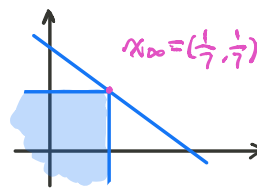
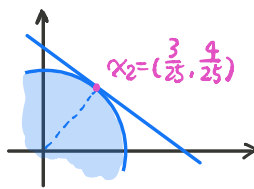
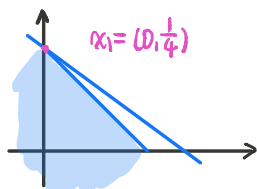


Lec 11: Minimizing $\|x\|$ Subject to $Ax=b$

min $\|x\|_1, \|x\|_2, \|x\|_\infty$ with $3x_1 + 4x_2 = 1$.



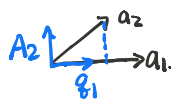
Gram-Schmidt

1. Standard way $A \rightarrow QR$.
2. Column exchanges.
3. "Krylov-Arnoldi"

$$A = \begin{bmatrix} | & & | \\ a_1 & \dots & a_n \\ | & & | \end{bmatrix} \rightarrow Q = \begin{bmatrix} | & & | \\ q_1 & \dots & q_n \\ | & & | \end{bmatrix}$$

$$A = QR. (a_i = r_1 q_1 + \dots + r_n q_n) \Rightarrow R = Q^T A = \begin{bmatrix} -q_1^T - \\ \vdots \\ -q_n^T - \end{bmatrix} \begin{bmatrix} | & & | \\ a_1 & \dots & a_n \\ | & & | \end{bmatrix}$$

$$\begin{bmatrix} | & | \\ a_1 & a_2 \\ | & | \end{bmatrix}$$



$$q_1 = \frac{a_1}{\|a_1\|}$$

$$A_2 = a_2 - (a_2^T q_1) q_1$$

$$q_2 = \frac{A_2}{\|A_2\|}$$

check $q_1 \cdot A_2 = 0$.

$$A_3 = a_3 - (a_3^T q_1) q_1 - (a_3^T q_2) q_2$$

$$q_3 = \frac{A_3}{\|A_3\|}$$



$$q_2 = \frac{A_2}{\|A_2\|} \quad \|A_2\| \text{ is too small.}$$

column exchange: get q_1 , choose biggest A_2

Column pivoting possible: How to decide q_2 .

$$\left. \begin{array}{l} A_2 = a_2 - (a_2^T q_1) q_1 \\ \text{also compute: } A_3 = a_3 - (a_3^T q_1) q_1 \\ A_4 = \dots \\ \vdots \end{array} \right\} \text{find the biggest one, } q_2 = \frac{A_2}{\|A_2\|}$$

Go on to $q_3 \dots$

Krylov. (Large sparse matrix A).

$$Ax = b \Rightarrow \underline{b, Ab, A(Ab), \dots, A^{j-1}b}$$

Gram-Schmidt $\left\{ \begin{array}{l} \text{Combinations give the Krylov Space } K_j \\ \alpha_j = \text{best vector in } K_j \\ q_1 = \frac{b}{\|b\|}, q_2 = \dots, q_j = \dots \end{array} \right.$

Why orthogonal basis is the best to do projection?

$$x \approx c_1 q_1 + c_2 q_2 + \dots + c_n q_n = QC.$$

$$C = Q^T x = Q^T x$$

$$q_1^T x \approx c_1 q_1^T q_1 + c_2 \cancel{q_1^T q_2} + \dots + c_n \cancel{q_1^T q_n}$$