

IoT Security and Privacy

Create IoT devices with Raspberry Pi

Learning Outcomes

Upon completion of this unit:

1. Students will master the use of Raspberry Pi
2. Students will understand basic circuits interacting with Raspberry Pi
3. Students will master programming Raspberry Pi

Outline

- **Overview**
- Setup and configurations
- 10 Use of Raspberry Pi
- Breadboard
- GPIO
- Sample use: Control LED
- Sample use: Read PIR motion sensor

What is a Raspberry Pi?

- [University of Cambridge's Computer Laboratory](#)
 - Decline in skill level
 - Designed for education
- A credit card sized PC
- Plugs into a TV or monitor
- Inexpensive <\$40 each
- Capability:
 - Programming
 - Electronic Projects
 - Office
 - Play HD Videos

Different Versions

- Raspberry Pi 3 model B
- Raspberry Pi 2 model B
- Raspberry Pi model B+
- Raspberry Pi model A+
- Raspberry Pi Zero W
- Raspberry Pi Zero

Components

- Essential components
 - *Raspberry Pi 3 with WiFi (or USB WiFi dongle for old models)*
 - *Prepared Operating System SD Card*
 - USB keyboard
 - USB mouse
 - Display (HDMI, DVI, or composite input (TV cable), *DSI touch screen*)
 - *Power Supply*
- Highly suggested extras
 - Internet connectivity - LAN cable
 - *Case*
 - *Breadboard*
 - *Sensors*
 - *Wires*

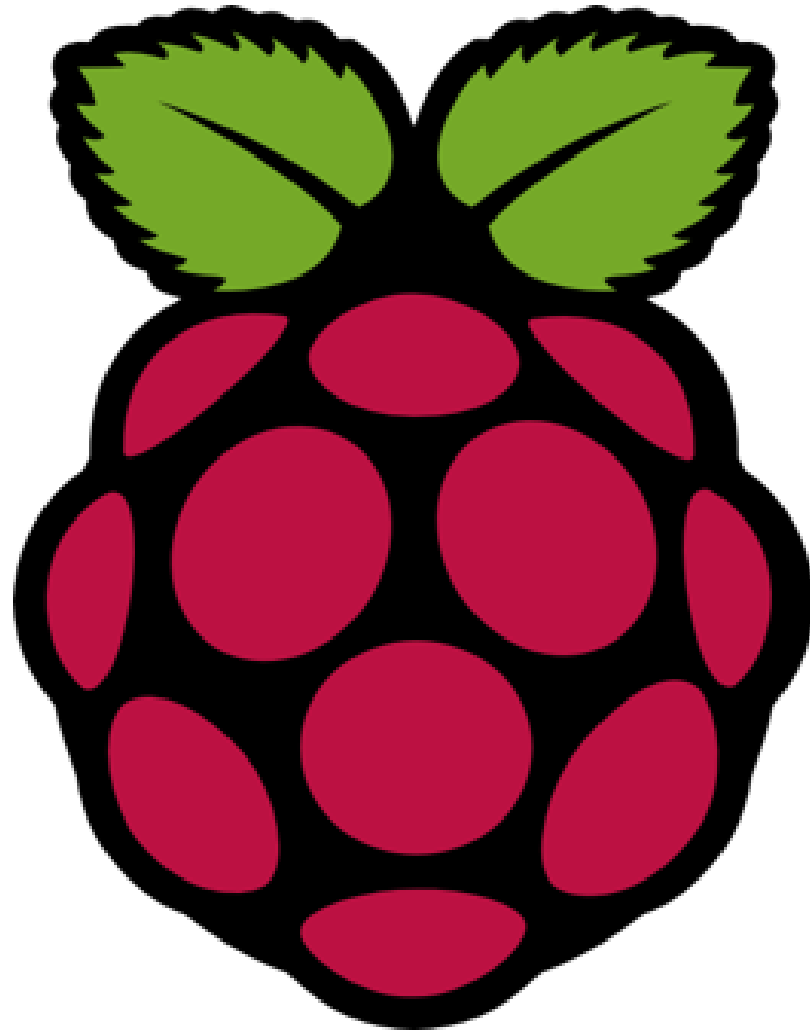
Programming Languages

- Any language which will compile for the ARM chip used in the Pi
- Python
- C
- C++
- Java
- Scratch
- Ruby

Outline

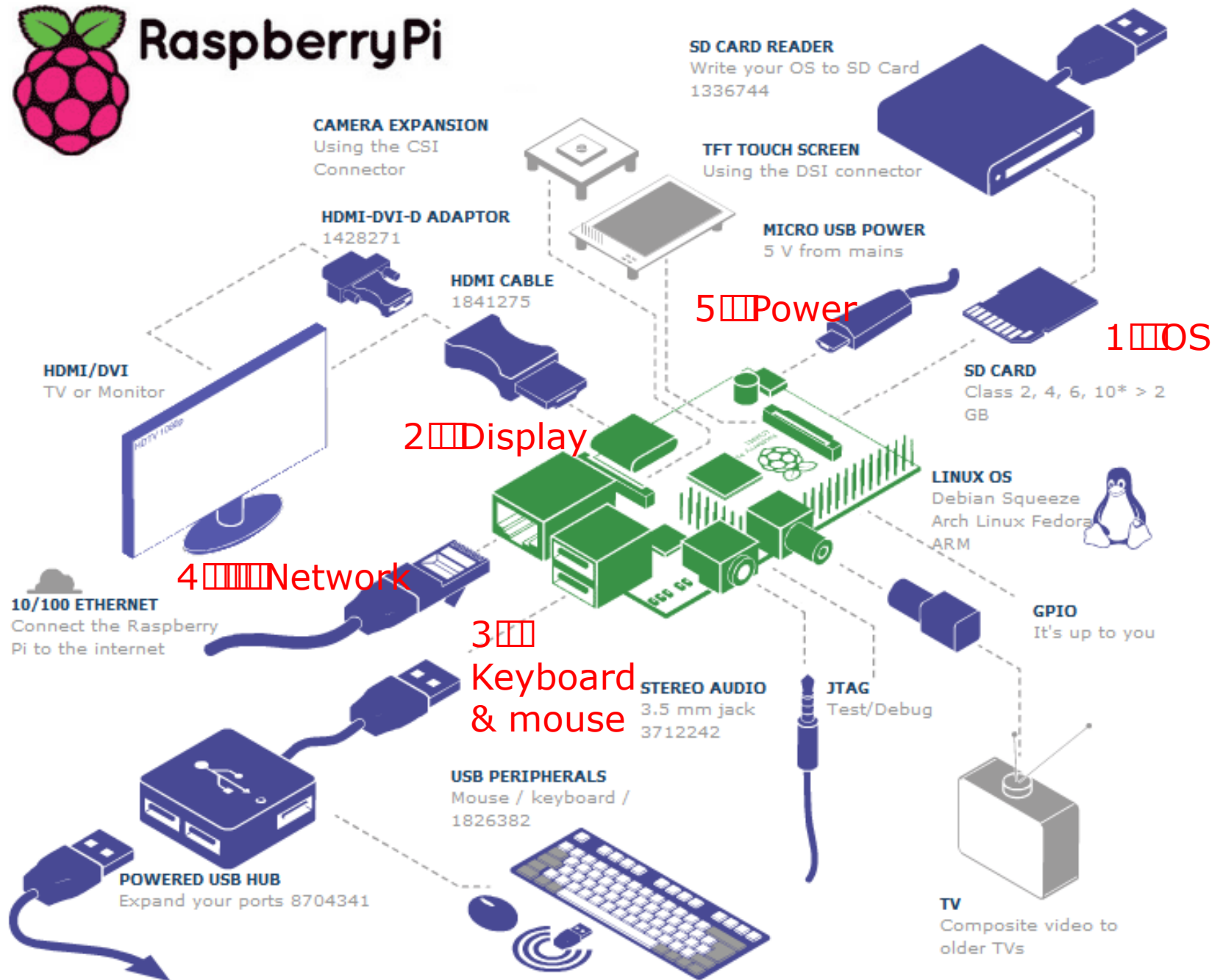
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Setup

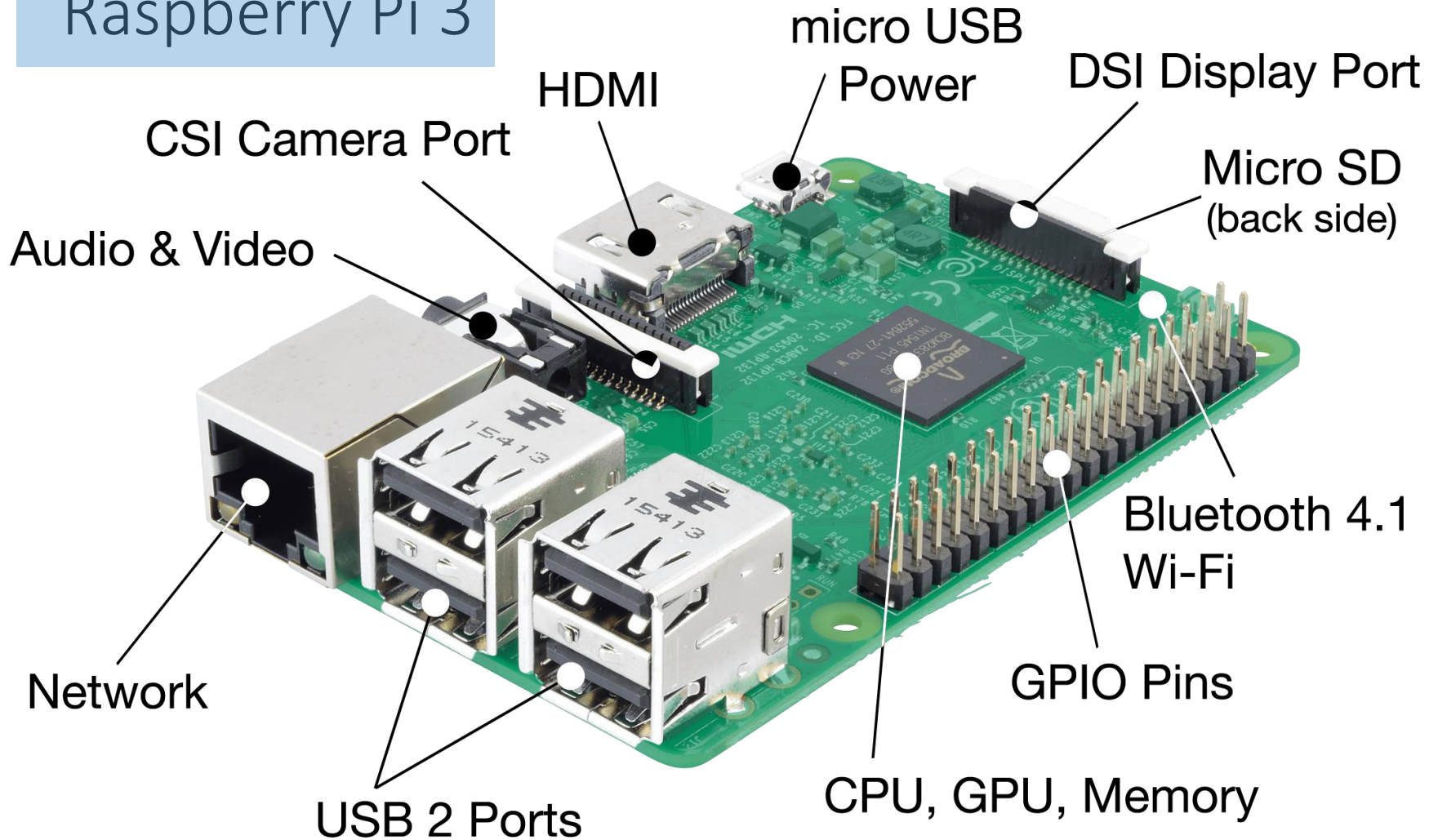




Raspberry Pi



Raspberry Pi 3



Configurations

- Booting Up for the First Time
 - Choose OS (Raspbian – recommended)
 - Configure to use the Whole SD Card
 - Change Timezone
 - Boot into Desktop
- Run the configuration later
 - *sudo raspi-config*
 - Or use the GUI
- Network setup
 - Using a Wired Network
 - USB WiFi Adapter/Onboard WiFi

Software Packages to Use I/O (Input/Output)

- GPIO setup: install Python library *Rpi.GPIO*
 1. `sudo apt-get update`
 2. `sudo apt-get install python-dev`
 3. `sudo apt-get install python-rpi.gpio`
- I2C: A standard for chips talking to each other
 - Multiple devices to Raspberry Pi through I2C bus
 - Unique address for each device through jumper settings
 - To use with Pi: Enable kernel support from `rasp-config`
- Install the `i2c-tools` utility.
 1. `sudo apt-get update`
 2. `sudo apt-get install python-smbus`
 3. `sudo apt-get install i2c-tools`
 - Test I2C devices: `sudo i2cdetect -y 1`

Sample Starter Kits

- [CanaKit Raspberry Pi 2 Ultimate Starter Kit with WiFi](#) \$84.99
- [Raspberry Pi 2 Model B Starter Pack - Includes a Raspberry Pi 2](#) \$99.95

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Example Use

- Office: LibreOffice
- Programming: Python, Scratch
- Game console
- Web server: Apache
- Tor router
- HTPC - A home theater PC (HTPC) or media center computer
- Bird house
- Super computer
- Clock
- PiBot

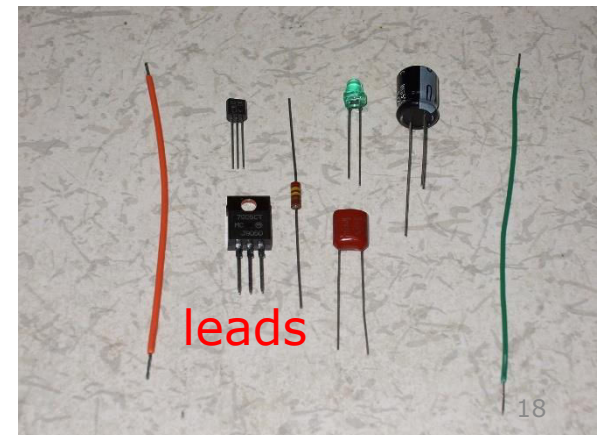
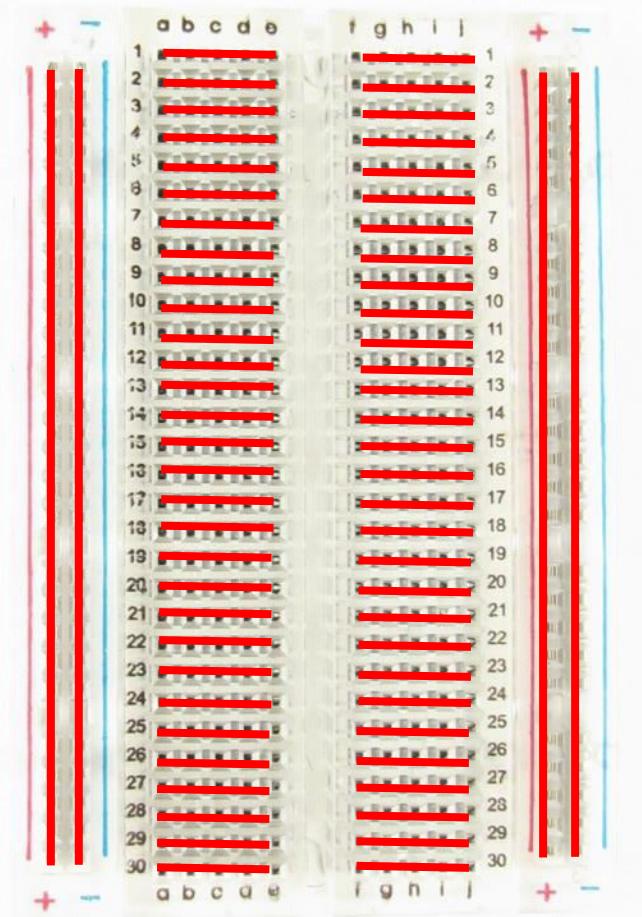


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How A Breadboard Works

- A grid of holes on a plastic board
- Internal metal strips underlining the holes as jumper wires
 - Connecting specific rows or columns of holes.
- Electric component leads and wires are inserted into the holes
 - Wires connect electric component leads
- Building circuits with a breadboard: stick components and wires into the holes.



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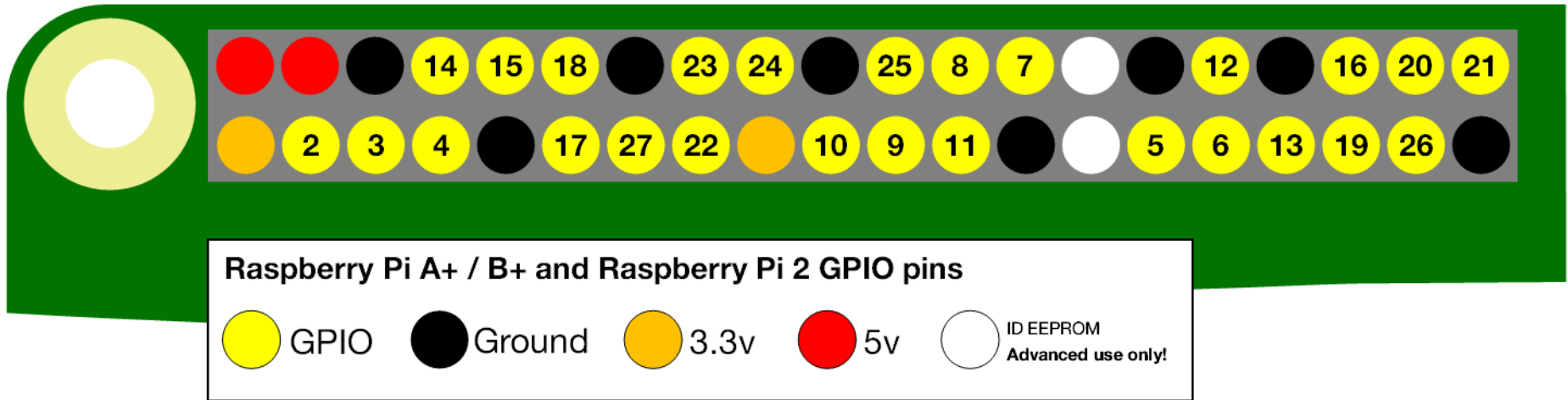
GPIO: MODELS A+, B+ AND RASPBERRY PI 2, 3

- Physical interface between the Pi and the outside world.
- Can be viewed as switches
 - that you can turn on or off (input)
 - or that the Pi can turn on or off (output).



GPIO Pins

- 40 pins on the board
 - 26 GPIO pins
 - Others are power or ground pins



Use of GPIO Pins

- Program the pins to interact in various ways
- Input to a pin from a sensor, another computer or device
 - For example, from a motion sensor
- Output from a pin can do
 - Turn on an LED
 - Send a signal or data to another device.
- A networked Raspberry Pi
 - Remote control of attached physical devices
 - Receiving data from those devices

Pin Numbering

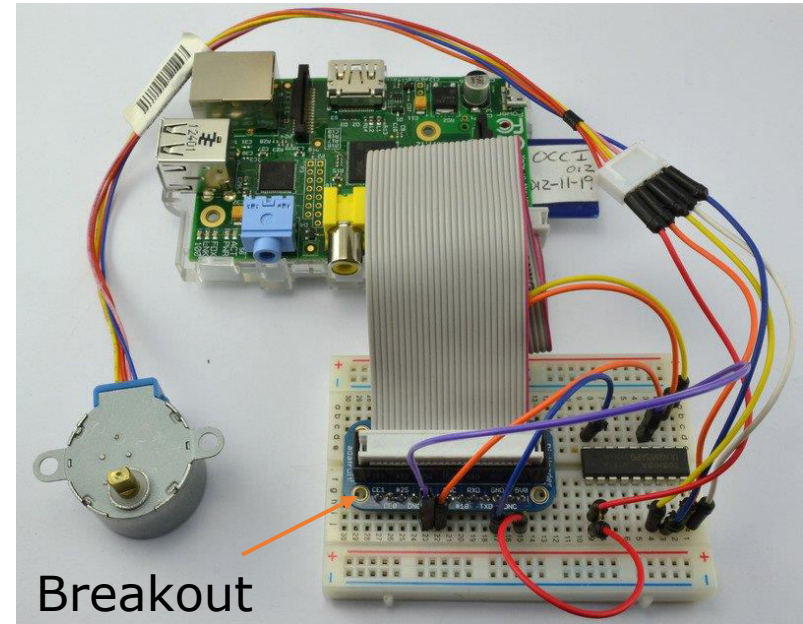
- GPIO NUMBERING
 - Seen by the onboard computer
- PHYSICAL NUMBERING
 - Counting across and down from pin 1 at the top left

Raspberry Pi 3 GPIO Header

Pin#	NAME		NAME	Pin#
01	3.3v DC Power		DC Power 5v	02
03	GPIO02 (SDA1 , I ² C)		DC Power 5v	04
05	GPIO03 (SCL1 , I ² C)		Ground	06
07	GPIO04 (GPIO_GCLK)		(TXD0) GPIO14	08
09	Ground		(RXD0) GPIO15	10
11	GPIO17 (GPIO_GEN0)		(GPIO_GEN1) GPIO18	12
13	GPIO27 (GPIO_GEN2)		Ground	14
15	GPIO22 (GPIO_GEN3)		(GPIO_GEN4) GPIO23	16
17	3.3v DC Power		(GPIO_GEN5) GPIO24	18
19	GPIO10 (SPI_MOSI)		Ground	20
21	GPIO09 (SPI_MISO)		(GPIO_GEN6) GPIO25	22
23	GPIO11 (SPI_CLK)		(SPI_CE0_N) GPIO08	24
25	Ground		(SPI_CE1_N) GPIO07	26
27	ID_SD (I ² C ID EEPROM)		(I ² C ID EEPROM) ID_SC	28
29	GPIO05		Ground	30
31	GPIO06		GPIO12	32
33	GPIO13		Ground	34
35	GPIO19		GPIO16	36
37	GPIO26		GPIO20	38
39	Ground		GPIO21	40

Warning

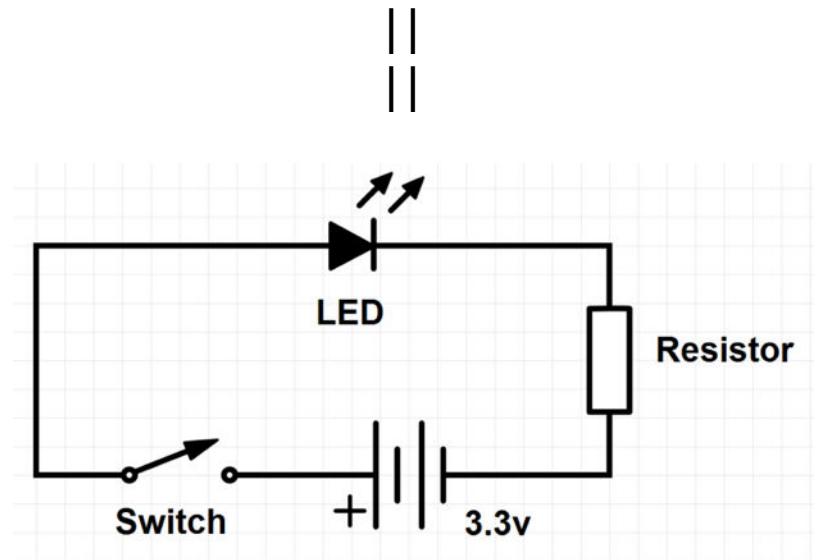
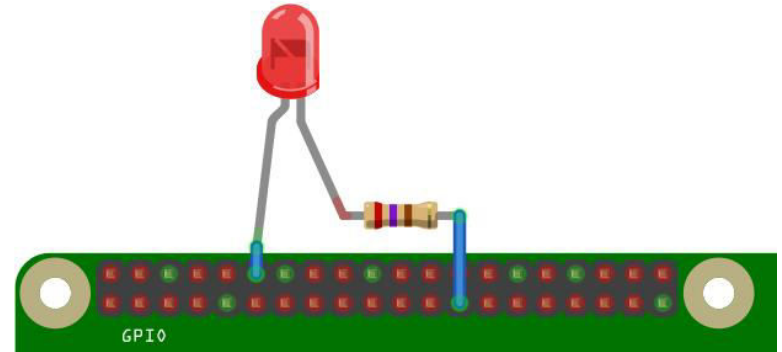
- **Unknowingly plugging wires and power sources may damage Pi** when connecting power hungry things to a Pi
 - LEDs are fine,
 - motors are not.
- For caution and ease of use, use a breakout board like [Pibrella](#) Until you become familiar with Pi
 - Labeled pins (otherwise needs a diagram)
 - Maybe protection circuit



Breakout board

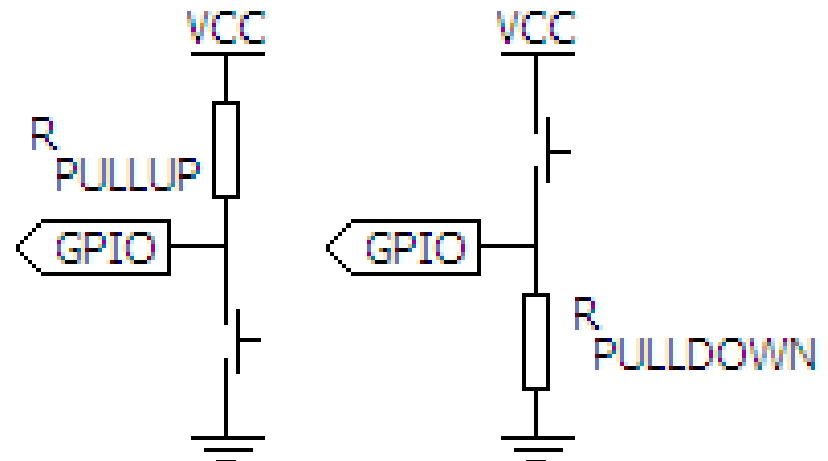
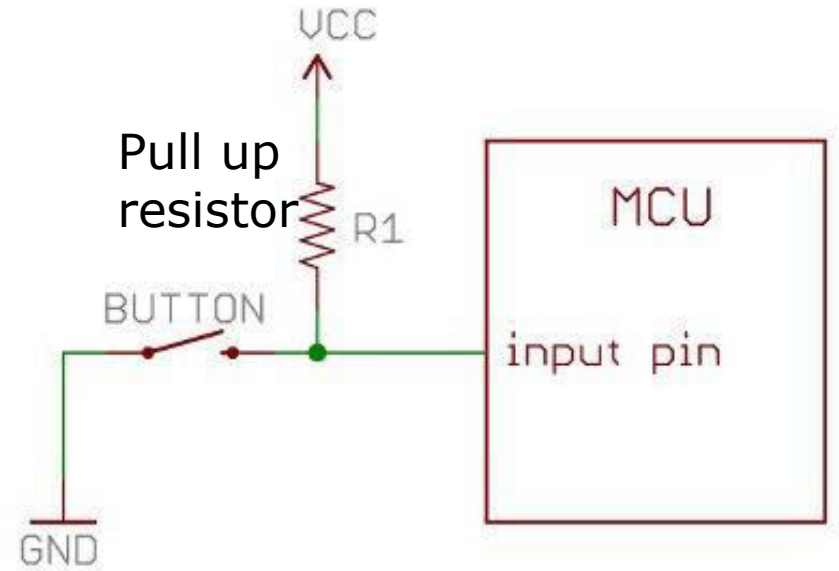
Output

- GPIO pin **outputs** are 3v3 or 0v
 - Can be called **on** or **off**, **HIGH** or **LOW**
 - Each pin can turn on or off
- Example use
 - Raspberry Pi as **the switch** and the **battery** in the left diagram.



INPUT

- GPIO pins are the simplest I/O on microcontrollers
- "pull up" and "pull down" circuits give an input pin a reference
 - In a case that the switch is off
 - To differentiate noise from signal
- **The input mode of a GPIO pin has high impedance**



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Program with Python to Control LED

- Open **Terminal** application
 - Click the terminal icon on the taskbar or
 - **Main Menu -> Accessories -> Terminal.**
- Open editor **idle3**: `sudo idle3 &` and press
- Create a Python file within idle3
 - **File -> new window.**
 - *File -> New Window.*
 - *File -> Save As* **reaction.py**
 - Type the code
 - Save the file: *File -> Save.*
- Run the code: **Run -> Run Module** or by pressing F5

Run Python File from the Command Line

- Run Python 2
 - `python reaction.py`
- Run python3
 - `Python3 reaction.py`

Python [7]

- Hello world
 - `print("Hello world")`
- Indentation
 - Indicate a block of code
 - 4 blank spaces in tradition
- Variables
 - Assignment like c with no need of type definition
 - Type can be changed
- Comments
 - Single line #
 - Multi-line: triple quotes `"""` comments `"""`

Python [7] (Cont'd)

- Lists (like array)
 - Mylist=[7, 8, 9]

- Iteration
 - for

```
N = [1, 2, 3]
for n in N:
    print(n)
```

- Range

```
for i in range(5):
    print(i)
```

- if statement

```
name = "Joe"
if len(name) > 3:
    print("Nice name,")
    print(name)
else:
    print("That's a short name,")
    print(name)
```

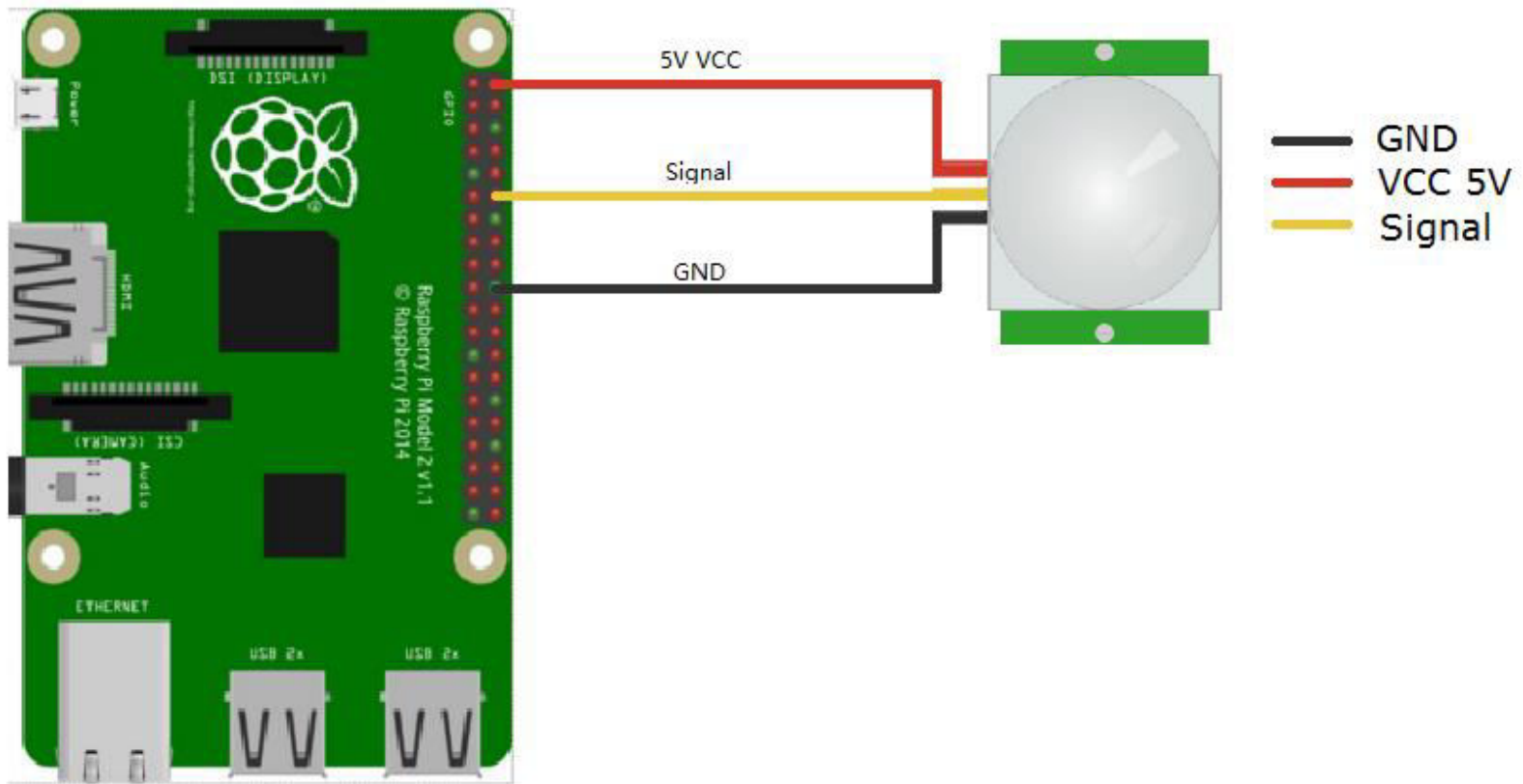

Code

1. `import RPi.GPIO as GPIO # Import GPIO library`
2. `import time # Import time library`
3. `GPIO.setmode(GPIO.BCM) #Use BCM pin numbering`
4. `GPIO.setwarnings(False) #Ignore GPIO warning messages`
5. `led = 4 # Assign 4 to variable led`
6. `GPIO.setup(led, GPIO.OUT) # Set pin 4 for outputting information`
7. `GPIO.output(led, 1) # Turns the GPIO pin 'on' (i.e., outputs 3.3v)`
8. `time.sleep(5) # Pause the program for 5 second`
9. `GPIO.output(led, 0) # Turns the GPIO pin 'off' (i.e., outputs 0v)`
10. `# Clean up all the used ports in the program. Resets any ports you have used in this program back to input mode`
11. `GPIO.cleanup()`

Outline

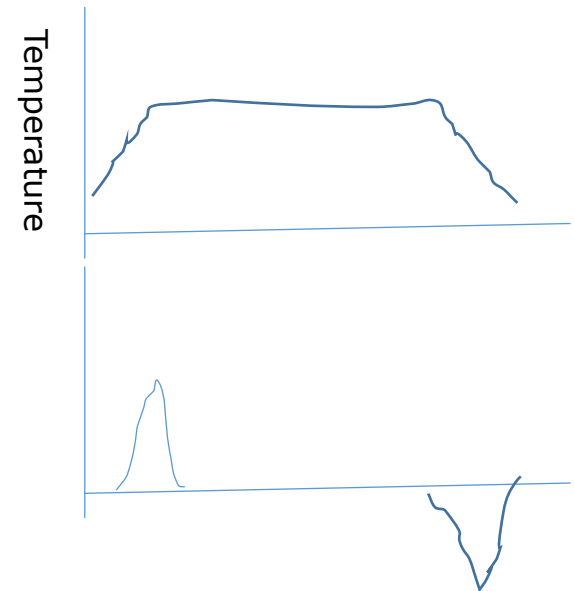
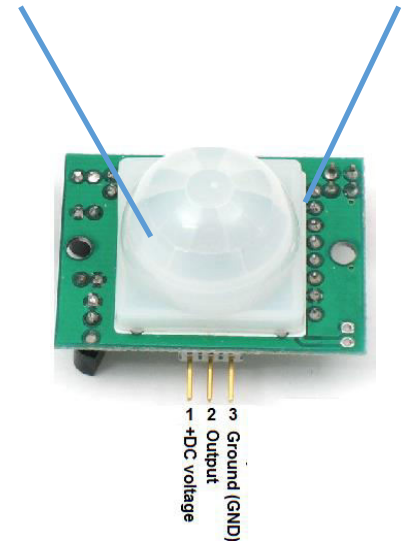
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Demo – Motion Sensor



PIR Sensor Principle

- The PIR sensor is made of IR sensitive material
- The lens over the sensor can change
 - breadth, range, sensing pattern
- An idle sensor detect the same amount of IR from the environment.
- Motion detection
 - A warm entity entering the sensing zone causes a *positive differential* change
 - The warm entity leaving the sensing zone generates a negative differential change



PIR Sensor Code Example

```
1.  import RPi.GPIO as GPIO
2.  import time

3.  GPIO.setmode(GPIO.BCM)
4.  pir= 7
5.  GPIO.setup(pir, GPIO.IN)

6.  try:
7.      print "PIR Module Test (CTRL+C to
          exit)"
8.      time.sleep(10)
9.      print "Ready"

10. while True:
11.     # read status of pin pir
12.     if GPIO.input(pir): #
13.         print "Motion Detected!"
14.         time.sleep(1)

15. except KeyboardInterrupt:
16.     print " Quit"

17. GPIO.cleanup()
```

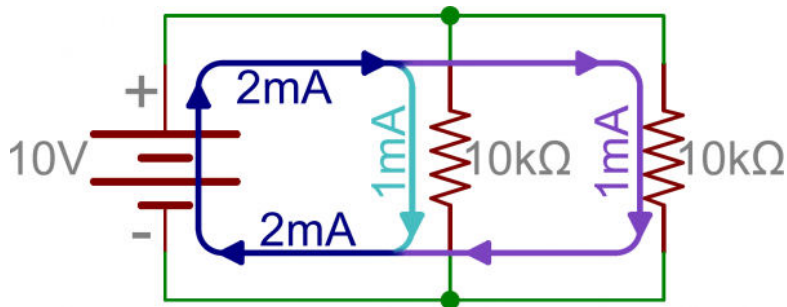
Circuits

- Equivalent Resistances in Series Circuits



- Equivalent Resistances in Parallel Circuits

$$R_{tot} = R_1 + R_2 + \dots + R_{N-1} + R_N$$



$$\frac{1}{R_{tot}} = \frac{1}{R_1} + \frac{1}{R_2} + \dots + \frac{1}{R_{N-1}} + \frac{1}{R_N}$$

References

- [1] CTAYLOR, [Voltage, Current, Resistance, and Ohm's Law](#), 2016
- [2] Smon Monk, [LEARN RASPBERRY PI 13 GUIDES](#), 2015
- [3] Mtaylor, [Raspberry gPlo](#), 2016
- [4] [How PIRs work](#), 2015
- [5] PETE-O, [Series and Parallel Circuits](#), 2016
- [6] [RPi.GPIO basics 6 – Using inputs and outputs together with RPi.GPIO – pull-ups and pull-downs](#), Jul 17 2013
- [7] [Python](#), 2017