhiding Yu, Meng Yang

Cross-entropy loss together with softmax is arguably one of the most common used supervision components in convolutional neural networks (CNNs). Despite its sim plicity, popularity and excellent performance, the component does not explicitly encourage discriminative learning of features. In this paper, we propose a gene ralized large-margin softmax (L-Softmax) loss which explicitly encourages intraclass compactness and inter-class separability between learned features. Moreove r, L-Softmax not only can adjust the desired margin but also can avoid overfitting. We also show that the L-Softmax loss can be optimized by typical stochastic gradient descent. Extensive experiments on four benchmark datasets demonstrate that the deeply-learned features with L-softmax loss become more discriminative, hence significantly boosting the performance on a variety of visual classification and verification tasks.

A Random Matrix Approach to Echo-State Neural Networks

Romain Couillet, Gilles Wainrib, Hafiz Tiomoko Ali, Harry Sevi

Recurrent neural networks, especially in their linear version, have provided man y qualitative insights on their performance under different configurations. This article provides, through a novel random matrix framework, the quantitative counterpart of these performance results, specifically in the case of echo-state networks. Beyond mere insights, our approach conveys a deeper understanding on the core mechanism under play for both training and testing.

Supervised and Semi-Supervised Text Categorization using LSTM for Region Embeddings

Rie Johnson, Tong Zhang

One-hot CNN (convolutional neural network) has been shown to be effective for te xt categorization (Johnson & Zhang, 2015). We view it as a special case of a gen eral framework which jointly trains a linear model with a non-linear feature gen erator consisting of 'text region embedding + pooling'. Under this framework, we explore a more sophisticated region embedding method using Long Short-Term Memo ry (LSTM). LSTM can embed text regions of variable (and possibly large) sizes, w hereas the region size needs to be fixed in a CNN. We seek effective and efficie nt use of LSTM for this purpose in the supervised and semi-supervised settings. The best results were obtained by combining region embeddings in the form of LST M and convolution layers trained on unlabeled data. The results indicate that on

this task, embeddings of text regions, which can convey complex concepts, are m ore useful than embeddings of single words in isolation. We report performances exceeding the previous best results on four benchmark datasets.

Optimality of Belief Propagation for Crowdsourced Classification Jungseul Ok, Sewoong Oh, Jinwoo Shin, Yung Yi

Crowdsourcing systems are popular for solving large-scale labelling tasks with 1 ow-paid (or even non-paid) workers. We study the problem of recovering the true labels from noisy crowdsourced labels under the popular Dawid-Skene model. To ad dress this inference problem, several algorithms have recently been proposed, but the best known guarantee is still significantly larger than the fundamental limit. We close this gap under a simple but canonical scenario where each worker is assigned at most two tasks. In particular, we introduce a tighter lower bound on the fundamental limit and prove that Belief Propagation (BP) exactly matches this lower bound. The guaranteed optimality of BP is the strongest in the sense that it is information-theoretically impossible for any other algorithm to correctly label a larger fraction of the tasks. In the general setting, when more than two tasks are assigned to each worker, we establish the dominance result on BP that it outperforms other existing algorithms with known provable guarantees. Experimental results suggest that BP is close to optimal for all regimes considered, while existing state-of-the-art algorithms exhibit suboptimal performances

Stability of Controllers for Gaussian Process Forward Models

Julia Vinogradska, Bastian Bischoff, Duy Nguyen-Tuong, Anne Romer, Henner Schmidt, Jan Peters

Learning control has become an appealing alternative to the derivation of control laws based on classic control theory. However, a major shortcoming of learning control is the lack of performance guarantees which prevents its application in many real-world scenarios. As a step in this direction, we provide a stability analysis tool for controllers acting on dynamics represented by Gaussian process es (GPs). We consider arbitrary Markovian control policies and system dynamics g iven as (i) the mean of a GP, and (ii) the full GP distribution. For the first c ase, our tool finds a state space region, where the closed-loop system is provably stable. In the second case, it is well known that infinite horizon stability guarantees cannot exist. Instead, our tool analyzes finite time stability. Empirical evaluations on simulated benchmark problems support our theoretical results

Learning privately from multiparty data Jihun Hamm, Yingjun Cao, Mikhail Belkin

Learning a classifier from private data distributed across multiple parties is a n important problem that has many potential applications. How can we build an ac curate and differentially private global classifier by combining locally-trained classifiers from different parties, without access to any party's private data? We propose to transfer the "knowledge" of the local classifier ensemble by firs t creating labeled data from auxiliary unlabeled data, and then train a global d ifferentially private classifier. We show that majority voting is too sensitive and therefore propose a new risk weighted by class probabilities estimated from the ensemble. Relative to a non-private solution, our private solution has a gen eralization error bounded by $O(\epsilon^-2 M^-2)$. This allows strong privacy without pe rformance loss when the number of participating parties M is large, such as in c rowdsensing applications. We demonstrate the performance of our framework with r ealistic tasks of activity recognition, network intrusion detection, and malicio us URL detection.

Network Morphism

Tao Wei, Changhu Wang, Yong Rui, Chang Wen Chen

We present a systematic study on how to morph a well-trained neural network to a new one so that its network function can be completely preserved. We define thi s as network morphism in this research. After morphing a parent network, the child network is expected to inherit the knowledge from its parent network and also has the potential to continue growing into a more powerful one with much shorte ned training time. The first requirement for this network morphism is its ability to handle diverse morphing types of networks, including changes of depth, width, kernel size, and even subnet. To meet this requirement, we first introduce the network morphism equations, and then develop novel morphing algorithms for all these morphing types for both classic and convolutional neural networks. The second requirement is its ability to deal with non-linearity in a network. We propose a family of parametric-activation functions to facilitate the morphing of any continuous non-linear activation neurons. Experimental results on benchmark datasets and typical neural networks demonstrate the effectiveness of the proposed network morphism scheme.

A Kronecker-factored approximate Fisher matrix for convolution layers Roger Grosse, James Martens

Second-order optimization methods such as natural gradient descent have the pote ntial to speed up training of neural networks by correcting for the curvature of the loss function. Unfortunately, the exact natural gradient is impractical to compute for large models, and most approximations either require an expensive it erative procedure or make crude approximations to the curvature. We present Kron ecker Factors for Convolution (KFC), a tractable approximation to the Fisher mat rix for convolutional networks based on a structured probabilistic model for the distribution over backpropagated derivatives. Similarly to the recently propose d Kronecker-Factored Approximate Curvature (K-FAC), each block of the approximat e Fisher matrix decomposes as the Kronecker product of small matrices, allowing for efficient inversion. KFC captures important curvature information while stil 1 yielding comparably efficient updates to stochastic gradient descent (SGD). We show that the updates are invariant to commonly used reparameterizations, such as centering of the activations. In our experiments, approximate natural gradien t descent with KFC was able to train convolutional networks several times faster than carefully tuned SGD. Furthermore, it was able to train the networks in 10-20 times fewer iterations than SGD, suggesting its potential applicability in a distributed setting.

Experimental Design on a Budget for Sparse Linear Models and Applications Sathya Narayanan Ravi, Vamsi Ithapu, Sterling Johnson, Vikas Singh Budget constrained optimal design of experiments is a classical problem in stati stics. Although the optimal design literature is very mature, few efficient stra tegies are available when these design problems appear in the context of sparse linear models commonly encountered in high dimensional machine learning and stat istics. In this work, we study experimental design for the setting where the und erlying regression model is characterized by a \ell_1-regularized linear functio n. We propose two novel strategies: the first is motivated geometrically whereas the second is algebraic in nature. We obtain tractable algorithms for this prob lem and also hold for a more general class of sparse linear models. We perform a n extensive set of experiments, on benchmarks and a large multi-site neuroscienc e study, showing that the proposed models are effective in practice. The latter experiment suggests that these ideas may play a small role in informing enrollme nt strategies for similar scientific studies in the short-to-medium term future.

Minding the Gaps for Block Frank-Wolfe Optimization of Structured SVMs Anton Osokin, Jean-Baptiste Alayrac, Isabella Lukasewitz, Puneet Dokania, Simon Lacoste-Julien

In this paper, we propose several improvements on the block-coordinate Frank-Wol fe (BCFW) algorithm from Lacoste-Julien et al. (2013) recently used to optimize the structured support vector machine (SSVM) objective in the context of structured prediction, though it has wider applications. The key intuition behind our improvements is that the estimates of block gaps maintained by BCFW reveal the block suboptimality that can be used as an *adaptive* criterion. First, we sample

objects at each iteration of BCFW in an adaptive non-uniform way via gap-based s ampling. Second, we incorporate pairwise and away-step variants of Frank-Wolfe i nto the block-coordinate setting. Third, we cache oracle calls with a cache-hit criterion based on the block gaps. Fourth, we provide the first method to comput e an approximate regularization path for SSVM. Finally, we provide an exhaustive empirical evaluation of all our methods on four structured prediction datasets.

Exact Exponent in Optimal Rates for Crowdsourcing Chao Gao, Yu Lu, Dengyong Zhou

Crowdsourcing has become a popular tool for labeling large datasets. This paper studies the optimal error rate for aggregating crowdsourced labels provided by a collection of amateur workers. Under the Dawid-Skene probabilistic model, we es tablish matching upper and lower bounds with an exact exponent mI(pi), where m is the number of workers and I(pi) is the average Chernoff information that cha racterizes the workers' collective ability. Such an exact characterization of the error exponent allows us to state a precise sample size requirement m \ge \frac{11}{pi} \log\frac1E in order to achieve an Emisclassification error. In addition , our results imply optimality of various forms of EM algorithms given accurate initializers of the model parameters.

Augmenting Supervised Neural Networks with Unsupervised Objectives for Large-sca le Image Classification

Yuting Zhang, Kibok Lee, Honglak Lee

Unsupervised learning and supervised learning are key research topics in deep le arning. However, as high-capacity supervised neural networks trained with a larg e amount of labels have achieved remarkable success in many computer vision task s, the availability of large-scale labeled images reduced the significance of un supervised learning. Inspired by the recent trend toward revisiting the importan ce of unsupervised learning, we investigate joint supervised and unsupervised le arning in a large-scale setting by augmenting existing neural networks with deco ding pathways for reconstruction. First, we demonstrate that the intermediate ac tivations of pretrained large-scale classification networks preserve almost all the information of input images except a portion of local spatial details. Then, by end-to-end training of the entire augmented architecture with the reconstruc tive objective, we show improvement of the network performance for supervised ta sks. We evaluate several variants of autoencoders, including the recently propos ed "what-where" autoencoder that uses the encoder pooling switches, to study the importance of the architecture design. Taking the 16-layer VGGNet trained under the ImageNet ILSVRC 2012 protocol as a strong baseline for image classification , our methods improve the validation-set accuracy by a noticeable margin.

Online Low-Rank Subspace Clustering by Basis Dictionary Pursuit Jie Shen, Ping Li, Huan Xu

Low-Rank Representation (LRR) has been a significant method for segmenting data that are generated from a union of subspaces. It is also known that solving LRR is challenging in terms of time complexity and memory footprint, in that the siz e of the nuclear norm regularized matrix is n-by-n (where n is the number of sam ples). In this paper, we thereby develop a novel online implementation of LRR th at reduces the memory cost from $O(n^2)$ to O(pd), with p being the ambient dimens ion and d being some estimated rank (d < p < n). We also establish the theoretic al guarantee that the sequence of solutions produced by our algorithm converges to a stationary point of the expected loss function asymptotically. Extensive ex periments on synthetic and realistic datasets further substantiate that our algorithm is fast, robust and memory efficient.

A Self-Correcting Variable-Metric Algorithm for Stochastic Optimization Frank Curtis

An algorithm for stochastic (convex or nonconvex) optimization is presented. The algorithm is variable-metric in the sense that, in each iteration, the step is computed through the product of a symmetric positive definite scaling matrix and

a stochastic (mini-batch) gradient of the objective function, where the sequence of scaling matrices is updated dynamically by the algorithm. A key feature of the algorithm is that it does not overly restrict the manner in which the scaling matrices are updated. Rather, the algorithm exploits fundamental self-correcting properties of BFGS-type updating—properties that have been over-looked in other attempts to devise quasi-Newton methods for stochastic optimization. Numerical experiments illustrate that the method and a limited memory variant of it are stable and outperform (mini-batch) stochastic gradient and other quasi-Newton methods when employed to solve a few machine learning problems.

Stochastic Quasi-Newton Langevin Monte Carlo

Umut Simsekli, Roland Badeau, Taylan Cemgil, Gaël Richard

Recently, Stochastic Gradient Markov Chain Monte Carlo (SG-MCMC) methods have be en proposed for scaling up Monte Carlo computations to large data problems. Whil st these approaches have proven useful in many applications, vanilla SG-MCMC mig ht suffer from poor mixing rates when random variables exhibit strong couplings under the target densities or big scale differences. In this study, we propose a novel SG-MCMC method that takes the local geometry into account by using ideas from Quasi-Newton optimization methods. These second order methods directly appr oximate the inverse Hessian by using a limited history of samples and their grad ients. Our method uses dense approximations of the inverse Hessian while keeping the time and memory complexities linear with the dimension of the problem. We p rovide a formal theoretical analysis where we show that the proposed method is a symptotically unbiased and consistent with the posterior expectations. We illust rate the effectiveness of the approach on both synthetic and real datasets. Our experiments on two challenging applications show that our method achieves fast c onvergence rates similar to Riemannian approaches while at the same time having low computational requirements similar to diagonal preconditioning approaches.

Doubly Robust Off-policy Value Evaluation for Reinforcement Learning Nan Jiang, Lihong Li

We study the problem of off-policy value evaluation in reinforcement learning (R L), where one aims to estimate the value of a new policy based on data collected by a different policy. This problem is often a critical step when applying RL to real-world problems. Despite its importance, existing general methods either have uncontrolled bias or suffer high variance. In this work, we extend the doubly robust estimator for bandits to sequential decision-making problems, which get sithe best of both worlds: it is guaranteed to be unbiased and can have a much lower variance than the popular importance sampling estimators. We demonstrate the estimator's accuracy in several benchmark problems, and illustrate its use as a subroutine in safe policy improvement. We also provide theoretical results on the inherent hardness of the problem, and show that our estimator can match the lower bound in certain scenarios.

Fast Rate Analysis of Some Stochastic Optimization Algorithms Chao Qu, Huan Xu, Chong Ong

In this paper, we revisit three fundamental and popular stochastic optimization algorithms (namely, Online Proximal Gradient, Regularized Dual Averaging method and ADMM with online proximal gradient) and analyze their convergence speed under conditions weaker than those in literature. In particular, previous works show ed that these algorithms converge at a rate of O (\ln T/T) when the loss function is strongly convex, and O (1 /\sqrtT) in the weakly convex case. In contrast, we relax the strong convexity assumption of the loss function, and show that the algorithms converge at a rate O (\ln T/T) if the \em expectation of the loss function is \em locally strongly convex. This is a much weaker assumption and is satisfied by many practical formulations including Lasso and Logistic Regression. Our analysis thus extends the applicability of these three methods, as well as provides a general recipe for improving analysis of convergence rate for stochas tic and online optimization algorithms.

Fast k-Nearest Neighbour Search via Dynamic Continuous Indexing Ke Li, Jitendra Malik

Existing methods for retrieving k-nearest neighbours suffer from the curse of di mensionality. We argue this is caused in part by inherent deficiencies of space partitioning, which is the underlying strategy used by most existing methods. We devise a new strategy that avoids partitioning the vector space and present a n ovel randomized algorithm that runs in time linear in dimensionality of the space and sub-linear in the intrinsic dimensionality and the size of the dataset and takes space constant in dimensionality of the space and linear in the size of the dataset. The proposed algorithm allows fine-grained control over accuracy and speed on a per-query basis, automatically adapts to variations in data density, supports dynamic updates to the dataset and is easy-to-implement. We show appealing theoretical properties and demonstrate empirically that the proposed algorithm outperforms locality-sensitivity hashing (LSH) in terms of approximation quality, speed and space efficiency.

Smooth Imitation Learning for Online Sequence Prediction

Hoang Le, Andrew Kang, Yisong Yue, Peter Carr

We study the problem of smooth imitation learning for online sequence prediction , where the goal is to train a policy that can smoothly imitate demonstrated beh avior in a dynamic and continuous environment in response to online, sequential context input. Since the mapping from context to behavior is often complex, we take a learning reduction approach to reduce smooth imitation learning to a regre ssion problem using complex function classes that are regularized to ensure smoothness. We present a learning meta-algorithm that achieves fast and stable convergence to a good policy. Our approach enjoys several attractive properties, including being fully deterministic, employing an adaptive learning rate that can provably yield larger policy improvements compared to previous approaches, and the ability to ensure stable convergence. Our empirical results demonstrate significant performance gains over previous approaches.

Community Recovery in Graphs with Locality

Yuxin Chen, Govinda Kamath, Changho Suh, David Tse

Motivated by applications in domains such as social networks and computational be iology, we study the problem of community recovery in graphs with locality. In this problem, pairwise noisy measurements of whether two nodes are in the same community or different communities come mainly or exclusively from nearby nodes rather than uniformly sampled between all node pairs, as in most existing models. We present two algorithms that run nearly linearly in the number of measurements

we present two algorithms that run nearly linearly in the number of measureme and which achieve the information limits for exact recovery.

Variance Reduction for Faster Non-Convex Optimization Zeyuan Allen-Zhu, Elad Hazan

We consider the fundamental problem in non-convex optimization of efficiently re aching a stationary point. In contrast to the convex case, in the long history of this basic problem, the only known theoretical results on first-order non-convex optimization remain to be full gradient descent that converges in O(1/\varepsilon) iterations for smooth objectives, and stochastic gradient descent that converges in O(1/\varepsilon^2) iterations for objectives that are sum of smooth functions. We provide the first improvement in this line of research. Our result is based on the variance reduction trick recently introduced to convex optimization, as well as a brand new analysis of variance reduction that is suitable for non-convex optimization. For objectives that are sum of smooth functions, our fir st-order minibatch stochastic method converges with an O(1/\varepsilon) rate, and is faster than full gradient descent by $\Omega(n^*1/3)$. We demonstrate the effective ness of our methods on empirical risk minimizations with non-convex loss functions and training neural nets.

Loss factorization, weakly supervised learning and label noise robustness Giorgio Patrini, Frank Nielsen, Richard Nock, Marcello Carioni

We prove that the empirical risk of most well-known loss functions factors into a linear term aggregating all labels with a term that is label free, and can fur ther be expressed by sums of the same loss. This holds true even for non-smooth, non-convex losses and in any RKHS. The first term is a (kernel) mean operator — the focal quantity of this work — which we characterize as the sufficient stati stic for the labels. The result tightens known generalization bounds and sheds n ew light on their interpretation. Factorization has a direct application on weak ly supervised learning. In particular, we demonstrate that algorithms like SGD a nd proximal methods can be adapted with minimal effort to handle weak supervision, once the mean operator has been estimated. We apply this idea to learning with asymmetric noisy labels, connecting and extending prior work. Furthermore, we show that most losses enjoy a data-dependent (by the mean operator) form of nois e robustness, in contrast with known negative results.

Analysis of Deep Neural Networks with Extended Data Jacobian Matrix Shengjie Wang, Abdel-rahman Mohamed, Rich Caruana, Jeff Bilmes, Matthai Plilipos e, Matthew Richardson, Krzysztof Geras, Gregor Urban, Ozlem Aslan Deep neural networks have achieved great successes on various machine learning t asks, however, there are many open fundamental questions to be answered. In this paper, we tackle the problem of quantifying the quality of learned wights of different networks with possibly different architectures, going beyond considering the final classification error as the only metric. We introduce \emphExtended D ata Jacobian Matrix to help analyze properties of networks of various structures, finding that, the spectrum of the extended data jacobian matrix is a strong discriminating factor for networks of different structures and performance. Based on such observation, we propose a novel regularization method, which manages to improve the network performance comparably to dropout, which in turn verifies the observation.

Doubly Decomposing Nonparametric Tensor Regression Masaaki Imaizumi, Kohei Hayashi

Nonparametric extension of tensor regression is proposed. Nonlinearity in a high -dimensional tensor space is broken into simple local functions by incorporating low-rank tensor decomposition. Compared to naive nonparametric approaches, our formulation considerably improves the convergence rate of estimation while maint aining consistency with the same function class under specific conditions. To es timate local functions, we develop a Bayesian estimator with the Gaussian proces s prior. Experimental results show its theoretical properties and high performan ce in terms of predicting a summary statistic of a real complex network.

Hyperparameter optimization with approximate gradient Fabian Pedregosa

Most models in machine learning contain at least one hyperparameter to control f or model complexity. Choosing an appropriate set of hyperparameters is both cruc ial in terms of model accuracy and computationally challenging. In this work we propose an algorithm for the optimization of continuous hyperparameters using in exact gradient information. An advantage of this method is that hyperparameters can be updated before model parameters have fully converged. We also give suffic ient conditions for the global convergence of this method, based on regularity c onditions of the involved functions and summability of errors. Finally, we valid ate the empirical performance of this method on the estimation of regularization constants of L2-regularized logistic regression and kernel Ridge regression. Empirical benchmarks indicate that our approach is highly competitive with respect to state of the art methods.

SDCA without Duality, Regularization, and Individual Convexity Shai Shalev-Shwartz

Stochastic Dual Coordinate Ascent is a popular method for solving regularized lo ss minimization for the case of convex losses. We describe variants of SDCA that do not require explicit regularization and do not rely on duality. We prove lin ear convergence rates even if individual loss functions are non-convex, as long as the expected loss is strongly convex.

Heteroscedastic Sequences: Beyond Gaussianity

Oren Anava, Shie Mannor

We address the problem of sequential prediction in the heteroscedastic setting, when both the signal and its variance are assumed to depend on explanatory varia bles. By applying regret minimization techniques, we devise an efficient online learning algorithm for the problem, without assuming that the error terms comply with a specific distribution. We show that our algorithm can be adjusted to pro vide confidence bounds for its predictions, and provide an application to ARCH m odels. The theoretic results are corroborated by an empirical study.

A Neural Autoregressive Approach to Collaborative Filtering

Yin Zheng, Bangsheng Tang, Wenkui Ding, Hanning Zhou

This paper proposes CF-NADE, a neural autoregressive architecture for collaborat ive filtering (CF) tasks, which is inspired by the Restricted Boltzmann Machine (RBM) based CF model and the Neural Autoregressive Distribution Estimator (NADE). We first describe the basic CF-NADE model for CF tasks. Then we propose to improve the model by sharing parameters between different ratings. A factored versi on of CF-NADE is also proposed for better scalability. Furthermore, we take the ordinal nature of the preferences into consideration and propose an ordinal cost to optimize CF-NADE, which shows superior performance. Finally, CF-NADE can be extended to a deep model, with only moderately increased computational complexity. Experimental results show that CF-NADE with a single hidden layer beats all previous state-of-the-art methods on MovieLens 1M, MovieLens 10M, and Netflix dat asets, and adding more hidden layers can further improve the performance.

On the Quality of the Initial Basin in Overspecified Neural Networks Itay Safran, Ohad Shamir

Deep learning, in the form of artificial neural networks, has achieved remarkable practical success in recent years, for a variety of difficult machine learning applications. However, a theoretical explanation for this remains a major open problem, since training neural networks involves optimizing a highly non-convex objective function, and is known to be computationally hard in the worst case. In this work, we study the \emphyseometric structure of the associated non-convex objective function, in the context of ReLU networks and starting from a random initialization of the network parameters. We identify some conditions under which it becomes more favorable to optimization, in the sense of (i) High probability of initializing at a point from which there is a monotonically decreasing path to a global minimum; and (ii) High probability of initializing at a basin (suitably defined) with a small minimal objective value. A common theme in our results is that such properties are more likely to hold for larger ("overspecified") ne tworks, which accords with some recent empirical and theoretical observations.

Primal-Dual Rates and Certificates

Celestine Dünner, Simone Forte, Martin Takac, Martin Jaggi

We propose an algorithm-independent framework to equip existing optimization met hods with primal-dual certificates. Such certificates and corresponding rate of convergence guarantees are important for practitioners to diagnose progress, in particular in machine learning applications. We obtain new primal-dual convergen ce rates, e.g., for the Lasso as well as many L1, Elastic Net, group Lasso and T V-regularized problems. The theory applies to any norm-regularized generalized l inear model. Our approach provides efficiently computable duality gaps which are globally defined, without modifying the original problems in the region of inte rest.

Minimizing the Maximal Loss: How and Why

Shai Shalev-Shwartz, Yonatan Wexler

A commonly used learning rule is to approximately minimize the \emphaverage loss

over the training set. Other learning algorithms, such as AdaBoost and hard-SVM, aim at minimizing the \emphmaximal loss over the training set. The average loss is more popular, particularly in deep learning, due to three main reasons. First, it can be conveniently minimized using online algorithms, that process few examples at each iteration. Second, it is often argued that there is no sense to minimize the loss on the training set too much, as it will not be reflected in the generalization loss. Last, the maximal loss is not robust to outliers. In this paper we describe and analyze an algorithm that can convert any online algorithm to a minimizer of the maximal loss. We show, theoretically and empirically, that in some situations better accuracy on the training set is crucial to obtain good performance on unseen examples. Last, we propose robust versions of the approach that can handle outliers.

The Information-Theoretic Requirements of Subspace Clustering with Missing Data Daniel Pimentel-Alarcon, Robert Nowak

Subspace clustering with missing data (SCMD) is a useful tool for analyzing incomplete datasets. Let d be the ambient dimension, and r the dimension of the subspaces. Existing theory shows that Nk = O(r d) columns per subspace are necessary for SCMD, and $Nk = O(\min d^{(\log d)}, d^{(r+1)})$ are sufficient. We close this gap, showing that Nk = O(r d) is also sufficient. To do this we derive deterministic sampling conditions for SCMD, which give precise information theoretic requirements and determine sampling regimes. These results explain the performance of SCMD algorithms from the literature. Finally, we give a practical algorithm to cert ify the output of any SCMD method deterministically.

Online Learning with Feedback Graphs Without the Graphs Alon Cohen, Tamir Hazan, Tomer Koren

We study an online learning framework introduced by Mannor and Shamir (2011) in which the feedback is specified by a graph, in a setting where the graph may var y from round to round and is \emphaser fully revealed to the learner. We show a large gap between the adversarial and the stochastic cases. In the adversarial case, we prove that even for dense feedback graphs, the learner cannot improve u pon a trivial regret bound obtained by ignoring any additional feedback besides her own loss. In contrast, in the stochastic case we give an algorithm that achi eves \widetilde\Theta(\sqrt\T) regret over T rounds, provided that the independence n umbers of the hidden feedback graphs are at most \Theta. We also extend our results to a more general feedback model, in which the learner does not necessarily obser ve her own loss, and show that, even in simple cases, concealing the feedback graphs might render the problem unlearnable.

PAC learning of Probabilistic Automaton based on the Method of Moments Hadrien Glaude, Olivier Pietquin

Probabilitic Finite Automata (PFA) are generative graphical models that define d istributions with latent variables over finite sequences of symbols, a.k.a. stoc hastic languages. Traditionally, unsupervised learning of PFA is performed throu gh algorithms that iteratively improves the likelihood like the Expectation-Maxi mization (EM) algorithm. Recently, learning algorithms based on the so-called Me thod of Moments (MoM) have been proposed as a much faster alternative that comes with PAC-style guarantees. However, these algorithms do not ensure the learnt a utomata to model a proper distribution, limiting their applicability and prevent ing them to serve as an initialization to iterative algorithms. In this paper, we propose a new MoM-based algorithm with PAC-style guarantees that learns automa ta defining proper distributions. We assess its performances on synthetic problems from the PAutomaC challenge and real datasets extracted from Wikipedia agains to previous MoM-based algorithms and EM algorithm.

Estimating Structured Vector Autoregressive Models

Igor Melnyk, Arindam Banerjee

While considerable advances have been made in estimating high-dimensional struct ured models from independent data using Lasso-type models, limited progress has

been made for settings when the samples are dependent. We consider estimating st ructured VAR (vector auto-regressive model), where the structure can be captured by any suitable norm, e.g., Lasso, group Lasso, order weighted Lasso, etc. In V AR setting with correlated noise, although there is strong dependence over time and covariates, we establish bounds on the non-asymptotic estimation error of st ructured VAR parameters. The estimation error is of the same order as that of th e corresponding Lasso-type estimator with independent samples, and the analysis holds for any norm. Our analysis relies on results in generic chaining, sub-exponential martingales, and spectral representation of VAR models. Experimental results on synthetic and real data with a variety of structures are presented, validating theoretical results.

Mixing Rates for the Alternating Gibbs Sampler over Restricted Boltzmann Machine s and Friends

Christopher Tosh

Alternating Gibbs sampling is a modification of classical Gibbs sampling where s everal variables are simultaneously sampled from their joint conditional distribution. In this work, we investigate the mixing rate of alternating Gibbs sampling with a particular emphasis on Restricted Boltzmann Machines (RBMs) and variants

Polynomial Networks and Factorization Machines: New Insights and Efficient Train ing Algorithms

Mathieu Blondel, Masakazu Ishihata, Akinori Fujino, Naonori Ueda

Polynomial networks and factorization machines are two recently-proposed models that can efficiently use feature interactions in classification and regression t asks. In this paper, we revisit both models from a unified perspective. Based on this new view, we study the properties of both models and propose new efficient training algorithms. Key to our approach is to cast parameter learning as a low -rank symmetric tensor estimation problem, which we solve by multi-convex optimi zation. We demonstrate our approach on regression and recommender system tasks.

A New PAC-Bayesian Perspective on Domain Adaptation

Pascal Germain, Amaury Habrard, François Laviolette, Emilie Morvant

We study the issue of PAC-Bayesian domain adaptation: We want to learn, from a source domain, a majority vote model dedicated to a target one. Our theoretical contribution brings a new perspective by deriving an upper-bound on the target risk where the distributions' divergence - expressed as a ratio - controls the trade-off between a source error measure and the target voters' disagreement. Our bound suggests that one has to focus on regions where the source data is informative. From this result, we derive a PAC-Bayesian generalization bound, and specialize it to linear classifiers. Then, we infer a learning algorithm and perform experiments on real data.

Correlation Clustering and Biclustering with Locally Bounded Errors Gregory Puleo, Olgica Milenkovic

We consider a generalized version of the correlation clustering problem, defined as follows. Given a complete graph G whose edges are labeled with + or -, we wi sh to partition the graph into clusters while trying to avoid errors: + edges be tween clusters or - edges within clusters. Classically, one seeks to minimize the e total number of such errors. We introduce a new framework that allows the objective to be a more general function of the number of errors at each vertex (for example, we may wish to minimize the number of errors at the worst vertex) and provide a rounding algorithm which converts "fractional clusterings" into discrete clusterings while causing only a constant-factor blowup in the number of errors at each vertex. This rounding algorithm yields constant-factor approximation a lgorithms for the discrete problem under a wide variety of objective functions.

PAC Lower Bounds and Efficient Algorithms for The Max K-Armed Bandit Problem Yahel David, Nahum Shimkin

We consider the Max K-Armed Bandit problem, where a learning agent is faced with several stochastic arms, each a source of i.i.d. rewards of unknown distribution. At each time step the agent chooses an arm, and observes the reward of the obtained sample. Each sample is considered here as a separate item with the reward designating its value, and the goal is to find an item with the highest possible value. Our basic assumption is a known lower bound on the \em tail function of the reward distributions. Under the PAC framework, we provide a lower bound on the sample complexity of any (ϵ, δ) -correct algorithm, and propose an algorithm that attains this bound up to logarithmic factors. We provide an analysis of the robustness of the proposed algorithm to the model assumptions, and further compare its performance to the simple non-adaptive variant, in which the arms are chosen randomly at each stage.

A Comparative Analysis and Study of Multiview CNN Models for Joint Object Catego rization and Pose Estimation

Mohamed Elhoseiny, Tarek El-Gaaly, Amr Bakry, Ahmed Elgammal

In the Object Recognition task, there exists a dichotomy between the categorizat ion of objects and estimating object pose, where the former necessitates a view-invariant representation, while the latter requires a representation capable of capturing pose information over different categories of objects. With the rise of deep architectures, the prime focus has been on object category recognition. Deep learning methods have achieved wide success in this task. In contrast, object pose estimation using these approaches has received relatively less attention. In this work, we study how Convolutional Neural Networks (CNN) architectures can be adapted to the task of simultaneous object recognition and pose estimation. We investigate and analyze the layers of various CNN models and extensively compare between them with the goal of discovering how the layers of distributed representations within CNNs represent object pose information and how this contradicts with object category representations. We extensively experiment on two recent large and challenging multi-view datasets and we achieve better than the state-of-the-art.

BASC: Applying Bayesian Optimization to the Search for Global Minima on Potentia l Energy Surfaces

Shane Carr, Roman Garnett, Cynthia Lo

We present a novel application of Bayesian optimization to the field of surface science: rapidly and accurately searching for the global minimum on potential en ergy surfaces. Controlling molecule-surface interactions is key for applications ranging from environmental catalysis to gas sensing. We present pragmatic techn iques, including exploration/exploitation scheduling and a custom covariance ker nel that encodes the properties of our objective function. Our method, the Bayes ian Active Site Calculator (BASC), outperforms differential evolution and constrained minima hopping – two state-of-the-art approaches – in trial examples of carbon monoxide adsorption on a hematite substrate, both with and without a defect

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On the Iteration Complexity of Oblivious First-Order Optimization Algorithms Yossi Arjevani, Ohad Shamir

We consider a broad class of first-order optimization algorithms which are \emph oblivious, in the sense that their step sizes are scheduled regardless of the function under consideration, except for limited side-information such as smoothness or strong convexity parameters. With the knowledge of these two parameters, we show that any such algorithm attains an iteration complexity lower bound of $\Omega(\sqrtL/\epsilon)$ for L-smooth convex functions, and $\tilde\Omega(\sqrtL/\mu\ln(1/\epsilon))$ for L-smooth μ -strongly convex functions. These lower bounds are stronger than those in the traditional oracle model, as they hold independently of the dimension. To attain these, we abandon the oracle model in favor of a structure-based approach which builds upon a framework recently proposed in Arjevani et al. (2015). We further show that without knowing the strong convexity parameter, it is impossible to attain an iteration complexity better than $\tilde\Omega\sqrt(L/\mu)\ln(1/\epsilon)$. This res

ult is then used to formalize an observation regarding L-smooth convex functions , namely, that the iteration complexity of algorithms employing time-invariant s tep sizes must be at least $\Omega(L/\epsilon)$.

Stochastic Variance Reduced Optimization for Nonconvex Sparse Learning Xingguo Li, Tuo Zhao, Raman Arora, Han Liu, Jarvis Haupt

We propose a stochastic variance reduced optimization algorithm for solving a cl ass of large-scale nonconvex optimization problems with cardinality constraints, and provide sufficient conditions under which the proposed algorithm enjoys str ong linear convergence guarantees and optimal estimation accuracy in high dimens ions. Numerical experiments demonstrate the efficiency of our method in terms of both parameter estimation and computational performance.

Analysis of Variational Bayesian Factorizations for Sparse and Low-Rank Estimation

David Wipf

Variational Bayesian (VB) approximations anchor a wide variety of probabilistic models, where tractable posterior inference is almost never possible. Typically based on the so-called VB mean-field approximation to the Kullback-Leibler diver gence, a posterior distribution is sought that factorizes across groups of laten t variables such that, with the distributions of all but one group of variables held fixed, an optimal closed-form distribution can be obtained for the remainin g group, with differing algorithms distinguished by how different variables are grouped and ultimately factored. This basic strategy is particularly attractive when estimating structured low-dimensional models of high-dimensional data, exem plified by the search for minimal rank and/or sparse approximations to observed data. To this end, VB models are frequently deployed across applications includi ng multi-task learning, robust PCA, subspace clustering, matrix completion, affi ne rank minimization, source localization, compressive sensing, and assorted com binations thereof. Perhaps surprisingly however, there exists almost no attendan t theoretical explanation for how various VB factorizations operate, and in whic h situations one may be preferable to another. We address this relative void by comparing arguably two of the most popular factorizations, one built upon Gaussi an scale mixture priors, the other bilinear Gaussian priors, both of which can f avor minimal rank or sparsity depending on the context. More specifically, by re expressing the respective VB objective functions, we weigh multiple factors rela ted to local minima avoidance, feature transformation invariance and correlation , and computational complexity to arrive at insightful conclusions useful in exp laining performance and deciding which VB flavor is advantageous. We also envisi on that the principles explored here are quite relevant to other structured inve rse problems where VB serves as a viable solution.

Fast k-means with accurate bounds James Newling, Francois Fleuret

We propose a novel accelerated exact k-means algorithm, which outperforms the current state-of-the-art low-dimensional algorithm in 18 of 22 experiments, running up to 3 times faster. We also propose a general improvement of existing state-of-the-art accelerated exact k-means algorithms through better estimates of the distance bounds used to reduce the number of distance calculations, obtaining speedups in 36 of 44 experiments, of up to 1.8 times. We have conducted experiments with our own implementations of existing methods to ensure homogeneous evaluation of performance, and we show that our implementations perform as well or better than existing available implementations. Finally, we propose simplified variants of standard approaches and show that they are faster than their fully-fledged counterparts in 59 of 62 experiments.

Boolean Matrix Factorization and Noisy Completion via Message Passing Siamak Ravanbakhsh, Barnabas Poczos, Russell Greiner

Boolean matrix factorization and Boolean matrix completion from noisy observations are desirable unsupervised data-analysis methods due to their interpretabilit

y, but hard to perform due to their NP-hardness. We treat these problems as maxi mum a posteriori inference problems in a graphical model and present a message p assing approach that scales linearly with the number of observations and factors . Our empirical study demonstrates that message passing is able to recover low-r ank Boolean matrices, in the boundaries of theoretically possible recovery and c ompares favorably with state-of-the-art in real-world applications, such collabo rative filtering with large-scale Boolean data.

Convolutional Rectifier Networks as Generalized Tensor Decompositions Nadav Cohen, Amnon Shashua

Convolutional rectifier networks, i.e. convolutional neural networks with rectif ied linear activation and max or average pooling, are the cornerstone of modern deep learning. However, despite their wide use and success, our theoretical unde rstanding of the expressive properties that drive these networks is partial at b est. On the other hand, we have a much firmer grasp of these issues in the world of arithmetic circuits. Specifically, it is known that convolutional arithmetic circuits possess the property of "complete depth efficiency", meaning that besi des a negligible set, all functions realizable by a deep network of polynomial s ize, require exponential size in order to be realized (or approximated) by a sha llow network. In this paper we describe a construction based on generalized tens or decompositions, that transforms convolutional arithmetic circuits into convol utional rectifier networks. We then use mathematical tools available from the wo rld of arithmetic circuits to prove new results. First, we show that convolution al rectifier networks are universal with max pooling but not with average poolin g. Second, and more importantly, we show that depth efficiency is weaker with co nvolutional rectifier networks than it is with convolutional arithmetic circuits . This leads us to believe that developing effective methods for training convol utional arithmetic circuits, thereby fulfilling their expressive potential, may give rise to a deep learning architecture that is provably superior to convoluti onal rectifier networks but has so far been overlooked by practitioners.

Low-rank Solutions of Linear Matrix Equations via Procrustes Flow Stephen Tu, Ross Boczar, Max Simchowitz, Mahdi Soltanolkotabi, Ben Recht In this paper we study the problem of recovering a low-rank matrix from linear measurements. Our algorithm, which we call Procrustes Flow, starts from an initial estimate obtained by a thresholding scheme followed by gradient descent on a non-convex objective. We show that as long as the measurements obey a standard restricted isometry property, our algorithm converges to the unknown matrix at a geometric rate. In the case of Gaussian measurements, such convergence occurs for a nl \times n2 matrix of rank r when the number of measurements exceeds a constant times (n1 + n2)r.

Anytime Exploration for Multi-armed Bandits using Confidence Information Kwang-Sung Jun, Robert Nowak

We introduce anytime Explore-m, a pure exploration problem for multi-armed bandi ts (MAB) that requires making a prediction of the top-m arms at every time step. Anytime Explore-m is more practical than fixed budget or fixed confidence formu lations of the top-m problem, since many applications involve a finite, but unpredictable, budget. However, the development and analysis of anytime algorithms present many challenges. We propose AT-LUCB (AnyTime Lower and Upper Confidence Bound), the first nontrivial algorithm that provably solves anytime Explore-m. Our analysis shows that the sample complexity of AT-LUCB is competitive to anytime variants of existing algorithms. Moreover, our empirical evaluation on AT-LUCB shows that AT-LUCB performs as well as or better than state-of-the-art baseline methods for anytime Explore-m.

Structured Prediction Energy Networks

David Belanger, Andrew McCallum

We introduce structured prediction energy networks (SPENs), a flexible framework for structured prediction. A deep architecture is used to define an energy func

tion of candidate labels, and then predictions are produced by using back-propag ation to iteratively optimize the energy with respect to the labels. This deep a rchitecture captures dependencies between labels that would lead to intractable graphical models, and performs structure learning by automatically learning disc riminative features of the structured output. One natural application of our tec hnique is multi-label classification, which traditionally has required strict pr ior assumptions about the interactions between labels to ensure tractable learni ng and prediction. We are able to apply SPENs to multi-label problems with subst antially larger label sets than previous applications of structured prediction, while modeling high-order interactions using minimal structural assumptions. Ove rall, deep learning provides remarkable tools for learning features of the input s to a prediction problem, and this work extends these techniques to learning fe atures of structured outputs. Our experiments provide impressive performance on a variety of benchmark multi-label classification tasks, demonstrate that our te chnique can be used to provide interpretable structure learning, and illuminate fundamental trade-offs between feed-forward and iterative structured prediction. **********

L1-regularized Neural Networks are Improperly Learnable in Polynomial Time Yuchen Zhang, Jason D. Lee, Michael I. Jordan

We study the improper learning of multi-layer neural networks. Suppose that the neural network to be learned has k hidden layers and that the \ell_1-norm of the incoming weights of any neuron is bounded by L. We present a kernel-based metho d, such that with probability at least $1-\delta$, it learns a predictor whose genera lization error is at most Eworse than that of the neural network. The sample com plexity and the time complexity of the presented method are polynomial in the in put dimension and in $(1/\epsilon, \log(1/\delta), F(k, L))$, where F(k, L) is a function dependin g on (k, L) and on the activation function, independent of the number of neurons. The algorithm applies to both sigmoid-like activation functions and ReLU-like a ctivation functions. It implies that any sufficiently sparse neural network is learnable in polynomial time.

Compressive Spectral Clustering

Nicolas Tremblay, Gilles Puy, Remi Gribonval, Pierre Vandergheynst

Spectral clustering has become a popular technique due to its high performance in many contexts. It comprises three main steps: create a similarity graph between N objects to cluster, compute the first k eigenvectors of its Laplacian matrix to define a feature vector for each object, and run k-means on these features to separate objects into k classes. Each of these three steps becomes computation ally intensive for large N and/or k. We propose to speed up the last two steps be ased on recent results in the emerging field of graph signal processing: graph f iltering of random signals, and random sampling of bandlimited graph signals. We prove that our method, with a gain in computation time that can reach several or reders of magnitude, is in fact an approximation of spectral clustering, for which we are able to control the error. We test the performance of our method on art ificial and real-world network data.

Low-rank tensor completion: a Riemannian manifold preconditioning approach Hiroyuki Kasai, Bamdev Mishra

We propose a novel Riemannian manifold preconditioning approach for the tensor c ompletion problem with rank constraint. A novel Riemannian metric or inner product is proposed that exploits the least-squares structure of the cost function and takes into account the structured symmetry that exists in Tucker decomposition. The specific metric allows to use the versatile framework of Riemannian optimization on quotient manifolds to develop preconditioned nonlinear conjugate gradient and stochastic gradient descent algorithms in batch and online setups, respectively. Concrete matrix representations of various optimization-related ingredients are listed. Numerical comparisons suggest that our proposed algorithms robustly outperform state-of-the-art algorithms across different synthetic and real-world datasets.

Provable Non-convex Phase Retrieval with Outliers: Median TruncatedWirtinger Flow

Huishuai Zhang, Yuejie Chi, Yingbin Liang

Solving systems of quadratic equations is a central problem in machine learning and signal processing. One important example is phase retrieval, which aims to r ecover a signal from only magnitudes of its linear measurements. This paper focu ses on the situation when the measurements are corrupted by arbitrary outliers, for which the recently developed non-convex gradient descent Wirtinger flow (WF) and truncated Wirtinger flow (TWF) algorithms likely fail. We develop a novel m edian-TWF algorithm that exploits robustness of sample median to resist arbitrar y outliers in the initialization and the gradient update in each iteration. We s how that such a non-convex algorithm provably recovers the signal from a near-op timal number of measurements composed of i.i.d. Gaussian entries, up to a logari thmic factor, even when a constant portion of the measurements are corrupted by arbitrary outliers. We further show that median-TWF is also robust when measurem ents are corrupted by both arbitrary outliers and bounded noise. Our analysis of performance guarantee is accomplished by development of non-trivial concentrati on measures of median-related quantities, which may be of independent interest. We further provide numerical experiments to demonstrate the effectiveness of the approach.

Estimating Maximum Expected Value through Gaussian Approximation

Carlo D'Eramo, Marcello Restelli, Alessandro Nuara

This paper is about the estimation of the maximum expected value of a set of ind ependent random variables. The performance of several learning algorithms (e.g., Q-learning) is affected by the accuracy of such estimation. Unfortunately, no unbiased estimator exists. The usual approach of taking the maximum of the sample means leads to large overestimates that may significantly harm the performance of the learning algorithm. Recent works have shown that the cross validation estimator—which is negatively biased—outperforms the maximum estimator in many sequential decision—making scenarios. On the other hand, the relative performance of the two estimators is highly problem—dependent. In this paper, we propose a new estimator for the maximum expected value, based on a weighted average of the sample means, where the weights are computed using Gaussian approximations for the distributions of the sample means. We compare the proposed estimator with the of the state—of—the—art methods both theoretically, by deriving upper bounds to the bias and the variance of the estimator, and empirically, by testing the performance on different sequential learning problems.

Representational Similarity Learning with Application to Brain Networks Urvashi Oswal, Christopher Cox, Matthew Lambon-Ralph, Timothy Rogers, Robert Now ak

Representational Similarity Learning (RSL) aims to discover features that are im portant in representing (human-judged) similarities among objects. RSL can be po sed as a sparsity-regularized multi-task regression problem. Standard methods, like group lasso, may not select important features if they are strongly correlated with others. To address this shortcoming we present a new regularizer for multitask regression called Group Ordered Weighted \ell_1 (GrOWL). Another key contribution of our paper is a novel application to fMRI brain imaging. Representational Similarity Analysis (RSA) is a tool for testing whether localized brain regions encode perceptual similarities. Using GrOWL, we propose a new approach called Network RSA that can discover arbitrarily structured brain networks (possibly widely distributed and non-local) that encode similarity information. We show, in theory and fMRI experiments, how GrOWL deals with strongly correlated covariates.

Dropout as a Bayesian Approximation: Representing Model Uncertainty in Deep Lear ning

Yarin Gal, Zoubin Ghahramani

Deep learning tools have gained tremendous attention in applied machine learning

. However such tools for regression and classification do not capture model unce rtainty. In comparison, Bayesian models offer a mathematically grounded framework to reason about model uncertainty, but usually come with a prohibitive computa tional cost. In this paper we develop a new theoretical framework casting dropout training in deep neural networks (NNs) as approximate Bayesian inference in de ep Gaussian processes. A direct result of this theory gives us tools to model un certainty with dropout NNs - extracting information from existing models that has been thrown away so far. This mitigates the problem of representing uncertainty in deep learning without sacrificing either computational complexity or test a ccuracy. We perform an extensive study of the properties of dropout's uncertainty. Various network architectures and non-linearities are assessed on tasks of regression and classification, using MNIST as an example. We show a considerable i mprovement in predictive log-likelihood and RMSE compared to existing state-of-the-art methods, and finish by using dropout's uncertainty in deep reinforcement learning.

Generative Adversarial Text to Image Synthesis

Scott Reed, Zeynep Akata, Xinchen Yan, Lajanugen Logeswaran, Bernt Schiele, Hong lak Lee

Automatic synthesis of realistic images from text would be interesting and useful, but current AI systems are still far from this goal. However, in recent years generic and powerful recurrent neural network architectures have been developed to learn discriminative text feature representations. Meanwhile, deep convolutional generative adversarial networks (GANs) have begun to generate highly compelling images of specific categories such as faces, album covers, room interiors and flowers. In this work, we develop a novel deep architecture and GAN formulation to effectively bridge these advances in text and image modeling, translating visual concepts from characters to pixels. We demonstrate the capability of our model to generate plausible images of birds and flowers from detailed text descriptions.

Dirichlet Process Mixture Model for Correcting Technical Variation in Single-Cel l Gene Expression Data

Sandhya Prabhakaran, Elham Azizi, Ambrose Carr, Dana Pe'er

We introduce an iterative normalization and clustering method for single-cell ge ne expression data. The emerging technology of single-cell RNA-seq gives access to gene expression measurements for thousands of cells, allowing discovery and c haracterization of cell types. However, the data is confounded by technical variation emanating from experimental errors and cell type-specific biases. Current approaches perform a global normalization prior to analyzing biological signals, which does not resolve missing data or variation dependent on latent cell types. Our model is formulated as a hierarchical Bayesian mixture model with cell-specific scalings that aid the iterative normalization and clustering of cells, teasing apart technical variation from biological signals. We demonstrate that this approach is superior to global normalization followed by clustering. We show id entifiability and weak convergence guarantees of our method and present a scalable Gibbs inference algorithm. This method improves cluster inference in both synthetic and real single-cell data compared with previous methods, and allows easy interpretation and recovery of the underlying structure and cell types.

Improved SVRG for Non-Strongly-Convex or Sum-of-Non-Convex Objectives Zeyuan Allen-Zhu, Yang Yuan

Many classical algorithms are found until several years later to outlive the con fines in which they were conceived, and continue to be relevant in unforeseen se ttings. In this paper, we show that SVRG is one such method: being originally de signed for strongly convex objectives, it is also very robust in non-strongly co nvex or sum-of-non-convex settings. More precisely, we provide new analysis to i mprove the state-of-the-art running times in both settings by either applying SV RG or its novel variant. Since non-strongly convex objectives include important examples such as Lasso or logistic regression, and sum-of-non-convex objectives

include famous examples such as stochastic PCA and is even believed to be relate d to training deep neural nets, our results also imply better performances in th ese applications.

Sparse Parameter Recovery from Aggregated Data Avradeep Bhowmik, Joydeep Ghosh, Oluwasanmi Koyejo

Data aggregation is becoming an increasingly common technique for sharing sensit ive information, and for reducing data size when storage and/or communication co sts are high. Aggregate quantities such as group-average are a form of semi-supe rvision as they do not directly provide information of individual values, but de spite their wide-spread use, prior literature on learning individual-level model s from aggregated data is extremely limited. This paper investigates the effect of data aggregation on parameter recovery for a sparse linear model, when known results are no longer applicable. In particular, we consider a scenario where th e data are collected into groups e.g. aggregated patient records, and first-orde r empirical moments are available only at the group level. Despite this obfuscat ion of individual data values, we can show that the true parameter is recoverabl e with high probability using these aggregates when the collection of true group moments is an incoherent matrix, and the empirical moment estimates have been c omputed from a sufficiently large number of samples. To the best of our knowledg e, ours are the first results on structured parameter recovery using only aggreg ated data. Experimental results on synthetic data are provided in support of the se theoretical claims. We also show that parameter estimation from aggregated da ta approaches the accuracy of parameter estimation obtainable from non-aggregate d or "individual" samples, when applied to two real world healthcare application s- predictive modeling of CMS Medicare reimbursement claims, and modeling of Tex as State healthcare charges.

Deep Structured Energy Based Models for Anomaly Detection Shuangfei Zhai, Yu Cheng, Weining Lu, Zhongfei Zhang

In this paper, we attack the anomaly detection problem by directly modeling the data distribution with deep architectures. We hence propose deep structured ener gy based models (DSEBMs), where the energy function is the output of a determini stic deep neural network with structure. We develop novel model architectures to integrate EBMs with different types of data such as static data, sequential dat a, and spatial data, and apply appropriate model architectures to adapt to the d ata structure. Our training algorithm is built upon the recent development of sc ore matching (Hyvarinen, 2005), which connects an EBM with a regularized autoenc oder, eliminating the need for complicated sampling method. Statistically sound decision criterion can be derived for anomaly detection purpose from the perspec tive of the energy landscape of the data distribution. We investigate two decisi on criteria for performing anomaly detection: the energy score and the reconstruction error. Extensive empirical studies on benchmark anomaly detection tasks de monstrate that our proposed model consistently matches or outperforms all the competing methods.

Even Faster Accelerated Coordinate Descent Using Non-Uniform Sampling Zeyuan Allen-Zhu, Zheng Qu, Peter Richtarik, Yang Yuan

Accelerated coordinate descent is widely used in optimization due to its cheap p er-iteration cost and scalability to large-scale problems. Up to a primal-dual t ransformation, it is also the same as accelerated stochastic gradient descent th at is one of the central methods used in machine learning. In this paper, we imp rove the best known running time of accelerated coordinate descent by a factor u p to \sqrtn. Our improvement is based on a clean, novel non-uniform sampling that t selects each coordinate with a probability proportional to the square root of its smoothness parameter. Our proof technique also deviates from the classical e stimation sequence technique used in prior work. Our speed-up applies to important problems such as empirical risk minimization and solving linear systems, both in theory and in practice.

Unitary Evolution Recurrent Neural Networks Martin Arjovsky, Amar Shah, Yoshua Bengio

Recurrent neural networks (RNNs) are notoriously difficult to train. When the eigenvalues of the hidden to hidden weight matrix deviate from absolute value 1, optimization becomes difficult due to the well studied issue of vanishing and exploding gradients, especially when trying to learn long-term dependencies. To circumvent this problem, we propose a new architecture that learns a unitary weight matrix, with eigenvalues of absolute value exactly 1. The challenge we address is that of parametrizing unitary matrices in a way that does not require expensive computations (such as eigendecomposition) after each weight update. We construct an expressive unitary weight matrix by composing several structured matrices that act as building blocks with parameters to be learned. Optimization with this parameterization becomes feasible only when considering hidden states in the complex domain. We demonstrate the potential of this architecture by achieving state of the art results in several hard tasks involving very long-term dependencies.

Markov Latent Feature Models Aonan Zhang, John Paisley

We introduce Markov latent feature models (MLFM), a sparse latent feature model that arises naturally from a simple sequential construction. The key idea is to interpret each state of a sequential process as corresponding to a latent featur e, and the set of states visited between two null-state visits as picking out fe atures for an observation. We show that, given some natural constraints, we can represent this stochastic process as a mixture of recurrent Markov chains. In th is way we can perform correlated latent feature modeling for the sparse coding p roblem. We demonstrate two cases in which we define finite and infinite latent f eature models constructed from first-order Markov chains, and derive their assoc iated scalable inference algorithms. We show empirical results on a genome analy sis task and an image denoising task.

The Knowledge Gradient for Sequential Decision Making with Stochastic Binary Fee dbacks

Yingfei Wang, Chu Wang, Warren Powell

We consider the problem of sequentially making decisions that are rewarded by "s uccesses" and "failures" which can be predicted through an unknown relationship that depends on a partially controllable vector of attributes for each instance. The learner takes an active role in selecting samples from the instance pool. The goal is to maximize the probability of success, either after the offline training phase or minimizing regret in online learning. Our problem is motivated by real-world applications where observations are time consuming and/or expensive. With the adaptation of an online Bayesian linear classifier, we develop a knowle dge-gradient type policy to guide the experiment by maximizing the expected value of information of labeling each alternative, in order to reduce the number of expensive physical experiments. We provide a finite-time analysis of the estimated error and demonstrate the performance of the proposed algorithm on both synth etic problems and benchmark UCI datasets.

A Simple and Provable Algorithm for Sparse Diagonal CCA

Megasthenis Asteris, Anastasios Kyrillidis, Oluwasanmi Koyejo, Russell Poldrack Given two sets of variables, derived from a common set of samples, sparse Canoni cal Correlation Analysis (CCA) seeks linear combinations of a small number of va riables in each set, such that the induced \emphcanonical variables are maximall y correlated. Sparse CCA is NP-hard. We propose a novel combinatorial algorithm for sparse diagonal CCA, \textiti.e., sparse CCA under the additional assumption that variables within each set are standardized and uncorrelated. Our algorithm operates on a low rank approximation of the input data and its computational complexity scales linearly with the number of input variables. It is simple to implement, and parallelizable. In contrast to most existing approaches, our algorithm administers precise control on the sparsity of the extracted canonical vector

s, and comes with theoretical data-dependent global approximation guarantees, th at hinge on the spectrum of the input data. Finally, it can be straightforwardly adapted to other constrained variants of CCA enforcing structure beyond sparsit y. We empirically evaluate the proposed scheme and apply it on a real neuroimaging dataset to investigate associations between brain activity and behavior measurements.

Quadratic Optimization with Orthogonality Constraints: Explicit Lojasiewicz Exponent and Linear Convergence of Line-Search Methods

Huikang Liu, Weijie Wu, Anthony Man-Cho So

A fundamental class of matrix optimization problems that arise in many areas of science and engineering is that of quadratic optimization with orthogonality con straints. Such problems can be solved using line-search methods on the Stiefel manifold, which are known to converge globally under mild conditions. To determine the convergence rates of these methods, we give an explicit estimate of the exponent in a Lojasiewicz inequality for the (non-convex) set of critical points of the aforementioned class of problems. This not only allows us to establish the linear convergence of a large class of line-search methods but also answers an important and intriguing problem in mathematical analysis and numerical optimization. A key step in our proof is to establish a local error bound for the set of critical points, which may be of independent interest.

Normalization Propagation: A Parametric Technique for Removing Internal Covariat e Shift in Deep Networks

Devansh Arpit, Yingbo Zhou, Bhargava Kota, Venu Govindaraju

While the authors of Batch Normalization (BN) identify and address an important problem involved in training deep networks- \textitInternal Covariate Shift- the current solution has certain drawbacks. For instance, BN depends on batch stati stics for layerwise input normalization during training which makes the estimate s of mean and standard deviation of input (distribution) to hidden layers inaccu rate due to shifting parameter values (especially during initial training epochs). Another fundamental problem with BN is that it cannot be used with batch-size during training. We address these drawbacks of BN by proposing a non-adapti ve normalization technique for removing covariate shift, that we call \textitNor malization Propagation. Our approach does not depend on batch statistics, but ra ther uses a data-independent parametric estimate of mean and standard-deviation in every layer thus being computationally faster compared with BN. We exploit th e observation that the pre-activation before Rectified Linear Units follow Gauss ian distribution in deep networks, and that once the first and second order stat istics of any given dataset are normalized, we can forward propagate this normal ization without the need for recalculating the approximate statistics for hidden layers.

Learning to Generate with Memory Chongxuan Li, Jun Zhu, Bo Zhang

Memory units have been widely used to enrich the capabilities of deep networks on capturing long-term dependencies in reasoning and prediction tasks, but little investigation exists on deep generative models (DGMs) which are good at inferring high-level invariant representations from unlabeled data. This paper presents a deep generative model with a possibly large external memory and an attention mechanism to capture the local detail information that is often lost in the bott om-up abstraction process in representation learning. By adopting a smooth attention model, the whole network is trained end-to-end by optimizing a variational bound of data likelihood via auto-encoding variational Bayesian methods, where an asymmetric recognition network is learnt jointly to infer high-level invariant representations. The asymmetric architecture can reduce the competition between bottom-up invariant feature extraction and top-down generation of instance details. Our experiments on several datasets demonstrate that memory can significant by boost the performance of DGMs on various tasks, including density estimation, image generation, and missing value imputation, and DGMs with memory can achiev

e state-of-the-art quantitative results.

Learning End-to-end Video Classification with Rank-Pooling Basura Fernando, Stephen Gould

We introduce a new model for representation learning and classification of video sequences. Our model is based on a convolutional neural network coupled with a novel temporal pooling layer. The temporal pooling layer relies on an inner-opti mization problem to efficiently encode temporal semantics over arbitrarily long video clips into a fixed-length vector representation. Importantly, the representation and classification parameters of our model can be estimated jointly in an end-to-end manner by formulating learning as a bilevel optimization problem. Furthermore, the model can make use of any existing convolutional neural network a rchitecture (e.g., AlexNet or VGG) without modification or introduction of additional parameters. We demonstrate our approach on action and activity recognition tasks.

Learning to Filter with Predictive State Inference Machines

Wen Sun, Arun Venkatraman, Byron Boots, J.Andrew Bagnell

Latent state space models are a fundamental and widely used tool for modeling dy namical systems. However, they are difficult to learn from data and learned mode ls often lack performance guarantees on inference tasks such as filtering and pr ediction. In this work, we present the PREDICTIVE STATE INFERENCE MACHINE (PSIM), a data-driven method that considers the inference procedure on a dynamical system as a composition of predictors. The key idea is that rather than first learn ing a latent state space model, and then using the learned model for inference, PSIM directly learns predictors for inference in predictive state space. We provide theoretical guarantees for inference, in both realizable and agnostic settings, and showcase practical performance on a variety of simulated and real world robotics benchmarks.

A Subspace Learning Approach for High Dimensional Matrix Decomposition with Efficient Column/Row Sampling

Mostafa Rahmani, Geroge Atia

This paper presents a new randomized approach to high-dimensional low rank (LR) plus sparse matrix decomposition. For a data matrix D \in R^N_1 \times N_2, the complexity of conventional decomposition methods is O(N_1 N_2 r), which limits their usefulness in big data settings (r is the rank of the LR component). In addition, the existing randomized approaches rely for the most part on uniform random sampling, which may be inefficient for many real world data matrices. The proposed subspace learning based approach recovers the LR component using only a small subset of the columns/rows of data and reduces complexity to O(\max(N_1,N_2) r^2). Even when the columns/rows are sampled uniformly at random, the sufficient number of sampled columns/rows is shown to be roughly O(r μ), where μ is the coherency parameter of the LR component. In addition, efficient sampling algorithms a reproposed to address the problem of column/row sampling from structured data.

DCM Bandits: Learning to Rank with Multiple Clicks

Sumeet Katariya, Branislav Kveton, Csaba Szepesvari, Zheng Wen

A search engine recommends to the user a list of web pages. The user examines th is list, from the first page to the last, and clicks on all attractive pages unt il the user is satisfied. This behavior of the user can be described by the dependent click model (DCM). We propose DCM bandits, an online learning variant of the DCM where the goal is to maximize the probability of recommending satisfactor yitems, such as web pages. The main challenge of our learning problem is that we do not observe which attractive item is satisfactory. We propose a computation ally-efficient learning algorithm for solving our problem, dcmKL-UCB; derive gap dependent upper bounds on its regret under reasonable assumptions; and also prove a matching lower bound up to logarithmic factors. We evaluate our algorithm on synthetic and real-world problems, and show that it performs well even when our model is misspecified. This work presents the first practical and regret-optim

al online algorithm for learning to rank with multiple clicks in a cascade-like click model.

Train faster, generalize better: Stability of stochastic gradient descent Moritz Hardt, Ben Recht, Yoram Singer

We show that parametric models trained by a stochastic gradient method (SGM) with few iterations have vanishing generalization error. We prove our results by ar guing that SGM is algorithmically stable in the sense of Bousquet and Elisseeff. Our analysis only employs elementary tools from convex and continuous optimization. We derive stability bounds for both convex and non-convex optimization under standard Lipschitz and smoothness assumptions. Applying our results to the convex case, we provide new insights for why multiple epochs of stochastic gradient methods generalize well in practice. In the non-convex case, we give a new interpretation of common practices in neural networks, and formally show that popular techniques for training large deep models are indeed stability-promoting. Our findings conceptually underscore the importance of reducing training time beyond its obvious benefit.

Copeland Dueling Bandit Problem: Regret Lower Bound, Optimal Algorithm, and Computationally Efficient Algorithm

Junpei Komiyama, Junya Honda, Hiroshi Nakagawa

We study the K-armed dueling bandit problem, a variation of the standard stochas tic bandit problem where the feedback is limited to relative comparisons of a pa ir of arms. The hardness of recommending Copeland winners, the arms that beat the greatest number of other arms, is characterized by deriving an asymptotic regret bound. We propose Copeland Winners Deterministic Minimum Empirical Divergence (CW-RMED), an algorithm inspired by the DMED algorithm (Honda and Takemura, 2010), and derive an asymptotically optimal regret bound for it. However, it is not known whether the algorithm can be efficiently computed or not. To address this issue, we devise an efficient version (ECW-RMED) and derive its asymptotic regret bound. Experimental comparisons of dueling bandit algorithms show that ECW-RMED significantly outperforms existing ones.

Contextual Combinatorial Cascading Bandits

Shuai Li, Baoxiang Wang, Shengyu Zhang, Wei Chen

We propose the contextual combinatorial cascading bandits, a combinatorial online e learning game, where at each time step a learning agent is given a set of contextual information, then selects a list of items, and observes stochastic outcomes of a prefix in the selected items by some stopping criterion. In online recomendation, the stopping criterion might be the first item a user selects; in net work routing, the stopping criterion might be the first edge blocked in a path. We consider position discounts in the list order, so that the agent's reward is discounted depending on the position where the stopping criterion is met. We design a UCB-type algorithm, C^3-UCB, for this problem, prove an n-step regret bound \tildeO(\sqrtn) in the general setting, and give finer analysis for two special cases. Our work generalizes existing studies in several directions, including contextual information, position discounts, and a more general cascading bandit model. Experiments on synthetic and real datasets demonstrate the advantage of involving contextual information and position discounts.

Conservative Bandits

Yifan Wu, Roshan Shariff, Tor Lattimore, Csaba Szepesvari

We study a novel multi-armed bandit problem that models the challenge faced by a company wishing to explore new strategies to maximize revenue whilst simultaneo usly maintaining their revenue above a fixed baseline, uniformly over time. Whil e previous work addressed the problem under the weaker requirement of maintaining the revenue constraint only at a given fixed time in the future, the design of those algorithms makes them unsuitable under the more stringent constraints. We consider both the stochastic and the adversarial settings, where we propose nat ural yet novel strategies and analyze the price for maintaining the constraints.

Amongst other things, we prove both high probability and expectation bounds on the regret, while we also consider both the problem of maintaining the constrain ts with high probability or expectation. For the adversarial setting the price of maintaining the constraint appears to be higher, at least for the algorithm considered. A lower bound is given showing that the algorithm for the stochastic setting is almost optimal. Empirical results obtained in synthetic environments complement our theoretical findings.

Variance-Reduced and Projection-Free Stochastic Optimization Elad Hazan, Haipeng Luo

The Frank-Wolfe optimization algorithm has recently regained popularity for mach ine learning applications due to its projection-free property and its ability to handle structured constraints. However, in the stochastic learning setting, it is still relatively understudied compared to the gradient descent counterpart. In this work, leveraging a recent variance reduction technique, we propose two st ochastic Frank-Wolfe variants which substantially improve previous results in terms of the number of stochastic gradient evaluations needed to achieve 1-Eaccura cy. For example, we improve from O(\frac1\varepsilon) to O(\ln\frac1\varepsilon) if the objective function is smooth and strongly convex, and from O(\frac1\varepsilon^2) to O(\frac1\varepsilon^1.5) if the objective function is smooth and Lipschitz. The theoretical improvement is also observed in experiments on real-world datasets for a multiclass classification application.

Factored Temporal Sigmoid Belief Networks for Sequence Learning Jiaming Song, Zhe Gan, Lawrence Carin

Deep conditional generative models are developed to simultaneously learn the tem poral dependencies of multiple sequences. The model is designed by introducing a three-way weight tensor to capture the multiplicative interactions between side information and sequences. The proposed model builds on the Temporal Sigmoid Be lief Network (TSBN), a sequential stack of Sigmoid Belief Networks (SBNs). The t ransition matrices are further factored to reduce the number of parameters and i mprove generalization. When side information is not available, a general framework for semi-supervised learning based on the proposed model is constituted, allowing robust sequence classification. Experimental results show that the proposed approach achieves state-of-the-art predictive and classification performance on sequential data, and has the capacity to synthesize sequences, with controlled style transitioning and blending.

False Discovery Rate Control and Statistical Quality Assessment of Annotators in Crowdsourced Ranking

QianQian Xu, Jiechao Xiong, Xiaochun Cao, Yuan Yao

With the rapid growth of crowdsourcing platforms it has become easy and relative ly inexpensive to collect a dataset labeled by multiple annotators in a short ti me. However due to the lack of control over the quality of the annotators, some abnormal annotators may be affected by position bias which can potentially degra de the quality of the final consensus labels. In this paper we introduce a stati stical framework to model and detect annotator's position bias in order to control the false discovery rate (FDR) without a prior knowledge on the amount of bia sed annotators—the expected fraction of false discoveries among all discoveries being not too high, in order to assure that most of the discoveries are indeed true and replicable. The key technical development relies on some new knockoff filters adapted to our problem and new algorithms based on the Inverse Scale Space dynamics whose discretization is potentially suitable for large scale crowdsour cing data analysis. Our studies are supported by experiments with both simulated examples and real-world data. The proposed framework provides us a useful tool for quantitatively studying annotator's abnormal behavior in crowdsourcing.

Strongly-Typed Recurrent Neural Networks

David Balduzzi, Muhammad Ghifary

Recurrent neural networks are increasing popular models for sequential learning.

Unfortunately, although the most effective RNN architectures are perhaps excess ively complicated, extensive searches have not found simpler alternatives. This paper imports ideas from physics and functional programming into RNN design to p rovide guiding principles. From physics, we introduce type constraints, analogous to the constraints that forbids adding meters to seconds. From functional programming, we require that strongly-typed architectures factorize into stateless learnware and state-dependent firmware, reducing the impact of side-effects. The features learned by strongly-typed nets have a simple semantic interpretation via dynamic average-pooling on one-dimensional convolutions. We also show that strongly-typed gradients are better behaved than in classical architectures, and characterize the representational power of strongly-typed nets. Finally, experiments show that, despite being more constrained, strongly-typed architectures achieve lower training and comparable generalization error to classical architectures

Distributed Clustering of Linear Bandits in Peer to Peer Networks Nathan Korda, Balazs Szorenyi, Shuai Li

We provide two distributed confidence ball algorithms for solving linear bandit problems in peer to peer networks with limited communication capabilities. For the first, we assume that all the peers are solving the same linear bandit problem, and prove that our algorithm achieves the optimal asymptotic regret rate of any centralised algorithm that can instantly communicate information between the peers. For the second, we assume that there are clusters of peers solving the same bandit problem within each cluster, and we prove that our algorithm discovers these clusters, while achieving the optimal asymptotic regret rate within each one. Through experiments on several real-world datasets, we demonstrate the performance of proposed algorithms compared to the state-of-the-art.

Collapsed Variational Inference for Sum-Product Networks

Han Zhao, Tameem Adel, Geoff Gordon, Brandon Amos

Sum-Product Networks (SPNs) are probabilistic inference machines that admit exact inference in linear time in the size of the network. Existing parameter learning approaches for SPNs are largely based on the maximum likelihood principle and are subject to overfitting compared to more Bayesian approaches. Exact Bayesian posterior inference for SPNs is computationally intractable. Even approximation techniques such as standard variational inference and posterior sampling for SPNs are computationally infeasible even for networks of moderate size due to the large number of local latent variables per instance. In this work, we propose a novel deterministic collapsed variational inference algorithm for SPNs that is computationally efficient, easy to implement and at the same time allows us to in corporate prior information into the optimization formulation. Extensive experiments show a significant improvement in accuracy compared with a maximum likeliho od based approach.

On the Analysis of Complex Backup Strategies in Monte Carlo Tree Search Piyush Khandelwal, Elad Liebman, Scott Niekum, Peter Stone

Over the past decade, Monte Carlo Tree Search (MCTS) and specifically Upper Conf idence Bound in Trees (UCT) have proven to be quite effective in large probabili stic planning domains. In this paper, we focus on how values are backpropagated in the MCTS tree, and apply complex return strategies from the Reinforcement Lea rning (RL) literature to MCTS, producing 4 new MCTS variants. We demonstrate that in some probabilistic planning benchmarks from the International Planning Competition (IPC), selecting a MCTS variant with a backup strategy different from Monte Carlo averaging can lead to substantially better results. We also propose a hypothesis for why different backup strategies lead to different performance in particular environments, and manipulate a carefully structured grid-world domain to provide empirical evidence supporting our hypothesis.

Benchmarking Deep Reinforcement Learning for Continuous Control Yan Duan, Xi Chen, Rein Houthooft, John Schulman, Pieter Abbeel

Recently, researchers have made significant progress combining the advances in deep learning for learning feature representations with reinforcement learning. Some notable examples include training agents to play Atari games based on raw pixel data and to acquire advanced manipulation skills using raw sensory inputs. However, it has been difficult to quantify progress in the domain of continuous control due to the lack of a commonly adopted benchmark. In this work, we present a benchmark suite of continuous control tasks, including classic tasks like car t-pole swing-up, tasks with very high state and action dimensionality such as 3D humanoid locomotion, tasks with partial observations, and tasks with hierarchical structure. We report novel findings based on the systematic evaluation of a range of implemented reinforcement learning algorithms. Both the benchmark and reference implementations are released at https://github.com/rllab/rllab in order to facilitate experimental reproducibility and to encourage adoption by other researchers.

K-Means Clustering with Distributed Dimensions

Hu Ding, Yu Liu, Lingxiao Huang, Jian Li

Distributed clustering has attracted significant attention in recent years. In this paper, we study the k-means problem in the distributed dimension setting, where the dimensions of the data are partitioned across multiple machines. We provide new approximation algorithms, which incur low communication costs and achieve constant approximation ratios. The communication complexity of our algorithms significantly improve on existing algorithms. We also provide the first communication lower bound, which nearly matches our upper bound in a certain range of parameter setting. Our experimental results show that our algorithms outperform existing algorithms on real data-sets in the distributed dimension setting.

Texture Networks: Feed-forward Synthesis of Textures and Stylized Images Dmitry Ulyanov, Vadim Lebedev, Andrea, Victor Lempitsky

Gatys et al. recently demonstrated that deep networks can generate beautiful tex tures and stylized images from a single texture example. However, their methods requires a slow and memory-consuming optimization process. We propose here an al ternative approach that moves the computational burden to a learning stage. Give n a single example of a texture, our approach trains compact feed-forward convol utional networks to generate multiple samples of the same texture of arbitrary s ize and to transfer artistic style from a given image to any other image. The re sulting networks are remarkably light-weight and can generate textures of qualit y comparable to Gatys et al., but hundreds of times faster. More generally, our approach highlights the power and flexibility of generative feed-forward models trained with complex and expressive loss functions.

Fast Constrained Submodular Maximization: Personalized Data Summarization Baharan Mirzasoleiman, Ashwinkumar Badanidiyuru, Amin Karbasi

Can we summarize multi-category data based on user preferences in a scalable man ner? Many utility functions used for data summarization satisfy submodularity, a natural diminishing returns property. We cast personalized data summarization a s an instance of a general submodular maximization problem subject to multiple c onstraints. We develop the first practical and FAst coNsTrained submOdular Maxim ization algorithm, FANTOM, with strong theoretical guarantees. FANTOM maximizes a submodular function (not necessarily monotone) subject to intersection of a psystem and 1 knapsacks constrains. It achieves a $(1 + \varepsilon)(p + 1)(2p + 21 + 1)/p$ a pproximation guarantee with only $O(nrp \log(n)/\epsilon)$ query complexity (n and r indic ate the size of the ground set and the size of the largest feasible solution, re spectively). We then show how we can use FANTOM for personalized data summarizat ion. In particular, a p-system can model different aspects of data, such as cate gories or time stamps, from which the users choose. In addition, knapsacks encod e users' constraints including budget or time. In our set of experiments, we con sider several concrete applications: movie recommendation over 11K movies, perso nalized image summarization with 10K images, and revenue maximization on the You Tube social networks with 5000 communities. We observe that FANTOM constantly pr

ovides the highest utility against all the baselines.

On the Statistical Limits of Convex Relaxations Zhaoran Wang, Quanquan Gu, Han Liu

Many high dimensional sparse learning problems are formulated as nonconvex optim ization. A popular approach to solve these nonconvex optimization problems is th rough convex relaxations such as linear and semidefinite programming. In this paper, we study the statistical limits of convex relaxations. Particularly, we consider two problems: Mean estimation for sparse principal submatrix and edge probability estimation for stochastic block model. We exploit the sum-of-squares relaxation hierarchy to sharply characterize the limits of a broad class of convex relaxations. Our result shows statistical optimality needs to be compromised for achieving computational tractability using convex relaxations. Compared with existing results on computational lower bounds for statistical problems, which consider general polynomial-time algorithms and rely on computational hardness hypotheses on problems like planted clique detection, our theory focuses on a broad class of convex relaxations and does not rely on unproven hypotheses.

Ask Me Anything: Dynamic Memory Networks for Natural Language Processing Ankit Kumar, Ozan Irsoy, Peter Ondruska, Mohit Iyyer, James Bradbury, Ishaan Gul rajani, Victor Zhong, Romain Paulus, Richard Socher

Most tasks in natural language processing can be cast into question answering (Q A) problems over language input. We introduce the dynamic memory network (DMN), a neural network architecture which processes input sequences and questions, for ms episodic memories, and generates relevant answers. Questions trigger an itera tive attention process which allows the model to condition its attention on the inputs and the result of previous iterations. These results are then reasoned ov er in a hierarchical recurrent sequence model to generate answers. The DMN can be trained end-to-end and obtains state-of-the-art results on several types of tasks and datasets: question answering (Facebook's bAbI dataset), text classificat ion for sentiment analysis (Stanford Sentiment Treebank) and sequence modeling for part-of-speech tagging (WSJ-PTB). The training for these different tasks relies exclusively on trained word vector representations and input-question-answer triplets.

Gossip Dual Averaging for Decentralized Optimization of Pairwise Functions Igor Colin, Aurelien Bellet, Joseph Salmon, Stéphan Clémençon

In decentralized networks (of sensors, connected objects, etc.), there is an imp ortant need for efficient algorithms to optimize a global cost function, for ins tance to learn a global model from the local data collected by each computing un it. In this paper, we address the problem of decentralized minimization of pairw ise functions of the data points, where these points are distributed over the no des of a graph defining the communication topology of the network. This general problem finds applications in ranking, distance metric learning and graph infere nce, among others. We propose new gossip algorithms based on dual averaging which aims at solving such problems both in synchronous and asynchronous settings. The proposed framework is flexible enough to deal with constrained and regularized distributed variants of the optimization problem. Our theoretical analysis reveals that the proposed algorithms preserve the convergence rate of centralized dual averaging up to an additive bias term. We present numerical simulations on Area Under the ROC Curve (AUC) maximization and metric learning problems which illustrate the practical interest of our approach.

Solving Ridge Regression using Sketched Preconditioned SVRG Alon Gonen, Francesco Orabona, Shai Shalev-Shwartz

We develop a novel preconditioning method for ridge regression, based on recent linear sketching methods. By equipping Stochastic Variance Reduced Gradient (SVR G) with this preconditioning process, we obtain a significant speed-up relative to fast stochastic methods such as SVRG, SDCA and SAG.

Cumulative Prospect Theory Meets Reinforcement Learning: Prediction and Control Prashanth L.A., Cheng Jie, Michael Fu, Steve Marcus, Csaba Szepesvari

Cumulative prospect theory (CPT) is known to model human decisions well, with su bstantial empirical evidence supporting this claim. CPT works by distorting prob abilities and is more general than the classic expected utility and coherent ris k measures. We bring this idea to a risk-sensitive reinforcement learning (RL) s etting and design algorithms for both estimation and control. The RL setting pre sents two particular challenges when CPT is applied: estimating the CPT objective requires estimations of the entire distribution of the value function and find ing a randomized optimal policy. The estimation scheme that we propose uses the empirical distribution to estimate the CPT-value of a random variable. We then u se this scheme in the inner loop of a CPT-value optimization procedure that is b ased on the well-known simulation optimization idea of simultaneous perturbation stochastic approximation (SPSA). We provide theoretical convergence guarantees for all the proposed algorithms and also empirically demonstrate the usefulness of our algorithms.

Estimating Accuracy from Unlabeled Data: A Bayesian Approach Emmanouil Antonios Platanios, Avinava Dubey, Tom Mitchell

We consider the question of how unlabeled data can be used to estimate the true accuracy of learned classifiers, and the related question of how outputs from se veral classifiers performing the same task can be combined based on their estima ted accuracies. To answer these questions, we first present a simple graphical m odel that performs well in practice. We then provide two nonparametric extension s to it that improve its performance. Experiments on two real-world data sets pr oduce accuracy estimates within a few percent of the true accuracy, using solely unlabeled data. Our models also outperform existing state-of-the-art solutions in both estimating accuracies, and combining multiple classifier outputs.

Non-negative Matrix Factorization under Heavy Noise

Chiranjib Bhattacharya, Navin Goyal, Ravindran Kannan, Jagdeep Pani

The Noisy Non-negative Matrix factorization (NMF) is: given a data matrix A (d x n), find non-negative matrices B_i C (d x k, k x n respy.) so that A = BC + N, whe re N is a noise matrix. Existing polynomial time algorithms with proven error gu arantees require EACH column N_.j to have 11 norm much smaller than ||(BC)_.j || _1, which could be very restrictive. In important applications of NMF such as To pic Modeling as well as theoretical noise models (e.g. Gaussian with high sigma) , almost EVERY column of N_.j violates this condition. We introduce the heavy no ise model which only requires the average noise over large subsets of columns to be small. We initiate a study of Noisy NMF under the heavy noise model. We show that our noise model subsumes noise models of theoretical and practical interes t (for e.g. Gaussian noise of maximum possible sigma). We then devise an algorit hm TSVDNMF which under certain assumptions on B,C, solves the problem under heav y noise. Our error guarantees match those of previous algorithms. Our running ti me of $O(k.(d+n)^2)$ is substantially better than the $O(d.n^3)$ for the previous be st. Our assumption on B is weaker than the "Separability" assumption made by all previous results. We provide empirical justification for our assumptions on C. We also provide the first proof of identifiability (uniqueness of B) for noisy N MF which is not based on separability and does not use hard to check geometric c onditions. Our algorithm outperforms earlier polynomial time algorithms both in time and error, particularly in the presence of high noise.

Extreme F-measure Maximization using Sparse Probability Estimates

Kalina Jasinska, Krzysztof Dembczynski, Robert Busa-Fekete, Karlson Pfannschmidt, Timo Klerx, Eyke Hullermeier

We consider the problem of (macro) F-measure maximization in the context of extr eme multi-label classification (XMLC), i.e., multi-label classification with ext remely large label spaces. We investigate several approaches based on recent results on the maximization of complex performance measures in binary classification. According to these results, the F-measure can be maximized by properly thresh

olding conditional class probability estimates. We show that a naive adaptation of this approach can be very costly for XMLC and propose to solve the problem by classifiers that efficiently deliver sparse probability estimates (SPEs), that is, probability estimates restricted to the most probable labels. Empirical results provide evidence for the strong practical performance of this approach.

Auxiliary Deep Generative Models

Lars Maaløe, Casper Kaae Sønderby, Søren Kaae Sønderby, Ole Winther

Deep generative models parameterized by neural networks have recently achieved s tate-of-the-art performance in unsupervised and semi-supervised learning. We ext end deep generative models with auxiliary variables which improves the variation al approximation. The auxiliary variables leave the generative model unchanged b ut make the variational distribution more expressive. Inspired by the structure of the auxiliary variable we also propose a model with two stochastic layers and skip connections. Our findings suggest that more expressive and properly specified deep generative models converge faster with better results. We show state-of-the-art performance within semi-supervised learning on MNIST, SVHN and NORB dat asets.

Importance Sampling Tree for Large-scale Empirical Expectation Olivier Canevet, Cijo Jose, Francois Fleuret

We propose a tree-based procedure inspired by the Monte-Carlo Tree Search that d ynamically modulates an importance-based sampling to prioritize computation, whi le getting unbiased estimates of weighted sums. We apply this generic method to learning on very large training sets, and to the evaluation of large-scale SVMs. The core idea is to reformulate the estimation of a score - whether a loss or a prediction estimate - as an empirical expectation, and to use such a tree whose leaves carry the samples to focus efforts over the problematic "heavy weight" o nes. We illustrate the potential of this approach on three problems: to improve Adaboost and a multi-layer perceptron on 2D synthetic tasks with several million points, to train a large-scale convolution network on several millions deformat ions of the CIFAR data-set, and to compute the response of a SVM with several hu ndreds of thousands of support vectors. In each case, we show how it either cuts down computation by more than one order of magnitude and/or allows to get better loss estimates.

Starting Small - Learning with Adaptive Sample Sizes Hadi Daneshmand, Aurelien Lucchi, Thomas Hofmann

For many machine learning problems, data is abundant and it may be prohibitive to make multiple passes through the full training set. In this context, we invest igate strategies for dynamically increasing the effective sample size, when using iterative methods such as stochastic gradient descent. Our interest is motivated by the rise of variance-reduced methods, which achieve linear convergence rates that scale favorably for smaller sample sizes. Exploiting this feature, we show - theoretically and empirically - how to obtain significant speed-ups with a novel algorithm that reaches statistical accuracy on an n-sample in 2n, instead of n log n steps.

Deep Gaussian Processes for Regression using Approximate Expectation Propagation Thang Bui, Daniel Hernandez-Lobato, Jose Hernandez-Lobato, Yingzhen Li, Richard Turner

Deep Gaussian processes (DGPs) are multi-layer hierarchical generalisations of G aussian processes (GPs) and are formally equivalent to neural networks with mult iple, infinitely wide hidden layers. DGPs are nonparametric probabilistic models and as such are arguably more flexible, have a greater capacity to generalise, and provide better calibrated uncertainty estimates than alternative deep models. This paper develops a new approximate Bayesian learning scheme that enables DGPs to be applied to a range of medium to large scale regression problems for the first time. The new method uses an approximate Expectation Propagation procedure and a novel and efficient extension of the probabilistic backpropagation algor

ithm for learning. We evaluate the new method for non-linear regression on eleve n real-world datasets, showing that it always outperforms GP regression and is a lmost always better than state-of-the-art deterministic and sampling-based approximate inference methods for Bayesian neural networks. As a by-product, this work provides a comprehensive analysis of six approximate Bayesian methods for training neural networks.

DR-ABC: Approximate Bayesian Computation with Kernel-Based Distribution Regressi on

Jovana Mitrovic, Dino Sejdinovic, Yee-Whye Teh

Performing exact posterior inference in complex generative models is often diffi cult or impossible due to an expensive to evaluate or intractable likelihood fun ction. Approximate Bayesian computation (ABC) is an inference framework that con structs an approximation to the true likelihood based on the similarity between the observed and simulated data as measured by a predefined set of summary stati stics. Although the choice of informative problem-specific summary statistics cr ucially influences the quality of the likelihood approximation and hence also th e quality of the posterior sample in ABC, there are only few principled generalpurpose approaches to the selection or construction of such summary statistics. In this paper, we develop a novel framework for solving this problem. We model t he functional relationship between the data and the optimal choice (with respect to a loss function) of summary statistics using kernel-based distribution regre ssion. Furthermore, we extend our approach to incorporate kernel-based regressio n from conditional distributions, thus appropriately taking into account the spe cific structure of the posited generative model. We show that our approach can b e implemented in a computationally and statistically efficient way using the ran dom Fourier features framework for large-scale kernel learning. In addition to t hat, our framework outperforms related methods by a large margin on toy and real -world data, including hierarchical and time series models.

Predictive Entropy Search for Multi-objective Bayesian Optimization Daniel Hernandez-Lobato, Jose Hernandez-Lobato, Amar Shah, Ryan Adams We present \small PESMO, a Bayesian method for identifying the Pareto set of mul ti-objective optimization problems, when the functions are expensive to evaluate . \small PESMO chooses the evaluation points to maximally reduce the entropy of the posterior distribution over the Pareto set. The $\sl mall$ PESMO acquisition fun ction is decomposed as a sum of objective-specific acquisition functions, which makes it possible to use the algorithm in \emphdecoupled scenarios in which the objectives can be evaluated separately and perhaps with different costs. This de coupling capability is useful to identify difficult objectives that require more evaluations. \small PESMO also offers gains in efficiency, as its cost scales 1 inearly with the number of objectives, in comparison to the exponential cost of other methods. We compare \small PESMO with other methods on synthetic and realworld problems. The results show that \small PESMO produces better recommendatio ns with a smaller number of evaluations, and that a decoupled evaluation can lea d to improvements in performance, particularly when the number of objectives is large.

Rich Component Analysis

Rong Ge, James Zou

In many settings, we have multiple data sets (also called views) that capture different and overlapping aspects of the same phenomenon. We are often interested in finding patterns that are unique to one or to a subset of the views. For exam ple, we might have one set of molecular observations and one set of physiologica lobservations on the same group of individuals, and we want to quantify molecul ar patterns that are uncorrelated with physiology. Despite being a common proble m, this is highly challenging when the correlations come from complex distributions. In this paper, we develop the general framework of Rich Component Analysis (RCA) to model settings where the observations from different views are driven by different sets of latent components, and each component can be a complex, high

-dimensional distribution. We introduce algorithms based on cumulant extraction that provably learn each of the components without having to model the other components. We show how to integrate RCA with stochastic gradient descent into a meta-algorithm for learning general models, and demonstrate substantial improvement in accuracy on several synthetic and real datasets in both supervised and unsupervised tasks. Our method makes it possible to learn latent variable models when we don't have samples from the true model but only samples after complex perturbations.

Black-Box Alpha Divergence Minimization

Jose Hernandez-Lobato, Yingzhen Li, Mark Rowland, Thang Bui, Daniel Hernandez-Lobato, Richard Turner

Black-box alpha (BB- α) is a new approximate inference method based on the minimi zation of α -divergences. BB- α scales to large datasets because it can be implemented using stochastic gradient descent. BB- α can be applied to complex probabilist ic models with little effort since it only requires as input the likelihood function and its gradients. These gradients can be easily obtained using automatic differentiation. By changing the divergence parameter α , the method is able to interpolate between variational Bayes (VB) ($\alpha \rightarrow 0$) and an algorithm similar to expectation propagation (EP) (α = 1). Experiments on probit regression and neural network regression and classification problems show that BB- α with non-standard settings of α , such as α = 0.5, usually produces better predictions than with $\alpha \rightarrow 0$ (VB) or α = 1 (EP).

One-Shot Generalization in Deep Generative Models

Danilo Rezende, Shakir, Ivo Danihelka, Karol Gregor, Daan Wierstra

Humans have an impressive ability to reason about new concepts and experiences f rom just a single example. In particular, humans have an ability for one-shot ge neralization: an ability to encounter a new concept, understand its structure, a nd then be able to generate compelling alternative variations of the concept. We develop machine learning systems with this important capacity by developing new deep generative models, models that combine the representational power of deep learning with the inferential power of Bayesian reasoning. We develop a class of sequential generative models that are built on the principles of feedback and a ttention. These two characteristics lead to generative models that are among the state-of-the art in density estimation and image generation. We demonstrate the one-shot generalization ability of our models using three tasks: unconditional sampling, generating new exemplars of a given concept, and generating new exempl ars of a family of concepts. In all cases our models are able to generate compel ling and diverse samples—having seen new examples just once—providing an important class of general-purpose models for one-shot machine learning.

Optimal Classification with Multivariate Losses

Nagarajan Natarajan, Oluwasanmi Koyejo, Pradeep Ravikumar, Inderjit Dhillon Multivariate loss functions are extensively employed in several prediction tasks arising in Information Retrieval. Often, the goal in the tasks is to minimize e xpected loss when retrieving relevant items from a presented set of items, where the expectation is with respect to the joint distribution over item sets. Our k ey result is that for most multivariate losses, the expected loss is provably op timized by sorting the items by the conditional probability of label being posit ive and then selecting top k items. Such a result was previously known only for the F-measure. Leveraging on the optimality characterization, we give an algorit hm for estimating optimal predictions in practice with runtime quadratic in size of item sets for many losses. We provide empirical results on benchmark dataset s, comparing the proposed algorithm to state-of-the-art methods for optimizing m ultivariate losses.

A ranking approach to global optimization Cedric Malherbe, Emile Contal, Nicolas Vayatis

We consider the problem of maximizing an unknown function f over a compact and c

onvex set using as few observations f(x) as possible. We observe that the optimization of the function f essentially relies on learning the induced bipartite ranking rule of f. Based on this idea, we relate global optimization to bipartite ranking which allows to address problems with high dimensional input space, as well as cases of functions with weak regularity properties. The paper introduces novel meta-algorithms for global optimization which rely on the choice of any bipartite ranking method. Theoretical properties are provided as well as convergen ce guarantees and equivalences between various optimization methods are obtained as a by-product. Eventually, numerical evidence is given to show that the main algorithm of the paper which adapts empirically to the underlying ranking struct ure essentially outperforms existing state-of-the-art global optimization algorithms in typical benchmarks.

Parallel and Distributed Block-Coordinate Frank-Wolfe Algorithms
Yu-Xiang Wang, Veeranjaneyulu Sadhanala, Wei Dai, Willie Neiswanger, Suvrit Sra,
Eric Xing

We study parallel and distributed Frank-Wolfe algorithms; the former on shared m emory machines with mini-batching, and the latter in a delayed update framework. In both cases, we perform computations asynchronously whenever possible. We ass ume block-separable constraints as in Block-Coordinate Frank-Wolfe (BCFW) method (Lacoste et. al., 2013), but our analysis subsumes BCFW and reveals problem-de pendent quantities that govern the speedups of our methods over BCFW. A notable feature of our algorithms is that they do not depend on worst-case bounded delay s, but only (mildly) on **expected** delays, making them robust to stragglers and faulty worker threads. We present experiments on structural SVM and Group Fuse d Lasso, and observe significant speedups over competing state-of-the-art (and s ynchronous) methods.

Autoencoding beyond pixels using a learned similarity metric

Anders Boesen Lindbo Larsen, Søren Kaae Sønderby, Hugo Larochelle, Ole Winther We present an autoencoder that leverages learned representations to better measu re similarities in data space. By combining a variational autoencoder (VAE) with a generative adversarial network (GAN) we can use learned feature representations in the GAN discriminator as basis for the VAE reconstruction objective. There by, we replace element-wise errors with feature-wise errors to better capture the data distribution while offering invariance towards e.g. translation. We apply our method to images of faces and show that it outperforms VAEs with element-wise similarity measures in terms of visual fidelity. Moreover, we show that the method learns an embedding in which high-level abstract visual features (e.g. wearing glasses) can be modified using simple arithmetic.

Ensuring Rapid Mixing and Low Bias for Asynchronous Gibbs Sampling Christopher De Sa, Chris Re, Kunle Olukotun

Gibbs sampling is a Markov chain Monte Carlo technique commonly used for estimat ing marginal distributions. To speed up Gibbs sampling, there has recently been interest in parallelizing it by executing asynchronously. While empirical result s suggest that many models can be efficiently sampled asynchronously, traditional Markov chain analysis does not apply to the asynchronous case, and thus asynchronous Gibbs sampling is poorly understood. In this paper, we derive a better un derstanding of the two main challenges of asynchronous Gibbs: bias and mixing time. We show experimentally that our theoretical results match practical outcomes

Simultaneous Safe Screening of Features and Samples in Doubly Sparse Modeling Atsushi Shibagaki, Masayuki Karasuyama, Kohei Hatano, Ichiro Takeuchi The problem of learning a sparse model is conceptually interpreted as the proces s of identifying active features/samples and then optimizing the model over them . Recently introduced safe screening allows us to identify a part of non-active features/samples. So far, safe screening has been individually studied either for feature screening or for sample screening. In this paper, we introduce a new a

pproach for safely screening features and samples simultaneously by alternativel y iterating feature and sample screening steps. A significant advantage of consi dering them simultaneously rather than individually is that they have a synergy effect in the sense that the results of the previous safe feature screening can be exploited for improving the next safe sample screening performances, and vice -versa. We first theoretically investigate the synergy effect, and then illustrate the practical advantage through intensive numerical experiments for problems with large numbers of features and samples.

Anytime optimal algorithms in stochastic multi-armed bandits Rémy Degenne, Vianney Perchet

We introduce an anytime algorithm for stochastic multi-armed bandit with optimal distribution free and distribution dependent bounds (for a specific family of p arameters). The performances of this algorithm (as well as another one motivated by the conjectured optimal bound) are evaluated empirically. A similar analysis is provided with full information, to serve as a benchmark.

Bounded Off-Policy Evaluation with Missing Data for Course Recommendation and Curriculum Design

William Hoiles, Mihaela Schaar

Successfully recommending personalized course schedules is a difficult problem g iven the diversity of students knowledge, learning behaviour, and goals. This pa per presents personalized course recommendation and curriculum design algorithms that exploit logged student data. The algorithms are based on the regression es timator for contextual multi-armed bandits with a penalized variance term. Guara ntees on the predictive performance of the algorithms are provided using empiric al Bernstein bounds. We also provide guidelines for including expert domain know ledge into the recommendations. Using undergraduate engineering logged data from a post-secondary institution we illustrate the performance of these algorithms.

On collapsed representation of hierarchical Completely Random Measures Gaurav Pandey, Ambedkar Dukkipati

The aim of the paper is to provide an exact approach for generating a Poisson process sampled from a hierarchical CRM, without having to instantiate the infinit ely many atoms of the random measures. We use completely random measures (CRM) and hierarchical CRM to define a prior for Poisson processes. We derive the marginal distribution of the resultant point process, when the underlying CRM is marginalized out. Using well known properties unique to Poisson processes, we were a ble to derive an exact approach for instantiating a Poisson process with a hierarchical CRM prior. Furthermore, we derive Gibbs sampling strategies for hierarchical CRM models based on Chinese restaurant franchise sampling scheme. As an example, we present the sum of generalized gamma process (SGGP), and show its application in topic-modelling. We show that one can determine the power-law behaviour of the topics and words in a Bayesian fashion, by defining a prior on the parameters of SGGP.

From Softmax to Sparsemax: A Sparse Model of Attention and Multi-Label Classific ation

Andre Martins, Ramon Astudillo

We propose sparsemax, a new activation function similar to the traditional softm ax, but able to output sparse probabilities. After deriving its properties, we s how how its Jacobian can be efficiently computed, enabling its use in a network trained with backpropagation. Then, we propose a new smooth and convex loss func tion which is the sparsemax analogue of the logistic loss. We reveal an unexpect ed connection between this new loss and the Huber classification loss. We obtain promising empirical results in multi-label classification problems and in attention-based neural networks for natural language inference. For the latter, we achieve a similar performance as the traditional softmax, but with a selective, mo re compact, attention focus.

Black-box Optimization with a Politician

Sebastien Bubeck, Yin Tat Lee

We propose a new framework for black-box convex optimization which is well-suite d for situations where gradient computations are expensive. We derive a new meth od for this framework which leverages several concepts from convex optimization, from standard first-order methods (e.g. gradient descent or quasi-Newton method s) to analytical centers (i.e. minimizers of self-concordant barriers). We demon strate empirically that our new technique compares favorably with state of the a rt algorithms (such as BFGS).

Gaussian process nonparametric tensor estimator and its minimax optimality Heishiro Kanagawa, Taiji Suzuki, Hayato Kobayashi, Nobuyuki Shimizu, Yukihiro Ta gami

We investigate the statistical efficiency of a nonparametric Gaussian process me thod for a nonlinear tensor estimation problem. Low-rank tensor estimation has been used as a method to learn higher order relations among several data sources in a wide range of applications, such as multi-task learning, recommendation systems, and spatiotemporal analysis. We consider a general setting where a common linear tensor learning is extended to a nonlinear learning problem in reproducing kernel Hilbert space and propose a nonparametric Bayesian method based on the Gaussian process method. We prove its statistical convergence rate without assuming any strong convexity, such as restricted strong convexity. Remarkably, it is shown that our convergence rate achieves the minimax optimal rate. We apply our proposed method to multi-task learning and show that our method significantly outperforms existing methods through numerical experiments on real-world data set s.

No-Regret Algorithms for Heavy-Tailed Linear Bandits

Andres Munoz Medina, Scott Yang

We analyze the problem of linear bandits under heavy tailed noise. Most of of the work on linear bandits has been based on the assumption of bounded or sub-Gaus sian noise. However, this assumption is often violated in common scenarios such as financial markets. We present two algorithms to tackle this problem: one based on dynamic truncation and one based on a median of means estimator. We show that, when the noise admits admits only a 1 + &moment, these algorithms are still able to achieve regret in \widetildeO(T^\frac2 + &2(1 + &)) and \widetildeO(T^\frac1 + 2&1 + 3 &) respectively. In particular, they guarantee sublinear regret as long as the noise has finite variance. We also present empirical results showing that our algorithms achieve a better performance than the current state of the art for bounded noise when the L_ ∞ bound on the noise is large yet the 1 + &mome nt of the noise is small.

Extended and Unscented Kitchen Sinks

Edwin Bonilla, Daniel Steinberg, Alistair Reid

We propose a scalable multiple-output generalization of unscented and extended G aussian processes. These algorithms have been designed to handle general likelih ood models by linearizing them using a Taylor series or the Unscented Transform in a variational inference framework. We build upon random feature approximation s of Gaussian process covariance functions and show that, on small-scale single-task problems, our methods can attain similar performance as the original algorithms while having less computational cost. We also evaluate our methods at a lar ger scale on MNIST and on a seismic inversion which is inherently a multi-task p roblem.

Matrix Eigen-decomposition via Doubly Stochastic Riemannian Optimization Zhiqiang Xu, Peilin Zhao, Jianneng Cao, Xiaoli Li

Matrix eigen-decomposition is a classic and long-standing problem that plays a f undamental role in scientific computing and machine learning. Despite some exist ing algorithms for this inherently non-convex problem, the study remains inadequ ate for the need of large data nowadays. To address this gap, we propose a Doubl

y Stochastic Riemannian Gradient EIGenSolver, DSRG-EIGS, where the double stocha sticity comes from the generalization of the stochastic Euclidean gradient ascen t and the stochastic Euclidean coordinate ascent to Riemannian manifolds. As a r esult, it induces a greatly reduced complexity per iteration, enables the algori thm to completely avoid the matrix inversion, and consequently makes it well-sui ted to large-scale applications. We theoretically analyze its convergence proper ties and empirically validate it on real-world datasets. Encouraging experimenta l results demonstrate its advantages over the deterministic counterparts.

Recommendations as Treatments: Debiasing Learning and Evaluation

Tobias Schnabel, Adith Swaminathan, Ashudeep Singh, Navin Chandak, Thorsten Joac

Most data for evaluating and training recommender systems is subject to selection biases, either through self-selection by the users or through the actions of the recommendation system itself. In this paper, we provide a principled approach to handle selection biases by adapting models and estimation techniques from causal inference. The approach leads to unbiased performance estimators despite biased data, and to a matrix factorization method that provides substantially improved prediction performance on real-world data. We theoretically and empirically characterize the robustness of the approach, and find that it is highly practical and scalable.

ForecastICU: A Prognostic Decision Support System for Timely Prediction of Intensive Care Unit Admission

Jinsung Yoon, Ahmed Alaa, Scott Hu, Mihaela Schaar

We develop ForecastICU: a prognostic decision support system that monitors hospi talized patients and prompts alarms for intensive care unit (ICU) admissions. Fo recastICU is first trained in an offline stage by constructing a Bayesian belief system that corresponds to its belief about how trajectories of physiological d ata streams of the patient map to a clinical status. After that, ForecastICU mon itors a new patient in real-time by observing her physiological data stream, upd ating its belief about her status over time, and prompting an alarm whenever its belief process hits a predefined threshold (confidence). Using a real-world dat aset obtained from UCLA Ronald Reagan Medical Center, we show that ForecastICU c an predict ICU admissions 9 hours before a physician's decision (for a sensitivi ty of 40% and a precision of 50%). Also, ForecastICU performs consistently bette r than other state-of-the-art machine learning algorithms in terms of sensitivit y, precision, and timeliness: it can predict ICU admissions 3 hours earlier, and offers a 7.8% gain in sensitivity and a 5.1% gain in precision compared to the best state-of-the-art algorithm. Moreover, ForecastICU offers an area under curv e (AUC) gain of 22.3% compared to the Rothman index, which is the currently depl oyed technology in most hospital wards.

An optimal algorithm for the Thresholding Bandit Problem Andrea Locatelli, Maurilio Gutzeit, Alexandra Carpentier

We study a specific combinatorial pure exploration stochastic bandit problem whe re the learner aims at finding the set of arms whose means are above a given thr eshold, up to a given precision, and for a fixed time horizon. We propose a para meter-free algorithm based on an original heuristic, and prove that it is optima 1 for this problem by deriving matching upper and lower bounds. To the best of o ur knowledge, this is the first non-trivial pure exploration setting with fixed budget for which provably optimal strategies are constructed.

Fast Parameter Inference in Nonlinear Dynamical Systems using Iterative Gradient Matching

Mu Niu, Simon Rogers, Maurizio Filippone, Dirk Husmeier

Parameter inference in mechanistic models of coupled differential equations is a topical and challenging problem. We propose a new method based on kernel ridge regression and gradient matching, and an objective function that simultaneously encourages goodness of fit and penalises inconsistencies with the differential e

quations. Fast minimisation is achieved by exploiting partial convexity inherent in this function, and setting up an iterative algorithm in the vein of the EM a lgorithm. An evaluation of the proposed method on various benchmark data suggest s that it compares favourably with state-of-the-art alternatives.

Structured and Efficient Variational Deep Learning with Matrix Gaussian Posteriors

Christos Louizos, Max Welling

We introduce a variational Bayesian neural network where the parameters are gove rned via a probability distribution on random matrices. Specifically, we employ a matrix variate Gaussian (Gupta & Nagar '99) parameter posterior distribution we here we explicitly model the covariance among the input and output dimensions of each layer. Furthermore, with approximate covariance matrices we can achieve a more efficient way to represent those correlations that is also cheaper than fully factorized parameter posteriors. We further show that with the "local reprara metrization trick" (Kingma & Welling '15) on this posterior distribution we arrive at a Gaussian Process (Rasmussen '06) interpretation of the hidden units in each layer and we, similarly with (Gal & Ghahramani '15), provide connections with deep Gaussian processes. We continue in taking advantage of this duality and incorporate "pseudo-data" (Snelson & Ghahramani '05) in our model, which in turn allows for more efficient posterior sampling while maintaining the properties of the original model. The validity of the proposed approach is verified through extensive experiments.

Learning Granger Causality for Hawkes Processes Hongteng Xu, Mehrdad Farajtabar, Hongyuan Zha

Learning Granger causality for general point processes is a very challenging tas k. We propose an effective method learning Granger causality for a special but s ignificant type of point processes — Hawkes processes. Focusing on Hawkes processes, we reveal the relationship between Hawkes process's impact functions and it s Granger causality graph. Specifically, our model represents impact functions u sing a series of basis functions and recovers the Granger causality graph via group sparsity of the impact functions' coefficients. We propose an effective lear ning algorithm combining a maximum likelihood estimator (MLE) with a sparse-group-lasso (SGL) regularizer. Additionally, the pairwise similarity between the dimensions of the process is considered when their clustering structure is available. We analyze our learning method and discuss the selection of the basis functions. Experiments on synthetic data and real-world data show that our method can learn the Granger causality graph and the triggering patterns of Hawkes processes simultaneously.

Neural Variational Inference for Text Processing Yishu Miao, Lei Yu, Phil Blunsom

Recent advances in neural variational inference have spawned a renaissance in de ep latent variable models. In this paper we introduce a generic variational infe rence framework for generative and conditional models of text. While traditional variational methods derive an analytic approximation for the intractable distributions over latent variables, here we construct an inference network conditione d on the discrete text input to provide the variational distribution. We validate this framework on two very different text modelling applications, generative document modelling and supervised question answering. Our neural variational document model combines a continuous stochastic document representation with a bag-of-words generative model and achieves the lowest reported perplexities on two standard test corpora. The neural answer selection model employs a stochastic representation layer within an attention mechanism to extract the semantics between a question and answer pair. On two question answering benchmarks this model exceeds all previous published benchmarks.

Dictionary Learning for Massive Matrix Factorization
Arthur Mensch, Julien Mairal, Bertrand Thirion, Gael Varoquaux

Sparse matrix factorization is a popular tool to obtain interpretable data decom positions, which are also effective to perform data completion or denoising. Its applicability to large datasets has been addressed with online and randomized methods, that reduce the complexity in one of the matrix dimension, but not in both of them. In this paper, we tackle very large matrices in both dimensions. We propose a new factorization method that scales gracefully to terabyte-scale data sets. Those could not be processed by previous algorithms in a reasonable amount of time. We demonstrate the efficiency of our approach on massive functional Magnetic Resonance Imaging (fMRI) data, and on matrix completion problems for recommender systems, where we obtain significant speed-ups compared to state-of-the art coordinate descent methods.

Pixel Recurrent Neural Networks

Aäron van den Oord, Nal Kalchbrenner, Koray Kavukcuoglu

Modeling the distribution of natural images is a landmark problem in unsupervise d learning. This task requires an image model that is at once expressive, tracta ble and scalable. We present a deep neural network that sequentially predicts the pixels in an image along the two spatial dimensions. Our method models the discrete probability of the raw pixel values and encodes the complete set of dependencies in the image. Architectural novelties include fast two-dimensional recurrent layers and an effective use of residual connections in deep recurrent networks. We achieve log-likelihood scores on natural images that are considerably bet ter than the previous state of the art. Our main results also provide benchmarks on the diverse ImageNet dataset. Samples generated from the model appear crisp, varied and globally coherent.

Why Most Decisions Are Easy in Tetris—And Perhaps in Other Sequential Decision P roblems, As Well

Özgür ■im■ek, Simón Algorta, Amit Kothiyal

We examined the sequence of decision problems that are encountered in the game of Tetris and found that most of the problems are easy in the following sense: On e can choose well among the available actions without knowing an evaluation function that scores well in the game. This is a consequence of three conditions that are prevalent in the game: simple dominance, cumulative dominance, and noncompensation. These conditions can be exploited to develop faster and more effective learning algorithms. In addition, they allow certain types of domain knowledge to be incorporated with ease into a learning algorithm. Among the sequential decision problems we encounter, it is unlikely that Tetris is unique or rare in having these properties.

Gaussian quadrature for matrix inverse forms with applications Chengtao Li, Suvrit Sra, Stefanie Jegelka

We present a framework for accelerating a spectrum of machine learning algorithm s that require computation of \emphbilinear inverse forms u^T A^-lu, where A is a positive definite matrix and u a given vector. Our framework is built on Gauss-type quadrature and easily scales to large, sparse matrices. Further, it allows retrospective computation of lower and upper bounds on u^T A^-lu, which in turn accelerates several algorithms. We prove that these bounds tighten iteratively and converge at a linear (geometric) rate. To our knowledge, ours is the first w ork to demonstrate these key properties of Gauss-type quadrature, which is a cla ssical and deeply studied topic. We illustrate empirical consequences of our results by using quadrature to accelerate machine learning tasks involving determin antal point processes and submodular optimization, and observe tremendous speedups in several instances.

Train and Test Tightness of LP Relaxations in Structured Prediction Ofer Meshi, Mehrdad Mahdavi, Adrian Weller, David Sontag

Structured prediction is used in areas such as computer vision and natural langu age processing to predict structured outputs such as segmentations or parse tree s. In these settings, prediction is performed by MAP inference or, equivalently,

by solving an integer linear program. Because of the complex scoring functions required to obtain accurate predictions, both learning and inference typically r equire the use of approximate solvers. We propose a theoretical explanation to t he striking observation that approximations based on linear programming (LP) rel axations are often tight on real-world instances. In particular, we show that le arning with LP relaxed inference encourages integrality of training instances, a nd that tightness generalizes from train to test data.

Stochastic Optimization for Multiview Representation Learning using Partial Leas t Squares

Raman Arora, Poorya Mianjy, Teodor Marinov

Partial Least Squares (PLS) is a ubiquitous statistical technique for bilinear f actor analysis. It is used in many data analysis, machine learning, and informat ion retrieval applications to model the covariance structure between a pair of d ata matrices. In this paper, we consider PLS for representation learning in a mu ltiview setting where we have more than one view in data at training time. Furth ermore, instead of framing PLS as a problem about a fixed given data set, we arg ue that PLS should be studied as a stochastic optimization problem, especially in a "big data" setting, with the goal of optimizing a population objective based on sample. This view suggests using Stochastic Approximation (SA) approaches, such as Stochastic Gradient Descent (SGD) and enables a rigorous analysis of their benefits. In this paper, we develop SA approaches to PLS and provide iteration complexity bounds for the proposed algorithms.

Hierarchical Compound Poisson Factorization

Mehmet Basbug, Barbara Engelhardt

Non-negative matrix factorization models based on a hierarchical Gamma-Poisson s tructure capture user and item behavior effectively in extremely sparse data set s, making them the ideal choice for collaborative filtering applications. Hierar chical Poisson factorization (HPF) in particular has proved successful for scala ble recommendation systems with extreme sparsity. HPF, however, suffers from a t ight coupling of sparsity model (absence of a rating) and response model (the value of the rating), which limits the expressiveness of the latter. Here, we introduce hierarchical compound Poisson factorization (HCPF) that has the favorable Gamma-Poisson structure and scalability of HPF to high-dimensional extremely sparse matrices. More importantly, HCPF decouples the sparsity model from the response model, allowing us to choose the most suitable distribution for the response. HCPF can capture binary, non-negative discrete, non-negative continuous, and z ero-inflated continuous responses. We compare HCPF with HPF on nine discrete and three continuous data sets and conclude that HCPF captures the relationship bet ween sparsity and response better than HPF.

Opponent Modeling in Deep Reinforcement Learning

He He, Jordan Boyd-Graber, Kevin Kwok, Hal Daumé III

No penalty no tears: Least squares in high-dimensional linear models Xiangyu Wang, David Dunson, Chenlei Leng

Ordinary least squares (OLS) is the default method for fitting linear models, bu

t is not applicable for problems with dimensionality larger than the sample size . For these problems, we advocate the use of a generalized version of OLS motiva ted by ridge regression, and propose two novel three-step algorithms involving 1 east squares fitting and hard thresholding. The algorithms are methodologically simple to understand intuitively, computationally easy to implement efficiently, and theoretically appealing for choosing models consistently. Numerical exercis es comparing our methods with penalization-based approaches in simulations and d ata analyses illustrate the great potential of the proposed algorithms.

SDNA: Stochastic Dual Newton Ascent for Empirical Risk Minimization Zheng Qu, Peter Richtarik, Martin Takac, Olivier Fercoq

We propose a new algorithm for minimizing regularized empirical loss: Stochastic Dual Newton Ascent (SDNA). Our method is dual in nature: in each iteration we u pdate a random subset of the dual variables. However, unlike existing methods su ch as stochastic dual coordinate ascent, SDNA is capable of utilizing all local curvature information contained in the examples, which leads to striking improve ments in both theory and practice – sometimes by orders of magnitude. In the spe cial case when an L2-regularizer is used in the primal, the dual problem is a concave quadratic maximization problem plus a separable term. In this regime, SDNA in each step solves a proximal subproblem involving a random principal submatrix of the Hessian of the quadratic function; whence the name of the method.

On Graduated Optimization for Stochastic Non-Convex Problems Elad Hazan, Kfir Yehuda Levy, Shai Shalev-Shwartz

The graduated optimization approach, also known as the continuation method, is a popular heuristic to solving non-convex problems that has received renewed inte rest over the last decade. Despite being popular, very little is known in terms of its theoretical convergence analysis. In this paper we describe a new first-or der algorithm based on graduated optimization and analyze its performance. We characterize a family of non-convex functions for which this algorithm provably converges to a global optimum. In particular, we prove that the algorithm converges to an ϵ -approximate solution within O(1 / ϵ ^2) gradient-based steps. We extend our algorithm and analysis to the setting of stochastic non-convex optimization with noisy gradient feedback, attaining the same convergence rate. Additionally, we discuss the setting of "zero-order optimization", and devise a variant of our algorithm which converges at rate of O(d^2/ ϵ ^4).

Meta-Learning with Memory-Augmented Neural Networks

Adam Santoro, Sergey Bartunov, Matthew Botvinick, Daan Wierstra, Timothy Lillicr ap

Despite recent breakthroughs in the applications of deep neural networks, one se tting that presents a persistent challenge is that of "one-shot learning." Traditional gradient-based networks require a lot of data to learn, often through ext ensive iterative training. When new data is encountered, the models must inefficiently relearn their parameters to adequately incorporate the new information without catastrophic interference. Architectures with augmented memory capacities, such as Neural Turing Machines (NTMs), offer the ability to quickly encode and retrieve new information, and hence can potentially obviate the downsides of conventional models. Here, we demonstrate the ability of a memory-augmented neural network to rapidly assimilate new data, and leverage this data to make accurate predictions after only a few samples. We also introduce a new method for accessing an external memory that focuses on memory content, unlike previous methods that additionally use memory location-based focusing mechanisms.

The knockoff filter for FDR control in group-sparse and multitask regression Ran Dai, Rina Barber

We propose the group knockoff filter, a method for false discovery rate control in a linear regression setting where the features are grouped, and we would like to select a set of relevant groups which have a nonzero effect on the response. By considering the set of true and false discoveries at the group level, this m

ethod gains power relative to sparse regression methods. We also apply our method to the multitask regression problem where multiple response variables share si milar sparsity patterns across the set of possible features. Empirically, the group knockoff filter successfully controls false discoveries at the group level in both settings, with substantially more discoveries made by leveraging the group structure.

Softened Approximate Policy Iteration for Markov Games Julien Pérolat, Bilal Piot, Matthieu Geist, Bruno Scherrer, Olivier Pietquin This paper reports theoretical and empirical investigations on the use of quasi-Newton methods to minimize the Optimal Bellman Residual (OBR) of zero-sum two-pl ayer Markov Games. First, it reveals that state-of-the-art algorithms can be der ived by the direct application of Newton's method to different norms of the OBR. More precisely, when applied to the norm of the OBR, Newton's method results in the Bellman Residual Minimization Policy Iteration (BRMPI) and, when applied to the norm of the Projected OBR (POBR), it results into the standard Least Square s Policy Iteration (LSPI) algorithm. Consequently, new algorithms are proposed, making use of quasi-Newton methods to minimize the OBR and the POBR so as to tak e benefit of enhanced empirical performances at low cost. Indeed, using a quasi-Newton method approach introduces slight modifications in term of coding of LSPI and BRMPI but improves significantly both the stability and the performance of those algorithms. These phenomena are illustrated on an experiment conducted on artificially constructed games called Garnets.

Stochastic Block BFGS: Squeezing More Curvature out of Data Robert Gower, Donald Goldfarb, Peter Richtarik

We propose a novel limited-memory stochastic block BFGS update for incorporating enriched curvature information in stochastic approximation methods. In our meth od, the estimate of the inverse Hessian matrix that is maintained by it, is updated at each iteration using a sketch of the Hessian, i.e., a randomly generated compressed form of the Hessian. We propose several sketching strategies, present a new quasi-Newton method that uses stochastic block BFGS updates combined with the variance reduction approach SVRG to compute batch stochastic gradients, and prove linear convergence of the resulting method. Numerical tests on large-scal e logistic regression problems reveal that our method is more robust and substantially outperforms current state-of-the-art methods.

Differential Geometric Regularization for Supervised Learning of Classifiers Qinxun Bai, Steven Rosenberg, Zheng Wu, Stan Sclaroff

We study the problem of supervised learning for both binary and multiclass class ification from a unified geometric perspective. In particular, we propose a geom etric regularization technique to find the submanifold corresponding to an estim ator of the class probability P(y|vec x). The regularization term measures the volume of this submanifold, based on the intuition that overfitting produces rap id local oscillations and hence large volume of the estimator. This technique can be applied to regularize any classification function that satisfies two requirements: firstly, an estimator of the class probability can be obtained; secondly, first and second derivatives of the class probability estimator can be calculated. In experiments, we apply our regularization technique to standard loss functions for classification, our RBF-based implementation compares favorably to widely used regularization methods for both binary and multiclass classification.

Exploiting Cyclic Symmetry in Convolutional Neural Networks Sander Dieleman, Jeffrey De Fauw, Koray Kavukcuoglu

Many classes of images exhibit rotational symmetry. Convolutional neural network s are sometimes trained using data augmentation to exploit this, but they are st ill required to learn the rotation equivariance properties from the data. Encoding these properties into the network architecture, as we are already used to doing for translation equivariance by using convolutional layers, could result in a more efficient use of the parameter budget by relieving the model from learning

them. We introduce four operations which can be inserted into neural network mo dels as layers, and which can be combined to make these models partially equivar iant to rotations. They also enable parameter sharing across different orientati ons. We evaluate the effect of these architectural modifications on three datase ts which exhibit rotational symmetry and demonstrate improved performance with s maller models.

Graying the black box: Understanding DQNs

Tom Zahavy, Nir Ben-Zrihem, Shie Mannor

In recent years there is a growing interest in using deep representations for re inforcement learning. In this paper, we present a methodology and tools to analy ze Deep Q-networks (DQNs) in a non-blind matter. Using our tools we reveal that the features learned by DQNs aggregate the state space in a hierarchical fashion , explaining its success. Moreover we are able to understand and describe the po licies learned by DQNs for three different Atari2600 games and suggest ways to i nterpret, debug and optimize of deep neural networks in Reinforcement Learning.

The Sum-Product Theorem: A Foundation for Learning Tractable Models Abram Friesen, Pedro Domingos

Inference in expressive probabilistic models is generally intractable, which mak es them difficult to learn and limits their applicability. Sum-product networks are a class of deep models where, surprisingly, inference remains tractable even when an arbitrary number of hidden layers are present. In this paper, we genera lize this result to a much broader set of learning problems: all those where inference consists of summing a function over a semiring. This includes satisfiability, constraint satisfaction, optimization, integration, and others. In any semiring, for summation to be tractable it suffices that the factors of every product have disjoint scopes. This unifies and extends many previous results in the literature. Enforcing this condition at learning time thus ensures that the learned models are tractable. We illustrate the power and generality of this approach by applying it to a new type of structured prediction problem: learning a noncon vex function that can be globally optimized in polynomial time. We show empirically that this greatly outperforms the standard approach of learning without regard to the cost of optimization.

Pareto Frontier Learning with Expensive Correlated Objectives Amar Shah, Zoubin Ghahramani

There has been a surge of research interest in developing tools and analysis for Bayesian optimization, the task of finding the global maximizer of an unknown, expensive function through sequential evaluation using Bayesian decision theory. However, many interesting problems involve optimizing multiple, expensive to evaluate objectives simultaneously, and relatively little research has addressed this setting from a Bayesian theoretic standpoint. A prevailing choice when tackling this problem, is to model the multiple objectives as being independent, typically for ease of computation. In practice, objectives are correlated to some extent. In this work, we incorporate the modelling of inter-task correlations, developing an approximation to overcome intractable integrals. We illustrate the power of modelling dependencies between objectives on a range of synthetic and real world multi-objective optimization problems.

Asynchronous Methods for Deep Reinforcement Learning

Volodymyr Mnih, Adria Puigdomenech Badia, Mehdi Mirza, Alex Graves, Timothy Lill icrap, Tim Harley, David Silver, Koray Kavukcuoglu

We propose a conceptually simple and lightweight framework for deep reinforcemen t learning that uses asynchronous gradient descent for optimization of deep neur al network controllers. We present asynchronous variants of four standard reinfo reement learning algorithms and show that parallel actor-learners have a stabili zing effect on training allowing all four methods to successfully train neural n etwork controllers. The best performing method, an asynchronous variant of actor-critic, surpasses the current state-of-the-art on the Atari domain while traini

ng for half the time on a single multi-core CPU instead of a GPU. Furthermore, we show that asynchronous actor-critic succeeds on a wide variety of continuous motor control problems as well as on a new task of navigating random 3D mazes using a visual input.

A Simple and Strongly-Local Flow-Based Method for Cut Improvement Nate Veldt, David Gleich, Michael Mahoney

Many graph-based learning problems can be cast as finding a good set of vertices nearby a seed set, and a powerful methodology for these problems is based on mi nimum cuts and maximum flows. We introduce and analyze a new method for locally-biased graph-based learning called SimpleLocal, which finds good conductance cut s near a set of seed vertices. An important feature of our algorithm is that it is strongly-local, meaning it does not need to explore the entire graph to find cuts that are locally optimal. This method is related to other strongly-local flow-based methods, but it enables a simple implementation. We also show how it achieves localization through an implicit l1-norm penalty term. As a flow-based method, our algorithm exhibits several advantages in terms of cut optimality and a ccurate identification of target regions in a graph. We demonstrate the power of SimpleLocal solving segmentation problems on a 467 million edge graph based on an MRI scan.

Nonlinear Statistical Learning with Truncated Gaussian Graphical Models Qinliang Su, Xuejun Liao, Changyou Chen, Lawrence Carin

We introduce the truncated Gaussian graphical model (TGGM) as a novel framework for designing statistical models for nonlinear learning. A TGGM is a Gaussian graphical model (GGM) with a subset of variables truncated to be nonnegative. The truncated variables are assumed latent and integrated out to induce a marginal model. We show that the variables in the marginal model are non-Gaussian distributed and their expected relations are nonlinear. We use expectation-maximization to break the inference of the nonlinear model into a sequence of TGGM inference problems, each of which is efficiently solved by using the properties and numerical methods of multivariate Gaussian distributions. We use the TGGM to design models for nonlinear regression and classification, with the performances of these models demonstrated on extensive benchmark datasets and compared to state-of-the-

Barron and Cover's Theory in Supervised Learning and its Application to Lasso Masanori Kawakita, Jun'ichi Takeuchi

We study Barron and Cover's theory (BC theory) in supervised learning. The original BC theory can be applied to supervised learning only approximately and limit edly. Though Barron (2008) and Chatterjee and Barron (2014) succeeded in removing the approximation, their idea cannot be essentially applied to supervised learning in general. By solving this issue, we propose an extension of BC theory to supervised learning. The extended theory has several advantages inherited from the original BC theory. First, it holds for finite sample number n. Second, it requires remarkably few assumptions. Third, it gives a justification of the MDL principle in supervised learning. We also derive new risk and regret bounds of lasso with random design as its application. The derived risk bound hold for any finite n without boundedness of features in contrast to past work. Behavior of the regret bound is investigated by numerical simulations. We believe that this is the first extension of BC theory to general supervised learning without approximation.

Nonparametric Canonical Correlation Analysis Tomer Michaeli, Weiran Wang, Karen Livescu

Canonical correlation analysis (CCA) is a classical representation learning tech nique for finding correlated variables in multi-view data. Several nonlinear ext ensions of the original linear CCA have been proposed, including kernel and deep neural network methods. These approaches seek maximally correlated projections among families of functions, which the user specifies (by choosing a kernel or n

eural network structure), and are computationally demanding. Interestingly, the theory of nonlinear CCA, without functional restrictions, had been studied in the population setting by Lancaster already in the 1950s, but these results have not inspired practical algorithms. We revisit Lancaster's theory to devise a practical algorithm for nonparametric CCA (NCCA). Specifically, we show that the solution can be expressed in terms of the singular value decomposition of a certain operator associated with the joint density of the views. Thus, by estimating the population density from data, NCCA reduces to solving an eigenvalue system, su perficially like kernel CCA but, importantly, without requiring the inversion of any kernel matrix. We also derive a partially linear CCA (PLCCA) variant in which one of the views undergoes a linear projection while the other is nonparametric. Using a kernel density estimate based on a small number of nearest neighbors, our NCCA and PLCCA algorithms are memory-efficient, often run much faster, and perform better than kernel CCA and comparable to deep CCA.

BISTRO: An Efficient Relaxation-Based Method for Contextual Bandits Alexander Rakhlin, Karthik Sridharan

We present efficient algorithms for the problem of contextual bandits with i.i.d. covariates, an arbitrary sequence of rewards, and an arbitrary class of polici es. Our algorithm BISTRO requires d calls to the empirical risk minimization (ER M) oracle per round, where d is the number of actions. The method uses unlabeled data to make the problem computationally simple. When the ERM problem itself is computationally hard, we extend the approach by employing multiplicative approx imation algorithms for the ERM. The integrality gap of the relaxation only enter s in the regret bound rather than the benchmark. Finally, we show that the adver sarial version of the contextual bandit problem is learnable (and efficient) whe never the full-information supervised online learning problem has a non-trivial regret bound (and efficient).

Associative Long Short-Term Memory

Ivo Danihelka, Greg Wayne, Benigno Uria, Nal Kalchbrenner, Alex Graves We investigate a new method to augment recurrent neural networks with extra memo ry without increasing the number of network parameters. The system has an associ ative memory based on complex-valued vectors and is closely related to Holograph ic Reduced Representations and Long Short-Term Memory networks. Holographic Reduced Representations have limited capacity: as they store more information, each retrieval becomes noisier due to interference. Our system in contrast creates re dundant copies of stored information, which enables retrieval with reduced noise. Experiments demonstrate faster learning on multiple memorization tasks.

Dueling Network Architectures for Deep Reinforcement Learning
Ziyu Wang, Tom Schaul, Matteo Hessel, Hado Hasselt, Marc Lanctot, Nando Freitas
In recent years there have been many successes of using deep representations in
reinforcement learning. Still, many of these applications use conventional archi
tectures, such as convolutional networks, LSTMs, or auto-encoders. In this paper
, we present a new neural network architecture for model-free reinforcement lear
ning. Our dueling network represents two separate estimators: one for the state
value function and one for the state-dependent action advantage function. The ma
in benefit of this factoring is to generalize learning across actions without im
posing any change to the underlying reinforcement learning algorithm. Our result
s show that this architecture leads to better policy evaluation in the presence
of many similar-valued actions. Moreover, the dueling architecture enables our R
L agent to outperform the state-of-the-art on the Atari 2600 domain.

Persistence weighted Gaussian kernel for topological data analysis Genki Kusano, Yasuaki Hiraoka, Kenji Fukumizu

Topological data analysis (TDA) is an emerging mathematical concept for characte rizing shapes in complex data. In TDA, persistence diagrams are widely recognize d as a useful descriptor of data, and can distinguish robust and noisy topologic al properties. This paper proposes a kernel method on persistence diagrams to de

velop a statistical framework in TDA. The proposed kernel satisfies the stabilit y property and provides explicit control on the effect of persistence. Furthermo re, the method allows a fast approximation technique. The method is applied into practical data on proteins and oxide glasses, and the results show the advantage of our method compared to other relevant methods on persistence diagrams.

Learning Convolutional Neural Networks for Graphs Mathias Niepert, Mohamed Ahmed, Konstantin Kutzkov

Numerous important problems can be framed as learning from graph data. We propose a framework for learning convolutional neural networks for arbitrary graphs. These graphs may be undirected, directed, and with both discrete and continuous node and edge attributes. Analogous to image-based convolutional networks that operate on locally connected regions of the input, we present a general approach to extracting locally connected regions from graphs. Using established benchmark data sets, we demonstrate that the learned feature representations are competitive with state of the art graph kernels and that their computation is highly efficient.

Persistent RNNs: Stashing Recurrent Weights On-Chip

Greg Diamos, Shubho Sengupta, Bryan Catanzaro, Mike Chrzanowski, Adam Coates, Erich Elsen, Jesse Engel, Awni Hannun, Sanjeev Satheesh

This paper introduces a new technique for mapping Deep Recurrent Neural Networks (RNN) efficiently onto GPUs. We show how it is possi- ble to achieve substantia lly higher computational throughput at low mini-batch sizes than direct implemen tations of RNNs based on matrix multiplications. The key to our approach is the use of persistent computational kernels that exploit the GPU's inverted memory h ierarchy to reuse network weights over multiple timesteps. Our initial implement ation sustains 2.8 TFLOP/s at a mini-batch size of 4 on an NVIDIA TitanX GPU. Th is provides a 16x reduction in activation memory footprint, enables model training with 12x more parameters on the same hardware, allows us to strongly scale RN N training to 128 GPUs, and allows us to efficiently explore end-to-end speech recognition models with over 100 layers.

Recurrent Orthogonal Networks and Long-Memory Tasks

Mikael Henaff, Arthur Szlam, Yann LeCun

Although RNNs have been shown to be power- ful tools for processing sequential d ata, finding architectures or optimization strategies that al- low them to model very long term dependencies is still an active area of research. In this work, we carefully analyze two synthetic datasets orig- inally outlined in (Hochreiter & Schmidhuber, 1997) which are used to evaluate the ability of RNNs to store in formation over many time steps. We explicitly construct RNN solutions to these p roblems, and using these constructions, illumi- nate both the problems themselves and the way in which RNNs store different types of information in their hidden states. These constructions fur- thermore explain the success of recent methods that specify unitary initializations or constraints on the transition matrices.

The Arrow of Time in Multivariate Time Series Stefan Bauer, Bernhard Schölkopf, Jonas Peters

We prove that a time series satisfying a (linear) multivariate autoregressive mo ving average (VARMA) model satisfies the same model assumption in the reversed time direction, too, if all innovations are normally distributed. This reversibility breaks down if the innovations are non-Gaussian. This means that under the a ssumption of a VARMA process with non-Gaussian noise, the arrow of time becomes detectable. Our work thereby provides a theoretic justification of an algorithm that has been used for inferring the direction of video snippets. We present a slightly modified practical algorithm that estimates the time direction for a given sample and prove its consistency. We further investigate how the performance of the algorithm depends on sample size, number of dimensions of the time series and the order of the process. An application to real world data from economics shows that considering multivariate processes instead of univariate processes ca

n be beneficial for estimating the time direction. Our result extends earlier wo rk on univariate time series. It relates to the concept of causal inference, whe re recent methods exploit non-Gaussianity of the error terms for causal structur e learning.

Mixture Proportion Estimation via Kernel Embeddings of Distributions Harish Ramaswamy, Clayton Scott, Ambuj Tewari

Mixture proportion estimation (MPE) is the problem of estimating the weight of a component distribution in a mixture, given samples from the mixture and compone nt. This problem constitutes a key part in many "weakly supervised learning" pro blems like learning with positive and unlabelled samples, learning with label no ise, anomaly detection and crowdsourcing. While there have been several methods proposed to solve this problem, to the best of our knowledge no efficient algori thm with a proven convergence rate towards the true proportion exists for this p roblem. We fill this gap by constructing a provably correct algorithm for MPE, a nd derive convergence rates under certain assumptions on the distribution. Our m ethod is based on embedding distributions onto an RKHS, and implementing it only requires solving a simple convex quadratic programming problem a few times. We run our algorithm on several standard classification datasets, and demonstrate t hat it performs comparably to or better than other algorithms on most datasets.

Fast DPP Sampling for Nystrom with Application to Kernel Methods Chengtao Li, Stefanie Jegelka, Suvrit Sra

The Nystrom method has long been popular for scaling up kernel methods. Its theo retical guarantees and empirical performance rely critically on the quality of the landmarks selected. We study landmark selection for Nystrom using Determinant al Point Processes (DPPs), discrete probability models that allow tractable gene ration of diverse samples. We prove that landmarks selected via DPPs guarantee bounds on approximation errors; subsequently, we analyze implications for kernel ridge regression. Contrary to prior reservations due to cubic complexity of DPP sampling, we show that (under certain conditions) Markov chain DPP sampling requires only linear time in the size of the data. We present several empirical results that support our theoretical analysis, and demonstrate the superior performance of DPP-based landmark selection compared with existing approaches.

Complex Embeddings for Simple Link Prediction

Théo Trouillon, Johannes Welbl, Sebastian Riedel, Eric Gaussier, Guillaume Bouch ard

In statistical relational learning, the link prediction problem is key to automa tically understand the structure of large knowledge bases. As in previous studie s, we propose to solve this problem through latent factorization. However, here we make use of complex valued embeddings. The composition of complex embeddings can handle a large variety of binary relations, among them symmetric and antisym metric relations. Compared to state-of-the-art models such as Neural Tensor Netw ork and Holographic Embeddings, our approach based on complex embeddings is argu ably simpler, as it only uses the Hermitian dot product, the complex counterpart of the standard dot product between real vectors. Our approach is scalable to 1 arge datasets as it remains linear in both space and time, while consistently ou tperforming alternative approaches on standard link prediction benchmarks.

Interactive Bayesian Hierarchical Clustering

Sharad Vikram, Sanjoy Dasgupta

Clustering is a powerful tool in data analysis, but it is often difficult to fin d a grouping that aligns with a user's needs. To address this, several methods i ncorporate constraints obtained from users into clustering algorithms, but unfor tunately do not apply to hierarchical clustering. We design an interactive Bayes ian algorithm that incorporates user interaction into hierarchical clustering wh ile still utilizing the geometry of the data by sampling a constrained posterior distribution over hierarchies. We also suggest several ways to intelligently query a user. The algorithm, along with the querying schemes, shows promising resu

lts on real data.

A Convolutional Attention Network for Extreme Summarization of Source Code Miltiadis Allamanis, Hao Peng, Charles Sutton

Attention mechanisms in neural networks have proved useful for problems in which the input and output do not have fixed dimension. Often there exist features th at are locally translation invariant and would be valuable for directing the mod el's attention, but previous attentional architectures are not constructed to le arn such features specifically. We introduce an attentional neural network that employs convolution on the input tokens to detect local time-invariant and longrange topical attention features in a context-dependent way. We apply this architecture to the problem of extreme summarization of source code snippets into short, descriptive function name-like summaries. Using those features, the model se quentially generates a summary by marginalizing over two attention mechanisms: one that predicts the next summary token based on the attention weights of the input tokens and another that is able to copy a code token as-is directly into the summary. We demonstrate our convolutional attention neural network's performance on 10 popular Java projects showing that it achieves better performance compared to previous attentional mechanisms.

How to Fake Multiply by a Gaussian Matrix

Michael Kapralov, Vamsi Potluru, David Woodruff

Have you ever wanted to multiply an n \times d matrix X, with n $\blacksquare d$, on the left by an m \times n matrix \tilde G of i.i.d. Gaussian random variables, but could not afford to do it because it was too slow? In this work we propose a new rando mized m \times n matrix T, for which one can compute T \cdot X in only O(nnz(X)) +\tilde $O(m^1.5 \cdot d^3)$ time, for which the total variation distance between the dist ributions T \cdot X and \tilde G \cdot X is as small as desired, i.e., less than any posit ive constant. Here nnz(X) denotes the number of non-zero entries of X. Assuming nnz(X) $\blacksquare m^1.5 \cdot d^3$, this is a significant savings over the naïve O(nnz(X)) m) time to compute \tilde G \cdot X. Moreover, since the total variation distance is small, we can provably use T \cdot X in place of \tilde G \cdot X in any application and have the same guarantees as if we were using \tilde G \cdot X, up to a small positive constant in error probability. We apply this transform to nonnegative matrix factorization (NMF) and support vector machines (SVM).

Differentially Private Chi-Squared Hypothesis Testing: Goodness of Fit and Indep endence Testing

Marco Gaboardi, Hyun Lim, Ryan Rogers, Salil Vadhan

Hypothesis testing is a useful statistical tool in determining whether a given m odel should be rejected based on a sample from the population. Sample data may c ontain sensitive information about individuals, such as medical information. Thu s it is important to design statistical tests that guarantee the privacy of subjects in the data. In this work, we study hypothesis testing subject to different ial privacy, specifically chi-squared tests for goodness of fit for multinomial data and independence between two categorical variables.

Pliable Rejection Sampling

Akram Erraqabi, Michal Valko, Alexandra Carpentier, Odalric Maillard

Rejection sampling is a technique for sampling from difficult distributions. How ever, its use is limited due to a high rejection rate. Common adaptive rejection sampling methods either work only for very specific distributions or without pe rformance guarantees. In this paper, we present pliable rejection sampling (PRS), a new approach to rejection sampling, where we learn the sampling proposal using a kernel estimator. Since our method builds on rejection sampling, the sample sobtained are with high probability i.i.d. and distributed according to f. More over, PRS comes with a guarantee on the number of accepted samples.

Differentially Private Policy Evaluation Borja Balle, Maziar Gomrokchi, Doina Precup We present the first differentially private algorithms for reinforcement learnin g, which apply to the task of evaluating a fixed policy. We establish two approaches for achieving differential privacy, provide a theoretical analysis of the privacy and utility of the two algorithms, and show promising results on simple empirical examples.

Data-Efficient Off-Policy Policy Evaluation for Reinforcement Learning Philip Thomas, Emma Brunskill

In this paper we present a new way of predicting the performance of a reinforcem ent learning policy given historical data that may have been generated by a diff erent policy. The ability to evaluate a policy from historical data is important for applications where the deployment of a bad policy can be dangerous or costly. We show empirically that our algorithm produces estimates that often have ord ers of magnitude lower mean squared error than existing methods—it makes more efficient use of the available data. Our new estimator is based on two advances: a n extension of the doubly robust estimator (Jiang & Li, 2015), and a new way to mix between model based and importance sampling based estimates.

Discrete Deep Feature Extraction: A Theory and New Architectures
Thomas Wiatowski, Michael Tschannen, Aleksandar Stanic, Philipp Grohs, Helmut Bo
elcskei

First steps towards a mathematical theory of deep convolutional neural networks for feature extraction were made—for the continuous—time case—in Mallat, 2012, a nd Wiatowski and Bölcskei, 2015. This paper considers the discrete case, introdu ces new convolutional neural network architectures, and proposes a mathematical framework for their analysis. Specifically, we establish deformation and transla tion sensitivity results of local and global nature, and we investigate how cert ain structural properties of the input signal are reflected in the corresponding feature vectors. Our theory applies to general filters and general Lipschitz—continuous non—linearities and pooling operators. Experiments on handwritten digit classification and facial landmark detection—including feature importance evaluation—complement the theoretical findings.

Efficient Algorithms for Adversarial Contextual Learning Vasilis Syrgkanis, Akshay Krishnamurthy, Robert Schapire

We provide the first oracle efficient sublinear regret algorithms for adversaria l versions of the contextual bandit problem. In this problem, the learner repeat edly makes an action on the basis of a context and receives reward for the chose n action, with the goal of achieving reward competitive with a large class of po licies. We analyze two settings: i) in the transductive setting the learner know s the set of contexts a priori, ii) in the small separator setting, there exists a small set of contexts such that any two policies behave differently on one of the contexts in the set. Our algorithms fall into the Follow-The-Perturbed-Leader family (Kalai and Vempala, 2005) and achieve regret O(T^3/4\sqrtK\log(N)) in the transductive setting and O(T^2/3 d^3/4 K\sqrt\log(N)) in the separator setti ng, where T is the number of rounds, K is the number of actions, N is the number of baseline policies, and d is the size of the separator. We actually solve the more general adversarial contextual semi-bandit linear optimization problem, wh ilst in the full information setting we address the even more general contextual combinatorial optimization. We provide several extensions and implications of o ur algorithms, such as switching regret and efficient learning with predictable sequences.

Training Deep Neural Networks via Direct Loss Minimization
Yang Song, Alexander Schwing, Richard, Raquel Urtasun
Supervised training of deep neural nets typically relies on minimizing cross-ent
ropy. However, in many domains, we are interested in performing well on metrics
specific to the application. In this paper we propose a direct loss minimization

specific to the application. In this paper we propose a direct loss minimization approach to train deep neural networks, which provably minimizes the application-specific loss function. This is often non-trivial, since these functions are n

either smooth nor decomposable and thus are not amenable to optimization with st andard gradient-based methods. We demonstrate the effectiveness of our approach in the context of maximizing average precision for ranking problems. Towards this goal, we develop a novel dynamic programming algorithm that can efficiently compute the weight updates. Our approach proves superior to a variety of baselines in the context of action classification and object detection, especially in the presence of label noise.

Sequence to Sequence Training of CTC-RNNs with Partial Windowing Kyuyeon Hwang, Wonyong Sung

Connectionist temporal classification (CTC) based supervised sequence training o f recurrent neural networks (RNNs) has shown great success in many machine learn ing areas including end-to-end speech and handwritten character recognition. For the CTC training, however, it is required to unroll (or unfold) the RNN by the length of an input sequence. This unrolling requires a lot of memory and hinders a small footprint implementation of online learning or adaptation. Furthermore, the length of training sequences is usually not uniform, which makes parallel t raining with multiple sequences inefficient on shared memory models such as grap hics processing units (GPUs). In this work, we introduce an expectation-maximiza tion (EM) based online CTC algorithm that enables unidirectional RNNs to learn s equences that are longer than the amount of unrolling. The RNNs can also be trai ned to process an infinitely long input sequence without pre-segmentation or ext ernal reset. Moreover, the proposed approach allows efficient parallel training on GPUs. Our approach achieves 20.7% phoneme error rate (PER) on the very long i nput sequence that is generated by concatenating all 192 utterances in the TIMIT core test set. In the end-to-end speech recognition task on the Wall Street Jou rnal corpus, a network can be trained with only 64 times of unrolling with littl e performance loss.

Variational Inference for Monte Carlo Objectives Andriy Mnih, Danilo Rezende

Recent progress in deep latent variable models has largely been driven by the de velopment of flexible and scalable variational inference methods. Variational tr aining of this type involves maximizing a lower bound on the log-likelihood, usi ng samples from the variational posterior to compute the required gradients. Rec ently, Burda et al. (2016) have derived a tighter lower bound using a multi-samp le importance sampling estimate of the likelihood and showed that optimizing it yields models that use more of their capacity and achieve higher likelihoods. Th is development showed the importance of such multi-sample objectives and explain ed the success of several related approaches. We extend the multi-sample approac h to discrete latent variables and analyze the difficulty encountered when estim ating the gradients involved. We then develop the first unbiased gradient estima tor designed for importance-sampled objectives and evaluate it at training gener ative and structured output prediction models. The resulting estimator, which is based on low-variance per-sample learning signals, is both simpler and more eff ective than the NVIL estimator proposed for the single-sample variational object ive, and is competitive with the currently used biased estimators.

Hierarchical Decision Making In Electricity Grid Management Gal Dalal, Elad Gilboa, Shie Mannor

The power grid is a complex and vital system that necessitates careful reliabili ty management. Managing the grid is a difficult problem with multiple time scale s of decision making and stochastic behavior due to renewable energy generations, variable demand and unplanned outages. Solving this problem in the face of uncertainty requires a new methodology with tractable algorithms. In this work, we introduce a new model for hierarchical decision making in complex systems. We apply reinforcement learning (RL) methods to learn a proxy, i.e., a level of abstraction, for real-time power grid reliability. We devise an algorithm that alternates between slow time-scale policy improvement, and fast time-scale value function approximation. We compare our results to prevailing heuristics, and show the

strength of our method.

Learning Sparse Combinatorial Representations via Two-stage Submodular Maximization

Eric Balkanski, Baharan Mirzasoleiman, Andreas Krause, Yaron Singer

We consider the problem of learning sparse representations of data sets, where the goal is to reduce a data set in manner that optimizes multiple objectives. Mo tivated by applications of data summarization, we develop a new model which we refer to as the two-stage submodular maximization problem. This task can be viewed as a combinatorial analogue of representation learning problems such as dictionary learning and sparse regression. The two-stage problem strictly generalizes the problem of cardinality constrained submodular maximization, though the objective function is not submodular and the techniques for submodular maximization cannot be applied. We describe a continuous optimization method which achieves an approximation ratio which asymptotically approaches 1-1/e. For instances where the asymptotics do not kick in, we design a local-search algorithm whose approximation ratio is arbitrarily close to 1/2. We empirically demonstrate the effectiveness of our methods on two multi-objective data summarization tasks, where the goal is to construct summaries via sparse representative subsets w.r.t. to pred efined objectives.

Understanding and Improving Convolutional Neural Networks via Concatenated Rectified Linear Units

Wenling Shang, Kihyuk Sohn, Diogo Almeida, Honglak Lee

Recently, convolutional neural networks (CNNs) have been used as a powerful tool to solve many problems of machine learning and computer vision. In this paper, we aim to provide insight on the property of convolutional neural networks, as well as a generic method to improve the performance of many CNN architectures. Specifically, we first examine existing CNN models and observe an intriguing property that the filters in the lower layers form pairs (i.e., filters with opposite phase). Inspired by our observation, we propose a novel, simple yet effective a ctivation scheme called concatenated ReLU (CReLU) and theoretically analyze its reconstruction property in CNNs. We integrate CReLU into several state-of-the-art CNN architectures and demonstrate improvement in their recognition performance on CIFAR-10/100 and ImageNet datasets with fewer trainable parameters. Our results suggest that better understanding of the properties of CNNs can lead to sign ificant performance improvement with a simple modification.

Isotonic Hawkes Processes

Yichen Wang, Bo Xie, Nan Du, Le Song

Hawkes processes are powerful tools for modeling the mutual-excitation phenomena commonly observed in event data from a variety of domains, such as social netwo rks, quantitative finance and healthcare records. The intensity function of a Hawkes process is typically assumed to be linear in the sum of triggering kernels, rendering it inadequate to capture nonlinear effects present in real-world data. To address this shortcoming, we propose an Isotonic-Hawkes process whose intensity function is modulated by an additional nonlinear link function. We also developed a novel iterative algorithm which learns both the nonlinear link function and other parameters provably. We showed that Isotonic-Hawkes processes can fit a variety of nonlinear patterns which cannot be captured by conventional Hawkes processes, and achieve superior empirical performance in real world application

Cross-Graph Learning of Multi-Relational Associations

Hanxiao Liu, Yiming Yang

Cross-graph Relational Learning (CGRL) refers to the problem of predicting the s trengths or labels of multi-relational tuples of heterogeneous object types, thr ough the joint inference over multiple graphs which specify the internal connect ions among each type of objects. CGRL is an open challenge in machine learning d ue to the daunting number of all possible tuples to deal with when the numbers o

f nodes in multiple graphs are large, and because the labeled training instances are extremely sparse as typical. Existing methods such as tensor factorization or tensor-kernel machines do not work well because of the lack of convex formula tion for the optimization of CGRL models, the poor scalability of the algorithms in handling combinatorial numbers of tuples, and/or the non-transductive nature of the learning methods which limits their ability to leverage unlabeled data in training. This paper proposes a novel framework which formulates CGRL as a convex optimization problem, enables transductive learning using both labeled and unlabeled tuples, and offers a scalable algorithm that guarantees the optimal solution and enjoys a constant time complexity with respect to the sizes of input graphs. In our experiments with a subset of DBLP publication records and an Enzyme multi-source dataset, the proposed method successfully scaled to the large cross-graph inference problem, and outperformed other representative approaches significantly.

Markov-modulated Marked Poisson Processes for Check-in Data

Jiangwei Pan, Vinayak Rao, Pankaj Agarwal, Alan Gelfand

We develop continuous-time probabilistic models to study trajectory data consist ing of times and locations of user "check-ins". We model the data as realization s of a marked point process, with intensity and mark-distribution modulated by a latent Markov jump process (MJP). We also include user-heterogeneity in our mod el by assigning each user a vector of "preferred locations". Our model extends l atent Dirichlet allocation by dropping the bag-of-words assumption and operating in continuous time. We show how an appropriate choice of priors allows efficien t posterior inference. Our experiments demonstrate the usefulness of our approach by comparing with various baselines on a variety of tasks.

Beyond Parity Constraints: Fourier Analysis of Hash Functions for Inference Tudor Achim, Ashish Sabharwal, Stefano Ermon

Random projections have played an important role in scaling up machine learning and data mining algorithms. Recently they have also been applied to probabilistic inference to estimate properties of high-dimensional distributions; however, they all rely on the same class of projections based on universal hashing. We provide a general framework to analyze random projections which relates their statistical properties to their Fourier spectrum, which is a well-studied area of the oretical computer science. Using this framework we introduce two new classes of hash functions for probabilistic inference and model counting that show promising performance on synthetic and real-world benchmarks.

On the Power and Limits of Distance-Based Learning Periklis Papakonstantinou, Jia Xu, Guang Yang

We initiate the study of low-distortion finite metric embeddings in multi-class (and multi-label) classification where (i) both the space of input instances and the space of output classes have combinatorial metric structure and (ii) the concepts we wish to learn are low-distortion embeddings. We develop new geometric techniques and prove strong learning lower bounds. These provable limits hold even when we allow learners and classifiers to get advice by one or more experts. Our study overwhelmingly indicates that post-geometry assumptions are necessary in multi-class classification, as in natural language processing (NLP). Technically, the mathematical tools we developed in this work could be of independent in terest to NLP. To the best of our knowledge, this is the first work which formally studies classification problems in combinatorial spaces. and where the concepts are low-distortion embeddings.

A Convex Atomic-Norm Approach to Multiple Sequence Alignment and Motif Discovery Ian En-Hsu Yen, Xin Lin, Jiong Zhang, Pradeep Ravikumar, Inderjit Dhillon Multiple Sequence Alignment and Motif Discovery, known as NP-hard problems, are two fundamental tasks in Bioinformatics. Existing approaches to these two problems are based on either local search methods such as Expectation Maximization (EM), Gibbs Sampling or greedy heuristic methods. In this work, we develop a convex

relaxation approach to both problems based on the recent concept of atomic norm and develop a new algorithm, termed Greedy Direction Method of Multiplier, for solving the convex relaxation with two convex atomic constraints. Experiments show that our convex relaxation approach produces solutions of higher quality than those standard tools widely-used in Bioinformatics community on the Multiple Sequence Alignment and Motif Discovery problems.

Generalized Direct Change Estimation in Ising Model Structure Farideh Fazayeli, Arindam Banerjee

We consider the problem of estimating change in the dependency structure of two p-dimensional Ising models, based on respectively n_1 and n_2 samples drawn from the models. The change is assumed to be structured, e.g., sparse, block sparse, node-perturbed sparse, etc., such that it can be characterized by a suitable (a tomic) norm. We present and analyze a norm-regularized estimator for directly estimating the change in structure, without having to estimate the structures of the individual Ising models. The estimator can work with any norm, and can be generalized to other graphical models under mild assumptions. We show that only one set of samples, say n_2 , needs to satisfy the sample complexity requirement for the estimator to work, and the estimation error decreases as $\frac{1}{n_2}$, where c depends on the Gaussian width of the unit norm ball. For example, for $\frac{1}{n_2}$, where c depends on the Gaussian width of the unit norm ball. For example ated with $\frac{1}{n_1}$ norm applied to s-sparse change, the change can be accurately estim ated with $\frac{1}{n_1}$ norm applied to s-sparse change, the change can be accurately estim ated with $\frac{1}{n_1}$ norm applied to s-sparse change, the change can be accurately estim ated with $\frac{1}{n_1}$ norm applied to s-sparse change, the change can be accurately estim ated with $\frac{1}{n_1}$ norm applied to s-sparse change, the change can be accurately estim ated with $\frac{1}{n_1}$ norm applied to s-sparse change, the change can be accurately estim ated with $\frac{1}{n_1}$ norm applied to s-sparse change, the change can be accurately estim ated with $\frac{1}{n_1}$ norm applied to s-sparse change, the change can be accurately estim ated with $\frac{1}{n_1}$ norm applied to s-sparse change, the change can be accurately estim at no sparse change.

Robust Principal Component Analysis with Side Information Kai-Yang Chiang, Cho-Jui Hsieh, Inderjit Dhillon

The robust principal component analysis (robust PCA) problem has been considered in many machine learning applications, where the goal is to decompose the data matrix as a low rank part plus a sparse residual. While current approaches are d eveloped by only considering the low rank plus sparse structure, in many applica tions, side information of row and/or column entities may also be given, and it is still unclear to what extent could such information help robust PCA. Thus, in this paper, we study the problem of robust PCA with side information, where bot h prior structure and features of entities are exploited for recovery. We propos e a convex problem to incorporate side information in robust PCA and show that t he low rank matrix can be exactly recovered via the proposed method under certai n conditions. In particular, our guarantee suggests that a substantial amount of low rank matrices, which cannot be recovered by standard robust PCA, become rec overable by our proposed method. The result theoretically justifies the effectiv eness of features in robust PCA. In addition, we conduct synthetic experiments a s well as a real application on noisy image classification to show that our meth od also improves the performance in practice by exploiting side information.

Towards Faster Rates and Oracle Property for Low-Rank Matrix Estimation Huan Gui, Jiawei Han, Quanquan Gu

We present a unified framework for low-rank matrix estimation with a nonconvex p enalty. A proximal gradient homotopy algorithm is proposed to solve the proposed optimization problem. Theoretically, we first prove that the proposed estimator attains a faster statistical rate than the traditional low-rank matrix estimator with nuclear norm penalty. Moreover, we rigorously show that under a certain c ondition on the magnitude of the nonzero singular values, the proposed estimator enjoys oracle property (i.e., exactly recovers the true rank of the matrix), be sides attaining a faster rate. Extensive numerical experiments on both synthetic and real world datasets corroborate our theoretical findings.

Early and Reliable Event Detection Using Proximity Space Representation Maxime Sangnier, Jerome Gauthier, Alain Rakotomamonjy

Let us consider a specific action or situation (called event) that takes place w ithin a time series. The objective in early detection is to build a decision fun

ction that is able to go off as soon as possible from the onset of an occurrence of this event. This implies making a decision with an incomplete information. T his paper proposes a novel framework that i) guarantees that a detection made wi th a partial observation will also occur at full observation of the time-series; ii) incorporates in a consistent manner the lack of knowledge about the minimal amount of information needed to make a decision. The proposed detector is based on mapping the temporal sequences to a landmarking space thanks to appropriatel y designed similarity functions. As a by-product, the framework benefits from a scalable training algorithm and a theoretical guarantee concerning its generaliz ation ability. We also discuss an important improvement of our framework in whic h decision function can still be made reliable while being more expressive. Our experimental studies provide compelling results on toy data, presenting the trad e-off that occurs when aiming at accuracy, earliness and reliability. Results on real physiological and video datasets show that our proposed approach is as acc urate and early as state-of-the-art algorithm, while ensuring reliability and be ing far more efficient to learn.

Stratified Sampling Meets Machine Learning

Edo Liberty, Kevin Lang, Konstantin Shmakov

This paper solves a specialized regression problem to obtain sampling probabilit ies for records in databases. The goal is to sample a small set of records over which evaluating aggregate queries can be done both efficiently and accurately. We provide a principled and provable solution for this problem; it is parameterl ess and requires no data insights. Unlike standard regression problems, the loss is inversely proportional to the regressed-to values. Moreover, a cost zero sol ution always exists and can only be excluded by hard budget constraints. A unique form of regularization is also needed. We provide an efficient and simple regularized Empirical Risk Minimization (ERM) algorithm along with a theoretical generalization result. Our extensive experimental results significantly improve over both uniform sampling and standard stratified sampling which are de-facto the industry standards.

Efficient Multi-Instance Learning for Activity Recognition from Time Series Data Using an Auto-Regressive Hidden Markov Model

Xinze Guan, Raviv Raich, Weng-Keen Wong

Activity recognition from sensor data has spurred a great deal of interest due to its impact on health care. Prior work on activity recognition from multivariat e time series data has mainly applied supervised learning techniques which require a high degree of annotation effort to produce training data with the start and end times of each activity. In order to reduce the annotation effort, we present a weakly supervised approach based on multi-instance learning. We introduce a generative graphical model for multi-instance learning on time series data based on an auto-regressive hidden Markov model. Our model has a number of advantages, including the ability to produce both bag and instance-level predictions as we ell as an efficient exact inference algorithm based on dynamic programming.

Generalization Properties and Implicit Regularization for Multiple Passes SGM Junhong Lin, Raffaello Camoriano, Lorenzo Rosasco

We study the generalization properties of stochastic gradient methods for learning with convex loss functions and linearly parameterized functions. We show that, in the absence of penalizations or constraints, the stability and approximation properties of the algorithm can be controlled by tuning either the step-size or the number of passes over the data. In this view, these parameters can be seen to control a form of implicit regularization. Numerical results complement the theoretical findings.

Principal Component Projection Without Principal Component Analysis
Roy Frostig, Cameron Musco, Christopher Musco, Aaron Sidford

We show how to efficiently project a vector onto the top principal components of a matrix, *without explicitly computing these components*. Specifically, we int

roduce an iterative algorithm that provably computes the projection using few ca lls to any black-box routine for ridge regression. By avoiding explicit principa l component analysis (PCA), our algorithm is the first with no runtime dependence on the number of top principal components. We show that it can be used to give a fast iterative method for the popular principal component regression problem, giving the first major runtime improvement over the naive method of combining P CA with regression. To achieve our results, we first observe that ridge regression can be used to obtain a "smooth projection" onto the top principal components. We then sharpen this approximation to true projection using a low-degree polynomial approximation to the matrix step function. Step function approximation is a topic of long-term interest in scientific computing. We extend prior theory by constructing polynomials with simple iterative structure and rigorously analyzing their behavior under limited precision.

Recovery guarantee of weighted low-rank approximation via alternating minimizati on

Yuanzhi Li, Yingyu Liang, Andrej Risteski

Many applications require recovering a ground truth low-rank matrix from noisy o bservations of the entries, which in practice is typically formulated as a weigh ted low-rank approximation problem and solved by non-convex optimization heurist ics such as alternating minimization. In this paper, we provide provable recover y guarantee of weighted low-rank via a simple alternating minimization algorithm . In particular, for a natural class of matrices and weights and without any ass umption on the noise, we bound the spectral norm of the difference between the r ecovered matrix and the ground truth, by the spectral norm of the weighted noise plus an additive error term that decreases exponentially with the number of rou nds of alternating minimization, from either initialization by SVD or, more impo rtantly, random initialization. These provide the first theoretical results for weighted low-rank approximation via alternating minimization with non-binary det erministic weights, significantly generalizing those for matrix completion, the special case with binary weights, since our assumptions are similar or weaker th an those made in existing works. Furthermore, this is achieved by a very simple algorithm that improves the vanilla alternating minimization with a simple clipp ing step.

Deconstructing the Ladder Network Architecture

Mohammad Pezeshki, Linxi Fan, Philemon Brakel, Aaron Courville, Yoshua Bengio The Ladder Network is a recent new approach to semi-supervised learning that tur ned out to be very successful. While showing impressive performance, the Ladder Network has many components intertwined, whose contributions are not obvious in such a complex architecture. This paper presents an extensive experimental inves tigation of variants of the Ladder Network in which we replaced or removed indiv idual components to learn about their relative importance. For semi-supervised t asks, we conclude that the most important contribution is made by the lateral co nnections, followed by the application of noise, and the choice of what we refer to as the 'combinator function'. As the number of labeled training examples inc reases, the lateral connections and the reconstruction criterion become less imp ortant, with most of the generalization improvement coming from the injection of noise in each layer. Finally, we introduce a combinator function that reduces t est error rates on Permutation-Invariant MNIST to 0.57% for the supervised setti ng, and to 0.97% and 1.0% for semi-supervised settings with 1000 and 100 labeled examples, respectively.

Generalization and Exploration via Randomized Value Functions Ian Osband, Benjamin Van Roy, Zheng Wen

We propose randomized least-squares value iteration (RLSVI) - a new reinforcement learning algorithm designed to explore and generalize efficiently via linearly parameterized value functions. We explain why versions of least-squares value iteration that use Boltzmann or epsilon-greedy exploration can be highly inefficient, and we present computational results that demonstrate dramatic efficiency g

ains enjoyed by RLSVI. Further, we establish an upper bound on the expected regret of RLSVI that demonstrates near-optimality in a tabula rasa learning context. More broadly, our results suggest that randomized value functions offer a promising approach to tackling a critical challenge in reinforcement learning: synthe sizing efficient exploration and effective generalization.

Evasion and Hardening of Tree Ensemble Classifiers

Alex Kantchelian, J. D. Tygar, Anthony Joseph

Classifier evasion consists in finding for a given instance x the "nearest" instance x' such that the classifier predictions of x and x' are different. We present two novel algorithms for systematically computing evasions for tree ensembles such as boosted trees and random forests. Our first algorithm uses a Mixed Integer Linear Program solver and finds the optimal evading instance under an expressive set of constraints. Our second algorithm trades off optimality for speed by using symbolic prediction, a novel algorithm for fast finite differences on tree ensembles. On a digit recognition task, we demonstrate that both gradient boosted trees and random forests are extremely susceptible to evasions. Finally, we harden a boosted tree model without loss of predictive accuracy by augmenting the training set of each boosting round with evading instances, a technique we call adversarial boosting.

Dynamic Memory Networks for Visual and Textual Question Answering Caiming Xiong, Stephen Merity, Richard Socher

Neural network architectures with memory and attention mechanisms exhibit certain reason-ing capabilities required for question answering. One such architecture, the dynamic memory net-work (DMN), obtained high accuracy on a variety of language tasks. However, it was not shown whether the architecture achieves strong results for question answering when supporting facts are not marked during training or whether it could be applied to other modalities such as images. Based on an analysis of the DMN, we propose several improvements to its memory and input modules. Together with these changes we introduce a novel input module for images in order to be able to answer visual questions. Our new DMN+ model improves the state of the art on both the Visual Question Answering dataset and the bAbI-1 Ok text question-answering dataset without supporting fact supervision.

Estimating Cosmological Parameters from the Dark Matter Distribution Siamak Ravanbakhsh, Junier Oliva, Sebastian Fromenteau, Layne Price, Shirley Ho, Jeff Schneider, Barnabas Poczos

A grand challenge of the 21st century cosmology is to accurately estimate the cosmological parameters of our Universe. A major approach in estimating the cosmological parameters is to use the large scale matter distribution of the Universe. Galaxy surveys provide the means to map out cosmic large-scale structure in three dimensions. Information about galaxy locations is typically summarized in a "single" function of scale, such as the galaxy correlation function or power-spectrum. We show that it is possible to estimate these cosmological parameters directly from the distribution of matter. This paper presents the application of deep 3D convolutional networks to volumetric representation of dark matter simulations as well as the results obtained using a recently proposed distribution regression framework, showing that machine learning techniques are comparable to, and can sometimes outperform, maximum-likelihood point estimates using "cosmological models". This opens the way to estimating the parameters of our Universe with higher accuracy.

Learning Population-Level Diffusions with Generative RNNs Tatsunori Hashimoto, David Gifford, Tommi Jaakkola

We estimate stochastic processes that govern the dynamics of evolving population s such as cell differentiation. The problem is challenging since longitudinal tr ajectory measurements of individuals in a population are rarely available due to experimental cost and/or privacy. We show that cross-sectional samples from an evolving population suffice for recovery within a class of processes even if sam

ples are available only at a few distinct time points. We provide a stratified a nalysis of recoverability conditions, and establish that reversibility is suffic ient for recoverability. For estimation, we derive a natural loss and regulariza tion, and parameterize the processes as diffusive recurrent neural networks. We demonstrate the approach in the context of uncovering complex cellular dynamics known as the 'epigenetic landscape' from existing biological assays.

Expressiveness of Rectifier Networks

Xingyuan Pan, Vivek Srikumar

Rectified Linear Units (ReLUs) have been shown to ameliorate the vanishing gradient problem, allow for efficient backpropagation, and empirically promote sparsity in the learned parameters. They have led to state-of-the-art results in a variety of applications. However, unlike threshold and sigmoid networks, ReLU networks are less explored from the perspective of their expressiveness. This paper studies the expressiveness of ReLU networks. We characterize the decision boundary of two-layer ReLU networks by constructing functionally equivalent threshold networks. We show that while the decision boundary of a two-layer ReLU network can be captured by a threshold network, the latter may require an exponentially larger number of hidden units. We also formulate sufficient conditions for a corresponding logarithmic reduction in the number of hidden units to represent a sign network as a ReLU network. Finally, we experimentally compare threshold network and their much smaller ReLU counterparts with respect to their ability to lear network synthetically generated data.

Discrete Distribution Estimation under Local Privacy

Peter Kairouz, Keith Bonawitz, Daniel Ramage

The collection and analysis of user data drives improvements in the app and web ecosystems, but comes with risks to privacy. This paper examines discrete distribution estimation under local privacy, a setting wherein service providers can learn the distribution of a categorical statistic of interest without collecting the underlying data. We present new mechanisms, including hashed k-ary Randomized Response (KRR), that empirically meet or exceed the utility of existing mechanisms at all privacy levels. New theoretical results demonstrate the order-optima lity of KRR and the existing RAPPOR mechanism at different privacy regimes.

Square Root Graphical Models: Multivariate Generalizations of Univariate Exponen tial Families that Permit Positive Dependencies

David Inouye, Pradeep Ravikumar, Inderjit Dhillon

We develop Square Root Graphical Models (SQR), a novel class of parametric graph ical models that provides multivariate generalizations of univariate exponential family distributions. Previous multivariate graphical models [Yang et al. 2015] did not allow positive dependencies for the exponential and Poisson generalizat ions. However, in many real-world datasets, variables clearly have positive depe ndencies. For example, the airport delay time in New York-modeled as an exponent ial distribution-is positively related to the delay time in Boston. With this mo tivation, we give an example of our model class derived from the univariate expo nential distribution that allows for almost arbitrary positive and negative depe ndencies with only a mild condition on the parameter matrix—a condition akin to the positive definiteness of the Gaussian covariance matrix. Our Poisson general ization allows for both positive and negative dependencies without any constrain ts on the parameter values. We also develop parameter estimation methods using n ode-wise regressions with \ell_1 regularization and likelihood approximation met hods using sampling. Finally, we demonstrate our exponential generalization on a synthetic dataset and a real-world dataset of airport delay times.

A Box-Constrained Approach for Hard Permutation Problems Cong Han Lim, Steve Wright

We describe the use of sorting networks to form relaxations of problems involvin g permutations of n objects. This approach is an alternative to relaxations base d on the Birkhoff polytope (the set of n \times n doubly stochastic matrices), p

roviding a more compact formulation in which the only constraints are box constraints. Using this approach, we form a variant of the relaxation of the quadratic assignment problem recently studied in Vogelstein et al. (2015), and show that the continuation method applied to this formulation can be quite effective. We develop a coordinate descent algorithm that achieves a per-cycle complexity of O($n^2 \log^2 n$). We compare this method with Fast Approximate QAP (FAQ) algorithm introduced in Vogelstein et al. (2015), which uses a conditional-gradient method whose per-iteration complexity is O(n^3). We demonstrate that for most problems in QAPLIB and for a class of synthetic QAP problems, the sorting-network formulation returns solutions that are competitive with the FAQ algorithm, often in significantly less computing time.

Geometric Mean Metric Learning

Pourya Zadeh, Reshad Hosseini, Suvrit Sra

We revisit the task of learning a Euclidean metric from data. We approach this p roblem from first principles and formulate it as a surprisingly simple optimizat ion problem. Indeed, our formulation even admits a closed form solution. This so lution possesses several very attractive properties: (i) an innate geometric app eal through the Riemannian geometry of positive definite matrices; (ii) ease of interpretability; and (iii) computational speed several orders of magnitude fast er than the widely used LMNN and ITML methods. Furthermore, on standard benchmar k datasets, our closed-form solution consistently attains higher classification accuracy.

Sparse Nonlinear Regression: Parameter Estimation under Nonconvexity

Zhuoran Yang, Zhaoran Wang, Han Liu, Yonina Eldar, Tong Zhang

We study parameter estimation for sparse nonlinear regression. More specifically , we assume the data are given by y = f(\bf x^T \bf β^{**}) + ϵ , where f is nonlinear. To recover \bf β s, we propose an \ell_1-regularized least-squares estimator. Unlike classical linear regression, the corresponding optimization problem is nonconvex because of the nonlinearity of f. In spite of the nonconvexity, we prove that under mild conditions, every stationary point of the objective enjoys a noptimal statistical rate of convergence. Detailed numerical results are provided to back up our theory.

Conditional Bernoulli Mixtures for Multi-label Classification

Cheng Li, Bingyu Wang, Virgil Pavlu, Javed Aslam

Multi-label classification is an important machine learning task wherein one ass igns a subset of candidate labels to an object. In this paper, we propose a new multi-label classification method based on Conditional Bernoulli Mixtures. Our p roposed method has several attractive properties: it captures label dependencies; it reduces the multi-label problem to several standard binary and multi-class problems; it subsumes the classic independent binary prediction and power-set su bset prediction methods as special cases; and it exhibits accuracy and/or comput ational complexity advantages over existing approaches. We demonstrate two imple mentations of our method using logistic regressions and gradient boosted trees, together with a simple training procedure based on Expectation Maximization. We further derive an efficient prediction procedure based on dynamic programming, thus avoiding the cost of examining an exponential number of potential label subs ets. Experimental results show the effectiveness of the proposed method against competitive alternatives on benchmark datasets.

Scalable Discrete Sampling as a Multi-Armed Bandit Problem Yutian Chen, Zoubin Ghahramani

Drawing a sample from a discrete distribution is one of the building components for Monte Carlo methods. Like other sampling algorithms, discrete sampling suffe rs from the high computational burden in large-scale inference problems. We study the problem of sampling a discrete random variable with a high degree of dependency that is typical in large-scale Bayesian inference and graphical models, and propose an efficient approximate solution with a subsampling approach. We make

a novel connection between the discrete sampling and Multi-Armed Bandits proble ms with a finite reward population and provide three algorithms with theoretical guarantees. Empirical evaluations show the robustness and efficiency of the app roximate algorithms in both synthetic and real-world large-scale problems.

Recycling Randomness with Structure for Sublinear time Kernel Expansions Krzysztof Choromanski, Vikas Sindhwani

We propose a scheme for recycling Gaussian random vectors into structured matric es to ap- proximate various kernel functions in sublin- ear time via random embe ddings. Our frame- work includes the Fastfood construction of Le et al. (2013) as a special case, but also ex- tends to Circulant, Toeplitz and Hankel matri- ces, and the broader family of structured matri- ces that are characterized by the concept of low- displacement rank. We introduce notions of co- herence and grap h-theoretic structural constants that control the approximation quality, and prove unbiasedness and low-variance properties of ran- dom feature maps that arise within our frame- work. For the case of low-displacement matri- ces, we show how the degree of structure and randomness can be controlled to reduce statis- tical variance at the cost of increased computa- tion and storage requirements. Empirical results strongly support our theory and justify the use of a broader family of structured matrices for scal- ing up kernel methods using random features.

Bidirectional Helmholtz Machines

Jorg Bornschein, Samira Shabanian, Asja Fischer, Yoshua Bengio

Efficient unsupervised training and inference in deep generative models remains a challenging problem. One basic approach, called Helmholtz machine or Variation al Autoencoder, involves training a top-down directed generative model together with a bottom-up auxiliary model used for approximate inference. Recent results indicate that better generative models can be obtained with better approximate i nference procedures. Instead of improving the inference procedure, we here propo se a new model, the bidirectional Helmholtz machine, which guarantees that the t op-down and bottom-up distributions can efficiently invert each other. We achiev e this by interpreting both the top-down and the bottom-up directed models as ap proximate inference distributions and by defining the model distribution to be t he geometric mean of these two. We present a lower-bound for the likelihood of t his model and we show that optimizing this bound regularizes the model so that t he Bhattacharyya distance between the bottom-up and top-down approximate distrib utions is minimized. This approach results in state of the art generative models which prefer significantly deeper architectures while it allows for orders of $\mathfrak m$ agnitude more efficient likelihood estimation.

Faster Convex Optimization: Simulated Annealing with an Efficient Universal Barrier

Jacob Abernethy, Elad Hazan

This paper explores a surprising equivalence between two seemingly-distinct convex optimization methods. We show that simulated annealing, a well-studied random walk algorithms, is *directly equivalent*, in a certain sense, to the central path interior point algorithm for the the entropic universal barrier function. The is connection exhibits several benefits. First, we are able improve the state of the art time complexity for convex optimization under the membership oracle model by devising a new temperature schedule for simulated annealing motivated by central path following interior point methods. Second, we get an efficient random ized interior point method with an efficiently computable universal barrier for any convex set described by a membership oracle. Previously, efficiently computable barriers were known only for particular convex sets.

Preconditioning Kernel Matrices

Kurt Cutajar, Michael Osborne, John Cunningham, Maurizio Filippone

The computational and storage complexity of kernel machines presents the primary barrier to their scaling to large, modern, datasets. A common way to tackle the scalability issue is to use the conjugate gradient algorithm, which relieves th

e constraints on both storage (the kernel matrix need not be stored) and computa tion (both stochastic gradients and parallelization can be used). Even so, conjugate gradient is not without its own issues: the conditioning of kernel matrices is often such that conjugate gradients will have poor convergence in practice. Preconditioning is a common approach to alleviating this issue. Here we propose preconditioned conjugate gradients for kernel machines, and develop a broad range of preconditioners particularly useful for kernel matrices. We describe a scal able approach to both solving kernel machines and learning their hyperparameters. We show this approach is exact in the limit of iterations and outperforms state-of-the-art approximations for a given computational budget.

Greedy Column Subset Selection: New Bounds and Distributed Algorithms

Jason Altschuler, Aditya Bhaskara, Gang Fu, Vahab Mirrokni, Afshin Rostamizadeh,

Morteza Zadimoqhaddam

The problem of column subset selection has recently attracted a large body of re search, with feature selection serving as one obvious and important application. Among the techniques that have been applied to solve this problem, the greedy a lgorithm has been shown to be quite effective in practice. However, theoretical guarantees on its performance have not been explored thoroughly, especially in a distributed setting. In this paper, we study the greedy algorithm for the column subset selection problem from a theoretical and empirical perspective and show its effectiveness in a distributed setting. In particular, we provide an improved approximation guarantee for the greedy algorithm which we show is tight up to a constant factor, and present the first distributed implementation with provable approximation factors. We use the idea of randomized composable core-sets, developed recently in the context of submodular maximization. Finally, we validate the effectiveness of this distributed algorithm via an empirical study.

Dynamic Capacity Networks

Amjad Almahairi, Nicolas Ballas, Tim Cooijmans, Yin Zheng, Hugo Larochelle, Aaro n Courville

We introduce the Dynamic Capacity Network (DCN), a neural network that can adapt ively assign its capacity across different portions of the input data. This is a chieved by combining modules of two types: low-capacity sub-networks and high-capacity sub-networks. The low-capacity sub-networks are applied across most of the input, but also provide a guide to select a few portions of the input on which to apply the high-capacity sub-networks. The selection is made using a novel gradient-based attention mechanism, that efficiently identifies input regions for which the DCN's output is most sensitive and to which we should devote more capacity. We focus our empirical evaluation on the Cluttered MNIST and SVHN image datasets. Our findings indicate that DCNs are able to drastically reduce the number of computations, compared to traditional convolutional neural networks, while maintaining similar or even better performance.

Pricing a Low-regret Seller

Hoda Heidari, Mohammad Mahdian, Umar Syed, Sergei Vassilvitskii, Sadra Yazdanbod As the number of ad exchanges has grown, publishers have turned to low regret le arning algorithms to decide which exchange offers the best price for their inven tory. This in turn opens the following question for the exchange: how to set prices to attract as many sellers as possible and maximize revenue. In this work we formulate this precisely as a learning problem, and present algorithms showing that by simply knowing that the counterparty is using a low regret algorithm is enough for the exchange to have its own low regret learning algorithm to find the optimal price.

Estimation from Indirect Supervision with Linear Moments Aditi Raghunathan, Roy Frostig, John Duchi, Percy Liang

In structured prediction problems where we have indirect supervision of the outp ut, maximum marginal likelihood faces two computational obstacles: non-convexity of the objective and intractability of even a single gradient computation. In t his paper, we bypass both obstacles for a class of what we call linear indirectly-supervised problems. Our approach is simple: we solve a linear system to estimate sufficient statistics of the model, which we then use to estimate parameters via convex optimization. We analyze the statistical properties of our approach and show empirically that it is effective in two settings: learning with local privacy constraints and learning from low-cost count-based annotations.

Speeding up k-means by approximating Euclidean distances via block vectors Thomas Bottesch, Thomas Bühler, Markus Kächele

This paper introduces a new method to approximate Euclidean distances between po ints using block vectors in combination with the Hölder inequality. By defining lower bounds based on the proposed approximation, cluster algorithms can be considerably accelerated without loss of quality. In extensive experiments, we show a considerable reduction in terms of computational time in comparison to standar d methods and the recently proposed Yinyang k-means. Additionally we show that the memory consumption of the presented clustering algorithm does not depend on the number of clusters, which makes the approach suitable for large scale problem s.

Learning and Inference via Maximum Inner Product Search Stephen Mussmann, Stefano Ermon

A large class of commonly used probabilistic models known as log-linear models a re defined up to a normalization constant. Typical learning algorithms for such m odels require solving a sequence of probabilistic inference queries. These infer ences are typically intractable, and are a major bottleneck for learning models with large output spaces. In this paper, we provide a new approach for amortizin g the cost of a sequence of related inference queries, such as the ones arising during learning. Our technique relies on a surprising connection with algorithms developed in the past two decades for similarity search in large data bases. Our approach achieves improved running times with provable approximation guarantees. We show that it performs well both on synthetic data and neural language mode ls with large output spaces.

A Superlinearly-Convergent Proximal Newton-type Method for the Optimization of F inite Sums

Anton Rodomanov, Dmitry Kropotov

We consider the problem of minimizing the strongly convex sum of a finite number of convex functions. Standard algorithms for solving this problem in the class of incremental/stochastic methods have at most a linear convergence rate. We pro pose a new incremental method whose convergence rate is superlinear – the Newton – type incremental method (NIM). The idea of the method is to introduce a model of the objective with the same sum-of-functions structure and further update a single component of the model per iteration. We prove that NIM has a superlinear local convergence rate and linear global convergence rate. Experiments show that the method is very effective for problems with a large number of functions and a small number of variables.

A Kernel Test of Goodness of Fit

Kacper Chwialkowski, Heiko Strathmann, Arthur Gretton

We propose a nonparametric statistical test for goodness-of-fit: given a set of samples, the test determines how likely it is that these were generated from a t arget density function. The measure of goodness-of-fit is a divergence construct ed via Stein's method using functions from a Reproducing Kernel Hilbert Space. O ur test statistic is based on an empirical estimate of this divergence, taking t he form of a V-statistic in terms of the log gradients of the target density and the kernel. We derive a statistical test, both for i.i.d. and non-i.i.d. sample s, where we estimate the null distribution quantiles using a wild bootstrap proc edure. We apply our test to quantifying convergence of approximate Markov Chain Monte Carlo methods, statistical model criticism, and evaluating quality of fit vs model complexity in nonparametric density estimation.

Interacting Particle Markov Chain Monte Carlo

Tom Rainforth, Christian Naesseth, Fredrik Lindsten, Brooks Paige, Jan-Willem Vandemeent, Arnaud Doucet, Frank Wood

We introduce interacting particle Markov chain Monte Carlo (iPMCMC), a PMCMC met hod based on an interacting pool of standard and conditional sequential Monte Carlo samplers. Like related methods, iPMCMC is a Markov chain Monte Carlo sampler on an extended space. We present empirical results that show significant improvements in mixing rates relative to both non-interacting PMCMC samplers and a single PMCMC sampler with an equivalent memory and computational budget. An additional advantage of the iPMCMC method is that it is suitable for distributed and multi-core architectures.

Faster Eigenvector Computation via Shift-and-Invert Preconditioning
Dan Garber, Elad Hazan, Chi Jin, Sham, Cameron Musco, Praneeth Netrapalli, Aaro

We give faster algorithms and improved sample complexities for the fundamental p roblem of estimating the top eigenvector. Given an explicit matrix \$A \in \mathb $b\{R\}^{n \in \mathbb{R}}$, we show how to compute an $\epsilon = 0$ ctor of \$A^TA\$ in time \$\tilde O\left(\left[\text{nnz}(A) + \frac{d \text{sr}(A)) \{\text{gap}^2\ \right] \cdot \log 1/\epsilon\right)\\$. Here \\$\text{nnz}(A)\\$ is the number of nonzeros in A, $\text{text}\{sr\}(A)$ is the stable rank, and gap is the relative eigengap. We also consider an online setting in which, given a stream of i.i.d. samples from a distribution D with covariance matrix \$\Sigma\$ and a ve ctor x_0 which is an 0(gap) approximate top eigenvector for swe show how to refine x_0 to an ϵ $ac{\text{var}(\mathcal{D})}{\text{gap}-\text{epsilon}}\$ samples from ∞ D\$. Here $\star {\text{var}}(\mathcal{D})$ \$ is a natural notion of variance. Combining o ur algorithm with previous work to initialize \$x_0\$, we obtain improved sample c omplexities and runtimes under a variety of assumptions on D. We achieve our res ults via a robust analysis of the classic shift-and-invert preconditioning metho d. This technique lets us reduce eigenvector computation to approximately solvin g a series of linear systems with fast stochastic gradient methods.

A Theory of Generative ConvNet

Jianwen Xie, Yang Lu, Song-Chun Zhu, Yingnian Wu

We show that a generative random field model, which we call generative ConvNet, can be derived from the commonly used discriminative ConvNet, by assuming a Conv Net for multi-category classification and assuming one of the category is a base category generated by a reference distribution. If we further assume that the n on-linearity in the ConvNet is Rectified Linear Unit (ReLU) and the reference di stribution is Gaussian white noise, then we obtain a generative ConvNet model th at is unique among energy-based models: The model is piecewise Gaussian, and the means of the Gaussian pieces are defined by an auto-encoder, where the filters in the bottom-up encoding become the basis functions in the top-down decoding, a nd the binary activation variables detected by the filters in the bottom-up conv olution process become the coefficients of the basis functions in the top-down d econvolution process. The Langevin dynamics for sampling the generative ConvNet is driven by the reconstruction error of this auto-encoder. The contrastive dive rgence learning of the generative ConvNet reconstructs the training images by th e auto-encoder. The maximum likelihood learning algorithm can synthesize realist ic natural image patterns.

Efficient Learning with a Family of Nonconvex Regularizers by Redistributing Non convexity

Quanming Yao, James Kwok

The use of convex regularizers allow for easy optimization, though they often pr oduce biased estimation and inferior prediction performance. Recently, nonconvex regularizers have attracted a lot of attention and outperformed convex ones. Ho wever, the resultant optimization problem is much harder. In this paper, for a l

arge class of nonconvex regularizers, we propose to move the nonconvexity from the regularizer to the loss. The nonconvex regularizer is then transformed to a familiar convex regularizer, while the resultant loss function can still be guaranteed to be smooth. Learning with the convexified regularizer can be performed by existing efficient algorithms originally designed for convex regularizers (such as the standard proximal algorithm and Frank-Wolfe algorithm). Moreover, it can be shown that critical points of the transformed problem are also critical points of the original problem. Extensive experiments on a number of nonconvex regularization problems show that the proposed procedure is much faster than the state-of-the-art nonconvex solvers.

Computationally Efficient Nyström Approximation using Fast Transforms Si Si, Cho-Jui Hsieh, Inderjit Dhillon

Our goal is to improve the \it training and \it prediction time of Nyström metho d, which is a widely-used technique for generating low-rank kernel matrix approx imations. When applying the Nyström approximation for large-scale applications, both training and prediction time is dominated by computing kernel values betwee n a data point and all landmark points. With m landmark points, this computation requires $\Theta(md)$ time (flops), where d is the input dimension. In this paper, we propose the use of a family of fast transforms to generate structured landmark p oints for Nyström approximation. By exploiting fast transforms, e.g., Haar trans form and Hadamard transform, our modified Nyström method requires only $\Theta(\mathsf{m})$ or Θ (m\log d) time to compute the kernel values between a given data point and m lan dmark points. This improvement in time complexity can significantly speed up ker nel approximation and benefit prediction speed in kernel machines. For instance, on the webspam data (more than 300,000 data points), our proposed algorithm ena bles kernel SVM prediction to deliver 98% accuracy and the resulting prediction time is 1000 times faster than LIBSVM and only 10 times slower than linear SVM p rediction (which yields only 91% accuracy).

Gromov-Wasserstein Averaging of Kernel and Distance Matrices Gabriel Peyré, Marco Cuturi, Justin Solomon

This paper presents a new technique for computing the barycenter of a set of dis tance or kernel matrices. These matrices, which define the inter-relationships be tween points sampled from individual domains, are not required to have the same size or to be in row-by-row correspondence. We compare these matrices using the softassign criterion, which measures the minimum distortion induced by a probabilistic map from the rows of one similarity matrix to the rows of another; this criterion amounts to a regularized version of the Gromov-Wasserstein (GW) distance between metric-measure spaces. The barycenter is then defined as a Fréchet me an of the input matrices with respect to this criterion, minimizing a weighted sum of softassign values. We provide a fast iterative algorithm for the resulting nonconvex optimization problem, built upon state-of-the-art tools for regularized optimal transportation. We demonstrate its application to the computation of shape barycenters and to the prediction of energy levels from molecular configurations in quantum chemistry.

Robust Monte Carlo Sampling using Riemannian Nosé-Poincaré Hamiltonian Dynamics Anirban Roychowdhury, Brian Kulis, Srinivasan Parthasarathy

We present a Monte Carlo sampler using a modified Nosé-Poincaré Hamiltonian alon g with Riemannian preconditioning. Hamiltonian Monte Carlo samplers allow better exploration of the state space as opposed to random walk-based methods, but, fr om a molecular dynamics perspective, may not necessarily provide samples from the canonical ensemble. Nosé-Hoover samplers rectify that shortcoming, but the resultant dynamics are not Hamiltonian. Furthermore, usage of these algorithms on large real-life datasets necessitates the use of stochastic gradients, which acts as another potentially destabilizing source of noise. In this work, we propose dynamics based on a modified Nosé-Poincaré Hamiltonian augmented with Riemannian manifold corrections. The resultant symplectic sampling algorithm samples from the canonical ensemble while using structural cues from the Riemannian precondit

ioning matrices to efficiently traverse the parameter space. We also propose a s tochastic variant using additional terms in the Hamiltonian to correct for the n oise from the stochastic gradients. We show strong performance of our algorithms on synthetic datasets and high-dimensional Poisson factor analysis-based topic modeling scenarios.

The Segmented iHMM: A Simple, Efficient Hierarchical Infinite HMM Ardavan Saeedi, Matthew Hoffman, Matthew Johnson, Ryan Adams We propose the segmented iHMM (siHMM), a hierarchical infinite hidden Markov mod el (iHMM) that supports a simple, efficient inference scheme. The siHMM is well suited to segmentation problems, where the goal is to identify points at which a time series transitions from one relatively stable regime to a new regime. Conv entional iHMMs often struggle with such problems, since they have no mechanism f or distinguishing between high-and low-level dynamics. Hierarchical HMMs (HHMMs) can do better, but they require much more complex and expensive inference algor ithms. The siHMM retains the simplicity and efficiency of the iHMM, but outperforms it on a variety of segmentation problems, achieving performance that matches or exceeds that of a more complicated HHMM.

Meta-Gradient Boosted Decision Tree Model for Weight and Target Learning Yury Ustinovskiy, Valentina Fedorova, Gleb Gusev, Pavel Serdyukov Labeled training data is an essential part of any supervised machine learning fr amework. In practice, there is a trade-off between the quality of a label and it s cost. In this paper, we consider a problem of learning to rank on a large-scal e dataset with low-quality relevance labels aiming at maximizing the quality of a trained ranker on a small validation dataset with high-quality ground truth re levance labels. Motivated by the classical Gauss-Markov theorem for the linear r egression problem, we formulate the problems of (1) reweighting training instanc es and (2) remapping learning targets. We propose meta-gradient decision tree le arning framework for optimizing weight and target functions by applying gradient -based hyperparameter optimization. Experiments on a large-scale real-world data set demonstrate that we can significantly improve state-of-the-art machine-learn ing algorithms by incorporating our framework.

Discriminative Embeddings of Latent Variable Models for Structured Data Hanjun Dai, Bo Dai, Le Song

Kernel classifiers and regressors designed for structured data, such as sequence s, trees and graphs, have significantly advanced a number of interdisciplinary a reas such as computational biology and drug design. Typically, kernels are desig ned beforehand for a data type which either exploit statistics of the structures or make use of probabilistic generative models, and then a discriminative class ifier is learned based on the kernels via convex optimization. However, such an elegant two-stage approach also limited kernel methods from scaling up to millio ns of data points, and exploiting discriminative information to learn feature re presentations. We propose, structure2vec, an effective and scalable approach for structured data representation based on the idea of embedding latent variable ${\tt m}$ odels into feature spaces, and learning such feature spaces using discriminative information. Interestingly, structure2vec extracts features by performing a seq uence of function mappings in a way similar to graphical model inference procedu res, such as mean field and belief propagation. In applications involving millio ns of data points, we showed that structure2vec runs 2 times faster, produces mo dels which are 10,000 times smaller, while at the same time achieving the stateof-the-art predictive performance.

Robust Random Cut Forest Based Anomaly Detection on Streams Sudipto Guha, Nina Mishra, Gourav Roy, Okke Schrijvers

In this paper we focus on the anomaly detection problem for dynamic data streams through the lens of random cut forests. We investigate a robust random cut data structure that can be used as a sketch or synopsis of the input stream. We provide a plausible definition of non-parametric anomalies based on the influence of

an unseen point on the remainder of the data, i.e., the externality imposed by that point. We show how the sketch can be efficiently updated in a dynamic data stream. We demonstrate the viability of the algorithm on publicly available real data.

Training Neural Networks Without Gradients: A Scalable ADMM Approach Gavin Taylor, Ryan Burmeister, Zheng Xu, Bharat Singh, Ankit Patel, Tom Goldstei

With the growing importance of large network models and enormous training datase ts, GPUs have become increasingly necessary to train neural networks. This is la rgely because conventional optimization algorithms rely on stochastic gradient methods that don't scale well to large numbers of cores in a cluster setting. Fur thermore, the convergence of all gradient methods, including batch methods, suffers from common problems like saturation effects, poor conditioning, and saddle points. This paper explores an unconventional training method that uses alternating direction methods and Bregman iteration to train networks without gradient descent steps. The proposed method reduces the network training problem to a sequence of minimization sub-steps that can each be solved globally in closed form. The proposed method is advantageous because it avoids many of the caveats that make gradient methods slow on highly non-convex problems. In addition, the method exhibits strong scaling in the distributed setting, yielding linear speedups even when split over thousands of cores.

Clustering High Dimensional Categorical Data via Topographical Features Chao Chen, Novi Quadrianto

Analysis of categorical data is a challenging task. In this paper, we propose to compute topographical features of high-dimensional categorical data. We propose an efficient algorithm to extract modes of the underlying distribution and their attractive basins. These topographical features provide a geometric view of the data and can be applied to visualization and clustering of real world challenging datasets. Experiments show that our principled method outperforms state-of-the-art clustering methods while also admits an embarrassingly parallel property.

Efficient Algorithms for Large-scale Generalized Eigenvector Computation and Can onical Correlation Analysis

Rong Ge, Chi Jin, Sham, Praneeth Netrapalli, Aaron Sidford

This paper considers the problem of canonical-correlation analysis (CCA) and, mo re broadly, the generalized eigenvector problem for a pair of symmetric matrices . These are two fundamental problems in data analysis and scientific computing w ith numerous applications in machine learning and statistics. We provide simple iterative algorithms, with improved runtimes, for solving these problems that ar e globally linearly convergent with moderate dependencies on the condition numbe rs and eigenvalue gaps of the matrices involved. We obtain our results by reduci ng CCA to the top-k generalized eigenvector problem. We solve this problem throu gh a general framework that simply requires black box access to an approximate 1 inear system solver. Instantiating this framework with accelerated gradient desc ent we obtain a running time of $\operatorname{reg} k \operatorname{sqrtk} \log(1/\epsilon) \log \operatorname{left}(k\kappa/\rho)$ $\$ right) where z is the total number of nonzero entries, κ is the condition number and ρ is the relative eigenvalue gap of the appropriate matrices. Our algorithm is linear in the input size and the number of components k up to a $\log(k)$ facto r. This is essential for handling large-scale matrices that appear in practice. To the best of our knowledge this is the first such algorithm with global linear convergence. We hope that our results prompt further research and ultimately im prove the practical running time for performing these important data analysis pr ocedures on large data sets.

Algorithms for Optimizing the Ratio of Submodular Functions Wenruo Bai, Rishabh Iyer, Kai Wei, Jeff Bilmes

We investigate a new optimization problem involving minimizing the Ratio of Subm odular (RS) functions. We argue that this problem occurs naturally in several re

al world applications. We then show the connection between this problem and seve ral related problems, including minimizing the difference of submodular function s, and to submodular optimization subject to submodular constraints. We show RS that optimization can be solved within bounded approximation factors. We also provide a hardness bound and show that our tightest algorithm matches the lower bound up to a \log factor. Finally, we empirically demonstrate the performance and good scalability properties of our algorithms.

Model-Free Imitation Learning with Policy Optimization

Jonathan Ho, Jayesh Gupta, Stefano Ermon

In imitation learning, an agent learns how to behave in an environment with an unknown cost function by mimicking expert demonstrations. Existing imitation learning algorithms typically involve solving a sequence of planning or reinforcement learning problems. Such algorithms are therefore not directly applicable to large, high-dimensional environments, and their performance can significantly degrade if the planning problems are not solved to optimality. Under the apprentices hip learning formalism, we develop alternative model-free algorithms for finding a parameterized stochastic policy that performs at least as well as an expert policy on an unknown cost function, based on sample trajectories from the expert. Our approach, based on policy gradients, scales to large continuous environments with quaranteed convergence to local minima.

ADIOS: Architectures Deep In Output Space

Moustapha Cisse, Maruan Al-Shedivat, Samy Bengio

Multi-label classification is a generalization of binary classification where the task consists in predicting \emphsets of labels. With the availability of ever larger datasets, the multi-label setting has become a natural one in many applications, and the interest in solving multi-label problems has grown significantly. As expected, deep learning approaches are now yielding state-of-the-art performance for this class of problems. Unfortunately, they usually do not take into account the often unknown but nevertheless rich relationships between labels. In this paper, we propose to make use of this underlying structure by learning to partition the labels into a Markov Blanket Chain and then applying a novel deep architecture that exploits the partition. Experiments on several popular and lar ge multi-label datasets demonstrate that our approach not only yields significant improvements, but also helps to overcome trade-offs specific to the multi-label classification setting.

Conditional Dependence via Shannon Capacity: Axioms, Estimators and Applications Weihao Gao, Sreeram Kannan, Sewoong Oh, Pramod Viswanath

We consider axiomatically the problem of estimating the strength of a conditional dependence relationship $P_{-}Y \mid X$ from a random variables X to a random variable Y. This has applications in determining the strength of a known causal relationship, where the strength depends only on the conditional distribution of the effect given the cause (and not on the driving distribution of the cause). Shannon capacity, appropriately regularized, emerges as a natural measure under these axioms. We examine the problem of calculating Shannon capacity from the observed samples and propose a novel fixed-k nearest neighbor estimator, and demonstrate its consistency. Finally, we demonstrate an application to single-cell flow-cytometry, where the proposed estimators significantly reduce sample complexity.

Control of Memory, Active Perception, and Action in Minecraft

Junhyuk Oh, Valliappa Chockalingam, Satinder, Honglak Lee

In this paper, we introduce a new set of reinforcement learning (RL) tasks in Mi necraft (a flexible 3D world). We then use these tasks to systematically compare and contrast existing deep reinforcement learning (DRL) architectures with our new memory-based DRL architectures. These tasks are designed to emphasize, in a controllable manner, issues that pose challenges for RL methods including partia 1 observability (due to first-person visual observations), delayed rewards, high -dimensional visual observations, and the need to use active perception in a cor

rect manner so as to perform well in the tasks. While these tasks are conceptual ly simple to describe, by virtue of having all of these challenges simultaneousl y they are difficult for current DRL architectures. Additionally, we evaluate the generalization performance of the architectures on environments not used durin g training. The experimental results show that our new architectures generalize to unseen environments better than existing DRL architectures.

The Label Complexity of Mixed-Initiative Classifier Training Jina Suh, Xiaojin Zhu, Saleema Amershi

Mixed-initiative classifier training, where the human teacher can choose which i tems to label or to label items chosen by the computer, has enjoyed empirical su coess but without a rigorous statistical learning theoretical justification. We analyze the label complexity of a simple mixed-initiative training mechanism usi ng teach- ing dimension and active learning. We show that mixed-initiative train ing is advantageous com- pared to either computer-initiated (represented by active learning) or human-initiated classifier training. The advantage exists across all human teaching abilities, from optimal to completely unhelpful teachers. We further improve classifier training by educating the human teachers. This is do ne by showing, or explaining, optimal teaching sets to the human teachers. We conduct Mechanical Turk human experiments on two stylistic classifier training tas ks to illustrate our approach.

Bayesian Poisson Tucker Decomposition for Learning the Structure of Internationa l Relations

Aaron Schein, Mingyuan Zhou, David Blei, Hanna Wallach

We introduce Bayesian Poisson Tucker decomposition (BPTD) for modeling country-c ountry interaction event data. These data consist of interaction events of the f orm "country i took action a toward country j at time t." BPTD discovers overlap ping country-community memberships, including the number of latent communities. In addition, it discovers directed community-community interaction networks that are specific to "topics" of action types and temporal "regimes." We show that B PTD yields an efficient MCMC inference algorithm and achieves better predictive performance than related models. We also demonstrate that it discovers interpret able latent structure that agrees with our knowledge of international relations.

Tensor Decomposition via Joint Matrix Schur Decomposition Nicolo Colombo, Nikos Vlassis

We describe an approach to tensor decomposition that involves extracting a set of observable matrices from the tensor and applying an approximate joint Schur de composition on those matrices, and we establish the corresponding first-order perturbation bounds. We develop a novel iterative Gauss-Newton algorithm for joint matrix Schur decomposition, which minimizes a nonconvex objective over the manifold of orthogonal matrices, and which is guaranteed to converge to a global optimum under certain conditions. We empirically demonstrate that our algorithm is faster and at least as accurate and robust than state-of-the-art algorithms for this problem.

Continuous Deep Q-Learning with Model-based Acceleration Shixiang Gu, Timothy Lillicrap, Ilya Sutskever, Sergey Levine

Model-free reinforcement learning has been successfully applied to a range of ch allenging problems, and has recently been extended to handle large neural networ k policies and value functions. However, the sample complexity of model-free algorithms, particularly when using high-dimensional function approximators, tends to limit their applicability to physical systems. In this paper, we explore algorithms and representations to reduce the sample complexity of deep reinforcement learning for continuous control tasks. We propose two complementary techniques for improving the efficiency of such algorithms. First, we derive a continuous v ariant of the Q-learning algorithm, which we call normalized advantage functions (NAF), as an alternative to the more commonly used policy gradient and actor-cr itic methods. NAF representation allows us to apply Q-learning with experience r

eplay to continuous tasks, and substantially improves performance on a set of si mulated robotic control tasks. To further improve the efficiency of our approach , we explore the use of learned models for accelerating model-free reinforcement learning. We show that iteratively refitted local linear models are especially effective for this, and demonstrate substantially faster learning on domains whe re such models are applicable.

Domain Adaptation with Conditional Transferable Components

Mingming Gong, Kun Zhang, Tongliang Liu, Dacheng Tao, Clark Glymour, Bernhard Schölkopf

Domain adaptation arises in supervised learning when the training (source domain) and test (target domain) data have different distributions. Let X and Y denote the features and target, respectively, previous work on domain adaptation consi ders the covariate shift situation where the distribution of the features P(X) c hanges across domains while the conditional distribution P(Y|X) stays the same. To reduce domain discrepancy, recent methods try to find invariant components \m athcalT(X) that have similar $P(\mathbb{X})$ by explicitly minimizing a distribu tion discrepancy measure. However, it is not clear if $P(Y \mid \text{MathcalT}(X))$ in diffe rent domains is also similar when P(Y|X) changes. Furthermore, transferable comp onents do not necessarily have to be invariant. If the change in some components is identifiable, we can make use of such components for prediction in the targe t domain. In this paper, we focus on the case where P(X|Y) and P(Y) both change in a causal system in which Y is the cause for X. Under appropriate assumptions, we aim to extract conditional transferable components whose conditional distrib ution $P(\mathbb{T}(X)|Y)$ is invariant after proper location-scale (LS) transforma tions, and identify how P(Y) changes between domains simultaneously. We provide theoretical analysis and empirical evaluation on both synthetic and real-world d ata to show the effectiveness of our method.

Fixed Point Quantization of Deep Convolutional Networks Darryl Lin, Sachin Talathi, Sreekanth Annapureddy

In recent years increasingly complex architectures for deep convolution networks (DCNs) have been proposed to boost the performance on image recognition tasks. However, the gains in performance have come at a cost of substantial increase in computation and model storage resources. Fixed point implementation of DCNs has the potential to alleviate some of these complexities and facilitate potential deployment on embedded hardware. In this paper, we propose a quantizer design for fixed point implementation of DCNs. We formulate and solve an optimization problem to identify optimal fixed point bit-width allocation across DCN layers. Our experiments show that in comparison to equal bit-width settings, the fixed point DCNs with optimized bit width allocation offer >20% reduction in the model size without any loss in accuracy on CIFAR-10 benchmark. We also demonstrate that fine-tuning can further enhance the accuracy of fixed point DCNs beyond that of the original floating point model. In doing so, we report a new state-of-the-art fixed point performance of 6.78% error-rate on CIFAR-10 benchmark.

Provable Algorithms for Inference in Topic Models

Sanjeev Arora, Rong Ge, Frederic Koehler, Tengyu Ma, Ankur Moitra

Recently, there has been considerable progress on designing algorithms with provable guarantees—typically using linear algebraic methods—for parameter learning in latent variable models. Designing provable algorithms for inference has proved more difficult. Here we take a first step towards provable inference in topic models. We leverage a property of topic models that enables us to construct simple linear estimators for the unknown topic proportions that have small variance, and consequently can work with short documents. Our estimators also correspond to finding an estimate around which the posterior is well-concentrated. We show lower bounds that for shorter documents it can be information theoretically impossible to find the hidden topics. Finally, we give empirical results that demon strate that our algorithm works on realistic topic models. It yields good solutions on synthetic data and runs in time comparable to a single iteration of Gibbs

sampling.

Epigraph projections for fast general convex programming Po-Wei Wang, Matt Wytock, Zico Kolter

This paper develops an approach for efficiently solving general convex optimizat ion problems specified as disciplined convex programs (DCP), a common general-pu rpose modeling framework. Specifically we develop an algorithm based upon fast e pigraph projections, projections onto the epigraph of a convex function, an appr oach closely linked to proximal operator methods. We show that by using these op erators, we can solve any disciplined convex program without transforming the pr oblem to a standard cone form, as is done by current DCP libraries. We then deve lop a large library of efficient epigraph projection operators, mirroring and ex tending work on fast proximal algorithms, for many common convex functions. Fina lly, we evaluate the performance of the algorithm, and show it often achieves or der of magnitude speedups over existing general-purpose optimization solvers.

Fast Algorithms for Segmented Regression

Jayadev Acharya, Ilias Diakonikolas, Jerry Li, Ludwig Schmidt

We study the fixed design segmented regression problem: Given noisy samples from a piecewise linear function f, we want to recover f up to a desired accuracy in mean-squared error. Previous rigorous approaches for this problem rely on dynam ic programming (DP) and, while sample efficient, have running time quadratic in the sample size. As our main contribution, we provide new sample near-linear time algorithms for the problem that - while not being minimax optimal - achieve a significantly better sample-time tradeoff on large datasets compared to the DP approach. Our experimental evaluation shows that, compared with the DP approach, our algorithms provide a convergence rate that is only off by a factor of 2 to 4, while achieving speedups of three orders of magnitude.

Energetic Natural Gradient Descent

Philip Thomas, Bruno Castro Silva, Christoph Dann, Emma Brunskill

We propose a new class of algorithms for minimizing or maximizing functions of p arametric probabilistic models. These new algorithms are natural gradient algorithms that leverage more information than prior methods by using a new metric ten sor in place of the commonly used Fisher information matrix. This new metric ten sor is derived by computing directions of steepest ascent where the distance bet ween distributions is measured using an approximation of energy distance (as opposed to Kullback-Leibler divergence, which produces the Fisher information matrix), and so we refer to our new ascent direction as the energetic natural gradien t.

Partition Functions from Rao-Blackwellized Tempered Sampling David Carlson, Patrick Stinson, Ari Pakman, Liam Paninski

Partition functions of probability distributions are important quantities for mo del evaluation and comparisons. We present a new method to compute partition fun ctions of complex and multimodal distributions. Such distributions are often sam pled using simulated tempering, which augments the target space with an auxiliar y inverse temperature variable. Our method exploits the multinomial probability law of the inverse temperatures, and provides estimates of the partition function in terms of a simple quotient of Rao-Blackwellized marginal inverse temperatur e probability estimates, which are updated while sampling. We show that the method has interesting connections with several alternative popular methods, and off ers some significant advantages. In particular, we empirically find that the new method provides more accurate estimates than Annealed Importance Sampling when calculating partition functions of large Restricted Boltzmann Machines (RBM); mo reover, the method is sufficiently accurate to track training and validation log-likelihoods during learning of RBMs, at minimal computational cost.

Learning Mixtures of Plackett-Luce Models Zhibing Zhao, Peter Piech, Lirong Xia

In this paper we address the identifiability and efficient learning problems of finite mixtures of Plackett-Luce models for rank data. We prove that for any $k\geq 2$, the mixture of k Plackett-Luce models for no more than 2k-1 alternatives is no n-identifiable and this bound is tight for k=2. For generic identifiability, we prove that the mixture of k Plackett-Luce models over m alternatives is \em gene rically identifiable if $k\leq 1$ frac m-2 $2\leq 1$!. We also propose an efficient generaliz ed method of moments (GMM) algorithm to learn the mixture of two Plackett-Luce m odels and show that the algorithm is consistent. Our experiments show that our G MM algorithm is significantly faster than the EMM algorithm by Gormley & Murphy (2008), while achieving competitive statistical efficiency.

Near Optimal Behavior via Approximate State Abstraction

David Abel, David Hershkowitz, Michael Littman

The combinatorial explosion that plagues planning and reinforcement learning (RL) algorithms can be moderated using state abstraction. Prohibitively large task representations can be condensed such that essential information is preserved, a nd consequently, solutions are tractably computable. However, exact abstractions , which treat only fully-identical situations as equivalent, fail to present opp ortunities for abstraction in environments where no two situations are exactly a like. In this work, we investigate approximate state abstractions, which treat n early-identical situations as equivalent. We present theoretical guarantees of the quality of behaviors derived from four types of approximate abstractions. Add itionally, we empirically demonstrate that approximate abstractions lead to reduction in task complexity and bounded loss of optimality of behavior in a variety of environments.

Power of Ordered Hypothesis Testing

Lihua Lei, William Fithian

Ordered testing procedures are multiple testing procedures that exploit a pre-sp ecified ordering of the null hypotheses, from most to least promising. We analyz e and compare the power of several recent proposals using the asymptotic framewo rk of Li & Barber (2015). While accumulation tests including ForwardStop can be quite powerful when the ordering is very informative, they are asymptotically po werless when the ordering is weaker. By contrast, Selective SeqStep, proposed by Barber & Candes (2015), is much less sensitive to the quality of the ordering. We compare the power of these procedures in different regimes, concluding that S elective SeqStep dominates accumulation tests if either the ordering is weak or non-null hypotheses are sparse or weak. Motivated by our asymptotic analysis, we derive an improved version of Selective SeqStep which we call Adaptive SeqStep, analogous to Storey's improvement on the Benjamini-Hochberg procedure. We compare these methods using the GEO-Query data set analyzed by (Li & Barber, 2015) and find Adaptive SeqStep has favorable performance for both good and bad prior or derings.

PHOG: Probabilistic Model for Code

Pavol Bielik, Veselin Raychev, Martin Vechev

We introduce a new generative model for code called probabilistic higher order g rammar (PHOG). PHOG generalizes probabilistic context free grammars (PCFGs) by a llowing conditioning of a production rule beyond the parent non-terminal, thus c apturing rich contexts relevant to programs. Even though PHOG is more powerful t han a PCFG, it can be learned from data just as efficiently. We trained a PHOG m odel on a large JavaScript code corpus and show that it is more precise than exi sting models, while similarly fast. As a result, PHOG can immediately benefit ex isting programming tools based on probabilistic models of code.

Shifting Regret, Mirror Descent, and Matrices

Andras Gyorgy, Csaba Szepesvari

We consider the problem of online prediction in changing environments. In this f ramework the performance of a predictor is evaluated as the loss relative to an arbitrarily changing predictor, whose individual components come from a base cla ss of predictors. Typical results in the literature consider different base clas ses (experts, linear predictors on the simplex, etc.) separately. Introducing an arbitrary mapping inside the mirror decent algorithm, we provide a framework th at unifies and extends existing results. As an example, we prove new shifting regret bounds for matrix prediction problems.

Scalable Gradient-Based Tuning of Continuous Regularization Hyperparameters Jelena Luketina, Mathias Berglund, Klaus Greff, Tapani Raiko

Hyperparameter selection generally relies on running multiple full training tria ls, with selection based on validation set performance. We propose a gradient-ba sed approach for locally adjusting hyperparameters during training of the model. Hyperparameters are adjusted so as to make the model parameter gradients, and h ence updates, more advantageous for the validation cost. We explore the approach for tuning regularization hyperparameters and find that in experiments on MNIST, SVHN and CIFAR-10, the resulting regularization levels are within the optimal regions. The additional computational cost depends on how frequently the hyperparameters are trained, but the tested scheme adds only 30% computational overhead regardless of the model size. Since the method is significantly less computationally demanding compared to similar gradient-based approaches to hyperparameter optimization, and consistently finds good hyperparameter values, it can be a use ful tool for training neural network models.

Model-Free Trajectory Optimization for Reinforcement Learning Riad Akrour, Gerhard Neumann, Hany Abdulsamad, Abbas Abdolmaleki

Many of the recent Trajectory Optimization algorithms alternate between local ap proximation of the dynamics and conservative policy update. However, linearly ap proximating the dynamics in order to derive the new policy can bias the update a nd prevent convergence to the optimal policy. In this article, we propose a new model-free algorithm that backpropagates a local quadratic time-dependent Q-Func tion, allowing the derivation of the policy update in closed form. Our policy up date ensures exact KL-constraint satisfaction without simplifying assumptions on the system dynamics demonstrating improved performance in comparison to related Trajectory Optimization algorithms linearizing the dynamics.

Controlling the distance to a Kemeny consensus without computing it Yunlong Jiao, Anna Korba, Eric Sibony

Due to its numerous applications, rank aggregation has become a problem of major interest across many fields of the computer science literature. In the vast majority of situations, Kemeny consensus(es) are considered as the ideal solutions. It is however well known that their computation is NP-hard. Many contributions have thus established various results to apprehend this complexity. In this paper we introduce a practical method to predict, for a ranking and a dataset, how colose the Kemeny consensus(es) are to this ranking. A major strength of this method is its generality: it does not require any assumption on the dataset nor the ranking. Furthermore, it relies on a new geometric interpretation of Kemeny aggregation that, we believe, could lead to many other results.

Horizontally Scalable Submodular Maximization

Mario Lucic, Olivier Bachem, Morteza Zadimoghaddam, Andreas Krause

A variety of large-scale machine learning problems can be cast as instances of c onstrained submodular maximization. Existing approaches for distributed submodul ar maximization have a critical drawback: The capacity - number of instances that can fit in memory - must grow with the data set size. In practice, while one c an provision many machines, the capacity of each machine is limited by physical constraints. We propose a truly scalable approach for distributed submodular max imization under fixed capacity. The proposed framework applies to a broad class of algorithms and constraints and provides theoretical guarantees on the approximation factor for any available capacity. We empirically evaluate the proposed a lgorithm on a variety of data sets and demonstrate that it achieves performance competitive with the centralized greedy solution.

Group Equivariant Convolutional Networks

Taco Cohen, Max Welling

We introduce Group equivariant Convolutional Neural Networks (G-CNNs), a natural generalization of convolutional neural networks that reduces sample complexity by exploiting symmetries. G-CNNs use G-convolutions, a new type of layer that en joys a substantially higher degree of weight sharing than regular convolution layers. G-convolutions increase the expressive capacity of the network without increasing the number of parameters. Group convolution layers are easy to use and can be implemented with negligible computational overhead for discrete groups generated by translations, reflections and rotations. G-CNNs achieve state of the art results on CIFAR10 and rotated MNIST.

Stochastic Discrete Clenshaw-Curtis Quadrature

Nico Piatkowski, Katharina Morik

The partition function is fundamental for probabilistic graphical models—it is r equired for inference, parameter estimation, and model selection. Evaluating this s function corresponds to discrete integration, namely a weighted sum over an exponentially large set. This task quickly becomes intractable as the dimensionality of the problem increases. We propose an approximation scheme that, for any discrete graphical model whose parameter vector has bounded norm, estimates the partition function with arbitrarily small error. Our algorithm relies on a near minimax optimal polynomial approximation to the potential function and a Clenshaw-Curtis style quadrature. Furthermore, we show that this algorithm can be randomized to split the computation into a high-complexity part and a low-complexity part, where the latter may be carried out on small computational devices. Experime nts confirm that the new randomized algorithm is highly accurate if the parameter norm is small, and is otherwise comparable to methods with unbounded error.

Correcting Forecasts with Multifactor Neural Attention

Matthew Riemer, Aditya Vempaty, Flavio Calmon, Fenno Heath, Richard Hull, Elham Khabiri

Automatic forecasting of time series data is a challenging problem in many indus tries. Current forecast models adopted by businesses do not provide adequate mea ns for including data representing external factors that may have a significant impact on the time series, such as weather, national events, local events, socia l media trends, promotions, etc. This paper introduces a novel neural network at tention mechanism that naturally incorporates data from multiple external source s without the feature engineering needed to get other techniques to work. We dem onstrate empirically that the proposed model achieves superior performance for p redicting the demand of 20 commodities across 107 stores of one of America's lar gest retailers when compared to other baseline models, including neural networks, linear models, certain kernel methods, Bayesian regression, and decision trees. Our method ultimately accounts for a 23.9% relative improvement as a result of the incorporation of external data sources, and provides an unprecedented level of descriptive ability for a neural network forecasting model.

Learning Representations for Counterfactual Inference

Fredrik Johansson, Uri Shalit, David Sontag

Observational studies are rising in importance due to the widespread accumulation of data in fields such as healthcare, education, employment and ecology. We consider the task of answering counterfactual questions such as, "Would this patient have lower blood sugar had she received a different medication?". We propose a new algorithmic framework for counterfactual inference which brings together it deas from domain adaptation and representation learning. In addition to a theore tical justification, we perform an empirical comparison with previous approaches to causal inference from observational data. Our deep learning algorithm significantly outperforms the previous state-of-the-art.

Automatic Construction of Nonparametric Relational Regression Models for Multipl

e Time Series

Yunseong Hwang, Anh Tong, Jaesik Choi

Gaussian Processes (GPs) provide a general and analytically tractable way of mod eling complex time-varying, nonparametric functions. The Automatic Bayesian Cova riance Discovery (ABCD) system constructs natural-language description of time-s eries data by treating unknown time-series data nonparametrically using GP with a composite covariance kernel function. Unfortunately, learning a composite cova riance kernel with a single time-series data set often results in less informati ve kernel that may not give qualitative, distinctive descriptions of data. We ad dress this challenge by proposing two relational kernel learning methods which c an model multiple time-series data sets by finding common, shared causes of chan ges. We show that the relational kernel learning methods find more accurate mode ls for regression problems on several real-world data sets; US stock data, US ho use price index data and currency exchange rate data.

Inference Networks for Sequential Monte Carlo in Graphical Models Brooks Paige, Frank Wood

We introduce a new approach for amortizing inference in directed graphical model s by learning heuristic approximations to stochastic inverses, designed specific ally for use as proposal distributions in sequential Monte Carlo methods. We describe a procedure for constructing and learning a structured neural network which represents an inverse factorization of the graphical model, resulting in a conditional density estimator that takes as input particular values of the observed random variables, and returns an approximation to the distribution of the latent variables. This recognition model can be learned offline, independent from any particular dataset, prior to performing inference. The output of these networks can be used as automatically-learned high-quality proposal distributions to accelerate sequential Monte Carlo across a diverse range of problem settings.

Slice Sampling on Hamiltonian Trajectories

Benjamin Bloem-Reddy, John Cunningham

Hamiltonian Monte Carlo and slice sampling are amongst the most widely used and studied classes of Markov Chain Monte Carlo samplers. We connect these two metho ds and present Hamiltonian slice sampling, which allows slice sampling to be car ried out along Hamiltonian trajectories, or transformations thereof. Hamiltonian slice sampling clarifies a class of model priors that induce closed-form slice samplers. More pragmatically, inheriting properties of slice samplers, it offers advantages over Hamiltonian Monte Carlo, in that it has fewer tunable hyperpara meters and does not require gradient information. We demonstrate the utility of Hamiltonian slice sampling out of the box on problems ranging from Gaussian process regression to Pitman-Yor based mixture models.

Noisy Activation Functions

Caglar Gulcehre, Marcin Moczulski, Misha Denil, Yoshua Bengio

Common nonlinear activation functions used in neural networks can cause training difficulties due to the saturation behavior of the activation function, which ${\tt m}$ ay hide dependencies that are not visible to vanilla-SGD (using first order grad ients only). Gating mechanisms that use softly saturating activation functions t o emulate the discrete switching of digital logic circuits are good examples of this. We propose to exploit the injection of appropriate noise so that the gradi ents may flow easily, even if the noiseless application of the activation functi on would yield zero gradients. Large noise will dominate the noise-free gradient and allow stochastic gradient descent to explore more. By adding noise only to the problematic parts of the activation function, we allow the optimization proc edure to explore the boundary between the degenerate saturating) and the well-be haved parts of the activation function. We also establish connections to simulat ed annealing, when the amount of noise is annealed down, making it easier to opt imize hard objective functions. We find experimentally that replacing such satur ating activation functions by noisy variants helps optimization in many contexts , yielding state-of-the-art or competitive results on different datasets and tas

k, especially when training seems to be the most difficult, e.g., when curriculu m learning is necessary to obtain good results.

PD-Sparse : A Primal and Dual Sparse Approach to Extreme Multiclass and Multilab el Classification

Ian En-Hsu Yen, Xiangru Huang, Pradeep Ravikumar, Kai Zhong, Inderjit Dhillon We consider Multiclass and Multilabel classification with extremely large number of classes, of which only few are labeled to each instance. In such setting, st andard methods that have training, prediction cost linear to the number of class es become intractable. State-of-the-art methods thus aim to reduce the complexit y by exploiting correlation between labels under assumption that the similarity between labels can be captured by structures such as low-rank matrix or balanced tree. However, as the diversity of labels increases in the feature space, struc tural assumption can be easily violated, which leads to degrade in the testing p erformance. In this work, we show that a margin-maximizing loss with 11 penalty, in case of Extreme Classification, yields extremely sparse solution both in pri mal and in dual without sacrificing the expressive power of predictor. We thus p ropose a Fully-Corrective Block-Coordinate Frank-Wolfe (FC-BCFW) algorithm that exploits both primal and dual sparsity to achieve a complexity sublinear to the number of primal and dual variables. A bi-stochastic search method is proposed t o further improve the efficiency. In our experiments on both Multiclass and Mult ilabel problems, the proposed method achieves significant higher accuracy than e xisting approaches of Extreme Classification with very competitive training and prediction time.