

# INDIAN INSTITUTE OF TECHNOLOGY KHARAGPUR

## APPLIED COMPUTATIONAL METHODS LABORATORY Lab-2

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### LU\_PP Function

```
\% Code for the algorithm 1
%LU Factorisation; GEPP Constructing, P,L,U such that PA = LU
function [L,P,U] = LU__PP(A)
[n,n] = size(A);
P = eye(n);
L = eye(n);
U = A;
for i=1: n-1
  [pivot, m] = max(abs(U(i:n, i)));
  m = m+i-1;
  if m~=i
    % swap rows m and i in P
    temp = P(i,:);
    P(i,:) = P(m,:);
    P(m,:) = temp;
    % swap rows m and i in P
    temp = P(i,:);
    P(i,:) = P(m,:);
    P(m,:) = temp;
    % swap rows m and i in P
       if i>=2
         temp = L(i,1:i-1);
         L(i,1:i-1) = L(m,1:i-1);
         L(m,1:i-1) = temp;
       end
  end
  L(i+1:n,i) = U(i+1:n,i)/U(i,i);
  U(i+1:n, i+1:n) = U(i+1:n, i+1:n) - L(i+1:n, i)*U(i,i+1:n);
  U(i+1:n,i) = 0;
End
```

#### **GEPP 2D Poisson Function**

```
% number of inner nodes
n=20;
% A, Af
a_amp = 12;
f_amp = 1;
x_0 = 0.5;
y_0 = 0.5;
c_x = 1;
c_y = 1;
h = 1/(n+1);
% Generating Matrix A
S = DiscretePoisson2D(n);
% LU Factorisation of A (S) with pivoting
[L,U,P] = LU\_\_PP\_function(S);
% Generate coefficient a((x_1)_i,(x_2)_j) = a(i*h,j*h)
C = zeros(n,n);
for i=1:n
  for j = 1:n
    C(i,j) = 1 + a\_amp*exp(-((i*h-x\_0)^2/(2*c\_x^2) + (j*h-y\_0)^2/(2*c\_y^2)));
  end
end
% calculate the load vector
% if f is constant, f = af_amp*ones(n^2,1);
\% if f is Gaussian function
f = zeros(n^2,1);
for i = 1:n
 for j = 1:n
    f(n*(i-1)+j) = f_amp*exp(-((i*h-x_0)^2/(2*c_x^2)+(j*h-y_0)^2/(2*c_y^2)));
  end
end
```

```
% solving LSE Au = (1/h^2)DLUu = f
\% create diagonal matrix D from C
D = zeros(n^2,n^2);
for i = 1:n
  for j = 1:n
    D(j+n*(i-1),j+n*(i-1)) = C(i,j);
  end
end
% compute vector on RHS
% b = D^(-1)*f given by b(i,j) = f(i,j)/a(i,j)
b = zeros(n^2,1);
for i = 1:n
  for j = 1:n
    b(n*(i-1)+j) = f(n*(i-1)+j)/C(i,j);
  end
end
% To solve 1/h^2Au = b, use first LU decomposition
\%\ 1/h^2LUu = b, then compute v = \ L^{(-1)*b} by forward substitution
v = ForwSub_function(L,P*b);
% Now solve 1/h^2Uu = v
% Compute w = U^{(-1)}v by backward substitution
w = BackwSub_function(U,v);
% 4th step 1/h^2u=w
% compute final solution as u = h^2w
u = h^2*w;
```

```
%GEPP_2D_Poisson.m (main program)
%plot and figures
%sort the data in u into the mesh-grid
z=zeros(n+2,n+2);
for i=1:n
  for j=1:n
    z(i+1,j+1) = U(j+n*i-1);
  end
end
% Plotting
x1 = 0:h:1;
y1 = 0:h:1;
figure(1)
surf(x1,y1,z) \% 3D plot of solution
view(2)
colorbar
xlabel('x\_1')
ylabel('x_2')
{\sf zlabel('u(x\_1,x\_2)')}
title(['u(x_1,x_2) with A = ',num2str(a_amp),', N = ',num2str(n)])
figure(2)
surf(x1,y1,z) % same plot
%view(z)
colorbar
xlabel('x_1')
ylabel('x_2')
zlabel('u(x\_1,x\_2)')
title(['u(x\_1,x\_2) \ with \ A = ',num2str(a\_amp),', \ N = ',num2str(n)])
% Plotting a(x,y)
z_a = zeros(n+2);
for i = 1:(n+2)
  for j = 1:(n+2)
    z\_a(i,j) = 1 + a\_amp*exp(-((i*h-x\_0)^2/(2*c\_x^2) + (j*h-y\_0)^2/(2*c\_y^2)));
  end
```

```
end
```

```
figure(3)
surf(x1,y1,z_a) \% 3D plot of a(x_1,x_2)
xlabel('x_1')
ylabel('x_2')
zlabel('a(x_1,x_2)')
title(['a(x_1,x_2) with A = ',num2str(a_amp)])
% plot of f(x,y)
z_f = zeros(n+2);
for i = 1:n
 for j = 1:n
    z_f(i,j) = f_amp*exp(-((x1(i)-x_0)^2/(2*c_x^2) + (y1(j)-y_0)^2/(2*c_y^2)));
  end
end
figure(4)
surf(x1,y1,z\_f) \ \% \ 3D \ plot \ of \ f(x\_1,x\_2)*a(x\_1,x\_2)
xlabel('x_1')
ylabel('x_2')
zlabel('f(x_1,x_2)')
```

#### **Forward Sub Function**

```
function x = ForwSub(L,b)

s = size(L);

n = s(1);

x = zeros(n,1);

x(1) = b(1)/L(1,1);

for i=2:n

x(i) = (b(i) - L(i,1:i-1)*x(1:(i-1)))/L(i,i);

end

end
```

#### **Backward Sub Function**

```
function x = BackwSub(U,b)
```

```
s = size(U);
```

```
n = s(1);
x = zeros(n,1);
x(n) = b(n)/U(n,n);
for i=n-1:-1:1
 x(i) = (b(i) - U(i,(i+1):n)*x((i+1):n))/U(i,i);
end
end
Discrete Poisson 2D Function
% Constructs A for 2D discretization of - laplace operator
function A=DiscretePoisson2D(n)
% input parameter n, number of inner nodes, same in both directions
A = zeros(n*n,n*n);
% main diagonal
for i=1:n*n
A(i,i)=4;
end
% 1st and 2nd off-diagonals
for k=1:n % go through blocks 1 to n
  for i=1:(n-1)
  A(n*(k-1)+i,n*(k-1)+i+1)=-1;
  A(n*(k-1)+i+1,n*(k-1)+i)=-1;
  end
end
%3rd and 4th off-diagonals
for i=1:n*(n-1)
A(i,i+n)=-1;
A(i+n,i)=-1;
end
```

end

#### Output

