

Applications of DSP

Project 5

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Question 1:

Given,

The system with Gaussian white noise $x(n)$,

Input signal $\eta(n) = 0$

Need to find Wiener weights by computing $\mathbf{w}^* = [\mathbf{R}]^{-1}[\mathbf{P}]$ using 100 and 1000 samples of the input signals.

Initializing the problem with $c = [1, 2, 3]$, the unknown channel $F(z)$ is represented by $F(z) = c_0 + c_1 * z^{-1} + c_2 * z^{-2}$.

From the unknown channel, the output is $d(n)$, which is added to the input signal. We get the error $e(n)$ by subtracting the modeling system: $A(z) = w_0 + w_1 * z^{-1} + w_2 * z^{-2}$. Then generated the R (autocorrelation matrix of the input signal) and P matrix (cross correlation of the input and the desired signal) by convoluting the given c vector with a random vector $[1 \times n]$.

From the MATLAB console window, for 100 and 1000 samples, the Wiener weight output is:

```
the result of Problem1 for n=100

w_Problem1 =

    0.9931
    1.8961
    2.8622

the result of Problem1 for n=1000

w_Problem1 =

    0.9998
    1.9959
    2.9928
```

As I have generated a Random number in MATLAB the output is always different.

Question 2:

Given,

Adaptive system where the error $e(n)$ from the last system is fed back through the LMS Algorithm block to the modeling system.

Need to find iteratively w_0 , w_1 , w_2 using the LMS algorithm

Initializing the number of samples, n as 150. μ is 0.02.

Implemented the LMS algorithm using the following formula:

$$y(k) = w_0(k) * x(k) + w_1(k) * x(k-1) + w_2(k) * x(k-2)$$

$$\text{Error } e(k) = d(k) - y(k).$$

$$w_0(k+1) = w_0(k) + 2\mu * e(k) * x(k)$$

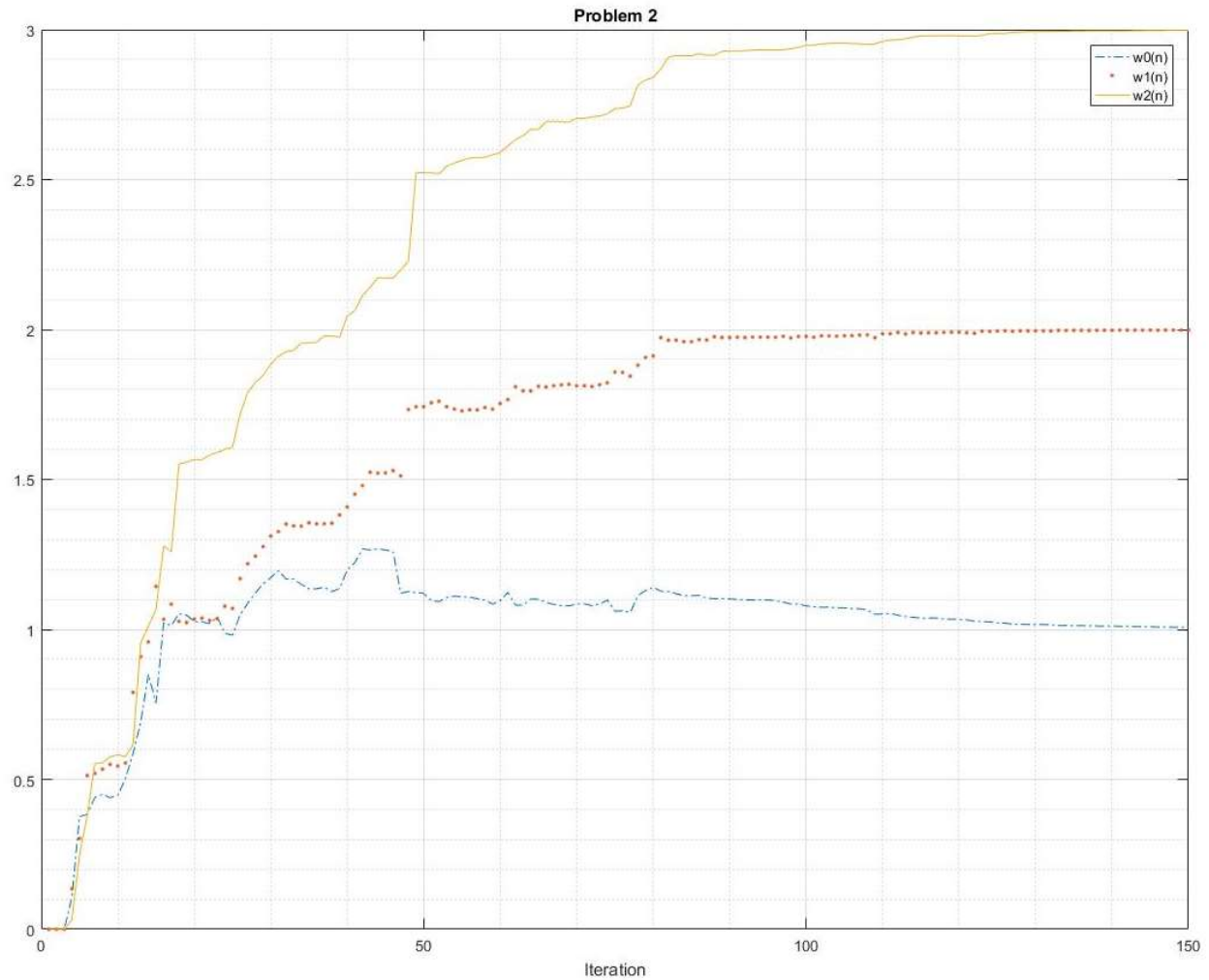
$$w_1(k+1) = w_1(k) + 2\mu * e(k) * x(k-1)$$

$$w_2(k+1) = w_2(k) + 2\mu * e(k) * x(k-2)$$

From the MATLAB console window:

```
the result of Problem1 for n=150  
  
w_Problem2 =  
  
    1.0068    1.9982    2.9980
```

Weight vs Iteration plot:



Question 3:

Given,

The same system setup as in problem 2. As discussed by Dr. Wasfy in the class, from the LMS algorithm

$$w_{n+1}(i) = w_n(i) + 2\mu e(n)x(n-i), i = 0 \rightarrow L$$

Need to find iteratively the weights w0, w1 and w2 using the Homogeneous Adaptive Algorithm.

Using Taylor's series expansion, we get:

$$e_{n+1} = e_n + \sum_{i=0}^L \frac{\partial e(n)}{\partial w_i} * \Delta w_i$$

Coupling the two equations we get

$$\mu = (1)/(2 \sum_{i=0}^L x^2(n - i))$$

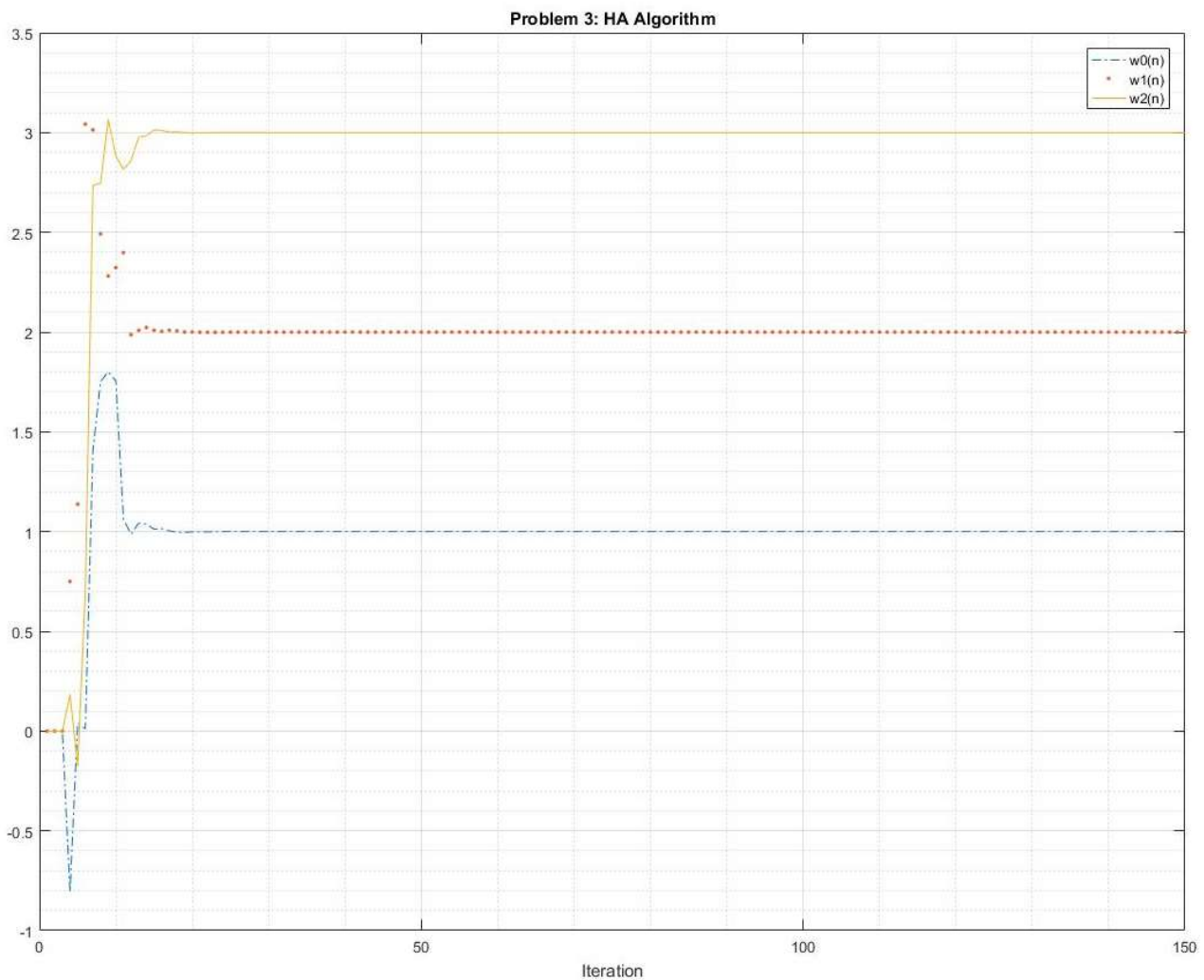
From the MATLAB console window:

```
the result of Problem1 for n=150

w_Problem3 =

    1.0000    2.0000    3.0000
```

Weight vs Iteration plot:



Question 4:

Given,

Uncorrelated input signal: $\eta(n) = 0.2 \cdot \frac{\sin(2\pi n)}{16}$

Need to find, iteratively the three weights using LMS algorithm.

The equation used here:

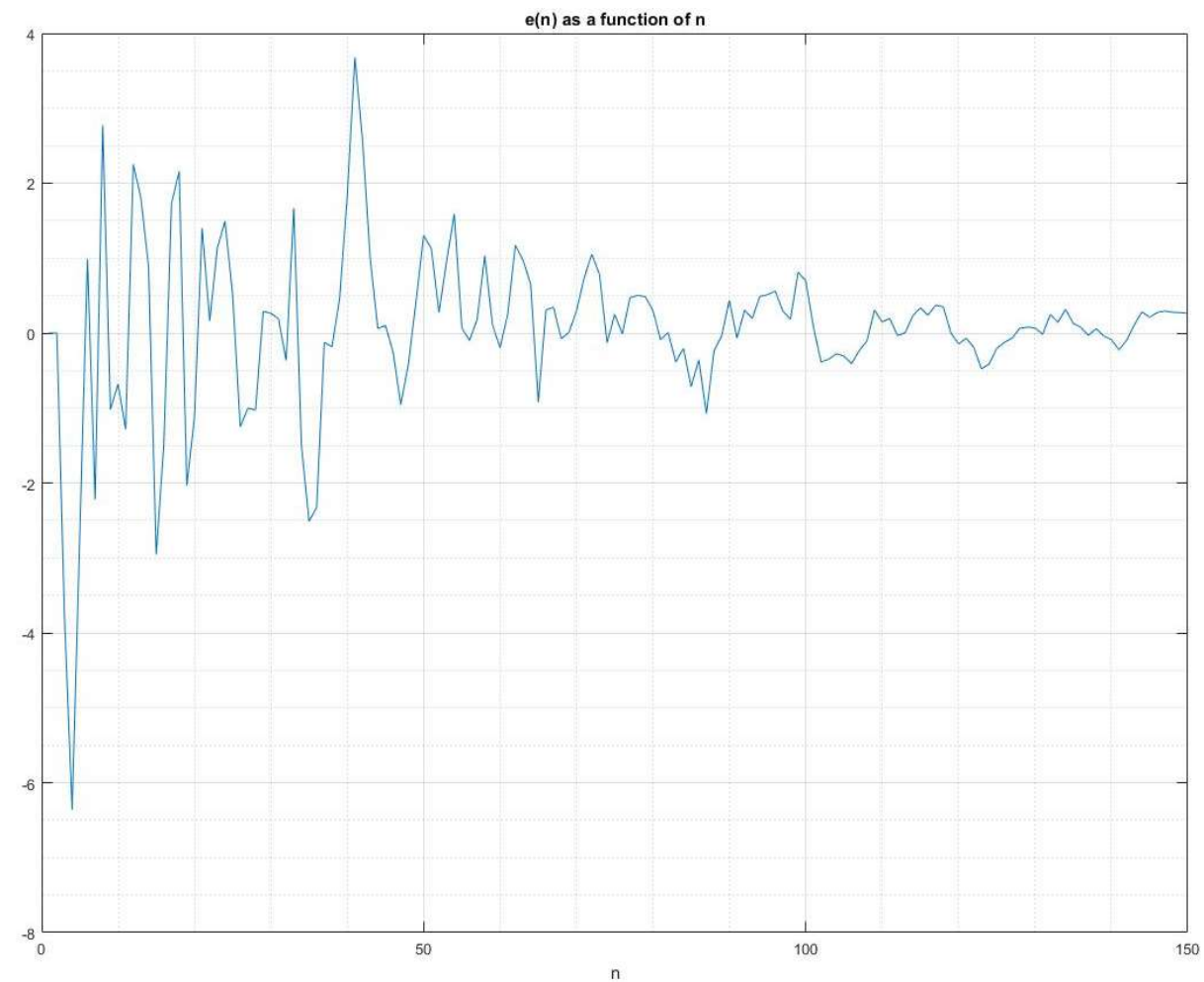
$$e(k) = d(k) + \eta k - y(k).$$

From the MATLAB console window:

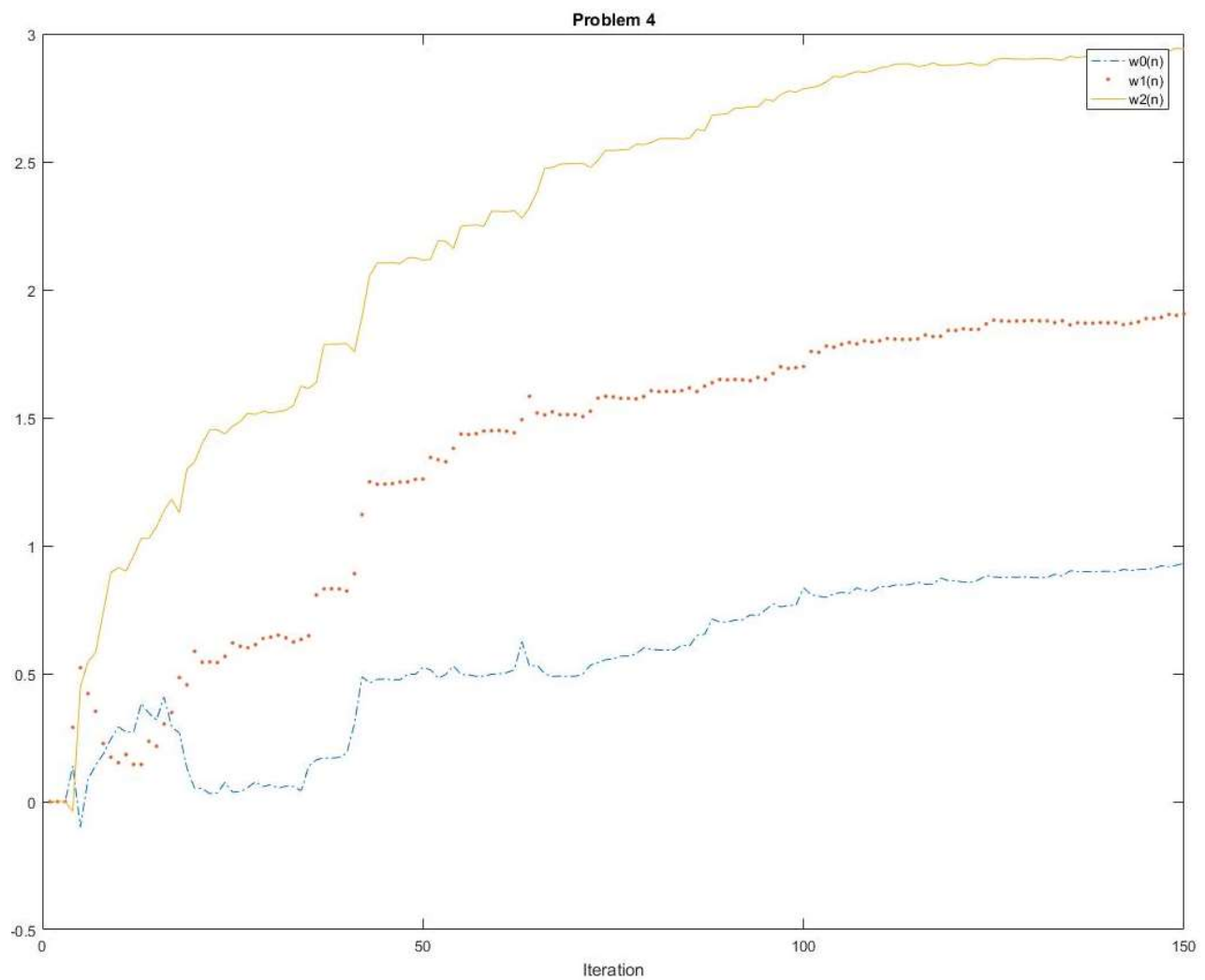
```
the result of Problem1 for n=150
```

```
w_Problem4 =
```

```
0.9354    1.9130    2.9459
```



Weight vs Iteration plot:



MATLAB Code

```
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%  
% EEL 5513 Applications of DSP  
% Project 5  
% Submitted by Rajib Dey  
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%  
  
% Code for Qu. no. 1-----  
  
% Initializing  
clear;  
clc;  
c=[1,2,3];
```

```

% for n=100
n=100;
x=randn(1,n);
d=conv(x,c);
d=d(1:n);

% Generating R & P Matrix
for k=1:3
    x_temp=[zeros(1,k-1),x(1:n-k+1)];
    r(k)=x*x_temp'/n;
    P(k)=d*x_temp'/n;
end
for i=1:3
    for j=1:3
        R(i,j)=r(abs(i-j)+1);
    end
end
% Displaying the result
display('the result of Problem1 for n=100');
w_Problem1=inv(R)*P'
% for n=1000
n=1000;
x=randn(1,n);
d=conv(x,c);
d=d(1:n);
% Generating R & P Matrix
for k=1:3
    x_temp=[zeros(1,k-1),x(1:n-k+1)];
    r(k)=x*x_temp'/n;
    P(k)=d*x_temp'/n;
end
for i=1:3
    for j=1:3
        R(i,j)=r(abs(i-j)+1);
    end
end
% Displaying the result
display('the result of Problem1 for n=1000');
w_Problem1=inv(R)*P'

% Code for Qu. no. 2-----
clear;
c=[1,2,3];
% Initializing for n=150
n=150;
x=randn(1,n);
d=conv(x,c);
d=d(1:n);
mu=0.02;
w0(1)=0;
w1(1)=0;
w2(1)=0;
w0(2)=0;
w1(2)=0;
w2(2)=0;

```



```

w0(3)=0;
w1(3)=0;
w2(3)=0;

% LMS Algorithm
for k=3:n
    y(k)=w0(k)*x(k)+w1(k)*x(k-1)+w2(k)*x(k-2);
    e(k)=d(k)-y(k);
    w0(k+1)=w0(k)+2*mu*e(k)*x(k);
    w1(k+1)=w1(k)+2*mu*e(k)*x(k-1);
    w2(k+1)=w2(k)+2*mu*e(k)*x(k-2);
end
% Plot
i=1:n;
figure;
plot(i,w0(i),'-.',i,w1(i),'.',i,w2(i),'-');
legend('w0(n)', 'w1(n)', 'w2(n)');
xlabel('Iteration');
title('Problem 2');
grid on;
grid minor;
% Displaying the result
display('the result of Problem1 for n=150');
w_Problem2=[w0(k+1),w1(k+1),w2(k+1)]

% Code for Qu. no. 3-----
clear;
c=[1,2,3];
% Initializing for n=150
n=150;
x=randn(1,n);
d=conv(x,c);
d=d(1:n);
mu=0.02;
w0(1)=0;
w1(1)=0;
w2(1)=0;
w0(2)=0;
w1(2)=0;
w2(2)=0;
w0(3)=0;
w1(3)=0;
w2(3)=0;

% HA Algorithm
for k=3:n
    y(k)=w0(k)*x(k)+w1(k)*x(k-1)+w2(k)*x(k-2);
    e(k)=d(k)-y(k);
    mu=1/(2*(x(k)^2+x(k-1)^2+x(k-2)^2));

    w0(k+1)=w0(k)+2*mu*e(k)*x(k);
    w1(k+1)=w1(k)+2*mu*e(k)*x(k-1);
    w2(k+1)=w2(k)+2*mu*e(k)*x(k-2);
end

% Plotting

```

```

i=1:n;
figure;
plot(i,w0(i), '-.',i,w1(i), '.',i,w2(i), '-');
legend('w0(n)', 'w1(n)', 'w2(n)');
xlabel('Iteration');
title('Problem 3: HA Algorithm');
grid on;
grid minor;
% Displaying the result
display('the result of Problem1 for n=150');
w_Problem3=[w0(k+1),w1(k+1),w2(k+1)]

% Code for Qu. no. 4-----
clear;
c=[1,2,3];
% Initializing for n=150
n=150;
x=randn(1,n);
d=conv(x,c);
d=d(1:n);
mu=0.02;
w0(1)=0;
w1(1)=0;
w2(1)=0;
w0(2)=0;
w1(2)=0;
w2(2)=0;
w0(3)=0;
w1(3)=0;
w2(3)=0;
% LMS Algorithm
for k=3:n
    y(k)=w0(k)*x(k)+w1(k)*x(k-1)+w2(k)*x(k-2);
    eta(k)=0.2*sin(2*pi*k/16);
    e(k)=d(k)+eta(k)-y(k);
    w0(k+1)=w0(k)+2*mu*e(k)*x(k);
    w1(k+1)=w1(k)+2*mu*e(k)*x(k-1);
    w2(k+1)=w2(k)+2*mu*e(k)*x(k-2);
end
% Plotting
i=1:n;
figure;
plot(i,w0(i), '-.',i,w1(i), '.',i,w2(i), '-');
legend('w0(n)', 'w1(n)', 'w2(n)');
xlabel('Iteration');
title('Problem 4');
figure;
plot(e(i))
xlabel('n');
title('e(n) as a function of n');
grid on;
grid minor;
% Displaying the result
display('the result of Problem1 for n=150');
w_Problem4=[w0(k+1),w1(k+1),w2(k+1)]

```