→ Get understanding about Data Set



| 10.700 A |
|----------------------------|
| |
| Data Set Characteristics: |
| Multivariate |
| Number of Instances: |
| 167 |
| Area: |
| Computer |
| Attribute Characteristics: |
| Categorical, Integer |
| Number of Attributes: |
| 4 |
| Date Donated |
| 1993-05-01 |
| Associated Tasks: |
| Regression |
| Missing Values? |
| No |
| Number of Web Hits: |
| 123354 |
| Source: |
| Creator: |
| Karl Ulrich (MIT) |
| Donor: |

Ross Quinlan

Data Set Information:

Ross Quinlan:

This data was given to me by Karl Ulrich at MIT in 1986. I didn't record his description at the time, but here's his subsequent (1992) recollection:

"I seem to remember that the data was from a simulation of a servo system involving a servo amplifier, a motor, a lead screw/nut, and a sliding carriage of some sort. It may have been on of the translational axes of a robot on the 9th floor of the AI lab. In any case, the output value is almost certainly a rise time, or the time required for the system to respond to a step change in a position set point."

(Quinlan, ML'93)

"This is an interesting collection of data provided by Karl Ulrich. It covers an extremely non-linear phenomenon - predicting the rise time of a servomechanism in terms of two (continuous) gain settings and two (discrete) choices of mechanical linkages."

Attribute Information:

1. motor: A,B,C,D,E

2. screw: A,B,C,D,E

3. pgain: 3,4,5,6

4. vgain: 1,2,3,4,5

5. class: 0.13 to 7.10

Import Library

import pandas as pd

import numpy as np

Import CSV as DataFrame

df = pd.read_csv(r'https://github.com/YBI-Foundation/Dataset/raw/main/Servo%20Mechan

→ GET THE fIRST FIVE ROWS OF THE DATA FRAME

df.head()

| | Motor | Screw | Pgain | Vgain | Class |
|---|-------|-------|-------|-------|-------|
| 0 | Е | Е | 5 | 4 | 4 |
| 1 | В | D | 6 | 5 | 11 |
| 2 | D | D | 4 | 3 | 6 |
| 3 | В | Α | 3 | 2 | 48 |
| 4 | D | В | 6 | 5 | 6 |

Get information about the data frame

```
df.info()
```

Get the Summary statistics

df.describe()

| | Pgain | Vgain | Class |
|-------|------------|------------|------------|
| count | 167.000000 | 167.000000 | 167.000000 |
| mean | 4.155689 | 2.538922 | 21.173653 |
| std | 1.017770 | 1.369850 | 13.908038 |
| min | 3.000000 | 1.000000 | 1.000000 |
| 25% | 3.000000 | 1.000000 | 10.500000 |
| 50% | 4.000000 | 2.000000 | 18.000000 |
| 75% | 5.000000 | 4.000000 | 33.500000 |
| max | 6.000000 | 5.000000 | 51.000000 |

Get column names

Get the shape of the DataFrame

Get catagories and counts of catagorical Variables

Get Encoding of Catagorical Features

```
df.replace({'Motor':{'A':0,'B':1,'C':2,'D':3,'E':4}},inplace = True)

df.replace({'Screw':{'A':0,'B':1,'C':2,'D':3,'E':4}},inplace = True)
```

Define y (dependant or label or target variable) and X (independent ,feature and attribute Variable)

Get train_test_split

Get Model Train

```
#from sklearn.linear_model import LinearRegression
#from sklearn.neighbors import KNeighborsRegressor
#from sklearn.svm import SVR
from sklearn.tree import DecisionTreeRegressor

model = DecisionTreeRegressor()
```

Get Model train

```
model.fit(X_train,y_train)
```

DecisionTreeRegressor()

Get model prediction

Gel Model Evaluation

```
from sklearn.metrics import mean_absolute_error,mean_absolute_percentage_error,mean_
mean_squared_error(y_test,y_pred)
        28.058823529411764

mean_absolute_error(y_test,y_pred)
        3.823529411764706

r2_score(y_test,y_pred)
        0.8643390102720245

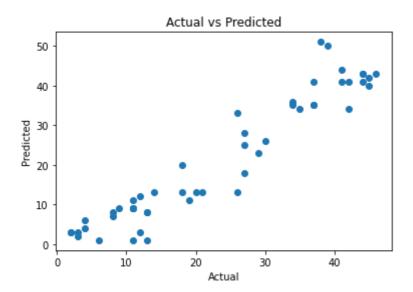
mean_square_error for
    1. LinearRegression = 66
    2. KNeighborsRegressor = 85
    3. SVR = 181
    4. DecisionTreeRegressor = 28
```

Double-click (or enter) to edit

Get visualisation of the actual vs predicted Results

```
import matplotlib.pyplot as plt
plt.scatter(y_test,y_pred)
```

```
plt.xlabel('Actual')
plt.ylabel('Predicted')
plt.title('Actual vs Predicted')
plt.show()
```



→ Get Future Prediction

Lets select a random sample from existing dataset as new value

- 1. Extract a randomrow using sample function
- 2. Separate X and y
- 3. Standardize X
- 4. Predict

df_new

df_new.shape

(1, 5)

X_new

| | Motor | Screw | Pgain | Vgain |
|-----|-------|-------|-------|-------|
| 142 | 0 | 4 | 3 | 1 |

```
X_new.shape
      (1, 4)

y_pred_new = model.predict(X_new)

y_pred_new
      array([41.])
```

*CONCLUSION *

• I tried all the regression model for the servo prediction among them **DecisionTreeRegressor** gives the higher accurecy of the Servo prediction.

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