

CSE 331L: Microprocessor Interfacing and Embedded Systems Lab

Summer 2025

Arm Assembly (Part-1)

Class # 02

Recap

- Microprocessor
- Memory (Primary → Register)
- Register Type & Size
- Instructions Parts & Type
- CPULator Basics
- MOV
- ADD
- SUB





Instructions

- An instruction is a low-level operation or command that the processor executes. It tells the ARM processor what specific action to perform, such as arithmetic operations, data movement, branching, and more
- MOV RO, R5 @ moves the value of R5 to R1

MOV

 Move (register) copies a value from a register to the destination register. It can optionally update the condition flags based on the value.

ADD immediate

This instruction adds an immediate value to a register value, and writes the result to the destination register. It can optionally update the condition flags based on the result.

ADD

 This instruction adds a register value and an optionally-shifted register value, and writes the result to the destination register. It can optionally update the condition flags based on the result.

```
ADD{S}<c> <Rd>, <Rn>, <Rm>{, <shift>}
```

SUB immediate

This instruction subtracts an **immediate value** from a **register value**, and writes the result to the destination register. It can optionally update the condition flags based on the result.

```
SUB{S}<c> <Rd>, <Rn>, #<const>
```

SUB

• This instruction adds a register value and an optionally-shifted register value, and writes the result to the destination register. It can optionally update the condition flags based on the result.

```
SUB{S}<c>.W <Rd>, <Rn>, <Rm>{, <shift>}
```

MUL

Multiply multiplies two register values. The least significant 32 bits of the
result are written to the destination register. These 32 bits do not depend on
whether the source register values are considered to be signed values or
unsigned values.



Memory Segments

8086 vs Arm

Declaring Variables

 Must be declared in data segment var_name : .<data_type> <value>

```
.global start
.data
a: .word 7
b: .word 10
.text
start
ldr r0, =a
ldr r1, [r0]
mov r2, #9
1dr r3, =b
str r2, [r3]
```

LDR (Load Register)

 Load Register (register) calculates an address from a base register value and an offset register value, loads a word from memory, and writes it to a register. The offset register value can optionally be shifted.

```
LDR<c> <Rt>, [<Rn>, +/-<Rm>{, <shift>}]{!}
```

LDR (Load Register)

- Two steps:
 - First, load the address of a variable

- then, use that address to get the values in a general purpose register
 Idr <register2> , [<register1>]
- Now, we get: register2 = variable_name

STR

• Store Register (register) calculates an address from a base register value and an offset register value, stores a word from a register to memory. The offset register value can optionally be shifted

```
STR<c> <Rt>, [<Rn>, +/-<Rm>{, <shift>}]{!}
```

STR

- Two steps:
 - First, load the address of a variable

- then, use that address to get the values in a general purpose register
 Idr <register2> , [<register1>]
- Now, we get: variable_name = register2

How to find address manually!!

