Lab Session 10

MA-581: Numerical Computations Lab

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Stability and accuracy: Consider a linear system Ax = b. Then $\operatorname{cond}(A) := \|A\|_2 \|A^{-1}\|_2$ is called the condition number of A which is a measure of sensitivity of the linear system to small changes in the linear system. Let \hat{x} be a computed solution of the linear system. Then $\eta(\hat{x}, A) := \frac{\|A\hat{x} - b\|_2}{\|A\|_2 \|x\|_2}$ is known as the backward error of \hat{x} . It can be shown that

$$\frac{\|x - \hat{x}\|_2}{\|x\|_2} \lesssim \operatorname{cond}(A) \, \eta(\hat{x}, A).$$

Origin of the Hilbert matrix: Suppose a function f is approximated by a polynomial p of degree n-1, that is, $p(x) = a_0 + a_1t + \cdots + a_{n-1}t^{n-1}$ on [0,1]. The method of least squares (more on this later) determines a_i such that the error

$$E := \|f - p\|_2^2 = \int_0^1 (f(t) - p(t))^2 dt$$

is minimized. Differentiating E w.r.t a_k and setting the partial derivative to 0 (necessary condition for minima), we have

$$\sum_{j=1}^{n-1} a_j \int_0^1 t^{j+k} dt = \int_0^1 t^k f(t) dt, \ k = 0 : n-1$$

which can be written in the matrix form Ha = b, where H is the Hilbert matrix given by H(i,j) := 1/(i+j-1). There is a built-in function in MATLAB for generating Hilbert matrix. Type help hilb and help invhilb for details.

The purpose of this lab tutorial is to understand ill-conditioning of linear system and stability of an algorithm and their influence on the accuracy of computed solution.

- 1. Consider the Hilbert matrix H, where H(i,j) := 1/(i+j-1) (the MATLAB command H = hilb(n) generates H) and perform the following experiments.
 - (a) Convince yourself that the condition number of H grows quickly with n. Try

>> N= 2:2:16;

for n=N

H=hilb(n); C=[C; cond(H)];

end

>> semilogy(N,C)

Can you guess an approximate relationship between $\operatorname{cond}(H)$ and n based on this graph? The MATLAB $\operatorname{cond}(H)$ computes the 2-norm condition number of H. Theoretically $\operatorname{cond}(H) \approx \left(\frac{(1+\sqrt{2})^{4n}}{\sqrt{n}}\right)$. Plot (in a single plot) the theoretical value of $\operatorname{cond}(H)$ and $\operatorname{cond}(H)$ computed by MATLAB. The condition number computed by MATLAB reaches the maximum when n=13. The computed condition number

does not continue to grow when n > 13. This can be explained as follows: Since H is positive definite (that is, $H = H^*$ and eigenvalues of H are all positive), $\operatorname{cond}(H) = \lambda_{\max}(H)/\lambda_{\min}(H)$, where $\lambda_{\max}(H)$ and $\lambda_{\min}(H)$ are the largest and the smallest eigenvalues of H. It is a fact that e $\lambda_{\max}(H) \to \pi$ and $\lambda_{\min}(H) \to 0$ as $n \to \infty$. Hence

$$\operatorname{cond}(H) = \frac{\sigma_{\max}(H)}{\sigma_{\min}(H)} \approx \frac{\pi}{\sigma_{\min}(H) + \operatorname{\mathsf{eps}}} \approx \frac{\pi}{\operatorname{\mathsf{eps}}}.$$

%%%%% Matlab program that implements growth of cond(H) % generate Hilbert matrices and compute cond number with 2-norm

```
N=50; % maximum size of a matrix
condofH = []; % conditional number of Hilbert Matrix
N_it= zeros(1,N);
% compute the cond number of Hn
for n = 1:N
    Hn = hilb(n);
    N_{it}(n)=n;
    condofH = [condofH cond(Hn,2)];
end
% at this point we have a vector condofH that contains the condition
% number of the Hilber matrices from 1x1 to 50x50.
% plot on the same graph the theoretical growth line.
% Theoretical growth of condofH
x = 1:50;
y = (1+sqrt(2)).^(4*x)./(sqrt(x));
% plot
plot(N_it, log(y));
plot(N_it, log(condofH),'x', N_it,log(y));
% plot labels
plot(N_it, log(condofH),'x', N_it,log(y))
title ('Conditional Number growth of Hilbert Matrix: Theoretical vs Matlab')
```

%%%%% end of the program

legend('show')

legend('MatLab', 'Theoretical')

xlabel('N', 'fontsize', 16)

ylabel('log(cond(Hn))', 'fontsize', 16)
lgd = legend ('Location', 'northwest')

(b) The importance of condition number stems from the fact that if $cond(H) = 10^t$ then

we may lose t digits in the computed solution of Hx = b. Examine this criterion by solving Hx = b. Here is how you can pick up the exact solution. Choose an arbitrary x and set b := Hx. Then x is the exact solution of Hx = b. The matrix H is SPD (symmetric positive definite). The matlab backslash $A \setminus b$ command uses Cholesky factorization to solve an SPD system. There is also a matlab command invhilb which computes H^{-1} in a special way. You can also use GEPP (Gaussian Elimination with Partial Pivoting) to solve Hx = b. You may have to use format long e to see more digits. Try

```
>> n=8;
>> H=hilb(n); HI = invhilb(n);
>> x= rand(n,1);
>> b =H*x;
>> x1 = H\ b; % Call this is method1
>> x2 = HI*b; % Call this is method2
```

Compute backward error eta, condition number cond and the error err for method1 and method2 and display the result in the format [eta cond err].

Repeat for n = 10 and n = 12.

- * List the results corresponding to n = 8, 10, 12, and determine correct digits in x1, x2.
- * How many digits are lost in computing x1 and x2? How does this correlate with the size of the condition number?
- * Which is better among x1 and x2 or isn't there much of a difference? Is it fair to say that the inaccuracy resulted from a poor algorithm?
- 2. Wilkinson's matrix is defined as follows: 1 on the diagonal, -1 everywhere below the main diagonal, 1 in the last column, and 0 everywhere else. Write a MATLAB function W = Wilkinson(n) that generates Wilkinson's matrix W of size n using MATLAB functions eye, tril and ones.
 - (a) For n=32, pick a random x and then compute b:=W*x. Solve Ax=b using MATLAB backslash command and compute the error $||x-\hat{x}||_{\infty}/||x||_{\infty}$ (type help norm for more info about computing norm). Does the size of the error confirm that GEPP is unstable for this system? Also compute $\operatorname{cond}(A)$. Can the poor answer be attributed to ill-conditioning of the matrix W? Repeat the test for n=64.
 - (b) Repeat the experiment in part (a) using QR decomposition. It is easy in matlab. The command [Q,R] =qr(A) gives unitary Q and upper triangular R such that A = QR. Solve Wx = b using QR decomposition and compare the results with those in part(a). Which of the two methods appear to give a better answer?
- 3. Pivot growth of Gaussian elimination with partial pivoting (GEPP) is given by $PG(A) = \max_{ij} |U(i,j)|/\max_{ij} |A(i,j)|$, which influences the accuracy of computed solution. Use MATLAB function [L, U, p] = lu(A) for computing LU decomposition of a nonsingular matrix A and compute the pivot growth rho = PG(A).

[**Hint:** Given a matrix X, max(X) is a row vector containing the maximum element from each column.]

It is well known that the pivot growth factor for GEPP satisfies $PG(A) \leq 2^{n-1}$ which is attained by the Wilkinson matrix. Verify this graphically by doing the following:

First plot the graph of 2^{n-1} in $\log 10$ scale for n = 10 : .5 : 505 by setting $X = 2.^(n-1)$ and then typing semilogy(n,X,'r'). Hold this plot by typing hold on and type the following sequence of commands (which assumes that the Wilkinson matrix of size n is generated by the function W = Wilkinson(n)).

```
n = 10:20:500;
m = length(n); G = zeros(m,1);
for i = 1:m
W = Wilkinson(n(i)); [L,U,p] = lu(W);
G(i) = max(max(abs(U)))/max(max(abs(W)));
end
semilogy(n,G,'b*')
```

The second plot should come in the form of blue dots that fall on the red curve produced by the earlier plot.

However, statistics suggest that for most practical examples, $PG(A) \leq n^{2/3}$ for GEPP. Verify this graphically by generating random matrices instead of Wilkinson matrices in the sequence of commands given above.

4. There is no strong correlation between pivot growth and the ill-conditioning of a matrix. This is illustrated by a Golub matrix. A Golub matrix A of size n is an ill-conditioned integer matrix whose LU factorization without pivoting fails to reveal that A is ill-conditioned. The matrix A is given by A := LU, where L unit lower triangular with random integer entries and U is unit upper triangular with random integer entries. The function golub given below generates a Golub matrix of size n:

```
function A = golub(n)
s = 10;
L = tril(round(s*randn(n)),-1)+eye(n);
U = triu(round(s*randn(n)),1)+eye(n);
A = L*U:
```

Compute LU factorization of A using your function [L, U] = GENP(A). Also, compute the pivot growth PG(A) and the condition number $\operatorname{cond}(A) = ||A||_{\infty} ||A^{-1}||_{\infty}$ using MATLAB command $\operatorname{cond}(A)$. If $\operatorname{cond}(A)$ is large then the system Ax = b is ill-conditioned and in such a case A is called ill-conditioned. Does PG(A) reflect the ill-conditioning of A?

**********End********